

Chapter 3. Determinant

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In This Chapter...

- Determinant
 - A Scalar value
 - Numbers or functions
 - Only square matrix
 - Rule for determinant
 - Similar to the 2×2 matrix in Chapter 2
 - Develop some properties of determinants
 - Evaluate and make usage of determinants

Introduction

- In Chapter 2
 - A 2×2 invertible matrix $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$
 - $ad - bc \neq 0$
 - For a 3×3 matrix

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{11}a_{21} & a_{11}a_{22} & a_{11}a_{23} \\ a_{11}a_{31} & a_{11}a_{32} & a_{11}a_{33} \end{bmatrix} \sim \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{11}a_{22} - a_{12}a_{21} & a_{11}a_{23} - a_{13}a_{21} \\ 0 & a_{11}a_{32} - a_{12}a_{31} & a_{11}a_{33} - a_{13}a_{31} \end{bmatrix} \quad (1)$$

$$A \sim \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{11}a_{22} - a_{12}a_{21} & a_{11}a_{23} - a_{13}a_{21} \\ 0 & 0 & a_{11}\Delta \end{bmatrix}$$

$$\Delta = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33} - a_{13}a_{22}a_{31} \quad (2)$$

$$\Delta = a_{11} \cdot \det \begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} - a_{12} \cdot \det \begin{bmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{bmatrix} + a_{13} \cdot \det \begin{bmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}$$

Permutation

- Rearrangement of some integers

$$1, 2, 3, 4, 5, 6 \rightarrow 3, 1, 4, 5, 2, 6,$$

then $p(1) = 3$, $p(2) = 1$, $p(3) = 4$, $p(4) = 5$, $p(5) = 2$ and $p(6) = 6$.

A permutation is characterized as even or odd according to a rule we will illustrate. Consider the permutation

$$p: 1, 2, 3, 4, 5 \rightarrow 2, 5, 1, 4, 3$$

of the integers 1, 2, 3, 4, 5. For each k in the permuted list on the right, count the number of integers to the right of k that are smaller than k . There is one number to the right of 2 smaller than 2, three numbers to the right of 5 smaller than 5, no numbers to the right of 1 smaller than 1, one number to the right of 4 smaller than 4, and no numbers to the right of 3 smaller than 3. Since $1 + 3 + 0 + 1 + 0 = 5$ is odd, p is an *odd permutation*. When this sum is even, p is an *even permutation*.

If p is a permutation on $1, 2, \dots, n$, define

$$\sigma(p) = \begin{cases} 1 & \text{if } p \text{ is an even permutation} \\ -1 & \text{if } p \text{ is an odd permutation.} \end{cases}$$

Determinant

- Definition

The *determinant* of an $n \times n$ matrix \mathbf{A} is defined to be

$$\det \mathbf{A} = \sum_p \sigma(\underline{p}) a_{1p(1)} a_{2p(2)} \cdots a_{np(n)} \quad (8.1)$$

with this sum extending over all permutations p of $1, 2, \dots, n$. Note that $\det \mathbf{A}$ is a sum of terms, each of which is plus or minus a product containing one element from each row and each column of \mathbf{A} .

- Notation

- $\det A$ as $|A|$

$$\det A = \sum_p$$

Determinant

- Example) $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$

- Only two permutations

- $p_1: 1,2 \rightarrow 1,2$ and $p_2: 1,2 \rightarrow 2,1$

$$|A| = \sigma(p_1) a_{1p_1(1)} a_{2p_1(2)} + \sigma(p_2) a_{1p_2(1)} a_{2p_2(2)}$$

$$= a_{11} a_{22} - a_{12} a_{21}.$$

$$\begin{pmatrix} p_1: 1,2 \rightarrow 1,2 \\ p_2: 1,2 \rightarrow 2,1 \end{pmatrix}$$

$$\sigma(p_1) = 0 \text{ (even)} \quad \begin{pmatrix} +1 \\ -1 \end{pmatrix}$$

$$\sigma(p_2) = 1 \text{ (odd)}$$

$$|A| = \sigma(p_1) a_{1p_1(1)} a_{2p_1(2)} + \sigma(p_2) a_{1p_2(1)} a_{2p_2(2)}$$

$$= (a_{11} a_{22} - a_{12} a_{21})$$

Determinant

• Example) $A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$

- Six permutations

$p_1 : 1, 2, 3 \rightarrow 1, 2, 3, \text{ (even)}; p_2 : 1, 2, 3, \rightarrow 1, 3, 2, \text{ (odd)};$

$p_3 : 1, 2, 3 \rightarrow 2, 3, 1, \text{ (even)}; p_4 : 1, 2, 3, \rightarrow 2, 1, 3, \text{ (odd)};$

$p_5 : 1, 2, 3, \rightarrow 3, 1, 2, \text{ (even)}; p_6 : 1, 2, 3, \rightarrow 3, 2, 1, \text{ (odd)}.$

$\sigma(p_1) a_{1p_1(1)} a_{2p_1(2)} a_{3p_1(3)}$

$+ \sigma(p_2) a_{1p_2(1)} a_{2p_2(2)} a_{3p_2(3)}$

$+ \sigma(p_3) a_{1p_3(1)} a_{2p_3(2)} a_{3p_3(3)}.$

이것이 4행 5열.

Determinant

- Some fundamental properties of determinants

- $|A^t| = |A|$
- $|A| = 0$, if A has a zero row or column
- If B is formed from A by type I operation, $|B| = -|A|$ → type I

$$b_{11} = a_{31}, b_{12} = a_{32}, b_{13} = a_{33},$$

$$b_{21} = a_{21}, b_{22} = a_{22}, b_{23} = a_{23},$$

$$b_{31} = a_{11}, b_{32} = a_{12}, b_{33} = a_{13}.$$

$$\begin{aligned} |B| &= b_{11}b_{22}b_{33} - b_{11}b_{23}b_{32} + b_{12}b_{23}b_{31} \\ &= -b_{12}b_{21}b_{33} + b_{13}b_{21}b_{32} - b_{13}b_{22}b_{31} \\ &= a_{31}a_{22}a_{13} - a_{31}a_{23}a_{12} + a_{32}a_{23}a_{11} \\ &= -a_{32}a_{21}a_{13} + a_{33}a_{21}a_{12} - a_{33}a_{22}a_{11} \\ &= -|A|. \end{aligned}$$

