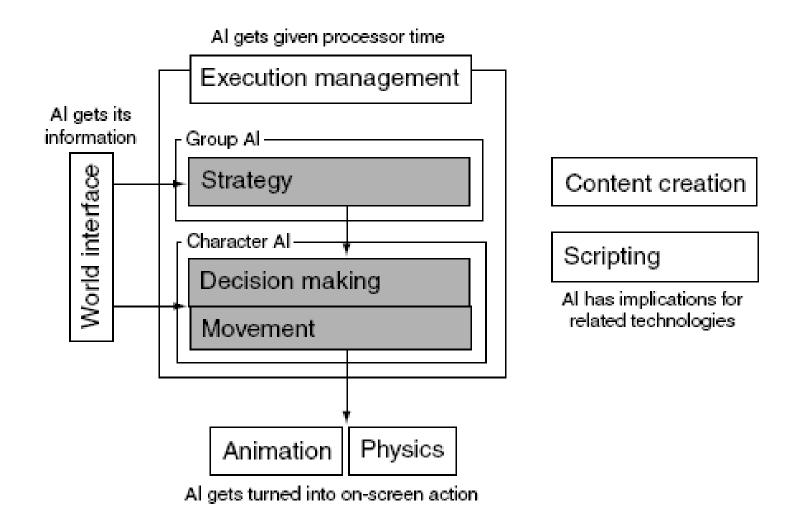
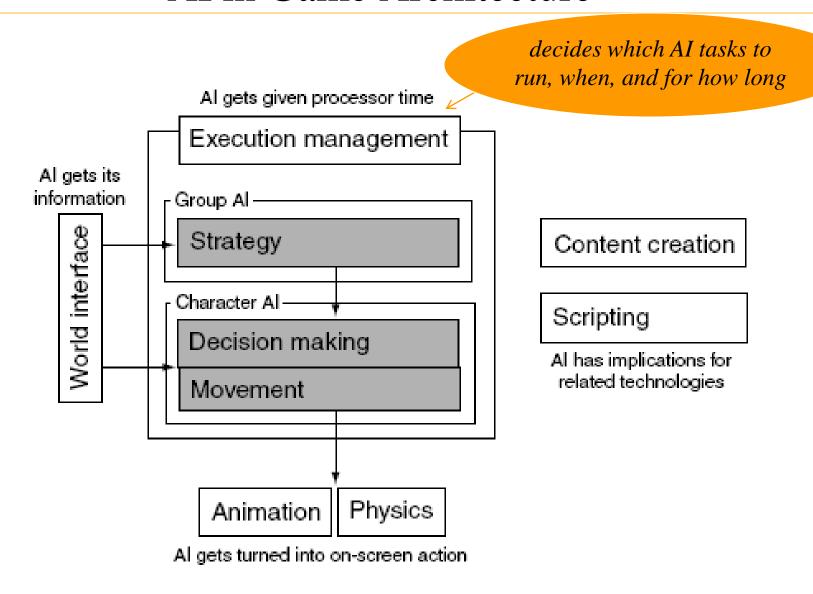
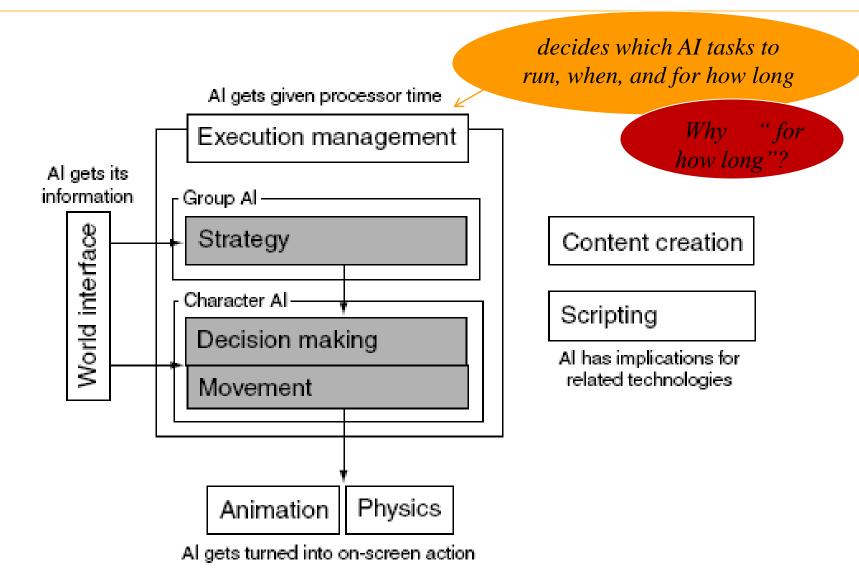
