

Low-power Wireless ECG Monitoring System for Android Devices

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June 3, 2012

Abstract

Keywords

Pablo Fernández, Rafael de la Hoz and Miguel Márquez authorize Complutense University of Madrid to spread and use this report with academical and non-comercial purposes, provided that its authors shall be explicitly mentioned.

June 3, 2012

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Acknowledgements

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Chapter 1

Introduction

1.1 Project description

This project exposes the research conducted for the development of an USB 802.15.4 receiver device for Android based systems employed in a fully functional electrocardiogram monitoring system encompassed in the field of in-home healthcare, as well as the development process involved in the realization of this whole system.

Electrocardiogram (ECG) monitoring consists on capture and interpretation of the activity of the heart [cit.needed] during a period of time, and continuous, remote ECG monitoring has become one of the main applications of wireless body sensor networks. Great interest has arisen recently among industrial and academic research parties in production of low-power, ambulatory ECG monitoring systems.

In order to maximize portability, such systems have recently started to employ the widely available smartphone devices as frontends, reducing the amount of extra devices carried by the user to just the ECG capturing node. In 2011 the École Polytechnique Fédérale de Lausanne presented a real-time personal ECG monitoring system which displayed data in an iPhone via Bluetooth.

Taking the aforementioned project as the base, this project seeks taking the inherently good low cost and low power aspects of that to the next level by the employment of a less energy requiring wireless personal area network protocol, namely IEEE 802.15.4, and the more accessible Android based platforms.

The system provides the user with a visual representation of his/her ECG wave highlighting relevant points of this in order to simplify its comprehension. Information about heart-beat-rate is also displayed. All this data is stored in realtime in a transparent to the user manner for later visualization with emphasis put in easy handling of the generated files.

This functionality is provided by the three devices that are part of the system: the ECG delineation node, the USB 802.15.4 receiver and the Android device through the front-end application. The ECG delineation node is connected to the body sensor network and is responsible for capturing and analyzing the electrocardiogram wave, as well as encoding and wirelessly sending the data. The USB 802.15.4 receiver is plugged to the Android system and manages data reception following the aforementioned protocol. Finally the Android based application is the real-time data decoder and acts as the frontend to the user, managing connections and storing and displaying received data.

Development of the Android application, realization of the USB 802.15.4 receiver device, employment of an already-existant ECG delineation node and successful intercommunication between all these elements are the project goals.

In order to do that, we have been using a system already developed which was responsible of monitoring the patient and sending the resulting data wirelessly as well. These devices were able to send their information through Bluetooth or using IEEE 802.15.4 standard, which is specially relevant for this project, as we will see later on in this document.

Once the results of ECG analysis are emitted, it will be necessary to properly receive and parse them within the displaying device and, finally, show them so they will be human-readable.

This displaying device acts as the system's user interface, and it provides functionality to visualize received data, change visualization parameters, and save and load already-parsed received data also. Thus, considering a monitoring device is sending data, a typical use of the system is: an user executes the developed application on the displaying device, then selects the monitoring device which ECG *he/she wants to analyze and the application starts to show the data as it is receiving it. Meanwhile, that information is being logged to a file at the same time it is being displayed, storing it so as to allow its later, further analysis.

In spite of the fact that the displaying application is needed because it allows

the development of the rest of the project, it is not the main goal since key feature is represented by the 802.15.4 communication. In other words, most efforts are focused in connecting and communicating emitter and receiver devices, considering the development of the application as way to complete the system with an useful purpose.

Regarding the communications, it is also worth of remark that our target displaying device, Xoom tablet from Motorola, incorporates the standard Bluetooth module, yet it is not equipped with a ZigBee one. Due to this lack, which is more than usual among portable devices nowadays, the making of a compatible receiver accessory centers a fairly important part of the project.

In short, the main objective for this project, seen as a whole system, consists of visually and wirelessly displaying and managing data obtained from portable, personal ECG-monitoring emitter devices on an Android tablet, paying special attention to make possible the communication with Android through 802.15.4. In order that the system can operate that way, the following issues will have to be resolved:

1. *Communication with 802.15.4 emitters*

Android devices are usually equipped with Bluetooth radio modules, so it is likely that they count with working Bluetooth communications out of the box, which is the case of the target device, a Motorola Xoom tablet. However, 802.15.4-compliant communication is not natively supported by any existing Android device –not even any other widely known portable computing device–, so it will be needed the development of an alternative method for achieving this goal. As the next item states, the solution to this problem consists of building up a receiver accessory capable of connecting to the tablet through USB interface. This particular task centers most of the efforts dedicated to the project, since it is both crucial for the proper operation of the system and unprecedented in its field, as it will be detailed later.

2. *Android accessory development*

As it was stated before, Android-powered devices are usually equipped with Bluetooth radio modules, yet they lack the capability to communicate with devices which implements other standards. In order to achieve this feature for this sort of device, development of an specifically designed accessory is both a required and mandatory task.

The aforementioned support Android OS provides for USB device and host modes would allow us to obtain data processed by the accessory

through an available interface for almost every Android device. In particular, USB host mode would be required so that the Android device were to be able to power the accessory, hence the restriction of using devices running Android version 3.1 or newer.

For this goal an USB-capable board equipped with an MSP430 microcontroller was chosen for acting as the receiver accessory. More specifically, this microcontroller would be running FreeRTOS (operating system oriented to tasks with real-time needs), which would be accordingly modified for dealing with the USB interface and 802.15.4 communication.

It is also noteworthy that the usage of a prototyping board and a potential miniaturisation of the previously described board were included into the scope of this objective as well. Besides, full description and more details about this development and 802.15.4 communication can be found at chapter 2, Hardware and communications.

3. *Android ECG application*

Finally, an Android application acts as the system's frontend. Its most relevant requirements were determined by the existing EPFL iOS application, with subtle modifications due to the different platform as well as the inclusion of an extra accessory.

The data the application displays, in the shape of ECG waves, may be retrieved from a Bluetooth or 802.15.4 streaming node or a local log file. These logs are written by the application itself as it receives an incoming data transmission, so that it can replay them later –original iOS application lacked this feature–.

Moreover, view controls shall also be offered for the user to modify display density, and move forwards and backwards if a log is being displayed.

More information about the application, such as requirements and other details, can be found at chapter 3, Software Development.

1.2 Project driver

The main motivation for developing this project was the fact that it meant the gathering of almost every branch of this career. From its very beginning, this work involved both software and hardware development, researching on unknown tools and platforms as well as high and low-level design and pro-

gramming.

