

## Team Note of Powered by Zigui

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|  |           |
|--|-----------|
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ALL BELOW HERE ARE USELESS IF YOU READ THE STATEMENT WRONG

## 0 Quotes and Prerequisites

evenharder : Mental Abuse To Humans  
 djkim0613 : 열심히 응원하겠습니다.  
 SoulTch : How much is this bus ticket?  
 \* This template is brought from that of 'Deobureo Minkyu Party'

### Run script

```
#!/bin/bash
g++ -fsanitize=undefined -std=c++14 -O2 -o /tmp/pow $1.cpp
time /tmp/pow < $1.in
# export PATH=~:$PATH
```

### Debug Code

```
#define setz(x) memset(x, 0, sizeof(x))
#define sz(x) ((int)(x).size())
#define rep(i, e) for (int i = 0, _##i = (e); i < _##i; i++)
#define repp(i, s, e) for (int i = (s), _##i = (e); i < _##i; i++)
#define repr(i, s, e) for (int i = (s)-1, _##i = (e); i >= _##i; i--)
#define repi(i, x) for (auto &i : (x))
// using namespace std;
using ll = long long;
using pii = pair<int, int>;
using pll = pair<ll, ll>;
template<typename T>
ostream &operator<<(ostream &os, const vector<T>& v) {
    cout << "[";
    for (auto p : v) cout << p << ", ";
    cout << "]";
    return os;
}
#ifdef __SOULTCH
#define debug(...) 0
#define endl '\n'
#else
#define debug(...) cout << " [-] ", _dbg(#__VA_ARGS__, __VA_ARGS__)
template<class TH> void _dbg(const char *sdbg, TH h){ cout << sdbg << '=' << h << endl; }
template<class TH, class... TA> void _dbg(const char *sdbg, TH h, TA... a) {
    while(*sdbg != ',') cout << *sdbg++;
    cout << '=' << (h) << ', ';
    _dbg(sdbg+1, a...);
}
#endif
```

## Reminders

| Pre-submit   | Wrong answer:   |
|--|---|
| 예제 작성해보기 (최소, 최대)<br>메모리, overflow 분석하기<br>올바른 문제에 제출하기  | 코드 + debug output 출력<br>다중 테케 문제에서 초기화 확인하기<br>알고리즘이 제한조건을 전부 다루는지 확인하기<br>지문 다시 읽어보기<br>corner case 찾아보기<br>초기화 안 된 지역변수 찾아보기<br>N, M, i, j 등 변수 확인하기<br>풀이 증명하기<br>STL 함수 다시 생각해보기<br>팀노트에서 그대로 가져온 변수값 다시 확인하기<br>이 목록 다시 읽어보기<br>알고리즘 팀원에게 설명하기<br>팀원이랑 코드 보기<br>잠깐 일어나서 생각 재정비하고 오기<br>입출력 형식 확인하기 (whitespace 포함) |
| Runtime error:   | Time limit exceeded: / Memory limit exceeded:   |
| 코너 케이스 처리해보기<br>초기화 안 된 변수 찾기<br>out-of-range 확인하기<br>팀노트에서 그대로 가져온 변수값 다시 확인하기<br>assertion 넣어보기<br>무한 재귀 확인하기<br>null pointer 확인하기<br>메모리 사용량 확인하기 | 무한 루프 확인하기<br>알고리즘 시간 복잡도 확인하기<br>data copy 어느 정도 하는지 확인하기 (reference)<br>입출력 규모 생각하기 (scanf 고려해보기)<br>vector, map 최소화하기<br>팀원에게 알고리즘 물어보기<br>최대 메모리 사용량 계산하기<br>다중 테케 문제에서 초기화하기   |

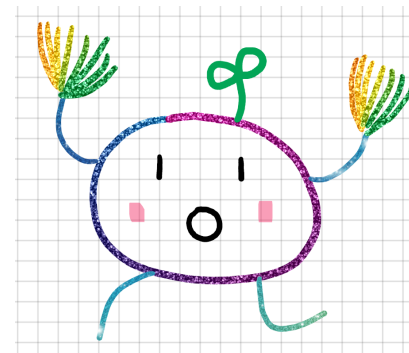


Figure 1: 풀다가 막힐 때는 이 그림을 봅시다. 아자아자 화이팅!

# 1 Math

## 1.1 Basic Mathematics

### 1.1.1 Trigonometry

- $\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$
- $\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta$
- $\tan(\alpha \pm \beta) = \frac{\tan \alpha \pm \tan \beta}{1 \mp \tan \alpha \tan \beta}$
- $\sin 2\theta = 2 \sin \theta \cos \theta$
- $c^2 = a^2 + b^2 - 2ab \cos \gamma$

### 1.1.2 Generating Function

- $\sum_n (pn + q)x^n = \frac{p}{1-x} + \frac{q}{(1-x)^2}$  (Arithmetic progression)
- $\sum_n (rx)^n = (1 - rx)^{-1}$  (Geometric progression)
- $\sum_n \binom{m}{n} x^n = (1 + x)^m$  (Binomial coefficient)
- $\sum_n \binom{m+n-1}{n} x^n = (1 - x)^{-m}$  (Multiset coefficient)

### 1.1.3 Calculus

- $\int_a^b f(x) dx = \frac{b-a}{6} \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right]$  (Simpson's Rule, for cubic poly)
- $\int u'v dx = uv - \int uv' dx$  (Integration by parts)

### 1.1.4 Combinatorics

$\begin{bmatrix} n \\ k \end{bmatrix}$  (Stirling numbers of the first kind /  $n$  elem,  $k$  cycle)

- $\begin{bmatrix} n+1 \\ k \end{bmatrix} = n \begin{bmatrix} n \\ k \end{bmatrix} + \begin{bmatrix} n \\ k-1 \end{bmatrix}$ ,  $\begin{bmatrix} n \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ n \end{bmatrix} = 1$

$\begin{Bmatrix} n \\ k \end{Bmatrix}$  (Stirling numbers of the second kind /  $n$  elem,  $k$  unlabeled subset)

- $\begin{Bmatrix} n+1 \\ k \end{Bmatrix} = k \begin{Bmatrix} n \\ k \end{Bmatrix} + \begin{Bmatrix} n \\ k-1 \end{Bmatrix}$ ,  $\begin{Bmatrix} n \\ 0 \end{Bmatrix} = \begin{Bmatrix} 0 \\ n \end{Bmatrix} = 1$

$B_n$  (Bell number,  $n$  elem, partition)

- $B_{n+1} = \sum_{k=0}^n \binom{n}{k} B_k$ ,  $B_{n+1} = \sum_{k=0}^n \begin{Bmatrix} n \\ k \end{Bmatrix}$

- $B_{p^m+n} \equiv mB_n + B_{n+1}$

## 1.2 Number Theory

### 1.2.1 Lattice Points under Line

$$\text{divsum}(\text{to}, c, k, m) = \sum_{i=0}^{\text{to}-1} \left\lfloor \frac{ki + c}{m} \right\rfloor, \text{modsum}(\text{to}, c, k, m) = \sum_{i=0}^{\text{to}-1} (ki + c) \% m$$

```
ull sumsq(ull to) { return to / 2 * ((to-1) | 1); }
ull divsum(ull to, ull c, ull k, ull m) {
    ull res = k / m * sumsq(to) + c / m * to;
    k %= m; c %= m;
    if (!k) return res;
    ull to2 = (to * k + c) / m;
    return res + (to - 1) * to2 - divsum(to2, m-1 - c, m, k);
}
ll modsum(ull to, ll c, ll k, ll m) {
    c = ((c % m) + m) % m; k = ((k % m) + m) % m;
    return to * c + k * sumsq(to) - m * divsum(to, c, k, m);
}
```

### 1.2.2 Shanks' Baby-step Giant-step

```
ll mexp(ll x, ll y, ll p) {
    if (!y) return 1;
    if (y & 1) return x * mexp(x*x%p, y>>1, p) % p;
    return mexp(x*x%p, y>>1, p);
}
vector<ll> get_factor(ll n) {
    vector<ll> v;
    for (ll i=2; i*i<=n; i++) {
        if (n % i == 0) {
            v.push_back(i);
            while (n % i == 0) n /= i;
        }
    }
    if (n > 1) v.push_back(n);
    return v;
}
ll get_primitive(ll n) {
    ll phi = n-1; // assume n is prime
    vector<ll> fact = get_factor(phi);
    for (ll x=2; x<=n; x++) {
        int yes = 1;
        for (ll y : fact) {
            yes &= (mexp(x, phi / y, n) != 1);
        }
        if (yes) return x;
    }
    return -1;
}
// find k s.t. g^k = b mod n
ll bsgs(ll g, ll b, ll n) {
```

```

ll sq = ceil(sqrt(n) + 1e-9);
vector<pl> prec(sq);
for(ll i=0; i<sq; i++) {
    prec[i] = {mexp(g, i, n), i};
}
sort(prec.begin(), prec.end());
ll base = mexp(g, n-1-sq, n); // g^(-m), assume n : prime
ll cur = b;
for(int i=0; i<sq; i++) {
    auto it = lower_bound(prec.begin(), prec.end(), pl(cur, 0));
    if(it->first == cur) {
        return (i*sq + it->second) % (n-1);
    }
    cur = cur * base % n;
}
return -1;
}

