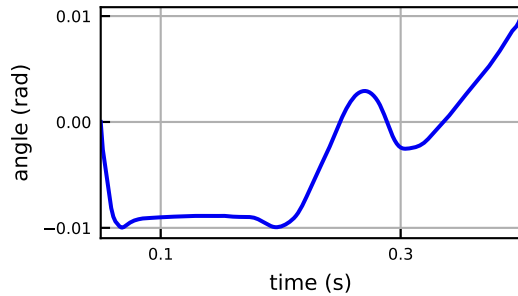
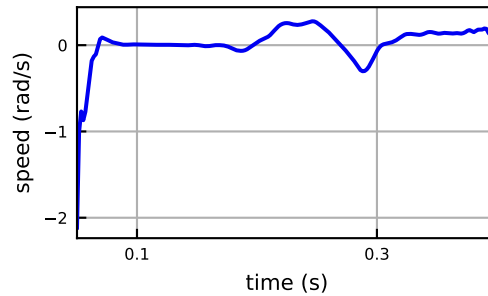


— D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (left leg)

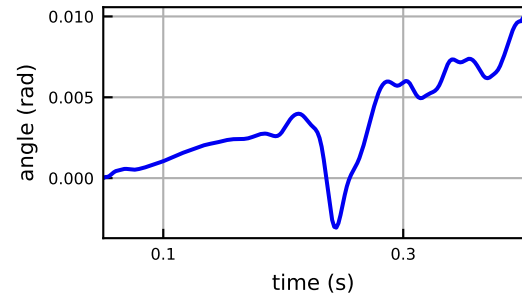
pelvis_tilt/value



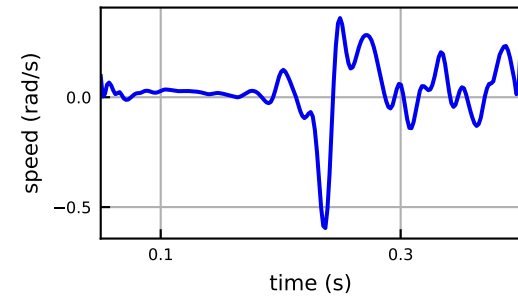
pelvis_tilt/speed



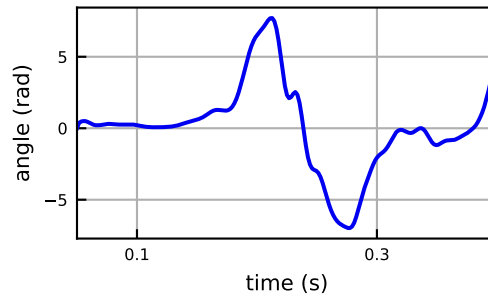
pelvis_list/value



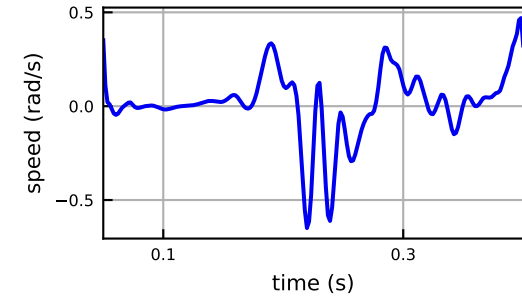
pelvis_list/speed



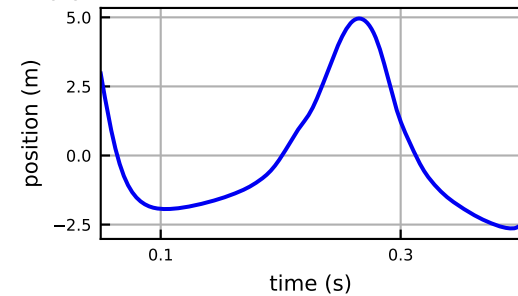
pelvis_rotation/value



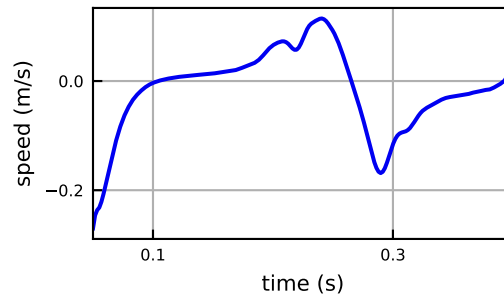
pelvis_rotation/speed



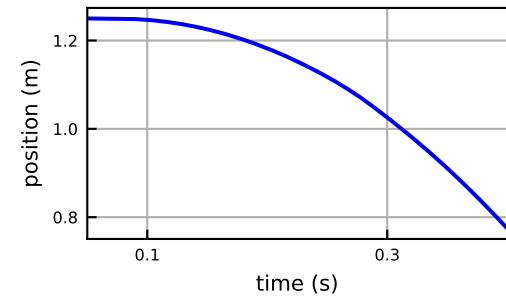
