



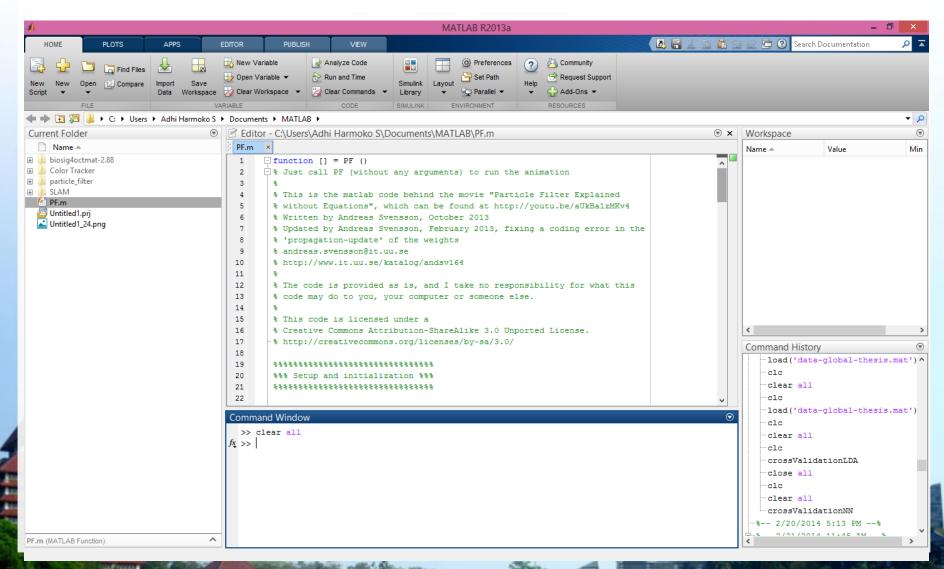
Adhi Harmoko Saputro





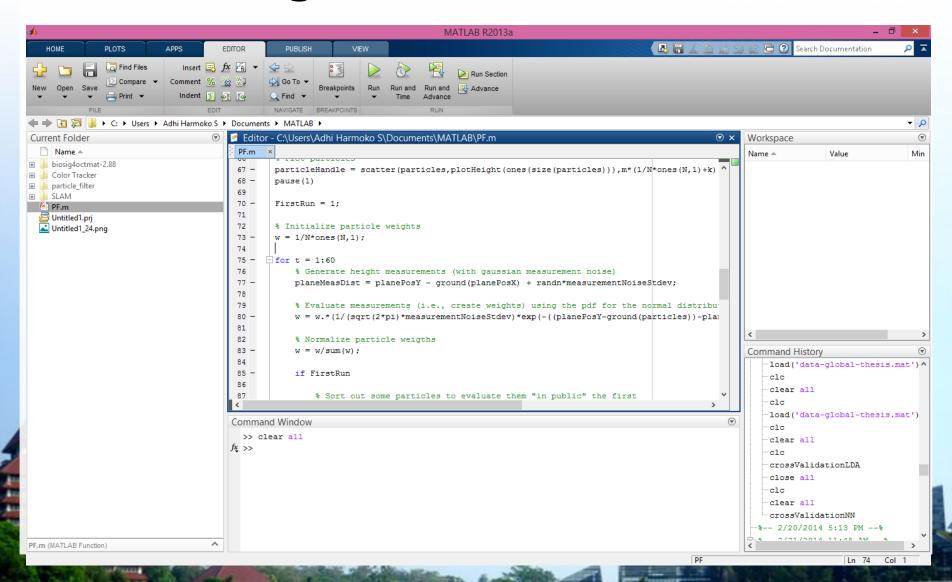


Navigating the Matlab Desktop



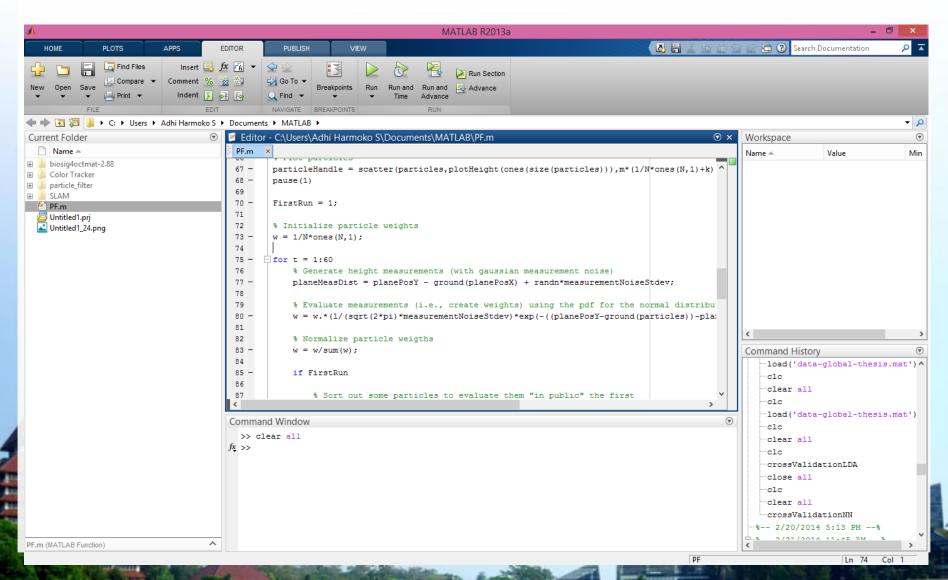


Editor Navigation





Plotting Navigation





Numbers

- MATLAB is a high-precision numerical engine and can handle all types of numbers, that is, integers, real numbers, complex numbers, among others, with relative ease.
- For example, the real number 1.23 is represented as simply 1.23 while the real number 4.56×10^7 can be written as $4.56e^7$.
- The imaginary number $\sqrt{-1}$ is denoted either by 1i or 1j, although in this book we will use the symbol 1j.
- Hence the complex number whose real part is 5 and whose imaginary part is 3 will be written as 5+1j*3.
- Other constants preassigned by MATLAB are pi for π , inf for ∞ , and NaN for not a number (for example, 0/0).
- These preassigned constants are very important and, to avoid confusion, should not be redefined by users.



Variables

- The basic variable is a matrix, or an array.
- MATLAB now supports multidimensional arrays
 - Matrix: A matrix is a two-dimensional set of numbers arranged in rows and columns. Numbers can be real- or complex-valued.
 - **Array:** This is another name for matrix. However, operations on arrays are treated differently from those on matrices. This difference is very important in implementation.

- Matlab works with essentially only one kind of object, a rectangular numerical matrix
- A matrix is a collection of numerical values that are organized into a specific configuration of rows and columns.
- The number of rows and columns can be any number

Example

• 3 rows and 4 columns define a 3 x 4 matrix having 12 elements

• Scalar: This is a 1×1 matrix or a single number that is denoted by the *variable* symbol, that is, lowercase italic typeface like

$$a = a_{11}$$

- Column vector: This is an $(N \times 1)$ matrix or a vertical arrangement of numbers.
- It is denoted by the *vector* symbol, that is, lowercase bold typeface like

