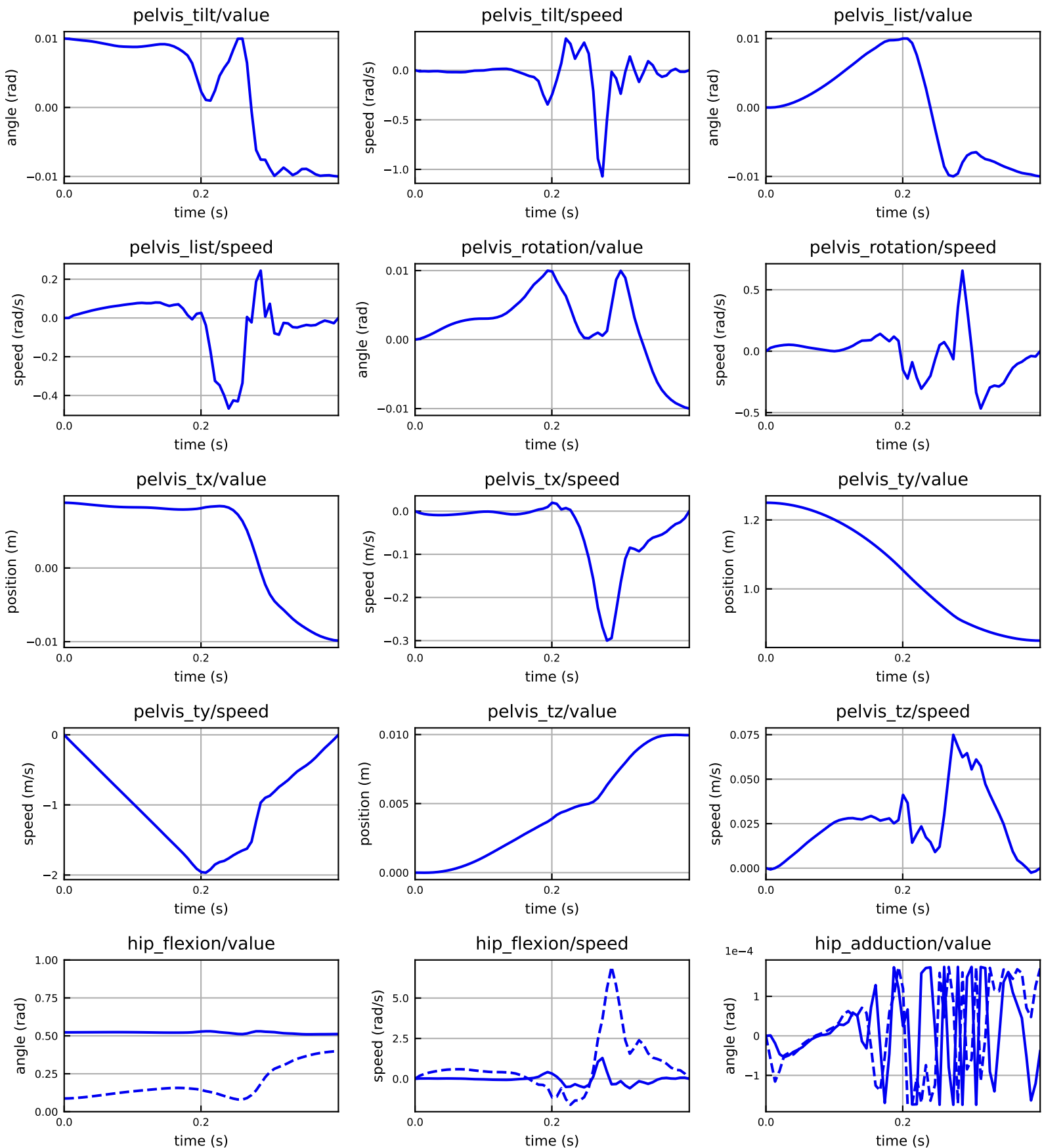
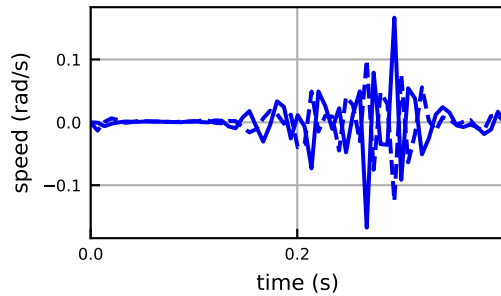


— D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (right leg)
- - - D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (left leg)

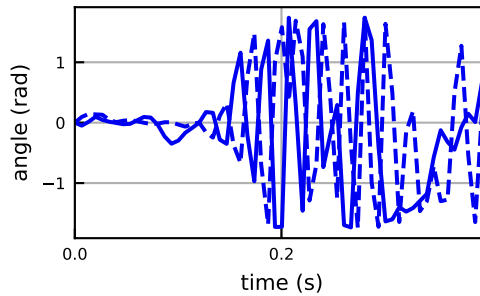


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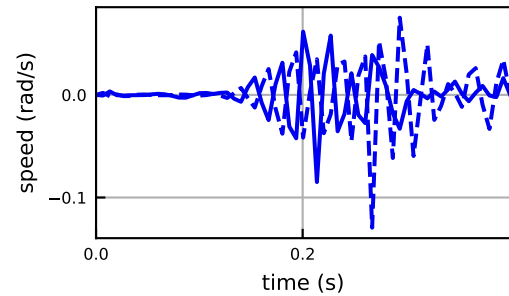
hip_adduction/speed



