Rotation

이진영



Flip

Mirror reversal of an image across a horizontal or vertical axis

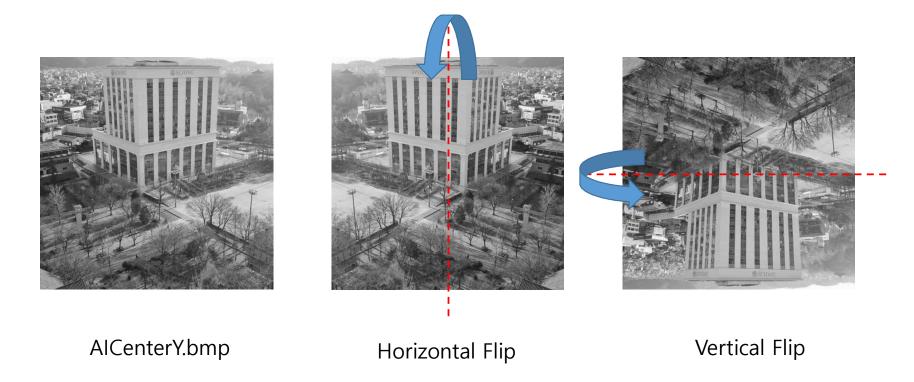
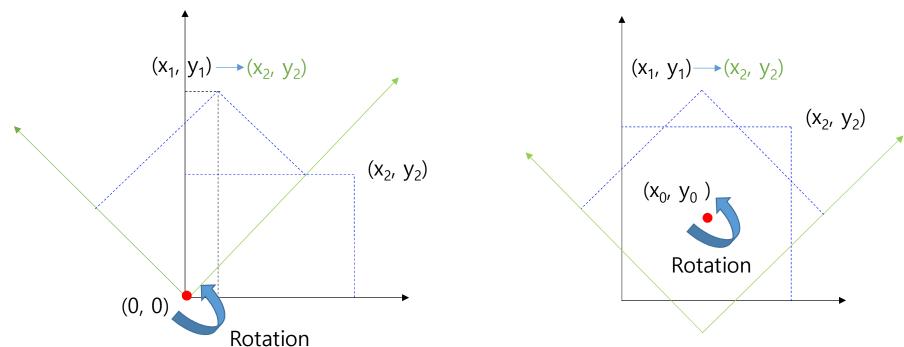




Image Rotation

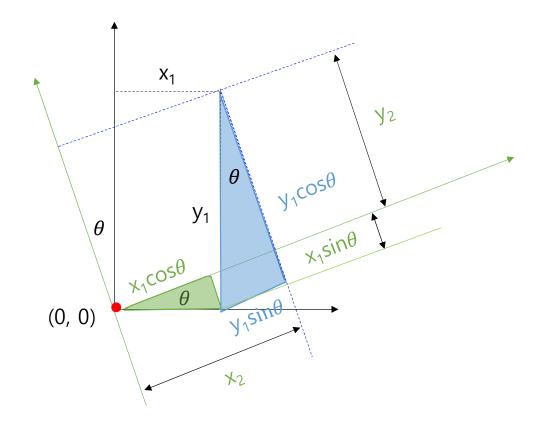
- Image processing of turning an image in a clockwise or counterclockwise direction
- Circular movement of an image around an origin of rotation





Basic Principle

- Geometric transformation from a source coordinate (x_1, y_1) to a target coordinate (x_2, y_2)
- lacktriangledown Rotation of a coordinate by an angle heta
- Integer coordinate, but floating operation with $\cos\theta$ and $\sin\theta$
- Ignored, if (x₂, y₂) is located out of image boundaries



