

Universidade de São Paulo  
Instituto de Física de São Carlos  
Mathematical-Computational  
Modeling

## **Harmonic Signals**

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# 1 Introduction

In this project, signals corresponding to the sum of cosines according to the harmonic series will be analyzed, with a reference frequency set. For each signal, three types of component amplitude were used. Finally, a damped harmonic oscillator signal obtained from the Physics Laboratory 2 was studied.

## 2 Synthesized Signs

For a better analysis of these types of signals, two frequencies were used as a reference.

$$\begin{cases} f_1 = 10Hz \\ f_2 = 25Hz \end{cases}$$

For each one, the harmonic series up to grade 4 was used.

$$\begin{cases} n = 1, 2, 3, 4 \end{cases}$$

The signals were obtained using the formula below:

$$signal(t) = m(t) \sum_n \cos(2\pi f_n t) \quad (1)$$

Where  $m(t)$  can be one of the three functions below:

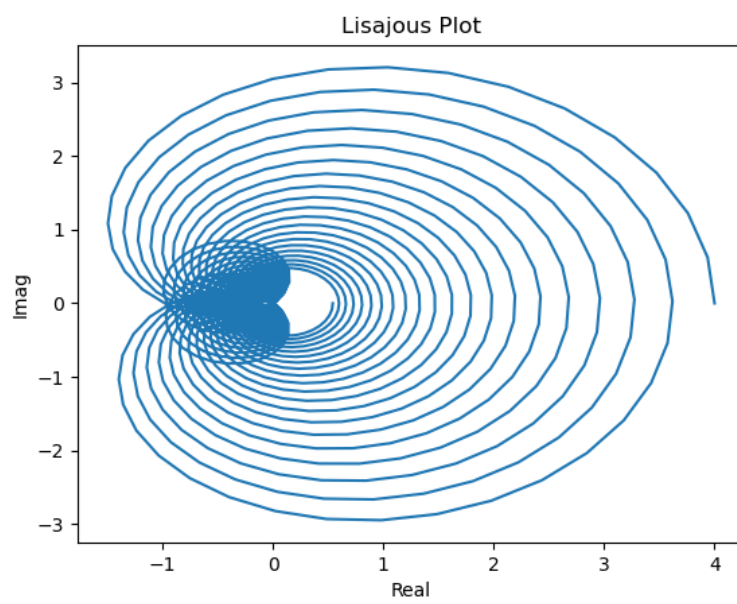
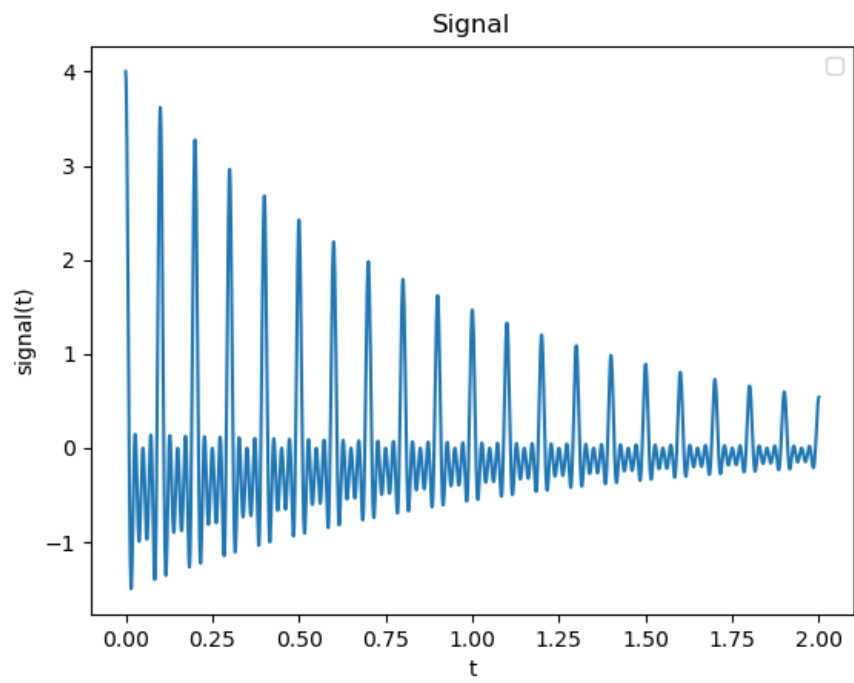
$$m(t) \begin{cases} f_1(t) = e^{-t} \\ f_2(t) = t^2 - t^3 \\ f_3(t) = t^2 - t^4 + t\cos(t) \end{cases}$$

## 3 Visualization of Signals

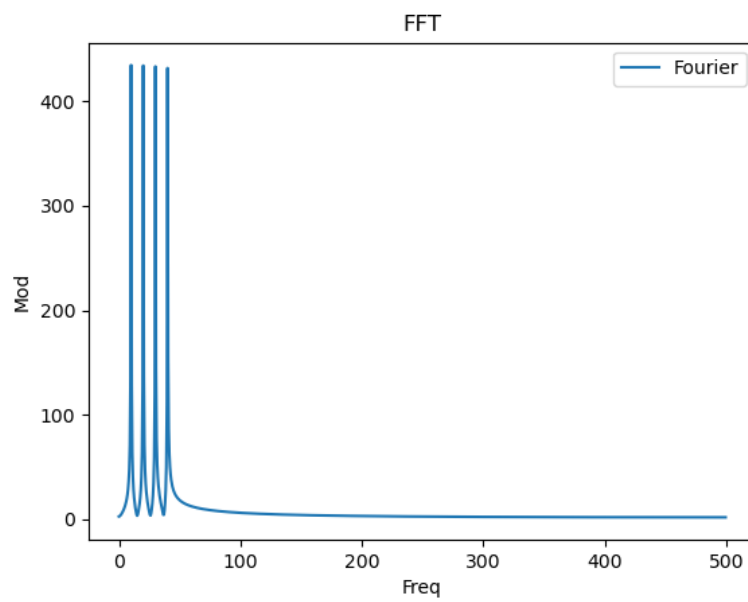
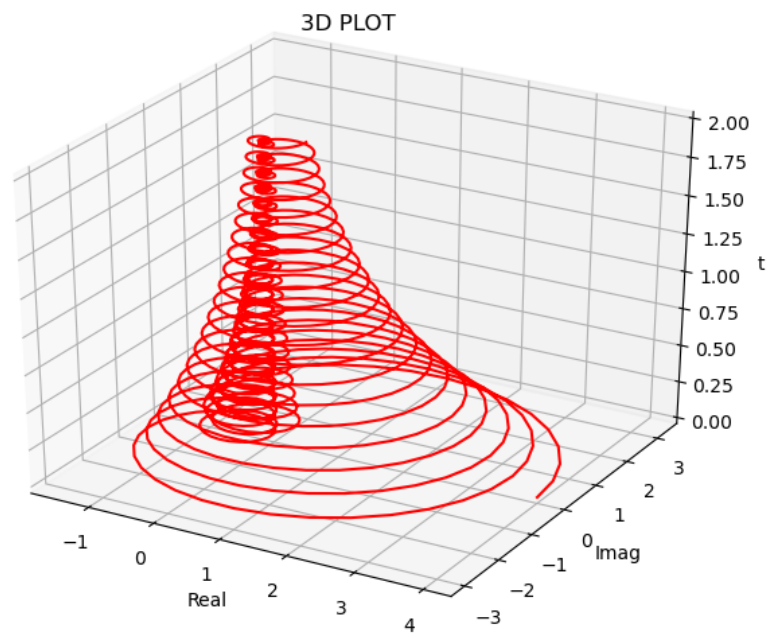
```
#function that returns a signal which is the sum of several cosines
def SignalCosine(m, freq, time=2, H=4):
    |
    |
    | signal=[]
    | signal1=[]
    | t=np.linspace(0,time, 2000)
    |
    | Hlist=[]
    | for i in range(H):
    |     | Hlist.append(i+1)
    |
    | for j in t:
    |     | sum_cosines=0.0
    |     | sum_sines=0.0
    |
    |     | for i in Hlist:
    |     |     | argument=2*(np.pi)*freq*i*j
    |     |     |
    |     |     | element=np.cos(argument)
    |     |     | element1=np.sin(argument)
    |     |
    |     |     | sum_sines+=float(element1)
    |     |     | sum_cosines+=float(element)
    |
    |     | sum_cosines= sum_cosines*(m(j))
    |     | sum_sines= sum_sines*(m(j))
    |
    |     | signal.append(sum_cosines)
    |     | signal1.append(sum_sines)
    |
    | return signal, signal1, t
```

