# Universidade de São Paulo Instituto de Física de São Carlos Mathematical-Computational Modeling

Genetic Algorithm

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# 1 Introduction

This project aims to solve the traveling salesman problem using the genetic algorithm. For this, several operators of genetic modification were considered, aiming thus, with the intuition of understanding its importance for minimizing the distance covered.

# 2 Cities

For analysis, points randomly distributed within a circle of radius 1 were chosen. Thus, each point represents a city to be covered by the traveler.

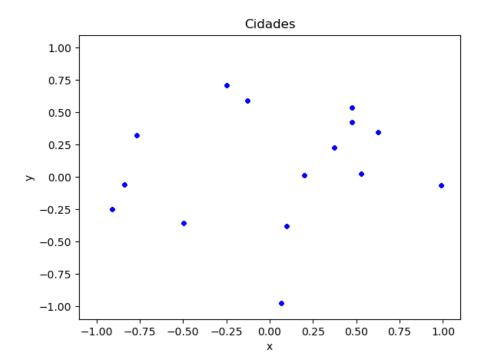


Figure 1

For each city a letter of the alphabet was assigned for identification.

```
i = City('i', -0.25046, 0.7103)
j = City('j', 0.62429, 0.34748)
k = City('k', 0.37447, 0.2277900)
l = City('l', 0.09789, -0.37945)
m = City('m', 0.19876000, 0.013430)
n = City('n', -0.90785, -0.24529)
o = City('o', 0.9890200, -0.0622200)
p = City('p', -0.13048, 0.5943700)
g = City('q', 0.47351000, 0.54068)
r = City('r', 0.47406000, 0.42436)
s = City('r', 0.49768000, -0.35516000)
t = City('t', 0.52642, 0.026430000)
u = City('u', 0.06719, -0.97528)
v = City('v', -0.8371000, -0.055650000)
w = City('w', -0.76578, 0.32402000)
```

Figure 2

# 3 Types of genetic modification

The genes were modified from some operators explained in the CDT-38. These operators are 'mutation', 'inversion', 'transposition', 'crossing-over'. Such operators are presented in the codes below, respectively:

```
def mutate(self, route_to_mut):
    ...
    Route() --> Route()
    Swaps two random indexes in route_to_mut.route. Runs k_mut_prob of the time
    ...
    # k_mut_prob %
    if random.random() < m_mut_prob:
        # two random indices:
        mut_pos1 = random.randint(0,len(route_to_mut.route)-1)
        mut_pos2 = random.randint(0,len(route_to_mut.route)-1)

        # if they're the same, skip to the chase
        if mut_pos1 == mut_pos2:
            return route_to_mut

        # Otherwise swap them:
        city1 = route_to_mut.route[mut_pos1]
        city2 = route_to_mut.route[mut_pos2]
        route_to_mut.route[mut_pos2] = city1
        route_to_mut.route[mut_pos1] = city2

# Recalculate the length of the route (updates it's .length)
        route_to_mut.recalc_rt_len()
        return route_to_mut</pre>
```

Figure 3: Mutation

```
def inversion(self, route_to_mut):
    if random.random() < i_mut_prob:
        # two random indices:
        mut_pos1 = random.randint(0,len(route_to_mut.route)-1)
        mut_pos2 = random.randint(0,len(route_to_mut.route)-1)

        # if they're the same, skip to the chase
        if mut_pos1 == mut_pos2:
            return route_to_mut

        route_to_mut.route[mut_pos1:mut_pos2] = route_to_mut.route[mut_pos1:mut_pos2][::-1]

    return route_to_mut</pre>
```

Figure 4: inversion

```
def transposition(self, route_to_mut):
    if random.random() < t_mut_prob:
        n= random.randint(0,(len(route_to_mut.route))//2)

# two random indices:
    mut_pos1 = random.randint(0,(len(route_to_mut.route)-1)//2-n)
    mut_pos2 = random.randint((len(route_to_mut.route)-1)//2,len(route_to_mut.route)-1-n)

# if they're the same, skip to the chase
    if mut_pos1 == mut_pos2:
        return route_to_mut

slice1 = route_to_mut.route[mut_pos1:mut_pos1+n]
    slice2 = route_to_mut.route[mut_pos2: mut_pos2+n]

route_to_mut.route[mut_pos1:mut_pos2+n]= slice2[:]
    route_to_mut.route[mut_pos2:mut_pos2+n]= slice1[:]

return route_to_mut</pre>
```

