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ATSC 500 – Boundary Layer Meteorology

Final project report

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A COMPARISON OF MODEL AND OBSERVATIONAL DATA IN THE ATMOSPHERIC BOUNDARY LAYER

**Introduction**

It’s important for models to be able to simulate the atmosphere fairly accurately for them to be useful to us. The boundary layer (BL) is one of the many things a model should be able to simulate. In order to simulate the boundary layer, models are required to have planetary boundary layer (PBL) schemes in which they parameterize boundary layer processes. These parameterizations need to be made because models are not able to resolve fluxes at the required spatial scales for the BL.  This is because the length-scales of eddies are smaller than the model grid spacing (which is normally somewhere between 1 and 4 km). Accuracy in PBL schemes is important because uncertainty and inaccuracies in these forecasts can have impacts on larger scale phenomena (Coniglio et al, 2013).

In order to determine the ability of a model to simulate the BL, I will compare the results of model simulations to observations taken in the boundary layer by atmospheric soundings (sondes).

**Study Area**

My area of study is Cape Town, South Africa (33° 55’ 31’’ S, 18° 25’ 26’’ E). I have chosen this location because I am familiar with the area and the weather and thus I am able to have an intuition of the physical processes represented by the data. Cape Town’s time zone is GMT+2. This means that the data at 00z and 12z correspond to 02:00 and 14:00 local time, respectively, and provides examples of soundings both during the day and at night. Although I have specifically chose Cape Town for this project, the methodology could easily be applied to other locations given available data.

