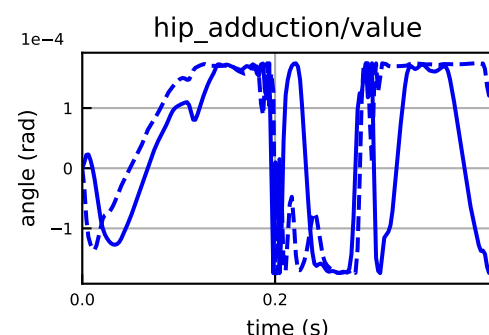
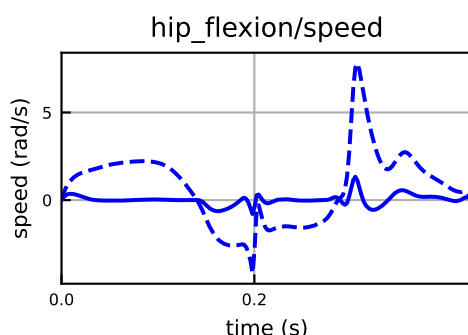
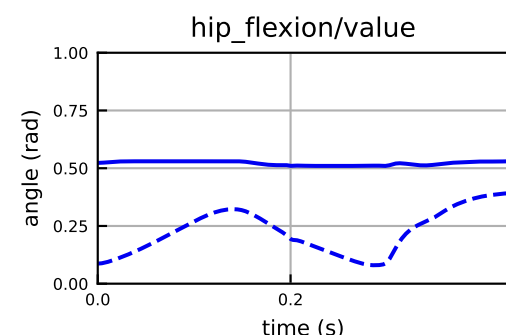
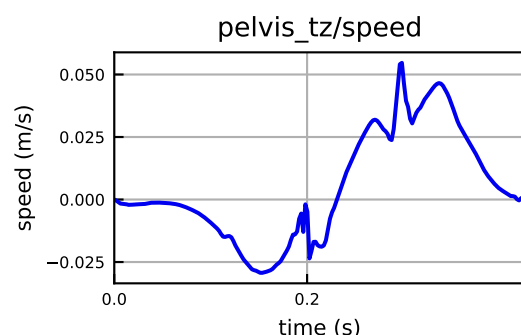
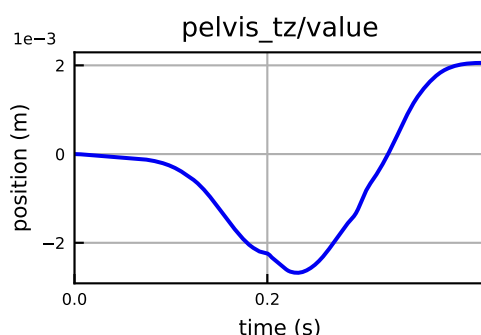
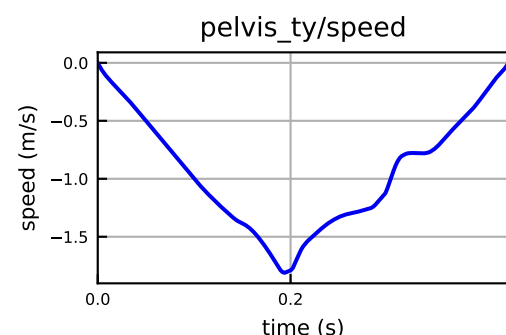
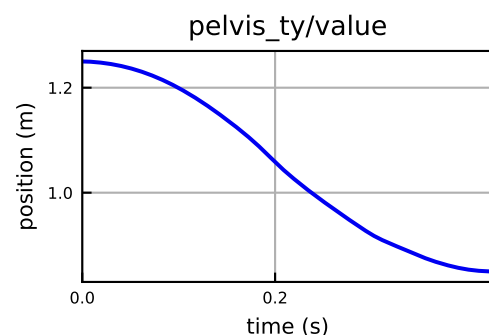
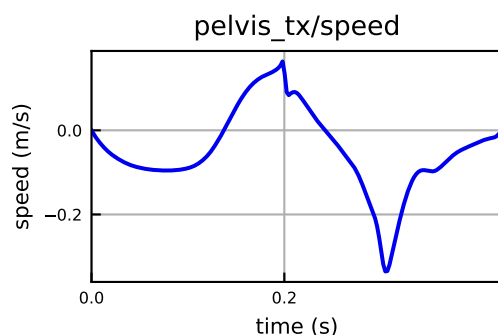
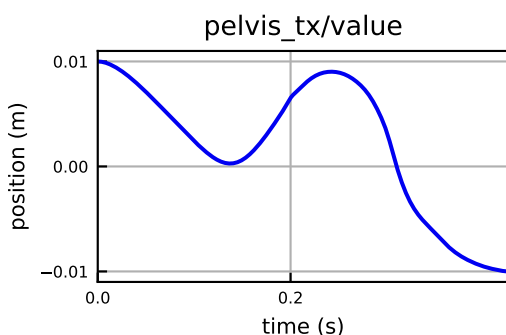
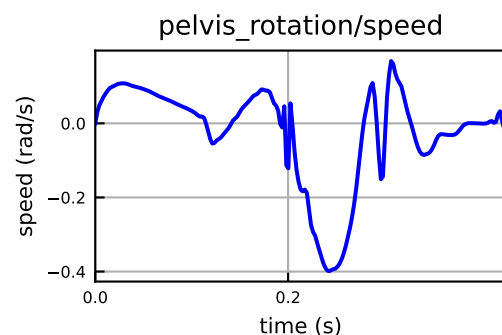
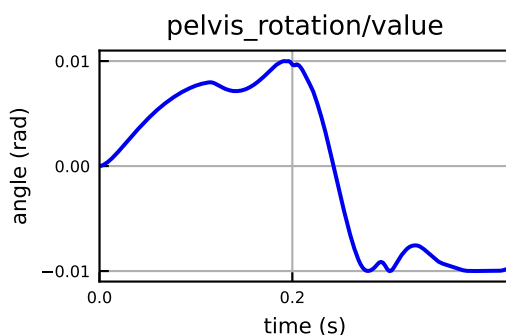
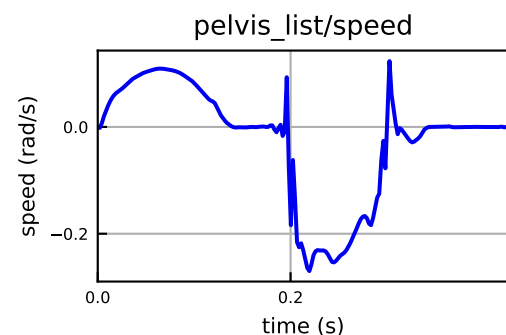
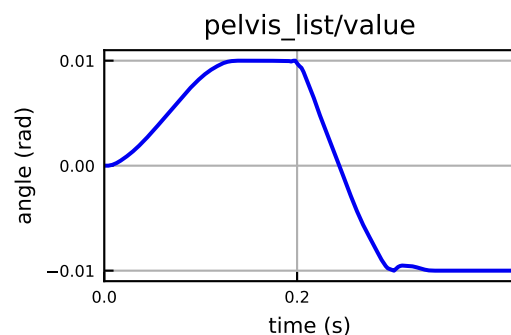
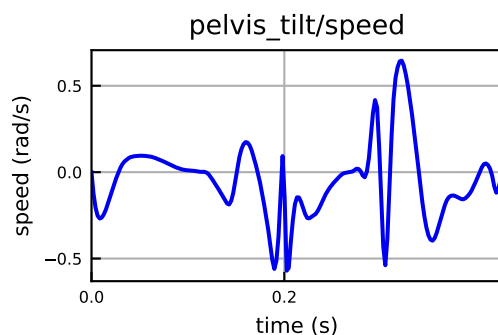
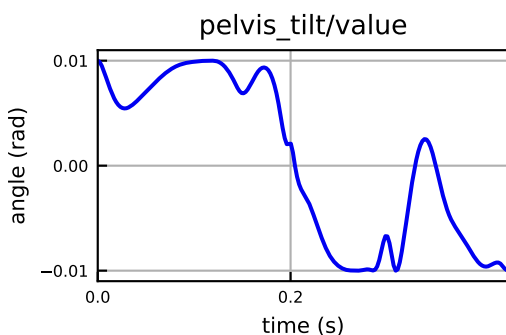
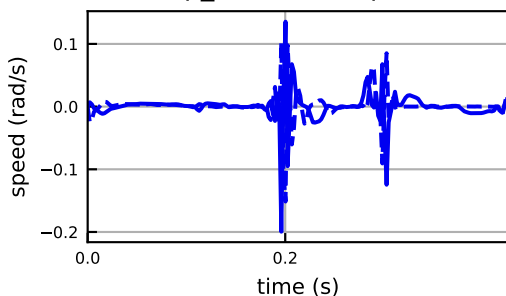


