

Understanding Random SAT

Beyond the Clauses-to-Variables Ratio

Eugene Nudelman
Stanford University

joint work with...

Kevin Leyton-Brown
Holger Hoos

University of British Columbia

Alex Devkar
Yoav Shoham
Stanford University

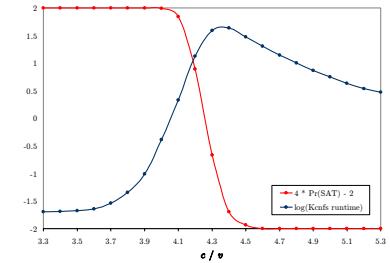
Introduction

- SAT is one of the **most studied** problems in CS
- Lots known about its **worst-case** complexity
 - But often, particular instances of \mathcal{NP} -hard problems like SAT are **easy in practice**
- “Drosophila” for **average-case** and **empirical** (typical-case) complexity studies
- (Uniformly) random SAT provides a way to bridge analytical and empirical work



Previously...

- **Easy-hard-less hard** transitions discovered in the behaviour of DPLL-type solvers [Selman, Mitchell, Levesque]
 - Strongly correlated with phase transition in solvability
 - Spawned a new enthusiasm for using empirical methods to study algorithm performance
- Follow up included study of:
 - Islands of tractability [Kolaitis et. al.]
 - SLS search space topologies [Frank et.al., Hoos]
 - Backbones [Monasson et.al., Walsh and Slaney]
 - Backdoors [Williams et. al.]
 - Random restarts [Gomes et. al.]
 - Restart policies [Horvitz et.al, Ruan et.al.]
 - ...

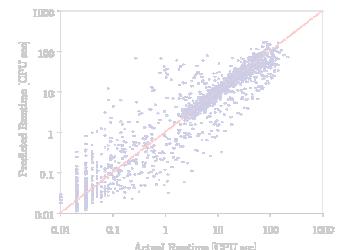
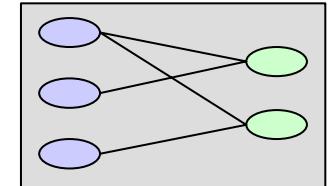


Empirical Hardness Models

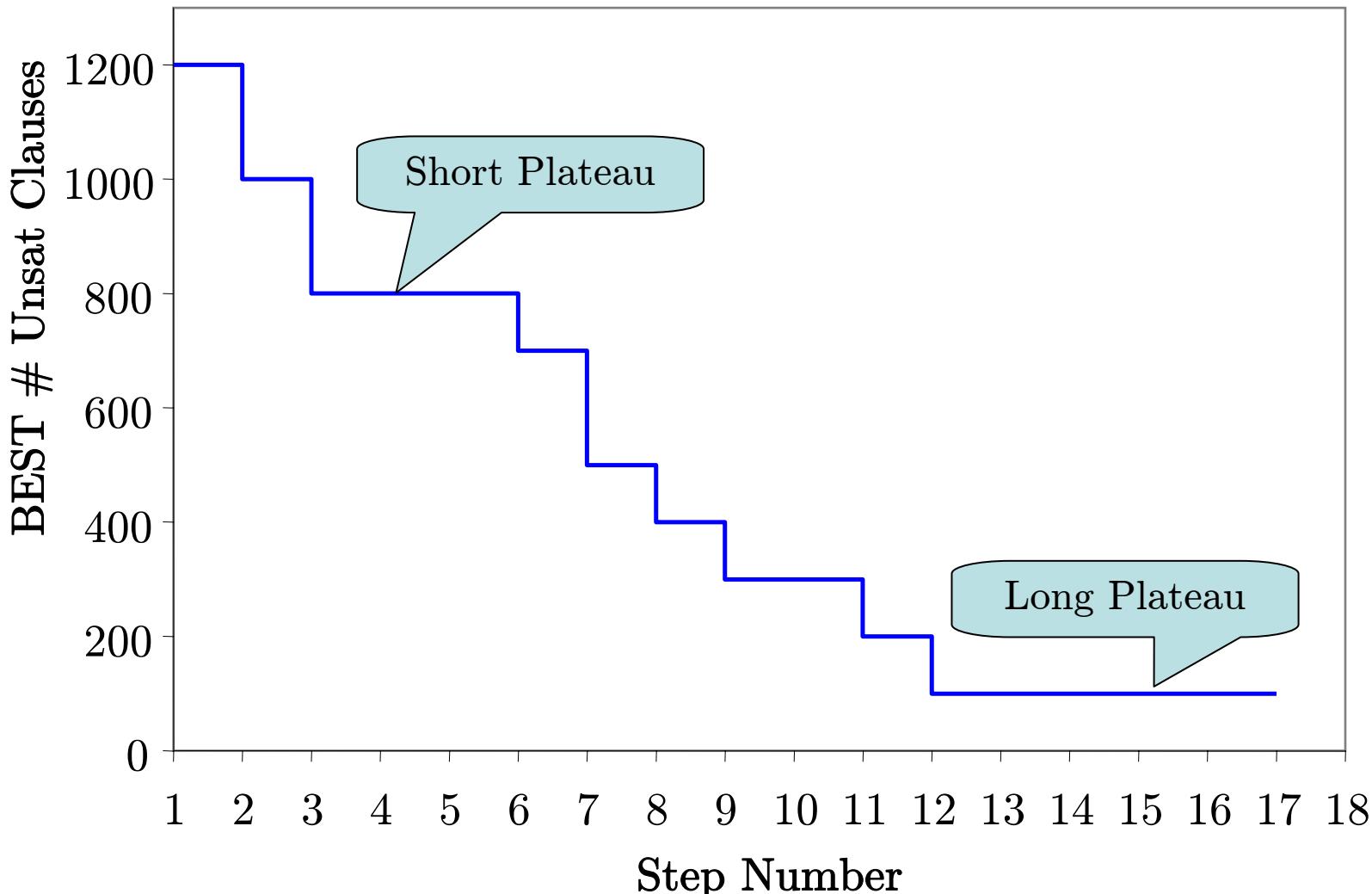
- We proposed building **regression models** as a disciplined way of predicting and studying algorithms' behaviour
[Leyton-Brown, Nudelman, Shoham, CP-02]
- **Applications** of this machine learning approach:
 - 1) Predict running time
 - Useful to know **how long** an algorithm will run
 - 2) Gain theoretical understanding
 - Which variables are **important** to the hardness model?
 - 3) Build algorithm portfolios
 - Can select the right algorithm on a **per-instance** basis
 - 4) Tune distributions for hardness
 - Can generate **harder** benchmarks by rejecting easy instances

Outline

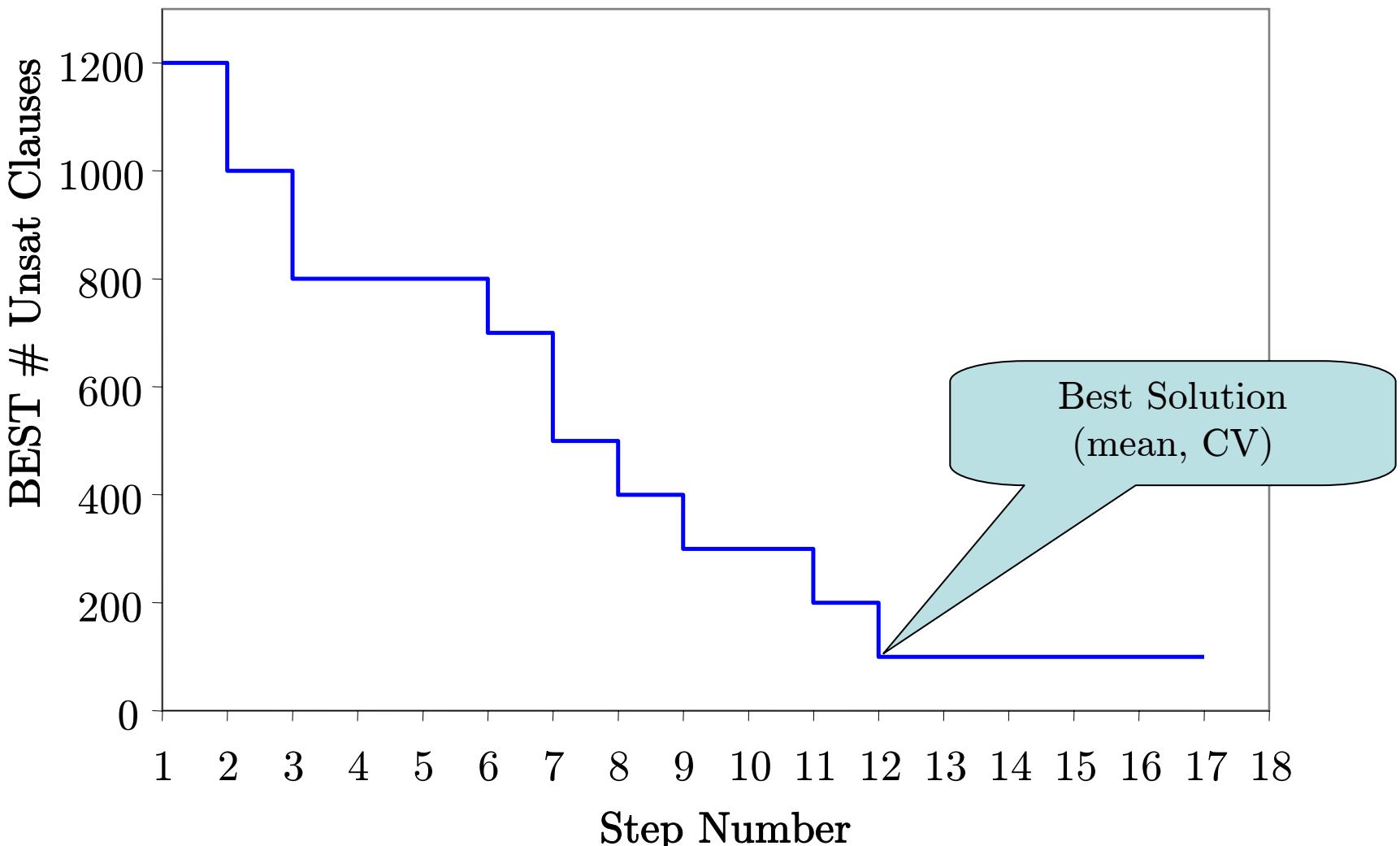
- Features
- Experimental Results
 - Variable Size Data
 - Fixed Size Data



