Project of EL-GY9123 Introduction to Machine Learning

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Guide to get data

The dataset used in this project is PASCAL Visual Object Classes Challenge 2011 (known as VOC2011). To download it and make the program work, first you need to download the dataset in tar format.

\$ curl -L http://host.robots.ox.ac.uk/pascal/VOC/voc2011/VOCtrainval_25-May-2011.tar \
> > VOCtrainval_25-May-2011.tar

Then extract it.

\$ tar -xvzf VOCtrainval_25-May-2011.tar

Finally move the data to data folder.

\$ mv TrainVal/VOCdevkit/VOC2011 /path/to/workspace/data

Main files

1. model.py

```
To build a FCN model based on VGG16.
```

```
#!usr/bin/python
#-*- coding:utf-8 -*-
Fully Convolutional Neural Network Based on VGG16
Standard libraries
import keras
import keras.backend as K
from keras.models import Model
from keras.layers import Input, Flatten, Activation, Reshape, Dropout, Conv2D, Lambda
from keras.layers.merge import add
from keras.regularizers import 12
from keras.applications.vgg16 import VGG16
. . .
Custom functions
from BilinearUpSampling import BilinearUpSampling2D
def fc_vgg16(filters=4096, weight_decay=0., block_name='block5'):
   Add fully connected layer to the model
    1 1 1
```

```
def f(x):
        x = Conv2D(filters=filters,
                kernel size=(7, 7),
                activation='relu',
                padding='same',
                dilation rate=(2, 2),
                kernel initializer='he normal',
                kernel_regularizer=12(weight_decay),
                name='{}_fc6'.format(block_name))(x)
        x = Dropout(0.5)(x)
        x = Conv2D(filters=filters,
                kernel_size=(1, 1),
                activation='relu',
                padding='same',
                dilation_rate=(2, 2),
                kernel_initializer='he_normal',
                kernel_regularizer=12(weight_decay),
                name='{}_fc7'.format(block_name))(x)
        x = Dropout(0.5)(x)
        return x
   return f
def upsampling_vgg16(classes, target_shape=None, scale=1, weight_decay=0., block_name='featx'):
   Upsampling layers
    1 1 1
   def f(x, y):
        score = Conv2D(filters=classes,
                kernel_size=(1, 1),
                activation='linear',
                padding='valid',
                kernel_initializer='he_normal',
                kernel_regularizer=12(weight_decay),
                name='score_{}'.format(block_name))(x)
        if v is not None:
            def scaling(xx, ss=1):
                return xx*ss
            scaled = Lambda(scaling, arguments={'ss': scale},
                    name='scale_{}'.format(block_name))(score)
            score = add([y, scaled])
        upscore = BilinearUpSampling2D(target shape=target shape,
                name='upscore_{}'.format(block_name))(score)
        return upscore
   return f
def UpSampler_vgg16(pyramid, scales, classes, weight_decay=0.):
    Upsampling block
   blocks = []
   for i in range(len(pyramid) - 1):
        block_name = 'feat{}'.format(i + 1)
        block = upsampling_vgg16(classes=classes,
```

```
target_shape=K.int_shape(pyramid[i+1]),
                scale=scales[i],
                weight decay=weight decay,
                block_name=block_name)
        blocks.append(block)
   decoded = None
   for feat, blk in zip(pyramid[:-1], blocks):
        decoded = blk(feat, decoded)
   return decoded
def fcn_vgg16(input_shape, classes, weight_decay=0.,
        trainable_encoder=True, weights='imagenet'):
    . . .
   Construct model
    inputs = Input(shape=input_shape)
   pyrmid_layers = 3
   # Use VGG16 as the encoder
   encoder = VGG16(include_top=False, input_shape=input_shape, weights=weights, classes=classes)
   # Set parameters in VGG16 to be untrainable
   for layer in encoder.layers:
        layer.trainable = False
   first = True
   pyramid = []
   for layer in encoder.layers:
        if first:
            x = layer(inputs)
            first = False
            pyramid.append(x)
        else:
            x = layer(x)
            if x.shape[1:-1] != pyramid[-1].shape[1:-1]:
                pyramid.append(x)
   x = fc_vgg16(filters=4096)(x)
   pyramid[-1] = x
   feat_pyramid = pyramid[::-1][:pyrmid_layers]
   feat_pyramid.append(inputs)
    outputs = UpSampler_vgg16(feat_pyramid,
            scales=[1, 1e-2, 1e-4],
            classes=classes,
            weight_decay=weight_decay)
    scores = Activation('softmax')(outputs)
```