```

### 1.2.3 Extended Euclidean Algorithm

```

// ax + by = gcd(a,b). x, y?
pll ext_gcd(ll a, ll b) {
    if(b) {
        auto tmp = ext_gcd(b, a%b);
        return {tmp.second, tmp.first - (a/b) * tmp.second};
    }
    else return {1, 0};
}
// ax = gcd(a, m) mod m. x?
ll mod_inv(ll a, ll m) {
    return (ext_gcd(a, m).first + m) % m;
}

```

### 1.2.4 Chinese Remainder Theorem

```

ll pos_rem(ll a, ll m) { // m > 0. a % m?
    ll res = abs(a) % m;
    return a > 0 ? res : (res ? m - res : 0);
}
// ax = c mod m, bx = d mod n. x?
ll solve(ll a, ll c, ll m, ll b, ll d, ll n) {
    a = pos_rem(a, m); c = pos_rem(c, m); // if a, c not in [0, m)
    b = pos_rem(b, n); d = pos_rem(d, n); // if b, d not in [0, n)
    ll g = _gcd(a, _gcd(c, m)); a /= g, c /= g, m /= g;
    g = _gcd(b, _gcd(d, n)); b /= g, d /= g, n /= g;
    if(c % _gcd(a, m) || d % _gcd(b, n)) return inf;
    ll t1 = (mod_inv(a, m) * c) % m;
    ll t2 = (mod_inv(b, n) * d) % n;
    g = _gcd(m, n);
    ll lc = m * n / g;
    if(abs(t1 - t2) % g) return inf;
}

```

```

pl p = ext_gcd(m, n);
ll q = (t1 * p.second * n/g + t2 * p.first * m/g);
return pos_rem(q, lc);
}

```

### 1.2.5 Möbius Inversion Formula

$$\forall n \in \mathbb{N} \ g(n) = \sum_{d|n} f(d) \implies f(n) = \sum_{d|n} \mu(d) g(n/d)$$

### 1.3 FFT

$$\text{FFT} : (a_0, a_1, \dots, a_{n-1}) \mapsto (\sum_{j=0}^{n-1} a_j (\omega^0)^j, \sum_{j=0}^{n-1} a_j (\omega^1)^j, \dots, \sum_{j=0}^{n-1} a_j (\omega^{n-1})^j)$$

```

using base = complex<double>;
void fft(vector<base>& a, bool inv) {
    int n = a.size(), j = 0;
    vector<base> roots(n/2);
    for(int i=1; i<n; i++) {
        int bit = (n >> 1);
        while(j >= bit) {
            j -= bit;
            bit >>= 1;
        }
        j += bit;
        if(i < j) swap(a[i], a[j]);
    }

    double ang = 2 * acos(-1) / n * (inv ? -1 : 1);
    for(int i=0; i<n/2; i++)
        roots[i] = base(cos(ang * i), sin(ang * i));
    /* In NTT, let prr = primitive root. Then,
    int prr = 3, ang = mexp(prr, (mod - 1) / n);
    if(inv) ang = mexp(ang, mod - 2);
    for(int i=0; i<n/2; i++){
        roots[i] = (i ? (1ll * roots[i-1] * ang % mod) : 1);
    }
    also, make sure to apply modulus under here
    and pre-compute mexp(n, mod-2)
    */
    for(int i=2; i<=n; i<=<1) {
        int step = n / i;
        for(int j=0; j<n; j+=i) {
            for(int k=0; k<i/2; k++) {
                base u = a[j+k], v = a[j+k+i/2] * roots[step * k];
                a[j+k] = u+v;
                a[j+k+i/2] = u-v;
            }
        }
    }
    if(inv) for(int i=0; i<n; i++) a[i] /= n;
}

```

```

void conv(vector<base>& x, vector<base>& y) {
    int n = 2; while(n < x.size()+y.size()) n <= 1;
    x.resize(n); y.resize(n);
    fft(x, false); fft(y, false);
    for(int i=0; i<n; i++) x[i] *= y[i];
    fft(x, true); // access (ll)round(x[i].real())
}

```

#### 1.4 Miller-Rabin + Pollard-Rho

//Prove By Solving - <https://www.acmicpc.net/problem/4149>

```

namespace miller_rabin{
    lint mul(lint x, lint y, lint mod){ return (__int128) x * y % mod; }
    lint ipow(lint x, lint y, lint p){
        lint ret = 1, piv = x % p;
        while(y){
            if(y&1) ret = mul(ret, piv, p);
            piv = mul(piv, piv, p);
            y >>= 1;
        }
        return ret;
    }
    bool miller_rabin(lint x, lint a){
        if(x % a == 0) return 0;
        lint d = x - 1;
        while(1){
            lint tmp = ipow(a, d, x);
            if(d&1) return (tmp != 1 && tmp != x-1);
            else if(tmp == x-1) return 0;
            d >>= 1;
        }
    }
    bool isprime(lint x){
        for(auto &i : {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37}){
            if(x == i) return 1;
            if(x > 40 && miller_rabin(x, i)) return 0;
        }
        if(x <= 40) return 0;
        return 1;
    }
}

namespace pollard_rho{
    lint f(lint x, lint n, lint c){
        return (c + miller_rabin::mul(x, x, n)) % n;
    }
    void rec(lint n, vector<lint> &v){
        if(n == 1) return;
        if(n % 2 == 0){
            v.push_back(2);

```

```

            rec(n/2, v);
            return;
        }
        if(miller_rabin::isprime(n)){
            v.push_back(n);
            return;
        }
        lint a, b, c;
        while(1){
            a = rand() % (n-2) + 2;
            b = a;
            c = rand() % 20 + 1;
            do{
                a = f(a, n, c);
                b = f(f(b, n, c), n, c);
            }while(gcd(abs(a-b), n) == 1);
            if(a != b) break;
        }
        lint x = gcd(abs(a-b), n);
        rec(x, v);
        rec(n/x, v);
    }
    vector<lint> factorize(lint n){
        vector<lint> ret;
        rec(n, ret);
        sort(ret.begin(), ret.end());
        return ret;
    }
};

```

#### 1.5 Black Box Linear Algebra + Kitamasa

```

const int mod = 998244353;
using lint = long long;
lint ipow(lint x, lint p){
    lint ret = 1, piv = x;
    while(p){
        if(p & 1) ret = ret * piv % mod;
        piv = piv * piv % mod;
        p >>= 1;
    }
    return ret;
}

vector<int> berlekamp_massey(vector<int> x){
    vector<int> ls, cur;
    int lf, ld;
    for(int i=0; i<x.size(); i++){
        lint t = 0;
        for(int j=0; j<cur.size(); j++){
            t = (t + 1ll * x[i-j-1] * cur[j]) % mod;
        }

```

```

    if((t - x[i]) % mod == 0) continue;
    if(cur.empty()){
        cur.resize(i+1);
        lf = i;
        ld = (t - x[i]) % mod;
        continue;
    }
    lint k = -(x[i] - t) * ipow(ld, mod - 2) % mod;
    vector<int> c(i-lf-1);
    c.push_back(k);
    for(auto &j : ls) c.push_back(-j * k % mod);
    if(c.size() < cur.size()) c.resize(cur.size());
    for(int j=0; j<cur.size(); j++){
        c[j] = (c[j] + cur[j]) % mod;
    }
    if(i-lf+(int)ls.size()>=(int)cur.size()){
        tie(ls, lf, ld) = make_tuple(cur, i, (t - x[i]) % mod);
    }
    cur = c;
}
for(auto &i : cur) i = (i % mod + mod) % mod;
return cur;
}
int get_nth(vector<int> rec, vector<int> dp, lint n){
    int m = rec.size();
    vector<int> s(m), t(m);
    s[0] = 1;
    if(m != 1) t[1] = 1;
    else t[0] = rec[0];
    auto mul = [&rec](vector<int> v, vector<int> w){
        int m = v.size();
        vector<int> t(2 * m);
        for(int j=0; j<m; j++){
            for(int k=0; k<m; k++){
                t[j+k] += 111 * v[j] * w[k] % mod;
                if(t[j+k] >= mod) t[j+k] -= mod;
            }
        }
        for(int j=2*m-1; j>=m; j--){
            for(int k=1; k<=m; k++){
                t[j-k] += 111 * t[j] * rec[k-1] % mod;
                if(t[j-k] >= mod) t[j-k] -= mod;
            }
        }
        t.resize(m);
        return t;
    };
    while(n){
        if(n & 1) s = mul(s, t);
        t = mul(t, t);