### 3.1 First Signal (10Hz)

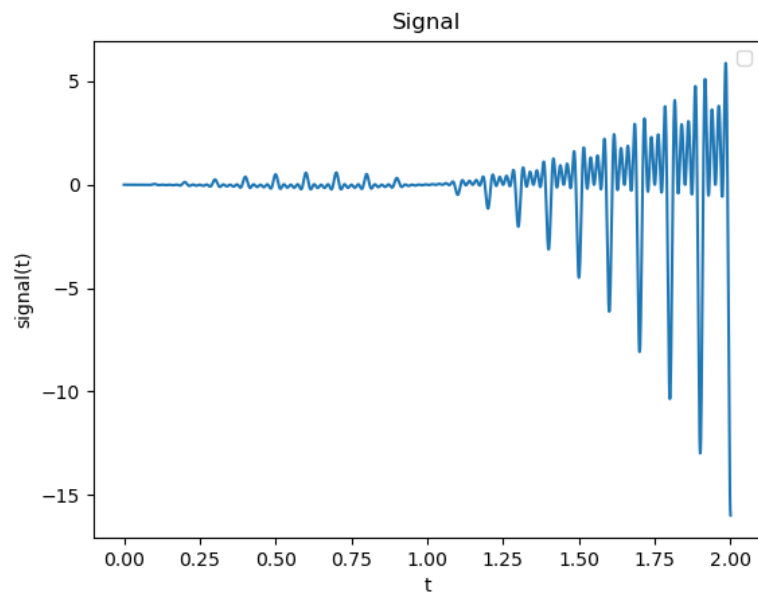
#### 3.1.1 $f_1$

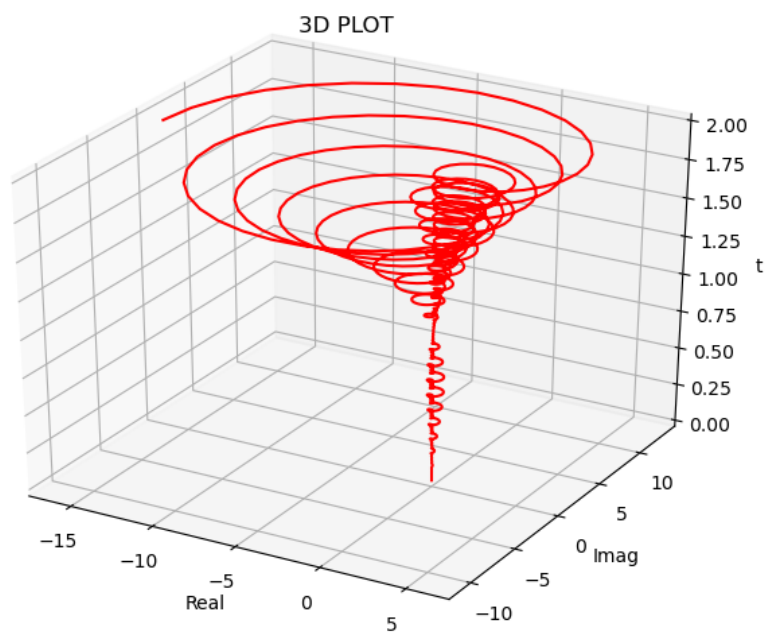
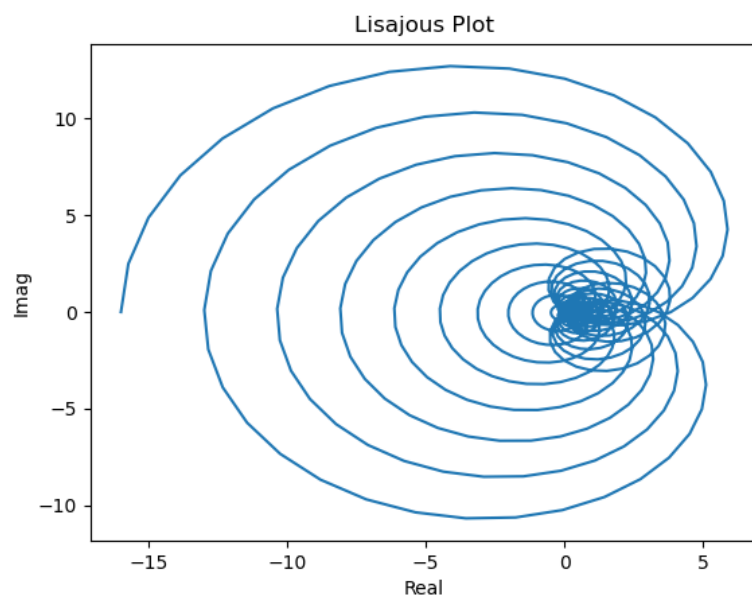




