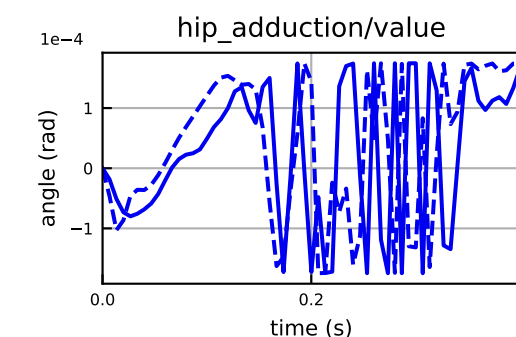
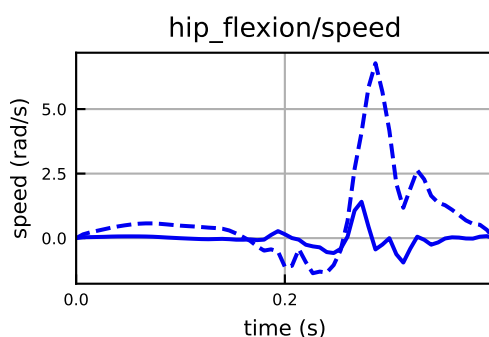
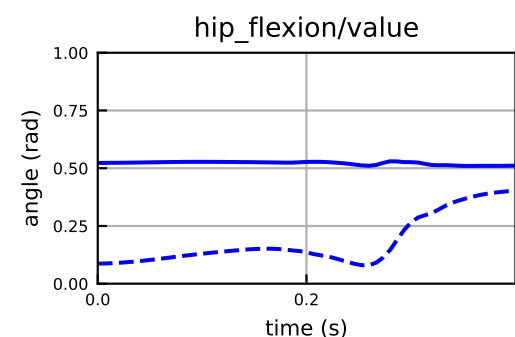
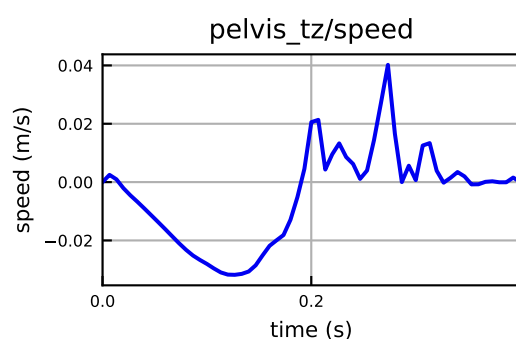
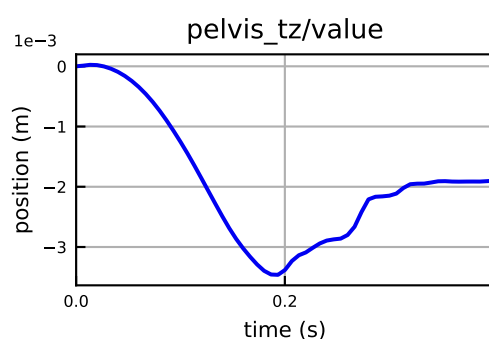
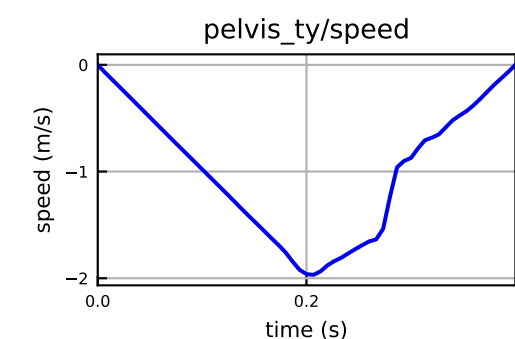
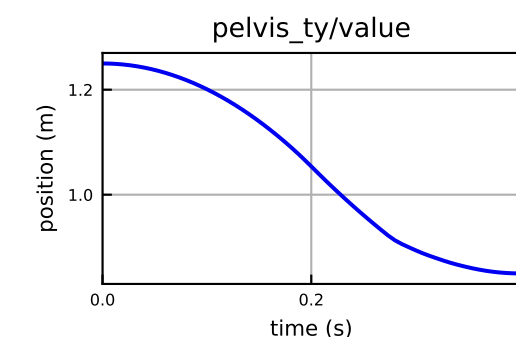
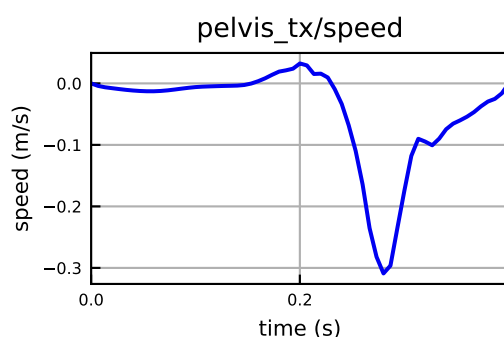
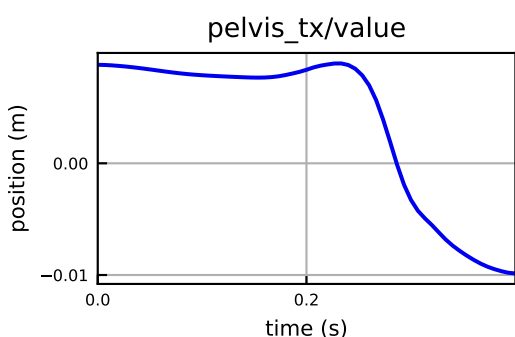
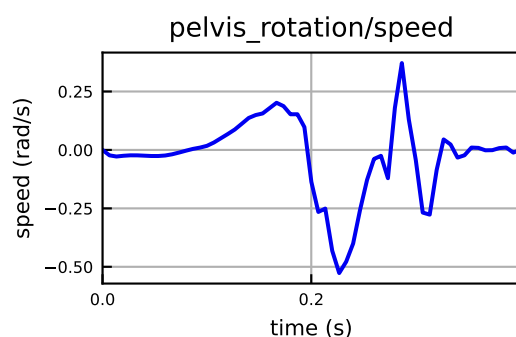
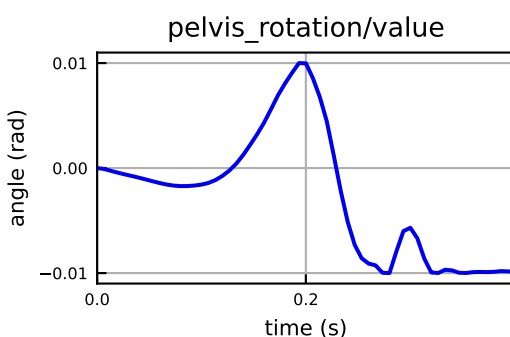
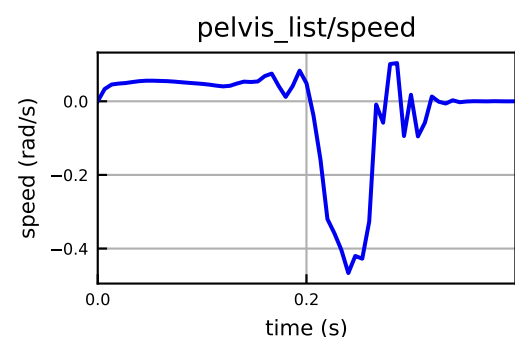
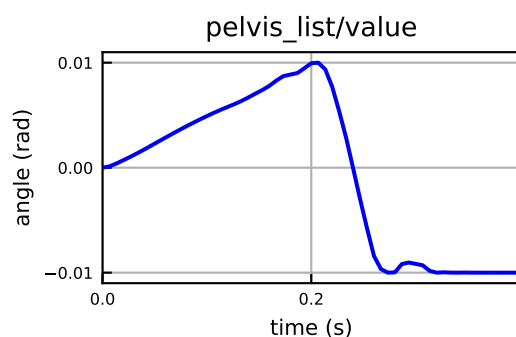
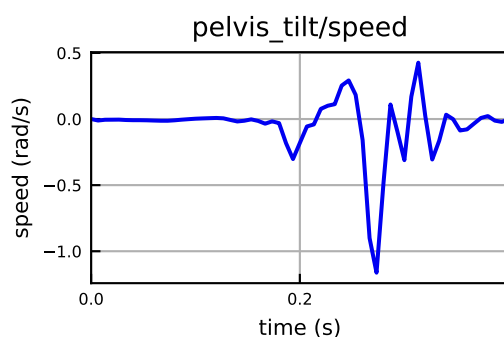
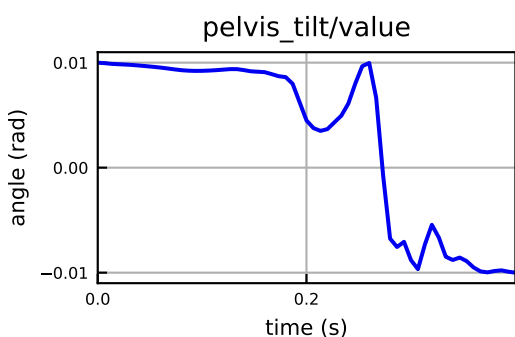
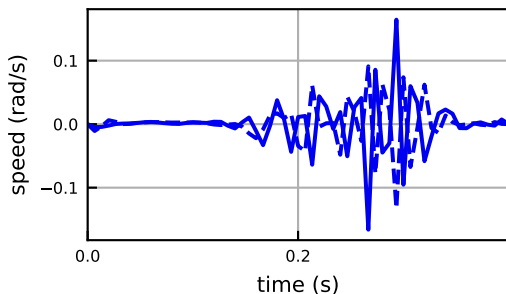


— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\rot\_-5\solution.sto (right leg)  
- - - D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\rot\_-5\solution.sto (left leg)

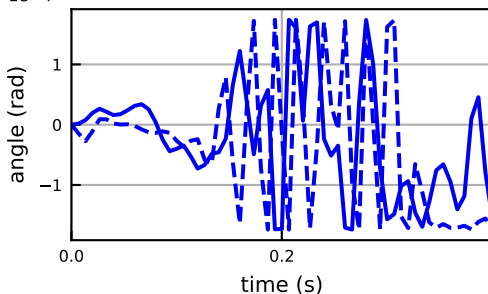


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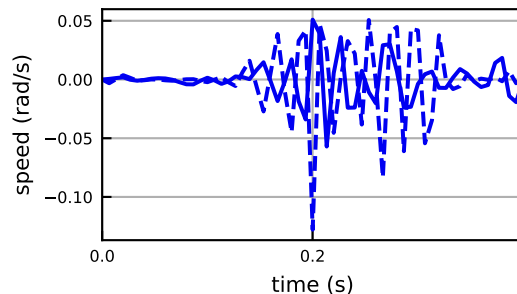
hip\_adduction/speed



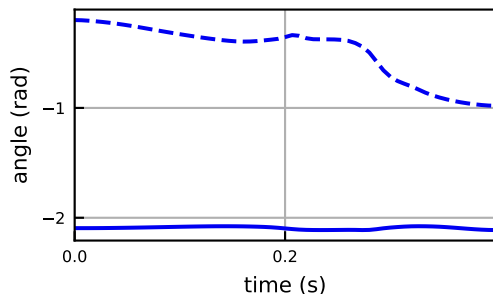
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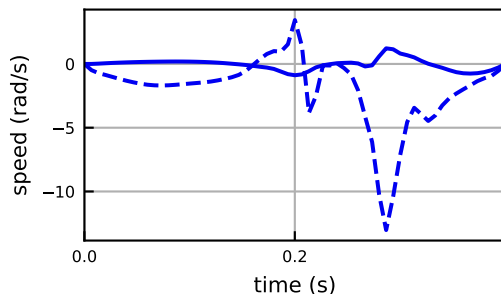
hip\_rotation/speed