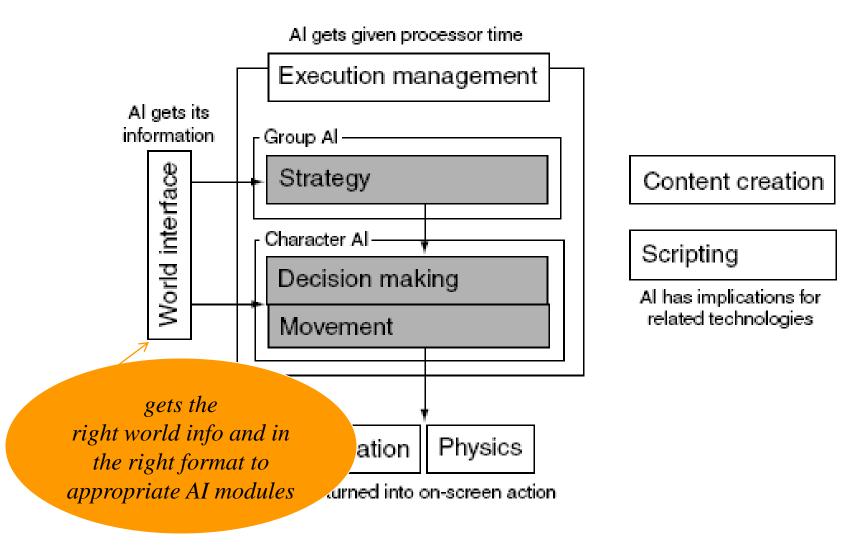
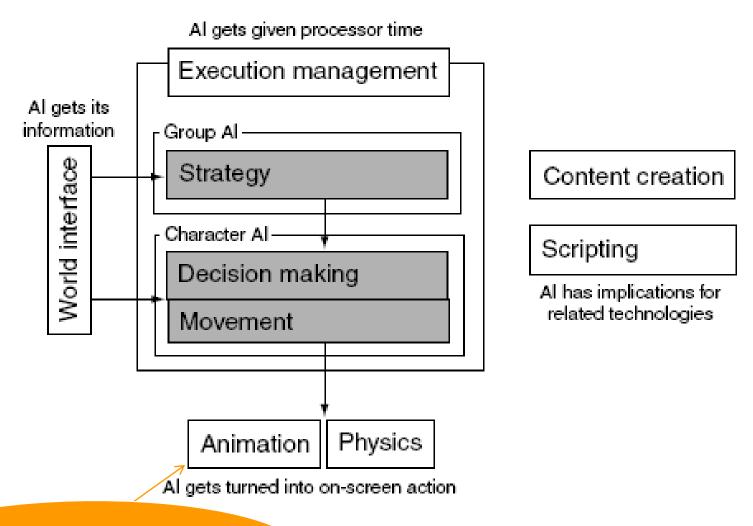
Game Artificial Intellligence