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (left leg)

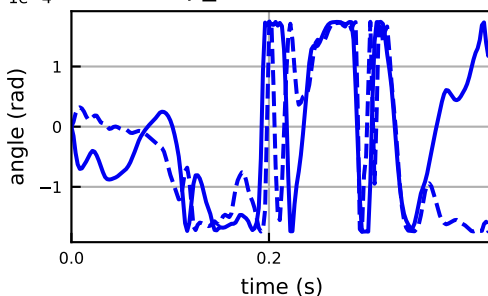


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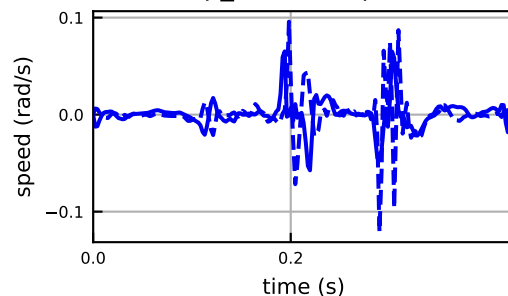
hip_adduction/speed



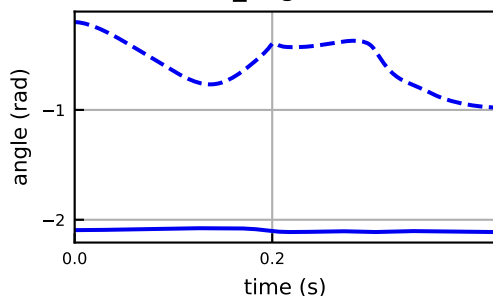
hip_rotation/value



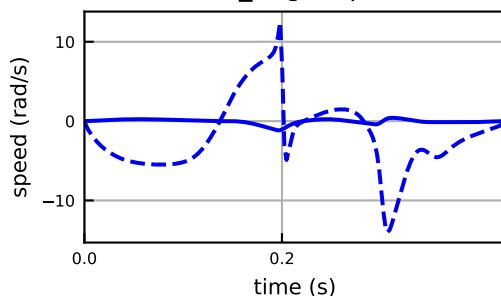
hip_rotation/speed



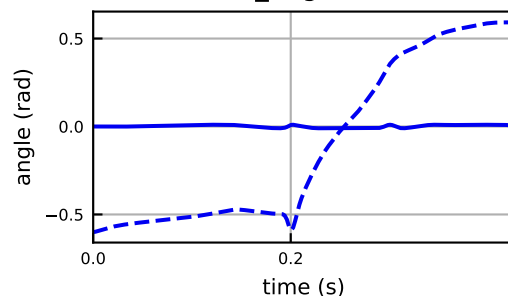
knee_angle/value



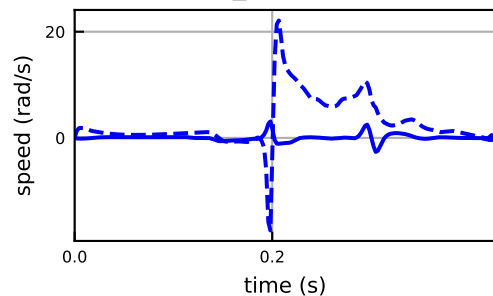
knee_angle/speed



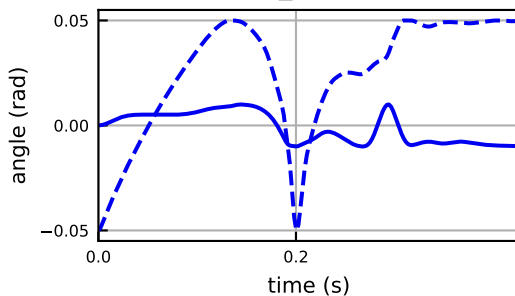
ankle_angle/value



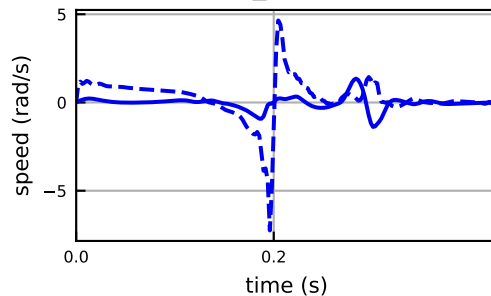
ankle_angle/speed



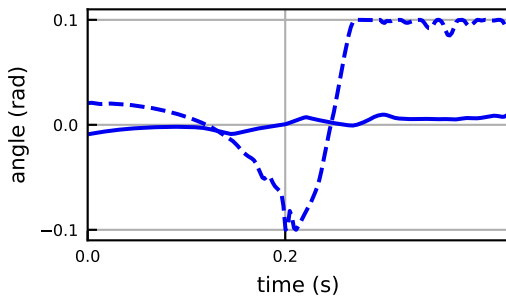
subtalar_angle/value



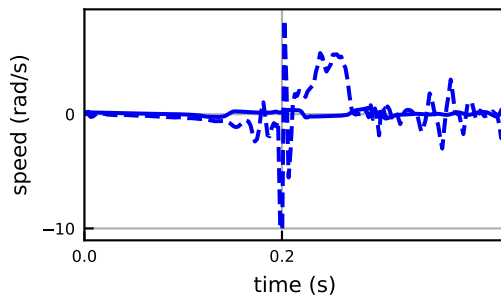
subtalar_angle/speed



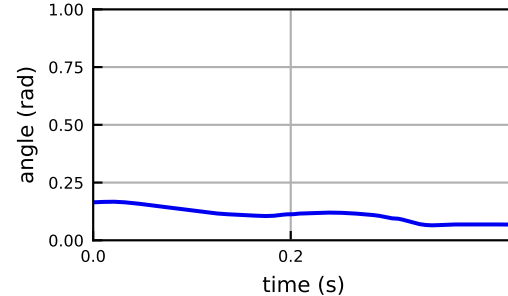
mtp_angle/value



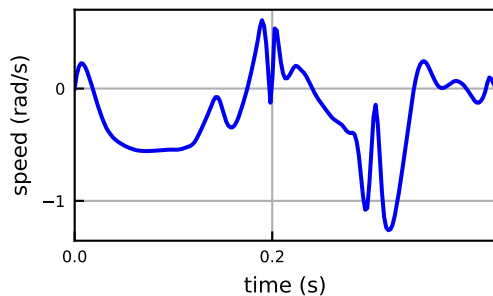
mtp_angle/speed



