

```
% Problem 6.1 - Viterbi Algorithm
clear; clc; close all

load('emissionMatrix.mat')
load('initialStateDistribution.mat')
load('observations.mat')
load('transitionMatrix.mat')

% Initialize
transitionMatrix(:,27) = [];
A = transitionMatrix;
B = emissionMatrix;
O = observations;
T = length(O);
n = length(A);
max_P = zeros(1,T);
P = zeros(n,T);
P0 = initialStateDistribution;

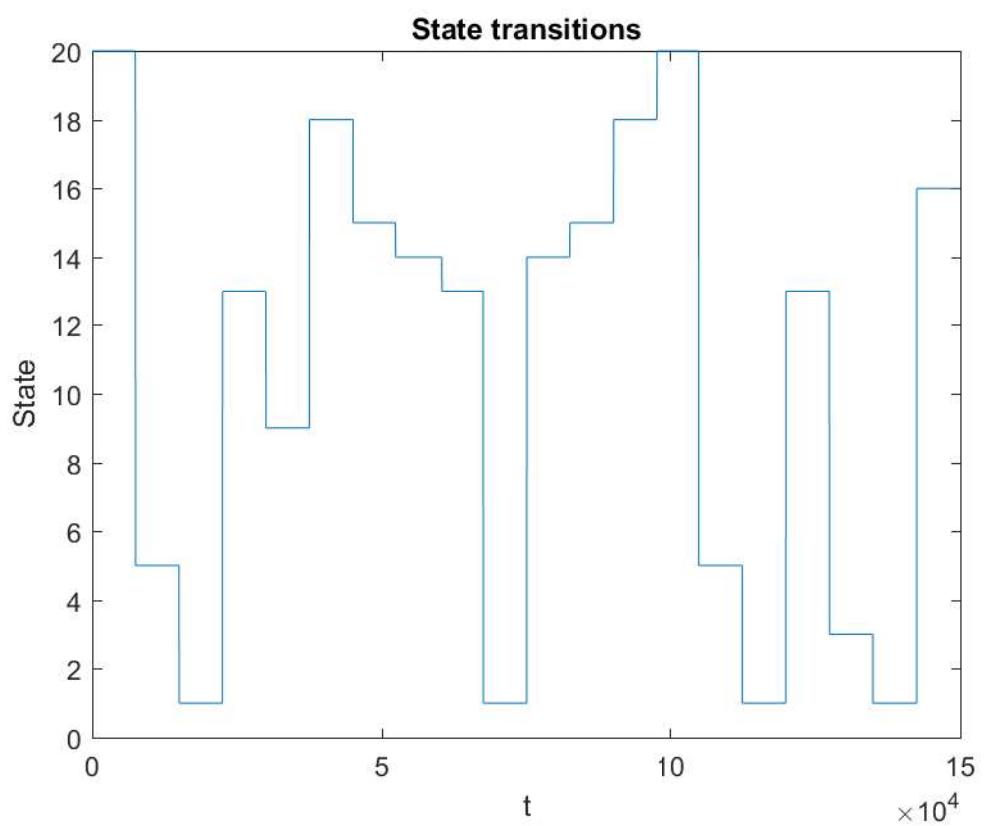
tree = zeros(n,T);
path = zeros(1,T);

% Calculate the first probability vector
P(:,1) = (A*P0).*B(:,O(1)+1)/sum((A*P0).*B(:,O(1)+1));

% Using probabilities, construct a matrix containing indices of connected
% node
for t = 2:T
    for j = 1:n % j is the index of the 2nd column
        best_val = 0;
        for i = 1:n % i is the index of the 1st column
            new = P(i,t-1)*A(i,j);
            if new > best_val
                best_val = new;
                tree(j,t) = i;
                P(j,t) = new*B(j,O(t)+1);
            end
        end
    end
    P(:,t) = P(:,t)/sum(P(:,t));
end

% Construct path backwards
[~,path(T)] = max(P(:,T));
for t = T-1:-1:1
    path(t) = tree(path(t+1),t+1);
end
plot(path)
title('State transitions')
xlabel('t')
ylabel('State')
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```
% print out message converted into a string
% 97 is a on ASCII table
str = char(path(1)+96);
for t = 2:T
    if path(t) ~= path(t-1)
        str = [str char(path(t)+96)];
    end
end
disp(['The hidden message is: ' str])
```



