

Technical Safety Concept Lane Assistance

**Document Version: 1.1**

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# Document history

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| --- | --- | --- | --- |
| Date | Version | Editor | Description |
| 5 September 2017 | 1.0 | Edward Venator | Initial submission |
| 16 September 2017 | 1.1 | Edward Venator | Correct allocation of TSR-01-01-05  Correct typo in TSR-01-02-01  Correct allocation of TSR-01-02-05  Correct typo in WDC-02  Correct ASIL level of FSR-02-01  Correct FTTI of all TSRs of FSR-02-01 |
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# Purpose of the Technical Safety Concept

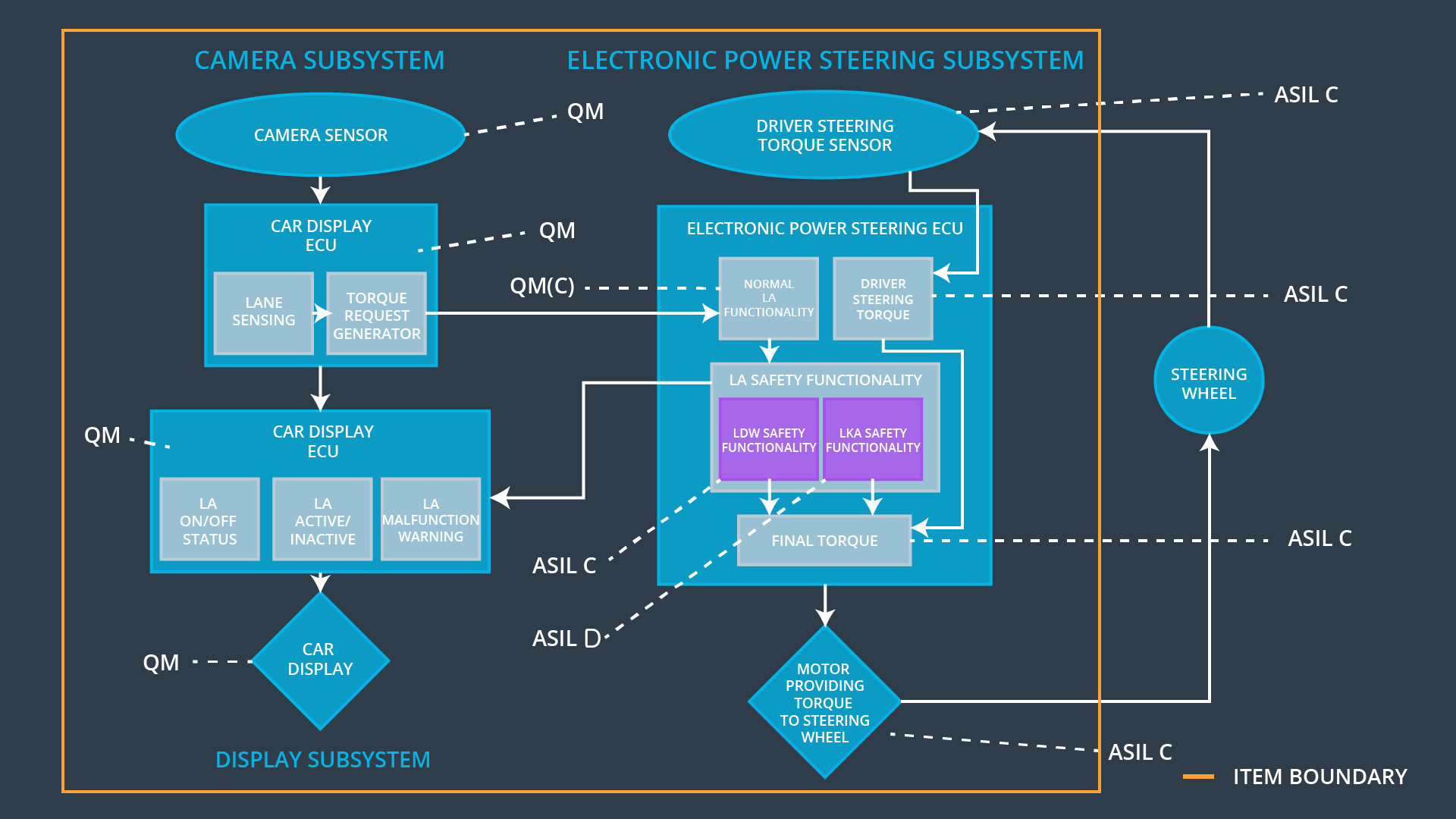
The purpose of the technical safety concept is to refine the functional safety concept to a level of detail that can be implemented.