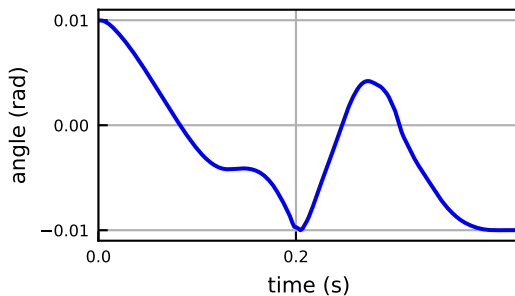
lumbar_extension/value



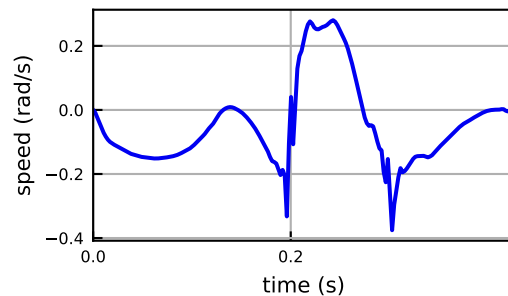
lumbar_extension/speed



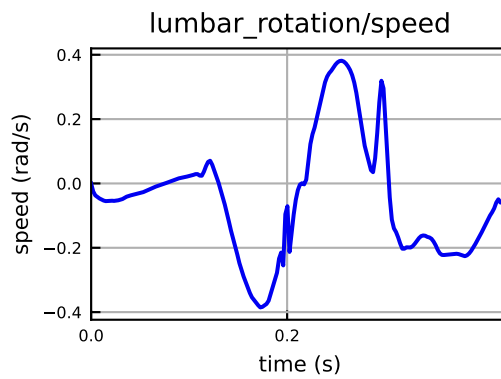
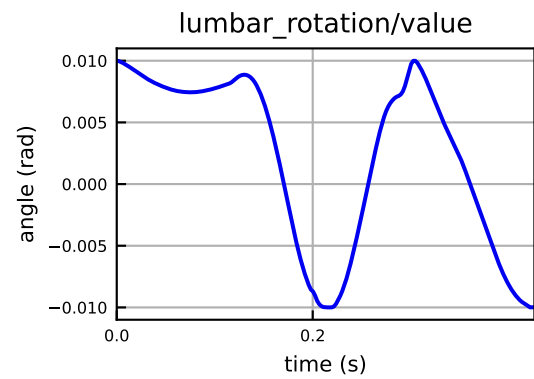
lumbar_bending/value



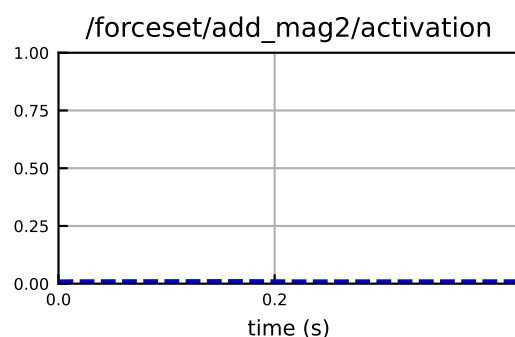
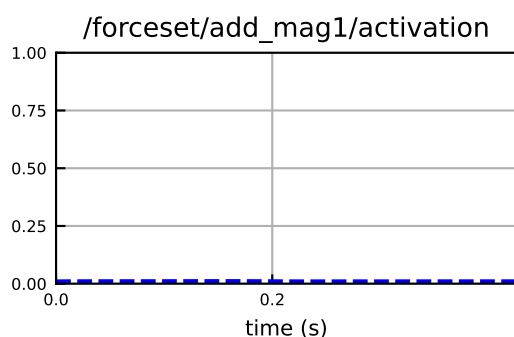
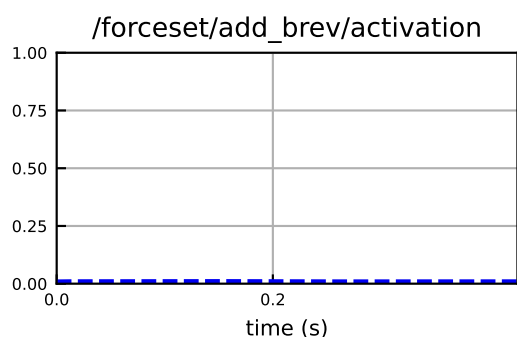
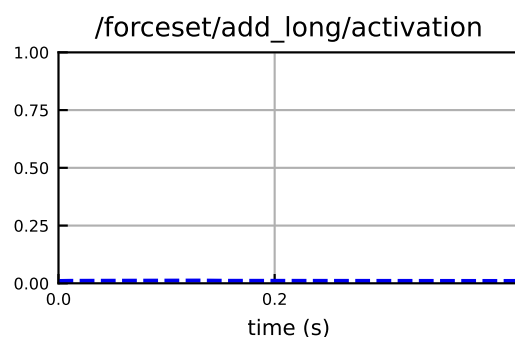
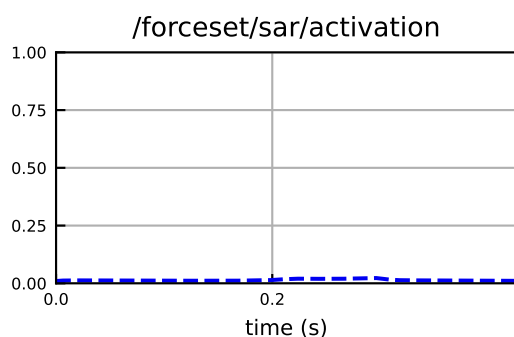
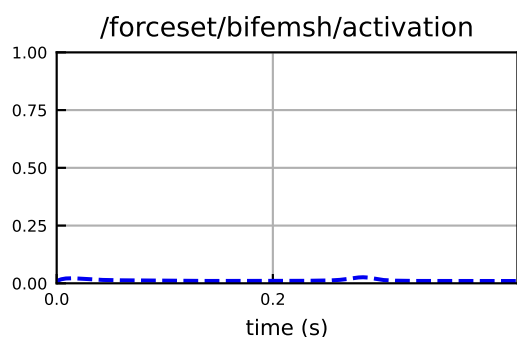
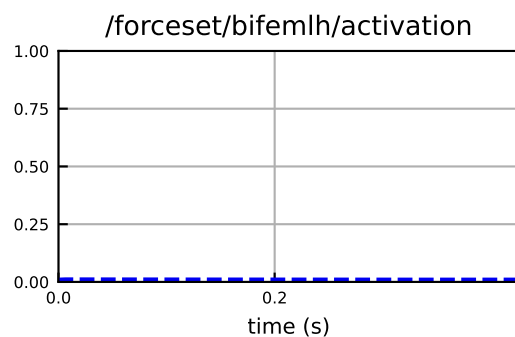
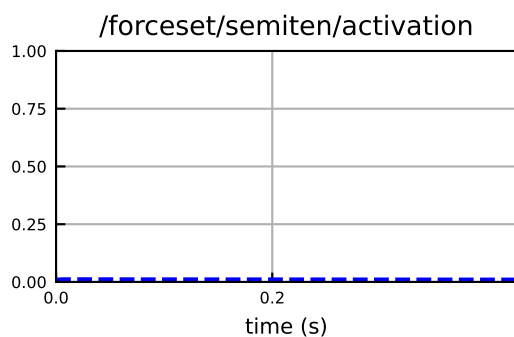
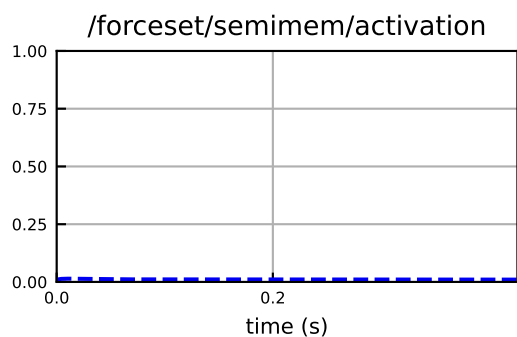
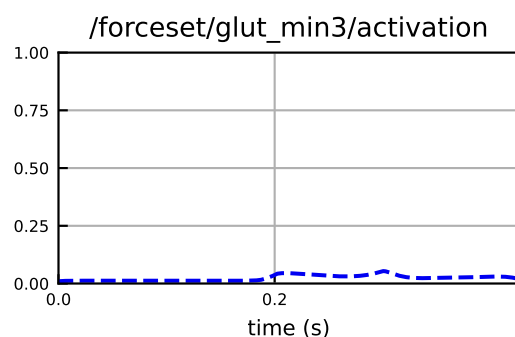
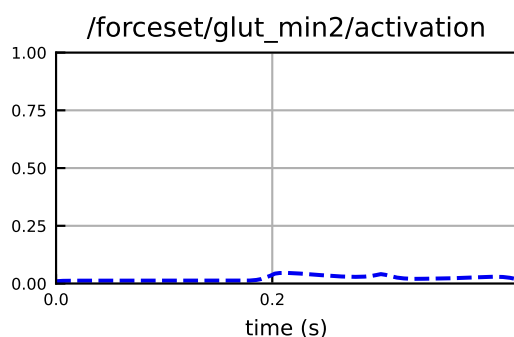
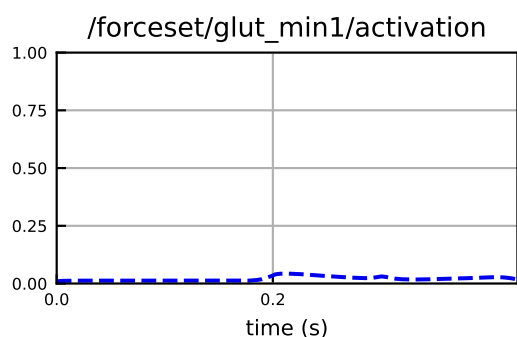
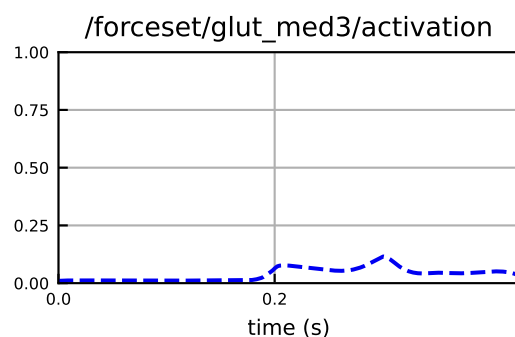
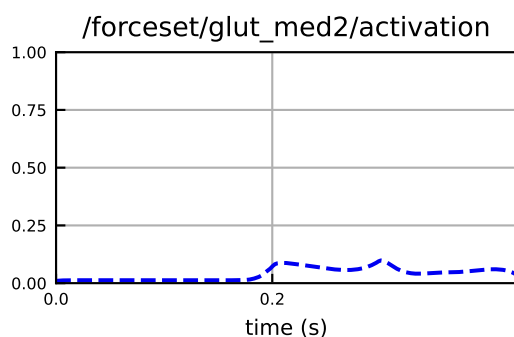
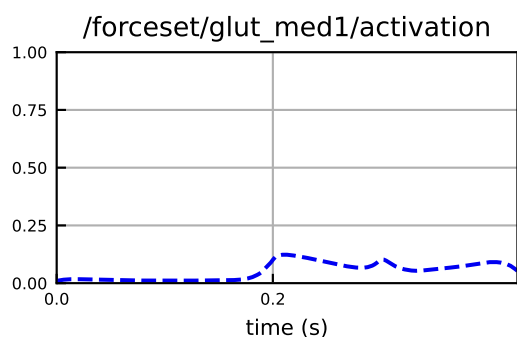
lumbar_bending/speed