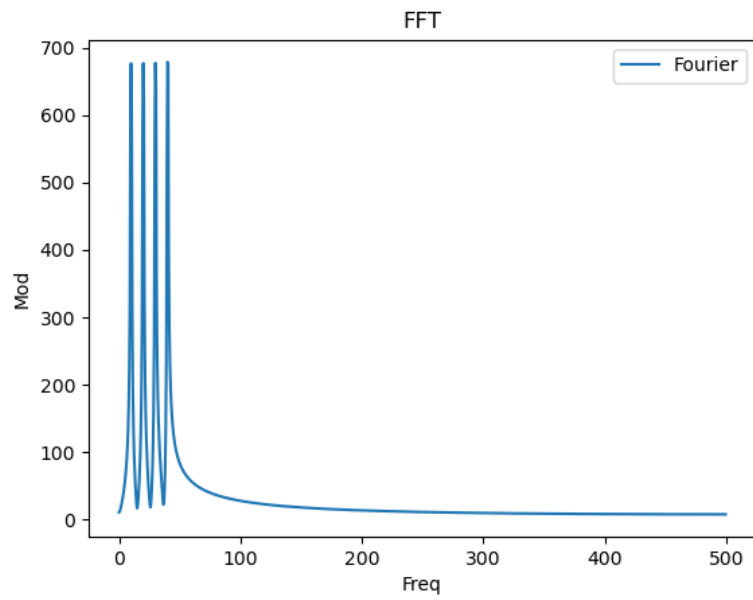


### 3.1.2 $f_2$

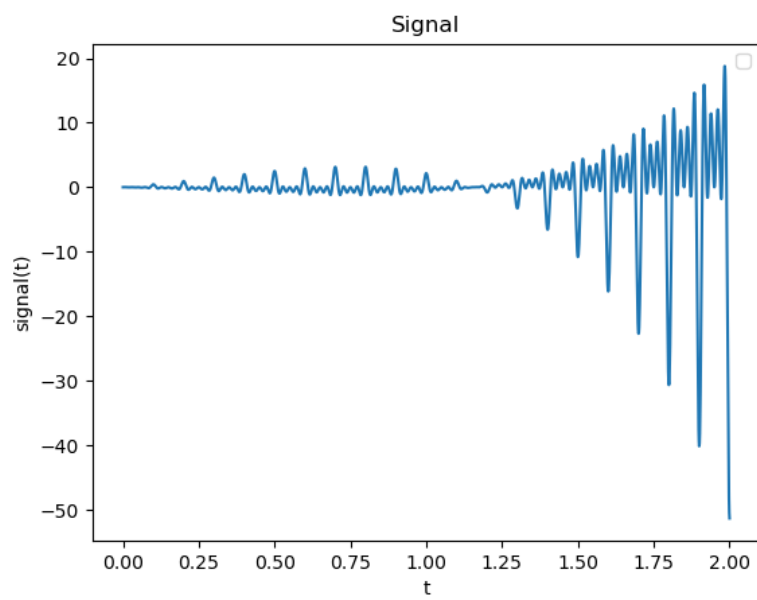




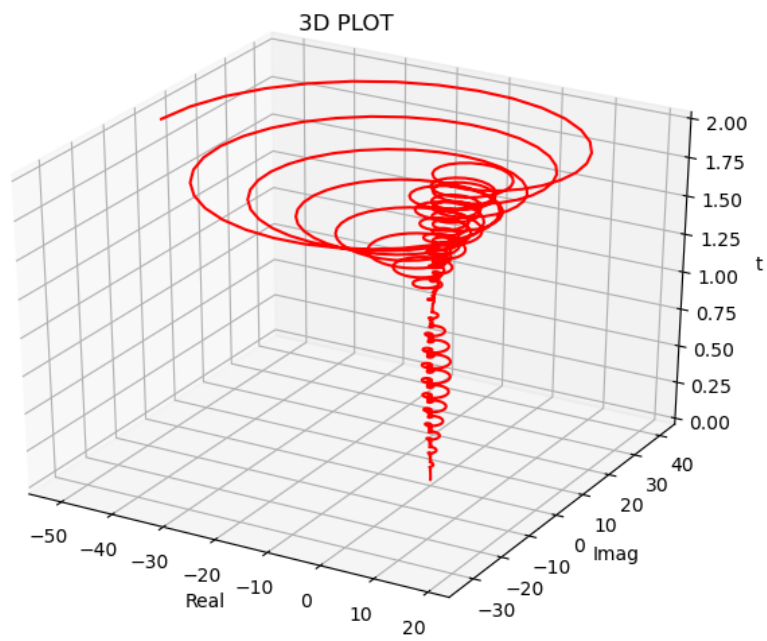
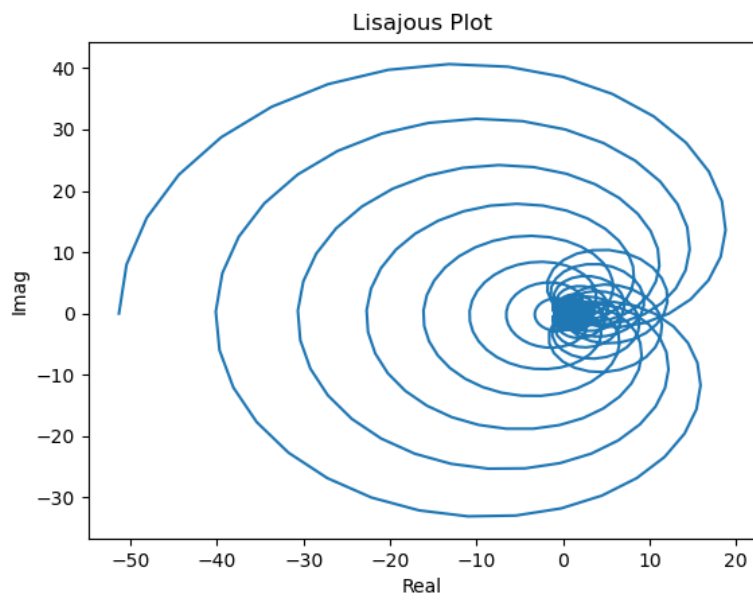


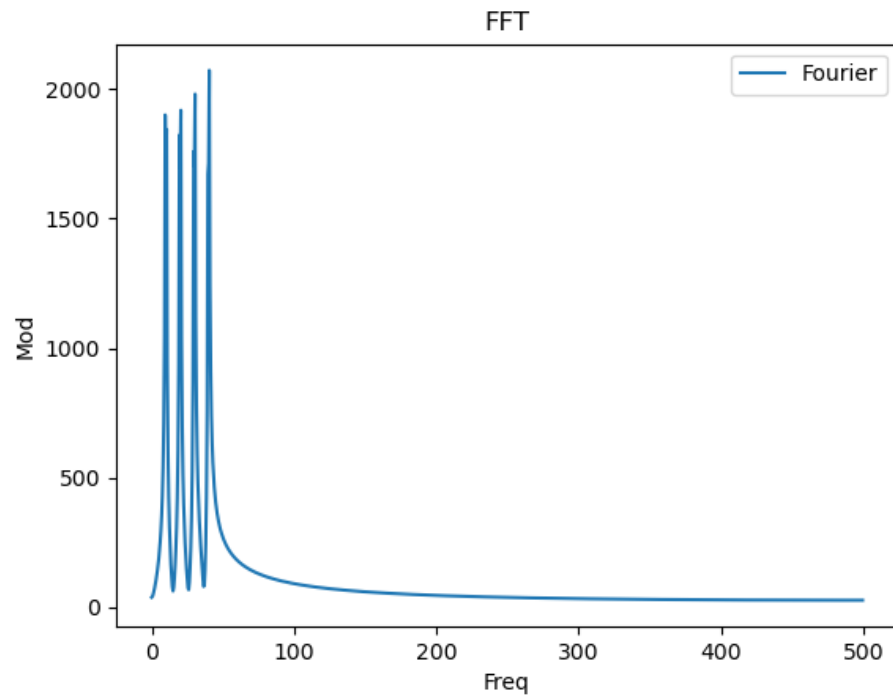


### 3.1.3 $f_3$



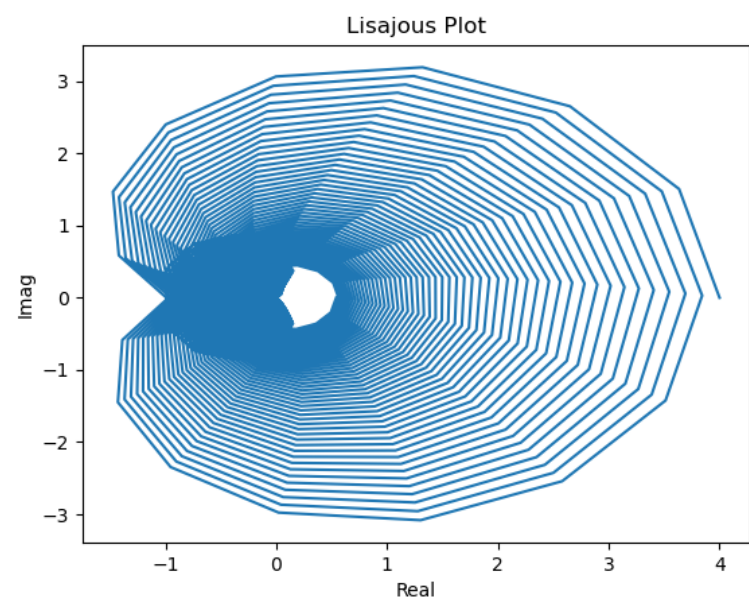
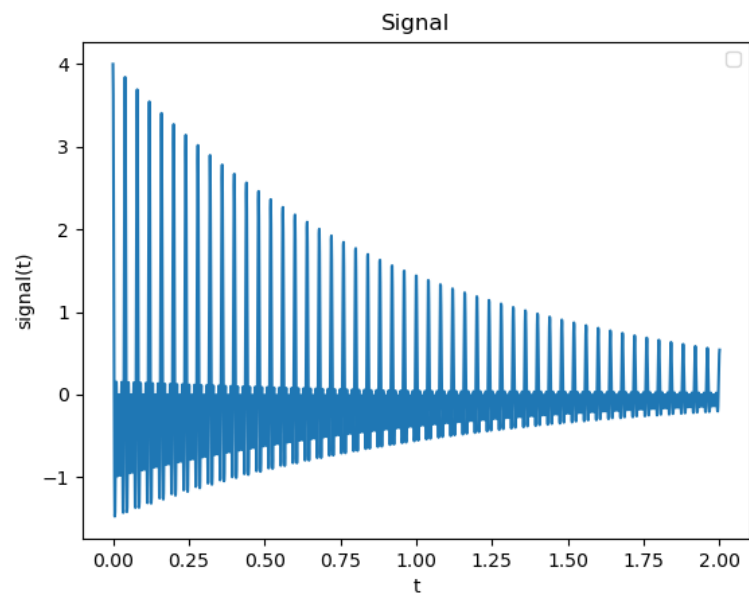