2. train.py

```
To train the model with VOC2011.
#!/usr/bin/python
#-*- coding:utf-8 -*-
Standard libraries
import keras
import keras.backend as K
from keras.optimizers import Adam
from keras.callbacks import (ModelCheckpoint,
        ReduceLROnPlateau,
        EarlyStopping,
        TerminateOnNaN,
        CSVLogger)
from keras import Input
{\tt from\ voc\_generator\ import\ PascalVocGenerator,\ ImageSetLoader}
import numpy as np
1 1 1
Custom libraries
import model
# Clear session
K.clear_session()
def arg_gen(dataset_name):
    Generate arguments of dataset generators
    image_set = 'data/VOC2011/ImageSets/Segmentation/{}.txt'.format(dataset_name)
    image_dir = 'data/VOC2011/JPEGImages/'
    label_dir = 'data/VOC2011/SegmentationClass/'
    target_size = (224, 224)
    return image_set, image_dir, label_dir, target_size
def main():
    1 1 1
    Main function
    # Define common arguments
    checkpointer = ModelCheckpoint(
            filepath='output/fcn_vgg16_weights_tmp.h5',
            verbose=1,
            save_best_only=True)
    lr_reducer = ReduceLROnPlateau(
            monitor='val_loss',
```

```
factor=np.sqrt(0.1),
        cooldown=0,
        patience=10,
        min_lr=1e-12)
early_stopper = EarlyStopping(
        monitor='val loss',
        min delta=0.001,
        patience=30)
nan terminator = TerminateOnNaN()
csv_logger = CSVLogger('output/tmp_fcn_vgg16.csv')
# Set data generator
datagen = PascalVocGenerator(image_shape=[224, 224, 3],
        image_resample=True,
        pixelwise_center=True,
        pixel_mean=[115.85100, 110.50989, 102.16182],
        pixelwise_std_normalization=True,
        pixel_std=[70.30930, 69.41244, 72.60676])
# Define training set and validation set
train_loader = ImageSetLoader(*arg_gen('train'))
val_loader = ImageSetLoader(*arg_gen('val'))
# Construct model
fcn_vgg16 = model.fcn_vgg16(input_shape=(224, 224, 3),
        classes=21,
        weight_decay=3e-3,
        weights='imagenet',
        trainable_encoder=False)
# Set optimizer
optimizer = Adam(1e-4)
# Compile model
fcn_vgg16.compile(
        optimizer=optimizer,
        loss='categorical crossentropy',
        metrics=['accuracy'])
# Fit model with the above generators
fcn vgg16.fit generator(
    datagen.flow_from_imageset(
        class_mode='categorical',
        classes=21,
        batch_size=1,
        shuffle=True,
        image_set_loader=train_loader),
    steps_per_epoch=1112,
    epochs=40,
    validation_data=datagen.flow_from_imageset(
        class_mode='categorical',
        classes=21,
        batch_size=1,
        shuffle=True,
```

```
image_set_loader=val_loader),
        validation_steps=1111,
        callbacks=[lr_reducer, early_stopper, csv_logger, checkpointer, nan_terminator])
   # Save weights
   fcn vgg16.save('output/fcn vgg16.h5')
if __name__ == '__main__':
   main()
3. inference.ipynb
The jupyter notebook to test the model.
import numpy as np
import keras
import keras.backend as K
from keras.models import load_model
from voc_generator import PascalVocGenerator, ImageSetLoader
from BilinearUpSampling import BilinearUpSampling2D
import matplotlib.pyplot as plt
/home/y14704/.local/lib/python3.6/site-packages/h5py/__init__.py:36: FutureWarning: Conversion of the s
  from ._conv import register_converters as _register_converters
Using TensorFlow backend.
def arg_gen(dataset_name):
    Generate arguments of dataset generators
    image_set = 'data/VOC2011/ImageSets/Segmentation/{}.txt'.format(dataset_name)
    image_dir = 'data/VOC2011/JPEGImages/'
   label_dir = 'data/VOC2011/SegmentationClass/'
   target_size = (224, 224)
   return image_set, image_dir, label_dir, target_size
datagen = PascalVocGenerator(image_shape=[224, 224, 3],
            image_resample=True,
            pixelwise_center=True,
           pixel_mean=[115.85100, 110.50989, 102.16182],
           pixelwise_std_normalization=True,
           pixel_std=[70.30930, 69.41244, 72.60676])
train_loader = ImageSetLoader(*arg_gen('train'))
val_loader = ImageSetLoader(*arg_gen('val'))
model = load_model('output/fcn_vgg16_weights.h5',
        custom_objects={'BilinearUpSampling2D': BilinearUpSampling2D})
print(model.summary())
WARNING:tensorflow:From /home/y14704/.local/lib/python3.6/site-packages/keras/backend/tensorflow_backen
Instructions for updating:
keep_dims is deprecated, use keepdims instead
```