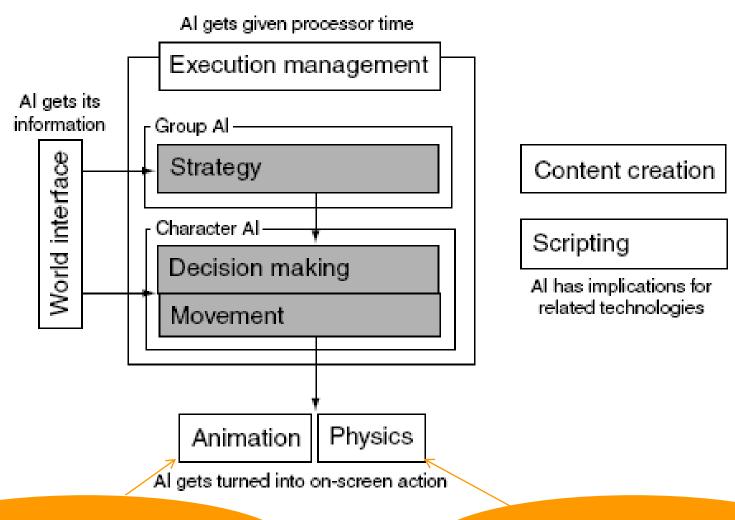












translates AI decisions into the actual (animated) actions

Games" by

translates actions into changes to the world

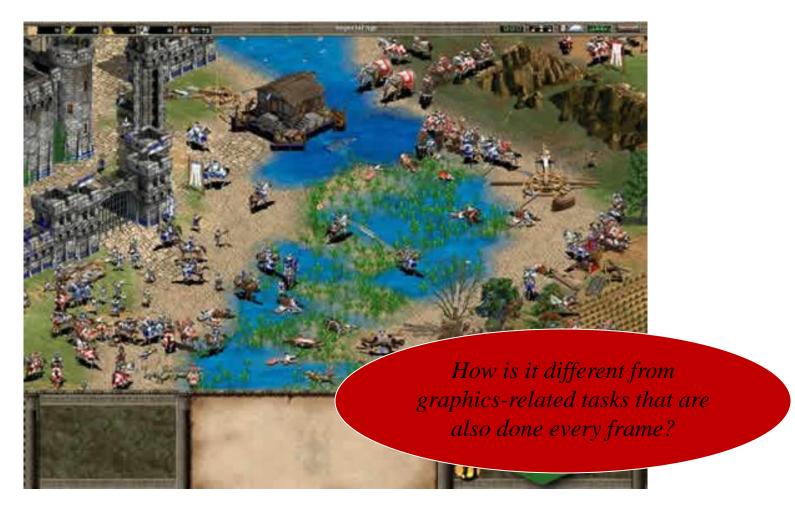
- Modern AI processing in games can often take 5-50% of processing
- Someone needs to control the limited processing time
 - dividing available time among AI tasks
 - scheduling algorithms to work over time
 - making preferences for "important" characters

• Dividing available time among AI tasks



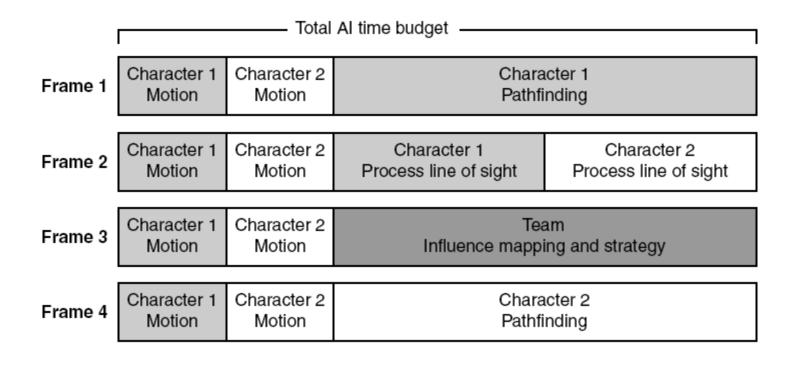
from Age of Empires

• Dividing available time among AI tasks



from Age of Empires

• Dividing available time among AI tasks



- Dividing available time among AI tasks: **Frequency-based scheduler**
- -takes in N tasks, each task T_i has execution frequency f_i
 - -runs each task T_i at its frequency

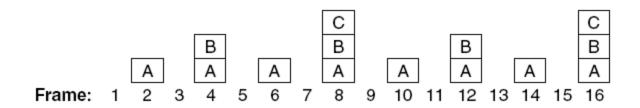
Any issues?

• Dividing available time among AI tasks: **Frequency-based scheduler**

-takes in N tasks, each task T_i has execution frequency f_i

-runs each task T_i at its frequency

Example:
$$f(A) = 2$$
, $f(B)=4$, $f(C)=8$



• Dividing available time among AI tasks: **Frequency-based scheduler**

-takes in N tasks, each task T_i has execution frequency f_i

-runs each task T_i at its frequency

Example: f(A) = 2, f(B) = 4, f(C) = 8Any ideas how to mitigate this?

Frame: 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16

• Dividing available time among AI tasks: **Frequency-based scheduler**

-takes in N tasks, each task T_i has execution frequency f_i

-runs each task T_i at its frequency and with its own phase p_i

Example:

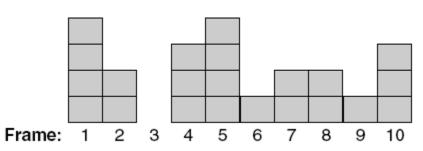
```
Initialization:
for \ i = 1...100
task[i].freq = 10;
task[i].phase = i;
Main \ Loop:
for \ i = 1...100
task[i].freq \% (frame + task[i].phase) == 0
run \ task[i];
```

• Dividing available time among AI tasks: **Frequency-based scheduler**

-computing a good quality p_i according to Wright's method:

whenever new task T_i with frequency f_i needs to be scheduled run the scheduler for K frames pick frame $F < f_i$ with least total # of tasks executed at F,F+fi,... set phase p_i to F

Example: Task with f=5 comes in



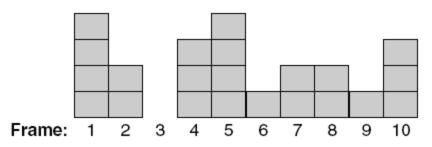
F=?