# Inputs to the Technical Safety Concept

## Functional Safety Requirements

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Safe State** |
| Functional  Safety  Requirement  01-01 | The lane keeping item shall ensure that the lane departure oscillating torque is below Max\_Torque\_Ampliltude. | C | 50ms | LDW disabled (output torque zero) |
| Functional  Safety  Requirement  01-02 | The lane keeping item shall ensure that the lane departure oscillating torque is below Max\_Torque\_Frequency. | C | 50ms | LDW disabled (output torque zero) |
| Functional  Safety  Requirement  02-01 | The electronic power steering ECU shall ensure that the lane keeping assistance torque is applied for only Max\_Duration. | B | 500ms | LKA disabled (output torque zero) |
| Functional Safety Requirement 03-01 | The electronic power steering ECU shall ensure that the lane keeping assistance torque is below Max\_Torque\_Magnitude. | D | 50ms | LKA disabled (output torque zero) |

## Refined System Architecture from Functional Safety Concept



### Functional overview of architecture elements

|  |  |
| --- | --- |
| **Element** | **Description** |
| Camera Sensor | Captures imagery of the road in front of the car. |
| Camera Sensor ECU - Lane Sensing | Determines the position of the car in the ego lane based on imagery from the Camera Sensor. |
| Camera Sensor ECU - Torque request generator | Calculates required torque for LDW and LKA functions and sends torque requests to the Electronic Power Steering ECU. |
| Car Display | Displays the status of system functions using lights. |
| Car Display ECU - Lane Assistance On/Off Status | Keeps track of whether the Lane Assistance is on or off and controls an indicator on the Car Display. |
| Car Display ECU - Lane Assistant Active/Inactive | Keeps track of whether the Lane Assistant is Active or Inactive and controls an indicator on the Car Display. |
| Car Display ECU - Lane Assistance malfunction warning | In the event of any malfunction in the Lane Assistance system, illuminates an indicator light on the Car Display. |
| Driver Steering Torque Sensor | Measures the torque being applied to the steering wheel. |
| Electronic Power Steering (EPS) ECU - Driver Steering Torque | Processes measurements from the Driver Steering Torque Sensor. |
| EPS ECU - Normal Lane Assistance Functionality | Calculate torque to apply to the steering wheel to maintain the car’s position in the lane. |
| EPS ECU - Lane Departure Warning Safety Functionality | Ensure that steering wheel torque does not exceed Max\_Torque\_Amplitude or Max\_Torque\_Frequency. |
| EPS ECU - Lane Keeping Assistant Safety Functionality | Ensure the LKA function is not active for longer than Max\_Duration. |
| EPS ECU - Final Torque | Combine driver steering torque and lane assistance torque to get the final torque requires from the motor. |
| Motor | Provides torque to the steering wheel; controlled by the Electronic Power Steering ECU. |

# Technical Safety Concept

## Technical Safety Requirements

**Lane Departure Warning (LDW) Requirements:**

Functional Safety Requirement 01-01 with its associated system elements

(derived in the functional safety concept)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Functional  Safety  Requirement  01-01 | The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max\_Torque\_Amplitude | X |  |  |

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **ID** | **Technical Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Architecture Allocation** | **Safe State** |
| Technical  Safety  Requirement  01 | The LDW safety component shall ensure that the amplitude of the 'LDW\_Torque\_Request' sent to the 'Final electronic power steering Torque' component is below 'Max\_Torque\_Amplitude. | C | 50ms | LDW Safety | LDW disabled (output torque zero) |
| Technical  Safety  Requirement  02 | As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW\_Torque\_Request' shall be set to zero. | C | 50ms | LDW Safety | LDW disabled (output torque zero) |
| Technical  Safety  Requirement  03 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light. | C | 50ms | LDW Safety | LDW disabled (output torque zero) |
| Technical  Safety  Requirement  04 | The validity and integrity of the data transmission for 'LDW\_Torque\_Request' signal shall be ensured. | C | 50ms | Data Transmission Integrity Check | LDW disabled (output torque zero) |
| Technical  Safety  Requirement  05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | C | Ignition cycle | Separate External Block of Memory | LDW disabled (output torque zero) |

Functional Safety Requirement 01-2 with its associated system elements

(derived in the functional safety concept)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Functional  Safety  Requirement  01-02 | The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max\_Torque\_Frequency | X |  |  |

