

## 14.5 Gradients of Functions of Three Variables

Let  $f(x, y, z)$  be a function of three variables  $x$ ,  $y$ , and  $z$ . Recall that in order to “graph”  $f(x, y, z)$  we would require us to have a four-dimensional coordinate system which unfortunately we can not visualize. Instead, we graph the *level surfaces* of  $f(x, y, z)$  which are obtained by setting  $f(x, y, z)$  equal to some constant  $k$ . In particular, if  $f(x, y, z) = x^2 + y^2 + z^2$ , then the level surface of  $f$  for a given constant  $k$  is  $x^2 + y^2 + z^2 = k$ , that is, the sphere of radius  $\sqrt{k}$  centered at the origin.

Analogous to the functions of two variables, we can define partial derivatives of  $f(x, y, z)$  at each point  $(a, b, c)$ ,

$$f_x(a, b, c), \quad f_y(a, b, c), \quad f_z(a, b, c),$$

by fixing two of the variables and differentiating with respect to the third. For example,

$$\left. \frac{\partial f}{\partial z} \right|_{(a, b, c)} = f_z(a, b, c) = \lim_{h \rightarrow 0} \frac{f(a, b, c+h) - f(a, b, c)}{h} = \left. \frac{d}{dz} \right|_{z=c} (f(a, b, z)).$$

**Example 17.** Find all the partial derivatives of the function  $f(x, y, z) = x^2y + yz$  at the point  $(1, 2, 3)$ .

**Solution :**

In addition to the partial derivatives, we can also define the *directional derivative* of  $f(x, y, z)$  at the point  $(a, b, c)$  in the direction of a unit vector  $\vec{u} = u_1\vec{i} + u_2\vec{j} + u_3\vec{k}$  as follows:

$$f_{\vec{u}}(a, b, c) = \lim_{h \rightarrow 0} \frac{f(a + hu_1, b + hu_2, c + hu_3) - f(a, b, c)}{h}$$

If the *gradient vector* of  $f(x, y, z)$  at the point  $(a, b, c)$  is defined as

$$\nabla f(a, b, c) = f_x(a, b, c)\vec{i} + f_y(a, b, c)\vec{j} + f_z(a, b, c)\vec{k},$$

we can rewrite the directional derivative of  $f$  at  $(a, b, c)$  in the direction of  $\vec{u} = u_1\vec{i} + u_2\vec{j} + u_3\vec{k}$  as

$$f_{\vec{u}}(a, b, c) = \nabla f(a, b, c) \cdot \vec{u} = f_x(a, b, c)u_1 + f_y(a, b, c)u_2 + f_z(a, b, c)u_3.$$

As before we have the following theorem:

**Theorem:** Let  $f(x, y, z)$  be a differentiable function at  $(a, b, c)$  with  $\nabla f(a, b, c) \neq \vec{0}$ . Then:

- (i)  $\nabla f(a, b, c)$  points in the *direction of the largest (maximum) rate of increase* of  $f$  at  $(a, b, c)$ .
- (ii) The *maximum rate of change* of  $f$  at  $(a, b, c)$  is  $\|\nabla f(a, b, c)\|$ .
- (iii)  $\nabla f(a, b, c)$  is perpendicular to the contour line of  $f(x, y, z)$  at the point  $(a, b, c)$ .

**Example 18.** Suppose that the function  $C(x, y, z) = x^2 + y^4 + x^2z^2$  gives concentration of salt, in gr/gal, at any point  $(x, y, z)$  of a rectangular tank of water occupying the region

$$-2 \leq x \leq 2, \quad -2 \leq y \leq 2, \quad 0 \leq z \leq 2,$$

(all measurements in meters). Suppose you are at the point  $(-1, 1, 1)$ .

- (a) In what direction should you move if you want the concentration to increase the fastest?
- (b) If you move from  $(-1, 1, 1)$  toward the origin  $(0, 0, 0)$ , how fast is the concentration changing?

