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# **Preparing Raspberry Pi**

#### Install Raspbian Jessie on the Raspberry Pi

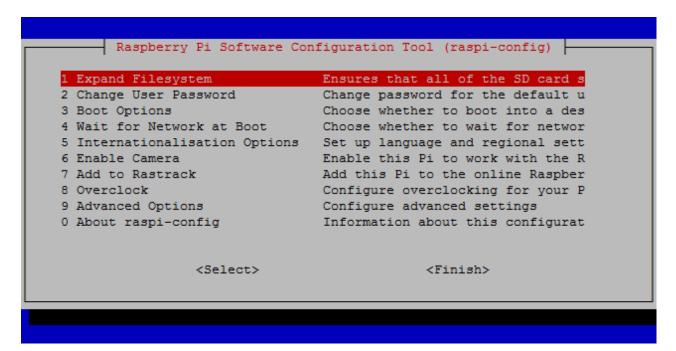
Click **HERE** to download Raspbian Jessie.

#### **Expand file system**

Run the following command line within the Raspberry Pi's terminal.

sudo raspi-config

You should see a blue screen with options in a gray box in the center, like so



Choose "Expand Filesystem"

Choosing this option will expand your installation to fill the rest of the SD card, giving you more space to use for files. You will need to reboot the Raspberry Pi to make this available.



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#### **Update and Upgrade Packages**

First, you will need to update your system's package list by entering the following command in terminal.

sudo apt-get update

Next, upgrade your installed packages to their latest versions with the command.

sudo apt-get upgrade

Running the upgrade may take up to 30 minuets depending on which version of the Raspberry Pi you have.

# Download the sample code

To download the Atlas Scientific<sup>™</sup> sample code,run the following commands within the Raspberry Pi's terminal.

cd ~

git clone https://github.com/AtlasScientific/Raspberry-Pi-sample-code.git

Once the sample code has finished downloading, you will be almost ready to begin using the Atlas Scientific™ EZO™ class circuits with your updated Raspberry Pi.

There are three different ways to interact with the Atlas Scientific™ EZO™ class circuits with your Raspberry Pi.

- USB Mode
- I<sup>2</sup>C Mode
- UART Mode

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## Sample code compatibility chart



The Raspberry Pi Foundation has failed to make a working UART on the Pi 3. Because of this no UART connected devices can run on a Raspberry Pi 3.

# **USB** Mode





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#### **USB** Mode

USB mode will let you communicate through the Raspberry Pi's USB port to any FTDI based USB device. This includes all USB based Atlas Scientific™ devices.

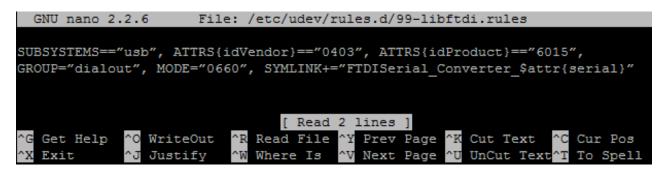
First, we need to install the libftdi package.

sudo apt-get install libftdi-dev

Next, we need to install the pylibftdi python package.

We need to create a udev rule file by entering the following command in terminal.

sudo nano /etc/udev/rules.d/99-libftdi.rules



Replace the current rule with following revised rule below.

SUBSYSTEMS=="usb", ATTRS{idVendor}=="0403", ATTRS{idProduct}=="6015", GROUP="dialout", MODE="0660", SYMLINK+="FTDISerial\_Converter\_\$attr{serial}"

Press "CTRL+X", then "Y" and hit Enter to save & exit.



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Once the updated udev rule has been saved, a restart is required in order to apply changes to the rule.

sudo service udev restart

Lastly, we need to modify the FTDI python driver.

