

# Contents

---

<b>1</b>	<b>Introduction</b>	<b>2</b>
1.1	System Requirements . . . . .	2
1.1.1	Operating System . . . . .	2
1.1.2	Hardware Requirements . . . . .	3
1.1.3	External Libraries . . . . .	3
1.1.4	Docker . . . . .	5
1.2	Installation . . . . .	5
1.3	Frequently Asked Questions . . . . .	6
<b>2</b>	<b>Modeling</b>	<b>7</b>
2.1	Setup . . . . .	7
2.1.1	Compilation . . . . .	7
2.1.2	Basic Structures: The Grid . . . . .	8
2.1.3	Input Structures . . . . .	9
2.1.4	Basic Structures: The Image . . . . .	13
2.1.5	Making a Model . . . . .	15
2.1.6	FITS File Handling . . . . .	16
2.2	Continuum Models . . . . .	17
2.2.1	The Power Law Disk . . . . .	17
2.2.2	Disk with Gaps . . . . .	19
2.2.3	Common Problems . . . . .	22
2.3	Line Emission . . . . .	24
2.3.1	Line Opacities . . . . .	24
2.3.2	Line Specific Setup . . . . .	25
2.3.3	The Power Law Disk in CO . . . . .	26
<b>3</b>	<b>Fourier Nonsense</b>	<b>30</b>
3.1	Fourier Transforms and Back Transforms . . . . .	30
3.1.1	The <code>fourierImage</code> Class . . . . .	31
3.1.2	Back Transforms . . . . .	32

---

3.2	The Beam Class . . . . .	33
3.3	Examples . . . . .	33
<b>4</b>	<b>Fitting</b>	<b>37</b>
<b>A</b>	<b>Line Opacity</b>	<b>38</b>

## List of Figures

---

2.1	Basic Power Law Disk . . . . .	18
2.2	Gap Disk Model . . . . .	19
2.3	Disk Model with Too Few Steps . . . . .	22
2.4	Improperly Truncated Disk Model . . . . .	23
2.5	Power Law Disk Imaged in CO and Dust Emission . . . . .	28
3.1	Line Emission with Frequency Averaging and Beam Smoothing . . .	36

## List of Tables

---

1.1	External Libraries . . . . .	3
-----	------------------------------	---

Magrathea is a tool for simulating and fitting millimeter wavelength emission from protoplanetary disks. This involves two largely separate sections: the first handles modeling of emission, and the second Markov Chain Monte Carlo fitting of those models to data. This tutorial will provide information on compiling and running the Magrathea code, and include examples highlighting the most common use cases. While some information on the algorithms used will be provided in the following chapters, detailed explanations of which methods were chosen and why can be found in my thesis, which can be found on the Rice University Library website.<sup>1</sup>

The Magrathea source code is in the form of libraries. Users can include its various sections to write C++ programs of their own for fitting and modeling disk emission.

This document is split into three parts. Chapter 1 provides introductory information, including system requirements and compilation instructions. Chapter 2 will describe in detail how to make model disk images, of both continuum and multi-channel line emission. Chapter 3 will explain how to set up and run a full MCMC fit.

The documentation here assumes a basic level of knowledge about C++ language features. Users should not need to be experts, however, in order to use Magrathea for basic modeling and fitting.

## **1.1 System Requirements**

### **1.1.1 Operating System**

Magrathea is designed to run on most recent Linux and Unix systems. I have personally verified functionality on several Linux systems, including Ubuntu (version 16 and 20), Mint (version 20, based off of Ubuntu 20), CentOS 8, RHEL 6, and RHEL 7. Several MacOS versions have been tested as well, including versions from 10.12 to 10.15. In principle, Magrathea should be able to run on basically any Unix system that you are capable of getting a working C++17 capable compiler on.

---

<sup>1</sup>I'll include a link here once I've submitted the final version and they've put it up.

It is also possible to use Magrathea from Windows, using the Windows Subsystem for Linux (WSL). This requires updating the operating system to a preview build of Windows 10, and then installing the newer WSL 2.<sup>1</sup> Once installed, Magrathea will run in the Linux VM just like on any other Linux system, though I did notice some intermittent connection issues when connecting in to large fits from Windows.

### 1.1.2 Hardware Requirements

There are few explicit requirements on the hardware needed. Both Intel and AMD systems work fine (you could probably even get an ARM system working, but I never needed to). However, for full functionality, it is recommended to use a newer processor.

Magrathea will attempt to use the wider SIMD instructions provided by newer systems in order to speed up calculation. Currently, the most recent recent instruction set used is AVX2, which is supported by most Intel and AMD processors made after 2015. Older systems will fall back on older instruction sets when possible, such as SSE4.2, and will use the basic X86 instructions if necessary.<sup>2</sup> It is never necessary to use the vector extensions, but can improve speed by a factor of two to three.

### 1.1.3 External Libraries

Besides the source code, Magrathea requires several external libraries in order to run properly. For details of what each of these libraries contributes, see the relevant sections of my thesis.

External Dependencies		
Code	Source	Purpose
Boost	<a href="http://www.boost.org">www.boost.org</a>	Various C++ Libraries
Cap'n Proto	<a href="http://capnproto.org">capnproto.org</a>	Serialization
CFITSIO	<a href="http://heasarc.gsfc.nasa.gov/fitsio/">heasarc.gsfc.nasa.gov/fitsio/</a>	FITS File Handling
FFTW	<a href="http://www.fftw.org">www.fftw.org</a>	Fast Fourier Transform
libcuckoo	<a href="https://github.com/efficient/libcuckoo">github.com/efficient/libcuckoo</a>	Hashing
ThreadPool	<a href="https://github.com/progschj/ThreadPool/">github.com/progschj/ThreadPool/</a>	Multithreading
VCL	<a href="https://github.com/vectorclass">github.com/vectorclass</a>	Vectorization

Table 1.1: External libraries and their uses for Magrathea.

<sup>1</sup>For details on WSL installation, see <https://docs.microsoft.com/en-us/windows/wsl/install-win10>.

<sup>2</sup>There is a known issue in how Agner Fog's Vectorclass library handles decomposing certain math functions to smaller register widths. It can be necessary to unpack certain operations, such as exponentials, in order to make them run on very old systems. This seems to be a bug in the vectorclass library, but will likely not come up on any computer made post 2012.

## Boost

Boost provides a wide variety of extensions to the C++ standard libraries, from mathematical algorithms to networking. Several Boost libraries have been added as official language features, with more to be included in the future.

This thesis makes use of the Boost HTTP server, which provides a simple way to send newly generated temperature files from the server to worker nodes. Worker nodes can request the temperature files from the HTTP server via libcurl.

## Cap'n Proto

Cap'n Proto provides serialization and remote process control for C++ programs, written and maintained by Kenton Varda. Here, Cap'n Proto is used to send commands and information between the server and worker nodes. The server sends work units to worker nodes, as well as commands to wait or shut down, as necessary. The worker nodes send connection notifications to the central server, as well as work requests and periodic “heartbeat” signals.

## CFITSIO

CFITSIO provides C libraries for reading and writing to FITS files **cite Penc1999**, one of the primary file formats used in astronomy. Internally, CFITSIO is used to read in observations which come as FITS files, and to output models as FITS files for viewing.

## FFTW

FFTW provides C libraries for extremely rapid Fast Fourier Transforms, written by Matteo Frigo and Steven G. Johnson. FFTs are used primarily for calculating the goodness of fit of model images, but can also be used to generate beam convolved models.

## libcuckoo

libcuckoo provides an efficient, compact, and thread safe hash table **cite Fan2013**. Internally, this is used to generate unique worker IDs when each worker node is started.

## Threadpool

The Threadpool library is a C++ library written by Jakob Progsch, which simplifies multithreading in C++. The threadpool allows the programmer to spawn a threadpool with a given number of threads, which are handled internally, so that the programmer does not need to work directly with UNIX threads. This is used internally in every place where a task has been multithreaded, most importantly in generating model images, but also calculating  $\chi^2$  values.

## VCL

VCL, Agner Fog’s vector class, provides simple C++ classes to handle vectorized programs. The vector class provides convenient wrappers around the system provided vector intrinsics, making it much easier to write simple C++ code which takes full advantage of SIMD instructions. Internally, vectorized instructions are used extensively to optimize the ray tracing, and to calculate the goodness of fit.

### 1.1.4 Docker

For those attempting truly ambitious fits, it may be necessary to shift calculation from local computing resources to larger, cloud based systems. Most of these, such as those operated by AWS, are most easily used via containers, such as Docker. A Docker image contains an operating system, typically a small Linux distribution, as well as the libraries required to build the code. I’ll include a link here to the Docker image I’ve made for Magrathea once it is more finalized.

## 1.2 Installation

In order to use Magrathea, it is necessary to first necessary to compile the source libraries. This is done in the typical, if old fashioned, way using **make**:

```
./configure.sh --prefix=[install location]
make
make install
```

To set up, first run the provided configure shell script, which will check for the required external libraries and compiler features. To set the install location to something other than the default directory, use the **--prefix** flag. The configure script will check the usual locations for libraries and compilers, but can be directed to look for specific libraries in specific directories using the **--using-[library]** option. For a complete list of options, use the **--help** or **-h** flag.

If successful, then run **make**, to build the source code to the local directory. Lastly, running **make install** will copy the files to the specified install directory.

Magrathea also comes with a collection of examples which are detailed in later chapters. These examples are freestanding programs which demonstrate the various capabilities of Magrathea. To build them, first build the library, then run

```
make examples
```

Though it is necessary to build the library first, it is not necessary to install it. The example executables all build to **Magrathea/examples**, and can be run from that directory.



---

## 1.3 Frequently Asked Questions

Actually, none of these are frequently asked questions, since this software and manual are brand new. However, I suspect some of these might become frequently asked, in the event that anyone ever tries to use Magrathea.

I'll add more if anyone frequently asks me something.

### **Where can I submit bug reports?**

Send bugs and other issues to [etweaver@gmail.com](mailto:etweaver@gmail.com). I can't promise to rapidly fix anything, since it will no longer be my job to maintain this code in the future, but I will try to.

### **Will the code ever include scattering?**

Nope. The entire system is structured on the assumption that radiative transfer can be treated only along lines of sight. Adding scattering would lose that, and with it, most of the multithreading and vectorization. If you need scattering in your models, the tool you need is RADMC 3d, which can be found at [ita.uni-heidelberg.de/~dullemond/software/radmc-3d/](http://ita.uni-heidelberg.de/~dullemond/software/radmc-3d/).

### **Why “Magrathea”?**

Magrathea was a planet in *The Hitchhiker's Guide to the Galaxy*, where they made planets for people. This is code for modeling planet formation, and it needed a good name, so here you go.

It turns out, unsurprisingly, that I'm not the first person to decide that Magrathea is a good name for some code. Looking on Github, there's like a hundred things already called that. However, I'm pretty sure I'm the only one who actually is doing anything related to planet formation, so I feel more entitled.

### **Why is this manual formatted like a thesis?**

Because I just finished writing the thesis, and the thesis template is what I had handy.

This chapter will explain in detail how one goes about setting up a program to model a disk. Examples are included for several simple cases, for both continuum and line emission. Each example will output a FITS file containing the resulting model.

