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Team Note of Powered by Zigui

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ALL BELOW HERE ARE USELESS IF YOU READ THE STATEMENT WRONG

0 Quotes and Prerequisites

```
evenharder : Mental Abuse To Humans
djkim0613 : 열심히 응원하겠습니다.
SoulTch : How much is this bus ticket?
* This template is brought from that of 'Deobureo Minkyu Party'
```

Run script

```
#!/bin/bash
g++ -fsanitize=undefined -std=c++14 -02 -o /tmp/pow $1.cpp
time /tmp/pow < $1.in
# export PATH=~:$PATH</pre>
```

Debug Code

```
#define fi first
#define se second
#define pb push_back
#define rep(i, e) for (int i = 0, _##i = (e); i < _##i; i++)
#define repp(i, s, e) for (int i = (s), _##i = (e); i < _##i; i++)
#define repr(i, s, e) for (int i = (s)-1, _##i = (e); i \ge _{\#}i; i--)
// using namespace std;
using 11 = long long;
using pii = pair<int, int>;
using pll = pair<11, 11>;
template<typename T>
ostream &operator<<(ostream &os, const vector<T>& v) {
    cout << "[":
    for (auto p : v) cout << p << ",";</pre>
    cout << "]":
    return os;
}
#ifndef SOULTCH
#define debug(...) 0
#define endl '\n'
#define debug(...) cout << " [-] ", _dbg(#__VA_ARGS__, __VA_ARGS__)</pre>
template<class TH> void _dbg(const char *sdbg, TH h){ cout << sdbg << '=' << h <<
endl; }
template<class TH, class... TA> void _dbg(const char *sdbg, TH h, TA... a) {
    while(*sdbg != ',') cout << *sdbg++;</pre>
    cout << '=' << (h) << ',';
    _dbg(sdbg+1, a...);
}
#endif
```

Reminders

Should be added.

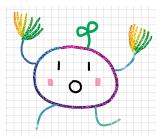


Figure 1: 풀다가 막힐 때는 이 그림을 봅시다. 아자아자 화이팅!

1 Math

1.1 Basic Mathematics

1.1.1 Trigonometry

- $\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$
- $\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta$
- $\tan(\alpha \pm \beta) = \frac{\tan \alpha \pm \tan \beta}{1 \mp \tan \alpha \tan \beta}$
- $\sin 2\theta = 2\sin\theta\cos\theta$
- $c^2 = a^2 + b^2 2ab\cos\gamma$

1.1.2 Generating Function

- $\sum_{n} (pn+q)x^{n} = \frac{p}{1-x} + \frac{q}{(1-x)^{2}}$ (Arithmetic progression)
- $\sum_{n} (rx)^n = (1 rx)^{-1}$ (Geometric progression)
- $\sum_{n} {m \choose n} x^n = (1+x)^m$ (Binomial coefficient)
- $\sum_{n} {m+n-1 \choose n} x^n = (1-x)^{-m}$ (Multiset coefficient)

1.1.3 Calculus

Should be added.

1.1.4 Gaussian Elimination

Should be **added**....?

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1.2 Number Theory

1.2.1 Lattice Points under Line

for(ll j=0;j<m;j++) {</pre>

```
// 0 \le x \le n, 0 \le y \le (a/c)x+(b/c)
11 calc(l1 a,l1 b,l1 c,l1 n){
    if(!n)return 0;
    11 tmp=a/c*n*(n-1)/2;
    tmp+=b/c*n:
    return tmp+calc(c,(a*n+b)%c,a%c,((a%c)*n+b%c)/c);
}
1.2.2 Shanks' Baby-step Giant-step
  Should be revised.
11 mexp(ll x, ll y, ll p) {
    if(!v) return 1:
    if(v & 1) return x * mexp(x*x%p, y>>1, p) % p;
    return mexp(x*x\%p, y>>1, p);
}
vector<ll> get_factor(ll n) {
    vector<ll> v;
    for(ll i=2:i*i<=n:i++) {
        if(n \% i == 0) {
            v.push_back(i);
            while(n \% i == 0) n /= i:
        }
    }
    if(n > 1) v.push_back(n);
    return v:
}
ll get_primitive(ll n) {
    11 phi = n-1; // assume n is prime
    vector<ll> fact = get_factor(phi);
    for(11 x=2;x<=n;x++) {
        int ves = 1:
        for(ll y : fact) {
            yes &= (mexp(x, phi / y, n) != 1);
        if(yes) return x;
    }
    return -1;
// find x s.t. x^k \mod n = a \rightarrow (g^k)^y \mod n = a, where x = g^y
11 bsgs(ll k, ll a, ll n) {
    11 g = get_primitive(n);
    11 phi = n-1; // assume n is prime
    if(g == -1) return -1;
    ll m = ceil(sqrt(n) + 1e-9);
    vector<pl> prec(m);
```

```
prec[j] = {mexp(g, j * k % phi, n), j};
   }
   sort(prec.begin(), prec.end());
   ll cur = a, ncur = mexp(g, (phi - m) * k % phi, n);
   for(ll i=0:i<m:i++) {
        auto it = lower_bound(prec.begin(), prec.end(), pl(cur, 0));
        if(it->first == cur) {
            ll ans = mexp(g, (i*m + it->second) \% phi, n);
            assert(mexp(ans, k, n) == a);
            return ans:
        }
        cur = cur * ncur % n;
   }
   return 0;
}
1.2.3 Extended Euclidean Algorithm
// ax + by = gcd(a,b) \Rightarrow x ? y ?
typedef long long int 11
pair<11,11> ext_gcd(11 a,11 b) {
   if(b) {
        auto tmp = ext_gcd(b, a%b);
        return {tmp.second, tmp.first - (a/b) * tmp.second};
   }
    else return {1, 0};
// ax = 1 mod M, x?
ll mod inv(ll a, ll M) {
   return (ext_gcd(a, M).first + M) % M;
1.2.4 Chinese Remainder Theorem
typedef long long int 11;
11 CRT(vector<ll> rem. vector<ll> mod. int k) {
    11 m = 1:
   for(auto i : mod) m *= i;
   11 \text{ ret} = 0:
   for(int i = 0 ; i < k ; i++) {
        11 tmp = (m / mod[i]) % mod[i];
        11 si = mod inv(tmp, mod[i]):
        ret += (rem[i] * si % m) * (m / mod[i]) % m;
        ret %= m:
   }
    return ret;
x \equiv a \pmod{m}, x \equiv b \pmod{n}일 경우 해가 존재하려면 a \equiv b \pmod{\gcd(m,n)}이여야 함.
 q = \gcd(n, m) = um + vn이라 할 때 x \equiv (avn + bum)/q \pmod{lcm(n, m)}. Should be added.
```

