

Waves!

EVAN H. ANDERS,¹ DANIEL LECOANET,^{1,2} KEATON J. BURNS,³ MATTEO CANTIELLO,^{4,5} ADAM S. JERMYN,⁴
BENJAMIN P. BROWN,^{6,7} GEOFFREY M. VASIL,⁸ JEFFREY S. OISHI,⁹ AND OTHERS?

¹*CIERA, Northwestern University, Evanston IL 60201, USA*

²*Department of Engineering Sciences and Applied Mathematics, Northwestern University, Evanston IL 60208, USA*

³*Massachusetts Institute of Technology Departments of Mathematics and Physics, Cambridge, Massachusetts 02139, USA*

⁴*Center for Computational Astrophysics, Flatiron Institute, New York, NY 10010, USA*

⁵*Department of Astrophysical Sciences, Princeton University, Princeton, NJ 08544, USA*

⁶*University of Colorado Laboratory for Atmospheric and Space Physics and Department of Astrophysical and Planetary Sciences, Boulder, Colorado 80309, USA*

⁷*Center for Computational Astrophysics, Flatiron Institute, New York, New York 10010, USA*

⁸*School of Mathematics and Statistics, University of Sydney, Sydney, New South Wales 2006, Australia*

⁹*Bates College Department of Physics and Astronomy, Lewiston, Maine 04240, USA*

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ABSTRACT

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1. INTRODUCTION

Here’s what Evan needs to do:

1. Get all of the damping layer simulations run.

2. Get a really long simulation run without a damping layer.

3. Do the transfer function derivation again.

4. Make figures and write out the story!

2. GRAIVITY WAVES IN THE TERMINOLOGY OF SOUND WAVES

3. SIMULATION DETAILS

We solve a version of the LBR Anelastic equations based on Eqns. 118-120 of Vasil et al. (2013),

$$\nabla \cdot \mathbf{u} + \mathbf{u} \cdot \nabla \ln \rho_0 = 0, \quad (1)$$

$$\partial_t \mathbf{u} + \nabla \varpi + s_1 \nabla T_0 + \mathbf{u} \mathcal{D} = -\mathbf{u} \cdot \nabla \mathbf{u} + \nabla \cdot \Pi, \quad (2)$$

$$\begin{aligned} \partial_t s_1 + \mathbf{u} \cdot \nabla s_0 = \\ -\mathbf{u} \cdot \nabla s_1 + \frac{1}{\rho_0 T_0} (\nabla \cdot [\rho_0 T_0 \chi_R \nabla s_1] + \mathcal{H} + \text{VH}), \end{aligned} \quad (3)$$

where \mathbf{u} is the velocity, s is the specific entropy, and $\varpi = h + \phi - T_0 s_1$ is the dynamic pressure with h the enthalpy and ϕ the gravitational potential. The background density ρ_0 , temperature T_0 , and specific entropy s_0 stratification are loaded from a MESA stellar model. We define the viscous stress tensor

$$\Pi_{ij} = 2\rho_0 \nu \left(e_{ij} - \frac{1}{3} \delta_{ij} \nabla \cdot \mathbf{u} \right), \quad (4)$$

where $e = 0.5(\nabla \mathbf{u} + [\nabla \mathbf{u}]^T)$ is the rate of strain tensor and ν is the kinematic viscosity. The viscous heating term is then $\text{VH} = 2\rho\nu(\text{Tr}(e \cdot e) - (1/3)(\nabla \cdot \mathbf{u})^2)$ where Tr is the trace operation. The effective internal heating accounts for nuclear energy generation and flux carried radiative $\mathcal{H} = \rho\epsilon - \nabla \cdot (F_{\text{rad}})$ with ϵ the nuclear energy generation rate per unit mass. Finally, χ_R is the radiative conductivity; we assume this is a constant in the

interior of the star, but use the real value in the outer portions of the stellar envelope where diffusivity is large.

The momentum equation includes a damping term ($\mathbf{u}\mathcal{D}$). In simulations which include damping, $\mathcal{D} = f_{\text{char}}H(r = r_{\text{transition}})$ where f_{char} is a characteristic frequency and H is the Heaviside step function, which is zero below $r = r_{\text{transition}}$. In simulations without damping, we set $\mathcal{D} = 0$.

For full details about how we implement these equations, we refer the reader to appendix A.

4. RESULTS OF SIMULATIONS WITH DAMPING LAYERS

This is the “recording studio” section – it’s useful to report the amplitude here because the theory doesn’t give that.

We should run simulations as turbulent as possible here. Hopefully more turbulence doesn’t change the result. We will ignore the low-resolution laminar runs.