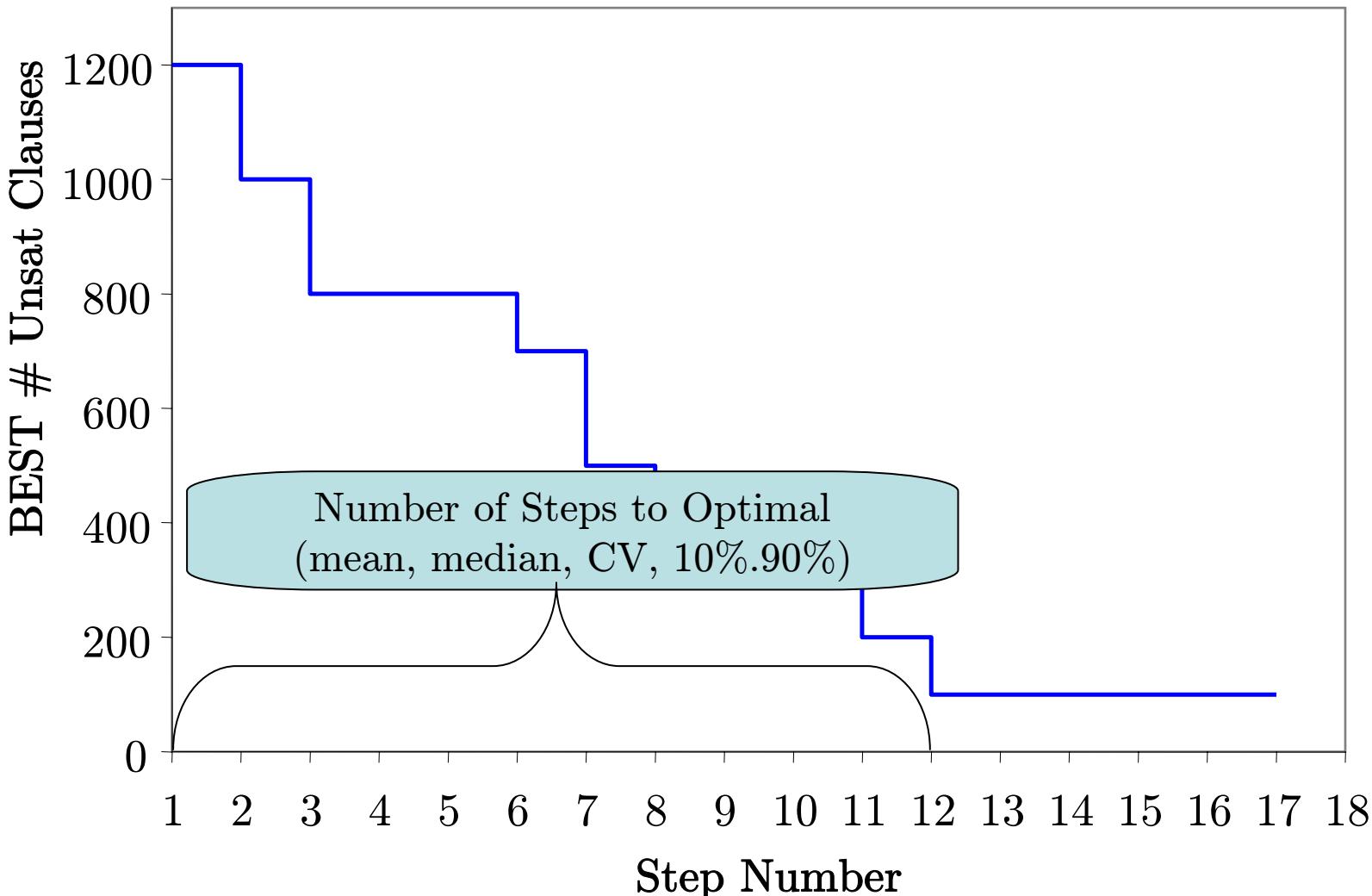
Features: Local Search Probing



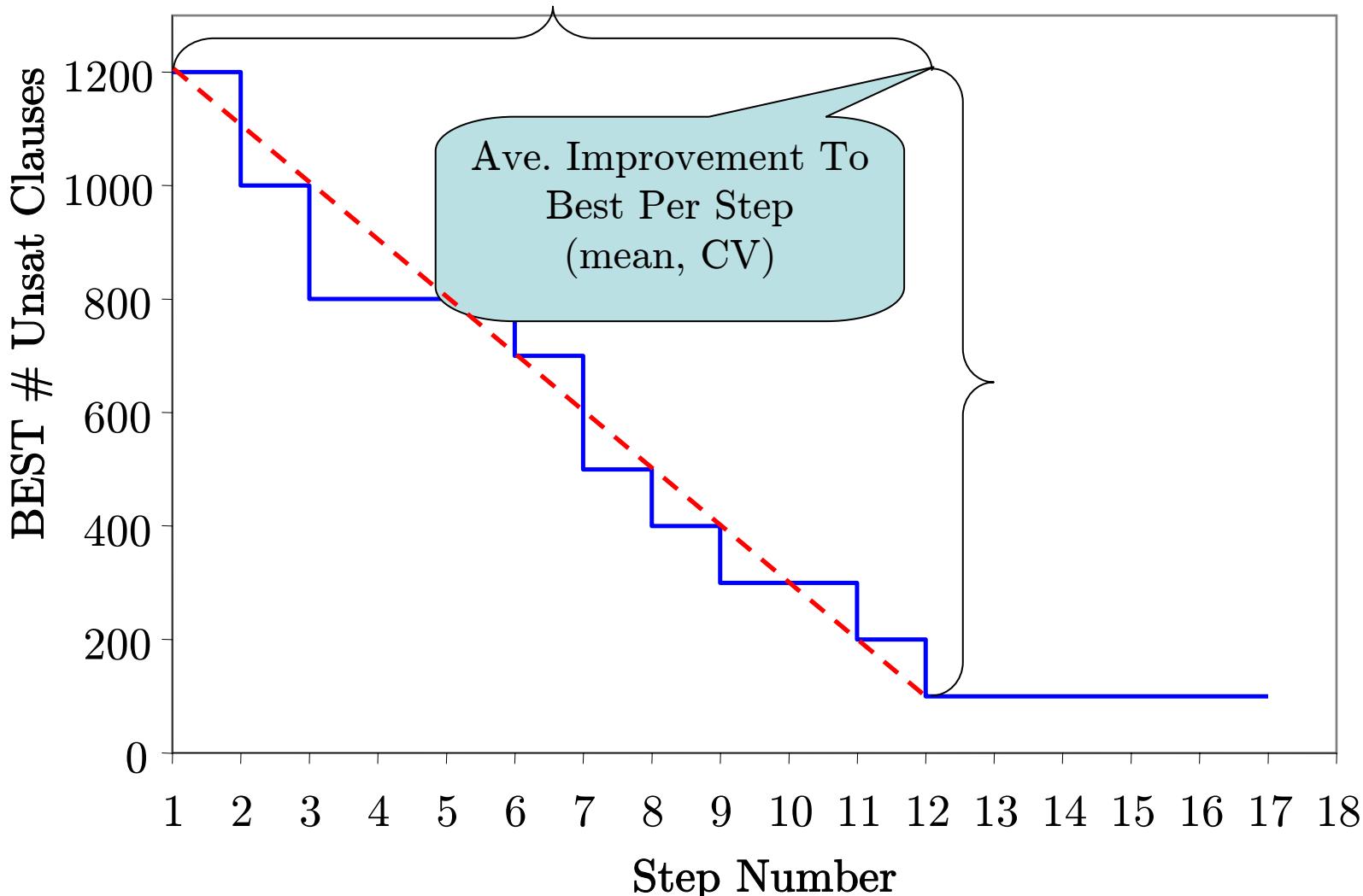
Features: Local Search Probing



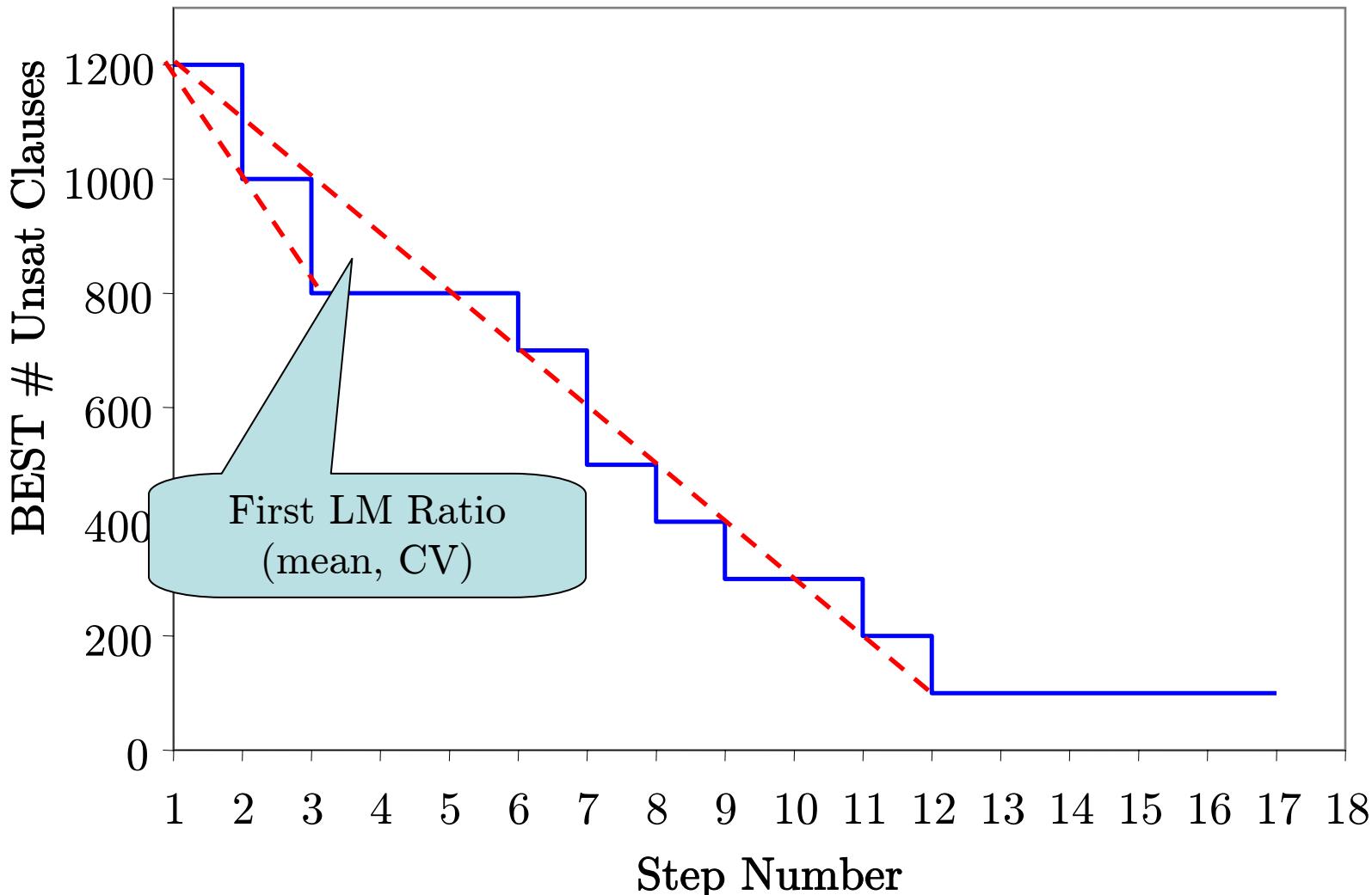
Features: Local Search Probing



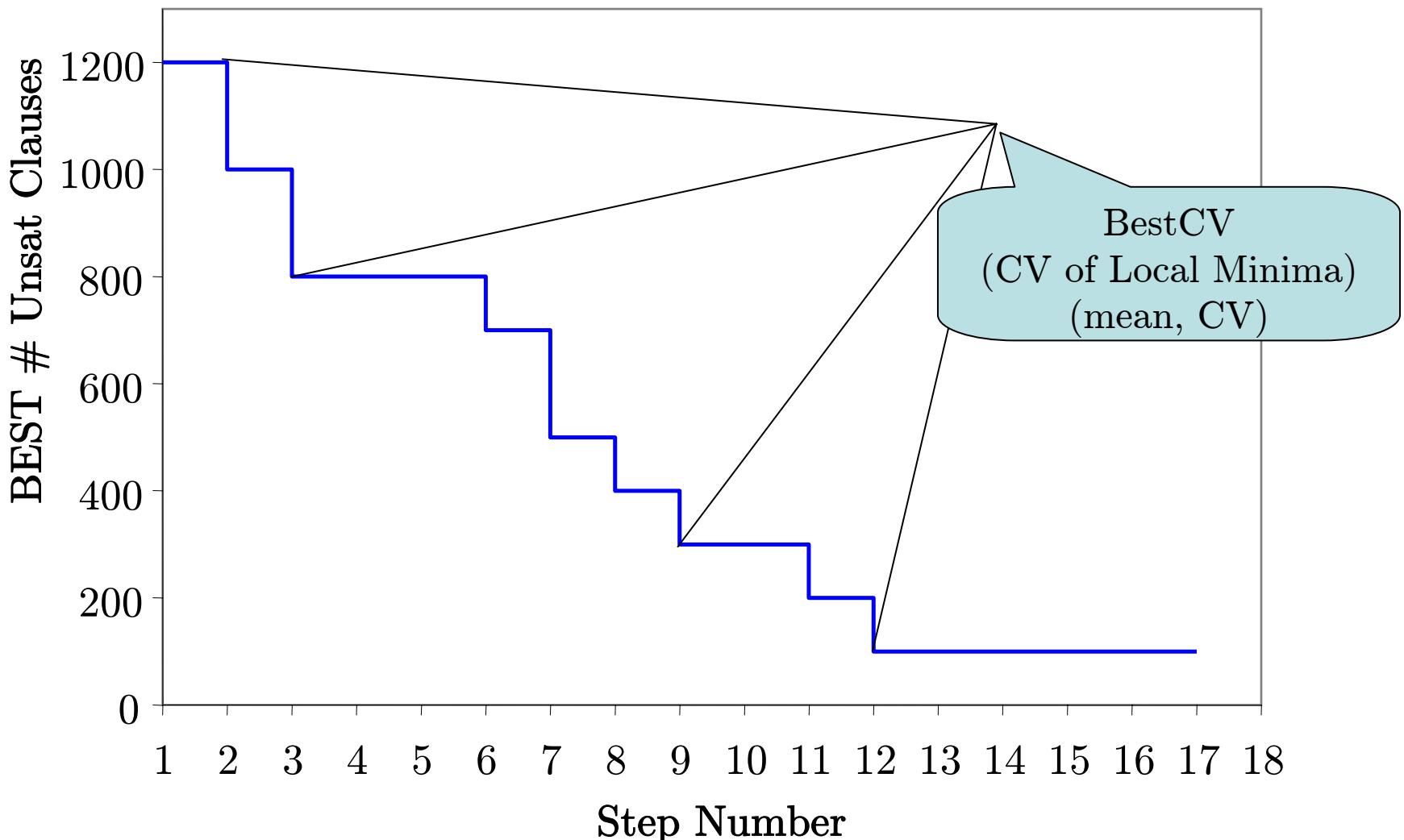
Features: Local Search Probing



Features: Local Search Probing

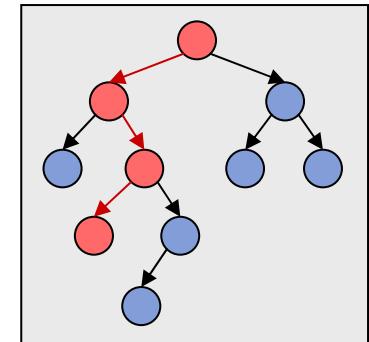


Features: Local Search Probing



Features: DPLL, LP

- **DPLL** search space size estimate
 - Random probing with unit propagation
 - Compute mean depth till contradiction
 - Estimate $\log(\# \text{nodes})$



- Cumulative number of **unit propagations** at different depths (DPLL with Satz heuristic)

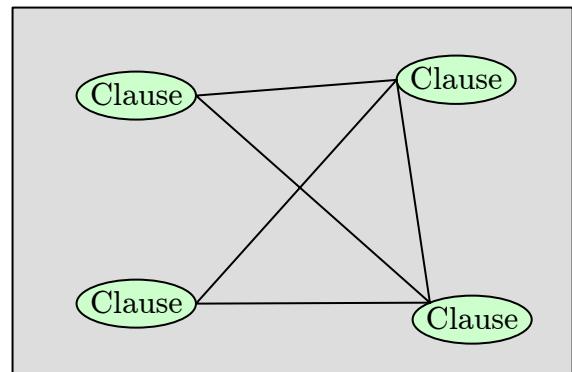
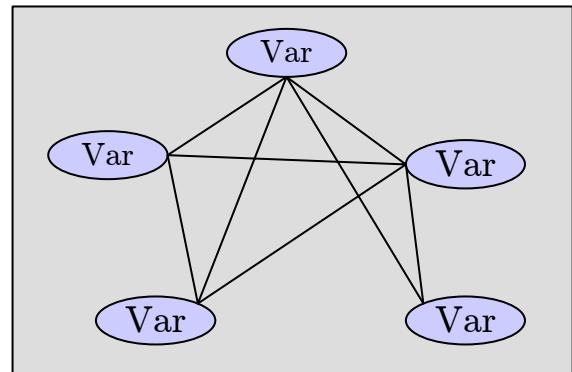
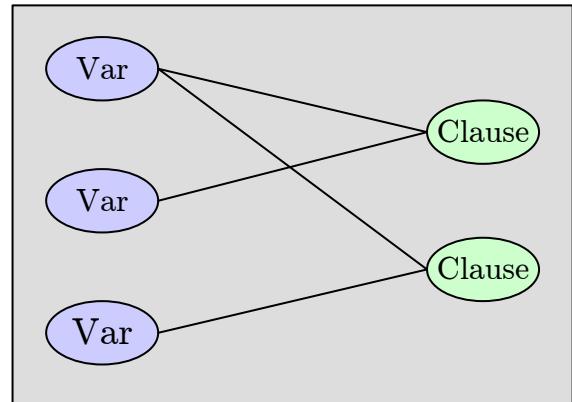
• LP relaxation

- Objective value
- stats of integer slacks