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Example: Task with f=5 comes in



F=3

- Dividing available time among Interruptible AI tasks
- -Interruptible tasks can be paused and resumed as time allows
 - -can use threads (less common in games)
- -can use software threads (tasks are supposed to return as soon as their time expires)

Load-balancing Scheduler:

during each frame

it distributes time among the tasks scheduled for this frame

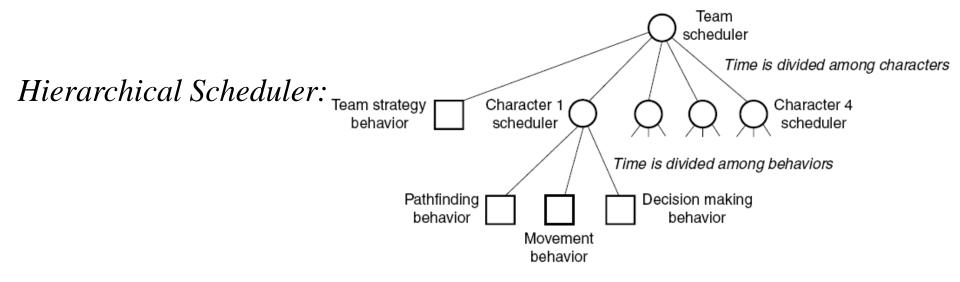
- Dividing available time among Interruptible AI tasks
- -Interruptible tasks can be paused and resumed as time allows
 - -can use threads (less common in games)
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Priority Scheduler:

during each frame

it distributes time among the tasks scheduled for this frame proportionally to the priority of the tasks

- Dividing available time among Interruptible AI tasks
- -Interruptible tasks can be paused and resumed as time allows
 - -can use threads (less common in games)
- -can use software threads (tasks are supposed to return as soon as their time expires)



Anytime AI tasks

- -compute the best solution they can within provided time
- -can often improve the solution within the subsequent (next cycle) executions
- -common in Path Finding

- we will learn more about it in the later classes

Anytime AI tasks

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• Level of Details-based management

- -less important characters run at lower frequencies
- -less important characters run at lower priorities
- -less important characters get less AI tasks and behaviors to run

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 - -less important characters run at lower priorities
 - -less important characters get less AI tasks and behaviors to run

 Example?

• To be believable, characters need to know the "right" world information at the "right" time

- Information can be received via polling or event processing
 - -polling (e.g., Is this door open or closed?)
 - -events (e.g., need to know whenever the door closes)
 - -tasks subscribe to events of interest
 - -other entities send out events
 - -event manager receives and dispatches messages to those tasks that subscribed to them

Getting the "right" information:-the believable sensory ability of AI characters

- Getting the "right" information:
 - -the believable sensory ability of AI characters

-typical senses used in games (in the order of popularity): sight, touch, hearing, smell

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 - -the believable sensory ability of AI characters

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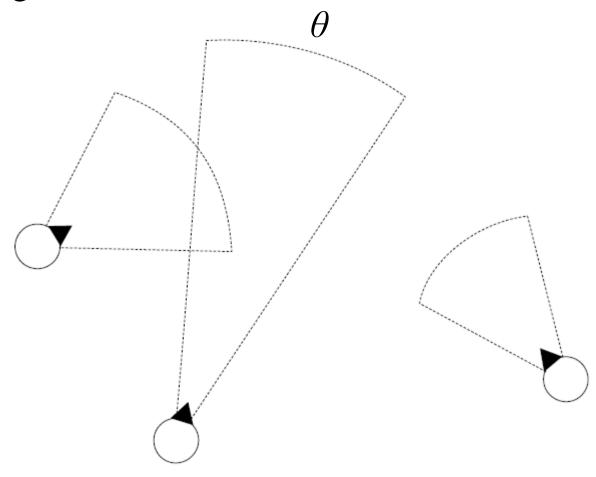
Any others?

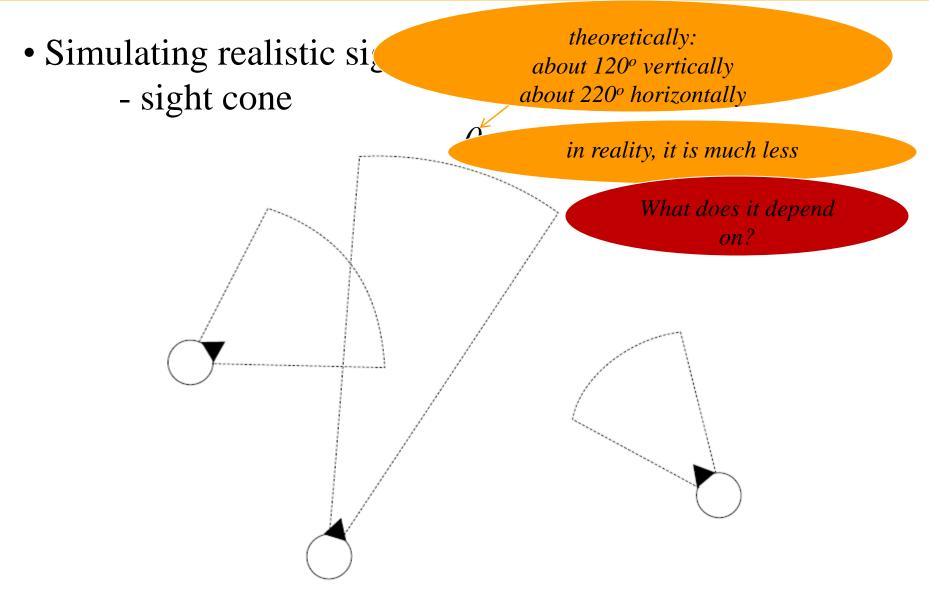
- Simulating realistic sight
 - sight cone