Instructions for updating:

WARNING:tensorflow:From /home/y14704/.local/lib/python3.6/site-packages/keras/backend/tensorflow_backen

keep_dims is deprecated, use keepdims instead

WARNING:tensorflow:From /home/y14704/.local/lib/python3.6/site-packages/keras/backend/tensorflow_backend Instructions for updating:

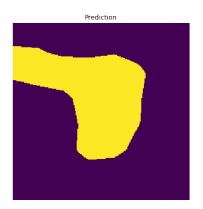
 ${\tt keep_dims}$ is deprecated, use keepdims instead

Layer (type)	Output Shape	Param #	Connected to
input_1 (InputLayer)	(None, 224, 224, 3)	0	
block1_conv1 (Conv2D)	(None, 224, 224, 64)	1792	input_1[0][0]
block1_conv2 (Conv2D)	(None, 224, 224, 64)	36928	block1_conv1[0][0]
block1_pool (MaxPooling2D)	(None, 112, 112, 64)	0	block1_conv2[0][0]
block2_conv1 (Conv2D)	(None, 112, 112, 128)	73856	block1_pool[0][0]
block2_conv2 (Conv2D)	(None, 112, 112, 128)	147584	block2_conv1[0][0]
block2_pool (MaxPooling2D)	(None, 56, 56, 128)	0	block2_conv2[0][0]
block3_conv1 (Conv2D)	(None, 56, 56, 256)	295168	block2_pool[0][0]
block3_conv2 (Conv2D)	(None, 56, 56, 256)	590080	block3_conv1[0][0]
block3_conv3 (Conv2D)	(None, 56, 56, 256)	590080	block3_conv2[0][0]
block3_pool (MaxPooling2D)	(None, 28, 28, 256)	0	block3_conv3[0][0]
block4_conv1 (Conv2D)	(None, 28, 28, 512)	1180160	block3_pool[0][0]
block4_conv2 (Conv2D)	(None, 28, 28, 512)	2359808	block4_conv1[0][0]
block4_conv3 (Conv2D)	(None, 28, 28, 512)	2359808	block4_conv2[0][0]
block4_pool (MaxPooling2D)	(None, 14, 14, 512)	0	block4_conv3[0][0]
block5_conv1 (Conv2D)	(None, 14, 14, 512)	2359808	block4_pool[0][0]
block5_conv2 (Conv2D)	(None, 14, 14, 512)	2359808	block5_conv1[0][0]
block5_conv3 (Conv2D)	(None, 14, 14, 512)	2359808	block5_conv2[0][0]
block5_pool (MaxPooling2D)	(None, 7, 7, 512)	0	block5_conv3[0][0]
block5_fc6 (Conv2D)	(None, 7, 7, 4096)	102764544	block5_pool[0][0]
dropout_1 (Dropout)	(None, 7, 7, 4096)	0	block5_fc6[0][0]
block5_fc7 (Conv2D)	(None, 7, 7, 4096)	16781312	dropout_1[0][0]
dropout_2 (Dropout)	(None, 7, 7, 4096)	0	block5_fc7[0][0]
score_feat1 (Conv2D)	(None, 7, 7, 21)	86037	dropout_2[0][0]

```
score_feat2 (Conv2D) (None, 14, 14, 21) 10773 block4_pool[0][0]
upscore_feat1 (BilinearUpSamplin (None, 14, 14, 21) 0
                                                     score_feat1[0][0]
scale_feat2 (Lambda) (None, 14, 14, 21) 0
                                                     score_feat2[0][0]
                           (None, 14, 14, 21) 0 upscore_feat1[0][0]
add 1 (Add)
                                                      scale_feat2[0][0]
score_feat3 (Conv2D)
                   (None, 28, 28, 21) 5397 block3_pool[0][0]
upscore_feat2 (BilinearUpSamplin (None, 28, 28, 21) 0
                                                     add_1[0][0]
scale_feat3 (Lambda)