$$\mathbf{x} = \begin{bmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{N1} \end{bmatrix}$$

• A typical vector in linear algebra is denoted by the column vector

- Row vector: This is a $(1 \times M)$ matrix or a horizontal arrangement of numbers.
- It is also denoted by the vector symbol, that is,

$$\mathbf{y} = \begin{bmatrix} y_{1j} \end{bmatrix}_{j=1,\dots,M} = \begin{bmatrix} y_{11} & y_{12} & \cdots & y_{1M} \end{bmatrix}$$

• A one-dimensional discrete-time signal is typically represented by an array as a row vector.

• General matrix: This is the most general case of an $(N \times M)$ matrix and is denoted by the matrix symbol, that is, uppercase bold typeface like

$$\mathbf{A} = \begin{bmatrix} a_{ij} \end{bmatrix}_{i=1,\dots,N; j=1,\dots,M} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1M} \\ a_{21} & a_{22} & \cdots & a_{2M} \\ \vdots & \vdots & \ddots & \vdots \\ a_{N1} & a_{N2} & \cdots & a_{NM} \end{bmatrix}$$

 This arrangement is typically used for two-dimensional discretetime signals or images

Example

```
• c = 5.66 or c = [5.66]

• x = [3.5, 33.22, 24.5]

• x1 = [2

5

3

-1]

• A = [124

2-22

035
```

5 4 9]

```
c = 5.66 or c = [5.66] c is a scalar or a 1 x 1 matrix
x = [3.5, 33.22, 24.5] x is a row vector or a 1 x 3 matrix
```

x1 is column vector or a 4 x 1 matrix

A is a 4 x 3 matrix

 Spaces, commas, and semicolons are used to separate elements of a matrix

Spaces or commas separate elements of a row

Semicolons separate columns

$$[1,2,3,4;5,6,7,8;9,8,7,6] = [1 2 3 4]$$

5678

9876]



Operators

- MATLAB provides several arithmetic and logical operators, some of which follow.
 - = assignment
 - + addition
 - * multiplication
 - ^ power
 - / division
 - <> relational operators
 - logical OR
 - 'transpose

- == equality
- subtraction or minus
- .* array multiplication
- .^ array power
- ./ array division
- & logical AND
- ~ logical NOT
- .' array transpose

• Matrix addition and subtraction: These are straightforward operations that are also used for array addition and subtraction. Care must be taken that the two matrix operands be *exactly* the same size.