```

```

        n >>= 1;
    }
    lint ret = 0;
    for(int i=0; i<m; i++) ret += 111 * s[i] * dp[i] % mod;
    return ret % mod;
}
int guess_nth_term(vector<int> x, lint n){ // init with > 3k, 0(1^2 lg n)
    if(n < x.size()) return x[n];
    vector<int> v = berlekamp_massey(x);
    if(v.empty()) return 0;
    return get_nth(v, x, n);
}
struct elem{int x, y, v;}; // A_(x, y) <- v, 0-based. no duplicate please..
vector<int> get_min_poly(int n, vector<elem> M){
    // smallest poly P such that A^i = sum_{j < i} {A^j \times P_j}
    vector<int> rnd1, rnd2;
    mt19937 rng(0x14004);
    auto randint = [&rng](int lb, int ub){
        return uniform_int_distribution<int>(lb, ub)(rng);
    };
    for(int i=0; i<n; i++){
        rnd1.push_back(randint(1, mod - 1));
        rnd2.push_back(randint(1, mod - 1));
    }
    vector<int> gobs;
    for(int i=0; i<2*n+2; i++){
        int tmp = 0;
        for(int j=0; j<n; j++){
            tmp += 111 * rnd2[j] * rnd1[j] % mod;
            if(tmp >= mod) tmp -= mod;
        }
        gobs.push_back(tmp);
        vector<int> nxt(n);
        for(auto &i : M){ // sparse matrix * vector
            nxt[i.x] += 111 * i.v * rnd1[i.y] % mod;
            if(nxt[i.x] >= mod) nxt[i.x] -= mod;
        }
        rnd1 = nxt;
    }
    auto sol = berlekamp_massey(gobs);
    reverse(sol.begin(), sol.end());
    return sol;
}
lint det(int n, vector<elem> M){
    vector<int> rnd;
    mt19937 rng(0x14004);
    auto randint = [&rng](int lb, int ub){
        return uniform_int_distribution<int>(lb, ub)(rng);
    };
    for(int i=0; i<n; i++) rnd.push_back(randint(1, mod - 1));

```

```

for(auto &i : M){
    i.v = 111 * i.v * rnd[i.y] % mod;
}
auto sol = get_min_poly(n, M)[0];
if(n % 2 == 0) sol = mod - sol;
for(auto &i : rnd) sol = 111 * sol * ipow(i, mod - 2) % mod;
return sol;
}

```

## 2 Geometry

### 2.1 struct Point

```

const double eps = 1e-10;
template <class T>
struct point{
    typedef point P;
    T x, y;
    point(T x=0, T y=0) : x(x), y(y) {}
    bool operator< (P a) const {return x!=a.x ? x<a.x : y<a.y;}
    bool operator== (P a) const {return x==a.x && y==a.y;}
    P operator+ (P a) const {return P(x+a.x, y+a.y);}
    P operator- (P a) const {return P(x-a.x, y-a.y);}
    P operator- () const {return P(-x, -y);}
    T operator* (P a) const {return x*a.x + y*a.y;} // inner prod
    T operator/ (P a) const {return x*a.y - y*a.x;} // outer prod
    T dist2() const {return x*x + y*y;}
    double dist() const {return sqrt(double(dist2()));}
    P perp() const {return P(-y, x);} // rotate 90 deg ccw
    P mult(T t) const {return P(x*t, y*t);}
    P unit() const {return P(x/dist(), y/dist());}
    P rotate(double a){
        return P(x*cos(a)-y*sin(a), x*sin(a)+y*cos(a));
    }
};
int sgn(double x) {return (x > eps) - (x < -eps);}
typedef point<ll> P; // use point<double> at caution with fabs, eps

```

### 2.2 Distance, Intersection

#### 2.2.1 Point-to-Line

```

double lineDist(P a, P b, P p) {
    return ((b-a)/(p-a))/(b-a).dist(); // a->b : left (+), right : (-);
}

```

#### 2.2.2 Point-to-Segment

```

double segDist(P s, P e, P p) {
    if(s == e) return (p-s).dist(); // mind the eps
    double d = (e-s).dist2(), t = min(d, max(.0, (p-s)*(e-s)));

```

```

    return ((p-s).mult(d)-(e-s).mult(t)).dist() / d;
}

```

#### 2.2.3 Line intersection

```

template<class P>
pair<int, P> lineInter(P a, P b, P c, P d){
    if((b-a)/(d-c) == 0) // parallel, mind the eps
        return {-(b-a)/(c-a) == 0}, a;
    double oa = (d-c)/(a-c), ob = (d-c)/(b-c);
    return {(a.mult(ob) - b.mult(oa)).mult(1/(ob-oa))};
} // 1,0,-1(inf) : inter

```

#### 2.2.4 Segment Intersection

```

bool onSegment(P s, P e, P p) {return segDist(s, e, p) < eps;}

```

```

template<class P> vector<P> segInter(P a, P b, P c, P d){
    double oa = (d-c)/(a-c), ob = (d-c)/(b-c),
           oc = (b-a)/(c-a), od = (b-a)/(d-a);
    if(sgn(oa)*sgn(ob) < 0 && sgn(oc)*sgn(od) < 0)
        return {(a.mult(ob) - b.mult(oa)).mult(1/(ob-oa))};
    set<P> S;
    if(onSegment(c, d, a)) S.insert(a);
    if(onSegment(c, d, b)) S.insert(b);
    if(onSegment(a, b, c)) S.insert(c);
    if(onSegment(a, b, d)) S.insert(d);
    return vector<P>(S.begin(), S.end());
}

```

#### 2.2.5 Circle-Line Intersection

```

vector<P> circLine(P A, P B, P O, double r){
    vector<P> v;
    P X = O-A, D = B-A;
    double rat = 1.0 * (X*D) / (D*D);
    double det = (X*D)*(X*D) - (D*D)*(X*X - r*r);
    if(det < 0) return {};
    else if(det < eps) return {P(A + D.mult(rat))};
    det = sqrt(det);
    return {P(A + D.mult(rat + det/(D*D))),
           P(A + D.mult(rat - det/(D*D)))};
}

```

#### 2.2.6 Circle-Line Tangent

```

vector<P> circTangent(P A, P O, double r){
    if((O-A).dist2() < r*r + eps) return {};
    double th = asin(r/(O-A).dist());
    return {A + (O-A).rotate(th).mult(cos(th)),
           A + (O-A).rotate(-th).mult(cos(th))};
}

```

## 2.3 Convex Hull

```
vector<P> make_hull(vector<P>& v) {
    sort(v.begin(), v.end());
    int n = v.size(), sz = 0;
    vector<P> L, U;
    for(int i=0; i<n; i++) {
        while(sz >= 2 && (L[sz-1]-L[sz-2])/(v[i]-L[sz-1]) <= 0)
            L.pop_back(), sz--;
        L.push_back(v[i]); sz++;
    }
    sz = 0;
    for(int i=n-1; i>=0; i--) {
        while(sz >= 2 && (U[sz-1]-U[sz-2])/(v[i]-U[sz-1]) <= 0)
            U.pop_back(), sz--;
        U.push_back(v[i]); sz++;
    }
    L.pop_back(), U.pop_back();
    L.insert(L.end(), U.begin(), U.end());
    return L;
}
```

## 2.4 Sorting Points by Angle

```
// credit : http://koosaga.com/97
auto angle_sort = [&] (P &a, P &b){
    if((a < P(0, 0)) ^ (b < P(0, 0))) return b < a;
    if(a / b != 0) return a / b > 0;
    return a.dist2() < b.dist2(); // norm
}; // counter-clockwise sort
```

## 2.5 Rotating Calipers

```
ll rotating_calipers(vector<P> v) {
    v = make_hull(v);
    ll mdist = 0;
    int j = 1, n = v.size();
    v.insert(v.end(), v.begin(), v.end());
    for(int i=0; i<n; i++) {
        while((v[i+1]-v[i])/(v[j+1]-v[j]) > 0) j++;
        for(int k=0; k<2; k++)
            mdist = max(mdist, (v[j+k]-v[i]).dist2());
    }
    return mdist;
}
```

## 2.6 Smallest Enclosing Circle

```
//Prove By Solving - https://www.acmicpc.net/problem/11930
int main(){
    scanf("%d", &N);
```

```
for(int i = 1 ; i <= N ; i++) scanf("%lf%lf%lf", &A[i].x, &A[i].y, &A[i].z);

int t = 70000;
double rate = 1.0;
point cur = (point){0, 0, 0};
for(int i = 1 ; i <= t; i++){
    int ind = 1;
    for(int j = 1 ; j <= N ; j++)
        if( (A[j] - cur) * (A[j] - cur) >
            (A[ind] - cur) * (A[ind] - cur)) ind = j;
    cur = cur + (A[ind] - cur).mult(rate);
    rate *= 0.99;
}
double r = 0;
for(int i = 1 ; i <= N ; i++) r = max(r, (A[i] - cur) * (A[i] - cur));
cout << setprecision(10) << fixed << sqrt(r);
return 0;
} // Non-deterministic, deterministic O(n lg n) requires Voronoi diagram
```

## 2.7 Circumcircle

```
double cc_radius(P& A, P& B, P& C){
    return (B-A).dist() * (C-B).dist() * (A-C).dist() / fabs((A-B) / (B-C)) / 2;
}

P cc_center(P& A, P& B, P& C){
    P b = C-A, c = B-A;
    return A + (b.mult(c.dist2()) - c.mult(b.dist2())).perp().mult(0.5/(b/c));
}
```

## 2.8 Polygon Area

```
double ans = 0; // ans : double area
for(int i=0; i<points.size(); i++)
    ans += points[i] / points[(i+1 == points.size() ? 0 : i+1)];
```