Figure 5: transposition

```
def crossover(self, parent1, parent2):
   Returns a child route Route() after breeding the two parent routes.
   Routes must be of same length.
   Breeding is done by selecting a random range of parent1, and placing it into the empty child route (in th
   Gaps are then filled in, without duplicates, in the order they appear in parent2.
   child_rt = Route()
   for x in range(0,len(child_rt.route)):
       child_rt.route[x] = None
   # Two random integer indices of the parent1:
   start_pos = random.randint(0,len(parent1.route))
   end_pos = random.randint(0,len(parent1.route))
   if start_pos < end_pos:</pre>
       for x in range(start_pos,end_pos):
           child_rt.route[x] = parent1.route[x] # set the values to eachother
   elif start_pos > end_pos:
       for i in range(end_pos,start_pos):
           child_rt.route[i] = parent1.route[i] # set the values to eachother
```

Figure 6: Crossing-over 1

Figure 7: Crossing-over 2

# 4 Genetic Algorithm

In order to find the best parameters for the traveling salesman problem, several values were tested for this problem. These sets will be handled by the representations below.

Parameters 
$$\rightarrow \left\{\phi_n, \ n=1, 2, ..., 8\right\}$$

### **4.1** $\phi_1$

$$\rightarrow \begin{cases} Number\ of\ generations = 100 \\ Number\ of\ population = 100 \\ Prob.\ of\ Mutation = 0.5 \\ Prob.\ of\ Inversion = 0.5 \\ Prob.\ of\ Transposition = 0.1 \\ Prob.\ of\ Crossing-over = 0.5 \end{cases}$$

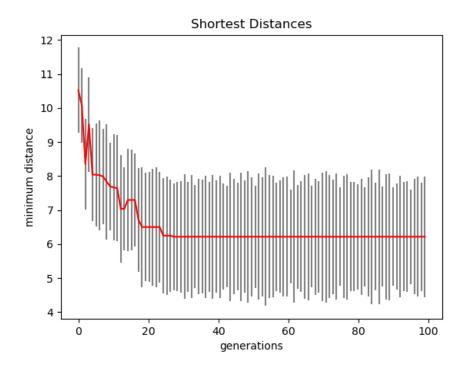


Figure 8

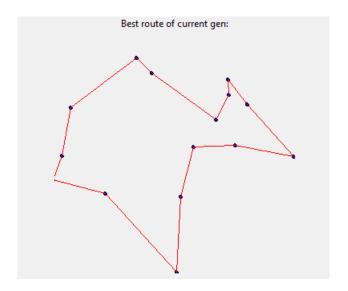


Figure 9

# **4.2** $\phi_2$

```
 \Rightarrow \begin{cases} Number\ of\ generations = 100 \\ Number\ of\ population = 50 \\ Prob.\ of\ Mutation = 0.3 \\ Prob.\ of\ Inversion = 0.5 \\ Prob.\ of\ Transposition = 0.4 \\ Prob.\ of\ Crossing - over = 0.1 \end{cases}
```

