

# CS161 Discussion 2

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# Lisp practice

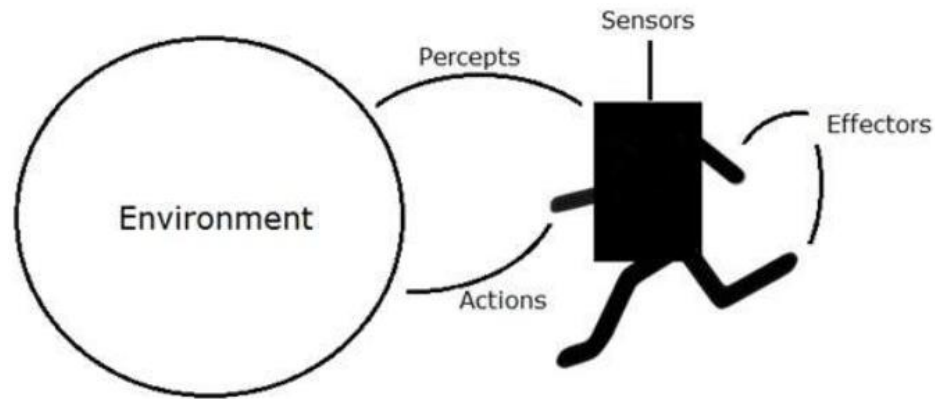
- if a list is increasing

# Check if a list is increasing

```
(defun is_increasing (lst)
  (if (null (second lst))
      t
      (and (< (first lst)
              (second lst))
           (is_increasing (cdr lst)))))
```

# Agents

An agent ***perceives*** its ***environment*** through ***sensors*** and ***acts*** upon it through ***actuators***



# Agents

- **Rational agents:**
  - Choose actions that maximize the expected utility
  - Example 1: have a goal and a cost
    - Reach the goal with the lowest cost
  - Example 2: have numerical utilities, rewards, etc.
    - Take actions that maximize total reward over time
      - Reinforcement learning

# Agents

- **Reflex agents:**

- Action based on current percept of the environment (and maybe memory)
- Does not consider future consequence of actions
- If-else condition-action: What the world is like now => behave this way

## Example

- Agent: Mail sorting robot
- Environment: Conveyor belt of letters
- Rule: city=Los Angeles -> put letter to California bag

# Search Problem

**A search problem** consists of

- Initial State
- A state space  $S = \{s_1, s_2, \dots s_d\}$
- Actions: a set of possible actions
- Successor function (transition model):  $F(s_t, a_t) = s_{t+1}$ , sometimes with a path cost function
- Goal test : determine if solution is achieved.

**A solution:**

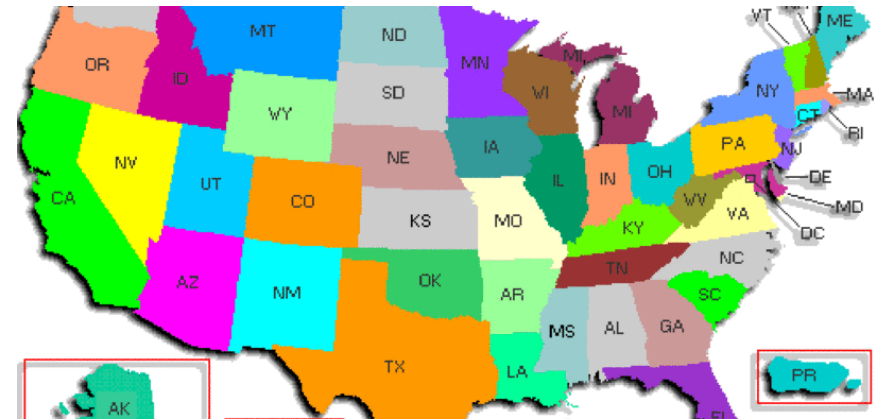
a sequence of actions that transform the initial state to a goal state

**Problem formulation:**

the process of deciding what actions and states to consider, given a goal.

# Search Problem – Example - Travel from CA to MA

- **Initial State:** CA
- **State space:** 50 states in U.S.
- **Actions:** go to adjacent state. cost=distance
  - For example,  $\text{Actions}(\text{CA}) = \{\text{Go}(\text{OR}), \text{Go}(\text{AZ}), \text{Go}(\text{Nevada})\}$
- **Successor function** (transition model)
  - $\text{RESULT}(\text{In}(\text{CA}), \text{Go}(\text{AZ})) = \text{In}(\text{AZ})$
- **Goal test:**
  - $\text{state} == \text{MA?}$
- **Path cost function**
- **Solution ?**