### 3 Strings

#### 3.1 Aho-Corasick Algorithm

```
// required macro : rep, repi, setz
namespace aho_corasick {
    const int MAXN = 200002, MAXC = 26;
    int go[MAXN+1][MAXC];
    int fail[MAXN+1];
    bool term[MAXN+1];

    void build(const vector<string> &v) {
        setz(go), setz(fail), setz(term);
        int cnode = 1;

        repi(s, v) {
            int p = 0; // root is 0
            repi(j, s) {
                char c = j-'a'; // check starting alphabet
                if (!go[p][c]) go[p][c] = cnode++;
                p = go[p][c];
            }
            term[p] = true;
        }

        queue<int> q; rep(i, MAXC) if (go[0][i]) q.push(go[0][i]);
        while(!q.empty()) {
            int t = q.front(); q.pop();
            rep(i, MAXC) {
                if (go[t][i]) {
                    int p = fail[t];
                    while(p and not go[p][i]) p = fail[p];
                    p = go[p][i];
                    fail[go[t][i]] = p;
                    if (term[p]) term[go[t][i]] = true;
                    q.push(go[t][i]);
                }
            }
        }

        int step(int p, int c) {
            if(go[p][c]) return go[p][c];
            if(p) return go[p][c] = step(fail[p], c); // if not root
            return go[p][c] = -1; // -1 is same as 0, but is visited
        }

        bool query(string &t) {
            int p = 0;
            repi(i, t) {
                char c = i-'a'; // check starting alphabet
```

```
                p = max(0, step(p, c));
                /* if you need the original trie, use this or make length array
                while(p and not go[p][c]) p = fail[p];
                p = max(0, go[p][c]);
                */
                if (term[p]) return true;
            }
            return false;
        }
    }
}
```

#### 3.2 Suffix Array

```
// required macro : rep, repr, repp
// str : abracadabra
// SA : 10 7 0 3 5 8 1 4 6 9 2 (0-based)
// LCP : 1 4 1 1 0 3 0 0 2 (lcp[i] : lcp of sa[i], sa[i+1])
vector<int> make_sa(const string& s) {
    int n = s.length();
    int lim = max(128, n+1);
    vector<int> sa(n), g(n+1), ng(n+1), cnt(lim), ind(lim+1);
    rep(i, n) sa[i] = i, g[i] = s[i];
    g[n] = 0;
    for(int t=1; t<s.length(); t<=1)
    {
        auto cmp = [&] (int a, int b) {
            return g[a] != g[b] ? g[a] < g[b] : g[a+t] < g[b+t];
        };
        rep (i, n) cnt[g[min(i+t, n)]]++;
        repp(i, 1, lim) cnt[i] += cnt[i-1];
        repr(i, n, 0) ind[--cnt[g[min(i+t, n)]]] = i;
        rep (i, lim) cnt[i] = 0;
        rep (i, n) cnt[g[i]]++; // same as cnt[g[ind[i]]]++
        repp(i, 1, lim) cnt[i] += cnt[i-1];
        repr(i, n, 0) sa[--cnt[g[ind[i]]]] = ind[i];
        ng[sa[0]] = 1;
        repp(i, 1, n) ng[sa[i]] = ng[sa[i-1]] + cmp(sa[i-1], sa[i]);
        g = ng;

        fill(cnt.begin(), cnt.end(), 0);
        fill(ind.begin(), ind.end(), 0);
    }
    return sa;
}

vector<int> make_lcp(const string& s, const vector<int>& sa) {
    int n = s.length(), len = 0;
    vector<int> lcp(n-1), rank(n);
    rep(i, n) rank[sa[i]] = i;
    rep(i, n) {
        if(rank[i]) {
            int j = sa[rank[i]-1];
```

```

        int lc = n - max(i,j);
        while(len < lc && s[i+len] == s[j+len]) len++;
        lcp[rank[i]-1] = len;
    }
    if(len) len--;
}
return lcp;
}

```

### 3.3 Lexicographically Smallest String Rotation

```

int min_rotation(string s) {
    int a=0, N=s.size(); s += s;
    rep(b,N) rep(i,N) {
        if (a+i == b || s[a+i] < s[b+i]) {b += max(0, i-1); break;}
        if (s[a+i] > s[b+i]) { a = b; break; }
    }
    return a; // rotate(v.begin(), v.begin()+min_rotation(v), v.end());
}

```

### 3.4 Manacher's Algorithm

```

// 0-based
// s  = # h # e # l # l # o #
// ret = 0 1 0 1 0 1 2 1 0 1 0

vector<int> manacher(const string& s) {
    int n = s.size(), r = -1, k = -1;
    vector<int> p(n);
    for (int i=0; i<n; i++) {
        if (i<=r) p[i] = min(r-i, p[2*k-i]);
        while (i-p[i]-1>=0 and i+p[i]+1<n and s[i-p[i]-1] == s[i+p[i]+1]) p[i]++;
        if (r < i+p[i]) r = i+p[i], k = i;
    }
    return p;
}

```

### 3.5 Z Algorithm

```

// 0-based
// s  = a b c a b a b c a
// ret = 9 0 0 2 0 4 0 0 1

vector<int> z_algo(const string &s) {
    int l = 0, r = 0, N = sz(s);
    vector<int> Z(N);
    Z[0] = N;
    repp(i, 1, N) {
        if (i > r) {
            l = r = i;
            while(r < N and s[r] == s[r-l]) r++;

```

```

            r--;
            Z[i] = r-l+1;
        } else {
            int k = i-l;
            if (Z[k] < r-i+1) Z[i] = Z[k];
            else {
                l = i;
                while(r < N and s[r] == s[r-l]) r++;
                r--;
                Z[i] = r-l+1;
            }
        }
    }
    return Z;
}

```

## 4 Graph Theory

### 4.1 Biconnected Component

```

// https://gist.github.com/koosaga/6f6fd50dd7067901f1b1
void dfs(int x, int p){
    dfn[x] = low[x] = ++piv;
    par[x] = p;
    for(int i=0; i<graph[x].size(); i++){
        int w = graph[x][i];
        if(w == p) continue;
        if(!dfn[w]){
            dfs(w, x);
            low[x] = min(low[x], low[w]);
        }
        else low[x] = min(low[x], dfn[w]);
    }
}

void color(int x, int c){
    if(c > 0) bcc[x].push_back(c); // c == 0 : first component
    vis[x] = 1;
    for(int i=0; i<graph[x].size(); i++){
        int w = graph[x][i];
        if(vis[w]) continue;
        if(dfn[x] <= low[w]){
            bcc[x].push_back(++cpiv);
            color(w, cpiv);
        }
        else color(w, c);
    }
}

```

## 4.2 Strongly Connected Component

```
const int MAXN = 2e5 + 10; // > 2*N
int N, M;
int dfsn[MAXN], low[MAXN], finished[MAXN], cnt;
vector<int> ADJ[MAXN];
vector<vector<int>> G;
stack<int> S;
int f(int x){ // f(1) f(-1) f(2) f(-2) f(3) f(-3) ... -> 0 1 2 3 4 5 ...
    return 2 * (abs(x) - 1) + (x < 0);
}

void add_edge(int x, int y){ // call by f(x), f(y)
    ADJ[x ^ 1].push_back(y);
    ADJ[y ^ 1].push_back(x);
}

// memset(finished, -1, sizeof(finished));
int scc(int here){
    static vector<int> tmp;
    S.push(here);
    dfsn[here] = low[here] = ++cnt;
    int &ret = low[here];
    for(int there : ADJ[here]){
        if(dfsn[there] == 0) ret = min(ret, scc(there));
        else if(finished[there] == -1) ret = min(ret, dfsn[there]);
    }

    if(dfsn[here] == low[here]){
        while(1){
            int x = S.top();    S.pop();
            finished[x] = G.size();
            tmp.push_back(x);
            if(x == here) break;
        }
        G.push_back(tmp);
        tmp.clear();
    }
    return ret;
}
```

### 4.2.1 2-SAT

scc를 실행시켜  $f(i)$ 와  $f(-i)$ 가 같은 component에 있다면, 모순.  $f(i)$ 와  $f(-i)$  중  $finished$  배열의 수가 작은 것이 참이다. (SCC numbering의 역순이 위상정렬이기때문에,  $F \rightarrow T$ 를 유지하기 위함)

## 4.3 Euler Tour

```
struct Edge{
    int to, cnt; // to: 인접한 정점, cnt: 남은 사용 횟수
    Edge *dual; // dual: 역방향 간선을 가리키는 포인터
};
```

```
Edge(): Edge(-1, 0){}
Edge(int to1, int cnt1): to(to1), cnt(cnt1), dual(nullptr){}
};

void Eulerian(int curr){
    for(Edge *e: adj[curr]){
        if(e->cnt > 0){
            e->cnt--;
            e->dual->cnt--;
            Eulerian(e->to); // dfs
        }
    }
    cout << curr << '\n';
}
```

## 4.4 Heavy-Light Decomposition

```
int par[16][MAXN], head[MAXN], sz[MAXN], in[MAXN], out[MAXN], lv[MAXN];
vector<int> v[MAXN];
int dfs0(int x, int p) {
    lv[x] = lv[p] + 1; // lv[0] = -1;
    sz[x] = 1;
    for(int& y : v[x]) {
        if(y == p) continue;
        par[0][y] = x;
        sz[x] += dfs0(y, x);
        if(sz[v[x][0]] < sz[y]) swap(y, v[x][0]);
    }
    return sz[x];
}

void dfs1(int x, int p) {
    static int cnt = 0;
    in[x] = ++cnt;
    for(int y : v[x]) {
        if(y == p) continue;
        head[y] = y == v[x][0] ? head[x] : y;
        dfs1(y, x);
    }
    out[x] = cnt;
}

int get_query(segtree& seg, int x, int p) {
    int ret = 0;
    while(head[x] != head[p]) {
        // query(in[head[x]], in[x]);
        x = par[0][head[x]];
    }
    // query(in[p], in[x]);
    return ret;
}

// for(int i=1;i<=n;i++) if(!in[i]) head[i] = i, dfs0(i, 0), dfs1(i, 0);
```

