

Lock-based Concurrent Data Structures

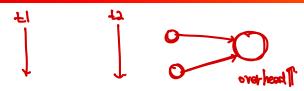




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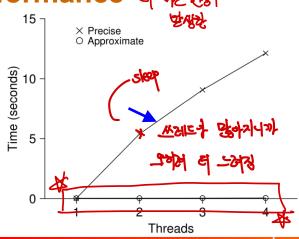
Concurrent Counters



- A concurrent counter requires locks to make it work correctly
 - Before accessing the counter variable, each thread must acquire the lock

The problem of this implementation is performance.

- Each thread update the counter one million times
- Varying the number of threads (1~4)
- Running on iMac with four Intel 2.7GHz i5 CPUs
- Unfortunately, the performance scales poorly
- Adding thread leads to massive slowdown



Scalable Counting

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- The approximate counter works by representing a single logical counter via many local physical counters, one per CPU core, and a single global counter
- Each local counter and the global counter have their own lock
- The basic idea of approximate counting is
 -) Each thread running on a given core increments its local counter using lock
 - 2) The local values are periodically transferred to the global counter using lock
 - 3) The local counter resets to zero after the transfer

■ Tracing the approximate counters: (he 4

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the global counterful the

Time	L_1	L_2	L_3	L_4	G
0	0	0	0	0	
1	0	0	1	1	0 (5) threshold '
2	1	0	2	1	0
3	2	0	3	1	0
4	3	0	3	2	0 (alphal contrats that of a
5	4	1	3	3	0
6	$5 \rightarrow 0$	1	3	4	$5 ext{ (from } L_1)$
7	0	2	4	$5 \rightarrow 0$	$10 \text{ (from } L_4)$
,					

S = 5

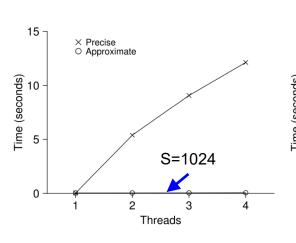
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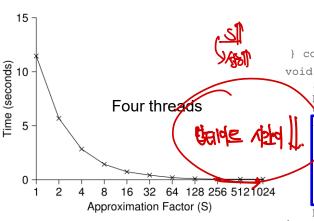




- How often this local-to-global transfer occurs is determined by a threshold S
 - The smaller S is, the more the counter behaves like the non-scalable counter
 - The bigger S is, the more scalable the counter, but the further off the global value might be from the actual count
- The performance of approximate counter is excellent
 - The time does not increase significantly as the number of thread increases
 - If S is high, the performance is excellent but the global counter lags

If S is low, the performance is poor (accurate)





```
// global count
    pthread mutex t glock;
                     local[NUMCPUS]; //
    pthread mutex t llock[NUMCPUS]; // ... and locks
    int
                                      // update frequency
} counter_t;
void update(counter_t *c, int threadID,
    int cpu = threadID % NUMCPUS;
   pthread_mutex_lock(&c->llock[cpu]);
    ->local[cpu] += amt;
       (c->local[cpu] >= c->threshold)
        // transfer to global (assumes amt>0)
        pthread_mutex_lock(&c->glock);
        c->global += c->local[cpu];
        pthread_mutex_unlock(&c->glock);
        c \rightarrow local[cpu] = 0;
    pthread mutex unlock(&c->llock[cpu]);
```

Concurrent Linked Lists

We next examine a more complicated structure, the linked list

```
// basic list structure (one used per list)
// basic node structure
                                                     typedef struct __list_t {
typedef struct node t {
                                                         node t
    int
                         key;
                                                                                *head;
                                                        pthread_mutex_t
    struct __node_t
} node t;
                                                      list t;
int List_Insert(list_t *L, int key) {
                                                     int List_Lookup(list_t *L, int key) {

    pthread_mutex_lock(&L->lock);

                                                         pthread_mutex_lock(&L->lock);
    node_t *new = malloc(sizeof(node_t));
                                                         node t *curr = L->head;
    if (new == NULL) {
                                                         while (curr) {
        perror("malloc");
                                                             if (curr->key - key)
       pthread_mutex_unlock(&L->lock);
                                                                 pthread_mutex_unlock(&L->lock);
       return -1; // fail
    new->key = key;
                                                              curr = curr->next;
    new->next = L->head;
    L->head = new;
                                                         pthread_mutex_unlock(&L->lock);
   pthread_mutex_unlock(&L->lock);
    return 0; // success
```