All units in Magrathea are assumed to be in cgs. Not everyone is happy about this, but it is the standard for most astronomy, and is used here.

## 2.1 Setup

This section will go into detail about how one sets up a model disk and makes an image of it. Before getting into examples, it is necessary to include the library, and to consider the primary data structures, the Grid, and the Image.

### 2.1.1 Compilation

Before we can get into the details of running a model, it is first necessary to set up the program correctly. Because Magrathea is a typical library, this has two parts. First, the correct files need to be included in any of the C++ files where Magrathea is used, and second, the compiler must be told to include the library.

Magrathea is small enough that it is entirely included in one umbrella file, `magrathea.h`. To use it, simply include it as any other header file by adding

```
#include "magrathea.h"
```

This gives access to all of the modeling classes and functions, as well as various physical constants.

In order to compile, the correct linker command must be added. If Magrathea has been installed in a default location, simply adding `-lmagrathea` will include it. If it is installed to a custom location not included in the search path, add `-L/path/to/magrathea` as well.

## 2.1.2 Basic Structures: The Grid

With the libraries included, we now have access to the Magrathea Grid class. The purpose of the Grid class is to contain the physical data of the disk, including its temperature and density structures, and to provide an interface for radiative transfer. The Grid is one of the largest and most complex parts of Magrathea, as it connects the structures of the disk to the physical processes involved, and it has many parameters.

The basic constructor for initializing a Grid for continuum imaging is

```
grid(double rmin, double rmax, double tmin, double tmax,
    double starMass, shared_ptr<density_base> dustDens,
    shared_ptr<temperature_base> diskTemp,
    shared_ptr<opacity_base> dustOpac):
```

The parameters fall into two basic groups: First, the dimensions of the Grid, as well as the star mass. Next come the user defined structures for the density, temperature, and the opacity. Don't be intimidated by the `std::shared_ptrs`! This is just a slightly fancier way of the old C style of passing pointers to the objects, which ensures that they are properly deleted, and keeps you from leaking memory everywhere.

### Extent

First, the physical extent. The Grid structure is designed around modeling protoplanetary disks, and has a shape which reflects this. There are inner and outer radial boundaries, which are defined spherically, and upper and lower azimuth boundaries, defined by cones.<sup>1</sup> This way, the region around the central star can be excluded, as it is typically very hot and has different physics.

It is important to understand that the inner and outer boundaries of the Grid are not necessarily connected to the physical structure of the disk material being modeled. Why? Because in order to do ray tracing, the rays must have a start and stop location, and it's easiest to this by seeing where they intersect the Grid. The structure meanwhile, is often defined in a continuous way. But because most emission comes from the inner regions, and near the midplane, it is reasonable to terminate the disk once there is little emission.

Some care must be taken to define the Grid boundaries in a sensible way that includes all of the important disk emission. The simple heuristics I tend to use are based around the power law disk with exponential cutoff, which is the basic disk model from the similarity solution. Because the exponential cutoff terminates extremely sharply, it isn't necessary to expand the Grid much beyond this. For a disk with a cutoff at 100 au, I might conservatively put the Grid boundary at 150 au, but if really pressed for speed, might contract it to 120 au. Vertically, you don't need to include

---

<sup>1</sup>Technically, there are also `pmin` and `pmax` variables you can use to set the azimuth boundaries. Personally, I can't think of any reason you would ever want these not to be 0 and  $2\pi$ , so they default to these. However, if you always dreamed of cutting a slice out of your disk like a pie, this is your chance.

much beyond a few scale heights, since the vertical structure is typically Gaussian. For a flared disk, you could calculate the opening angle that fits the vertical extent at the radial cutoff, but for flat disks this is usually overkill. I tend to just assume an opening angle of  $30^\circ$ , and go from there.

One other important note is that the angles, `tmin` and `tmax` start at 0 being the pole and  $\pi$  being the opposite pole, they are not defined relative to the midplane. So, to specify a symmetric,  $30^\circ$  opening angle, `tmin` would be  $5\pi/12$ , and `tmax` would be  $7\pi/12$ .

## Star Mass

This, fairly obviously, is the star mass, in grams. For continuum modeling, this has very little effect, but is included for completeness. The star mass will matter much more when we talk about modeling line emission.

### 2.1.3 Input Structures

In Magrathea, the disk can be quite general. The way this is done is by allowing the user to define their own temperatures, densities, and opacities. If you want a disk where the density structure is square, the temperature a spiral and the opacity dependent on radius, you can do that. However, because there are several very common types of disk, I provide a variety of common density, temperature, and opacity types.

For those wanting their own, all that is required is to define a class with the correct interface and pass a shared pointer into the grid. These user defined classes must inherit from the correct base class, either `density_base`, `temperature_base`, or `opacity_base`.

In this section, I'll describe some of the built in structures available, as well as how to define your own.

## Physical Structures

The most complicated section is how to specify the physical structures in the disk. In this simple case, two are needed, a single density and a temperature. For models with line emission, a second, separate, gas density can be specified. That will be detailed in the next section.

Dust structure, in particular, can vary considerably, depending on if you want gaps, rings, spirals, or other complicated features. The best way to do this is to define your own density structure. Your user defined density can be whatever you like, make the disk a hexagon if you want. The only requirement is that it have an overloaded call operator, which takes three spherical coordinates as arguments. This is how the integrator will expect to get the densities of positions in the disk. Here's an example for a classic power law disk with exponential cutoff:

```

struct myDensity : public density_base {
    double Sigma0;
    double rc;
    double h0;
    double P; //density index
    double S; //scale height index

    myDensity():
        Sigma0(0), rc(0), h0(0), P(0), S(0){ }
    myDensity(const newDensity& other):
        Sigma0(other.Sigma0), rc(other.rc), h0(other.h0),
        P(other.P), S(other.S){ }
    myDensity(double Sigma0, double rc, double h0,
    double P, double S):
        Sigma0(Sigma0), rc(rc), h0(h0), P(P), S(S){ }

    myDensity& operator= (const myDensity& other){
        Sigma0=other.Sigma0; rc=other.rc;
        h0=other.h0; P=other.P; S=other.S;
        return *this;
    }

    double surfaceMassDensity(const double r) const{
        return (Sigma0*pow(r/rc, -P)) * exp(-(pow(r/rc, 2-P)));
    }

    double scaleHeight(const double r) const{
        return (h0*pow(r/rc, S));
    }

    double operator()(double r, double theta, double phi) const{
        double r_cyl=r*sin(theta);
        double z=r*cos(theta);
        double h=scaleHeight(r_cyl);

        return(( (surfaceMassDensity(r_cyl))/(sqrt(2*pi)*h)) *
            exp(-z*z/(2*h*h)));
    }
};

```

This provides the basic power law disk structure described in Chapter 2 of my thesis:

$$\rho(r, z) = \frac{\Sigma(r)}{\sqrt{2\pi}h(r)} \exp\left(\frac{-z^2}{2h^2(r)}\right) \quad (2.1)$$

with

$$\Sigma(r) = \Sigma_0 \times \left( \frac{r}{r_0} \right)^{-p}, \quad (2.2)$$

and where  $\Sigma_0$  is the surface density normalization at the reference radius  $r_0$ , and  $h_d(r)$  is the dust scale height, parameterized as

$$h_d(r) = h_0 \left( \frac{r}{r_0} \right)^S \quad (2.3)$$

with  $r_0$  and  $h_0$  being the radius normalization and corresponding scale height.

This basic power law disk is included in Magrathea as a default. I'll cover all of the supplied structures in section ???. I've used several adaptations of this basic model over the years. The DSHARP based models had additional parameters describing Gaussian gaps which got subtracted out, for example.

On last note on setting up a density: The Grid constructor expects an `shared_ptr<density_base>`. These can be made using the `make_shared` function, which uses the object constructor. For example:

```
shared_ptr<myDensity> dptr=
    make_shared<myDensity>(1,100*AU,5*AU,1.0,1.25);
```

will make a shared pointer to a power law density.

### Additional Notes on User Defined Densities

For continuum modeling purposes, the only requirement on a density is that it inherit from `density_base` and provide an overloaded call operator which takes three spherical coordinates. There are two additional virtual functions which can be overloaded optionally. One `scaleHeight()`, takes a radius value and returns the scale height of the disk at that radius. This is used with an optional ray tracing feature we'll discuss in Section 2.2. There is also a `colDensityAbove()` function, which is used primarily for handling freezeout of molecules, and takes three spherical coordinates. Neither of these functions is needed for basic continuum modeling, though providing a `scaleHeight()` can be useful.

### Temperature Structures

The temperature structure operates the same way as the density. A user defined temperature inherits from `temperature_base`, and provides an identical overloaded call operator. For simple models, it is easy enough to define a parametric temperature which is similar in structure to the density above. However, for more complicated cases, it is often necessary to use a temperature model produced by an external code, such as RADMC. These must be read in from a file. The next example shows how to read in from temperature models based on the output of RADMC 3d modeling.

I say based on because this doesn't take a raw `.dat` file from RADMC.<sup>1</sup> RADMC works on a user defined grid, while the ray tracing here steps along the rays, but not in a neat gridded way. That means that to use a grid defined temperature (or density) profile, it's necessary to interpolate. To do that, I provide an interpolation surface, called `interpSurf`, which is designed to work with two dimensional RADMC output.

Internally, the `interpSurf` contains two arrays for the dimensions, i.e. a list of center points in the `r` and `theta` directions, and a large set of data. A data point consists of the spherical coordinates, and the value. The `interpSurf` class provides a constructor which takes two `std::istream`s, the grid file, and the temperature file:

```
interpSurface(std::istream& gridFile , std::istream& dataFile)
```

This assumes the input files are formatted as follows: The grid file is the standard RADMC `amr_grid.inp`, as described at [www.ita.uni-heidelberg.de/~dullemond/software/radmc-3d/manual\\_radmc3d/inputoutputfiles.html](http://www.ita.uni-heidelberg.de/~dullemond/software/radmc-3d/manual_radmc3d/inputoutputfiles.html) The temperature file is different than the basic RADMC defined output, and assumes four columns, `theta`, `phi`, `r`, and temperature. The `interpSurf` class also provides the `interp2d` function, which takes two coordinates, `r` and `theta`, and returns the value at that point:

```
double interp2d(double r , double theta)
```

Using the `interpSurf`, we can now define a simple, table based temperature, with the same interface as the density struct above:

```
struct tableTemp: public temperature_base{
    interpSurface tempSurf;
    tableTemp():tempSurf(){}
    tableTemp(const advancedTemp& other):tempSurf(other.tempSurf){}

    tableTemp(std::istream& gridFile , std::istream& dataFile):
        tempSurf(gridFile , dataFile) {}

    double operator()(double r , double theta , double phi) const{
        return(tempSurf.interp2d(r , theta));
    }
};
```

I've included these example density and temperature structures because they are simple cases of the ones that I used most frequently over the last few years. Most projects generally only needed some modifications to one or the other, such as adding gaps or a spiral to the density. The `interpSurf` class, is, unfortunately, pretty janky. If there's sufficient interest, I can expand it to handle three dimensional structures, etc.