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1.2.5 Möbius Inversion Formula

```
\forall n \in \mathbb{N} \ g(n) = \sum_{d \mid n} f(d) \implies f(n) = \sum_{d \mid n} \mu(d) g(n/d)
```

1.3 FFT

```
FFT: (a_0, a_1, \dots, a_{n-1}) \mapsto (\sum_{j=0}^{n-1} a_0(\omega^0)^j, \sum_{j=0}^{n-1} a_1(\omega^1)^j, \dots, \sum_{j=0}^{n-1} a_{n-1}(\omega^{n-1})^j)
void fft(vector<base>& a, bool inv) {
    int n = a.size(), i = 0:
    vector<ll> roots(n/2);
    for(int i=1:i<n:i++) {
        int bit = (n >> 1);
        while(j >= bit) {
             j -= bit;
             bit >>= 1;
        j += bit;
        if(i < j) swap(a[i], a[j]);</pre>
    }
    double ang = 2 * acos(-1) / n * (inv ? -1 : 1);
    for(int i=0:i<n/2:i++) {
        roots[i] = base(cos(ang * i), sin(ang * i));
    }
    /* In NTT, let prr = primitive root. Then,
    int ang = mexp(prr, (mod - 1) / n);
    if(inv) ang = mexp(ang, mod - 2);
    for(int i=0; i< n/2; i++){
        roots[i] = (i ? (111 * roots[i-1] * ang % mod) : 1);
    also, make sure to apply modulus under here
    for(int i=2;i<=n;i<<=1) {</pre>
        int step = n / i:
        for(int j=0;j<n;j+=i) {</pre>
             for(int k=0;k<i/2;k++) {</pre>
                 ll u = a[i+k], v = a[i+k+i/2] * roots[step * k]:
                 a[j+k] = u+v;
                 a[j+k+i/2] = u-v;
             }
        }
    }
    if(inv) for(int i=0;i<n;i++) a[i] /= n;</pre>
void conv(vector<base>& x, vector<base>& y) {
    int n = 2; while (n < max(x.size(), y.size())) n <<= 1;
    n <<= 1:
    x.resize(n); y.resize(n);
```

```
fft(x, false); fft(y, false);
   for(int i=0;i<n;i++) x[i] *= y[i];</pre>
   fft(x, true): // access (ll)round(x[i].real())
1.4 Miller-Rabin + Pollard-Rho
//Prove By Solving - https://www.acmicpc.net/problem/4149
namespace miller_rabin{
   lint mul(lint x, lint y, lint mod){ return (__int128) x * y % mod; }
 lint ipow(lint x, lint y, lint p){
   lint ret = 1, piv = x \% p:
   while(v){
     if(v&1) ret = mul(ret, piv, p);
     piv = mul(piv, piv, p);
     y >>= 1;
   return ret;
 bool miller_rabin(lint x, lint a){
   if(x % a == 0) return 0;
   lint d = x - 1;
   while(1){
     lint tmp = ipow(a, d, x);
     if(d&1) return (tmp != 1 && tmp != x-1);
     else if(tmp == x-1) return 0;
     d >>= 1;
   }
 }
 bool isprime(lint x){
   for(auto &i : {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37}){
     if(x == i) return 1;
     if (x > 40 \&\& miller rabin(x, i)) return 0:
   if(x <= 40) return 0;
   return 1:
 }
namespace pollard_rho{
 lint f(lint x, lint n, lint c){
   return (c + miller_rabin::mul(x, x, n)) % n;
 void rec(lint n, vector<lint> &v){
   if(n == 1) return;
   if(n \% 2 == 0){
     v.push back(2):
     rec(n/2, v);
     return;
   }
   if(miller_rabin::isprime(n)){
```

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};

```
v.push_back(n);
      return:
    }
    lint a, b, c;
    while(1){
     a = rand() \% (n-2) + 2;
      b = a;
      c = rand() \% 20 + 1;
       a = f(a, n, c);
       b = f(f(b, n, c), n, c);
      }while(gcd(abs(a-b), n) == 1);
      if(a != b) break:
    lint x = gcd(abs(a-b), n);
    rec(x, v):
    rec(n/x, v);
  vector<lint> factorize(lint n){
    vector<lint> ret;
    rec(n. ret):
    sort(ret.begin(), ret.end());
    return ret;
 }
};
```

