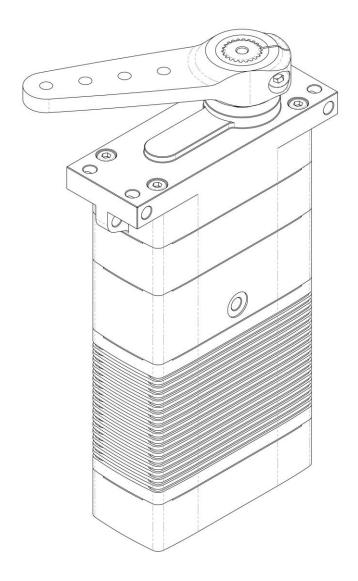


# DA 30 Technical Specification



DA 30-30-5224

# DA 30 Technical Specification

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# DA 30 Technical Specification

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## 1. General Description

To guarantee maximum safety and reliability, our DA 30 features a brushless motor and a contactless wear free position sensor. This means maximum service life with the greatest-possible power delivery and its design prevents electromagnetic emissions (EMI) caused by brush sparking. The housing made of saltwater-resistant aluminum is HART-coat treated, meets the IP-67 standard for water and dust sealing and provides an integrated Sub-D connector (MIL spec. circular connector or cable gland on request). Brackets integrated in the housing for horizontal and vertical assembly. 8-fold, ball-bearing supported, steel gear train, drive shaft with ANSI multi-tooth.

The DA 30 series can be equipped with a standard PWM input (Pulse Width Modulation) that has two different interfaces: a differential, galvanic isolated interface (Opto-Coupler) and a single-ended interface with CMOS levels that is also used to program the servo parameters. It includes analog position feedback to detect the drive shaft position. A differential RS-422 PWM interface can be chosen instead of the opto-coupled interface.

The DA 30 with digital serial command interface (RS-485) receives its commands via a CRC secured protocol. It can return not only the shaft position in digital format, but also several diagnostic data such as the level of the supply voltage, current consumption and the temperature of the motor and electronics in digital form (optionally also the humidity within the actuator case). These kind of diagnostic capabilities help to determine the health state of the actuators before, during and after deployment.

**Interface Options:** 

#### **PWM-OPTO**

PWM-Level Compatible, OPTO-coupler PWM Interface

#### **PWM-TTL**

PWM-Level Compatible, TTL PWM Interface

#### **RS 422/TTL**

RS 422-Level Compatible, Differential PWM Interface

#### RS 485 (2-wire)

RS-485 Compatible, Asynchronous Serial Command Interface

#### **RS 485 Redundant**

RS 485 Redundant Communication Interface and Redundant Power Supply

#### RS 485 (4-wire)

RS 485 Separated Receiver and Transmitter Lines for Interface A and B

#### For RS 485-Versions Only:

Customized commands can be implemented on request. Humidity sensor available.