---

<sup>1</sup>I originally wrote this to work on processed files because I needed to be able to plot them easily. If you want to work directly with the RADMC output, you can adapt the input code to do so. If not, I'll provide my code that does this formatting in the appendix

## Opacity Structures

In principle, opacities function just like temperatures and densities. Users are free to define their own, which inherit from the `opacity_base` class, and provide the correct overloaded call operators. In practice, the opacities tend to be either very simple, in the continuum case, or hideously complex, in the line emission case. Here, I mostly recommend using the ones I’ve already written.

For continuum opacity, I think most cases will simply rely on an external code. This means reading in from a file, for which I provide the `dustOpacity` struct, whose constructor requires only a string giving the path to a file. The continuum opacity is handled fairly differently from that of CO, which we’ll look at later, because I don’t think there are convenient functional approximations. Modeling dust opacity requires complicated codes, and is thus best handled by just using a table.

The formatting of the input file is the same as that used by RADMC: Two columns, wavelength in microns, and mass opacity, in  $cm^2/gm$ . For example

0.06500000	487.61199622
0.07150000	498.78685764
0.07860000	511.38581128
0.08650000	522.97715957
0.09120000	532.03370124
0.09510000	536.52678339
0.10500000	545.26333220
0.11500000	551.29091179
0.12700000	558.95778938
...	...

If you are quite determined, you can implement your own dust opacity, which inherits from the `opacity_base` class. I assume that continuum opacity is just a function of frequency, so the main function you must provide is an overloaded call operator which only takes a double. However, if you want to use this opacity in a model with AVX propagation (which I’ll discuss in Section 2.3), you will also need to provide a vectorized analogue which operates on a `Vec4d` of frequencies and returns a `Vec4d` of opacities.<sup>1</sup>

### 2.1.4 Basic Structures: The Image

Now that the Grid is set up, we can think about making images. The `image` class handles relative positions of the disk itself and the array of pixels that form the actual image. This involves, as one might guess, a lot of rather fiddly geometry, and if you break the Euler angle stuff, I’m not fixing it.

<sup>1</sup>Vectorization is done using Agner Fog’s excellent `Vectorclass` library. This provides wrappers around the basic vectorized intrinsics provided by the operating system. The `Vec4d` is a 256 bit vector which holds four doubles. It’s usually enough to define your own function that works on one frequency and then make a vectorized version that replaces the single frequency value with a `Vec4d`, but is still more advanced than the rest of what I discuss here.



The basic constructor for setting up and image is

```
image(unsigned int vpix, unsigned int hpix, double w, double h,
      std::vector<double> frequencies, astroParams& astroData);
```

The parameters are as follows: `vpix` and `hpix`, are the number of pixels, vertically and horizontally, for this image. The number of pixels is, ideally, set by the resolution of the observation you are modeling. Generally, you'd like the beam width to be something like 5 pixels. If you go much higher, you don't gain anything, since we can't resolve it. Unfortunately, for large fits, the time required for this is simply too high, so the resolution has to be reduced to save computation time. I usually ended up with images that were of order 1000 by 1000 pixels.

`w` and `h` are the width and height of the image in centimeters. It is important to remember here that the image itself has no field of view. Because the target is so far away, we are (thankfully) safe making the assumption of parallel rays. That means that you want the physical dimensions of the image to be roughly that of the target, plus some safety margins around the edge. For a disk with a major axis of 100 au, you might use a 200 au by 200 au image.

Next comes the frequency list. For continuum images, we typically just do single frequency models, but for line emission, this may be a large set. I'll discuss some of the intricacies of the frequency list when we do line emission later.

Lastly, the astronomical data. This is where we specify things like the Right Ascension, Declination, and other features that describe where the disk is and how it's oriented. The `astroParams` struct is simply a wrapper around this data with the following constructor:

```
astroParams(double RA, double Dec, double dist,
            double inc, double PA)
```

It takes the Right Ascension, Declination, distance to the target, and the inclination and position angle of the target.

Internally, the image class contains this information, and also a large array of pixels. When instantiated, this array is empty, we won't have the actual values until we call the `propagate` function, which I'll go into next.

## The Image Data

Internally, the image is just a wrapper around a large array of numbers. This is the actual data, and can be treated as a three dimensional array, the pixel values in `x` and `y`, and also the frequency. The main way this data is filled in is by using the `propagate` function, but it is there for the user to work directly with if desired.

The way to access a pixel value is through the `data` struct included in an Image class. This struct provides subscript (that's the brackets) operators so that it can be handled like C arrays. For example:

```
image.data[0][200][100]
```

will return the pixel (100,200) for the first frequency. The order is always frequency, then row, then column, so `data[f][y][x]`. Using this, you can get or set pixel values easily.

### 2.1.5 Making a Model

To actually generate an image, the image class includes the `propagate` function, with the following signature:

```
void propagate(const grid& g, typename grid::prop_type type,
               const vect& offset, ThreadPool& pool, bool avx,
               unsigned int nsteps, double contractionFactor)
```

The first argument is simply the grid that will be imaged. Next comes the propagation type, which tells the system what to include in the ray tracing. There are several types available:

```
enum prop_type {normal, continuum, attenuated_continuum,
                 subtracted_bad, subtracted_real};
```

Most cases will either be `normal`, which includes both continuum and line emission, or `continuum`, which has no line emission. The other cases are left over from my 2018 paper, and provide the various components of the temperature derivation calculations. `attenuated_continuum` does a continuum model, but includes absorption from line emission. `subtracted_bad` does improper continuum subtraction, which I complain about at great length in the paper, where `subtracted_real` handles it properly. It's unlikely that most users will need either of these last two, but they are included, just in case.

`offset` is a `vect`, a simple three vector which can be used to offset the center of the disk. If you don't want any offset, you can simply give it the vect (0,0,0).

Now, what's this `Threadpool`? The `Threadpool` is a handy piece of code written by Jakob Progsch, which I use to handle the multithreading. In the, actually quite ideal, case we have here, the different threads don't need to communicate, and there are no race conditions. We don't need anything as complicated as OpenMP or MPI, simple Unix threads will do. The `Threadpool` provides a handy system which sets up a user specified number of threads, which are used to divide up the work needed. You can set the number of threads to whatever you want, up to the maximum your system can support. An easy way to ask for that maximum, whatever it may be, is to use

```
const size_t nThreadsMax=std::thread::hardware_concurrency();
ThreadPool pool(nThreads);
```

This will initialize a `Threadpool` as large as possible.

Lastly, there are some settings for the ray tracing. `AVX` is a boolean stating whether or not to use the AVX enabled ray tracing. This is immensely useful for large models of line emission, but not generally for continuum. `nsteps` is simply the base number

of steps that each ray will take through the disk. You have a lot of leeway with the number of steps. In a perfect world, you would raise this until changing it no longer changed the results noticeably. That usually is unmanageable for most large projects, but I find that 100-300 steps usually gives results which are good enough.

And finally there's the contraction factor. This is a continuum specific bit of optimization based around the idea that the continuum emission is generally all optically thin, and therefore peaks along the disk midplane. Since we have the rare bit of information about where the emission comes from, we can do a sort of bootleg adaptive step size. The contraction factor simply shrinks the step size by the factor you specify when within 2.5 (dust) scale heights of the midplane. This way, you can have far fewer steps, but still get a reasonable result.

## 2.1.6 FITS File Handling

Astronomers often rely on FITS files to store or examine observations. Magrathea therefore provides a simple interface for handling fits files, both as inputs and outputs.

The most common case is outputting a model as a FITS file. This is done using the provided `printToFits()` function in the `Image` class, which takes a string representing the file name. `printToFits()` functions identically for single and multichannel images, with the important caveat that the basic ALMA format header assumes that channels are evenly spaced. If you do a multifrequency model with uneven channels, the output file will have an incorrect header.

This produces a FITS file, with a header generated based on the parameters of the image. The header style roughly matches that of a basic ALMA observation.

I've also provided ways of importing FITS files as images. This is designed around ALMA data, and so the files must have properly constructed headers, including all the CRPIX, CRVAL, and CDELT values. The `fitsExtract` function has two different signatures:

```
image fitsExtract(string filename , vector<double> frequencies)
```

and

```
image fitsExtract(string filename , vector<double> frequencies ,
    double distance)
```

depending on whether or not you know the distance to the source. The frequency list is not simply inferred from the header for the reason I mentioned above, it may not be regular. The distance is important because the `Image` class has a defined physical extent, but an actual observation is only in terms of angle subtended on the sky. In order to properly generate a physically meaningful image, a distance is necessary. However, you can still upload the data and work with it even without this information.

## 2.2 Continuum Models

We now have all of the basic pieces in place to make continuum models. This section will include a few examples, starting with the very basic power law disk above, and going through some more complicated ones. I'll also show a couple of cases of common pitfalls and how to avoid them.

### 2.2.1 The Power Law Disk

This is the real workhorse of the disk modeling world. The power law disk is about as simple as you can get while still remaining physically motivated. Let's write an example which sets up a power law disk and makes an image. What follows is included in the examples folder as `PowerLawDisk.cpp`, in its entirety:<sup>1</sup>

```
#include "magrathea/magrathea.h"
using namespace std;
int main(int argc, char* argv[]) {
    const size_t nThreadsMax=thread::hardware_concurrency();
    ThreadPool pool(nThreadsMax);
    astroParams diskData(246.6, -24.72, 3.18e20, pi/4, pi/4);
    shared_ptr<powerLawDisk> dptr=make_shared<powerLawDisk>
        (1, 100*AU, 5*AU, 1.0, 1.25);
    ifstream gridfile("sampleData/amr_grid.inp");
    ifstream datafile("sampleData/dust_temperature_phi0.ascii");
    shared_ptr<fileTemp> tptr=make_shared<fileTemp>
        (gridfile, datafile);
    shared_ptr<dustOpacity> doptr=make_shared<dustOpacity>
        ("sampleData/dustopac.txt");

    grid g(0.1*AU, 150*AU, 75*pi/180, 105*pi/180, 2.18*mSun,
        dptr, tptr, doptr);
    image img(500, 500, 200*AU, 200*AU, {2.30538e11}, diskData);
    vect offset(0, 0, 0);

    img.propagate(g, grid::continuum, offset, pool, false, 100, 5);
    img.printToFits("PowerLawDisk.fits");

    return 0;
}
```

That's it! Let's look closely at a few of the lines. First we set up our Threadpool, to be as large as possible. Then we make an `astroParams`, located, if I remember correctly at DoAr 25's actual coordinates. It's put at a distance of 100pc, and at an inclination and position angle of  $\pi/4$ . Then we set up the disk itself. Looking at

<sup>1</sup>With one change: I switched to using the standard namespace here so that the lines are shorter and a little clearer.