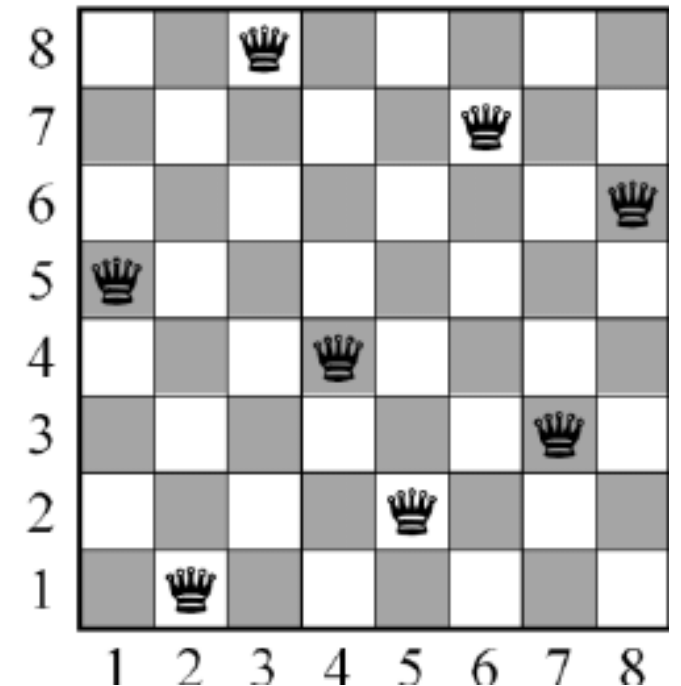
# Search Problem – 8 queens

Objective:

Place eight queens on a chessboard such that no queen attacks any other.

(No two queens on the same row, column, diagonal)

(We don't care about how or how long you find the solution)



# Search Problem – 8 queens

Formulate this problem.

- **States:** Any arrangement of 0 to 8 queens on the board is a state.
- **Initial state:** No queens on the board.
- **Actions:** Add a queen to any empty square.
- **Transition model:** Returns the board with a queen added to the specified square.
- **Goal test:** 8 queens are on the board, none attacked.

(We don't care about path cost here)

How many possible sequences?

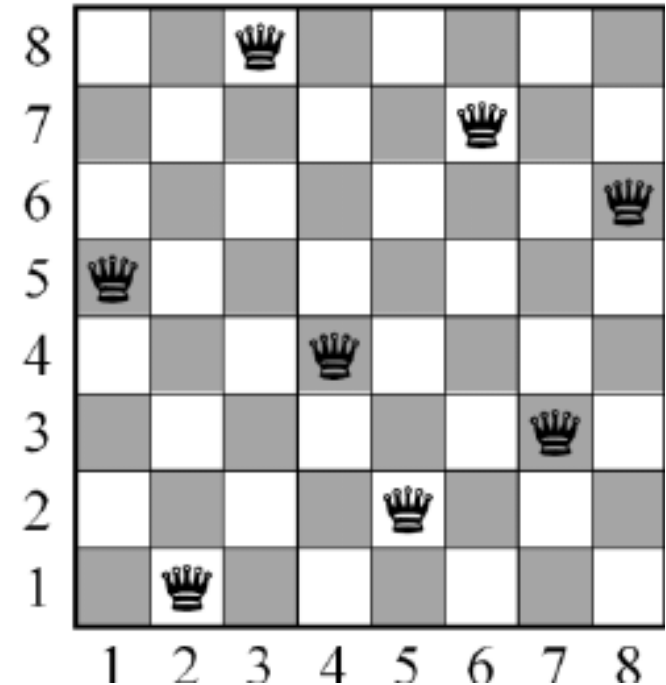
$$64! = 1.8 \times 10^{14}$$

# Search Problem – 8 queens

- **States:** All possible arrangements of  $n$  queens ( $0 \leq n \leq 8$ ), one per column in the **leftmost  $n$  columns, with no queen attacking another.**
- **Actions:** Add a queen to any square in the **leftmost empty column** such that it is not attacked by any other queen.
- **Transition model:** Returns the board with a queen added to the specified square.
- **Goal test:** 8 queens are on the board, none attacked.

How large is the state space?

2057 (Why?)



# Search Problem – 8 queens

- Incremental formulation
  - Start with an empty state
  - Each action adds a queen
- Complete-state formulation
  - Start with all 8 queens on the board
  - Moves queens around

In either case, path cost doesn't matter because only final state counts.

# Search Problem Formulation - Exercise 1

- Two friends live in different cities on a map
- On every turn, we can simultaneously move each friend to a neighboring city
- $\text{Time}(\text{city } i \rightarrow \text{neighbor } j) = \text{distance } d(i, j)$
- On each turn **the friend that arrives first must wait until the other one arrives** (and calls the first on his/her cell phone) before the next turn can begin.
- We want the two friends to **meet as quickly as possible**.

