Team Note of `Powered by Zigui`

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Contents

ALL BELOW HERE ARE USELESS IF YOU READ THE STATEMENT WRONG

0 Quotes and Prerequisites

```
evenharder : Mental Abuse To Humans
djkim0613 : 열심히 응원하겠습니다.
SoulTch : How much is this bus ticket?
* This template is brought from that of 'Deobureo Minkyu Party'
```

Run script

```
#!/bin/bash
g++ -fsanitize=undefined -std=c++14 -O2 -o /tmp/pow $1.cpp
time /tmp/pow < $1.in
# export PATH=~:$PATH
```

Debug Code

```
#define fi first
#define se second
#define pb push_back
#define rep(i, e) for (int i = 0, _##i = (e); i < _##i; i++)
#define repp(i, s, e) for (int i = (s), _##i = (e); i < _##i; i++)
#define repr(i, s, e) for (int i = (s)-1, _##i = (e); i >= _##i; i--)
// using namespace std;
using ll = long long;
using pii = pair<int, int>;
using pll = pair<ll, ll>;
template<typename T>
ostream &operator<<(ostream &os, const vector<T>& v) {
    cout << "[";
    for (auto p : v) cout << p << ",";
    cout << "]";
    return os;
}
#ifndef __SOULTCH
#define debug(...) 0
#define endl '\n'
#else
#define debug(...) cout << " [-] ", _dbg(#__VA_ARGS__, __VA_ARGS__)
template<class TH> void _dbg(const char *sdbg, TH h){ cout << sdbg << '=' << h <<
endl; }
template<class TH, class... TA> void _dbg(const char *sdbg, TH h, TA... a) {
    while(*sdbg != ',') cout << *sdbg++;
    cout << '=' << (h) << ',';
    _dbg(sdbg+1, a...);
}
#endif
```

Reminders

Should be **added**.

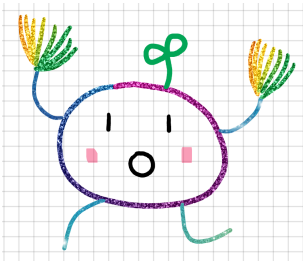

Figure 1: 풀다가 막힐 때는 이 그림을 봅시다. 아자아자 화이팅!

1 Math

1.1 Basic Mathematics

1.1.1 Trigonometry

- $\sin(\alpha \pm \beta) = \sin\alpha\cos\beta \pm \cos\alpha\sin\beta$
- $\cos(\alpha \pm \beta) = \cos\alpha\cos\beta \mp \sin\alpha\sin\beta$
- $\tan(\alpha \pm \beta) = \frac{\tan\alpha \pm \tan\beta}{1 \mp \tan\alpha\tan\beta}$
- $\sin 2\theta = 2\sin\theta\cos\theta$
- $c^2 = a^2 + b^2 - 2ab\cos\gamma$

1.1.2 Generating Function

- $\sum_n (pn+q)x^n = \frac{p}{1-x} + \frac{q}{(1-x)^2}$ (Arithmetic progression)
- $\sum_n (rx)^n = (1-rx)^{-1}$ (Geometric progression)
- $\sum_n \binom{m}{n} x^n = (1+x)^m$ (Binomial coefficient)
- $\sum_n \binom{m+n-1}{n} x^n = (1-x)^{-m}$ (Multiset coefficient)

1.1.3 Calculus

Should be **added**.

1.1.4 Gaussian Elimination

Should be **added**....?

1.2 Number Theory

1.2.1 Lattice Points under Line

```
// 0 <= x < n, 0 < y <= (a/c)x+(b/c)
ll calc(ll a,ll b,ll c,ll n){
    if(!n)return 0;
    ll tmp=a/c*n*(n-1)/2;
    tmp+=b/c*n;
    return tmp+calc(c,(a*n+b)%c,a%c,((a%c)*n+b%c)/c);
}
```

1.2.2 Shanks' Baby-step Giant-step

Should be **revised**.

```
ll mexp(ll x, ll y, ll p) {
    if(!y) return 1;
    if(y & 1) return x * mexp(x*x%p, y>>1, p) % p;
    return mexp(x*x%p, y>>1, p);
}
vector<ll> get_factor(ll n) {
    vector<ll> v;
    for(ll i=2;i*i<=n;i++) {
        if(n % i == 0) {
            v.push_back(i);
            while(n % i == 0) n /= i;
        }
    }
    if(n > 1) v.push_back(n);
    return v;
}
ll get_primitive(ll n) {
    ll phi = n-1; // assume n is prime
    vector<ll> fact = get_factor(phi);
    for(ll x=2;x<=n;x++) {
        int yes = 1;
        for(ll y : fact) {
            yes &= (mexp(x, phi / y, n) != 1);
        }
        if(yes) return x;
    }
    return -1;
}
// find x s.t. x^k mod n = a -> (g^k)^y mod n = a, where x = g^y
ll bsgs(ll k, ll a, ll n) {
    ll g = get_primitive(n);
    ll phi = n-1; // assume n is prime
    if(g == -1) return -1;
    ll m = ceil(sqrt(n) + 1e-9);
    vector<pl> prec(m);
    for(ll j=0;j<m;j++) {
        prec[j] = {mexp(g, j * k % phi, n), j};
    }
    sort(prec.begin(), prec.end());
    ll cur = a, ncur = mexp(g, (phi - m) * k % phi, n);
    for(ll i=0;i<m;i++) {
        auto it = lower_bound(prec.begin(), prec.end(), pl(cur, 0));
        if(it->first == cur) {
            ll ans = mexp(g, (i*m + it->second) % phi, n);
            assert(mexp(ans, k, n) == a);
            return ans;
        }
        cur = cur * ncur % n;
    }
    return 0;
}
```