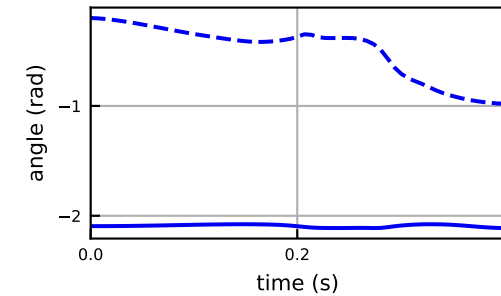
hip_rotation/value



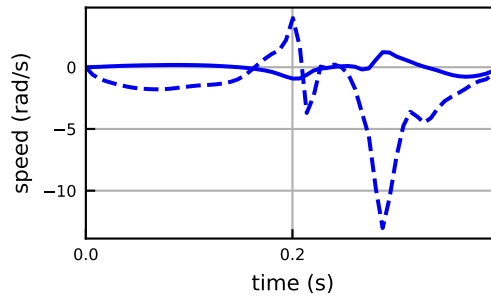
hip_rotation/speed



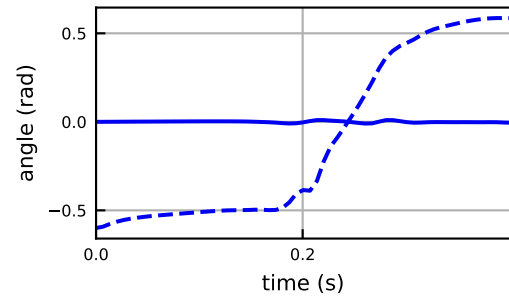
knee_angle/value



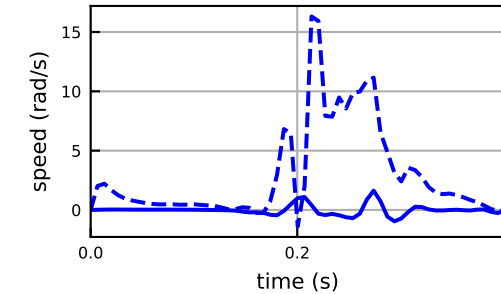
knee_angle/speed



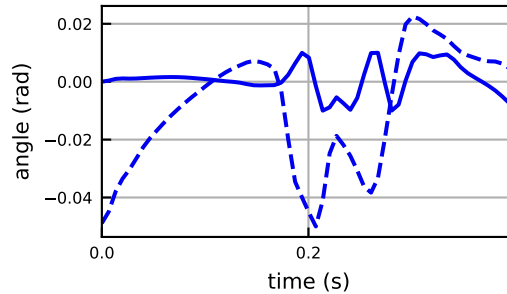
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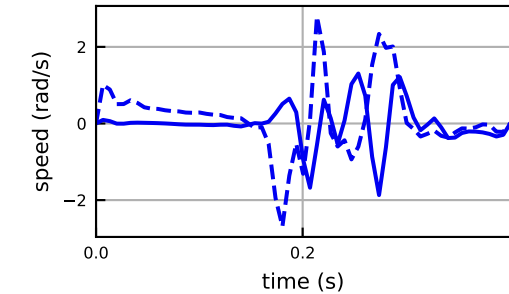
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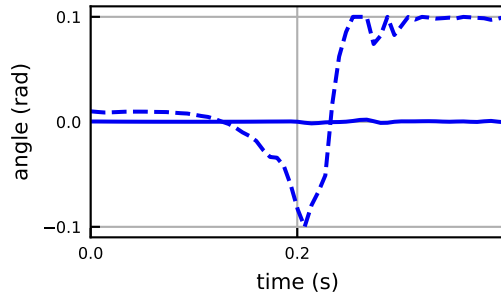
subtalar_angle/value



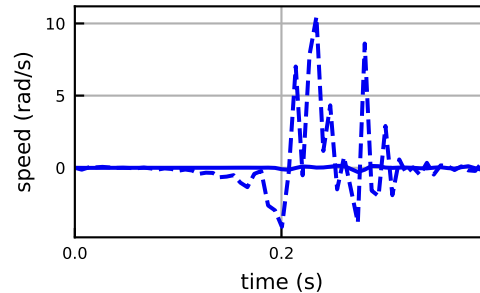
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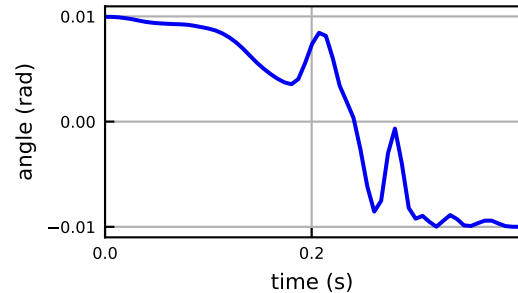
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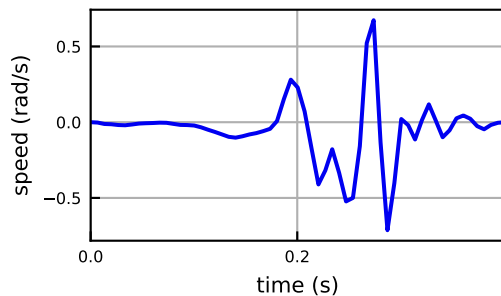
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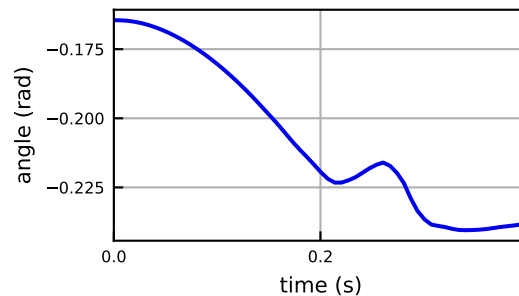
lumbar_extension/value



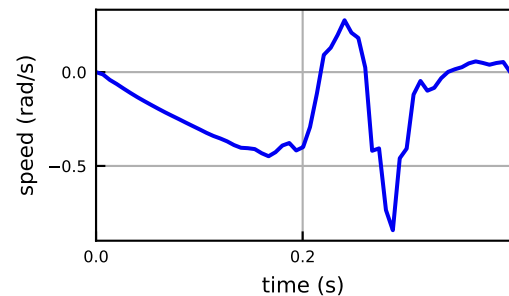
lumbar_extension/speed



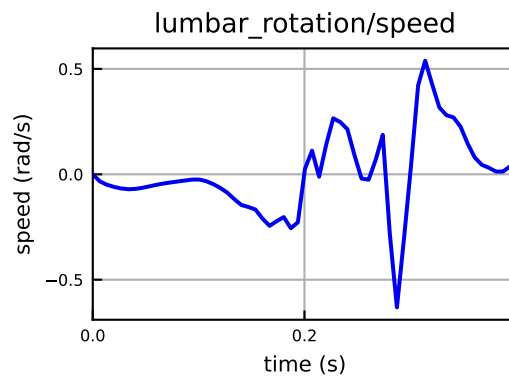
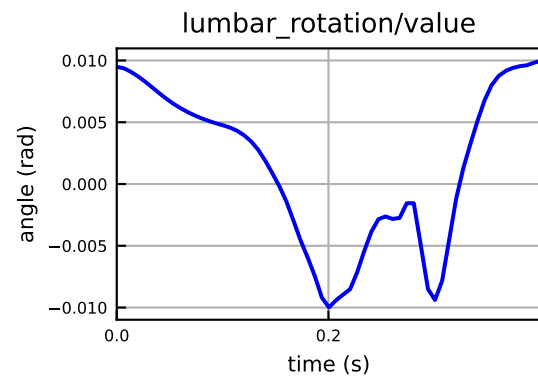
lumbar_bending/value



