

MODELING THE MODELER: A NORMATIVE THEORY OF EXPERIMENTAL DESIGN

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- ◇ Decision theoretic analysis of experiments: analyst's preference over experiments
- ◇ The value of an exp is determined by what it allows to identify
- ◇ In principle any kind of experiment, but adapt the analysis to *revealed preference*
 - ◇ Laboratory economics experiments
 - ◇ Any agent who can probe at the preference of other agents

- ◇ We propose three normative principles for experimental design
 - ◇ minimal rationality properties, independent of specific motivations
 - ◇ We will specifically think about revealed preference experiments
- ◇ We show that they imply a particular representation
 - ◇ Relates an experiment to the expected value of identification
 - ◇ Unifies many distinct models of experimentation
 - ◇ Axiomatic characterization for Bayesian Experimental Design
 - ◇ Test for analyst to make sure they do not have an “agenda”

- ◇ A space of parameters \mathcal{U}
- ◇ Experiment A has possible observable outcomes $\{P_1, \dots, P_n\}$
- ◇ Observing P *identifies* a set of parameters:
 - ◇ $W_{A,P} \subseteq \mathcal{U}$ consistent with observation
- ◇ An “ideal” experiment should induce a partition over \mathcal{U}
 - ◇ Not always possible (some parameters might not uniquely determine an observation)

Ranking over experiments should reflect the value of potential identification

Normative Principles

Structural Invariance: Two experiments that identify the sets of parameters are equally valued

Information Monotonicity: Experiments that induce sharper identification are (weakly) better

Identification Separability: The value of identifying a set of parameters should *not* depend on counterfactuals

Expected Identification Value

These principles characterize ranking according to *expected identification value*

- ◇ Exists some τ : for $W \subseteq \mathcal{U}$, $\tau(W)$ is the value of identifying W
- ◇ Experiments are valued according to:

$$F(A, \mathcal{P}) = \sum_{P \in \mathcal{P}} \tau(W_{A,P}) \mu(W_{A,P})$$

- ◇ where μ is the (exogenous) prior probability

Special Case: Entropy

$$\tau(W) = -\log(\mu(W))$$

- ◇ Value of experiment is expected reduction in entropy

Special Case: Hypothesis Testing

$$\tau(W) = \begin{cases} 1 & \text{if } W \subseteq W^* \text{ or } W^* \subseteq W^c \\ 0 & \text{otherwise.} \end{cases}$$

- ◇ Hypothesis: the parameter lies in W^*
- ◇ Value of exp is the probability the hypothesis can be accepted or rejected

Special Case: Actions

$$\tau(W) = \max_{a \in \mathbb{A}} \int_W \xi(a, u) d\mu.$$

- ◇ The analyst will take action $a \in \mathbb{A}$
- ◇ Utility of outcome depends on the parameter: $\xi(a, u)$
- ◇ Value of exp is expected value of conditionally optimal action

Related literature

Decision Theory

- ◇ Dekel, Lipman and Rustichini (2001) “Representing Preferences with a Unique Subjective State Space”
- ◇ Gilboa and Lerher (1991) “The value of information-An axiomatic approach”
- ◇ Ergin and Sarver (2015) “Hidden actions and preferences for timing of resolution of uncertainty”

Statistics

- ◇ Lindley (1972) “Bayesian statistics: A review”
- ◇ Chaloner and Verdinelli (1995) “Bayesian experimental design: A review”



An analyst (she) wishes to infer a subject's (he) utility function over Z :

- ◇ Revealed Preference: she should offer a menu $A \subseteq Z$ and observe the subject's choice
- ◇ Different menus offer different “inference” opportunities
- ◇ Ranking over menus will depend on the goals for the analyst

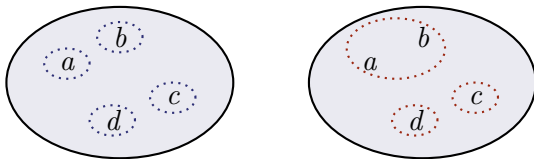
Experimental Environment

- ◇ Z set of alternatives
- ◇ $\mathcal{U} \subseteq \{u : Z \rightarrow \mathbb{R}\}$ set of utility functions over Z
- ◇ Ω algebra of measurable sets of \mathcal{U}
- ◇ μ prior over (\mathcal{U}, Ω)

The tuple $(Z, \mathcal{U}, \Omega, \mu)$ constitutes a theory for a Bayesian experimenter