1.2.3 Extended Euclidean Algorithm

```
// ax + by = gcd(a,b) => x ? y ?
typedef long long int ll
pair<ll,ll> ext_gcd(ll a,ll b) {
    if(b) {
        auto tmp = ext_gcd(b, a%b);
        return {tmp.second, tmp.first - (a/b) * tmp.second};
    }
    else return {1, 0};
}

// ax = 1 mod M, x?
ll mod_inv(ll a, ll M) {
    return (ext_gcd(a, M).first + M) % M;
}
```

1.2.4 Chinese Remainder Theorem

```
typedef long long int ll;
ll CRT(vector<ll> rem, vector<ll> mod, int k) {
    ll m = 1;
    for(auto i : mod) m *= i;
    ll ret = 0;
    for(int i = 0 ; i < k ; i++) {
        ll tmp = (m / mod[i]) % mod[i];
        ll si = mod_inv(tmp, mod[i]);
        ret += (rem[i] * si % m) * (m / mod[i]) % m;
        ret %= m;
    }
    return ret;
}
```

$x \equiv a \pmod m$, $x \equiv b \pmod n$일 경우 해가 존재하려면 $a \equiv b \mod \gcd(m,n)$이여야 함.
$g = \gcd(n,m) = um + vn$이라 할 때 $x \equiv (avn + bum)/g \pmod{} lcm(n,m)$. Should be **added**.

1.2.5 Möbius Inversion Formula

$\forall n \in \mathbb{N}\ g(n) = \sum_{d|n} f(d) \implies f(n) = \sum_{d|n} \mu(d) g(n/d)$

1.3 FFT

$\text{FFT} : (a_0, a_1, \cdots, a_{n-1}) \mapsto (\sum_{j=0}^{n-1} a_0(\omega^0)^j, \sum_{j=0}^{n-1} a_1(\omega^1)^j, \cdots, \sum_{j=0}^{n-1} a_{n-1}(\omega^{n-1})^j)$

```
void fft(vector<base>& a, bool inv) {
    int n = a.size(), j = 0;
    vector<ll> roots(n/2);
    for(int i=1;i<n;i++) {
        int bit = (n >> 1);
        while(j >= bit) {
            j -= bit;
            bit >>= 1;
        }
        j += bit;
        if(i < j) swap(a[i], a[j]);
    }

    double ang = 2 * acos(-1) / n * (inv ? -1 : 1);
    for(int i=0;i<n/2;i++) {
        roots[i] = base(cos(ang * i), sin(ang * i));
    }

    /* In NTT, let prr = primitive root. Then,
    int ang = mexp(prr, (mod - 1) / n);
    if(inv) ang = mexp(ang, mod - 2);
    for(int i=0; i<n/2; i++){
        roots[i] = (i ? (1ll * roots[i-1] * ang % mod) : 1);
    }
    also, make sure to apply modulus under here
    */
    for(int i=2;i<=n;i<<=1) {
        int step = n / i;
        for(int j=0;j<n;j+=i) {
            for(int k=0;k<i/2;k++) {
                ll u = a[j+k], v = a[j+k+i/2] * roots[step * k];
                a[j+k] = u+v;
                a[j+k+i/2] = u-v;
            }
        }
    }
    if(inv) for(int i=0;i<n;i++) a[i] /= n;
}

void conv(vector<base>& x, vector<base>& y) {
    int n = 2; while(n < max(x.size(), y.size())) n <<= 1;
    n <<= 1;
    x.resize(n); y.resize(n);
    fft(x, false); fft(y, false);
    for(int i=0;i<n;i++) x[i] *= y[i];
    fft(x, true); // access (ll)round(x[i].real())
}
```

1.4 Miller-Rabin + Pollard-Rho

```
//Prove By Solving - https://www.acmicpc.net/problem/4149
namespace miller_rabin{
    lint mul(lint x, lint y, lint mod){ return (__int128) x * y % mod; }
  lint ipow(lint x, lint y, lint p){
    lint ret = 1, piv = x % p;
    while(y){
      if(y&1) ret = mul(ret, piv, p);
      piv = mul(piv, piv, p);
      y >>= 1;
    }
    return ret;
  }
  bool miller_rabin(lint x, lint a){
    if(x % a == 0) return 0;
    lint d = x - 1;
    while(1){
      lint tmp = ipow(a, d, x);
      if(d&1) return (tmp != 1 && tmp != x-1);
      else if(tmp == x-1) return 0;
      d >>= 1;
    }
  }
  bool isprime(lint x){
    for(auto &i : {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37}){
      if(x == i) return 1;
      if(x > 40 && miller_rabin(x, i)) return 0;
    }
    if(x <= 40) return 0;
    return 1;
  }
}

namespace pollard_rho{
  lint f(lint x, lint n, lint c){
    return (c + miller_rabin::mul(x, x, n)) % n;
  }
  void rec(lint n, vector<lint> &v){
    if(n == 1) return;
    if(n % 2 == 0){
      v.push_back(2);
      rec(n/2, v);
      return;
    }
    if(miller_rabin::isprime(n)){
```

```
      v.push_back(n);
      return;
    }
    lint a, b, c;
    while(1){
      a = rand() % (n-2) + 2;
      b = a;
      c = rand() % 20 + 1;
      do{
        a = f(a, n, c);
        b = f(f(b, n, c), n, c);
      }while(gcd(abs(a-b), n) == 1);
      if(a != b) break;
    }
    lint x = gcd(abs(a-b), n);
    rec(x, v);
    rec(n/x, v);
  }
  vector<lint> factorize(lint n){
    vector<lint> ret;
    rec(n, ret);
    sort(ret.begin(), ret.end());
    return ret;
  }
};
```