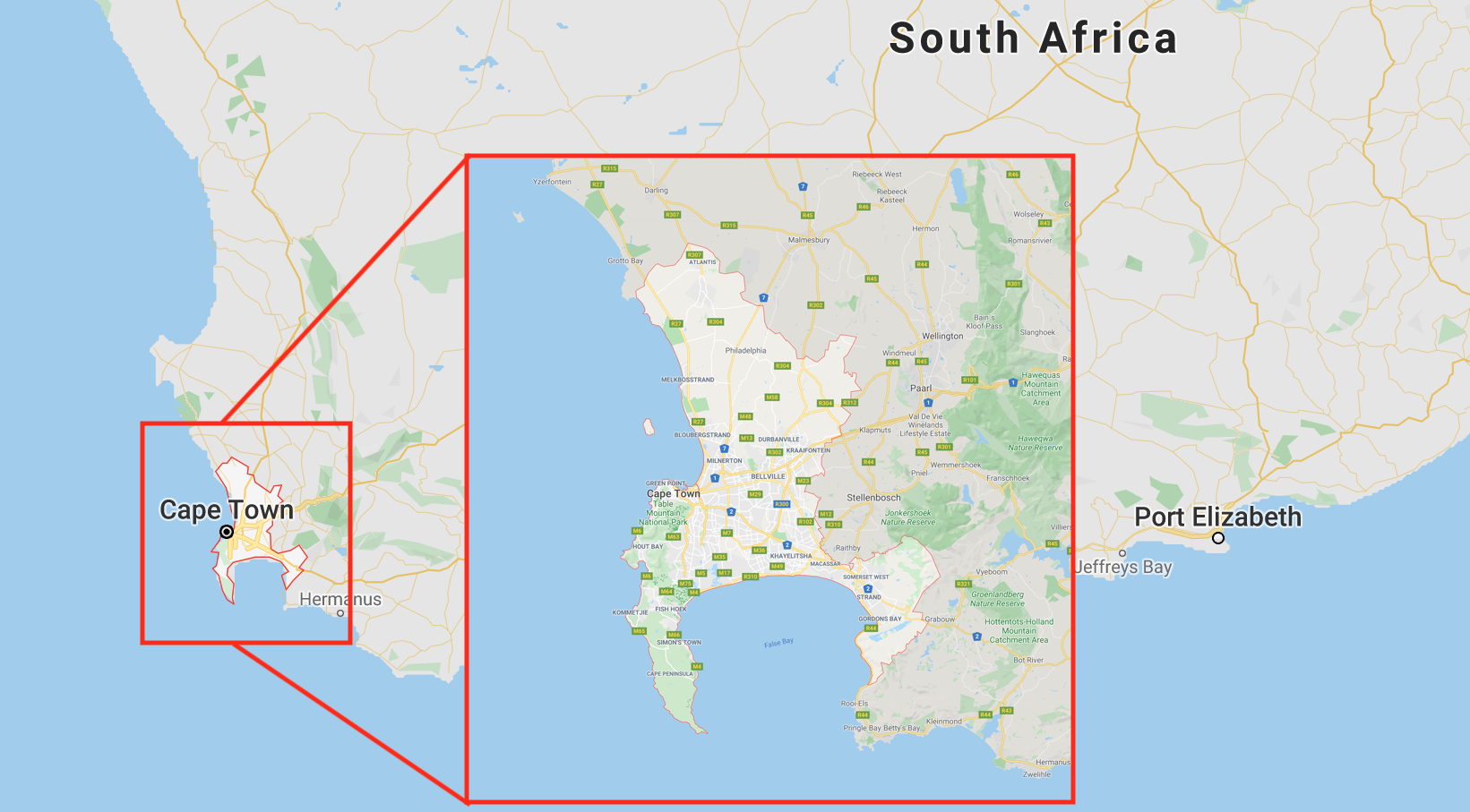


Fig. Map of Cape Town, South Africa

**Data**

**MODEL**

I use two different data sets for this project: model data and observational data. The model data is from the North American Ensemble Forecast System (NAEFS; archived NAEFS data is available on out team servers; ref). NAEFS is a 42-member ensemble, made up of 21 Canadian members and 21 American members. Each group of 21 members comprises one control member and 20 perturbed members. The control members are the national weather models for Canada: the Global Environmental Multiscale Model (GEM), and for the United States: the Global Forecast System Model (GFS). Perturbations in the model are in initial conditions and the physics schemes (ECC Canada, 2019).

For this project I use only one ensemble member: the GFS control member. The model is initialised at 00z every day and I use daily forecast runs initialised at this time. The forecasts are available for 6-hourly time intervals: 00z, 06z, 12z and 18z. In order to compare model data with corresponding observations, I use only the data available at only 00z and 12z.

The NAEFS models have forecasts for various pressure levels, three of which may able to capture the boundary layer, depending on boundary layer height: 1000 kPa, 925 kPa and 850 kPa. Thus, these are the levels used in my analysis.

**OBSERVATIONS**

Observations are from sounding data, available from the University of Wyoming website (ref). Sounding data is generally available at 00z and 12z and sometimes for Cape Town it is available at 09z. Soundings record data at many points within the PBL. The heights and associated pressure levels at which they are recorded are not consistent. In order to compare soundings with model data, I interpolate the soundings to the 1000 kPa, 925 kPa and 850 kPa pressure levels.

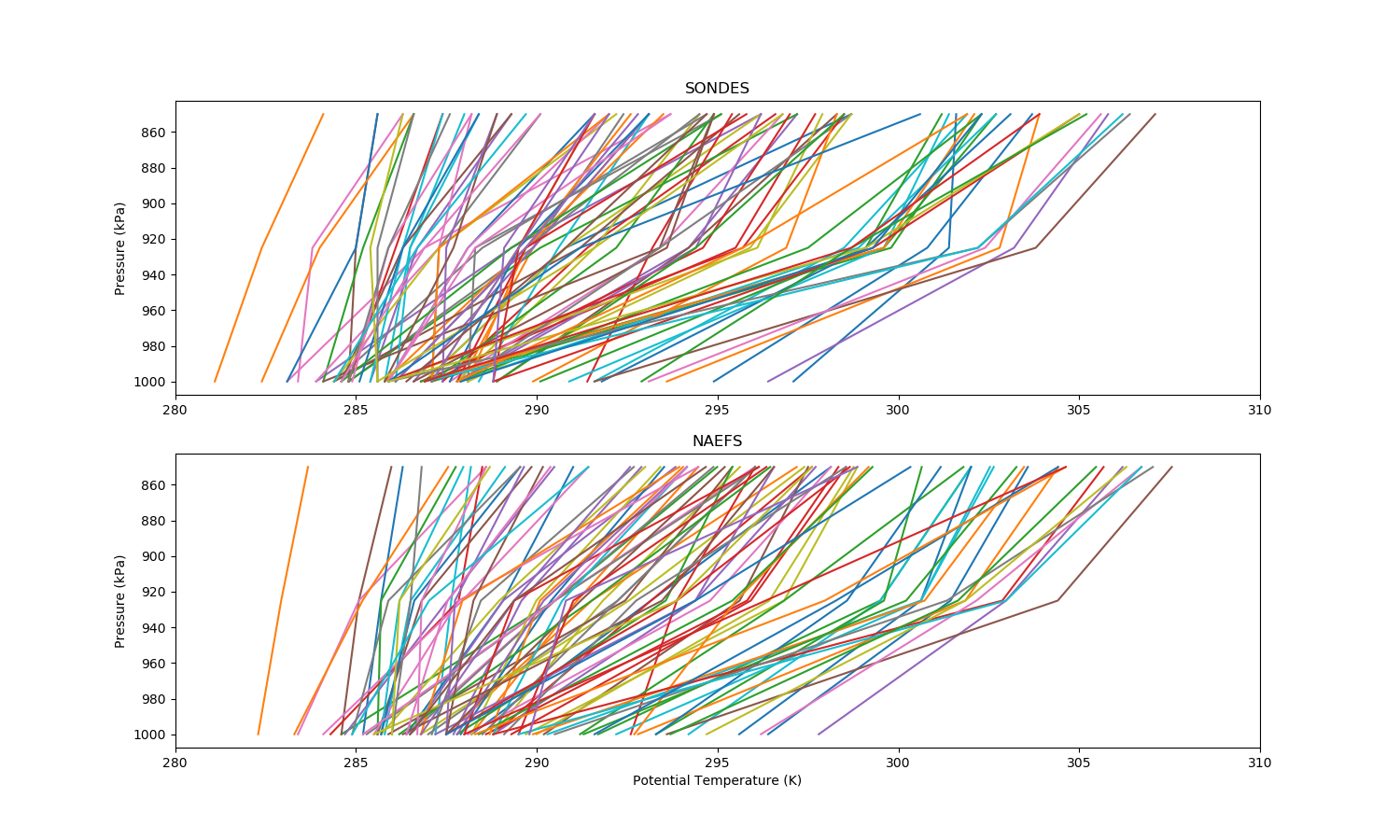
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Fig. Potential temperature at 1000 kPa, 925 kPa and 850 kPa for soundings and NAEFs