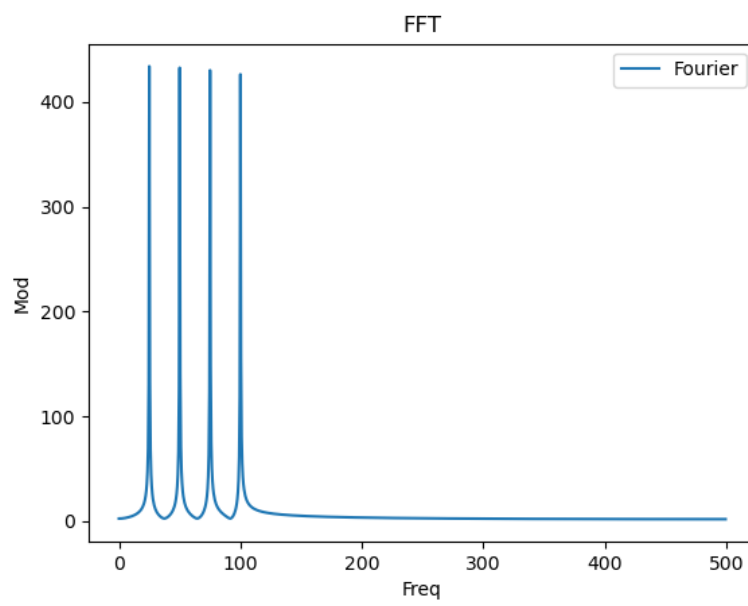
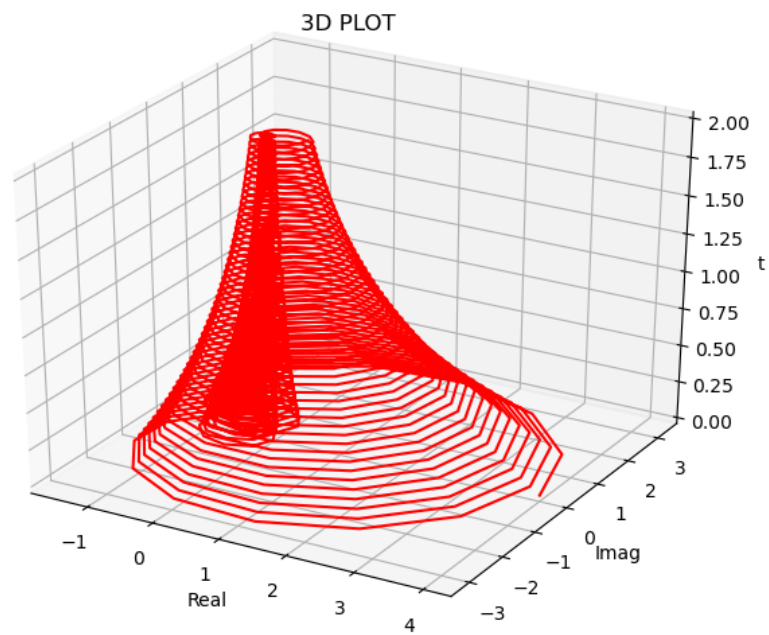




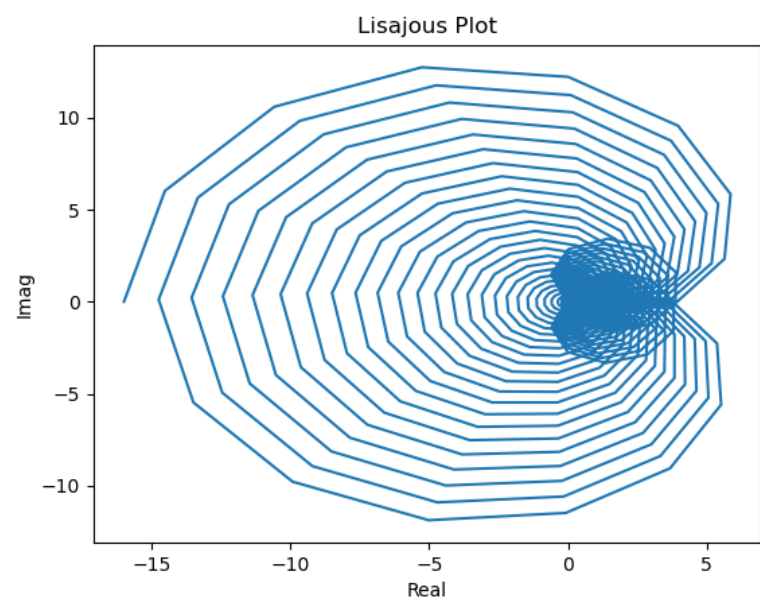
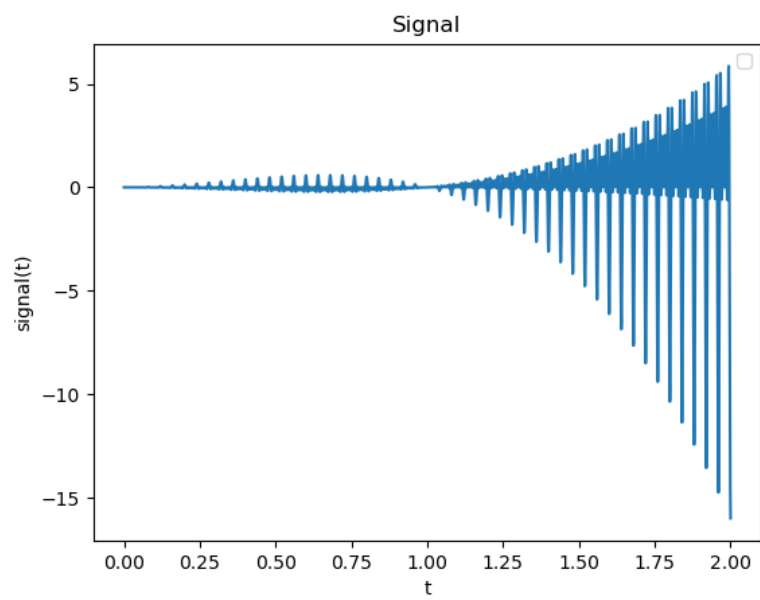
## 3.2 Second Signal 25Hz

