```
G++ 2.91.57,cygnus\cygwin-b20\include\g++\stl_alloc.h 完整列表
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* purpose. It is provided "as is" without express or implied warranty.
/* NOTE: This is an internal header file, included by other STL headers.
  You should not attempt to use it directly.
#ifndef __SGI_STL_INTERNAL_ALLOC_H
#define __SGI_STL_INTERNAL_ALLOC_H
#ifdef ___SUNPRO_CC
# define __PRIVATE public
  // Extra access restrictions prevent us from really making some things
  // private.
#else
# define ___PRIVATE private
#endif
#ifdef __STL_STATIC_TEMPLATE_MEMBER_BUG
# define __USE_MALLOC
#endif
// This implements some standard node allocators. These are
// NOT the same as the allocators in the C++ draft standard or in
// in the original STL. They do not encapsulate different pointer
// types; indeed we assume that there is only one pointer type.
// The allocation primitives are intended to allocate individual objects,
\ensuremath{//} not larger arenas as with the original STL allocators.
#if 0
# include <new>
  define __THROW_BAD_ALLOC throw bad_alloc
#elif !defined(__THROW_BAD_ALLOC)
  include <iostream.h>
# define __THROW_BAD_ALLOC cerr << "out of memory" << endl; exit(1)</pre>
#endif
```

```
#ifndef __ALLOC
# define __ALLOC alloc
#endif
#ifdef __STL_WIN32THREADS
# include <windows.h>
#endif
#include <stddef.h>
#include <stdlib.h>
#include <string.h>
#include <assert.h>
#ifndef ___RESTRICT
# define __RESTRICT
#endif
#if !defined(__STL_PTHREADS) && !defined(_NOTHREADS) \
&& !defined(__STL_SGI_THREADS) && !defined(__STL_WIN32THREADS)
# define _NOTHREADS
#endif
# ifdef __STL_PTHREADS
   // POSIX Threads
   // This is dubious, since this is likely to be a high contention
   // lock. Performance may not be adequate.
  include <pthread.h>
  define __NODE_ALLOCATOR_LOCK \
      if (threads) pthread_mutex_lock(&__node_allocator_lock)
  define __NODE_ALLOCATOR_UNLOCK \
      if (threads) pthread_mutex_unlock(&__node_allocator_lock)
  define __NODE_ALLOCATOR_THREADS true
   define __VOLATILE volatile // Needed at -03 on SGI
# endif
# ifdef __STL_WIN32THREADS
   \ensuremath{//} The lock needs to be initialized by constructing an allocator
   // objects of the right type. We do that here explicitly for alloc.
   define __NODE_ALLOCATOR_LOCK \
      EnterCriticalSection(&__node_allocator_lock)
   define __NODE_ALLOCATOR_UNLOCK \
      LeaveCriticalSection(&__node_allocator_lock)
  define __NODE_ALLOCATOR_THREADS true
  define __VOLATILE volatile // may not be needed
# endif /* WIN32THREADS */
# ifdef __STL_SGI_THREADS
   \ensuremath{//} This should work without threads, with sproc threads, or with
   // pthreads. It is suboptimal in all cases.
   // It is unlikely to even compile on nonSGI machines.
   extern "C" {
    extern int __us_rsthread_malloc;
```

```
// The above is copied from malloc.h. Including <malloc.h>
      // would be cleaner but fails with certain levels of standard
      // conformance.
   define __NODE_ALLOCATOR_LOCK if (threads && __us_rsthread_malloc) \
             { __lock(&__node_allocator_lock); }
   define __NODE_ALLOCATOR_UNLOCK if (threads && __us_rsthread_malloc) \
            { __unlock(&__node_allocator_lock); }
   define __NODE_ALLOCATOR_THREADS true
   define __VOLATILE volatile // Needed at -03 on SGI
# endif
# ifdef _NOTHREADS
// Thread-unsafe
  define __NODE_ALLOCATOR_LOCK
   define __NODE_ALLOCATOR_UNLOCK
   define __NODE_ALLOCATOR_THREADS false
  define ___VOLATILE
# endif
 _STL_BEGIN_NAMESPACE
#if defined(__sgi) && !defined(__GNUC__) && (_MIPS_SIM != _MIPS_SIM_ABI32)
#pragma set woff 1174
#endif
// Malloc-based allocator. Typically slower than default alloc below.
// Typically thread-safe and more storage efficient.
