



Modeling the Modeler:

A Normative Theory of Experimental Design

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An experimenter seeks to learn about a subject:

- ◊ has a theory about how subjects makes choices, conditional on their type
 - ◊ type =_{def} parameters of preference / beliefs / whatever drives choices
- ◊ provides experiments to the subject, observes outcome
 - ◊ experiment =_{def} a choice problem, from which the subject's behavior is observed

Our paper: how should the experimenter's goals (and her theory of behavior) determine her valuation of experiments

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Deceitful: Uninterested in truth, only wishes to validate hypothesis

- ◊ We offer a framework unifying the many goals of experimentation
- ◊ We propose three normative principles for how to rank experiments
 - ◊ minimal rationality properties, independent of specific motivations
- ◊ We show that they imply a particular representation
 - ◊ Relates an experiment to the expected value of identification
 - ◊ Provides a recipe for choosing experiments
 - ◊ Distinguish between various ‘types’ of experimenters
 - ◊ Test to ensure experimenter does not have an ‘agenda’

- ◊ A space of choice parameters Θ
- ◊ A (costly) experiment A has
 - ◊ possible observable outcomes $\mathcal{P} = \{P_1, \dots, P_n\}$
 - ◊ cost on implementation $c \geq 0$
- ◊ Observing $P \in \mathcal{P}$ *partially identifies* a set of parameters:
 - ◊ $W_{A,P} \subseteq \Theta$ consistent with observation

Normative Principles



Structural Invariance: Prefer the least costly implementation of a given identification of parameters

Information Monotonicity: (Weakly) prefer experiments that induce sharper identification

Identification Separability: Consider only the elements of experiments that can be controlled

Expected Identification Value



These principles characterize *expected identification value* maximization

- ◊ Exists some τ : for $W \subseteq \Theta$, $\tau(W)$ is the value of identifying W
- ◊ Experiment (A, \mathcal{P}, c) is valued according to:

$$\sum_{P \in \mathcal{P}} \tau(W_{A,P}) \mu(W_{A,P}) - c$$

- ◊ where μ is the (exogenous) prior probability

Special Case: Entropy



$$\tau(W) = -\log(\mu(W))$$

- ◊ Value of experiment is expected reduction in entropy
- ◊ Exp is valued proportional to information gain
- ◊ ‘Information Maximizing’ experimenter

Special Case: Hypothesis Testing



$$\tau(W) = \begin{cases} 1 & \text{if } W \subseteq W^* \text{ or } W^* \subseteq W^c \\ 0 & \text{otherwise.} \end{cases}$$

- ◊ Hypothesis: the parameter lies in W^*
- ◊ Value of \exp is the probability the hypothesis can be accepted or rejected
- ◊ ‘Theory Testing’ experimenter

Special Case: Actions



$$\tau(W) = \max_{\alpha \in \mathbb{A}} \int_{\theta \in W} \xi(\alpha, \theta) d\mu.$$

- ◊ The analyst will take action $\alpha \in \mathbb{A}$
- ◊ Utility of outcome depends on the parameter: $\xi(a, \theta)$
- ◊ Value of exp is expected value of conditionally optimal action
- ◊ ‘Profit Seeking’ experimenter



Experimental Paradigms

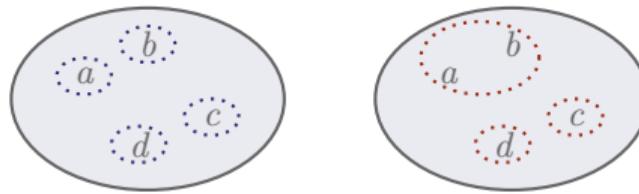


An **Experimental Paradigm** is (Z, E, T)

- ◊ Z is a set of **choice patterns**
- ◊ E is a set of **experiments**.
- ◊ T is the experimenters **theory of behavior**.

An **experiment** $e = (A, \mathcal{P})$ is:

- ◊ $A \subseteq Z$ is finite choice problem
- ◊ \mathcal{P} is a partition of A



- ◊ Represents observability constraints
- ◊ Allows for dynamic experiments, non-lab settings, etc

A **theory of behavior** $T = \langle \Theta, \Omega, \mu \rangle$:

- ◊ Θ is a set of types (choice parameters), each $\theta \in \Theta$ associated with a choice function

$$c_\theta : 2^Z \rightarrow Z \quad \text{such that} \quad c_\theta(A) \in A.$$

- ◊ Ω algebra of measurable sets of Θ
- ◊ μ prior over (Θ, Ω)

Given (A, \mathcal{P}) , define the *identified set*:

$$W_{A,P} = \{\theta \in \Theta \mid c_\theta(A) \in P\}$$

Observing $P \in \mathcal{P}$ identifies that the subject's type is in $W_{A,P}$

Concordant Exp. Paradigms



We call an experimental paradigm (Z, E, T) **concordant** if the following hold:

- (1) Any observable outcome can be measured

- (2) Any measurable hypothesis can be tested

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(2) Any measurable hypothesis can be tested

- ◊ For all Ω -meas. partitions $\{W_1, \dots, W_n\}$ of Θ , there exists $(A, \mathcal{P}) \in E$:

$$\{W_{A,P} | P \in \mathcal{P}\} =_{\mu} \{W_1, \dots, W_n\}$$

$(=_{\mu}$ means up to μ -measure 0 differences)

Example: Choice Functions



Let X be a finite set of alternatives, subject chooses element out of $A \subseteq X$

