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mobilenet-ssd

Use Case and High-Level Description

The **mobilenet-ssd** model is a Single-Shot multibox Detection (SSD) network intended to perform object detection. This model is implemented using the Caffe* framework. For details about this model, check out the [repository](#).

The model input is a blob that consists of a single image of **1, 3, 300, 300** in **BGR** order, also like the **densenet-121** model. The BGR mean values need to be subtracted as follows: [127.5, 127.5, 127.5] before passing the image blob into the network. In addition, values must be divided by 0.007843.

The model output is a typical vector containing the tracked object data, as previously described.

Specification

Metric	Value
Type	Detection
GFLOPs	2.316
MParams	5.783
Source framework	Caffe*

Accuracy

The accuracy results were obtained on test data from VOC2007 dataset.

Metric	Value
mAP	67.00%

See [the original repository](#).

Input

Original model

Image, name - **prob**, shape - **1, 3, 300, 300**, format is **B, C, H, W**, where:

- B** - batch size
- C** - channel
- H** - height
- W** - width

Channel order is **BGR**. Mean values - [127.5, 127.5, 127.5], scale value - 127.5.

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Converted model

Image, name - **prob**, shape - **1, 3, 300, 300**, format is **B, C, H, W**, where:

- **B** - batch size
- **C** - channel
- **H** - height
- **W** - width

Channel order is **BGR**

Output

Original model

The array of detection summary info, name - **detection_out**, shape - **1, 1, 100, 7** in the format **1, 1, N, 7**, where **N** is the number of detected bounding boxes. For each detection, the description has the format: [**image_id**, **label**, **conf**, **x_min**, **y_min**, **x_max**, **y_max**], where:

- **image_id** - ID of the image in the batch
- **label** - predicted class ID (1..20 - PASCAL VOC defined class ids). Mapping to class names provided by `<omz_dir>/data/dataset_classes/voc_20c1_bkgr.txt` file.
- **conf** - confidence for the predicted class
- (**x_min**, **y_min**) - coordinates of the top left bounding box corner (coordinates are in normalized format, in range [0, 1])
- (**x_max**, **y_max**) - coordinates of the bottom right bounding box corner (coordinates are in normalized format, in range [0, 1])

Converted model

The array of detection summary info, name - **detection_out**, shape - **1, 1, 100, 7** in the format **1, 1, N, 7**, where **N** is the number of detected bounding boxes. For each detection, the description has the format: [**image_id**, **label**, **conf**, **x_min**, **y_min**, **x_max**, **y_max**], where:

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Download a Model and Convert it into OpenVINO™ IR Format

You can download models and if necessary convert them into OpenVINO™ IR format using the [Model Downloader and other automation tools](#) as shown in the examples below.

An example of using the Model Downloader:

```
omz_downloader --name <model_name>
```

An example of using the Model Converter:

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Demo usage

The model can be used in the following demos provided by the Open Model Zoo to show its capabilities:

- [Single Human Pose Estimation Demo](#)

Legal Information

The original model is distributed under the following [license](#):

```
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```