

# CV\_Assignment6

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## 1 Exercise

### 1.1 a)

$$E = \sum_{i=1}^n \|x'_i - Mx_i - t\|^2$$

We can rewrite the above equation in form

$$E = \sum_{i=1}^n \left\| \begin{pmatrix} x'_i \\ y'_i \end{pmatrix} - \begin{pmatrix} m_1 & m_2 \\ m_3 & m_4 \end{pmatrix} * \begin{pmatrix} x_i \\ y_i \end{pmatrix} - \begin{pmatrix} t_1 \\ t_2 \end{pmatrix} \right\|^2$$

Therefore,

$$E = \sum_{i=1}^n [(x'_i - m_1 * x_i - m_2 * y_i - t_1)^2 + (y'_i - m_3 * x_i - m_4 * y_i - t_2)^2]$$

Taking the derivative w.r.t to each of  $(m_1, m_2, m_3, m_4, t_1, t_2)$

$$\frac{\partial E}{\partial m_1} = 2 * \sum_{i=1}^n -x_i * (x'_i - m_1 * x_i - m_2 * y_i - t_1)$$

$$\frac{\partial E}{\partial m_2} = 2 * \sum_{i=1}^n -y_i * (x'_i - m_1 * x_i - m_2 * y_i - t_1)$$

$$\frac{\partial E}{\partial m_3} = 2 * \sum_{i=1}^n -x_i * (y'_i - m_3 * x_i - m_4 * y_i - t_2)$$

$$\frac{\partial E}{\partial m_4} = 2 * \sum_{i=1}^n -y_i * (y'_i - m_3 * x_i - m_4 * y_i - t_2)$$

$$\frac{\partial E}{\partial t_1} = 2 * \sum_{i=1}^n -1 * (x'_i - m_1 * x_i - m_2 * y_i - t_1)$$

$$\frac{\partial E}{\partial t_2} = 2 * \sum_{i=1}^n -1 * (y'_i - m_3 * x_i - m_4 * y_i - t_2)$$

### 1.2 b)

$$S^*h = u$$

Vector  $h$  contains the unknown parameters of the transformation, therefore

$$h = \begin{pmatrix} m_1 \\ m_2 \\ m_3 \\ m_4 \\ t_1 \\ t_2 \end{pmatrix} \quad \text{Vector } u \text{ is } \begin{pmatrix} \sum_{i=1}^n x_i * x'_i \\ \sum_{i=1}^n y_i * x'_i \\ \sum_{i=1}^n x_i * y'_i \\ \sum_{i=1}^n y_i * y'_i \\ \sum_{i=1}^n x'_i \\ \sum_{i=1}^n y'_i \end{pmatrix} \quad \text{Therefore matrix } S \text{ is:}$$

$$S = \begin{pmatrix} \sum_{i=1}^n x_i^2 & \sum_{i=1}^n x_i * y_i & 0 & 0 & \sum_{i=1}^n x_i & 0 \\ \sum_{i=1}^n x_i * y_i & \sum_{i=1}^n y_i^2 & 0 & 0 & \sum_{i=1}^n y_i & 0 \\ 0 & 0 & \sum_{i=1}^n x_i^2 & \sum_{i=1}^n x_i * y_i & 0 & \sum_{i=1}^n x_i \\ 0 & 0 & \sum_{i=1}^n x_i * y_i & \sum_{i=1}^n y_i^2 & 0 & \sum_{i=1}^n y_i \\ \sum_{i=1}^n x_i & \sum_{i=1}^n y_i & 0 & 0 & n & 0 \\ 0 & 0 & \sum_{i=1}^n x_i & \sum_{i=1}^n y_i & 0 & n \end{pmatrix}$$