- #vars set to an integer

$$\begin{aligned} & \text{maximize: } \sum_{k \in C} \left(\sum_{i \in L, i \in k} v_i + \sum_{j \in \bar{L}, i \in k} (1 - v_j) \right) \\ & \text{subject to: } \sum_{i \in k, i \in L} v_i + \sum_{j \in k, j \in \bar{L}} (1 - v_j) \geq 1 \quad \forall k \in C \\ & \quad v_i \in \{0, 1\} \quad \forall i \end{aligned}$$

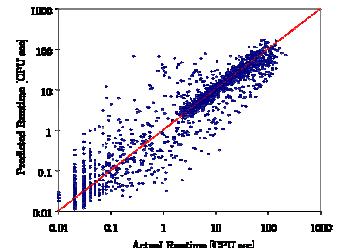
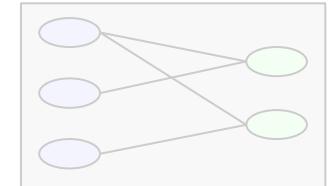
Other Features

- **Problem Size:**
 - v (#vars)
 - c (#clauses)
 - Powers of $c/v, v/c, |c/v - 4.26|$
- **Graphs:**
 - **Variable-Clause** (VCG, bipartite)
 - **Variable** (VG, edge whenever two variables occur in the same clause)
 - **Clause** (CG, edge iff two clauses share a variable with opposite sign)
- **Balance**
 - #pos vs. #neg literals
 - unary, binary, ternary clauses
- Proximity to **Horn formula**