**Solution :**

**Example 19.** Find the equation of the tangent plane to the ellipsoid  $x^2 + 2y^2 + z^2 = 15$  at  $(2, 1, 3)$ .

**Solution :**

## 14.6 Chain Rule

Recall that the [Chain Rule](#) for functions of a *single* variable gives the rule for differentiating a *composite function*: if  $y = f(x)$  and  $x = g(t)$ , where  $f$  and  $g$  are differentiable functions, the  $y$  is indirectly a differentiable function of  $t$  and

$$\frac{dy}{dt} = \frac{dy}{dx} \frac{dx}{dt}.$$

For functions of more than one variable, the Chain Rule has several versions, each of them giving a rule for differentiating a composite functions.

**Case 1:** We start by considering a special case where  $z = f(x, y)$  and each of the variables  $x$  and  $y$  is a function of another variable  $t$ , that is,  $x = g(t)$  and  $y = h(t)$ . But this implies that  $z$  is indirectly a function of ONE variable  $t$ ,  $z = f(g(t), h(t))$ , and the Chain Rule gives us the formula for differentiating  $z$  as a function of  $t$ .

**Theorem:** Suppose that  $f(x, y)$  is a differentiable function of  $x$  and  $y$ , where  $x = g(t)$  and  $y = h(t)$  are both differentiable functions of  $t$ . Then  $z$  is a differentiable function of  $t$  and

$$\frac{dz}{dt} = \frac{\partial f}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial f}{\partial y} \cdot \frac{dy}{dt}.$$

**Remark:** We now provide some intuition behind this theorem. Start by observing that a change of  $\Delta t$  in  $t$  produces changes of  $\Delta x$  in  $x$  and  $\Delta y$  in  $y$ . More specifically,

$$\Delta x = g(t + \Delta t) - g(t) \quad \text{and} \quad \Delta y = h(t + \Delta t) - h(t).$$

These changes in turn produce a change of  $\Delta z$  in  $z$  which due to the fact that  $z = f(x, y)$  is a differentiable function can be approximated by

$$\Delta z \approx \frac{\partial f}{\partial x} \cdot \Delta x + \frac{\partial f}{\partial y} \cdot \Delta y. \quad (14.5)$$

Dividing the both sides of equation (14.5) gives

$$\frac{\Delta z}{\Delta t} \approx \frac{\partial f}{\partial x} \cdot \frac{\Delta x}{\Delta t} + \frac{\partial f}{\partial y} \cdot \frac{\Delta y}{\Delta t}. \quad (14.6)$$

If  $\Delta t \rightarrow 0$ , then

$$\frac{\Delta x}{\Delta t} = \frac{g(t + \Delta t) - g(t)}{\Delta t} \longrightarrow \frac{dx}{dt} \quad \text{and} \quad \frac{\Delta y}{\Delta t} = \frac{h(t + \Delta t) - h(t)}{\Delta t} \longrightarrow \frac{dy}{dt}.$$

Thus, by letting  $\Delta t \rightarrow 0$  we obtain the “infinitesimal” version of equation (14.6)

$$\frac{dz}{dt} \approx \frac{\partial f}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial f}{\partial y} \cdot \frac{dy}{dt}. \quad (14.7)$$

**Example 20.** If  $z(x, y) = x^2y + 3xy^4$ , where  $x = \sin(2t)$  and  $y = \cos(t)$ , find  $dz/dt$  when  $t = 0$ .

**Solution :**

**Case 2:** For our next case, we consider the situation where  $z = f(x, y)$ , but BOTH  $x$  and  $y$  are now functions of TWO variables  $u$  and  $v$ , namely,  $x = g(u, v)$  and  $y = h(u, v)$ . Then  $z$  is indirectly a function of two variables  $u$  and  $v$  and we wish to determine  $\partial z/\partial u$  and  $\partial z/\partial v$ . Recall that in computing  $\partial z/\partial u$  we hold  $v$  fixed and compute the ordinary derivative of  $z$  with respect to  $u$ . Therefore, by applying the previous theorem we obtain

$$\frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial u}$$

A similar argument holds for  $\partial z/\partial v$ , which leads us to the following result:

**Theorem:** Suppose that  $f(x, y)$  is a differentiable function of  $x$  and  $y$ , where  $x = g(u, v)$  and  $y = h(u, v)$  are both differentiable functions of  $u$  and  $v$ . Then:

$$\frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial u}$$

$$\frac{\partial z}{\partial v} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial v}$$

**Example 21.** If  $z(x, y) = e^x \sin(y)$ , where  $x(u, v) = u \cdot v^2$  and  $y(u, v) = u^2 \cdot v$ , then find  $\frac{\partial z}{\partial u}$  and  $\frac{\partial z}{\partial v}$ .

**Solution :**

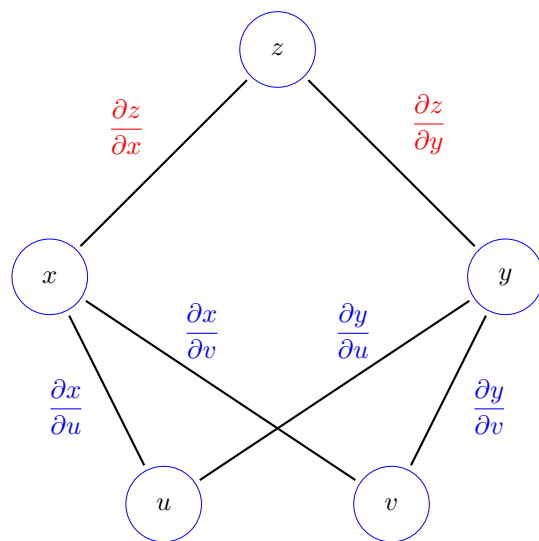
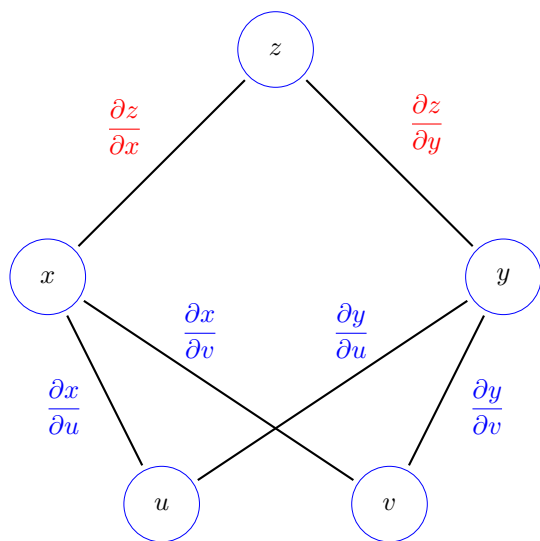
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**Question:** Now that we have experience with computing with the Chain Rule, is there an easier way to remember it???

**Answer:** For illustration purposes, we will assume that  $z = z(x, y)$  and  $x = g(u, v)$  and  $y = h(u, v)$ . Now consider a diagram consisting of three levels – main function  $z$ , variables  $x$  and  $y$ , and finally, variables  $u$  and  $v$ .