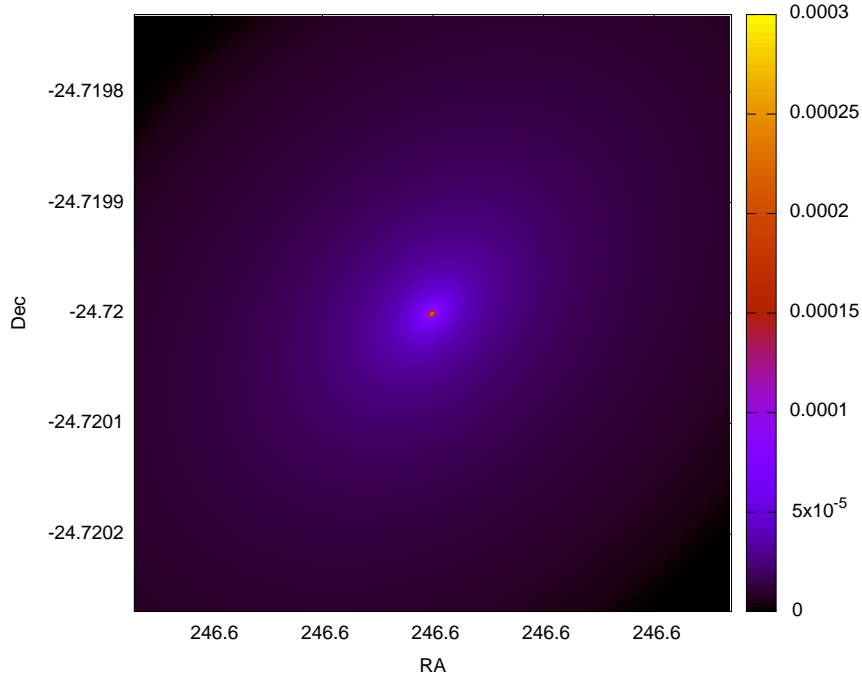


Figure 2.1: A linear scale plot of the power law disk model.

the constructor for `dptr`, we can see that the surface mass density is  $1 \text{ gm/cm}^2$ , at a reference distance of 100 au. The scale height at the reference distance is 5 au, and the power law indices are 1, radially, and 1.25 for the scale height. This is a pretty standard flared disk. The temperature is read in from a file, and then we set up the grid. The grid extends from 0.1 to 150 au, and has a  $30^\circ$  opening angle. The star has a mass of  $2.18M_\odot$ . Lastly, the image itself. The image is 500x500 pixels, and has a width and height of 200 au. We image at one frequency, 230.538 GHz. Finally, we make the image, with rays that take 100 steps each, but increased by a factor of 5 near the midplane. The resulting model is then printed to `PowerLawDisk.fits`.

You can compile this program with `clang++ PowerLawDisk.cpp -std=c++17 -lmagrathea -o PowerLawDisk`, and run it with `./PowerLawDisk`. On my laptop with 8 cores, it took 8.491 seconds to run. And the output is `PowerLawDisk.fits`, which looks like this:

There are a couple of things to note immediately about Figure 2.1. Most important are the units. Those who spend a lot of time looking at processed ALMA images may wonder about the color scale, given that this disk is located 100pc away. The important thing to remember is that there is still a very fundamental difference between this model and an ALMA image: There is no beam convolution here. Instead of the typical Janskys per beam, here we have Jy per pixel, which is typically a much smaller space than the beam size. Although the total flux is the same, to usefully compare point-by-point to an ALMA image, you will need to first convolve with a beam model. I'll discuss this at the end of the chapter.

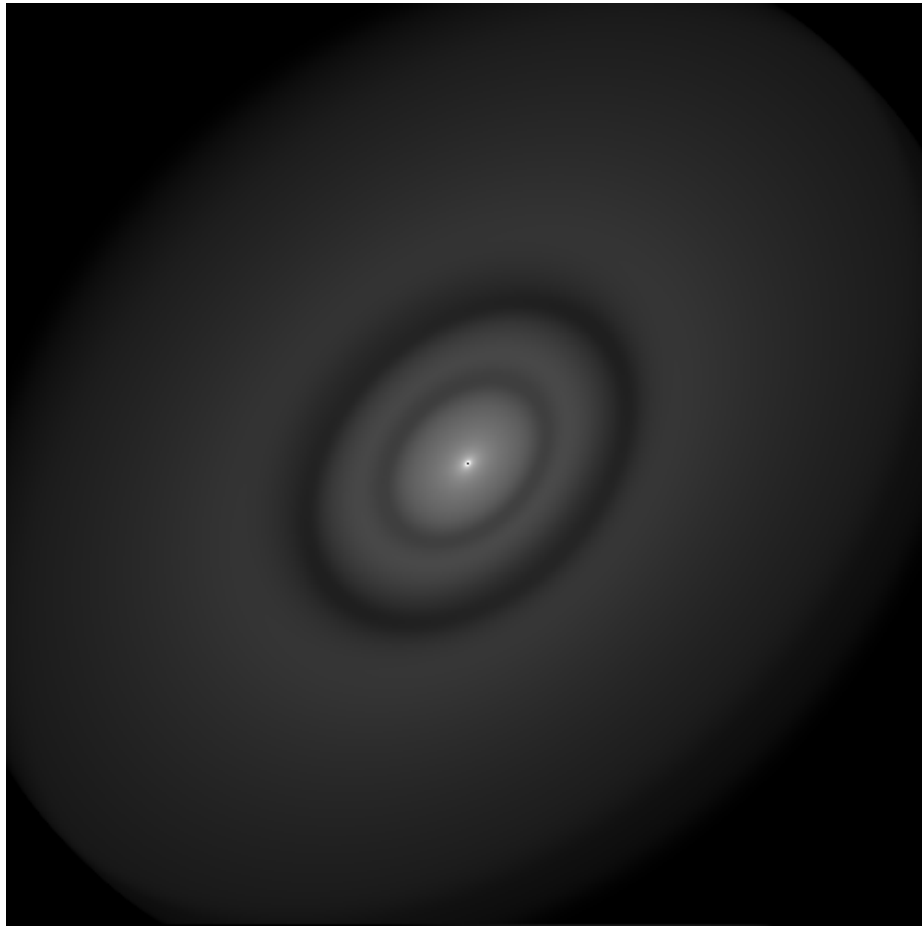


Figure 2.2: The gap disk model. I find an asinh color stretch makes these look good.

This sort of model often looks a little different from what you expect if you're only used to real observations. For one thing, there's no beam smearing, so we have resolution on the scale of the pixel size, which is usually much higher than you actually get. Sometimes this can lead to odd effects in the innermost region of the disk, where emission is much higher than anywhere else. If you convolve this with a realistic beam, that effect will largely go away. Similarly, the middlemost pixel will always go right through the inner cutoff of the grid if there's no offset, and have no emission. There is also no noise in these models, so everything will seem very smooth and perfectly symmetric. I haven't added any kind of noise, that turns out to be pretty complicated, but you can do it with CASA using the `simobserve` command.

### 2.2.2 Disk with Gaps

The basic power law disk is pretty boring to look at. In this section, I'll make a new density structure which adds gaussian gaps to the disk.

This is another common disk type, where we assume that gaps are carved out of

an otherwise ideal similarity solution disk. To do this, I tend to parameterize the gaps as azimuthally symmetric gaussians, where the parameter varied is "depth", or how much of the surface mass density is subtracted out. There isn't a whole lot of physical motivation to this model, it just happens to be a simple one which roughly fits a lot of gapped disks we observe. Since we have pretty poor understanding of the vertical structure of most disks, we tend to add these sorts of deviation by simply adjusting the surface mass density. Basically, we just change the midplane and assume that the vertical structure works as always.

Each gap needs three parameters, a central position, a depth, and a width. The surface mass density becomes

$$\tilde{\Sigma}(r) = \Sigma(r) \cdot \prod_i \left[ 1 - \Delta^i \cdot \exp\left(\frac{-(r - r^i)^2}{2\sigma^i}\right) \right], \quad (2.4)$$

where  $\Sigma(r)$  is the basic power law disk, given in Equation 2.2. Because the gaps are applied as a removal factor, they are multiplicative, rather than additive.  $r^i$  indicates the position of the center of gap  $i$ ,  $\Delta^i$  its depth, and  $\sigma^i$  its width.

Equation 2.4 is more general than we really need most of the time, so for this example, I'll implement it for two gaps. The new density structure must include all 6 new gap variables, so the constructors are messier, but otherwise it works like before.

```
#include "magrathea/magrathea.h"
using namespace std;
struct gapDisk: public density_base {
    double Sigma0;
    double rc;
    double h0;
    double P; //density index
    double S; //scale height index
    double p1, p2; //ring positions (au)
    double d1, d2; //ring depths (0 to 1)
    double w1, w2; //ring widths (au)

    gapDisk(): Sigma0(0), rc(0), h0(0), P(0), S(0),
               p1(0), p2(0), d1(0), d2(0), w1(0), w2(0){ }
    gapDisk(const gapDisk& other): Sigma0(other.Sigma0),
                                   rc(other.rc), h0(other.h0), P(other.P), S(other.S),
                                   p1(other.p1), p2(other.p2), d1(other.d1), d2(other.d2),
                                   w1(other.w1), w2(other.w2) { }
    gapDisk(double Sigma0, double rc, double h0, double P,
            double S, double p1, double p2,
            double d1, double d2, double w1, double w2):
        Sigma0(Sigma0), rc(rc), h0(h0), P(P), S(S),
        p1(p1), p2(p2), d1(d1), d2(d2), w1(w1), w2(w2){ }

    gapDisk& operator= (const gapDisk& other){
```

```

        Sigma0=other.Sigma0; rc=other.rc; h0=other.h0;
        P=other.P; S=other.S; p1=other.p1; p2=other.p2;
        d1=other.d1; d2=other.d2; w1=other.w1; w2=other.w2;
        return *this;
    }

    double surfaceMassDensity(const double r) const{
        return (Sigma0*pow(r/rc, -P)) * exp(-(pow(r/rc, 2-P)));
    }

    double scaleHeight(const double r) const{
        return (h0*pow(r/rc, S));
    }

    double operator()(double r, double theta, double phi) const{
        double r_cyl=r*sin(theta);
        double z=r*cos(theta);
        double h=scaleHeight(r_cyl);
        double gap1=(1-d1*(gaussianNotNorm(r_cyl, p1, w1)));
        double gap2=(1-d2*(gaussianNotNorm(r_cyl, p2, w2)));

        return(((surfaceMassDensity(r_cyl))/(sqrt(2*pi)*h)) *
            exp(-z*z/(2*h*h))*gap1*gap2);
    }
};

int main(int argc, char* argv[]){
    const size_t nThreadsMax=thread::hardware_concurrency();
    ThreadPool pool(nThreadsMax);
    astroParams diskData(246.6, -24.72, 3.18e18*100, pi/4, pi/4);
    shared_ptr<gapDisk> dptr=std::make_shared<gapDisk>
        (1, 100*AU, 5*AU, 0.5, 1.25, 25*AU, 50*AU, 0.8, 0.9, 5*AU, 10*AU);
    ifstream gridfile("../amr_grid.inp");
    ifstream datafile("../dust_temperature_phi0.ascii");
    shared_ptr<fileTemp> tptr=make_shared<fileTemp>
        (gridfile, datafile);
    shared_ptr<dustOpacity> doptr=make_shared<dustOpacity>
        ("../dustopac.txt");

    grid g(0.1*AU, 150*AU, 75*pi/180, 105*pi/180, 2.18*mSun,
        dptr, tptr, doptr);
    image img(500, 500, 250*AU, 250*AU, {2.30538e11}, diskData);
    vect offset(0, 0, 0);

    img.propagate(g, grid::continuum, offset, pool, false, 100, 5);
    img.printToFits("GapDisk.fits");
}