6.2

$$\begin{aligned}
 a) P(S_{t+1}=j | S_t=i, O_{1:T}) &= \frac{P(S_{t+1}=j, O_{1:T} | S_t=i)}{P(O_{1:T} | S_t=i)} = \frac{P(S_{t+1}=j, O_{1:T} | S_t=i)}{P(O_{1:t}, O_{t+1:T} | S_t=i)} \\
 &= \frac{P(O_{1:T} | S_t=i, S_{t+1}=j) P(S_{t+1}=j | S_t=i)}{P(O_{1:t} | S_t=i) P(O_{t+1:T} | S_t=i)} \\
 &= \frac{P(O_{1:t} + S_{t+1}=j) P(O_{t+1:T} | S_{t+1}=j) P(S_{t+1}=j | S_t=i)}{P(O_{1:t} | S_t=i) P(O_{t+1:T} | S_t=i)} \\
 &= \boxed{\frac{\beta_{jt} q_{ij}}{\beta_{it}}}
 \end{aligned}$$

$$\begin{aligned}
 b) P(S_t=i | S_{t+1}=j, O_{1:T}) &= \frac{P(S_t=i, O_{1:T} | S_{t+1}=j)}{P(O_{1:T} | S_{t+1}=j)} = \frac{P(S_t=i, O_{1:T} | S_{t+1}=j)}{P(O_{1:t+1} | S_{t+1}=j) P(O_{t+2:T} | S_{t+1}=j)} \\
 &= \frac{P(O_{1:t} | S_t=i, S_{t+1}=j) P(S_t=i | S_{t+1}=j) \cdot P(S_{t+1}=j)}{P(O_{1:t+1} | S_{t+1}=j) P(O_{t+2:T} | S_{t+1}=j) \cdot P(S_{t+1}=j)} \\
 &= \frac{P(O_{1:t} | S_t=i) P(O_{t+1:T} | S_{t+1}=j) P(S_t=i, S_{t+1}=j)}{P(O_{1:t+1} | S_{t+1}=j) P(O_{t+2:T} | S_{t+1}=j)} \\
 &= \frac{P(O_{1:T}, S_t=i) P(O_{t+1:T} | S_{t+1}=j) P(S_{t+1}=j | S_t=i)}{P(O_{1:t+1}, S_{t+1}=j) P(O_{t+2:T} | S_{t+1}=j)}
 \end{aligned}$$

$$\boxed{\frac{\alpha_{it} b_{j,t} \beta_{j,t+1} q_{ij}}{\alpha_{j,t+1} \beta_{i,t+1}}}$$

$$\begin{aligned}
 c) P(S_{t-1}=i, S_t=j, S_{t+1}=k | O_{1:T}) &= P(S_{t+1}=k | S_t=j, S_{t-1}=i, O_{1:T}) P(S_t=j | S_{t-1}=i, O_{1:T}) \\
 &= P(S_{t+1}=k | S_t=j, O_{t+1:T}) P(S_t=j | S_{t-1}=i, O_{1:T}) P(S_{t-1}=i | O_{1:T}) \\
 &= P(S_{t+1}=k | S_t=j, O_{t+1:T}) P(S_t=j | S_{t-1}=i, O_{1:T}) \sum_h P(S_{t-1}=i | S_{t-2}=h, O_{1:T}) P(S_{t-2}=h | O_{1:T}) \\
 &= P(S_{t+1}=k | S_t=j, O_{t+1:T}) P(S_t=j | S_{t-1}=i, O_{1:T}) \sum_h P(S_{t-1}=i | S_{t-2}=h, O_{t+1:T}) P(S_{t-2}=h | O_{1:T}) \\
 &\quad \boxed{\frac{\beta_{kt} q_{jk}}{\beta_{jt}} \cdot \frac{\beta_{j,t-1} q_{ij}}{\beta_{i,t-1}} \cdot \sum_h \frac{\beta_{h,t-2} q_{hi}}{\beta_{h,t-2}} \cdot \dots}
 \end{aligned}$$

$$d) P(S_{t+1}=k | S_{t+1}=i, O_{1:T}) = \frac{P(S_{t+1}=k, O_{1:T} | S_{t+1}=i)}{P(O_{1:t+1} | S_{t+1}=i) P(O_{t+2:T} | S_{t+1}=i)} =$$