#ifdef __STL_STATIC_TEMPLATE_MEMBER_BUG
# ifdef __DECLARE_GLOBALS_HERE
   void (* __malloc_alloc_oom_handler)() = 0;
   // g++ 2.7.2 does not handle static template data members.
# else
   extern void (* __malloc_alloc_oom_handler)();
# endif
#endif
template <int inst>
class __malloc_alloc_template {
private:
static void *oom_malloc(size_t);
static void *oom_realloc(void *, size_t);
#ifndef __STL_STATIC_TEMPLATE_MEMBER_BUG
   static void (* __malloc_alloc_oom_handler)();
#endif
```

```
public:
static void * allocate(size_t n)
   void *result = malloc(n);
   if (0 == result) result = oom_malloc(n);
   return result;
static void deallocate(void *p, size_t /* n */)
   free(p);
static void * reallocate(void *p, size_t /* old_sz */, size_t new_sz)
   void * result = realloc(p, new_sz);
   if (0 == result) result = oom_realloc(p, new_sz);
   return result;
static void (* set_malloc_handler(void (*f)()))()
   void (* old)() = __malloc_alloc_oom_handler;
   __malloc_alloc_oom_handler = f;
   return(old);
}
};
// malloc_alloc out-of-memory handling
#ifndef __STL_STATIC_TEMPLATE_MEMBER_BUG
template <int inst>
void (* __malloc_alloc_template<inst>::__malloc_alloc_oom_handler)() = 0;
template <int inst>
void * __malloc_alloc_template<inst>::oom_malloc(size_t n)
   void (* my_malloc_handler)();
   void *result;
   for (;;) {
      my_malloc_handler = __malloc_alloc_oom_handler;
      if (0 == my_malloc_handler) { __THROW_BAD_ALLOC; }
      (*my_malloc_handler)();
      result = malloc(n);
      if (result) return(result);
```

```
template <int inst>
void * __malloc_alloc_template<inst>::oom_realloc(void *p, size_t n)
   void (* my_malloc_handler)();
   void *result;
   for (;;) {
      my_malloc_handler = __malloc_alloc_oom_handler;
      if (0 == my_malloc_handler) { __THROW_BAD_ALLOC; }
      (*my_malloc_handler)();
      result = realloc(p, n);
      if (result) return(result);
}
typedef __malloc_alloc_template<0> malloc_alloc;
template<class T, class Alloc>
class simple_alloc {
public:
   static T *allocate(size_t n)
             { return 0 == n? 0 : (T*) Alloc::allocate(n * sizeof (T)); }
   static T *allocate(void)
             { return (T*) Alloc::allocate(sizeof (T)); }
   static void deallocate(T *p, size_t n)
             { if (0 != n) Alloc::deallocate(p, n * sizeof (T)); }
   static void deallocate(T *p)
             { Alloc::deallocate(p, sizeof (T)); }
};
// Allocator adaptor to check size arguments for debugging.
// Reports errors using assert. Checking can be disabled with
// NDEBUG, but it's far better to just use the underlying allocator
// instead when no checking is desired.
// There is some evidence that this can confuse Purify.
template <class Alloc>
class debug_alloc {
private:
enum {extra = 8};
                       // Size of space used to store size. Note
                    // that this must be large enough to preserve
                    // alignment.
public:
```

```
static void * allocate(size_t n)
   char *result = (char *)Alloc::allocate(n + extra);
   *(size_t *)result = n;
   return result + extra;
static void deallocate(void *p, size_t n)
   char * real_p = (char *)p - extra;
   assert(*(size_t *)real_p == n);
   Alloc::deallocate(real_p, n + extra);
static void * reallocate(void *p, size_t old_sz, size_t new_sz)
   char * real_p = (char *)p - extra;
   assert(*(size_t *)real_p == old_sz);
   char * result = (char *)
               Alloc::reallocate(real_p, old_sz + extra, new_sz + extra);
   *(size_t *)result = new_sz;
   return result + extra;
}
};
# ifdef __USE_MALLOC
typedef malloc_alloc alloc;
typedef malloc_alloc single_client_alloc;
# else
// Default node allocator.
// With a reasonable compiler, this should be roughly as fast as the
\ensuremath{//} original STL class-specific allocators, but with less fragmentation.
// Default_alloc_template parameters are experimental and MAY
\ensuremath{//} DISAPPEAR in the future. Clients should just use alloc for now.
//
// Important implementation properties:
// 1. If the client request an object of size > __MAX_BYTES, the resulting
   object will be obtained directly from malloc.