An **experiment** $e = (A, \mathcal{P})$ is a pair:

- ◇ $A \subseteq Z$ is finite decision problem
- ◇ \mathcal{P} is a partition of A



- ◇ Represents observability constraints
- ◇ Allows for dynamic experiments, non-lab settings, etc

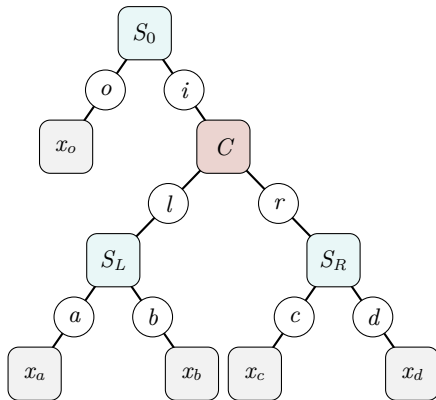
Example: Dynamic Games

Consider a dynamic game:

- ◇ Computer randomizes 50-50
- ◇ Subject's strategies:

$$A = \left\{ \begin{array}{l} (i, a, c), (i, b, c), (i, a, d), (i, b, d), \\ (o, a, c), (o, a, d), (o, b, c), (o, b, d) \end{array} \right\}$$

- ◇ There are observable paths:
 (o) , (i, a) , (i, b) , (i, c) , and (i, d)

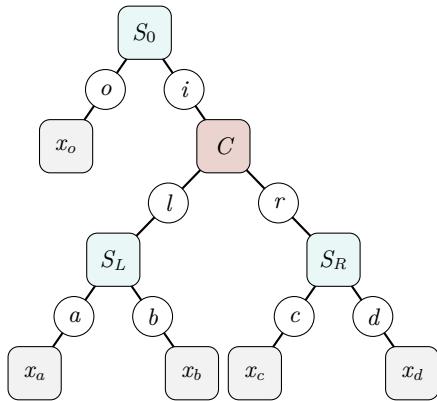


Example: Dynamic Games

Now consider the following partitions of A

$$\mathcal{P}_L = \left\{ \begin{array}{l} \left\{ (o, a, c), (o, b, c), \right. \\ \left. (o, a, d), (o, b, d) \right\}, \\ \left\{ (i, a, c), (i, a, d) \right\}, \\ \left\{ (i, b, c), (i, b, d) \right\} \end{array} \right\}$$

$$\mathcal{P}_R = \left\{ \begin{array}{l} \left\{ (o, a, c), (o, b, c), \right. \\ \left. (o, a, d), (o, b, d) \right\}, \\ \left\{ (i, a, c), (i, b, c) \right\}, \\ \left\{ (i, a, d), (i, b, d) \right\} \end{array} \right\}$$



Given an experiment, (A, \mathcal{P}) , define the *identified set*:

$$W_{A,P} = \{u \in \mathcal{U} \mid P \cap \operatorname{argmax}_{x \in A} u(x) \neq \emptyset\}$$

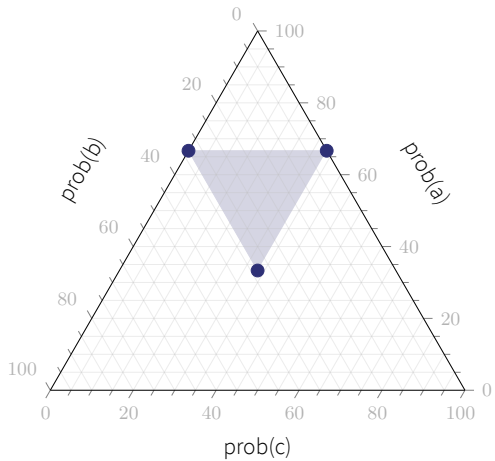
- ◇ Observing $P \in \mathcal{P}$ identifies that the subject's utility is in $W_{A,P}$
- ◇ We require for an experiment (A, \mathcal{P}) that for any $P, Q \in \mathcal{P}$
 - (1) $W_{A,P} \in \Omega$ — measurability
 - (2) $\mu(W_{A,P} \cap W_{A,Q}) = 0$ — zero μ -prob of ties