2 Geometry

2.1 struct Point

```
template <class T>
struct point{
    typedef point P;
    T x, y;
    point(T x=0, T y=0) : x(x), y(y) {}
    bool operator< (P a) const { return x != a.x ? x < a.x : y < a.y;}
    bool operator== (P a) const {return x == a.x and y == a.y;}
    P operator+ (P a) const {return P(x+a.x, y+a.y);}
    P operator- (P a) const {return P(x-a.x, y-a.y);}
    P operator- () const {return P(-x, -y);};
    T operator* (P a) const {return x*a.x + y*a.y;} // inner prod
    T operator/ (P a) const {return x*a.y - y*a.x;} // outer prod
    T dist2() const {return x*x + y*y;}
    double dist() const {return sqrt(double(dist2()));}
    P perp() const {return P(-y, x);}; // rotate 90 deg ccw
    P mult(T t) const {return P(x*t, y*t);}
    P unit() const {return P(x/dist(), y/dist());}
    P rotate(double a){
        return P(x*cos(a)-y*sin(a), x*sin(a)+y*cos(a));
    }
};
```

2.1.1 Sorting Points by Angle

```
// credit : http://koosaga.com/97
auto angle_sort = [&](const point &a, const point &b){
    if((a > point(0, 0)) ^ (b > point(0, 0))) return a > b;
    if(a / b != 0) return a / b > 0;
    return a.dist() < b.dist(); // norm
}; // clockwise sort
```

2.2 Intersections

벡터 내적 외적 이용하면 생각보다 간단 / 선분은 예외처리가 좀 많음 Should be **added**.

2.2.1 Line-Line intersection

2.2.2 Line-Segment intersection

2.2.3 Segment-Segment Intersection

2.2.4 Circle-Line Intersection

2.3 Projection, Reflection

Should be **added**.

2.4 Convex Hull

```
vector<pll> get_CV(vector<pll> V){
    sort(V.begin(), V.end());
    sort(V.begin() + 1, V.end(), [&](pll x, pll y){
        pll xx = x - V[0];
        pll yy = y - V[0];
        ll res = xx / yy;
        if(res != 0) return res > 0;
        if(xx.first != yy.first) return xx.first < yy.first;
        return xx.second < yy.second;
    });

    vector<pll> ret;
    for(auto val : V){
        while(ret.size() > 1){
            pll xx = ret[ret.size() - 2] - val;
            pll yy = ret[ret.size() - 1] - val;

            if(xx / yy <= 0) ret.pop_back();
            else break;
        }
        ret.push_back(val);
    }
```

```
    return ret;
}
```

2.5 Rotating Calipers

```
void rotating_calipers(vector<pll> CV){
    int pos = 0;
    for(int i = 0 ; i < CV.size() ; i++) if(CV[pos] < CV[i]) pos = i;

    int ind1 = 0, ind2 = pos;
    ll dist = (CV[ind1] - CV[ind2]) * (CV[ind1] - CV[ind2]);

    auto get_v = [&](int x) { return CV[(x + 1) % CV.size()] - CV[x];};
    for(int i = 0 ; i < CV.size() ; i++){
        pll v = get_v(i);
        while((-v) / get_v(pos) < 0) pos = (pos + 1) % CV.size();
        ll tmp_dist = (CV[pos] - CV[i]) * (CV[pos] - CV[i]);
        if(dist < tmp_dist) {
            dist = tmp_dist;
            ind1 = i;   ind2 = pos;
        }
    }

    printf("%lld %lld %lld %lld\n", CV[ind1].first, CV[ind1].second, CV[ind2].first,
    CV[ind2].second);
}
```

2.6 Smallest Enclosing Circle

```
//Prove By Solving - https://www.acmicpc.net/problem/11930
int main(){
    scanf("%d", &N);

    for(int i = 1 ; i <= N ; i++) scanf("%lf%lf%lf", &A[i].x, &A[i].y, &A[i].z);

    int t = 70000;
    double rate = 1.0;
    point cur = (point){0, 0, 0};
    for(int i = 1 ; i <= t; i++){
        int ind = 1;
        for(int j = 1 ; j <= N ; j++) if((A[j] - cur) * (A[j] - cur) > (A[ind] -
        cur) * (A[ind] - cur)) ind = j;
        cur = cur + (A[ind] - cur) * rate;
        rate *= 0.99;
    }

    double r = 0;
    for(int i = 1 ; i <= N ; i++) r = max(r, (A[i] - cur) * (A[i] - cur));
    cout << sqrt(r);
    return 0;
}
```

2.7 Polygon Area

Should be **added**.

2.7.1 Polygon Area

2.7.2 Polygon Overlapping

3 Strings

3.1 Aho-Corasick Algorithm

```
// credit : https://github.com/koosaga/DeobureoMinkyuParty/blob/master/teamnote.tex
const int MAXN = 100005, MAXC = 26;
int trie[MAXN][MAXC], fail[MAXN], term[MAXN], piv;
void init(vector<string> &v){
  memset(trie, 0, sizeof(trie));
  memset(fail, 0, sizeof(fail));
  memset(term, 0, sizeof(term));
  piv = 0;
  for(auto &i : v){
    int p = 0;
    for(auto &j : i){
      if(!trie[p][j]) trie[p][j] = ++piv;
      p = trie[p][j];
    }
    term[p] = 1;
  }
  queue<int> q;
  for(int i=0; i<MAXC; i++){
    if(trie[0][i]) que.push(trie[0][i]);
  }
  while(!que.empty()){
    int x = q.front();
    q.pop();
    for(int i=0; i<MAXC; i++){
      if(trie[x][i]){
        int p = fail[x];
        while(p && !trie[p][i]) p = fail[p];
        p = trie[p][i];
        fail[trie[x][i]] = p;
        if(term[p]) term[trie[x][i]] = 1;
        q.push(trie[x][i]);
      }
    }
  }
}
bool query(string &s){
  int p = 0;
  for(auto &i : s){
    while(p && !trie[p][i]) p = fail[p];
    p = trie[p][i];
```

```
    if(term[p]) return 1;
  }
  return 0;
}
```