2 Geometry

2.1 struct Point

```
template <class T>
struct point{
   typedef point P;
   T x, y;
   point(T x=0, T y=0) : x(x), y(y) {}
   bool operator< (P a) const { return x != a.x ? x < a.x : y < a.y;}
    bool operator== (P a) const {return x == a.x and y == a.y;}
    P operator+ (P a) const {return P(x+a.x, y+a.y);}
   P operator- (P a) const {return P(x-a.x, y-a.y);}
   P operator- () const {return P(-x, -y);};
    T operator* (P a) const {return x*a.x + y*a.y;} // inner prod
    T operator/ (P a) const {return x*a.y - y*a.x;} // outer prod
   T dist2() const {return x*x + y*y;}
    double dist() const {return sqrt(double(dist2()));}
   P perp() const {return P(-y, x);}; // rotate 90 deg ccw
   P mult(T t) const {return P(x*t, v*t);}
   P unit() const {return P(x/dist(), y/dist());}
   P rotate(double a){
        return P(x*cos(a)-y*sin(a), x*sin(a)+y*cos(a));
    }
```

```
2.1.1 Sorting Points by Angle
// credit : http://koosaga.com/97
```

```
// credit : http://koosaga.com/97
auto angle_sort = [&](const point &a, const point &b){
   if((a > point(0, 0)) ^ (b > point(0, 0))) return a > b;
   if(a / b != 0) return a / b > 0;
   return a.dist() < b.dist(); // norm
}; // clockwise sort</pre>
```

2.2 Intersections

벡터 내적 외적 이용하면 생각보다 간단 / 선분은 예외처리가 좀 많음 Should be added.

- 2.2.1 Line-Line intersection
- 2.2.2 Line-Segment intersection
- 2.2.3 Segment-Segment Intersection
- 2.2.4 Circle-Line Intersection
- 2.3 Projection, Reflection

Should be added.

2.4 Convex Hull

```
vector<pll> get_CV(vector<pll> V){
    sort(V.begin(), V.end());
   sort(V.begin() + 1, V.end(), [&](pll x, pll y){
        pll xx = x - V[0];
        pll yy = y - V[0];
        11 \text{ res} = xx / vv:
        if(res != 0) return res > 0;
        if(xx.first != yy.first) return xx.first < yy.first;</pre>
        return xx.second < yy.second;</pre>
   });
   vector<pll> ret;
   for(auto val : V){
        while(ret.size() > 1){
            pll xx = ret[ret.size() - 2] - val;
            pll yy = ret[ret.size() - 1] - val;
            if(xx / yy <= 0) ret.pop_back();</pre>
            else break:
        ret.push_back(val);
   }
```

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```
return ret;
}
      Rotating Calipers
void rotating_calipers(vector<pll> CV){
    int pos = 0;
    for(int i = 0 ; i < CV.size() ; i++) if(CV[pos] < CV[i]) pos = i;</pre>
    int ind1 = 0, ind2 = pos;
    11 dist = (CV[ind1] - CV[ind2]) * (CV[ind1] - CV[ind2]);
    auto get_v = [\&](int x) { return CV[(x + 1) \% CV.size()] - <math>CV[x];};
    for(int i = 0 ; i < CV.size() ; i++){</pre>
        pll v = get_v(i);
        while((-v) / get_v(pos) < 0) pos = (pos + 1) % CV.size();
        11 tmp_dist = (CV[pos] - CV[i]) * (CV[pos] - CV[i]);
        if(dist < tmp_dist) {</pre>
            dist = tmp_dist;
            ind1 = i; ind2 = pos;
        }
    }
    printf("%lld %lld %lld %lld\n", CV[ind1].first, CV[ind1].second, CV[ind2].first,
    CV[ind2].second);
}
     Smallest Enclosing Circle
//Prove By Solving - https://www.acmicpc.net/problem/11930
int main(){
    scanf("%d", &N);
    for(int i = 1; i \le N; i++) scanf("%lf%lf", &A[i].x, &A[i].y, &A[i].z);
    int t = 70000:
    double rate = 1.0;
    point cur = (point)\{0, 0, 0\};
    for(int i = 1 : i \le t: i++){}
        int ind = 1;
        for(int j = 1; j \le N; j++) if((A[j] - cur) * (A[j] - cur) > (A[ind] -
        cur) * (A[ind] - cur)) ind = j;
        cur = cur + (A[ind] - cur) * rate;
        rate *= 0.99:
    }
```

for(int i = 1; $i \le N$; $i \leftrightarrow r = max(r, (A[i] - cur) * (A[i] - cur));$

double r = 0:

return 0;

}

cout << sqrt(r);</pre>

2.7 Polygon Area

Should be added.

- 2.7.1 Polygon Area
- 2.7.2 Polygon Overlapping
- 3 Strings

3.1 Aho-Corasick Algorithm