```



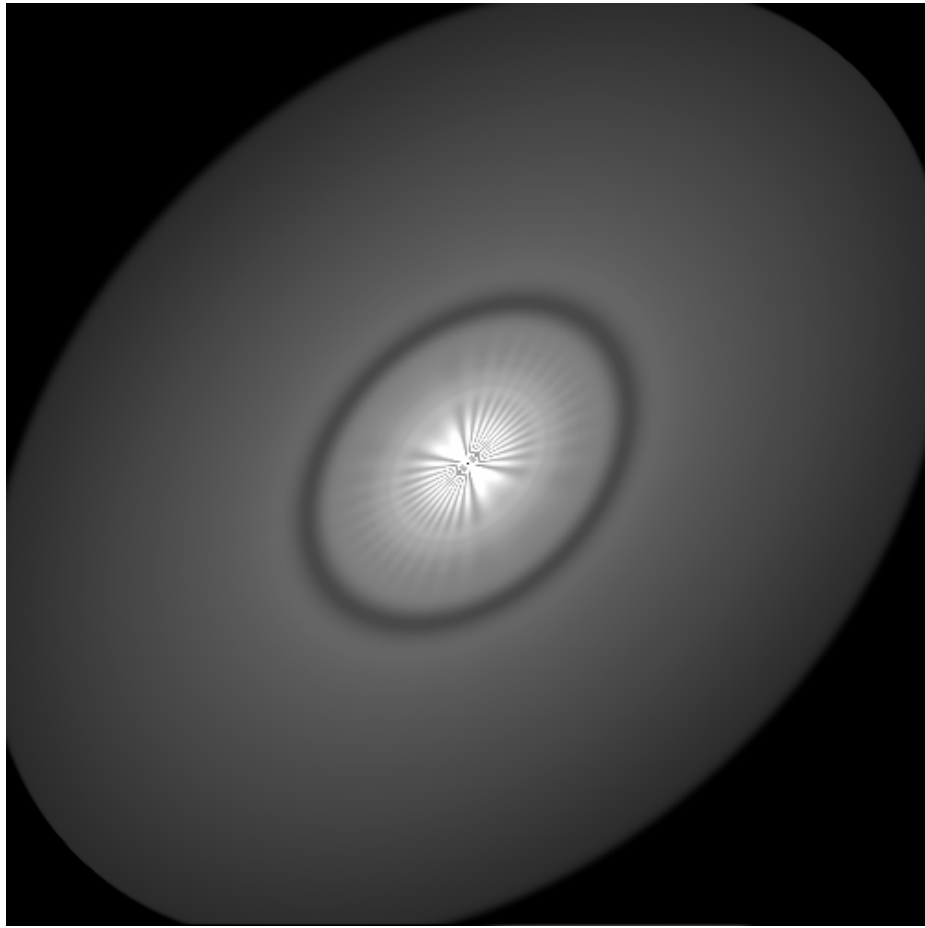


Figure 2.3: This model has too few steps for each line of sight, leading to the odd patterns in the center.

```
    return 0;  
}
```

The output, `GapDisk.fits`, is shown in Figure 2.2 I was lazy here, and didn't bother to add axes or a color bar here. On my laptop, it took 7.765 seconds to generate this image. That's faster than the last one, but there are two effects here. One is that I increased the size of the image from 200x200 au to 250x250, so more pixels entirely miss the disk. On the other hand, we're doing a lot more math each time the ray tracer needs to look up a density.

### 2.2.3 Common Problems

In this section, I'll highlight a couple of common problems I've had when making models like this. Consider this first example: This is a similar model to the gap disk we just made, with a few changes. One is that I've made the vertical structure flatter,

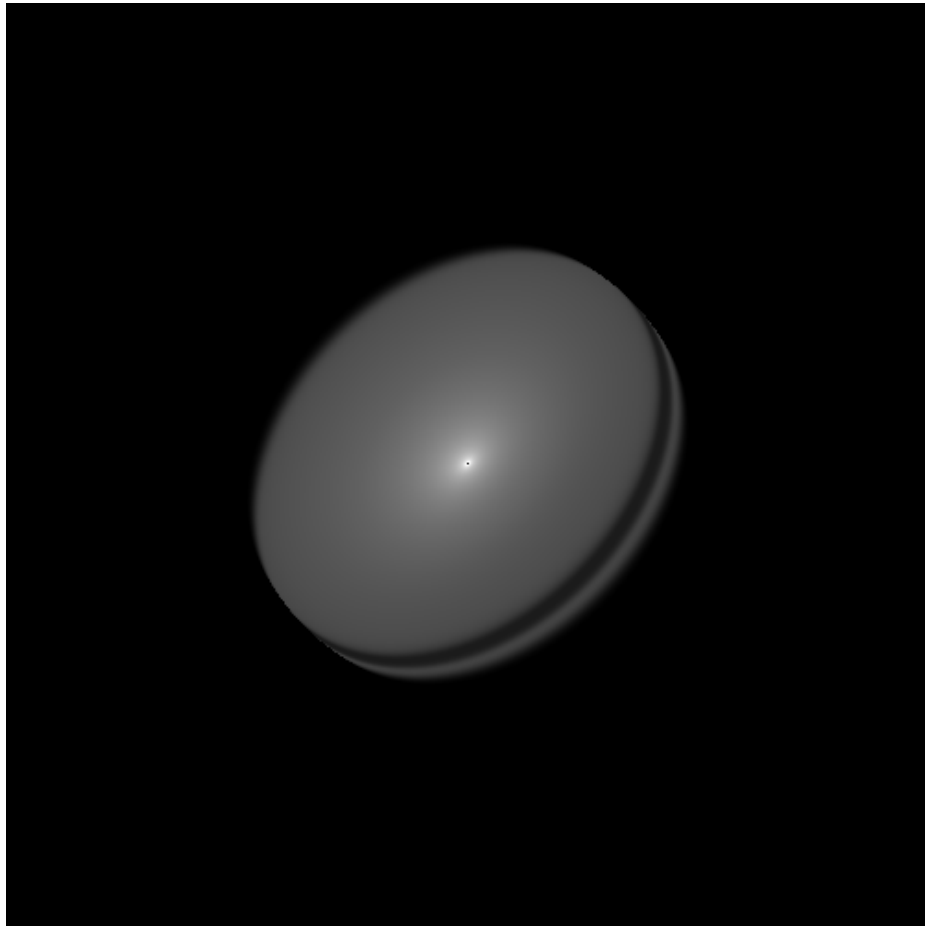


Figure 2.4: This model has been truncated at too low a radius, and we’re looking into it from the side.

by a factor of five. The other is that I’ve reduced the number of steps through the disk by half, and turned off the midplane reduction. The result is that we are now taking far too few steps through the disk to adequately sample the emission.

We know that for a continuum model like this, the emission peaks on the midplane, but with so few steps, it makes a big difference how close the center step is to the midplane. For some lines of sight, it’s right about on, and we measure a lot of emission. Some are farther off, and don’t see any. This leads to the strange and curiously artistic patterning you see in the middle. Generally, any time you make art with Magrathea, it means something has gone wrong.

Now consider Figure 2.4. This effect occurs when the outer radius of the grid is set to be too short for the density and temperature structures. In this case, the reference point for the density is at 100 au, but the grid itself terminates at 50. The vertical effect you see is us looking into the disk from the side. Basically, we’re looking at the vertical temperature structure here. If only we had disks like this in reality! Generally speaking, any time you see a disk that looks like an inverse Oreo cookie,

it's been truncated.

The continuum models tend to be much simpler, so there is less to go interestingly wrong like this. I also often make mistakes that lead to there being no emission whatsoever, which can happen in a couple of ways. First, there could simply be an error in how the camera is pointed, and any time the image is all zero, you'll get a warning which includes the camera position and pointing. This also can mean something went wrong and that either the temperature, density, or opacity is zero. You can debug this easily by simply asking for the temperature or density at a random point that you know should have nonzero values.

## 2.3 Line Emission

Line emission works exactly the same way as the continuum, it simply has more components. For one thing, there can be separate density structures for the gas and the dust, and you must also supply an opacity for the line in question. The line opacities are complicated. You can see in my thesis what goes into rotational CO opacity, or, in the really ugly case,  $\text{H}_2\text{O}$ .

The more significant change is that line emission is frequency dependent in a way that the continuum isn't. Most of the time, you will want to generate multiple frequencies at a time. This means that the output is much larger, and the running time will be much longer.

### 2.3.1 Line Opacities

There's no need to go over temperature and density structures again, because they function the same for line emission models (with the caveat that there can be separate densities for gas and for dust). However, the opacity is generally more complicated for line emission. In this section, I'll introduce the opacity structure for CO emission, as it's one of the most commonly targeted molecules with ALMA.

Rotational transitions of CO are in a bit of an odd spot. They're extremely complicated, but the line strengths can still mostly be calculated from first principles in closed form. If it was any more complicated, the opacity would have to cover only a single transition for a single isotopologue, and have the data for that from an external table. As it is, I was able to write the opacity for a general CO molecule, and the user can choose which transition and isotopologue.

The line opacity for CO is called the `COopac`, and is declared like this:

```
COopac(int lowerEnergyLevel, isotopologue_type isot)
```

The key thing to remember is that the user specifies only the lower energy level. (Again, this is made easy for me since for a diatomic molecule like this, the transitions only cover  $\Delta J = \pm 1$ . A different line would be more complicated.) The second argument is the isotopologue, of which I provide four options: `iso_12C0`, `iso_13C0`, and `iso_C18O`. This is missing some, like  $^{13}\text{C}^{18}\text{O}$ , but these are generally so rare

you'll never see much with ALMA. Choosing an isotopologue sets things like the energy levels, transition temperatures, abundance ratios, and molecular masses.

As mentioned before, the opacity calculation itself has two versions, one for a single frequency, and a vectorized one for four simultaneous frequencies. If you want to implement your own opacities, they will also need to provide vectorized versions, if you want to be able to use the faster ray tracing. For those curious about how to set up a line opacity of their own, the complete definition of the COopac, which is a little too large to include here, is available in the appendix.

### 2.3.2 Line Specific Setup

Setting up the grid and image functions mostly as it did for continuum models, but requires more inputs. First let's look at the full grid constructor:

```
grid(double rmin,double rmax,double tmin,double tmax,
    double starMass, shared_ptr<density_base> dens,
    shared_ptr<density_base> dustDens,
    shared_ptr<temperature_base> diskTemp,
    shared_ptr<opacity_base> dustOpac,
    shared_ptr<opacity_base> lineOpac,
    bool freezeout, double turb)
```

This is mostly like the continuum case, but now has an extra pointer to a separate dust density and dust opacity. In addition, there's now the option to turn on freezeout, which is currently only implemented for CO. Lastly, there is a turbulence parameter. This is a single number characterizing a uniform turbulence across the disk, parameterized as a fraction of sonic turbulence. In other words, if you set it to 1, all gas in the disk will have a turbulent velocity equal to the local sound speed. This is a very simple parameterization, but useful for simple cases. In the future, if someone wants to do a huge fit for a complicated turbulence profile, I'll probably change this so that you can point to a turbulence structure the way you do a density.