3.2 Suffix Array

```
vector<int> make_sa(const string& s) {
    int n = s.length();
    int lim = max(128, n+1);
    vector<int> sa(n), g(n+1), ng(n+1);
    for(int i=0;i<n;i++) {
        sa[i] = i;
        g[i] = s[i];
    }
    g[n] = 0;
    for(int t=1;t<s.length();t<<=1)
    {
        auto cmp = [&] (int a, int b) {
            return g[a] != g[b] ? g[a] < g[b] : g[a+t] < g[b+t];
        };
        vector<int> cnt(lim), ind(lim+1);
        for(int i=0;i<n;i++) cnt[g[min(i+t, n)]]++;
        for(int i=1;i<lim;i++) cnt[i] += cnt[i-1];
        for(int i=n-1;i>=0;i--) ind[--cnt[g[min(i+t, n)]]] = i;
        for(int i=0;i<lim;i++) cnt[i] = 0;
        for(int i=0;i<n;i++) cnt[g[i]]++; // same as cnt[g[ind[i]]]++
        for(int i=1;i<lim;i++) cnt[i] += cnt[i-1];
        for(int i=n-1;i>=0;i--) sa[--cnt[g[ind[i]]]] = ind[i];
        ng[sa[0]] = 1;
        for(int i=1;i<n;i++) {
            ng[sa[i]] = ng[sa[i-1]];
            if(cmp(sa[i-1], sa[i])) ng[sa[i]]++;
        }
        g = ng;
    }
    return sa;
}

vector<int> make_lcp(const string& s, const vector<int>& sa) {
    int n = s.length();
    vector<int> lcp(n-1), rank(n);
    for(int i=0;i<n;i++)
        rank[sa[i]] = i;
    int len = 0;
    for(int i=0;i<n;i++) {
        if(rank[i]) {
            int j = sa[rank[i]-1];
            int lc = n - max(i,j);
            while(len < lc && s[i+len] == s[j+len]) len++;
            lcp[rank[i]-1] = len;
        }
        if(len) len--;
    }
    return lcp;
}
/* str  : abracadabra
 * SA   : 10 7 0 3 5 8 1 4 6 9 2
 * LCP  : 1 4 1 1 0 3 0 0 0 2
 */
```

3.3 Manacher's Algorithm

```
vector<int> manacher(const string& s) {
    vector<int> x(s.length());
    int r = -1, p = -1;
    for(int i=0;i<s.length();i++) {
        if(i <= r) x[i] = min(r-i, x[2*p-i]);
        while(x[i]+1 <= i && i+x[i]+1 < s.length() &&
            s[i-x[i]-1] == s[i+x[i]+1])
                x[i]++;
        if(i + x[i] > r)
            r = i + x[i], p = i;
    }
    return x;
}
```

3.4 Z Algorithm

```
vector<int> z_algo(const string& s) {
   vector<int> z(s.length());
    int r = -1, p = -1;
    for(int i=1;i<s.length();i++) {
        if(i <= r) z[i] = min(r-i, z[i-p]);
        while(i+z[i]<s.length() && s[i+z[i]] == s[z[i]]) z[i]++;
        if(r > i+z[i]) r = i+z[i], p = i;
    }
    return z;
}
```

3.5 Lexicographically Smallest String Rotation

```
// rotate(v.begin(), v.begin()+min_rotation(v), v.end());
int min_rotation(string s) {
  int a=0, N=sz(s); s += s;
  rep(b,0,N) rep(i,0,N) {
    if (a+i == b || s[a+i] < s[b+i]) {b += max(0, i-1); break;}
    if (s[a+i] > s[b+i]) { a = b; break; }
  }
  return a;
}
```

4 Graph Theory

4.1 Strongly Connected Component

```
vector<int> adj[MAX_V];
int finished[MAX];
int dfsn[MAX_V];
int cnt = 1;
vector<vector<int>> SCC;
stack<int> s;

int dfs(int cur) {
    dfsn[cur] = cnt++;
    s.push(cur);
    int res = dfsn[cur];
    for (int n : adj[cur]) {
        if (!dfsn[n]) res = min(res, dfs(n));
        else if (!finished[n]) res = min(res, dfsn[n]);
    }
    if (res == dfsn[cur]) {
        vector<int> sub;
        int t = -1;
        do {
            t = s.top(); s.pop();
            finished[t] = 1;
            sub.push_back(t);
        } while (t != cur);
        SCC.push_back(sub);
    }
    return res;
}
```

4.2 2-SAT

Should be **added**.

4.3 Biconnected Component

Should be **added**.

4.4 Euler Tour

```
struct Edge{
    int to, cnt; // to: 인접한 정점, cnt: 남은 사용 횟수
    Edge *dual; // dual: 역방향 간선을 가리키는 포인터
    Edge(): Edge(-1, 0){}
    Edge(int to1, int cnt1): to(to1), cnt(cnt1), dual(nullptr){}
};
void Eulerian(int curr){
    for(Edge *e: adj[curr]){
        if(e->cnt > 0){
            e->cnt--;
            e->dual->cnt--;
            Eulerian(e->to); // dfs
        }
    }
    cout << curr << '\n';
}
```

4.5 Offline Dynamic Connectivity

Should be **added**.