```
namespace aho {
   const int N = 4000000, C = 2;
   int trans[N][C];
   int lst = 1;
   int fail[N];
   int term[N]:
   void build(const vector<string> &v) {
       rep(i, sz(v)) {
           int s = 0;
           repi(j, v[i]) {
               int &t = trans[s][j=='o'];
               if (!t) t = lst++;
               s = t;
            term[s] = i+1;
        queue<int> q; rep(i, C) if (trans[0][i]) q.push(trans[0][i]);
        while(sz(q) > 0) {
           int t = q.front(); q.pop();
           rep(i, C) if (trans[t][i]) {
                int p = fail[t]:
                while(p and !trans[p][i]) p = fail[p];
                p = trans[p][i];
                fail[trans[t][i]] = p;
                assert(term[p] == 0);
                q.push(trans[t][i]);
           }
   bool query(string &s){
     int p = 0;
     for(auto &i : s){
        while(p and !trans[p][i]) p = fail[p];
       p = trans[p][i];
       if(term[p]) return 1;
     return 0;
```

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```
3.2
      Suffix Array
vector<int> make_sa(const string& s) {
    int n = s.length();
    int lim = max(128, n+1);
    vector<int> sa(n), g(n+1), ng(n+1);
    for(int i=0:i<n:i++) {</pre>
        sa[i] = i;
        g[i] = s[i];
    }
    g[n] = 0;
    for(int t=1;t<s.length();t<<=1)</pre>
        auto cmp = [&] (int a, int b) {
            return g[a] != g[b] ? g[a] < g[b] : g[a+t] < g[b+t];
        vector<int> cnt(lim), ind(lim+1);
        for(int i=0;i<n;i++) cnt[g[min(i+t, n)]]++;</pre>
        for(int i=1;i<lim;i++) cnt[i] += cnt[i-1];</pre>
        for(int i=n-1;i>=0;i--) ind[--cnt[g[min(i+t, n)]]] = i;
        for(int i=0;i<lim;i++) cnt[i] = 0;</pre>
        for(int i=0; i< n; i++) cnt[g[i]]++; // same as cnt[g[ind[i]]]++
        for(int i=1:i<lim:i++) cnt[i] += cnt[i-1]:</pre>
        for(int i=n-1;i>=0;i--) sa[--cnt[g[ind[i]]]] = ind[i];
        ng[sa[0]] = 1;
        for(int i=1;i<n;i++) {</pre>
            ng[sa[i]] = ng[sa[i-1]];
            if(cmp(sa[i-1], sa[i])) ng[sa[i]]++;
        }
        g = ng;
    }
    return sa;
}
vector<int> make_lcp(const string& s, const vector<int>& sa) {
    int n = s.length():
    vector<int> lcp(n-1), rank(n);
    for(int i=0:i<n:i++)</pre>
        rank[sa[i]] = i;
    int len = 0:
    for(int i=0;i<n;i++) {</pre>
        if(rank[i]) {
            int j = sa[rank[i]-1];
            int lc = n - max(i,i):
            while(len < lc && s[i+len] == s[j+len]) len++;
            lcp[rank[i]-1] = len;
```

}

if(len) len--;

```
}
   return lcp;
/* str : abracadabra
* SA : 10 7 0 3 5 8 1 4 6 9 2
 * LCP : 1 4 1 1 0 3 0 0 0 2
3.3 Manacher's Algorithm
vector<int> manacher(const string& s) {
   vector<int> x(s.length());
    int r = -1, p = -1;
   for(int i=0;i<s.length();i++) {</pre>
        if(i \le r) x[i] = min(r-i, x[2*p-i]);
        while (x[i]+1 \le i \&\& i+x[i]+1 \le s.length() \&\&
            s[i-x[i]-1] == s[i+x[i]+1])
                x[i]++;
        if(i + x[i] > r)
           r = i + x[i], p = i;
   }
    return x;
}
3.4 Z Algorithm
// 0-base
// input : a b c a b a b c a
// output : 9 0 0 2 0 4 0 0 1
vector<int> z_algo(const string &s) {
   int 1 = 0, r = 0, N = sz(s);
   vector<int> Z(N):
   Z[0] = N:
   repp(i, 1, N) {
        if (i > r) {
           1 = r = i;
            while(r < N and s[r] == s[r-1]) r++;
            Z[i] = r-1+1;
        } else {
            int k = i-1:
            if (Z[k] < r-i+1) Z[i] = Z[k];
            else {
               1 = i;
                while(r < N \text{ and } s[r] == s[r-1]) r++;
                Z[i] = r-l+1;
           }
        }
```

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```
return Z;
}
```

3.5 Lexicographically Smallest String Rotation

```
// rotate(v.begin(), v.begin()+min_rotation(v), v.end());
int min_rotation(string s) {
   int a=0, N=sz(s); s += s;
   rep(b,0,N) rep(i,0,N) {
      if (a+i == b || s[a+i] < s[b+i]) {b += max(0, i-1); break;}
      if (s[a+i] > s[b+i]) { a = b; break; }
   }
   return a;
}
```

4 Graph Theory

4.1 Strongly Connected Component

```
vector<int> adj[MAX_V];
int finished[MAX];
int dfsn[MAX_V];
int cnt = 1;
vector<vector<int>> SCC;
stack<int> s:
int dfs(int cur) {
    dfsn[cur] = cnt++:
    s.push(cur);
    int res = dfsn[cur]:
   for (int n : adj[cur]) {
       if (!dfsn[n]) res = min(res, dfs(n));
        else if (!finished[n]) res = min(res, dfsn[n]);
   }
   if (res == dfsn[cur]) {
       vector<int> sub:
       int t = -1;
        do {
            t = s.top(); s.pop();
            finished[t] = 1;
            sub.push_back(t);
       } while (t != cur);
       SCC.push_back(sub);
   }
    return res;
```

4.2 2-SAT

Should be added.

4.3 Biconnected Component

Should be added.

4.4 Euler Tour

