

# Divergence of tensors in spherical geometry up to third order

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## BACKGROUND READING:

CONTINUUM MECHANICS (Lecture Notes)

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$$\nabla(.) = \sum_n \frac{\mathbf{e}_n}{h_n} \frac{\partial(.)}{\partial x_n} \quad : \text{ nabla operator} \qquad \mathbf{V} = \sum_i V_i \mathbf{e}_i \qquad : \text{ tensor of first order (vector)} \quad (1)$$

$$\mathbf{S} = \sum_{ij} S_{ij} (\mathbf{e}_i \otimes \mathbf{e}_j) \qquad : \text{ tensor of second order} \quad (2)$$

$$\mathbf{T} = \sum_{ijk} T_{ijk} (\mathbf{e}_i \otimes \mathbf{e}_j \otimes \mathbf{e}_k) \qquad : \text{ tensor of third order} \quad (3)$$

$$\nabla \cdot \mathbf{V} = \sum_i \frac{1}{h_i} \left[ \frac{\partial V_i}{\partial x_i} + \sum_m \Gamma_{mi}^i V_m \right] \qquad : \text{ div of first order tensor (vector)} \quad (4)$$

$$\nabla \cdot \mathbf{S} = \sum_{ij} \frac{1}{h_i} \left[ \frac{\partial S_{ij}}{\partial x_i} + \sum_m \Gamma_{mi}^i S_{mj} + \sum_m \Gamma_{mi}^j S_{im} \right] \mathbf{e}_j \qquad : \text{ div of second order tensor} \quad (5)$$

$$\nabla \cdot \mathbf{T} = \sum_{ijk} \frac{1}{h_i} \left[ \frac{\partial T_{ijk}}{\partial x_i} + \sum_m \Gamma_{mi}^i T_{mjk} + \sum_m \Gamma_{mi}^j T_{imk} + \sum_m \Gamma_{mi}^k T_{ijm} \right] (\mathbf{e}_j \otimes \mathbf{e}_k) \qquad : \text{ div of third order tensor} \quad (6)$$

### Divergence of first order tensor $\nabla \cdot \mathbf{V}$

$$\frac{1}{r^2} \frac{\partial(r^2 V_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (V_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial V_\phi}{\partial \phi} \quad (7)$$

### Divergence of second order tensor $\nabla \cdot \mathbf{S}$

$$S_r(\mathbf{e}_r) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 S_{rr}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta S_{\theta r}) + \frac{1}{r \sin \theta} \frac{\partial S_{\phi r}}{\partial \phi} - \frac{S_{\theta\theta}}{r} - \frac{S_{\phi\phi}}{r} \quad (8)$$

$$S_\theta(\mathbf{e}_\theta) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 S_{r\theta}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta S_{\theta\theta}) + \frac{1}{r \sin \theta} \frac{\partial S_{\phi\theta}}{\partial \phi} + \frac{S_{\theta r}}{r} - \frac{S_{\phi\phi} \cos \theta}{r \sin \theta} \quad (9)$$

$$S_\phi(\mathbf{e}_\phi) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 S_{r\phi}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta S_{\theta\phi}) + \frac{1}{r \sin \theta} \frac{\partial S_{\phi\phi}}{\partial \phi} + \frac{S_{\phi r}}{r} + \frac{S_{\theta\theta} \cos \theta}{r \sin \theta} \quad (10)$$

### Divergence of third order tensor $\nabla \cdot \mathbf{T}$

$$T_{rr}(\mathbf{e}_r \otimes \mathbf{e}_r) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{rrr}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta rr}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi rr}}{\partial \phi} - \frac{T_{\theta\theta r}}{r} - \frac{T_{\theta r\theta}}{r} - \frac{T_{\phi\phi r}}{r} - \frac{T_{\phi r\phi}}{r} \quad (11)$$

$$T_{r\theta}(\mathbf{e}_r \otimes \mathbf{e}_\theta) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{rr\theta}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta r\theta}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi r\theta}}{\partial \phi} - \frac{T_{\theta\theta\theta}}{r} + \frac{T_{\theta rr}}{r} - \frac{T_{\phi\phi\theta}}{r} - \frac{T_{\phi r\phi} \cos \theta}{r \sin \theta} \quad (12)$$

$$T_{r\phi}(\mathbf{e}_r \otimes \mathbf{e}_\phi) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{rr\phi}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta r\phi}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi r\phi}}{\partial \phi} + \frac{T_{\theta\theta\phi}}{r} - \frac{T_{\phi\phi\phi}}{r} + \frac{T_{\phi r\phi} \cos \theta}{r \sin \theta} \quad (13)$$

$$T_{\theta r}(\mathbf{e}_\theta \otimes \mathbf{e}_r) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{r\theta r}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta\theta r}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi\theta r}}{\partial \phi} + \frac{T_{\theta rr}}{r} - \frac{T_{\theta\theta\theta}}{r} - \frac{T_{\phi\phi r} \cos \theta}{r \sin \theta} - \frac{T_{\phi\theta\phi}}{r} \quad (14)$$

$$T_{\theta\theta}(\mathbf{e}_\theta \otimes \mathbf{e}_\theta) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{r\theta\theta}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta\theta\theta}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi\theta\theta}}{\partial \phi} + \frac{T_{\theta r\theta}}{r} + \frac{T_{\theta\theta r}}{r} - \frac{T_{\phi\phi\theta} \cos \theta}{r \sin \theta} - \frac{T_{\phi\theta\phi} \cos \theta}{r \sin \theta} \quad (15)$$

$$T_{\theta\phi}(\mathbf{e}_\theta \otimes \mathbf{e}_\phi) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{r\theta\phi}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta\theta\phi}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi\theta\phi}}{\partial \phi} + \frac{T_{\theta r\phi}}{r} + \frac{T_{\phi\theta r}}{r} + \frac{T_{\phi\theta\theta} \cos \theta}{r \sin \theta} \quad (16)$$

$$T_{\phi r}(\mathbf{e}_\phi \otimes \mathbf{e}_r) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{r\phi r}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta\phi r}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi\phi r}}{\partial \phi} - \frac{T_{\theta\phi\theta}}{r} + \frac{T_{\phi rr}}{r} + \frac{T_{\phi\theta r} \cos \theta}{r \sin \theta} - \frac{T_{\phi\phi\phi}}{r} \quad (17)$$

$$T_{\phi\theta}(\mathbf{e}_\phi \otimes \mathbf{e}_\theta) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{r\phi\theta}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta\phi\theta}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi\phi\theta}}{\partial \phi} + \frac{T_{\theta\phi r}}{r} + \frac{T_{\phi r\theta}}{r} + \frac{T_{\phi\theta\theta} \cos \theta}{r \sin \theta} - \frac{T_{\phi\theta\phi} \cos \theta}{r \sin \theta} \quad (18)$$

$$T_{\phi\phi}(\mathbf{e}_\phi \otimes \mathbf{e}_\phi) : \quad \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{r\phi\phi}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta\phi\phi}) + \frac{1}{r \sin \theta} \frac{\partial T_{\phi\phi\phi}}{\partial \phi} + \frac{T_{\phi r\phi}}{r} + \frac{T_{\phi\theta\phi} \cos \theta}{r \sin \theta} + \frac{T_{\phi\phi r}}{r} + \frac{T_{\phi\phi\theta} \cos \theta}{r \sin \theta} \quad (19)$$