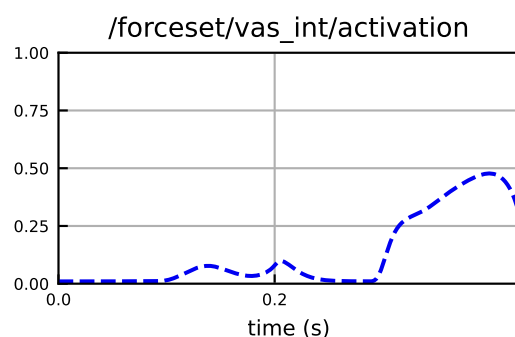
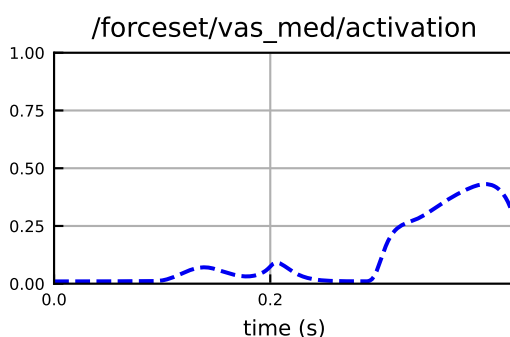
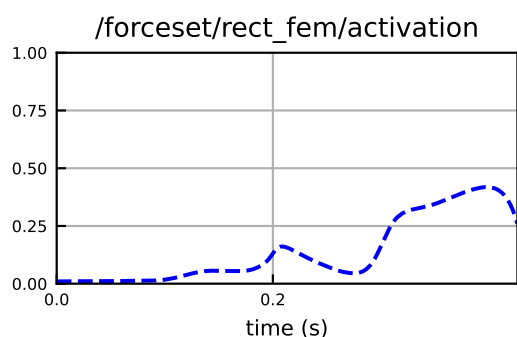
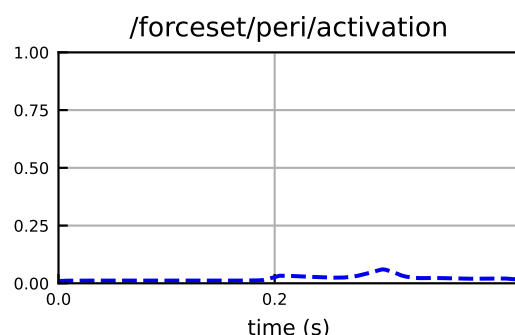
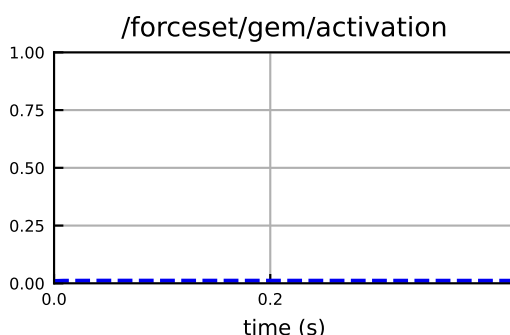
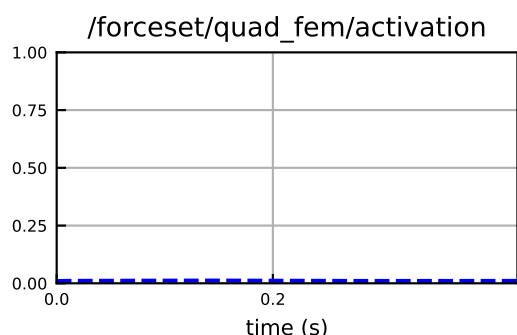
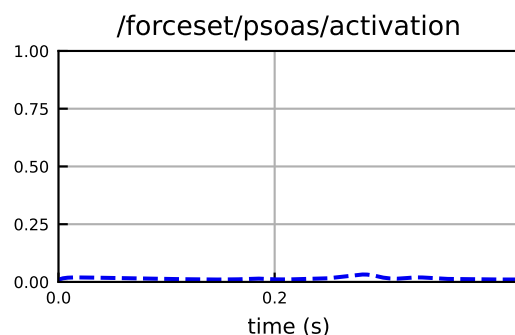
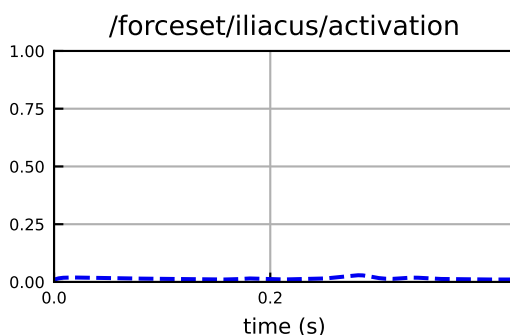
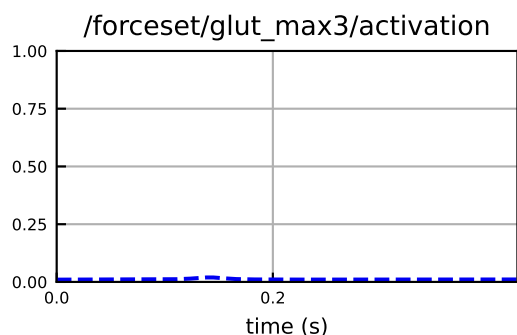
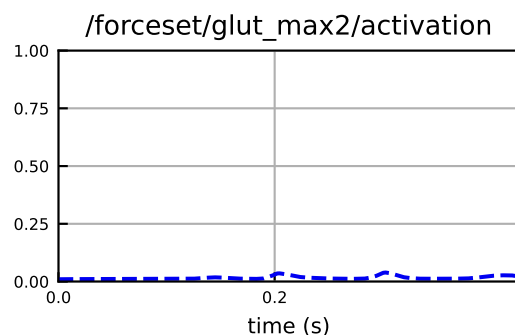
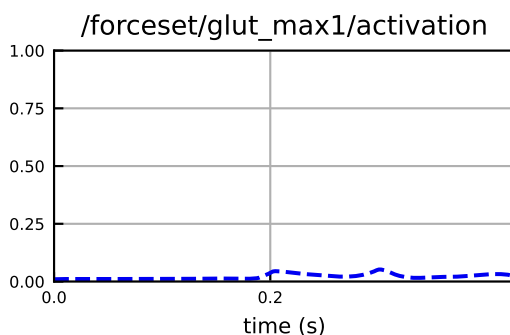
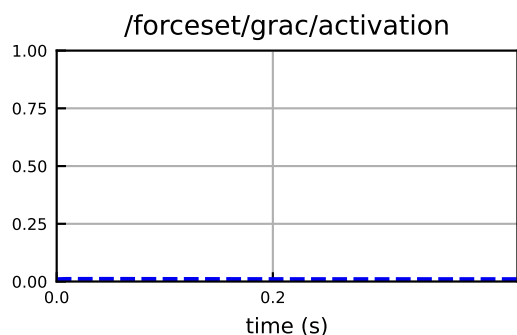
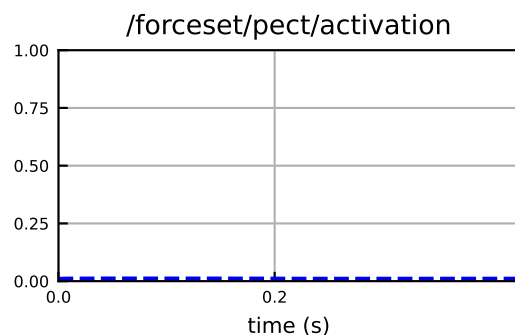
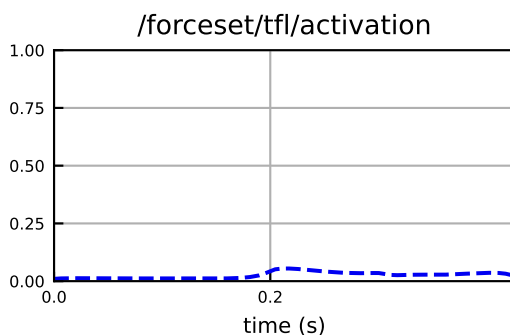
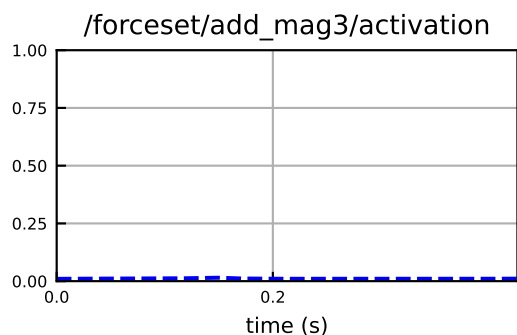
— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (left leg)