4.6 Heavy-Light Decomposition

Should be **added**.

4.7 Dominator Tree

Should be **added**.

4.8 Negative Cycle Detection

Should be **added**.

4.9 Tree Compress

Should be **added**.

5 Network Flow

5.1 Theorems

Should be **added**.LR-flow and bunch of theories?

5.2 Dinic's Algorithm

```
const int INF = 1e9;
struct Dinic{
    int N;
    struct edge{
        int index, cap, rev;
        edge() : index(0), cap(0), rev(0) {}
        edge(int index, int cap, int rev) : index(index), cap(cap), rev(rev) {}
    };

    vector<vector<edge>> ADJ;
    vector<int> R, W;

    Dinic() {}
    Dinic(int N) : N(N){
        ADJ.resize(N);  R.resize(N);    W.resize(N);
```

```
    }

    void CE(int node1, int node2, int cap){
        ADJ[node1].push_back(edge(node2, cap, ADJ[node2].size()));
        ADJ[node2].push_back(edge(node1, 0, ADJ[node1].size() - 1));
    }

    bool bfs(int src, int sink){
        for(int i = 0 ; i < R.size() ; i++) R[i] = -1;
        R[src] = 0;
        queue<int> Q; Q.push(src);
        while(Q.size()){
            int here = Q.front();   Q.pop();
            for(auto e : ADJ[here]){
                if(e.cap > 0 && R[e.index] == -1) R[e.index] = R[here] + 1,
                Q.push(e.index);
            }
        }
        return R[sink] != -1;
    }

    int dfs(int here, int sink, int f){
        if(here == sink) return f;
        for(int &i = W[here] ; i < ADJ[here].size() ; i++){
            auto &e = ADJ[here][i];
            if(e.cap > 0 && R[here] < R[e.index]){
                int res = dfs(e.index, sink, min(f, e.cap));
                if(res) {
                    e.cap -= res;
                    ADJ[e.index][e.rev].cap += res;
                    return res;
                }
            }
        }
        return 0;
    }

    int solve(int src, int sink){
        int ret = 0;
        while(bfs(src, sink)){
            for(int i = 0 ; i < N ; i++) W[i] = 0;
            int res;
            while((res = dfs(src, sink, INF))) ret += res;
        }
        return ret;
    }
};
```

5.3 MCMF with SPFA

Should be **revised**.

```
struct MCMF {
  struct Edge {
    int to, cap, cost, rev;
    Edge(int to, int cap, int cost) : to(to), cap(cap), cost(cost) {}
  };
  int N, src, sink;
  vector<vector<Edge>> G;
  vector<long long> dist;
  vector<pair<int, int>> P;
  vector<bool> InQ;
  MCMF(int N, int src, int sink) : N(N), src(src), sink(sink) {
    G.resize(N);
    dist.resize(N);
    P.resize(N);
    InQ.resize(N);
  }
  void add_edge(int f, int t, int cap, int cost) {
    G[f].emplace_back(t, cap, cost);
    G[t].emplace_back(f, 0, -cost);
    G[f].back().rev = G[t].size() - 1;
    G[t].back().rev = G[f].size() - 1;
  }
  void add_edge_from_source(int t, int cap, int cost) {
    add_edge(src, t, cap, cost);
  }
  void add_edge_to_sink(int f, int cap, int cost) {
    add_edge(f, sink, cap, cost);
  }
  pair<long long,long long> flow() {
    pair<long long, long long>  ret;
    queue<int> Q;
    for (;;) {
      long long flow = 0x7fffffffffffffLL;
      fill(dist.begin(), dist.end(), 0x7fffffffffffffLL);
      fill(P.begin(), P.end(), make_pair(-1, -1));
      dist[src] = 0;
      Q.push(src);
      while (!Q.empty()) {
        int c = Q.front();
        Q.pop();
        InQ[c] = false;
        for (int i = 0; i < G[c].size(); i++) {
          auto &e = G[c][i];
          if (e.cap > 0 && dist[e.to] > dist[c]+ e.cost) {
            dist[e.to] = dist[c] + e.cost;
            P[e.to] = make_pair(c, i);
            if (!InQ[e.to]) {
              InQ[e.to];
              Q.push(e.to);
            }
```

```
        }
      }
    }
    for (int now = sink; P[now].first != -1; now = P[now].first) {
      auto &e = G[P[now].first][P[now].second];
      flow = min(flow, 1LL*e.cap);
    }
    for (int now = sink; P[now].first != -1; now = P[now].first) {
      auto &e = G[P[now].first][P[now].second];
      e.cap -= flow;
      G[e.to][e.rev].cap += flow;
      ret.second += e.cost*flow;
    }
    ret.first += flow;
  }
  return ret;
 }
};
```