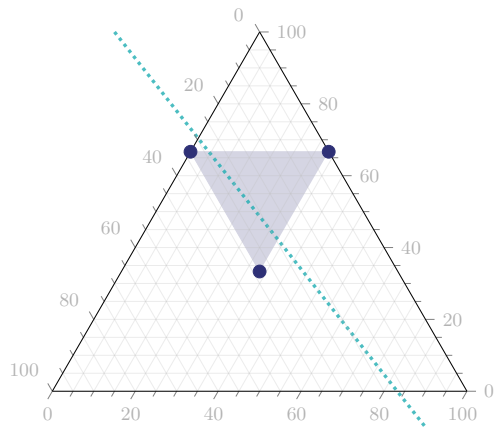
Example: EU Preferences

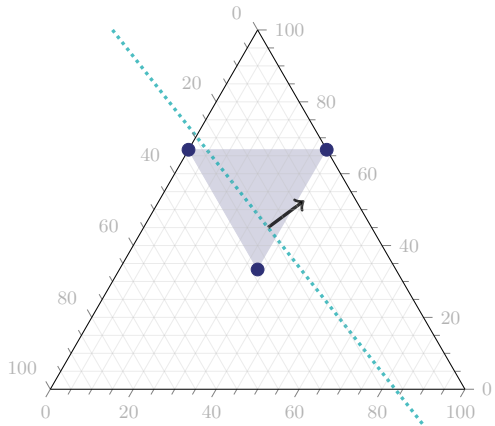
We can example identifying EU preferences as an example:

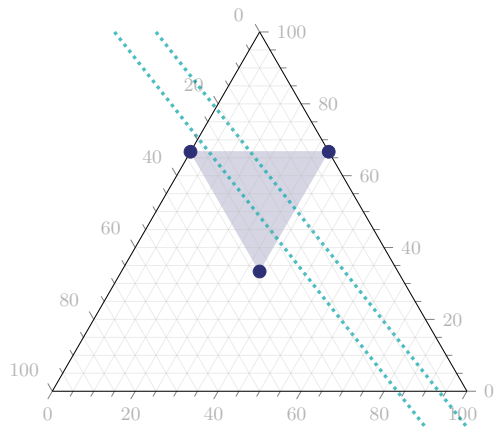
- ◇ Z is lotteries over $\{a, b, c\}$
- ◇ \mathcal{U} is affine functions

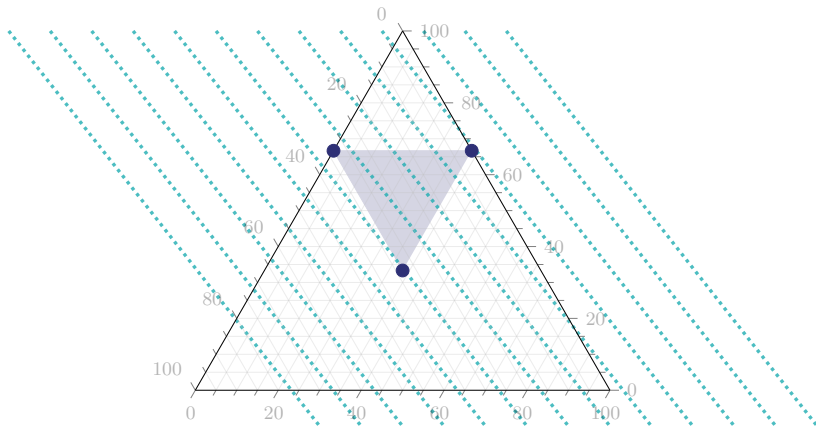
$$\{\frac{2}{3}a + \frac{1}{3}b, \frac{2}{3}a + \frac{1}{3}c, \frac{1}{3}a + \frac{1}{3}b + \frac{1}{3}c\}$$

