

Order in the Underground – How to Automate the Drawing of Metro Maps

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GD 2005



Outline

1 Modeling the Metro Map Problem

- What is a metro map?
- Hard and soft constraints

2 Our Solution

- Mixed-integer programming formulation
- Experiments
- Labeling

3 NP-Hardness

- Rectilinear vs. octilinear drawing
- Reduction from planar 3-SAT



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What is a Metro Map?



- schematic diagram for public transport
- visualizes lines and stations
- goal: ease navigation for passengers
 - “How do I get from A to B?”
 - “Where to get off and change trains?”
- distorts geometry and scale
- improves readability
- compromise between schematic road map ↔ abstract graph



More Formally

The Metro Map Problem

Given: planar embedded graph $G = (V, E)$, $V \subset \mathbb{R}^2$,
line cover \mathcal{L} of paths or cycles in G (the metro lines),
Goal: draw G and \mathcal{L} **nicely**.



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 - hard constraints – must be fulfilled,
 - soft constraints – should hold as tightly as possible.



Hard Constraints

(H1) preserve embedding of G



U-Bahn in Wien

09/2003 ©1996-2003 H. Pröller
Travelys.com
Vienna U-Bahn
Kundenzentrum



Hard Constraints

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 - (H2) draw all edges as **octilinear** line segments,
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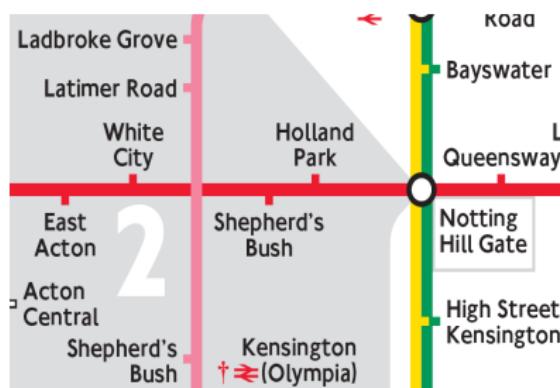
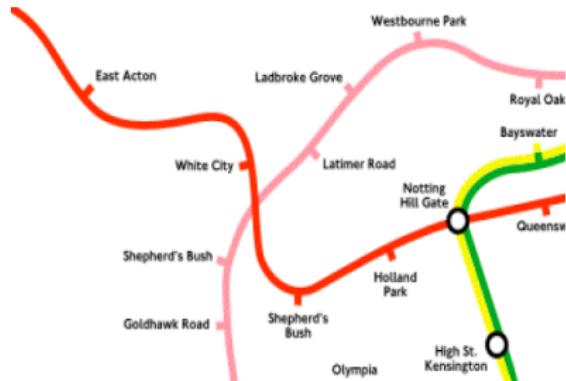
Hard Constraints

- (H1) preserve embedding of G
- (H2) draw all edges as **octilinear** line segments,
i.e., parallel to a coordinate axes or at 45° degrees
- (H3) draw each edge e with length $\geq \ell_e$
- (H4) keep vertices d_{\min} away from non-incident edges



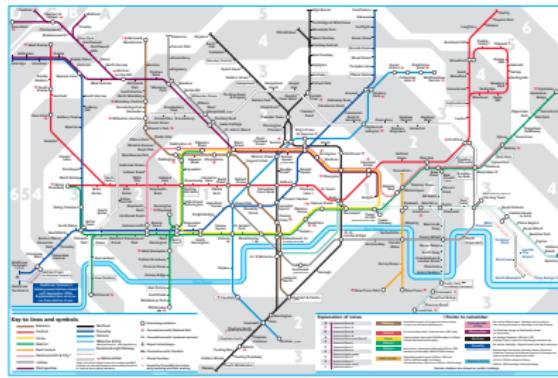
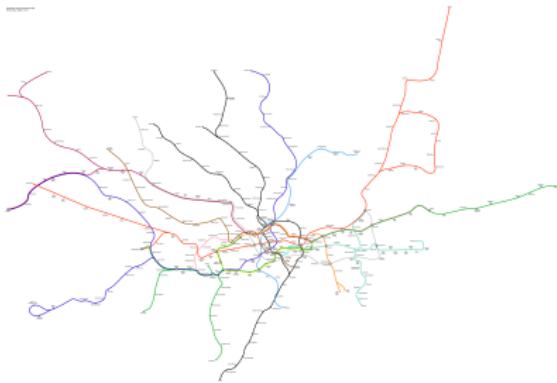
Soft Constraints

(S1) draw metro lines with few bends



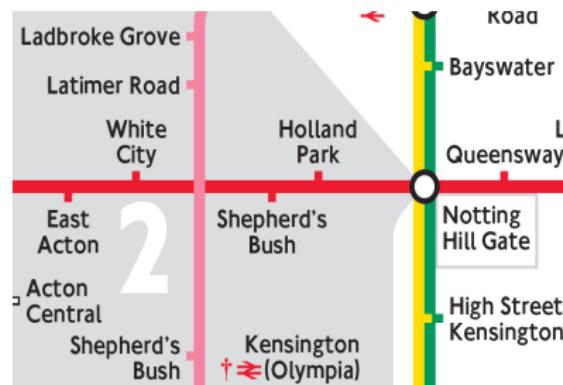
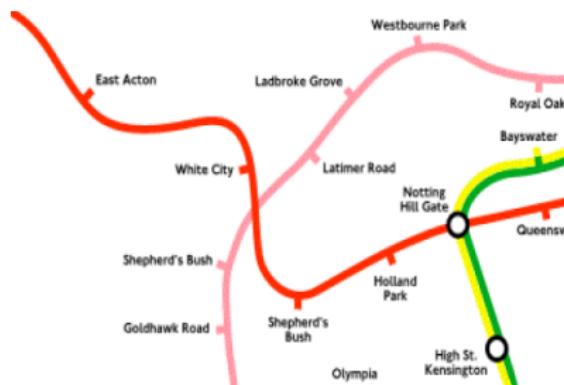
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- (S2) keep total edge length small



Soft Constraints

- (S1) draw metro lines with few bends
- (S2) keep total edge length small
- (S3) draw each octilinear edge similar to its geographical orientation: keep its **relative position**



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Mathematical Programming

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Theorem (Nöllenburg & Wolff GD'05)

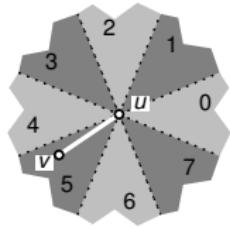
*The problem MetroMapLayout can be formulated as a MIP s.th.
linear constraints → hard constraints,
objective function → soft constraints.*



Example: Octilinearity and Relative Position



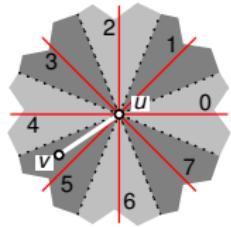
Example: Octilinearity and Relative Position



Sectors

- for each vtx. u partition plane into sectors 0–7
 - here: $\text{sec}(u, v) = 5$ (input)

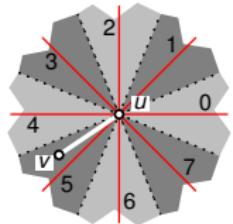
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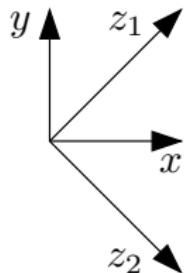
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 - e.g., $\text{dir}(u, v) = 4$ (output)

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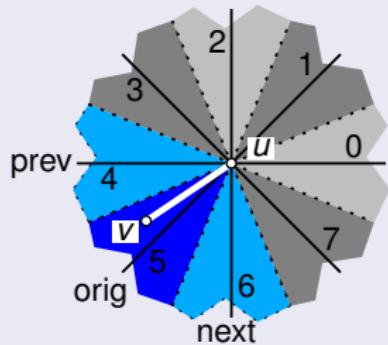
Coordinates

assign z_1 - and z_2 -coordinates to each vertex v :

- $z_1(v) = x(v) + y(v)$
- $z_2(v) = x(v) - y(v)$

Example: Octilinearity and Relative Position

Goal

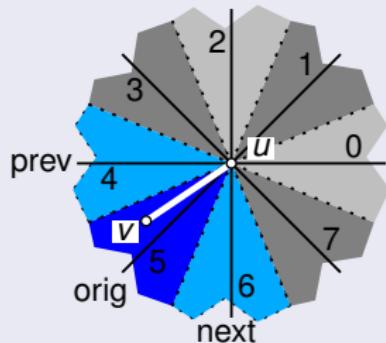


Draw edge uv

- with minimum length ℓ_{uv}
- restricted to 3 directions

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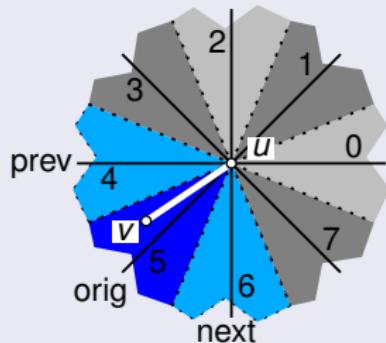
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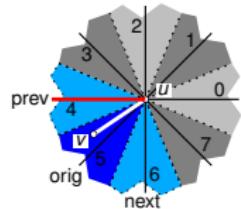
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How to model this using linear constraints?

Binary Variables

$$\alpha_{\text{prev}}(u, v) + \alpha_{\text{orig}}(u, v) + \alpha_{\text{next}}(u, v) = 1$$

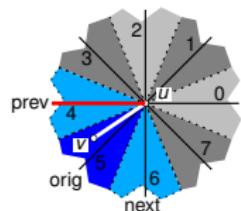
Example: Octilinearity and Relative Position



Previous Sector

$$\begin{aligned}y(u) - y(v) &\leq M(1 - \alpha_{\text{prev}}(u, v)) \\-y(u) + y(v) &\leq M(1 - \alpha_{\text{prev}}(u, v)) \\x(u) - x(v) &\geq -M(1 - \alpha_{\text{prev}}(u, v)) + \ell_{uv}\end{aligned}$$

Example: Octilinearity and Relative Position

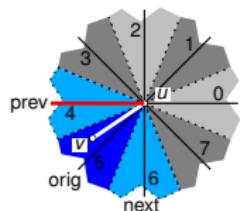


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Example: Octilinearity and Relative Position



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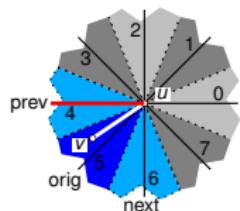
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How does this work?