5.4 Hungarian Method

```
const int N_SIZE = 2000, M_SIZE = 2000;
int lx[N_SIZE], ly[M_SIZE],  cost[N_SIZE][M_SIZE],

int hungarian(int N, int M) // N <= M
{
  int xy[N_SIZE], yx[M_SIZE], T[M_SIZE];;
  pair<int, int> slack[M_SIZE];
  bool S[N_SIZE];

  int ret = 0;
  memset(xy, -1, sizeof(xy));
  memset(yx, -1, sizeof(yx));
  memset(ly, 0, sizeof(ly));
  for (int i = 0; i < N; i++) {
    lx[i] = cost[i][0];
    for (int j = 1; j < M; j++) {
      lx[i] = max(lx[i], cost[i][j]);
    }
  }
  for (int r = 0; r < N; r++) {
    int y;
    for (int j = 0; j < M; j++) {
      slack[j] = make_pair(lx[r] + ly[j] - cost[r][j], r);
    }
    memset(S, 0, sizeof(S));
    memset(T, -1, sizeof(T));
    S[r] = true;
    for (;;) {
      int a = 0x7fffffff, x;
      for (int j = 0; j < M; j++) {
        if (T[j] == -1 && a > slack[j].first) {
          a = slack[j].first;
          x = slack[j].second;
          y = j;
        }
      }
      if (a) {
        for (int i = 0; i < N; i++) {
          if (S[i]) lx[i] -= a;
        }
        for (int j = 0; j < M; j++) {
          if (T[j] != -1) ly[j] += a;
          else slack[j].first -= a;
        }
      }
      T[y] = x;
      x = yx[y];
      if (x == -1) break;
      S[x] = true;
      for (int j = 0; j < M; j++) {
        pair<int, int> temp(lx[x] + ly[j] - cost[x][j], x);
        if (T[j] == -1 && slack[j].first > temp.first) {
          slack[j] = temp;
        }
      }
    }
    while (y != -1) {
      int x = T[y];
      int temp = xy[x];
      yx[y] = x;
      xy[x] = y;
      y = temp;
    }
  }
  for (int i = 0; i < N; i++) {
    ret += cost[i][xy[i]];
  }
  return ret;
}
```

5.5 Hopcroft-Karp Algorithm

```
struct hopcroft_karp{
    int N;
    vector<vector<int>> ADJ;
    vector<int> L, rev, used;

    hopcroft_karp() {}
    hopcroft_karp(int N) : N(N) {
        ADJ.resize(N);
        L.resize(N), rev.resize(N, -1), used.resize(N, 0);
```

```
    }

    void CE(int here, int there){
        ADJ[here].push_back(there);
    }

    void bfs(){
        queue<int> Q;
        for(int i = 0 ; i < N ; i++) {
            if(used[i]) L[i] = -1;
            else L[i] = 0, Q.push(i);
        }

        while(Q.size()){
            int here = Q.front();   Q.pop();
            for(int there : ADJ[here]){
                if(rev[there] != -1 && L[rev[there]] == -1) {
                    L[rev[there]] = L[here] + 1;
                    Q.push(rev[there]);
                }
            }
        }
    }

    bool dfs(int here){
        for(int there : ADJ[here]){
            if(rev[there] == -1 || (L[here] < L[rev[there]] && dfs(rev[there]))){
                rev[there] = here;
                used[here] = 1;
                return true;
            }
        }
        return false;
    }

    int solve(){
        int ret = 0;
        while(1){
            bfs();
            int res = 0;
            for(int i = 0 ; i < N ; i++) {
                if(used[i]) continue;
                res += dfs(i);
            }
            if(res == 0) break;
            ret += res;
        }
        return ret;
    }
};
```

6 Optimization Tricks

6.1 Knuth Optimization

- Recurrence : $D[i][j] = \min_{i<k<j}(D[i][k] + D[k][j]) + C[i][j]$
- Quadrangle Inequality : $C[a][c] + C[b][d] \leq C[a][d] + C[b][c],\ a \leq b \leq c \leq d$
- Monotonicity : $C[b][c] \leq C[a][d],\ a \leq b \leq c \leq d$
- $A[i][j] =$ (min. k *s.t.* $D[i][j]$ is min.). Then $A[i][j-1] \leq A[i][j] \leq A[i+1][j]$
- $O(N^2)$ time complexity

```
// opt[i-1][i] = i
for(int d=2;d<=n;d++) {
    for(int i=1;i+d<=n+1;i++) {
        for(int k=opt[i][j-1], j=i+d; k<=opt[i+1][j]; k++) {
            int v = dp[i][k] + dp[k][j] + c[i][j];
            if(dp[i][j] > v) dp[i][j] = v, opt[i][j] = k;
        }
    }
}
```

6.2 Divide and Conquer Optimization

- Recurrence : $D[t][i] = \min_{k<i}(D[t-1][k] + C[k][i])$
- Min index : $A[t][i] \leq A[t][i+1]$ ($A[t][i] =$ (min. k *s.t.* $D[t][i]$ is min.))

  [-] Quadrangle Inequality : $C[a][c] + C[b][d] \leq C[a][d] + C[b][c],\ a \leq b \leq c \leq d$
- Able to Divide and Conquer base on calculating $D[t][i]$
- $O(TN \lg N)$ time complexity

```
// range of index : [l,r]
// range of dp    : [s,e]
void dnc(int t, int l, int r, int s, int e)
{
    if(s > e) return;
    int m = (s+e)/2;
    D[t][m] = 2e9;
    for(int k=l;k<m&&k<=r;k++)
    {
        int tmp = D[t-1][k] + C[k][m];
        if(D[t][m] > tmp)
            D[t][m] = tmp, A[t][m] = k;
    }
    dnc(t, l, A[t][m], s, D[t][m]-1);
    dnc(t, A[t][m], r, D[t][m]+1, e);
}
```

6.3 Convex Hull Trick

- Recurrence : $dp[i] = \min_{j<i}(dp[j] + a[i]b[j]),\ b[i-1] \le b[i]$
- Think as $dp[x = a[i]] = \min_{j<i}(b[j] \cdot x + dp[j])$
- Thus push lines and find minimum (by binary search)
- If $a[i] \le a[i+1]$ sweeping is possible
- Intersection of $y = a_i x + b_i$ and $y = a_{i+1}x + b_{i+1}$: $x = \frac{b_{i+1}-b_i}{a_i - a_{i+1}}$