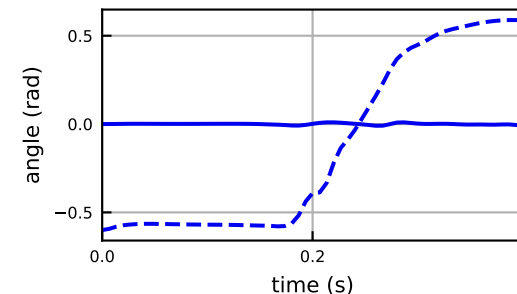
knee\_angle/value



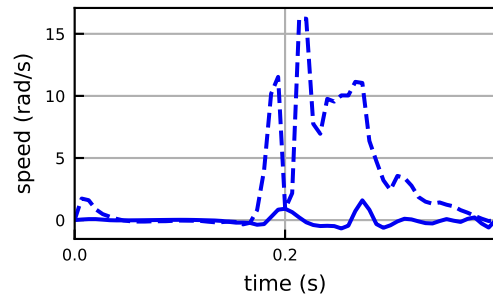
knee\_angle/speed



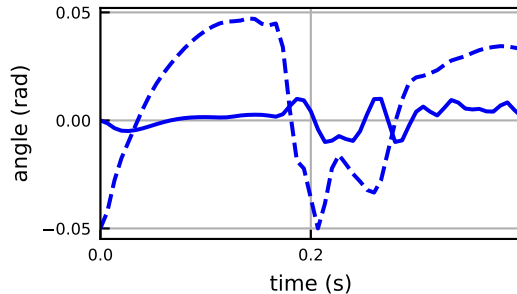
ankle\_angle/value



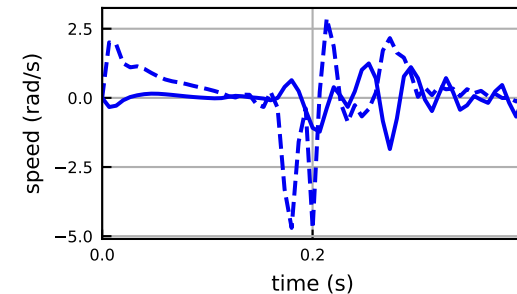
ankle\_angle/speed



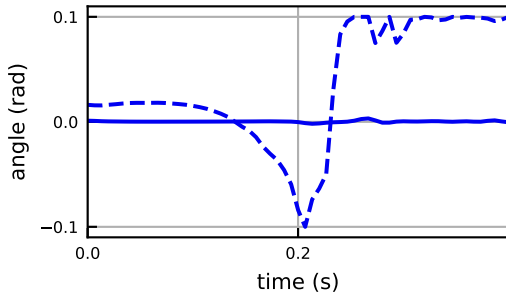
subtalar\_angle/value



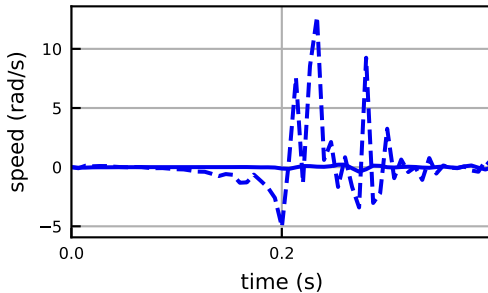
subtalar\_angle/speed



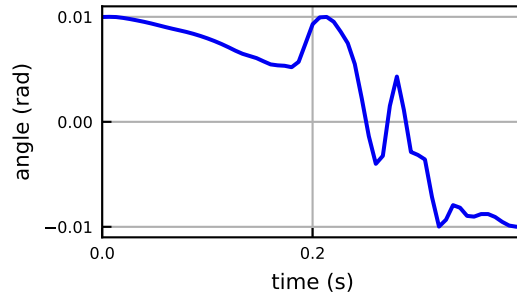
mtp\_angle/value



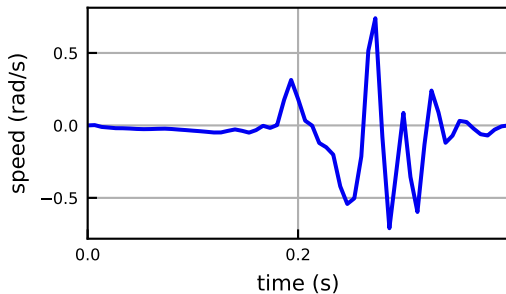
mtp\_angle/speed



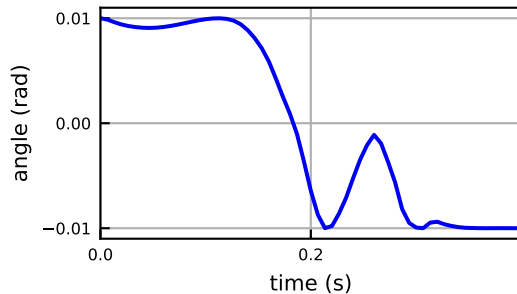
lumbar\_extension/value



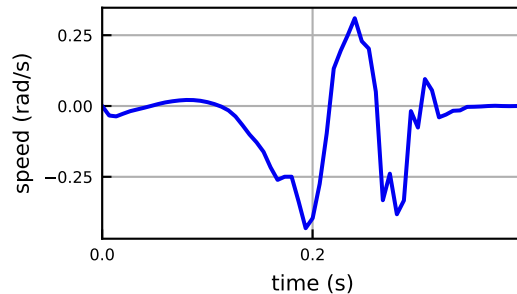
lumbar\_extension/speed



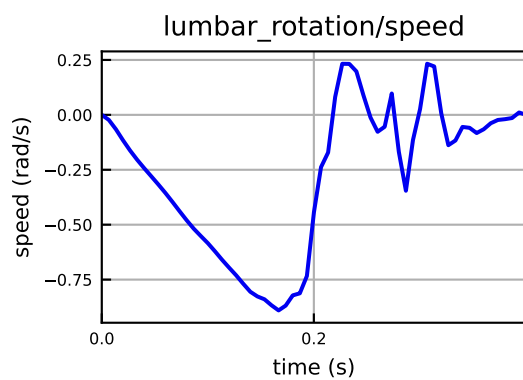
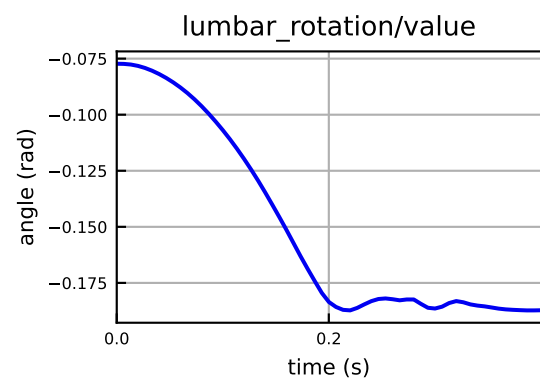
lumbar\_bending/value



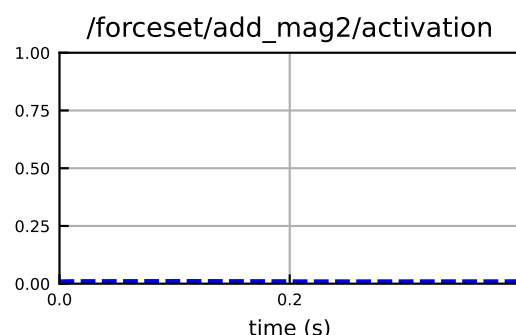
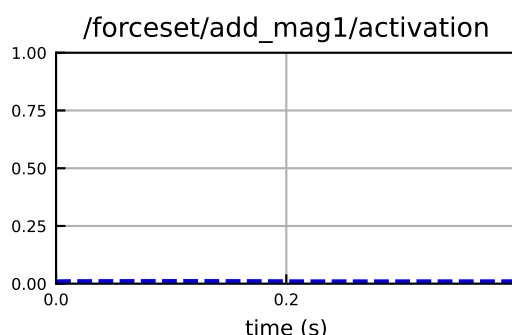
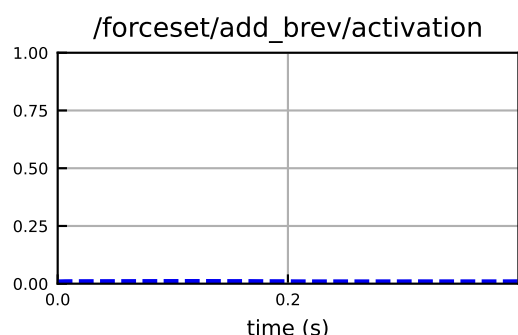
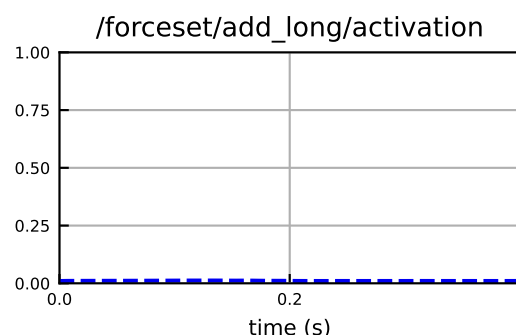
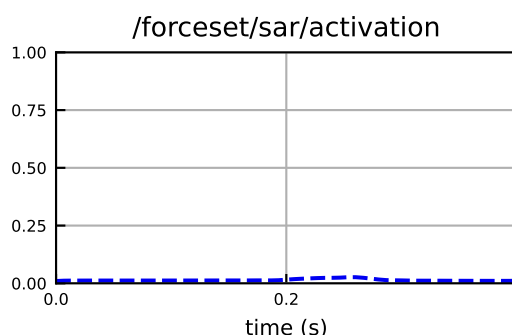
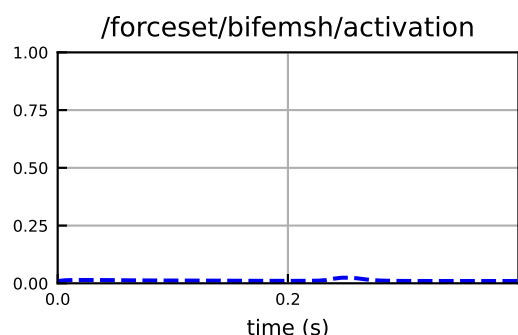
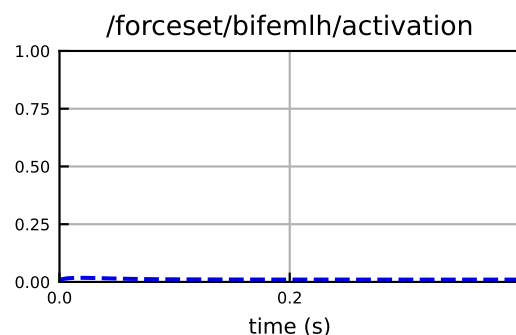
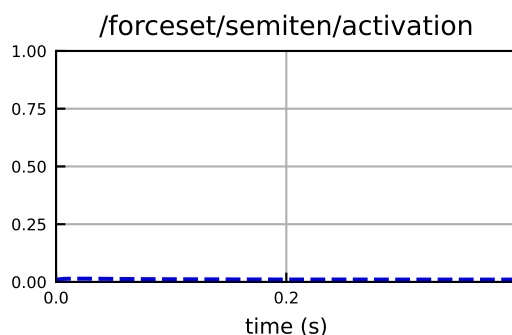
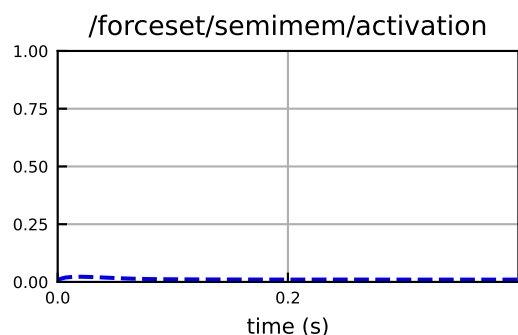
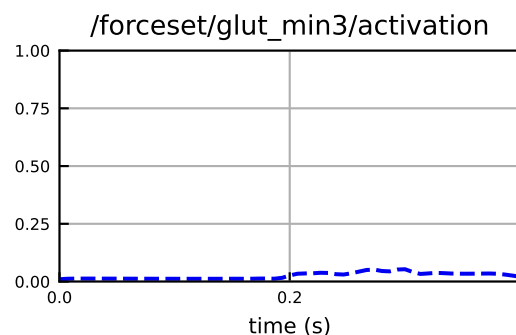
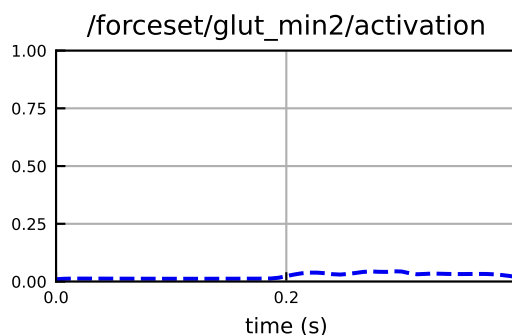
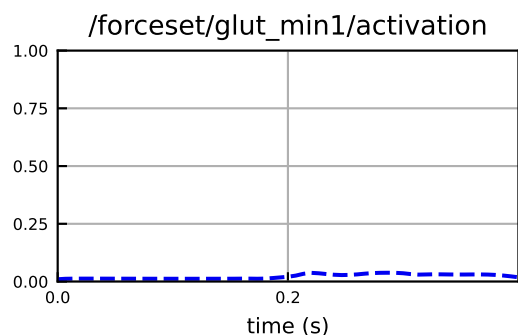
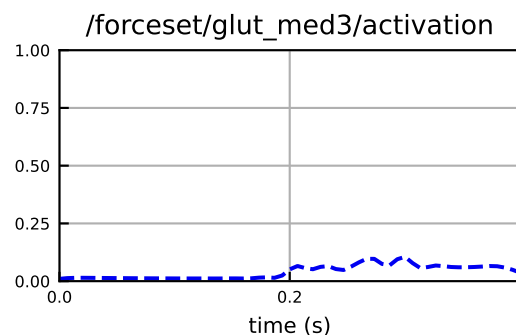
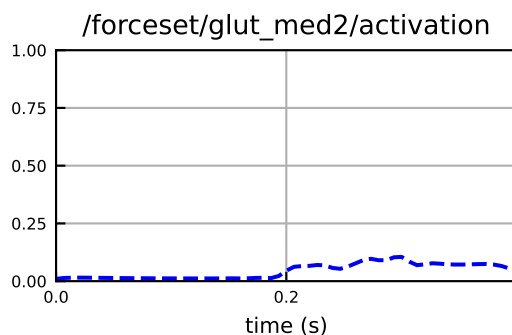
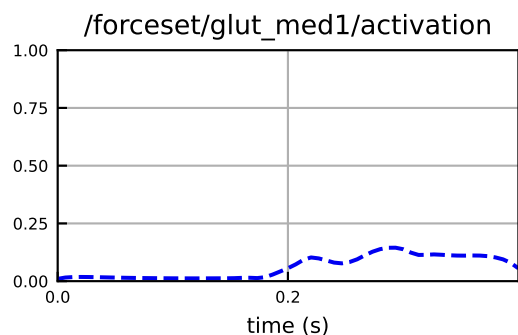
lumbar\_bending/speed