Outline

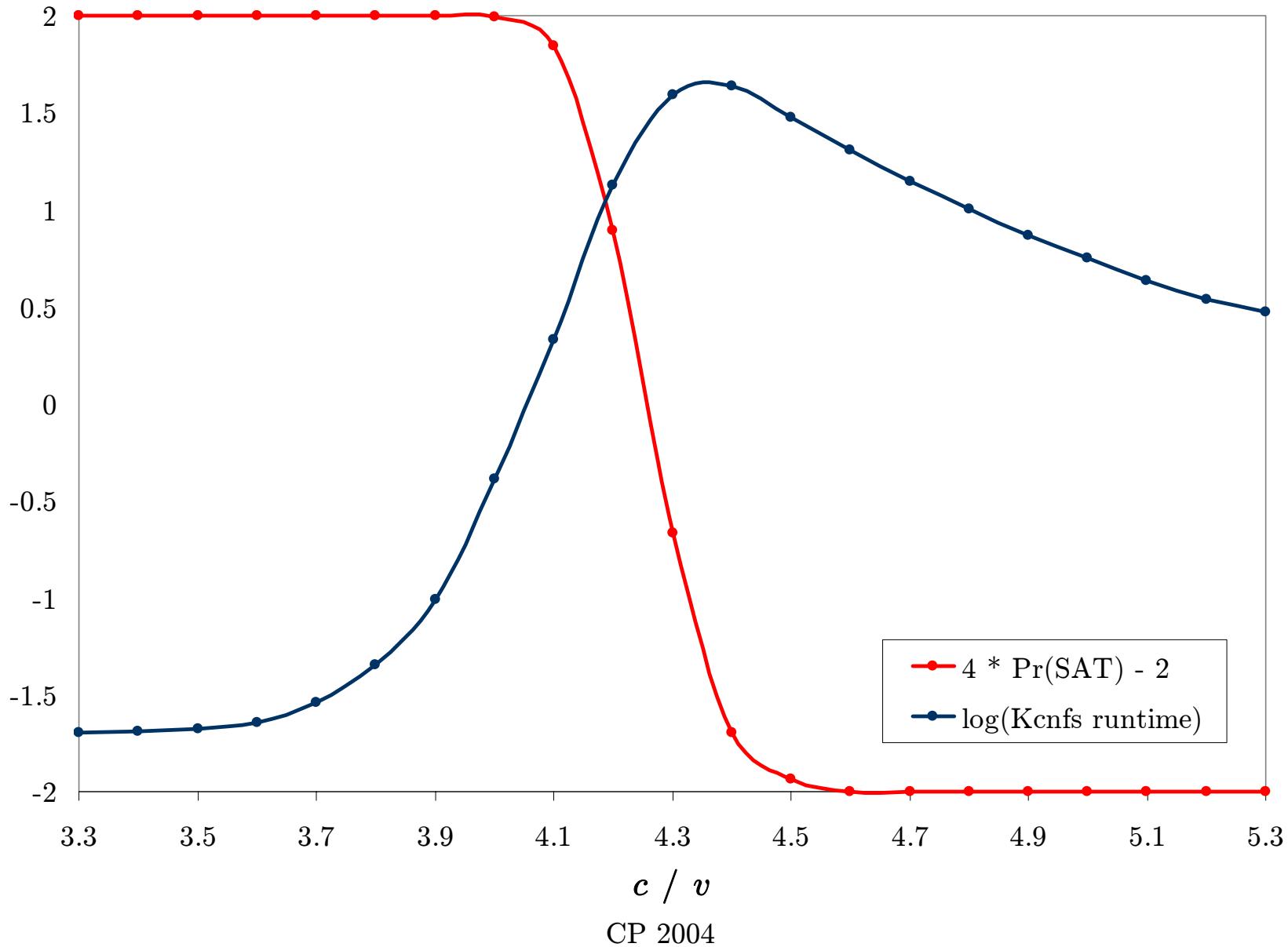
- Features
- Experimental Results
 - Variable Size Data
 - Fixed Size Data



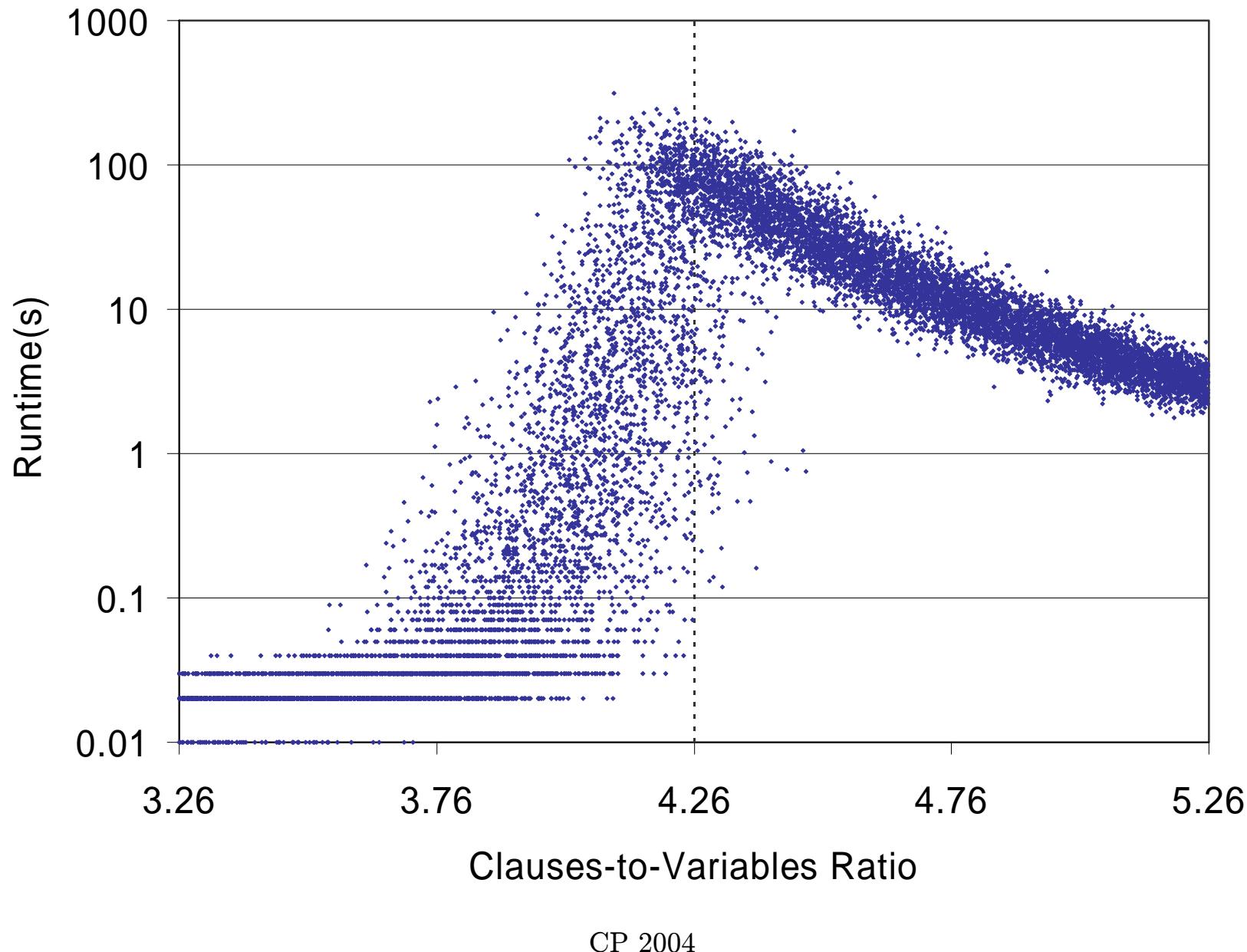
Experimental Setup

- Uniform random 3-SAT, 400 vars
- **Datasets** (20000 instances each)
 - **Variable-ratio** dataset (1 CPU-month)
 - c/v uniform in [3.26, 5.26] ($\therefore c \in [1304, 2104]$)
 - **Fixed-ratio** dataset (4 CPU-months)
 - $c/v=4.26$ ($\therefore v=400, c=1704$)
- **Solvers**
 - Kcnfs [Dubois and Dequen]
 - OKsolver [Kullmann]
 - Satz [Chu Min Li]
- **Quadratic regression** with logistic response function
- Training : test : validation split – 70 : 15 : 15