pelvis_tx/value



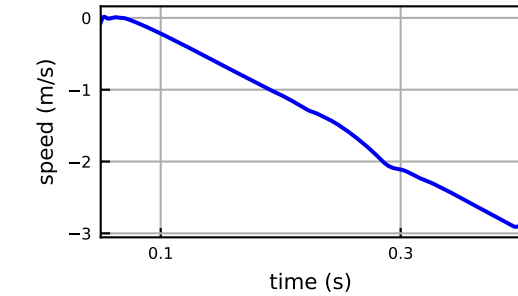
pelvis_tx/speed



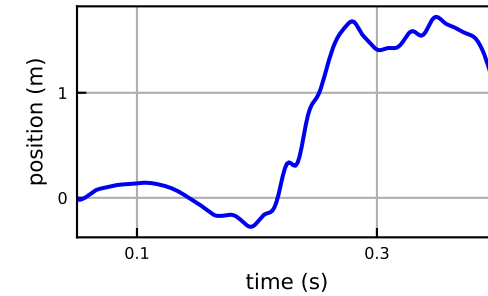
pelvis_ty/value



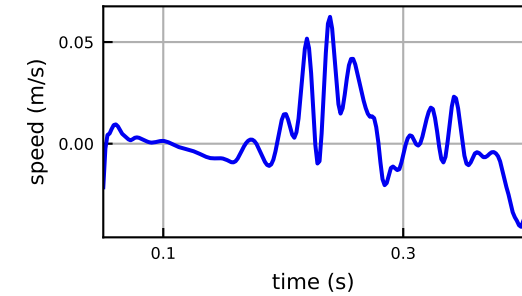
pelvis_ty/speed



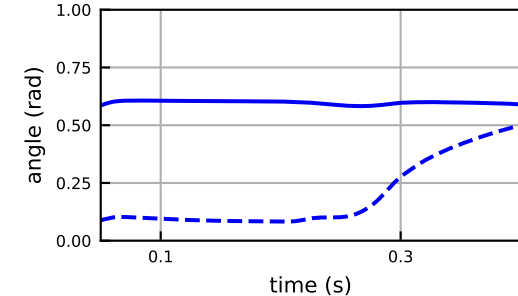
pelvis_tz/value



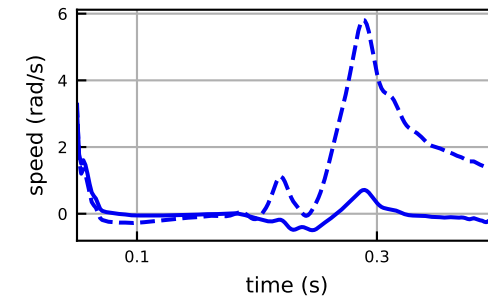
pelvis_tz/speed



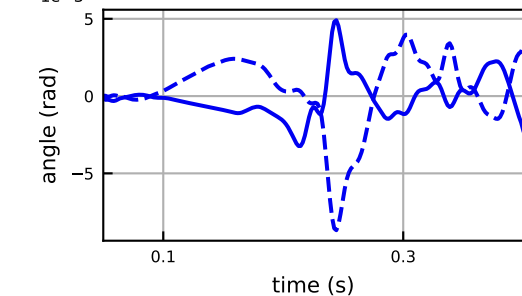
hip_flexion/value



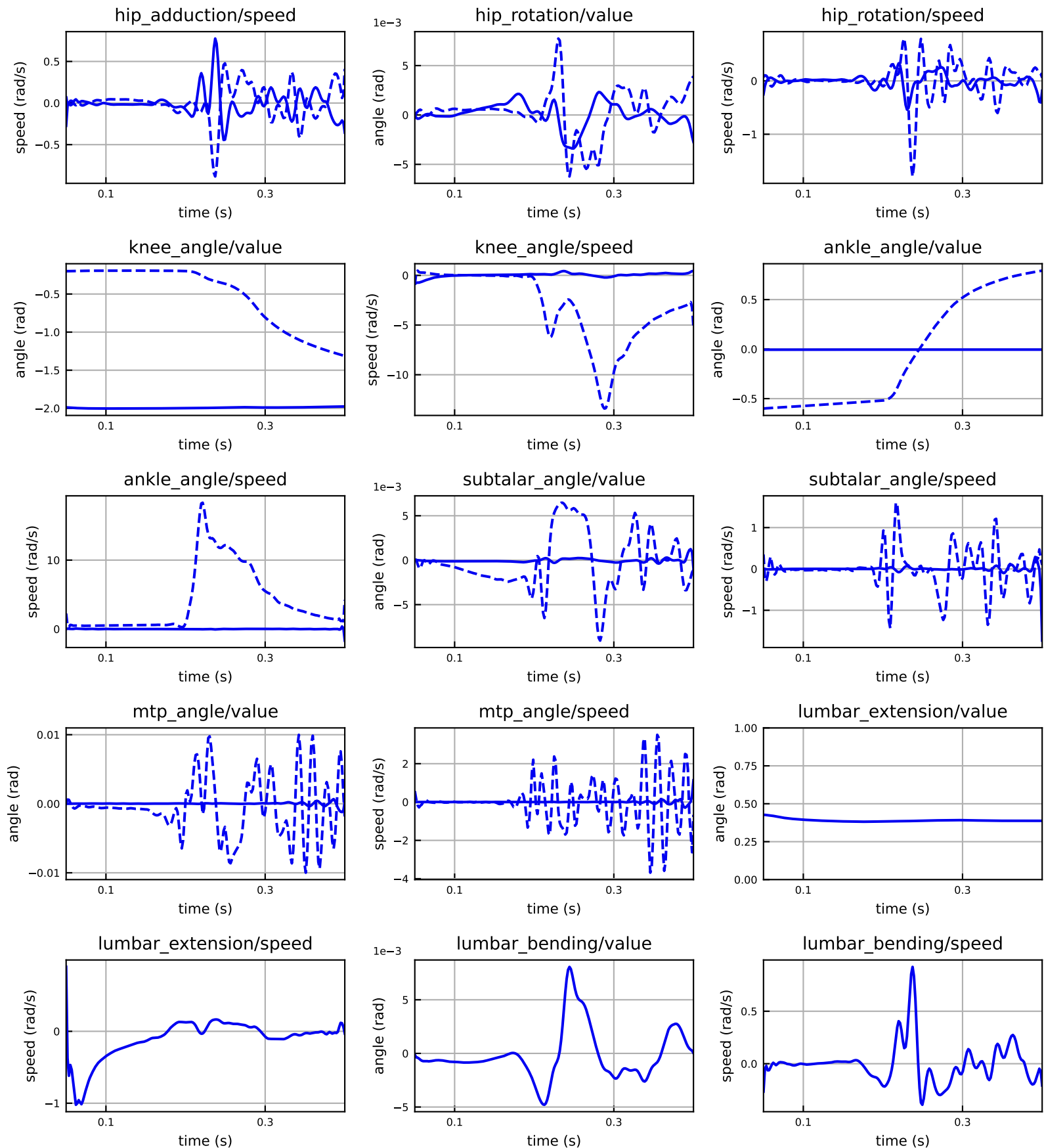
hip_flexion/speed



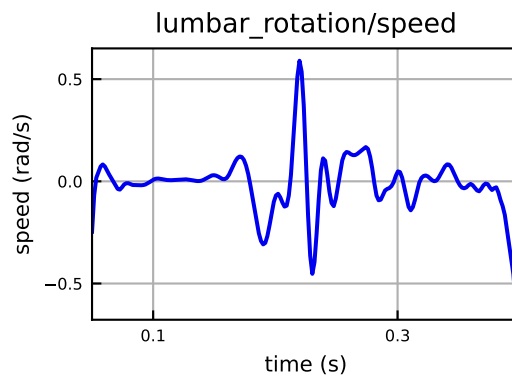
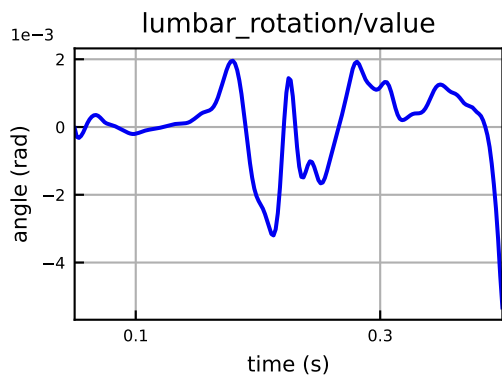
hip_adduction/value