• Matrix conjugation: This operation is meaningful only for complex valued matrices. It produces a matrix in which all imaginary parts are negated. It is denoted by **A*** in analysis and by conj(A) in MATLAB.

• Matrix transposition: This is an operation in which every row (column) is turned into column (row). Let X be an $(N \times M)$ matrix. Then

$$\mathbf{X}' = [x_{ji}]; \quad j = 1, \dots, M, \ i = 1, \dots, N$$

• is an $(M \times N)$ matrix

 Multiplication by a scalar: This is a simple straightforward operation in which each element of a matrix is scaled by a constant, that is

$$ab \Rightarrow a*b (scalar)$$
 $a\mathbf{x} \Rightarrow a*\mathbf{x} (vector or array)$

This operation is also valid for an array scaling by a constant

 $a\mathbf{X} \Rightarrow a*\mathbf{X} \text{ (matrix)}$

- **Vector-vector multiplication:** In this operation, one has to be careful about matrix dimensions to avoid invalid results.
- The operation produces either a scalar or a matrix. Let \mathbf{x} be an $(N \times 1)$ and \mathbf{y} be a $(1 \times M)$ vectors.
- Then

$$\mathbf{x} * \mathbf{y} \Rightarrow \mathbf{x}\mathbf{y} = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} \begin{bmatrix} y_1 & \cdots & y_M \end{bmatrix} = \begin{bmatrix} x_1y_1 & \cdots & x_1y_M \\ \vdots & \ddots & \vdots \\ x_Ny_1 & \cdots & x_Ny_M \end{bmatrix}$$

produces a matrix.

• Matrix-vector multiplication: If the matrix and the vector are compatible (i.e., the number of matrix-columns is equal to the vector-rows), then this operation produces a column vector:

$$\mathbf{y} = \mathbf{A} * \mathbf{x} \Rightarrow \mathbf{y} = \mathbf{A} \mathbf{x} = \begin{bmatrix} a_{11} & \cdots & a_{1M} \\ \vdots & \ddots & \vdots \\ a_{N1} & \cdots & a_{NM} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_M \end{bmatrix} = \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix}$$



- Matrix-matrix multiplication: Finally, if two matrices are compatible, then their product is well-defined.
- The result is also a matrix with the number of rows equal to that of the first matrix and the number of columns equal to that of the second matrix.
- Note that the order in matrix multiplication is very important.

- These operations treat matrices as arrays.
- They are also known as *dot operations* because the arithmetic operators are prefixed by a dot (.), that is, .*, ./, or .^.

- Array multiplication: This is an element by element multiplication operation.
- For it to be a valid operation, both arrays must be the same size. Thus we have

$$X.*Y \rightarrow 2D \text{ array}$$

• Array exponentiation: In this operation, a scalar (real- or complex valued) is raised to the power equal to every element in an array, that is,

$$\mathbf{a}.\mathbf{\hat{x}} \equiv \begin{bmatrix} a^{x_1} \\ a^{x_2} \\ \vdots \\ a^{x_N} \end{bmatrix}$$

• Array transposition: As explained, the operation A. produces transposition of real- or complex-valued array A.

Indexing Matrices

- A m x n matrix is defined by the number of m rows and number of n columns
- An individual element of a matrix can be specified with the notation A(i,j) or Ai,j for the generalized element, or by A(4,1)=5 for a specific element.

$$>> A = [1 2 4 5;6 3 8 2]$$

A is a 2 x 4 matrix

$$Ans = 2$$

• The colon operator can be used to index a range of elements

$$Ans = 638$$

Indexing Matrices

 Specific elements of any matrix can be overwritten using the matrix index

Example:

$$A = [1 \ 2 \ 4 \ 5 \ 6 \ 3 \ 8 \ 2]$$

Matrix Shortcuts

• The ones and zeros functions can be used to create any m x n matrices composed entirely of ones or zeros

Example

```
a = ones(3,2)
a = \begin{bmatrix} 1 & 1 \\ & 1 & 1 \end{bmatrix}
b = zeros(1,5)
b = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \end{bmatrix}
```



Control-Flow

• if-elseif-else structure



Control-Flow

for..end loop

```
for index = values
    program statements
    :
end
```

Example

Consider the following sum of sinusoidal functions

$$x(t) = \sin(2\pi t) + \frac{1}{3}\sin(6\pi t) + \frac{1}{5}\sin(10\pi t) = \sum_{k=1}^{3} \frac{1}{k}\sin(2\pi kt), \qquad 0 \le t \le 1$$

• Using MATLAB, we want to generate samples of x(t) at time instances 0:0.01:1.