Besides, if successful, it would be likely it could become a real product and be useful both in a professional and particular scope, which added a practical end for the work to be carried out. Something like this could be made thanks to the special features –such as less power consumption and required investment– 802.15.4-compliant technologies provide which wider spread ones lack (Bluetooth, for instance). It is also expected that technologies based on IEEE 802.15.4 specification like ZigBee will increase their importance in the medium term due to their potential applications in domotics (home automation).

In addition, not only developing applications for portable devices but accessories are mainstream nowadays; thus, getting in touch with these activities could provide us with extra experience at leading edge practices, what would broaden our areas of expertise and, consequently, increment our chances to access the labour market.

However, certain areas of the project would mean working on unprecedented techniques –as it will be detailed later on within this section– and dealing with tools which were unknown for us at that moment. Hitches like these could lead to the unfulfillment of the project, yet they could also add extra value to it if they were overcome.

1.3 State of the art

- *EPFL Project*

As a precedent of the present project, the École Polytechnique Fédérale de Lausanne (EPFL) – represented by its Embedded Systems Laboratory (ESL) –, along with the Complutense University of Madrid (UCM), developed a wireless ECG monitoring system [1], similar to the one has been built up during this project.

Just as ours, this system also used ShimmerTM as monitoring, transmitter platform; and the obtained data could be displayed in portable computing devices. Nonetheless, the list of similarities ends there. The application responsible for rendering the ECG waves was meant to be used over iOS devices, particularly iPhone. This fact led to several additional restrictions, such as mandatory usage of Bluetooth as wireless transmission method as well as the need of “jailbreaking” the device itself. This process allows the user to gain root access to the OS, and it was needed in order that an explicitly installed Bluetooth stack allowed the device to receive the emitted data properly. However, according to

the manufacturer, jailbreaking the device nulls its warranty. Therefore, the employment of Android in our project is partially motivated by this sort of limitations other platforms usually impose.

Our project collaborates with EPFL, from whom we have received feedback as well as hardware and software requirements. In fact, the aforementioned iOS application *settled most of the requirements for the Android one in our project, although there were added some extra ones –such as making logs from received data so they can be read again later–.

- *IEEE 802.15.4*

This standard describes the physical and Media Access Control (MAC) layers for low-rate wireless personal area networks. It is intended to be implemented into embedded devices, so as to build up short-range networks –10 meters, typically– with narrow bandwidth, up to 250kbps, among other possibilities with lower transfer rates.

802.15.4 is specially suitable for this kind of project due to its low power consumption. In fact, ZigBee, which uses this standard as its low-level layer, presents a series of advantages over Bluetooth, underlying technology of the previously mentioned EPFL project:

- **Lower power consumption:** without going into detail, it can be stated that Bluetooth requires more power than ZigBee does. For example, Bluetooth is constantly emitting information, consequently consuming power, while 802.15.4 allows to enable the radio only when it is needed. These statements are properly justified and explained at chapter 2
- **Bandwidth:** Bluetooth offers much wider bandwidth, up to 3Mbps, meanwhile ZigBee only offers up to 250kbps. This, however, is not a relevant disadvantage because our needs are not so high.
- **Host number:** ZigBee allows to build networks with up to 65535 hosts, subnetworks with 255 hosts. On the other hand, Bluetooth can only support as much as 8 hosts within a network.

ZigBee, though, is not employed as a whole within this project, but 802.15.4 standard as its basis. Nevertheless, its advantages over Bluetooth remains the same, with the additional one that it does not compromise soft real-time developments as the complete stack does.

- *Android Accessory Development*

As of May, 2011, there were no easy nor official methods to develop accessories capable of communicating with Android running devices. At that certain time, the release of the Android Open Accessory Development Kit (also known as “ADK”) was announced in San Francisco, within the context of Google I/O, developers conference arranged by Google.

ADK consists of an USB microcontroller board based on Arduino (Arduino Mega2560 to be precise) and a series of software libraries which add specific functionalities and support for other hardware add-ons, typically known as *shields*, that equip the accessory with sensors or interactive elements which broaden its capabilities. Shields are plugged to the board through its numerous input/output pins, which also allow the connection of personally crafted hardware additions –allowing that way to create tailored behaviours, following the Arduino’s “Do It Yourself” (DIY) spirit.

With the release of that kit, Android project opened itself to the development of all kind of new accessories which would add potential and functionalities it lacked.

As well as this kit, the following release of Android 3.1 API version completed the accessory ecosystem with the inclusion of directly supported host and device USB modes –this support was also backported to Android v2.3.4; only the device mode, though–. By doing so, Google completely cleared the way for the development of Android-compatible accessories, which was previously reduced to the underlying, quite complete but not enough, Linux kernel driver support.

- *ZigBee dongles*

In spite of the fact that there were available devices which implemented the complete ZigBee stack at the time of the start of this project, they were only designed for being connected to personal computers, some models with OS restrictions as well.

Moreover, even if they were to be compatible with our target device, the only available dongles fully implemented the ZigBee stack, which also made them unsuitable for this project due to the relatively high latency that fact imposed –as it can be read at chapter 2, Hardware and communications, soft-realtime needs required the usage of the 802.15.4 MAC layer on its own–.

- *Communication with Android using ZigBee*

One year ago, around mid-2011, there were very few projects which were working on this sort of communication, between Android and 802.15.4 radio-equipped devices. Concretely, the only project of this kind we were aware of was one from Texas Instruments, which was stated to be pioneer in this field (as it can be seen in [2]). Despite that, several differences stands between this project and ours. For instance:

- **USB communication:** Texas Instruments developed its own Android driver, namely “virtual COM port”, so they could directly connect their ZigBee Network Processor (ZNP) to the Android device through USB. Instead, Android USB host mode is used in this project in order to establish the connection between the receiver and the device. Because of using this method, USB communication between MSP430 microcontroller and the Android device has to be specifically implemented and tuned.
- **Android platform:** TI’s project employed Android 2.2, while we are using version 3.1 in ours, due to the aforementioned need of USB host mode support this API provides. In addition, received data is used by our Android application, while TI employed ZigBee communication for less specific ends, such as controlling other devices like PCs, lamps or obtaining data from certain sensors.
- **Wireless communication:** in order that the ECG delineation could be done in real-time (namely soft real-time, as it will be explained later), this project does not use the complete ZigBee stack, but its 802.15.4 MAC layer. This restriction requires the radio –in particular, TI CC2420 radio module– has to be programmed specifically. Meanwhile, Texas Instruments made use of its TI CC2530 system on chip (SoC), which fully implemented ZigBee stack.
- **USB dongle:** as it was mentioned before, TI directly plugged their ZNP to an OMAP4 Blaze thanks to their driver. However, so that the same result could be obtained, we had to connect the radio, CC2420 module, to the MSP430 board –*nombre de la placa–, which was equipped with a USB interface. Furthermore, miniaturisation of this board was designed afterwards to make it an usable dongle.