- If two rows or two columns are same, $|A| = 0$ ↗
- If B is formed from A by type II operation(α), $|B| = \alpha|A|$
- If one row or column of A is a constant multiple of another row or column, $|A| = 0$ ↖

$$\begin{aligned} 2x_1 + 3x_2 &= 0 \\ 4x_1 + 6x_2 &= 0 \end{aligned}$$

$$\left[\begin{array}{cc|c} 2 & 3 & 0 \\ 4 & 6 & 0 \end{array} \right] \xrightarrow{\text{row 2} - 2 \times \text{row 1}} \left[\begin{array}{cc|c} 2 & 3 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

trivial solution
↖
 $2x_1 + 3x_2 = 0$

Determinant

$$\frac{2x_1 = -3x_2}{\text{trivial } \curvearrowright}$$

Some fundamental properties of determinants

- Each element of row k of A , $a_{kj} = b_{kj} + c_{kj}$

$$B = \begin{pmatrix} a_{11} & \cdots & a_{1j} & \cdots & a_{1n} \\ \vdots & & \vdots & & \vdots \\ b_{k1} & \cdots & b_{kj} & \cdots & b_{kn} \\ \vdots & & \vdots & & \vdots \\ a_{n1} & \cdots & a_{nj} & \cdots & a_{nn} \end{pmatrix}, \quad C = \begin{pmatrix} a_{11} & \cdots & a_{1j} & \cdots & a_{1n} \\ \vdots & & \vdots & & \vdots \\ c_{k1} & \cdots & c_{kj} & \cdots & c_{kn} \\ \vdots & & \vdots & & \vdots \\ a_{n1} & \cdots & a_{nj} & \cdots & a_{nn} \end{pmatrix}$$

fundamental rule

- $|A| = |B| + |C|$

- If D is formed from A by type III operation, $|D| = |A|$

$$D = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{i1} & a_{i2} & \cdots & a_{in} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha a_{i1} + a_{k1} & \alpha a_{i2} + a_{k2} & \cdots & \alpha a_{in} + a_{kn} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{i1} & a_{i2} & \cdots & a_{in} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha a_{i1} & \alpha a_{i2} & \cdots & \alpha a_{in} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} + \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{i1} & a_{i2} & \cdots & a_{in} \\ \vdots & \vdots & \ddots & \vdots \\ a_{k1} & a_{k2} & \cdots & a_{kn} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix}$$

linearly dependent $\rightarrow 0$

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linearly dependent: $\det = 0$

\downarrow
 $\det = |A|$

Determinant

- Some fundamental properties of determinants
 - If A is ~~nonsingular~~ nonsingular, $|A| \neq 0$
 - If A, B are $n \times n$ matrices, $|AB| = |A||B|$

$$|AB| = |A||B|$$

Evaluation of Determinants I

- Example) $A = \begin{pmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$

$$(-1)^{1+1} a_{11} |A_{11}|$$

$$= a_{11} |A_{11}|$$

$$= a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix}$$

$$= a_{11} (a_{22}a_{33} - a_{23}a_{32})$$

Determinant

- Definition

co-factor expansion

For $n \geq 2$, the determinant of an $n \times n$ matrix $A = [a_{ij}]$ is the sum of n terms of the form $\pm a_{1j} \det A_{1j}$, with plus and minus signs alternating, where the entries $a_{11}, a_{12}, \dots, a_{1n}$ are from the first row of A . In symbols,

$$\begin{aligned}\det A &= a_{11} \det A_{11} - a_{12} \det A_{12} + \cdots + (-1)^{1+n} a_{1n} \det A_{1n} \\ &= \sum_{j=1}^n (-1)^{1+j} a_{1j} \det A_{1j}\end{aligned}$$

Determinant

- Theorem 1

The determinant of an $n \times n$ matrix A can be computed by a cofactor expansion across any row or down any column. The expansion across the i th row using the cofactors in (4) is

$$\det A = a_{i1}C_{i1} + a_{i2}C_{i2} + \cdots + a_{in}C_{in}$$

The cofactor expansion down the j th column is

$$\det A = a_{1j}C_{1j} + a_{2j}C_{2j} + \cdots + a_{nj}C_{nj}$$

- Theorem 2

If A is a triangular matrix, then $\det A$ is the product of the entries on the main diagonal of A .

$$\begin{bmatrix} 1 & 0 & 0 \\ 4 & 2 & 0 \\ -5 & 6 & 3 \end{bmatrix}$$

Properties of Determinants

- Theorem 3



Row Operations

Let A be a square matrix.

- If a multiple of one row of A is added to another row to produce a matrix B , then $\det B = \det A$.
type III operation.
- If two rows of A are interchanged to produce B , then $\det B = -\det A$.
type I operation.
- If one row of A is multiplied by k to produce B , then $\det B = k \cdot \det A$.
type II operation.

Evaluation of Determinants I

- Lemma 8.1

Let \mathbf{A} be $n \times n$, and suppose row k or column r has all zero elements, except perhaps for a_{kr} . Then

$$|\mathbf{A}| = (-1)^{k+r} a_{kr} |\mathbf{A}_{kr}|, \quad (8.3)$$

where \mathbf{A}_{kr} is the $(n-1) \times (n-1)$ matrix formed by deleting row k and column r of \mathbf{A} . ♦

$$\mathbf{A} = \begin{pmatrix} a_{11} & 0 & 0 & \cdots & 0 \\ a_{12} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{pmatrix}.$$

Evaluation of Determinants I

• Example) $A = \begin{pmatrix} 4 & 2 & -3 \\ 3 & 4 & 6 \\ 2 & -6 & 8 \end{pmatrix} \rightarrow B = \begin{pmatrix} 4 & 2 & -3 \\ -5 & 0 & 12 \\ 14 & 0 & -1 \end{pmatrix}$

○ row2 of B: $-2 \cdot (\text{row1}) + \text{row2}$

○ row3 of B: $3 \cdot (\text{row1}) + \text{row3}$

○ If B is formed from A by type III operation, $|B| = |A|$

○ $|A| = |B|$

$$= -2 \begin{vmatrix} -5 & 12 \\ 14 & -1 \end{vmatrix} = -2 (5 - 168) = -2 \cdot -163 = 326$$

• $|B| = (-1)^{1+2}(2)|B_{12}| = -2 \begin{vmatrix} -5 & 12 \\ 14 & -1 \end{vmatrix} = -2(5 - 168) = 326$

Evaluation of Determinants I

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 4 & 0 \\ 3 & 5 & 6 \end{pmatrix} \quad 6.$$

•
$$\mathbf{A} = \begin{pmatrix} -6 & 0 & 1 & 3 & 2 \\ -1 & 5 & 0 & 1 & 7 \\ 8 & 3 & 2 & 1 & 7 \\ 0 & 1 & 5 & -3 & 2 \\ 1 & 15 & -3 & 9 & 4 \end{pmatrix} \rightarrow \mathbf{B} = \begin{pmatrix} -6 & 0 & 1 & 3 & 2 \\ -1 & 5 & 0 & 1 & 7 \\ 20 & 3 & 0 & -5 & 3 \\ 30 & 1 & 0 & -18 & -8 \\ -17 & 15 & 0 & 18 & 10 \end{pmatrix}.$$

$$\mathbf{C} = \begin{pmatrix} -1 & 5 & 1 & 7 \\ 20 & 3 & -5 & 3 \\ 30 & 1 & -18 & -8 \\ -17 & 15 & 18 & 10 \end{pmatrix} \rightarrow \mathbf{D} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 20 & 103 & 15 & 143 \\ 30 & 151 & 12 & 202 \\ -17 & 70 & 1 & -109 \end{pmatrix}.$$

$$\mathbf{E} = \begin{pmatrix} 103 & 15 & 143 \\ 151 & 12 & 202 \\ -70 & 1 & -109 \end{pmatrix} \rightarrow \mathbf{F} = \begin{pmatrix} 1153 & 0 & 1778 \\ 991 & 0 & 1510 \\ -70 & 1 & -109 \end{pmatrix}.$$

Evaluation of Determinants II

- Cofactor expansion.