from Doom

- Simulating realistic sight
 - sight cone





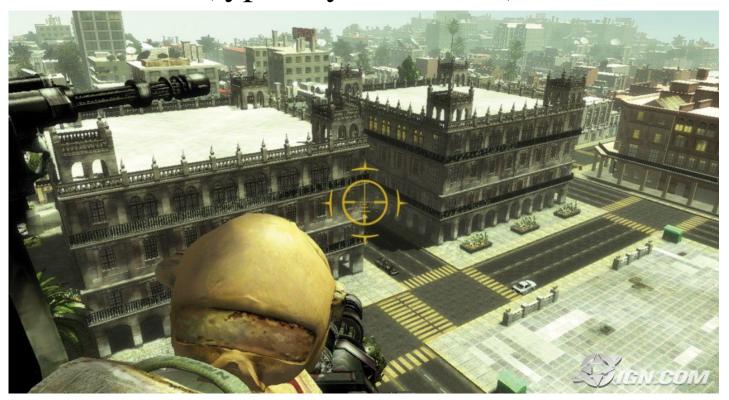
• Simulating realistic sight commonly used cone: 60° - sight cone

- Simulating realistic sight, other factors (in the order of popularity):
 - line-of-sight



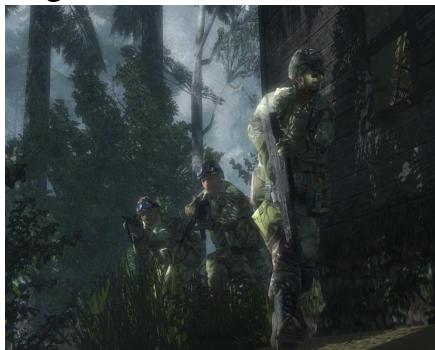
from Splinter Cell

- Simulating realistic sight, other factors (in the order of popularity):
 - line-of-sight
 - distance (typically, hard limit)



from Ghost Recon

- Simulating realistic sight, other factors (in the order of popularity):
 - line-of-sight
 - distance (typically, hard limit)
 - brightness



from Splinter Cell

- Simulating realistic sight, other factors (in the order of popularity):
 - line-of-sight
 - distance (typically, hard limit)
 - brightness

- contrast with background

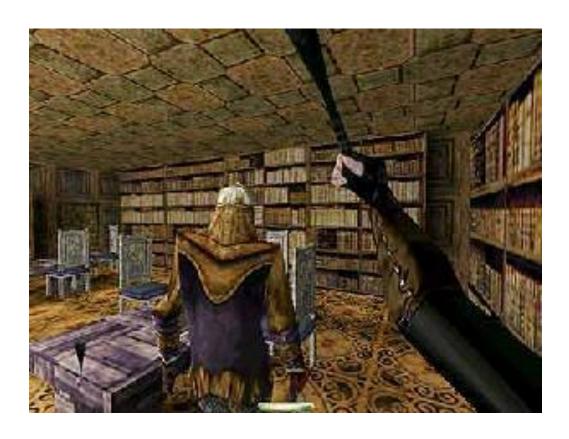


- Simulating realistic hearing
- if implemented, then it typically travels at 100m/sec for some distance



from Conflict: Desert Storm

- Simulating realistic touch
 - typically, limited to collision checking
 - sometimes used in stealthy games



from Thief: The Dark Project

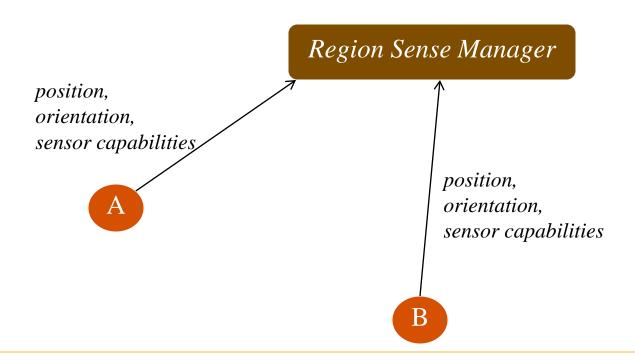
- Simulating smell
 - distance-limited, slow-speed propagation
 - rarely used in games