**NAEFS PBL SCHEME**

As discussed earlier, the PBL scheme of any model will determine its ability to forecast variables in the boundary layer. What follows will be a brief discussion of the PBL scheme used in the Global Forecast System model.

GFS uses a hybrid Eddy Diffusivity Mass Flux (EDMF) boundary layer parameterization scheme. It is hybrid in the sense that different schemes are used under different conditions in order to improve forecast accuracy. This new hybrid scheme was implemented in 2015 in order to improve the simulation of PBL growth in the model. The previous scheme that was used is an Eddy Diffusivity Counter Gradient (EDCG) scheme, which tended to under estimate PBL growth, hence the implementation of the EDMF scheme, which takes into account updraft fluxes. However, the EDMF scheme was shown to overestimate mixing in the tropics where the PBL is seldom strongly unstable. Thus, the EDCG scheme is still used in these areas as it better represents vertical mixing under more stable conditions. The BL scheme is selected depending on the stability of the model, making it a hybrid scheme. Stability is determined using z/L where L is the Monin-Obukhov stability parameter. The PBL is classified as strongly unstable (convective) for z/L < -0.5, and as weakly and moderately unstable for 0 > z/L > -0.5, after Sorbjan (1989) (Han et. al., 2016).

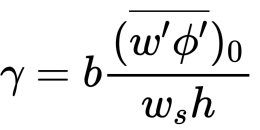
How the two schemes differ:

The two schemes differ in their calculation of the vertical turbulent flux. In the counter gradient (CG) scheme the vertical turbulent flux is determined as follows:

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where overbars denote spatial averages, primes are turbulent fluxes, K is the turbulent eddy diffusivity, and is the nonlocal CG mixing term due to large nonlocal convective eddies.

Here is determined as:

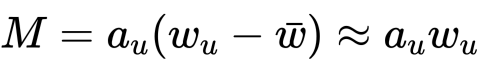
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which is the surface turbulent flux of the variable, over the velocity scale (ws) multiplied by BL height (h).

In the mass flux (MF) scheme the nonlocal gradient mixing term, γ, is replaced with a mass flux term and the vertical turbulent flux is calculated by:

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where the subscript u refers to the updraft properties and M is the updraft mass flux, calculated as:

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and *au* is a small, fixed updraft fractional area that contains the strongest upward vertical velocities.

The results of changing this scheme can be seen in Figure ? and figure ?. These figures show the comparison of the GFS single column model with a Large Eddy Simulation (LES) from SAM (the System for Atmospheric Modeling). Plotted are the vertical profiles of potential temperature and turbulent heat flux for both models.

Fig ? shows the EDCG PBL scheme and one can see that the potential temperature does not mix high enough. This is because the SCM under estimates the heat flux in comparison to the LES (b). Figure ? shows that the EDMF scheme improves results by better representing updraft fluxes.

