

# # Variance Estimator of DR Estimator : Sandwich Variance #

: 8월 24일 Version (DR of ATE)

1) Treatment model :  $\log \left( \frac{P(E=1|X)}{1-P(E=1|X)} \right) = \beta^T X \leftrightarrow e(X_T) = \frac{e^{\beta^T X_i}}{1 + e^{\beta^T X_i}}$

2) Outcome model :  $Y_T = \alpha^T X_T + \varepsilon_T \leftrightarrow E[Y_T | X_T] = \alpha^T X_T$

## [Score function of treatment model]

$E_i \sim \text{Ber}(p_T) / \log_{\pi}(p_T) = \beta^T X_i$  model 가정 :  $L(\beta; \underline{X}) \propto \prod_{i=1}^n p_i^{E_i} (1-p_i)^{1-E_i}$

$\log L(\beta; \underline{X}) \propto \sum_{i=1}^n E_i \log p_T + (1-E_i) \log (1-p_T)$

$\left( = \sum_{i=1}^n E_i \log \left( \frac{e^{\beta^T X_i}}{1 + e^{\beta^T X_i}} \right) + (1-E_i) \log \left( \frac{1}{1 + e^{\beta^T X_i}} \right) \right)$

$\left( = \sum_{i=1}^n (\beta^T X_i - \log(1 + e^{\beta^T X_i})) \right)$

$S(\beta; \underline{X}) = \frac{\partial}{\partial \beta} \log(L(\beta; \underline{X})) = \frac{X}{1 + e^{\beta^T X}}$

## [Score function of Outcome regression model]

$Y \sim N(X\alpha, \sigma^2) / f_Y(y) = \frac{1}{\sqrt{2\pi} \sigma} e^{-\frac{(y-X\alpha)^2}{2\sigma^2}}$

$L(\alpha; \underline{X}) \propto \prod_{i=1}^n e^{-\frac{(Y_i - X_i^T \alpha)^2}{2\sigma^2}} \Rightarrow \log L(\alpha; \underline{X}) \propto \frac{n}{2} - \frac{(Y_T - \alpha^T X_T)^2}{2\sigma^2}$

$\frac{\partial}{\partial \alpha} \log L(\alpha; \underline{X}) \propto \frac{n}{2} - \frac{2(Y_T - \alpha^T X_T) \cdot (-X_T)}{2\sigma^2} \left( = \sum_{i=1}^n \frac{X_T (Y_T - \alpha^T X_T)}{\sigma^2} \right)$

$S(\alpha; \underline{X}) \propto X(Y - \alpha^T X)$

$\hat{\psi}_T(\theta) = \begin{bmatrix} \mathcal{V}_1 - \{E_T Y_T - (E_T - \hat{e}_T) E[Y_T | \hat{E}_T=1, X_T]\} / \hat{e}_T \\ \mathcal{V}_0 - \{(1-E_T) Y_T + (E_T - \hat{e}_T) E[Y_T | \hat{E}_T=0, X_T]\} / (1-\hat{e}_T) \\ X_T (Y_T - \alpha^T X_T) \\ X_T \left( \frac{1}{1 + e^{\beta^T X_T}} \right) \end{bmatrix}$

# # Sandwich Variance Estimator of DR Estimator of ATE #

: 9월 1일 Version

$$\psi_T(\hat{\theta}) = \begin{bmatrix} \nu_1 - \frac{\{E_T Y_T - (E_T - \hat{e}_T) E[Y_T | \hat{E}=1, X_T]\}}{\hat{e}_T} & \dots (\psi_{\nu_1}) \\ \nu_0 - \frac{\{(1-E_T) Y_T - (E_T - \hat{e}_T) E[Y_T | \hat{E}=0, X_T]\}}{1 - \hat{e}_T} & \dots (\psi_{\nu_0}) \\ X_T (Y_T - \alpha^T X_T) & \dots (\psi_\alpha) \\ \frac{X_T}{1 + e^{\beta^T X_T}} & \dots (\psi_\beta) \end{bmatrix}, \quad \theta = (\nu_1, \nu_0, \alpha, \beta)$$