- The code acquires a lock in the insert routine upon entry and releases upon exit
- If malloc() fails, the code must also release the lock before failing the insert
- This kind of exceptional control flow is to be quite error prone
 - Can we rewrite the insert and lookup codes to remain correct under concurrent insert but avoid the case where the failure path requires the call to unlock?
 - The answer is YES

Revised Concurrent Linked List

- We can do the lock and release only surround the actual critical section and a common exit path is used in the lookup code
 - The former works because part of the insert actually need not be locked
 - Only when updating the shared list does a lock need to be held

```
void List_Insert(list_t *L, int key) {
                                                                      int List_Lookup(list_t *L, int key) {
    // synchronization not needed
                                                                          int rv = -1;
   node_t *new = malloc(sizeof(node_t));
                                                                          pthread mutex lock (&L->lock);
    if (new == NULL) {
                                                 ħead
                                                                          node_t *curr = L->head;
        perror("malloc");
                                                                          while (curr) {
        return;
                                                                              if (curr->key == key) {
                                          new
                                                                                  rv = 0;
   new->key = key;
                                                                                  break:
    // just lock critical section
                                     T2: new
                                                                              curr = curr->next;
    pthread_mutex_lock(&L->lock
    new->next = L->head;
                                                                          pthread_mutex_unlock(&
    L->head = new;
                                                                          return rv: // now both success and failure
    pthread_mutex_unlock(&L/>lock);
                                                                                类胎 0
```

- Scalable linked list can be achieved by adding a lock per node
 - This enables a high degree of concurrency in list operations
 - However, it is hard to make it faster than the single lock approach

Concurrent Queues - heads to looke 2019 to



- There is always a standard method to make a concurrent data structure: add a big lock
 - For concurrent queues, we can achieve scalability by adding two locks, each for head and tail of the queue, enabling concurrency of enqueue and dequeue

```
typedef struct __node_t {
    int
                        value;
    struct node t
                       *next;
} node t;
void Queue_Init(queue_t *q) {
    node_t *tmp = malloc(sizeof(node_t));
    tmp->next = NULL;
   q->head = q->tail = tmp;
    pthread_mutex_init(&q->head_lock, NULL);
    pthread_mutex_init(&q->tail_lock, NULL);
void Queue_Enqueue(queue_t *q, int value) {
    node_t *tmp = malloc(sizeof(node_t));
    assert (tmp != NULL);
    tmp->value = value;
    tmp->next = NULL;
    pthread_mutex_lock(&q->tail_lock);
    q->tail->next = tmp;
    q->tail = tmp;
    pthread_mutex_unlock(&q->tail_lock);
```

```
typedef struct __queue_t {
                         *head;
    node t
    node t
                         *tail:
    pthread mutex t
                         head_lock, tail_lock
} queue t;
int Queue_Dequeue(queue_t *q, int *value) {
   pthread_mutex_lock(&q->head_lock);
    node t *tmp = q->head;
    node_t *new_head = tmp->next;
    if (new head == NULL) {
        pthread_mutex_unlock(&q->head_lock);
        return -1; // queue was empty
    *value = new_head->value;
   q->head = new_head;
   pthread_mutex_unlock(&q->head_lock);
    free (tmp);
    return 0;
```

Concurrent Hash Table

- We finally consider a simple and widely applicable concurrent data structure, the hash table "All 350%",
 - Let's focus on a simple hash table that does not resize
 - This concurrent hash table is straightforward, is built using the concurrent lists we developed earlier
- The performance of this hash table is good
 - Instead of a single lock for the entire structure, it uses a lock per hash bucket

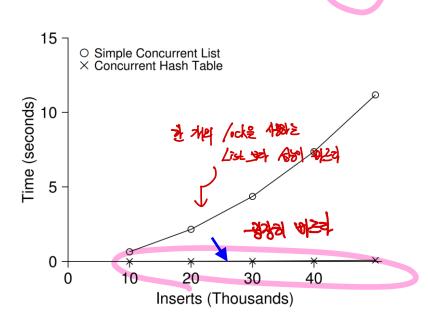
```
#define BUCKETS (101)

typedef struct __hash_t {
    list_t lists[BUCKETS];
} hash_t;

void Hash_Init(hash_t *H) {
    int i;
    for (i = 0; i < BUCKETS; i++)
        List_Init(&H->lists[i]);
}

int Hash_Insert(hash_t *H, int key) {
    return List_Insert(&H->lists[key % BUCKETS], key);
}

int Hash_Lookup(hash_t *H, int key) {
    return List_Lookup(&H->lists[key % BUCKETS], key);
}
```



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