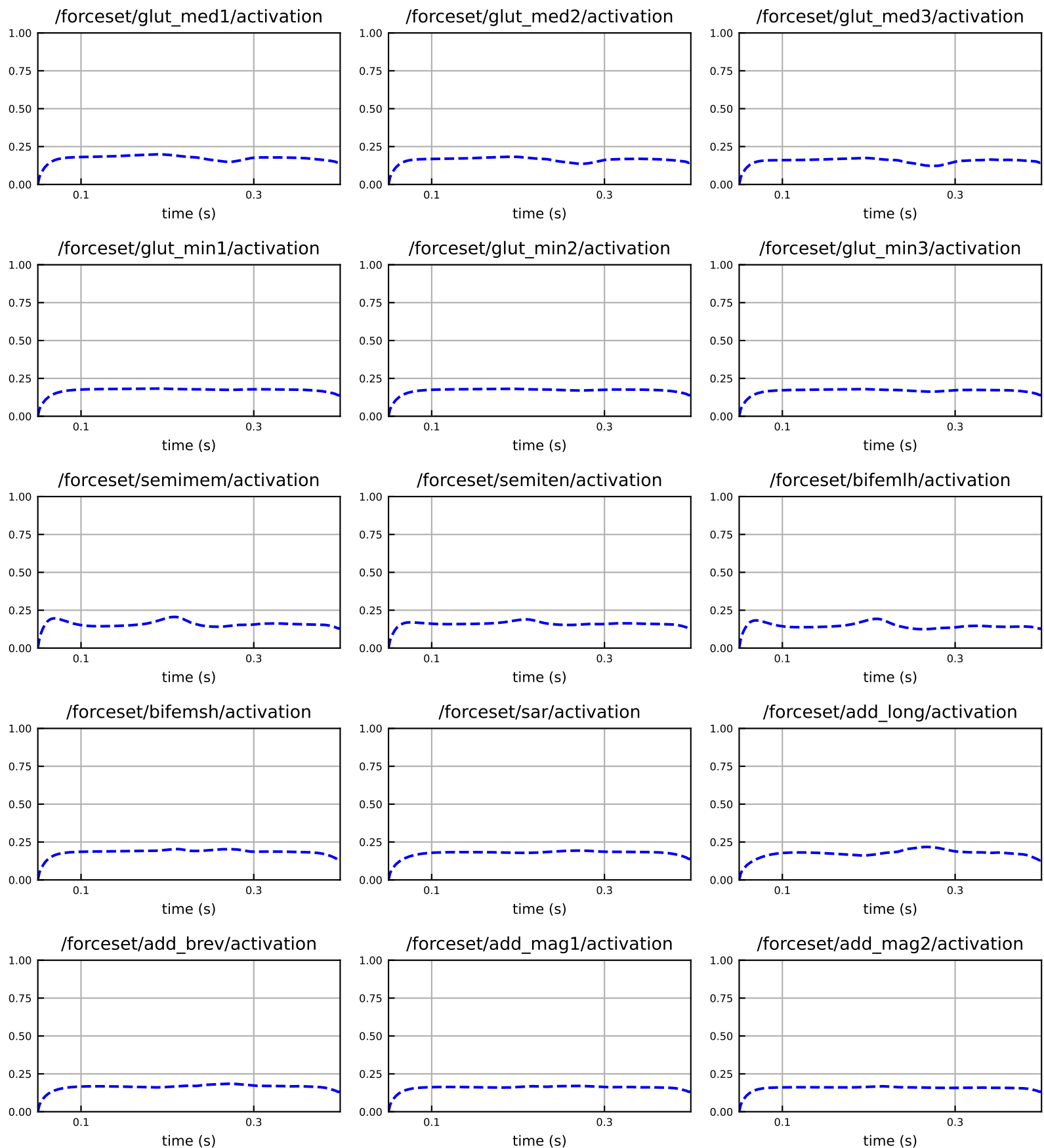
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- - - D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (left leg)



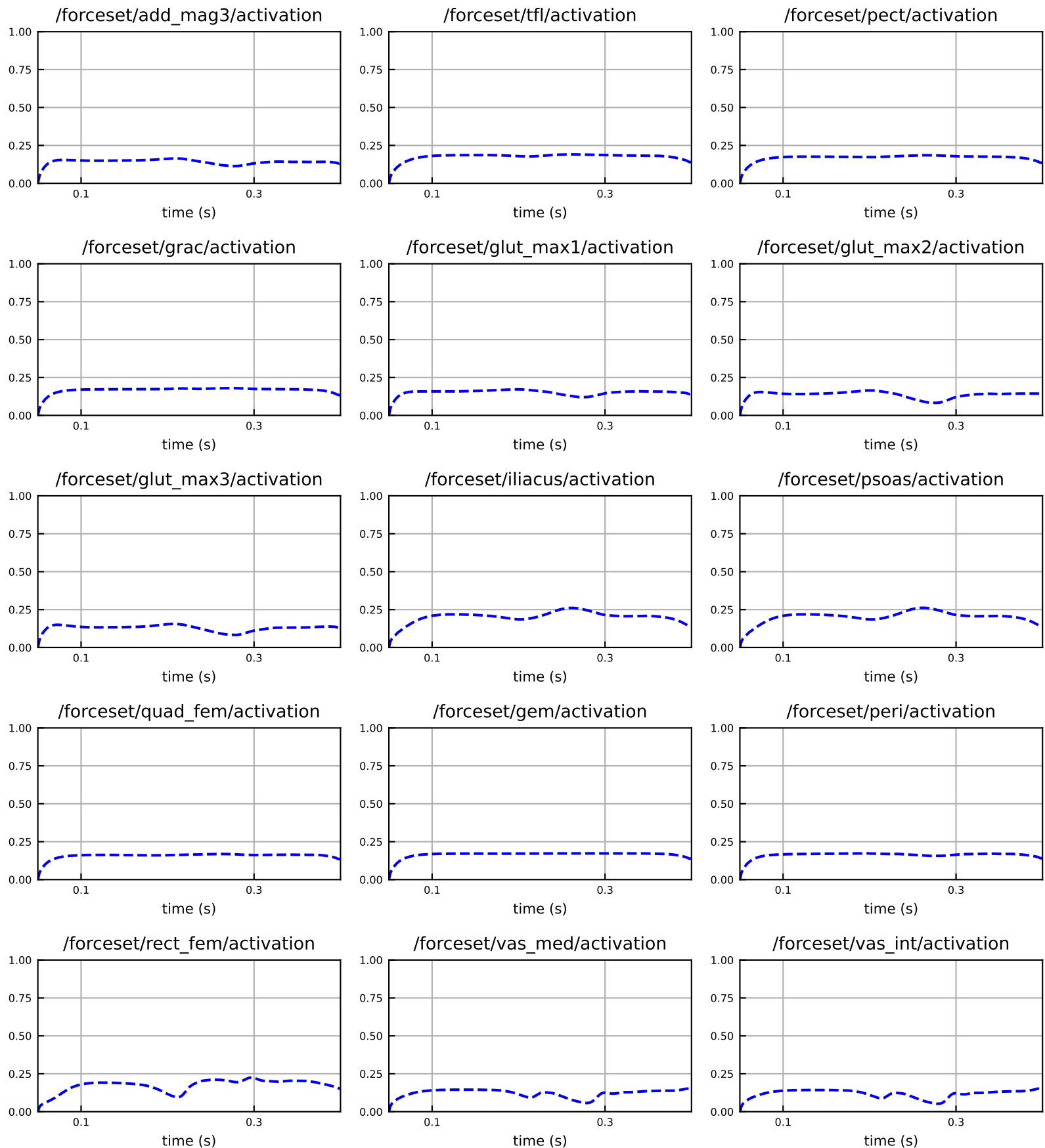
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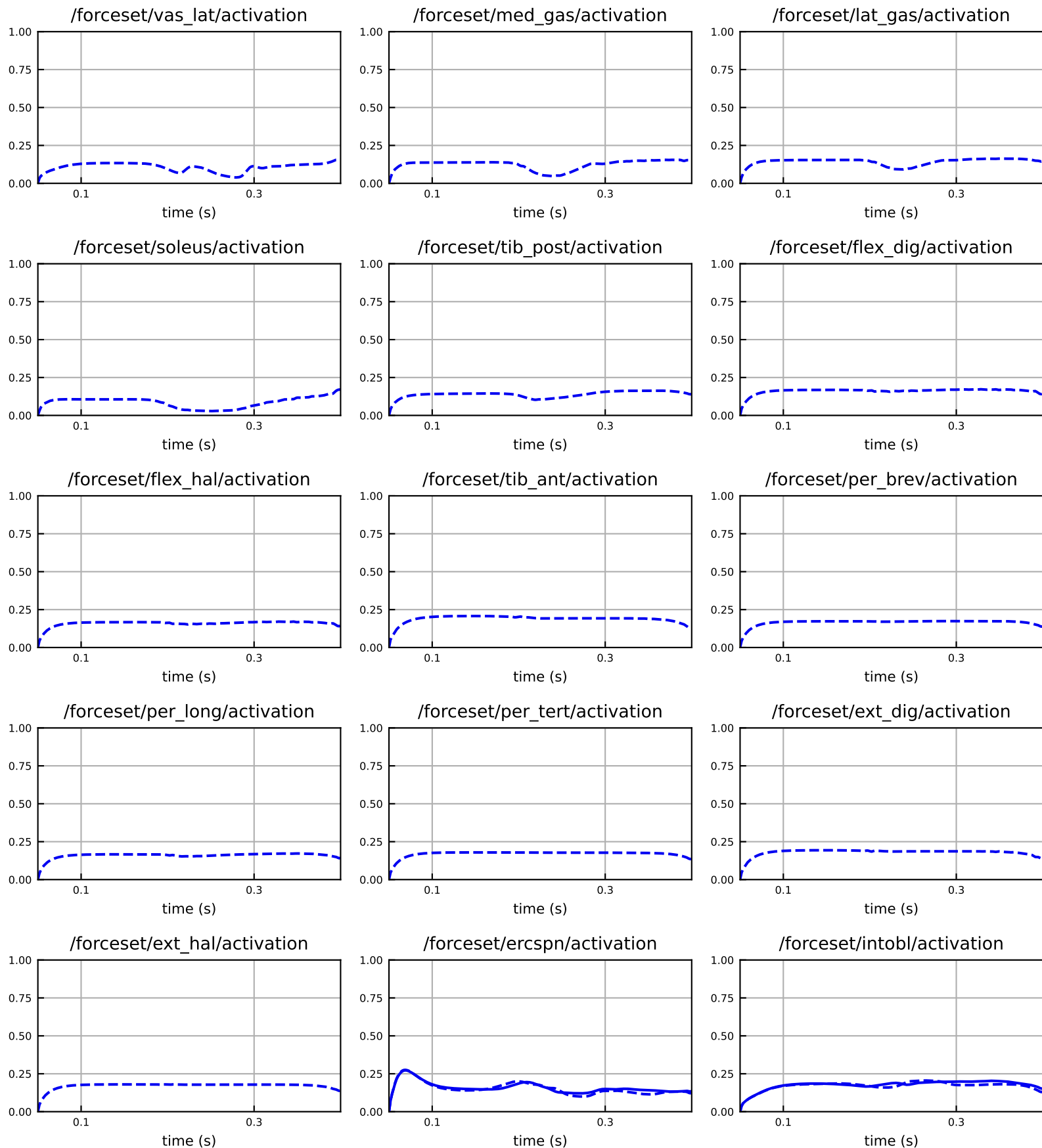
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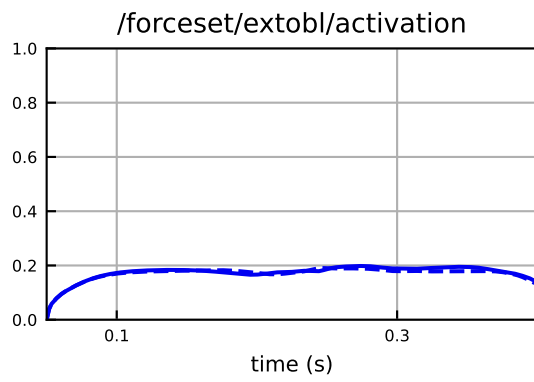
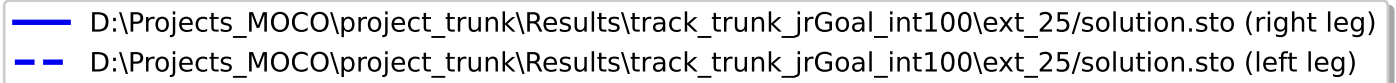


