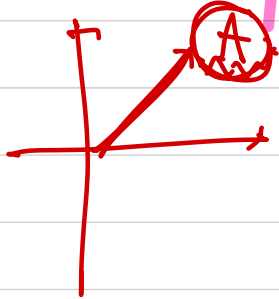


Eigenvalues and Diagonalization and special Matrices

$$\underline{A\vec{e} = \lambda\vec{e}}$$



$$A(c\vec{e}) = \underline{\lambda(c\vec{e})}$$

\vec{e} 이 multiple을 일러야 하는
 λ 는 변하지 않는다.

$$\underline{A\vec{e} = \lambda\vec{e}}$$

$$A\vec{e} - \lambda\vec{e} = 0$$

$$\underline{(A - I_n \lambda) \vec{e} = 0}$$

$\rightarrow 0$ 이 되어야 한다

$$BX = 0 \Rightarrow$$

But: non-singular matrix X

$$\underline{B^{-1}BX = 0}$$

singular 이려면

singular matrix 행렬식 0

$$A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{pmatrix}$$

$$(A - \lambda I) \vec{t} = 0$$

$$\begin{pmatrix} 1-\lambda & -1 & 0 \\ 0 & 1-\lambda & 1 \\ 0 & 0 & -1-\lambda \end{pmatrix}$$

$$(-1)^3 (1-\lambda)(1-\lambda)(-1-\lambda)$$

$$= -(1-\lambda)^2 (1+\lambda)$$

$$\lambda = 1 \text{ or } \lambda = -1$$

$$\begin{pmatrix} 2 & -1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} t_1 \\ t_2 \\ t_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} t_1 \\ t_2 \\ t_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} 2t_1 - t_2 &= 0 \\ 2t_2 + t_3 &= 0 \\ t_3 &= -2t_2 \end{aligned}$$

$$t_3 = -2t_2 = -4t_1$$

$$t_2 = 2t_1$$

$$\lambda = 1, \vec{t} = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$$

$$\lambda = -1, \vec{t} = \begin{pmatrix} 1 \\ 2 \\ -4 \end{pmatrix}$$

Let A be a real number matrix

$$\boxed{\lambda = \alpha + i\beta}$$

the λ is eigen value. ~~is~~.

$\vec{E} \rightarrow \lambda$ is eigenvector. ~~is~~.

$$A\vec{E} = \lambda\vec{E}$$

eigen vector \vec{E} is \rightarrow eigen value λ ~~is~~

$$A\vec{E} = \lambda\vec{E} \quad \left(\begin{pmatrix} 1 & 2 \\ \sim & \end{pmatrix} \quad \begin{pmatrix} 3 & 4 \\ \sim & \end{pmatrix} \right)$$

$$\begin{aligned} \underbrace{\vec{E}^t A \vec{E}}_{\text{Vector}} &= \vec{E}^t \lambda \vec{E} = \lambda \underbrace{\vec{E}^t \vec{E}}_{\text{Scalar}} \\ &= \underbrace{(\vec{E} \cdot \vec{E})}_{\text{Scalar}} \lambda \\ &\quad \underbrace{\hspace{1cm}}_{\text{Scalar}} \end{aligned}$$

$$\left(\lambda = \frac{\vec{E}^t A \vec{E}}{\vec{E}^t \vec{E}} \right)$$

$$A = \begin{pmatrix} 5 & -4 & 4 \\ 12 & -11 & 12 \\ 4 & -4 & 5 \end{pmatrix} \quad (A - \lambda I)\mathbf{t} =$$

↓

$$-3 \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

↓

$$\begin{pmatrix} 1 & -4 & 4 \\ 12 & -12 & 12 \\ 4 & -4 & 1 \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -4 & 4 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix}$$

$$e_1 - e_2 + e_3 = 0$$

$$e_1 = e_2 - e_3$$

$$\mathbf{t} = \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix} = \begin{pmatrix} e_2 - e_3 \\ e_2 \\ e_3 \end{pmatrix} = e_2 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + e_3 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

2개 4을 1로

$$\lambda = 1 \rightarrow \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$\lambda = -3 \rightarrow \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}$$

A be real symmetric matrix.

$$\begin{pmatrix} \lambda_1 \rightarrow E_1 \\ \lambda_2 \rightarrow E_2 \end{pmatrix}$$