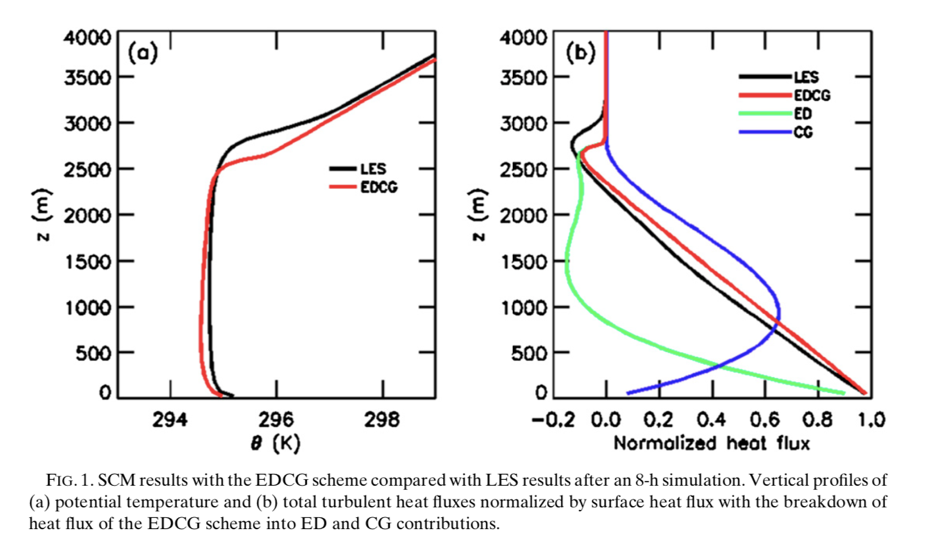


FIG. 1. Results of LES model and SCM using the EDCG scheme after an 8-hour simulation. Vertical profiles of (a) potential temperature and (b) total turbulent heat fluxes normalized by surface heat flux are shown, with fluxes broken down into the contributing ED and CG parts.

SCM results with the EDCG scheme compared with LES results after an 8-h simulation. Vertical profiles of (a) potential temperature and (b) total turbulent heat fluxes normalized by surface heat flux with the breakdown of heat flux of the EDCG scheme into ED and CG contributions (Han et. al., 2016).