## 4.5 Dominator Tree

```

namespace Dtree {
    const int MAXN = 250001;
    vector<int> E[MAXN], RE[MAXN], rdom[MAXN];

    int S[MAXN], RS[MAXN], cs;
    int par[MAXN], val[MAXN];
    int sdom[MAXN], rp[MAXN];
    int dom[MAXN];

    int Find(int x, int c = 0) {
        if (par[x] == x) return c?-1:x;
        int p = Find(par[x], 1);
        if (p == -1) return c?par[x]:val[x];
        if (sdom[val[x]] > sdom[val[par[x]]]) val[x] = val[par[x]];
        par[x] = p;
        return c?p:val[x];
    }

    void Union(int x, int y) {
        par[x] = y;
    }

    void dfs(int x) {
        RS[S[x] = ++cs] = x;
        par[cs] = sdom[cs] = val[cs] = cs;
        for(int e : E[x]) {
            if (S[e] == 0) dfs(e), rp[S[e]] = S[x];
            RE[S[e]].pb(S[x]);
        }
    }

    int Do(int s, int *up) {
        dfs(s);
        for (int i = cs; i-->0) {
            for (int e : RE[i]) sdom[i] = min(sdom[i], sdom[Find(e)]);
            if (i > 1) rdom[sdom[i]].pb(i);
            for (int e:rdom[i]) {
                int p = Find(e);
                if (sdom[p] == i) dom[e] = i;
                else dom[e] = p;
            }
            if (i > 1) Union(i, rp[i]);
        }
        for (int i = 2; i <= cs; i++) if (sdom[i] != dom[i]) dom[i] = dom[dom[i]];
        for (int i = 2; i <= cs; i++) {
            up[RS[i]] = RS[dom[i]];
        }
        return cs;
    }
}

```

```

    void addE(int x, int y) {E[x].pb(y);}
}

```

## 4.6 Global Min Cut

```

// Stoer-Wagner Algorithm, O(VE lg E)
int minimum_cut_phase(int n, int &s, int &t,
    vector<vector<int>> &adj, vector<int> vis){
    vector<int> dist(n);
    int mincut = 1e9;
    while(true){
        int pos = -1, cur = -1e9;
        for(int i=0; i<n; i++){
            if(!vis[i] && dist[i] > cur){
                cur = dist[i];
                pos = i;
            }
        }
        if(pos == -1) break;
        s = t;
        t = pos;
        mincut = cur;
        vis[pos] = 1;
        for(int i=0; i<n; i++){
            if(!vis[i]) dist[i] += adj[pos][i];
        }
    }
    return mincut; // optimal s-t cut here is, {t} and V \ {t}
}

int solve(int n, vector<vector<int>> adj){
    if(n <= 1) return 0;
    vector<int> vis(n);
    int ans = 1e9;
    for(int i=0; i<n-1; i++){
        int s, t;
        ans = min(ans, minimum_cut_phase(n, s, t, adj, vis));
        vis[t] = 1;
        for(int j=0; j<n; j++){
            if(!vis[j]){
                adj[s][j] += adj[t][j];
                adj[j][s] += adj[j][t];
            }
        }
        adj[s][s] = 0;
    }
    return ans;
}

```

## 5 Network Flow

### 5.1 Theorems

**Max-flow Min-cut theorem** : 정점  $s$ 에서 정점  $t$ 까지 흐를 수 있는 최대 유량(max-flow)은 정점  $s$ 와 정점  $t$ 를 분리하는 간선들의 가중치 합(min-cut)과 같다.

**Vertex cover** : 어떤 그래프의 정점의 집합  $S$ 에 대해 그래프의 모든 간선이  $S$ 의 원소 중 최소 하나와 연결되어 있을 때,  $S$ 를 해당 그래프의 vertex cover라고 하며, minimum vertex cover는 최소 개수의 정점을 사용한 vertex cover이다.

**Independent set** : 어떤 그래프의 정점의 집합  $S$ 에 대해  $S$ 의 서로 다른 두 정점을 연결하는 간선이 없을 때,  $S$ 를 해당 그래프의 independent set이라고 하며, maximum independent set은 최대 개수의 정점을 사용한 independent set이다.

**Matching (independent edge set)** : 어떤 그래프의 간선의 집합  $S$ 에 대해  $S$ 의 서로 다른 두 간선이 공통된 정점을 가지지 않을 때,  $S$ 를 해당 그래프의 matching이라고 하며, maximum matching은 최대 개수의 간선을 사용한 matching이다.

**König's theorem** : 이분 그래프의 maximum matching의 크기는 minimum vertex cover의 것과 같다.

**Dinic's Algorithm** : 시간 복잡도  $O(V^2E)$ , unit capacity에서는  $\min(V^{2/3}E, E^{3/2})$ .

**Circulation Problem** : 새로운 source/sink  $s_n, t_n$ 를 만들어서 다음과 같이 간선을 추가하고  $\max flow(s_n \rightarrow t_n) = \sum l_i$ 인지 확인, 이후  $s \rightarrow t$ 로 maxflow

- $s_n \rightarrow b(l), a \rightarrow t_n(l), a \rightarrow b(r-l), t \rightarrow s(\infty)$

### 5.2 Dinic's Algorithm

```
const int INF = 1e9;
struct Dinic{
    int N;
    struct edge{
        int index, cap, rev;
        edge() : index(0), cap(0), rev(0) {}
        edge(int index, int cap, int rev) : index(index), cap(cap), rev(rev) {}
    };

    vector<vector<edge>> ADJ;
    vector<int> R, W;

    Dinic() {}
    Dinic(int N) : N(N){
        ADJ.resize(N); R.resize(N); W.resize(N);
    }

    void CE(int node1, int node2, int cap){
        ADJ[node1].push_back(edge(node2, cap, ADJ[node2].size()));
        ADJ[node2].push_back(edge(node1, 0, ADJ[node1].size() - 1));
    }

    bool bfs(int src, int sink){
        fill(R.begin(), R.end(), -1);
        R[src] = 0;
        queue<int> Q; Q.push(src);
        while(Q.size()){
            int here = Q.front(); Q.pop();
```

```
                for(auto e : ADJ[here]){
                    if(e.cap > 0 && R[e.index] == -1)
                        R[e.index] = R[here] + 1, Q.push(e.index);
                }
            }
        }
        return R[sink] != -1;
    }

    int dfs(int here, int sink, int f){
        if(here == sink) return f;
        for(int &i = W[here] ; i < ADJ[here].size() ; i++){
            auto &e = ADJ[here][i];
            if(e.cap > 0 && R[here] < R[e.index]){
                int res = dfs(e.index, sink, min(f, e.cap));
                if(res) {
                    e.cap -= res;
                    ADJ[e.index][e.rev].cap += res;
                    return res;
                }
            }
        }
        return 0;
    }

    int solve(int src, int sink){
        int ret = 0;
        while(bfs(src, sink)){
            fill(W.begin(), W.end(), 0);
            int res;
            while((res = dfs(src, sink, INF))) ret += res;
        }
        return ret;
    }
};
```

### 5.3 MCMF with SPFA

```
const int INF = 1e9;
struct MCMF {
    struct edge {
        int there, cap, cost, rev;

        edge() : there(0), cap(0), cost(0), rev(0) {}
        edge(int there, int cap, int cost, int rev) : there(there), cap(cap),
            cost(cost), rev(rev) {}
    };

    int N;
    vector<vector<edge>> ADJ;
    vector<int> R, INQ, C, I;
```

```

MCMF() : N(0) {}
MCMF(int N) : N(N) { ADJ.resize(N + 1); R.resize(N + 1); INQ.resize(N + 1);
    C.resize(N + 1); I.resize(N + 1); }

void CE(int i, int j, int cap, int cost) {
    ADJ[i].push_back(edge(j, cap, cost, ADJ[j].size()));
    ADJ[j].push_back(edge(i, 0, -cost, ADJ[i].size() - 1));
}

bool SPFA(int src, int sink) {
    queue<int> Q;    Q.push(src);
    fill(R.begin(), R.end(), -1);    R[src] = 0;
    fill(C.begin(), C.end(), -1);    C[src] = 0;
    fill(INQ.begin(), INQ.end(), 0);    INQ[src] = 1;
    while (Q.size()) {
        int here = Q.front();    Q.pop();
        INQ[here] = 0;
        for (int i = 0; i < ADJ[here].size(); i++) {
            auto e = ADJ[here][i];
            if ((C[e.there] == -1 || C[e.there] > C[here] + e.cost)
                && e.cap > 0) {
                C[e.there] = C[here] + e.cost;
                R[e.there] = here;
                I[e.there] = i;
                if (!INQ[e.there]) INQ[e.there] = 1, Q.push(e.there);
            }
        }
    }
    if (C[sink] == -1) return false;
    return true;
}

pii mcmf(int src, int sink) {
    pii ret = { 0, 0 };
    while (SPFA(src, sink)) {
        int flow = INF, cost = 0;
        for (int here = sink; here != src; here = R[here])
            flow = min(flow, ADJ[R[here]][I[here]].cap);
        for (int here = sink; here != src; here = R[here]) {
            auto &e = ADJ[R[here]][I[here]];
            cost += e.cost * flow;
            e.cap -= flow;
            ADJ[e.there][e.rev].cap += flow;
        }
        ret.first += flow, ret.second += cost;
    }
    return ret;
}
};