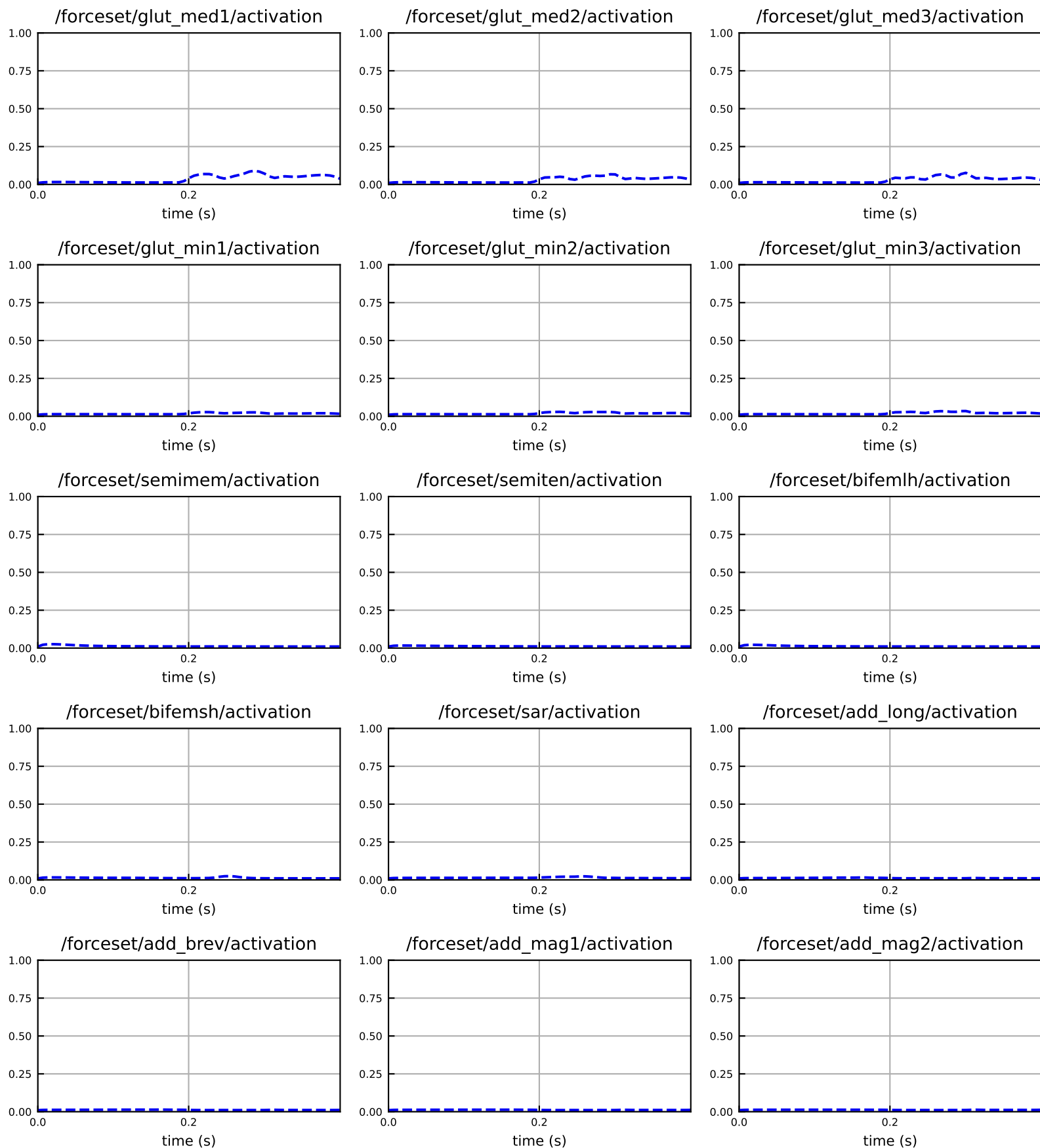
lumbar_bending/speed



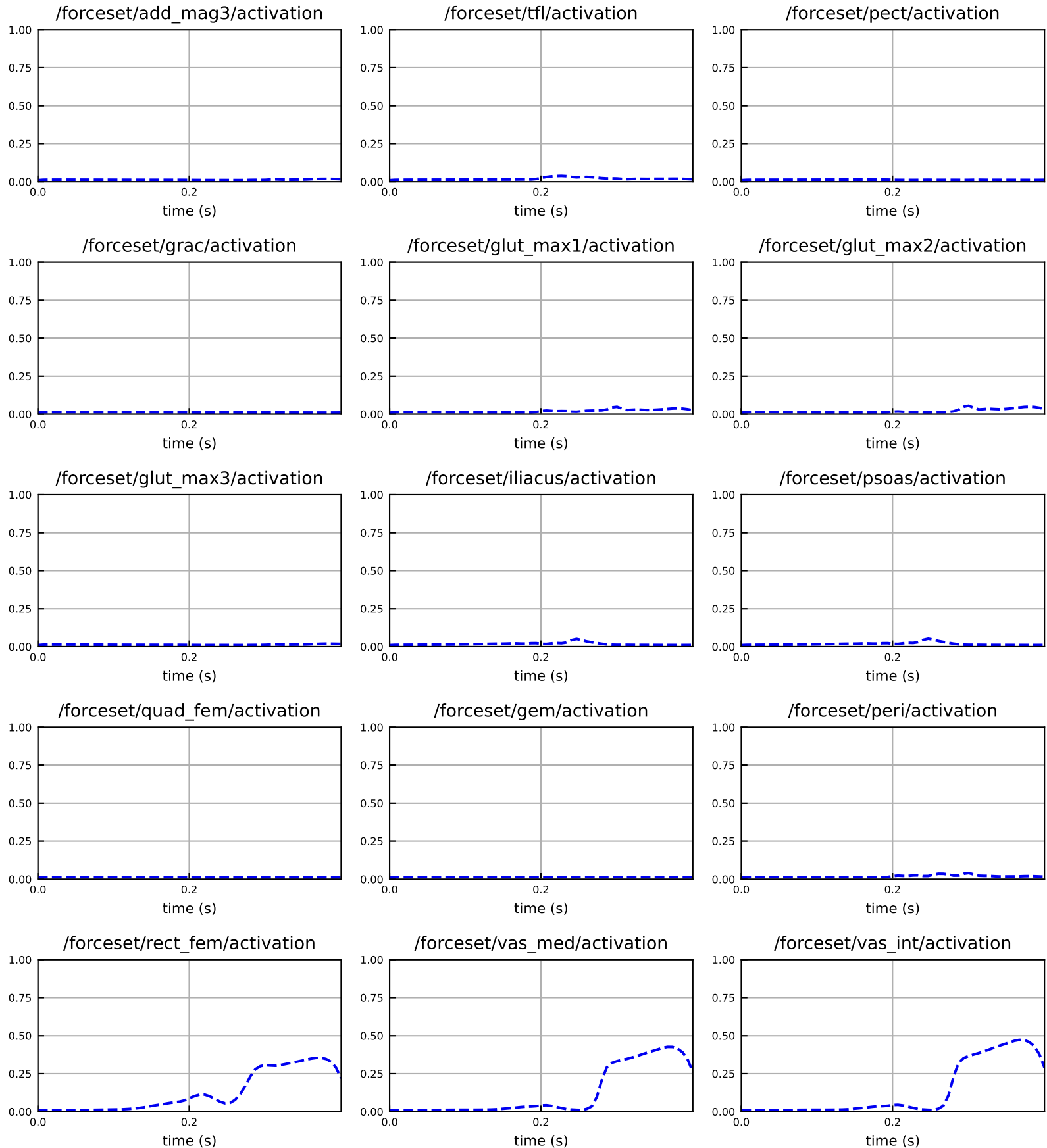
— D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (right leg)
- - D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (left leg)