```
struct Edge{
    int to, cnt; // to: 인접한 정점, cnt: 남은 사용 횟수
    Edge *dual; // dual: 역방향 간선을 가리키는 포인터
    Edge(): Edge(-1, 0){}
    Edge(int to1, int cnt1): to(to1), cnt(cnt1), dual(nullptr){}
};

void Eulerian(int curr){
    for(Edge *e: adj[curr]){
        if(e->cnt > 0){
            e->cnt--;
            e->dual->cnt--;
            Eulerian(e->to); // dfs
        }
    }
    cout << curr << '\n';
}
```

4.5 Offline Dynamic Connectivity

Should be added.

4.6 Heavy-Light Decomposition

Should be added.

4.7 Dominator Tree

Should be added.

4.8 Negative Cycle Detection

Should be added.

4.9 Tree Compress

Should be added.

5 Network Flow

5.1 Theorems

Should be added.LR-flow and bunch of theories?

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5.2 Dinic's Algorithm

```
const int INF = 1e9;
struct Dinic{
   int N;
    struct edge{
       int index, cap, rev;
       edge(): index(0), cap(0), rev(0) {}
       edge(int index, int cap, int rev) : index(index), cap(cap), rev(rev) {}
   };
    vector<vector<edge>> ADJ:
    vector<int> R, W;
   Dinic() {}
   Dinic(int N) : N(N){
        ADJ.resize(N): R.resize(N):
                                        W.resize(N):
   }
   void CE(int node1, int node2, int cap){
        ADJ[node1].push_back(edge(node2, cap, ADJ[node2].size()));
        ADJ[node2].push_back(edge(node1, 0, ADJ[node1].size() - 1));
   }
   bool bfs(int src, int sink){
       for(int i = 0; i < R.size(); i++) R[i] = -1;
       R[src] = 0;
       queue<int> Q; Q.push(src);
        while(Q.size()){
           int here = Q.front(); Q.pop();
           for(auto e : ADJ[here]){
                if (e.cap > 0 \&\& R[e.index] == -1) R[e.index] = R[here] + 1,
                Q.push(e.index);
           }
       }
       return R[sink] != -1:
   }
    int dfs(int here, int sink, int f){
        if(here == sink) return f;
       for(int &i = W[here] ; i < ADJ[here].size() ; i++){</pre>
           auto &e = ADJ[here][i];
           if(e.cap > 0 && R[here] < R[e.index]){
               int res = dfs(e.index, sink, min(f, e.cap));
               if(res) {
                    e.cap -= res;
                    ADJ[e.index][e.rev].cap += res;
                    return res;
               }
           }
```

```
return 0;
   }
   int solve(int src, int sink){
       int ret = 0:
        while(bfs(src, sink)){
           for(int i = 0; i < N; i++) W[i] = 0;
           int res:
           while((res = dfs(src, sink, INF))) ret += res;
       return ret;
   }
};
5.3 MCMF with SPFA
 Should be revised.
struct MCMF {
 struct Edge {
   int to, cap, cost, rev;
   Edge(int to, int cap, int cost) : to(to), cap(cap), cost(cost) {}
 }:
 int N, src, sink;
 vector<vector<Edge>> G;
 vector<long long> dist;
 vector<pair<int, int>> P;
 vector<bool> InQ;
 MCMF(int N, int src, int sink) : N(N), src(src), sink(sink) {
   G.resize(N):
   dist.resize(N);
   P.resize(N);
   InQ.resize(N);
 void add_edge(int f, int t, int cap, int cost) {
   G[f].emplace_back(t, cap, cost);
   G[t].emplace_back(f, 0, -cost);
   G[f].back().rev = G[t].size() - 1;
   G[t].back().rev = G[f].size() - 1;
 void add_edge_from_source(int t, int cap, int cost) {
   add_edge(src, t, cap, cost);
 void add_edge_to_sink(int f, int cap, int cost) {
   add_edge(f, sink, cap, cost);
 pair<long long,long long> flow() {
   pair<long long, long long> ret;
   queue<int> Q;
   for (;;) {
     long long flow = 0x7ffffffffffffffLL;
```

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```
fill(dist.begin(), dist.end(), 0x7fffffffffffffffLL);
      fill(P.begin(), P.end(), make_pair(-1, -1));
      dist[src] = 0:
      Q.push(src);
      while (!Q.emptv()) {
       int c = Q.front();
        Q.pop();
        InQ[c] = false;
        for (int i = 0; i < G[c].size(); i++) {</pre>
         auto &e = G[c][i];
          if (e.cap > 0 && dist[e.to] > dist[c]+ e.cost) {
            dist[e.to] = dist[c] + e.cost;
           P[e.to] = make_pair(c, i);
            if (!InQ[e.to]) {
             InQ[e.to];
              Q.push(e.to);
         }
       }
      for (int now = sink: P[now].first != -1: now = P[now].first) {
        auto &e = G[P[now].first][P[now].second];
        flow = min(flow, 1LL*e.cap);
      for (int now = sink; P[now].first != -1; now = P[now].first) {
        auto &e = G[P[now].first][P[now].second];
        e.cap -= flow:
        G[e.to][e.rev].cap += flow;
       ret.second += e.cost*flow:
      ret.first += flow;
    }
    return ret;
 }
};
5.4 Hungarian Method
namespace Hung {
    const int MX = 2000;
    // IMPORTANT : n <= m, 1-based</pre>
    using T = long double;
    T \max v = 1e200:
    T a[MX][MX], n, m;
    void init(int nn, int mm) { n = nn: m = mm: }
    void set_value(int x, int y, T val) { a[x][y] = val; }
    T solve(vector <int> &ans) {
        vectorT> v(m+1), u(n+1);
```