In other words, Texas Instruments’ project was actually able to build up working communications of this kind by the time ours was starting; all the same, special requirements like real time needs entail additional challenges for this project to overcome.

1.4 Document overview

Over the following pages, this document will present the details about the project it refers to. Beginning with a deep description and analysis of the Android application’s design and implementation, which can be found at the “Software Development” chapter; next, a thorough explanation about the employed hardware and the work it required; and, finally, an exposition of the obtained results, potential expansions and findings.

Chapter 2

Hardware and communications

2.1 Overview

The hardware research and development part of the project objective is covering a main need: production of an external device that enables communication between an Android system and a *shimmer through 802.15.4. Such a device should be a portable and low-powered device that can be plugged via the widely used USB On-The-Go (USB OTG) to a host Android system, acting the device as a slave. It has to be small sized because of the target application environment: a particular who requires constant, in-home, ambulatory monitorization. In that scenario unobtrusive operation is a main need, and usual life style activity modification is to be minimized. It has to be low-powered, because were the power cost of application higher than that of the Bluetooth technology, a main advantage of 802.15.4 is lost. The ability to communicate through USB is required because, at the time, its is the most low battery consuming method to interact with Android powered platforms for any external device[quote here wlan and bt costs]. And finally it should be able to act as the slave in the USB connection to avoid the need of an extra power source for the device that would increase the cost and size of the product.

In order to achieve such ambitious goals, and being aware of the sustancial ammount of research involved in this part of the project, the decision was made to adopt a milestone driven development which simplified scheduling and helped focusing on specific tasks while maintaining a global view of the evolution and the objectives of the project.

Before diving any further into the development a section describing technolo-

gies involved in the research process is presented, as such information will be key to the understanding of the rest of the chapter and will be throughoutly referenced during the exposition.

2.2 Researched Tecnologies

This part of the project involves a lot of terms and references a number of technologies and concepts which are important to be acquainted with in order to achieve a full understanding of the current chapter. These explanations won't be presented interlaced with the rest of the sections due to the unmanageable size they would acquire leading to a loss of focus which can only act against full comprehension of the exposed content.

2.2.1 Arduino

2.2.2 MSP430

2.2.3 802.15.4

2.2.4 FreeRTOS

2.2.5 USB device & USB host

2.3 Description

The hardware related investigation is the main section of the research part of the project. Not that there wasn't any research involved in other areas, but some critical elements of this part had never been researched before. At the beginning of the project specific objectives were established and main milestones elected, but absolutely no clue or direction for most of those milestones was available. Moreover, in some cases the feasibility of the proposed goals was unknown. Specifically the achievement of the very important objective of USB communication between an [TI's] MSP430 and an Android powered device assuming the latter the role of master and acting the former as a slave was something not done before and therefore no information was available even in the Texas Instrument support site.

This whole development and research poses quite an interesting challenge as it involves working nearly at every abstraction layer present on device development, ranging from schematic capture and PCB design to operating

system related development. Extend this paragraph?

Scrap zone.

As we explain in the subsection 2.2.5 **Como se ponen enlaces?** the host rol is assumed by who manage the connection, and device rol by the one who just use this connection to send and recive data and recive energy, for us, this minds a simpler programming in our MSP430 device, which code is harder to develop than android code.

The interaction between MSP430 and android was the most dangerous risk of this develop because there aren't information of any kind because it's not researched. USB is quite not as simple as everybody believes, there are many different protocols that works with USB, and each protocol can be implemented in very different ways, this implies a huge investigation process to find if any of them can be used by us. The final way to communicate both devices will be extendedly explained en section 3.4.2.

We decided to use 802.15.4 instead of Bluetooth for many reasons, like lower consums or aviability to create networks to cover big surfaces. But the more important one is that **shimmer* have a very small battery that, with blue-tooth just lasts 5 or 6 hours, but with 802.15.4 it colud lasts more than a week. Talking about the delineator device that have to be carried by the patient, the difference between charge the device 3 or 4 times every day and charge it less than once every week is more than significant.

Parrafo para introducir los hitos en el que no tengo ni idea que decir, viva!

2.4 Milestones

This section is presented in chronological order and with milestones view due to its research content, and also because of this was the planification that we follow, as we have no idea of what troubles can we found or how far we can ¿overtake? we have to plan the following milestones and its ¿contents?

2.4.1 Arduino for Android USB Device Comunication

This first milestone's objectives are:

- Acquire a suitable Android device prototyping environment,

- manage correct communication between Android and a prototype device, and
- develop an application emulating desired behaviour.

When we decide to develop a usb device the first step is look for a device tha provide the USB host libraries to connect to android, because the USB host device is which implements most of comunication, thanks to this we can focus our efforts in just try a comunication with android with not so much worries, the device selected to this end was the goole ADK, that is based on arduino(link).ADK is a device developed by google to help android developers to make his first prototypes of USB connected devices. The google ADK is an Arduino with all the facilities that a developer can expect such as libraries, some shields, examples and a good documentation, in our case we are specially interested in the USB host communication libraries.

When we reciebe our google ADK(link to an image?) we investigate documentacion and we start to develop a small arduino aplicacion based on the expamples, paraelly we develop the android USB device part(link) that we be needed to test this part of communication. The initial develop, just to make the first test was a little long, because even been the main parts of the implementation os USB communication made we need to learn how to use it. Our first attempts was no very productives because arduino was a new develop platform but especially because this was our first try with android USB communication.

Several days later we achieve to Andorid and ADK view each other, but in our definitive test we discover that the communication was not correct because what anyones send was not recibed equally by the other one. But finally we discover what was going wrong and fix it to view how our first milestone has been ahieved.

Once finished we discover the huge importance of plan this first milestone, that will not be used in then final device, but it was very usefull to train the team about USB communication in android. Conidering than this milestone was not as easy as we expect, if we had start the research in the second milestone which investigation is actualy used in the device, we probably found a lot of troubles that wasn't trully related with the investigation and it would be higly sealed.