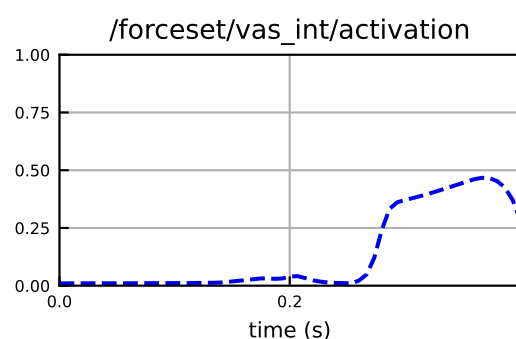
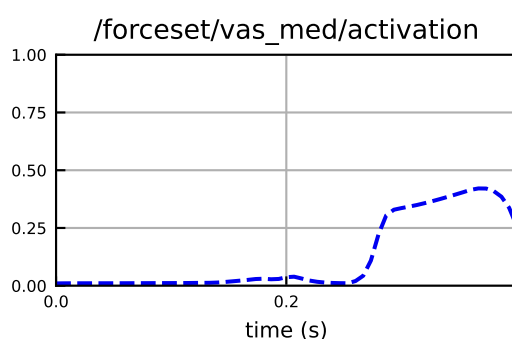
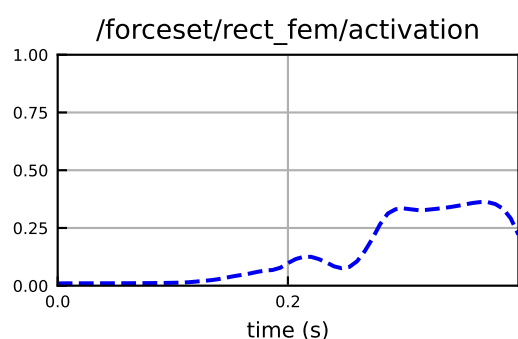
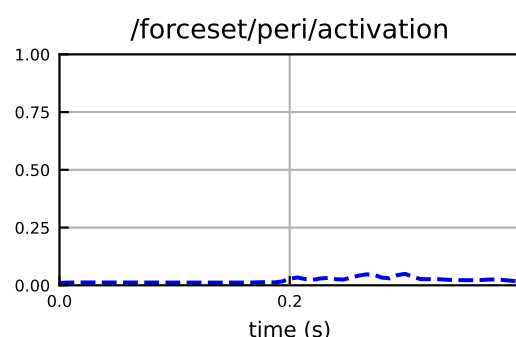
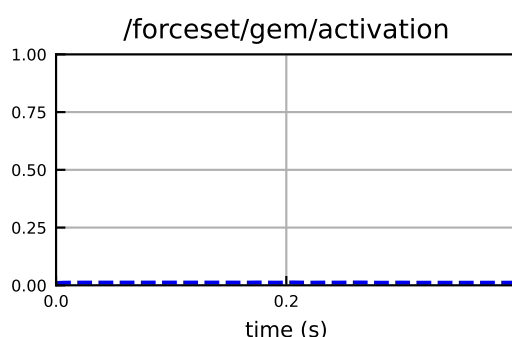
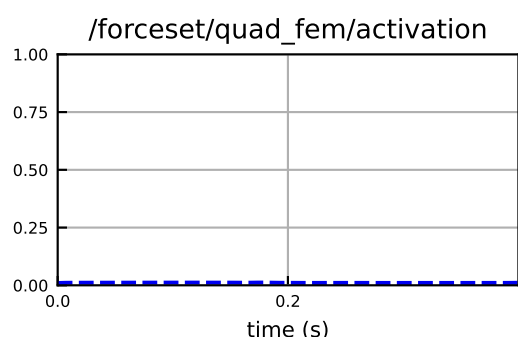
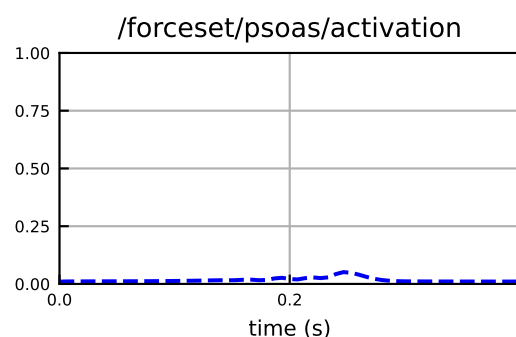
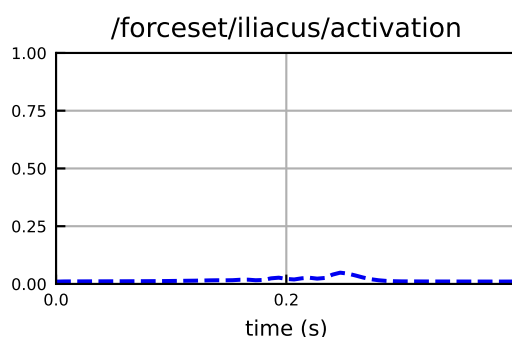
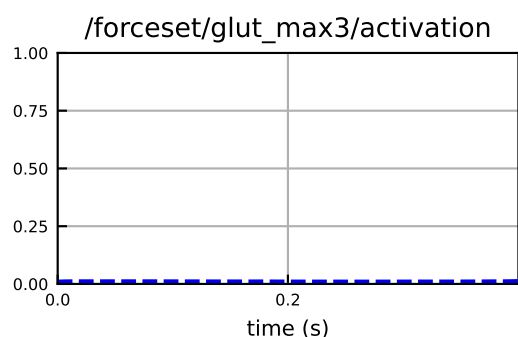
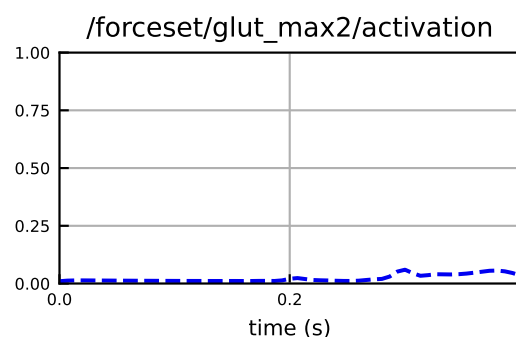
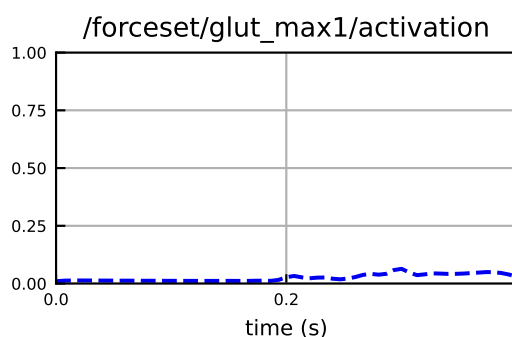
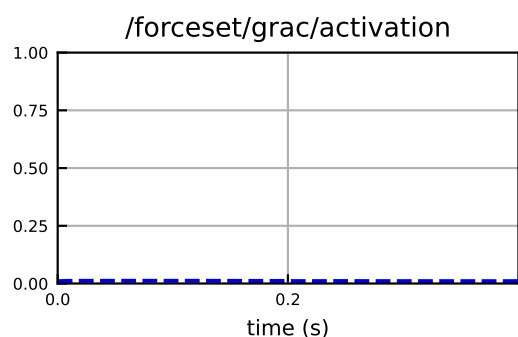
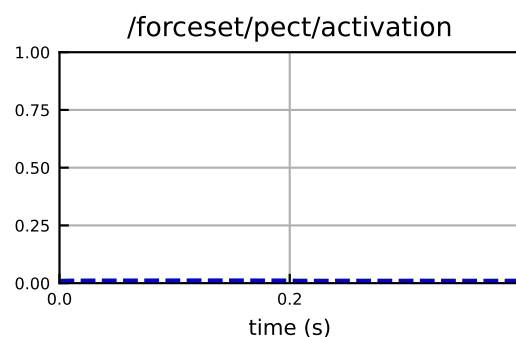
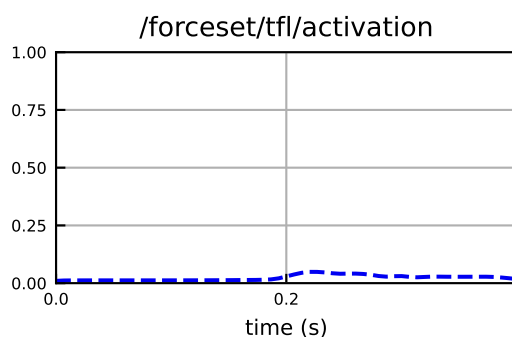
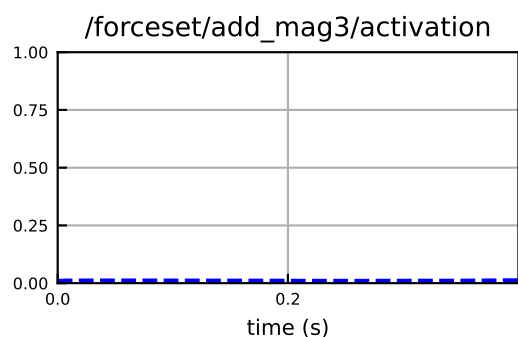
— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\rot\_-5/solution.sto (right leg)  
- - D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\rot\_-5/solution.sto (left leg)

