COMP6248 Lab 1 Exercise – Playing with gradients and matrices in PyTorch

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Introduction

The results are seeded using torch.manual_seed(0) to provide reproducible results.

1 Implement a matrix factorisation using gradient descent

1.1 Implement gradient-based factorisation

```
from typing import Tuple
import torch

def sgd_factorise(A: torch.Tensor, rank: int,
    num_epochs=1000, lr=0.01) ->
    Tuple[torch.Tensor, torch.Tensor]:
    m, n = A.shape
    U = torch.rand((m, rank))
    V = torch.rand((n, rank))

for epoch in range(num_epochs):
    for r in range(m):
        for c in range(n):
            e = A[r, c] - (U[r] @ V[c].T)
            U[r] += lr * e * V[c]
            V[c] += lr * e * U[r]

return U, V
```

1.2 Factorise and compute reconstruction error

$$\hat{\mathbf{U}} = \begin{bmatrix}
0.6168 & -0.1530 \\
0.4108 & 1.5961 \\
1.0798 & 1.1800
\end{bmatrix}$$

$$\hat{\mathbf{V}} = \begin{bmatrix}
0.8126 & 1.8290 \\
0.7836 & -0.2088 \\
0.8384 & 1.0195
\end{bmatrix}$$

Loss = 0.12197002023458481

2 Compare your result to truncated SVD

2.1 Compare to the truncated-SVD

Loss = 0.12191088497638702

The reconstruction loss of the truncated SVD is almost identical to the results in Section 1.2. This is explained by the Eckart-Young-Mirsky theorem. The Eckart-Young-Mirsky theorem states that a matrix \boldsymbol{D} can be approximated with subject to $rank(\boldsymbol{D}) \leq r$. The truncated SVD provides the optimal solution for the approximation.

3 Matrix completion

3.1 Implement masked factorisation

```
^1\mathrm{Carl} Eckart and Gale Young. "The Approximation of One Matrix by Another of Lower Rank". In: Psychometrika~1.3 (Sept. 1, 1936), pp. 211–218. ISSN: 1860-0980. DOI: 10.1007/BF02288367. URL: https://doi.org/10.1007/BF02288367 (visited on 04/19/2021).
```

3.2 Reconstruct a matrix

$$\hat{\mathbf{U}} = \begin{bmatrix}
0.6501 & -0.1515 \\
0.2346 & 1.2954 \\
1.1472 & 1.2511
\end{bmatrix},
\hat{\mathbf{V}} = \begin{bmatrix}
0.9019 & 1.5197 \\
0.8868 & -0.1223 \\
0.5406 & 1.3175
\end{bmatrix},
\hat{\mathbf{A}} = \hat{\mathbf{U}}\hat{\mathbf{V}}^T = \begin{bmatrix}
0.3561 & 0.5951 & 0.1518 \\
2.1802 & 0.0496 & 1.8334 \\
2.9360 & 0.8643 & 2.2685
\end{bmatrix},$$

Loss = 1.4483590126037598

Although the matrix completion approximation of $\hat{\boldsymbol{A}}$ is not identical with $\hat{\boldsymbol{A}}$, the gradient descent-based approach of minimization provides reasonable results in the recovery of the missing values subject to rank r.