Since Atlas Scientific<sup>™</sup> FTDI devices use *USB PID (0x6015)*, we need to tweak the original FTDI driver, by entering the following command in terminal.

sudo nano /usr/local/lib/python2.7/dist-packages/pylibftdi/driver.py

Move down to the line 70 and add **0x6015** at the end of line.

```
GNU nano 2.2.6 File: ...python2.7/dist-packages/pylibftdi/driver.py
FLUSH OUTPUT = 3
 Device Modes
SITMODE RESET = 0 \times 00
BITMODE BITBANG = 0x01
 Opening / searching for a device uses this list of IDs to search
    default. These can be extended directly after import if required.
FTDI VENDOR ID = 0 \times 0403
USB VID LIST = [FTDI VENDOR ID]
SB PID LIST = [0x6001, 0x6010, 0x6011, 0x6014] \leftarrow line 70
FTDI ERROR DEVICE NOT FOUND = -3
class Driver(object):
   This is where it all happens...
   We load the libftdi library, and use it.
                             Read File ^Y Prev Page ^K Cut Text
  Get Help
```

Original line

 $USB_PID_LIST = [0x6001, 0x6010, 0x6011, 0x6014]$ 

Modified line

USB\_PID\_LIST = [0x6001, 0x6010, 0x6011, 0x6014, 0x6015]

Press "CTRL+X", then "Y" and hit Enter to save & exit.



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Your Atlas Scientific™ EZO™ class circuits are almost ready to work with your Raspberry Pi, we just have to run a simple test first.

Connect your FTDI based USB device and run the following command in the terminal.

sudo python -m pylibftdi.examples.list\_devices

The program will report information about each connected device. You will get result like this:

FTDI:FT230X Basic UART:DA00TN6Q

Each FTDI adaptor has its own unique serial number.

In the result above, serial number is DA00TN6Q

#### Using pylibftdi module for Atlas Scientific™ EZO™ class circuits

Run the following commands in terminal.

cd ~/Raspberry-Pi-sample-code

sudo python ftdi.py

The program will present a list of available FTDI devies. Enter the index of the device you wish to use, and you will now be able to control an Atlas Scientific<sup> $\top$ </sup> EZO $^{\top}$  class circuit via the USB port.

```
Discovered FTDI serial numbers:

Index: 0 Serial: DA000IQH

Index: 1 Serial: DA000JSH

Please select a device index:
```

For more details on the commands and responses, please refer to the datasheets of each Atlas Scientific™ EZO™ class circuit in use.

# I<sup>2</sup>C Mode



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#### I<sup>2</sup>C Mode

Before we can start using the Atlas Scientific<sup>TM</sup> EZO<sup>TM</sup> class circuits with your Raspberry Pi, we have to install and enable  $I^2C$  bus on the Raspberry Pi.

Run the following commands in terminal.

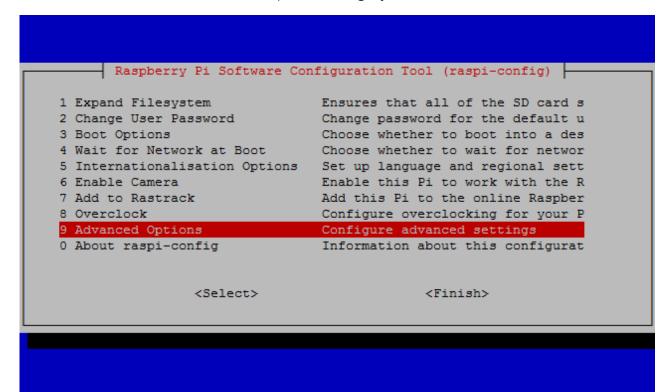
sudo apt-get install python-smbus

sudo apt-get install i2c-tools

Once those have finished installing, we need to head back to the Raspberry Pi config.

sudo raspi-config

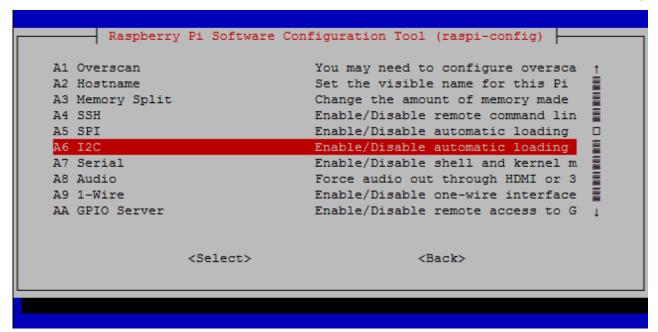
You should see a blue screen with options in a grey box in the center, like so