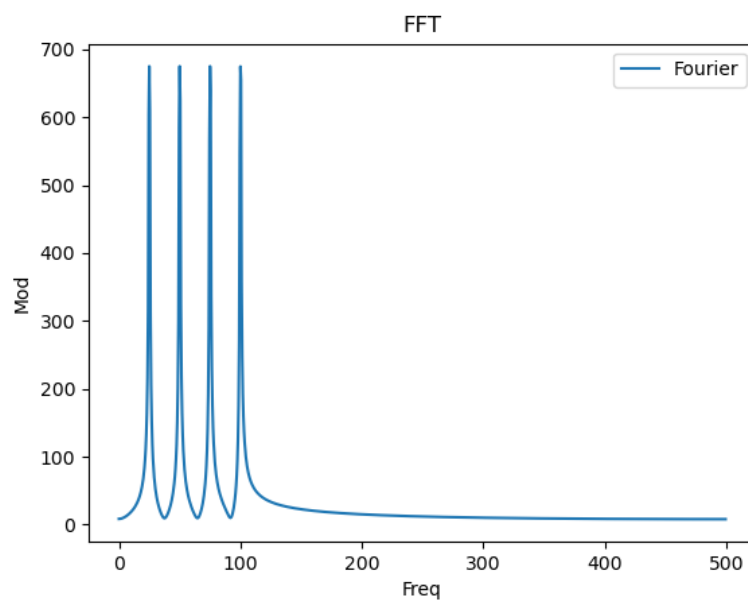
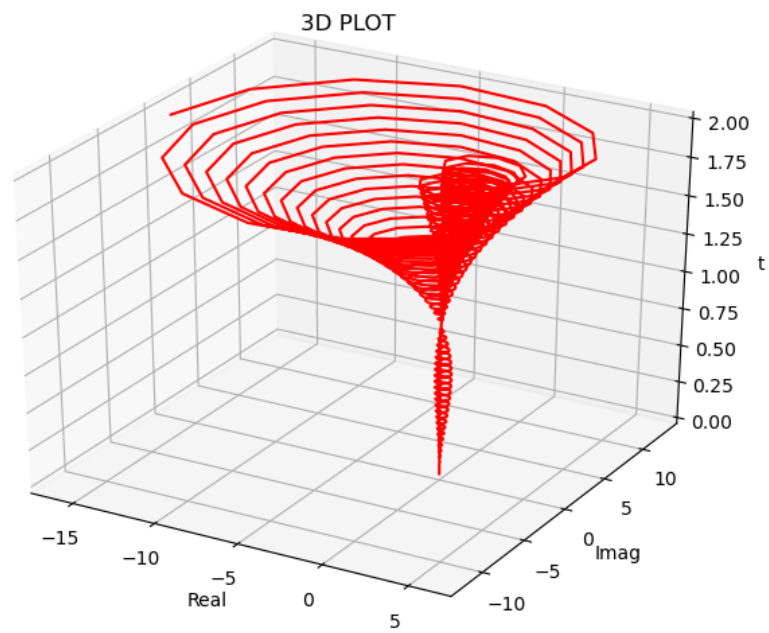
### 3.2.1 $f_1$





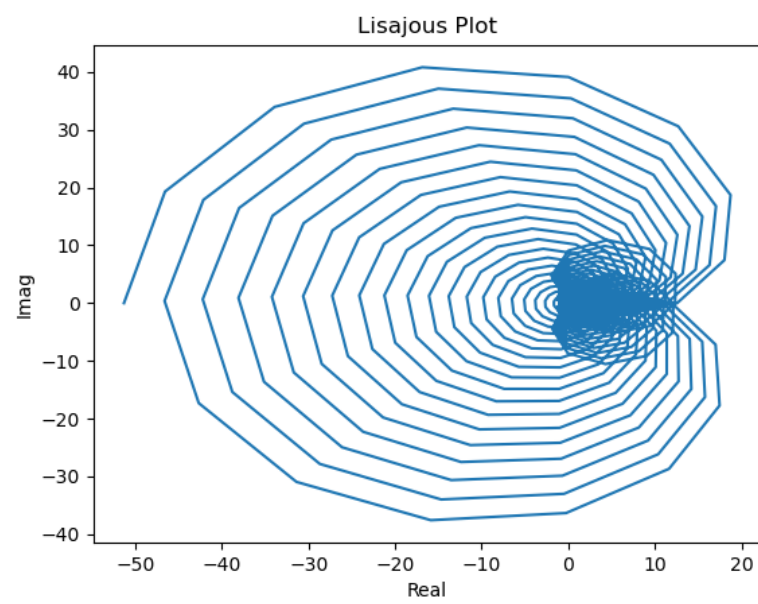
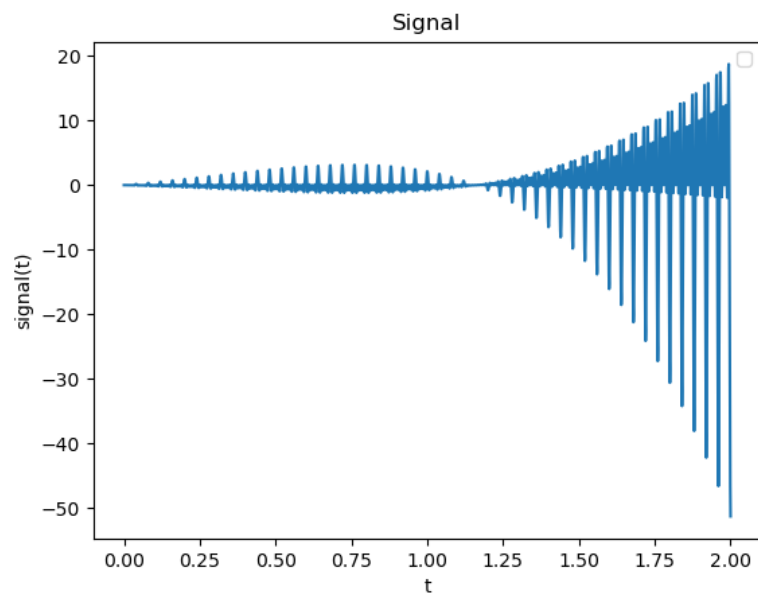
### 3.2.2 $f_2$

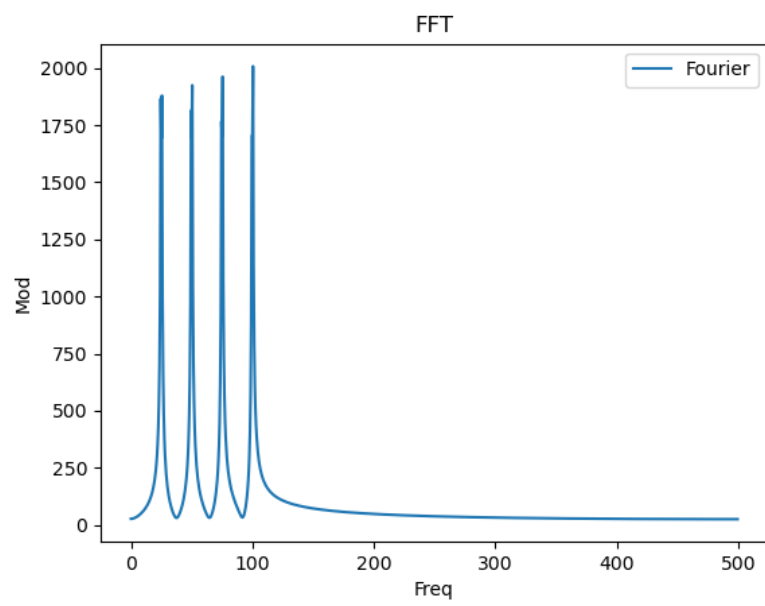
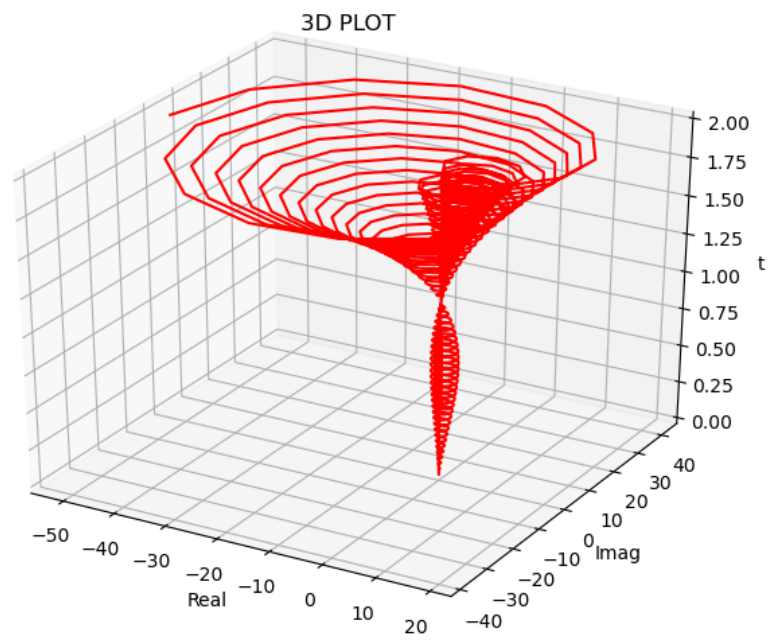