☐ **Write a formulation for this search problem**

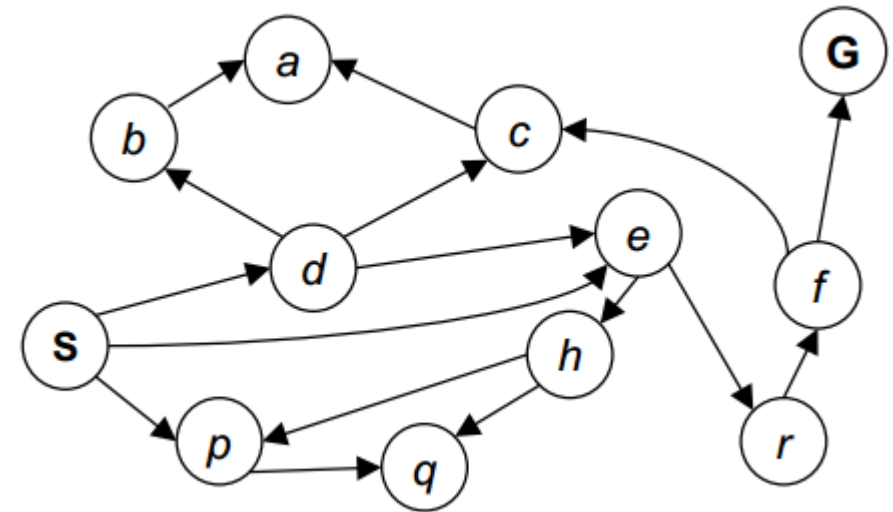
# Search Problem Formulation – Exercise 2

- 3 missionaries and 3 cannibals are on one side of a river
- A boat can hold one or two people.
- **NOT** allowed (on either side): # of cannibals > # of missionaries
- Find a way to get everyone to the other side

**Write a formulation for this search problem**

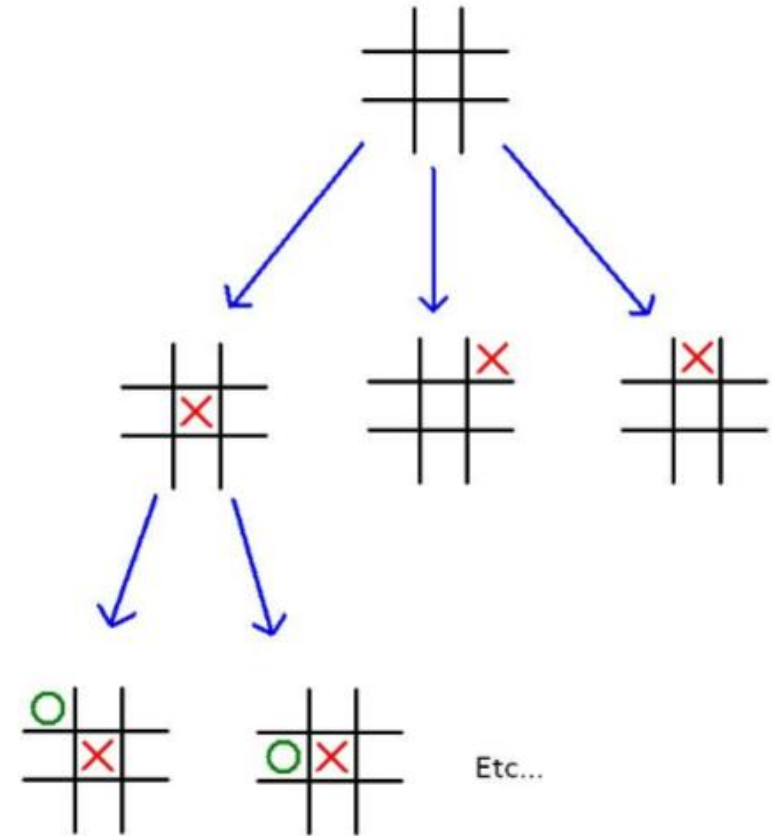
# State space graph

- Nodes are (abstracted) world configurations
- Arcs represent successors (action results)
- Goal test: one or a set of goal nodes
- Each state occurs only once!