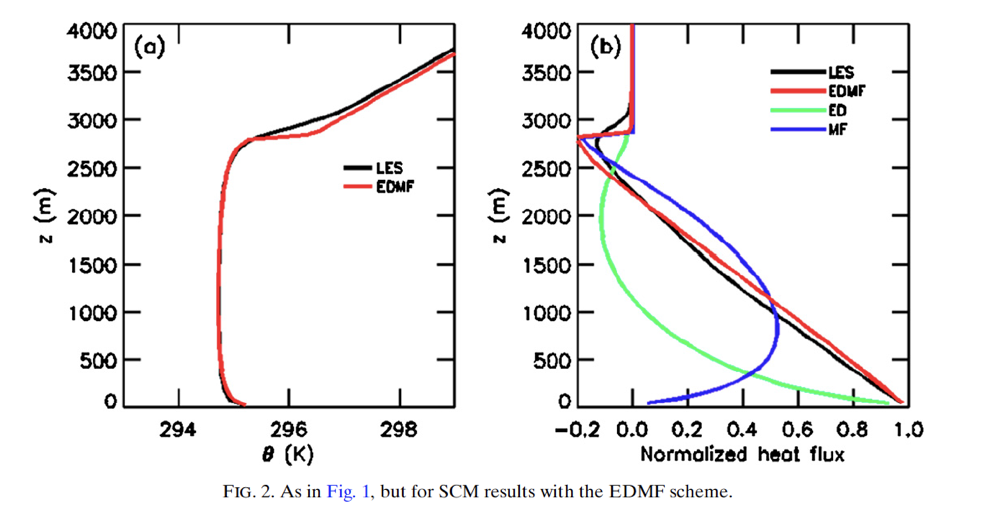
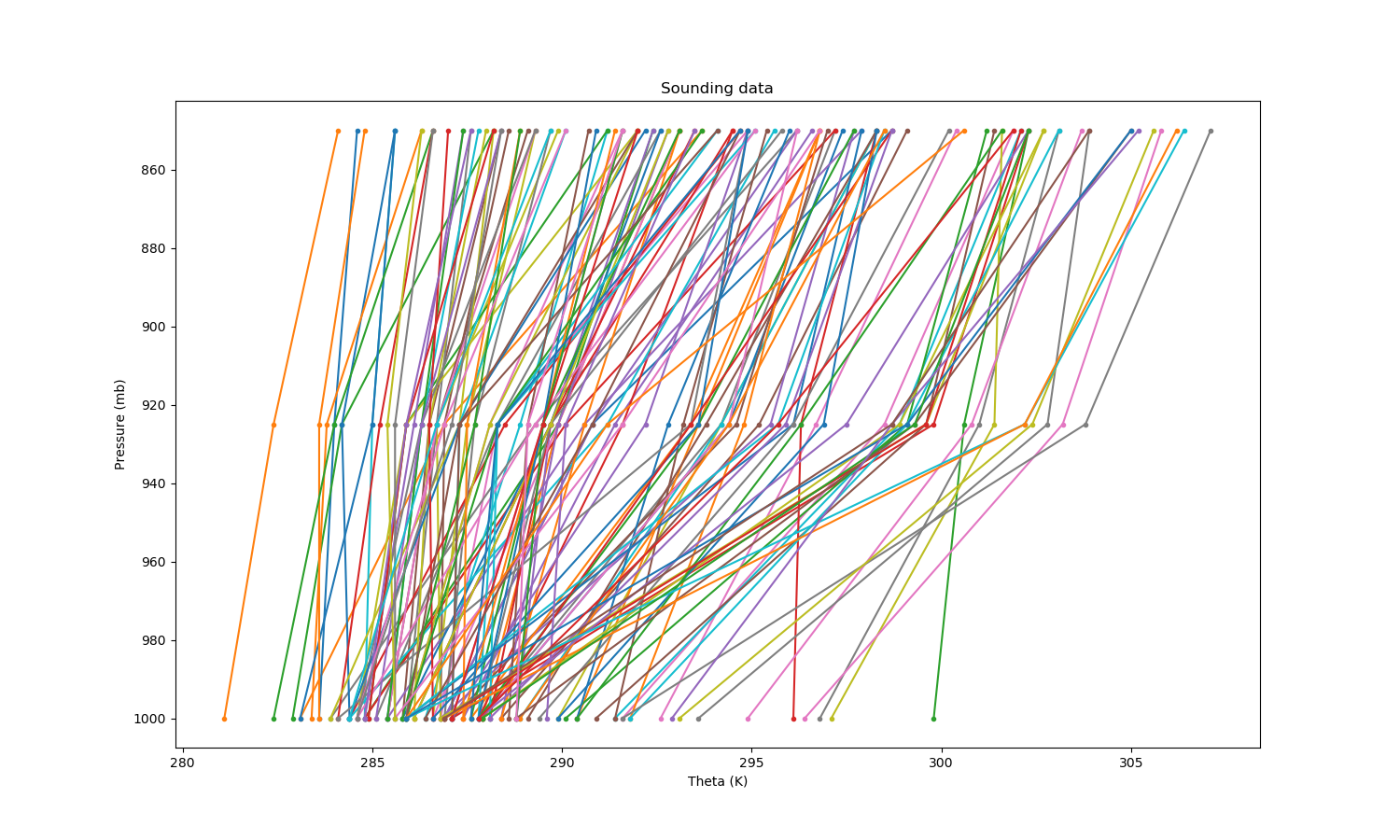
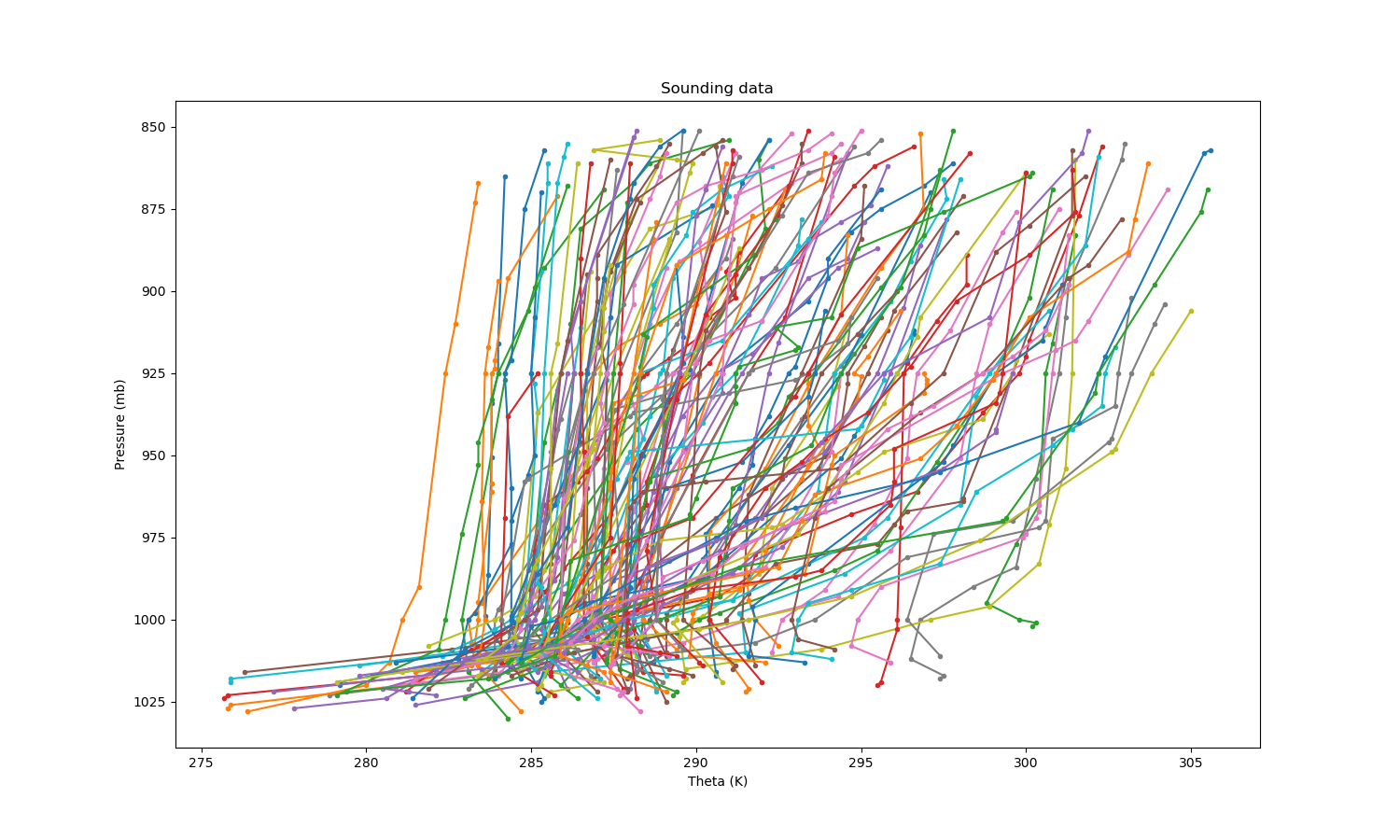