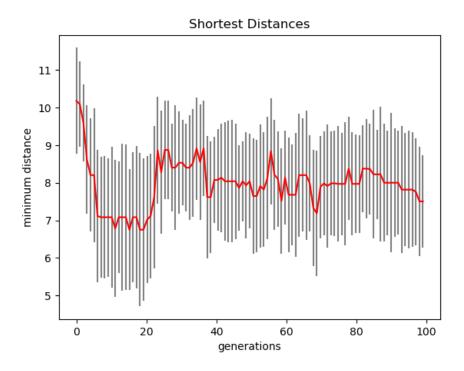


Figure 10

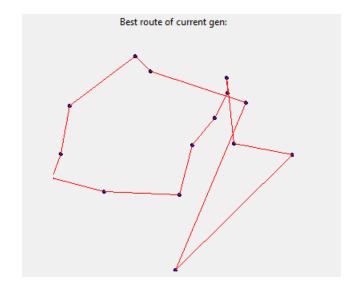


Figure 11

# **4.3** $\phi_3$

```
 \rightarrow \begin{cases} Number\ of\ generations = 100 \\ Number\ of\ population = 200 \\ Prob.\ of\ Mutation = 0.3 \\ Prob.\ of\ Inversion = 0.5 \\ Prob.\ of\ Transposition = 0.4 \\ Prob.\ of\ Crossing - over = 0.1 \end{cases}
```

### Shortest Distances minimum distance ò generations

Figure 12

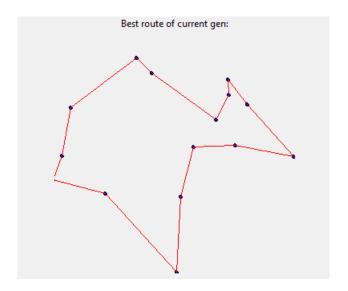


Figure 13

# **4.4** $\phi_4$

```
 \Rightarrow \begin{cases} Number\ of\ generations = 50 \\ Number\ of\ population = 200 \\ Prob.\ of\ Mutation = 0.3 \\ Prob.\ of\ Inversion = 0.3 \\ Prob.\ of\ Transposition = 0.2 \\ Prob.\ of\ Crossing - over = 0.3 \end{cases}
```

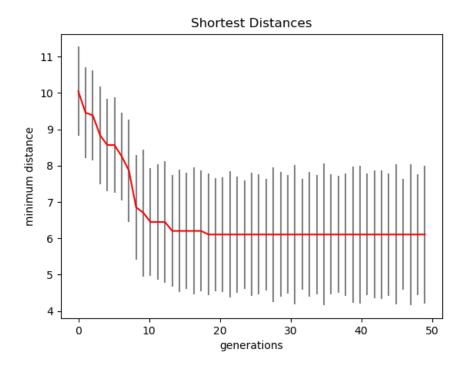


Figure 14

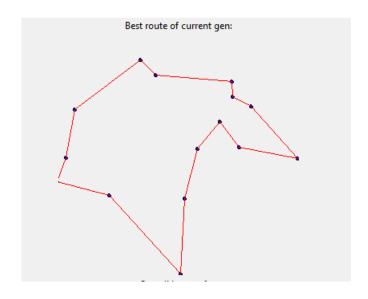


Figure 15

# **4.5** $\phi_5$

```
 \rightarrow \begin{cases} Number\ of\ generations = 100 \\ Number\ of\ population = 200 \\ Prob.\ of\ Mutation = 0.1 \\ Prob.\ of\ Inversion = 0.7 \\ Prob.\ of\ Transposition = 0.1 \\ Prob.\ of\ Crossing - over = 0.3 \end{cases}
```

# Shortest Distances 9 8 7 5 0 20 40 60 80 100

Figure 16

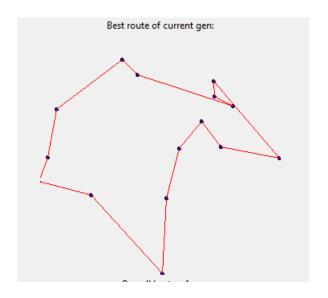


Figure 17

# **4.6** $\phi_6$

```
 \rightarrow \begin{cases} Number\ of\ generations = 100 \\ Number\ of\ population = 300 \\ Prob.\ of\ Mutation = 0.1 \\ Prob.\ of\ Inversion = 0.2 \\ Prob.\ of\ Transposition = 0.8 \\ Prob.\ of\ Crossing-over = 0.1 \end{cases}
```

