

By eq (5.276), with $|i\rangle = |0\rangle$,

$$\begin{aligned}
 c_n^{(1)}(t) &= \frac{-i}{\hbar} \int_{t_0}^t e^{i\omega_{n0}t'} V_{n0}(t') dt' \\
 &= \frac{-i}{\hbar} \int_{t_0}^t e^{i\omega_{n0}t'} \langle n|F_0 x \cos \omega t'|0\rangle dt' \\
 &= \frac{-iF_0}{\hbar} \sqrt{\frac{\hbar}{2m\omega_0}} \int_{t_0}^t e^{i\omega_{n0}t'} \cos \omega t' \langle n|a + a^\dagger|0\rangle dt' \quad (\text{only } n = 1 \text{ survives, with } \omega_{10} = \omega_0) \\
 &= \frac{-iF_0}{\hbar} \sqrt{\frac{\hbar}{2m\omega_0}} \int_{t_0}^t e^{i\omega_0 t'} \cos \omega t' dt' \\
 &= \frac{-iF_0}{\hbar} \sqrt{\frac{\hbar}{2m\omega_0}} \int_{t_0}^t e^{i\omega_0 t'} \frac{1}{2} (e^{i\omega t'} + e^{-i\omega t'}) dt' \\
 &= \frac{-iF_0}{\hbar} \sqrt{\frac{\hbar}{2m\omega_0}} \frac{1}{2} \left[\frac{e^{i(\omega_0+\omega)t} - 1}{i(\omega_0 + \omega)} + \frac{e^{i(\omega_0-\omega)t} - 1}{i(\omega_0 - \omega)} \right] \\
 &= -\frac{F_0}{2\hbar} \sqrt{\frac{\hbar}{2m\omega_0}} \left[\frac{e^{i(\omega_0+\omega)t} - 1}{\omega_0 + \omega} + \frac{e^{i(\omega_0-\omega)t} - 1}{\omega_0 - \omega} \right] \quad (1)
 \end{aligned}$$

To evaluate $\langle x \rangle$ at t , we will have to obtain the Schrödinger-picture final state by applying $e^{-iH_0 t/\hbar}$ to $|\alpha, t_0; t\rangle_I = |0\rangle + c_1^{(1)}(t)|1\rangle$:

$$|\alpha, t_0; t\rangle_S = e^{-iH_0 t/\hbar} |0\rangle + e^{-iH_0 t/\hbar} c_1^{(1)}(t) |1\rangle = e^{-i\omega_0 t/2} |0\rangle + e^{-i3\omega_0 t/2} c_1^{(1)}(t) |1\rangle \quad (2)$$

which gives

$$\begin{aligned}
 \langle x \rangle_S &= \sqrt{\frac{\hbar}{2m\omega_0}} \langle \alpha, t_0; t | a + a^\dagger | \alpha, t_0; t \rangle_S \\
 &= \sqrt{\frac{\hbar}{2m\omega_0}} \left[e^{i\omega_0 t/2} e^{-i3\omega_0 t/2} c_1^{(1)}(t) + e^{i3\omega_0 t/2} e^{-i\omega_0 t/2} c_1^{(1)*}(t) \right] \\
 &= \sqrt{\frac{\hbar}{2m\omega_0}} \left[e^{-i\omega_0 t} c_1^{(1)}(t) + e^{i\omega_0 t} c_1^{(1)*}(t) \right] \\
 &= -\frac{F_0}{4m\omega_0} \left[\frac{e^{i\omega t} - e^{-i\omega_0 t}}{\omega_0 + \omega} + \frac{e^{-i\omega t} - e^{-i\omega_0 t}}{\omega_0 - \omega} + \frac{e^{-i\omega t} - e^{i\omega_0 t}}{\omega_0 + \omega} + \frac{e^{i\omega t} - e^{i\omega_0 t}}{\omega_0 - \omega} \right] \\
 &= -\frac{F_0}{4m\omega_0} \left[\frac{2 \cos \omega t - 2 \cos \omega_0 t}{\omega_0 + \omega} + \frac{2 \cos \omega t - 2 \cos \omega_0 t}{\omega_0 - \omega} \right] \\
 &= -\frac{F_0}{2m\omega_0} (\cos \omega t - \cos \omega_0 t) \left(\frac{1}{\omega_0 + \omega} + \frac{1}{\omega_0 - \omega} \right) \\
 &= -\frac{F_0}{m} \frac{\cos \omega t - \cos \omega_0 t}{\omega_0^2 - \omega^2} \quad (3)
 \end{aligned}$$

Note the expected value $\langle x \rangle$ as a function of t agrees with classical solution to the forced oscillator

$$m \frac{d^2 x}{dt^2} + m\omega_0^2 x + F_0 \cos \omega t = 0 \quad (4)$$

whose solution, with boundary condition $x(0) = 0, \dot{x}(0) = 0$, is exactly (3).