Case 1: $\alpha_{\text{prev}}(u, v) = 0$

$$\begin{aligned}y(u) - y(v) &\leq M \\-y(u) + y(v) &\leq M \\x(u) - x(v) &\geq \ell_{uv} - M\end{aligned}$$

Example: Octilinearity and Relative Position



Previous Sector

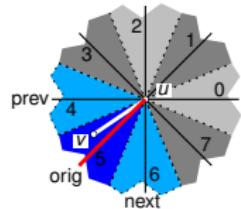
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Case 2: $\alpha_{\text{prev}}(u, v) = 1$

$$\begin{aligned}y(u) - y(v) &\leq 0 \\-y(u) + y(v) &\leq 0 \\x(u) - x(v) &\geq \ell_{uv}\end{aligned}$$

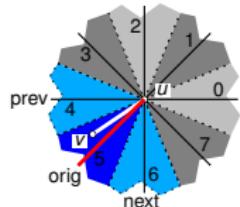
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Original Sector

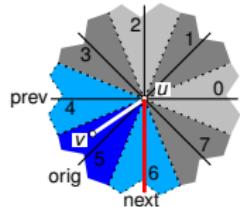
$$\begin{aligned} z_2(u) - z_2(v) &\leq M(1 - \alpha_{\text{orig}}(u, v)) \\ -z_2(u) + z_2(v) &\leq M(1 - \alpha_{\text{orig}}(u, v)) \\ z_1(u) - z_1(v) &\geq -M(1 - \alpha_{\text{orig}}(u, v)) + 2\ell_{uv} \end{aligned}$$

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Next Sector

$$\begin{aligned} x(u) - x(v) &\leq M(1 - \alpha_{\text{next}}(u, v)) \\ -x(u) + x(v) &\leq M(1 - \alpha_{\text{next}}(u, v)) \\ y(u) - y(v) &\geq -M(1 - \alpha_{\text{next}}(u, v)) + \ell_{uv} \end{aligned}$$

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- The above constraints enforce
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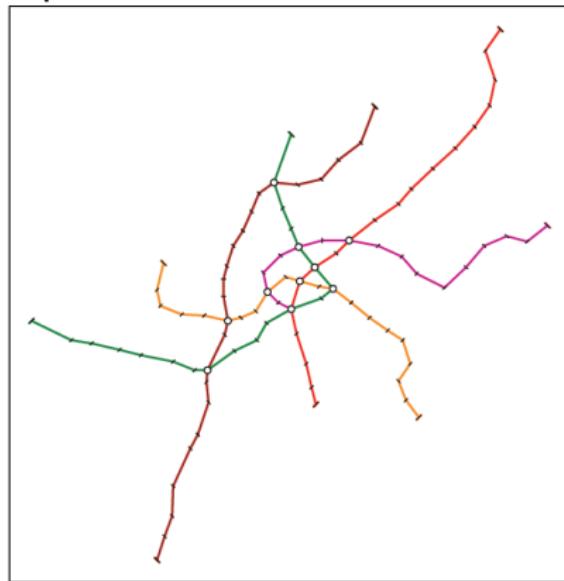
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Results – Vienna

Input



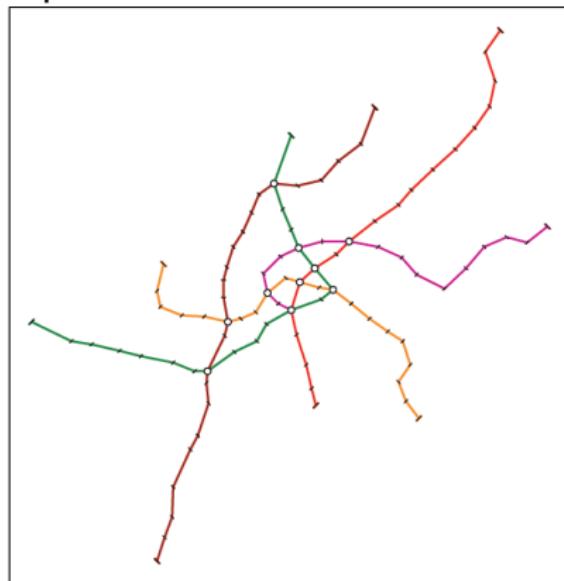
Input

	$ V $	$ E $	lines
normal	90	96	
reduced	44	50	5



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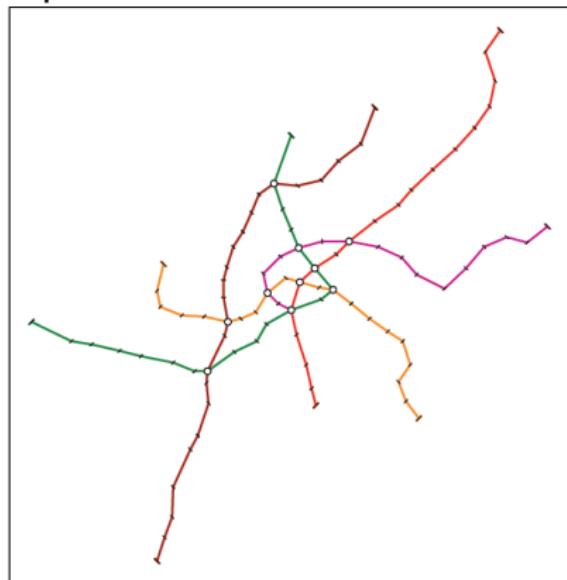


MIP	constr.	var.
normal	39363	9960
improved	23226	6048
heuristic 1	5703	1800
heuristic 2	1875	872



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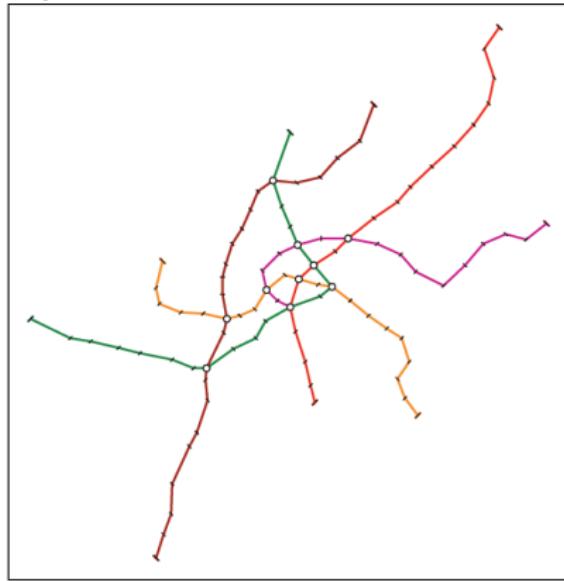
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*) 29 seconds w/o proof of opt.

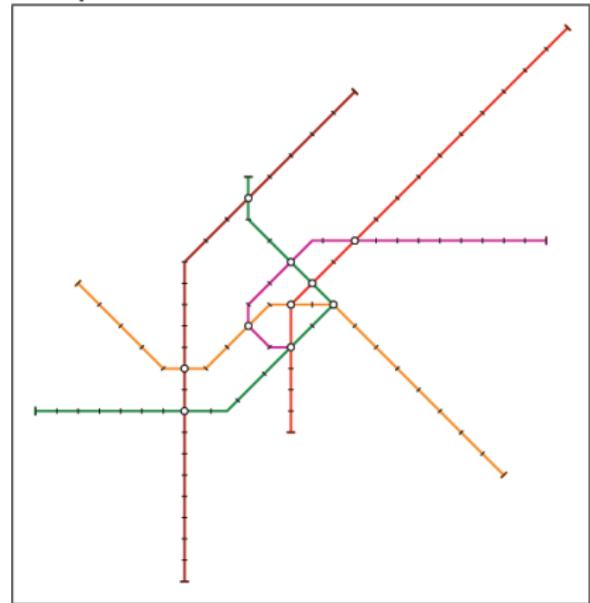


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Input



Output

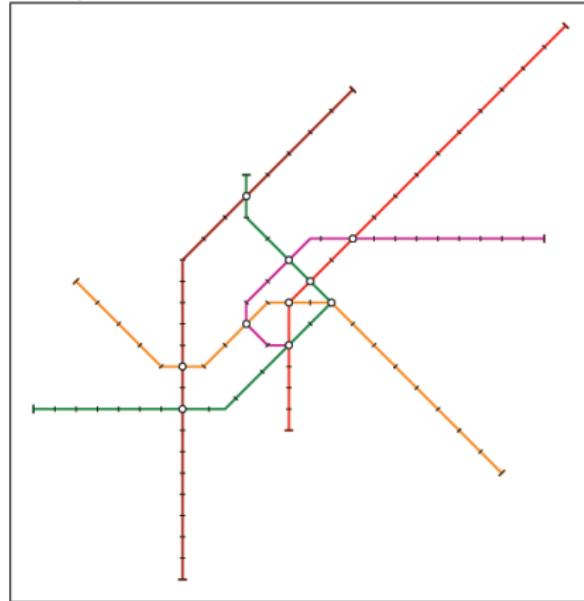


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Official map

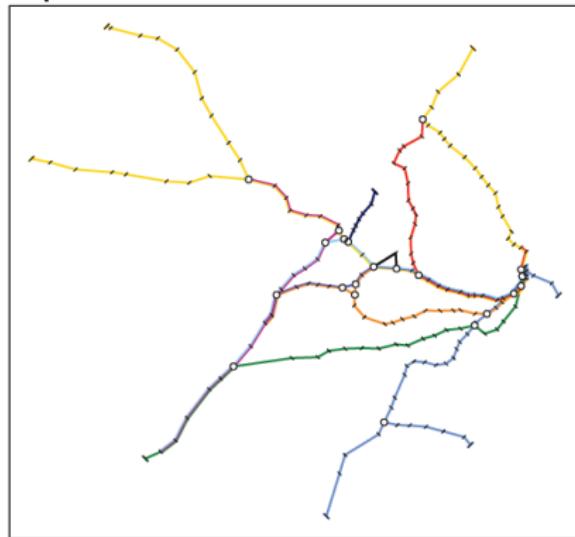


Output



Results – Sydney

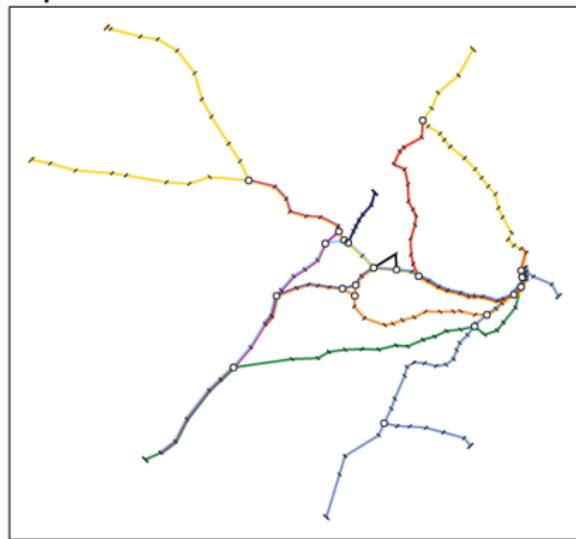
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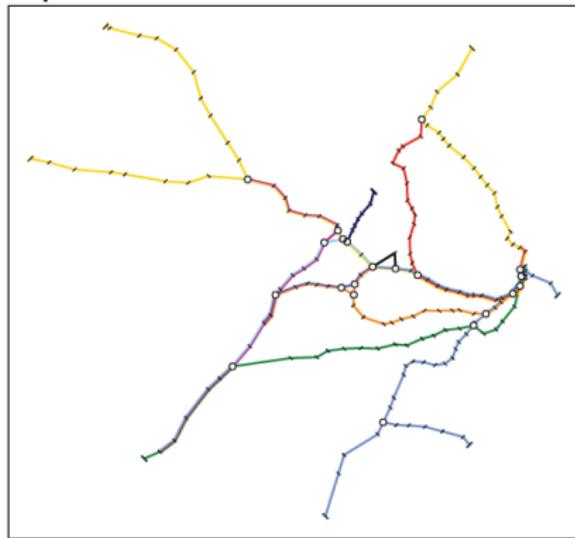