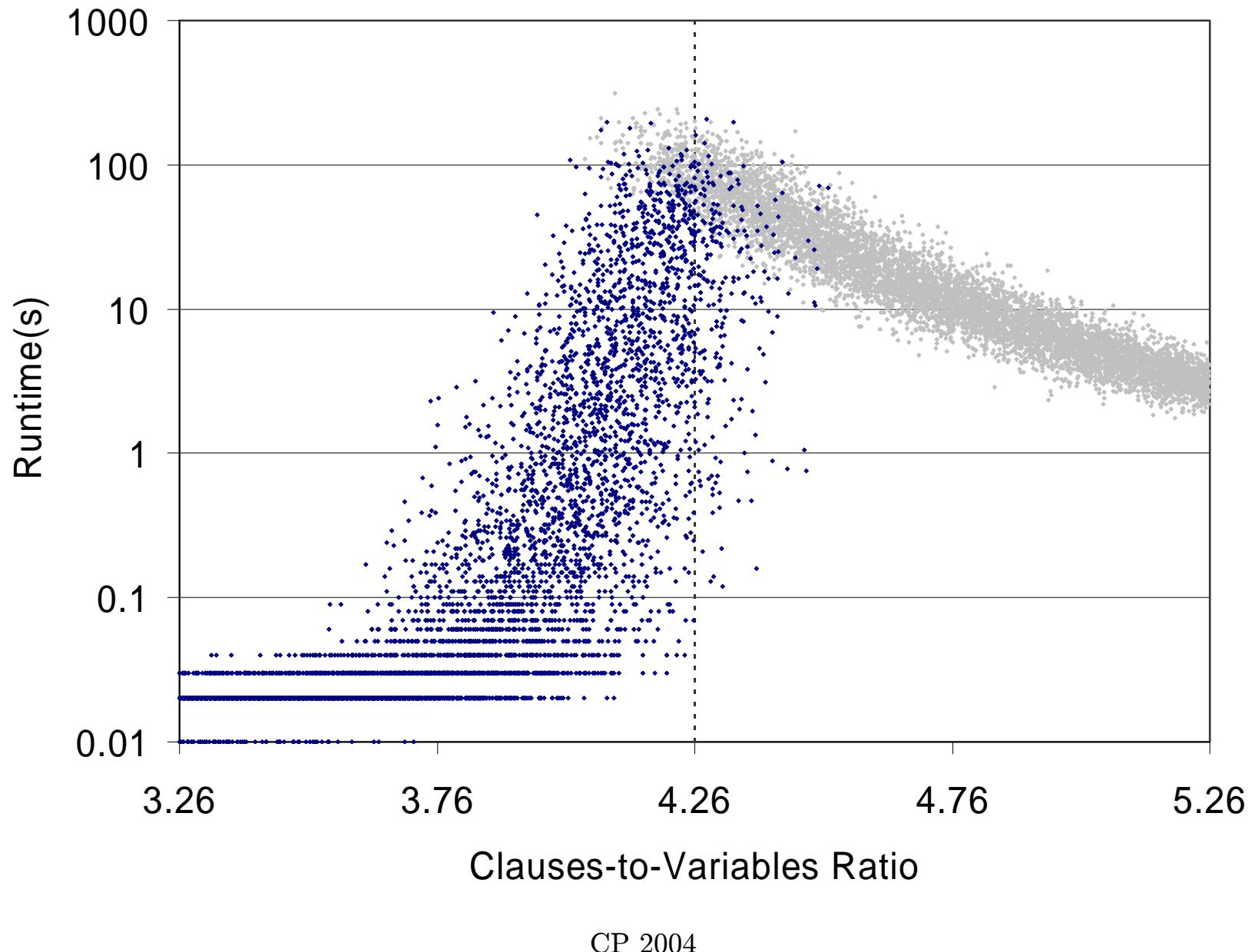
Kcnfs Data



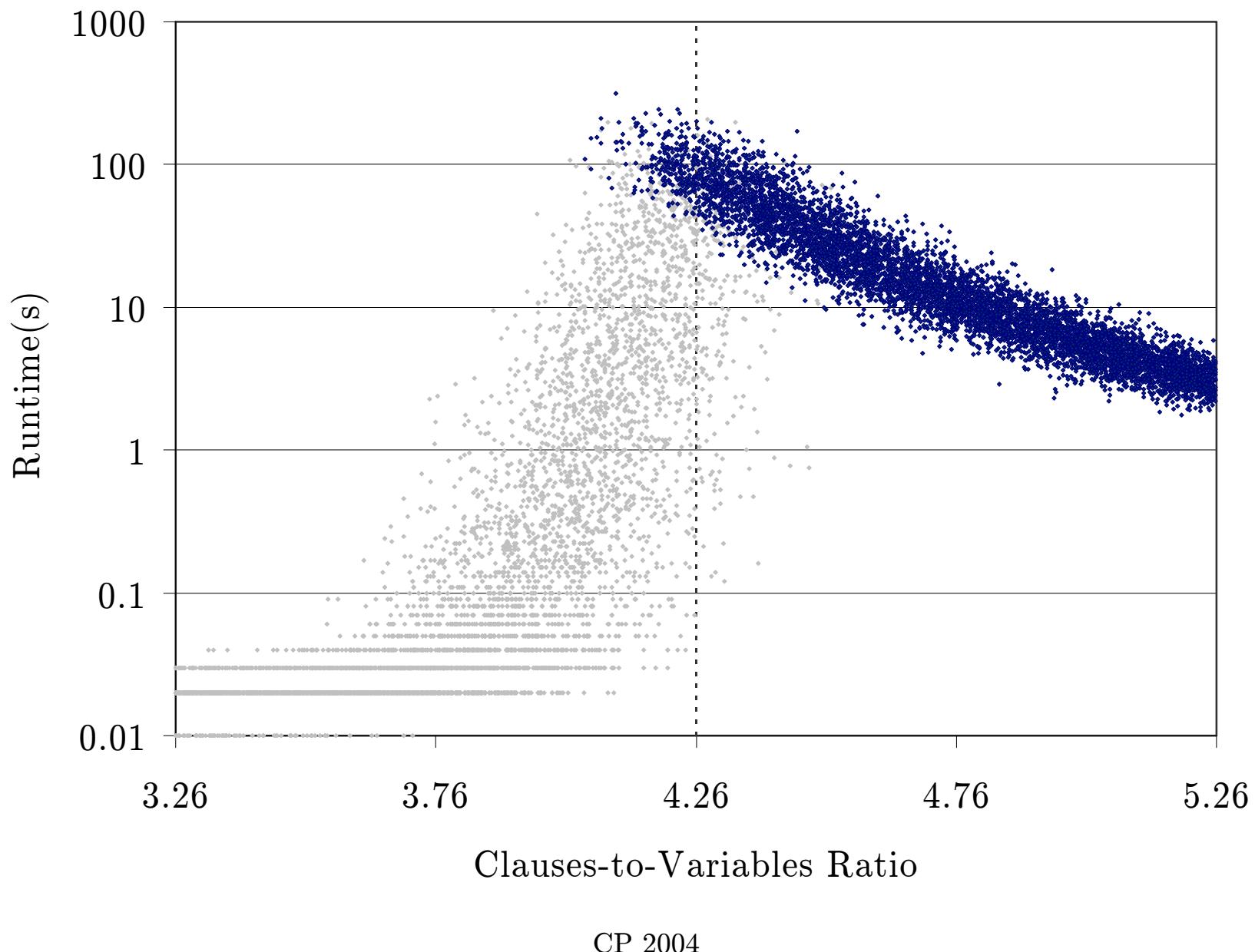
Kcnfs Data



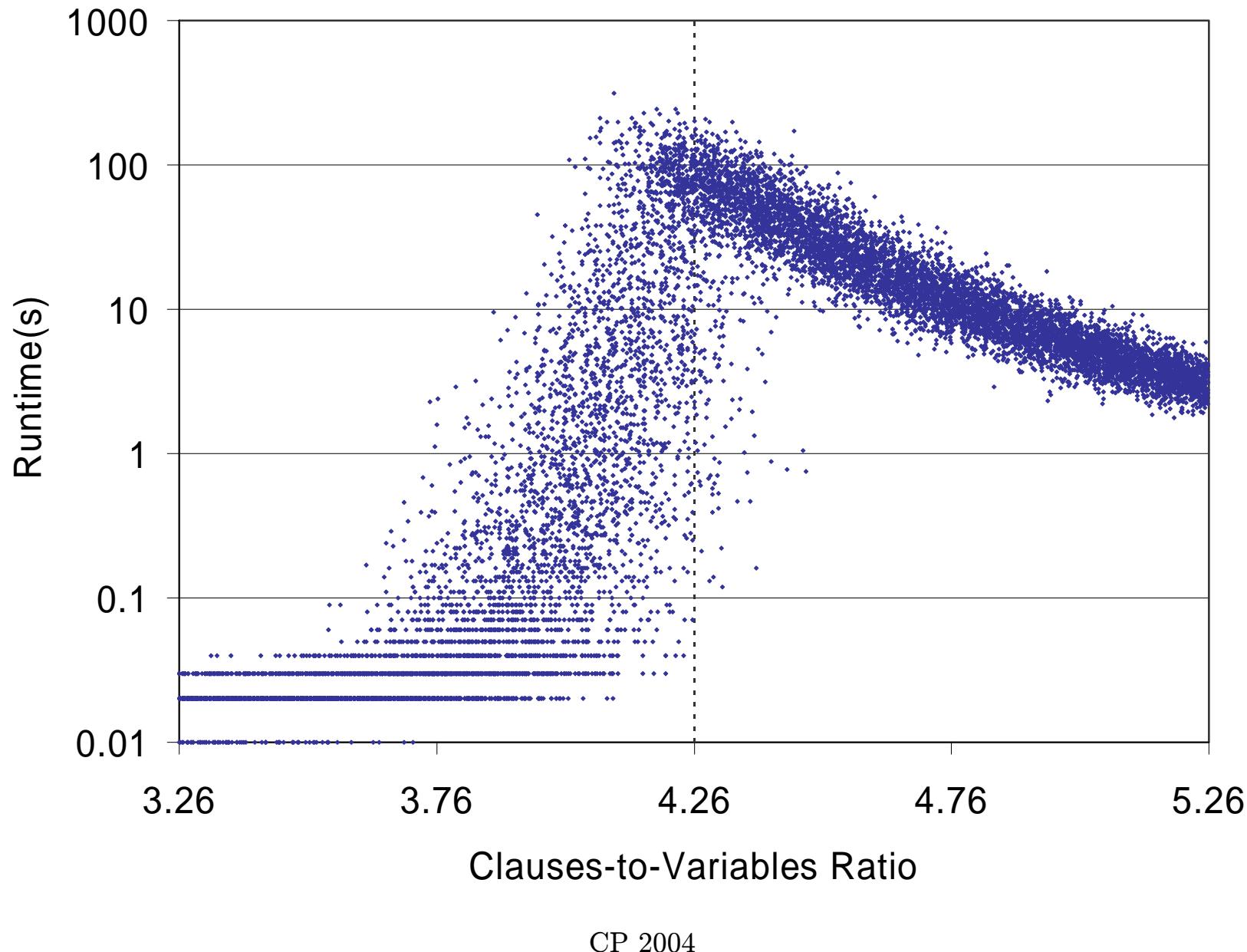
Kcnfs Data