// 2. In all other cases, we allocate an object of size exactly
   ROUND_UP(requested_size). Thus the client has enough size
     information that we can return the object to the proper free list
```

```
without permanently losing part of the object.
\ensuremath{//} The first template parameter specifies whether more than one thread
\ensuremath{//} may use this allocator. It is safe to allocate an object from
\ensuremath{//} one instance of a default_alloc and deallocate it with another
// one. This effectively transfers its ownership to the second one.
// This may have undesirable effects on reference locality.
// The second parameter is unreferenced and serves only to allow the
// creation of multiple default_alloc instances.
// Node that containers built on different allocator instances have
// different types, limiting the utility of this approach.
#ifdef ___SUNPRO_CC
// breaks if we make these template class members:
 enum \{\_\_ALIGN = 8\};
 enum \{\_\_MAX\_BYTES = 128\};
 enum {__NFREELISTS = __MAX_BYTES/__ALIGN};
#endif
template <bool threads, int inst>
class __default_alloc_template {
private:
 // Really we should use static const int x = N
 // instead of enum \{ x = N \}, but few compilers accept the former.
# ifndef __SUNPRO_CC
   enum \{\_\_ALIGN = 8\};
   enum \{ \__MAX\_BYTES = 128 \};
   enum {__NFREELISTS = __MAX_BYTES/__ALIGN};
# endif
 static size_t ROUND_UP(size_t bytes) {
      return (((bytes) + __ALIGN-1) & ~(__ALIGN - 1));
 }
 _PRIVATE:
 union obj {
      union obj * free_list_link;
       char client_data[1]; /* The client sees this.
 };
private:
# ifdef __SUNPRO_CC
   static obj * __VOLATILE free_list[];
      // Specifying a size results in duplicate def for 4.1
# else
   static obj * __VOLATILE free_list[__NFREELISTS];
# endif
 static size_t FREELIST_INDEX(size_t bytes) {
       return (((bytes) + __ALIGN-1)/__ALIGN - 1);
```

```
// Returns an object of size n, and optionally adds to size n free list.
 static void *refill(size_t n);
 // Allocates a chunk for nobjs of size "size". nobjs may be reduced
 \ensuremath{//} if it is inconvenient to allocate the requested number.
 static char *chunk_alloc(size_t size, int &nobjs);
 // Chunk allocation state.
 static char *start_free;
 static char *end_free;
 static size_t heap_size;
# ifdef __STL_SGI_THREADS
   static volatile unsigned long __node_allocator_lock;
   static void __lock(volatile unsigned long *);
   static inline void __unlock(volatile unsigned long *);
# endif
# ifdef __STL_PTHREADS
   static pthread_mutex_t __node_allocator_lock;
# endif
# ifdef __STL_WIN32THREADS
   static CRITICAL_SECTION __node_allocator_lock;
   static bool __node_allocator_lock_initialized;
 public:
   __default_alloc_template() {
     // This assumes the first constructor is called before threads
      // are started.
      if (!__node_allocator_lock_initialized) {
         InitializeCriticalSection(&__node_allocator_lock);
          __node_allocator_lock_initialized = true;
       }
   }
 private:
# endif
   class lock {
      public:
          lock() { __NODE_ALLOCATOR_LOCK; }
          ~lock() { __NODE_ALLOCATOR_UNLOCK; }
   };
   friend class lock;
public:
 /* n must be > 0
 static void * allocate(size_t n)
  {
```

```
obj * __VOLATILE * my_free_list;
   obj * ___RESTRICT result;
   if (n > (size_t) \__{MAX\_BYTES}) {
      return(malloc_alloc::allocate(n));
   my_free_list = free_list + FREELIST_INDEX(n);
   // Acquire the lock here with a constructor call.
   // This ensures that it is released in exit or during stack
   // unwinding.
      ifndef _NOTHREADS
      /*REFERENCED*/
      lock lock_instance;
      endif
   result = *my_free_list;
   if (result == 0) {
      void *r = refill(ROUND_UP(n));
      return r;
   *my_free_list = result -> free_list_link;
  return (result);
 };
 /* p may not be 0 */
 static void deallocate(void *p, size_t n)
   obj *q = (obj *)p;
   obj * __VOLATILE * my_free_list;
   if (n > (size_t) __MAX_BYTES) {
      malloc_alloc::deallocate(p, n);
      return;
   my_free_list = free_list + FREELIST_INDEX(n);
   // acquire lock
      ifndef _NOTHREADS
      /*REFERENCED*/
      lock lock_instance;
      endif /* _NOTHREADS */
   q -> free_list_link = *my_free_list;
   *my_free_list = q;
   // lock is released here
 static void * reallocate(void *p, size_t old_sz, size_t new_sz);
} ;
typedef __default_alloc_template<__NODE_ALLOCATOR_THREADS, 0> alloc;
```

```
typedef __default_alloc_template<false, 0> single_client_alloc;
/* We allocate memory in large chunks in order to avoid fragmenting
/* the malloc heap too much.