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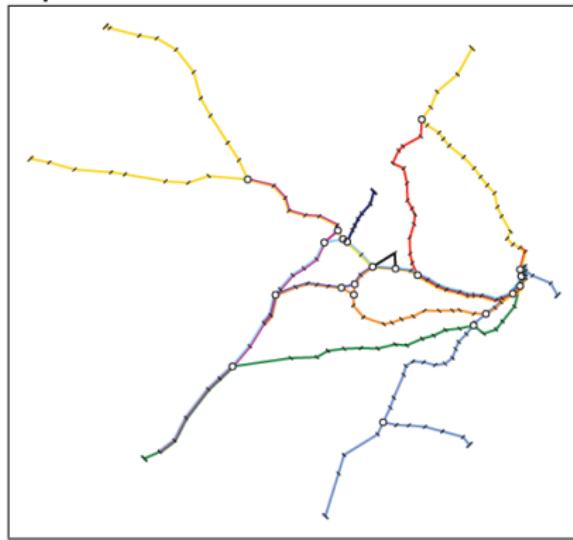
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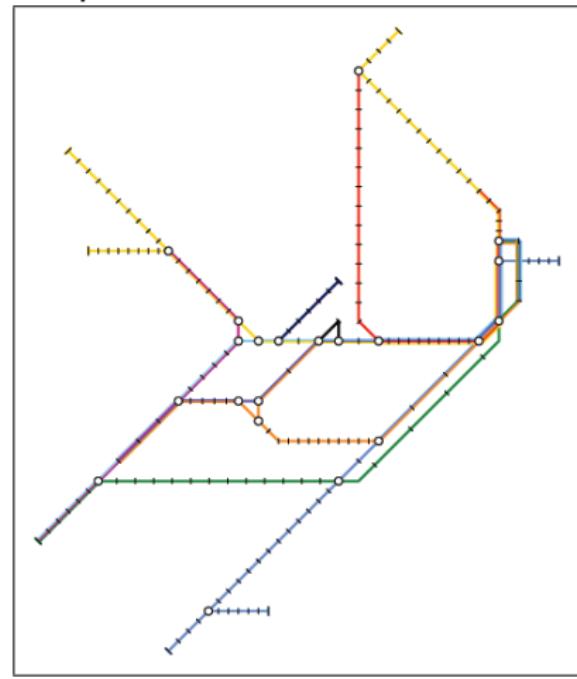


Results – Sydney

Input

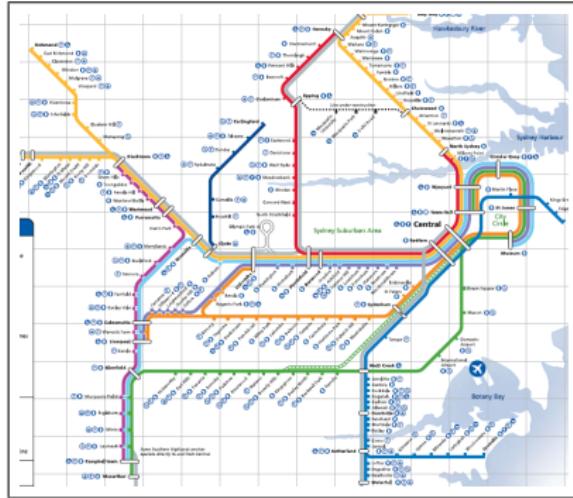


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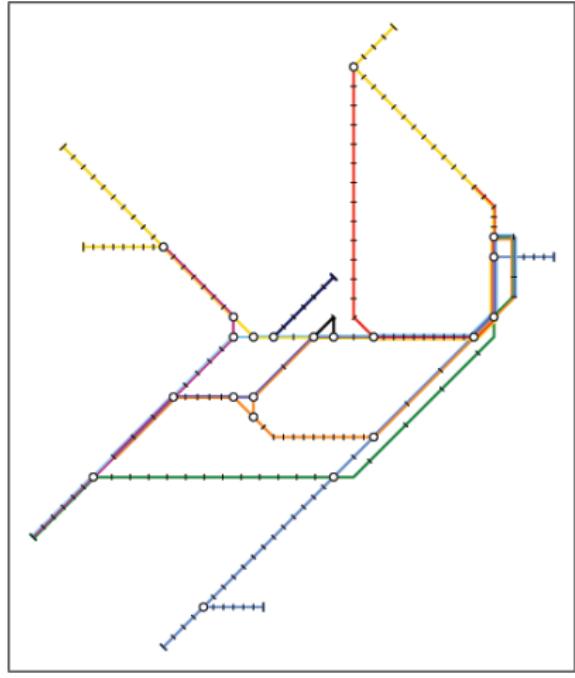


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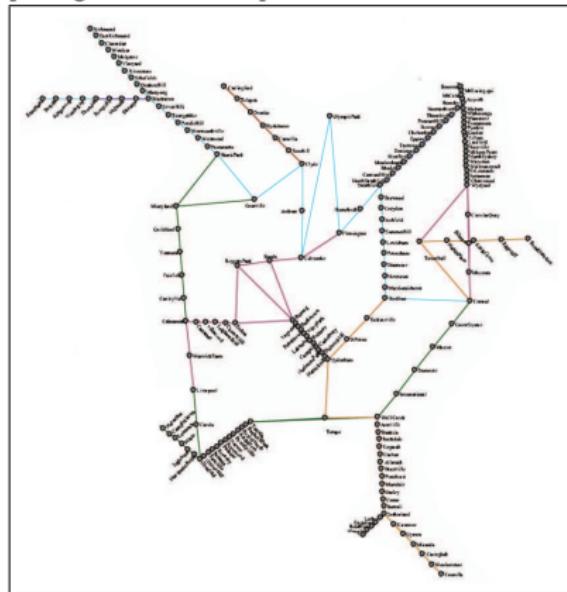


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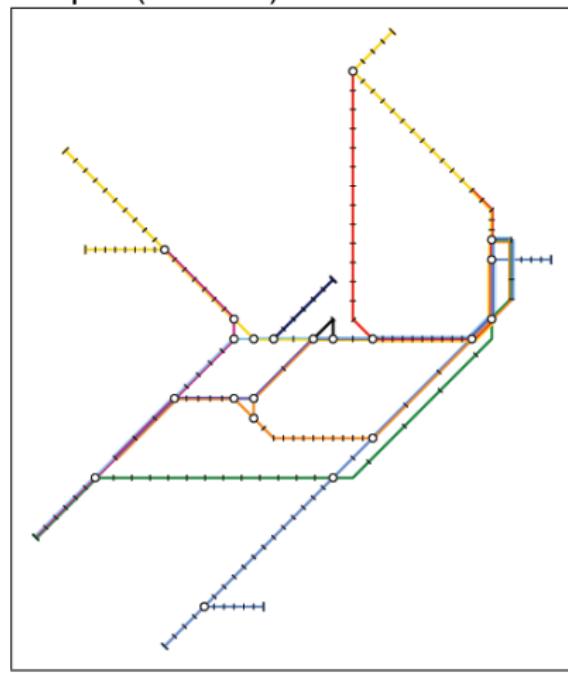


Sydney: Related Work

[Hong et al.: GD04] 7.6 sec.

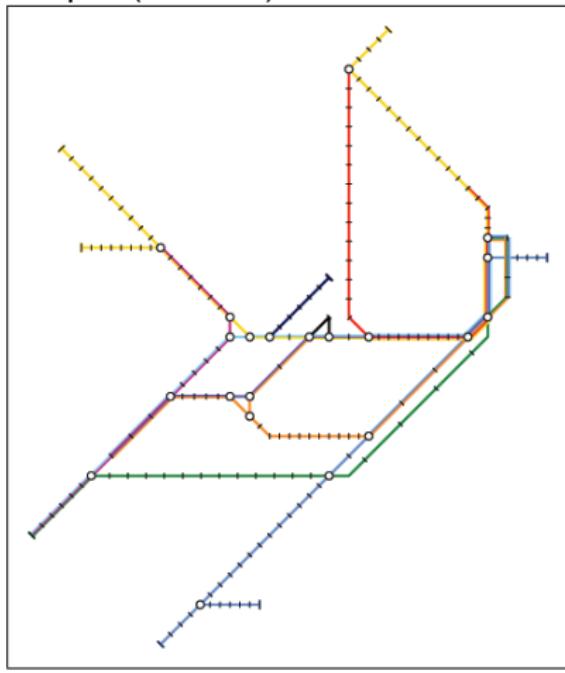
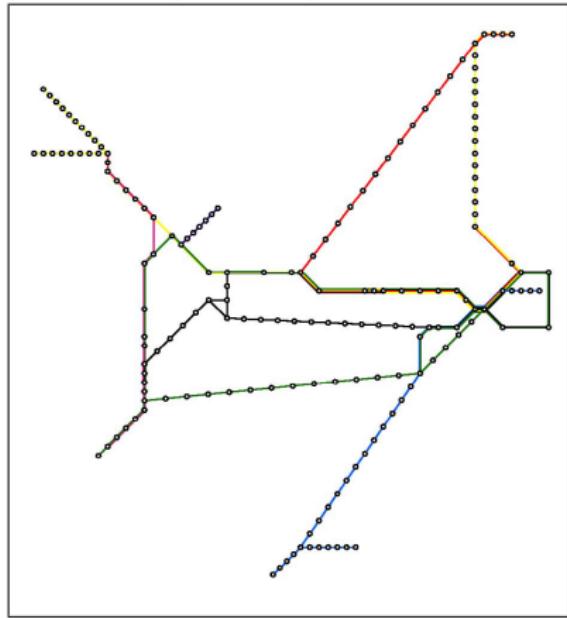


Output (22 min.)



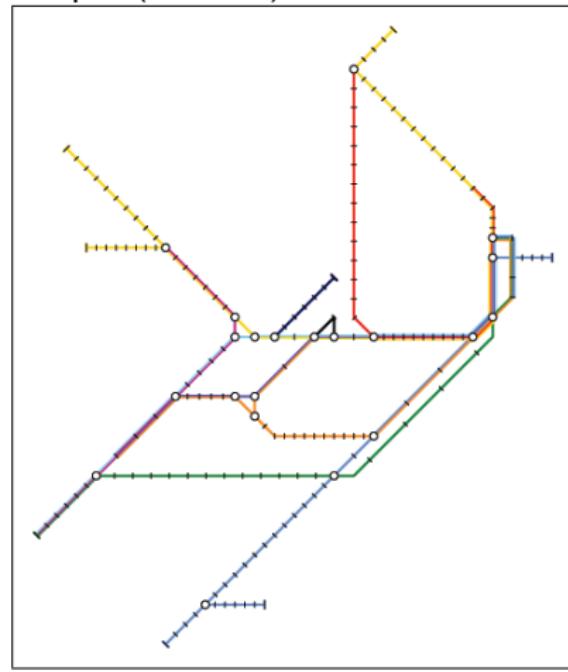
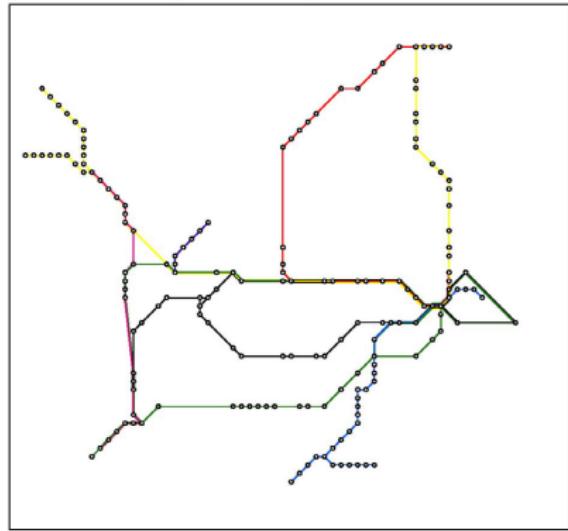
Sydney: Related Work

[Stott & Rodgers: IV04] reduced: 4 min. Output (22 min.)