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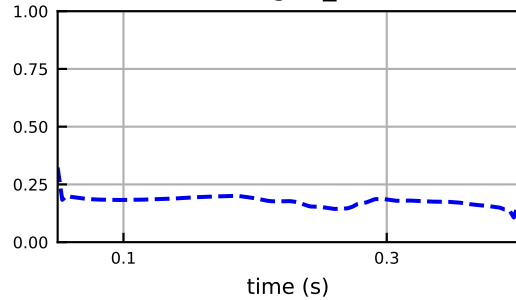
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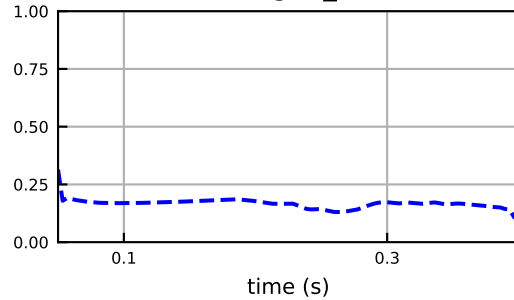


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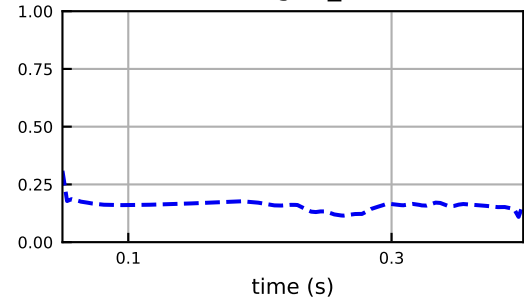
forcesetglut_med1



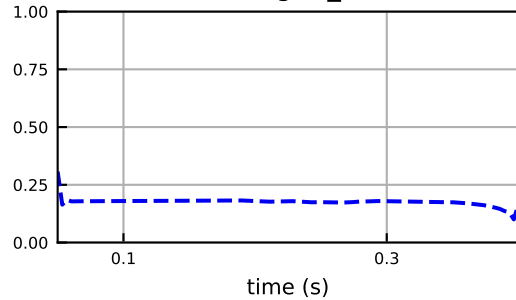
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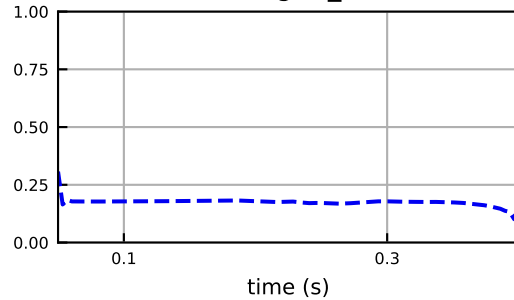
forcesetglut_med3