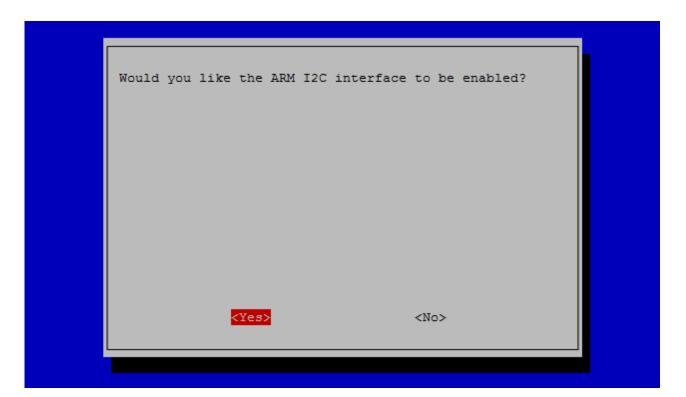
Choose "Advanced Options"



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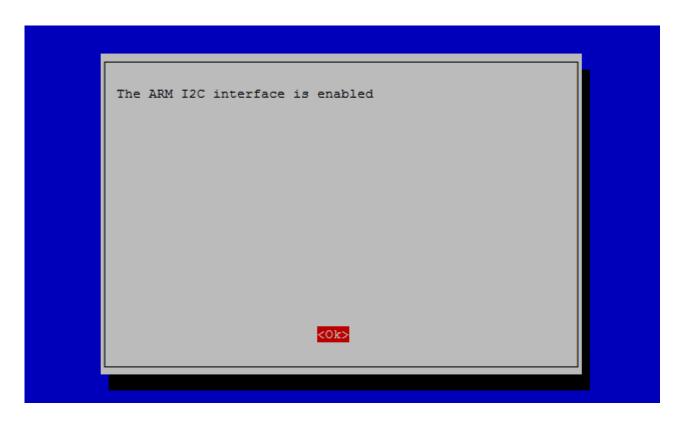
Choose "I2C"



Choose "YES"



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Hit "OK" and reboot the Raspberry Pi.

sudo reboot



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Your Atlas Scientific<sup>m</sup> EZO<sup>m</sup> class circuits are almost ready to work with your Raspberry Pi, we just have to run a simple test first.

Connect your EZO™ class circuit, and run the following command in terminal.

sudo i2cdetect -y 1

	0	1	2	3	4	5	6	7	8	9	a	b	С	d	e	f
00:																
10:																
20:																
30:																
40:																
50:																
60:				63												
70:																

I2C address list							
Device	Decimal	Hex					
рН	99	0x63					
ORP	98	0x62					
DO	97	0x61					
EC	100	0x64					
RTD	102	0x66					
PMP	103	0x67					

The program will report information about each connected  $I^2C$  device. This shows that an  $I^2C$  address (0x63) is in use.

Run the following commands in terminal.

cd ~/Raspberry-Pi-sample-code

sudo python i2c.py

#### Each Atlas Scientific™ device has a different default I<sup>2</sup>C address.

To see a list of connected I<sup>2</sup>C devices from the program, use the command

List\_addr

The last step is to tell the Raspberry Pi which circuit you want to talk to. For example, if you give the command (address, 99), the Raspberry Pi will now send all command to the pH circuit. Only after the Raspberry Pi knows which EZO™ circuit to communicate with, can you send EZO commands. Such as, "I", "status", "R", etc...

#### ADDRESS,99

This will now tell the Raspberry Pi to communicate with the EZO™ pH circuit 99 (0x63)

For more details on the commands, responses and I<sup>2</sup>C addresses, please refer to the datasheets of each Atlas Scientific<sup>™</sup> EZO<sup>™</sup> class circuit in use.