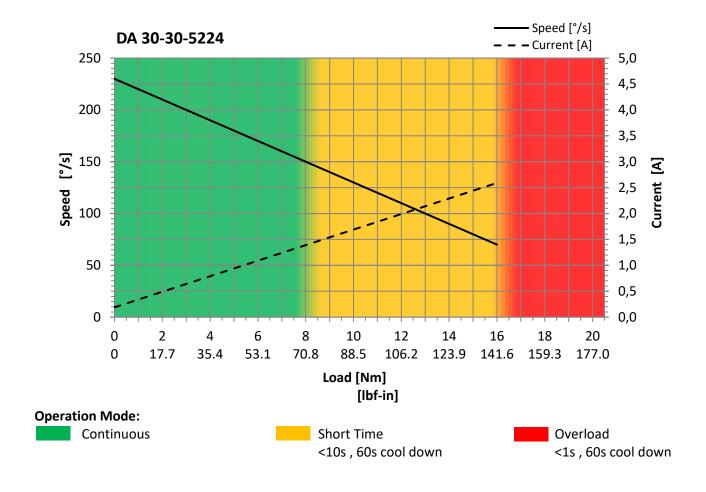
# 2. Operating Data

		DA 30-30-5224	
Supply Voltage (rated)		28 V DC	
Supply Voltage Range		24 32 V DC	
Standby Current <sup>1</sup>	at rated voltage	< 0.04 A	
Rated Current <sup>1</sup>	at rated voltage	1.3 A	
Peak Current <sup>1</sup>	at rated voltage	2.6 A	
Rated Torque <sup>1</sup>	at rated speed	8.0 Nm (70.8 lbf-in)	
Peak Torque <sup>1</sup>	at rated voltage	16.0 Nm (141.6 lbf-in)	
No Load Speed <sup>1</sup>	at rated voltage	230 °/s	
Rated Speed <sup>1</sup>	at rated torque	150 °/s	
Default Travel Angle		±45° = 90° total travel	
Max. Travel Angle <sup>2</sup>		±85° = 170° total travel	
Backlash (mechanical)		≤ 0.5°	
Position Error under Tempera	ture <sup>3</sup>	≤ ±1.0°	
Operating Temperature Range	e <sup>4</sup>	-30°C +70°C (-22°F +158°F)	
Storage Temperature Range		-55°C +85°C (-67°F +185°F)	

- 1) Tolerance ±10%
- 2) Programming Tool # 985.4 for PWM-Versions required
- 3) -20°C ... +50°C ,  $\Delta t$  = 70°C (-4°F ... +122°F ,  $\Delta t$  = 126°F)
- 4) Low Temperature Modification (-70°C /-94°F) on request



## 3. Performance





# 4. Command Signal

## 4.1. PWM Command Interface

PWM-OPTO/TTL , PWM-RS 422/TTL	DA 30-30-5224.1	DA 30-30-5224.2
Signal Voltage	TTL-Level HIGH: min. 3.5\	/ , max. 5.5V
Signal Voltage	TTL-Level LOW: min. 0.0\	' , max. 1.5V
Frame Rate	2.6 2000 ms	
Valid Pulse Lengths	0.9 2.1 ms	
Pulse Lengths for Position Left / Center / Right	1.0 / 1.5 / 2.0 ms	
Resolution	≤ 1.0 µs	

# 4.2. RS 485 Command Signal

RS 4	485 , RS 485 Redundant	DA 30-30-5224.3	DA 30-30-5224.4	DA 30-30-5224.5
Baud-Rate		115200 ±1.5% bits/s		
Protocol (Documentation available)		6 Byte (incl. 2 by	te CRC)	



# 4.3. RS 485 Protocol Specifications

RS 485 , RS 485 Redundant	DA 30-30-5224.3	DA 30-30-5224.4	DA 30-30-5224.5
Number of Data Bits	8		
Number of Stop Bits	1 or 2		
Parity	None		

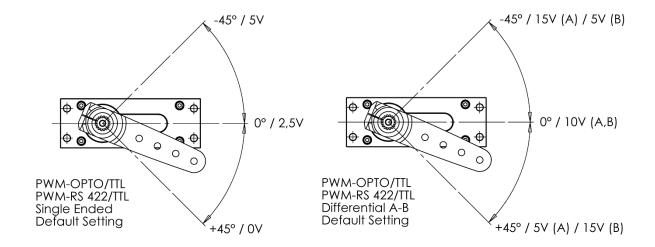
# **Command / Response Frame**

Byte #	Description				
1	Command / Response-Code				
2	Actuator ID				
3	Argument 1				
4	Argument 2				
5	CRC High Byte				
6	CRC Low Byte				

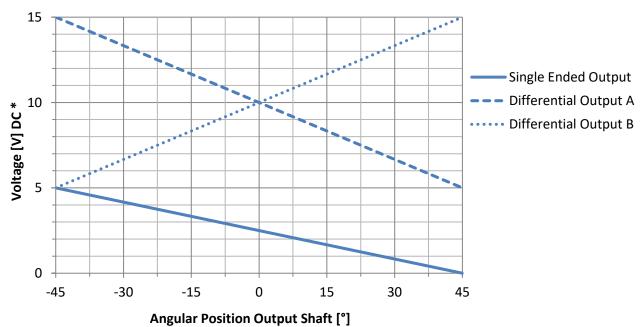


# 4.4. Position Feedback Signal (PWM Versions)

The Position Feedback signal (Pos FB) is an analog output signal with a voltage value which is directly related to the output shaft's angular position. Reference is Supply Ground / Signal Ground (GND).