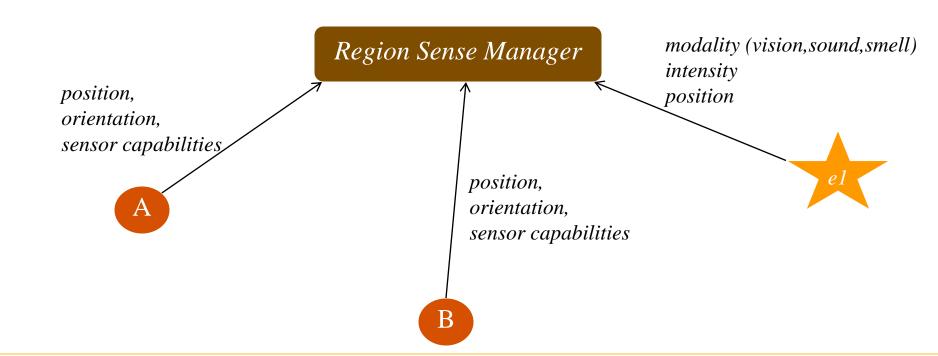
from Alien vs. Predator

Managing sense signals and sensors: Region Sense
 Manager

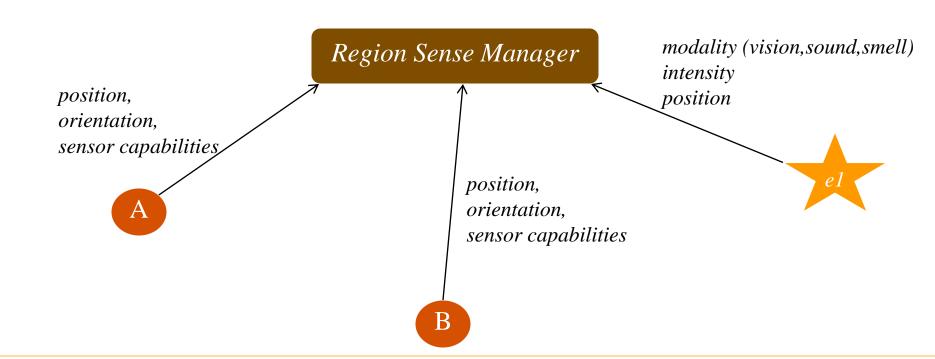
-potential sensors are registered



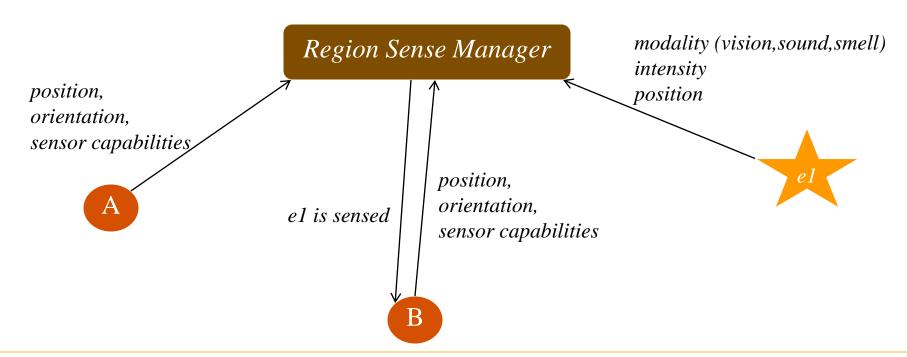
- Managing sense signals and sensors: Region Sense
 Manager
 - -potential sensors are registered
 - -signals from emitters received



- Managing sense signals and sensors: Region Sense
 Manager
 - -aggregation phase: find all sensors within the max range of the emitter given its modality
 - -testing phase: test against their sensor capabilities

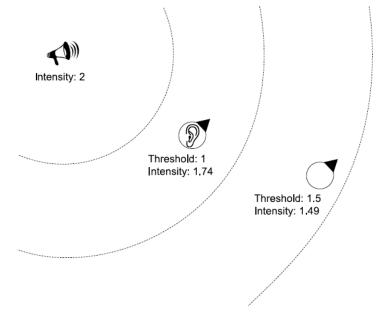


- Managing sense signals and sensors: Region Sense
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 - -aggregation phase: find all sensors within the max range of the emitter given its modality
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 - -notification phase: notify sensors that pass at "right" times



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Example: attenuation=0.9/meter



Managing sense signals and sensors: Region Sense
 Manager

-aggregation phase: find all sensors within the max range of the emitter given its modality

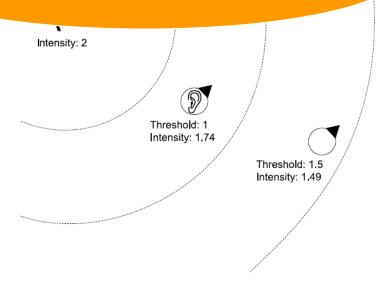
Issues leading to non-realistic effects?