$$\begin{aligned} 1) \psi_{\nu_1} &= \nu_1 - \frac{(1 + e^{\beta^T X_T}) \{E_T Y_T - (E_T - \frac{e^{\beta^T X_T}}{1 + e^{\beta^T X_T}}) \cdot \alpha^T(1, 1, X_T)\}}{e^{\beta^T X_T}} \\ &= \nu_1 - \frac{(1 + e^{\beta^T X_T}) (E_T Y_T) - E_T (1 + e^{\beta^T X_T}) \cdot \alpha^T(1, 1, X_T) + e^{\beta^T X_T} \cdot \alpha^T(1, 1, X_T)}{e^{\beta^T X_T}} \end{aligned}$$

$$\begin{aligned} 2) \psi_{\nu_0} &= \nu_0 - (1 + e^{\beta^T X_T}) \{(1 - E_T) Y_T - (E_T - \frac{e^{\beta^T X_T}}{1 + e^{\beta^T X_T}}) \cdot \alpha^T(1, 0, X_T)\} \\ &= \nu_0 - (1 + e^{\beta^T X_T}) (1 - E_T) Y_T + (1 + e^{\beta^T X_T}) \cdot E_T \cdot \alpha^T(1, 0, X_T) - e^{\beta^T X_T} \cdot \alpha^T(1, 0, X_T) \end{aligned}$$

$$\frac{\partial}{\partial \theta'} \psi_T(\hat{\theta}) = \begin{bmatrix} \frac{\partial}{\partial \nu_1} \psi_{\nu_1}, \frac{\partial}{\partial \nu_0} \psi_{\nu_1}, \frac{\partial}{\partial \alpha} \psi_{\nu_1}, \frac{\partial}{\partial \beta} \psi_{\nu_1} & \dots (1) \\ \frac{\partial}{\partial \nu_1} \psi_{\nu_0}, \frac{\partial}{\partial \nu_0} \psi_{\nu_0}, \frac{\partial}{\partial \alpha} \psi_{\nu_0}, \frac{\partial}{\partial \beta} \psi_{\nu_0} & \dots (2) \\ \frac{\partial}{\partial \nu_1} \psi_\alpha, \frac{\partial}{\partial \nu_0} \psi_\alpha, \frac{\partial}{\partial \alpha} \psi_\alpha, \frac{\partial}{\partial \beta} \psi_\alpha & \dots (3) \\ \frac{\partial}{\partial \nu_1} \psi_\beta, \frac{\partial}{\partial \nu_0} \psi_\beta, \frac{\partial}{\partial \alpha} \psi_\beta, \frac{\partial}{\partial \beta} \psi_\beta & \dots (4) \end{bmatrix}$$

$$\begin{aligned} (1) \frac{\partial}{\partial \nu_1} \psi_{\nu_1} &= 1, \quad \frac{\partial}{\partial \nu_0} \psi_{\nu_0} = 0, \quad \frac{\partial}{\partial \alpha} \psi_{\nu_1} = \frac{E_T (1 + e^{\beta^T X_T}) (1, 1, X_T)}{e^{\beta^T X_T}} - (1, 1, X_T) \\ &= (1, 1, X_T) \left( \frac{E_T (1 + e^{\beta^T X_T})}{e^{\beta^T X_T}} - 1 \right) \end{aligned}$$

$$\frac{\partial}{\partial \beta} \psi_{\gamma_1} = \frac{-E_T(Y_T - \alpha^T(1, 1, X_T)) \cdot e^{\beta^T X_T} \cdot X_T}{(e^{\beta^T X_T})^2} = \frac{-E_T \cdot X_T (Y_T - \alpha^T(1, 1, X_T))}{e^{\beta^T X_T}}$$

