

CENG 384 - Signals and Systems for Computer Engineers

Spring 2021

Homework 1

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1. $e = \lim_{n \rightarrow \infty} (1 + \frac{1}{n})^n = \lim_{n \rightarrow 0} (1 + n)^{\frac{1}{n}}$. By the definition of the derivative;

$$\frac{d}{dt} e^t = \lim_{\Delta t \rightarrow 0} \frac{e^{t+\Delta t} - e^t}{\Delta t} = \lim_{\Delta t \rightarrow 0} \frac{e^t e^{\Delta t} - e^t}{\Delta t} = e^t \lim_{\Delta t \rightarrow 0} \frac{e^{\Delta t} - 1}{\Delta t} \Rightarrow$$

Let $n = e^{\Delta t} - 1$. $n+1 = e^{\Delta t}$. $\ln(n+1) = \Delta t$. Thus; when $\Delta t \rightarrow 0 \Rightarrow n \rightarrow 0$

$$\Rightarrow e^t \lim_{n \rightarrow 0} \frac{n}{\ln(n+1)} = e^t \lim_{n \rightarrow 0} \frac{\frac{1}{n}}{\frac{1}{n} \ln(n+1)} = e^t \lim_{n \rightarrow 0} \frac{1}{\ln(n+1)^{\frac{1}{n}}} = e^t \frac{1}{\ln(\lim_{n \rightarrow 0} (1+n)^{\frac{1}{n}})} = e^t \frac{1}{\ln e} = e^t$$

end of proof

2. (a) $z = x + jy \Rightarrow x + jy - 3 = j - 2x + 2jy \Rightarrow x = 1, y = -1, z = 1 - j$. Thus; $|z|^2 = 1^2 + (-1)^2 = 2$
 (b) $z = re^{j\theta}$ and $z^4 = -81$. $z^4 = r^4 e^{j4\theta} = r^4 (\cos 4\theta + j \sin 4\theta)$ where $\cos 4\theta = -1$ and $\sin 4\theta = 0$. Hence, $r = 3$ and $4\theta = \pi, \theta = \frac{\pi}{4}$. Thus; $z = 3e^{j\frac{\pi}{4}}$
 (c) $z = \frac{(\frac{1}{2} + \frac{1}{2}j)(1-j)(1+\sqrt{3}j)}{(1-\sqrt{3}j)(1+\sqrt{3}j)} = \frac{1+\sqrt{3}j}{4} \Rightarrow z = \frac{1}{2}e^{j\frac{\pi}{3}}$. Thus; $r = \frac{1}{2}, \theta = \frac{\pi}{3}$
 (d) $z = \frac{-3}{j}e^{j\frac{\pi}{2}} = 3je^{j\frac{\pi}{2}}$. Since $j = e^{j\frac{\pi}{2}} \Rightarrow z = 3e^{j\frac{\pi}{2}}e^{j\frac{\pi}{2}} = 3e^{j\pi}$

3.

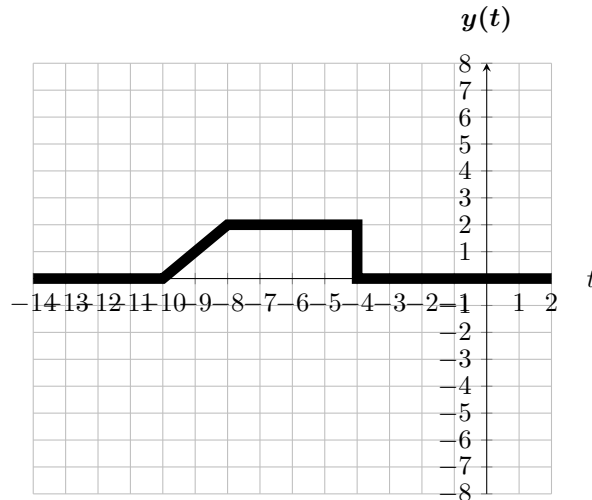


Figure 1: t vs. $y(t)$.

4. (a)

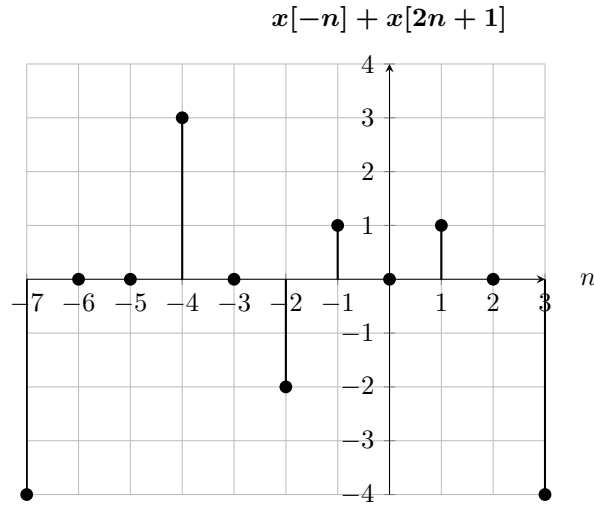


Figure 2: n vs. $x[-n] + x[2n+1]$.