## **Position Feedback (Pos FB)**



<sup>\*</sup> Tolerance ±5%

# DA 30 Technical Specification

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# 4.5. Position Feedback Value (RS 485 Versions)

Integrated in the RS 485 protocol a Position Feedback Value is available, representing the output shaft's angular position. Value readout by sending a request command. Detailed information is provided in the RS 485 documentation.

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# **Materials and Protective Features**

Case Material	Saltwater resistant Aluminum Alloy
Splash Water Resistance	IP 67 , waterproof to 1m depth
Case Surface Treatment	HART®-Coat
Salt Water Resistance	> 100 hrs. Salt Water Spray
Salt Water Resistance	Standard, Case Material
EMI / RFI Shielding	Case Shielding
Motor Type	Brushless DC Motor
Gear Set Material	Hardened Steel
Position Sensor	Contactless
Position Feedback	Standard
RS 485 Communication Interface	Optional
Humidity Sensor	Optional
Temperature Sensor <sup>5</sup>	Standard , Motor and PCB

5) RS 485-Versions only

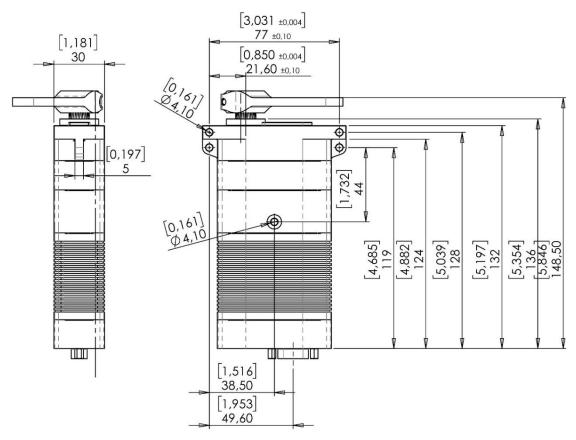
#### **Dimensions** 6.

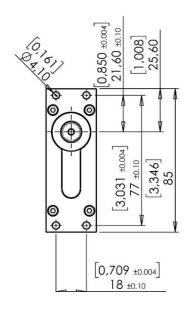
	DA 30-30-5224
Case Dimensions	132.0 mm x 67.5 mm x 30.0 mm ±0.2 mm
	(5.197 in x 2.658 in x 1.181 in ±0.008 in)
Weight (with DE-9m Standard Connectors)	670g (23.6oz) ±10%
Weight (with MIL Grade D38999 Connectors)	770g (27.2oz) ±10%