- ◊ $Z = X \times \dots \times X$
- ◊ $E = \{(A_1 \times \dots \times A_n, \mathcal{P}) \mid A_i \subseteq X, \mathcal{P} \text{ partitions } A_1 \times \dots \times A_n\}$
- ◊ Θ is all (strict) preference orders over X :

$$c_\theta(A_1 \times \dots \times A_n) = \prod_{i \leq n} \{x \in A_i \mid x \succ_\theta y, \text{ for all } y \in A_i\}$$

- ◊ Then for discrete Ω , any μ forms a concordant paradigm

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- ◊ Then for discrete Ω , any μ forms a concordant paradigm
 - ◊ this is **not** true for weak preferences; no way to test for tie-breaking

Example: Choice Correspondences



Let X be a finite set of alternatives, subject chooses subset out of $A \subseteq X$

- ◊ $Z = 2^X \times \dots \times 2^X$
- ◊ $E = \{(2^{Y_1} \times \dots \times 2^{Y_n}, \mathcal{P}) \mid Y_i \subseteq X, \mathcal{P} \text{ partitions } 2^{Y_1} \times \dots \times 2^{Y_n}\}$
- ◊ Θ is all preference orders over Z :

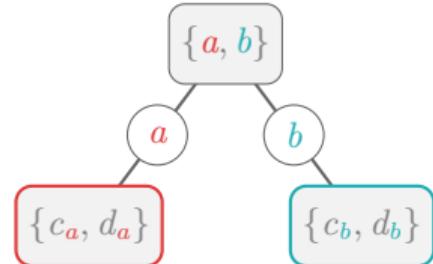
$$c_\theta(2^{Y_1} \times \dots \times 2^{Y_n}) = \prod_{i \leq n} \{x \in Y_i \mid x \succsim_\theta y, \text{ for all } y \in Y_i\}$$

- ◊ Then for discrete Ω , any μ forms a concordant paradigm

Example: Adaptive Experiments

Let $X = \{a, b, c_a, c_b, d_a, d_b\}$

- ◊ $Z = \{(a, c_a), (a, d_a), (b, c_b), (b, d_b)\}$
- ◊ $E = \{(Z, \mathcal{P}) \mid \mathcal{P} \text{ partitions } Z\}$
- ◊ Θ collect utility functions over X : could represent naive subjects



$$c_\theta(Z) = (x, y) \text{ such that } x \in \arg \max_{z \in \{a, b\}} \theta(z) \text{ and } y \in \arg \max_{w \in \{c_x, d_x\}} \theta(w)$$

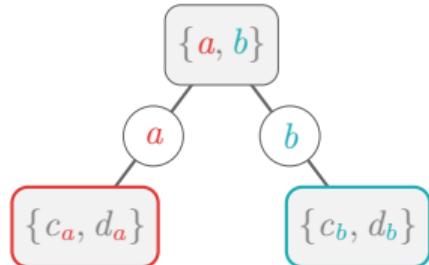
or sophisticated subjects

$$c_\theta(Z) = (x, y) \text{ such that } x \in \arg \max_{(z, w) \in Z} \theta(z) + \theta(w)$$

Example: Adaptive Experiments

Let $X = \{a, b, c_a, c_b, d_a, d_b\}$

- ◊ $Z = \{(a, c_a), (a, d_a), (b, c_b), (b, d_b)\}$
- ◊ $E = \{(Z, \mathcal{P}) \mid \mathcal{P} \text{ partitions } Z\}$
- ◊ In either case: Ω must reflect the inability to simultaneously measure preferences over $\{c_a, d_a\}$ and also $\{c_b, d_b\}$
- ◊ Ω must be generated by the four choice patterns in Z