$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$$

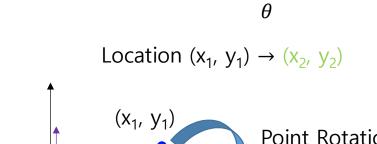


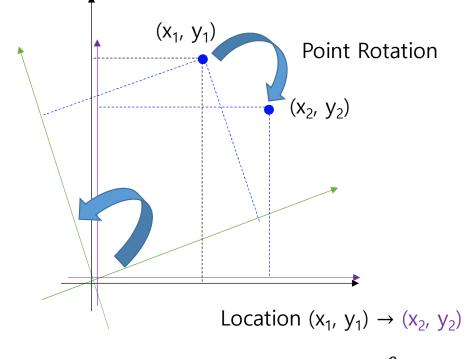
Rotation Matrix

$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$$

$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} \cos(-\theta) & \sin(-\theta) \\ -\sin(-\theta) & \cos(-\theta) \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$$

$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$$





Coordinate Rotation $-\theta$

Rotation Equation

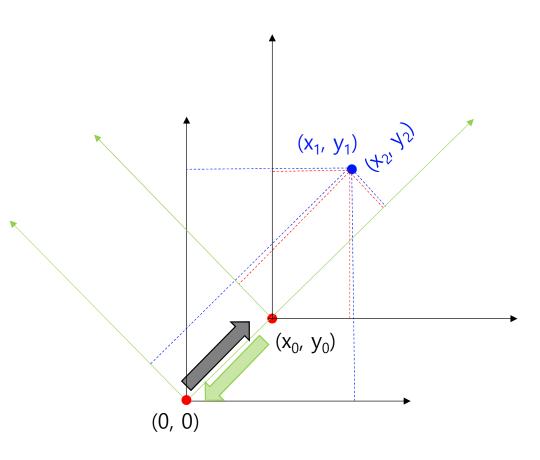
■ Rotation from (x_1, y_1) into (x_2, y_2) around an origin of (x_0, y_0)



$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x_1 - x_0 \\ y_1 - y_0 \end{bmatrix} + \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}$$

$$x_2 = \cos\theta \cdot (x_1 - x_0) - \sin\theta \cdot (y_1 - y_0) + x_0$$

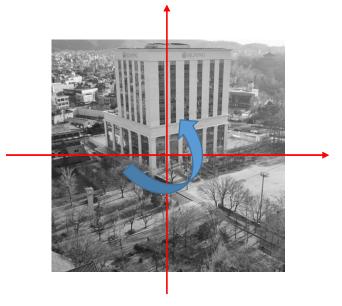
 $y_2 = \sin\theta \cdot (x_1 - x_0) + \cos\theta \cdot (y_1 - y_0) + y_0$

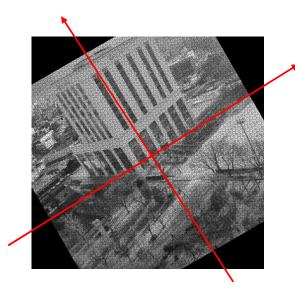


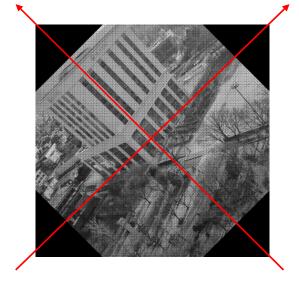


Hole

- Unmapped pixels in a rotated image
- Rounding error for an integer coordinate, after floating transformation
- Hole filling, for example, interpolation with neighboring pixels surrounding unmapped pixels







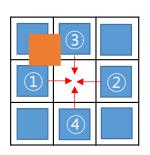


Rotation by 30°

Rotation by 45°

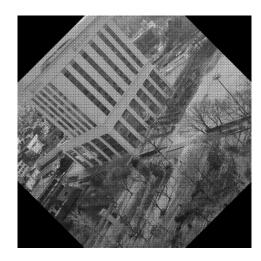
Experiment

- Rotation by 45° (π /4, π =3.1415926535)
- Nearest neighbor interpolation in left, right, top, and bottom order

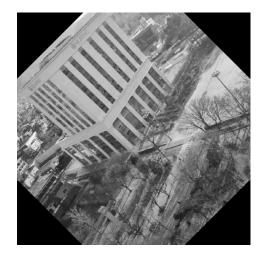




AlCenterY.bmp



Rotation without hole filling



Rotation with hole filling