Technical Safety Requirements related to Functional Safety Requirement 01-02 are:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **ID** | **Technical Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Architecture Allocation** | **Safe State** |
| Technical  Safety  Requirement  01 | The LDW safety component shall ensure that the frequency of the 'LDW\_Torque\_Request' sent to the 'Final electronic power steering Torque' component is below 'Max\_Torque\_Frequency. | C | 50ms | LDW Safety | LDW disabled (output torque zero) |
| Technical  Safety  Requirement  02 | As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW\_Torque\_Request' shall be set to zero. | C | 50ms | LDW Safety | LDW disabled (output torque zero) |
| Technical  Safety  Requirement  03 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light. | C | 50ms | LDW Safety | LDW disabled (output torque zero) |
| Technical  Safety  Requirement  04 | The validity and integrity of the data transmission for 'LDW\_Torque\_Request' signal shall be ensured. | C | 50ms | Data Transmission Integrity Check | LDW disabled (output torque zero) |
| Technical  Safety  Requirement  05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | A | Ignition cycle | Separate External Block of Memory | LDW disabled (output torque zero) |

**Lane Keeping Assistance (LKA) Requirements:**

Functional Safety Requirement 02-1 with its associated system elements

(derived in the functional safety concept)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Functional  Safety  Requirement  02-01 | The lane keeping item shall ensure that the lane keeping assistance torque is applied for only Max\_Duration | X |  |  |

Technical Safety Requirements related to Functional Safety Requirement 02-01 are:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **ID** | **Technical Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Allocation to Architecture** | **Safe State** |
| Technical  Safety  Requirement  01 | The LKA safety component shall ensure that the lane keeping assistance torque is applied for only Max\_Duration. | B | 500ms | LKA Safety | LKA disabled (output torque zero) |
| Technical  Safety  Requirement  02 | As soon as a failure is detected by the LKA function, it shall deactivate the LKA feature and the ‘LKA\_Torque\_Request' shall be set to zero. | B | 50ms | LKA Safety | LKA disabled (output torque zero) |
| Technical  Safety  Requirement  03 | As soon as the LKA function deactivates the LKA feature, the LKA Safety' software block shall send a signal to the car display ECU to turn on a warning light. | B | 500ms | LKA Safety | LKA disabled (output torque zero) |
| Technical  Safety  Requirement  04 | The validity and integrity of the data transmission for LKA\_Torque\_Request' signal shall be ensured. | B | 500ms | Data Transmission Integrity Check | LKA disabled (output torque zero) |
| Technical  Safety  Requirement  05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | A | Ignition cycle | Safety Startup | LKA disabled (output torque zero) |