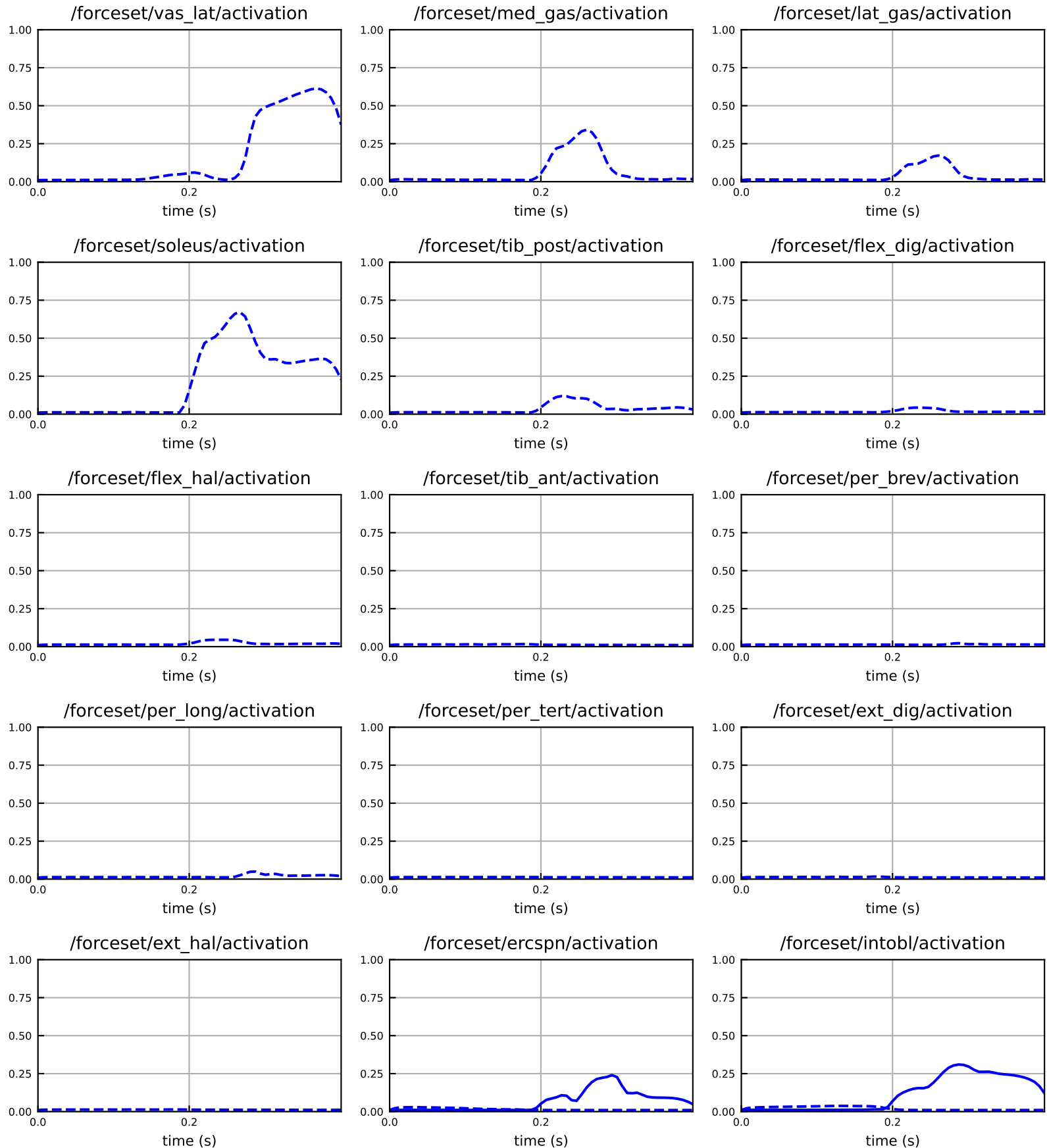
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— D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (right leg)
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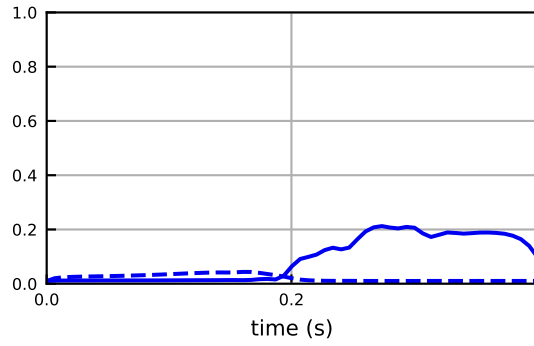


— D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (right leg)
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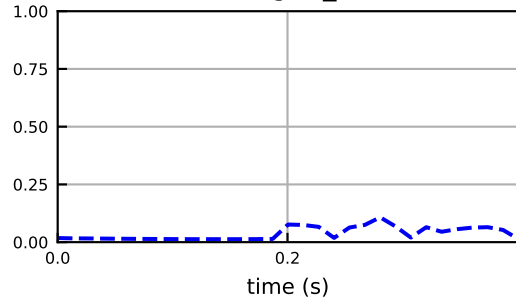
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/forceset/extobl/activation