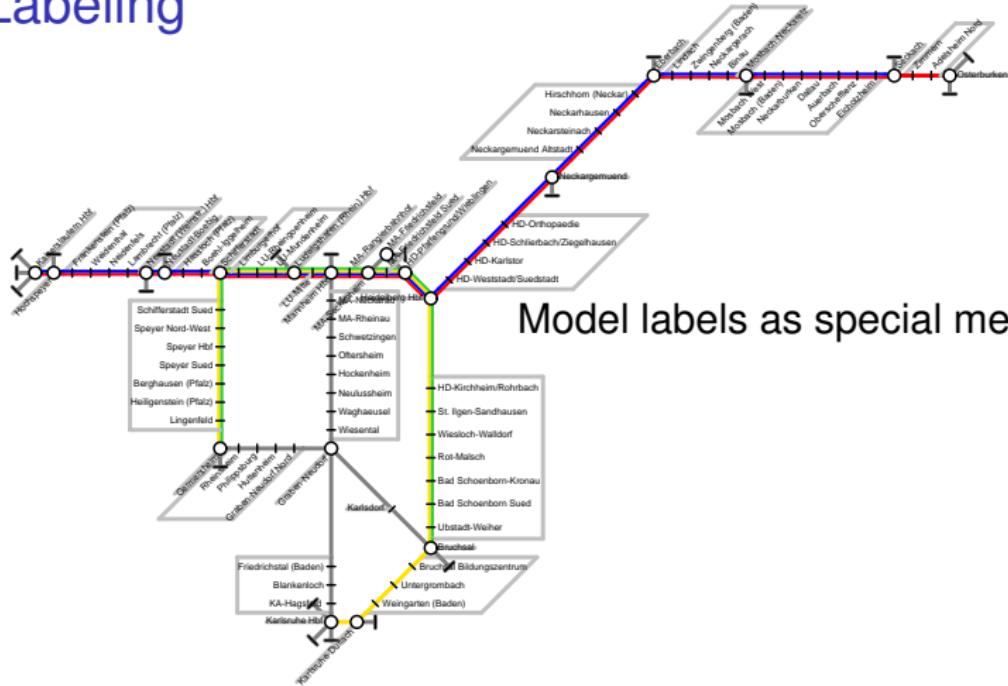


Sydney: Related Work

[Stott & Rodgers: IV04] normal: 28 min. Output (22 min.)



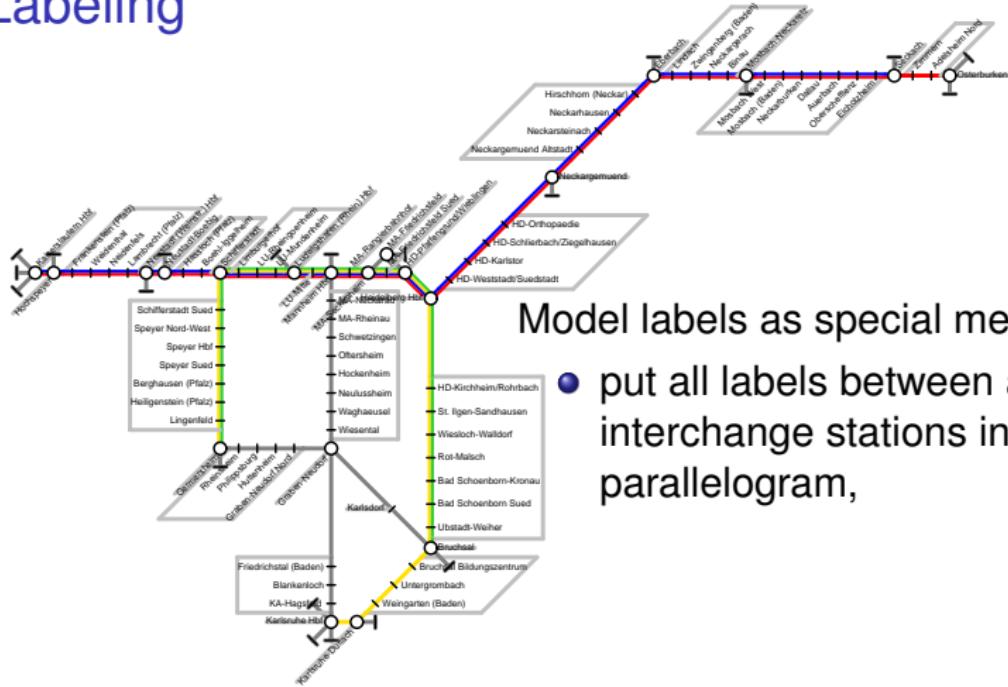
Labeling



Model labels as special metro lines:



Labeling

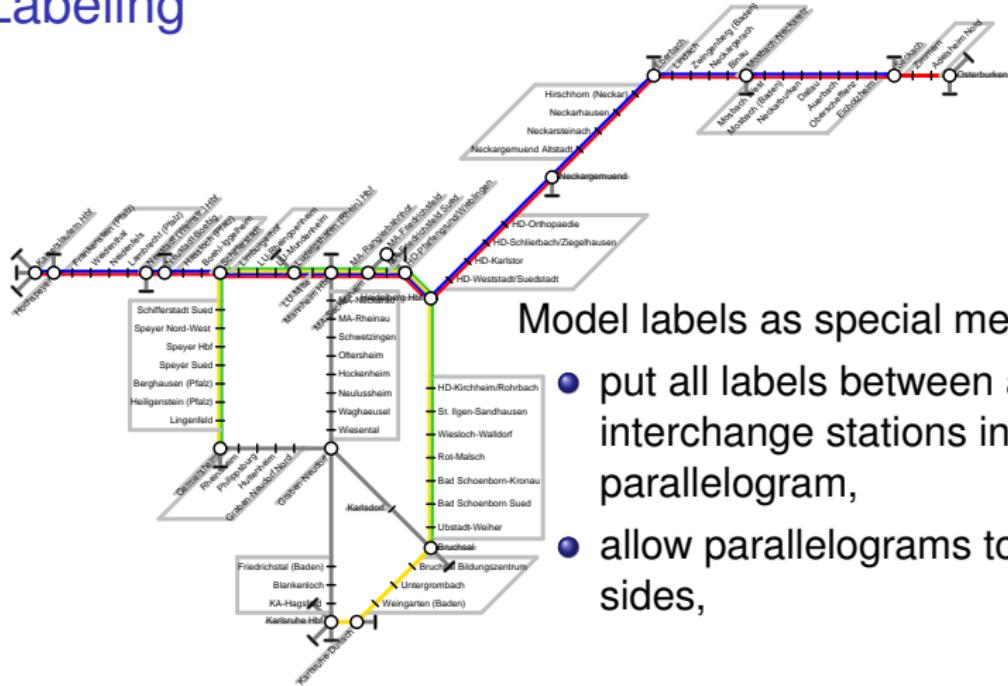


Model labels as special metro lines:

- put all labels between a pair of interchange stations into one parallelogram,



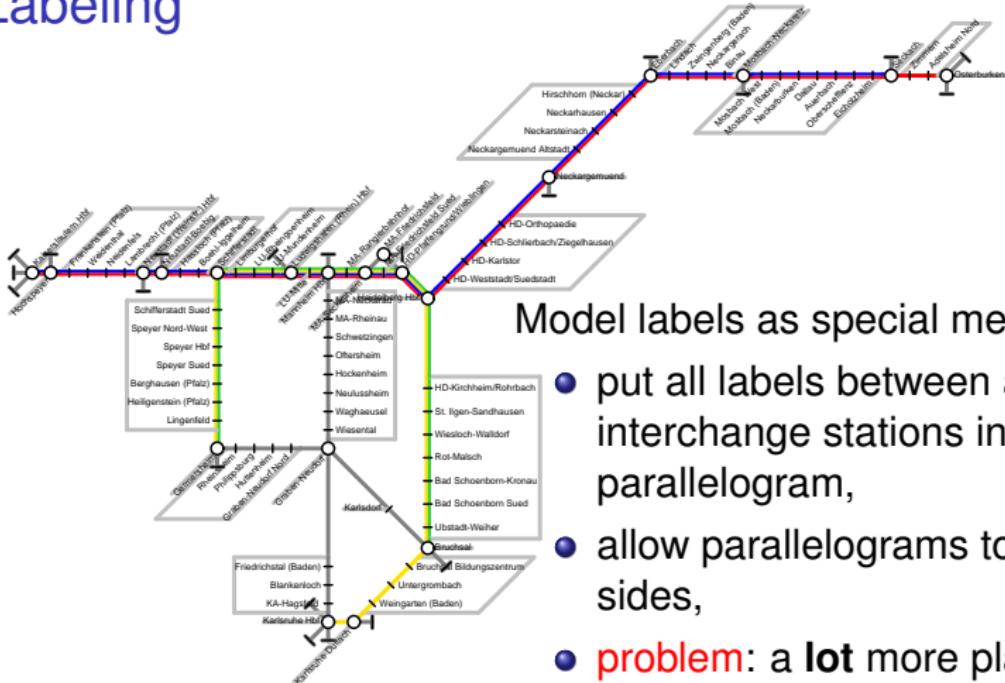
Labeling



Model labels as special metro lines:

- put all labels between a pair of interchange stations into one parallelogram,
 - allow parallelograms to change sides,

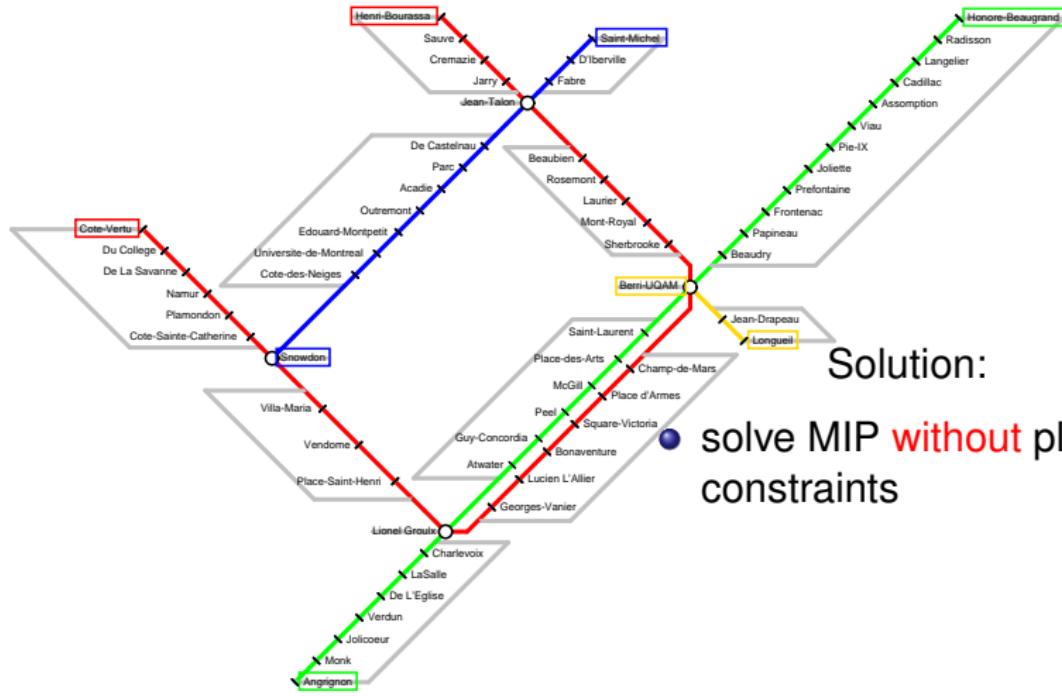
Labeling



Model labels as special metro lines:

- put all labels between a pair of interchange stations into one parallelogram,
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 - **problem:** a **lot** more planarity constraints :-(

Labeling

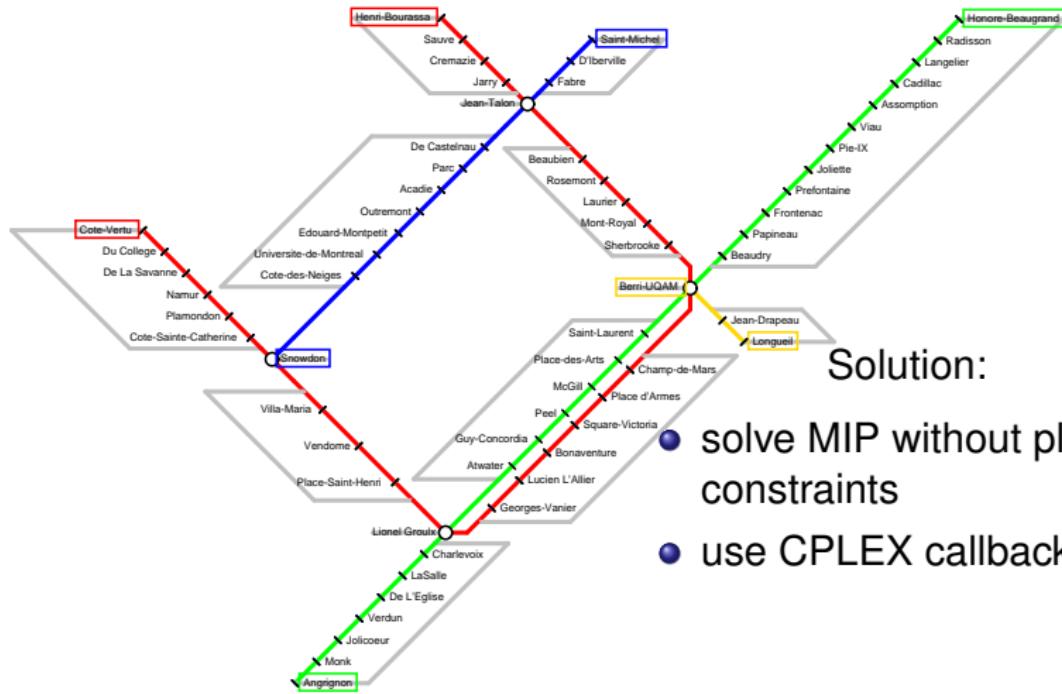


Solution:

- solve MIP without planarity constraints



Labeling

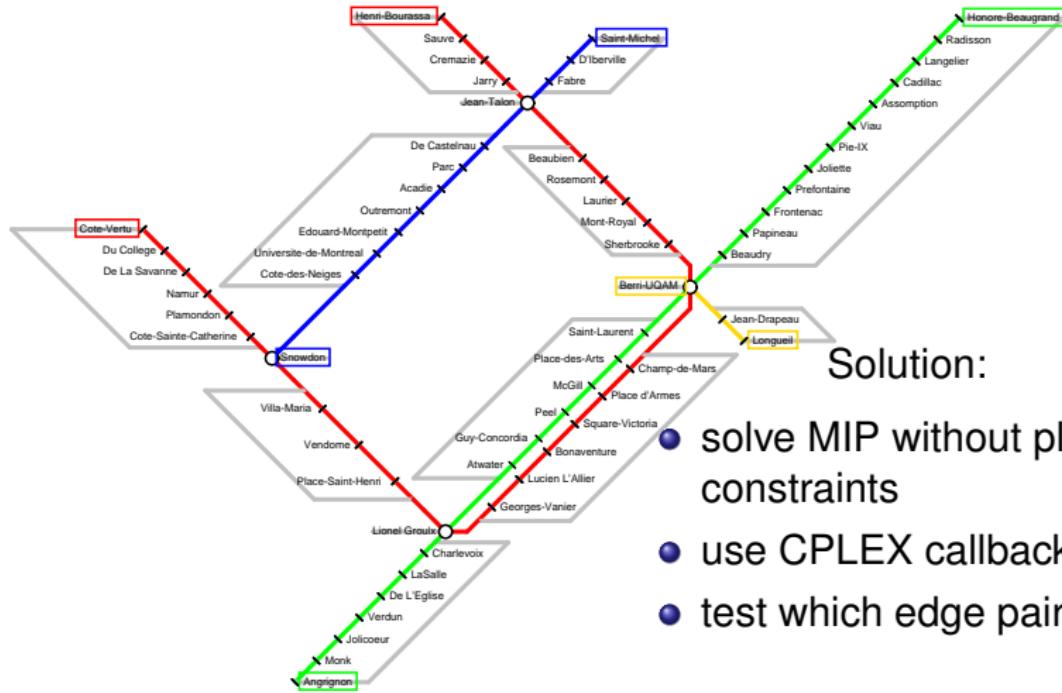


Solution:

- solve MIP without planarity constraints
- use CPLEX callback fct.



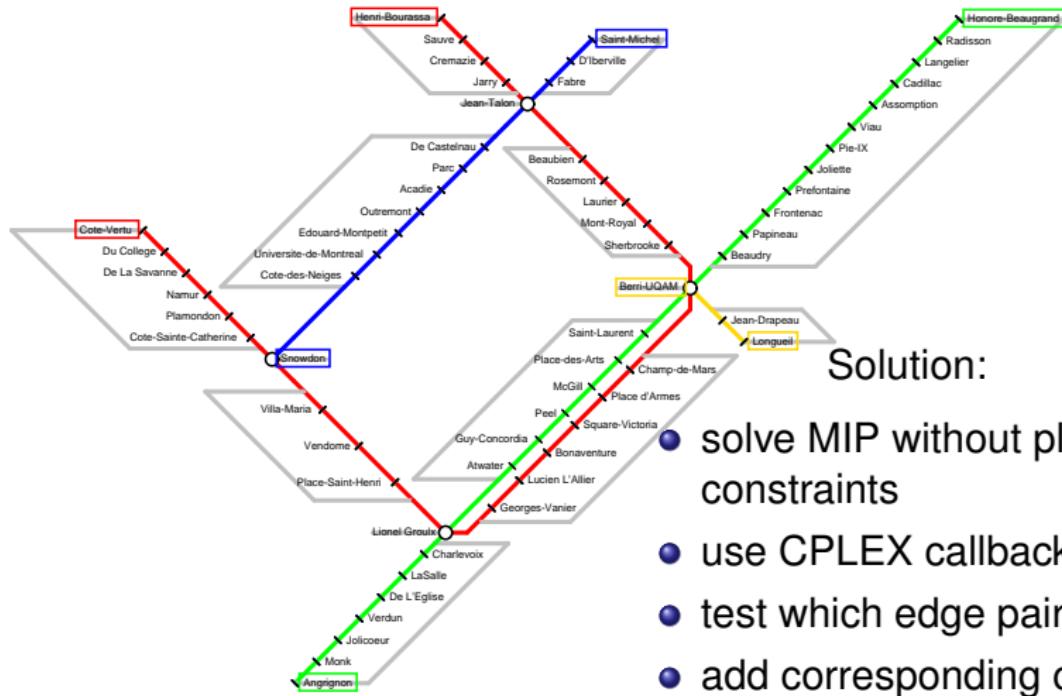
Labeling



Solution:

- solve MIP without planarity constraints
- use CPLEX callback fct.
- test which edge pairs cross

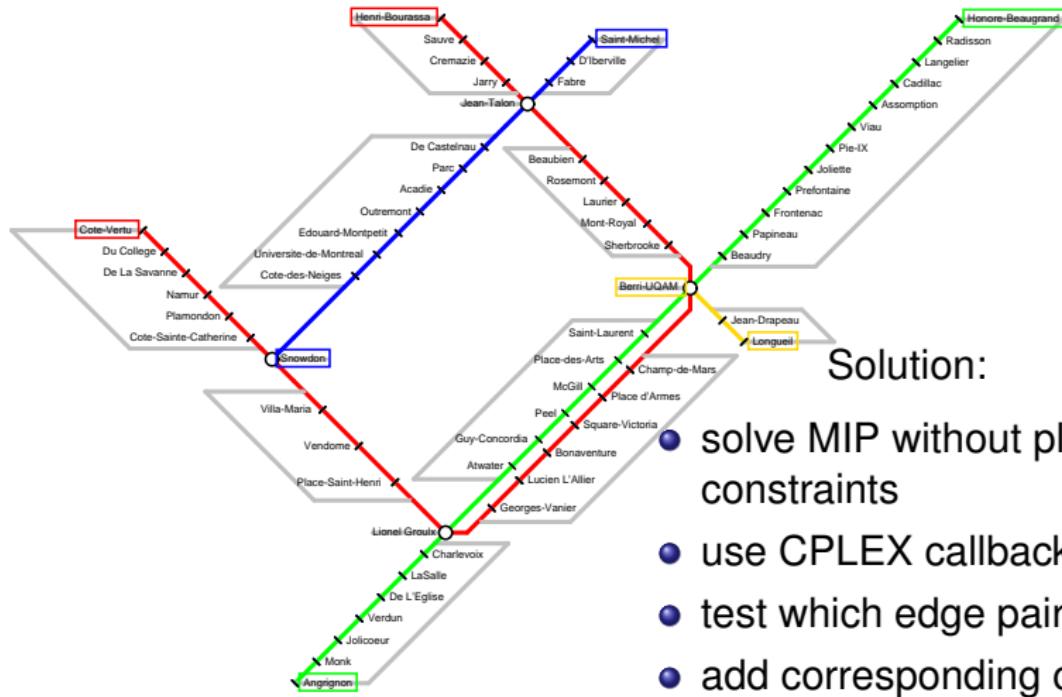
Labeling



Solution:

- solve MIP without planarity constraints
- use CPLEX callback fct.
- test which edge pairs cross
- add corresponding constr.