vector $\langle int \rangle$ p (m+1), way (m+1);

```
for (int i=1; i<=n; ++i) {
           p[0] = i;
            int j0 = 0;
            vector<T> minv (m+1, maxv);
            vector<char> used (m+1, false):
            do {
                used[j0] = true;
                T delta = maxv:
                int i0 = p[i0], i1;
                for (int j=1; j<=m; ++j) if (!used[j]) {</pre>
                    T cur = a[i0][j]-u[i0]-v[j];
                    if (cur < minv[j]) {</pre>
                        minv[j] = cur, way[j] = j0;
                    if (minv[j] < delta) {</pre>
                        delta = minv[j], j1 = j;
                for (int j=0; j<=m; ++j) {
                    if (used[i]) {
                        u[p[j]] += delta, v[j] -= delta;
                    }
                    else {
                        minv[j] -= delta;
                }
                j0 = j1;
           } while (p[j0] != 0);
            do {
                int j1 = way[j0];
                p[j0] = p[j1];
                j0 = j1;
           } while (i0);
        ans.resize(n + 1);
        for(int j=1; j<=m;++j) {</pre>
            ans[p[j]] = j;
        return -v[0];
   }
}
5.5 Hopcroft-Karp Algorithm
struct hopcroft_karp{
   int N;
   vector<vector<int>> ADJ:
   vector<int> L, rev, used;
   hopcroft_karp() {}
   hopcroft_karp(int N) : N(N) {
```

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```
ADJ.resize(N);
   L.resize(N), rev.resize(N, -1), used.resize(N, 0);
}
void CE(int here, int there){
    ADJ[here].push_back(there);
}
void bfs(){
    queue<int> Q;
   for(int i = 0 ; i < N ; i++) {</pre>
        if(used[i]) L[i] = -1;
        else L[i] = 0, Q.push(i);
   }
    while(Q.size()){
        int here = Q.front(); Q.pop();
        for(int there : ADJ[here]){
            if(rev[there] != -1 && L[rev[there]] == -1) {
                L[rev[there]] = L[here] + 1;
                Q.push(rev[there]);
           }
        }
   }
}
bool dfs(int here){
   for(int there : ADJ[here]){
        if(rev[there] == -1 || (L[here] < L[rev[there]] && dfs(rev[there]))){
            rev[there] = here;
            used[here] = 1;
            return true;
       }
   }
   return false;
}
int solve(){
   int ret = 0;
    while(1){
        bfs();
        int res = 0;
        for(int i = 0 ; i < N ; i++) {
            if(used[i]) continue;
            res += dfs(i):
        if(res == 0) break;
        ret += res:
    return ret;
```

```
};
    Optimization Tricks
6.1 Knuth Optimization
  • Recurrence : D[i][j] = \min_{i < k < j} (D[i][k] + D[k][j]) + C[i][j]
 • Quadrangle Inequality : C[a][c] + C[b][d] \le C[a][d] + C[b][c], \ a \le b \le c \le d
  • Monotonicity : C[b][c] \le C[a][d], \ a \le b \le c \le d
  • A[i][j] = (\min k \ s.t. \ D[i][j] \ \text{is min.}). Then A[i][j-1] \le A[i][j] \le A[i+1][j]
  • O(N^2) time complexity
// opt[i-1][i] = i
for(int d=2;d<=n;d++) {</pre>
    for(int i=1;i+d<=n+1;i++) {</pre>
         for(int k=opt[i][j-1], j=i+d; k<=opt[i+1][j]; k++) {</pre>
             int v = dp[i][k] + dp[k][j] + c[i][j];
             if(dp[i][j] > v) dp[i][j] = v, opt[i][j] = k;
    }
}
6.2 Divide and Conquer Optimization
  • Recurrence : D[t][i] = \min_{k < i} (D[t-1][k] + C[k][i])
  • Min index : A[t][i] < A[t][i+1] (A[t][i] = (\min. k \ s.t. \ D[t][i] \text{ is min.}))
         [-] Quadrangle Inequality : C[a][c] + C[b][d] \le C[a][d] + C[b][c], \ a \le b \le c \le d
  • Able to Divide and Conquer base on calculating D[t][i]
  • O(TN \lg N) time complexity
// range of index : [1,r]
// range of dp : [s,e]
```

void dnc(int t, int l, int r, int s, int e)

int tmp = D[t-1][k] + C[k][m];

dnc(t, 1, A[t][m], s, D[t][m]-1);
dnc(t, A[t][m], r, D[t][m]+1, e);

D[t][m] = tmp, A[t][m] = k;

if(s > e) return;

for(int k=1;k<m&&k<=r;k++)</pre>

if(D[t][m] > tmp)

int m = (s+e)/2;
D[t][m] = 2e9:

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6.3 Convex Hull Trick

- Recurrence: $dp[i] = \min_{j < i} (dp[j] + a[i]b[j]), b[i-1] \le b[i]$
- Think as $dp[x = a[i]] = \min_{j < i} (b[j] \cdot x + dp[j])$
- Thus push lines and find minimum (by binary search)
- If a[i] < a[i+1] sweeping is possible
- Intersection of $y = a_i x + b_i$ and $y = a_{i+1} x + b_{i+1} : x = \frac{b_{i+1} b_i}{a_i a_{i+1}}$

6.4 Centroid Decomposition

```
// credit : https://gist.github.com/igorcarpanese/75162f3253bd230abd0f32f9950bf384
int dfs(int u, int p) {
    sub[u] = 1;
    for (auto v : tree[u])
        if (v != p) sub[u] += dfs(v, u);
    return sub[u] + 1;
}
int centroid(int u, int p, int r) { // r : root
    for (auto v : tree[u])
        if (v != p and sub[v] > sub[r]/2) return centroid(v, u);
    return u;
}
```

7 Data Structure

7.1 Persistent Segment Tree