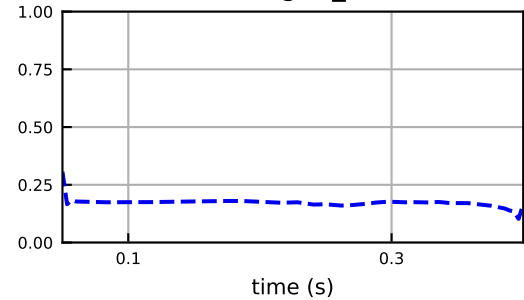
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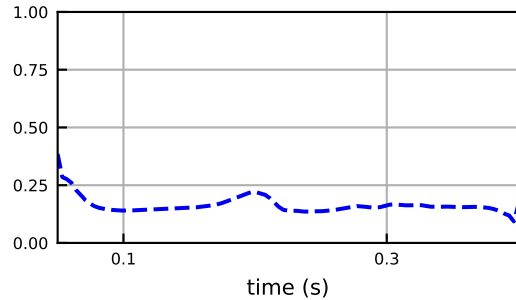
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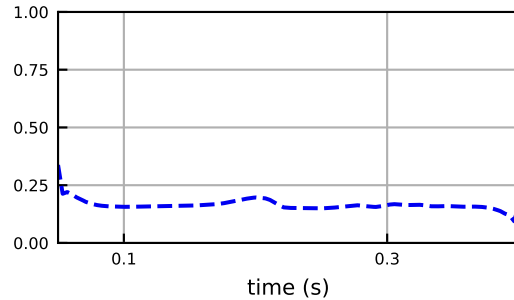
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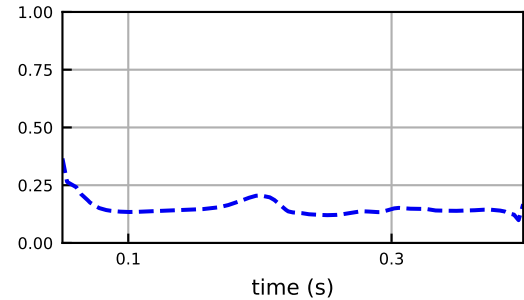
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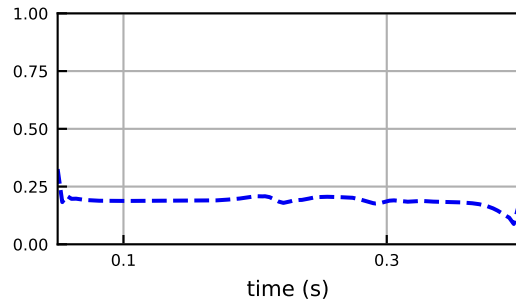
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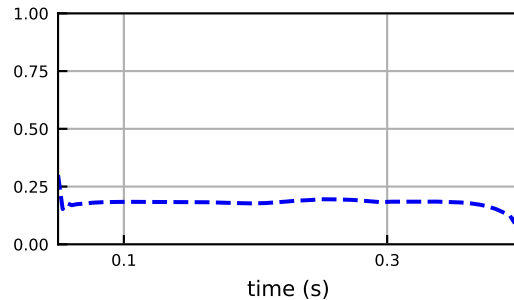
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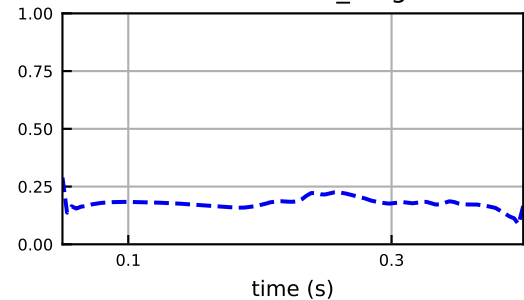
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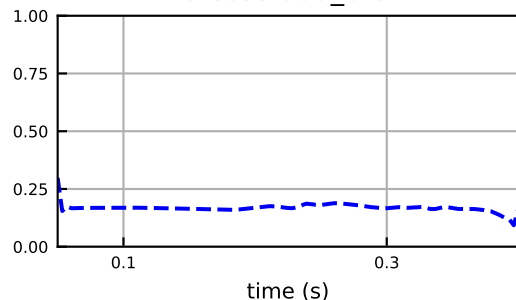
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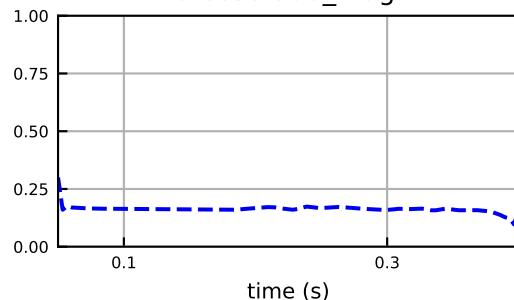
forcesetadd_long



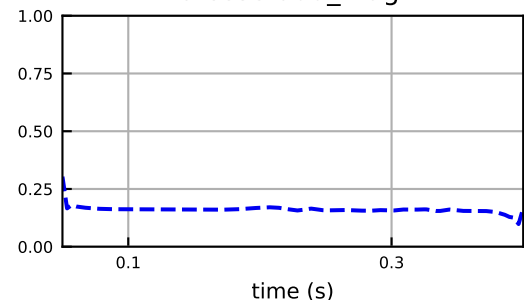
forcesetadd_brev



forcesetadd_mag1

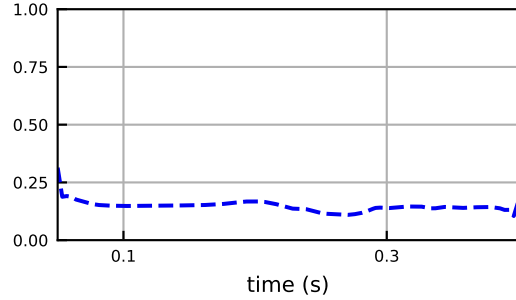


forcesetadd_mag2

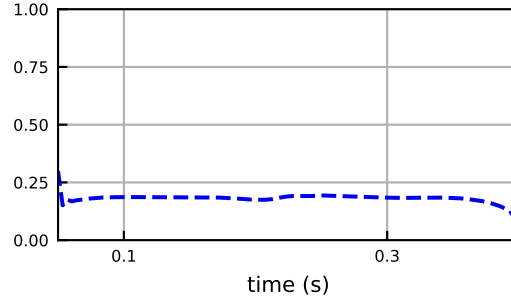


— D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (left leg)

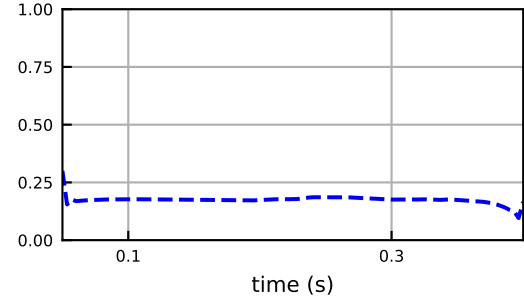
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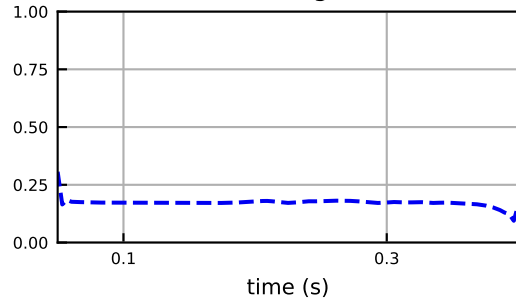
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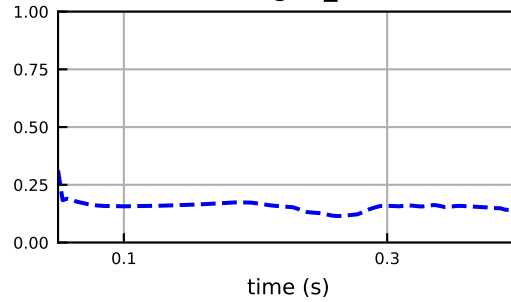
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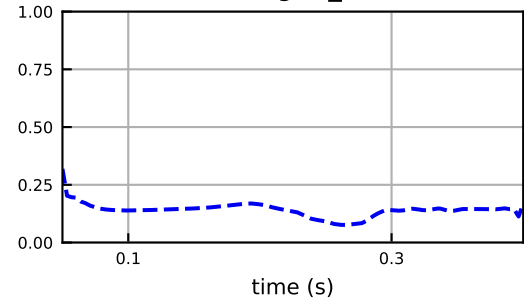
forcesetgrac