The image class doesn't change for line emission, but the way we call `propagate()` can. Let's look once again at the signature for `image::propagate()`:

```
propagate(const grid& g, typename grid::prop_type type,
    const vect& offset, ThreadPool& pool, bool avx,
    unsigned int nsteps, double contractionFactor)
```

First, the `prop_type` is no longer continuum, for most line emission you'll want `normal`. More importantly, we can now consider multifrequency models.<sup>1</sup> Recall that the image class has a vector of doubles describing the list of frequencies. It's simple enough to add multiple values to this, but some thought must be given to how best to do this.

<sup>1</sup>You can do this for continuum emission too, it's just usually not as important.

First of all, while Magrathea works perfectly well with an arbitrarily spaced set of frequencies, the FITS standard mostly does not. Given that, it's often most convenient to evenly space frequencies unless there's a specific reason not to.

More importantly, it's time to discuss the AVX ray tracing. There are two versions of `grid::propagate()`, one which is vectorized, one not, which the continuum version defaults to. The way vectorization works is by operating on larger registers. The processor implements instructions, similar to the usual adds and multiplies, but for wider registers, allowing you to effectively operate on several variables at once. Everything here uses the AVX2 instruction set, which uses 256 bit registers, which fit four doubles.

When you vectorize something like this, it's important to consider how to group the variables. You can access the individual members of a set of four, but it's expensive, and if you do it a lot, you won't gain any efficiency. So, to most effectively vectorize the ray tracing, it's split up on frequency, which requires the least elemental access, and is most internally streamlined.

This has important implications for the user. Because frequencies are bundled into groups of four, it is most efficient to make models where the number of frequencies is a multiple of four. Magrathea will pad out partially filled bundles, but this wastes computation.

Otherwise, the using the vectorized version requires no input from the user aside from setting the `avx` flag to true. There is some overhead involved with using the larger vector instructions. Using the quadruple width provided by the AVX2 instruction set doesn't get a full factor of four in efficiency. I tend to see something like a factor of two in speed, but with some important caveats we'll discuss below.

### 2.3.3 The Power Law Disk in CO

Let's look at an example of line emission in a model. For this example, I'm going to go back to the power law disk from Section 2.2.1, but this time add a gas structure and look at the line emission. Instead of a single frequency, this time we'll look at multiple.

```
#include "magrathea/magrathea.h"
int main(int argc, char* argv[]) {
    const size_t nThreadsMax=thread::hardware_concurrency();
    ThreadPool pool(nThreadsMax);
    astroParams diskData(246.6, -24.72, 3.18e18*100, pi/4, pi/4);
    shared_ptr<powerLawDisk> dptr=make_shared<powerLawDisk>
        (1, 100*AU, 1*AU, 0.5, 0.5);
    shared_ptr<powerLawDisk> gptr=make_shared<powerLawDisk>
        (14, 100*AU, 5*AU, 1.0, 1.25);
    ifstream gridfile("data/amr_grid.inp");
    ifstream datafile("data/dust_temperature_phi0.ascii");
    shared_ptr<fileTemp> tptr=make_shared<fileTemp>
        (gridfile, datafile);
```

```

shared_ptr<dustOpacity> doptr=make_shared<dustOpacity>
    ("data/dustopac.txt");
shared_ptr<COopac> goptr=make_shared<COopac>
    (1,COopac::iso_12CO);

grid g(0.1*AU,150*AU,75*pi/180,105*pi/180, 2.18*mSun,
    gptr, dptr, tptr, doptr, goptr, false, 0);
//set up the frequency
//center around the 12CO 2-1 line, with 50KHz spacing
unsigned int nfreqs=20;
double freqRange=2e7; //1MHz
double freqStep=freqRange/nfreqs;
std::vector<double> frequencies;
for(int i=0;i<nfreqs;i++){
    double freq=2.30538e11+freqStep*i-freqRange/2.0;
    frequencies.push_back(freq);
}
image img(2000, 2000,250*AU, 250*AU, frequencies, diskData);
vect offset(0,0,0);

img.propagate(g, grid::normal, offset, pool, true, 100, 5);
img.printToFits("PowerLawDiskCO.fits");

return 0;
}

```

So what's different between this example and the one in Section 2.2.1? First of all, we need to set up additional structures for the disk, a CO structure and opacity. If you're curious, the normalizations for the dust and CO are chosen to give a disk dust mass of about  $5 \times 10^{-3} M_{\odot}$ , and a gas mass of  $10^{-1} M_{\odot}$ . Most of the additional code has to do with setting up the frequency list. In this case, I've chosen 20 frequencies, spaced around the  $^{12}\text{CO}$  J=3-2 line, with a spacing of 1MHz. That nicely captures the full spectral extent of the line. Lastly, we image the disk, with both gas and dust, and vectorization on. This is a much larger model than we did before, and on my laptop took 112.76 seconds.

The output is shown in Figure 2.5. This is a pretty good example of "regular" line emission, with all its complicated morphology. Here also, with our technically infinite resolution, we see the vertical structure of the disk in the CO emission. This is usually only visible in the most flared and best resolved disks.

There are a couple of things to note about this model. One is the time taken. This model is twice the resolution of the first continuum model, and has 20 channels. One might naively expect it therefore to take 80 times as long, which would be 11 and a half minutes. We get much better performance than that, however, for a couple of reasons. One is that some of the work of ray tracing doesn't need to be repeated for different frequencies. The positions of each step, for example, depend only on

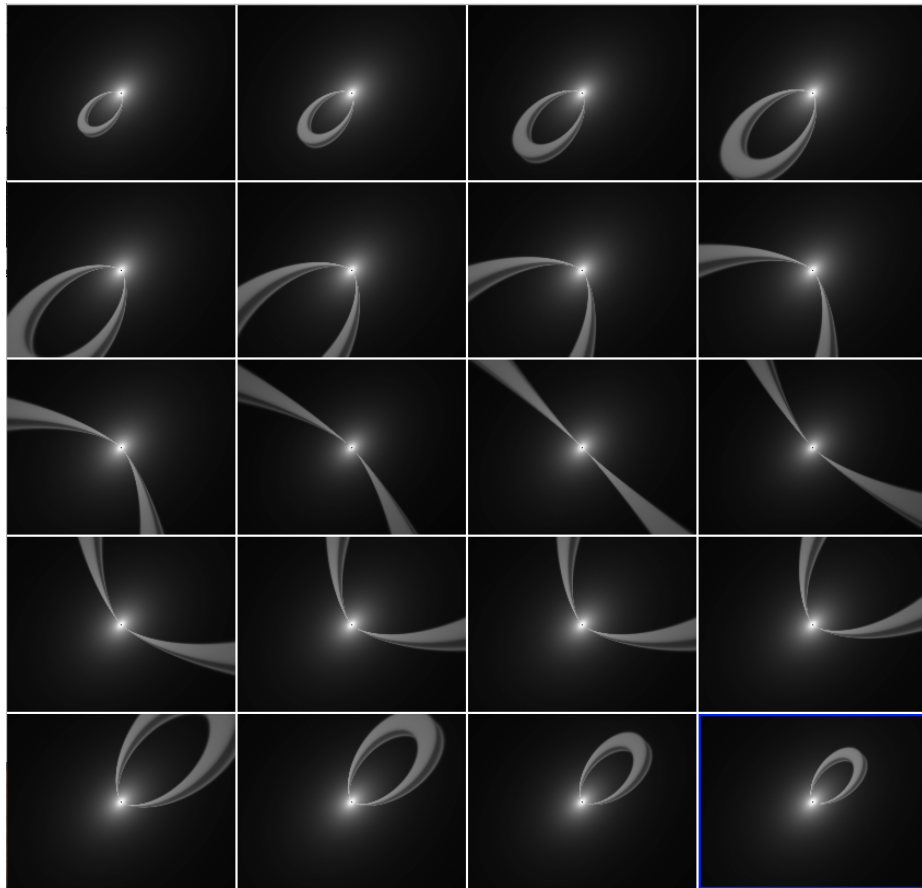


Figure 2.5: The power law disk model, this time with CO. Line center is the 11th panel.

geometry. This gives better returns on larger models. The other thing is that much of the time in the continuum case is spent on set up work: reading input files and the like. This also doesn't need to be repeated. When setting up systems that will run multiple models, it's important to do it in a way that doesn't need to reread inputs files when not necessary, as the overhead is nontrivial.

Another thing to mention here is that we could probably have turned down the midplane contraction factor. The CO emission is generally optically thick, but doesn't peak at the midplane, so unless we care specifically about the dust here, we aren't gaining that much. Because  $^{12}\text{CO}$  emission is typically very optically thick, the emission peaks rapidly, but at some unknown altitude. This, unfortunately, means that we often need to take many more steps for line emission models, which slows things down considerably. The high opacity of CO also means that the radial extent of the CO emission is much higher. If you zoom out on the fits file, you'll see that the CO is actually clipping at the edge of the disk boundary. So, in addition to needing more steps through the disk, we also need to make the disk itself larger.

One last thing, perhaps the most important. Each frame in Figure 2.5 is an image

at one exact frequency. This is not how the telescope actually works! The actual telescope has a defined band width, and the emission in each channel is an average over that band.

That means, that to more accurately model ALMA emission, we would need to oversample each frame, and average them down. For the case here, the frames are quite widely spaced, I would guess we would need to oversample by something like 4 to 8 to get a more reasonable average. You are probably beginning to see why modeling line emission is so much more costly than continuum.

## Notes on Vectorization

As I mentioned before, switching on the AVX ray tracing can be very useful, and can sometimes even double the speed. However, it's not always as powerful as that example, and sometimes adds very little. This is one of those cases. Tested on my laptop, switching the AVX mode off resulted in a time of 132.6 seconds. Slower, but not be a significant amount.

Part of the reason is that I'm doing all this on a laptop. Laptops are not known for their amazing cooling capacity, and seem to be quite limited when you really run the processor flat out. This gives an advantage to the non-vectorized version.

The choice of compiler matters here too. Using the Apple Clang version provided with the operating system (version 12.0.0), the code is actually 8 times slower! Near as I can tell, this is an actual but with that clang version. Using a newer GCC version gives the results above. If you get absolutely terrible results from turning on the AVX code, this is probably why.

So when do you want AVX on? My general advice is that it's most useful for very large projects. If you're running a large fit, or a gigantic single model on a server, you'll benefit a fair amount. For something like this example, it won't hurt but won't make a big difference.



When working with interferometers, everything is actually the Fourier Transform of what you want. The data we work with is actually a set of points in Fourier space. However, the imaging described in Chapter 2 is all done in real space.

To help with this, Magrathea provides a way to take a model and compute its Fourier Transform, as well as taking Fourier images and backtransform them. This is useful for two main purposes: fitting to real data, where one must interpolate uv points onto the transform of a model, and for beam convolution. This chapter will describe how to work with Fourier Transforms in Magrathea, as well as how to convolve an image with a simulated beam.

Things like beam convolution can, of course, be done with CASA as well. Using CASA's `simobserve()` command, you can also add realistic noise, which is something that Magrathea can't do. However, it's also nice to be able to quickly do a beam convolution without needing an external program to do it, so I provide the functionality here.

## 3.1 Fourier Transforms and Back Transforms

Fourier transforms are generally made based off of a provided image. In many ways, they simply are a special kind of image, with a few key differences. First of all, the `image` class contains information about the observation it is simulating, such as its sky coordinates, and distance. The `image` class also has a physical extent.