2.4.2 MSP430 for Android USB Host Communication

This milestone's objectives are:

- Supply MSP430 with USB protocol application functionality,
- research Android USB protocol related functionality,
- get Android system to recognize MSP430 as a plugged device, and
- manage communication between Android and MSP430 via USB.

Unlike the arduino's part where we know what we have to use and how we will use it, now we found that we just have an Texas Instruments(TI) API to communicate the MSP430 with windows and our goal. Both MSP430 microcontroller and MSP430 board was new devices because all the existing ones have no USB port, the microcontroller is a MSP430 6638 and the board is a TS430PZ100USB(link to the MSP430 section).

This API contains any simple applications for windows, to communicate by certain protocols with external devices or enumeration tools; an extense documentation about the API and about the USB characteristics of its devices; and a huge suite of examples that implements a lot of USB protocols to communicate the MSP430 whith windows such as Communications Device Class (CDC), Personal Healthcare Device Class (PHDC), Human Interface Device (HID) in traditional and datatype implementations, Mass Storage Class (MSC) and combinations of any of them. At this point we have an immense amount of information and we don't really know what can be usefull for us.

Initially in order to test the TI API we check some of the multiple examples, in our case was the CDC examples that be usefull to learn about basic concepts of what we try to do. Also we try to read part of the generic(not dependant of the MSP430 device nor USB protocol)documentation that TI provides. And it didn't start too good, the first test with a example provide in the API didn't work in windows, its target SO.

After a good time of investigation we found that it can't initialize a certain clock, this clock don't seems to be in the board and we there are not much references about it. Finally we found a little paragraph in one API document that metion the chance of a USB needed clock was not included in any kind of boards and a recomendation of how should be this clock, when we buy a clock of this features we can check that this was the problems, the TI example finally works.

All this test was carried out in a virtual machine with windows usually running over other windows, but in a casual situation when this virtual machine was running over ubuntu we discover that this examples not only don't work in ubuntu, something that we assume, but in addition ubuntu can't even detect our MSP430, this fact worry us because android is an UNIX based SO just like ubuntu.

When we try to connect our MSP430 running one of this examples mentioned before we observe that, as we expect, android also can't detect it. Initially we think our only possible solution to this important trouble was make or found a unix driver, then we investigate that way.

After much searching we see that there are no drivers for unix made by anyone, the closest driver we find was a MAC driver(that we are not sure that it going to work) and assuming that we will need to do a driver based on it, we consult some qualified personal in this area that said us to forget the idea of a generic UNIX driver and focus in an android driver, but also recommend that keep researching other ways to communicate android and MSP in order to avoid the develop a driver for MSP430 wich can be a very difficult work. This advice and the fact that there are no warranties of the develop of a driver was succesfull, we decide to leave the driver idea and follow investigating. That was a very risky decision because we have spendend a lot of time in this way and we don't know if we will find other idea to achieve this hard milestone.

After a few days of unsuccesfull days of investigation, we find in a forum a small mention in a comment about android actually implements HID protocol. This protocol was also suported by the MSP430 API, and although the information was found in a not very condiable place, we find it enought to put the full team to work in this, ones made the android USB host(link) and others find a HID aplication into the API to load into the MSP430. The second objetive was attemped first, with this we can check that our android device finally detect our MSP430.

That great news helps the android development team, than in this moment becomes the full team, to succesfully imlements the android USB host communication in our aplication in just a weekend. Android USB host communication was higly dependant of what device was in the other side of the communication, thus everybody was needed in this hard and delicated part of the develop to investigate the high cuantity of manuals contained in the API in orther to find and implement all this particularities. Finally we luckily discover that now, our android and MSP430 can also communicate each

other thought our application.

That was with no doubts the harder and more dangerous part of the research, there was a lot of chances to do not achieve our goal and the hard work of all the team was essential. This milestone suppose a very important fact not only in hardware part but in all the project because now, we can more accurately schedule all of the project.

2.4.3 USB in FreeRTOS

This milestone's objectives are:

- Validate the use of FreeRTOS in the new target MSP430
- Validate USB API utilization viability in conjunction with FreeRTOS in MSP430,
- correctly integrate USB API into FreeRTOS, and
- manage USB data sending in FreeRTOS.

Before to start the real objective of this milestone we need to adapt the FreeRTOS main functionalities to the new MSP430, that been a new device was not actually supported by. This mind the creation of a good number of new clases, most of them was exactly equal to their homonimes for the MSP430 5438A but other needs some little modifications.

The next need in the milestone was port as soon as posible the TI USB API to a task-based SO like FreeRTOS without taking too much care about its correction. The introduction into the FreeRTOS was pretty problematic because the size of just the the API was near to the size of the FreeRTOS. Plus, there are a very important risk, USB uses a important number of resources as pines or clock that can be also used by the FreeRTOS to another task, specially risky was the clock because both need a clock, but the selected board have 2 clock spots, and taking care in the port all this themes could resolved and everything works fine.

Once it's done our preoccupation was how to order all this files in a correct way, because our free RTOS was a multiplatform SO that must work in MSP430 5438A, Shimmer, and now, the new MSP430 6638 where take place this develope. In the first port where the multiplatform ability of FreeRTOS was

not a problem we lost this functionality. This separation of tasks help pretty much in focus the first steps in this milestone. This new functionality have to be included just in the supported platform, the MSP430 6638, without affect the other ones as before. Using the preciding generalization needed to coexists Shimmer and MSP430 5438A as a guide this port was not too traumatic.

2.4.4 802.15.4 in FreeRTOS

This milestone's objectives are:

- Validate current implementation of 802.15.4 in FreeRTOS in testing MSP430,
- manage connection to the CC2420 radio module to target MSP430 device,
- port implementation of 802.15.4 to target MSP430 device, and
- prepare such implementation for actual usage.

At the begining of this milestone there are a port of the needed part of the MAC layer of the 802.15.4, that have been tested in just certain conditions, like send of medium lenght packets.

As we are not sure of the right working of MAC layer in our system we decide to test it with the old board and microchip that provides serial port output that is extreamly usefull in the debug of a real-time system like this. This result to not works for a certain problems as although it's able to recibe 802.15.4 packets it's not programmed to it, and the max size packets wasn't received correctly.

Once the right working of the MAC layer is tested, it's time to port it to the new board and microchip, that implies a lot of troubles because the TS430PZ100USB have no conection to a CC2420 radio module. This mean that a full study of the 100 aviable pins to discover which ones are actually unused by both the SO and USB communication. The radio modlule also need a particular kind of pins in some cases that there are no very abundant. With this study and the mapping of pins made(mencionamos a carlos?) board and radio module is sent to be weld.