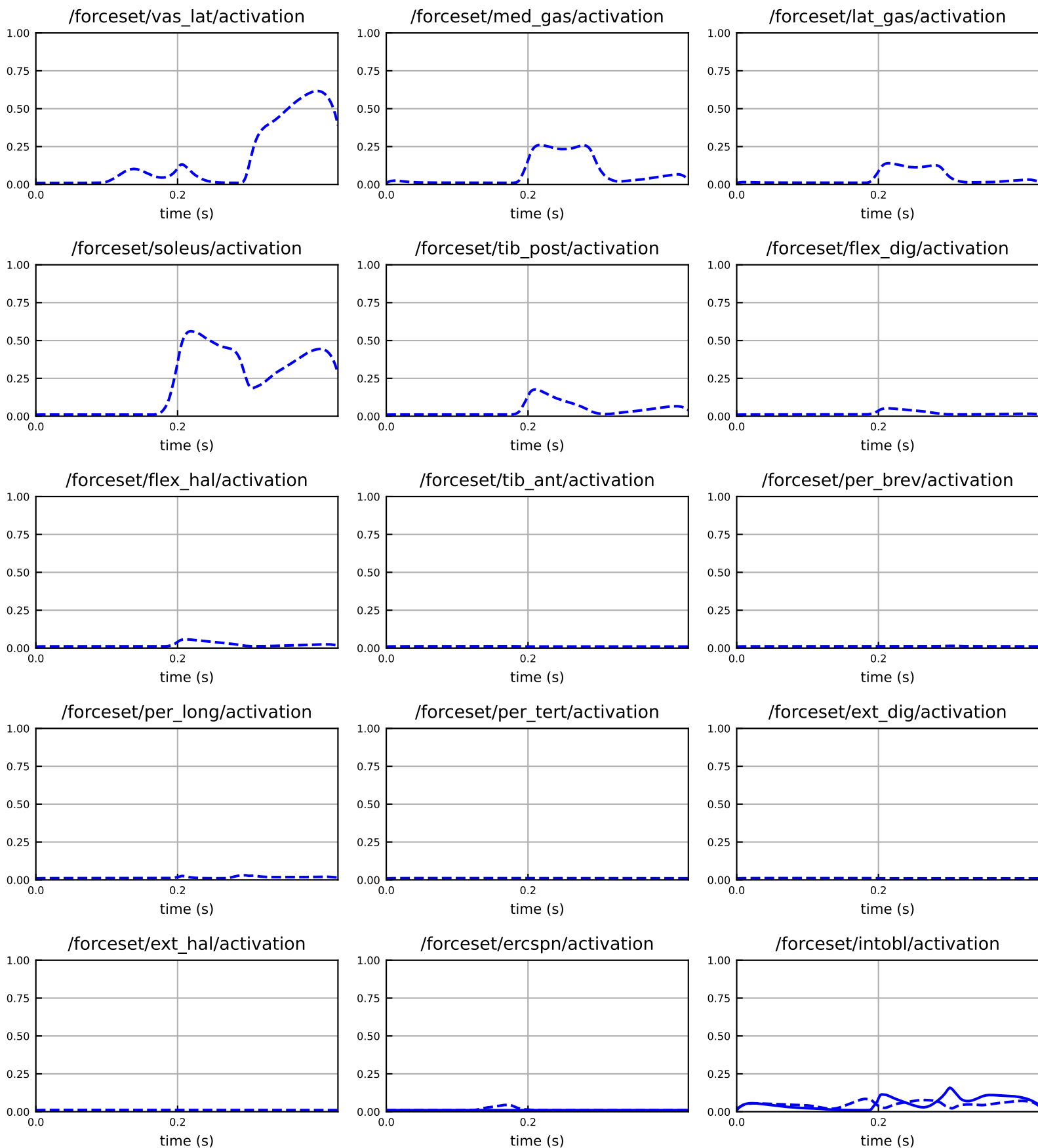
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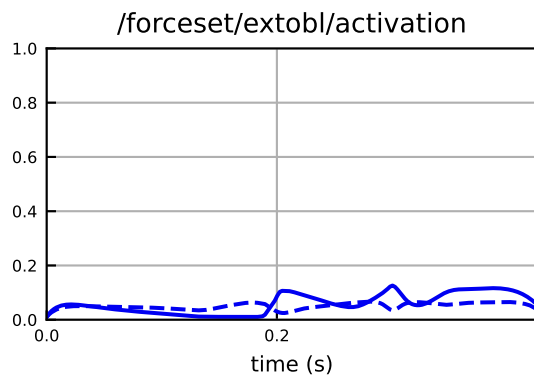
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- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (left leg)



— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (left leg)

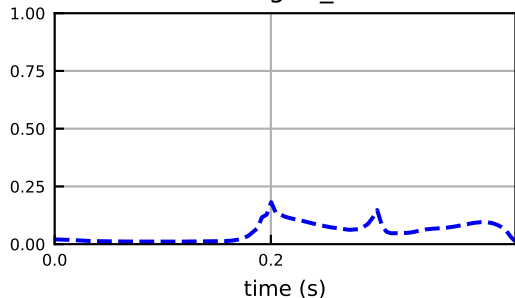


- D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (right leg)
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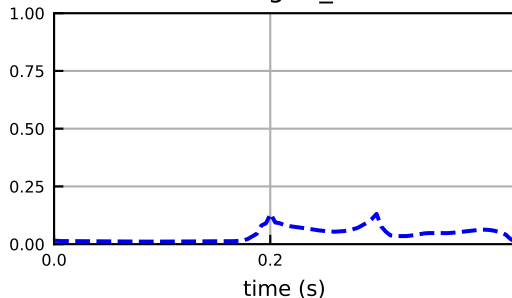


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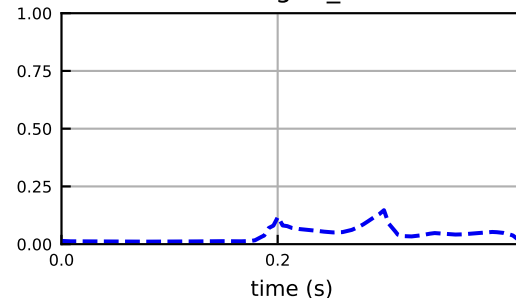
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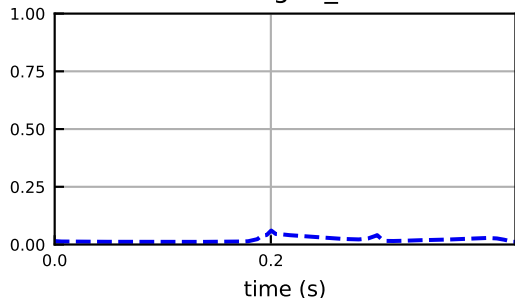
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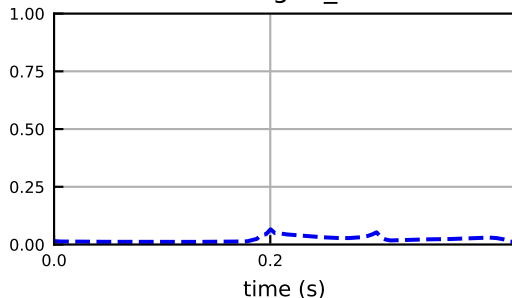
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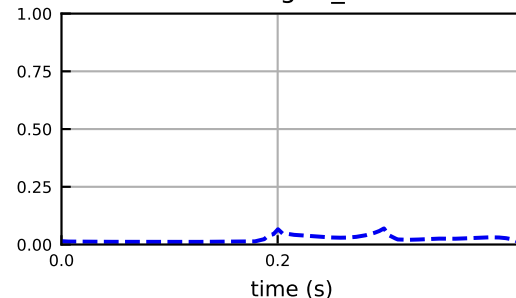
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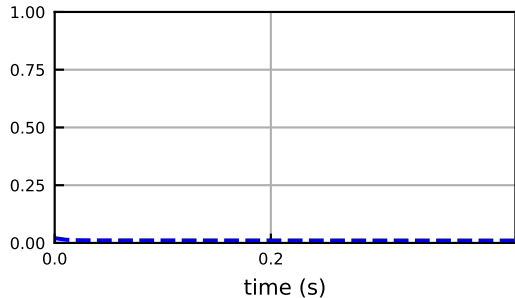
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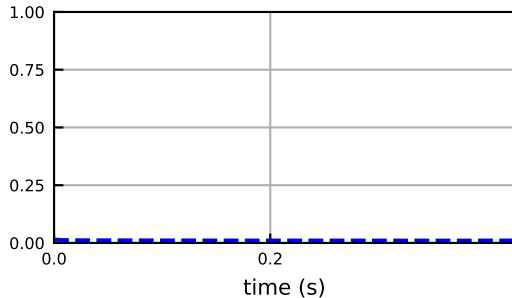
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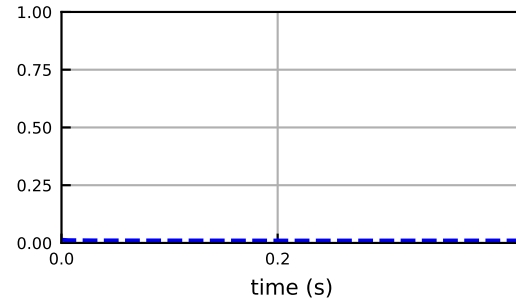
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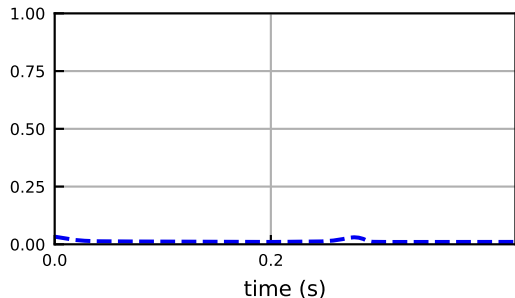
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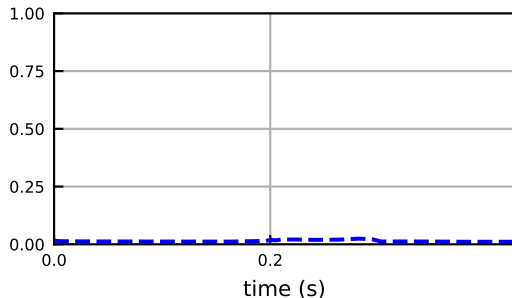
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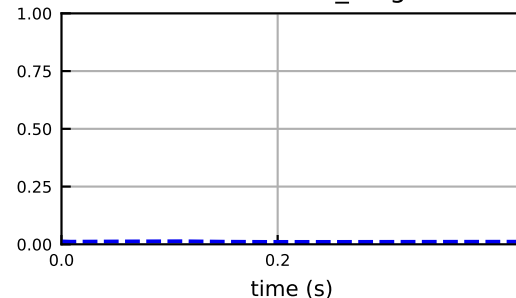
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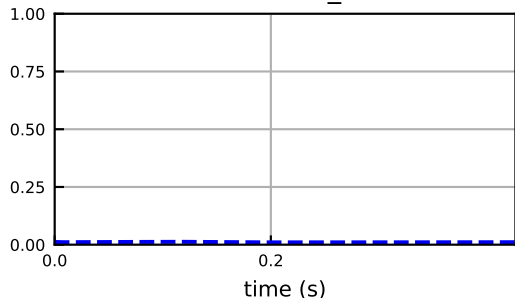
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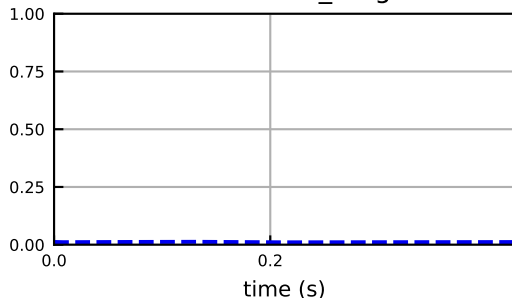
forcesetadd_long