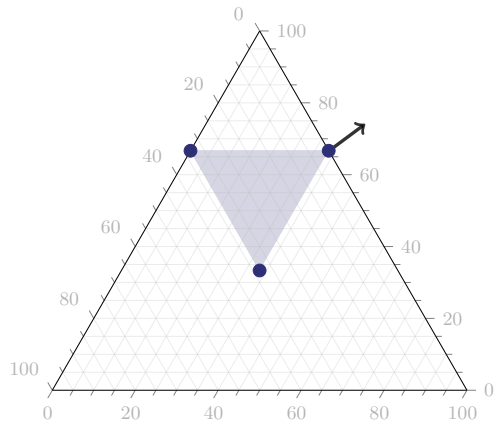


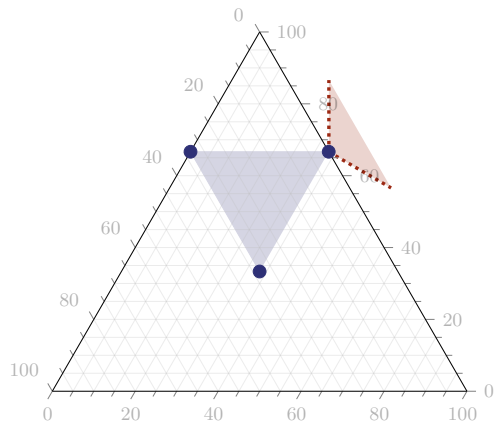


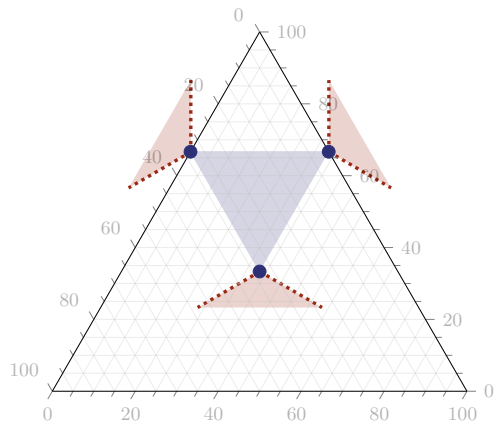




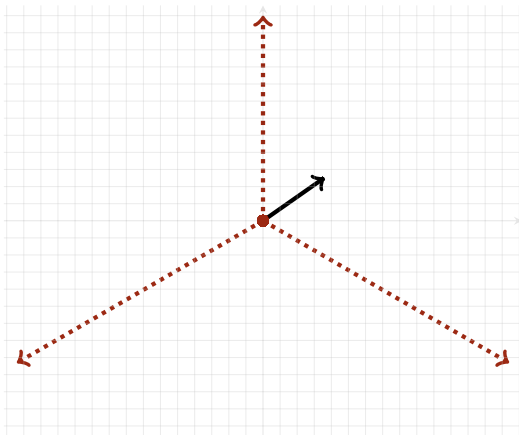








$$\mathcal{U} \cong \mathbb{R}^2$$



μ -equivalence

Call $\{W_1, \dots, W_n\}$ and $\{V_1, \dots, V_m\}$, families of subsets of \mathcal{U} , μ -*equivalent* if for all W_i and V_j :

$$\begin{aligned}\mu(W_i) &= \mu(W_i \cap V_j) \text{ for some } j \quad \text{and,} \\ \mu(V_j) &= \mu(W_i \cap V_j) \text{ for some } i\end{aligned}$$

- ◇ Such collections identify the same sets of utilities up to a measure zero
- ◇ Take $[0, 1]$ with λ the Lebesgue measure. The following are λ -equivalent:
 - ◇ $\{[0, \frac{1}{2}), (\frac{1}{2}, 1]\}; \quad \{[0, \frac{1}{2}), \{\frac{1}{2}\}, (\frac{1}{2}, 1]\}, \quad \{[0, \frac{1}{2}], [\frac{1}{2}, 1]\}$

Rich Experimental Settings

We say a set of experiments \mathbb{E} is *rich* if

- (1) $(A, \mathcal{P}) \in \mathbb{E} \rightarrow (A, \mathcal{Q}) \in \mathbb{E}$ whenever \mathcal{Q} is a coarsening of \mathcal{P}
- (2) For any finite Ω -measurable partition of \mathcal{U} , there exists an experiment (A, \mathcal{P}) such that $\{W_{A,P}\}_{P \in \mathcal{P}}$ is μ equivalent
 - ◇ Any partition can be approximated up to 0 probability events
 - ◇ For the EU model, the set of all experiments is rich for any “regular” μ

Primitive

- ◇ Our primitive is a ranking \succsim over the set of all random experiments
- ◇ A *random experiment* is a lottery over some (fixed) rich set \mathbb{E}



❖ *Normative Principles* ❖

“Two experiments that identify the sets of parameters are equally valued”

(P1) - Structural Invariance

If $\{W_{A,P} | P \in \mathcal{P}\}$ is μ -equivalent to $\{W_{B,Q} | Q \in \mathcal{Q}\}$ then $(A, \mathcal{P}) \sim (B, \mathcal{Q})$.