### 1.3 c)

point correspondences  $\underbrace{(0,0)}_{x_i, y_i} \rightarrow \underbrace{(1,2)}_{x'_i, y'_i}, (1,0) \rightarrow (3,2), \text{ and } (0,1) \rightarrow (1,4).$

$$u = \begin{pmatrix} \sum_{i=1}^n x_i * x'_i \\ \sum_{i=1}^n y_i * x'_i \\ \sum_{i=1}^n x_i * y'_i \\ \sum_{i=1}^n y_i * y'_i \\ \sum_{i=1}^n x'_i \\ \sum_{i=1}^n y'_i \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 2 \\ 4 \\ 5 \\ 8 \end{pmatrix}$$

$$S = \begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 1 & 1 & 0 & 0 & 3 & 0 \\ 0 & 0 & 1 & 1 & 0 & 3 \end{pmatrix}$$

$$h = S^{-1} * u = \begin{pmatrix} 2 \\ 0 \\ 0 \\ 2 \\ 1 \\ 2 \end{pmatrix}$$

## 2 Exercise

$$x' = sRx + t \rightarrow \begin{pmatrix} x' \\ y' \end{pmatrix} = s \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \end{pmatrix}$$

## 2.1 a)

Lets define  $x_i = \begin{pmatrix} x_i \\ y_i \end{pmatrix}$

$$v = x_2 - x_1 = \begin{pmatrix} x_2 - x_1 \\ y_2 - y_1 \end{pmatrix}$$

$$v' = x'_2 - x'_1 = \begin{pmatrix} x'_2 - x'_1 \\ y'_2 - y'_1 \end{pmatrix} = s * \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} * \begin{pmatrix} x_2 - x_1 \\ y_2 - y_1 \end{pmatrix}$$

From cos norm we have:

$$\cos(\theta) = \frac{v' * v}{||v'|| * ||v||} = \frac{(x'_2 - x'_1) * (x_2 - x_1) + (y'_2 - y'_1) * (y_2 - y_1)}{\sqrt{(y'_2 - y'_1)^2 + (x'_2 - x'_1)^2} * \sqrt{(y_2 - y_1)^2 + (x_2 - x_1)^2}}$$

where

$$\theta = \arccos\left(\frac{v' * v}{||v'|| * ||v||}\right) = \arccos\left(\frac{(x'_2 - x'_1) * (x_2 - x_1) + (y'_2 - y'_1) * (y_2 - y_1)}{\sqrt{(y'_2 - y'_1)^2 + (x'_2 - x'_1)^2} * \sqrt{(y_2 - y_1)^2 + (x_2 - x_1)^2}}\right)$$

## 2.2 b)

$$s = \frac{||v'||}{||v||} = \frac{\sqrt{(y'_2 - y'_1)^2 + (x'_2 - x'_1)^2}}{\sqrt{(y_2 - y_1)^2 + (x_2 - x_1)^2}}$$

## 2.3 c)

$$\begin{pmatrix} t_x \\ t_y \end{pmatrix} = \begin{pmatrix} x' - s * \cos(\theta) + s * \sin(\theta) \\ y' - s * \sin(\theta) - s * \cos(\theta) \end{pmatrix}$$

## 2.4 d)

Transformation from the following point correspondences:  $\{(\frac{1}{2}, 0) \rightarrow (0, 0)\}, \{(0, \frac{1}{2}) \rightarrow (-1, -1)\}$ .

$$v = x_2 - x_1 = \begin{pmatrix} x_2 - x_1 \\ y_2 - y_1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$$

$$v' = x'_2 - x'_1 = \begin{pmatrix} x'_2 - x'_1 \\ y'_2 - y'_1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

from section **a)**  $\theta = \frac{\pi}{2}$

from section **b)**  $s = 2$

$$\begin{pmatrix} t_x \\ t_y \end{pmatrix} = \begin{pmatrix} x' - s * \cos(\theta) + s * \sin(\theta) \\ y' - s * \sin(\theta) - s * \cos(\theta) \end{pmatrix} = \begin{pmatrix} 0 - 2 * \cos(\frac{\pi}{2}) + 2 * \sin(\frac{\pi}{2}) \\ 0 - 2 * \sin(\frac{\pi}{2}) - 2 * \cos(\frac{\pi}{2}) \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$x' = sRx + t \rightarrow \begin{pmatrix} x' \\ y' \end{pmatrix} = s \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \end{pmatrix} \rightarrow s * \begin{pmatrix} \cos(\frac{\pi}{2}) & -\sin(\frac{\pi}{2}) \\ \sin(\frac{\pi}{2}) & \cos(\frac{\pi}{2}) \end{pmatrix} * \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$