THEOREM 8.2 Cofactor Expansion by a Row

For any k with $1 \leq k \leq n$.

$$|\mathbf{A}| = \sum_{j=1}^n (-1)^{k+j} a_{kj} M_{kj}. \quad \blacklozenge \quad (8.4)$$

THEOREM 8.3 Cofactor Expansion by a Column

For any j with $1 \leq j \leq n$,

$$|\mathbf{A}| = \sum_{i=1}^n (-1)^{i+j} a_{ij} M_{ij}. \quad \blacklozenge \quad (8.5)$$

Evaluation of Determinants II

- Cofactor expansion

$$|\mathbf{A}| = |[a_{ij}]| = \begin{vmatrix} a_{11} & a_{12} & \cdots & \cdots & a_{1n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{k1} & a_{k2} & \cdots & \cdots & a_{kn} \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{vmatrix} = \begin{vmatrix} a_{11} & a_{12} & \cdots & \cdots & a_{1n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{k1} & 0 & \cdots & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{vmatrix}$$

$$\begin{aligned} \det \begin{pmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \\ m & n & o & p \end{pmatrix} &= afkp - aflo - agjp + agln + ahjo - ahkn - bekp + belo + bgip - bgln - bhio + bhkm \\ &\quad + cejp - celn - cfip + cflm + chin - chjm - dejo + dekn + dfio - dfkm - dgin + dgjm \\ &= a \det \begin{pmatrix} f & g & h \\ j & k & l \\ n & o & p \end{pmatrix} - b \det \begin{pmatrix} e & g & h \\ i & k & l \\ m & o & p \end{pmatrix} + c \det \begin{pmatrix} e & f & h \\ i & j & l \\ m & n & p \end{pmatrix} - d \det \begin{pmatrix} e & f & g \\ i & j & k \\ m & n & o \end{pmatrix} \\ &= \begin{vmatrix} a & b \\ e & f \end{vmatrix} \cdot \begin{vmatrix} k & l \\ o & p \end{vmatrix} - \begin{vmatrix} a & c \\ e & g \end{vmatrix} \cdot \begin{vmatrix} j & l \\ n & p \end{vmatrix} + \begin{vmatrix} a & d \\ e & h \end{vmatrix} \cdot \begin{vmatrix} j & k \\ n & o \end{vmatrix} + \begin{vmatrix} b & c \\ f & g \end{vmatrix} \cdot \begin{vmatrix} i & l \\ m & p \end{vmatrix} - \begin{vmatrix} b & d \\ f & h \end{vmatrix} \cdot \begin{vmatrix} i & k \\ m & o \end{vmatrix} + \begin{vmatrix} c & d \\ g & h \end{vmatrix} \cdot \begin{vmatrix} i & j \\ m & n \end{vmatrix} \\ &\quad + \begin{vmatrix} \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & a_{k2} & \cdots & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \cdots & \cdots & a_{nn} \end{vmatrix} + \cdots + \begin{vmatrix} \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & \cdots & a_{kn} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \cdots & \cdots & a_{nn} \end{vmatrix}. \end{aligned}$$

Evaluation of Determinants II

- Example) $A = \begin{pmatrix} -6 & 3 & 7 \\ 12 & -5 & -9 \\ 2 & 4 & -6 \end{pmatrix}$

- $|A| = -6 \begin{vmatrix} -5 & -9 \\ 4 & -6 \end{vmatrix} - 3 \begin{vmatrix} 12 & -9 \\ 2 & -6 \end{vmatrix} + 7 \begin{vmatrix} 12 & -5 \\ 2 & 4 \end{vmatrix} = 172$

$$= -6 (30 + 36) - 3 (-12 + 18) + 7 (48 + 10)$$

$$= -6 \cdot 66 - 3 \cdot -6 + 7 \cdot 58$$

$$= -396 + 18 + 406$$

$$= \underline{\underline{172}}$$

A (Determinant Formula) for A^{-1}

$$b_{ij} = \frac{1}{|A|} (-1)^{i+j} M_{ji}$$

- Elements of a (matrix inverse)

THEOREM 8.4 Elements of a Matrix Inverse

Let A be a nonsingular $n \times n$ matrix and define an $n \times n$ matrix $B = [b_{ij}]$ by

$$b_{ij} = \frac{1}{|A|} (-1)^{i+j} M_{ji}$$

Then $B = A^{-1}$. ♦

(determinant = ~~行列식~~
제행렬의 행렬식)

- M_{ji} : determinant of $(n-1) \times (n-1)$ matrix from A removing row j and column i

$$b_{ij} = \frac{1}{|A|} (-1)^{i+j} (M_{ji})$$

A Determinant Formula for A^{-1}

• Example) $A = \begin{pmatrix} -2 & 4 & 1 \\ 6 & 3 & -3 \\ 2 & 9 & -5 \end{pmatrix}$

$A^{-1} = B$

$B_{11} = \begin{vmatrix} 3 & -3 \\ 9 & -5 \end{vmatrix} = -15 - (-27) = 12$

$B_{12} = - \begin{vmatrix} 6 & -3 \\ 2 & -5 \end{vmatrix} = -(-30 - (-6)) = -(-24) = 24$

$B_{13} = \begin{vmatrix} 6 & 3 \\ 2 & 9 \end{vmatrix} = 54 - 6 = 48$

$B_{21} = \begin{vmatrix} 4 & 1 \\ 3 & -3 \end{vmatrix} = -12 - 3 = -15$

$B_{22} = - \begin{vmatrix} -2 & 1 \\ 6 & -3 \end{vmatrix} = -(6 - 6) = 0$

$B_{23} = \begin{vmatrix} -2 & 4 \\ 6 & 3 \end{vmatrix} = (-6 - 24) = -30$

$B = \begin{pmatrix} 12 & 24 & -15 \\ 24 & 0 & 0 \\ 48 & 26 & -30 \end{pmatrix} \times \frac{1}{\det(A)}$

$B_{21} = - \begin{vmatrix} 4 & 1 \\ 9 & -5 \end{vmatrix} = -(-20 - 9) = 29$

$B_{22} = \begin{vmatrix} -2 & 1 \\ 2 & -5 \end{vmatrix} = (10 - 2) = 8$

$B_{23} = - \begin{vmatrix} -2 & 4 \\ 2 & 9 \end{vmatrix} = -(-18 - 8) = 26$

$\begin{pmatrix} -2 & 4 & 1 \\ 2 & 1 & -1 \\ 2 & 9 & -5 \end{pmatrix}$

$\begin{pmatrix} -2 & 4 & 1 \\ 0 & 5 & 0 \\ 0 & 13 & -4 \end{pmatrix}$

$-2 \cdot (-1)^{1+1} \begin{vmatrix} 5 & 0 \\ 13 & -4 \end{vmatrix}$

$= -2 \begin{vmatrix} -20 & \end{vmatrix} = 20$

$\therefore \begin{bmatrix} 0.1 & 0.24 & -0.13 \\ 0.2 & 0.01 & 0 \\ 0.4 & 0.22 & -0.25 \end{bmatrix}$