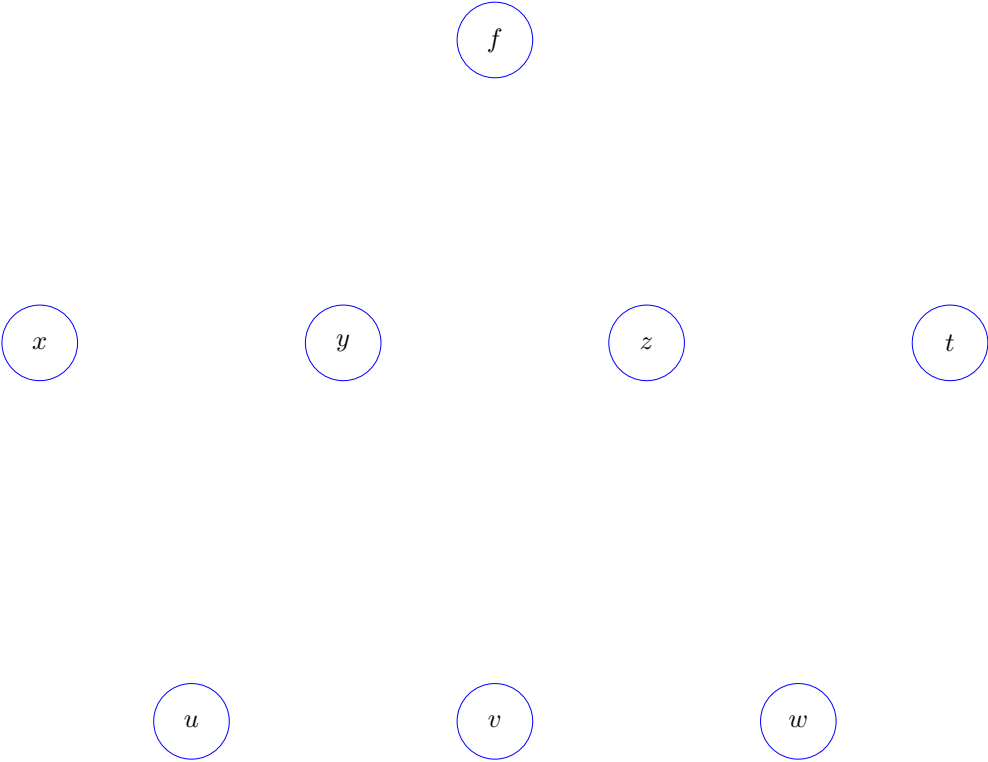


**Example 22.** *(not in our textbook!!) For a function  $f(x, y, z, t)$ , where*

$$\begin{aligned}x &= x(u, v, w), \\ y &= y(u, v), \\ z &= z(u, w), \\ t &= t(u),\end{aligned}$$

*find the general expressions for  $\frac{\partial f}{\partial u}$  and  $\frac{\partial f}{\partial w}$ .*

**Solution :**





**Example 23.** Use the Chain Rule to find  $\frac{\partial w}{\partial \rho}$  and  $\frac{\partial w}{\partial \theta}$ , given that

$$w(x, y, z) = x^2 + y^2 + z^2 \quad (14.8)$$

and

$$x = \rho \cdot \sin(\phi) \cdot \cos(\theta); \quad y = \rho \cdot \sin(\phi) \cdot \sin(\theta); \quad z = \rho \cdot \cos(\theta). \quad (14.9)$$

**Solution :**



## 14.7 Second Order Partial Derivatives

Given  $z = f(x, y)$  each partial derivative

$$\frac{\partial z}{\partial x} = f_x(x, y), \quad \frac{\partial z}{\partial y} = f_y(x, y),$$

is again a function of  $(x, y)$ . As such, one can also take their partial derivatives. *Partial derivatives of partial derivatives* are called **second-order partial derivatives**. We denote them as follows:

$$(f_x)_x = f_{xx} = \frac{\partial}{\partial x} \left[ \frac{\partial f}{\partial x} \right] = \frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} [f_x(x, y)]$$

$$(f_x)_y = f_{xy} = \frac{\partial}{\partial y} \left[ \frac{\partial f}{\partial x} \right] = \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} [f_x(x, y)]$$

$$(f_y)_x = f_{yx} = \frac{\partial}{\partial x} \left[ \frac{\partial f}{\partial y} \right] = \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} [f_y(x, y)]$$

$$(f_y)_y = f_{yy} = \frac{\partial}{\partial y} \left[ \frac{\partial f}{\partial y} \right] = \frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} [f_y(x, y)]$$

**Terminology:** For a function  $z = f(x, y)$ , the second-order partial derivatives  $f_{xy}$  and  $f_{yx}$  are called **mixed partials**.