Labeling

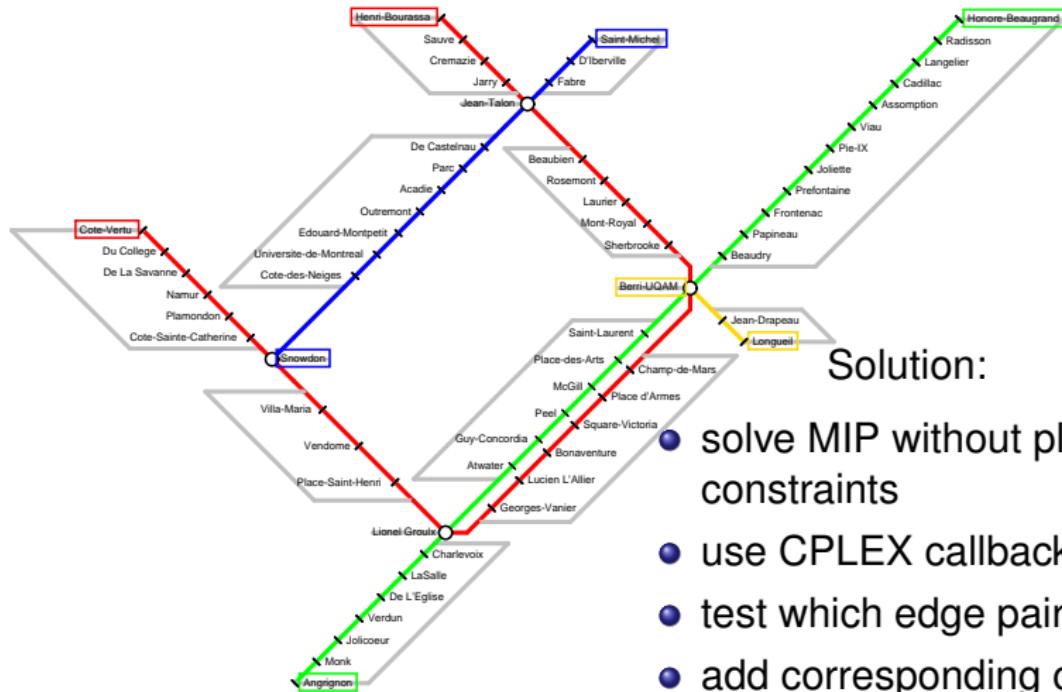


Solution:

- solve MIP without planarity constraints
- use CPLEX callback fct.
- test which edge pairs cross
- add corresponding constr.
- continue to solve MIP



Labeling



Solution:

- solve MIP without planarity constraints
- use CPLEX callback fct.
- test which edge pairs cross
- add corresponding constr.
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Montréal: 17 min.



Labeling



Wien: 1 day.

Labeling



Tokyo: < 10 sec.

[Kameda & Imai: IEICE'03]

Outline

1 Modeling the Metro Map Problem

- What is a metro map?
- Hard and soft constraints

2 Our Solution

- Mixed-integer programming formulation
- Experiments
- Labeling

3 NP-Hardness

- Rectilinear vs. octilinear drawing
- Reduction from planar 3-SAT



Another Problem

RECTILINEARGRAPHDRAWING Decision Problem

Given a planar embedded graph G with max degree 4.

Is there a drawing of G that

- preserves the embedding,
- uses straight-line edges,
- is rectilinear?



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Our Problem

METROMAPLAYOUT Decision Problem

Given a planar embedded graph G with max degree 8.

Is there a drawing of G that

- preserves the embedding,
- uses straight-line edges,
- is octilinear?

Theorem (Nöllenburg Master's Thesis'05)

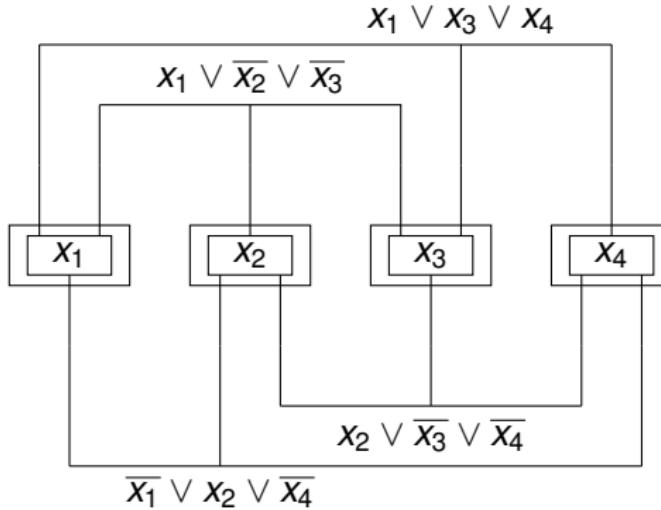
METROMAPLAYOUT is NP-hard.

Proof.

Reduction from PLANAR 3-SAT to METROMAPLAYOUT.

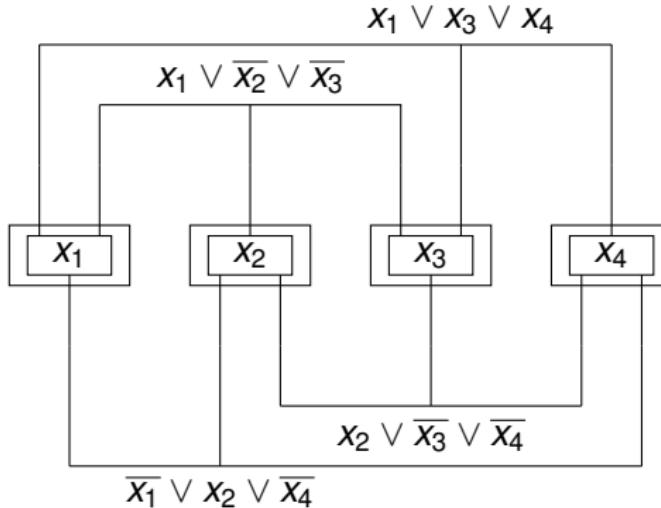


Outline of the Reduction



Input: planar 3-SAT formula $\varphi = (x_1 \vee x_3 \vee x_4) \wedge (x_1 \vee \overline{x}_2 \vee \overline{x}_3) \wedge \dots$

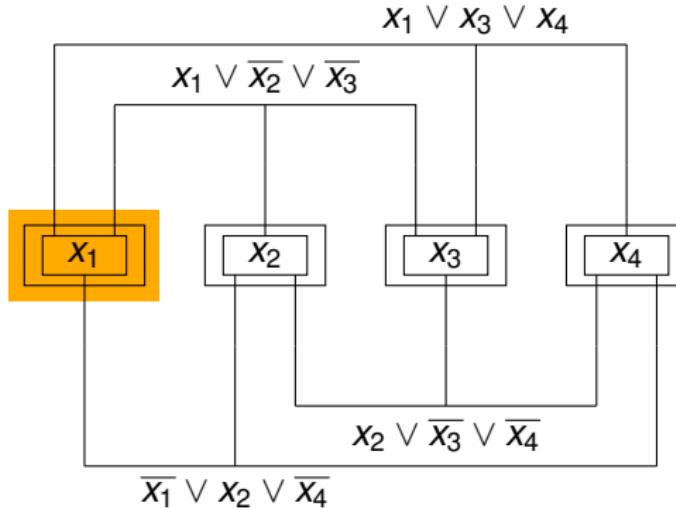
Outline of the Reduction



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Goal: planar embedded graph G_φ with:
 G_φ has a metro map drawing $\Leftrightarrow \varphi$ satisfiable.

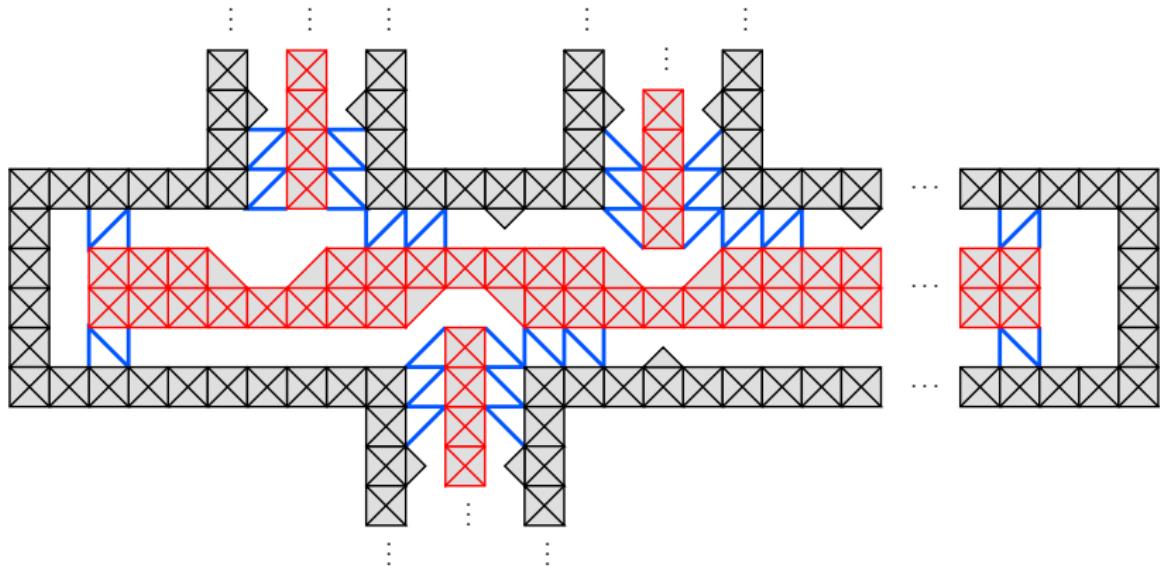
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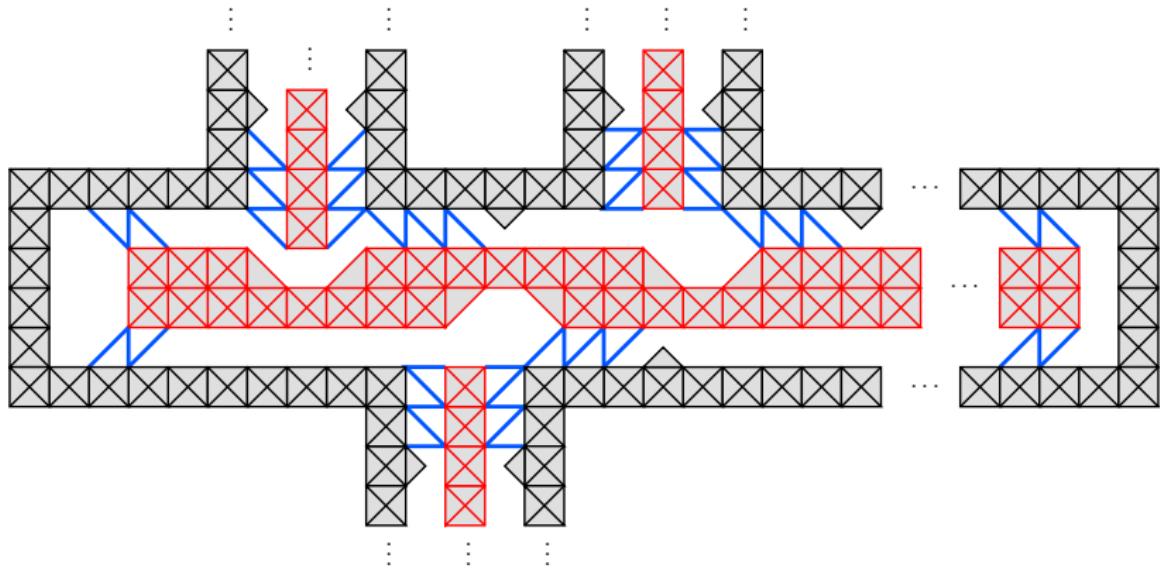
Variable Gadget