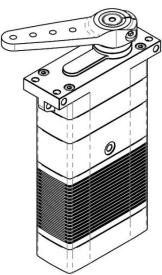


## **6.1. Installation Dimensions**

Valid for Versions DA 30.30.5224.\_.ST DE-9m Standard Connectors





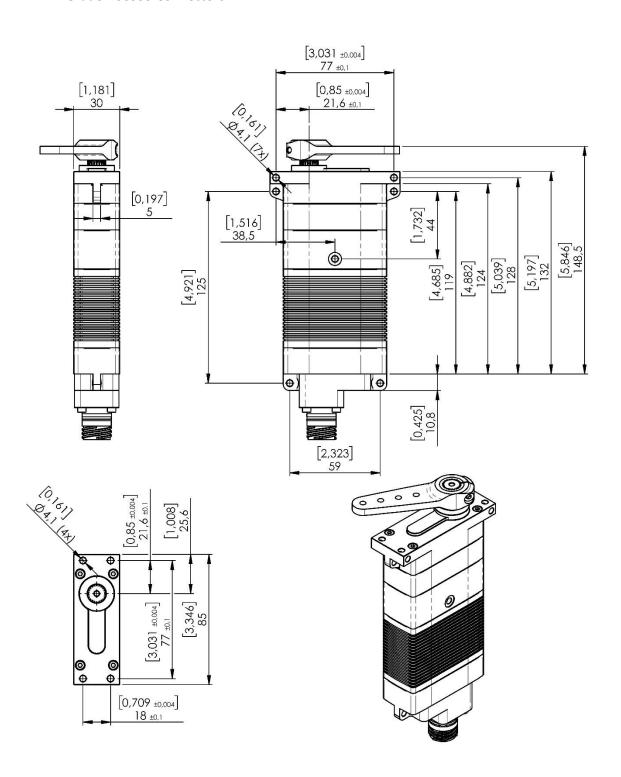


Not to scale

Dimensions [in], mm



Valid for Versions DA 30.30.5224.\_.MIL13 MIL Grade D38999 Connectors



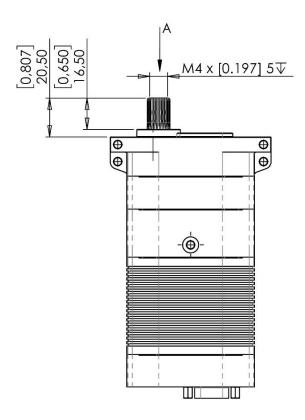
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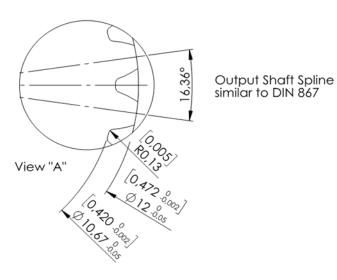
Dimensions [in], mm



# **Output Shaft Spline**

Valid for all Interface Versions DA 30.30.5224.\_.\_





Not to scale

Dimensions [in], mm



# 7. Electrical Connection Options

## **PWM-OPTO Interface**

#### **Integrated Connector**

Item # DA 30.30.5224.1.\_

	Standard Connector		
1 2 3 4 5	Manufacturer		ITT Cannon
	Туре		DEMM-9PE
6 7 8 9	Mating		D-SUB DE-9f
			PWM-OPTO Pin Assignment
	1	PWM (AO)	Command Signal, Anode Optocoupler
	2	PWM (CO)	Command Signal, Cathode Optocoupler
	3	Diff FB A	Differential Position Feedback Signal, Output A
	4	to Pin 7	Connect to Pin 7 (Supply Ground)
	5	Case GND	Case Ground
	6	+V DC	Supply Voltage
	7	GND	Supply Ground, Signal Ground
	8	Pos FB	Single Ended Position Feedback Signal
	9	Diff FB B	Differential Position Feedback Signal, Output B

#### NOTE:

Access to the actuator parameters is possible via the TTL-PWM-Interface only. Programming Tool # 985.4 required.



## **PWM-TTL Interface**

## **Integrated Connector**

Item # DA 30.30.5224.1.\_

	Standard Connector		
1 2 3 4 5	Manufacturer		ITT Cannon
	Туре		DEMM-9PE
6 7 8 9	Mating		D-SUB DE-9f
			PWM-TTL Pin Assignment
	1	NC	Do not connect
	2	NC	Do not connect
	3	Diff FB A	Differential Position Feedback Signal, Output A
	4	PWM	Command Signal
	5	Case GND	Case Ground
	6	+V DC	Supply Voltage
	7	GND	Supply Ground, Signal Ground
	8	Pos FB	Single Ended Position Feedback Signal
	9	Diff FB B	Differential Position Feedback Signal, Output B

#### NOTE:

Access to the actuator parameters is possible via the TTL-PWM-Interface only. Programming Tool # 985.4 required.



