

Sandwich Variance Estimator of DR ATE Estimator

: **Renewal Version** (9월 6일 Version)

$$\psi_T(\theta) = \begin{bmatrix} \nu_1 - \frac{\{E_T Y_T - (E_T - e_T) E[Y_T | E=1, X_T]\}}{e_T} \\ \nu_0 - \frac{\{(1-E_T) Y_T - (E_T - e_T) E[Y_T | E=0, X_T]\}}{1 - e_T} \\ \frac{X_T (Y_T - \alpha^T X_T)}{1 + e^{\beta^T X_T}} \end{bmatrix} \begin{matrix} \text{--- } (\psi_{\nu_1}) \\ \text{--- } (\psi_{\nu_0}) \\ \text{--- } (\psi_\alpha) \\ \text{--- } (\psi_\beta) \end{matrix}$$

$\theta = (\nu_1, \nu_0, \alpha, \beta)$

Annotations:
 - **Covariance term** (red arrow pointing to X_T in the first term)
 - **Outcome regression model of model matrix** (red arrow pointing to $Y_T - \alpha^T X_T$)
 - **PS model of model matrix** (red arrow pointing to $1 + e^{\beta^T X_T}$)

$$\frac{\partial}{\partial \theta'} \psi_T(\hat{\theta}) = \begin{bmatrix} \frac{\partial}{\partial \nu_1} \psi_{\nu_1} & \frac{\partial}{\partial \nu_0} \psi_{\nu_1} & \frac{\partial}{\partial \alpha} \psi_{\nu_1} & \frac{\partial}{\partial \beta} \psi_{\nu_1} \\ \frac{\partial}{\partial \nu_1} \psi_{\nu_0} & \frac{\partial}{\partial \nu_0} \psi_{\nu_0} & \frac{\partial}{\partial \alpha} \psi_{\nu_0} & \frac{\partial}{\partial \beta} \psi_{\nu_0} \\ \frac{\partial}{\partial \nu_1} \psi_\alpha & \frac{\partial}{\partial \nu_0} \psi_\alpha & \frac{\partial}{\partial \alpha} \psi_\alpha & \frac{\partial}{\partial \beta} \psi_\alpha \\ \frac{\partial}{\partial \nu_1} \psi_\beta & \frac{\partial}{\partial \nu_0} \psi_\beta & \frac{\partial}{\partial \alpha} \psi_\beta & \frac{\partial}{\partial \beta} \psi_\beta \end{bmatrix} \begin{matrix} \text{--- (1)} \\ \text{--- (2)} \\ \text{--- (3)} \\ \text{--- (4)} \end{matrix}$$

$$\begin{aligned} 1) \psi_{\nu_1} &= \nu_1 - \frac{(1 + e^{\beta^T X_T}) \{E_T Y_T - (E_T - \frac{e^{\beta^T X_T}}{1 + e^{\beta^T X_T}}) \cdot (1, 1, X_T^T) \alpha\}}{e^{\beta^T X_T}} \\ &= \nu_1 - \frac{(1 + e^{\beta^T X_T}) (E_T Y_T) - E_T (1 + e^{\beta^T X_T}) \cdot (1, 1, X_T^T) \alpha + e^{\beta^T X_T} \cdot (1, 1, X_T^T) \alpha}{e^{\beta^T X_T}} \\ &= \nu_1 - \frac{(1 + e^{\beta^T X_T}) E_T Y_T}{e^{\beta^T X_T}} + \frac{E_T (1 + e^{\beta^T X_T})}{e^{\beta^T X_T}} \cdot (1, 1, X_T^T) \alpha - (1, 1, X_T^T) \alpha \end{aligned}$$

Annotations:
 - **정렬** (blue arrow pointing to the fraction)
 - **++** (blue arrow pointing to the fraction)

$$\therefore \frac{\partial}{\partial \nu_1} \psi_{\nu_1} = 1 \quad / \quad \frac{\partial}{\partial \nu_0} \psi_{\nu_1} = 0$$

$$\therefore \frac{\partial}{\partial \alpha} \psi_1 = \frac{E_T(1+e^{\beta^T X_T})}{e^{\beta^T X_T}} \cdot (1, 1, X_T^T) - (1, 1, X_T^T) = \left(\frac{E_T(1+e^{\beta^T X_T})}{e^{\beta^T X_T}} - 1 \right) (1, 1, X_T^T)$$