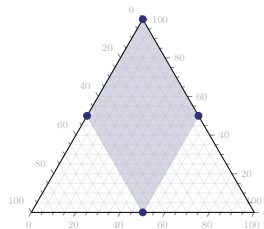
- ◇ Structural properties of experiments are irrelevant
- ◇ Also, 0-probability events are irrelevant

Consider our EU maximizing subject choosing lotteries over $\{a, b, c\}$.

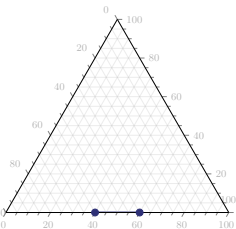
$$\begin{aligned}\text{EXP A : } A &= \{a, \tfrac{1}{2}a + \tfrac{1}{2}b, \tfrac{1}{2}a + \tfrac{1}{2}c, \tfrac{1}{2}b + \tfrac{1}{2}c\} \\ A' &= \{\tfrac{6}{10}b + \tfrac{4}{10}c, \tfrac{4}{10}b + \tfrac{6}{10}c\}.\end{aligned}$$

$$\begin{aligned}\text{EXP B : } B &= \{a, b, c\} \\ B' &= \{\tfrac{2}{3}a + \tfrac{1}{3}b, \tfrac{2}{3}a + \tfrac{1}{3}c, \tfrac{1}{3}a + \tfrac{1}{3}b + \tfrac{1}{3}c\}.\end{aligned}$$

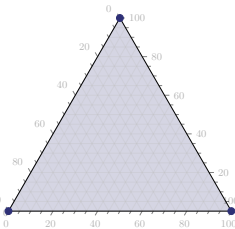
$$A = \{a, \frac{1}{2}a + \frac{1}{2}b, \frac{1}{2}a + \frac{1}{2}c, \frac{1}{2}b + \frac{1}{2}c\}$$



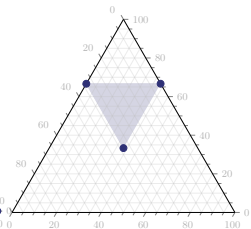
$$A' = \{\frac{6}{10}b + \frac{4}{10}c, \frac{4}{10}b + \frac{6}{10}c\}$$



$$B = \{a, b, c\}$$



$$B' = \{\frac{2}{3}a + \frac{1}{3}b, \frac{2}{3}a + \frac{1}{3}c, \frac{1}{3}a + \frac{1}{3}b + \frac{1}{3}c\}$$

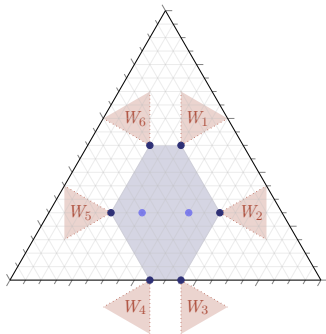


- ◇ Linearity states that

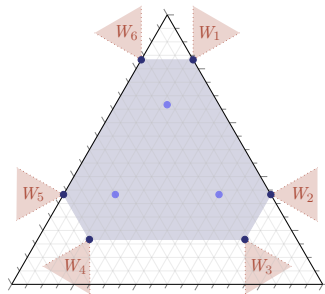
$$\left. \begin{array}{l} x \in \arg \max_A u(\cdot) \\ y \in \arg \max_B u(\cdot) \end{array} \right\} \quad \text{if and only if} \quad \alpha x + (1 - \alpha)y \in \arg \max_{\alpha A + (1 - \alpha)B} u(\cdot)$$

- ◇ Therefore, observing A followed by A' is equivalent to observing $\frac{1}{2}A + \frac{1}{2}A'$

$$\frac{1}{2}A + \frac{1}{2}A'$$



$$\frac{1}{2}B + \frac{1}{2}B'$$



- ◇ Structural invariance reflects the symmetries of the given domain
- ◇ With linear utility, the symmetry is *translation invariance*:

Structural Invariance for Expected Utility

$$(A, \{P_1, \dots, P_n\}) \sim (A + B, \{P_1 + B, \dots, P_n + B\})$$

This isn't exactly correct, since $\{P_1 + B, \dots, P_n + B\}$ might have overlaps....

“Experiments that induce sharper identification are (weakly) better”

(P2) - Information Monotonicity

If \mathcal{P} refines \mathcal{Q} then $(A, \mathcal{P}) \succsim (A, \mathcal{Q})$.