Cramer's Rule

- A determinant formula for the unique solution of a nonhomogeneous system $AX = B$, when A is nonsingular
 - $x_k = \frac{1}{|A|} |A(k; B)|$, for $k = 1, 2, \dots, n$,
 - $A(k; B)$ is the matrix obtained from A by replacing column k of A with B

Let \mathbf{A} be a nonsingular $n \times n$ matrix of numbers, and \mathbf{B} be an $n \times 1$ matrix of numbers. Then the unique solution of $\mathbf{AX} = \mathbf{B}$ is determined by

$$x_k = \frac{1}{|A|} |A(k; B)| \quad (8.7)$$

for $k = 1, 2, \dots, n$, where $\mathbf{A}(k; \mathbf{B})$ is the matrix obtained from \mathbf{A} by replacing column k of \mathbf{A} with \mathbf{B} . ♦

Cramer's Rule

- A determinant formula for the unique solution of a nonhomogeneous system $AX = B$, when A is nonsingular.
 - $x_k = \frac{1}{|A|} |A(k; B)|$, for $k = 1, 2, \dots, n$,
 - $A(k; B)$ is the matrix obtained from A by replacing column k of A with B

$$x_k |A| = \begin{vmatrix} a_{11} & a_{12} & \cdots & a_{1k}x_k & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2k}x_k & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nk}x_k & \cdots & a_{nn} \end{vmatrix} \cdot B = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}.$$

replacing column k of A with B .

$$\uparrow x_k(A) = |A(k, B)|$$

$$x_k = \frac{1}{|A|} |A(k, B)|$$

Cramer's Rule

- A determinant formula for the unique solution of a nonhomogeneous system $AX = B$, when A is nonsingular
 - $x_k = \frac{1}{|A|} |A(k; B)|$, for $k = 1, 2, \dots, n$,
 - $A(k; B)$ is the matrix obtained from A by replacing column k of A with B

$x_k |A| = \begin{vmatrix} a_{11} & a_{12} & \cdots & a_{11}x_1 + \cdots + a_{1n}x_n & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{21}x_1 + \cdots + a_{2n}x_n & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{n1}x_1 + \cdots + a_{nn}x_n & \cdots & a_{nn} \end{vmatrix}$

Handwritten notes: "type II operation" (circled), "type III operation" (circled), "determinant changes x" (with a red 'x' over the word determinant).

$= \begin{vmatrix} a_{11} & a_{12} & \cdots & b_1 & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & b_2 & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \cdots & b_n & \cdots & a_{nn} \end{vmatrix} = |A(k; B)|$

Handwritten notes: "C" (above the arrow), "→" (red arrow pointing to the final determinant).

Cramer's Rule

"계산은 그렇게 하지"

$$X_i = \frac{1}{|A|} |A(i, B)|$$

- Example)
$$\begin{aligned} x_1 - 3x_2 - 4x_3 &= 1 \\ -x_1 + x_2 - 3x_3 &= 14 \\ x_2 - 3x_3 &= 5 \end{aligned}$$

$$\left[\begin{array}{ccc|c} 1 & -3 & -4 & 1 \\ -1 & 1 & -3 & 14 \\ 0 & 1 & -3 & 5 \end{array} \right]$$

$$\left(\begin{array}{ccc|c} 1 & -3 & -4 & 1 \\ 0 & -2 & -7 & 15 \\ 0 & 0 & -\frac{13}{2} & \frac{27}{2} \end{array} \right)$$

non-singular

$$\left(\begin{array}{ccc|c} 1 & -3 & -4 & 1 \\ 0 & -2 & -7 & 15 \\ 0 & 1 & -3 & 5 \end{array} \right)$$

$$X_3 = \frac{1}{|A|} \left| \begin{array}{cc|c} 1 & -3 & 1 \\ -1 & 1 & 14 \\ 0 & 1 & 5 \end{array} \right|$$

$$X_1 = \frac{1}{|A|} |A(1, B)| = \frac{1}{|A|} \left| \begin{array}{cc|c} 1 & -3 & 14 \\ -1 & 1 & 5 \\ 0 & 1 & -3 \end{array} \right|$$

$$X_2 = \frac{1}{|A|} |A(2, B)| = \frac{1}{|A|} \left| \begin{array}{cc|c} 1 & -4 & 1 \\ -1 & -3 & 14 \\ 0 & -3 & 5 \end{array} \right|$$

$$3x_1 - 2x_2 = 6$$

$$-5x_1 + 4x_2 = 8$$

$$\left(\begin{array}{cc|c} 3 & -2 & 6 \\ -5 & 4 & 8 \end{array} \right) \quad \begin{array}{l} A \\ 12 - (10) \end{array}$$

$$x_1 = \frac{1}{|A|} |A(1, b)|$$

$$= \frac{1}{2} \begin{vmatrix} 6 & 2 \\ 8 & 4 \end{vmatrix}$$

$$= \frac{1}{2} (24 - 16)$$

$$= 2$$

$$x_2 = \frac{1}{2} \begin{vmatrix} 3 & 6 \\ -5 & 8 \end{vmatrix}$$

$$= \frac{1}{2} (24 - 30)$$

$$= \frac{1}{2} \cdot -6$$

$$= -3$$

#1.

$$A = \begin{bmatrix} 3 & -1 & 8 & 9 & -5 \\ 0 & 2 & -5 & 1 & 3 \\ 0 & 0 & -1 & 5 & 0 \\ 0 & 0 & 2 & 4 & 1 \\ 0 & 0 & 0 & -2 & 0 \end{bmatrix}$$

$$|A| = 3 \begin{vmatrix} 2 & -5 & 1 & 3 \\ 0 & -1 & 5 & 0 \\ 0 & 2 & -1 & 1 \\ 0 & 0 & -2 & 0 \end{vmatrix}$$

$$= 3 \cdot 2 \cdot \begin{vmatrix} 1 & 5 & 0 \\ 2 & -1 & 1 \\ 0 & -2 & 0 \end{vmatrix}$$

$$= 3 \cdot 2 \cdot 1 \begin{vmatrix} 1 & 5 \\ 0 & -2 \end{vmatrix}$$

$$= 3 \cdot 2 \cdot (-2)$$

$$= -12$$

type III \rightarrow determinant isn't change

$$A = \begin{bmatrix} 5 & -1 & 2 & 2 \\ 0 & 3 & 0 & -4 \\ 5 & -8 & 0 & 3 \\ 0 & 5 & 0 & -6 \end{bmatrix}$$