-testing phase: test against their sensor capabilities

-notification phase: notification

vision signals are tested for other line-of-sight, sight cone, ...

Example: attenuation=0.9/meter

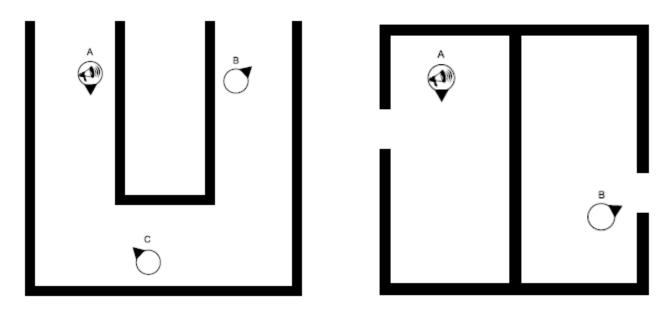


Managing sense signals and sensors: Region Sense
 Manager

-aggregation phase: find all sensors within the max range of the emitter given its modality

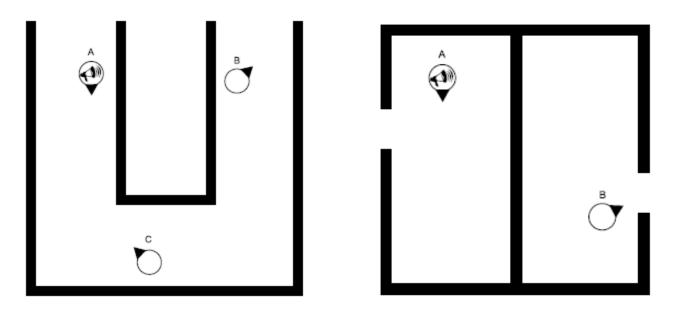
-testing phase: test against their sensor capabilities

-notification phase: notify sensors that pass at "right" times

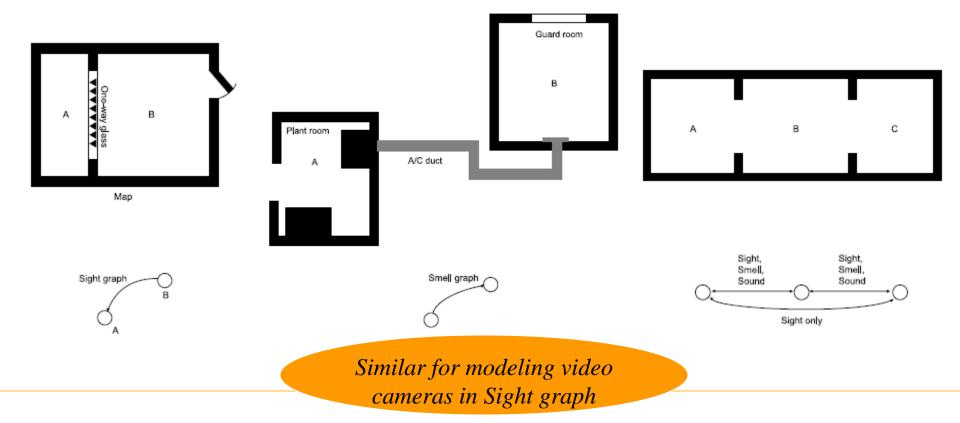


Managing sense signals and sensors: Region Sense
 Manager

- -aggregation phase: find all sensors within the max range of the emitter given its modality Solutions?
- -testing phase: test against their sensor capacinates
- -notification phase: notify sensors that pass at "right" times



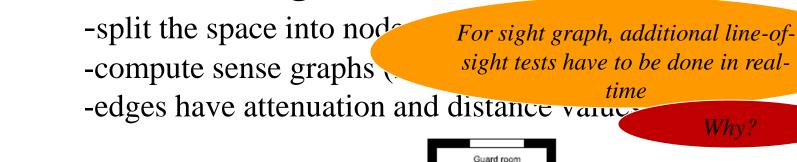
- Managing sense signals and sensors: Finite Element Model Sense Manager
 - -split the space into nodes (e.g., rooms)
 - -compute sense graphs (sight, sound and smell graphs)
 - -edges have attenuation and distance values