E_1, E_2 orthogonal

$$E \cdot G = \begin{pmatrix} E^t G \end{pmatrix}$$

$$\lambda E^t G = (A E^t) G$$

$$= E^t A G = \lambda E^t G$$

$$(\lambda_1 - \lambda_2) E^t G = 0$$

$$\underline{E \cdot G}$$

E_1, E_2 orthogonal \therefore

$$A = \begin{pmatrix} 3 & 0 & -2 \\ 0 & 2 & 0 \\ -2 & 0 & 0 \end{pmatrix}$$

$$\lambda_1 = 2 \quad \lambda_2 = -1 \quad \lambda_3 = 4$$

$$\begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & 0 \\ 0 & 2 & -1 \end{pmatrix} \rightarrow \text{matrixly orthogonal}$$

Diagonalization.

$$\begin{pmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{pmatrix}$$

$$\lambda_1 = a_{11} \quad \lambda_2 = a_{22} \quad \lambda_3 = a_{33}$$

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$



$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & a_{22} - a_{11} & 0 \\ 0 & 0 & a_{33} - a_{11} \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$e_2 = 0 \quad e_3 = 0$$

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \text{ 맞다.}$$

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & & 0 \\ \vdots & 0 & \ddots & \\ 0 & 0 & & d_n \end{pmatrix}$$

$P \rightarrow$ formed from eigenvectors

$$P^{-1}AP \rightarrow P \text{ diagonalizes } A$$

↳ P 를 통해 A 를 대각화 함.

Ex.

$$A = \begin{pmatrix} -1 & 4 \\ 0 & 3 \end{pmatrix} \quad (A \in \mathbb{R}^2)$$

$$\begin{pmatrix} -1-\lambda & 4 \\ 0 & 3-\lambda \end{pmatrix}$$

$$(-1-\lambda)(3-\lambda) = 0$$

$$\lambda_1 = -1 \quad \lambda_2 = 3$$

$$\begin{pmatrix} -4 & 4 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$e_1 = e_2$$

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 4 \\ 0 & 4 \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$e_1 = e_2$$

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\lambda = -1 \rightarrow E_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\lambda = 3 \rightarrow E_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$P = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \quad P^{-1} = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 4 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} =$$

$$\rightarrow \begin{pmatrix} -1 & 1 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} =$$

$$\begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 3 \\ 0 & 3 \end{pmatrix}$$

$$= \begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix}$$

eigen value.

Orthogonal matrices

$$A^T = A^{-1}$$

$$|A| = \pm 1$$

$$|I_n| = |AA^T| = |AA^{-1}| = (|A|)(|A^T|) = (|A|)^2$$

$n \times n$ real symmetric matrix with distinct eigenvalues
can be diagonalized by an orthogonal matrix.

$$S = \begin{pmatrix} 3 & 0 & -2 \\ 0 & 2 & 0 \\ -2 & 0 & 0 \end{pmatrix}$$

$$\begin{aligned} 2 &\rightarrow \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ -1 &\rightarrow \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \\ 1 &\rightarrow \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \end{aligned}$$

$$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix}$$

orthogonal matrix

$$\begin{pmatrix} 0 & \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ 1 & 0 & 0 \\ 0 & \frac{2}{\sqrt{5}} & -\frac{1}{\sqrt{5}} \end{pmatrix}$$

$$A^T = \lambda E$$

$\lambda E \rightarrow \lambda E$ matrix

$$A = Q^{-1} A Q$$

$$Q^T A Q$$

$$Q A Q^T$$

orthogonal decomposition
할 수 있다.

정리 할 수 있다.