\downarrow

$$\begin{bmatrix} 5 & -1 & 2 & 2 \\ 0 & 3 & 0 & -4 \\ 0 & -5 & 2 & 5 \\ 0 & 5 & 0 & -6 \end{bmatrix}$$

$$\begin{vmatrix} 5 & 3 & 0 & -4 \\ 5 & -5 & 2 & 5 \\ 5 & 5 & 0 & -6 \end{vmatrix} = 10 \begin{vmatrix} 3 & -4 \\ 5 & -6 \end{vmatrix} = 10(-18 - (-20)) = 10 \cdot 2 = 20$$

$$A = \begin{vmatrix} 2 & 5 & 0 & 0 \\ 3 & 5 & 1 & 0 \\ 3 & 0 & 1 & 2 \\ 1 & 4 & 0 & 6 \end{vmatrix}$$

$$= 2 \begin{vmatrix} 1 & -4 & 3 & 4 \\ 3 & -9 & 5 & 10 \\ -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 \end{vmatrix}$$



$$= 2 \begin{vmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & -12 & 10 & 10 \\ 0 & 0 & -3 & 2 \end{vmatrix}$$

$$= 2 \begin{vmatrix} 3 & -4 & -2 \\ -12 & 10 & 10 \\ 0 & -3 & 2 \end{vmatrix}$$

$$= 2 \cdot 2 \begin{vmatrix} 3 & -4 & -2 \\ -6 & 5 & 5 \\ 0 & -3 & 2 \end{vmatrix} \quad -4 + \frac{5}{2}$$

$$= 2 \cdot 2 \begin{vmatrix} 0 & -\frac{3}{2} & \frac{1}{2} \\ -6 & 5 & 5 \\ 0 & -3 & 2 \end{vmatrix} \quad -2 + \frac{5}{2}$$

$$-3 - \left(-\frac{3}{2}\right)$$

$$= 4 \cdot (-1) \cdot (-6) \begin{vmatrix} -\frac{3}{2} & \frac{1}{2} \\ -3 & 2 \end{vmatrix}$$

$$\frac{12}{2} - \frac{3}{2}$$

$$= 24 \left| 3 - \left(-\frac{3}{2}\right) \right|$$

$$= 24 \left(3 + \frac{3}{2} \right) = \boxed{-36}$$

Properties of Determinant

- $|A| = |A^T|$
 - a_{1i} : each element of first row vector of A
 - a_{i1} : each element of first column vector of A
 - C_{1i} : cofactor expansion of A (except first row and i th column)
 - C_{i1} : cofactor expansion of A (except i th row and first column)
 - $|A| = \sum_{i=1}^n a_{1i}C_{1i}$
 - $|A^T| = \sum_{i=1}^n a_{i1}C_{i1}$
 - By definition of determinant
 - $\sum_{i=1}^n a_{1i}C_{1i} = \sum_{i=1}^n a_{i1}C_{i1}$
 - $|A| = |A^T|$

Properties of Determinant

- $\det AB = (\det A)(\det B)$
 - Verification by example
 - $A = \begin{bmatrix} 6 & 1 \\ 3 & 2 \end{bmatrix}$, $B = \begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}$
 - $\det A = 9$, $\det B = 5$
 - $AB = \begin{bmatrix} 25 & 20 \\ 14 & 13 \end{bmatrix}$
 - $\det AB = 25 \times 13 - 20 \times 14 = 325 - 280 = 45 = 9 \times 5$
 - $\det EA = (\det E)(\det A)$
 - $\det E = \begin{cases} 1 & E \text{ is a row replacement} \\ -1 & E \text{ is an interchange} \\ r & E \text{ is a scalar multiplication} \end{cases}$

Warning: A common misconception is that Theorem 6 has an analogue for *sums* of matrices. However, $\det(A + B)$ is *not* equal to $\det A + \det B$, in general.

$$|A+B| \neq |A| + |B|$$

Properties of Determinant

$$\begin{bmatrix} 1 & 8 \\ 2 & 7 \end{bmatrix} + \begin{bmatrix} 1 & 6 \\ 2 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 9 \\ 2 & 8 \end{bmatrix}$$

$\uparrow -6$ $\uparrow -12$ $\uparrow -6$
 $-3-2$ -10 -10
 $8-10$

• Linearity property of the determinant function

- $A = [\mathbf{a}_1 \quad \dots \quad \mathbf{a}_{j-1} \quad \mathbf{x} \quad \mathbf{a}_{j+1} \quad \dots \quad \mathbf{a}_n]$ → determinant \equiv linear
- Define a transformation T from \mathbb{R}^n to \mathbb{R}

- $T = \det[\mathbf{a}_1 \quad \dots \quad \mathbf{a}_{j-1} \quad \mathbf{x} \quad \mathbf{a}_{j+1} \quad \dots \quad \mathbf{a}_n]$

- $T(c\mathbf{x}) = cT(\mathbf{x})$ → Type II operation
- $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$

$$T(\mathbf{u}) = \det([\mathbf{a}_1, \dots, \mathbf{u}, \dots, \mathbf{a}_n])$$

$$T(\mathbf{v}) = \det([\mathbf{a}_1, \dots, \mathbf{v}, \dots, \mathbf{a}_n])$$

Define a transformation T from.

$$T \left(\begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 1 & 4 & 3 \\ 1 & 4 & 3 \end{bmatrix} \right) = \begin{bmatrix} 1 & 6 & 3 \\ 1 & 6 & 3 \\ 1 & 6 & 3 \end{bmatrix}$$

$$T(\mathbf{u} + \mathbf{v}) = \det([\mathbf{a}_1, \dots, \mathbf{u} + \mathbf{v}, \dots, \mathbf{a}_n])$$

↓

co-factor expansion

det = □

$$\begin{bmatrix} \mathbf{a}_1, \dots, \mathbf{u}, \dots, \mathbf{a}_n \\ \mathbf{a}_1, \dots, \mathbf{v}, \dots, \mathbf{a}_n \end{bmatrix}$$

det = Δ

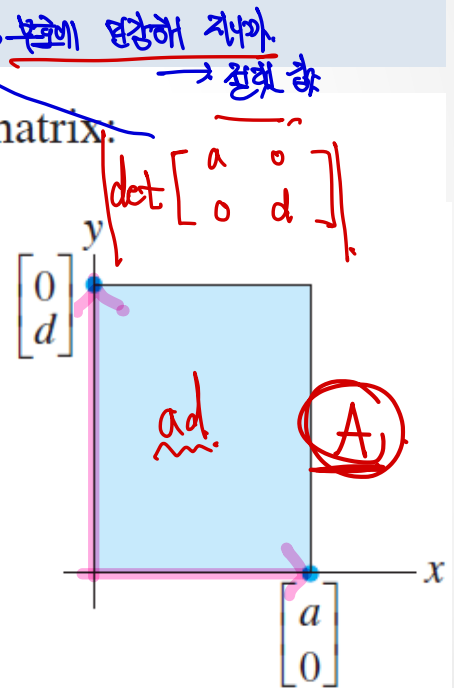
Determinants as Area or Volume

- Theorem 9

If A is a 2×2 matrix, the area of the (parallelogram) determined by the columns of A is $|\det A|$. If A is a 3×3 matrix, the volume of the parallelepiped determined by the columns of A is $|\det A|$.