Functional Safety Requirement 03-1 with its associated system elements

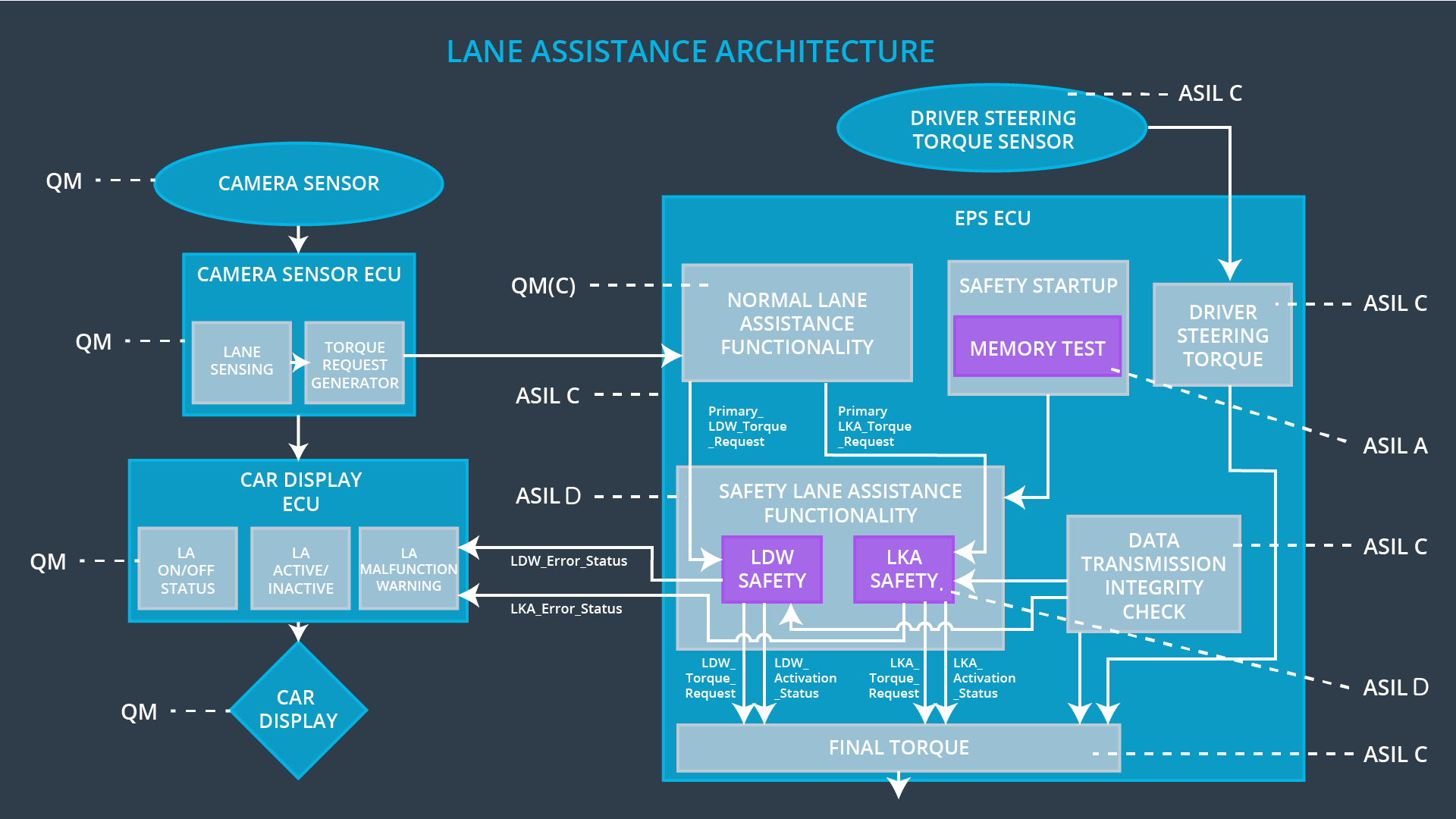
(derived in the functional safety concept)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Functional  Safety  Requirement  03-01 | The electronic power steering ECU shall ensure that the lane keeping assistance torque is below Max\_Torque\_Magnitude. | X |  |  |

Technical Safety Requirements related to Functional Safety Requirement 03-01 are:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **ID** | **Technical Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Allocation to Architecture** | **Safe State** |
| Technical  Safety  Requirement  01 | The LKA safety component shall ensure that the amplitude of the ‘LKA\_Torque\_Request' sent to the 'Final electronic power steering Torque' component is below 'Max\_Torque\_Magnitude.’ | D | 50ms | LKA Safety | LKA disabled (output torque zero) |
| Technical  Safety  Requirement  02 | As soon as a failure is detected by the LKA function, it shall deactivate the LKA feature and the LKA\_Torque\_Request' shall be set to zero. | D | 50ms | LKA Safety | LKA disabled (output torque zero) |
| Technical  Safety  Requirement  03 | As soon as the LKA function deactivates the LKA feature, the LKA Safety' software block shall send a signal to the car display ECU to turn on a warning light. | D | 50ms | LKA Safety | LKA disabled (output torque zero) |
| Technical  Safety  Requirement  04 | The validity and integrity of the data transmission for LKA\_Torque\_Request' signal shall be ensured. | D | 50ms | Data Transmission Integrity Check | LKA disabled (output torque zero) |
| Technical  Safety  Requirement  05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | A | Ignition cycle | Safety Startup | LKA disabled (output torque zero) |

## Refinement of the System Architecture

****Allocation of Technical Safety Requirements to Architecture Elements

All of the technical safety requirements are allocated the Electronic Power Steering ECU. Further detail is shown in the tables above.

## Warning and Degradation Concept

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Degradation Mode** | **Trigger for Degradation Mode** | **Safe State invoked?** | **Driver Warning** |
| WDC-01 | Turn off LDW | The LDW applies an oscillating torque with very high amplitude (above limit). | Yes | Display shows warning light |
| WDC-02 | Turn off LDW | The LDW applies an oscillating torque with very high frequency (above limit). | Yes | Display shows warning light |
| WDC-03 | Turn off LKA | The LKA function is not time-limited, allowing its misuse as an autonomous driving function. | Yes | Display shows warning light |