

Elizabeth Vargas

CONTACT INFORMATION	Ocean Systems Laboratory Earl Mountbatten G.06 Heriot-Watt University Edinburgh, United Kingdom	Website: https://evargasv.github.io/ Email: elizabeth.vargas@hw.ac.uk LinkedIn: https://www.linkedin.com/in/evargasv/ Portfolio: https://github.com/evargasv
---------------------	--	--

PROFESSIONAL EXPERIENCE	ORCA Hub <i>Research Associate</i>	Jan. 2019 - Present Edinburgh, United Kingdom
-------------------------	--	--

- Developed a real-time computer vision system, deployed on a remotely operated underwater vehicle for the surveying and inspection of offshore assets (ROS, C++).
- Implemented Visual Simultaneous Localisation And Mapping (SLAM) solution for limited visibility underwater environments, based on data fusion from acoustic and optical sensors.
- Employed stereo cameras for 3D reconstruction of submerged structures, enabling the offshore industry to inspect and certify their integrity.
- Designed, set-up, and executed practical experiments and prototype systems relating to the demonstration of solution capabilities to industry representatives.

	Toshiba Medical Visualization Systems <i>Research Intern with Corné Hoogendoorn</i>	Jun. 2015 - Sep. 2015 Edinburgh, United Kingdom
--	---	--

- Characterised Alzheimer disease using Magnetic Resonance Imaging (MRI), performing texture analysis in the hippocampus tissue enabling the diagnose the disease at various stages.
- Combined brain gyrus segmentation with regional texture metrics (Pandas).
- Applied machine learning to image texture, including feature selection, classification and regression techniques (Python, Scikit-Learn).

	Philips Research Aachen <i>Research Intern with Martin Weibrecht</i>	Mar. 2011 - Jul. 2011 Aachen, Germany
--	--	--

- Magnetic Resonance Imaging (MRI) applied to characterisation of liver diseases, by extraction of features relevant for disease diagnosis (MATLAB).
- Performed statistical analysis using linear regression on volume data sets to obtain parametric maps of apparent diffusion coefficients from diffusion-weighted MRI.
- Implemented image processing algorithms, including a gray level-based iterative segmentation that applies a threshold derived from histogram analysis.

EDUCATION	Ph.D. Signal Processing <i>Heriot-Watt University, United Kingdom</i>	Oct. 2015 - Sep. 2019
-----------	---	-----------------------

- Advanced the state-of-the-art in acoustic source localisation in constrained environments through three major contributions (detailed below).
- Reduced computation six fold while maintaining localisation accuracy at state-of-the-art levels (Python, NumPy, SciPy).
- Implemented a signal sampling algorithm to achieve accurate localisation for a signal transmitted at a compression ratio of 40 : 1 (MATLAB).
- Applied deep learning techniques to achieve a 20% improvement in localisation accuracy by training a Convolutional Neural Network (CNN) using data augmentation from a Generative Adversarial Network (GAN) (Python, Keras, TensorFlow).

	M.Sc. Computer Vision and Robotics with Distinction Sep. 2013 - Jun. 2015 <i>University of Burgundy, France</i> GPA: 15.3/20 <ul style="list-style-type: none"> • Joint Erasmus Mundus Master Program with <i>University of Burgundy</i> (France), <i>University of Girona</i> (Spain) and <i>Heriot-Watt University</i> (United Kingdom). • Basis of signal and image processing, medical image analysis (MATLAB). • Segmentation, multi-view geometry, object recognition and tracking (OpenCV). • Robot autonomy and intelligence, including SLAM and motion planning (ROS).
	B.Sc. Computer Science Aug. 2006 - Aug. 2012 <i>Universidad del Valle, Colombia</i> GPA: 4.67/5.0 <ul style="list-style-type: none"> • Courses in algorithms, data structures, compilers and software engineering. • Projects including image processing (C/C++), search algorithms, optimisation, evolutionary algorithms, software development (Java) and databases (MySQL).
SELECTED PUBLICATIONS	E. Vargas , J. R. Hopgood, K. Brown, K. Subr, <i>A Compressed Encoding Scheme for Approximate TDOA Estimation</i> , in European Signal Processing Conference (EU-SIPCO), Rome, Italy, September 2018. E. Vargas , K. Brown, K. Subr, <i>Impact of Microphone Array Configurations on Robust Indirect 3D Acoustic Source Localization</i> , in International Conference on Acoustics, Speech and Signal Processing (ICASSP), Calgary, Canada, April 2018.
DISTINCTIONS	James Watt Scholarship , <i>Heriot-Watt University</i> Oct. 2015 Granted to 5 applicants for a Ph.D. position at the School of Engineering and Physical Sciences (EPS), awarding tuition fees and annual stipend to support studies for 3 years. Erasmus Mundus Scholarship , <i>European Commission</i> Sep. 2013 Granted to 4 European students for academic and professional achievement to study a Master in Computer Vision and Robotics (ViBot) during the academic year 2013-2015.
TRAINING	International Summer School on Deep Learning Jul. 2018 Research training event aiming at updating participants about the most recent advances in the critical and fast developing area of deep learning. International Computer Vision Summer School (ICVSS) Jul. 2016 Provided an objective, clear, and in-depth summary of the state-of-the-art research in the areas of Computer Vision, Machine Learning and Artificial Intelligence.
TECHNICAL SKILLS	Operating Systems: Windows, Linux (Ubuntu) Programming Languages: Python, C/C++ Robotics: Robotics Operating System (ROS) Computer Vision: OpenCV Machine Learning: Scikit-Learn, NumPy, SciPy Software Tools: MATLAB Version Control: Git/Github
VOLUNTEER EXPERIENCE	Edinburgh International Science Festival , <i>Student Helper</i> 2017 - 2018 Helper at the “ <i>Marty: Activate!</i> ” workshop that taught children (11+ years) to program a robot to interact with its surroundings using the programming language <i>Scratch</i> . Cracking the Code , <i>Student Helper</i> Jun. 2017 Introduce girls (9-11 years) to programming a robot using LEGO MINDSTORMS, as part of a Equality Challenge Units (ECU) project aimed at attracting under-represented groups into subjects they don’t traditionally apply for.