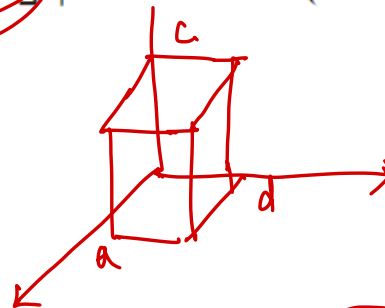
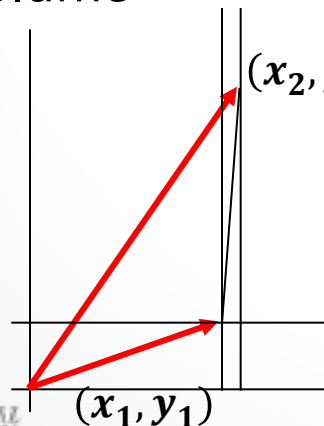
PROOF The theorem is obviously true for any 2×2 diagonal matrix:

$$\left| \det \begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix} \right| = |ad| = \left\{ \begin{array}{l} \text{area of} \\ \text{rectangle} \end{array} \right\}$$



○ In \mathbb{R}^3

- Volume



$$\det |A|$$

$$\frac{x_2 y_2}{2} - \frac{x_1 y_1}{2} - (x_2 - x_1) y_1 - \frac{(x_2 - x_1)(y_2 - y_1)}{2} = \frac{1}{2} (x_1 y_2 - x_2 y_1)$$

Determinants as Area or Volume

Let \mathbf{a}_1 and \mathbf{a}_2 be nonzero vectors. Then for any scalar c the area of the parallelogram determined by $(\mathbf{a}_1$ and $\mathbf{a}_2)$ equals the area of the parallelogram determined by \mathbf{a}_1 and $\mathbf{a}_2 + c\mathbf{a}_1$.

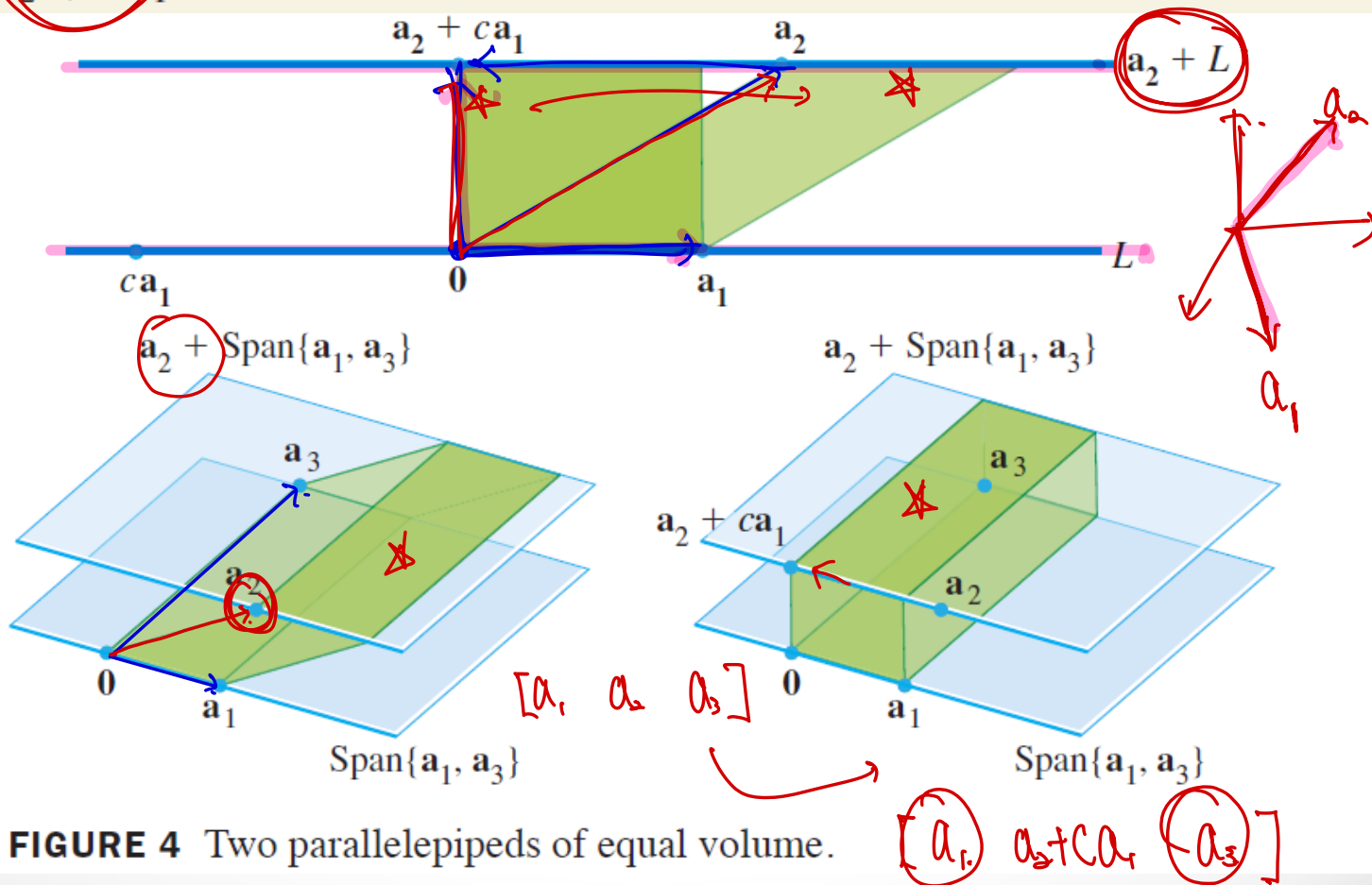


FIGURE 4 Two parallelepipeds of equal volume.

Linear Transformations

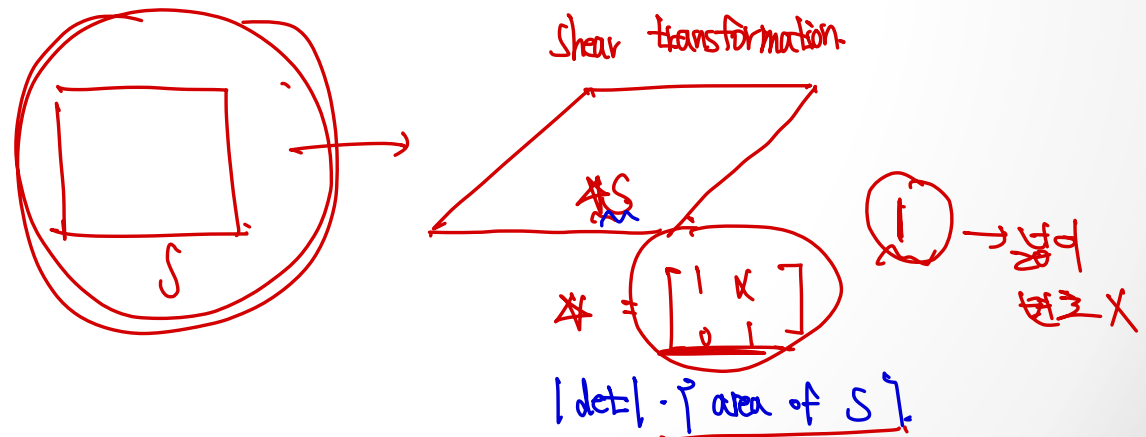
- Theorem 10

Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear transformation determined by a 2×2 matrix A . If S is a parallelogram in \mathbb{R}^2 , then

$$\{\text{area of } T(S)\} = |\det A| \cdot \{\text{area of } S\} \quad (5)$$

If T is determined by a 3×3 matrix A , and if S is a parallelepiped in \mathbb{R}^3 , then

$$\{\text{volume of } T(S)\} = |\det A| \cdot \{\text{volume of } S\} \quad (6)$$