**Example 24.** Let  $f(x, y) = x^3 + x^2y^2 - y^4$ . Find all second-order partial derivatives of  $f(x, y)$ . **Solution :**

**Clairaut's Theorem:** (XVIII century) – (name of this theorem is not in our textbook)

Let  $f(x, y)$  be a function with domain  $\mathcal{D}$ . If all partial derivatives of  $f(x, y)$  up to the second order are continuous at an interior point  $(a, b)$  of the domain, then

$$f_{xy}(a, b) = f_{yx}(a, b) .$$

**Key Point:** Under some mild conditions on  $f(x, y)$ , the *mixed partial derivatives of  $f$  are equal*.

As is the case with second derivatives of a *single variable* function, there are many uses for the second-order partial derivatives:

- Second Derivative Test for Local Extrema (Ch. 15)
- Taylor approximations of order two
- ...

Recall that so far we have seen **Taylor Polynomial of Degree ONE** that approximates  $f(x, y)$  for all  $(x, y)$  near  $(a, b)$ :

$$f(x, y) \approx L(x, y) = f(a, b) + f_x(a, b) \cdot (x - a) + f_y(a, b) \cdot (y - b) .$$

### Second Degree Taylor Polynomial for $f(x, y)$ near $(a, b)$

Let  $f(x, y)$  be such that all second-order partial derivatives are continuous at the point  $(a, b)$ . Then the **Taylor polynomial of degree TWO** of  $f(x, y)$  near  $(a, b)$  is given by

$$\begin{aligned} Q(x, y) = & f(a, b) + f_x(a, b) \cdot (x - a) + f_y(a, b) \cdot (y - b) + \dots \\ & \dots + \frac{1}{2} f_{xx}(a, b) \cdot (x - a)^2 + f_{xy}(a, b) \cdot (x - a) \cdot (y - b) + \frac{1}{2} f_{yy}(a, b) \cdot (y - b)^2. \end{aligned}$$

**Remark:** This idea can be quite easily extended to functions of three, four, ... variables, but it requires using tools from linear algebra/matrix theory.

**Example 25.** Find the quadratic Taylor polynomial about  $(0, 0)$  for the function

$$f(x, y) = (y - 1)(x + 1)^2.$$

**Solution :** We start by computing appropriate partial derivatives:

$$f_x(x, y) = \qquad \qquad \qquad f_x(0, 0) =$$

$$f_{xx}(x, y) = \qquad \qquad \qquad f_{xx}(0, 0) =$$

$$f_{xy}(x, y) = \qquad \qquad \qquad f_{xy}(0, 0) =$$

$$f_y(x, y) = \qquad \qquad \qquad f_y(0, 0) =$$

$$f_{yy}(x, y) = \qquad \qquad \qquad f_{yy}(0, 0) =$$

$$f_{yx}(x, y) = \qquad \qquad \qquad f_{yx}(0, 0) =$$

Many physical systems are readily described by *partial differential equations* in which derivatives of an unknown function are related to one another and/or to the function itself. For example, the **Laplace Equation**

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

can be used to model equilibrium temperature distribution in *planar* region or shape of a soap film suspended on a wire frame.

**Example 26.** Show that  $u(x, y) = \ln(x^2 + y^2)$  is a solution to the Laplace's equation.

**Example 27.** Verify that  $f(t, x) = \cos^2(t + x) + e^{e^{\sin(t+x)}}$  is a solution of the *transport equation*  $f_t(t, x) = f_x(t, x)$  (this equation models the concentration of a substance flowing in a fluid at a constant rate).

**Example 28.** Show that  $f(t, x) = \sin(x - t) + \sin(x + t)$  satisfies the *wave equation*  $f_{tt}(t, x) = f_{xx}(t, x)$  (this equation governs the motion of light or sound).

**Example 29.** Show that  $f(t, x) = \frac{1}{\sqrt{t}} e^{-x^2/(4t)}$  satisfies the *heat equation*  $f_t(t, x) = f_{xx}(t, x)$  (this equation describes diffusion of heat or spread of an epidemic).