DECISION PROBLEMS IN INVERTIBLE AUTOMATA

EVAN BERGERON & KLAUS SUTNER

May 5, 2017

Abstract

We consider a variety of decision problems in groups and semigroups induced by invertible Mealy machines. Notably, we present proof that the automorphism membership problem in decidable in these semigroups. In addition, we prove undecidability of a Knapsack variant. A discussion of iteration and orbit rationality follows.

CONTENTS

- 1 Introduction 1
- 2 Background 1
- 3 Decidable Abelian Automorphism Membership
- 4 Knapsack is Undecidable for Automaton Semigroups 3
 - 4.1 A group with decidable word problem with submonoid for which the IsGroup question is undecidable 3
 - 4.2 It is decidable if an Abelian automaton semigroup generates a group 4
 - 4.3 Residuation Fixed Point is Decidable for Abelian automaton semigroups 4
 - 4.4 Misc 4
- 5 Abelian Automata 5
- 6 Open Questions 5

References 5

INTRODUCTION

The word problem is a classic group-theoretic decision problem. Given a finitely generated group G, and a word w over the generators (and their inverses), the word problem asks "is $w \in G$." The word problem is known to be undecidable in surprisely small classes of groups - see TODO for background.

The invertible Mealy machines we consider here give rise to a class of semigroups (and sometimes groups) for which the word problem is decidable. The computability picture here is rather nuaced, however. Other important decision problems, among them the conjugacy problem, and the isomorphism problem are known to be undecidable. (See TODO and TODO for details).

We present proof that, for the Abelian case, automorphism membership testing is decidable in this class of semigroups.

BACKGROUND

An *automaton* is a formally a triple (Q, Σ, δ) , where Q is some finite state set, Σ is a finite alphabet of *symbols*, and δ is a transformation on $Q \times \Sigma$.

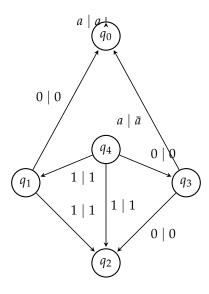


Figure 1: Grigorchuk's machine

Automata are typically viewed as directed graphs with vertex set Q and an edge between u, v if $(u, x)\delta = (v, y)$.

An automaton is said to be *synchronous* when δ outputs exactly one character for every transition and is called *invertible* when every state in Q has some bijection π on Σ such that $(u,x)\delta=(v,\pi(x))$. A state is a *copy state* if π is the identity permutation and is a *toggle state* otherwise.

Each state $q \in Q$ acts on Σ^* , the set of finite strings over Σ . We commonly view Σ^* as the infinite $|\Sigma|$ -nary tree, so we may view q as a transformation sending vertex w to wq.

We extend the action of Q on Σ^* to words $q = q_1 \cdots q_n$ over Q^+ by

$$wq = (\cdots ((wq_1)q_2)\cdots q_n)$$

We adopt the convention of applying functions from the right here. In this way, function composition corresponds naturally with concatenation.

For an automaton A, we denote by S(A) the semigroup generated by Q under composition. A is said to be *commutative* or *Abelian* when S(A) is Abelian. We write G(A) for the group generated by the elements of Q and their inverses.

One may also speak about S(A) and G(A) without explicit reference to an automaton A. As such, we call a semigroup S an automaton semigroup if there is some automaton A with $S \simeq \Sigma(A)$. Automaton groups G are similarly defined.

Invertible automata have recently been usefully applied the group theory. A classic result here is Grigorchuk's group of intermediate growth, generated by the 5 state invertible machine shown in figure 1.

Decision Problems

Automaton semigroups exhibit many interesting and nuanced computability properties. While it is an easy result that the WORD PROBLEM is solvable in such semigroups, similar group-theoretic problems such as the CONJUGACY PROBLEM and FINITENESS PROBLEM have been shown to be undecidable ([12], and [4], respectively).