# Search Tree

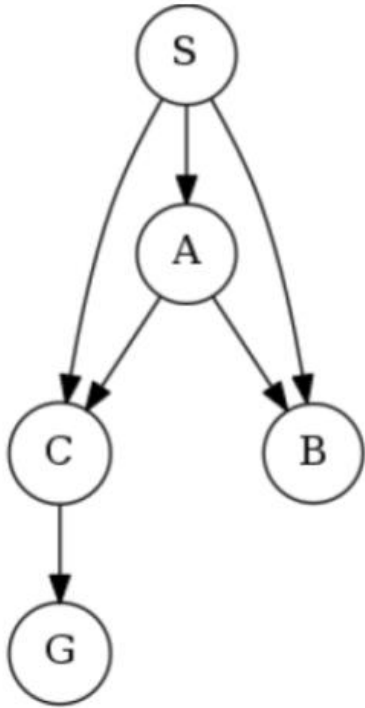
- A "what if" tree of plans and their outcomes
- Root: initial state
- Children: correspond to successors





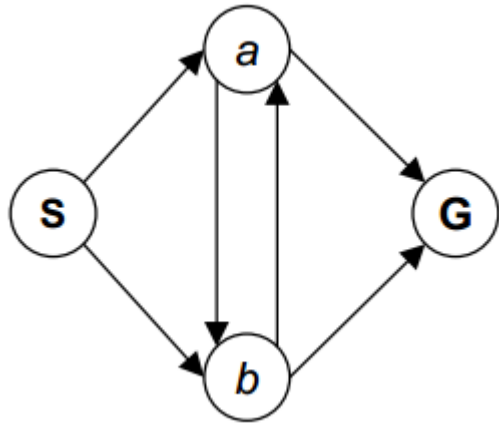
# Quiz

- How many nodes are there in this search tree?



# State Space Graph vs Search Tree

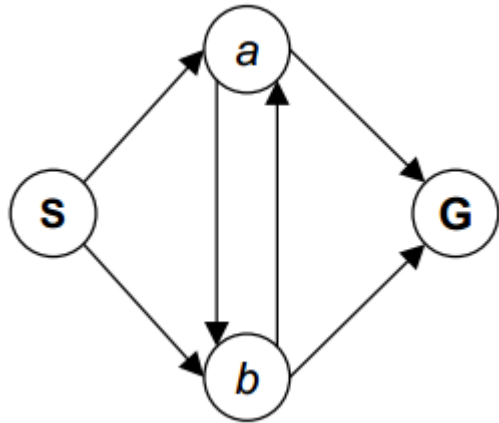
4-state graph



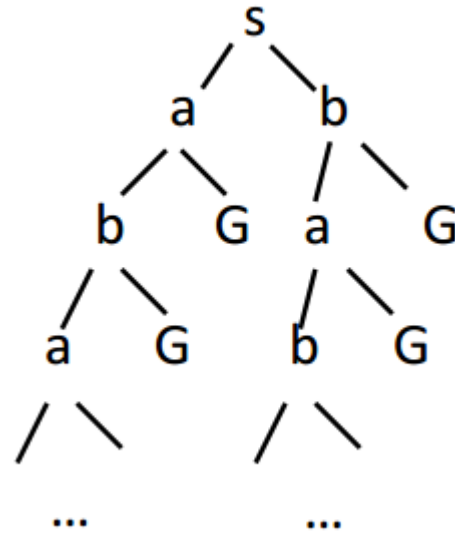
How big is the search tree?

# State Space Graph vs Search Tree

## 4-state graph

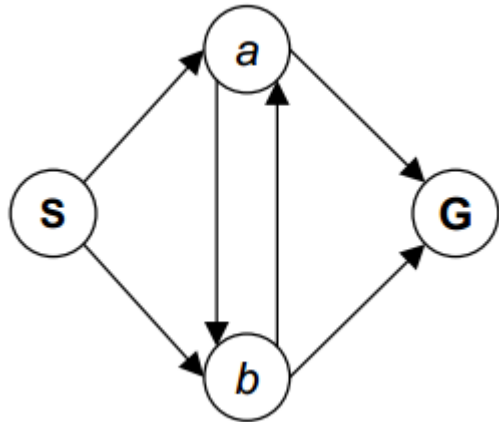


## How big is the search tree?

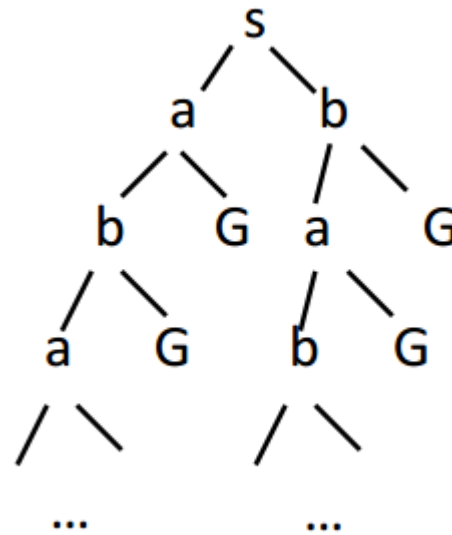

$$\infty$$

# State Space Graph vs Search Tree

## 4-state graph



## How big is the search tree?

 $\infty$ 

- Expand out potential tree nodes
- Maintain a fringe of partial plans under consideration
- Try to expand as few tree nodes as possible