                           (None, 28, 28, 21) 0 score_feat3[0][0]
                     (None, 28, 28, 21) 0 upscore_feat2[0][0] scale_feat3[0][0]
add_2 (Add)
upscore_feat3 (BilinearUpSamplin (None, 224, 224, 21) 0
                                                     add_2[0][0]
activation_1 (Activation) (None, 224, 224, 21) 0 upscore_feat3[0][0]
______
Total params: 134,362,751
Trainable params: 119,648,063
Non-trainable params: 14,714,688
None
def show_result(n, dataload=train_loader):
   Show the result of prediction and compare it with the ground truth both in classes and output figur
   classes = ['background',
            'aeroplane', 'bicycle', 'bird', 'boat',
            'bottle', 'bus', 'car', 'cat',
            'chair', 'sheep', 'dinning table', 'dog',
            'horse', 'motorbike', 'person', 'potted plant',
            'cow', 'sofa', 'train', 'monitor']
   for fn in dataload.filenames[n:n+1]:
      raw = dataload.load img(fn)
      x = datagen.standardize(raw)
      X = x[np.newaxis, ...]
      label = dataload.load_seg(fn)
      label = np.squeeze(label, axis=-1).astype('int')
      y_enc = np.eye(21)[label]
      y_true = y_enc[np.newaxis, ...]
      result = model.evaluate(X, y_true)
      y_pred = model.predict(X)
      loss = keras.losses.categorical_crossentropy(K.variable(y_true), K.variable(y_pred))
      #print(K.eval(loss))
      pred = np.argmax(y_pred, axis=-1)
```

```
pred = pred[..., np.newaxis]
       pred = np.squeeze(pred, axis=0)
       print('True Labels: ', np.unique(label))
       print('Predicted Labels: ', np.unique(pred))
       print('True Classes: ', end=' ')
       for i in range(1, len(np.unique(label))):
            if i != 1:
               print(end=', ')
            print(classes[np.unique(label)[i]], end='')
       print('Predicted Classes: ', end=' ')
       for i in range(1, len(np.unique(pred))):
            if i != 1:
               print(end=', ')
            print(classes[np.unique(pred)[i]], end='')
       print()
       plt.figure(figsize=(20,20))
       plt.subplot(1,3,1)
       plt.axis('off')
       plt.imshow(raw)
       plt.title('Original Image')
       plt.subplot(1,3,2)
       plt.axis('off')
       plt.imshow(np.squeeze(pred))
       plt.title('Prediction')
       plt.subplot(1,3,3)
       plt.axis('off')
       plt.imshow(label)
       plt.title('Groud Truth')
       plt.savefig('Result.png')
       plt.show()
show_result(10)
1/1 [======== ] - 0s
WARNING:tensorflow: Variable /= will be deprecated. Use variable.assign_div if you want assignment to th
Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integration
True Labels: [ 0 19]
Predicted Labels: [ 0 19]
True Classes: train
Predicted Classes: train
```