Fig. Results of LES model and SCM using the EDCG scheme after an 8-hour simulation. Vertical profiles of (a) potential temperature and (b) total turbulent heat fluxes normalized by surface heat flux are shown, with fluxes broken down into the contributing ED and MF parts. (Han et. al., 2016).

**Methods**

Determine overlapping dates

Interpolate soundings

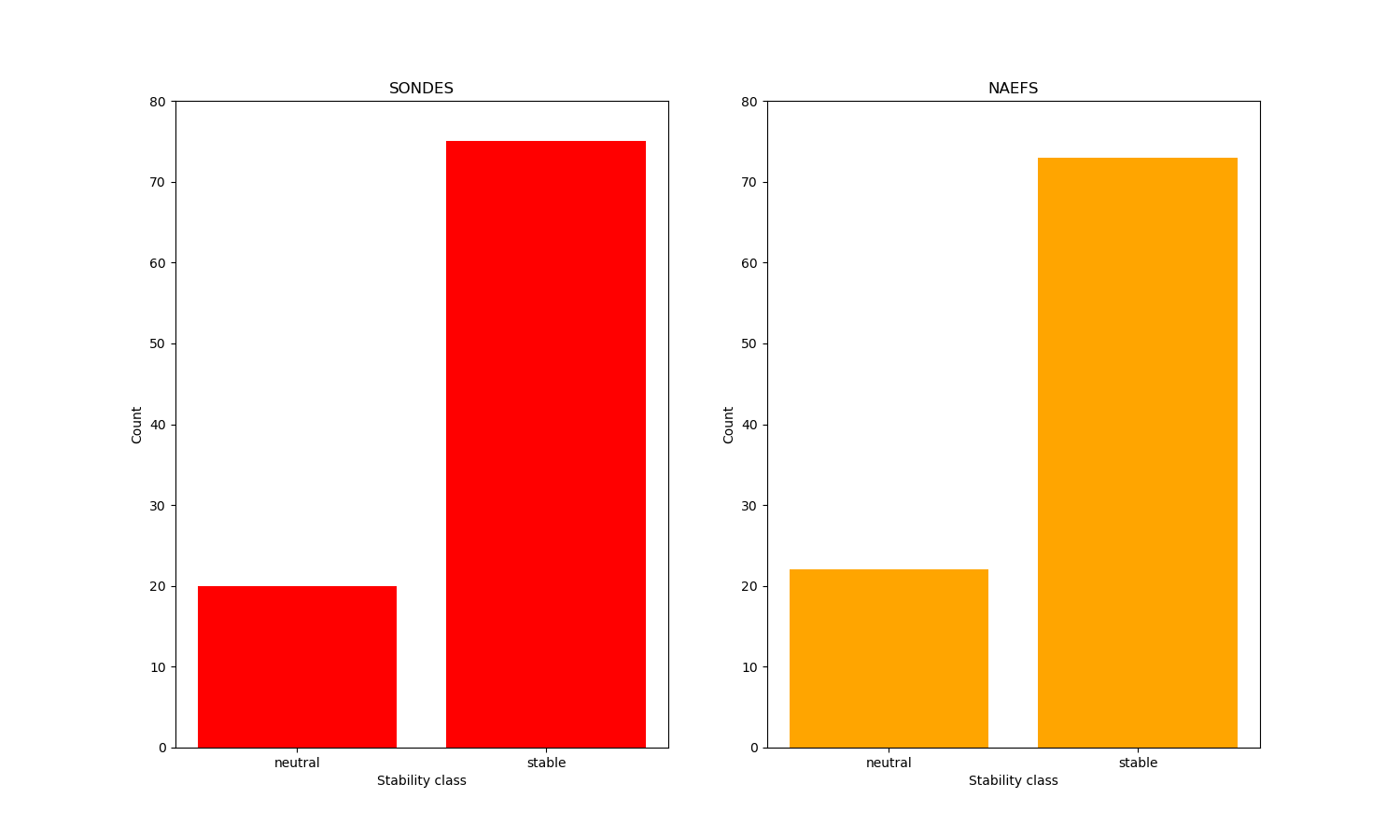


Calculate theta in NAEFS

Calculate gradients (theta)

