

# Elizabeth Vargas

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CONTACT INFORMATION	Ocean Systems Laboratory Earl Mountbatten G.06 Heriot-Watt University Edinburgh, United Kingdom	Website: <a href="https://evargasv.github.io/">https://evargasv.github.io/</a> Email: <a href="mailto:elizabeth.vargas@hw.ac.uk">elizabeth.vargas@hw.ac.uk</a> LinkedIn: <a href="https://www.linkedin.com/in/evargasv/">https://www.linkedin.com/in/evargasv/</a> Github: <a href="https://github.com/evargasv">https://github.com/evargasv</a>
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PROFESSIONAL EXPERIENCE	<b>ORCA Hub</b> <i>Research Associate</i>	Jan. 2019 - Present Edinburgh, United Kingdom
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- Computer Vision (CV) for Offshore Robotics for Certification of Assets (ORCA).
- Simultaneous Localisation And Mapping (SLAM) in underwater environments.
- Sensor Fusion of Visual Odometry (VO) with acoustic and inertial sensors (*ROS*).

	<b>Toshiba Medical Visualization Systems</b> <i>Research Intern with Corné Hoogendoorn</i>	Jun. 2015 - Sep. 2015 Edinburgh, United Kingdom
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- Alzheimer disease characterisation using Magnetic Resonance Imaging (MRI).
- Texture analysis in hippocampus tissue to diagnose the disease at various stages.
- Performed feature selection, classification and regression (*Python*, *Scikit-learn*).

	<b>Philips Research Aachen</b> <i>Research Intern with Martin Weibrecht</i>	Mar. 2011 - Jul. 2011 Aachen, Germany
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- Magnetic Resonance Imaging (MRI) applied to characterisation of liver diseases.
- Features extraction from Diffusion Weighted MRI relevant for disease diagnosis.
- Implementation of a gray level based iterative segmentation algorithm employing threshold derived from histogram analysis (*MATLAB*).

EDUCATION	<b>Ph.D. Signal Processing</b> <i>Heriot-Watt University, United Kingdom</i>	Oct. 2015 - Sep. 2019
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- Acoustic source localisation in environments in which a constraint is present.
- Source localisation via direct optimisation reducing computation six fold (*SciPy*).
- Signal sampling implementation in the spectrogram for compressed transmissions.
- Improved neural networks training for acoustic localisation (*Keras*, *TensorFlow*).
- Thesis: “Acoustic Source Localisation in Constrained Environments”.
- Advisors: Keith Brown (*Heriot-Watt University*) and Kartic Subr (*University of Edinburgh*).
- Examiners: Abderrahim Halimi (*Heriot-Watt University*) and Keith Holland (*University of Southampton*).

	<b>M.Sc. Computer Vision and Robotics with Distinction</b> <i>Heriot-Watt University, United Kingdom</i>	Sep. 2013 - Jun. 2015 GPA: 76.6/100
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- Joint Erasmus Mundus Master Program with *University of Burgundy* (France), *University of Girona* (Spain) and *Heriot-Watt University* (United Kingdom).
- Basis of signal and image processing, medical image analysis (*MATLAB*).
- Image segmentation, multi-view geometry, object recognition and tracking (*OpenCV*).
- Robot autonomy and intelligence, including SLAM and motion planning (*ROS*).
- Thesis: “Texture Enhanced Tissue Analysis”.
- Advisor: Keith Goatman (*Toshiba Medical Visualization Systems*).

	<b>B.Sc. Computer Science</b> <i>Universidad del Valle, Colombia</i>	Aug. 2006 - Aug. 2012 GPA: 4.67/5.0
	<ul style="list-style-type: none"> <li>• Courses in algorithms, data structures, compilers and software engineering.</li> <li>• Projects including image processing (<i>C/C++</i>), search algorithms, optimisation, evolutionary algorithms, software development (<i>Java</i>) and databases (<i>MySQL</i>).</li> <li>• Thesis: “Pruning Estimated Corresponding Points by Delaunay Triangulation”.</li> <li>• Advisor: Maria Trujillo.</li> </ul>	
SELECTED PUBLICATIONS	<ul style="list-style-type: none"> <li>• <b>E. Vargas</b>, J. R. Hopgood, K. Brown, K. Subr, <i>A Compressed Encoding Scheme for Approximate TDOA Estimation</i>, in European Signal Processing Conference (<b>EU-SIPCO</b>), Rome, Italy, September 2018. (<b><i>Oral Presentation</i></b>)</li> <li>• <b>E. Vargas</b>, K. Brown, K. Subr, <i>Impact of Microphone Array Configurations on Robust Indirect 3D Acoustic Source Localization</i>, in International Conference on Acoustics, Speech and Signal Processing (<b>ICASSP</b>), Calgary, Canada, April 2018. (<b><i>Oral Presentation</i></b>)</li> </ul>	
DISTINCTIONS	<b>James Watt Scholarship</b> , <i>Heriot-Watt University</i> Oct. 2015 Granted to 5 applicants for a Ph.D. position at the School of Engineering and Physical Sciences (EPS), awarding tuition fees and annual stipend to support studies for 3 years. <b>Erasmus Mundus Scholarship</b> , <i>European Commission</i> Sep. 2013 Granted to 4 European students for academic and professional achievement to study a Master in Computer Vision and Robotics (ViBot) during the academic year 2013-2015.	
TRAINING	<b>International Summer School on Deep Learning</b> Jul. 2018 Research training event aiming at updating participants about the most recent advances in the critical and fast developing area of deep learning. <b>International Computer Vision Summer School (ICVSS)</b> Jul. 2016 Provided an objective, clear, and in-depth summary of the state-of-the-art research in the areas of Computer Vision, Machine Learning and Artificial Intelligence.	
TECHNICAL SKILLS	<b>Operating Systems:</b> Windows, Linux (ubuntu) <b>Programming Languages:</b> Python, C/C++, Java <b>Libraries:</b> Visualization Toolkit (VTK), Point Cloud Library (PCL), Qt, SciPy <b>Frameworks:</b> Robotics Operating System (ROS) <b>Computer Vision:</b> OpenCV <b>Machine Learning:</b> WEKA, Scikit-learn, Keras, TensorFlow <b>Software Tools:</b> MATLAB <b>Version Control:</b> Git/Github <b>Markup Languages:</b> L <sup>A</sup> T <sub>E</sub> X, B <sub>I</sub> B <sub>T</sub> E <sub>X</sub> , HTML, XML	
VOLUNTEER EXPERIENCE	<b>Edinburgh International Science Festival</b> , <i>Student Helper</i> 2017 - 2018 Helper at the “ <i>Marty: Activate!</i> ” workshop that taught children (11+ years) to program a robot to interact with its surroundings using the programming language <i>Scratch</i> . <b>FIRST LEGO League (FLL)</b> , <i>Robot Game Judge</i> 2016-2018 Assess teams of young people (9-16 years) while solving a set of missions on a specialised field, using an autonomous robot built and programmed using LEGO MINDSTORMS <b>Cracking the Code</b> , <i>Student Helper</i> Jun. 2017 Introduce girls (9-11 years) to programming a robot using LEGO MINDSTORMS, as part of a Equality Challenge Units (ECU) project aimed at attracting under-represented groups into subjects they don’t traditionally apply for.	