Linear Transformations

- Theorem 10

PROOF Consider the 2×2 case, with $A = [a_1 \ a_2]$. A parallelogram at the origin in \mathbb{R}^2 determined by vectors b_1 and b_2 has the form

$$S = \{s_1 b_1 + s_2 b_2 : 0 \leq s_1 \leq 1, 0 \leq s_2 \leq 1\}$$

The image of S under T consists of points of the form

$$\begin{aligned} T(s_1 b_1 + s_2 b_2) &= s_1 T(b_1) + s_2 T(b_2) \\ &= s_1 A b_1 + s_2 A b_2 \end{aligned}$$

where $0 \leq s_1 \leq 1, 0 \leq s_2 \leq 1$. It follows that $T(S)$ is the parallelogram determined by the columns of the matrix $[A b_1 \ A b_2]$. This matrix can be written as AB , where $B = [b_1 \ b_2]$. By Theorem 9 and the product theorem for determinants,

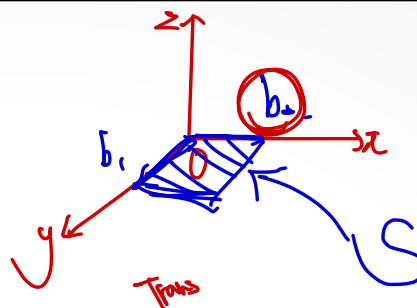
$$\begin{aligned} \det AB &= \det A \det B \\ \{\text{area of } T(S)\} &= |\det AB| = |\det A| |\det B| \\ &= |\det A| \cdot \{\text{area of } S\} \end{aligned}$$

$$[A b_1 \ A b_2]$$

$$AB$$

$$A = [a_1, a_2]$$

$$S = [s_1 b_1 + s_2 b_2]$$



$$\begin{aligned} T(s_1 b_1 + s_2 b_2) &= s_1 T(b_1) + s_2 T(b_2) \\ &= s_1 A b_1 + s_2 A b_2 \end{aligned}$$

$$[A b_1 \ A b_2] B$$

$$s_1 A b_1 + s_2 A b_2$$

$$B = [b_1 \ b_2]$$

$$T(s_1 b_1 + s_2 b_2)$$

$$= s_1 T(b_1) + s_2 T(b_2)$$

$$s_1 A b_1 + s_2 A b_2$$

(7)

Linear Transformations

- Theorem 10

An arbitrary parallelogram has the form $\mathbf{p} + S$ where \mathbf{p} is a vector and S is a parallelogram at the origin, as above. It is easy to see that T transforms $\mathbf{p} + S$ into $T(\mathbf{p}) + T(S)$. (See Exercise 26.) Since translation does not affect the area of a set,

$$\begin{aligned}\{\text{area of } T(\mathbf{p} + S)\} &= \{\text{area of } T(\mathbf{p}) + T(S)\} \\ &= \{\text{area of } T(S)\} && \text{Translation} \\ &= |\det A| \cdot \{\text{area of } S\} && \text{By equation (7)} \\ &= |\det A| \cdot \{\text{area of } \mathbf{p} + S\} && \text{Translation}\end{aligned}$$

This shows that (5) holds for all parallelograms in \mathbb{R}^2 . The proof of (6) for the 3×3 case is analogous. 

Linear Transformations

The conclusions of Theorem 10 hold whenever S is a region in \mathbb{R}^2 with finite area or a region in \mathbb{R}^3 with finite volume.

