

Inference Path

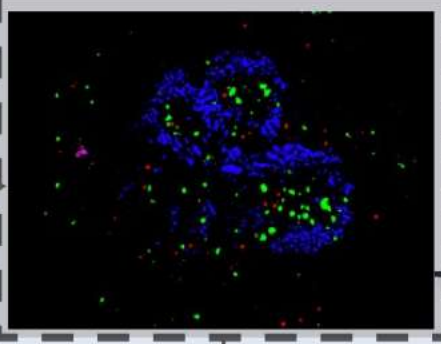
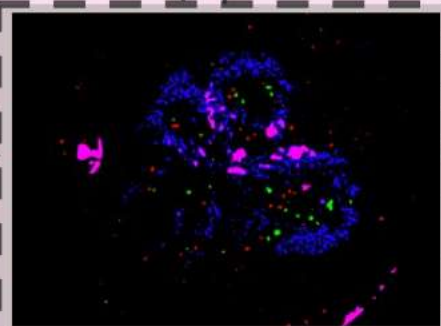
Supervised Path



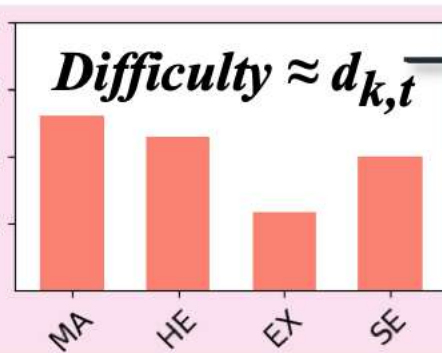
Labeled Image

f_{diff}

f_{dist}

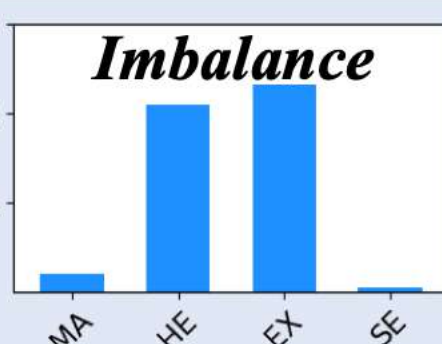


1-Dice



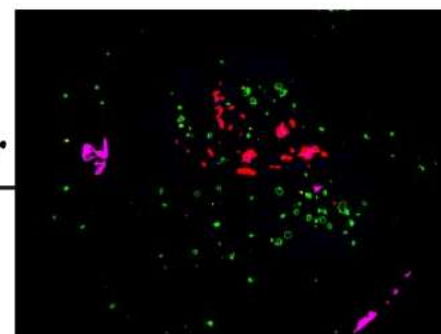
$W_{diff} L_{seg}$

pix(%)



$W_{dist} L_{seg}$

L_{cor}



Correction Module

L_{Dice}

Reverse $d_{k,t}$

Unsupervised Path



Unlabeled Image

Select One

Vector

Vector

f_{diff}

f_{dist}^*

f_{diff}^*

f_{dist}

$f_{diff}(x_u)$

P_{dist}

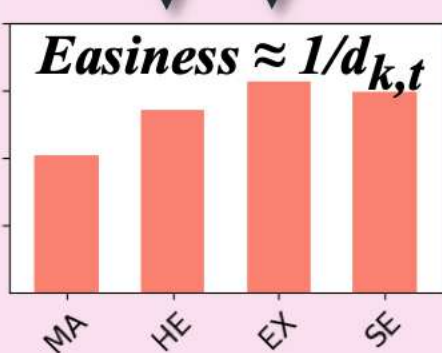
P_{diff}

$f_{dist}(x_u)$

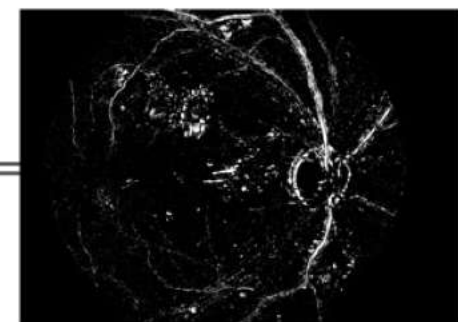
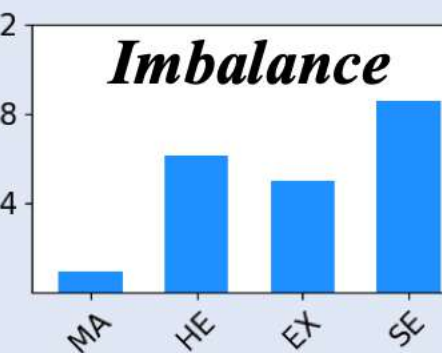
$W_{easy} L_{cons}$

$W_{min} L_{cons}$

Dice



pix(%)



Saliency Map