4. BilinearUpSampling.py

Upsampling part, modified from author, JihongJu.

```
#!/usr/bin/python
#-*- coding:utf-8 -*-
import keras.backend as K
import tensorflow as tf
from keras.utils import conv_utils
from keras.engine.topology import Layer
from keras.engine import InputSpec
def resize_images(x, size):
   new_size = tf.convert_to_tensor(size, dtype=tf.int32)
   resized = tf.image.resize_images(x, new_size)
   return resized
class BilinearUpSampling2D(Layer):
    """Upsampling2D with bilinear interpolation."""
   def __init__(self, target_shape=None, data_format=None, **kwargs):
        if data_format is None:
            data_format = K.image_data_format()
        assert data_format in {
            'channels_last', 'channels_first'}
        self.data_format = data_format
        self.input_spec = [InputSpec(ndim=4)]
        self.target_shape = target_shape
        if self.data_format == 'channels_first':
            self.target_size = (target_shape[2], target_shape[3])
        elif self.data_format == 'channels_last':
            self.target_size = (target_shape[1], target_shape[2])
        super(BilinearUpSampling2D, self).__init__(**kwargs)
   def compute_output_shape(self, input_shape):
        if self.data_format == 'channels_last':
            return (input_shape[0], self.target_size[0],
                    self.target_size[1], input_shape[3])
```

```
else:
            return (input_shape[0], input_shape[1],
                    self.target_size[0], self.target_size[1])
    def call(self, inputs):
        return resize_images(inputs, size=self.target_size)
        #return K.resize_images(inputs, self.target_size[0], self.target_size[1], data_format='channels
   def get_config(self):
        config = {'target_shape': self.target_shape,
                'data_format': self.data_format}
        base_config = super(BilinearUpSampling2D, self).get_config()
        return dict(list(base_config.items()) + list(config.items()))
5. printmodel.py
Used to plot the model in .png format.
#!/usr/bin/python
#-*- coding:utf-8 -*-
from keras.utils import plot_model
import model
def plot_fcn_vgg16():
    input_shape = (224, 224, 3)
   fcn_vgg16 = model.fcn_vgg16(input_shape=input_shape, classes=21)
   plot_model(fcn_vgg16, to_file='fcn_vgg16.png', show_shapes=True)
if __name__ == '__main__':
   plot_fcn_vgg16()
6. voc_generator.py
Data generator for VOC, copied from author, JihongJu.
"""Pascal VOC Segmenttion Generator."""
from __future__ import unicode_literals
import os
import numpy as np
from keras import backend as K
from keras.utils.np_utils import to_categorical
from keras.preprocessing.image import (
    ImageDataGenerator,
   Iterator,
   load_img,
    img_to_array,
   pil_image,
    array_to_img)
class PascalVocGenerator(ImageDataGenerator):
    """A real-time data augmentation generator for PASCAL VOC2011."""
```

```
def __init__(self,
             image_shape=(500, 500, 3),
             image resample=True,
             pixelwise_center=False,
             pixel_mean=(0., 0., 0.),
             pixelwise std normalization=False,
             pixel std=(1., 1., 1.),
             featurewise_center=False,
             samplewise_center=False,
             featurewise_std_normalization=False,
             samplewise_std_normalization=False,
             zca_whitening=False,
             rotation_range=0.,
             width_shift_range=0.,
             height_shift_range=0.,
             shear_range=0.,
             zoom_range=0.,
             channel shift range=0.,
             fill_mode='nearest',
             cval=0.,
             horizontal_flip=False,
             vertical_flip=False,
             rescale=None,
             preprocessing function=None,
             data format=None):
    self.image_shape = tuple(image_shape)
    self.image_resample = image_resample