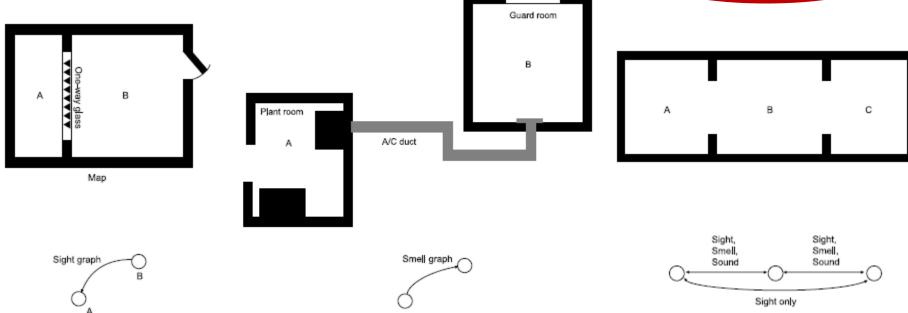


 Managing sense signals and sensors: Finite Element Model Sense Manager

> -split the space into nod--compute sense graphs
>
> For sight graph, no intermediate
>
> nodes – all line-of-sight nodes have
>
> direct edges

 Managing sense signals and sensors: Finite Element Model Sense Manager





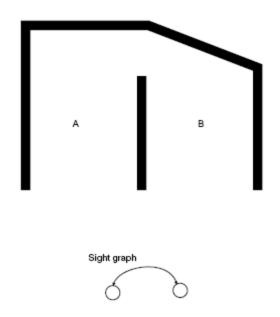
• Managing sense signals and sensors: Finite Element Model Sense Manager

-split the space into nod For sight graph, additional line-of-

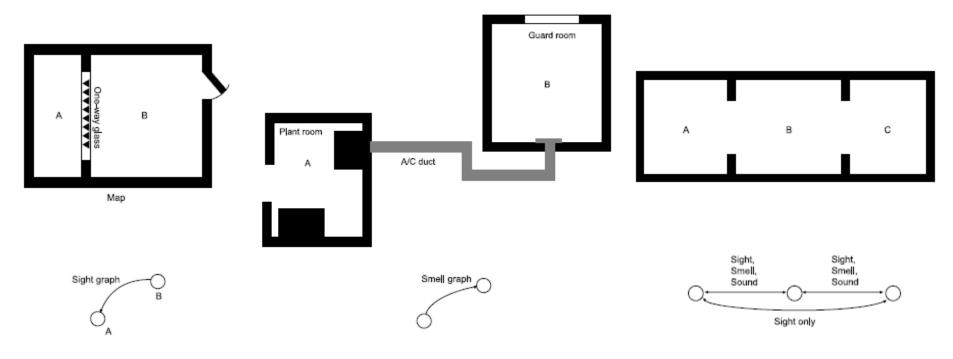
-compute sense graphs sight tests have to be done in real-

-edges have attenuation and distance value

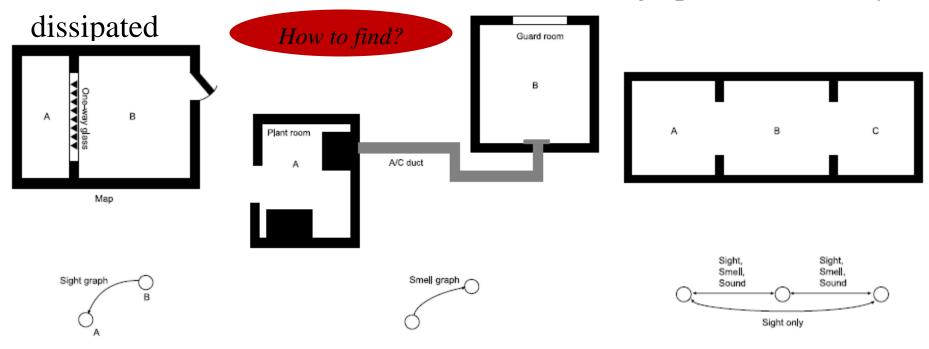
Why?



- Managing sense signals and sensors: Finite Element Model Sense Manager
 - -similar aggregation, testing, notification phases except...
- -for Sight: all aggregated nodes of signal in *u* are: sensors in *u* and its immediate neighbors according to Sight graph



- Managing sense signals and sensors: Finite Element Model Sense Manager
 - -similar aggregation, testing, notification phases except...
- -for Sound: all aggregated nodes of signal in u are: sensors in u and its descendants reachable in Sound graph without fully



• Managing sense signals and sensors: Finite Element Model Sense Manager

-similar aggregation, testing, notification phases except...

-for Smell: at every frame, smell is being dissipated and propagated to all successors, and aggregated nodes with value >