Example: Expected Utility

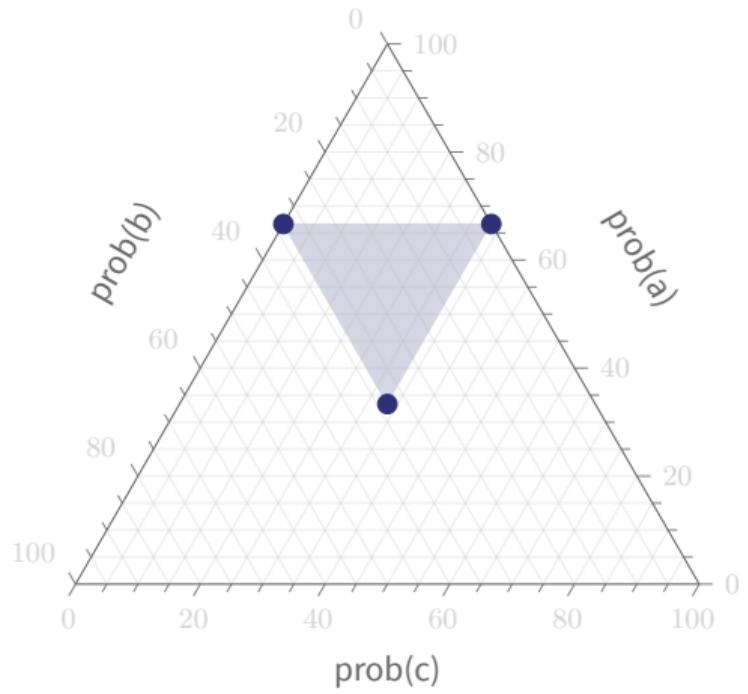


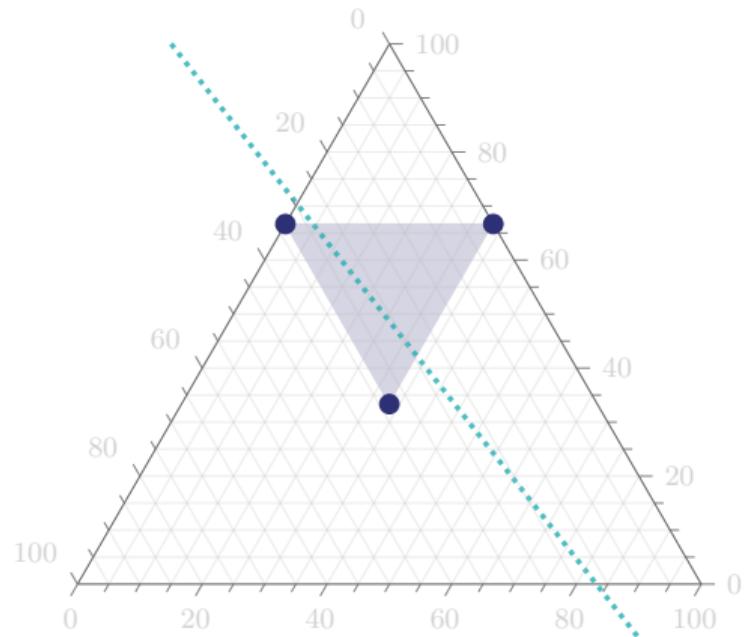
- ◊ Z is lotteries over $\{a, b, c\}$
- ◊ E is all finite subsets of Z (and all partitions thereof)
- ◊ Θ is all affine functions over Z :

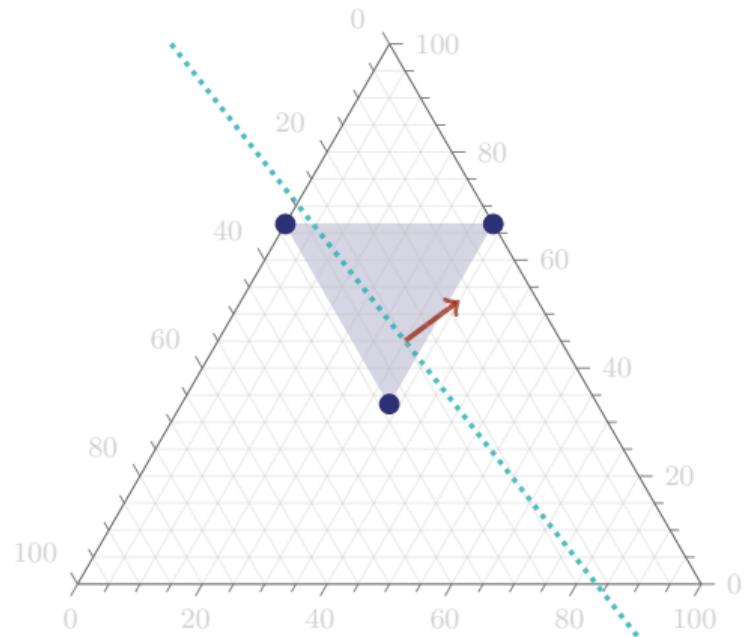
$$\theta(A) \in \arg \max_{x \in A} \theta(x)$$

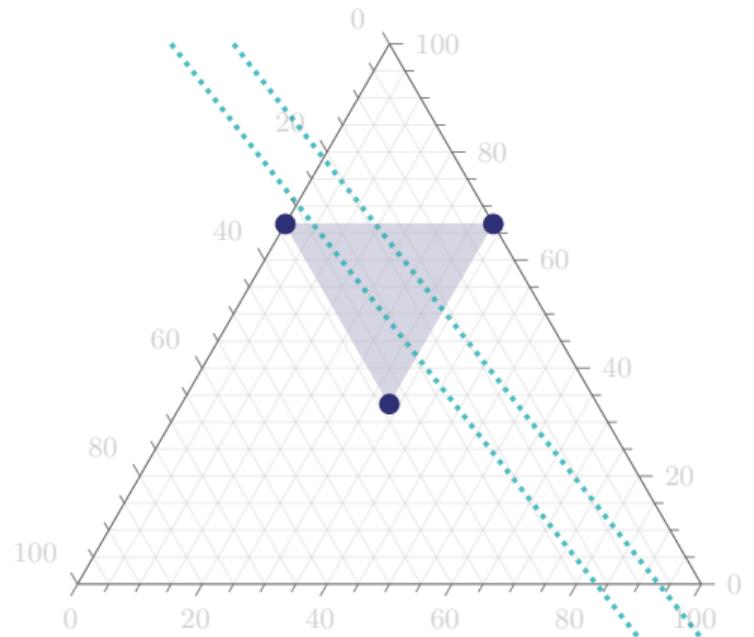
(so each parameter also specifies how ties are broken)