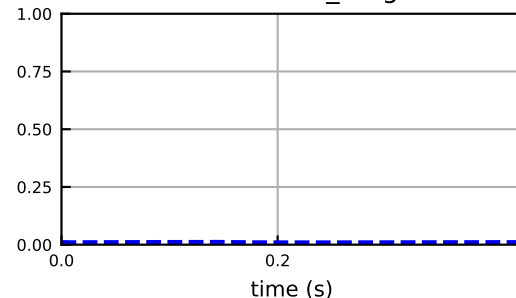
forcesetadd_brev



forcesetadd_mag1

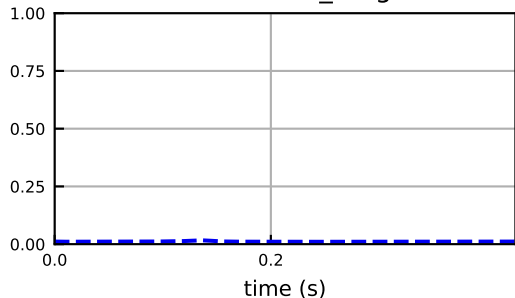


forcesetadd_mag2

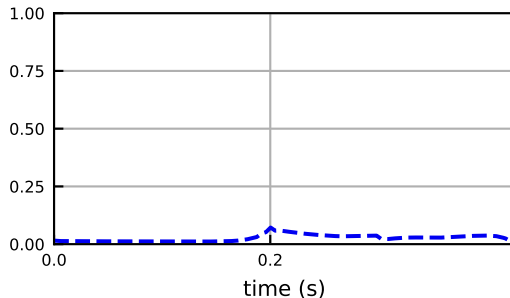


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (left leg)

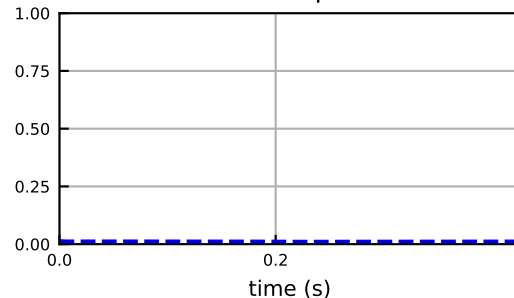
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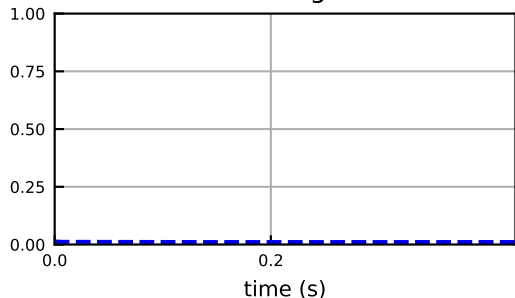
forcesetttfl



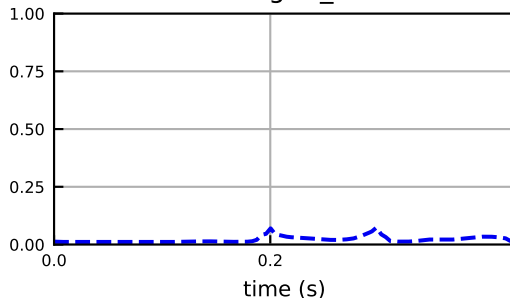
forcesetpect



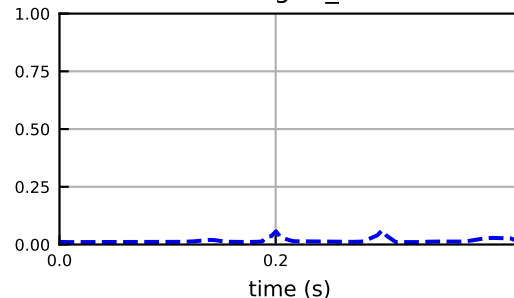
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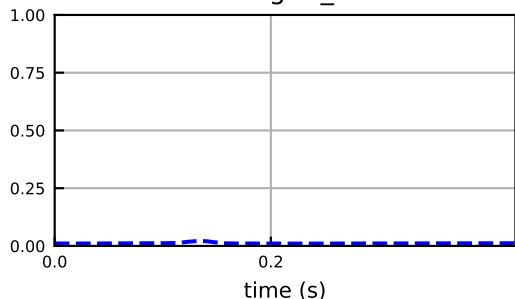
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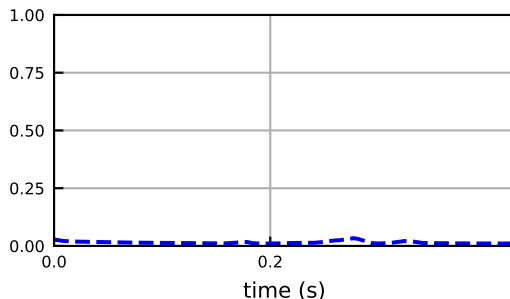
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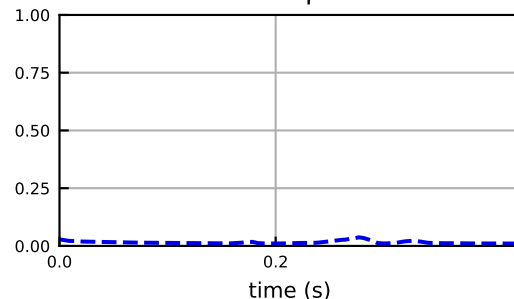
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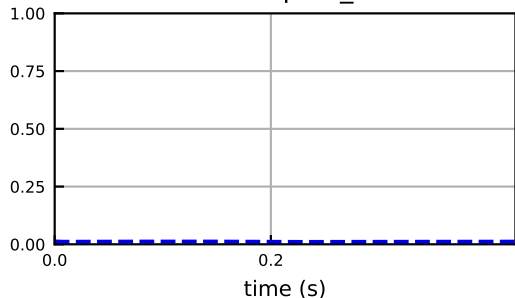
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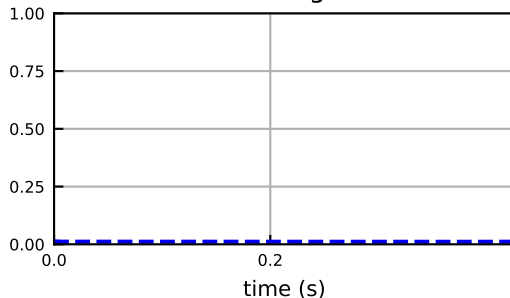
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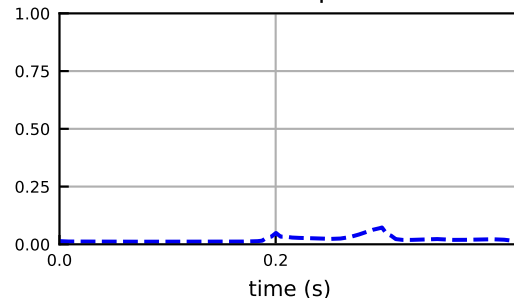
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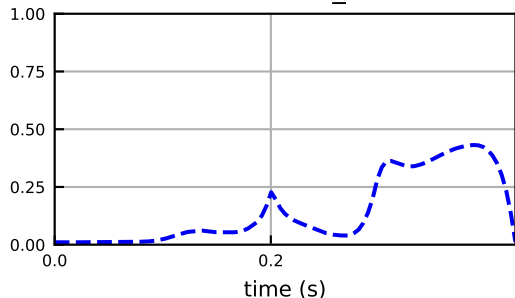
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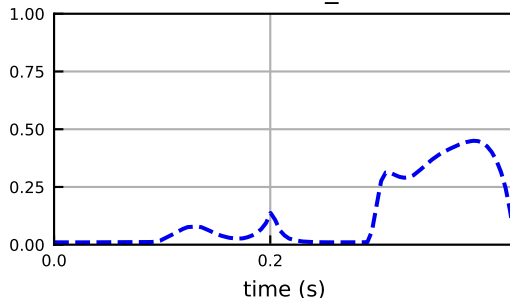
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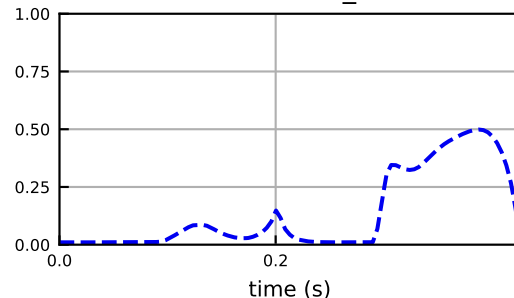
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forcesetvas_med