Various other semigroup theoretic decision problems have recently been considered for small classes of semigroups by Cain in [3]. We consider a subset of his distinguished properties in the automaton semigroup case here.

KNAPSACK IS UNDECIDABLE FOR AUTOMATON SEMIGROUPS

We follow a proof strategy similar to [7].

We define the *Knapsack Problem* as follows: given as input generators $g_1 \dots g_k$ and a target group element g, do there exist natural numbers $a_1 \dots a_k$ such that

$$g_1^{a_1}\cdots g_k^{a_K}=g$$

We prove that this problem is undecidable for automaton semigroups by reducing from Hilbert's tenth problem.

Hilbert's tenth problem asks: "given a polynomial over the integers and an integer *a*, do there exist values of the arguments to the polynomial such that the polynomial evaluated at this point is equal to *a*?" It is known that there exist polynomials for which this problem is undecidable.

We can expand this polynomial into a system of equations - think of a codegen step in a compiler. Each step is either an addition or a multiplication. We can take the terms with negative coefficients and move them to the other side of the equation, so we now have the equality of two different polynomials, each with positive coefficients. We can also choose to only substitute in natural numbers as arguments, by some trick that I don't know. So then we have systems of equations over the natural numbers.

We can turn each equation into a formulation of the Knapsack problem for automaton semigroups. It's known that the Heisenberg semigroup is an automaton group, and there's some equation over the elements of H_3 for multiplication. Same for addition in the natural numbers. Then we just take the direct product of these groups (the class of automaton semigroups is closed under direct product). So this polynomial is equal to a if and only if there exist $a_1 \dots a_n$ such that each of the individual elements of the direct product vectors are equal.

A group with decidable word problem with submonoid for which the IsGroup question is undecidable

We define the following ambient group: elements of the group represent states of a turing machine. This turing machine operates on the empty tape. There is a single halting configuration. In the group, the element corresponding to the halting configuration is the identity. If two group elements represent two configurations of the Turing machine such that one of the configurations can proceed to the other in a single step, then these two group elements are considered equal.

We have the take care defining the Turing machine, however. We'll define it to be a *self-verifying* Turing machine. How does this work? This Turing machine provides some canonical computation, that is, it proceeds from the start configuration onward, perhaps halting. However, there are all sorts of configurations that the Turing machine will never reach. A self-verifying Turing machine will, at every point, verify that it is along this canonical computation path. If it finds that it is not, it will transition to some death state, where it will stay.

This means that, considering the set of all possible configurations of the Turing machine as a graph, there's a path from the start state onward (perhaps ending in a halt state) and everything else is just a star graph transitioning to this death state.

How are these self-verifying Turing machines realized? As the canonical computation proceeds, a program counter is kept (perhaps to the left of the tapehead). After every step, the Turing machine will examine what "time step" the computation is currently sitting in. It will perform the canonical computation for the first n steps. If it does not wind up where

it's configuration says it is, it transitions to the death state. Otherwise, it continues.

Claim: This group has a decidable word problem.

We can verify if one configuration transitions to another in a single step. So given a word over the generators (that represents a sequence of TM configurations), we can first go through pairwise, rewriting these pairs. So I guess chains of consequentive configurations just become their first state. We can also go through and check to see if certain configurations lie upon the canonical computational path. So then everything becomes either the death state or the start state or the identity? Then we can just check for equality of exponents?

Claim: If s is the start configuration of the Turing machine, it is undecidable whether $\langle s \rangle$ is a group.

Suppose it was decidable. We can, given, a TM, transform it into a self-verifying version of itself, and then build this group around it. If the original TM halts, then the submonoid generated by s, (the start state) is just the trivial group. If the original TM hangs, then $\langle s \rangle$ is the free monoid of rank one. So then being able to answer the question "is $\langle s \rangle$ a group" would allow us to solve the halting problem.