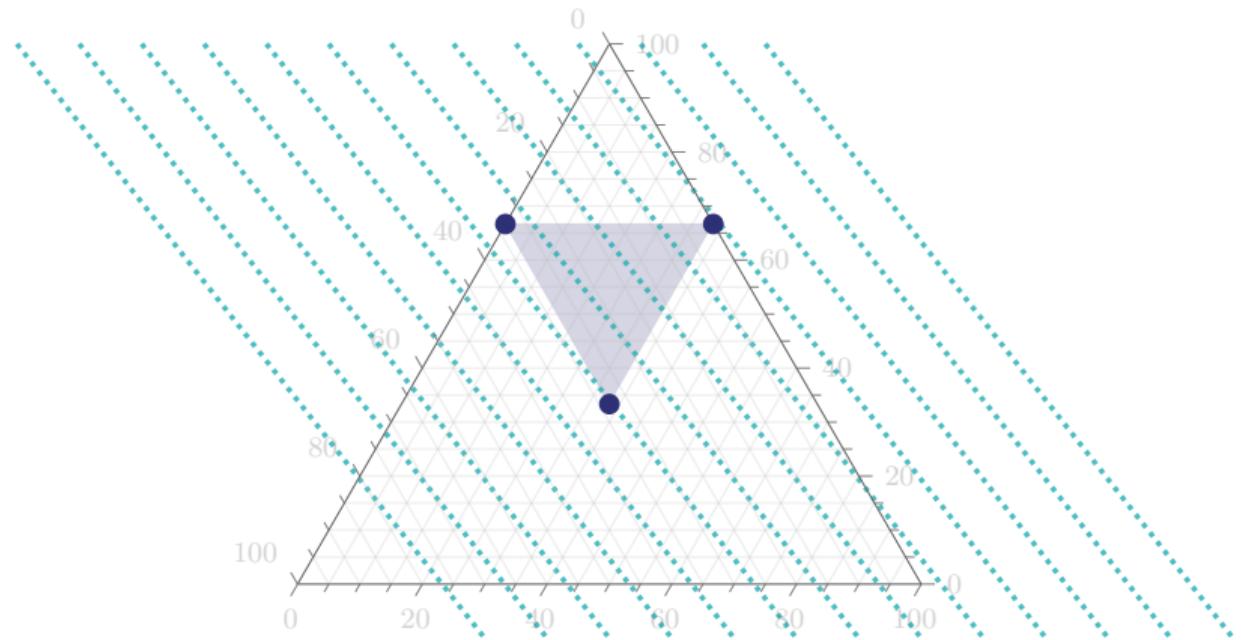
$$\left\{ \frac{2}{3}a + \frac{1}{3}b, \frac{2}{3}a + \frac{1}{3}c, \frac{1}{3}a + \frac{1}{3}b + \frac{1}{3}c \right\}$$

