Week 6 Lab, ASP3162 Consider equation $\frac{\partial u}{\partial t} + v \frac{\partial u}{\partial z} = 0, \quad v = vonst. \quad (1)$ Discretizing using Forward time Centered space method gives $\frac{U_{i}^{n+1} - U_{i}^{n}}{\Delta t} = -2 \frac{U_{i+1}^{n} - U_{i-1}^{n}}{2 \Delta x}$ where i've a space index, and n is a time We want to find a modified PDE. Using Taylor series we get $u_i^{n+1} = u_i^n + \Delta t \frac{\partial u_i^n}{\partial t} + \frac{1}{2} \Delta t^2 \frac{\partial^2 u_i^n}{\partial t^2} + O(\Delta t^3),$ (3) Uits = Ui ± DX DR + 1 DX DX2 + 6 DX3 D3U! + 1/24 AX4 Dyu! + O(6x5). Substituting Eq. 3,4 into Eq. 2 gives: $\frac{\partial u_i^n}{\partial t} + \frac{1}{2} \Delta t \frac{\partial^2 u_i^n}{\partial t^2} + \mathcal{O}(\Delta t^2) =$ $-v\left[\frac{\partial u_i^n}{\partial x} + \frac{1}{6}\Delta x^2 \frac{\partial^3 u_i^n}{\partial x^3} + O(\Delta x^4)\right].$ Rearranging and dropping undexes gives the modified PDE:

 $\frac{\partial u}{\partial t} + v \frac{\partial u}{\partial x} + \frac{1}{2} \Delta t \frac{\partial^2 u}{\partial t^2} + \frac{1}{6} v \Delta x^2 \frac{\partial^2 u}{\partial x^3} + O(\Delta t^2, \Delta x^4).(5)$

Q1.2 We can see from Eq.5 that largest step sizes are st and ox? Therefore, FTCS is first order accurate in time, and 2nd order in space

Q1,3 see the code and the plots Please in the archive, Q1.4 Assume ui = De e wtn, (6) then Ui=Deixxie W(tn+st) = De e e A, 7) where A= ewst. We can also write Eq. 6 as

ui = Deinni An Substituting " into Eq. 2 gives: Deika: An A - Deika: An $=-\frac{V}{24x}\left[De^{i\kappa(2\kappa_i+52\kappa)}A^n-iDe^{i\kappa(2\kappa_i-62\kappa)}A^n\right]$ Rearrange: Andersi (A-1) = - VD ikxi (eixx = ikxx) Andrewsi (2) Andr $\frac{A-1}{\Delta t} = -\frac{V}{\Delta x} i m(\kappa \Delta x)$ A=1-Waterm(KAX).

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$$|A| = \sqrt{1 + V^2 \frac{st^2}{sx^2}} t m^2(\kappa sx)$$

For stability we require $|A| \le 1$, but $|A| > 1$.

Therefore, FTCS method is unconditionally unstable. We see in the plots of the solution that large instabilities quickly develop, which is unsistent with our numerical analysis of instability

Q.1,5

The code and plots of the Lax method are in the archive.

Q1.6

The recurrence relation for the Lax method is given by

$$u_{i}^{n+1} = \frac{1}{2} \left[u_{i-1}^{n} + u_{i+1}^{n} \right] - V_{\Delta}t \frac{u_{i+1}^{n} - u_{i-1}^{n}}{2 \Delta x}.$$

Next we substitute ui from Eq.8 and simplify:

Rearranging gives?

 $A = \cos(k \Delta x) - i \sin(k \Delta x)$.

$$|A|^{2} = 1 - nn^{2}(\kappa \Delta x) + v^{2} \frac{d^{2}}{\Delta x^{2}} nn^{2}(\kappa \Delta x) \quad (cos^{2}\kappa \Delta x = 1 - nn^{2}\kappa \Delta x)$$

$$= 1 + nn^{2}(\kappa \Delta x) \left[V^{2} \frac{dt^{2}}{\Delta x^{2}} - 1 \right]$$

In order to have $|A| \le 1$, we need $V^2 \frac{5t^2}{5x^2} - 1 \le 0$

Rearranging gives: $\sqrt{2} \frac{\delta t^{2}}{\delta x^{2}} \leq 1$ $|V| \frac{\delta t}{\delta x} \leq 1$

(AO)

We have found that LAX method is numerically stable when Inequality 10 is satisfied. This is consistent with our calculations, where we used $V \stackrel{\text{dt}}{\Rightarrow} = 0.5$, and our program produced a stable-looking solution.