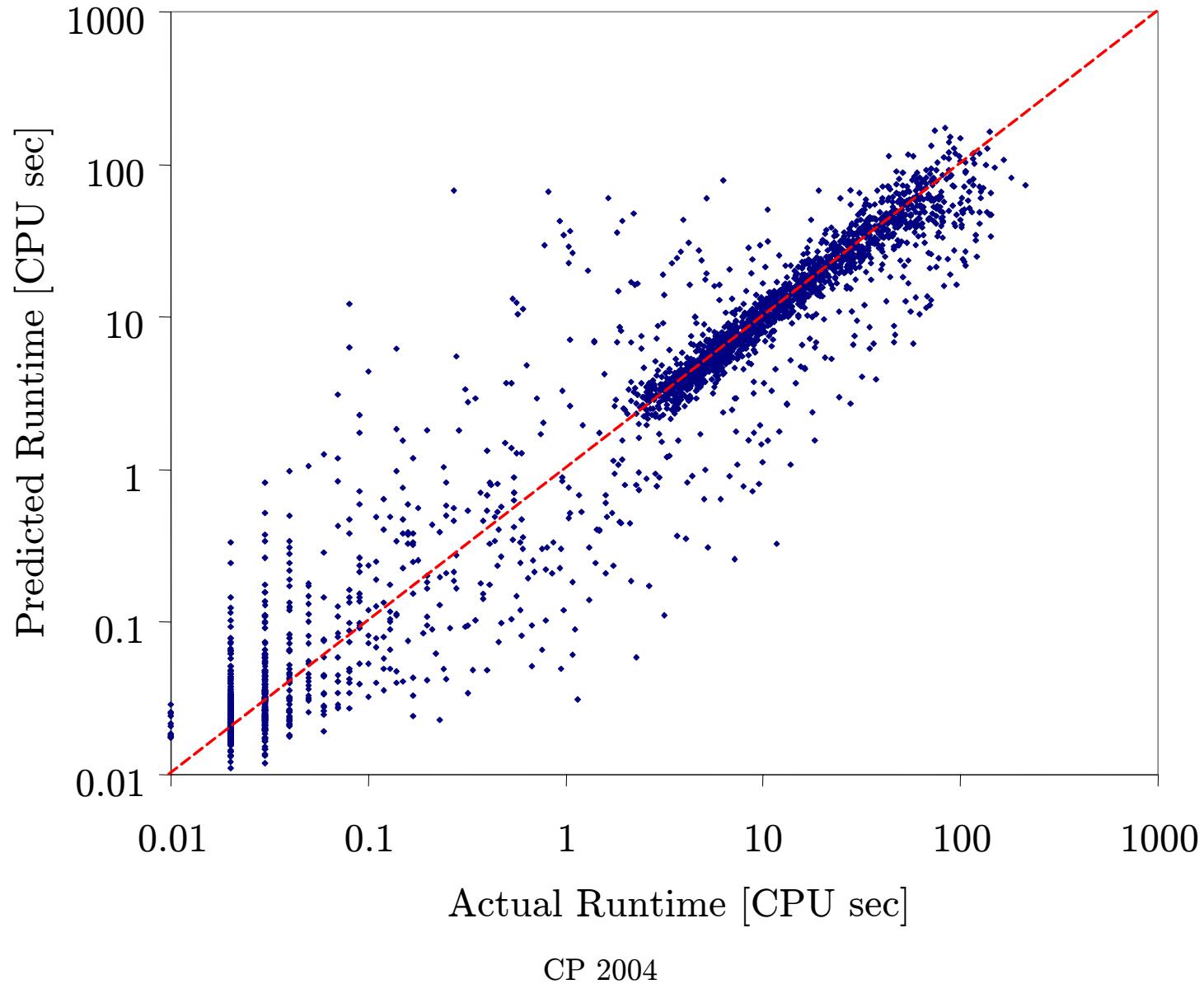
Kcnfs Data



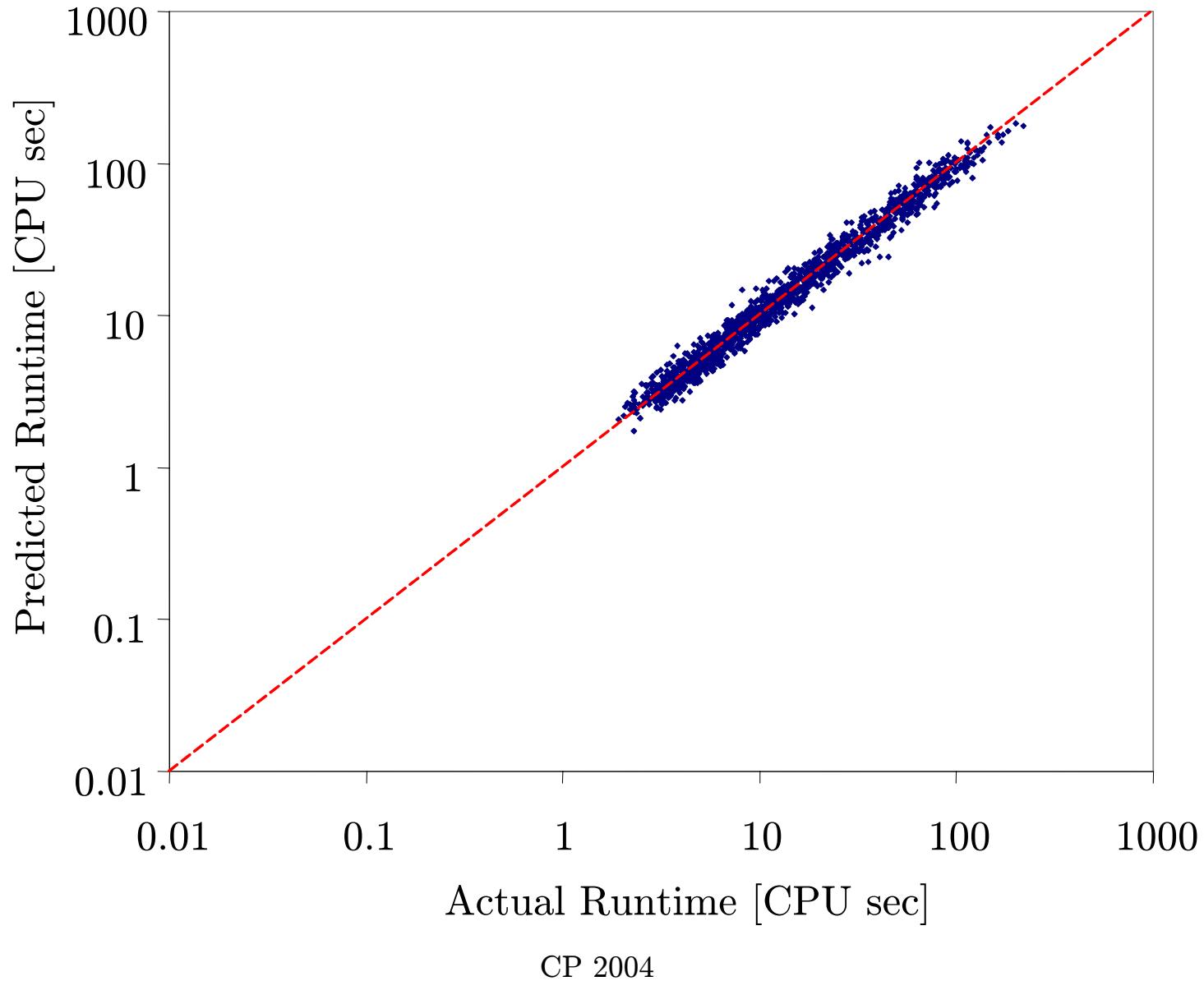
Kcnfs Data



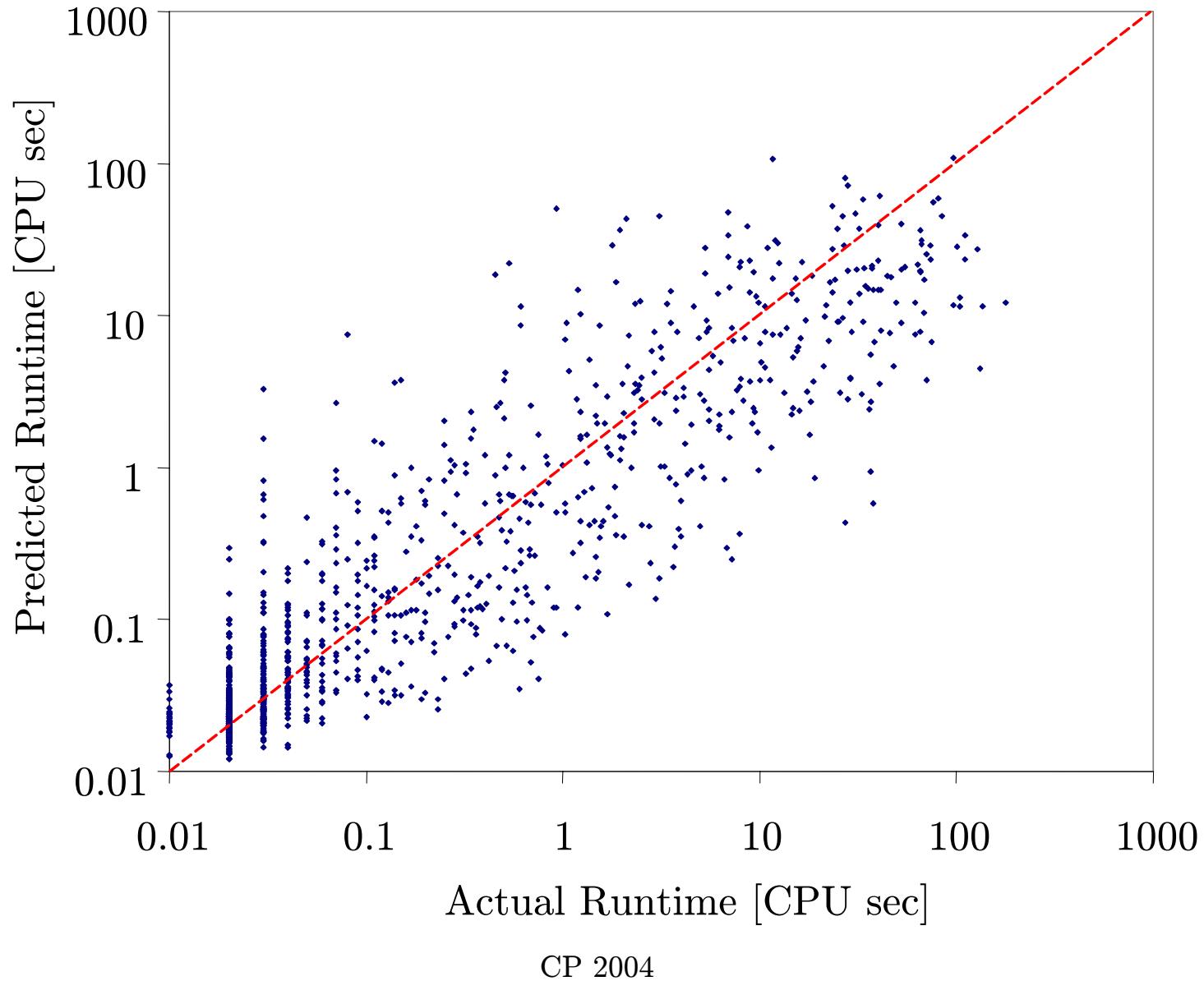
Variable Ratio Prediction (Kcnfs)