```
Should be revised.
// credit : http://junis3.tistory.com/8
const int maxn = 1 << 17:
int root[maxn];
struct pst {
    int v[maxn*17], l[maxn*17], r[maxn*17], t:
    // create root[0]
    int base(int s. int e) {
        int k = t++:
        if (s<e) {
            int m = (s+e)/2;
           l[k] = base(s, m);
            r[k] = base(m+1, e);
        }
        return k;
    }
    // make tree from root bef, position 'pos' with value 'val'
    int make(int bef, int s, int e, int pos, int val) {
```

```
if (pos<s or e<pos) return bef;
        int k = t++:
        if (s==e) {
            v[k] = v[bef] + val;
        } else {
            int m = (s+e)/2;
           1[k] = make(1[bef], s, m, pos, val);
           r[k] = make(r[bef], m+1, e, pos, val);
           v[k] = v[l[k]] + v[r[k]];
        } return k:
   }
    // gets sum from root k where index is from 1 to r (inclusive)
    int query(int k, int s, int e, int x, int y) {
        if (x<=s and e<=y) return v[k];
        else if (e<x or y<s) return 0;
        else {
            int m = (s+e)/2;
            return query(l[k], s, m, x, y) + query(r[k], m+1, e, x, y);
   }
} t;
7.2 Link-Cut Tree
struct node{
    node *pp, *p, *l, *r;
    int val;
   node(){p = 0, 1 = 0, r = 0;}
   node(int val) : val(val) \{ p = 0, 1 = 0, r = 0; \}
};
void push(node *x){}
void pull(node *x){}
void rotate(node *x){
 if(!x->p) return:
 push(x->p); // if there's lazy stuff
 push(x);
 node *p = x->p:
 bool is_left = (p->1 == x);
 node *b = (is_left ? x->r : x->1);
 x->p = p->p;
  if(x-p \&\& x-p->1 == p) x-p->1 = x;
  if(x-p \&\& x-p-r == p) x-p-r = x;
 if(is_left){
   if(b) b->p = p;
   p\rightarrow 1 = b:
   p->p = x;
   x->r = p;
 }
  else{
```

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```
if(b) b \rightarrow p = p;
    p->r = b;
   p->p = x;
   x->1 = p;
  pull(p); // if there's something to pull up
 pull(x);
  //if(!x->p) root = x; // IF YOU ARE SPLAY TREE
  if(p->pp){ // IF YOU ARE LINK CUT TREE
   x->pp = p->pp;
    p->pp = nullptr;
void splay(node *x){
  while(x->p){
   node *p = x->p;
    node *g = p->p;
    if(g){
      if((p->1 == x) ^ (g->1 == p)) rotate(x);
      else rotate(p);
    }
    rotate(x);
}
void access(node *x){
  splay(x);
  push(x);
  if(x->r){
   x->r->pp = x;
   x->r->p = nullptr;
    x->r = nullptr;
 }
  pull(x);
  while(x->pp){
   node *nxt = x->pp;
    splay(nxt);
    push(nxt);
    if(nxt->r){
     nxt->r->pp = nxt;
     nxt->r->p = nullptr;
      nxt->r = nullptr;
    }
    nxt->r = x;
    x->p = nxt;
    x->pp = nullptr;
    pull(nxt);
    splay(x);
}
node *root(node *x){
```

```
access(x);
 while(x->1){
   push(x);
   x = x->1;
 access(x);
 return x;
node *par(node *x){
 access(x);
 if(!x->1) return nullptr;
 push(x);
 x = x \rightarrow 1;
 while(x->r){
   push(x);
   x = x->r;
 access(x);
 return x;
node *lca(node *s, node *t){
 access(s);
 access(t);
 splay(s);
 if(s->pp == nullptr) return s;
 return s->pp;
void link(node *par, node *son){
 access(par);
 access(son);
 //son->rev ^= 1; // remove if needed
 push(son);
 son->1 = par;
 par->p = son;
 pull(son);
void cut(node *p){
 access(p);
 push(p);
 if(p->1){
   p->1->p = nullptr;
   p->1 = nullptr;
 pull(p);
```

7.3 Li-Chao Tree

Should be added....?

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7.4 Dynamic Convex Hull

```
// https://github.com/niklasb/contest-algos/blob/master/convex_hull/dynamic.cpp
const ll is_query = -(1LL<<62);</pre>
struct Line {
    ll m, b;
    mutable function<const Line*()> succ;
    bool operator<(const Line& rhs) const {</pre>
        if (rhs.b != is_query) return m < rhs.m;</pre>
        const Line* s = succ();
        if (!s) return 0;
        11 x = rhs.m;
        return b - s->b < (s->m - m) * x:
    }
};
struct HullDynamic : public multiset<Line> { // will maintain upper hull for maximum
    bool bad(iterator y) {
        auto z = next(y);
        if (v == begin()) {
            if (z == end()) return 0;
            return y->m == z->m && y->b <= z->b;
        auto x = prev(y);
        if (z == end()) return y \rightarrow m == x \rightarrow m && y \rightarrow b <= x \rightarrow b;
        return (x->b - y->b)*(z->m - y->m) >= (y->b - z->b)*(y->m - x->m);
    }
    void insert_line(ll m, ll b) {
        auto y = insert({ m, b });
        y->succ = [=] { return next(y) == end() ? 0 : &*next(y); };
        if (bad(y)) { erase(y); return; }
        while (next(y) != end() && bad(next(y))) erase(next(y));
        while (y != begin() && bad(prev(y))) erase(prev(y));
    }
    ll eval(ll x) {
        auto 1 = *lower_bound((Line) { x, is_query });
        return 1.m * x + 1.b;
    }
};
```

7.5 Stern-Brocot Tree

Should be added.