- ◇ Preference respects Blackwell order

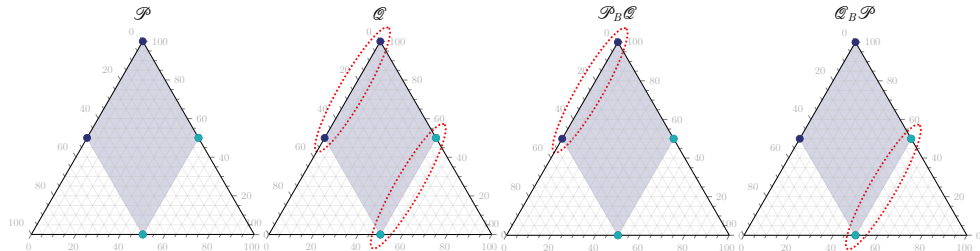
“The value of identification not depend on counterfactuals”

(P3) - Identification Separability

$$\frac{1}{2}(A, \mathcal{P}) + \frac{1}{2}(A, \mathcal{Q}) \sim \frac{1}{2}(A, \mathcal{P}_B \mathcal{Q}) + \frac{1}{2}(A, \mathcal{Q}_B \mathcal{P}).$$

- ◇ \mathcal{P} and \mathcal{Q} partitions of A and $B \subseteq A$, then $\mathcal{P}_B \mathcal{Q}$ denotes the partition that coincides with \mathcal{P} over B and with \mathcal{Q} over $A \setminus B$

Consider decision problem A (from before) with the following partitions



- ◇ The set B is the two south-east lotteries (in teal)

Theorem

Let \succsim be an expected utility preference, represented by index $F : \mathbb{E} \rightarrow \mathbb{R}$.

Then \succsim satisfies **P1-3** if and only if there exists a $\tau : \Omega \rightarrow \mathbb{R}$ such that:

$$F(A, \mathcal{P}) = \sum_{P \in \mathcal{P}} \tau(W_{A,P}) \mu(W_{A,P})$$

with $W \subseteq V$ implies

- ◇ $\tau(W) \mu(W|V) + \tau(V \setminus W) (1 - \mu(W|V)) \geq \tau(V)$
- ◇ $\mu(W) = \mu(V)$ implies $\tau(W) = \tau(V)$

Representation reflects our normative principles:

$$F(A, \mathcal{P}) = \sum_{P \in \mathcal{P}} \tau(W_{A,P}) \mu(W_{A,P})$$

- ◇ Only depends on $W_{A,P} \rightarrow$ Structural Invariance
- ◇ Additive \rightarrow Identification Separability
- ◇ $\tau(W)\mu(W|V) + \tau(V \setminus W)(1 - \mu(W|V)) \geq \tau(V)$ Monotonicity



- ◇ Entropy is a common measure of information
- ◇ Entropy of a probability measure is

$$- \sum_{x \in \text{supp}(\mu)} \log(\mu(x)) \mu(x)$$

- ◇ The experimenter's value for an experiment is the (expected) entropy of the induced identification

$$F(A, \mathcal{P}) = - \sum_{P \in \mathcal{P}} \log(\mu(W_{A,P})) \mu(W_{A,P})$$

We can specialize each of the normative principals to this context

Structural Invariance for Entropy: Symmetry

Fix $(A, \{P_1, \dots, P_n\})$ and $(B, \{Q_1, \dots, Q_n\})$. Then if for all $i \leq n$,

$$|\mu(W_{B, Q_i}) - \frac{1}{n}| \geq |\mu(W_{A, P_i}) - \frac{1}{n}|$$

it follows that

$$(A, \{P_1 \dots P_n\}) \succcurlyeq (B, \{Q_1 \dots Q_n\}).$$

- ◇ implies structural invariance:

- ◇ Fix $(A, \mathcal{P} = \{P_1, \dots, P_n\})$ and let $\mathcal{P}^1 = \{P_1^1, \dots, P_k^1\}$ partition P_1 .
- ◇ Then $\mathcal{P}^\dagger = \{P_1^1, \dots, P_k^1, P_2, \dots, P_n\}$ is also partition of A .
 - ◇ As if observing \mathcal{P} and then if P_1 is realized, further observing \mathcal{P}^1
 - ◇ \mathcal{P} observed with prob 1, \mathcal{P}^1 observed with probability $\mu(W_{A, \mathcal{P}^1})$
- ◇ Let $(B, \mathcal{Q} = \{Q_1, \dots, Q_k\})$ with $\mu(W_{B, Q_i}) = \mu(W_{A, P_i^1} \mid W_{A, P_1})$
 - ◇ Observing \mathcal{Q} has same ‘informational content’ as observing \mathcal{P}^1 conditional on realization of P_1