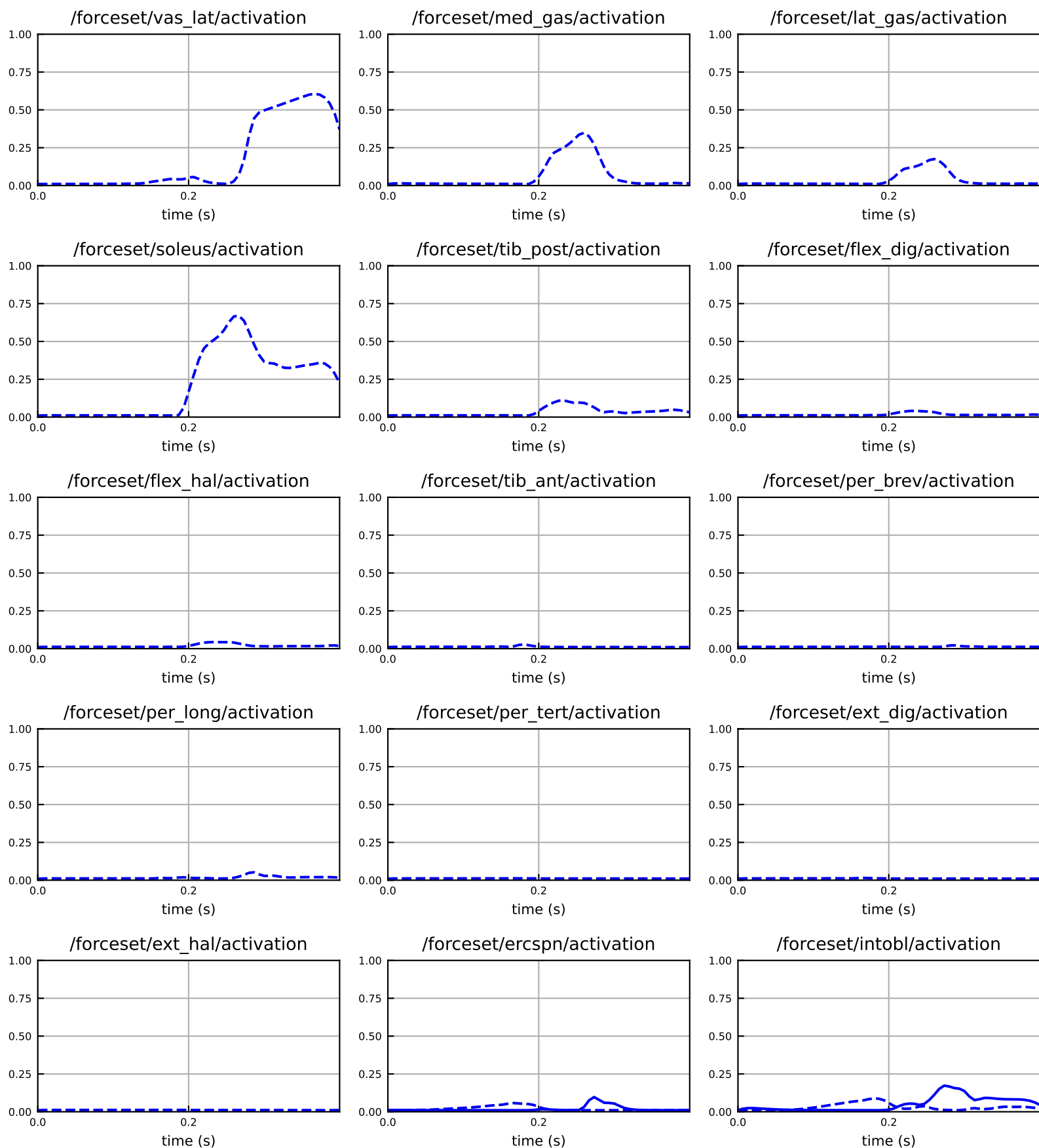
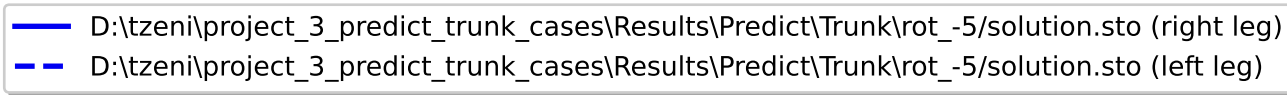


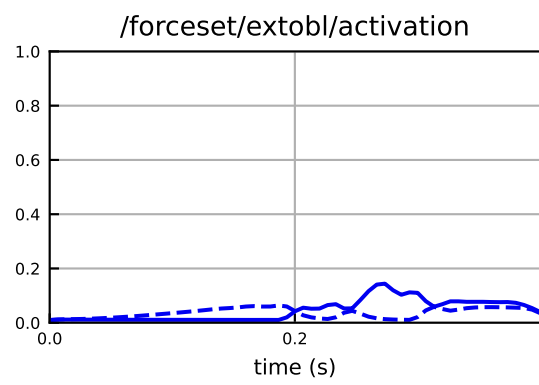
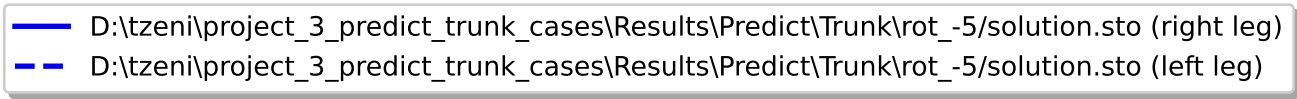
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- - D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\rot\_-5/solution.sto (left leg)



— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\rot\_-5\solution.sto (right leg)  
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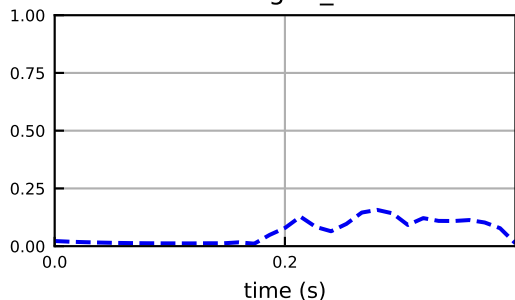




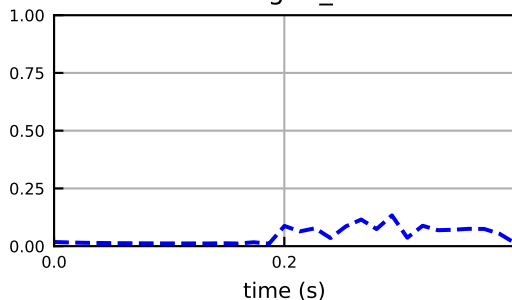


— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\rot\_-5\solution.sto (right leg)  
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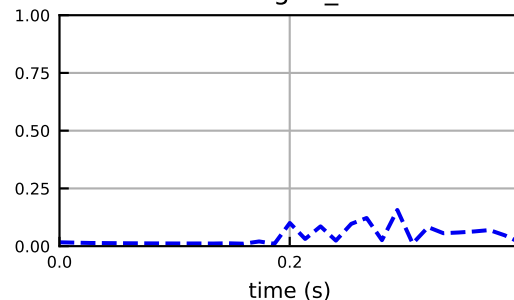
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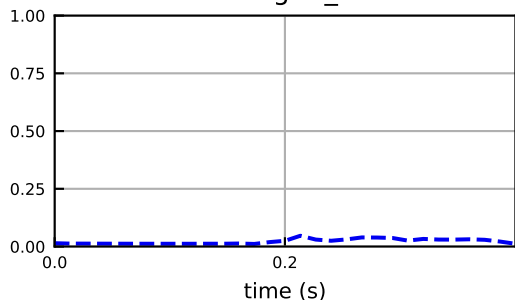
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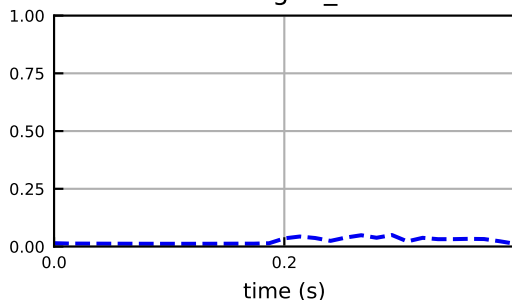
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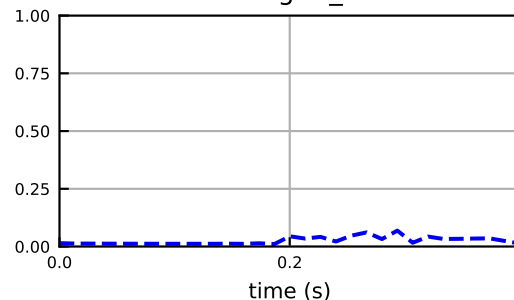
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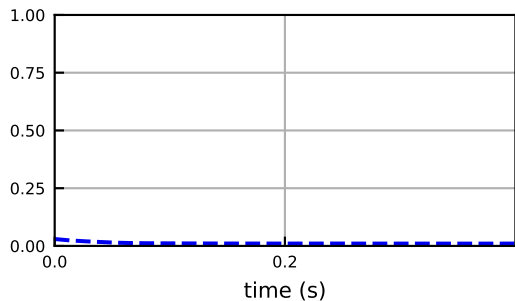
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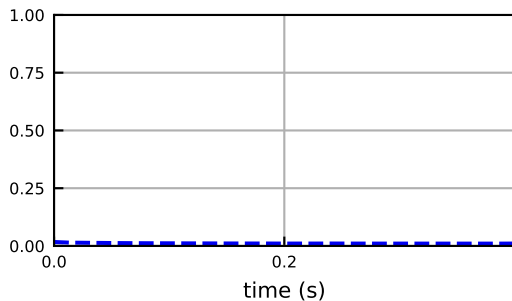
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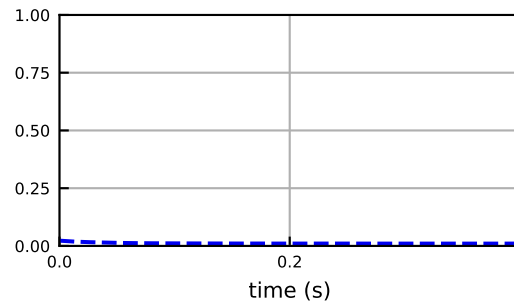
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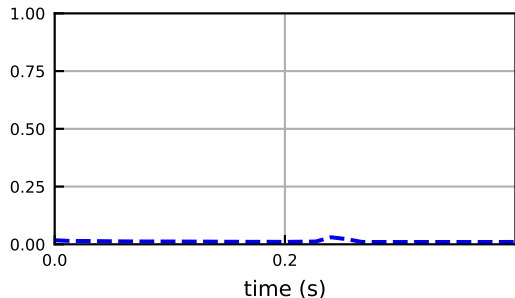
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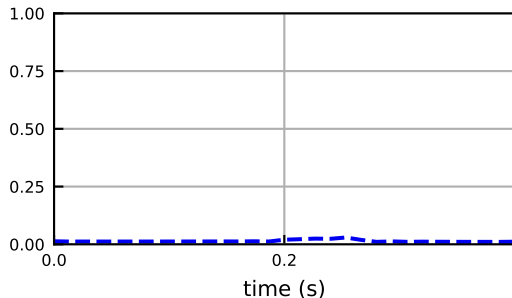
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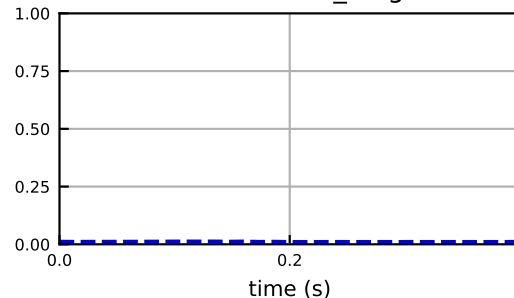
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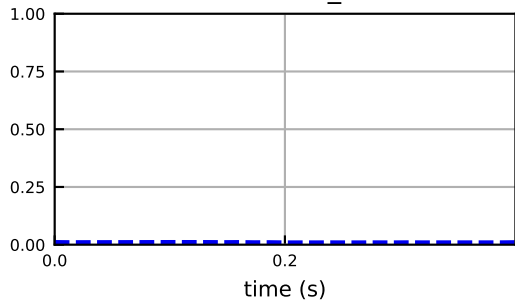
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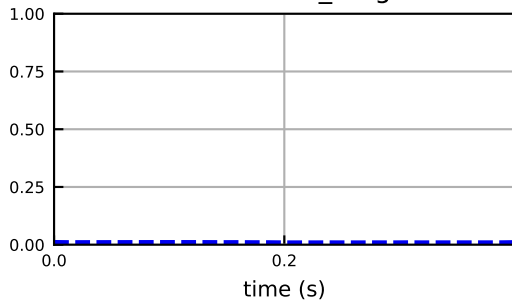
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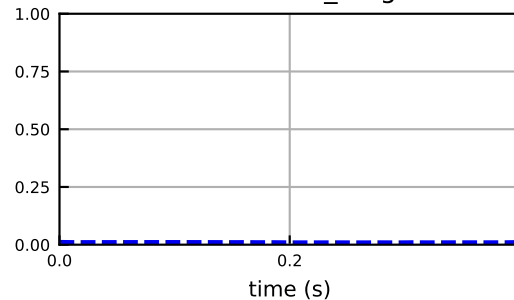
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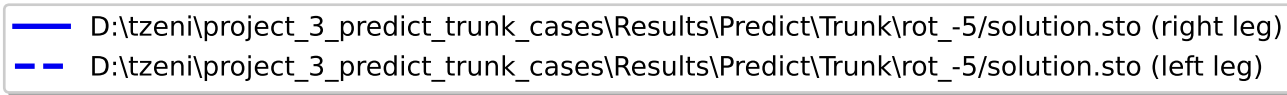
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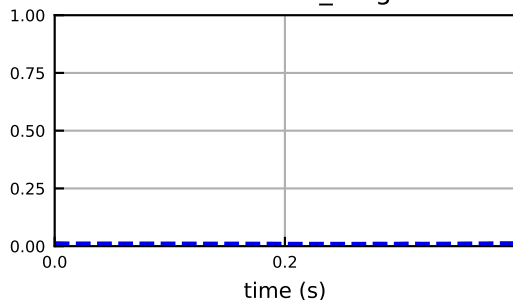
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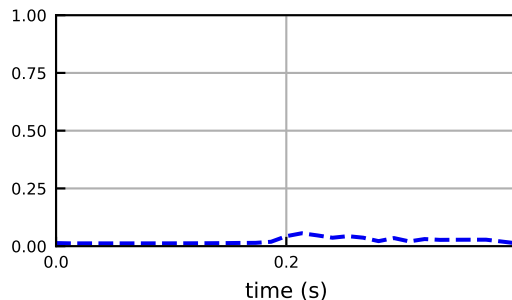