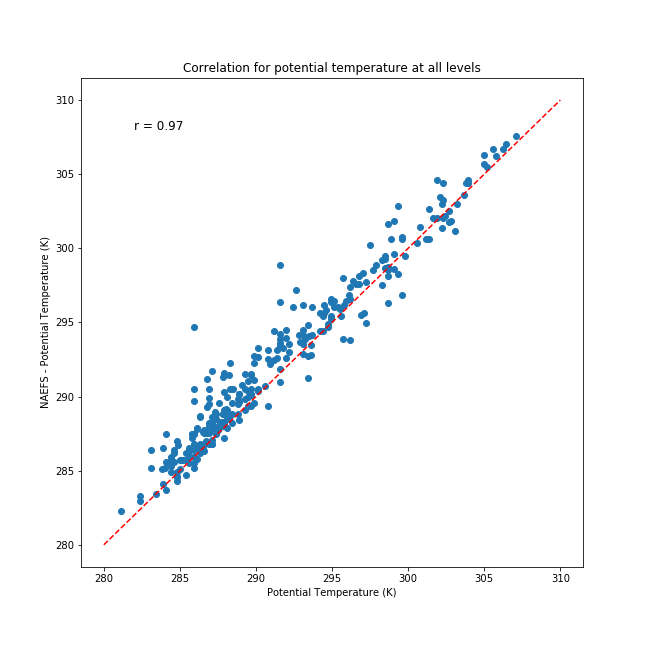
Identify stability classes

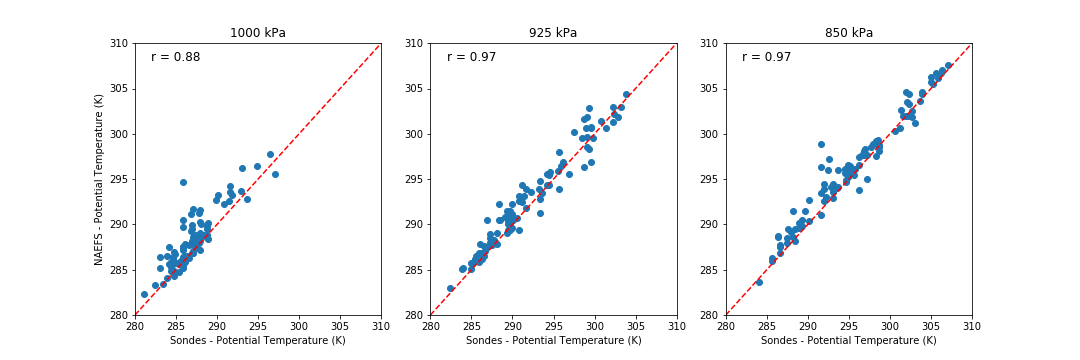
-- how did I do this?