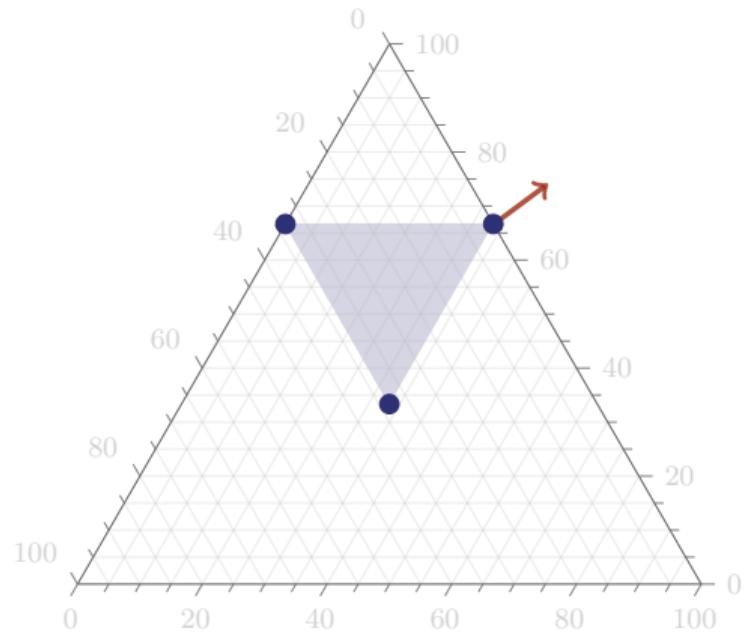


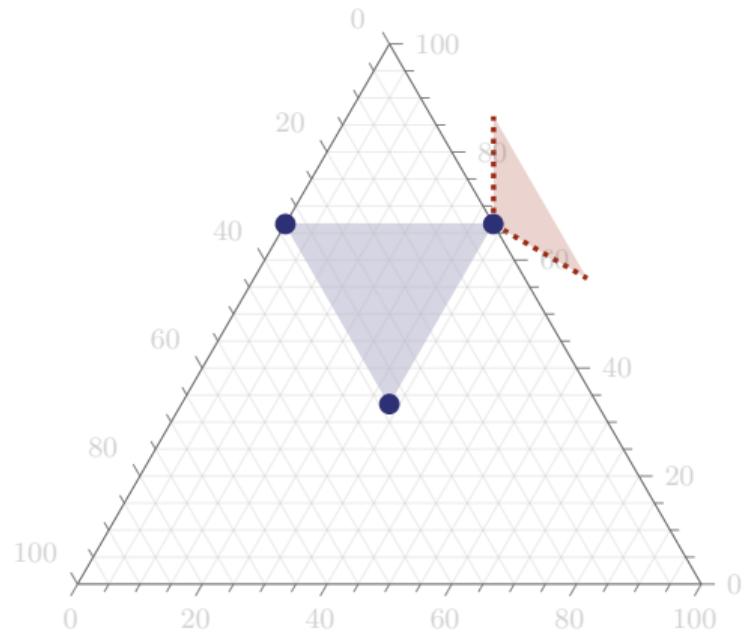


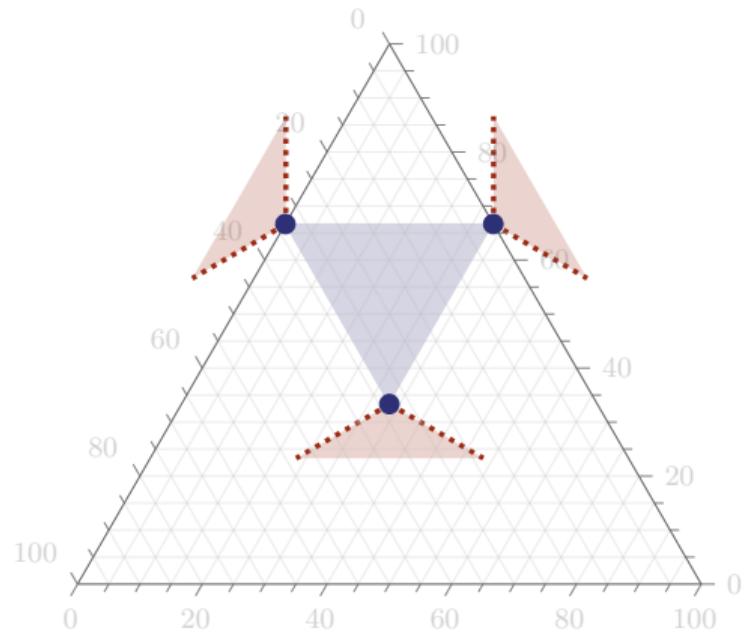


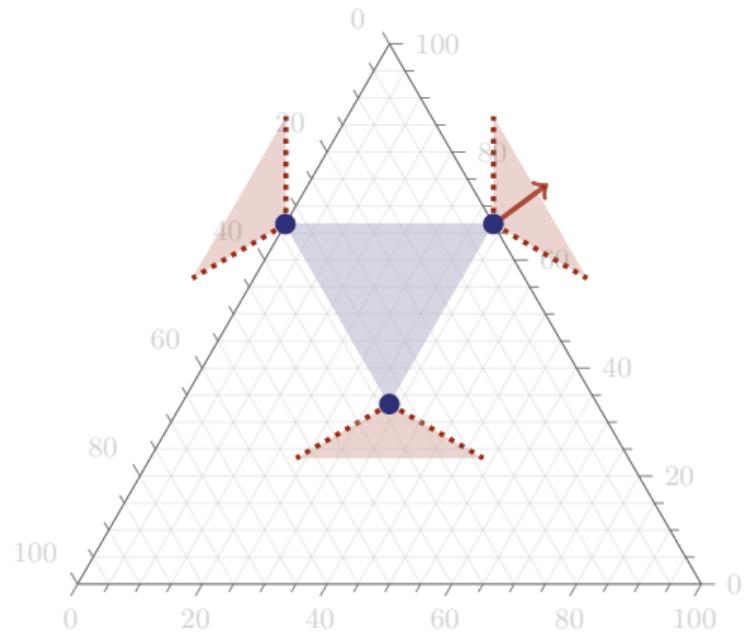




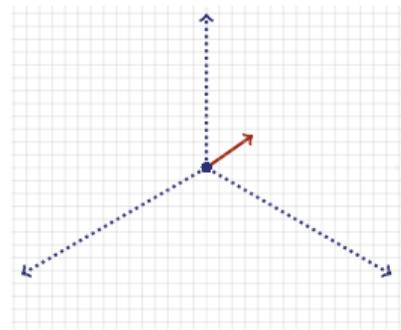








$$\Theta \cong \mathbb{R}^2$$



Example: Expected Utility



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- ◊ E is all finite subsets of Z (and all partitions thereof)
- ◊ Θ is all affine functions over Z :

$$\theta(A) \in \arg \max_{x \in A} \theta(x)$$

Theorem: Random Expected Utility

$(Z, (\Theta, \Omega, \mu), E)$ is concordant iff μ is regular à la Gul & Pesendorfer (2006):

$$\text{for all } p, q \in Z, \quad \mu(\{\theta \mid \theta(p) = \theta(q)\}) = 0$$



Normative Principles





- ◊ Fix some concordant paradigm: (Z, E, T) :
- ◊ Our primitive is a ranking \succcurlyeq over the set of all *costly* experiments:

$$(A, \mathcal{P}, c) \quad \text{where } (A, \mathcal{P}) \in E \quad \text{and} \quad c \geq 0$$

- ◊ We entertain 4 axioms:
 - ◊ 3 for our normative principles
 - ◊ 1 for quasi-linearity

“ Prefer the least costly implementation of a given identification of parameters ”

(P1) – Structural Invariance

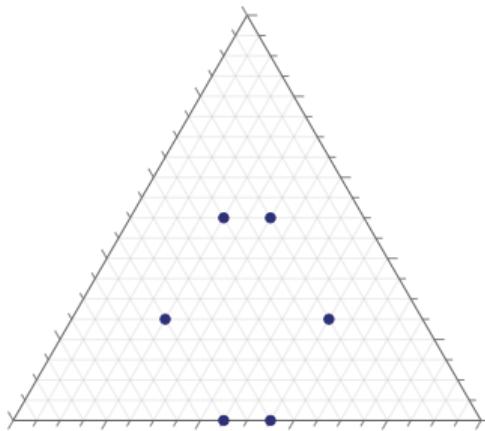
Let $\{W_{A,P} | P \in \mathcal{P}\} =_{\mu} \{W_{B,Q} | Q \in \mathcal{Q}\}$:

$$(A, \mathcal{P}, c) \succsim (B, \mathcal{Q}, c') \quad \text{if and only if} \quad c' \geq c.$$

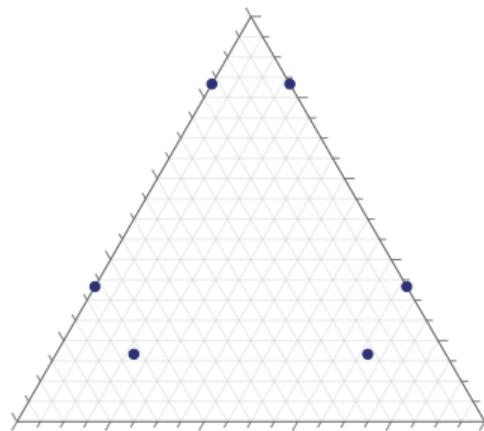
- ◊ Structural properties of experiments are irrelevant
- ◊ Also, 0-probability events are irrelevant ($=_{\mu}$)

Consider our EU maximizing subject choosing lotteries over $\{a, b, c\}$.