We report that we see powerlaw wave fluxes at all turbulence values, and no scaling with turbulence (hopefully).

5. SURFACE MANIFESTATION OF GRAVITY WAVES

This is the “Band plays in the bar” section – we can measure sound waves and resonances here.

We should run simulations for a long time here, at a resolution like 256^3 .

6. TRANSFER FUNCTION: LINEAR THEORY DESCRIBES SURFACE MANIFESTATION

This is the section where we open Garage Band and put our bar filter on the recordings we took earlier. We see if the filter actually reproduces the resonances of the bar, etc.

Need to check through the transfer function derivation and theory here carefully. It may be useful to include Kyle here?

7. TRANSFER FUNCTION EXTRAPOLATION TO REAL STARS

This is where we say, based on the last section, the bar filter does a pretty good job of turning studio into bar. So, let’s now see what happens if we use a stadium filter instead of a bar filter (whole star instead of sim). We obviously can’t actually simulate a whole star, but our hope is that this gives us an idea of what gravity waves would look like on stars in gyre.

8. CONCLUSIONS & DISCUSSION

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APPENDIX

A. NUMERICAL METHODS

We nondimensionalize Eqns. 1-3. Our nondimensional length scale L_{nd} is the radial coordinate of the outer boundary of the core convection zone. We nondimensionalize the temperature as the temperature at the stellar core $T_{\text{nd}} = T(r = 0)$ and we use the central density to nondimensionalize the mass $m_{\text{nd}} = \rho(r = 0)L_{\text{nd}}^3$. We use the central value of the nuclear generation rate $H_0 = (\rho\epsilon)(r = 0)$ to define the nondimensional timescale $\tau_{\text{nd}} = (m_{\text{nd}}/[H_0L_{\text{nd}}])^{1/3}$. The important remaining control parameters are then the nondimensional viscosity $\nu_{\text{nd}} = \nu\tau_{\text{nd}}/L_{\text{nd}}^2$ and thermal diffusivity $\chi_{\text{nd}} = \chi\tau_{\text{nd}}/L_{\text{nd}}^2$.

Under this nondimensionalization, the equations of evolution become

$$\nabla \cdot \mathbf{u} + \mathbf{u} \cdot \nabla \ln \rho_0 = 0, \quad (\text{A1})$$

$$\begin{aligned} \partial_t \mathbf{u} + \nabla \varpi + s_1 (\nabla T_0) + \mathbf{u} \mathcal{D} \\ - \nu_{\text{nd}} (\nabla \cdot \bar{\sigma} + \bar{\sigma} \cdot \nabla \ln \rho_0) \\ = \mathbf{u} \times (\nabla \times \mathbf{u}), \end{aligned} \quad (\text{A2})$$

$$\begin{aligned} \partial_t s_1 + \mathbf{u} \cdot (\nabla s_0) - \nabla s_1 \cdot \nabla \chi_{\text{nd}} \\ - \chi_{\text{nd}} (\nabla^2 s_1 + [\nabla s_1] \cdot [\nabla \ln \rho_0 + \nabla \ln T_0]) \\ = -\mathbf{u} \cdot \nabla s_1 + \frac{\nu_{\text{nd}}}{T_0} \mathcal{V} + \tilde{\mathcal{H}}, \end{aligned} \quad (\text{A3})$$

where we define $\tilde{\mathcal{H}} = \mathcal{H}/(\rho_0 T_0)$ before nondimensionalizing. The state variables are \mathbf{u} the velocity, s_1 the fluctuation

tuations of specific entropy, and ϖ the dynamic reduced pressure. We define the stress tensor $\bar{\sigma} = \Pi/(\rho_0\nu)$. The background stellar structure is that of a $15M_\odot$ MESA model (see appendices B & D). This provides radial profiles of $\nabla \ln \rho_0$, $\nabla \ln T_0$, ∇T_0 , T_0 , ∇s_0 , χ_R , and the effective heating \mathcal{H} . We refer the reader to appendix B for information on how these are calculated and what differences exist between MESA and Dedalus.

\mathcal{D} is a radial profile of a damping coefficient. For the runs with damping presented in sec. 4, we set $\mathcal{D} = 0$ in the interior and $\mathcal{D} = f_b$ where f_b is the frequency associated with the peak of N^2 in our simulation domain.

TODO: be more precise about \mathcal{D}

TODO: Update this to be true for this paper.

