

Evanns Morales-Cuadrado

U.S. Citizen

Robotics PhD Student
Georgia Institute of Technology

CONTACT

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Github: <https://github.com/evannsm>

TECHNICAL SKILLS

- **Programming Languages:** Python, C/C++, Matlab/Simulink
- **Frameworks & Libraries:** JAX, PyTorch, acados, CasADi, ROS 2, PX4, ArduPilot
- **Development & DevOps Tools:** Docker, Continuous Integration, Git/GitHub
- **Hardware & Experimentation:** UAV assembly, repair, and deployment
- **Motion-Capture:** OptiTrack and Vicon
- **Languages:** Spanish (Native), English (Native)

EDUCATION

Georgia Institute of Technology | 2022-2027

Ph.D. in Robotics

- GPA: 4.0/4.0
- Advisor: Dr. Samuel Coogan
- Goizueta Fellow

University of Texas at Arlington | 2018-2022

Honors Bachelor of Science in Electrical Engineering

Minor in Mathematics

Minor in Physics

Certificate in Unmanned Vehicle Systems

- GPA: 3.9/4.0 Summa Cum laude
- Full National Merit Scholarship Awarded
- Electrical Engineering Honors Scholar

WORK EXPERIENCE

Graduate Research Assistant | FACTS Lab

August 2022 - Present
Atlanta, GA

Georgia Institute of Technology

- Advised by Dr. Samuel Coogan
- Implemented novel aggressive tracking control methods on quadrotor hardware
- Developed novel nonlinear control methods for safe autonomy
- Published and presented novel research at top conferences and journals in the fields of robotics and control theory

Teaching Assistant | Vertically Integrated Project in Robotics

January 2024 - Present
Atlanta, GA

Georgia Institute of Technology

- Aided professor in his instruction of this research-based course
- Provided promising undergraduates with guidance performing applied research in the field of robotics
- Taught control theoretical concepts in an accessible manner for undergraduates

Research Assistant | Autonomous Systems Lab

November 2021 - May 2022
Arlington, TX

University of Texas at Arlington

- Advised by Dr. Frank Lewis
- Received personal mentorship from a leading researcher in the field of controls and reinforcement learning (ranked 12th in the USA and 23rd in the world during my time in his lab)
- Aided graduate students on reinforcement learning research applied to quadrotor control

Teaching Assistant | Graduate-Level Intelligent Systems Course

January 2022 - May 2022
Arlington, TX

University of Texas at Arlington

- Aided professor in his instruction of the course
- Hosted review sessions for students in preparation for exams
- Gained teaching experience in a graduate-level course while still an undergraduate

	Research Assistant Dynamical Networks and Control Lab University of Texas at Arlington	October 2019 - May 2022 Arlington, TX
	<ul style="list-style-type: none"> Advised by Dr. Yan Wan Gained experience with Robot Operating System (ROS), OpenCV, and path planning Original research in learning-based minimum time and energy path-planning for multi-vehicle systems 	
SELECTED PUBLICATIONS	<p>E. Morales-Cuadrado, C. Llanes, Y. Wardi and S. Coogan, “Newton-Raphson Flow for Aggressive Quadrotor Tracking Control.” <i>2024 American Control Conference (ACC)</i></p> <p>L. Baird, E. Morales-Cuadrado, and S. Coogan, “Runtime Assurance for Uncertain Systems from Interval Signal Temporal Logic.” Submitted to IEEE Transactions on Robotics. (<i>under revision</i>)</p> <p>E. Morales-Cuadrado, L. Baird, Y. Wardi and S. Coogan, “Lightweight Tracking Control for Computationally Constrained Aerial Systems with the Newton-Raphson Method.” Submitted to IEEE Transactions on Control Systems Technology. <i>arXiv preprint available.</i> (<i>under revision</i>)</p>	
RESEARCH INTERESTS	<ul style="list-style-type: none"> Safe Autonomy Hardware Deployment Unmanned Ground and Aerial Vehicles 	<ul style="list-style-type: none"> Advanced Nonlinear Control Learning-Based Control Trajectory Generation and Planning
OPEN-SOURCE CONTRIBUTIONS	<ul style="list-style-type: none"> PX4 Autopilot: Contributed documentation improvements to the official PX4 Autopilot manual. Vicon4PX4: Developed and open-sourced a ROS 2 C++ Vicon–PX4 interface enabling external vision fusion for indoor quadrotor flight experiments; adopted and showcased by Georgia Tech’s Indoor Flight Lab as part of its official codebase. Also created a parallel package for OptiTrack motion capture systems. 	
SERVICE & LEADERSHIP	<p>Co-Founder and President of Puerto Rican Student Association Georgia Institute of Technology</p> <ul style="list-style-type: none"> Addressed the need for an organization to help Puerto Rican students feel at home and stay connected to our culture Formed a three-member co-founder board and identified a faculty advisor Raised funds for the organization and recruited members from campus Hosted professional, social, and cultural events to meet the needs of the growing Puerto Rican student population at Georgia Tech 	August 2024 - Present Atlanta, GA
HONORS AND AWARDS	<p>Top-3 Finalist at a Deep Learning Research Symposium Professor-sponsored award for novel research in deep learning and robotics</p> <p>Goizueta Fellowship at Georgia Tech Highly selective fellowship for graduate students of Latin-American descent</p> <p>Summa Cum Laude Honors at University of Texas at Arlington Exceptional academic distinction in top GPA tier for graduation honors</p> <p>Electrical Engineering Honors Scholar at University of Texas at Arlington Inaugural member of the electrical engineering honors cohort</p> <p>IEEE-HKN International Electrical Engineering Honor Society Membership Selective undergraduate society recognizing outstanding academic achievement and community service</p> <p>Chance Vought Engineering and Science Endowment Scholarship Highly selective award given annually to three recipients across the entire College of Engineering</p> <p>National Hispanic Scholar Recognition of top national performers of Latin descent on the SAT</p> <p>National Merit Scholar Recognition of top national performers on the SAT</p>	November 2023 August 2022 May 2022 December 2021 August 2021 August 2020 March 2018 March 2018