A

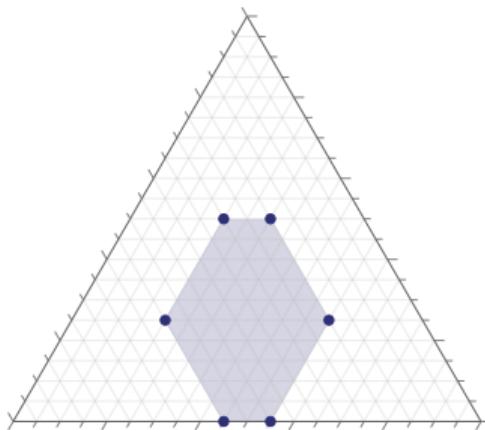


B

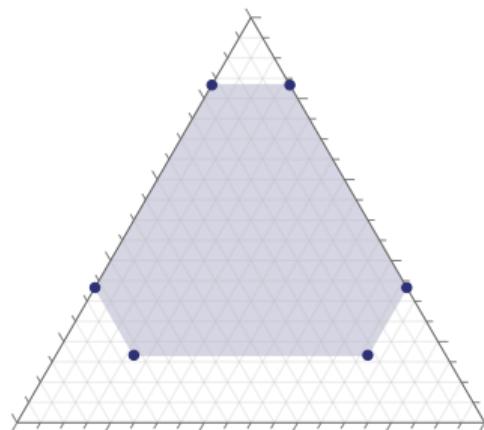


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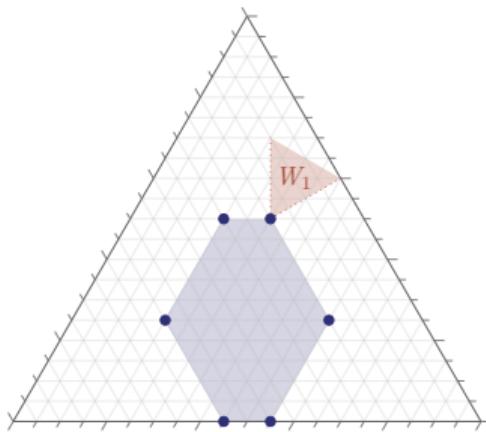


B

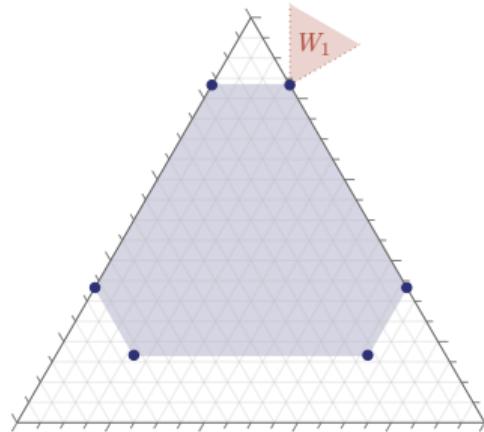


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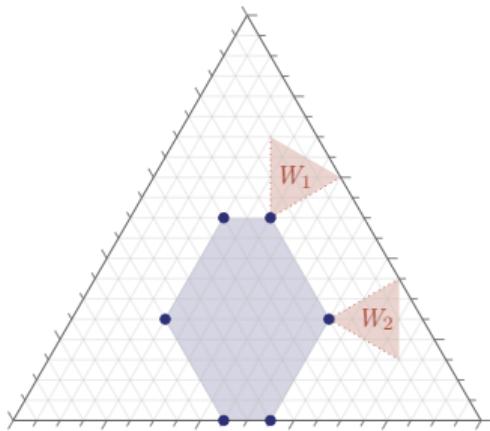


B

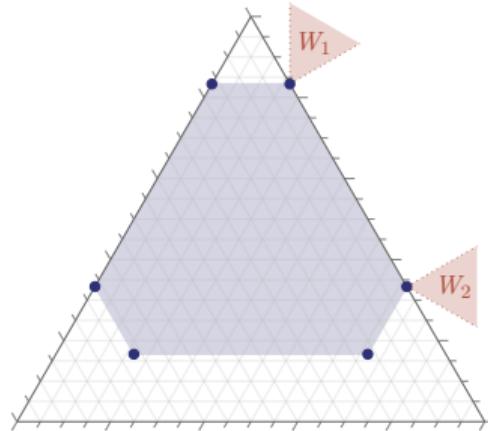


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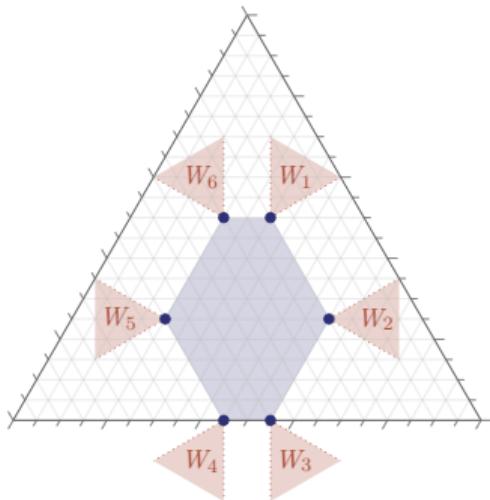


B

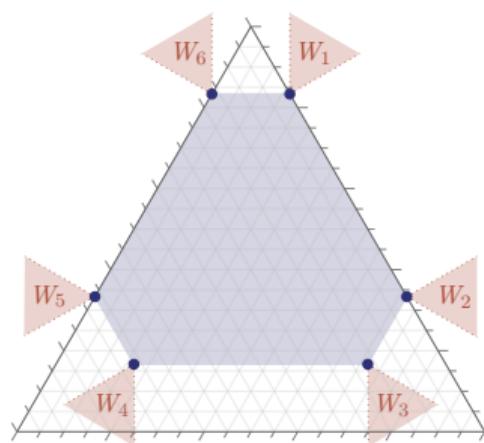


Consider our EU maximizing subject choosing lotteries over $\{a, b, c\}$.