$x = \text{true}$



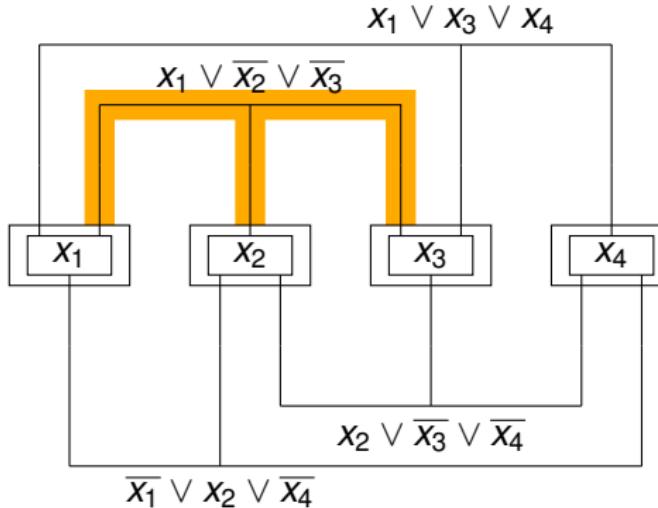
Variable Gadget



$x = \text{false}$



Outline of the Reduction

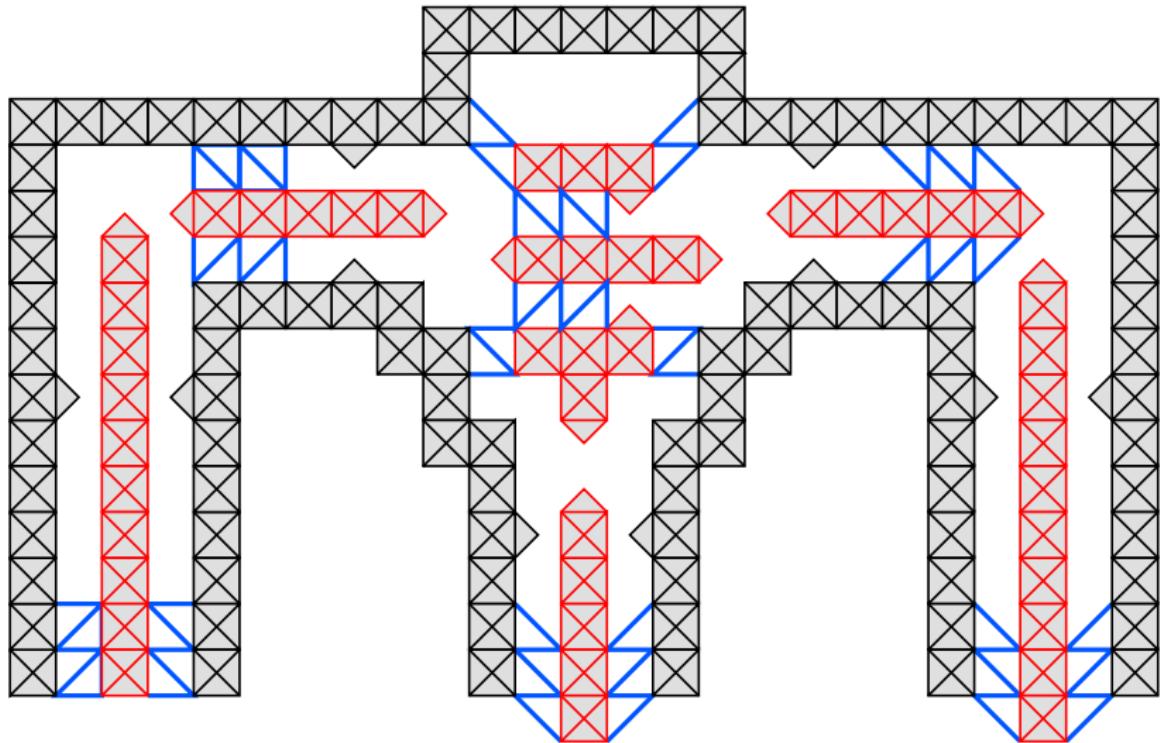


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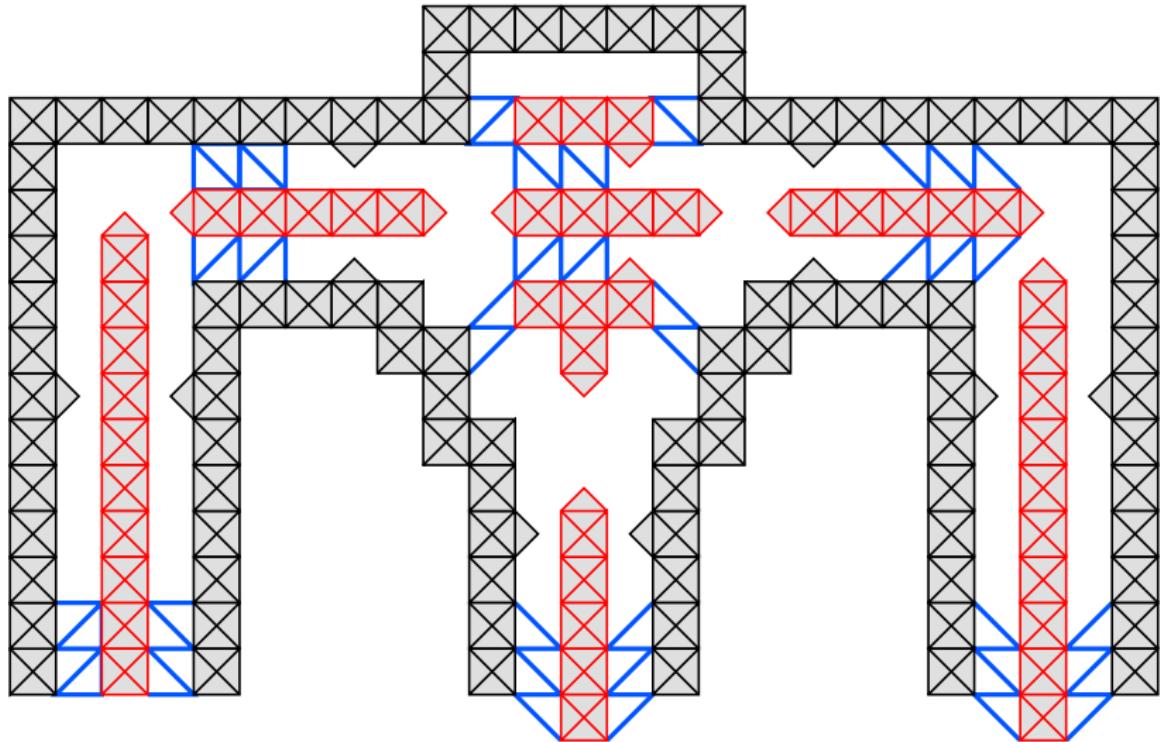
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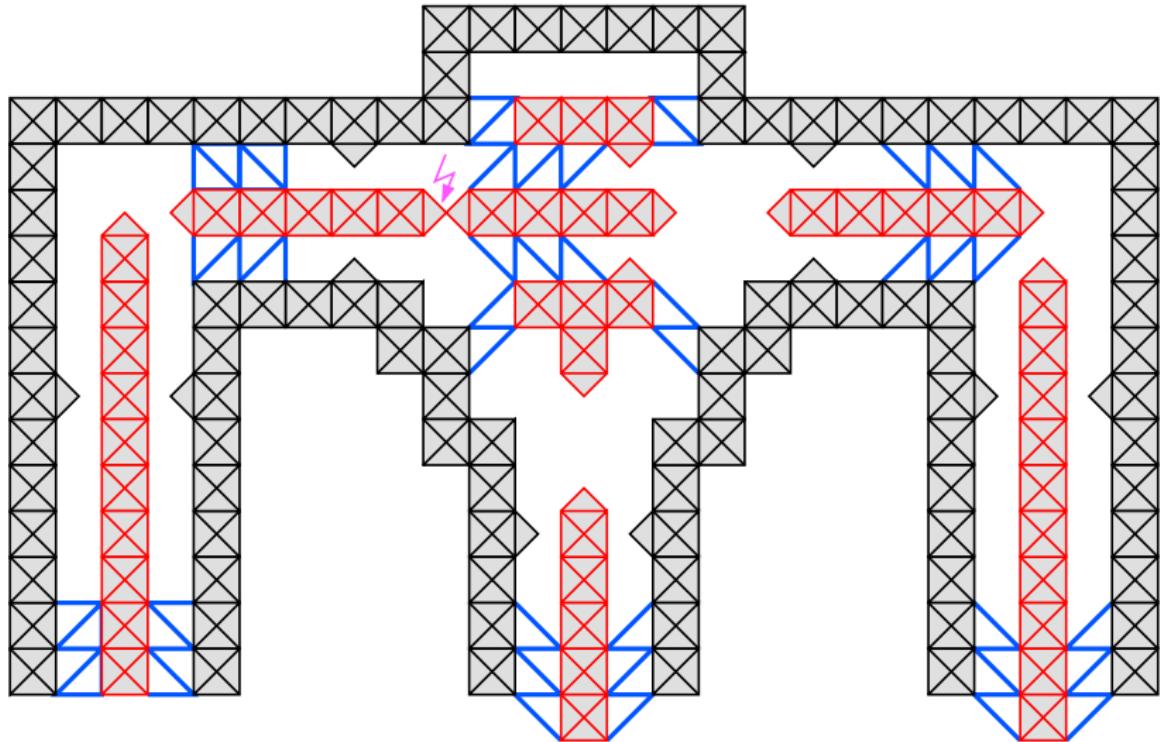
Clause Gadget