    self.pixelwise_center = pixelwise_center
    self.pixel_mean = np.array(pixel_mean)
    self.pixelwise_std_normalization = pixelwise_std_normalization
    self.pixel_std = np.array(pixel_std)
    super(PascalVocGenerator, self).__init__()
def standardize(self, x):
    """Standardize image."""
    if self.pixelwise center:
        x -= self.pixel_mean
    if self.pixelwise_std_normalization:
        x /= self.pixel_std
    return super(PascalVocGenerator, self).standardize(x)
def flow_from_imageset(self, image_set_loader,
                       class_mode='categorical', classes=None,
                       batch_size=1, shuffle=True, seed=None):
    """PascalVocGenerator."""
    return IndexIterator(
        image_set_loader, self,
        class_mode=class_mode,
        classes=classes,
        batch_size=batch_size,
        shuffle=shuffle,
        seed=seed)
```

```
class IndexIterator(Iterator):
    """Iterator over index."""
   def __init__(self, image_set_loader, image_data_generator,
                 class mode='categorical', classes=None,
                 batch size=1, shuffle=False, seed=None):
        """Tnit."""
        self.image_set_loader = image_set_loader
        self.image_data_generator = image_data_generator
        self.filenames = image_set_loader.filenames
        self.image_shape = image_set_loader.image_shape
        self.classes = classes
        if class_mode == 'binary':
            label_shape = list(self.image_shape).pop(self.channel_axis - 1)
            self.label shape = tuple(label shape)
        elif class_mode == 'categorical':
            label_shape = list(self.image_shape)
            label_shape[self.image_data_generator.channel_axis - 1] \
                = self.classes
            self.label_shape = tuple(label_shape)
        super(IndexIterator, self).__init__(len(self.filenames), batch_size,
                                            shuffle, seed)
   def next(self):
        """Next batch."""
        with self.lock:
            index_array, current_index, current_batch_size = next(
                self.index_generator)
        batch_x = np.zeros(
            (current_batch_size,) + self.image_shape,
            dtvpe=K.floatx())
        batch_y = np.zeros(
            (current_batch_size,) + self.label_shape,
            dtype=np.int8)
        #batch_y = np.reshape(batch_y, (current_batch_size, -1, self.classes))
        for i, j in enumerate(index_array):
           fn = self.filenames[j]
            x = self.image set loader.load img(fn)
            x = self.image_data_generator.standardize(x)
           batch_x[i] = x
            y = self.image_set_loader.load_seg(fn)
            y = to_categorical(y, self.classes).reshape(self.label_shape)
            #y = np.reshape(y, (-1, self.classes))
            batch_y[i] = y
        # save augmented images to disk for debugging
        #if self.image_set_loader.save_to_dir:
             for i in range(current_batch_size):
        #
                 x = batch x[i]
```

```
y = batch_y[i].argmax(
                     self.image_data_generator.channel_axis - 1)
                 if self.image data generator.data format == 'channels first':
        #
                     y = y[np.newaxis, ...]
        #
                 else:
        #
                     y = y[..., np.newaxis]
                 self.image set loader.save(x, y, current index + i)
        return batch_x, batch_y
class ImageSetLoader(object):
    """Helper class to load image data into numpy arrays."""
   def __init__(self, image_set, image_dir, label_dir, target_size=(500, 500),
                 image_format='jpg', color_mode='rgb', label_format='png',
                 data_format=None,
                 save_to_dir=None, save_prefix='', save_format='jpg'):
        """Init."""
        if data format is None:
            data_format = K.image_data_format()
