Practice Proofs — Week 2 (One-to-One & Onto)

Functions, maps, and transformations are all words for the same thing: a rule that relates each element in a set X to a unique element in a set Y. We can split this one condition into two and give a formal definition as follows:

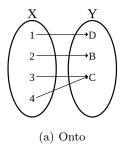
Let f be a relation over sets X and Y. Then f is a well defined function if

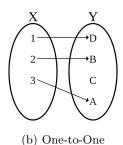
- 1. for every x in X there exists a y in Y such that f(x) = y. [all of X is sent to Y]
- 2. if $x_i = x_j$ then $f(x_i) = f(x_j)$. [each element in X is sent to only one element in Y]

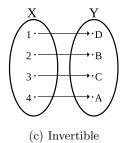
Ideally, our function is strong enough to work the other way around, but to be well defined in the opposite direction it would need to retain these two conditions. If 1 still works from Y to X then we call the function onto, and if 2 still works from Y to X we call it one-to-one. If both still work, then the opposite direction is well defined, and we can invert the function.

Let $f: X \to Y$ be a well defined function. Then

- (a) f is **onto** (surjective) if for every y in Y there exists a x in X such that f(x) = y.
- (b) f is **one-to-one** (injective) if $f(x_i) = f(x_j)$ implies that $x_i = x_j$.
- (c) f is **invertible** (bijective) if f is both one-to-one and onto.







Notice in the diagram above that the range of f in (a) is all of Y-this is an equivalent way of stating that f is onto. We'll be able to say a lot more about these properties if f is a linear transformation once we cover subspaces and dimensionality, but for now we just need the following.

Let $T: V \to W$ be a linear transformation between vector spaces V and W. Then

- (a) T is **onto** if
 - for every w in W there exists a v in V such that T(v) = w.
 - the range of T is equal to the codomain W.
- (b) T is **one-to-one** if $T(v_i) = T(v_i)$ implies that $v_i = v_i$.
- (c) T is **invertible** if
 - T is onto and one-to-one.
 - there exists a linear transformation $S:W\to V$ such that $S\circ T:V\to V$ is equal to I on V, and $T\circ S:W\to W$ is equal to I on W.

There are also more equivalent definitions if we talk about the matrices, solution sets, etc. of these transformations, but for this section we'll just be looking as the transformation in the abstract.

The exercises in this worksheet are adapted from Ch. 3 of Sheldon Axler's *Linear Algebra Done Right* (3rd ed.), although the notation and proofs have been modified to fit this course.

"PIFAND ONLY IF Q" -> SHOW P=> Q AND Q=>P

- 1. Prove that T is injective if and only if T(v) = 0 has only the trivial solution v = 0.
- (=) ASSUME T IS ONE-TO-ONE. THEN T(v):T(w)=>V=W. LET V BE SOME SOLUTION TO $T(v):\overline{O}$. BY LINEARITY, $T(\overline{O})$ MUST BE \overline{O} , SO WE HAVE $T(v):\overline{O}:T(\overline{O})$. SINCE T IS IN)., $T(v):T(\overline{O})\Longrightarrow V=\overline{O}$
- (\leftarrow) ASSUME V=0 IS THE ONLY SOL. TO T(V)=0, SUPPOSE THERE EXIST SOME u,w such that T(u)=T(w). Then T(u)=T(w)=T(u)=0, and Since V=0 is the only sol to T(V)=0, $V=u-w \implies u-w=0 \implies u=w$ Thus T(u)=T(w)=0 w=0 w=0

2. Prove that T is invertible if and only if T is injective and surjective.

WE'RE TRYING TO
PROVE THE DEFINITION
GIVEN EARLIER THAT I IS INVI.
IFF T IS 1-1 CONTO, SO WE
CAN ONLY USE THE OTHER
DEF (THAT 35 S.T. SOT: TOS = I)

(=>) ASSUME T IS INVERTIBLE.

SUPPOSE W, $V \in V$ AND T(U) = T(V).

THEN $U = T^{-1}(T(u)) = T^{-1}(T(v)) = V$, so T(u) = T(v) = V = V = V.

LET WEW. THEN $W = T(T^{-1}(w))$ SO FOR ANY WEW THERE IS A $T^{-1}(w) \in V$ 6. $T(T^{-1}(w)) = W = V$. TIS ONTO

(=) ASSUME TIS 1-1 AND ONTO

THEN FOR EACH WEW THERE IS A UNIQUE SWEV S.T. T(S(W))=W with S''?

THUS (ToS)(W)=W => ToS=I on W Function composition is associative =>

LET VEV. THEN T((SoT)(V))=(ToS)(T(V))=IoT(V)=T(V) (ToSoR)(V)=(ToS)(R(V))=T((SoR)(V))SINCE TIS 1-1, T((SoT)(V))=T(V)=Y (SoT(V)=V=Y SoT=I on VWE ALSO NEED TO SHOW THAS S is linear.

SUPPOSE WI, WZEW. THEN I

 $T(S(W_1) + S(W_2)) = (TOS)(W_1) + (TOS)(W_2) = W_1 + W_2$ $\implies S(T(S(W_1) + S(W_2))) = S(W_1 + W_2)$ $= (SOT)(S(W_1) + S(W_2)) = S(W_1) + S(W_2) = S(W_1 + W_2)$

SUPPOSE CETE. THEN

T(CS(W)) = CT(S(W)) = C(TOS)(W) = CW

=> S(T(CS(W))) = S(CW) => (SOT)(CS(W)) = CS(W) = S(CW)

"E

3. Prove that the inverse of T is unique.

SUPPOSE S, R ARE TWO INVS.

THEN S = SOI : SO(TOR) = (SOT)OR = IOR = R

THUS S = R

IAN ONLY DO PART OF IT

4. Prove that T is injective if and only if there exists a S such that ST = I.

(=>) ASSUME T IS INJ. DEFINE S': RANCE OF T -> V BY S'(T(V)) = V
THEN S'OT = I ON V (CHECKING LINEARITY IS EASY,
BUT WE NEED STUFF ABOUT DIMENSIONS | SUBSPACES TO
EXTEND S' TO S, WHERE THE DOMIN OF SIS ALL OF W)

(==) ASSUME THERE EXISTS A S S.T. ST = I. SUPPOSE
SUPPOSE T(u) = T(v). THEN S(T(u)) => U=V,
SO T IS INJ

5. Prove that T is surjective if and only if there exists a S such that TS = I.

(=>) ASSUME T IS SURJ. LET $W_1, W_2, ..., W_n$ BE A BASIS OF W.

W'= $\sum_{i=1}^{N} C_i W_i$ GOOD PROOF THEN, SINCE T IS SURJ, FOR EACH W_i & BASIS OF W THERE EXISTS A IN CONTEXT

OF "b-coopd" V_i & $V_$

(\Leftarrow) ASSUME THERE EXISTS SOME \leq S.T. TS=I. THEN FOR ANY WEW, $W: TS(W): T(S(W)) \Rightarrow$ THERE EXISTS A S(W) FOR EACH WEW S.T. $T(S(W)):W \Rightarrow T$ is surt