A



B



- ◊ Structural invariance reflects the symmetries of the given domain
- ◊ With linear utility, the symmetry is *translation invariance*:

Structural Invariance for Expected Utility

$$(A, \{P_1, \dots, P_n\}, c) \sim (A + B, \{P_1 + B, \dots, P_n + B\}, c)$$

“ (Weakly) prefer experiments that induce sharper identification ”

(P2) – Information Monotonicity

If \mathcal{P} refines \mathcal{Q} then $(A, \mathcal{P}, c) \succcurlyeq (A, \mathcal{Q}, c)$.

- ◊ Preference respects Blackwell order

“ Consider only the elements of experiments that can be controlled ”

(P3) – Identification Separability

$$(A, \mathcal{P}, c) \sim (A, \mathcal{Q}_B \mathcal{P}, 0) \quad \text{if and only if} \quad (A, \mathcal{P}_B \mathcal{Q}, c) \sim (A, \mathcal{Q}, 0).$$

- ◊ If \mathcal{P} and \mathcal{Q} partition of A and $B \subseteq A$, then $\mathcal{P}_B \mathcal{Q}$ denotes the partition that coincides with \mathcal{P} over B and with \mathcal{Q} over $A \setminus B$

(A, \mathcal{P})

P_1	P_2	P_3	P_4	P_5
-------	-------	-------	-------	-------

 (A, \mathcal{Q})

Q_1	Q_2	Q_3	Q_4
-------	-------	-------	-------

(A, \mathcal{P})

P_1	P_2	P_3	P_4	P_5
-------	-------	-------	-------	-------

 $(B, \mathcal{Q}_B \mathcal{P})$

Q_1	Q_2	P_4	P_5
-------	-------	-------	-------

 (A, \mathcal{Q})

Q_1	Q_2	Q_3	Q_4
-------	-------	-------	-------

(A, \mathcal{P})

P_1	P_2	P_3	P_4	P_5
-------	-------	-------	-------	-------

 $(B, \mathcal{Q}_B \mathcal{P})$

Q_1	Q_2	P_4	P_5
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 $(A, \mathcal{P}_B \mathcal{Q})$

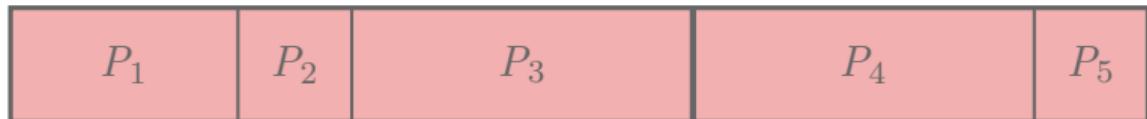
P_1	P_2	P_3	Q_3	Q_4
-------	-------	-------	-------	-------

 (A, \mathcal{Q})

Q_1	Q_2	Q_3	Q_4
-------	-------	-------	-------

$$(A, \mathcal{P}, c) \sim (A, \mathcal{Q}_B \mathcal{P}, 0) \quad \text{if and only if} \quad (A, \mathcal{P}_B \mathcal{Q}, c) \sim (A, \mathcal{Q}, 0).$$

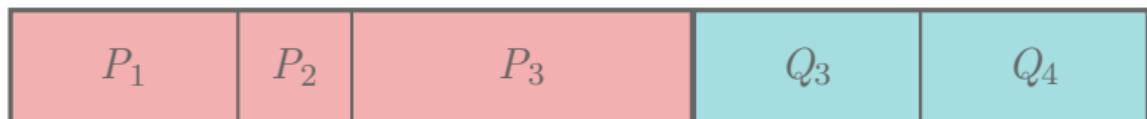
(A, \mathcal{P})



$(B, \mathcal{Q}_B \mathcal{P})$



$(A, \mathcal{P}_B \mathcal{Q})$



(A, \mathcal{Q})



Let \succsim be an quasi-linear preference, represented by index $U: E \times \mathbb{R}_+ \rightarrow \mathbb{R}$.

Theorem: Expected Identification Value Maximization

Then \succsim satisfies P1–3 if and only if there exists a $\tau: \Omega \rightarrow \mathbb{R}$ such that:

$$U(A, \mathcal{P}, c) = \sum_{P \in \mathcal{P}} \tau(W_{A,P})\mu(W_{A,P}) - c$$

with $W \subseteq V$ implies

- ◊ $\tau(V) \leq \tau(W)\mu(W|V) + \tau(V \setminus W)(1 - \mu(W|V))$
- ◊ if also $\mu(V \setminus W) = 0$ then $\tau(W) = \tau(V)$

Representation reflects our normative principles:

$$\sum_{P \in \mathcal{P}} \tau(W_{A,P}) \mu(W_{A,P})$$

- ◊ Only dependents on $W_{A,P} \implies$ Structural Invariance
- ◊ Additive \implies Identification Separability
- ◊ $\tau(V) \leq \tau(W)\mu(W|V) + \tau(V \setminus W)(1 - \mu(W|V)) \implies$ Monotonicity



Information Based Models



Information Based Models



- ◊ Often, we seek only to reduce uncertainty
 - ◊ Experimenter does not have a preference for *what* is learned
- ◊ Value of identification $\tau(W)$, depends only of $\mu(W)$.
 - ◊ We can specialize structural invariance to capture this.
- ◊ E.g., value for an experiment is the (expected) reduction in entropy

$$U(A, \mathcal{P}, c) = - \sum_{P \in \mathcal{P}} \log(\mu(W_{A,P}))\mu(W_{A,P}) - c$$

Probability Vectors



For each $e = (A, \{P_1, \dots, P_n\}) \in E$ let

$$\mathbf{p}_e = \{\mu(W_{A,P_1}), \dots, \mu(W_{A,P_n})\} \in \Delta^n$$

denote the probability vector induced by the experiment.