```

## 5.4 Hungarian Method

```

namespace Hung {
    const int MX = 2000;
    // IMPORTANT : n <= m, 1-based
    using T = long double;

    T maxv = 1e200;
    T a[MX][MX], n, m;

    void init(int nn, int mm) { n = nn; m = mm; }
    void set_value(int x, int y, T val) { a[x][y] = val; }
    T solve(vector<int> &ans) {
        vector<T> v(m+1), u(n+1);
        vector<int> p(m+1), way(m+1);
        for (int i=1; i<=n; ++i) {
            p[0] = i;
            int j0 = 0;
            vector<T> minv(m+1, maxv);
            vector<char> used(m+1, false);
            do {
                used[j0] = true;
                T delta = maxv;
                int i0 = p[j0], j1;
                for (int j=1; j<=m; ++j) if (!used[j]) {
                    T cur = a[i0][j] - u[i0] - v[j];
                    if (cur < minv[j]) minv[j] = cur, way[j] = j0;
                    if (minv[j] < delta) delta = minv[j], j1 = j;
                }
                for (int j=0; j<=m; ++j) {
                    if (used[j]) u[p[j]] += delta, v[j] -= delta;
                    else minv[j] -= delta;
                }
                j0 = j1;
            } while (p[j0] != 0);
            do {
                int j1 = way[j0];
                p[j0] = p[j1];
                j0 = j1;
            } while (j0);
        }
        ans.resize(n + 1);
        for (int j=1; j<=m; ++j) {
            ans[p[j]] = j;
        }
        return -v[0];
    }
}

```

## 5.5 Hopcroft-Karp Algorithm

```

struct hopcroft_karp{
    int N;
    vector<vector<int>> ADJ;
    vector<int> L, rev, used;

    hopcroft_karp() {}
    hopcroft_karp(int N) : N(N) {
        ADJ.resize(N);
        L.resize(N), rev.resize(N, -1), used.resize(N, 0);
    }

    void CE(int here, int there){
        ADJ[here].push_back(there);
    }

    void bfs(){
        queue<int> Q;
        for(int i = 0 ; i < N ; i++) {
            if(used[i]) L[i] = -1;
            else L[i] = 0, Q.push(i);
        }

        while(Q.size()){
            int here = Q.front(); Q.pop();
            for(int there : ADJ[here]){
                if(rev[there] != -1 && L[rev[there]] == -1) {
                    L[rev[there]] = L[here] + 1;
                    Q.push(rev[there]);
                }
            }
        }
    }

    bool dfs(int here){
        for(int there : ADJ[here]){
            if(rev[there] == -1 || (L[here] < L[rev[there]] && dfs(rev[there]))){
                rev[there] = here;
                used[here] = 1;
                return true;
            }
        }
        return false;
    }

    int solve(){
        int ret = 0;
        while(1){
            bfs();
            int res = 0;

```

```

                for(int i = 0 ; i < N ; i++) {
                    if(used[i]) continue;
                    res += dfs(i);
                }
                if(res == 0) break;
                ret += res;
            }
        }
        return ret;
    }
};

```

## 6 Optimization Tricks

### 6.1 Knuth Optimization

- Recurrence :  $D[i][j] = \min_{i < k < j} (D[i][k] + D[k][j]) + C[i][j]$
- Quadrangle Inequality :  $C[a][c] + C[b][d] \leq C[a][d] + C[b][c]$ ,  $a \leq b \leq c \leq d$
- Monotonicity :  $C[b][c] \leq C[a][d]$ ,  $a \leq b \leq c \leq d$
- $A[i][j] = (\min. k \text{ s.t. } D[i][j] \text{ is min.})$ . Then  $A[i][j-1] \leq A[i][j] \leq A[i+1][j]$
- $O(N^2)$  time complexity

```

// opt[i-1][i] = i
for(int d=2;d<=n;d++) {
    for(int i=1;i+d<=n+1;i++) {
        for(int k=opt[i][j-1], j=i+d; k<=opt[i+1][j]; k++) {
            int v = dp[i][k] + dp[k][j] + c[i][j];
            if(dp[i][j] > v) dp[i][j] = v, opt[i][j] = k;
        }
    }
}

```

### 6.2 Divide and Conquer Optimization

- Recurrence :  $D[t][i] = \min_{k < i} (D[t-1][k] + C[k][i])$
- Min index :  $A[t][i] \leq A[t][i+1]$  ( $A[t][i] = (\min. k \text{ s.t. } D[t][i] \text{ is min.})$ )
- Quadrangle Inequality :  $C[a][c] + C[b][d] \leq C[a][d] + C[b][c]$ ,  $a \leq b \leq c \leq d$
- Able to Divide and Conquer base on calculating  $D[t][i]$
- $O(TN \lg N)$  time complexity

```

// range of index : [l,r]
// range of dp : [s,e]
void dnc(int t, int l, int r, int s, int e)
{
    if(s > e) return;
    int m = (s+e)/2;

```

```

D[t][m] = 2e9;
for(int k=1;k<m&&k<=r;k++)
{
    int tmp = D[t-1][k] + C[k][m];
    if(D[t][m] > tmp)
        D[t][m] = tmp, A[t][m] = k;
}
dnc(t, 1, A[t][m], s, D[t][m]-1);
dnc(t, A[t][m], r, D[t][m]+1, e);
}

```

### 6.3 Convex Hull Trick

- Recurrence :  $dp[i] = \min_{j < i} (dp[j] + a[i]b[j])$ ,  $b[i-1] \leq b[i]$
- Think as  $dp[x] = a[i] = \min_{j < i} (b[j] \cdot x + dp[j])$

```

using ll = long long;
struct line {
    ll a, b, i;
    line(ll a=0, ll b=0, ll i=0) : a(a), b(b), i(i) {}
    ll calc(ll x) { return a*x+b; }
    double inter(line l) {
        return double(l.b - b) / (a - l.a);
    }
};
bool check_back(line& p0, line& p1, line& p2) {
    return (p1.b - p0.b) * (p1.a - p2.a) >= (p0.a - p1.a) * (p2.b - p1.b);
    return p0.inter(p1) > p1.inter(p2); // double
}
bool check_front(ll x, line& p0, line& p1) {
    return x * (p0.a - p1.a) >= (p1.b - p0.b);
    return x > p0.inter(p1);
}
struct ConvexHull {
    int l = 0;
    int r = 0;
    vector<line> v;
    void insert(line p) {
        while(r - l >= 2 && check_back(v[r-2], v[r-1], p))
            v.pop_back(), r--;
        v.push_back(p);
    }
    pair<ll, ll> query(ll x) { // if x is increasing, else do binary search
        while(r - l >= 2 && check_front(x, v[l], v[l+1]))
            l++;
        return pair<ll, ll>{v[l].calc(x), v[l].i};
    }
};
void calc() { // psuedo-code
    ConvexHull ch;

```

```

ll val = 0, cnt = 0; // current dp and track
for(int i=0;i<N;i++) {
    ch.insert(line{p[i], q[i]}); // j-dependent values (b[j], dp[j])
    pll res = ch.query(x[i]);
    val = res.first + c[i]; // i-dependent values
    cnt = res.second + 1;
}
return pll{val, cnt};
}

```

### 6.4 Centroid Decomposition

```

// credit : https://gist.github.com/igorcarpanese/75162f3253bd230abd0f32f9950bf384
int dfs(int u, int p) {
    sub[u] = 1;
    for (auto v : tree[u])
        if (v != p and !chk[v]) sub[u] += dfs(v, u);
    return sub[u] + 1;
} // calc subtree size, chk means that node was a centroid

// each tree has at most two centroids
int centroid(int u, int p, int r) { // r : root
    for (auto v : tree[u])
        if (v != p and !chk[v] and sub[v] > sub[r]/2) return centroid(v, u, r);
    return u;
}

```

### 6.5 Aliens Trick

- Recurrence:  $dp[i][j] = \min_{k < j} (dp[i-1][k] + C[k+1][j])$
- Condition:  $dp[*][n]$  is convex (implied if  $dp[*][n]$  is Monge array)

```

ll calc(...) {
    // (...)
    k = min(k, (int)v.size());
    ll leff = some_min_value, reff = some_big_value; // check range and overflow
    int lind = v.size(), rind = 1; // range of k, decreases when eff increase
    while(reff - leff >= 2) {
        ll meff = (leff + reff) / 2;
        pll res = calc_with_lambda(v, meff); // {value, k'}
        if(res.second < rind) res.second = rind; // rind (<) lind
        if(res.second > lind) res.second = lind; // lind (>) rind
        if(res.second == k) return res.first - k * meff;
        else if(res.second > k) lind = res.second; leff = meff; // lind (>) rind
        else rind = res.second; reff = meff;
    }
    // when minimizing, ans is max(calc_with_lambda().first - k * eff) for all eff
    // when maximizing, calculate min instead
    return max(calc_with_lambda(v, leff).first - k * leff,
               calc_with_lambda(v, reff).first - k * reff);
}