It is decidable if an Abelian automaton semigroup generates a group

Reduces to a system of equations. Abelian automaton semigroups can be written as a system of matrix equations: residuation is a linear operation here. We can then also write down the set of matrix equations for the inverse automaton.¹ Exactly what question do we then ask to verify there is a solution? Something about asking if the space spanned by the equations for A has any intersection with \mathbb{N}^n .

Residuation Fixed Point is Decidable for Abelian automaton semigroups

Take the matrix representing residuation for some word $w \in \Sigma^*$ and find if it has any eigenvectors in \mathbb{N}^n .

Misc

Proposition 1. In an Abelian, minimal transducer A, every state has in-degree at most 2.

Proof. Consider a state *s*. Every parent of *s* is either a copy or a toggle state. If *s* had two copy state parents, this contradicts minimality.

If s had two toggle state parents s_1 , s_2 , then either $s = \partial_a s_1 = \partial_a s_2$ or $s = \partial_a s_1 = \partial_{\bar{a}} s_2$. Certainly, the first case contradicts minimality, since then

$$\partial_{\bar{a}}s_1 = \theta\partial_a s_1 = \theta\partial_a s_2 = \partial_{\bar{a}}s_2$$

and so $s_1 = s_2$. For the second case, then TODO I have another argument for this.

$$\theta \partial_a s_1 = \theta \partial_{\bar{a}} s_2 = \partial_a s_2$$

Suppose some state s has in-degree $d \ge 3$. Then either at least 2 parents are toggles, or at least two are copies. If at least 2 are copies,

¹ Interesting to note that there's some duality here: if the semigroup of A is a group, then so is the semigroup of A^{-1} (and they are equal).

OPEN QUESTIONS

- All automaton semigroups are recursively presented. If these presentations are regular, or context-free, does that affect the soluability of these questions?
- Having a zero
- Isomorphism problem
- Bounded automata, etc

REFERENCES

- [1] L. Bartholdi and P. V. Silva. Groups defined by automata. *CoRR*, abs/1012.1531, 2010.
- [2] A. J. Cain. Automaton semigroups. TCS, 410(47–49):5022–5038, 2009.
- [3] A. J. Cain and V. Maltcev. Decision problems for finitely presented and one-relation semigroups and monoids. *International Journal of Algebra and Computation*, 19(6):747–770, 2009.
- [4] Pierre Gillibert. The finiteness problem for automaton semigroups is undecidable. *CoRR*, abs/1304.2295, 2013.
- [5] T. Godin. Knapsack problem for automaton groups. *HAL*, 2016.
- [6] O. Kharlampovich, B. Khoussainov, and A. Miasnikov. From automatic structures to automatic groups. *ArXiv e-prints*, July 2011.
- [7] D. Konig, M. Lohrey, and G. Zetzsche. Knapsack and subset sum problems in nilpotent, polycyclic, and co-context-free groups. *Contemporary Mathematics*, 2015.
- [8] Y. Muntyan. *Automata Groups*. PhD thesis, Texas A&M University, May 2009.
- [9] V. Nekrashevych. *Self-Similar Groups*, volume 117 of *Math. Surveys and Monographs*. AMS, 2005.
- [10] V. Nekrashevych and S. Sidki. *Automorphisms of the binary tree: state-closed subgroups and dynamics of 1/2-endomorphisms*. Cambridge University Press, 2004.
- [11] T. Okano. *Invertible Binary Transducers and Automorphisms of the Binary Tree*. PhD thesis, Carnegie Mellon University, May 2015.
- [12] Z. Sunic and E. Ventura. The conjugacy problem in automaton groups is not solvable. *Journal of Algebra*, 364(148–154), 2012.
- [13] K. Sutner. Invertible transducers, iterations and coordinates. 2013.
- [14] K. Sutner and K. Lewi. Iterating inverse binary transducers. *Journal of Automata, Languages, and Combinators*, 17(2–4):293–313, 2012.