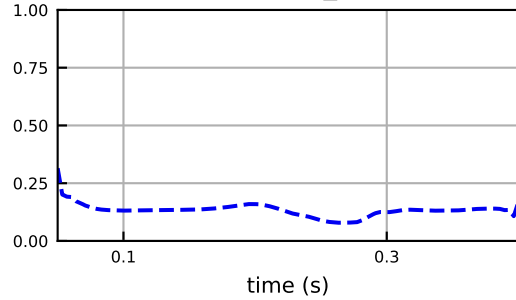
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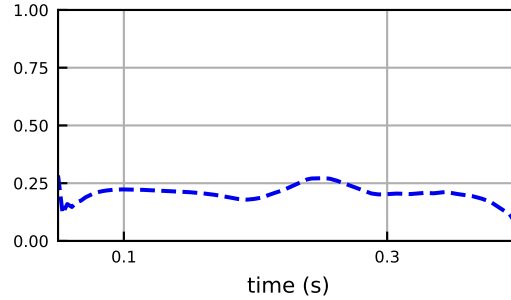
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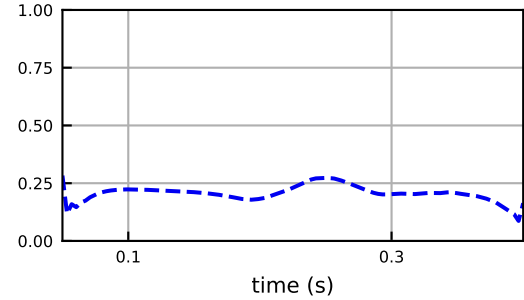
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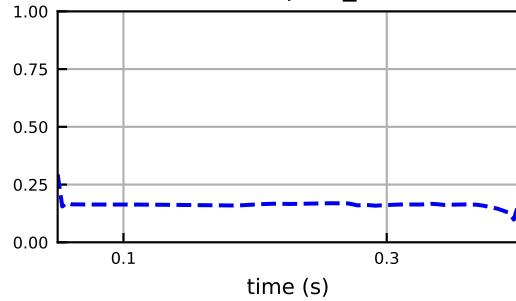
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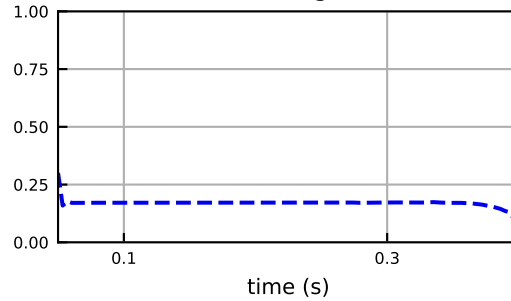
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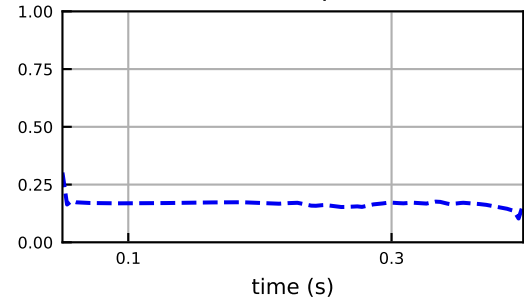
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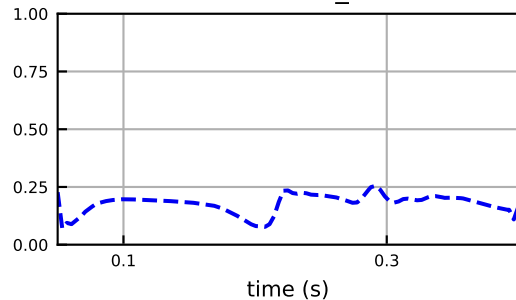
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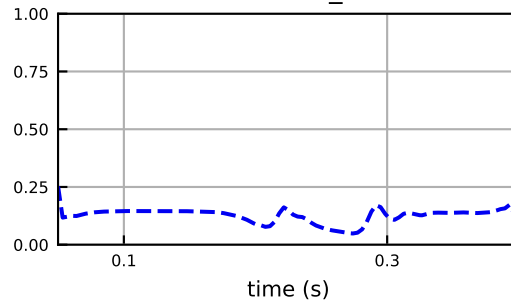
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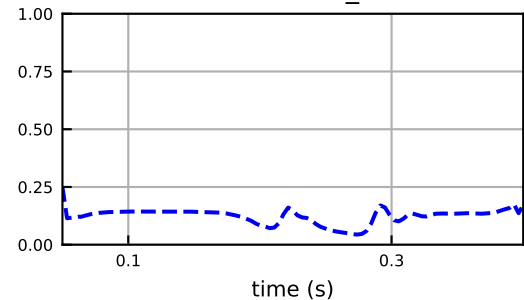
forcesetrect_fem



forcesetvas_med

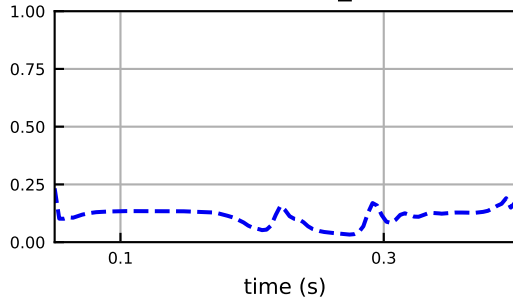


forcesetvas_int

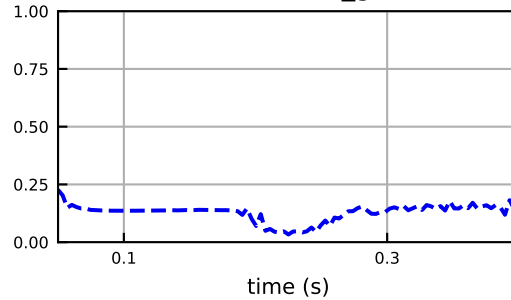


— D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (left leg)