Unitary matrices.

$$\underline{U^{-1} = U^{\dagger}}$$

λ of unitary matrix \rightarrow eigenvalues.

$$\underline{|\lambda| = 1}$$

$$\underline{U\vec{e} = \lambda\vec{e}}$$

$$\underline{\overline{U\vec{e}} = \overline{\lambda\vec{e}}}$$

$$\begin{aligned} (\overline{U\vec{e}})^{\dagger} &= \vec{e}^{\dagger} U^{\dagger} = \underline{\vec{e}^{\dagger} U^{-1}} \\ &\stackrel{||}{=} \underline{(\overline{\lambda\vec{e}})^{\dagger}} \\ &= \underline{\underline{\frac{1}{\lambda} \vec{e}^{\dagger}}} \end{aligned}$$

$$\cancel{\vec{e}^{\dagger} U^{-1} U \vec{e}} = \overline{\lambda} \vec{e}^{\dagger} U \vec{e}$$

$$\begin{aligned} \vec{e}^{\dagger} \vec{e} &= \overline{\lambda} \vec{e}^{\dagger} (U \vec{e}) \\ &= \overline{\lambda} \vec{e}^{\dagger} \lambda \vec{e} \\ &= \underline{\underline{\overline{\lambda} \lambda \vec{e}^{\dagger} \vec{e}}} \end{aligned}$$

$$\overline{\lambda} \lambda = 1$$

$$\begin{aligned} \lambda &= a + bi \\ \overline{\lambda} &= a - bi \\ \overline{\lambda} \lambda &= \underline{\underline{a^2 + b^2}} = 1 \end{aligned}$$

Hermitian

$$\underline{\underline{H = H^t}} \rightarrow \text{Hermitian}$$

$$\underline{\underline{S = -S^t}} \rightarrow \text{skew-Hermitian.}$$

$$\underline{\underline{H = H^t}}$$

$$Z = \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{pmatrix}$$

$$\underline{\underline{Z^t H Z}} = \underline{\underline{Z^t H Z}} \rightarrow B$$

$$\begin{aligned} (Z^t H Z)^t &= Z^t (H^t) Z \\ &= \underline{\underline{Z^t H Z}} \end{aligned}$$

conjugate is equal
to itself.

$$\underline{\underline{A = B \quad B^t = A}}$$

#

→ The eigenvalues of Hermitian matrix
are real

Skew-Hermitian matrix → pure imaginary

$$\lambda = \begin{pmatrix} a+bi \\ a-bi \end{pmatrix}$$

$$Q(x) = \cancel{5x_1^2} + \cancel{8x_1x_2} + \cancel{2x_2^2} - \cancel{4x_2x_3} + 6x_3^2$$

$$\rightarrow \begin{bmatrix} 5 & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 3 & 4 \\ 0 & 4 & 2 \end{bmatrix}$$

Quadratic form as $x^T A x$

$$(x_1 \ x_2 \ x_3) \begin{pmatrix} 5 & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 3 & 4 \\ 0 & 4 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$Q(x) = x_1^2 - 8x_1x_2 - 5x_2^2$$

$$(x_1, x_2) \begin{pmatrix} 1 & -4 \\ -4 & -5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\begin{bmatrix} -3 \\ 1 \end{bmatrix}$$

$$(-3 \ 1) \begin{pmatrix} 1 & -4 \\ -4 & -5 \end{pmatrix} \begin{pmatrix} -3 \\ 1 \end{pmatrix}$$

$$(-1 \ 1) \begin{pmatrix} -3 \\ 1 \end{pmatrix} = 2 + 1 = 28$$

$$9 + 24 - 5 = 28$$

$$\frac{12}{5}$$

principal axis theorem.

$A \rightarrow$ real symmetric matrix.

$\rightarrow X = QY$
orthogonal matrix. Q
회전 각도 결정

$$Q^{-1} = Q^T$$

$$Y = Q^T X = Q^T X$$

$$\alpha x_1^2 + \beta x_2^2 + \gamma x_3^2$$

$\rightarrow \alpha' y_1^2 + \beta' y_2^2 \rightarrow$ 이렇게 간단하게 표현 가능해짐!

$$\begin{aligned} X^T A X &= (Q^T)^T A Q^T = (Y^T Q^T) A Q^T \\ &= Y^T (Q^T A Q) Y \end{aligned}$$

\rightarrow 대각화 matrix가 됨

Ex $x_1^2 - 1x_1x_2 + x_2^2 \rightarrow \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