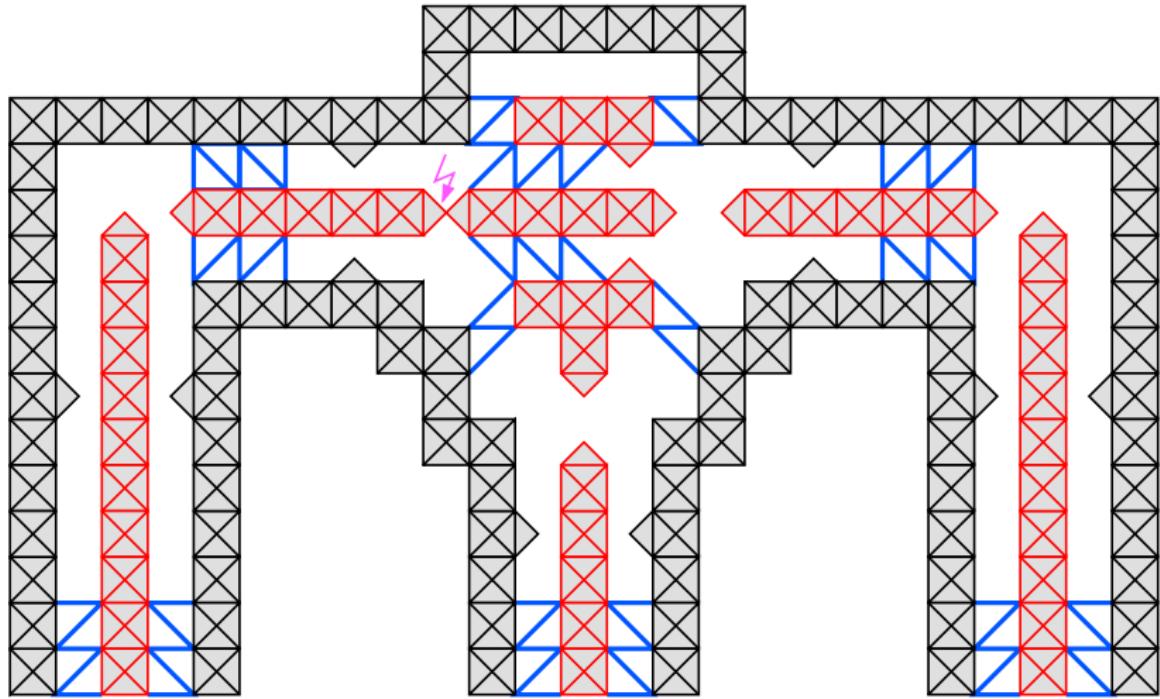
Clause Gadget



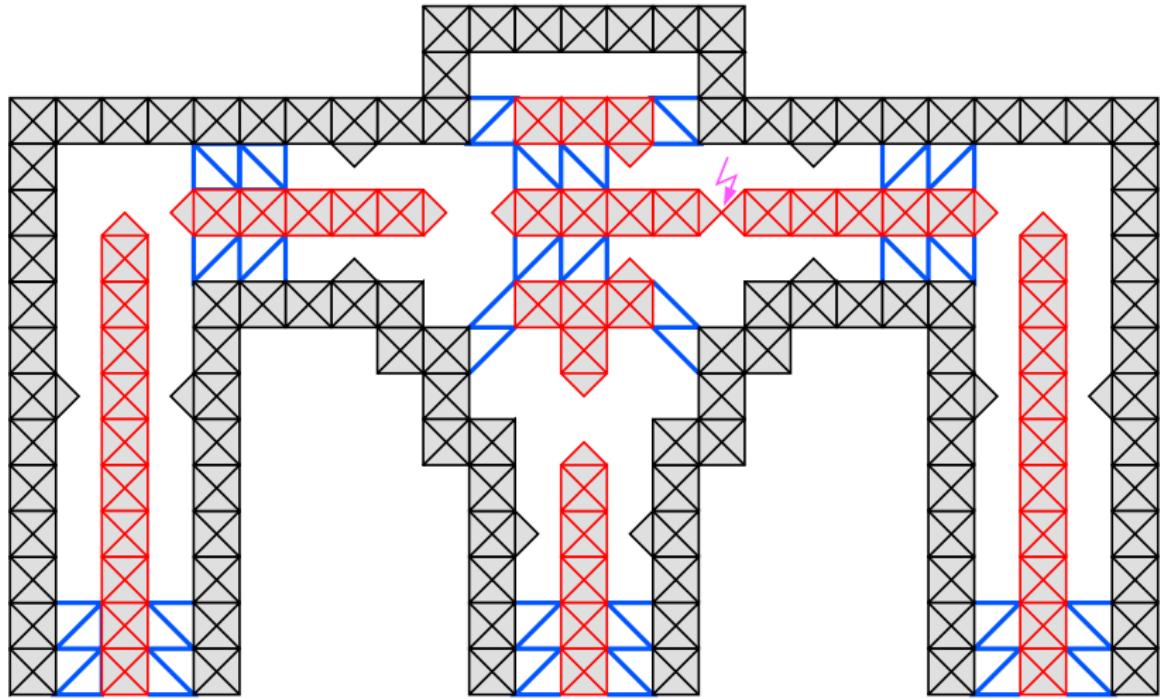
Clause Gadget



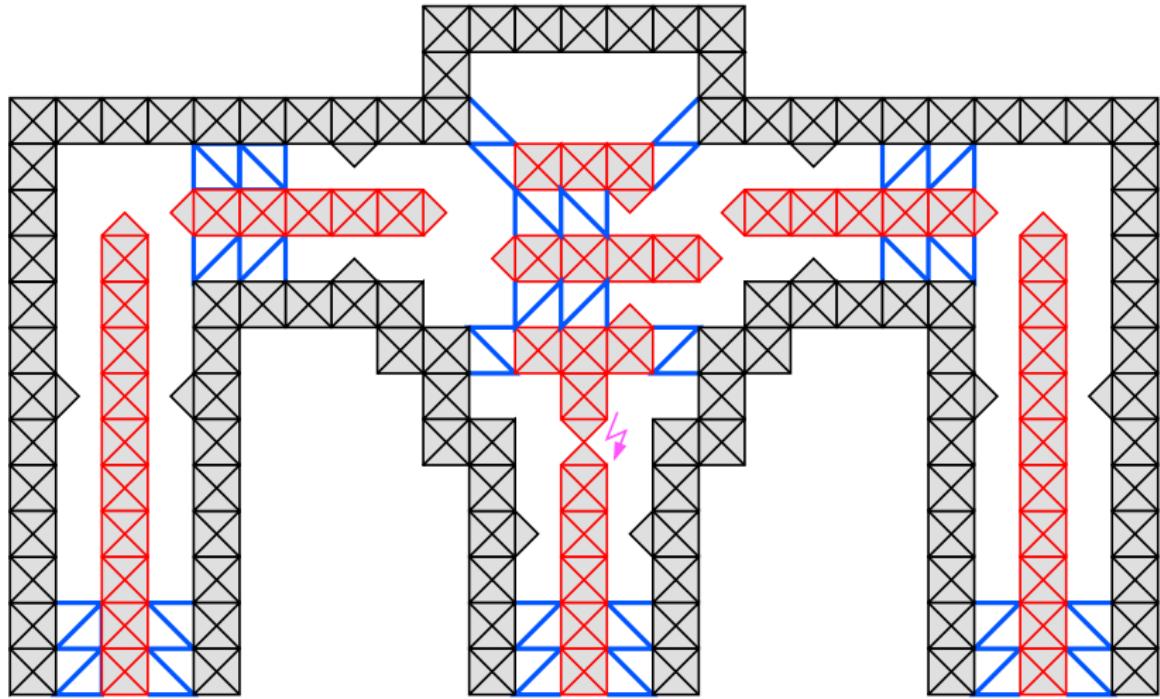
Clause Gadget



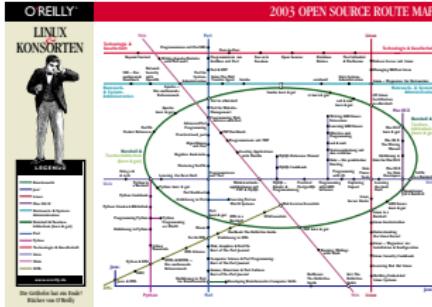
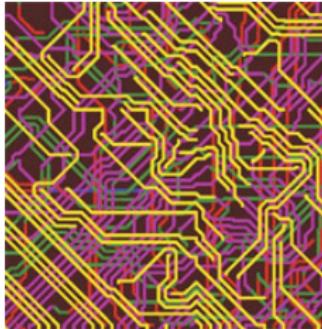
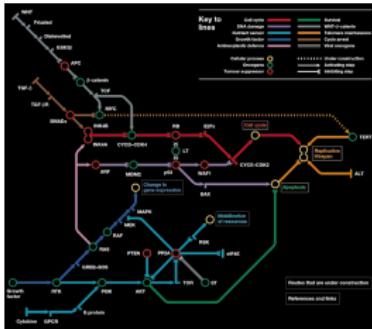
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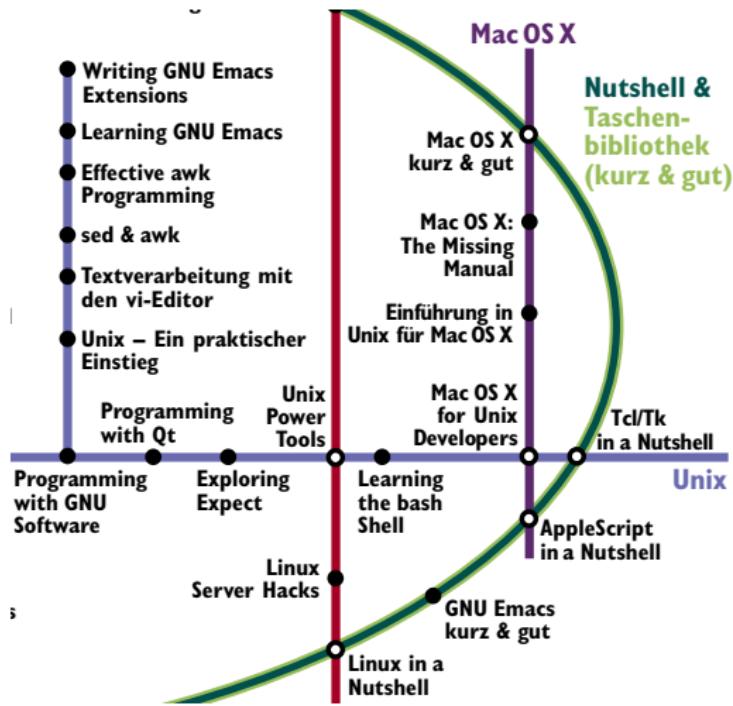
Clause Gadget



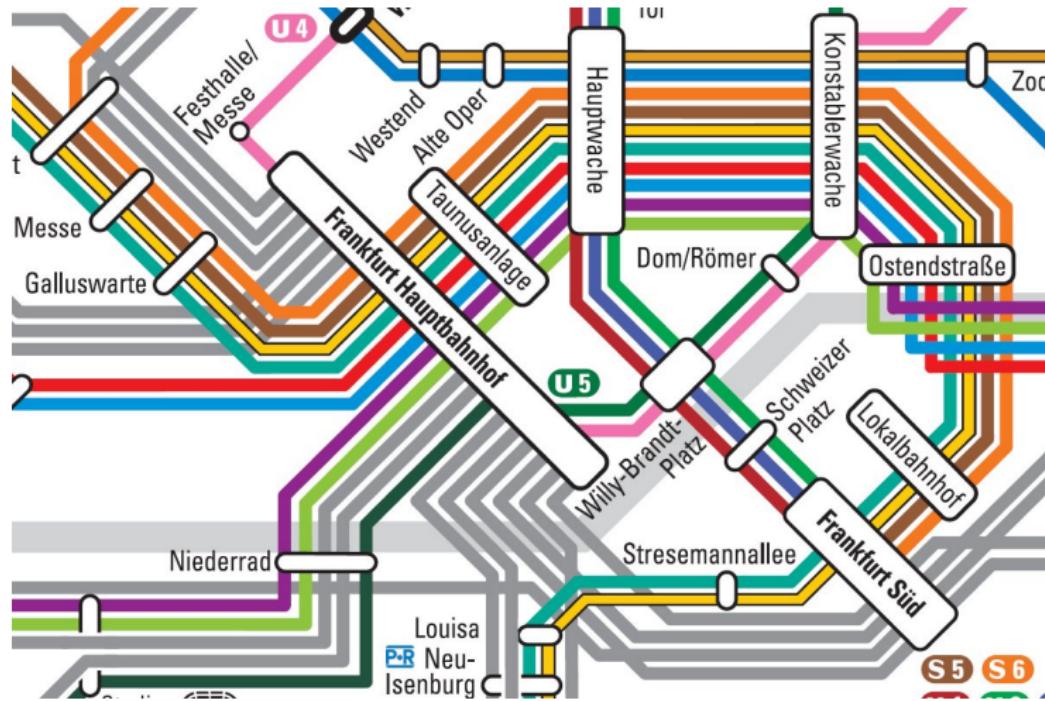
Other applications



Clipping



To do: rectangular stations & multi-edges



Summary (metro maps)

- METROMAPLAYOUT is NP-hard.
- Formulated and implemented MIP.
- Our MIP can draw *any* kind of sketch “nicely”.
- Results comparable to manually designed maps.
- Reduced MIP size & runtime drastically.



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To Do

- rectangular stations
- multi-edges
- user interaction (e.g., fixing certain edge directions)