6.4 Centroid Decomposition

```
// credit : https://gist.github.com/igorcarpanese/75162f3253bd230abd0f32f9950bf384
int dfs(int u, int p) {
    sub[u] = 1;
    for (auto v : tree[u])
        if (v != p) sub[u] += dfs(v, u);
    return sub[u] + 1;
}

int centroid(int u, int p, int r) { // r : root
    for (auto v : tree[u])
        if (v != p and sub[v] > sub[r]/2) return centroid(v, u);
    return u;
}
```

7 Data Structure

7.1 Persistent Segment Tree

Should be **revised**.

```
// credit : http://junis3.tistory.com/8

const int maxn = 1<<17;
int root[maxn];
struct pst {
    int v[maxn*17], l[maxn*17], r[maxn*17], t;
    // create root[0]
    int base(int s, int e) {
        int k = t++;
        if (s<e) {
            int m = (s+e)/2;
            l[k] = base(s, m);
            r[k] = base(m+1, e);
        }
        return k;
    }
    // make tree from root bef, position 'pos' with value 'val'
    int make(int bef, int s, int e, int pos, int val) {
        if (pos<s or e<pos) return bef;
        int k = t++;
        if (s==e) {
            v[k] = v[bef] + val;
        } else {
            int m = (s+e)/2;
            l[k] = make(l[bef], s, m, pos, val);
            r[k] = make(r[bef], m+1, e, pos, val);
            v[k] = v[l[k]] + v[r[k]];
        } return k;
    }
    // gets sum from root k where index is from l to r (inclusive)
    int query(int k, int s, int e, int x, int y) {
        if (x<=s and e<=y) return v[k];
        else if (e<x or y<s) return 0;
        else {
            int m = (s+e)/2;
            return query(l[k], s, m, x, y) + query(r[k], m+1, e, x, y);
        }
    }
} t;
```

7.2 Link-Cut Tree

```
struct node{
    node *pp, *p, *l, *r;
    int val;
    node(){ p = 0, l = 0, r = 0;}
    node(int val) : val(val) { p = 0, l = 0, r = 0;}
};

void push(node *x){}
void pull(node *x){}

void rotate(node *x){
  if(!x->p) return;
  push(x->p);  // if there's lazy stuff
  push(x);
  node *p = x->p;
  bool is_left = (p->l == x);
  node *b = (is_left ? x->r : x->l);
  x->p = p->p;
  if(x->p && x->p->l == p) x->p->l = x;
  if(x->p && x->p->r == p) x->p->r = x;
  if(is_left){
    if(b) b->p = p;
    p->l = b;
    p->p = x;
    x->r = p;
  }
  else{
```

```
    if(b) b->p = p;
    p->r = b;
    p->p = x;
    x->l = p;
  }
  pull(p); // if there's something to pull up
  pull(x);
  //if(!x->p) root = x; // IF YOU ARE SPLAY TREE
  if(p->pp){ // IF YOU ARE LINK CUT TREE
    x->pp = p->pp;
    p->pp = nullptr;
  }
}
void splay(node *x){
  while(x->p){
    node *p = x->p;
    node *g = p->p;
    if(g){
      if((p->l == x) ^ (g->l == p)) rotate(x);
      else rotate(p);
    }
    rotate(x);
  }
}
void access(node *x){
  splay(x);
  push(x);
  if(x->r){
    x->r->pp = x;
    x->r->p = nullptr;
    x->r = nullptr;
  }
  pull(x);
  while(x->pp){
    node *nxt = x->pp;
    splay(nxt);
    push(nxt);
    if(nxt->r){
      nxt->r->pp = nxt;
      nxt->r->p = nullptr;
      nxt->r = nullptr;
    }
    nxt->r = x;
    x->p = nxt;
    x->pp = nullptr;
    pull(nxt);
    splay(x);
  }
}
node *root(node *x){
  access(x);
  while(x->l){
    push(x);
    x = x->l;
  }
  access(x);
  return x;
}
node *par(node *x){
  access(x);
  if(!x->l) return nullptr;
  push(x);
  x = x->l;
  while(x->r){
    push(x);
    x = x->r;
  }
  access(x);
  return x;
}
node *lca(node *s, node *t){
  access(s);
  access(t);
  splay(s);
  if(s->pp == nullptr) return s;
  return s->pp;
}
void link(node *par, node *son){
  access(par);
  access(son);
  //son->rev ^= 1;  // remove if needed
  push(son);
  son->l = par;
  par->p = son;
  pull(son);
}
void cut(node *p){
  access(p);
  push(p);
  if(p->l){
    p->l->p = nullptr;
    p->l = nullptr;
  }
  pull(p);
}
```

7.3 Li-Chao Tree

Should be **added**....?

7.4 Dynamic Convex Hull

```
// https://github.com/niklasb/contest-algos/blob/master/convex_hull/dynamic.cpp
const ll is_query = -(1LL<<62);
struct Line {
    ll m, b;
    mutable function<const Line*()> succ;
    bool operator<(const Line& rhs) const {
        if (rhs.b != is_query) return m < rhs.m;
        const Line* s = succ();
        if (!s) return 0;
        ll x = rhs.m;
        return b - s->b < (s->m - m) * x;
    }
};
struct HullDynamic : public multiset<Line> { // will maintain upper hull for maximum
    bool bad(iterator y) {
        auto z = next(y);
        if (y == begin()) {
            if (z == end()) return 0;
            return y->m == z->m && y->b <= z->b;
        }
        auto x = prev(y);
        if (z == end()) return y->m == x->m && y->b <= x->b;
        return (x->b - y->b)*(z->m - y->m) >= (y->b - z->b)*(y->m - x->m);
    }
    void insert_line(ll m, ll b) {
        auto y = insert({ m, b });
        y->succ = [=] { return next(y) == end() ? 0 : &*next(y); };
        if (bad(y)) { erase(y); return; }
        while (next(y) != end() && bad(next(y))) erase(next(y));
        while (y != begin() && bad(prev(y))) erase(prev(y));
    }
    ll eval(ll x) {
        auto l = *lower_bound((Line) { x, is_query });
        return l.m * x + l.b;
    }
};
```

7.5 Stern-Brocot Tree

Should be **added**.