### 3.2.3 $f_3$







## 4 Signal Filters

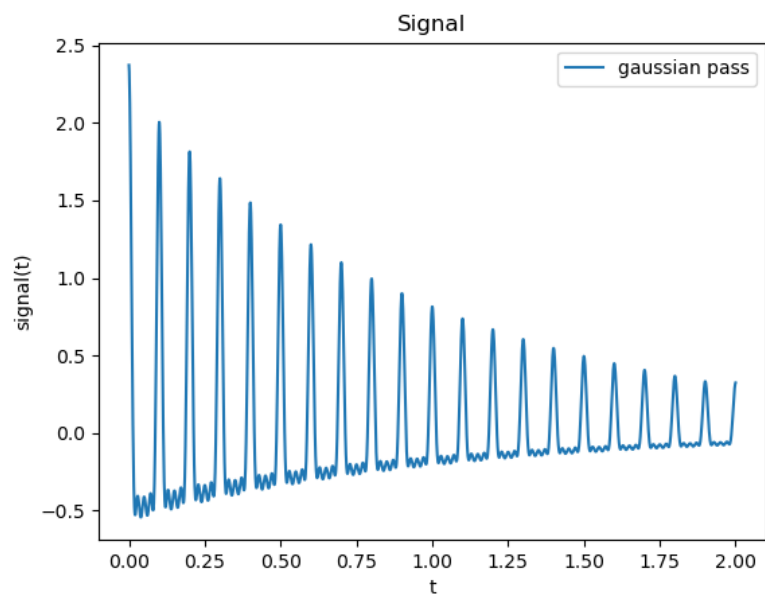
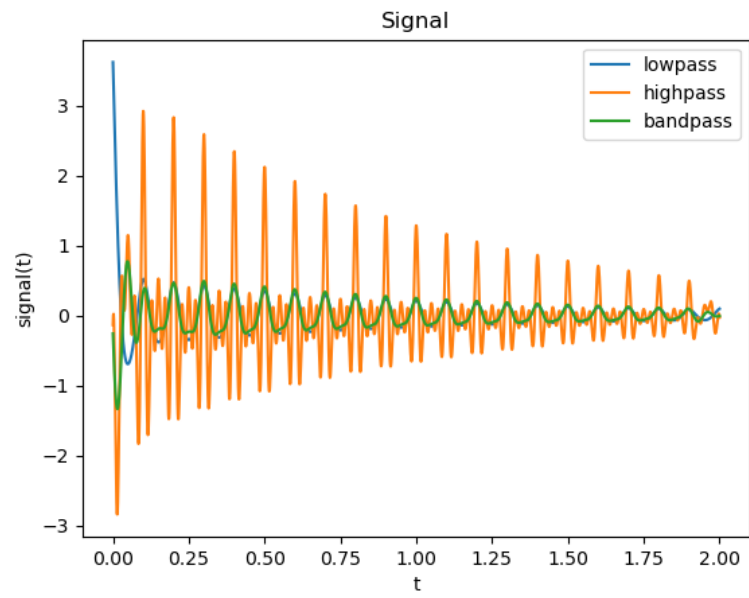
Now, having seen the signals synthesized by the sum of cosines, we can see the action of four types of filters ('lowpass', 'highpass', 'bandpass', 'Gaussian'). In this way, the code in python made to perform this task is shown below.

```
def filter_lowpass(data, cutoff=20, fs=2000, order=2):  
    ...  
    data , array to be filtered  
    cutoff, the frequency cut of the low pass  
    fs, max size of the time  
    order, order of the filter  
    ...  
    nyq=0.5*fs  
    normal_cutoff=cutoff/nyq  
    b, a= butter(order, normal_cutoff, btype='low')  
    y=filtfilt(b, a, data)  
  
    return y  
  
def filter_highpass(data, cutoff=20, fs=2000, order=5):  
  
    nyq=0.5*fs  
    normal_cutoff=cutoff/nyq  
    b, a = butter(order, normal_cutoff, btype='high', analog=False)  
    y = filtfilt(b, a, data)  
  
    return y
```

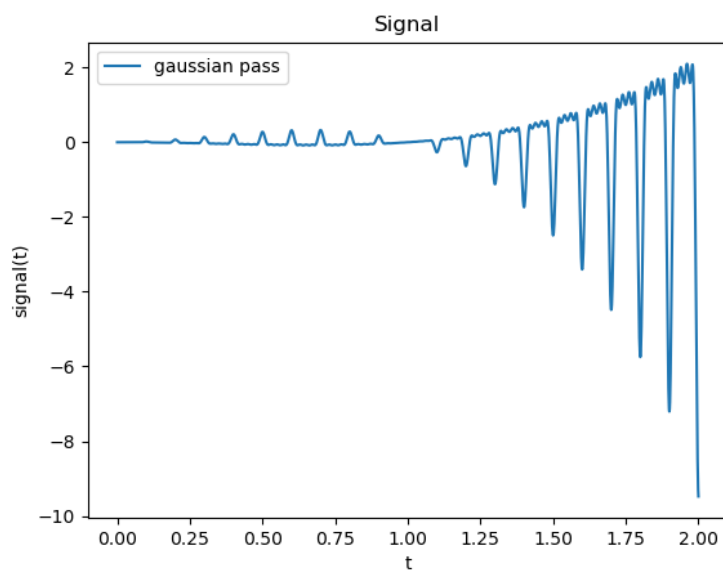
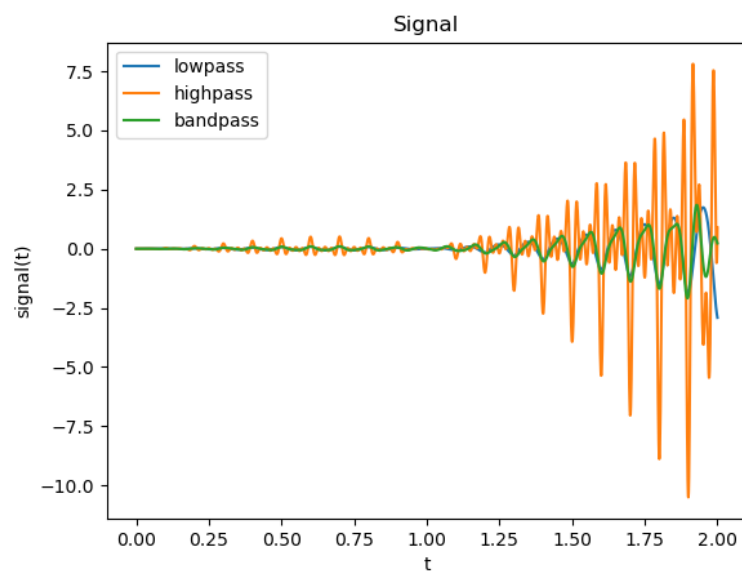
```
def filter_bandpass(data, lowcut=20, highcut=35, fs=2000, order=2):  
    nyq=0.5*fs  
    low= lowcut/nyq  
    high= highcut/nyq  
  
    b, a = butter(order, [low, high], 'bandpass', analog=False)  
    y=filtfilt(b, a, data)  
  
    return y  
  
def filter_gaussian(data, sigma=7):  
    y=gaussian_filter(data, sigma)  
  
    return y
```

The following are the respective signal filters from the previous section.