The Fourier Transform of an image does not exist on the sky, and doesn't need any of these things. It's "extent" is from -1 to 1, in the uv plane. More significant is the fact that the Fourier transform (generally) has a real and an imaginary part, where a regular image doesn't (the sky, after all, is real). So where an image is a grid of  $n$  by  $m$  pixels, its transform is two such grids.

Magrathea uses FFTW to do all of the Fast Fourier Transforms. FFTW is a C library which provides extremely fast discrete FFTs, and can be found at <http://fftw.org>.

### 3.1.1 The `fourierImage` Class

Just like how the model images are stored and managed by the `image` class, their Fourier Transforms are handled by the `fourierImage` class. As discussed above, this is essentially a stripped down image with an extra internal array for the imaginary component of the FFT.<sup>1</sup> In the `image` class, you can directly access the pixels through the `data` struct. For example:

```
image im(/*parameters*/);
im.data[0][100][200]=5;
```

sets the pixel 200,100 to 5 for the first frequency. You can do the same thing with a `fourierImage`, but instead of accessing `data`, the real and imaginary parts are stored in, you guessed it, `RealPart` and `ImaginaryPart`.

Unlike with the basic `image` class, you'll probably never need to set one up from its constructors. Instead, the main way users will generate `fourierImages` is by calling the `FFT()` function, which has the signature

```
fourierImage FFT(const image& im)
```

That's all you need to do! Hand it the image, get the FFT back. There is an additional version of this for the case where you want to use multithreading to speed up the FFT of a multichannel image:

```
fourierImage FFTmultiThread(const image& im, ThreadPool& pool)
```

which takes a `ThreadPool` as well. The multithreading is split on frequencies, so if you give the `ThreadPool` more threads than the image has channels, it won't do anything.

#### Comments

The internals of the FFT system get... ugly. FFTW is a C library and does little to hold your hand. This means a fair amount of index twiddling and fiddly programming. I've caught several bugs in the FFT stuff in the past, but I wouldn't be surprised if there are more subtle edge cases waiting to be found.

One other thing: Because the sky is real, the real and imaginary parts of the FFT are symmetric. You can use this symmetry to store both the real and imaginary parts of the FFT of an  $n$  by  $n$  image in an output array of size  $n$  by  $n+1$ . I've never yet gotten this to actually work, and have yet to find the strength of character to implement it. This means some loss of efficiency, but not a significant one. Compared to the time required to do the ray tracing that makes a model, the FFT is extremely quick.

---

<sup>1</sup>Actually, I do internally give the `fourierImage` things like width, height, and distance, but only so you can make an image from a back transform and have all the correct data still be present.

## Padding

One issue with discrete FFTs is that they can produce odd behavior if the image extends too close to the edges. I find that this isn't usually a huge issue for me, as most real observations have a much wider field of view than the extent of the target, and so the models I set up do too. However, if you want to quickly pad an image with zeroes, there is a function in the `image` class for this purpose:

```
image pad(unsigned int padNum)
```

which takes a number of pixels that will be the padding width around the image, and returns a new, larger image.

### 3.1.2 Back Transforms

We now have the ability to generate the FFT of a model. For some tasks, such as comparison to ALMA data, that's often all we need. However, some things, such as beam smoothing, are usually done assuming that you'll transform back.

The primary means of turning a `fourierImage` back into an `image` is the `backTransform` function:

```
image backTransform(const fourierImage& im)
```

This works by calculating the FFT of the FFT, to get back to an image. The resulting image is the real part of the final FFT. The imaginary part, which should be nothing more than numerical noise, is tossed out.

There is another version of the `backTransform` function, which is useful mainly for testing purposes, but which I've chosen to leave in, just in case:

```
fourierImage backTransform(const image& realInput ,  
                           const image& imaginaryInput)
```

The reason this takes two images as inputs is because sometimes you have the Fourier Transforms as external files, like FITS files. This way, you can read them in with the `fitsExtract` function, and transform them back. The output here is a `fourierImage`, because for the test case, I leave the imaginary part in.

Another test feature which I'm leaving in is printing FFTs to FITS files. Occasionally, you need to look at the FFT of something, so the `fourierImage` class contains a `printToFits` function just like regular images. The signature is

```
void printToFits(std::string outFileName)
```

This will output two FITS files, with the real part in `[outFileName]FFTReal.fits`, and the imaginary part in `[outFileName]FFTIm.fits`.

## 3.2 The Beam Class

As I’ve mentioned before, one of the primary uses of the Fourier Transform in this context is beam smoothing. Magrathea provides an easy way to do this so you can get a quick estimate of what an image will look like with a given resolution. The `Beam` class is designed to help with this.

Beam convolution is done via pointwise multiplication of the FFTs of the model and the beam. Here I make the assumption that the beam is a Gaussian, which is generally reasonable for ALMA observations. This is convenient because the Fourier Transform of a Gaussian is just a Gaussian, and we can compute everything analytically.

The `Beam` class, therefore, has three two dimensional arrays: One for the image plane beam, and two for its Fourier Transform components. The beam also has a width and a height. In other words, the `Beam` class is basically another special class of image.

The primary way one sets up a beam is with the special constructor:

```
beam(const image& im, double bmaj, double bmin, double PA)
```

where `bmaj` and `bmin` are the major and minor axes of the beam, and `PA` the beam’s position angle. Why does this constructor also take a reference to an image, though? The reason is that I’m assuming that you generally want to set up a beam to convolve with a given model. Since that requires pointwise multiplication of the Fourier Transforms, we need the beam’s internal data to be the same dimensions of the image in question. This way, you set up a beam that corresponds to your model, and the constructor will generate the Fourier Transform as well.

A quick note on the units here: Because I wrote this all to work with ALMA data, the major and minor axes are measured in arcseconds, the way the beam for a real observation is measured. The position angle is in radians.

Rather than have a specific example just for the beam, since I assume everyone reading this knows what a Gaussian looks like, I’ll include a demonstration of beam convolution in the next section.

## 3.3 Examples

In the previous chapters, I’ve provided small examples for how to set up the various modeling features. In this section, we’ll look at a somewhat larger example. Suppose we’d like a more realistic model of the line emission from Section 2.3.3. If we wanted to have some idea of what we would see were this a real ALMA observation, we’ll need to do beam convolution. However, recall that each channel of the previous example is at a single frequency. A more realistic model ought to oversample in frequency space, and then average down the channels based on the bandwidth.

The following code is included as `Fourier.cpp` in the examples folder. In this case, we’ll image a disk like the one in Section 2.3.3, but at many more frequencies.

We'll then average it down, and do beam smearing.

```
#include "magrathea/magrathea.h"

int main(int argc, char* argv[]){
    const size_t nThreadsMax=thread::hardware_concurrency();
    ThreadPool pool(nThreadsMax);
    astroParams diskData(246.6, -24.72, 3.18e18*100, pi/4, pi/4);
    shared_ptr<powerLawDisk> dptr=make_shared<powerLawDisk>
        (0.01, 100*AU, 1*AU, 0.5, 0.5);
    shared_ptr<powerLawDisk> gptr=make_shared<powerLawDisk>
        (14, 100*AU, 5*AU, 1.0, 1.25);
    ifstream gridfile("data/amr_grid.inp");
    ifstream datafile("data/dust_temperature_phi0.ascii");
    shared_ptr<fileTemp> tptr=make_shared<fileTemp>
        (gridfile, datafile);
    shared_ptr<dustOpacity> doptr=make_shared<dustOpacity>
        ("data/dustopac.txt");
    shared_ptr<COopac> goptr=make_shared<COopac>
        (1, COopac::iso_12CO);

    grid g(0.1*AU, 150*AU, 75*pi/180, 105*pi/180, 2.18*mSun,
        gptr, dptr, tptr, doptr, goptr, false, 0);
    //set up the frequency
    unsigned int nfreqs=240;
    double freqRange=2e7; //10MHz
    double freqStep=freqRange/nfreqs;
    std::vector<double> frequenciesBig;
    std::vector<double> frequenciesSmall;
    std::cout.precision(10);
    for(int i=0; i<nfreqs; i++){
        double freq=2.30538e11+freqStep*i-freqRange/2.0;
        frequenciesBig.push_back(freq);
        if(!((i-10)%20)) frequenciesSmall.push_back(freq);
    }
    image img(500, 500, 250*AU, 250*AU, frequenciesBig, diskData);
    vect offset(0,0,0);

    img.propagate(g, grid::normal, offset, pool, true, 100, 5);

    std::cout << "averaging" << std::endl;
    image imgAvg(500, 500, 250*AU, 250*AU,
        frequenciesSmall, diskData);
    for(int f=0; f<frequenciesSmall.size(); f++){
        for(int i=0; i<img.vpix; i++){
            for(int j=0; j<img.hpix; j++){
```

```

        //first we average the values in the full image
        double value=0;
        for(int subF=0;subF<20;subF++){
            value+=img.data[f*20+subF][i][j];
        }
        value/=20;
        //then add to the final image
        imgAvg.data[f][i][j]=value;
    }
}
imgAvg.printToFits("FourierDisk.fits");
//calculate the FFT
fourierImage FFTs=FFT(imgAvg);

//now we do the beam smoothing
beam bm(imgAvg, 0.030,0.020,pi/4);
for(int f=0;f<frequenciesSmall.size();f++){
    for(int i=0;i<img.vpix;i++){
        for(int j=0;j<img.hpix;j++){
            FFTs.realPart[f][i][j]*=bm.realPart[i][j];
            FFTs.imaginaryPart[f][i][j]*=bm.realPart[i][j];
        }
    }
}
//now transform back
image final=backTransform(FFTs);

final.printToFits("FourierDisk.fits");

return 0;
}

```

This example takes longer than the previous ones because we are now modeling so many more frequencies. On my laptop, this takes 41.1 seconds. The output, `FourierDisk.fits`, is shown in Figure 3.1.

The biggest difference from before is that each channel is now an average over 20 frequencies. Because the total frequency spanned by this model is fairly broad, to get a good coverage of each of the 12 final channels, we need a pretty high oversampling factor. If you have a model with higher spectral resolution, you won't need as high a factor because each channel is narrower.

For this model, I've chosen a 20x30mas beam. That's reasonably high resolution for ALMA. This disk is also only 100 pc away, but you can really see how the beam smearing affects it. Given the size of the beam in this case, we probably could have turned down the spatial resolution of the observation some.