Eigen Values of A

$$\begin{pmatrix} 1-\lambda & -\frac{1}{2} \\ -\frac{1}{2} & 1-\lambda \end{pmatrix}$$

$$(1-\lambda)^2 - \frac{1}{4}$$

$$= 1 - 2\lambda + \lambda^2 - \frac{1}{4}$$

$$= \lambda^2 - 2\lambda - \frac{1}{4}$$

$$4\lambda^2 - 8\lambda - 1$$

$$(2\lambda - 9)(2\lambda + 5)$$

$$\lambda_1 = \frac{9}{2}, \lambda_2 = -\frac{5}{2}$$

$$Q = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\rightarrow X = QY$$

$$\begin{pmatrix} \frac{1}{\sqrt{2}}y_1 - \frac{1}{\sqrt{2}}y_2 \\ \frac{1}{\sqrt{2}}y_1 + \frac{1}{\sqrt{2}}y_2 \end{pmatrix}$$

$$\frac{1}{\sqrt{2}} \begin{pmatrix} y_1 - y_2 \\ y_1 + y_2 \end{pmatrix}$$

$$(y_1, y_2) \begin{pmatrix} -\frac{9}{2} & 0 \\ 0 & \frac{5}{2} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$-\frac{9}{2}y_1^2 + \frac{5}{2}y_2^2$$

#

$$\rightarrow \underline{X^T A X} = (Q^T)^T A (Q^T)$$
$$X = \underline{Q^T} = \underline{Q^T A Q}$$

$Q \rightarrow$ orthogonal matrix.

$$\underline{Q^T A Q} \rightarrow \text{대각화 과정}$$

r

6장

$$X' = AX + G, \quad \underbrace{X(t_0) = X^0}_{\text{"initial value"}}$$

$$X' = AX$$

$$\underbrace{y'' + p(x)y' + q(x)y = 0}_{\text{"}}$$

$$x_1'(t) = a_{11}(t)x_1 + a_{12}(t)x_2(t)$$

$$x_2'(t) = a_{21}(t)x_1 + a_{22}(t)x_2$$

Ex

$$\underline{X' = \begin{pmatrix} 1 & -4 \\ 1 & 5 \end{pmatrix} X.}$$

$$\underline{X_1' = \begin{pmatrix} 1 & -4 \\ 1 & 5 \end{pmatrix} X_1.}$$

$$\begin{pmatrix} -6e^{3t} \\ 3e^{3t} \end{pmatrix} = \begin{pmatrix} 1 & -4 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} -2e^{3t} \\ e^{3t} \end{pmatrix}$$

$$= \underbrace{\begin{pmatrix} -6e^{3t} \\ 3e^{3t} \end{pmatrix}}_{\text{}}_{\text{f}}$$

$$X' = \begin{pmatrix} 1 & -4 \\ 1 & 5 \end{pmatrix} X.$$

$$\phi_1(t) = \begin{pmatrix} -2e^{3t} \\ e^{3t} \end{pmatrix}, \quad \phi_2(t) = \begin{pmatrix} (1-2t)e^{3t} \\ te^{3t} \end{pmatrix}.$$

$$\begin{pmatrix} -2 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \neq 0$$

2 linearly independent solution vectors

linearly independent set.

$$X' = \begin{pmatrix} 1 & -4 \\ 1 & 5 \end{pmatrix} X. \quad \left[C_1 \begin{pmatrix} -2e^{3t} \\ e^{3t} \end{pmatrix} + C_2 \begin{pmatrix} (1-2t)e^{3t} \\ te^{3t} \end{pmatrix} \right].$$

↳ general solution

$$\begin{pmatrix} -2e^{3t} & (1-2t)e^{3t} \\ e^{3t} & te^{3t} \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$$

fundamental matrix.

$$X(t_0) =$$

$$\uparrow$$

$$\begin{pmatrix} -2 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \rightarrow$$

$$\underline{Q(\omega)}C = \begin{pmatrix} -2 \\ 3 \end{pmatrix}$$

$$C = \begin{pmatrix} -2 & 1 \\ 1 & 0 \end{pmatrix}^{-1} \begin{pmatrix} -2 \\ 3 \end{pmatrix}$$

$$= - \begin{pmatrix} 0 & -1 \\ -1 & -2 \end{pmatrix} \begin{pmatrix} -2 \\ 3 \end{pmatrix}$$

$$= - \begin{pmatrix} -3 \\ -4 \end{pmatrix} = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

$$X(t) = \underline{Q(t)C}$$

$$= \begin{pmatrix} -2e^{3t} & (1-2t)e^{3t} \\ e^{3t} & te^{3t} \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