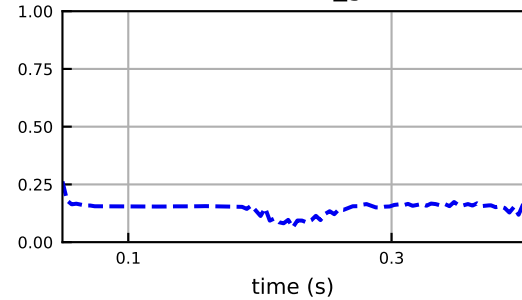
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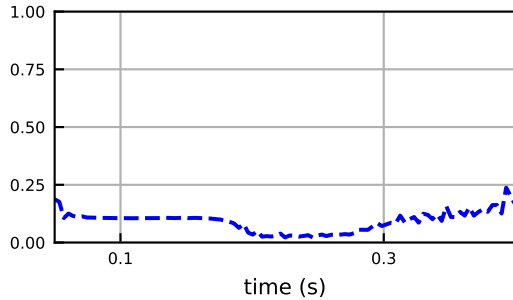
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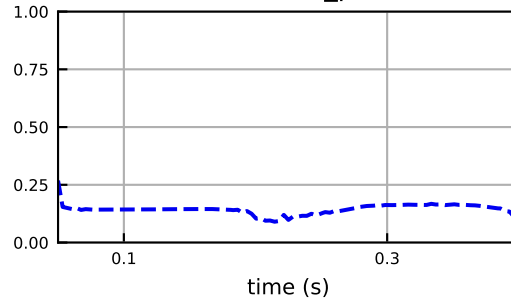
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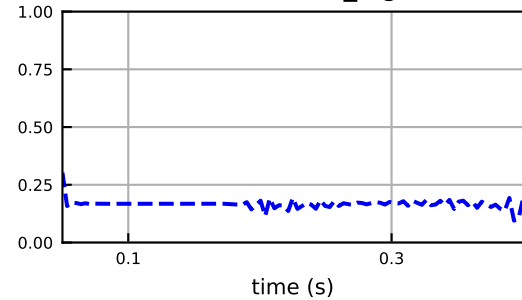
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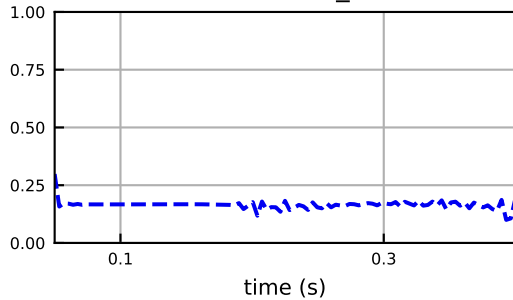
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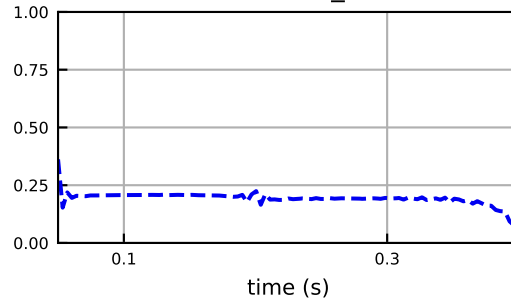
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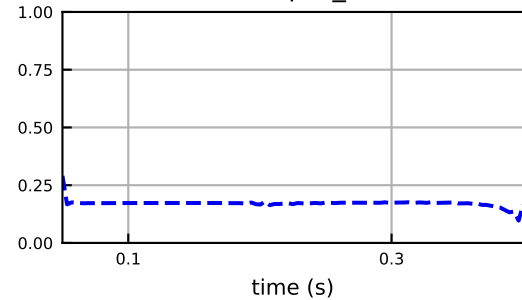
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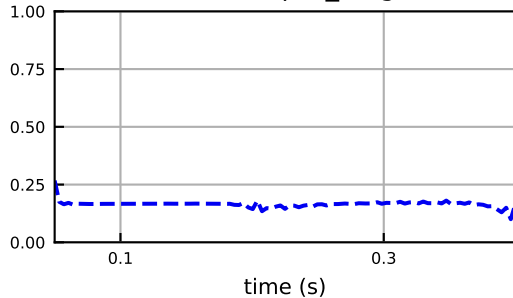
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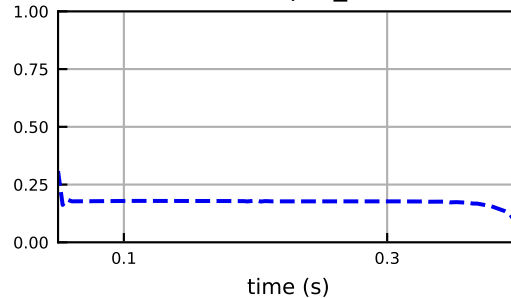
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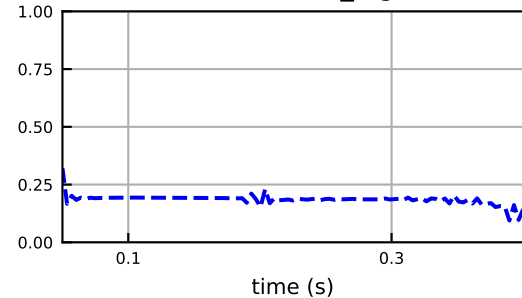
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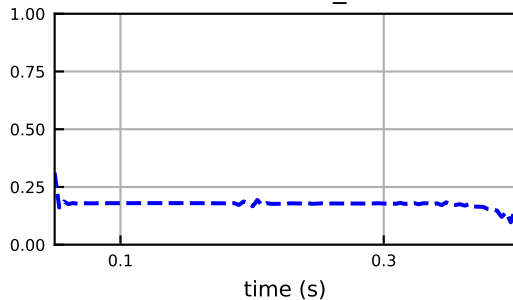
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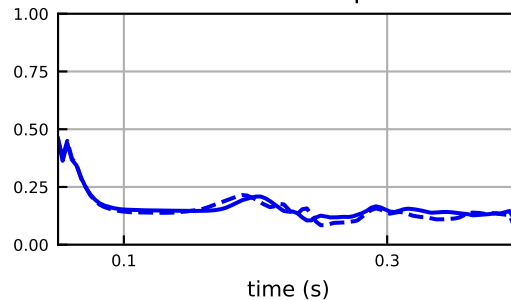
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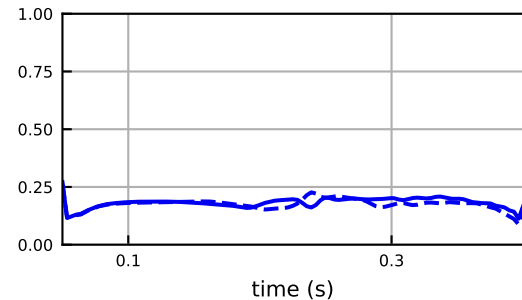
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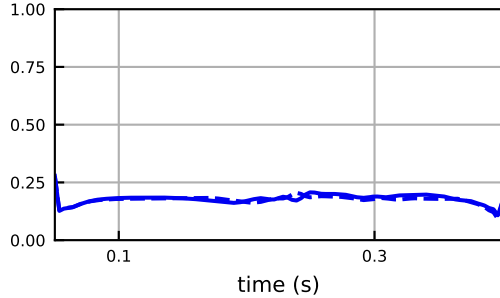


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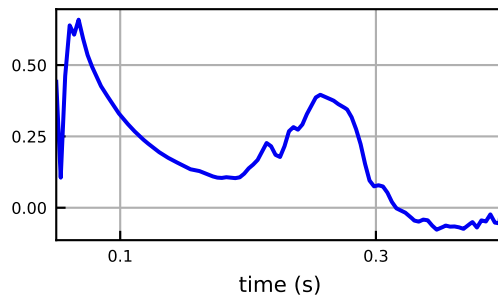