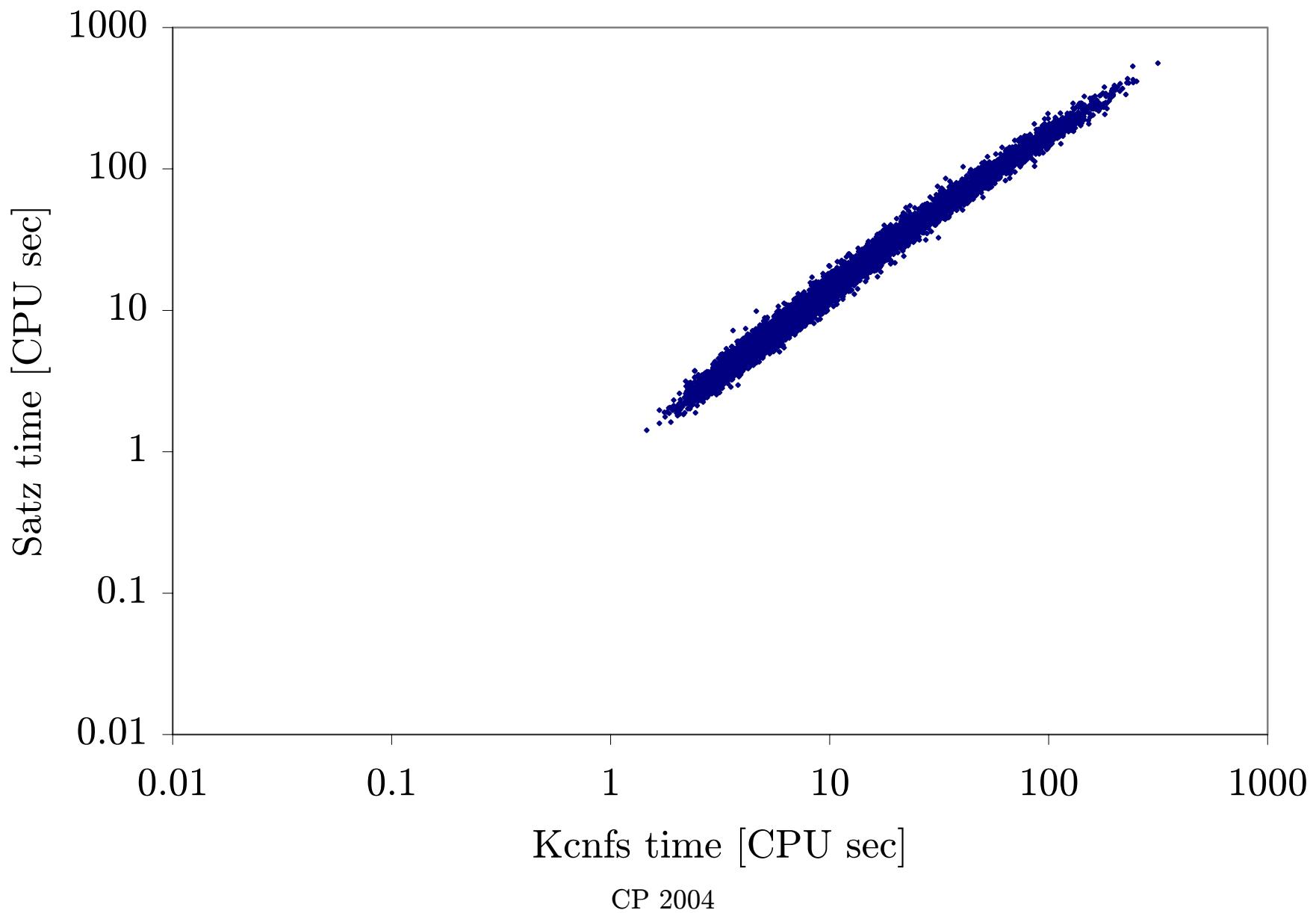
Variable Ratio - UNSAT



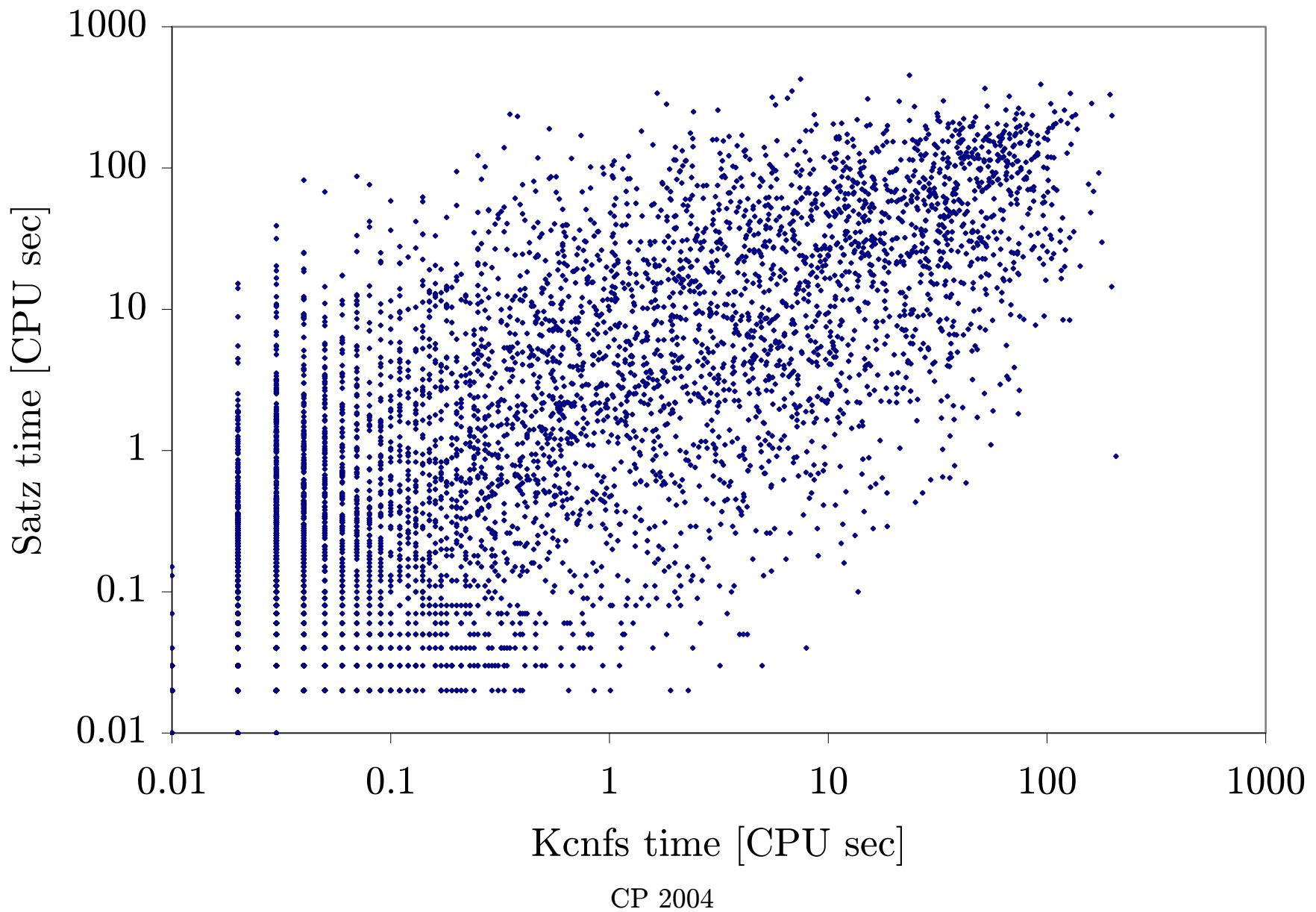
Variable Ratio - SAT



Kcnfs vs. Satz (UNSAT)



Kcnfs vs. Satz (SAT)



Feature Importance – Variable Ratio

- **Subset selection** can be used to identify features **sufficient** for approximating full model performance
- Other (correlated) sets could potentially achieve similar performance

Variable	Cost of Omission
$ c/v-4.26 $	100
$ c/v-4.26 ^2$	69
$(v/c)^2 \times SapsBestCVMean$	53
$ c/v-4.26 \times SapsBestCVMean$	33

Feature Importance – Variable Ratio

- **Subset selection** can be used to identify features **sufficient** for approximating full model performance
- Other (correlated) sets could potentially achieve similar performance

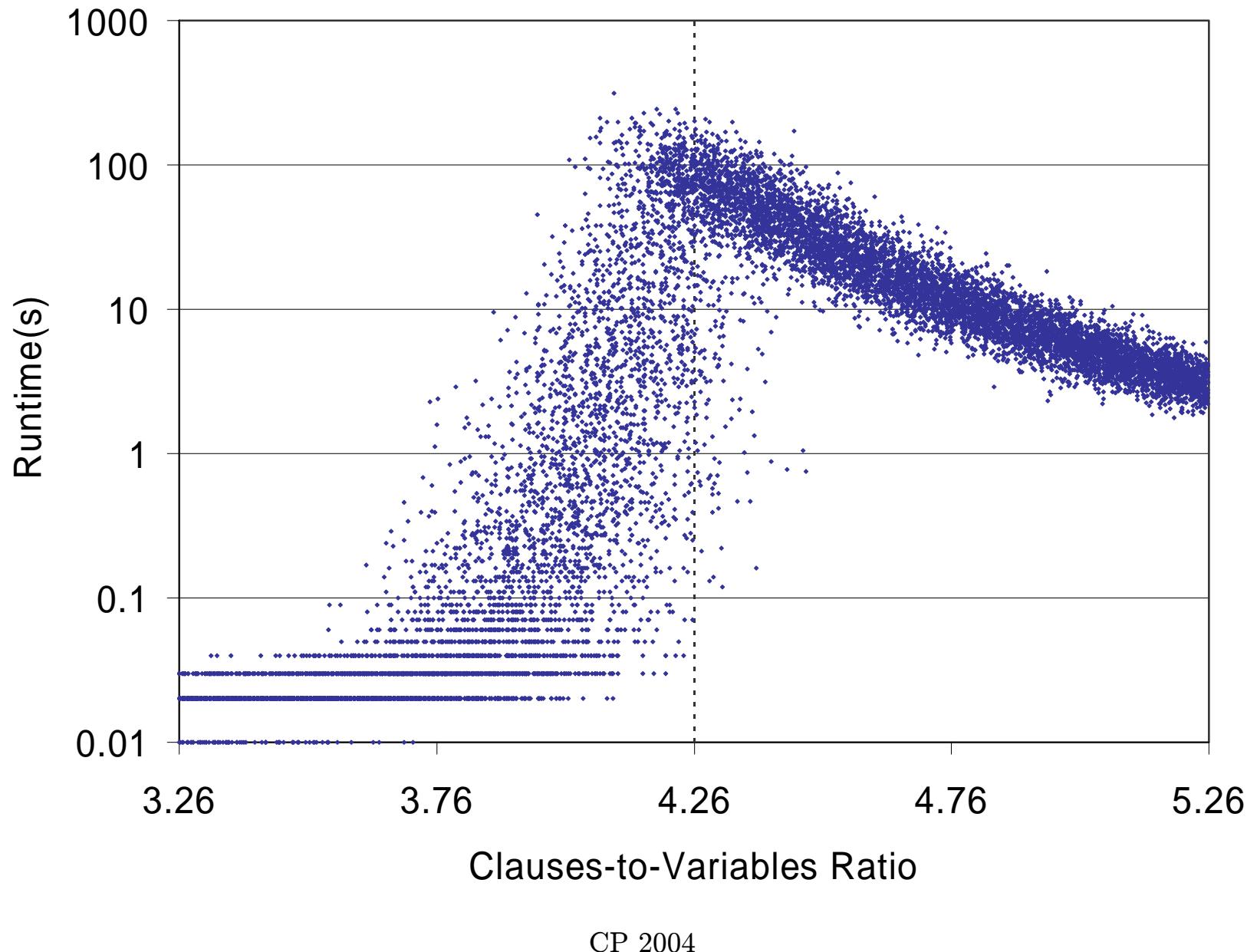
Variable	Cost of Omission
$ c/v-4.26 $	100
$ c/v-4.26 ^2$	69
$(v/c)^2 \times SapsBestCVMean$	53
$ c/v-4.26 \times SapsBestCVMean$	33