        self.data format = data format
        self.target_size = tuple(target_size)
        if not os.path.exists(image_set):
            raise IOError('Image set {} does not exist. Please provide a'
                          'valid file.'.format(image_set))
        self.filenames = np.loadtxt(image_set, dtype=bytes)
            self.filenames = [fn.decode('utf-8') for fn in self.filenames]
        except AttributeError as e:
            print(str(e), self.filenames[:5])
        if not os.path.exists(image_dir):
            raise IOError('Directory {} does not exist. Please provide a '
                          'valid directory.'.format(image_dir))
        self.image_dir = image_dir
        if label dir and not os.path.exists(label dir):
            raise IOError('Directory {} does not exist. Please provide a '
                          'valid directory.'.format(label_dir))
        self.label_dir = label_dir
        white_list_formats = {'png', 'jpg', 'jpeg', 'bmp'}
        self.image_format = image_format
        if self.image_format not in white_list_formats:
            raise ValueError('Invalid image format:', image_format,
                             '; expected "png", "jpg", "jpeg" or "bmp"')
        self.label_format = label_format
        if self.label_format not in white_list_formats:
            raise ValueError('Invalid image format:', label_format,
                             '; expected "png", "jpg", "jpeg" or "bmp"')
        if color mode not in {'rgb', 'grayscale'}:
            raise ValueError('Invalid color mode:', color_mode,
                             '; expected "rgb" or "grayscale".')
```

```
self.color_mode = color_mode
    if self.color_mode == 'rgb':
        if self.data format == 'channels last':
            self.image_shape = self.target_size + (3,)
        else:
            self.image_shape = (3,) + self.target_size
    else:
        if self.data_format == 'channels_last':
            self.image_shape = self.target_size + (1,)
        else:
            self.image_shape = (1,) + self.target_size
    self.grayscale = self.color_mode == 'grayscale'
    self.save_to_dir = save_to_dir
    self.save_prefix = save_prefix
    self.save_format = save_format
def load_img(self, fn):
    """Image load method.
    # Arguments
        fn: filename of the image (without extension suffix)
        arr: numpy array of shape self.image_shape
    img_path = os.path.join(self.image_dir,
                             '{}.{}'.format(fn,
                                           self.image_format))
    if not os.path.exists(img_path):
        raise IOError('Image {} does not exist.'.format(img_path))
    img = load_img(img_path, self.grayscale, self.target_size)
    x = img_to_array(img, data_format=self.data_format)
    return x
def load seg(self, fn):
    """Segmentation load method.
    # Arguments
        fn: filename of the image (without extension suffix)
    # Returns
        arr: numpy array of shape self.target_size
    label_path = os.path.join(self.label_dir,
                               '{}.{}'.format(fn, self.label_format))
    img = pil_image.open(label_path)
    if self.target_size:
        wh_tuple = (self.target_size[1], self.target_size[0])
    if img.size != wh_tuple:
        img = img.resize(wh_tuple)
    y = img_to_array(img, self.data_format)
    y[y == 255] = 0
```

```
return y

def save(self, x, y, index):
    """"Image save method."""
    img = array_to_img(x, self.data_format, scale=True)
    mask = array_to_img(y, self.data_format, scale=True)
    img.paste(mask, (0, 0), mask)

fname = 'img_{prefix}_{index}_{hash}.{format}'.format(
        prefix=self.save_prefix,
        index=index,
        hash=np.random.randint(1e4),
        format=self.save_format)
    img.save(os.path.join(self.save_to_dir, fname))
```

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