Our situation ; (B.T. CT)

$$\therefore \psi_1 \text{ 에서 } \beta \text{ 와 관련된 부분 } \Rightarrow -\frac{E_T Y_T}{e^{\beta^T X_T}} + \frac{E_T(1, 1, X_T^T) \alpha}{e^{\beta^T X_T}} - \frac{E_T(Y_T - (1, 1, X_T^T) \alpha)}{e^{\beta^T X_T}} =$$

$$\begin{aligned} \frac{\partial}{\partial \beta} \psi_1 &= \frac{E_T Y_T \cdot e^{\beta^T X_T} \cdot X_T}{(e^{\beta^T X_T})^2} - \frac{E_T(1, 1, X_T^T) \alpha \cdot e^{\beta^T X_T} \cdot X_T}{(e^{\beta^T X_T})^2} + \frac{E_T(Y_T - (1, 1, X_T^T) \alpha) e^{\beta^T X_T} \cdot X_T}{(e^{\beta^T X_T})^2} \\ &= \frac{E_T(Y_T - (1, 1, X_T^T) \alpha + Y_T - (1, 1, X_T^T) \alpha) \cdot X_T}{e^{\beta^T X_T}} = \frac{2 \cdot E_T(Y_T - (1, 1, X_T^T) \alpha) \cdot X_T}{e^{\beta^T X_T}} \end{aligned}$$

PS model 의 model matrix

$$2) \psi_{v_0} = v_0 - (1+e^{\beta^T X_T})(1-E_T)Y_T + (1+e^{\beta^T X_T}) \cdot E_T \cdot (1, 0, X_T^T) \alpha - e^{\beta^T X_T} \cdot (1, 0, X_T^T) \alpha$$

$$\therefore \frac{\partial}{\partial v_1} \psi_{v_0} = 0, \quad \frac{\partial}{\partial v_0} \psi_{v_0} = 1, \quad \frac{\partial}{\partial \alpha} \psi_{v_0} = (1+e^{\beta^T X_T}) \cdot E_T \cdot (1, 0, X_T^T) - e^{\beta^T X_T} (1, 0, X_T^T)$$

$$= \{ (1+e^{\beta^T X_T}) \cdot E_T - e^{\beta^T X_T} \} (1, 0, X_T^T)$$

$$\therefore \psi_{v_0} \text{ 중 } \beta \text{ 와 관련된 부분 } \Rightarrow -e^{\beta^T X_T} (1-E_T) Y_T + e^{\beta^T X_T} \cdot E_T (1, 0, X_T^T) \alpha - e^{\beta^T X_T} (1, 0, X_T^T) \alpha$$

$$\begin{aligned} \frac{\partial}{\partial \beta} \psi_{v_0} &= -e^{\beta^T X_T} (1-E_T) Y_T \cdot X_T + e^{\beta^T X_T} \cdot E_T \cdot (1, 0, X_T^T) \alpha \cdot X_T - e^{\beta^T X_T} (1, 0, X_T^T) \alpha \cdot X_T \\ &= e^{\beta^T X_T} \cdot X_T (-(1-E_T) Y_T + E_T (1, 0, X_T^T) \alpha - (1, 0, X_T^T) \alpha) \\ &= e^{\beta^T X_T} (-(1-E_T) Y_T - (1, 0, X_T^T) \alpha (1-E_T)) X_T = -e^{\beta^T X_T} ((1-E_T) (Y_T + (1, 0, X_T^T) \alpha)) \cdot X_T \end{aligned}$$

PS model 의 model matrix

$$3) \psi_\alpha = X_T (Y_T - X_T^T \alpha) \quad (X_T \text{ 는 Outcome model 의 model matrix } \Rightarrow (1, E, X))$$

$$\therefore \frac{\partial}{\partial v_1} \psi_\alpha = 0, \quad \frac{\partial}{\partial v_0} \psi_\alpha = 0, \quad \frac{\partial}{\partial \alpha} \psi_\alpha = -X_T X_T^T, \quad \frac{\partial}{\partial \beta} \psi_\alpha = 0 \quad (\leftarrow \text{원인 개수는 0, 결과의 개수})$$

$$4) \psi_\beta = \frac{X_T}{1+e^{\beta^T X_T}} \quad (X_T \text{ 는 PS model 의 model matrix } \Rightarrow (1, X))$$

$$\therefore \frac{\partial}{\partial v_1} \psi_\beta = \frac{\partial}{\partial v_0} \psi_\beta = 0, \quad \frac{\partial}{\partial \alpha} \psi_\beta = 0 \quad (\leftarrow \text{원인 개수는 0, 결과의 개수})$$

$$\frac{\partial}{\partial \beta} \psi_\beta = \frac{-X_T \cdot e^{\beta^T X_T} \cdot X_T}{(1+e^{\beta^T X_T})^2} = \frac{-e^{\beta^T X_T} \cdot X_T \cdot X_T^T}{(1+e^{\beta^T X_T})^2}$$

PS model 의 model matrix