Example

- **Approach 1** Here we will consider a typical C or Fortran approach, that is, we will use two for..end loops, one each on t and k.
- This is the most inefficient approach in MATLAB, but possible.

```
>> t = 0:0.01:1; N = length(t); xt = zeros(1,N);

>> for n = 1:N

>> temp = 0;

>> for k = 1:3

>> temp = temp + (1/k)*sin(2*pi*k*t(n));

>> end

>> xt(n) = temp;

>> end
```

Example

• **Approach 2** In this approach, we will compute each sinusoidal component in one step as a vector, using the time vector t = 0.0.01:1 and then add all components using one for..end loop.

```
>> t = 0:0.01:1; xt = zeros(1,length(t));
>> for k = 1:3
>> xt = xt + (1/k)*sin(2*pi*k*t);
>> end
```

• Scripts

- implemented using a *script* file called an m-file (with an extension .m), which is only a text file that contains each line of the file as though you typed them at the command prompt.
- built-in editor, which also provides for context-sensitive colors and indents for making fewer mistakes and for easy reading.
- executed by typing the name of the script at the command prompt.
- script file must be in the current directory on in the directory of the path environment.

- Example:
- General form of sinusoidal function is

$$x(t) = \sum_{k=1}^{K} c_k \sin(2\pi kt)$$

create a script file!
% Script file to implement

$$t = 0:0.01:1; k = 1:2:5; ck = 1./k;$$

xt = ck * sin(2*pi*k'*t);

• Functions

- The second construct of creating a block of code is through subroutines.
- A major difference between script and function files is that the first executable line in a function file begins with the keyword function followed by an output-input variable declaration

• Example

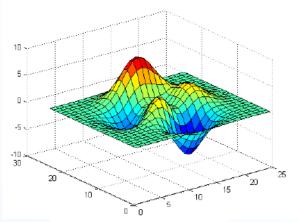
```
function xt = sinsum(t,ck)
% Computes sum of sinusoidal terms of the form in (1.1)
% x = sinsum(t,ck)
%
K = length(ck); k = 1:K;
ck = ck(:)'; t = t(:)';
xt = ck * sin(2*pi*k'*t);
```

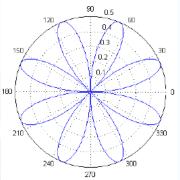


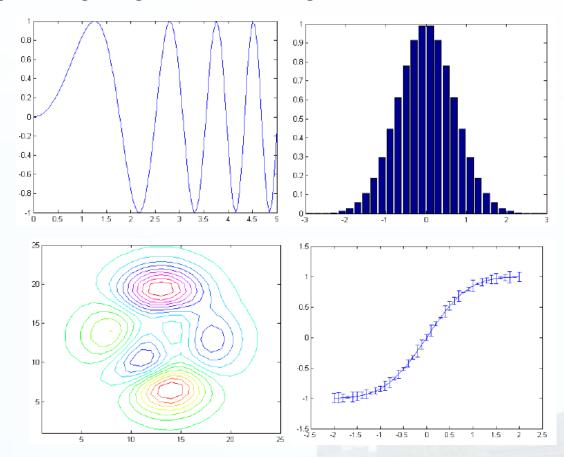
Plotting

• Matlab has a powerful plotting engine that can generate a wide

variety of plots.









Plotting

- The basic plotting command is the plot(t,x) command, which generates a plot of x values versus t values in a separate figure window.
- The arrays t and x should be the same length and orientation.
- Optionally, some additional formatting keywords can also be provided in the plot function.
- The commands xlabel and ylabel are used to add text to the axis, and the command title is used to provide a title on the top of the graph.
- All aspects of a plot (style, size, color, etc.) can be changed by appropriate commands embedded in the program or directly through the GU

Plotting Example

 Plot of a simple sinusoidal wave, putting axis labels and title on the plot

```
>> t = 0:0.01:2; % sample points from 0 to 2 in steps of 0.01
```

- $>> x = \sin(2*pi*t)$; % Evaluate $\sin(2 pi t)$
- >> plot(t,x,'b'); % Create plot with blue line
- >> xlabel('t in sec'); ylabel('x(t)'); % Label axis
- >> title('Plot of sin(2\pi t)'); % Title plot

Plotting Example

- MATLAB provides an ability to display more than one graph in the same figure window.
- By means of the hold on command, several graphs can be plotted on the same set of axes.
- The hold off command stops the simultaneous plotting
 - >> plot(t,xt,'b'); hold on; % Create plot with blue line
 - >> Hs = stem(n*0.05,xn,'b','filled'); % Stem-plot with handle Hs
 - >> set(Hs,'markersize',4); hold off; % Change circle size

Plotting Example

• The subplot command, which displays several graphs in each individual set of axes arranged in a grid, using the parameters in the subplot command.

```
>>> subplot(2,1,1); % Two rows, one column, first plot
>>> plot(t,x,'b'); % Create plot with blue line
...
>>> subplot(2,1,2); % Two rows, one column, second plot
>>> Hs = stem(n,x,'b','filled'); % Stem-plot with handle Hs
```





Terima Kasih