While the board is available, we addressed the programming the pin mapping for de MSP430F6638 into it's class in the FreeRTOS using as base the

MSP430F5438A pin mapping class. This is a particularly delicate code and was carefully developed, because if just one thing is not perfect the radio simply didn't work at all and the potential error will be hard to discover.

With both, board and coding finished the radio was tested and it didn't even turn on. The answer to this trouble was found in a code example provided by TI for the MSP430F6638, specifically in the *Universal Asynchronous Receiver/Transmitter(USART) initialization code* that resulted in a difference slightly from the old MSP430 USART initialization.

Finally some small changes were done in order to adapt it to our project needs. With this a fully functional MAC layer working on the MSP430F6638 was achieved and just the potential coexistence with the USB was on the air.

2.4.5 802.15.4 & USB coexistence under FreeRTOS

This milestone's objectives are:

- Assess conflict-free coexistence of current implementation of both USB and 802.15.4 modules in MSP430, and
- manage sending data received from 802.15.4 via USB.

With both USB and 802.15.4 communication working separately we need to test that they can work together. There are 2 main risks; hardware, because any pins used in 802.15.4 can be used also in USB and software, because the time between a radio interruption and the next radio interruption could be too short to send the data through USB.

The hardware risk was advised much before the beginning of this milestone, and when we made the pin mapping we kept in mind this risk, thanks to that, this risk was avoided.

However the software risk was initially not avoided because the Shimmer sends data packets too fast and MSP430 can't manage this amount of information to send it through USB and some packets were lost. A little adjustment was necessary, the packets sent were concentrated in the start of the available time slots then, we spaced it, sending the same number of packets but with the same time between packet and packet, filling the whole available time slots.

Now, our system was finally able to send through USB the packets received in radio with no losses. This achievement was very important before developing and testing the final application with several real-time restrictions.

2.4.6 Final application development

- Obtention of a shimmer final application,
- Obtention of an Android application, and
- Test the whole system in its real use.

2.4.7 MSP430 based device design

- Board exhaustive analysis,
- Capture of the schematic, and
- PCB design and routing.

2.4.8 Final Validation and Release Candidate Version Development

2.5 Final Product

Chapter 3

Software Development

3.1 Overview

The development of a software application targeted at Android Operating System for mobile devices is the counter-part to the hardware research part of the project. This application was to substitute the already developed one for iOS devices, adding functionality extracted from feedback obtained from actual medical staff [!][Fran](#) and [EPFL](#)[!]. The software must provide functionality to visualize ECG data from Bluetooth or 802.15.4 sources (the latter obtained via [!][our receiver node](#)[!]) in realtime, as well as to save that data into file logs for afterwards reading.

Android as a development platform provides a wide set of high abstraction level tools to emphasize robust and reusable design for low resource based, quick development cycles. Such benefits require the adequation of the software design and architecture to the constraints imposed by the Android development framework.

Given that none of the project team members had received any instruction on this framework, engaging the development of an Android application implied an important risk. Moreover, after the research and training steps concluded, follow up of that risk was not halted, as the quick, robust software development is only assured when building an standard Android application; dynamic, soft real-time functionality implementation is not discouraged, but also not guaranteed to work. Mobile devices development restrictions and common practices were also unknown to the team.

Even when the aforementioned eased development features are applicable,

mobile devices are harsh software environments due to, amongst others, memory and battery constraints, where processes have to handle being suspended by an incoming call or similar external events. These factors are specially critical for an application as the one developed in this project, which needs to continually parse and log data.

The application was also intended to act as a quick testing front-end for the prototypes produced by the parallel-conducted hardware research. By providing fully-functional application modules since early stages of development, hardware prototypes could be best-case and worst-case checked by directly connecting them to the Android device for data visualization. Visual verification proved to be a very effective method when working with large quantities of data which were more easily checked against their visual representation than value-by-value reading.

These factors lead to the adoption of an agile software development process focusing on functionality building while prototyping more high risk involving features. To avoid typical drawbacks of such methodologies, great emphasis was put on the application of characteristics found in *Iterative and Incremental processes*, namely, use case driven and risk focused development. That way, project scheduling was done addressing higher risks first while assuring expected functionality to be implemented on time thanks to the use case model.

In the following sections a complete view of the software development project will be presented, beginning with the requirements captured for the project. The use case scenarios identified from those requisites will be detailed next, followed by an explanation of the system architecture ?via 4+1 view model?. Then implementation details will be exposed and the chapter will finish with a short conclusion.

3.2 Requirements

The requirement capture process for the project considered three main stakeholders: the project masters (¿Nombres?), the EPFL[*] and the project team members; and was done in two sessions. The first one produced the basic requirement list which described the system and was used to schedule the earlier development iterations. This was so because of the strong time restrictions this software development project had to cope with. When the critical functionality was achieved and the hardware research was in a suitable state,

the second requirements capture session was conducted. By then, the +EPFL representative (Fran) [Murcia Hospital representative?] had shown the state of the development to the stakeholder party of him, and collected feedback. Thus, the requirements produced by this second session were of a more user-oriented nature.

The functional and non-functional requirement lists are presented next.

3.2.1 Functional Requirements

- R01 - Receive raw data via Bluetooth
- R02 - Receive raw data via 802.15.4
- R03 - Receive raw data from a log file
- R04 - Parse raw data into processed data
- R05 - Display processed data
- R06 - Log raw data
- R07 - Log processed data
- R08 - Scale View Vertically
- R09 - Scroll View Vertically
- R10 - Scroll View Horizontally

3.2.2 Non-functional Requirements

The following non-functional requirements are identified:

- The application must display ECG data at 30fps.
- The application must run on a Motorola Xoom device.

3.3 Risk Analysis

Being the project mainly a hardware research project, and considering the software development part of it useless without successful results on the hardware part, a detailed process of risk analysis was mandatory to be conducted since the earlier stages of planning and development so as to avoid wasting

manpower on futile work.

The risk list at the end of the project is as follows:

- **PR1.** Application functionality inferior to that featured by existing iOS application
- **HR1.** 802.15.4 receiver device delayed
- **HR2.** 802.15.4 receiver device unfeasible
- **MR1.** Mobile device unsuitable for target functionality
- **AR1.** Lack of instruction on Android development delays workflow
- **AR2.** Android providing subpar performance when handling required data
- **AR3.** Android rendering capabilities unable to handle required data

This risk analysis focused on two main risk sources: the parallel-conducted hardware research, and Android as a development platform. Project definition and team related risks were also considered.