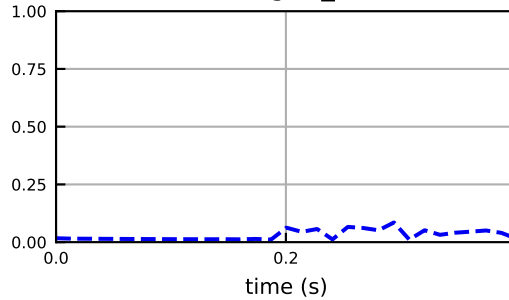


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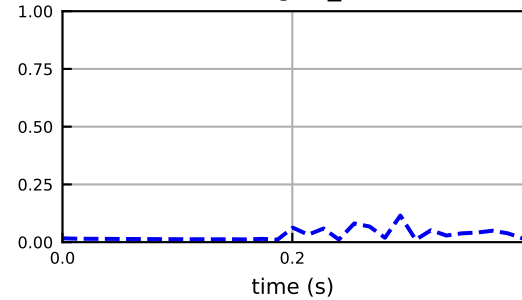
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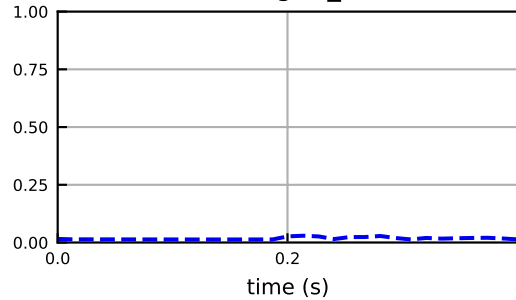
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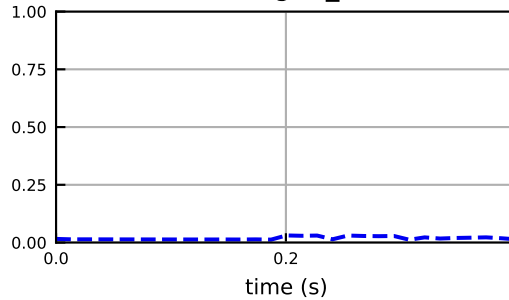
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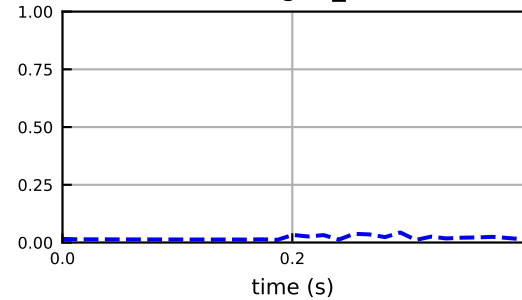
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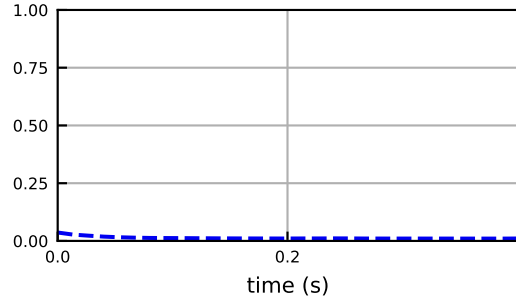
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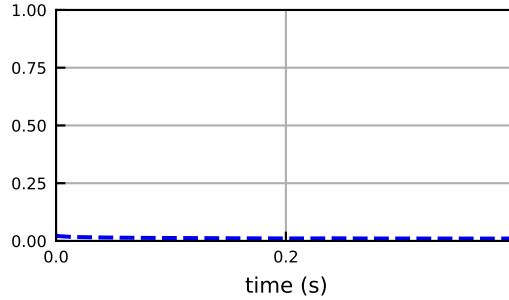
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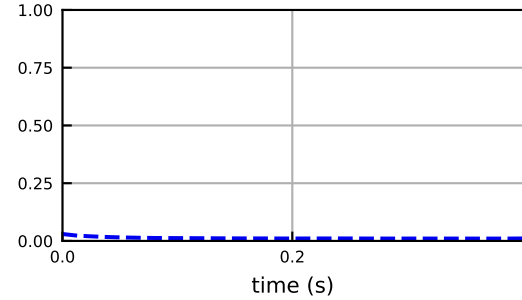
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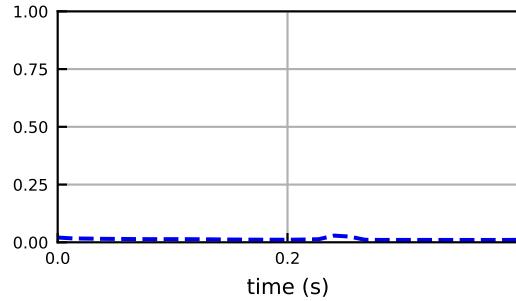
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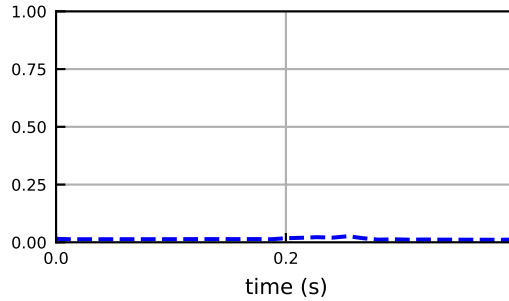
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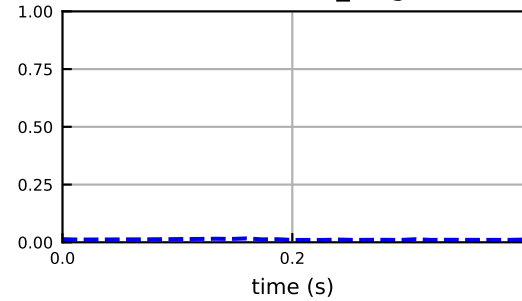
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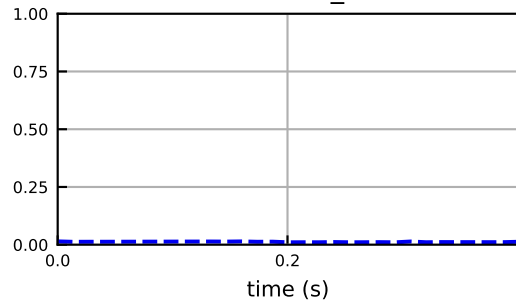
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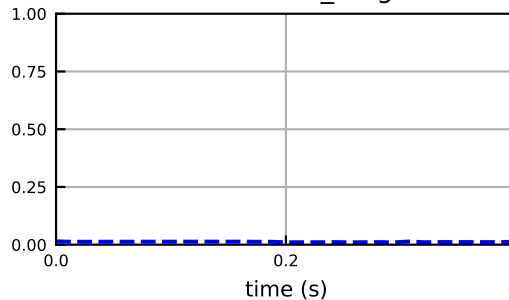
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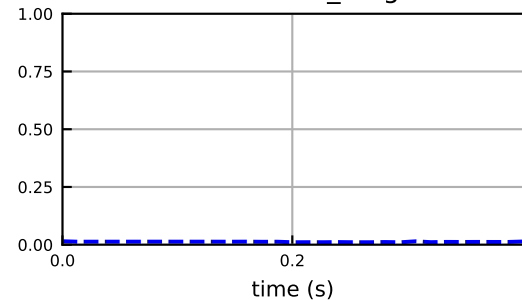
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forcesetadd_mag1

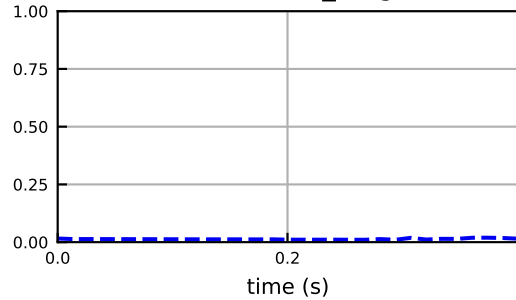


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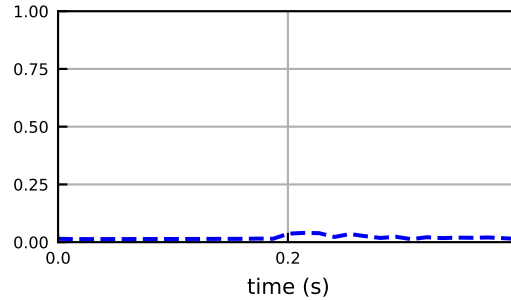


— D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (right leg)
- - D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (left leg)