6.3

$$\begin{aligned}
 a) P(S_t = i | o_{1:t}) &= \sum_j P(S_{t-1} = j | S_{t-1}, o_{1:t}) P(S_t = i | o_{1:t}) && * \text{ conditioning on } S_{t-1} \\
 &= \sum_i \frac{P(S_{t-1} = i | S_{t-1} = i) P(S_t = i | o_{1:t})}{P(o_{1:t} | S_{t-1} = i)} && * \text{ product rule} \\
 &= \sum_i \frac{P(S_{t-1} = i | S_{t-1} = i) P(o_{1:t} | S_{t-1} = i) \cdot P(S_t = i | o_{1:t})}{P(o_{1:t} | S_{t-1} = i) P(o_t | S_{t-1} = i)} && * \text{ split up observations} \\
 &\boxed{\frac{\sum_i a_{ij} b_j(o_t) q_{i,b-1}}{\sum_j b_j(o_t) a_j q_{j,b-1}}} && * \text{ substitute}
 \end{aligned}$$

$$\begin{aligned}
 b) P(x_t | y_{1:t}) &= \int P(x_t | dx_{t+1}, y_{1:t}) P(dx_{t+1} | y_{1:t}) \\
 &= \int \frac{P(x_t, y_{1:t} | dx_{t+1})}{P(y_{1:t} | dx_{t+1})} P(dx_{t+1} | y_{1:t}) \\
 &= \int \frac{P(x_t | dx_{t+1}) P(y_{1:t+1} | dx_{t+1}) P(dx_{t+1} | y_{1:t})}{P(y_{1:t+1} | dx_{t+1}) P(y_t | dx_{t+1})} \\
 &\boxed{\frac{P(y_t | x_t) \int dx_{t+1} P(x_t | x_{t+1}) P(x_{t+1} | y_{1:t+1})}{\int dx_t P(y_t | x_t) \int dx_{t+1} P(x_t | x_{t+1}) P(x_{t+1} | y_{1:t+1})}}
 \end{aligned}$$

$$6.5 \quad \textcircled{1} \xrightarrow{\textcircled{2}} P(\vec{x}|y=i) = \frac{P(y=i|\vec{x})}{\sum_i P(y=i)} \cdot \frac{P(\vec{x}|y=i)}{P(\vec{x})} = \frac{\pi_i}{\sum_i \pi_i} \cdot \frac{(2\pi)^{-\frac{d}{2}} |\Sigma_i|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_i)^T \Sigma_i^{-1} (\vec{x}-\vec{\mu}_i)}}{e^{\frac{1}{2}(\vec{x}-\vec{\mu}_0)^T \Sigma_0^{-1} (\vec{x}-\vec{\mu}_0)} + \dots}$$

a) $P(y=1|\vec{x}) = \frac{P(\vec{x}|y=1) P(y=1)}{P(\vec{x})} = \frac{P(\vec{x}|y=1) P(y=1)}{\sum_i P(\vec{x}|y=i) P(y=i)}$

$$= \frac{(2\pi)^{-\frac{d}{2}} |\Sigma_1|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_1)^T \Sigma_1^{-1} (\vec{x}-\vec{\mu}_1)} \cdot \pi_1}{(2\pi)^{-\frac{d}{2}} |\Sigma_0|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_0)^T \Sigma_0^{-1} (\vec{x}-\vec{\mu}_0)} \cdot \pi_0}$$

same term

$$\boxed{\frac{\pi_1 |\Sigma_1|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_1)^T \Sigma_1^{-1} (\vec{x}-\vec{\mu}_1)}}{\pi_0 |\Sigma_0|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_0)^T \Sigma_0^{-1} (\vec{x}-\vec{\mu}_0)} + \pi_0 |\Sigma_0|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_0)^T \Sigma_0^{-1} (\vec{x}-\vec{\mu}_0)}}}$$