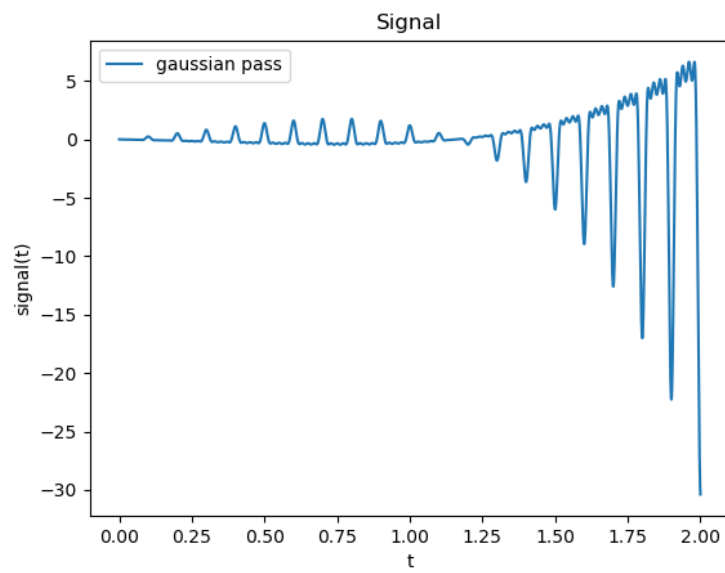
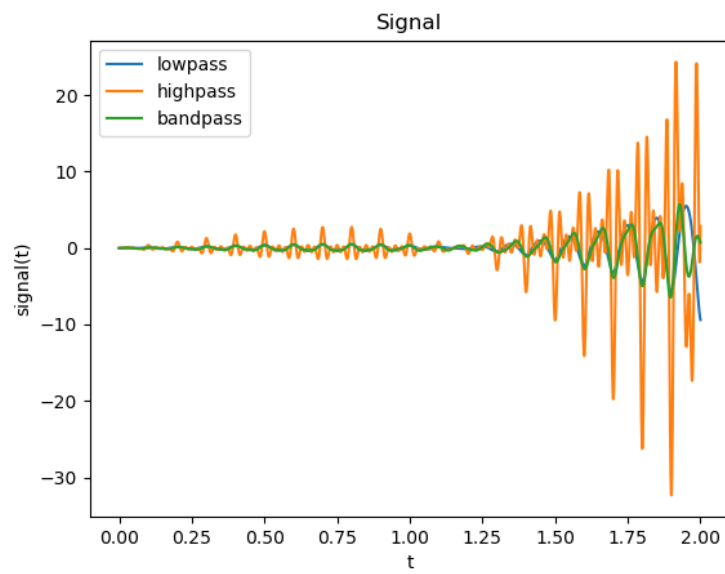
#### 4.1 $f_1$



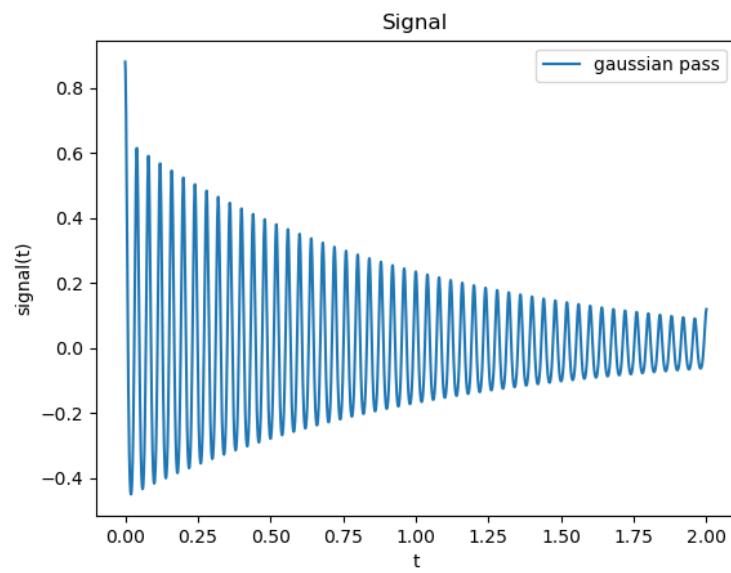
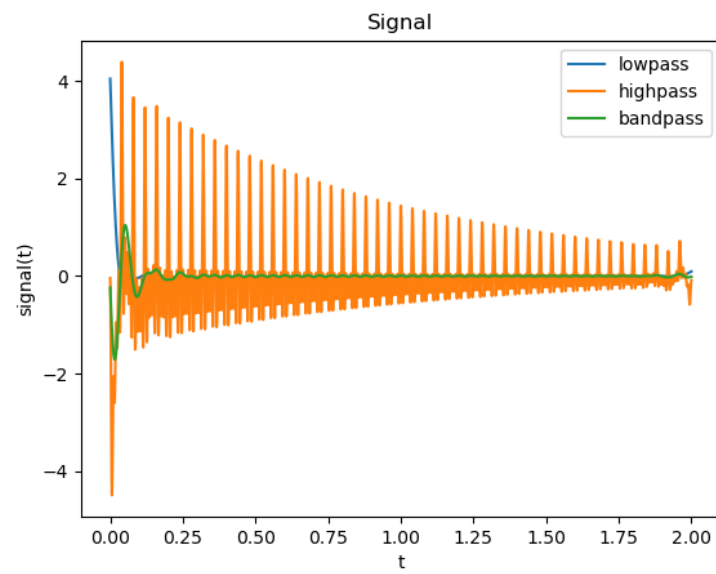
## 4.2 $f_2$



### 4.3 $f_3$

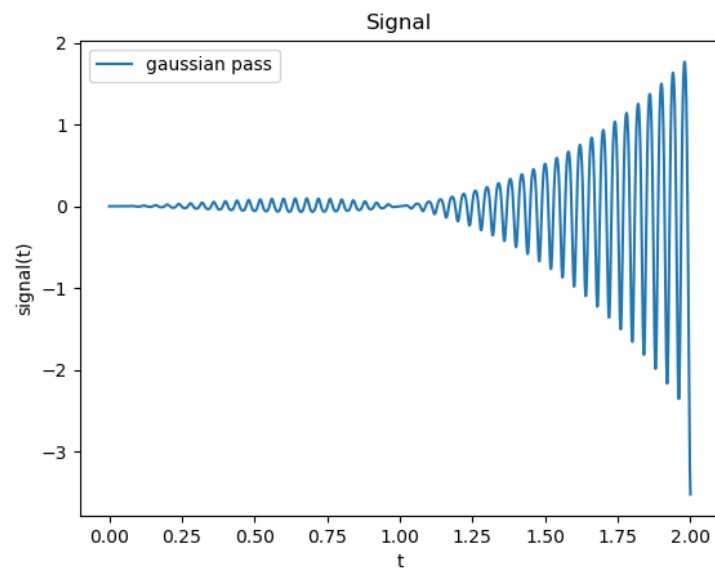
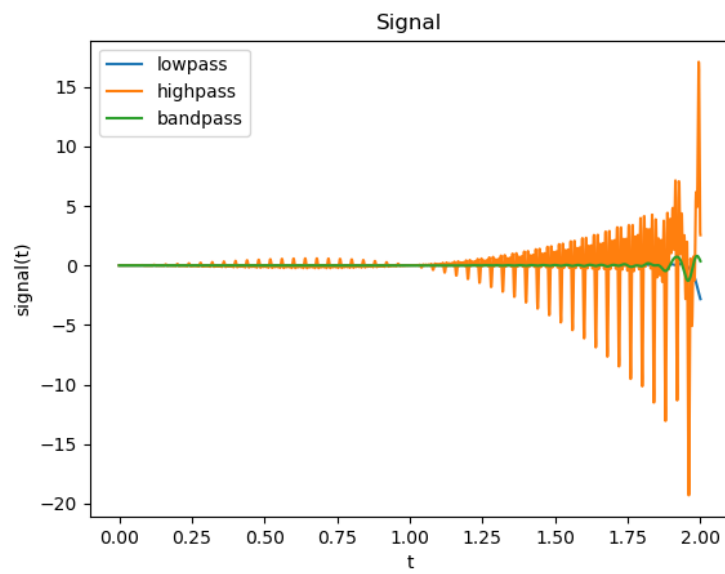