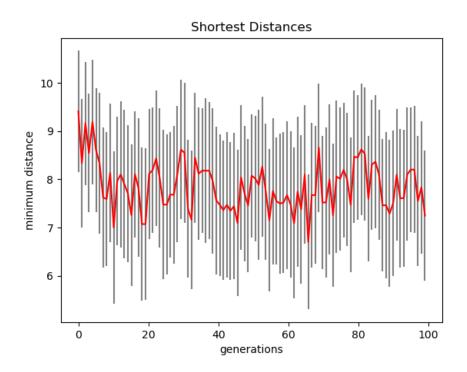


Figure 18

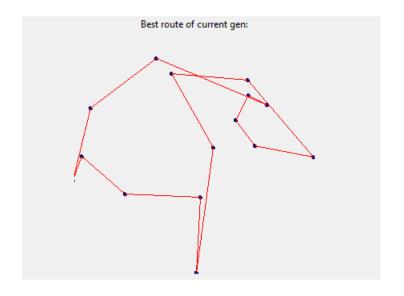


Figure 19

# **4.7** $\phi_7$

```
 \rightarrow \begin{cases} Number\ of\ generations = 100 \\ Number\ of\ population = 300 \\ Prob.\ of\ Mutation = 0.1 \\ Prob.\ of\ Inversion = 0.2 \\ Prob.\ of\ Transposition = 0.1 \\ Prob.\ of\ Crossing - over = 0.8 \end{cases}
```

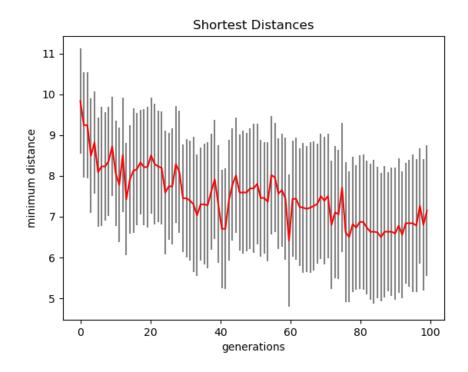


Figure 20

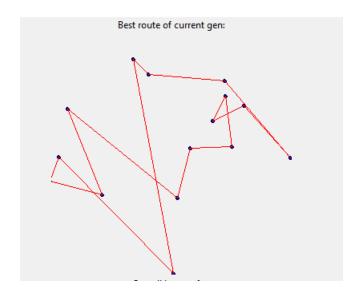


Figure 21

# **4.8** $\phi_8$

```
 \rightarrow \begin{cases} Number\ of\ generations = 100 \\ Number\ of\ population = 300 \\ Prob.\ of\ Mutation = 0.8 \\ Prob.\ of\ Inversion = 0.8 \\ Prob.\ of\ Transposition = 0.1 \\ Prob.\ of\ Crossing - over = 0.1 \end{cases}
```

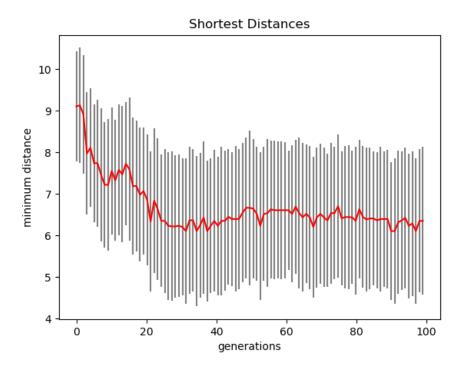


Figure 22

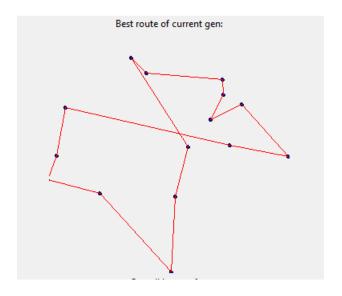


Figure 23

# 5 Conclusion

From the computational experiments performed, it becomes evident that operators such as 'transposition' and 'crossing-over' cannot be highly probable, since they involve the change of many crossomes. On the other hand, 'inversion' and 'mutation' even with their high probabilities over time tend to be the shortest path (as if they were a noise).

### 6 References

[1] da Silva, Éverton Luís Mendes. Codes and Images used in this project can be founded in my GItHub. ¡https://github.com/evertonmendes/Mathematical-Computational-Modeling;