view_frames Result Recorded at time: 782.480 world Broadcaster: /ground_truth_to_tf_fdcl_1294_9119137567730966097 Average rate: 527.062 Hz Most recent transform: 782.473 (0.007 sec old) Buffer length: 5.007 sec base_footprint Broadcaster: /ground_truth_to_tf_fdcl_1294_9119137567730966097 Average rate: 527.062 Hz Most recent transform: 782.473 (0.007 sec old) Buffer length: 5.007 sec base_stabilized Broadcaster: /ground_truth_to_tf_fdcl_1294_9119137567730966097 Average rate: 527.062 Hz Most recent transform: 782.473 (0.007 sec old) Buffer length: 5.007 sec base_link Broadcaster: /robot_state_publisher_fdcl_1294_3905587558651918445 Broadcaster: /robot_state_publisher_fdcl_1294_3905587558651918445 Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (782.480 sec old) Most recent transform: 0.000 (782.480 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_link laser Broadcaster: /robot_state_publisher_fdcl_1294_3905587558651918445 Broadcaster: /robot_state_publisher_fdcl_1294_3905587558651918445 Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (782.480 sec old) Most recent transform: 0.000 (782.480 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_depth_frame camera_rgb_frame Broadcaster: /robot_state_publisher_fdcl_1294_3905587558651918445 Broadcaster: /robot_state_publisher_fdcl_1294_3905587558651918445 Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (782.480 sec old) Most recent transform: 0.000 (782.480 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_depth_optical_frame camera_rgb_optical_frame