## **PWM-RS 422/TTL Interface**

## **Integrated Connector**

Item # DA 30.30.5224.2.\_

		Standard Connector			
1 2 3 4 5	Manufacturer		ITT Cannon		
	Туре		DEMM-9PE		
6 7 8 9	Mating		D-SUB DE-9f		
		PW	M-RS 422/TTL Pin Assignment		
	1	RS 422 / PWM	Non-Inverted RS 422-Input		
	2	RS 422 / PWM	Inverted RS 422-Input		
	3	Diff FB A	Position Feedback Signal, Output A		
	4	TTL / PWM	Command and Parameter Input		
	5	Case GND	Case Ground		
	6	+V DC	Supply Voltage		
	7	GND	Supply Ground, Signal Ground		
	8	Pos FB	Single Ended Position Feedback Signal		
	9	Diff FB B	Differential Position Feedback Signal, Output B		

#### NOTE:

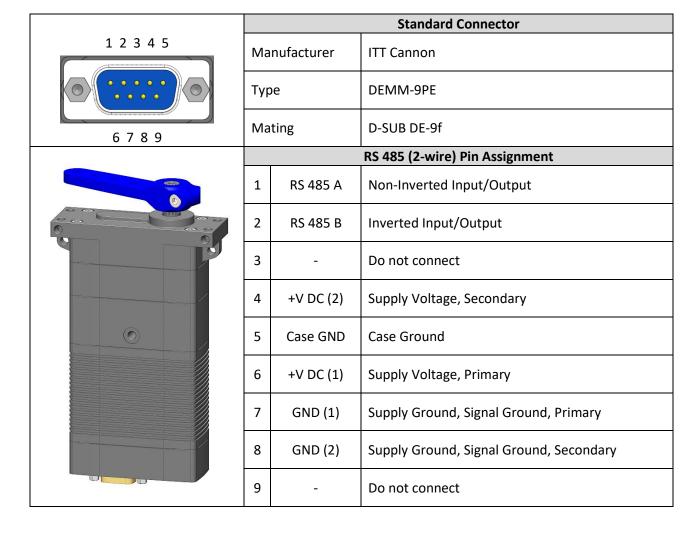
Access to the actuator parameters is possible via the TTL-PWM-Interface only. Programming Tool # 985.4 required.