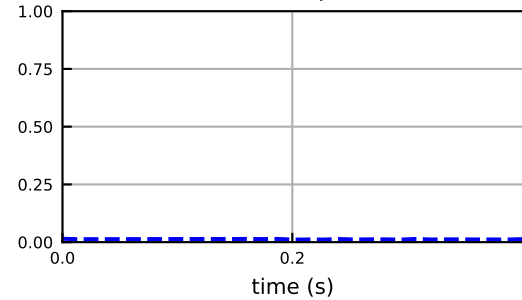
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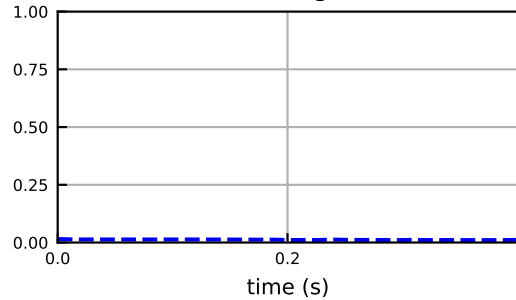
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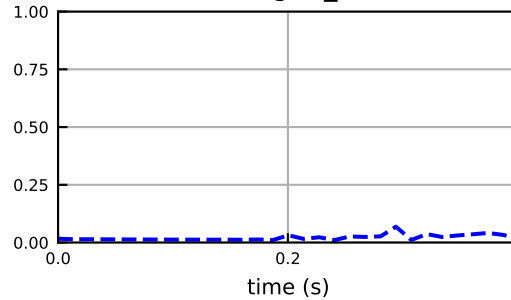
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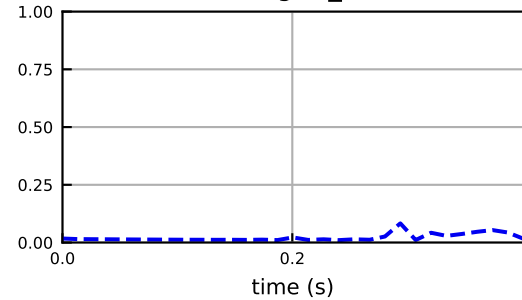
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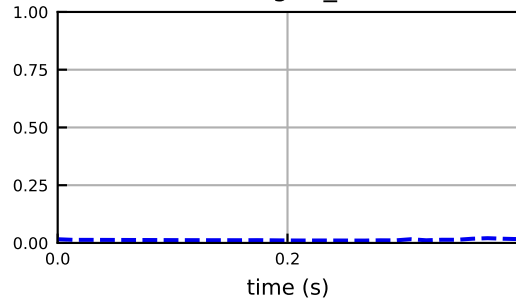
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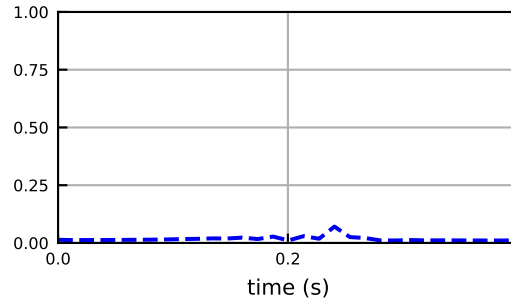
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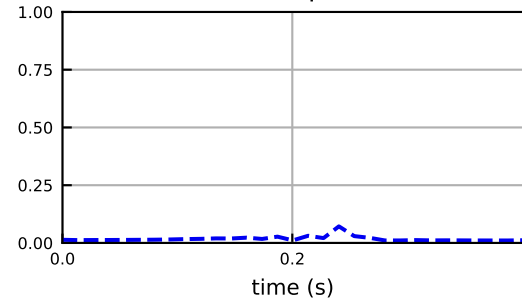
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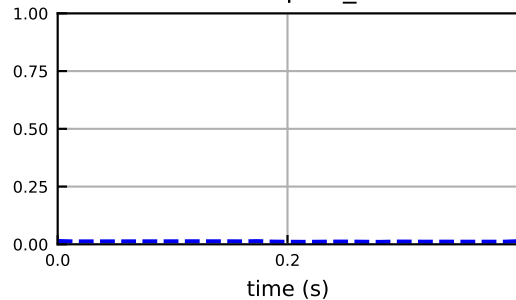
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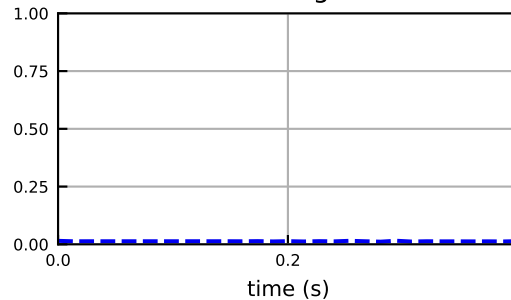
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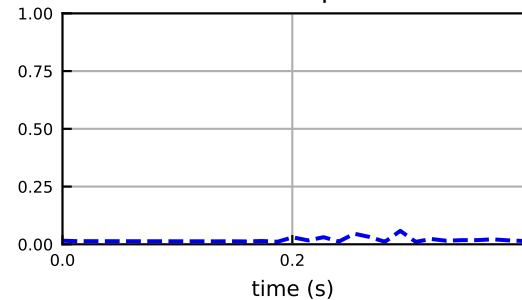
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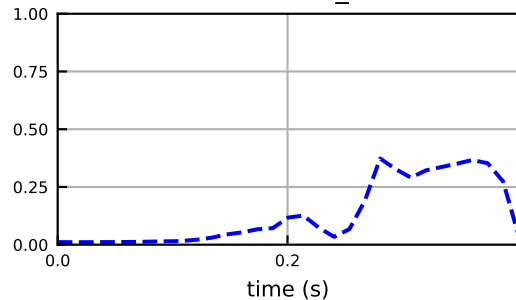