The hardware research part of the project delivered the highest probability and impact rated risks. It was so because those risks were external to the software development project scope and thus could not be handled by any of the tools provided by any development methodology. At the same time, should such risks come to be, the impact on the software product would be, in most of cases, as catastrophic as turning the whole development useless thus causing its cancellation.

Regarding Android development only a subset of the final set of risks was assessed at first. Every risk in this subset dealt with the team lack of knowledge about the Android platform and was scheduled to be addressed foremost. A last risk was added to this group after the first research on mobile devices limitations regarding potential unfitness of such devices for near real-time display and handling of not-so-small data packages, and that risk handling plan proved to be key to the successful outcome of the project as the remaining subset of Android-related risks were linked to Android applications display performance.

The usual project definition and personal risks such as incorrect deadline scheduling or inability to reach critical milestones on time were pondered,

increasing their impact rates as the application would be needed by the hardware device to secure a successful outcome for the project.

A detailed view of each assessed risk is provided next, including risk evolution throughout the project lifetime.

PR1. Application functionality inferior to that featured by existing iOS application

Probability: Moderate

Impact: Very High

Description: Failure to provide an expanded set of features in the Android application when compared with the iOS application renders the software part of the project invalid on its own. It could, then, only be valid as demo software for USB receiver device showcasing. If the device is not finished, then the whole software development project will have been futile. The key marker for this risk is inability to generate valid software modules throughout the development that provide required functionality. Failure to reach milestones and use case realizations on time is other important marker. Preventive measures were taken to avoid the occurrence of this risk since the beginning of the development by a functionality building focused project scheduling for the first development phases.

This risk was marked as surpassed at the reviewing meeting of Iteration 2 as all key functionality had been implemented, as planned.

HR1. 802.15.4 receiver device delayed

Probability: High

Impact: High

Description: Being the production of the 802.15.4 receiver device dependant on the hardware research part of the project a delay on the estimated milestones for that part of the project is likely to occur. Should that happen, hardware research and development will need to be prioritized over this software project. That could lead to big delays in software production. To prevent the rising of further problems derived from those potential delays, the software development process must always work with non-solid, ready-to-change deadlines and milestones. Application functionality is to be ranked in order of importance of implementation to be prepared, in case of an unexpectedly big delay, to leave less important functionality out of the scope of the project. Markers to be followed up are: unsuccessful output from hardware research (a new branch of the potential technologies tree has to be

explored), failure to reach hardware development or research milestones and delays in the acquisition of tools or devices needed for the hardware project. Preventive measures considered are: detailed follow up of the hardware research development, reducing the software development team if manpower is needed in the hardware area, and planning assuming delays on component acquisition.

HR1 was monitored throughout the whole software development project, and marked as surpassed at the reviewing meeting of Iteration 5.

HR2. 802.15.4 receiver device unfeasible

Probability: Medium

Impact: Critical

Description: Until hardware research results are successfully delivered there is no guarantee of the viability of the 802.15.4 receiver device. This software development project loses most of its value if such device is not developed, as the iOS application already exists. Developing an Android application with an equal feature set is also a valid objective, so this risk does not render the development invalid: the full team will then work on software development, and requirements will be restated to include more final-user oriented functionality and/or features from the *future* set. This risk can be monitored with the following markers: unsuccessful output from hardware research and failure to reach hardware development or research milestones. Being both external to this software project, no preventive measures can be applied apart from scheduling allowing smaller team sizes for the software area.

The probability of the risk was reduced to low after the reviewing meeting for Iteration 3, when the critical hardware research had concluded with positive results. HR2 was marked as surpassed when the production of a device prototype was finished and tested [?TIME?].

MR1. Mobile device unsuitable for target functionality

Probability: Low

Impact: Critical

Description: Even when mobile devices technical specifications have increased significantly in the previous years, specially regarding CPU power and rendering capabilities, the soft-realtime requirements of the project in terms of data manipulation and visual representation involve a low probability risk of the application being unsuitable for such devices. The risk probability is

decreased by the fact that similar featured applications exist both for iOS and Android powered devices. Even so, the 802.15.4 receiver device USB interface doesn't allow for this risk not to be reckoned. Preventive measures considered: quick prototyping of critical functionality to discard unfeasibility, conduction of performance tests, both rendering and data handling related, in the target device and testing of USB-Android communication as soon as possible in the project schedule.

As performance tests were conducted on early builds of the application, the need of further research on this risk arised as the data handling performance in the target device was low, but not as low as the rendering performance. Thus, this risk was unfolded into risks AR2 and AR3, both related to Android performance when handling the aforementioned tasks. This risk follow up was then halted, as it was no longer needed.

AR1. Lack of instruction on Android development delays workflow

Probability: High

Impact: Moderate

Description: None of the team members has received any instruction on Android development and throughout research is not viable because of time restrictions. It is reasonable to foresee potential delays in the development because of the parallel instruction-development flow, as well as the need to rewrite parts of the system rendered obsolete when further knowledge is acquired. Application malfunctioning, unexpected behaviours and low performance are markers to be tracked. As a preventive measure a short instruction time will be scheduled at the beginning of the project, but every team member is responsible to continue his instruction throughout the whole project. Application builds are to be checked for big differences against canon Android applications behaviour.

The risk was marked as surpassed after Iteration 3, as critical functionality had already been implemented and tested, though Android instruction was not halted.

AR2. Android providing subpar performance when handling required data

Probability: Moderate

Impact: High

Description: The benefits of the high-level, single application model provided by Android are such in behalf of the sacrifice of performance. In this project soft-realtime requirements are present, and the system needs to process around 250 ECG wave samples [quotation needed] (among other data)

per second. Android code reutilization and class based programming suggested practices, the absence of an explicit memory management API and the employment of the Garbage Collector only complicate the achievement of such requirements. Special care will need to be put on the development and performance checks are to be conducted regularly on generated builds to ensure the avoidance of this risk. If evidence is found of Android inability to provide the required performance (and there is no way of attributing the failure to the team's lack of ability), low-level Android development will be considered. As the probability of this last scenario to occur is quite low, no research will be conducted in low-level Android development until mandatory.

The risk was verified to be occurring during Iteration 2 testing phase. Lack of care on memory management was found to be the problem, and was solved in Iteration 3. The risk was marked as surpassed after the review meeting for Iteration 4.

