

## **Scheduling: Introduction**

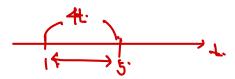


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#### Workload Assumptions and Scheduling Metrics

- Now, we have to understand the high-level policies that an OS scheduler employs
  - Before diving into the scheduling, let's make some assumption about the processes running in the system, which is called the workload
- We make the following assumptions about the processes (jobs)
  - 1) Each job run for the same amount of time
  - 2) All jobs arrives at the same time
  - 3) Once started, each job runs to completion
  - 4) All jobs only use the CPU (no I/O)
  - 5) The run-time of each job is known



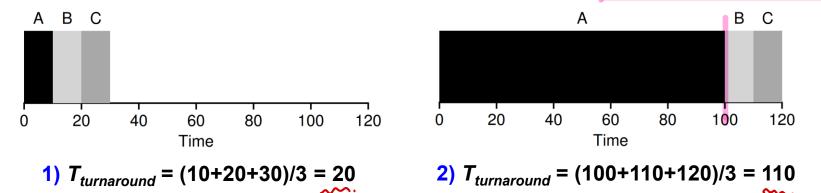
- We need one thing to compare different scheduling policies
  - Turnaround time is performance metric defined by  $T_{turnaround} = T_{completion} T_{arrival}$
  - In our assumptions,  $T_{arrival} = 0$  and hence  $T_{turnaround} = T_{completion}$
  - Another metric is fairness, which is often at odds with performance in scheduling

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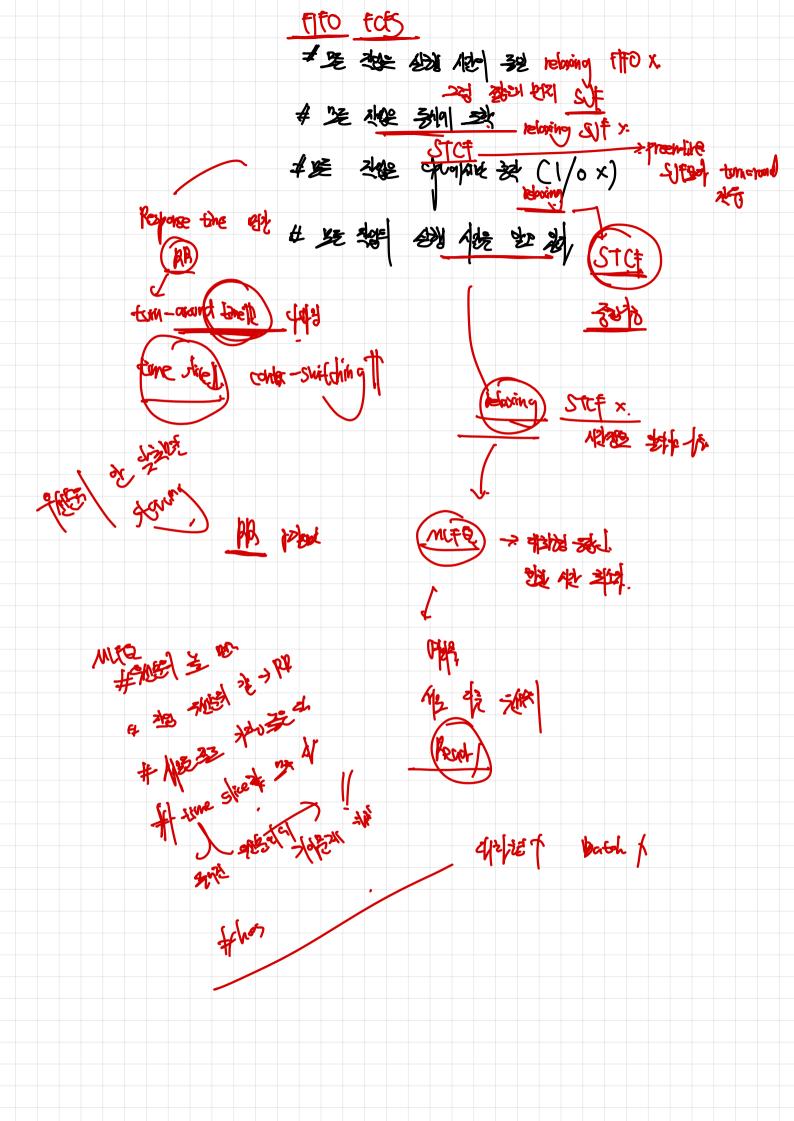
- The most basic algorithms is First In, First Out (FIFO) scheduling
  - This is sometimes called First Come, First Served (FCFS)
  - It is simple and easy to implement, and works well in some cases

#### Let's do a quick example

- 1) Three jobs (A, B, C) arrive at the same time ( $T_{arrival} = 0$ ) and each job runs for 10; A arrived just a hair before B which did just before C
- 2) What if A runs for 100 while B and C run for 10 each? (relaxing assumption #1)