b) If $\Sigma_1 = \Sigma_0 = \Sigma$, then

$$P(y=1|\vec{x}) = \frac{\pi_1 |\Sigma|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_1)^T \Sigma^{-1} (\vec{x}-\vec{\mu}_1)}}{\pi_0 |\Sigma|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_0)^T \Sigma^{-1} (\vec{x}-\vec{\mu}_0)} + \pi_0 |\Sigma|^{-\frac{1}{2}} e^{\frac{1}{2}(\vec{x}-\vec{\mu}_0)^T \Sigma^{-1} (\vec{x}-\vec{\mu}_0)}} \quad * \text{divide each term by denominator}$$

$$= \frac{1}{1 + \frac{\pi_0}{\pi_1} \frac{e^{\frac{1}{2}(\vec{x}-\vec{\mu}_0)^T \Sigma^{-1} (\vec{x}-\vec{\mu}_0)}}{e^{\frac{1}{2}(\vec{x}-\vec{\mu}_1)^T \Sigma^{-1} (\vec{x}-\vec{\mu}_1)}}} = \frac{1}{1 + e^{\frac{\pi_0}{\pi_1} \frac{(\vec{x}-\vec{\mu}_0)^T \Sigma^{-1} (\vec{x}-\vec{\mu}_0)}{(\vec{x}-\vec{\mu}_1)^T \Sigma^{-1} (\vec{x}-\vec{\mu}_1)}}}$$

* Now simplifying the exponential terms, Z,

$$Z = \pi_0 - \pi_1 - \frac{1}{2} \vec{x}^T \Sigma^{-1} \vec{x} + \vec{\mu}_0^T \Sigma^{-1} \vec{M}_0 - \vec{\mu}_0^T \Sigma^{-1} \vec{x} + \vec{M}_0^T \Sigma^{-1} \vec{M}_0 + \frac{1}{2} \vec{x}^T \Sigma^{-1} \vec{x} - \vec{x}^T \Sigma^{-1} \vec{M}_1 - \vec{M}_1^T \Sigma^{-1} \vec{x} + \vec{\mu}_1^T \Sigma^{-1} \vec{M}_1$$

$$Z = \pi_0 - \pi_1 + \frac{1}{2} \vec{M}_0^T \Sigma^{-1} \vec{x} + \frac{1}{2} \vec{\mu}_0^T \Sigma^{-1} \vec{x} - \frac{1}{2} \vec{M}_0^T \Sigma^{-1} \vec{M}_0 - \frac{1}{2} \vec{\mu}_1^T \Sigma^{-1} \vec{x} - \frac{1}{2} \vec{M}_1^T \Sigma^{-1} \vec{x} + \frac{1}{2} \vec{\mu}_1^T \Sigma^{-1} \vec{M}_1$$

so $P(y=1|\vec{x}) = \sigma(\vec{w}^T \vec{x} + b)$ where

$$\vec{w} = \frac{1}{2} (\vec{M}_0^T \Sigma^{-1} + \vec{M}_0^T \Sigma^{-1} - \vec{M}_1^T \Sigma^{-1} - \vec{M}_1^T \Sigma^{-1})$$

$$b = -\pi_0 + \pi_1 + \frac{1}{2} \vec{M}_0^T \Sigma^{-1} \vec{M}_0 - \frac{1}{2} \vec{M}_1^T \Sigma^{-1} \vec{M}_1$$

6.5

c) When does $\frac{P(y=1|\vec{x})}{P(y=0|\vec{x})} = n$, $n > 0$

$$\frac{P(y=1|\vec{x})}{P(y=0|\vec{x})} = \frac{\frac{1}{1+e^{-\vec{w}\cdot\vec{x}-b}}}{1 - \frac{1}{1+e^{-\vec{w}\cdot\vec{x}-b}}} = \frac{\frac{1}{1+e^{-\vec{w}\cdot\vec{x}-b}}}{\frac{1+e^{-\vec{w}\cdot\vec{x}-b}}{1+e^{-\vec{w}\cdot\vec{x}-b}}} =$$

$$\frac{P(y=1|\vec{x})}{P(y=0|\vec{x})} = e^{\vec{w}\cdot\vec{x}+b} = n$$

$$\boxed{\vec{w}\cdot\vec{x}+b = \ln(n)}$$