AR3. Android rendering capabilities unable to handle required data

Probability: Low

Impact: High

Description: The Android Operating System runs on quite a wide range of devices, each with its own technical specifications. Providing the single application development model that Android features requires many software layers, many of them of high abstraction level. The risk exists, thus, that the rendering required by the project couldn't be achieved within the involved time restrictions. The target device for the project is fixed (see Non-functional Requirements Subsection [link!]) as a Motorola Xoom. This device employs a dedicated Tegra2 GPU [quotation needed] which should suffice, so risk probability is chosen as *low*. Performance tests in the display module are to be conducted, though, so as to make sure that a correct usage of the available resources is being done. If low rendering performance is detected, Android native level rendering API, Renderscript, is to be looked into as a remedy, once the code is assured to be optimized.

Risk probability was increased to *Moderate* during Iteration 3 as low performance was detected but was considered not critical enough to apply the Renderscript solution. The risk was marked as surpassed in the reviewing meeting of Iteration 4.

Thanks to this risk analysis the project schedule was developed in such a manner that it prioritized risk suppressing and the decision was taken to plan only the first two of the five intended development iterations, leaving

the other three as drafts to allow them to evolve at par with the uncanceled risks. Use case realization order was also selected based on this risk analysis, ensuring that higher risk involving features were developed (or at least prototyped) as early as possible.

Use cases for the project are presented next, followed by the system architecture description, to allow a finer understanding of the software development project schedule and related decisions, which will be detailed in the next section.

3.4 Use Cases

The project use cases are now presented following the *use case common style* described by Martin Fowler [Fowler, 2004], as the relaxed template allows for quicker document producing than more detailed descriptions such as those presented by Cockburn [Cockburn, 2001].

Actor listing is omitted in all the descriptions, because of the following implicit:

- The main actor for the use case is the user
- The only other actor is the data emitter node, when applicable. It can refer to the Bluetooth emitter device or the USB 802.15.4 receiver device.

Please note that the 802.15.4 emitter node is not considered an actor as the communication with such device is handled by the USB 802.15.4 receiver, which actually is the considered actor.

3.4.1 UC1. View data from Bluetooth

Description The user wish to receive and visualize data from a Bluetooth ECG node in real time. He will start the communication, visualize real-time received data and finish the connection once done.

This use case captures requisites R01, R04, R05, R06, and R07.

Preconditions The application is in the main menu screen.

Main flow

1. User indicates his will to start Bluetooth data visualization.
2. The system prompts for the node to connect to.
3. User specifies the desired node.
4. The system manages connection to the node. If unable to establish the connection, see AF1.
5. The Bluetooth node sends data to the system.
6. The system shows processed data to the user. Received data is also logged.
7. The user can now adjust view parameters (See UC4)
8. User chooses to finish data visualization.
9. The system closes active connections and stops data visualization.
10. The system returns to the main menu.

Alternative Flow 1 The system cannot establish connection to the Bluetooth node selected by the user.

1. The system notifies the user about the problem.
2. The system returns to the main menu.

3.4.2 UC2. View data from USB Receiver

Description The user wish to receive and visualize data from an 802.15.4 ECG node in real time. He will start the communication, visualize real-time received data and finish the connection once done. The data from the node will be received via the USB 802.15.4 receiver device.

This use case captures requisites R02, R04, R05, R06, and R07.

Preconditions The application is in the main menu screen.

Main flow

1. User indicates his will to start USB receiver data visualization.
2. The system asks the user to connect the USB receiver.
3. User connects the USB receiver.
4. The system manages connection to the USB receiver. If unable to establish the connection, see AF1.
5. The USB receiver device sends data to the system.
6. The system shows processed data to the user. Received data is also logged.
7. User can now adjust view parameters (See UC4)
8. User chooses to finish data visualization.
9. The system closes active connections and stops data visualization.
10. The system returns to the main menu.

Alternative Flow 1 The system cannot establish connection to the USB receiver device.

1. The system notifies the user about the problem.
2. The system returns to the main menu.

3.4.3 UC3. View data from log file

Description The user wishes to read a log file created from a real time visualization session. He will specify the log file to load, visualize stored data and finish visualization once done.

This use case captures requisites R03, R04 and R05.

Preconditions The application is in the main menu screen.

Main flow

1. User indicates his will to start log data visualization.
2. The system prompts for the log file to load.
3. User specifies the desired file.
4. The system reads the selected log file.
5. The system shows logged data to the user.
6. User can now adjust view parameters (See UC4)
7. User chooses to finish data visualization.
8. The system stops data visualization.
9. The system returns to the file selection menu.
10. User selects to return to main menu. Else follow from step 3.
11. The system returns to the main menu.

3.4.4 UC4. Adjust view parameters

Description When visualizing ECG data the user wishes to adjust view parameters such as plot vertical scale, plot vertical scroll and plot horizontal scroll.

This use case captures requisites R08, R09, R10.

Preconditions The application is displaying ECG data.

Main flow

1. User indicates his will to change the vertical scale.
2. The system updates plot vertical scale.
3. User indicates his will to change plot vertical scroll.
4. The system updates plot vertical scroll.
5. If the displayed data is read from a log file, see AF1.

Alternate Flow 1 The user is able to control horizontal scroll parameter.

1. User indicates his will to change the horizontal scroll.
2. The system updates plot horizontal scroll.

3.5 Design and Architecture

3.6 Implementation Details

In this section a detailed description of the development is presented. The evolution of the application architecture and functionality; design, architectural and implementation decisions and explanations of the circumstances in which they were made, as well as the development of the project schedule are exposed in chronological order.

The section is arranged following the five iterations of the project, developing each one by presenting the target objectives and expected deadlines for the iteration, detailing application evolution with emphasis on use case realization and risk suppressing achievements and demonstrating the state of the project as assessed on the reviewing meeting conducted at the end of the iteration.

3.6.1 Project Scheduling

Before diving into the description of the development process an overview of the project schedule is mandatory.

As was mentioned in the previous sections, an agile software development methodology has been applied to the project, even if artifacts from more ordered and structured methodologies have been employed to avoid losing focus on the critical aspects of the development.

Software development project being dependant on parallel-conducted hardware research, project assets, both personal and development resources, being shared with the hardware research having the former higher priority, and team's lack of formation regarding Android development are some of the factors which lead to the adoption of such a mixed methodology. As they have been already exposed in previous sections, they won't be detailed here.

In such an scenario, a fully developed, eight month covering schedule was unfeasible, at least with the imposed time restrictions which didn't allow much time to be spent on planning. The decision was then made to plan only the earlier project iterations, assuring critical functionality identified from use case development to be implemented as soon as possible as well as higher threat involving risk suppression to be realized.