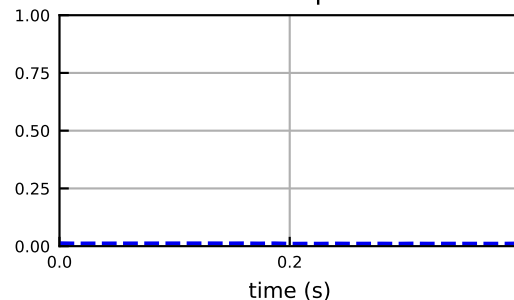
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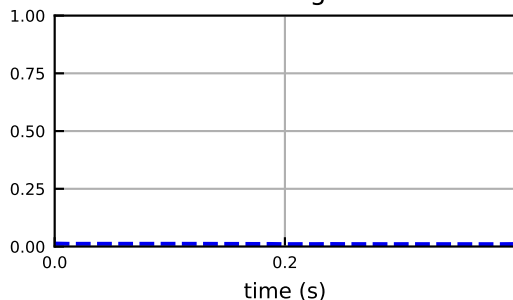
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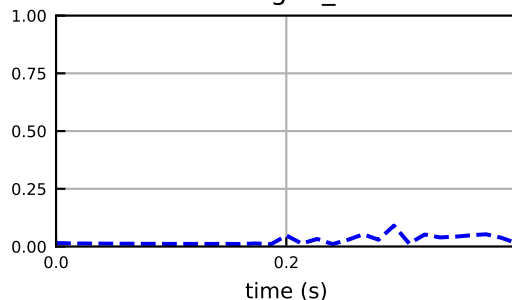
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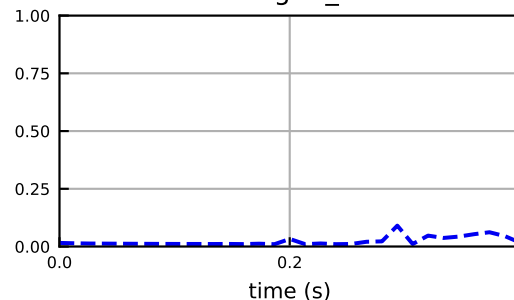
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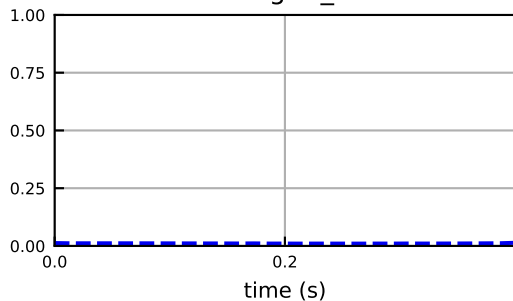
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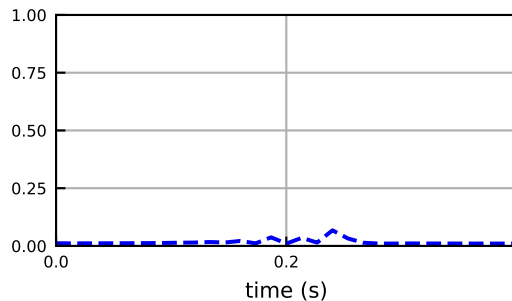
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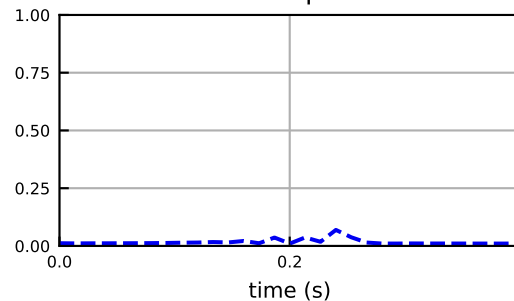
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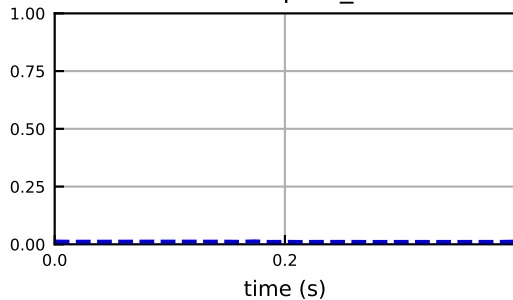
forcesetiliacus



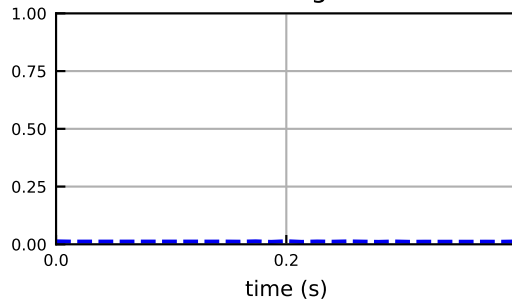
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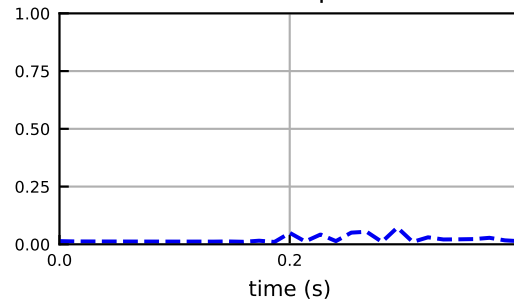
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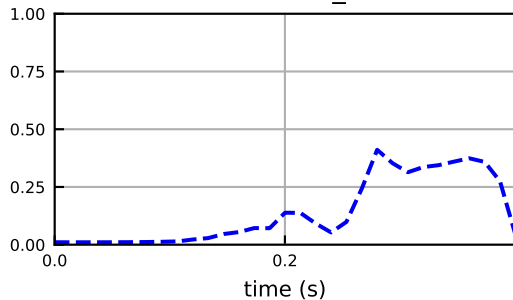
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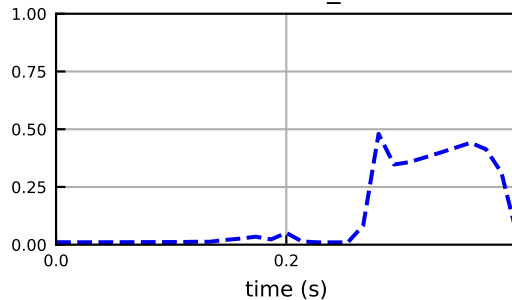
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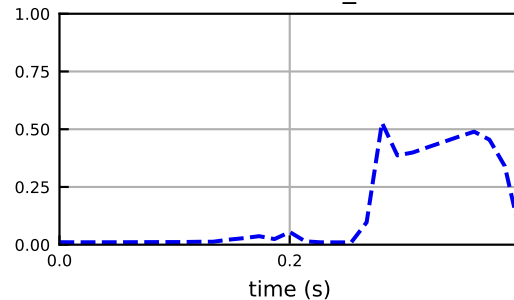
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forcesetvas\_med