## RS 485 Interface (2-wire)

#### **Integrated Connector**

#### Item # DA 30.30.5224.3.\_

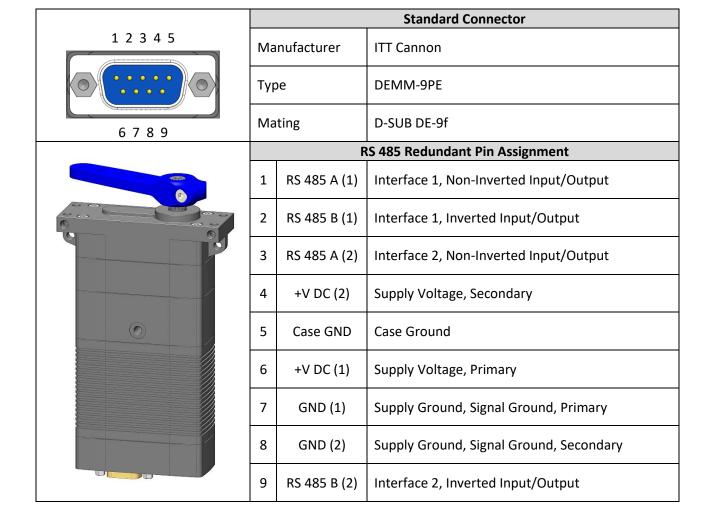




#### **RS 485 Redundant Interface**

#### **Integrated Connector**

#### Item # DA 30.30.5224.4.\_

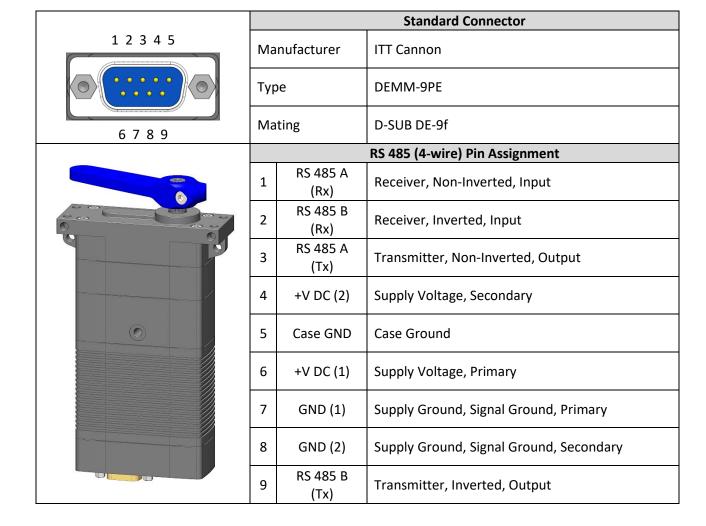




## RS 485 Interface (4-wire)

#### **Integrated Connector**

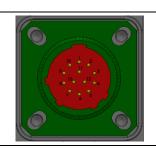
#### Item # DA 30.30.5224.5.\_



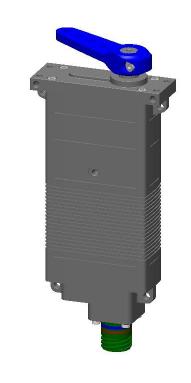


#### **Integrated MIL Grade D38999 Connector**

#### Item # DA 30.30.5224.\_.MIL13



Standard Connector					
Manufacturer	Amphenol				
Туре	D38999-20WB35SN				
Mating	e.g. D38999-26WB35SN				



Mating		e.g. D38999-26WB35SN	
RS 485 (4-wire) Interface Pin Assignment			
1	-	Do not connect	
2	+V DC (1)	Supply Voltage, Primary	
3	Case GND	Case Ground (connected to aluminum case)	
4	COM1 A (RS 485)	RS 485 1, Non-Inverted, Input/Output	
5	COM1 B (RS 485)	RS 485 1, Inverted, Input/Output	
6	-	Do not connect	
7	-	Do not connect	
8	COM2 A (RS 485)	RS 485 2, Non-Inverted, Input/Output	
9	COM2 B (RS 485)	RS 485 2, Inverted, Input/Output	
10	+V DC (2)	Supply Voltage, Secondary	
11	-	Do not connect	
12	GND (1)	Supply Ground, Signal Ground, Primary	
13	GND (2)	Supply Ground, Signal Ground, Secondary	

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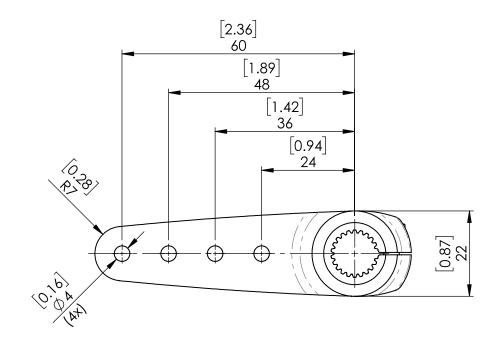
# 8. Accessories

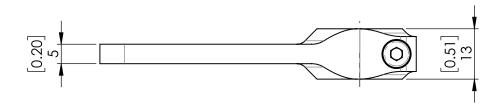
Item	Item-No.
Aluminum Servo Arm	1951.21
Programming Tool PWM	985.4
Programming Tool RS-485	985.5

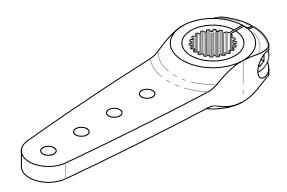


# 8.1. Aluminum Servo Arm

#### Item # 1951.21





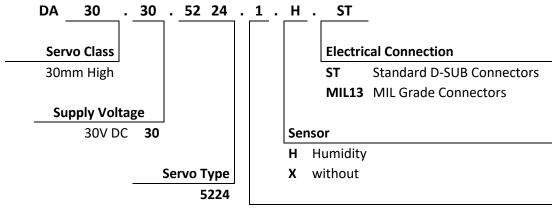


Not to scale

Dimensions [in], mm



# 9. Item Number System



#### Interface

- 1 PWM-OPTO / TTL
- 2 PWM-RS 422 / TTL
- 3 RS 485 (2-wire)
- 4 RS 485 Redundant
- **5** RS 485 (4-wire)



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