Actual software project development begun October 15, 2011, being the final deadline set on June 15, 2012. That deadline could not be pushed any further, so an estimated deadline was set on May 31, 2012, leaving half a month for further work or recovering from delays, and seven and a half months of development time.

Time was needed for the hardware research to start providing results, and no work could be done in the meantime on related application parts. Considering also that even in the most optimistic scenarios no actual work with the 802.15.4 USB receiver couldn't be done until mid February [link to hw planning or something], the schedule had to assume that the first four months of software development would need to cover the implementation of most of the features, leaving the rest of the development time for implementing hardware-related requirements, which couldn't actually be scheduled until hardware research was evaluated.

The adopted schedule dealt with the aforementioned facts by proposing five iterations, from October 15 to May 30, complying with the fifteen days reserved for contingencies. The first three iterations had a duration of two months, the third one a single month, and the remaining one was fifteen days long.

Having the previously developed iOS application as starting point, and being achieving at least the same feature list of that a critical target of the project, the first two iterations were planned so as to realize **UC1** and **UC3** which captured requisites expressing such feature list.

The next iterations were just scrapped as no accurate estimation could be done on the state of the project by those dates. Thus, the third iteration was planned to cover the implementation of the remaining features, namely, communication with the 802.15.4 receiver device, the fourth one reserved for polishing the application and the fifth one left for testing and validation. The fourth iteration was to shrink if objectives were achieved quickly to leave more time for validation.

The scheduled distribution of work for each iteration is as follows:

| It | Dates | Activity |
|----|-----------------|---------------------------------------|
| 1 | Oct 15 - Dec 15 | Application base and Bluetooth module |
| 2 | Dec 15 - Feb 15 | Log module and initial USB module |
| 3 | Feb 15 - Apr 15 | Final USB implementation |
| 4 | Apr 15 - May 15 | Polishing |
| 5 | May 15 - May 30 | Validation |
| - | May 30 - Jun 15 | Reserved |

Which can be seen as the following expected use case realization dates:

| It | Dates | Realized Use Case |
|----|-----------------|--------------------------|
| 1 | Oct 15 - Dec 15 | UC1, UC4 (first version) |
| 2 | Dec 15 - Feb 15 | UC3, UC2 (first version) |
| 3 | Feb 15 - Apr 15 | UC2 (final) |
| 4 | Apr 15 - May 15 | UC4 (final) |
| 5 | May 15 - May 30 | Validation |
| - | May 30 - Jun 15 | Reserved |

Throughout the development, as expected, this schedule had to be adapted as the hardware research advanced to assess the arise of difficulties and subsequent changes to its planning. Instead of providing a fixed snapshot of the altered schedule at the end of the project, a detailed description of each iteration is presented next, including modifications to the planning and the motivation for making them.

3.6.2 Iteration 1

The main objectives for this first iteration were

- the instruction of the team on Android development,
- the lay out of an initial version of the application architecture and
- the implementation of the Bluetooth receiver module.

The allotted time for the iteration was of two monts, from October 15 to December 15. During this period the hardware research didn't require much resources [link to hw], so in practical terms the full team was employed in

the software project.

In order to minimize risk AR1[quote?link?], the instruction of the team on Android development becomes the key objective for the iteration. Development starts with the implementation of the designed base architecture for the application, so it serves as a powerful learning resource. The notion of that implementation as disposable is not abandoned throughout iteration time and it is always considered as a prototype to evolve or be substituted by a more refined version once team's knowledge of Android increases.

Having the basic architectural framework developed, implementation of the Bluetooth receiver module begins. Special care is put both on design and implementation, as this functionality has to be ready as soon as possible, and little time will be available for reimplementation further in the development.

Testing of both architecture and Bluetooth module is conducted during the whole iteration, specially in the final weeks, so by the end of the iteration Bluetooth module is validated and expected to be stable until the scheduled architectural redesign.

As the Android formation phase takes less time than expected and hardware research doesn't allow advancing into next iteration at the time iteration objectives are achieved, an extra implementation effort is put to begin implementation of UC4. Adjust View Parameters.

In the review meeting for the iteration the following conclusions are obtained:

- Basic architecture implementation is done.
- Android is confirmed to be a very comfortable development environment even if non-standard functionality is not that easily achieved. Instruction is planned to continue.
- Realization of UC1-View data from Bluetooth is finished. Related user interface is not final, but it is functional, and is to be updated on further iterations.
- Realization of UC4-Adjust view parameters is done in relation to Bluetooth visualization. As remaining modules are developed, further work is to be done in this field.

3.6.3 Iteration 2

The main objectives for the second iteration were

- the development of the USB communication module and
- the implementation of the Log visualization module.

Log writing improved. USB module done as USB device, valid for arduino and first msp tests Log reading implemented, scrolling and such. Tests results indicate low performance, huge memory requirements. With the basic interface, first Prototype with (except usb host == 802.15.4) full functionality implemented. That nice and all. Shown to masters and feedback applied. On time ?

Took a loong break here for hardware development

3.6.4 Iteration 3

This is the first just-drafted iteration. Starting from the fully functional prototype, architectural and performance fixes were mandatory. Also, given the positive state of the hw research scheduling was done for the rest of the iterations.

The main objectives for this third iteration were

- the redesign of the application architecture,
- the achievement of required performance in data management and
- the scheduling of the rest of the project time.

(Scheduling seems strange as an objective)

Architecture redesigned targeting easy adaptation and versatility inside the scope of the application. Redesigned visualization initialization flow. Performance increased significantly and memory usage reduced THROUGHOUTLY in realtime view. Fixes in modules according to new architecture. Talk about scheduling??

3.6.5 Iteration 4

Final implementation iteration. Final performance increasing fixes and user interface implementation, as well as user-friendliness globally increased.

USB Host here!

The main objectives for this third iteration were

- the implementation of USB host communication,
- the achievement of required performance in rendering and,
- the implementation of user-friendly interfaces.

This ends the implementation phase, user-friendliness could be better but what gives. Performance left 50-50 because it was already ok (30fps not 60fps). One iteration left, devoted to testing.

3.6.6 Iteration 5

Testing and validation with the real thing.

Hey, us of the future, I hope everything's ok up there!

3.7 Closure

Chapter 4

Results

4.1 Final state

4.2 Potential additions and expansions

4.3 Findings

Appendices

Appendix A

Utilities and tools

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