```



## 7 Data Structure

### 7.1 Persistent Segment Tree

```
const MAXN = 1e5 + 10;
struct node{
    node *l, *r;
    int cnt;
    node () {}
} pool[(1 << 17) * 17], *tree_head[MAXN];

int tcnt;
node* alloc(){
    memset(pool + tcnt, 0, sizeof(node));
    return pool + tcnt++;
}

node * init(int l, int r){
    node *ret = alloc();
    if(l != r) {
        int mid = (l + r) / 2;
        ret->l = init(l, mid);
        ret->r = init(mid + 1, r);
    }
    return ret;
}

void update(node * here, node *par, int l, int r, int val){
    if(l == r) {
        here->cnt = par->cnt + 1;
        return;
    }

    int mid = (l + r) / 2;
    if(val <= mid){
        here->l = alloc();
        here->r = par->r;
        update(here->l, par->l, l, mid, val);
    }
    else {
        here->l = par->l;
        here->r = alloc();
        update(here->r, par->r, mid + 1, r, val);
    }
    here->cnt = here->l->cnt + here->r->cnt;
}

int query(node *node1, node *node2, int l, int r, int k){
    if(l == r) return l;
    int ccc = node1->l->cnt - node2->l->cnt;
    int mid = (l + r) / 2;
```

```
    if(k <= ccc) return query(node1->l, node2->l, l, mid, k);
    else return query(node1->r, node2->r, mid + 1, r, k - ccc);
}
```

### 7.2 Link-Cut Tree

```
struct node{
    node *pp, *p, *l, *r;
    int val;
    node(){ p = 0, l = 0, r = 0;}
    node(int val) : val(val) { p = 0, l = 0, r = 0;}
};

void push(node *x){}
void pull(node *x){}

void rotate(node *x){
    if(!x->p) return;
    push(x->p); // if there's lazy stuff
    push(x);
    node *p = x->p;
    bool is_left = (p->l == x);
    node *b = (is_left ? x->r : x->l);
    x->p = p->p;
    if(x->p && x->p->l == p) x->p->l = x;
    if(x->p && x->p->r == p) x->p->r = x;
    if(is_left){
        if(b) b->p = p;
        p->l = b;
        p->p = x;
        x->r = p;
    }
    else{
        if(b) b->p = p;
        p->r = b;
        p->p = x;
        x->l = p;
    }
    pull(p); // if there's something to pull up
    pull(x);
    //if(!x->p) root = x; // IF YOU ARE SPLAY TREE
    if(p->pp){ // IF YOU ARE LINK CUT TREE
        x->pp = p->pp;
        p->pp = nullptr;
    }
}

void splay(node *x){
    while(x->p){
        node *p = x->p;
        node *g = p->p;
        if(g){
```

```

        if((p->l == x) ^ (g->l == p)) rotate(x);
        else rotate(p);
    }
    rotate(x);
}
}
void access(node *x){
    splay(x);
    push(x);
    if(x->r){
        x->r->pp = x;
        x->r->p = nullptr;
        x->r = nullptr;
    }
    pull(x);
    while(x->pp){
        node *nxt = x->pp;
        splay(nxt);
        push(nxt);
        if(nxt->r){
            nxt->r->pp = nxt;
            nxt->r->p = nullptr;
            nxt->r = nullptr;
        }
        nxt->r = x;
        x->p = nxt;
        x->pp = nullptr;
        pull(nxt);
        splay(x);
    }
}
node *root(node *x){
    access(x);
    while(x->l){
        push(x);
        x = x->l;
    }
    access(x);
    return x;
}
node *par(node *x){
    access(x);
    if(!x->l) return nullptr;
    push(x);
    x = x->l;
    while(x->r){
        push(x);
        x = x->r;
    }
    access(x);
}

```

```

        return x;
    }
    node *lca(node *s, node *t){
        access(s);
        access(t);
        splay(s);
        if(s->pp == nullptr) return s;
        return s->pp;
    }
    void link(node *par, node *son){
        access(par);
        access(son);
        //son->rev ^= 1; // remove if needed
        push(son);
        son->l = par;
        par->p = son;
        pull(son);
    }
    void cut(node *p){
        access(p);
        push(p);
        if(p->l){
            p->l->p = nullptr;
            p->l = nullptr;
        }
        pull(p);
    }
}

```

### 7.3 Dynamic Convex Hull

```

// https://github.com/niklasb/contest-algos/blob/master/convex_hull/dynamic.cpp
const ll is_query = -(1LL<<62);
struct Line {
    ll m, b;
    mutable function<const Line*> succ;
    bool operator<(const Line& rhs) const {
        if (rhs.b != is_query) return m < rhs.m;
        const Line* s = succ();
        if (!s) return 0;
        return b - s->b < (s->m - m) * rhs.m;
    }
};
struct HullDynamic : public multiset<Line> { // will maintain upper hull for maximum
    bool bad(iterator y) {
        auto z = next(y);
        if (y == begin()) {
            if (z == end()) return 0;
            return y->m == z->m && y->b <= z->b;
        }
        auto x = prev(y);
        if (z == end()) return y->m == x->m && y->b <= x->b;
    }
}

```

```

    return (x->b - y->b)*(z->m - y->m) >= (y->b - z->b)*(y->m - x->m);
}
void insert_line(Line l) {
    auto y = insert(l);
    y->succ = [=] { return next(y) == end() ? 0 : &*next(y); };
    if (bad(y)) { erase(y); return; }
    while (next(y) != end() && bad(next(y))) erase(next(y));
    while (y != begin() && bad(prev(y))) erase(prev(y));
}
ll eval(ll x) {
    auto l = *lower_bound((Line) { x, is_query });
    return l.m * x + l.b;
}
};

```

## 7.4 Stern-Brocot Tree

```

// __int128 is recommended
bool test(ll a, ll b) { // for testing directions, vary by prob
    // return true if (true value) >= a/b
    ll n = 0, m = 1;

    rep(i, N) {
        if (n < m*A[i].fi) n = A[i].fi, m = 1;

        ll c = b*n+m*a, d = m*b;
        ll g = gcd(c, d);
        n = c/g;
        m = d/g;

        if (n > m*A[i].se) return false;
    }
    return true;
}

pair<ll, ll> stern_brocot(ll M, ll N) {
    // M : max value
    // N : max divisor
    // if result is a/b, return as {a, b}
    ll a = 0, b = 1; // l
    ll c = 1, d = 0; // r
    int l, r;
    bool chg = true;

    while(chg) {
        chg = false;

        // to left
        l = 0, r = (N-d-1)/b+1;
        while(l < r) {
            int mid = (l+r+1)/2;

```

```

            if (test(a*mid+c, b*mid+d)) r = mid-1;
            else l = mid;
        }

        c += a*1;
        d += b*1;
        chg |= (l > 0);

        // to right
        l = 0, r = (d?(N-b-1)/d+1:M);
        while(l < r) {
            int mid = (l+r+1)/2;
            if (test(a+mid*c, b+mid*d)) l = mid;
            else r = mid-1;
        }

        a += c*1;
        b += d*1;
        chg |= (l > 0);
    }

    return {a, b};
}

```

## 7.5 Rope

```

#include <bits/stdc++.h>
#include <ext/rope>
using namespace std;
using namespace __gnu_cxx;

int main()
{
    ios::sync_with_stdio(false);
    cin.tie(0);

    rope rp; // rope<char>
    string s("Lorem-ipsum");
    int n = s.length();
    rp.append(s.c_str()); // add element

    int x = 3, y = 8; // split and merge below
    rp = rp.substr(x, y-x) + rp.substr(0, x) + rp.substr(y, n);
    cout << rp.at(0) << '\n'; // get element, 'e'
    cout << rp << '\n'; // print, "em-ip|Lor|sum"
}

```

## 7.6 Bitset

```

#include <bitset>
#include <iostream>

```

```
using namespace std;

int main() {
    bitset<8> b1(13);           // 00001101
    bitset<8> b2("10111");     // 00010111

    cout << b1.count() << endl; // 3
    cout << b1.test(6) << endl; // 0, since 2^6-th bit is 0
    b1.set(6);                  // set to 1, 1-fill if no param
    b2.reset(2);                 // set to 0, 0-fill if no param
    // use 'flip' for flipping

    cout << "b1:" << b1 << endl; // b1:01001101
    cout << "b2:" << b2 << endl; // b2:00010011
    // use any, none, all (c++11) for bit checking
    // supported operators : &, |, ^, <<, >>, ~, ==, !=
    // these operators must match size (given to template)

    cout << "&: " << (b1 & b2) << endl; // &: 00000001
    cout << "^: " << (b1 ^ b2) << endl; // ^: 01011110
    cout << "|: " << (b1 | b2) << endl; // |: 01011111
    cout << "~: " << (~b1) << endl;    // ~: 10110010
    cout << "<<:" << (b1 << 3) << endl; // <<: 01101000
    cout << b2.to_ulong() << endl;    // 19, c++11 supports ullong
}