/* We assume that size is properly aligned.
                                                                     * /
/* We hold the allocation lock.
template <bool threads, int inst>
char*
__default_alloc_template<threads, inst>::chunk_alloc(size_t size, int& nobjs)
   char * result;
   size_t total_bytes = size * nobjs;
   size_t bytes_left = end_free - start_free;
   if (bytes_left >= total_bytes) {
      result = start_free;
      start_free += total_bytes;
      return(result);
   } else if (bytes_left >= size) {
      nobjs = bytes_left/size;
      total_bytes = size * nobjs;
      result = start_free;
      start_free += total_bytes;
      return(result);
   } else {
      size_t bytes_to_get = 2 * total_bytes + ROUND_UP(heap_size >> 4);
      // Try to make use of the left-over piece.
      if (bytes_left > 0) {
          obj * ___VOLATILE * my_free_list =
                    free_list + FREELIST_INDEX(bytes_left);
          ((obj *)start_free) -> free_list_link = *my_free_list;
          *my_free_list = (obj *)start_free;
      start_free = (char *)malloc(bytes_to_get);
      if (0 == start_free) {
          int i;
          obj * ___VOLATILE * my_free_list, *p;
          // Try to make do with what we have. That can't
          \ensuremath{//} hurt. We do not try smaller requests, since that tends
          \ensuremath{//} to result in disaster on multi-process machines.
          for (i = size; i <= __MAX_BYTES; i += __ALIGN) {</pre>
             my_free_list = free_list + FREELIST_INDEX(i);
             p = *my_free_list;
             if (0 != p) {
                 *my_free_list = p -> free_list_link;
                 start_free = (char *)p;
```

```
end_free = start_free + i;
                return(chunk_alloc(size, nobjs));
                 \ensuremath{//} Any leftover piece will eventually make it to the
                 // right free list.
             }
         }
         end_free = 0;  // In case of exception.
         start_free = (char *)malloc_alloc::allocate(bytes_to_get);
          // This should either throw an exception
          // or remedy the situation. Thus we assume it
          // succeeded.
      heap_size += bytes_to_get;
      end_free = start_free + bytes_to_get;
      return(chunk_alloc(size, nobjs));
}
/* Returns an object of size n, and optionally adds to size n free list.*/
/* We assume that n is properly aligned.
                                                                    * /
/* We hold the allocation lock.
template <bool threads, int inst>
void* __default_alloc_template<threads, inst>::refill(size_t n)
{
   int nobjs = 20;
   char * chunk = chunk_alloc(n, nobjs);
   obj * __VOLATILE * my_free_list;
   obj * result;
   obj * current_obj, * next_obj;
   int i;
   if (1 == nobjs) return(chunk);
   my_free_list = free_list + FREELIST_INDEX(n);
   /* Build free list in chunk */
    result = (obj *)chunk;
     *my_free_list = next_obj = (obj *)(chunk + n);
    for (i = 1; ; i++) {
      current_obj = next_obj;
      next_obj = (obj *)((char *)next_obj + n);
      if (nobjs - 1 == i) {
         current_obj -> free_list_link = 0;
         break;
      } else {
          current_obj -> free_list_link = next_obj;
    }
   return(result);
```

```
}
template <bool threads, int inst>
void*
__default_alloc_template<threads, inst>::reallocate(void *p,
                                            size_t old_sz,
                                            size_t new_sz)
   void * result;
   size_t copy_sz;
   if (old_sz > (size_t) __MAX_BYTES && new_sz > (size_t) __MAX_BYTES) {
       return(realloc(p, new_sz));
   if (ROUND_UP(old_sz) == ROUND_UP(new_sz)) return(p);
   result = allocate(new_sz);
   copy_sz = new_sz > old_sz? old_sz : new_sz;
   memcpy(result, p, copy_sz);
   deallocate(p, old_sz);
   return(result);
}
#ifdef __STL_PTHREADS
   template <bool threads, int inst>
   pthread_mutex_t
   __default_alloc_template<threads, inst>::__node_allocator_lock
       = PTHREAD_MUTEX_INITIALIZER;
#endif
#ifdef __STL_WIN32THREADS
   template <bool threads, int inst> CRITICAL_SECTION
   __default_alloc_template<threads, inst>::__node_allocator_lock;
   template <bool threads, int inst> bool
   __default_alloc_template<threads, inst>::__node_allocator_lock_initialized
     = false;
#endif
#ifdef __STL_SGI_THREADS
 __STL_END_NAMESPACE
#include <mutex.h>
#include <time.h>
 _STL_BEGIN_NAMESPACE
\ensuremath{//} Somewhat generic lock implementations. We need only test-and-set
\ensuremath{//} and some way to sleep. These should work with both SGI pthreads
// and sproc threads. They may be useful on other systems.
