

#### Exercise and Homework Round 6

These exercises (except for the last) will be gone through on **Tuesday October 27th 12:15–14:00** in the exercise session. The last exercise is a homework which you should return via mycourses by **Tuesday November 3rd at 12:00**.

### Exercise 1. (Ansatz solution of linear ODE)

Consider the spring model with zero force u(t) = 0:

$$ma(t) + kp(t) + \eta v(t) = 0.$$

- (a) Solve the equation with exponential ansatz  $p(t) = C \exp(\lambda t)$ .
- (b) Fix suitable initial conditions, visualize the solution, and discuss effects of the parameters k and  $\eta$  on the solution.

# Exercise 2. (Matrix exponential)

(a) Rewrite the spring model in the previous exercise as a state-space model of the form

$$\dot{\mathbf{x}}(t) = \mathbf{A}\mathbf{x}(t) + \mathbf{B}_{u}u(t) \tag{1}$$

- (b) With u(t) = 0, solve the equation in terms of the matrix exponential  $\exp(\mathbf{A} t)$ .
- (c) Visualize the solution and compare it to the solution obtained in the previous exercise.
- (d) Generalize the solution to the case with  $u(t) \neq 0$ .



# Exercise 3. (Numerical solution of ODEs)

Consider the state-space ODE in the previous exercise, but now assume that the force is given by the following alternatives:

$$u(t) = 1,$$
  

$$u(t) = \sin(t),$$
  

$$u(t) = t.$$
(2)

- (a) Solve the state-space ODE with Euler's method.
- (b) Compare the solution to the solution obtained in Exercise 2d.
- (c) Use a builtin ODE solver to obtain a numerical solution to the ODE.

# Homework 6 (DL Tuesday November 3rd at 12:00)

Consider the scalar differential equation

$$\dot{x} = f x, \qquad x(0) = x_0, \tag{3}$$

with f = -1/2 and  $x_0 = 3$ .

- (a) Solve the equation analytically.
- (b) Use Euler's method to solve the equation numerically.
- (c) Use a builtin ODE solver (e.g. Matlab's ode45 or Python's odeint) to numerically solve the equation.
- (d) Visualize the solutions and compare them to each other.