There's a couple of other things to note here as well. First, if you look at the output

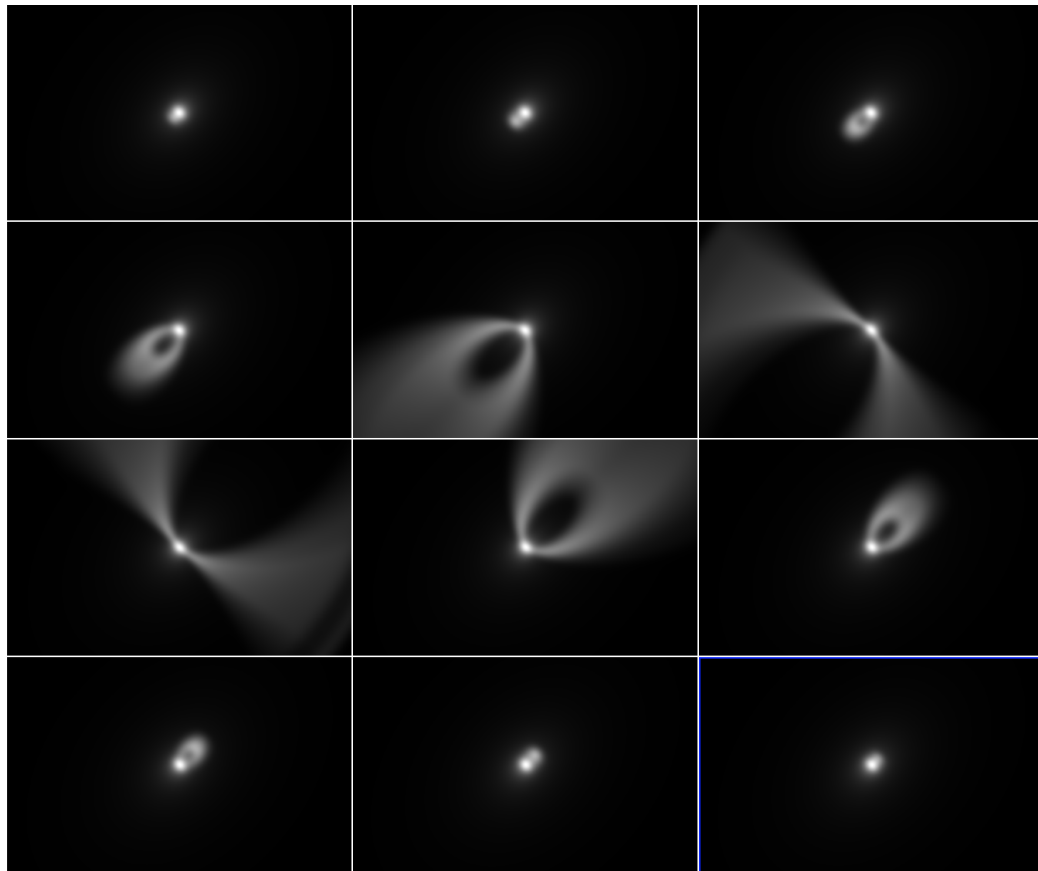


Figure 3.1: The same power law disk as before, with CO emission. This time, each channel is an average over 20 frequencies, and the output is smoothed with a 20x30mas beam.

file, the units will seem very different from the previous model. This is because, having done beam convolution, each pixel is multiplied by the beam size. If you want Jy/bm, we would need to divide each pixel by the size of the beam.

Lastly, look carefully at how the beam convolution is done in the code snippet there. Notice that the imaginary part of the FFT is multiplied pointwise with the real part of the beam. This seems wrong to me, yet gives the correct answer. I'll try to figure this out at some point in the future.





## APPENDIX A

# Line Opacity

---

The primary purpose of this appendix is to provide the code for the main CO opacity object as an example for those who wish to implement their own line opacities. The CO opacity is quite long and complicated compared to most of the other code snippets included, which is why I've moved it to an appendix. The definition is as follows:

```
//Opacity of CO. See Isella et al 2007
//The calculation of the partition function is based on a
//Taylor expansion. For details, see Mangum and Shirley 2015.
struct COopac:public opacity_base {
    double COFraction, dipoleMoment, COMass,B;
    double densityRatio; //ratio of chosen isotopologue to 12CO
    int lowerEnergyLevel;
    double* transitionTemps;
    double* restFrequencies;
    double* einsteinAs;
    enum isotopologue_type{iso_12CO, iso_13CO, iso_C17O, iso_C18O};
    isotopologue_type isot;

    COopac(int lowerEnergyLevel, isotopologue_type isot) :
        lowerEnergyLevel(lowerEnergyLevel){
            setTransitionTemps(isot);
            COFraction = 1e-5; //ratio of 12CO to H2
            COFraction *= 14; //convert density ratio to number ratio
            dipoleMoment = 1.1e-19; //dipole moment of CO
            B=5.763596e+10; //Hz. Rigid rotor rotation constant for CO
        }

    COopac(){
        setTransitionTemps(iso_12CO);
        lowerEnergyLevel = 0;
        COFraction = 1e-5; //density ratio of CO to H2
        COFraction *= 14; //convert density ratio to number ratio
        dipoleMoment = 1.12e-19; //dipole moment of CO
```

```

    B=5.763596e+10; //Hz. Rigid rotor rotation constant for CO
}

double operator()(double temperature, double frequency,
    double vTurb, bool freezeout) const{
    double freezeOutFactor=1;
    if(freezeout){
        if(temperature < 30)
            freezeOutFactor=temperature/20.0-0.5;
        if(temperature < 10)
            return 0;
    }
    double nu0=restFrequencies[lowerEnergyLevel];
    double partitionFunction = (kboltzmann*temperature)/(h*B) +
        1.0/3.0 + (h*B)/(15.0*kboltzmann*temperature)
        +4.0/315.0 *(h*B)*(h*B)/(kboltzmann*temperature)/
        (kboltzmann*temperature);
    double boltzFactor= multiplicity(lowerEnergyLevel)*
        exp(-energy(lowerEnergyLevel)/
        (kboltzmann*temperature))/partitionFunction;
    double deltaV=sqrt(2*kboltzmann*temperature/COMass +
        vTurb*vTurb);
    double deltaNu= c/nu0 * (frequency - nu0);
    double profile= c/(nu0*sqrt(pi)*deltaV)*
        exp(-deltaNu*deltaNu/deltaV/deltaV);
    double einsteinA=einsteinAs[lowerEnergyLevel];
    double opacity=c*c/(8*pi*nu0*nu0);
    opacity*=multiplicity(lowerEnergyLevel+1)/
        multiplicity(lowerEnergyLevel);
    opacity*=einsteinA;
    opacity*=profile;
    opacity*=boltzFactor;
    opacity*=(1-exp(-h*nu0/(kboltzmann*temperature)));

    //the integrator works with the mass density,
    //we need to convert to number density here
    opacity*=(COFraction*densityRatio/COMass);

    return opacity*freezeOutFactor;
}

//AVX version
Vec4d operator()(double temperature, Vec4d frequency,
    double vTurb, bool freezeout) const{
    double freezeOutFactor=1;
    if(freezeout){

```

---

```

        if(temperature < 30)
            freezeOutFactor=temperature/20.0-0.5;
        if(temperature < 10)
            return 0;
    }
    double nu0=restFrequencies[lowerEnergyLevel];
    double partitionFunction = (kboltzmann*temperature)/(h*B) +
        1.0/3.0 + (h*B)/(15.0*kboltzmann*temperature)
        +4.0/315.0 *(h*B)*(h*B)/(kboltzmann*temperature)/
        (kboltzmann*temperature);
    double boltzFactor= multiplicity(lowerEnergyLevel)*
        exp(-energy(lowerEnergyLevel)/
        (kboltzmann*temperature))/partitionFunction;
    double deltaV=sqrt(2*kboltzmann*temperature/COMass +
        vTurb*vTurb);

    Vec4d deltaNu= (frequency - nu0) * c/nu0;
    Vec4d profile= c/(nu0*sqrt(pi)*deltaV)*
        exp(-deltaNu*deltaNu/deltaV/deltaV);
    double einsteinA=einsteinAs[lowerEnergyLevel];
    Vec4d opacity=c*c/(8*pi*nu0*nu0);
    opacity*=multiplicity(lowerEnergyLevel+1)/
        multiplicity(lowerEnergyLevel);
    opacity*=einsteinA;
    opacity*=profile;
    opacity*=boltzFactor;
    opacity*=(1-exp(-h*nu0/(kboltzmann*temperature)));

    opacity*=(COFraction*densityRatio/COMass);

    return opacity*freezeOutFactor;
}

double multiplicity(int level) const {
    return 2*level+1;
}

double energy(int level) const{
    double T1=transitionTemps[0];
    return 0.5*kboltzmann*level*(level+1)*T1;
}

//Transition temperatures, energies, and
//frequencies come from the LAMDA database
//http://home.strw.leidenuniv.nl/~moldata/CO.html
void setTransitionTemps(isotopologue_type isot){

```

```

    switch (isot){
        case iso_12CO:
            densityRatio=1;
            transitionTemps = transitionTemps_12CO;
            restFrequencies=transitionFreqs_12CO;
            einsteinAs=einsteinA_12CO;
            COmass=28*amu;
            break;
        case iso_13CO:
            densityRatio=(1.0/70.0);
            transitionTemps = transitionTemps_13CO;
            restFrequencies = transitionFreqs_13CO;
            einsteinAs=einsteinA_13CO;
            COmass=29*amu;
            break;
        case iso_C17O:
            //I'll add the numbers when I have to.
            std::cout << "This CO isotopologue isn't in yet.
                Add the numbers" << std::endl;
            exit(1);
            break;
        case iso_C18O:
            densityRatio=(1.0/500.0);
            transitionTemps = transitionTemps_C18O;
            restFrequencies = transitionFreqs_C18O;
            einsteinAs=einsteinA_C18O;
            COmass=30*amu;
            break;
    }
}

//Disassociation of CO, following C. Qi et al 2011, and
//Rosenfeld 2013. It gets smoothly decreased over an
//order of magnitude around 10^21
double disassociationFactor(double colDensAbove) const{
    double factor;
    if(colDensAbove <= 5e20){
        factor=0;
    }else if(colDensAbove <= 1.5e21){
        factor=(colDensAbove-5e20)/(1e21);
    }else{
        factor=1;
    }
    return factor;
}
};

```

---

So there's a lot of code. Note that I'm choosing not to include the several pages of tables that go along with this.

The CO opacity structure here is doing a fair amount. It handles any rotational transition (up to  $J=40$ , where the tables end), and multiple isotopologues. As you can see, I never ended up using  $C^{17}O$ . This structure could be adapted to any diatomic molecule with a nonzero dipole moment.

Luckily, for more complicated lines, the code is actually simpler. There's little point in trying to write a general structure like this for a larger molecule, you'd be better off simply looking up the line strengths and using those.

So what does this struct do? In order to calculate the opacity, we need several physical parameters, which differ based on isotopologue. The primary constructor takes the lower energy level and the isotopologue, and chooses the correct values based on these from the tables. We do this in the constructor so that it doesn't have to be repeated each time we need an opacity. The core is in the two overloaded call operators, which take a frequency and temperature and then calculate the opacity based off of the long derivation you can find in my thesis. The difference is that the base version takes a single frequency and temperature, while the vectorized version takes 4 of each and returns 4 opacities.

It's also useful to look at the CO opacity, because it shows how one can incorporate a variety of additional physics into the ray tracing. The call operators, in addition to calculating the opacity, also are where I handle the freeze out of CO onto dust grains. In principle, this works by reducing the density, but in order to keep it as part of the CO, I apply it as a reduction factor on the opacity. I'm not completely happy with this choice, but it avoids needing to add more inputs into the grid.

Similarly, this is where we calculate disassociation by high energy UV radiation. Were you wondering why the opacity base class provides a virtual function for the column density above a point? It's for the photodisassociation. This is where you would add any additional physics which is specific to the particular line in question.