— D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25\solution.sto (left leg)

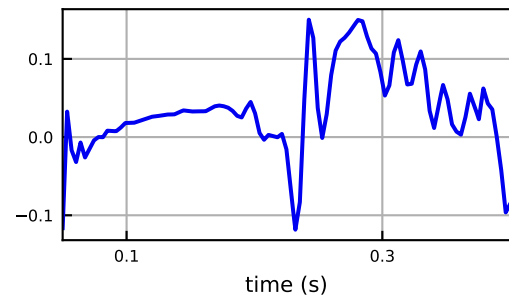
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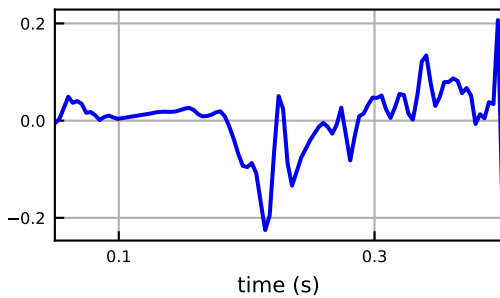
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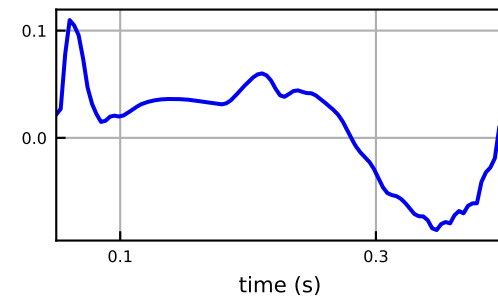
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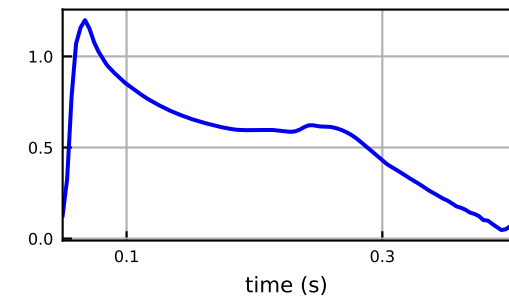
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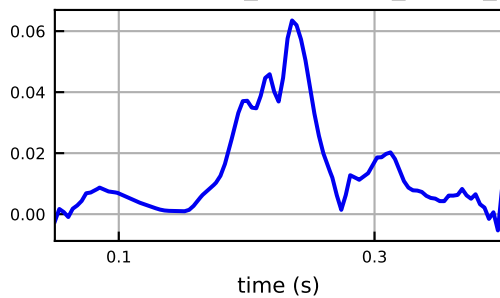
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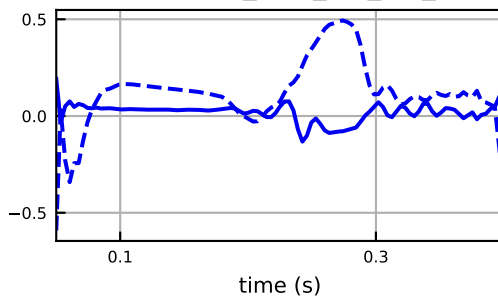
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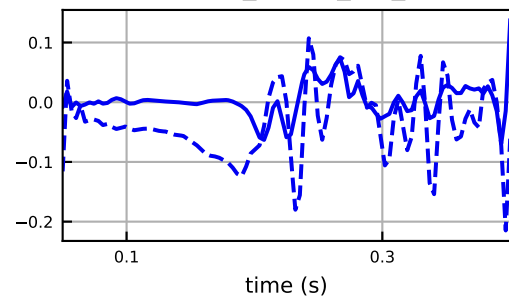
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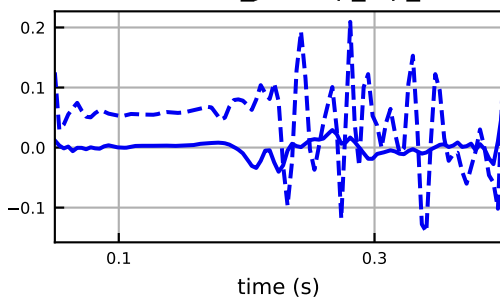
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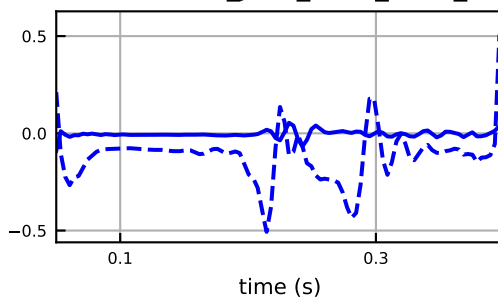
forcesetreserve_joi...ip_hip_adduction



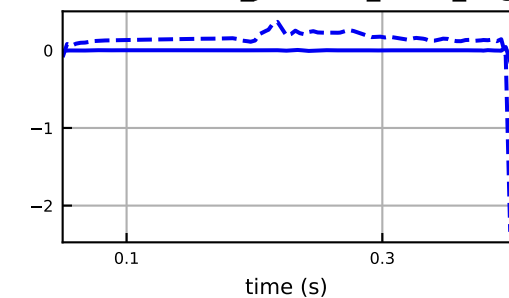
forcesetreserve_joi...hip_hip_rotation



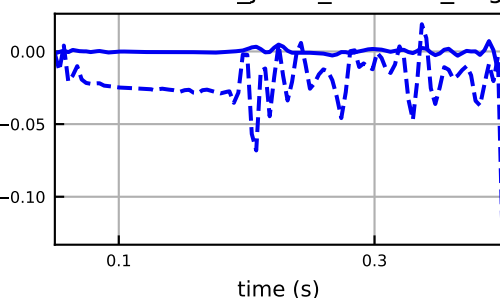
forcesetreserve_joi...knee_knee_angle



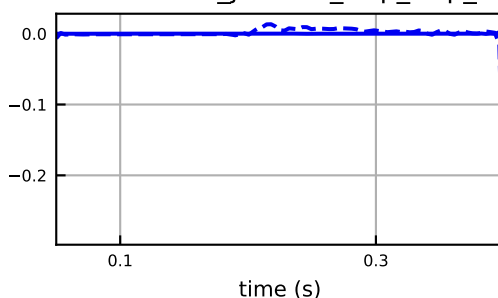
forcesetreserve_joi...nkle_ankle_angle



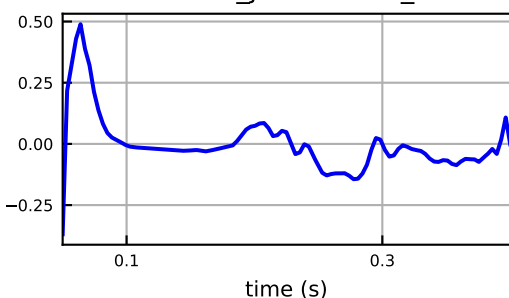
forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension



— D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25/solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_25/solution.sto (left leg)

forcesetreserve_joi...k_lumbar_bending forcesetreserve_joi..._lumbar_rotation