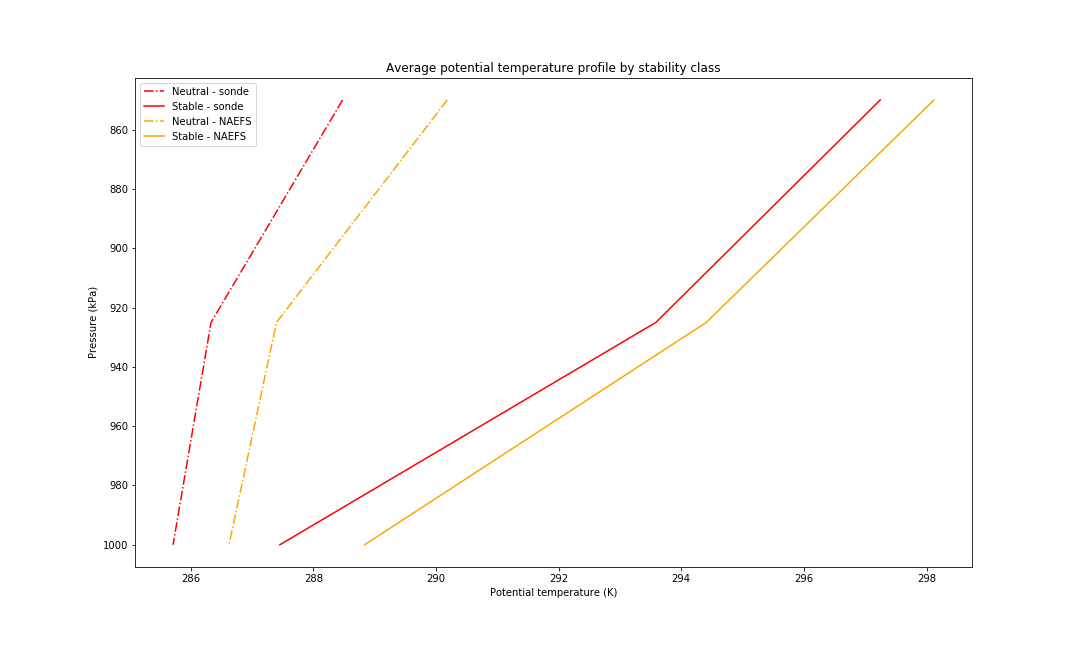


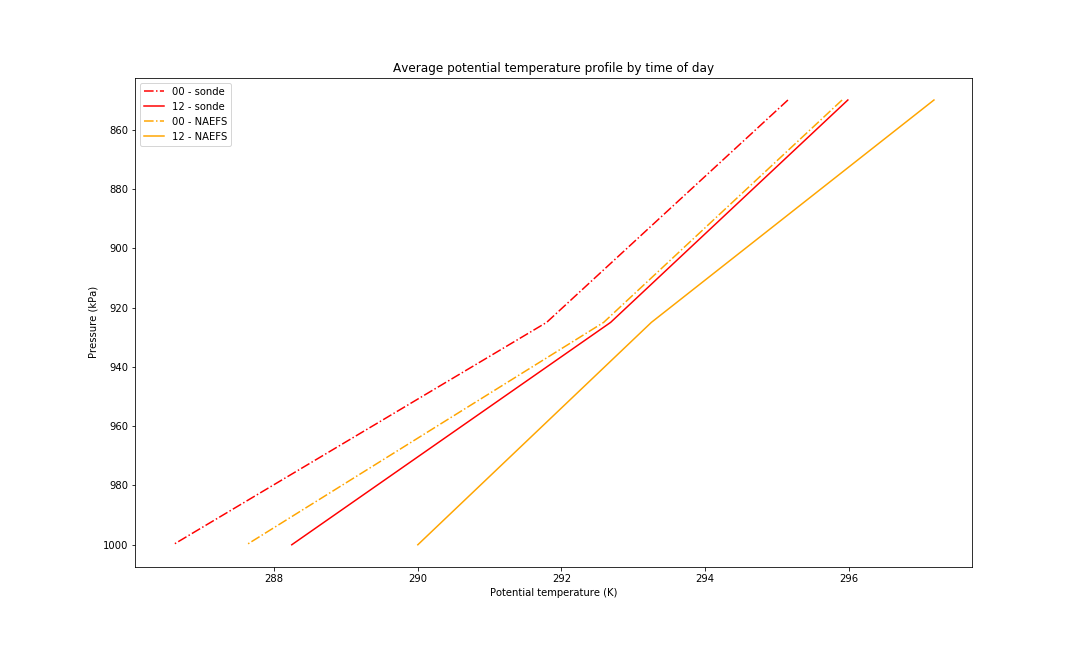
Compare data across stability classes

**Results**

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| --- | --- | --- | --- | --- |
|  | **MAE (K)** | **MAPE (%)** | **RMSE** | **Correlation (r)** |
| **All levels** | 1.220 | 0.419 | 1.670 | 0.973 |
| **1000 kPa** | 1.398 | 0.487 | 1.941 | 0.878 |
| **925 kPa** | 1.126 | 0.385 | 1.438 | 0.974 |
| **850 kPa** | 1.136 | 0.386 | 1.591 | 0.975 |

**Discussion**

**Conclusion**

**References**

Han, J., Witek, M. L., Teixeira, J., Sun, R., Pan, H.-L., Fletcher, J. K., & Bretherton, C. S. (2016). Implementation in the NCEP GFS of a Hybrid Eddy-Diffusivity Mass-Flux (EDMF) Boundary Layer Parameterization with Dissipative Heating and Modified Stable Boundary Layer Mixing. *Weather and Forecasting*, *31*(1), 341–352. <https://doi.org/10.1175/WAF-D-15-0053.1>

Coniglio, M. C., Correia, J., & Marsh, P. T. (n.d.). Verification of Convection-Allowing WRF Model Forecasts of the Planetary Boundary Layer Using Sounding Observations. https://doi.org/10.1175/WAF-D-12-00103.1

Environment and Climate Change Canada. (2019). *The Global Ensemble Prediction System (GEPS) version 6.0.0 of the Meteorological Service (MSC) of Canada*. Retrieved from http://collaboration.cmc.ec.gc.ca/cmc/cmoi/product\_guide/docs/lib/technote\_geps-600\_20190703\_e.pdfhttp://collaboration.cmc.ec.gc.ca/cmc/cmoi/product\_guide/docs/changes\_e.htmlhttp://collaboration.cmc.ec.gc.ca/cmc/CMOI/product\_guide/docs/

**NOTES**