(A, \mathcal{P})

P_1	P_2	P_3	P_4
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(A, \mathcal{P})	P_1	P_2	P_3	P_4
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(A, \mathcal{P}^\dagger)	P_1^1	P_2^1	P_3^1	P_2	P_3	P_4
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(A, \mathcal{P})	P_1	P_2	P_3	P_4
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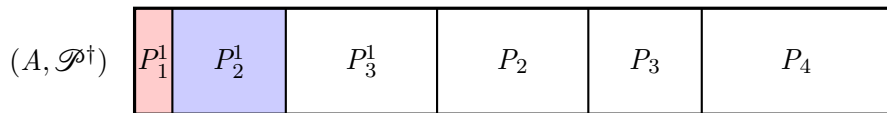
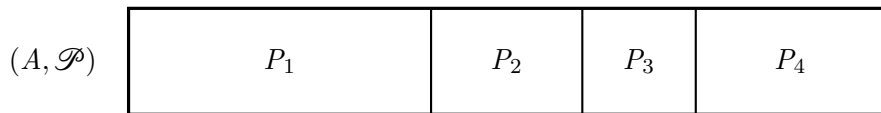
(A, \mathcal{P}^\dagger)	P_1^1	P_2^1	P_3^1	P_2	P_3	P_4
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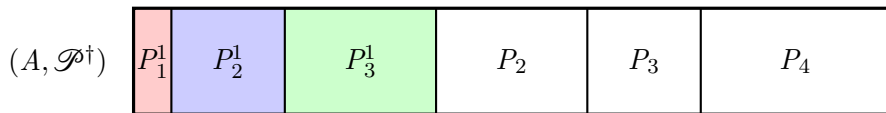
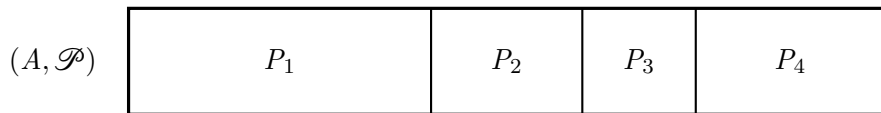
(B, \mathcal{Q})	Q_1	Q_2	Q_3
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(A, \mathcal{P})	P_1	P_2	P_3	P_4
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(A, \mathcal{P}^\dagger)	P_1^1	P_2^1	P_3^1	P_2	P_3	P_4
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(B, \mathcal{Q})	Q_1	Q_2	Q_3
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Option 1

- ◇ Observe \mathcal{P}^\dagger with prob α
- ◇ Observe nothing with prob $(1-\alpha)$

Option 2

- ◇ Observe \mathcal{P} with prob α
- ◇ Observe \mathcal{Q} with prob $(1-\alpha)$

- ◇ To be indifferent α must capture the likelihood of reviving extra information
- ◇ This is $\alpha = \frac{1}{1+\mu(W_{A,P_1})}$

Identification Separability for Entropy

Fix $(A, \mathcal{P} = \{P_1, \dots, P_n\})$ and $\mathcal{P}^\dagger = \{P_1^1, \dots, P_k^1, P_2, \dots, P_n\}$.

Set $\alpha = \frac{1}{1 + \mu(W_{A, P_1})}$.

Then if $(B, \{Q_1, \dots, Q_k\})$ is such that $\mu(W_{B, Q_i}) = \mu(W_{A, P_i^1} \mid W_{A, P_1})$, it follows that

$$\alpha(A, \mathcal{P}^\dagger) + (1 - \alpha)(A, \{A\}) \sim \alpha(A, \mathcal{P}) + (1 - \alpha)(B, \mathcal{Q})$$

- ◇ implies identification separability

Theorem

Let \succsim be an expected utility preference.

Then \succsim satisfies the entropic versions of **P1-3** if and only if

$$F(A, \mathcal{P}) = - \sum_{P \in \mathcal{P}} \log(\mu(W_{A,P})) \mu(W_{A,P})$$

is an utility index for \succsim