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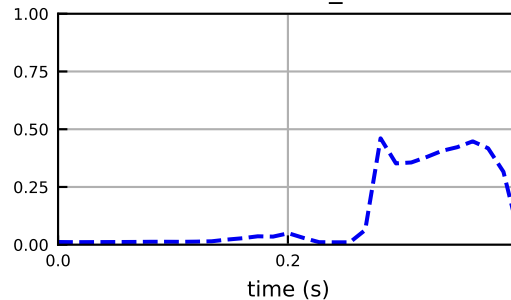
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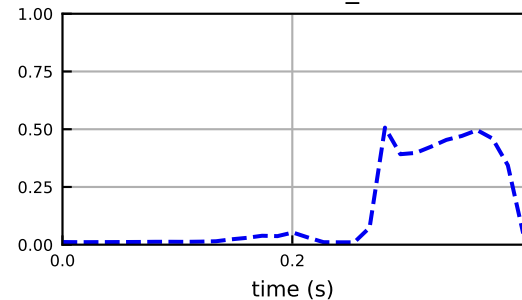
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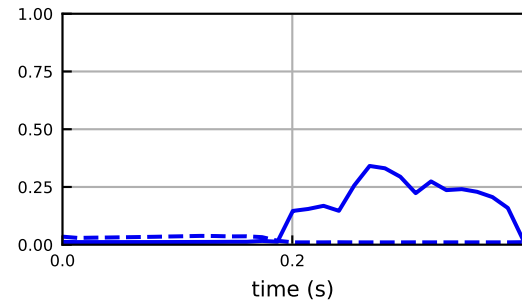
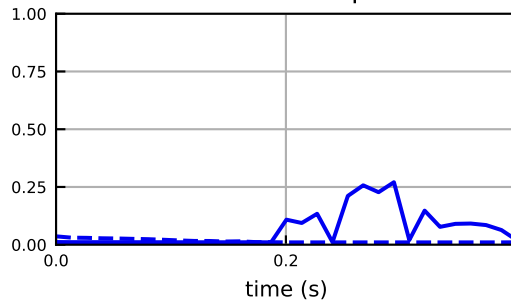
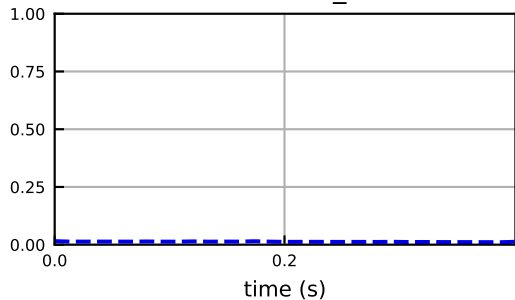
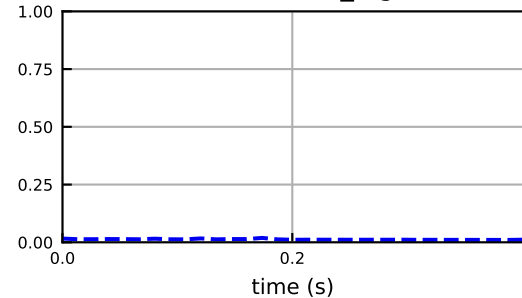
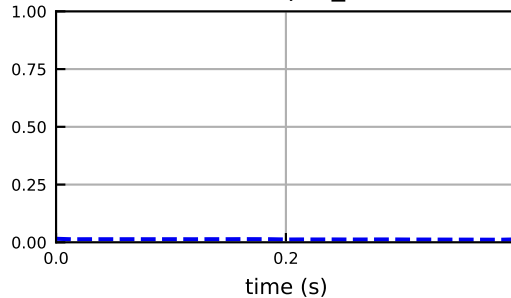
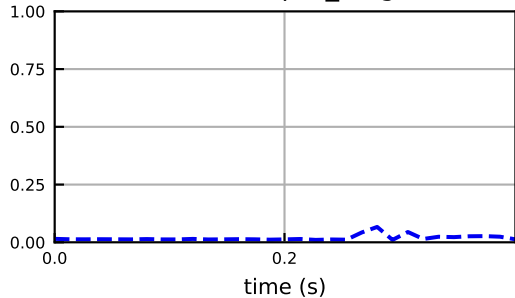
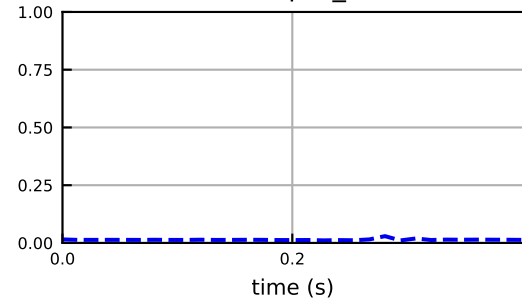
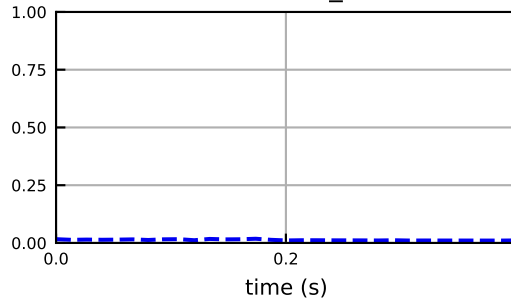
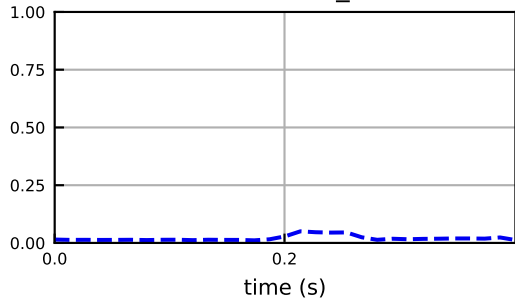
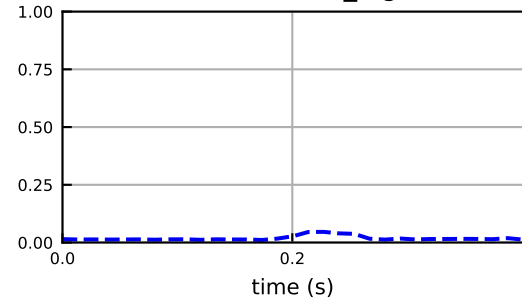
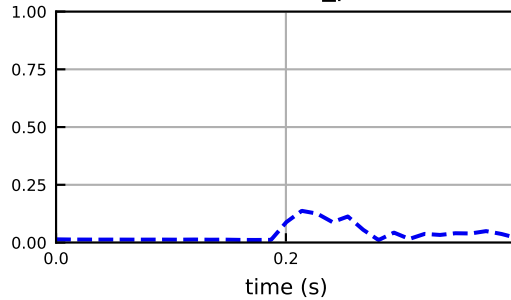
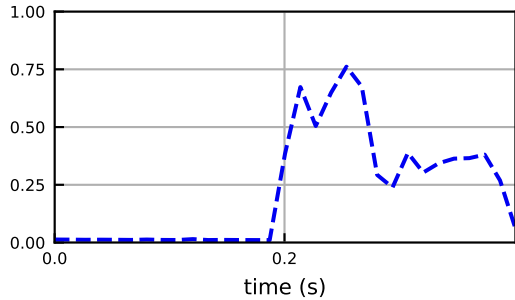
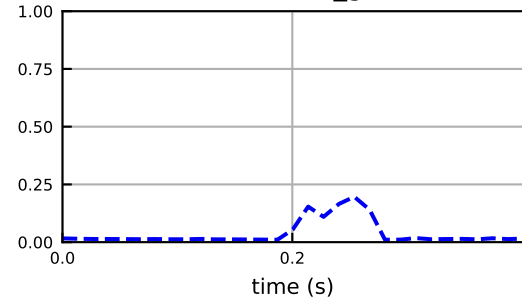
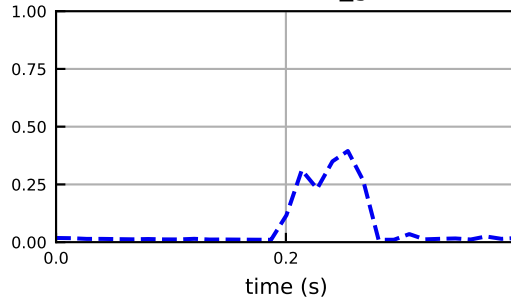
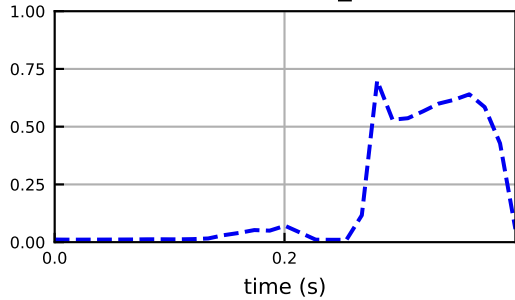
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forcesetvas_int

