Machine Learning Notes

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Chapter 3. Generalisation Bounds for Classification

3.2 Generalisation Bound for a Single Hypothesis

We start with the simplest case, where \mathcal{H} consists of a single prediction rule h. We are interested in the quality of h, measured by L(h), but all we can measure is $\hat{L}(h,S)$. What can we say about L(h) based on $\hat{L}(h,S)$? Note that the samples $(X_i,Y_i)\in S$ come from the same distribution as any future samples (X,Y) we will observe. Therefore, $\ell(h(X_i),Y_i)$ has the same distribution as $\ell(h(X),Y)$ for any future sample (X,Y). Let $Z_i=\ell(h(X_i),Y_i)$ be the loss of h on (X_i,Y_i) . Then $\hat{L}(h,S)=\frac{1}{n}\sum_{i=1}^n Z_i$ is an average of n i.i.d. random variables with $\mathbf{E}[Z_i]=\mathbf{E}[\ell(h(X),Y)]=L(h)$. The distance between $\hat{L}(h,S)$ and L(h) can thus be bounded by application of Hoeffding's inequality.

NB. Note that the samples $(X_i, Y_i) \in S$ come from the same distribution as any future samples (X, Y) we will observe. Let $Z_i \stackrel{\text{def}}{=} \ell(h(X_i), Y_i)$, then we have

$$\hat{L}(h,S) = \frac{1}{n} \sum_{i=1}^{n} Z_i = \frac{1}{n} \sum_{i=1}^{n} \ell(h(X_i), Y_i) , \qquad (3.6a)$$

$$L(h) = \mathbf{E}[Z_i] = \mathbf{E}[\ell(h(X_i), Y_i)] = \mathbf{E}\left[\ell(h(X_i), Y_i)\right] = \mathbf{E}\left[\frac{1}{n}\sum_{i=1}^n \ell(h(X_i), Y_i)\right] = \frac{1}{n}\sum_{i=1}^n \mathbf{E}[\ell(h(X_i), Y_i)].$$
(3.6b)

Theorem 3.1. Assume that ℓ is bounded in the [0,1] interval (i.e., $\ell(Y',Y) \in [0,1]$ for all Y',Y), then for a single h and any $\delta \in (0,1)$ we have:

$$\Pr\left(L(h) \geqslant \hat{L}(h,S) + \sqrt{\frac{\ln\frac{1}{\delta}}{2n}}\right) \leqslant \delta, \tag{3.7}$$

and

$$\Pr\left(\left|L(h) - \hat{L}(h,S)\right| \geqslant \sqrt{\frac{\ln\frac{2}{\delta}}{2n}}\right) \leqslant \delta. \tag{3.8}$$

Proof. For (3.7) take $\varepsilon = \sqrt{\ln(\frac{1}{\delta})/(2n)}$ in (2.16) and rearrange the terms. Eq. (3.8) follows in a similar way from the two-sided Hoeffding's inequality. Note that in (3.7) we have $1/\delta$ and in (3.8) we have $2/\delta$.

NB. According to Section 2.3,28 we know that

$$\Pr\left(\hat{L}(h,S) - L(h) \geqslant \varepsilon\right) \leqslant \exp(-2n\varepsilon^2),\tag{3.15a}$$

$$\Pr\left(\hat{L}(h,S) - L(h) \leqslant -\varepsilon\right) = \Pr\left(L(h) - \hat{L}(h,S) \geqslant \varepsilon\right) \leqslant \exp(-2n\varepsilon^2), \tag{3.15b}$$

$$\Pr(|\hat{L}(h,S) - L(h)| \ge \varepsilon) \le 2 \exp(-2n\varepsilon^2).$$
 (3.15c)

²⁸We relist the Hoeffding's inequalities here.

Let $\delta \stackrel{\text{def}}{=} e^{-2n\varepsilon^2} \in (0,1)$, then we have $n\varepsilon^2 = -\frac{1}{2} \ln \delta = \frac{1}{2} \ln \frac{1}{\delta}$, and then

$$\Pr\left(\hat{L}(h,S) - L(h) \geqslant \sqrt{\frac{1}{2n} \ln \frac{1}{\delta}}\right) \leqslant \delta, \tag{3.16a}$$

$$\Pr\left(L(h) - \hat{L}(h,S) \geqslant \sqrt{\frac{1}{2n} \ln \frac{1}{\delta}}\right) \leqslant \delta, \tag{3.16b}$$

therefore, we can get (3.7) according to (3.16b).

Let $\delta \stackrel{\text{def}}{=} 2e^{-2n\varepsilon^2} \in (0,2)$, then we have $n\varepsilon^2 = -\frac{1}{2} \ln \frac{\delta}{2} = \frac{1}{2} \ln \frac{2}{\delta}$, and then

$$\Pr\left(\left|L(h) - \hat{L}(h,S)\right| \geqslant \sqrt{\frac{1}{2n}\ln\frac{2}{\delta}}\right) \leqslant \delta, \tag{3.17}$$

that is, (3.8).