7.6 Rope

Should be added.

7.7 Policy Based Data Structure

8 Miscellaneous

8.1 Misc Formulae and Algorithms

8.1.1 Faulhaber's Formula

$$T(n,k) = \sum_{i=1}^{n} i^{k} = \frac{(n+1)^{k+1} - 1^{k+1} - \sum_{j=0}^{k-1} {k+1 \choose j} T(n,j)}{{k+1 \choose k}}$$

Also use

$$(x+1)^d - x^d = 1 + {d \choose 1}x + {d \choose 2}x^2 + \dots + {d \choose d-1}x^{d-1}$$

to get each coef.

8.1.2 Maximum Clique

Should be added....?

8.1.3 De Brujin Sequence

Should be **added**....?

8.2 Highly Composite Numbers, Large Prime

< 10^	k number	di	ivisors	2 3 5 71113171923293137
 1	6		4	1 1
2	60		12	2 1 1
3	840		32	3 1 1 1
4	7560		64	3 3 1 1
5	83160		128	3 3 1 1 1
6	720720		240	4 2 1 1 1 1
7	8648640		448	6 3 1 1 1 1
8	73513440		768	5 3 1 1 1 1 1
9	735134400		1344	6 3 2 1 1 1 1
10	6983776800		2304	5 3 2 1 1 1 1 1
11	97772875200		4032	6 3 2 2 1 1 1 1
12	963761198400		6720	6 4 2 1 1 1 1 1 1
13	9316358251200		10752	6 3 2 1 1 1 1 1 1 1
14	97821761637600		17280	5 4 2 2 1 1 1 1 1 1
15	866421317361600		26880	6 4 2 1 1 1 1 1 1 1 1
16	8086598962041600		41472	8 3 2 2 1 1 1 1 1 1 1
17	74801040398884800		64512	6 3 2 2 1 1 1 1 1 1 1 1
18 8	97612484786617600		103680	8 4 2 2 1 1 1 1 1 1 1 1
< 10^	k prime # of	-		-
1	7	4		10 999999967
2	97	25		11 9999999977

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```
997
                                        12
                           168
                                                    99999999999
  4
             9973
                          1229
                                        13
                                                   999999999971
            99991
                          9592
                                        14
                                                  999999999973
           999983
                         78498
                                        15
                                                 99999999999989
          9999991
                        664579
                                        16
                                                99999999999937
         9999989
                       5761455
                                        17
                                               999999999999997
        99999937
                      50847534
                                        18
                                             9999999999999989
NTT Prime:
  469762049 = 7 \times 2^{26} + 1. Primitive root : 3.
 998244353 = 119 \times 2^{23} + 1. Primitive root: 3.
 985661441 = 235 \times 2^{22} + 1. Primitive root: 3.
  1012924417 = 483 \times 2^{21} + 1. Primitive root: 5.
8.3 Fast Integer IO
// credit : https://github.com/koosaga/DeobureoMinkyuParty/blob/master/teamnote.tex
static char buf[1 << 19]: // size : any number geg than 1024
static int idx = 0;
static int bytes = 0:
static inline int _read() {
  if (!bytes || idx == bytes) {
   bytes = (int)fread(buf, sizeof(buf[0]), sizeof(buf), stdin);
    idx = 0;
  return buf[idx++]:
static inline int _readInt() {
  int x = 0, s = 1;
  int c = _read();
  while (c \le 32) c = read():
  if (c == '-') s = -1, c = _read();
  while (c > 32) x = 10 * x + (c - '0'), c = read():
  if (s < 0) x = -x:
  return x;
8.4 C++ Tips / Environments
 Should be revised.(with random, chrono)
#include <bits/stdc++.h> // magic header
using namespace std;
                       // magic namespace
struct StupidGCCCantEvenCompileThisSimpleCode{
  pair<int, int> array[1000000];
}; // https://gcc.gnu.org/bugzilla/show_bug.cgi?id=68203
// how to use rand (in 2017)
mt19937 rng(0xdeadbeef);
mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
int randint(int lb, int ub){ return uniform_int_distribution<int>(lb, ub)(rng); }
```

```
shuffle(permutation.begin(), permutation.end(), rng);
mt19937_64 _R(chrono::steady_clock::now().time_since_epoch().count()); // _R()
// comparator overload
auto cmp = [](seg a, seg b){return a.func() < b.func(): }:</pre>
set<seg, decltype(cmp)> s(cmp);
map<seg, int, decltype(cmp)> mp(cmp);
priority_queue<seg, vector<seg>, decltype(cmp)> pq(cmp); // max heap
// hash func overload
struct point{
int x, y;
bool operator==(const point &p)const{ return x == p.x && y == p.y; }
struct hasher {
size_t operator()(const point &p)const{ return p.x * 2 + p.y * 3; }
unordered_map<point, int, hasher> hsh;
// c++ setprecision example
                        // std::cout. std::fixed
#include <iostream>
#include <iomanip>
                        // std::setprecision
int main () {
 double f = 3.14159;
 std::cout << std::setprecision(5) << f << '\n'; // 3.1416
 std::cout << std::setprecision(9) << f << '\n': // 3.14159
 std::cout << std::fixed;</pre>
 std::cout << std::setprecision(5) << f << '\n': // 3.14159
 std::cout << std::setprecision(9) << f << '\n'; // 3.141590000
 return 0;
```