template <bool threads, int inst>
volatile unsigned long
__default_alloc_template<threads, inst>::__node_allocator_lock = 0;
```

```
#if __mips < 3 | | !(defined (_ABIN32) | | defined(_ABI64)) | | defined(__GNUC__)
# define __test_and_set(1,v) test_and_set(1,v)
#endif
template <bool threads, int inst>
void
__default_alloc_template<threads, inst>::__lock(volatile unsigned long *lock)
{
   const unsigned low_spin_max = 30; // spin cycles if we suspect uniprocessor
   const unsigned high_spin_max = 1000; // spin cycles for multiprocessor
   static unsigned spin_max = low_spin_max;
   unsigned my_spin_max;
   static unsigned last_spins = 0;
   unsigned my_last_spins;
   static struct timespec ts = \{0, 1000\};
   unsigned junk;
  define __ALLOC_PAUSE junk *= junk; junk *= junk; junk *= junk; junk *= junk
   int i;
   if (!__test_and_set((unsigned long *)lock, 1)) {
      return;
   my_spin_max = spin_max;
   my_last_spins = last_spins;
   for (i = 0; i < my_spin_max; i++) {</pre>
      if (i < my_last_spins/2 || *lock) {</pre>
          __ALLOC_PAUSE;
          continue;
      if (!__test_and_set((unsigned long *)lock, 1)) {
          // got it!
          // Spinning worked. Thus we're probably not being scheduled
          // against the other process with which we were contending.
          // Thus it makes sense to spin longer the next time.
          last_spins = i;
          spin_max = high_spin_max;
          return;
      }
   }
   \ensuremath{//} We are probably being scheduled against the other process. Sleep.
   spin_max = low_spin_max;
   for (;;) {
      if (!__test_and_set((unsigned long *)lock, 1)) \{
          return;
      }
      nanosleep(&ts, 0);
   }
}
```

```
template <bool threads, int inst>
inline void
__default_alloc_template<threads, inst>::__unlock(volatile unsigned long *lock)
{
   if defined(\underline{\_GNUC}\underline{\_}) \&\& \underline{\_mips} >= 3
#
      asm("sync");
       *lock = 0;
   elif __mips >= 3 && (defined (_ABIN32) || defined(_ABI64))
       __lock_release(lock);
   else
      *lock = 0;
      // This is not sufficient on many multiprocessors, since
      \ensuremath{//} writes to protected variables and the lock may be reordered.
   endif
#endif
template <bool threads, int inst>
char *__default_alloc_template<threads, inst>::start_free = 0;
template <bool threads, int inst>
char *__default_alloc_template<threads, inst>::end_free = 0;
template <bool threads, int inst>
size_t __default_alloc_template<threads, inst>::heap_size = 0;
template <bool threads, int inst>
__default_alloc_template<threads, inst>::obj * __VOLATILE
__default_alloc_template<threads, inst> ::free_list[
# ifdef __SUNPRO_CC
   __NFREELISTS
# else
   __default_alloc_template<threads, inst>::__NFREELISTS
# endif
// The 16 zeros are necessary to make version 4.1 of the SunPro
// compiler happy. Otherwise it appears to allocate too little
// space for the array.
# ifdef __STL_WIN32THREADS
 // Create one to get critical section initialized.
 \ensuremath{//} We do this onece per file, but only the first constructor
 // does anything.
 static alloc __node_allocator_dummy_instance;
# endif
#endif /* ! __USE_MALLOC */
```

```
#if defined(__sgi) && !defined(__GNUC__) && (_MIPS_SIM != _MIPS_SIM_ABI32)
#pragma reset woff 1174
#endif

__STL_END_NAMESPACE
#undef __PRIVATE
#endif /* __SGI_STL_INTERNAL_ALLOC_H */

// Local Variables:
// mode:C++
// End:
```