Question: There is a bit problem here though. Why the following content keep saying $\delta \in (0,1)$ for the two-sided inequality? Oh I was wrong, thay are talking about the one-sided inequality.

There is an alternative way to read Eq. (3.7): with probability at least $(1 - \delta)$ we have

$$L(h) \leqslant \hat{L}(h,S) + \sqrt{\frac{\ln\frac{1}{\delta}}{2n}}.$$
(3.18)

We remind the reader that the above inequality should actually be interpreted as

$$\hat{L}(h,S) \geqslant L(h) - \sqrt{\frac{\ln\frac{1}{\delta}}{2n}},\tag{3.19}$$

and it means that with probability at least $(1 - \delta)$ the empirical loss $\hat{L}(h, S)$ does not underestimate the expected loss L(h) by more than $\sqrt{\ln(1/\delta)/(2n)}$. However, it is customary to write

Theorem (2.3 Hoeffding's inequality). Let $X_1, ..., X_n$ be independent real-valued random variables, such that for each $i \in \{1, ..., n\}$ there exist $a_i \leq b_i$, such that $X_i \in [a_i, b_i]$. Then for every $\varepsilon > 0$,

$$\Pr\left(\sum_{i=1}^{n} X_i - \mathbb{E}\left[\sum_{i=1}^{n} X_i\right] \geqslant \varepsilon\right) \leqslant \exp\left(-2\varepsilon^2 / \sum_{i=1}^{n} (b_i - a_i)^2\right),\tag{3.9}$$

and

$$\Pr\left(\sum_{i=1}^{n} X_{i} - \mathbb{E}\left[\sum_{i=1}^{n} X_{i}\right] \leqslant -\varepsilon\right) \leqslant \exp\left(-2\varepsilon^{2} / \sum_{i=1}^{n} (b_{i} - a_{i})^{2}\right), \tag{3.10}$$

aka "one-sided Hoeffding's inequalities".

Remark (Corollary 2.4). *Under the assumption of Theorem 2.3, taking a union bound of the events in those two:*

$$\Pr\left(\left|\sum_{i=1}^{n} X_{i} - \mathbb{E}\left[\sum_{i=1}^{n} X_{i}\right]\right| \geqslant \varepsilon\right) \leqslant 2\exp\left(-2\varepsilon^{2}/\sum_{i=1}^{n} (b_{i} - a_{i})^{2}\right),\tag{3.11}$$

aka "two-sided Hoeffding's inequality".

Remark (Corollary 2.5). Let $X_1, ..., X_n$ be independent random variables, such that $X_i \in [0,1]$ and $\mathbf{E}[X_i] = \mu$ for all i, then for every $\varepsilon > 0$,

$$\Pr\left(\frac{1}{n}\sum_{i=1}^{n}X_{i}-\mu\geqslant\varepsilon\right)\leqslant\exp\left(-2n\varepsilon^{2}\right),\tag{3.12}$$

and

$$\Pr\left(\mu - \frac{1}{n}\sum_{i=1}^{n} X_{i} \geqslant \varepsilon\right) \leqslant \exp\left(-2n\varepsilon^{2}\right). \tag{3.13}$$

Remark (Lemma 2.6, Hoeffding's lemma). Let X be a random variable, such that $X \in [a, b]$. Then for any $\lambda \in \mathbb{R}$,

$$\mathbf{E}[e^{\lambda X}] \leqslant \exp\left(\lambda \mathbf{E}[X] + \lambda^2 (b-a)^2 / 8\right). \tag{3.14}$$

The function $f(\lambda) = \mathbf{E}[e^{\lambda X}]$ is known as the moment generating function of X, since generally, $f^{(k)}(0) = \mathbf{E}[X^k]$.

the inequality in the first form (as an upper bound on L(h)) and we follow the tradition (see the discussion at the end of Section 2.3.1).

Theorem 3.1 is analogous to the problem of estimating a bias of a coin based on coin flip outcomes. There is always a small probability that the flip outcomes will not be representative of the coin bias. For example, it may happen that we flip a fair coin 1,000 times (without knowing that it is a fair coin!) and observe "all heads" or some other misleading outcome. And if this happens we are doomed — there is nothing we can do when the sample doesn't represent the reality faithfully. Fortunately for us, this happens with a small probability that decreases exponentially with the sample size n.

Whether we use the one-sided bound (3.7) or the two-sided bound (3.8) depends on the situation. In most cases we are interested in the upper bound on the expected performance of the prediction rule given by (3.7).