$$(2) \frac{\partial}{\partial \gamma_1} \psi_{\gamma_0} = 0, \quad \frac{\partial}{\partial \gamma_0} \psi_{\gamma_0} = 1, \quad \frac{\partial}{\partial \alpha} \psi_{\gamma_0} = E_T \cdot (1, 0, X_T)$$

$$\begin{aligned} \frac{\partial}{\partial \beta} \psi_{\gamma_0} &= -e^{\beta^T X_T} (1 - E_T) Y_T \cdot X_T + e^{\beta^T X_T} X_T \cdot E_T \cdot \alpha^T(1, 0, X_T) - e^{\beta^T X_T} \cdot \alpha^T(1, 0, X_T) \cdot X_T \\ &= e^{\beta^T X_T} \cdot X_T \left\{ (E_T - 1) Y_T + E_T \cdot \alpha^T(1, 0, X_T) - \alpha^T(1, 0, X_T) \right\} \\ &= e^{\beta^T X_T} \cdot X_T \left\{ (E_T - 1) (Y_T + \alpha^T(1, 0, X_T)) \right\} \end{aligned}$$

$$(3) \frac{\partial}{\partial \gamma_1} \psi_{\alpha} = 0, \quad \frac{\partial}{\partial \gamma_0} \psi_{\alpha} = 0, \quad \frac{\partial}{\partial \alpha} \psi_{\alpha} = -X_T^T \cdot X_T, \quad \frac{\partial}{\partial \beta} \psi_{\alpha} = 0$$

$$(4) \frac{\partial}{\partial \gamma_1} \psi_{\beta} = 0, \quad \frac{\partial}{\partial \gamma_0} \psi_{\beta} = 0, \quad \frac{\partial}{\partial \alpha} \psi_{\beta} = 0, \quad \frac{\partial}{\partial \beta} \psi_{\beta} = \frac{-X_T \cdot e^{\beta^T X_T} \cdot X_T}{(1 + e^{\beta^T X_T})^2}$$

# # Sandwich Variance Estimator of DR ATT Estimator #

: 9월 1일 Version

$$\psi_T(\hat{\theta}) = \begin{bmatrix} v_1 - Y_T E_T & \dots (\psi_{v_1}) \\ v_0 - \frac{Y_T(1-E_T)\hat{e}(X_T) + \hat{E}[Y_T|E=0, X_T](E_T - \hat{e}(X_T))}{1 - \hat{e}(X_T)} & \dots (\psi_{v_0}) \\ X_T(Y_T - \hat{\alpha}^T X_T) & \dots (\psi_{\alpha}) \\ \frac{X_T}{1 + e^{\beta^T X_T}} & \dots (\psi_{\beta}) \end{bmatrix}, \quad \theta = (v_1, v_0, \alpha, \beta)$$

$$\begin{aligned} * \psi_{v_0} &= v_0 - \frac{Y_T(1-E_T) \cdot \frac{e^{\beta^T X_T}}{1+e^{\beta^T X_T}} + \alpha^T(1, 0, X_T) \cdot \left(E_T - \frac{e^{\beta^T X_T}}{1+e^{\beta^T X_T}}\right)}{1 - \frac{e^{\beta^T X_T}}{1+e^{\beta^T X_T}}} \\ &= v_0 - \frac{Y_T(1-E_T) \cdot \frac{e^{\beta^T X_T}}{1+e^{\beta^T X_T}} + \alpha^T(1, 0, X_T) \cdot \left(E_T - \frac{e^{\beta^T X_T}}{1+e^{\beta^T X_T}}\right)}{\frac{1}{1+e^{\beta^T X_T}}} \end{aligned}$$

$$= v_0 - Y_T(1-E_T) e^{\beta^T X_T} - \alpha^T(1, 0, X_T) (1+e^{\beta^T X_T}) \cdot E_T + \alpha^T(1, 0, X_T) e^{\beta^T X_T}$$