We time-evolve equations A1-A3 using the Dedalus pseudospectral solver (Burns et al. 2020, git commit 1339061) using timestepper SBDF2 (Wang & Ruuth 2008) and safety factor 0.3. All variables are spectral expansions of Chebyshev coefficients in the vertical (z) direction ($n_z = 512$ between $z = [0, 2.25]$ plus $n_z = 64$ between $z = [2.25, 3]$) and as $(n_x, n_y) = (192, 192)$ Fourier coefficients in the horizontally periodic (x, y) directions. Our domain spans $x \in [0, L_x]$, $y \in [0, L_y]$, and $z \in [0, L_z]$ with $L_x = L_y = 4$ and $L_z = 3$. To avoid aliasing errors, we use the 3/2-dealiasing rule in all directions. To start our simulations, we add random noise temperature perturbations with a magnitude of 10^{-6} to the initial temperature profile.

Spectral methods with finite coefficient expansions cannot capture true discontinuities. To approximate discontinuous functions such as Eqns. ?? & ??, we define a smooth Heaviside step function centered at $z = z_0$,

$$H(z; z_0, d_w) = \frac{1}{2} \left(1 + \operatorname{erf} \left[\frac{z - z_0}{d_w} \right] \right). \quad (\text{A4})$$

where erf is the error function and we set $d_w = 0.05$. The simulation in this work uses $\mathcal{P} = 3.2 \times 10^3$, $R_0^{-1} = 10$, $\operatorname{Pr} = \tau = 0.5$, $\tau_0 = 1.5 \times 10^{-3}$, and $\kappa_{T,0} = \mathcal{P}^{-1}[(\partial T/\partial z)_{\text{rad}}|_{z=0}]/(\partial T/\partial z)_{\text{rad}}$

We produce figures ?? and ?? using matplotlib (Hunter 2007; Caswell et al. 2021). We produce figure ?? using plotly (Inc. 2015) and matplotlib. All of the Python scripts used to run the simulations in this paper and to create the figures in this paper are publicly available in a git repository (https://github.com/evanhanders/d3_stars) and in a Zenodo repository (?).

B. FROM MESA TO DEDALUS

We use a $15 M_\odot$ ZAMS MESA stellar model to construct our background stratification. From this model,

we load the radial profiles of the mass m , radial coordinate r , density ρ , pressure P , temperature T , energy generation rate per unit mass ϵ , opacity κ , logarithmic temperature gradient $\nabla = d \ln T / d \ln P$, adiabatic temperature gradient ∇_{ad} , $\chi_\rho = (d \ln P / d \ln \rho)|_T$, $\chi_T = (d \ln P / d \ln T)|_\rho$, Brunt-Väisälä frequency N^2 , specific heat at constant pressure c_P , luminosity L_* , convective luminosity fraction $f_L = L_{\text{conv}}/L_*$, and sound speed c_s . We secondarily calculate

$$\frac{d \ln P}{dr} = -\frac{\rho g}{P}, \quad (\text{B5})$$

$$\frac{d \ln \rho}{dr} = \frac{d \ln P}{dr} \frac{\chi_T}{\chi_\rho} (\nabla_{\text{ad}} - \nabla) - \frac{g}{c_s^2}, \quad (\text{B6})$$

$$\frac{d \ln T}{dr} = \frac{d \ln P}{dr} \nabla, \quad (\text{B7})$$

and we define $L_{\text{conv}} = L_* f_L$ and $dT/dr = T d \ln T / dr$ and gravitational acceleration $g = Gm/r^2$ and specific entropy gradient $ds/dr = c_P N^2 / g$. We calculate the radiative conductivity,

$$k_{\text{rad}} \equiv \frac{16 \sigma_{\text{SB}} T^3}{3 \rho \kappa} = \frac{L_* - L_{\text{conv}}}{4 \pi r^2 dT/dr}, \quad (\text{B8})$$

where we use the second definition because it produces a smoother profile. We define the heating function

$$\begin{aligned} \mathcal{H} &= \rho \epsilon - \frac{1}{4 \pi r^2} \frac{d}{dr} \left(-4 \pi r^2 k_{\text{rad}} \frac{dT}{dr} \right) \\ &= \frac{1}{4 \pi r^2} \left[\frac{dL_*}{dr} - \frac{d}{dr} \left(-4 \pi r^2 k_{\text{rad}} \frac{dT}{dr} \right) \right] \end{aligned} \quad (\text{B9})$$

We find that the second equality produces a smoother profile than the first quantity, but use the first quantity (with $\rho \epsilon$) for the innermost radial points where the numerical derivative of L_* is less well-defined. We nondimensionalize using $L_{\text{nd}} = 8.21 \times 10^{10}$ cm, $T_{\text{nd}} = 3.63 \times 10^7$ K, $m_{\text{nd}} = 4.30 \times 10^{33}$ g, and $\tau_{\text{nd}} = 4.66 \times 10^5$ s.