## 4.4 $f_1$

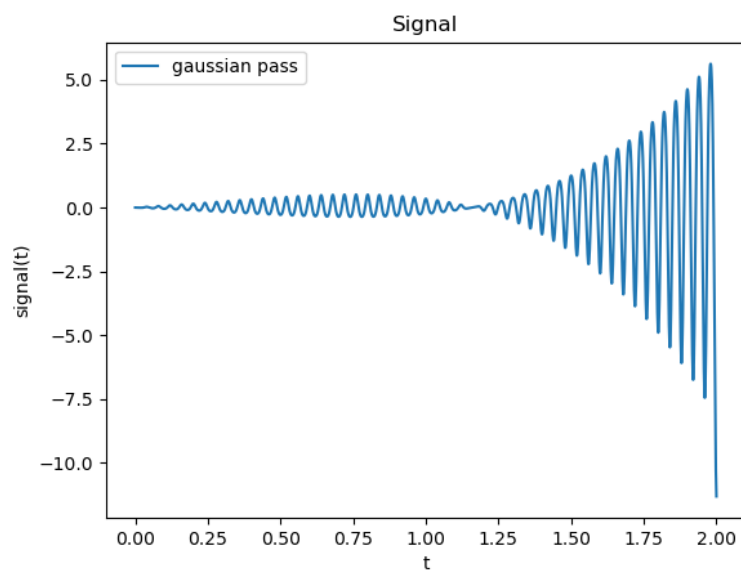
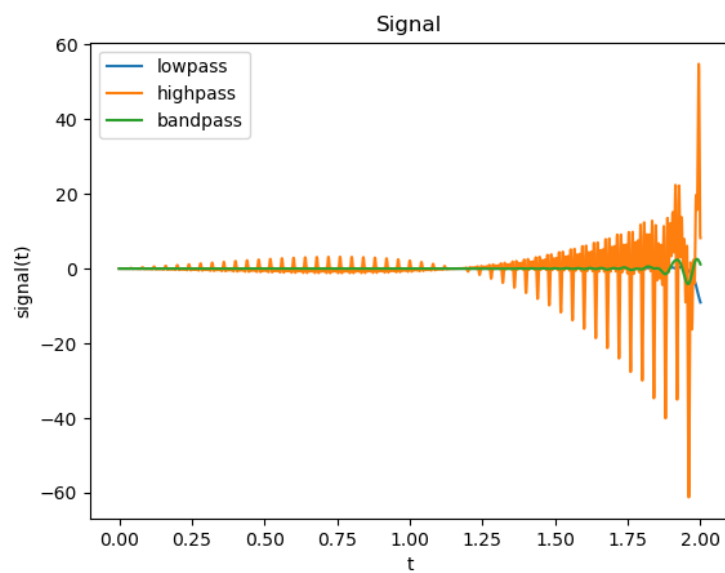




## 4.5 $f_2$

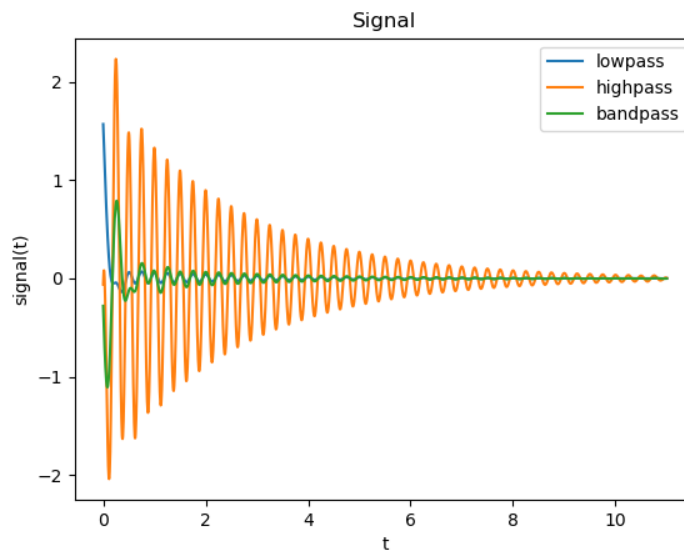
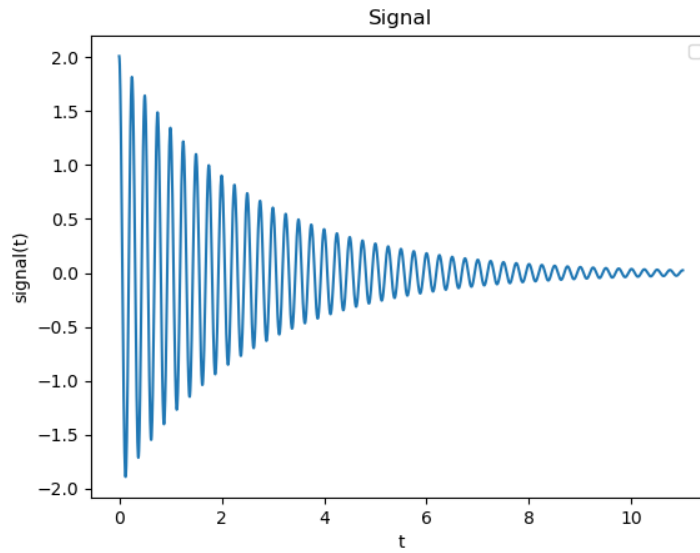


## 4.6 $f_3$

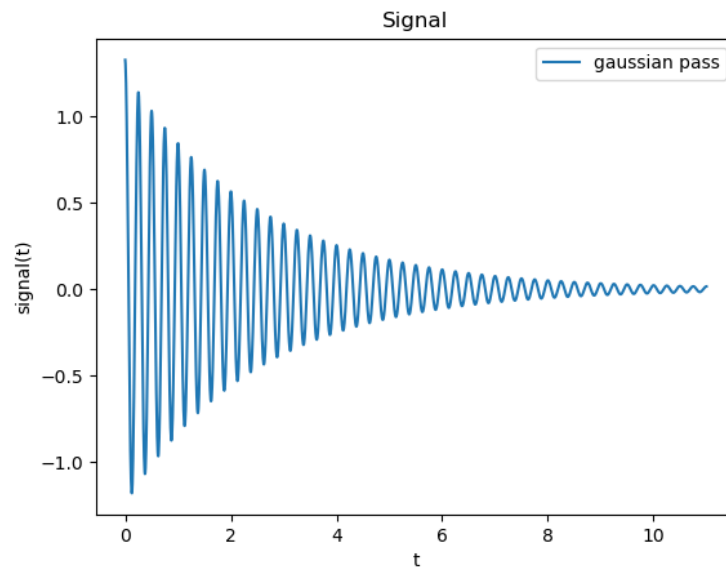


## 5 Real Signal

Finally, we have the data of a real signal from a damped oscillator from the physics lab 2.







## 6 References

- [1] Codes and images used in this project. <https://github.com/everttonmendes>