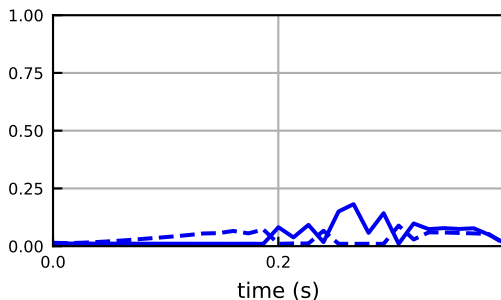
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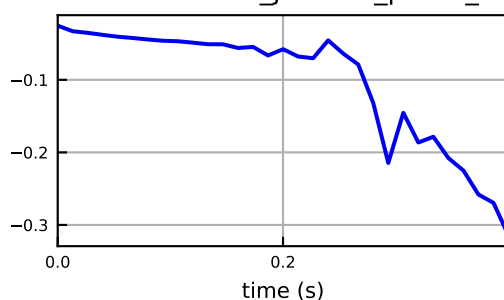


— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\rot\_-5\solution.sto (right leg)  
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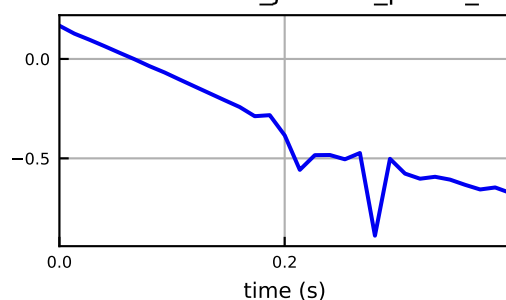
forcesetextobl



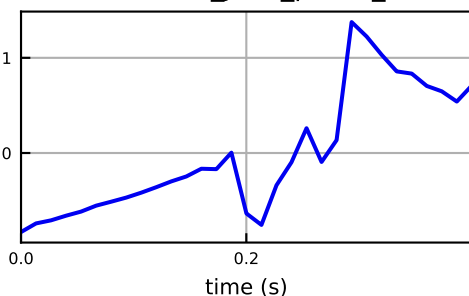
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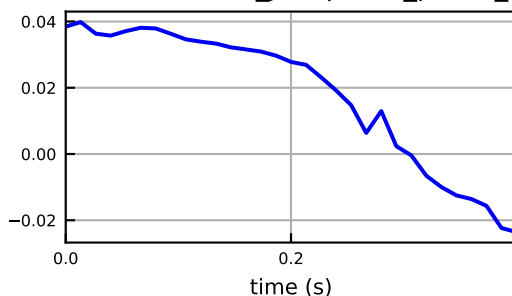
forcesetreserve\_joi...lvis\_pelvis\_list



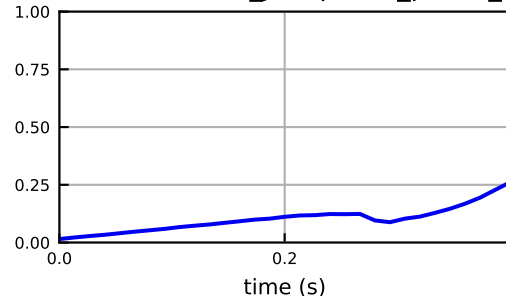
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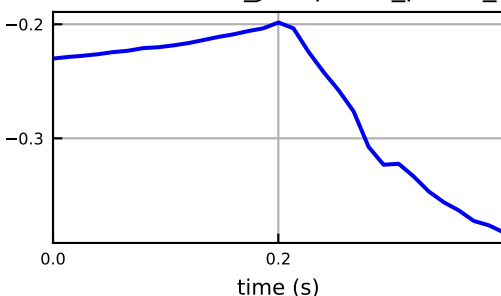
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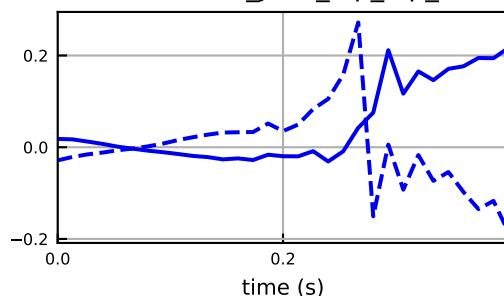
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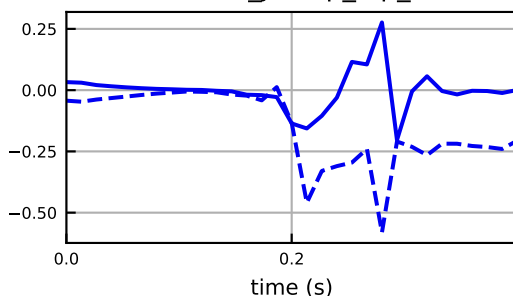
forcesetreserve\_joi...pelvis\_pelvis\_tz



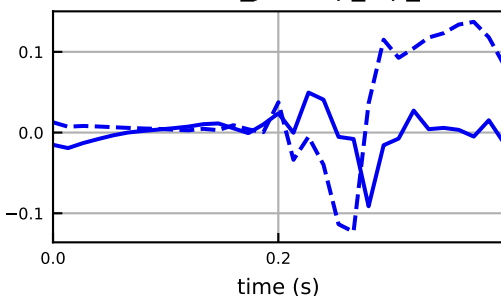
forcesetreserve\_joi...hip\_hip\_flexion



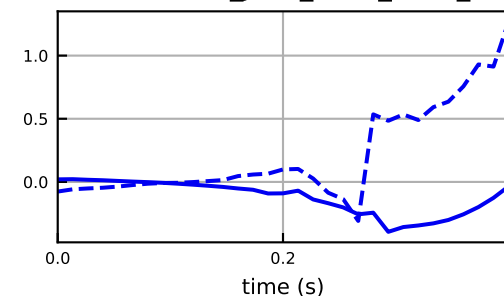
forcesetreserve\_joi...ip\_hip\_adduction



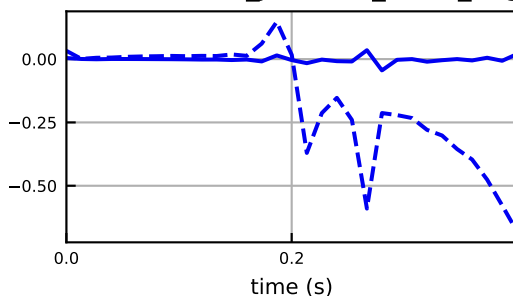
forcesetreserve\_joi...hip\_hip\_rotation



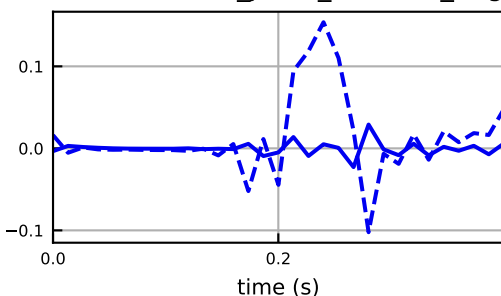
forcesetreserve\_joi...knee\_knee\_angle



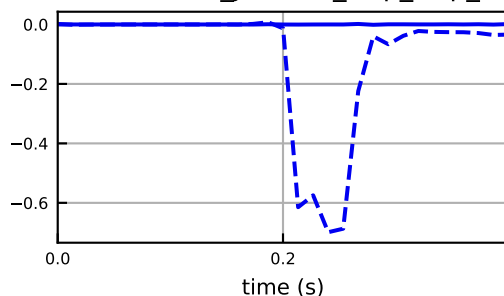
forcesetreserve\_joi...nkle\_ankle\_angle



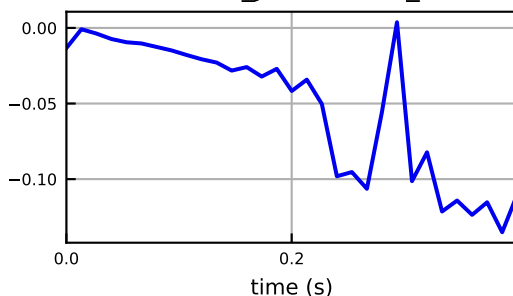
forcesetreserve\_joi...r\_subtalar\_angle

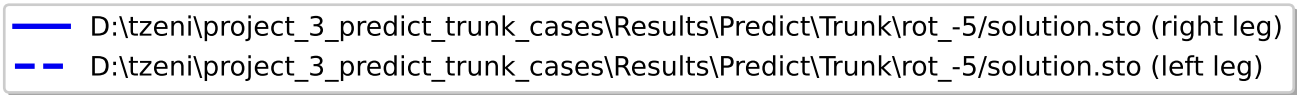


forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension





forcesetreserve\_joi...k\_lumbar\_bending    forcesetreserve\_joi...\_lumbar\_rotation