Given this nondimensionalization and these MESA profiles, we control the turbulence and resolution requirement of a simulation by specifying a nondimensional viscosity ν_{nd} . We then compute the following nondimensional radial profiles:

1. $\chi_{\text{nd}} = (k_{\text{rad}}/[\rho c_P])(\tau_{\text{nd}}/L_{\text{nd}}^2)$. When $\chi_{\text{nd}} < \nu_{\text{nd}}$, we set $\chi_{\text{nd}} = \nu_{\text{nd}}$.
2. $\ln \rho$ is set to be $\ln[\rho(L_{\text{nd}}^3/m_{\text{nd}})]$.
3. $\ln T$ is set to be $\ln(T/T_{\text{nd}})$.
4. T is set to be T/T_{nd} .
5. ∇T is set to be $(d \ln T/dr)(L_{\text{nd}}/T_{\text{nd}})$.

$$6. \tilde{\mathcal{H}} = (H/[\rho T])(T_{\text{nd}}\tau_{\text{nd}}^3/L_{\text{nd}}^2).$$

$$7. \nabla s_0 = (ds/dr)(T_{\text{nd}}\tau_{\text{nd}}^2/L_{\text{nd}})$$

Some fields with particularly sharp transitions (e.g., ∇s_0 , \mathcal{H}) require additional smoothing. In Fig.

TODO: put fig in

, we show comparisons between the stratification felt by the Dedalus simulation and the original MESA model.

C. TRANSFORMS AND SPECTRA

All wave flux and power spectra in this work are calculated from long time series of data of our state variables projected onto a 2D sphere. Given a 3D data cube of a variable $a(t, \phi, \theta)$, we transform the data into frequency space as

$$a(t, \phi, \theta) \xrightarrow{\text{SHT}} \hat{a}_{\ell, m}(t) \xrightarrow{\text{FT}} \hat{A}_{\ell, m}(f). \quad (\text{C10})$$

We perform the spherical harmonic transform (SHT) using Dedalus. Dedalus returns two coefficient amplitudes, b_1 and b_2 , corresponding to the $\cos(m\phi)$ and $-\sin(m\phi)$ components. From these, we construct the spherical harmonic amplitude $\hat{a}_{\ell, m}(t) = b_1 + ib_2$.

We calculate the Discrete Fourier Transform using NumPy and define its normalization such that

$$\hat{A}_{\ell, m, f} = \frac{1}{N} \sqrt{\frac{8}{3}} \sum_{j=0}^{N-1} H_N(j) \hat{a}_{\ell, m}(t_j) \exp \left\{ -2\pi i \frac{jf}{N} \right\} \quad (\text{C11})$$

In this definition, $H_N(j)$ is the j th point of the Hanning window defined over N total data points, and the factor of $\sqrt{8/3}$ accounts for this window.

To calculate a power-like quantity (power spectrum, wave flux spectrum), we multiply one transformed field with the complex conjugate of another, e.g., $P_A(f) = \hat{A}^* \hat{A}$. To properly account for power in negative frequencies, we define $P_A(f) = P_A(f) + P_A(-f)$ for all $f \geq 0$.

To calculate the wave flux, we output $p = \varpi - 0.5|\mathbf{u}|^2$ and $u_r = \mathbf{u} \cdot \hat{\mathbf{e}}_r$. We take transforms per the above recipe and calculate the wave flux $W(f) = R^2 \rho(R) \hat{P}^* \hat{U}_r$, where R is the radial coordinate at which the shell is sampled.

TODO: call it wave luminosity and add 4π

D. MESA

The MESA EOS is a blend of the OPAL (Rogers & Nayfonov 2002), SCVH (Saumon et al. 1995), FreeEOS (Irwin 2004), HELM (Timmes & Swesty 2000), and PC (Potekhin & Chabrier 2010) EOSes.

Radiative opacities are primarily from OPAL (Iglesias & Rogers 1993, 1996), with low-temperature data from Ferguson et al. (2005) and the high-temperature, Compton-scattering dominated regime by Buchler & Yueh (1976). Electron conduction opacities are from Cassisi et al. (2007).

Nuclear reaction rates are from JINA REACLIB (Cyburt et al. 2010) plus additional tabulated weak reaction rates Fuller et al. (1985); Oda et al. (1994); Langanke & Martínez-Pinedo (2000). Screening is included via the prescription of Chugunov et al. (2007). Thermal neutrino loss rates are from Itoh et al. (1996).

E. DATA AVAILABILITY

The inlists and plotting scripts used in this work may be found at **Cite Github and Zenodo**.

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