- (b) $x[-n] + x[2n+1] = -4\delta[n+7] + 3\delta[n+4] - 2\delta[n+2] + \delta[n+1] + \delta[n-1] - 4\delta[n-3]$
5. (a) $x(t) = 3\cos(7\pi t - \frac{4\pi}{5}) = x(t+T_0) = 3\cos(7\pi t + 7\pi T_0 - \frac{4\pi}{5})$
 $\Rightarrow 7\pi T_0 = 2\pi \Rightarrow T_0 = \frac{2}{7}$ It is periodic and its fundamental period is $T_0 = \frac{2}{7}$
- (b) $x[n] = \sin[4n - \frac{\pi}{2}] = x[n+N_0] = \sin[4n+4N_0 - \frac{\pi}{2}]$
 $\Rightarrow 4N_0 = 2\pi m \Rightarrow N_0 = \frac{2\pi m}{4}$ Since N_0 is not an integer for any integer m , $x[n]$ is not periodic
- (c) $x[n] = 2\cos[\frac{7\pi}{5}n] + 7\sin[\frac{5\pi}{2}n - \frac{\pi}{3}]$. Let $x[n] = x_1[n] + x_2[n]$ where $x_1[n] = 2\cos[\frac{7\pi}{5}n]$, $x_2[n] = 7\sin[\frac{5\pi}{2}n - \frac{\pi}{3}]$
For $x_1[n] \Rightarrow x_1[n] = 2\cos[\frac{7\pi}{5}n] = x_1[n+N_0] = 2\cos[\frac{7\pi}{5}n + \frac{7\pi}{5}N_0] \Rightarrow \frac{7\pi}{5}N_0 = 2\pi m \Rightarrow N_0 = \frac{10\pi m}{7\pi}$ for $m=7$, $N_0 = 10$ for $x_1[n]$
For $x_2[n] \Rightarrow x_2[n] = 7\sin[\frac{5\pi}{2}n - \frac{\pi}{3}] = x_2[n+N_0] = 7\sin[\frac{5\pi}{2}n + \frac{5\pi}{2}N_0 - \frac{\pi}{3}]$
 $\Rightarrow \frac{5\pi}{2}N_0 = 2\pi m \Rightarrow N_0 = \frac{4\pi m}{5\pi}$ for $m = 5$, $N_0 = 4$ for $x_2[n]$. Thus; fundamental period of $x[n]$ is $\text{LCM}(10,4) = 20 = N_0$
6. (a) A signal is even if and only if $x(t) = x(-t)$. In Figure 1, one can see that $x(\frac{3}{2}) \neq x(-\frac{3}{2})$. $x(\frac{3}{2}) = 0$ but $x(-\frac{3}{2}) = \frac{1}{2}$. Thus; $x(t)$ is not an even signal.
A signal is odd if and only if $x(t) = -x(-t)$. In Figure 1, one can see that $x(\frac{1}{2}) = x(-\frac{1}{2}) = 1$. Thus; $x(t)$ is not an odd signal.
- (b) Even part of the signal $\Rightarrow x(-4 \leq t \leq -2) = x(2 \leq t \leq 4) = 0$ and $x(-1 \leq t \leq 0) = x(0 \leq t \leq 1) = 1$

Even decomposition of $x(t)$

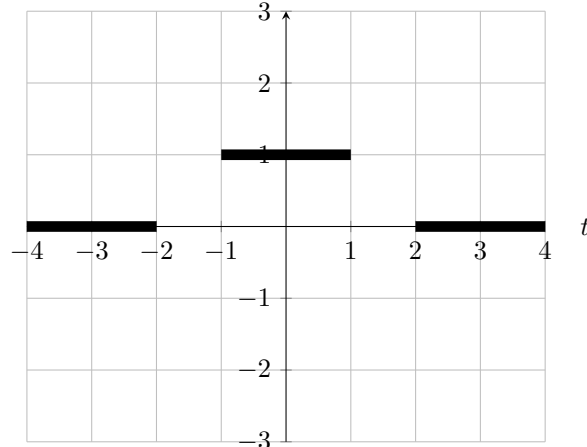


Figure 3: t vs. *Even decomposition of $x(t)$* .

Odd part of the signal $\Rightarrow x(-4 \leq t \leq -2) = -x(2 \leq t \leq 4) = 0$

Odd decomposition of $x(t)$



Figure 4: t vs. *Odd decomposition of $x(t)$* .