Feature Importance – Variable Ratio

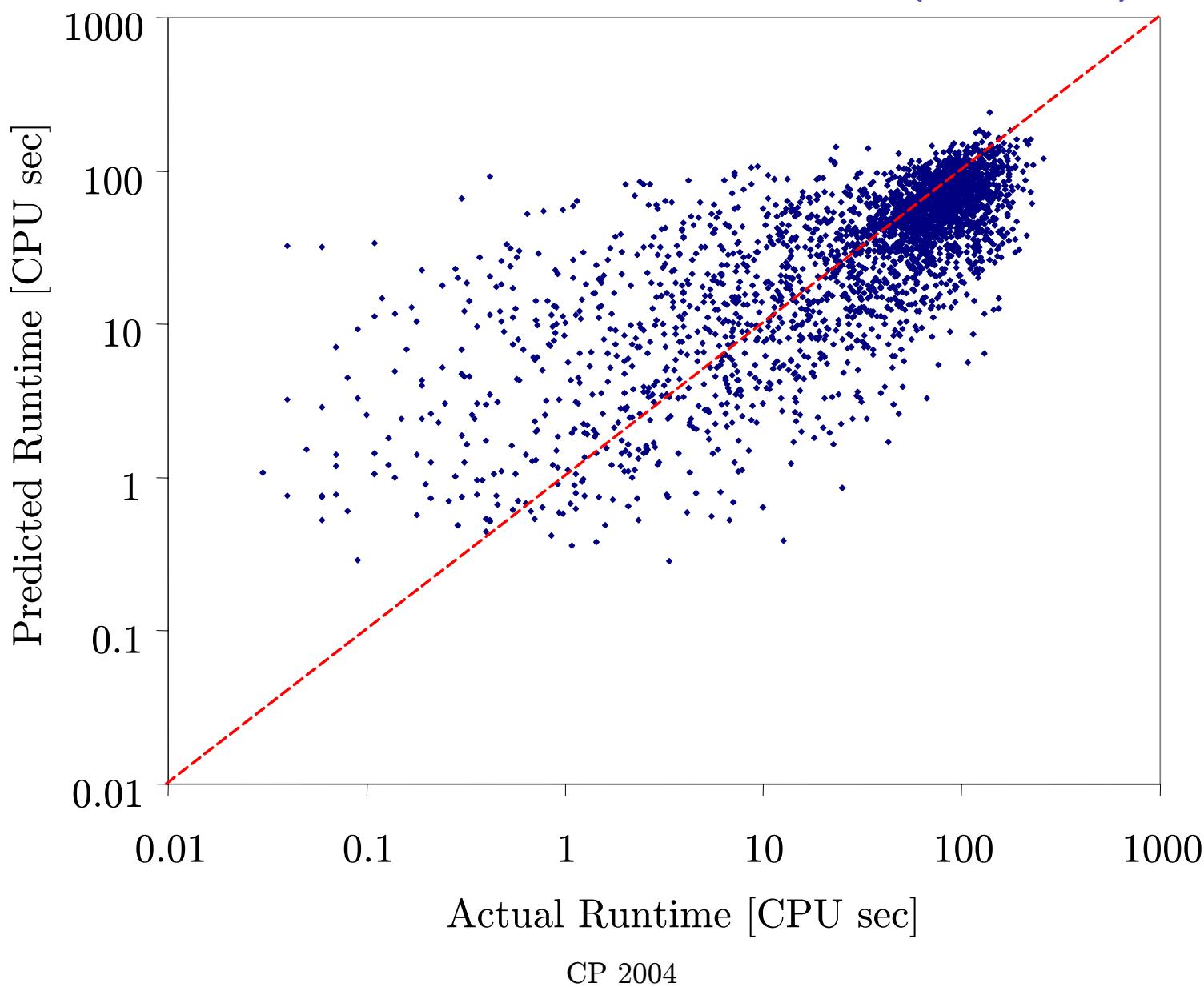
- **Subset selection** can be used to identify features **sufficient** for approximating full model performance
- Other (correlated) sets could potentially achieve similar performance

Variable	Cost of Omission
$ c/v - 4.26 $	100
$ c/v - 4.26 ^2$	69
$(v/c)^2 \times \text{SapsBestCVMean}$	53
$ c/v - 4.26 \times \text{SapsBestCVMean}$	33

Fixed Ratio Data



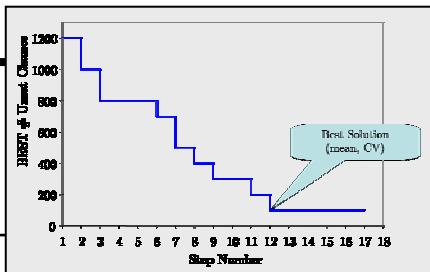
Fixed Ratio Prediction (Kcnfs)

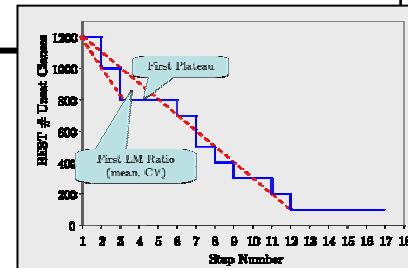


Feature Importance – Fixed Ratio

Variable	Cost of Omission
$SapsBestSolMean^2$	100
$SapsBestSolMean \times MeanDPLLDepth$	74
$GsatBestSolCV \times MeanDPLLDepth$	21
$VCGClauseMean \times GsatFirstLMRatioMean$	9

Feature Importance – Fixed Ratio

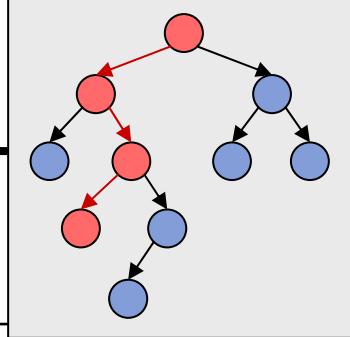
Variable	Cost of Omission
	100
$SapsBestSolMean^2 \times MeanDPLLDepth$	74
$GsatBestSolCV \times MeanDPLLDepth$	21
$VCGClauseMean \times GsatFirstLMRatioMean$	9

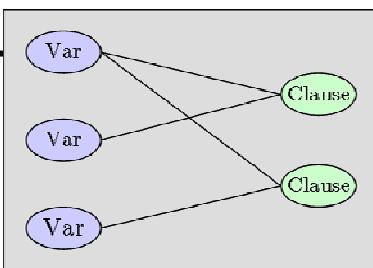


Feature Importance – Fixed Ratio

Variable	Cost of Omission
$SapsBestSolMean^2$	100
$SapsBestSolMean \times \text{MeanDPLLDepth}$	74
$GsatBestSolCV \times \text{MeanDPLLDepth}$	21
$VCGClauseMean \times GsatFirstLMRatioMean$	9

(Note: The first four rows correspond to the variables shown in the table above.)



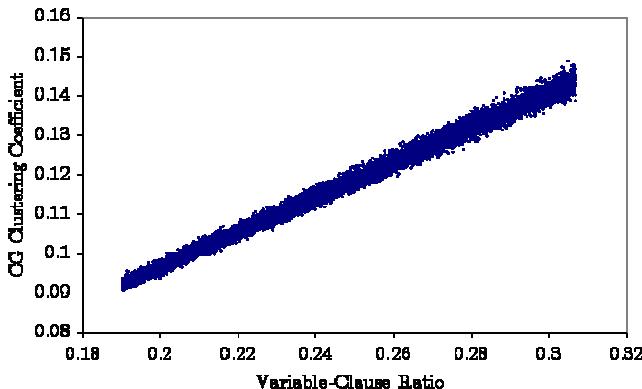


SAT vs. UNSAT

- Training models separately for SAT and UNSAT instances:
 - good models require fewer features
 - model accuracy improves
 - c/v no longer an important feature for VR data
 - Completely different features are useful for SAT than for UNSAT
- Feature importance on SAT instances:
 - Local Search features sufficient
 - 7 features for good VR model
 - 1 feature for good FR model ($SAPSBestSolCV \times SAPSAveImpMean$)
 - If LS features omitted, LP + DPLL search space probing
- Feature importance on UNSAT instances:
 - DPLL search space probing
 - Clause graph features

Beyond Ratio: Weighted CG Clustering Coefficient

- Byproduct of our analysis: a very **strong correlation** between weighted CG clustering coefficient and v/c



- Clustering coefficient is a more fundamental concept than v/c , since it describes the **structure of the constraints** explicitly, not implicitly.
 - correlation between (unweighted) CC and hardness has been shown for **other constraint problems** (e.g., graph coloring, combinatorial auctions)
- We have a **proof sketch** of this correlation

Conclusions

- Can construct **good models** for DPLL solvers
- These models can be **analyzed** to gain understanding about what makes instances hard or easy for solvers
- **Algorithm portfolios** can be constructed (**Satzilla**)
- More specifically:
 - Strong relationship between **LS** and **DPLL** search spaces
 - Our approach **automatically identified** importance of c/v
 - **SAT/UNSAT instances** have very different performance characteristics; it helps to model them separately
 - **Clustering Coefficient** explains why c/v is important in terms of local properties of constraint graph