$$\begin{pmatrix} e^{3t}(-2-8t) \\ e^{3t}(3+4t) \end{pmatrix}$$

↳ particular solution

$$y'' + p(x)y' + Q(x)y = f(x).$$

$y_1 - y_2 \rightarrow$ associated homogeneous
equation of solution

\downarrow
linear Comb

$$y_1 = y_2 + \square$$

$$\boxed{X' = AX + G}$$

$$X = \underbrace{QC}_{\text{homogeneous}} + \underbrace{\psi}_{\text{particular solution (nonhomogeneous)}}$$

$$\underline{X' = AX}$$

$$y'' + p(x)y' + q(x)y = 0$$

$$\underline{y = e^{\lambda x}} \rightarrow \text{가능 풀었을까}$$

$$X = \underbrace{\begin{pmatrix} \lambda \\ 1 \end{pmatrix}}_{\text{vector}} e^{\lambda t} \quad \text{scalar}$$

"이러한 형태가 정해지"

$$\underline{X' = \lambda \cancel{e^{\lambda t}} = A \cancel{e^{\lambda t}} = \underline{AX}}$$

행렬 A 의 (eigen value)
(eigen vector)
를 찾아야 된다.

$$e^{\lambda t} \rightarrow X' = AX \rightarrow \text{solution of}$$

suppose A has $\lambda_1, \dots, \lambda_n$ eigenvalues \rightarrow

Then $(\underline{e^{\lambda_1 t}}, \dots, e^{\lambda_n t})$ are linearly independent solutions,

✓

characteristic equation의 solution의 경우
여러 경우가

- ① $\lambda =$ distinct real
 " repeated
 " complex.

ex

$$X' = \begin{pmatrix} 4 & 2 \\ 3 & 3 \end{pmatrix} X$$

$$\begin{pmatrix} 4-\lambda & 2 \\ 3 & 3-\lambda \end{pmatrix}$$

$$(4-\lambda)(3-\lambda) - 6$$

$$= \lambda^2 - 7\lambda + 6$$

$$(\lambda-1)(\lambda-6)$$

① $\lambda = 1$

$$\begin{pmatrix} 3 & 2 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$3x_1 + 2x_2 = 0$$

$$\begin{pmatrix} x_1 \\ \frac{3}{2}x_1 \end{pmatrix}$$

$$\begin{pmatrix} -2 \\ 3 \end{pmatrix}$$

$$e^{xt}$$

$$X_1 = \begin{pmatrix} -2 \\ 3 \end{pmatrix} e^{t}$$

② $\lambda = 6$

$$\begin{pmatrix} -2 & 2 \\ 3 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$x_1 = x_2 \quad \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$X_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{6t}$$

$$X = \begin{pmatrix} -2e^t & e^{6t} \\ 3e^t & e^{6t} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

Complex eigen value

$$y_1 = e^{(\alpha + i\beta)x} = e^{\alpha x} e^{i\beta x} = e^{\alpha x} (\cos(\beta x) + i \sin(\beta x))$$

$$y_2 = e^{\alpha x} (\cos(\beta x) - i \sin(\beta x))$$

$$E e^{(\alpha + i\beta)t} \rightarrow e^{\alpha t} (\cos(\beta t) + i \sin(\beta t))$$

$$\begin{pmatrix} 2+4i & 5 \\ 1 & -2i \end{pmatrix} \rightarrow \begin{pmatrix} 2 \\ 5 \\ 1 \end{pmatrix} + \begin{pmatrix} 4 \\ 0 \\ -2 \end{pmatrix} i$$

\downarrow \downarrow
 (V) (V)

$$\phi_1(t) = e^{\alpha t} (\cos(\beta t) + i \sin(\beta t)) (V + iV)$$

$$= e^{\alpha t} (\cos(\beta t)V - \sin(\beta t)V) + i e^{\alpha t} (\sin(\beta t)V + \cos(\beta t)V)$$

$$\frac{1}{2}(\phi_1 + \phi_2) = e^{\alpha t} (\cos(\beta t)V - \sin(\beta t)V)$$

$$\frac{1}{2}(\phi_1 - \phi_2) = i e^{\alpha t} (\sin(\beta t)V + \cos(\beta t)V)$$

$$\underline{\dot{X}} = AX$$

$$A = \begin{pmatrix} 2 & 0 & 1 \\ 0 & -2 & -2 \\ 0 & 2 & 0 \end{pmatrix}$$

$$2, \quad -1 + \sqrt{3}i, \quad -1 - \sqrt{3}i \rightarrow \text{eigen value.}$$