7. (a) $x(t) = -3u(t-2) + 5u(t-3) - 3u(t-5)$
 (b) $\frac{dx(t)}{dt} = -3\delta(t-2) + 5\delta(t-3) - 3\delta(t-5)$

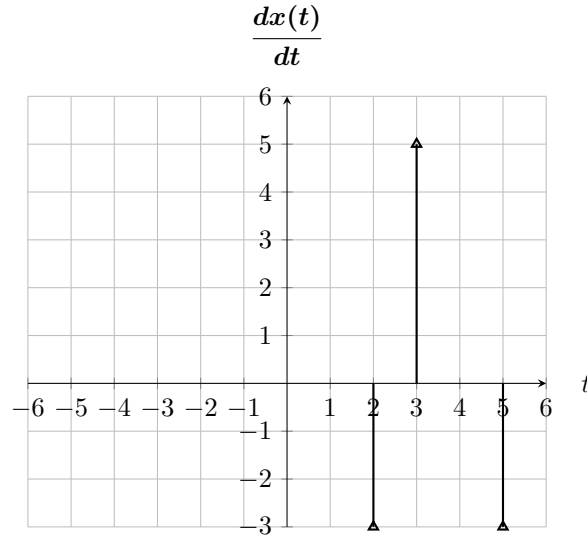


Figure 5: t vs. $\frac{dx(t)}{dt}$.

8. (a) $y[n] = x[3n-5] \Rightarrow$ It has memory since $y[n]$ depends on past and future values of input. $y[2] = x[1]$ (past), $y[3] = x[4]$ (future). Since $y[n]$ depends on some future values of input, it is not casual. It is invertible, we can find a unique h^{-1} , $x[n] = y[\frac{n+5}{3}]$ ($n+5 = 3k$ for integer k) It is stable since for bounded input, it has bounded output. It is not time invariant since $x[n - n_0] \rightarrow y[n - n_0] = x[3n - 3n_0 - 5] \neq x[3n - n_0 - 5]$. It is linear since it has superposition property such that $y_1[n] = x_1[3n-5]$, $y_2[n] = x_2[3n-5]$, thus; $y = a_1y_1 + a_2y_2 = h(a_1x_1 + a_2x_2)$
- (b) $y(t) = x(3t-5) \Rightarrow$ It has memory since $y(t)$ depends on past and future values of input. $y(2) = x(1)$ (past), $y(3) = x(4)$ (future). Since $y(t)$ depends on some future values of input, it is not casual. It is invertible, we can find a unique h^{-1} , $x(t) = y(\frac{t+5}{3})$. It is stable since for bounded input, it has bounded output. It is not time invariant since $x(t - t_0) \rightarrow y(t - t_0) = x(3t - 3t_0 - 5) \neq x(3t - t_0 - 5)$. It is linear since it has superposition property such that $y_1(t) = x_1(3t-5)$, $y_2(t) = x_2(3t-5)$, thus; $y = a_1y_1 + a_2y_2 = h(a_1x_1 + a_2x_2)$
- (c) $y(t) = tx(t-1) \Rightarrow$ It has memory since $y(t)$ depends on past values of input, $y(1) = x(0)$. It is casual since $y(t)$ does not depend on future values of input. It is invertible for $t \neq -1$; $x(t) = \frac{y(t+1)}{t+1}$. It is not stable since for bounded input, it has unbounded output. Since there is no restrictions over t , it can be any value $-\infty < t < \infty$. It is not time invariant since $x(t - t_0) \rightarrow y(t - t_0) = (t - t_0)x(t - t_0 - 1) \neq tx(t - t_0 - 1)$. It is linear since it has superposition property such that $y_1(t) = tx_1(t-1)$, $y_2(t) = tx_2(t-1)$, thus; $y = a_1y_1 + a_2y_2 = h(a_1x_1 + a_2x_2)$.

- (d) $y[n] = \sum_{k=1}^{\infty} x[n-k] \Rightarrow$ It has memory since $y[n]$ depends on past values of input. It is casual since $y[n]$ does not depend on future values of input. It is not stable since it is unbounded. Let $x[n] = u[n]$, a bounded signal. However, $y[n]$ will go to infinity. It is time invariant since $x[n-n_0] \rightarrow y[n-n_0] = \sum_{k=1}^{\infty} x[n-n_0-k] = y'[n]$. It is linear since it has superposition property such that $y_1[n] = \sum_{k=1}^{\infty} x_1[n-k]$, $y_2[n] = \sum_{k=1}^{\infty} x_2[n-k]$, thus; $y = a_1y_1 + a_2y_2 = h(a_1x_1 + a_2x_2)$. It is invertible since one can obtain $x[n] = y[n+1] - y[n]$.