$$\frac{\partial}{\partial \theta'} \psi_T(\hat{\theta}) = \begin{bmatrix} \frac{\partial}{\partial v_1} \psi_{v_1}, & \frac{\partial}{\partial v_0} \psi_{v_1}, & \frac{\partial}{\partial \alpha} \psi_{v_1}, & \frac{\partial}{\partial \beta} \psi_{v_1} & \dots (1) \\ \frac{\partial}{\partial v_1} \psi_{v_0}, & \frac{\partial}{\partial v_0} \psi_{v_0}, & \frac{\partial}{\partial \alpha} \psi_{v_0}, & \frac{\partial}{\partial \beta} \psi_{v_0} & \dots (2) \\ \frac{\partial}{\partial v_1} \psi_{\alpha}, & \frac{\partial}{\partial v_0} \psi_{\alpha}, & \frac{\partial}{\partial \alpha} \psi_{\alpha}, & \frac{\partial}{\partial \beta} \psi_{\alpha} & \dots (3) \\ \frac{\partial}{\partial v_1} \psi_{\beta}, & \frac{\partial}{\partial v_0} \psi_{\beta}, & \frac{\partial}{\partial \alpha} \psi_{\beta}, & \frac{\partial}{\partial \beta} \psi_{\beta} & \dots (4) \end{bmatrix}$$

$$(1) \frac{\partial}{\partial v_1} \psi_{v_1} = 1, \quad \frac{\partial}{\partial v_0} \psi_{v_1} = 0, \quad \frac{\partial}{\partial \alpha} \psi_{v_1} = 0, \quad \frac{\partial}{\partial \beta} \psi_{v_1} = 0$$

$$(2) \frac{\partial}{\partial v_1} \psi_{v_0} = 0, \quad \frac{\partial}{\partial v_0} \psi_{v_0} = 1$$

$$\begin{aligned}\frac{\partial}{\partial \alpha} \psi_{v_0} &= -(1, 0, x_T) (1 + e^{\beta^T x_T}) E_T + (1, 0, x_T) e^{\beta^T x_T} = -(1, 0, x_T) E_T - (1, 0, x_T) e^{\beta^T x_T} \cdot E_T \\ &\quad + (1, 0, x_T) e^{\beta^T x_T} \\ &= -(1, 0, x_T) E_T + (1, 0, x_T) e^{\beta^T x_T} (1 - E_T)\end{aligned}$$

$$\begin{aligned}\frac{\partial}{\partial \beta} \psi_{v_0} &= -Y_T (1 - E_T) e^{\beta^T x_T} \cdot x_T - \alpha^T (1, 0, x_T) \cdot e^{\beta^T x_T} \cdot x_T \cdot E_T + \alpha^T (1, 0, x_T) e^{\beta^T x_T} \cdot x_T \\ &= e^{\beta^T x_T} \cdot x_T \{-Y_T (1 - E_T) - \alpha^T (1, 0, x_T) E_T + \alpha^T (1, 0, x_T)\} \\ &= e^{\beta^T x_T} \cdot x_T \{-Y_T (1 - E_T) + \alpha^T (1, 0, x_T) (1 - E_T)\} = -e^{\beta^T x_T} \cdot x_T \cdot (1 - E_T) (Y_T - \alpha^T (1, 0, x_T))\end{aligned}$$

$$(3) \frac{\partial}{\partial v_1} \psi_\alpha = 0, \quad \frac{\partial}{\partial v_0} \psi_\alpha = 0, \quad \frac{\partial}{\partial \alpha} \psi_\alpha = -x_T x_T^T, \quad \frac{\partial}{\partial \beta} \psi_\alpha = 0$$

$$(4) \frac{\partial}{\partial v_1} \psi_\beta = 0, \quad \frac{\partial}{\partial v_0} \psi_\beta = 0, \quad \frac{\partial}{\partial \alpha} \psi_\beta = 0, \quad \frac{\partial}{\partial \beta} \psi_\beta = \frac{-x_T \cdot e^{\beta^T x_T} \cdot x_T}{(1 + e^{\beta^T x_T})^2}$$