(P2*) - Information Based Structural Invariance

Let $\mathbf{p}_e = \mathbf{p}_{e'}$ and $c' \geq c$: then

$$(e, c) \succsim (e', c'),$$

with a strict preference whenever $c' > c$.

(P2**) - Schur Concavity

Let $\mathbf{p}_e = \mathbf{D} \mathbf{p}_{e'}$ for some doubly stochastic matrix \mathbf{D} , and $c' \geq c$: then

$$(e, c) \succsim (e', c'),$$

with a strict preference whenever $c' > c$.

Let \succsim be an Expected Identification Value Maximization preference:

Theorem: Belief Based Models

Let μ be non-atomic. \succsim satisfies P2* if and only

$$U(A, \mathcal{P}, c) = \sum_{P \in \mathcal{P}} h(\mu(W_{A,P}))\mu(W_{A,P}) - c.$$

for some $h : [0, 1] \rightarrow \mathbb{R}$ with $h(0) = 0$ is such that

- ◊ For all $p, \alpha \in [0, 1]$,

$$h(p) \leq \alpha h(\alpha p) + (1 - \alpha)h((1 - \alpha)p)$$

- ◊ $p \mapsto h(p)p$ is concave iff P2* is strengthened to P2**.

Entropic Partitions



- ◊ Fix $(A, \mathcal{P} = \{P_1, \dots, P_n\})$ and let $\mathcal{P}^1 = \{P_1^1, \dots, P_k^1\}$ partition P_1 .
- ◊ Then $\mathcal{P}^\dagger = \{P_1^1, \dots, P_k^1, P_2, \dots, P_n\}$ is also partition of A .
 - ◊ As if observing \mathcal{P} and then if P_1 is realized, further observing \mathcal{P}^1
 - ◊ \mathcal{P} observed with prob 1, \mathcal{P}^1 observed with probability $\mu(W_{A, \mathcal{P}_1})$
- ◊ Let $(B, \mathcal{Q} = \{Q_1, \dots, Q_k\})$ with $\mu(W_{B, Q_i}) = \mu(W_{A, P_i^1} \mid W_{A, P_1})$
 - ◊ Observing \mathcal{Q} has same ‘informational content’ as observing \mathcal{P}^1 conditional on realization of P_1

(A, \mathcal{P})

P_1	P_2	P_3	P_4
-------	-------	-------	-------

(A, \mathcal{P})

P_1	P_2	P_3	P_4
-------	-------	-------	-------

 (A, \mathcal{P}^\dagger)

P_1^1	P_2^1	P_3^1	P_2	P_3	P_4
---------	---------	---------	-------	-------	-------

(A, \mathcal{P})

P_1	P_2	P_3	P_4
-------	-------	-------	-------

 (A, \mathcal{P}^\dagger)

P_1^1	P_2^1	P_3^1	P_2	P_3	P_4
---------	---------	---------	-------	-------	-------

 (B, \mathcal{Q})

Q_1	Q_2	Q_3
-------	-------	-------

(A, \mathcal{P})

	P_1	P_2	P_3	P_4
--	-------	-------	-------	-------

 (A, \mathcal{P}^\dagger)

P_1^1	P_2^1	P_3^1	P_2	P_3	P_4
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 (B, \mathcal{Q})

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(A, \mathcal{P})

	P_1	P_2	P_3	P_4
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 (A, \mathcal{P}^\dagger)

P_1^1	P_2^1	P_3^1	P_2	P_3	P_4
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 (B, \mathcal{Q})

Q_1	Q_2	Q_3
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(A, \mathcal{P})

	P_1	P_2	P_3	P_4
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 (A, \mathcal{P}^\dagger)

P_1^1	P_2^1	P_3^1	P_2	P_3	P_4
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 (B, \mathcal{Q})

Q_1	Q_2	Q_3
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(P3*) – Identification Separability for Entropy

Fix $(A, \mathcal{P} = \{P_1, \dots, P_n\})$ and $\mathcal{P}^\dagger = \{P_1^1, \dots, P_k^1, P_2, \dots, P_n\}$.

Then if $(B, \{Q_1, \dots, Q_k\})$ is such that $\mu(W_{B, Q_i}) = \mu(W_{A, P_i^1} \mid W_{A, P_1})$, it follows that

$$(B, \mathcal{Q}, c) \sim (A, \{A\}, 0) \quad \text{if and only if} \quad (A, \mathcal{P}^\dagger, \mu(W_{A, P_1}) \cdot c) \sim (A, P, 0)$$

- ◊ Conditional on P_1 being realized, observing \mathcal{P}^\dagger has the same information content as (unconditionally) observing \mathcal{Q}
- ◊ P_1 is realized with probability $\mu(W_{A, P_1})$.

Let \succcurlyeq be an Expected Identification Value Maximization preference:

Theorem: Entropy Minimization

Let μ be non-atomic. \succcurlyeq satisfies P2** and P3* if and only

$$U(A, \mathcal{P}, c) = - \sum_{P \in \mathcal{P}} \log(\mu(W_{A,P}))\mu(W_{A,P}) - c.$$



Thank You!