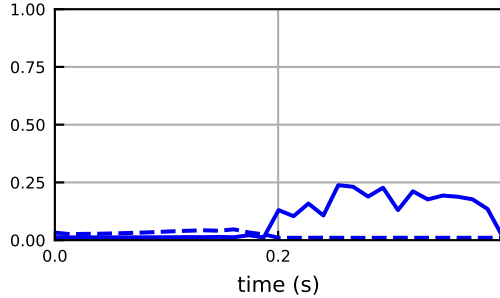


- D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (right leg)
- - D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (left leg)

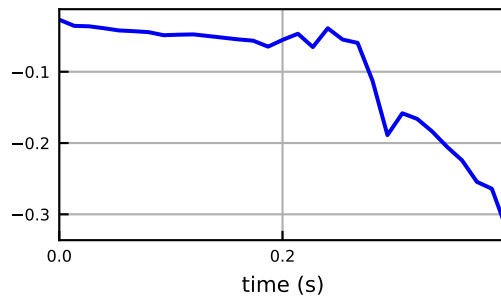


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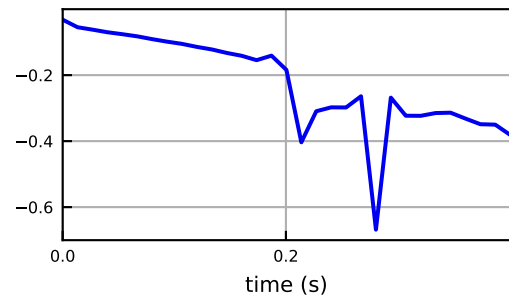
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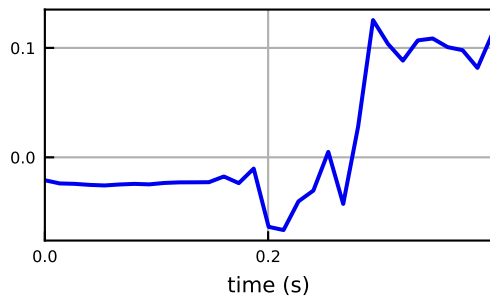
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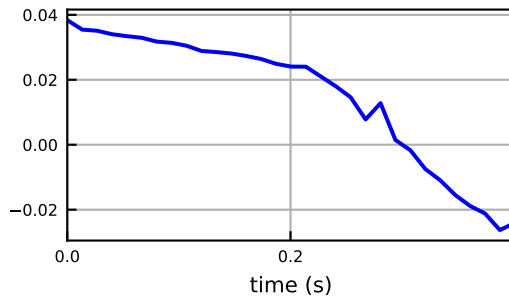
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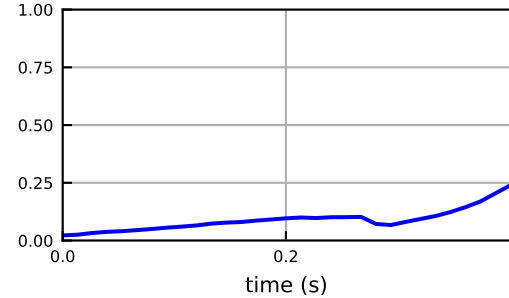
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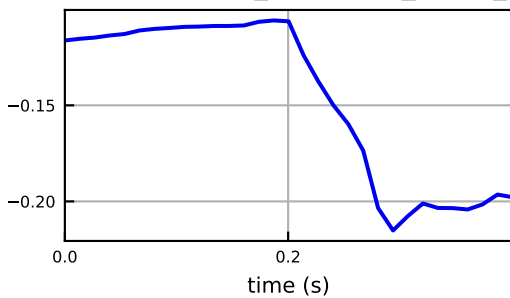
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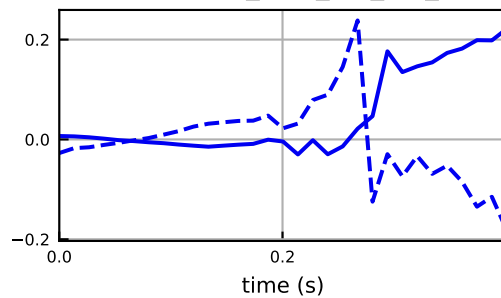
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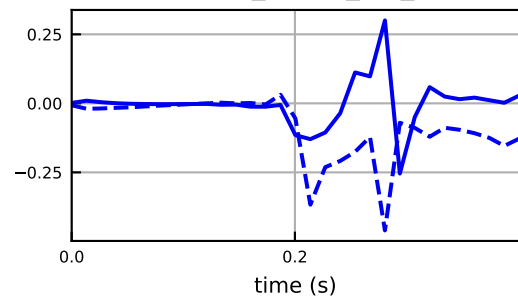
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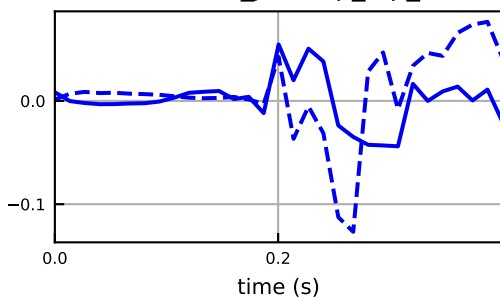
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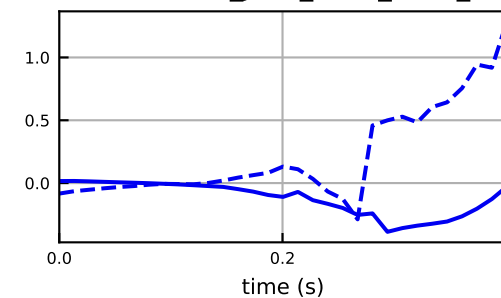
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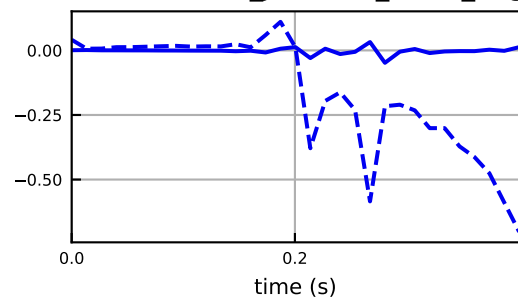
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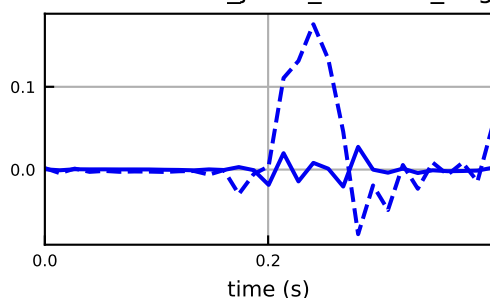
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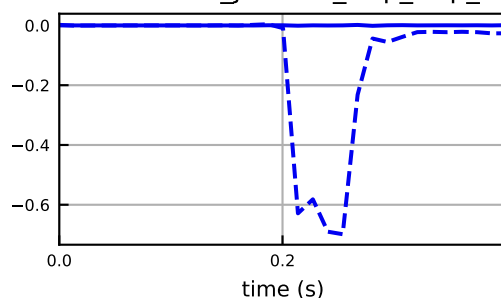
forcesetreserve_joi...nkle_ankle_angle



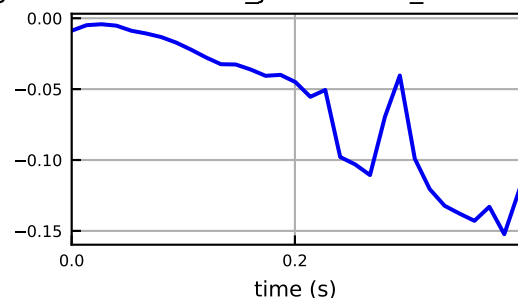
forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension



— D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (right leg)
- - D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_-10/solution.sto (left leg)

forcesetreserve_joi...k_lumbar_bending forcesetreserve_joi..._lumbar_rotation