# **UART Mode**



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#### **UART Mode**

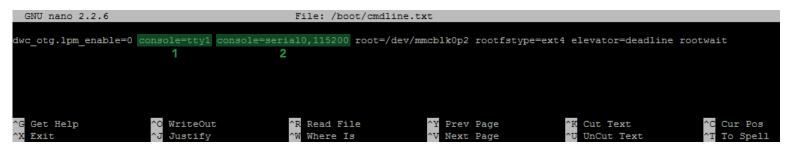
The Raspberry Pi Foundation has failed to make a working UART on the Pi 3. Because of this no UART connected devices can run on a Raspberry Pi 3 GPIO pins.

Before we can start using the Atlas Scientific™ EZO™ class circuits with your Raspberry Pi, we have to make a small tweak to the boot command line.

Run the following command line.

sudo nano /boot/cmdline.txt

You should see something that looks a lot like this:



You might see two seperate commands listed for the "console".

console=tty1 console=serial0,115200

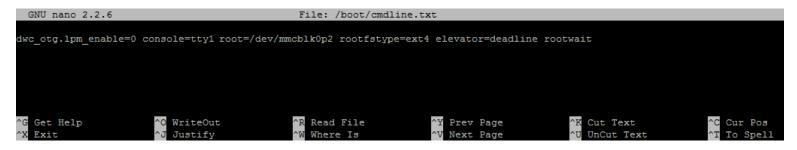
1

This can cause a conflict in the serial port.

To correct this issue, *delete* the command:

console=serial0,115200

The command line should now look like this:



Press "CTRL+X", then "Y" and hit Enter to save & exit.

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We need to ensure PySerial is installed for Python

sudo pip install pyserial

Run the following commands in terminal.

cd ~/Raspberry-Pi-sample-code

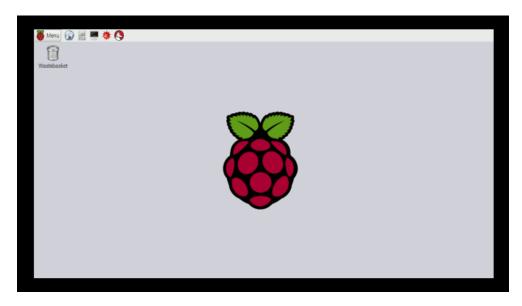
sudo python uart.py



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## \*Side note\*

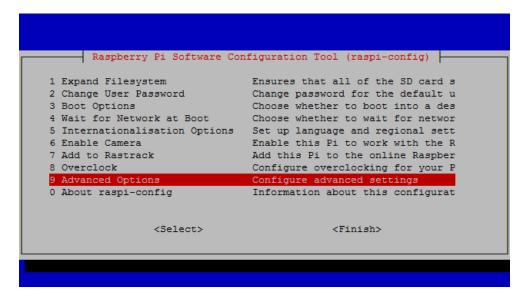
Does your Raspberry Pi have an annoying black border around the OS?



If so, here is how to remove it.

Run the following command line within the Raspberry Pi's terminal.

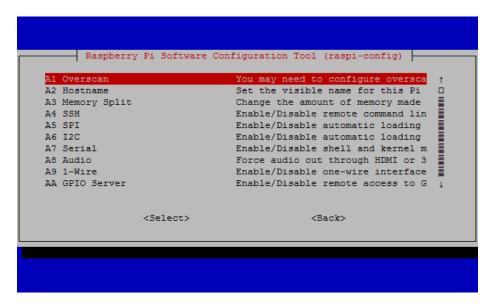
#### sudo raspi-config



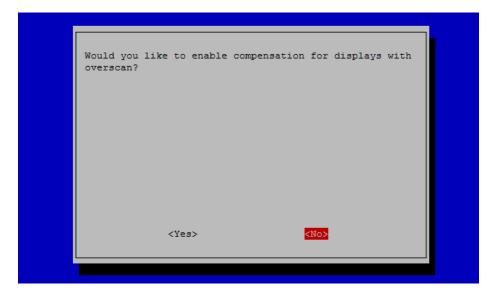
Choose the option "Advanced Options"



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Then, choose the option "A1 Overscan"



It will ask if you would like to enable compensation for displays with overscan? say "NO"

The black border will know be gone. Enjoy!