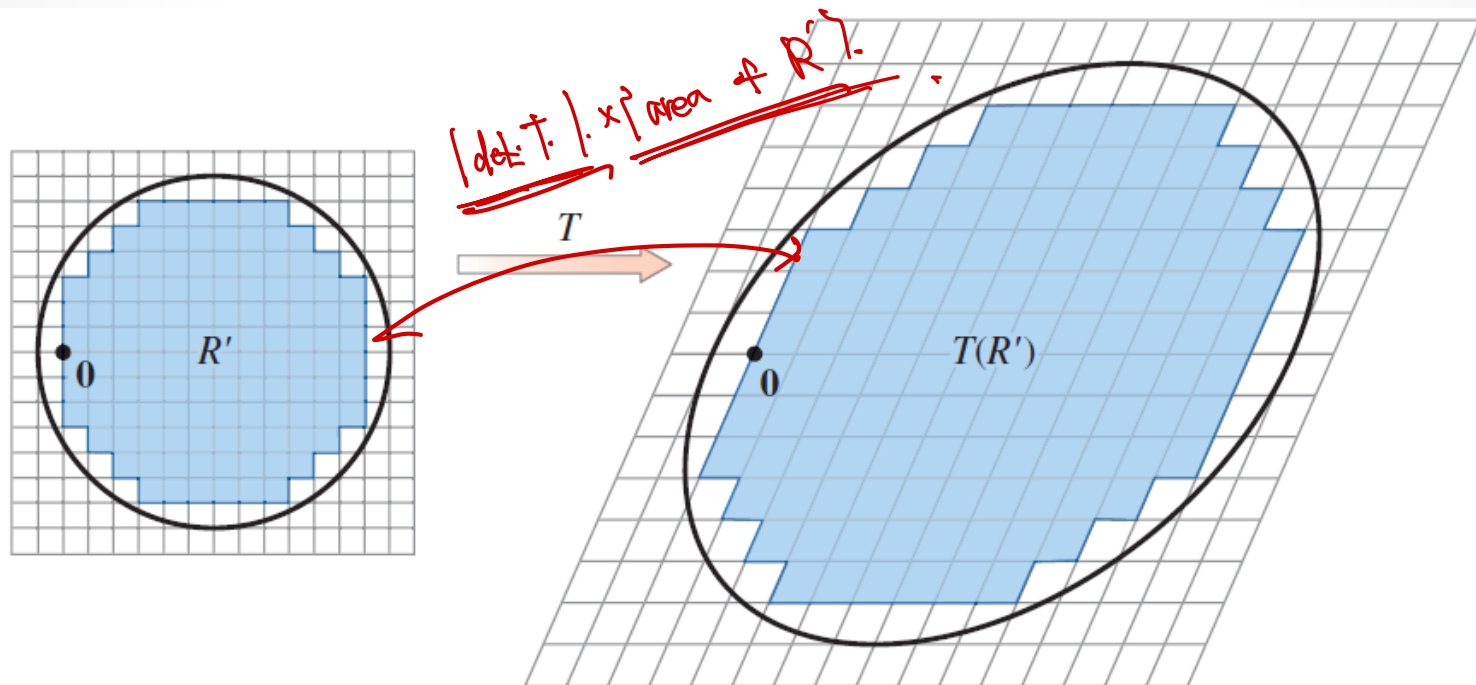
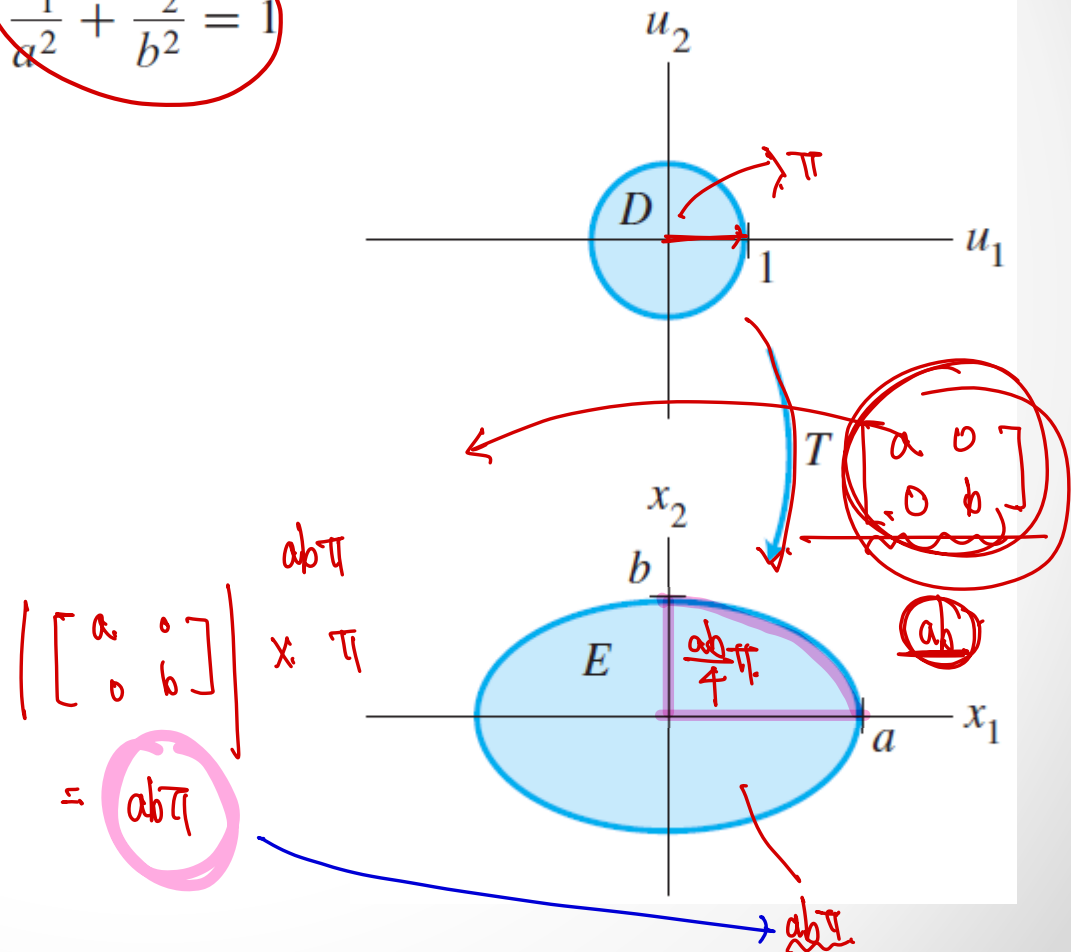


FIGURE 7 Approximating $T(R)$ by a union of parallelograms.

Linear Transformations

EXAMPLE 5 Let a and b be positive numbers. Find the area of the region E bounded by the ellipse whose equation is

$$\frac{x_1^2}{a^2} + \frac{x_2^2}{b^2} = 1$$



Linear Transformations

EXAMPLE 5 Let a and b be positive numbers. Find the area of the region E bounded by the ellipse whose equation is

$$\frac{x_1^2}{a^2} + \frac{x_2^2}{b^2} = 1$$

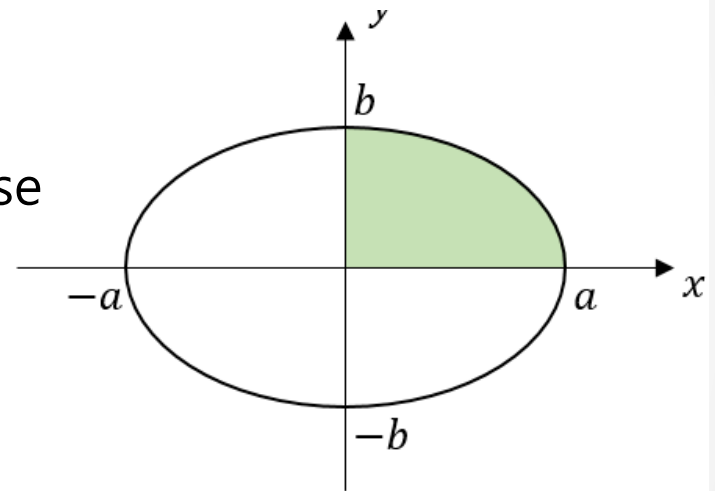
- $x_2 = \pm b \sqrt{1 - \frac{x_1^2}{a^2}}$
- The quarter-area of the given ellipse

- $\int_0^a b \sqrt{1 - \frac{x_1^2}{a^2}} dx_1: x_1 = a \sin \theta$

- $\int_0^{\frac{\pi}{2}} ab \sqrt{1 - \sin^2 \theta} \cos \theta d\theta$

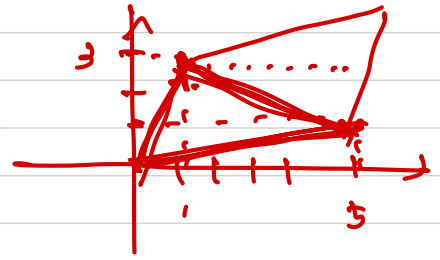
- $ab \int_0^{\frac{\pi}{2}} \cos^2 \theta d\theta = ab \int_0^{\frac{\pi}{2}} \frac{\cos 2\theta + 1}{2} d\theta = \frac{ab}{4} [\sin 2\theta + 2\theta]_0^{\frac{\pi}{2}}$

- $\frac{ab}{4} [0 + \pi - 0 - 0] = \frac{ab}{4} \pi$



#

$$b_1 = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \quad b_2 = \begin{bmatrix} 5 \\ 1 \end{bmatrix}$$



$$\text{let } A = \begin{bmatrix} 1 & -0.1 \\ 0 & 2 \end{bmatrix}$$

$$* \mid \underline{(Ax)}$$

$$\underline{2}$$

$$\det A = 2$$

$$\det \begin{bmatrix} 1 & 5 \\ 3 & 1 \end{bmatrix}$$

$$\Rightarrow |1-15| = \underline{14}$$

$$2 \cdot 14 = \underline{28}$$