```

## 7.7 Policy Based Data Structure

```
#include <bits/stdc++.h>
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>

using namespace std;
using namespace __gnu_pbds;

typedef tree<
    int,
    null_type,
    less<int>,
    rb_tree_tag,
    tree_order_statistics_node_update >
    ordered_set;

// less<int> : not allow for duplicate
// less_equal<int> : allow for duplicate
// use upper_bound when you erase from set used less_equal

int N;

int main(void) {

```

```
    iosstream::sync_with_stdio(false);
    cin.tie(nullptr);

    ordered_set X;

    X.insert(1);
    X.insert(2);
    X.insert(4);
    X.insert(8);
    X.insert(16);

    cout<<*X.find_by_order(1)<<endl; // 2
    cout<<*X.find_by_order(2)<<endl; // 4
    cout<<*X.find_by_order(4)<<endl; // 16
    cout<<(end(X)==X.find_by_order(6))<<endl; // true

    cout<<X.order_of_key(-5)<<endl; // 0
    cout<<X.order_of_key(1)<<endl; // 0
    cout<<X.order_of_key(3)<<endl; // 2
    cout<<X.order_of_key(4)<<endl; // 2
    cout<<X.order_of_key(400)<<endl; // 5
}

```

## 8 Miscellaneous

### 8.1 Misc Formulae and Algorithms

#### 8.1.1 Faulhaber's Formula

$$T(n, k) = \sum_{i=1}^n i^k = \frac{(n+1)^{k+1} - 1^{k+1} - \sum_{j=0}^{k-1} \binom{k+1}{j} T(n, j)}{\binom{k+1}{k}}$$

Also use

$$(x+1)^d - x^d = 1 + \binom{d}{1}x + \binom{d}{2}x^2 + \cdots + \binom{d}{d-1}x^{d-1}$$

to get each coef.

#### 8.1.2 Maximum Clique

```
typedef long long ll;
ll G[40]; // 0-index
int N, M;
int cur;
void get_clique(int R = 0, ll P = (1ll<<N)-1, ll X = 0){
    if((P|X) == 0){
        cur = max(cur, R);
        return;
    }
    int u = __builtin_ctzll(P|X);
    ll c = P&~G[u];

```

```

while(c){
    int v = __builtin_ctzll(c);
    get_clique(R + 1, P&G[v], X&G[v]);
    P ^= 111 << v;
    X |= 111 << v;
    c ^= 111 << v;
}
}

```

### 8.1.3 De Bruijn Sequence

```

// https://github.com/koosaga/DeobureoMinkyuParty/blob/master/teamnote.tex
// alphabet = [0, k - 1], substr length n, res starts with 0 (cyclic)
int res[10000000], aux[10000000]; // >= k^n, k*n
int de_bruijn(int k, int n, int lim) { // returns size (k^n)
    if(k == 1) {
        res[0] = 0;
        return 1;
    }
    for(int i = 0; i < k * n; i++) aux[i] = 0;
    int sz = 0;
    function<void(int, int)> db = [&](int t, int p) {
        if(sz > lim) return;
        if(t > n) {
            if(n % p == 0)
                for(int i = 1; i <= p; i++)
                    res[sz++] = aux[i];
        }
        else {
            aux[t] = aux[t - p];
            db(t + 1, p);
            for(int i = aux[t - p] + 1; i < k; i++) {
                aux[t] = i;
                db(t + 1, t);
            }
        }
    };
    db(1, 1);
    return sz;
}

```

## 8.2 Highly Composite Numbers, Large Prime

| < 10 <sup>k</sup> | number | divisors | 2 3 5 7 11 13 17 19 23 29 31 37 |
|-------------------|--------|----------|---------------------------------|
| 1                 | 6      | 4        | 1 1                             |
| 2                 | 60     | 12       | 2 1 1                           |
| 3                 | 840    | 32       | 3 1 1 1                         |
| 4                 | 7560   | 64       | 3 3 1 1                         |
| 5                 | 83160  | 128      | 3 3 1 1 1                       |
| 6                 | 720720 | 240      | 4 2 1 1 1 1                     |

|    |                    |        |                             |
|----|--------------------|--------|-----------------------------|
| 7  | 8648640            | 448    | 6 3 1 1 1 1                 |
| 8  | 73513440           | 768    | 5 3 1 1 1 1 1               |
| 9  | 735134400          | 1344   | 6 3 2 1 1 1 1               |
| 10 | 6983776800         | 2304   | 5 3 2 1 1 1 1 1             |
| 11 | 97772875200        | 4032   | 6 3 2 2 1 1 1 1             |
| 12 | 963761198400       | 6720   | 6 4 2 1 1 1 1 1 1           |
| 13 | 9316358251200      | 10752  | 6 3 2 1 1 1 1 1 1 1         |
| 14 | 97821761637600     | 17280  | 5 4 2 2 1 1 1 1 1 1 1       |
| 15 | 866421317361600    | 26880  | 6 4 2 1 1 1 1 1 1 1 1       |
| 16 | 8086598962041600   | 41472  | 8 3 2 2 1 1 1 1 1 1 1 1     |
| 17 | 74801040398884800  | 64512  | 6 3 2 2 1 1 1 1 1 1 1 1 1   |
| 18 | 897612484786617600 | 103680 | 8 4 2 2 1 1 1 1 1 1 1 1 1 1 |

|   | < 10 <sup>k</sup> prime | > 10 <sup>k</sup> prime | # of prime |
|---|-------------------------|-------------------------|------------|
| 1 | 7                       | 11                      | 4          |
| 2 | 97                      | 101                     | 25         |
| 3 | 997                     | 1009                    | 168        |
| 4 | 9973                    | 10007                   | 1229       |
| 5 | 99991                   | 100003                  | 9592       |
| 6 | 999983                  | 1000003                 | 78498      |
| 7 | 9999991                 | 10000019                | 664579     |
| 8 | 99999989                | 100000007               | 5761455    |
| 9 | 999999937               | 1000000007              | 50847534   |

|    | < 10 <sup>k</sup> prime | > 10 <sup>k</sup> prime |
|----|-------------------------|-------------------------|
| 10 | 9999999967              | 10000000019             |
| 11 | 99999999977             | 100000000003            |
| 12 | 999999999989            | 1000000000039           |
| 13 | 9999999999971           | 10000000000037          |
| 14 | 9999999999973           | 100000000000031         |
| 15 | 99999999999989          | 1000000000000037        |
| 16 | 999999999999937         | 10000000000000061       |
| 17 | 999999999999997         | 10000000000000003       |
| 18 | 9999999999999989        | 100000000000000003      |

NTT Prime:

$469762049 = 7 \times 2^{26} + 1$ . Primitive root : 3.

$998244353 = 119 \times 2^{23} + 1$ . Primitive root: 3.

$985661441 = 235 \times 2^{22} + 1$ . Primitive root: 3.

$1012924417 = 483 \times 2^{21} + 1$ . Primitive root: 5.

Primes near  $10^9$ :  $10^9 + [7, 9, 21, 33, 87]$

## 8.3 Fast Integer IO

```

// credit : https://github.com/koosaga/DeobureoMinkyuParty/blob/master/teamnote.tex
static char buf[1 << 19]; // size : any number geq than 1024
static int idx = 0;
static int bytes = 0;
static inline int _read() {

```

```

    if (!bytes || idx == bytes) {
        bytes = (int)fread(buf, sizeof(buf[0]), sizeof(buf), stdin);
        idx = 0;
    }
    return buf[idx++];
}

static inline int _readInt() {
    int x = 0, s = 1;
    int c = _read();
    while (c <= 32) c = _read();
    if (c == '-') s = -1, c = _read();
    while (c > 32) x = 10 * x + (c - '0'), c = _read();
    if (s < 0) x = -x;
    return x;
}

```

## 8.4 C++ Tips / Environments

```

#include <bits/stdc++.h> // magic header
using namespace std;    // magic namespace

struct StupidGCCcantEvenCompileThisSimpleCode{
    pair<int, int> array[1000000];
}; // https://gcc.gnu.org/bugzilla/show_bug.cgi?id=68203

// how to use rand (in 2017)
mt19937 rng(0xdeadbeef);
mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
int randint(int lb, int ub){ return uniform_int_distribution<int>(lb, ub)(rng); }
shuffle(permutation.begin(), permutation.end(), rng);
mt19937_64 _R(chrono::steady_clock::now().time_since_epoch().count()); // _R()

// comparator overload
auto cmp = [](seg a, seg b){return a.func() < b.func(); };
set<seg, decltype(cmp)> s(cmp);
map<seg, int, decltype(cmp)> mp(cmp);
priority_queue<seg, vector<seg>, decltype(cmp)> pq(cmp); // max heap

// hash func overload
struct point{
    int x, y;
    bool operator==(const point &p)const{ return x == p.x && y == p.y; }
};
struct hasher {
    size_t operator()(const point &p)const{ return p.x * 2 + p.y * 3; }
};
unordered_map<point, int, hasher> hsh;

// c++ setprecision example
#include <iostream>    // std::cout, std::fixed
#include <iomanip>      // std::setprecision

```

```

int main () {
    double f = 3.14159;
    std::cout << std::setprecision(5) << f << '\n'; // 3.1416
    std::cout << std::setprecision(9) << f << '\n'; // 3.14159
    std::cout << std::fixed;
    std::cout << std::setprecision(5) << f << '\n'; // 3.14159
    std::cout << std::setprecision(9) << f << '\n'; // 3.141590000
}

```