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 1 \\ -2\sqrt{3}i \\ -3 + \sqrt{3}i \end{pmatrix} \quad \begin{pmatrix} 1 \\ 2\sqrt{3}i \\ -3 - \sqrt{3}i \end{pmatrix}$$

$$e^{2t}$$

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} e^{2t}$$

$$\begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} + \begin{pmatrix} 0 \\ -2\sqrt{3} \\ \sqrt{3} \end{pmatrix} i = U + Vi$$

$$e^{2t} (\cos(\sqrt{3}t) U - \sin(\sqrt{3}t) V)$$

$$\phi_3 = e^{2t} \left[\cos(\sqrt{3}t) \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} - \sin(\sqrt{3}t) \begin{pmatrix} 0 \\ -2\sqrt{3} \\ \sqrt{3} \end{pmatrix} \right]$$

$$\phi_4 = e^{2t} \left[\sin(\sqrt{3}t) \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} + \cos(\sqrt{3}t) \begin{pmatrix} 0 \\ -2\sqrt{3} \\ \sqrt{3} \end{pmatrix} \right]$$

$$Q(t) = \begin{pmatrix} e^{At} & & \\ 0 & & \\ & & \sim \\ 0 & & \end{pmatrix}$$

$$\underline{X' = AX} \quad \rightarrow \text{repeated}$$

$$A = \begin{pmatrix} 1 & 3 \\ -3 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1-\lambda & 3 \\ -3 & 1-\lambda \end{pmatrix}$$

$$1 - 8\lambda + \lambda^2 + 9$$

$$\lambda^2 - 8\lambda + 16$$

$$(\lambda - 4)^2 = 0$$

$$\lambda = 4$$

$$P = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} -3 & 3 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\phi_2 = \underline{E_1} e^{\lambda t} + \underline{E_2} e^{\lambda t}.$$

$$\phi_2' = \underline{E_1} e^{\lambda t} + \underline{E_1} \lambda e^{\lambda t} + \lambda \underline{E_2} e^{\lambda t}.$$

$$\underline{X'} = A \underline{X}$$

$$\underline{E_1} e^{\lambda t} + \underline{E_1} \lambda e^{\lambda t} + \lambda \underline{E_2} e^{\lambda t}$$

$$= A \underline{E_1} e^{\lambda t} + A \underline{E_2} e^{\lambda t}$$

$$\underline{E_1} + \underline{E_1} \lambda + \lambda \underline{E_2}$$

$$= A \underline{E_1} + A \underline{E_2}$$

n/ 12h

E

$$(A - \lambda I) \underline{E_2} = \underline{E_1}$$

$$\lambda = 4 \quad E = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} \frac{1}{3} - \lambda_2 \\ \lambda_2 \end{pmatrix}$$

$$\begin{pmatrix} \frac{1}{3} \\ 0 \end{pmatrix} + \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\alpha \begin{pmatrix} -\frac{1}{3} \\ \alpha \end{pmatrix}$$

$$(A - 4I) \underline{E_2} = \underline{E_1}$$

$$\begin{pmatrix} 1-4 & 3 \\ -3 & 1-4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} -3 & 3 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\underline{-3x_1 + 3x_2 = 1} \quad \underline{3x_1 = -1 - 3x_2} \quad \underline{x_1 = -\frac{1}{3} - x_2}$$

$$\underline{E_2 = \begin{pmatrix} 1 \\ 4 \\ \frac{1}{3} \end{pmatrix}}$$

$$\underline{\phi_2} = \underline{E_1} e^{\lambda_1 t} + \underline{E_2} e^{\lambda_2 t}$$

$$= \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} t e^{4t} + \begin{pmatrix} 1 \\ 4 \\ \frac{1}{3} \end{pmatrix} e^{4t}$$

$$= \begin{pmatrix} t+1 \\ t+4 \\ t+\frac{1}{3} \end{pmatrix} e^{4t}$$