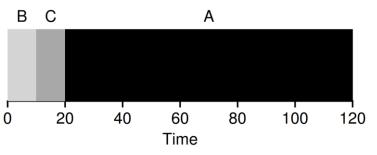


- The FCFS can cause a convoy effect
  - A number of relatively-short potential consumers of a resource get queued behind a heavyweight resource consumer → long waiting time

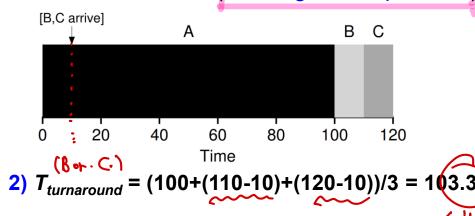


### **Shortest Job First (SJF)**

- Shortest Job First (SJF) algorithm runs the shortest job first, then the next shortest, and so on
  - This is a very simple approach to avoid the convoy effect
- Let's take the same example but with SJF
  - 1) SJF reduces average turnaround time from 110 to 50
  - 2) What if A arrives at t=0 and B and C arrive at t = 10? (relaxing assumption #2)



1) 
$$T_{turnaround} = (10+20+120)/3 = 50$$



- SJF is an optimal scheduling if all jobs arrive at the same time
  - Otherwise, it can also suffer from the same convoy problem as shown in 2)

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#### **Shortest Time-to-Completion First (STCF)**

- Shortest Time-to-Completion First (STCF) algorithm adds the preemption on top of SJF
  - This is also known as Preemptive Shortest Job First (PSJF) scheduler
  - Anytime a new job enters, the STCF scheduler determines which of remaining jobs (including the new job) has the least time left, and schedules that one
- Preemptive vs Non-preemptive scheduling
  - Preemptive: dan stop a job to run another, require the context switch
  - Non-preemptive: run a job to completion (can't stop a job until finishing)
- Let's take the same example but with STCF

80

- STCF reduces average turnaround time from 103.3 to 50

[B,C arrive]

A  $T_{turnaround} = ((120-0)+(20-10)+(30-10)+$ 

120

STCF is provably optimal given our new assumptions

100

20

40

60

Time

#### A New Metric: Response Time

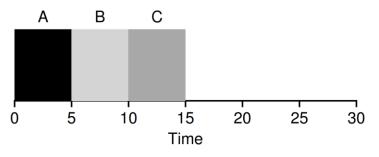
- The turnaround time is a good metric for early batch systems
  - However, the introduction of time-shared machines changed all that
  - Now users would sit a terminal and demand interactive performance as well
- A new metric was born: response time 文章 4 本語 中 超之 4
  - We define response time as time from when the job arrives to the first time it scheduled, more formally:  $T_{response} = T_{firstrun} T_{arrival}$

- STCF and related disciplines are not particularly good for response time
  - Imagine sitting at a terminal, typing, and having to wait 10 seconds to see a response from the system; not too pleasant
- Then, how can we build a scheduler sensitive to response time?

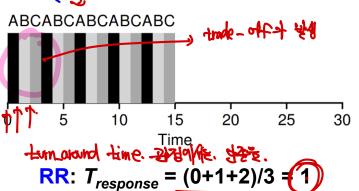
## Round Robin (RR) → 张, 传 程序 数析 金



- To solve this, we introduce Round Robin (RR) scheduling
  - Instead of running jobs to completion, RR runs a job for a time slice (scheduling quantum, time quantum) and then switches to the next job in the run queue
  - It repeatedly does so until the jobs are finished; called time-slicing
  - The length of a time slice must be a multiple of the timer-interrupt period
- Let's look at an example
  - Three jobs (A, B, C) arrive at the same time, each runs for 5, time slice is 1



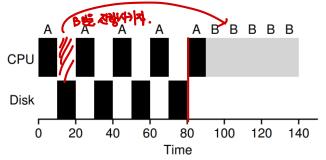
SJF: 
$$T_{response} = (0+5+10)/3 = 5$$



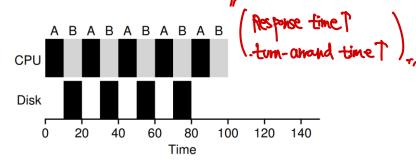
- As can be seen, the length of the time slice is critical for RR
  - The short it is, the better the response time; too short  $\rightarrow$  context switch cost  $\uparrow$
  - Deciding on the length presents a trade-off to a system designer

## Incorporating I/O

- Obviously, all programs perform I/O and let's relax assumption #4
  - A scheduler has a decision when a job has an I/O request and I/O complete
- Let's consider an example
  - Two jobs (A, B), which each needs 50 ms of CPU time A uns for 10 ms and then requests I/O (takes 10 ms) and B uses the CPU for 50 ms with no I/O



Waiting for I/O completion: Poor use of resources



Scheduling for another job: Better use of resources

- For better utilizing the processor, the scheduler should make
  - the CPU-intensive jobs (job B) run while the interactive jobs (job A) are performing I/O