7.6 Rope

Should be **added**.

7.7 Policy Based Data Structure

8 Miscellaneous

8.1 Misc Formulae and Algorithms

8.1.1 Faulhaber's Formula

$$T(n,k) = \sum_{i=1}^{n} i^k = \frac{(n+1)^{k+1} - 1^{k+1} - \sum_{j=0}^{k-1} \binom{k+1}{j} T(n,j)}{\binom{k+1}{k}}$$

Also use

$$(x+1)^d - x^d = 1 + \binom{d}{1}x + \binom{d}{2}x^2 + \cdots + \binom{d}{d-1}x^{d-1}$$

to get each coef.

8.1.2 Maximum Clique

Should be **added**....?

8.1.3 De Brujin Sequence

Should be **added**....?

8.2 Highly Composite Numbers, Large Prime

< 10^k	number	divisors	2 3 5 71113171923293137
1	6	4	1 1
2	60	12	2 1 1
3	840	32	3 1 1 1
4	7560	64	3 3 1 1
5	83160	128	3 3 1 1 1
6	720720	240	4 2 1 1 1 1
7	8648640	448	6 3 1 1 1 1
8	73513440	768	5 3 1 1 1 1 1
9	735134400	1344	6 3 2 1 1 1 1
10	6983776800	2304	5 3 2 1 1 1 1 1
11	97772875200	4032	6 3 2 2 1 1 1 1
12	963761198400	6720	6 4 2 1 1 1 1 1 1
13	9316358251200	10752	6 3 2 1 1 1 1 1 1 1
14	97821761637600	17280	5 4 2 2 1 1 1 1 1 1
15	866421317361600	26880	6 4 2 1 1 1 1 1 1 1 1
16	8086598962041600	41472	8 3 2 2 1 1 1 1 1 1 1
17	74801040398884800	64512	6 3 2 2 1 1 1 1 1 1 1 1 1
18	897612484786617600	103680	8 4 2 2 1 1 1 1 1 1 1 1 1

< 10^k	prime #	of prime	< 10^k	prime
1	7	4	10	9999999967
2	97	25	11	99999999977

3	997	168	12	999999999989
4	9973	1229	13	9999999999971
5	99991	9592	14	99999999999973
6	999983	78498	15	999999999999989
7	9999991	664579	16	9999999999999937
8	99999989	5761455	17	99999999999999997
9	999999937	50847534	18	999999999999999989

NTT Prime:
$469762049 = 7 \times 2^{26} + 1$. Primitive root : 3.
$998244353 = 119 \times 2^{23} + 1$. Primitive root: 3.
$985661441 = 235 \times 2^{22} + 1$. Primitive root: 3.
$1012924417 = 483 \times 2^{21} + 1$. Primitive root: 5.

8.3 Fast Integer IO

```
// credit : https://github.com/koosaga/DeobureoMinkyuParty/blob/master/teamnote.tex
static char buf[1 << 19]; // size : any number geq than 1024
static int idx = 0;
static int bytes = 0;
static inline int _read() {
  if (!bytes || idx == bytes) {
    bytes = (int)fread(buf, sizeof(buf[0]), sizeof(buf), stdin);
    idx = 0;
  }
  return buf[idx++];
}
static inline int _readInt() {
  int x = 0, s = 1;
  int c = _read();
  while (c <= 32) c = _read();
  if (c == '-') s = -1, c = _read();
  while (c > 32) x = 10 * x + (c - '0'), c = _read();
  if (s < 0) x = -x;
  return x;
}
```

8.4 C++ Tips / Environments

Should be **revised**.(with random, `chrono`)

```
#include <bits/stdc++.h> // magic header
using namespace std;     // magic namespace

struct StupidGCCCantEvenCompileThisSimpleCode{
  pair<int, int> array[1000000];
}; // https://gcc.gnu.org/bugzilla/show_bug.cgi?id=68203

// how to use rand (in 2017)
mt19937 rng(0xdeadbeef);
mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
int randint(int lb, int ub){ return uniform_int_distribution<int>(lb, ub)(rng); }
shuffle(permutation.begin(), permutation.end(), rng);
mt19937_64 _R(chrono::steady_clock::now().time_since_epoch().count()); // _R()

// comparator overload
auto cmp = [](seg a, seg b){return a.func() < b.func(); };
set<seg, decltype(cmp)> s(cmp);
map<seg, int, decltype(cmp)> mp(cmp);
priority_queue<seg, vector<seg>, decltype(cmp)> pq(cmp); // max heap

// hash func overload
struct point{
int x, y;
bool operator==(const point &p)const{ return x == p.x && y == p.y; }
};
struct hasher {
size_t operator()(const point &p)const{ return p.x * 2 + p.y * 3; }
};
unordered_map<point, int, hasher> hsh;

// c++ setprecision example
#include <iostream>     // std::cout, std::fixed
#include <iomanip>      // std::setprecision

int main () {
  double f =3.14159;
  std::cout << std::setprecision(5) << f << '\n'; // 3.1416
  std::cout << std::setprecision(9) << f << '\n'; // 3.14159
  std::cout << std::fixed;
  std::cout << std::setprecision(5) << f << '\n'; // 3.14159
  std::cout << std::setprecision(9) << f << '\n'; // 3.141590000
  return 0;
}
```