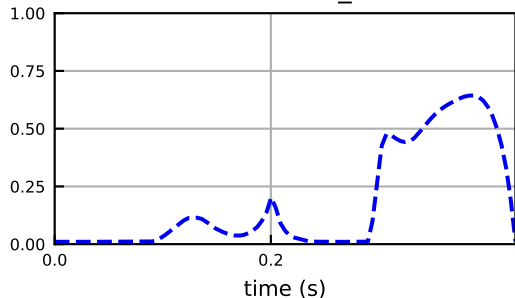


forcesetvas_int

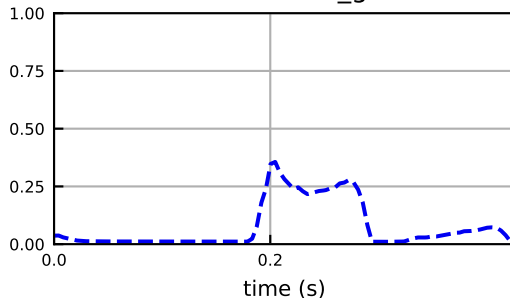


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10/solution.sto (right leg)
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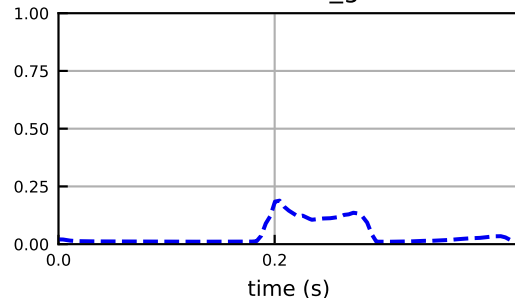
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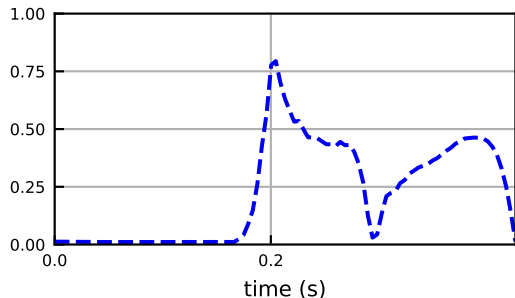
forcesetmed_gas



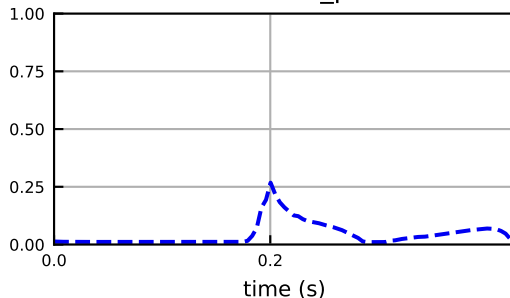
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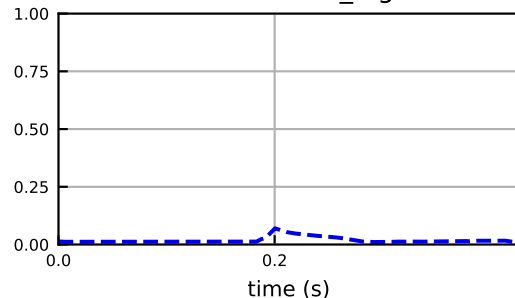
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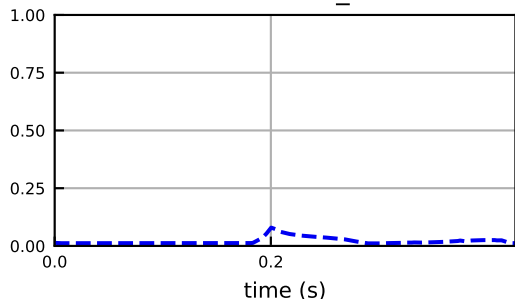
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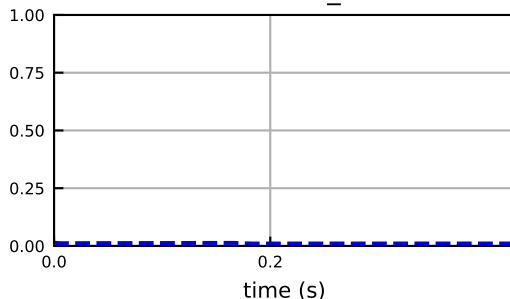
forcesetflex_dig



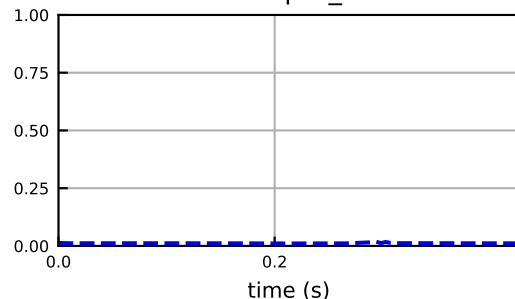
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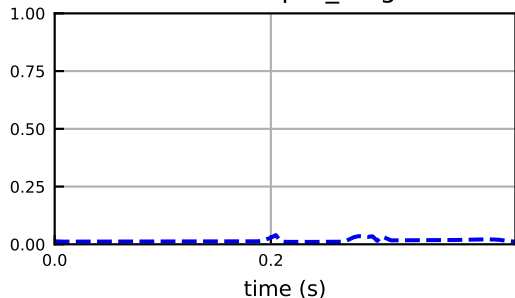
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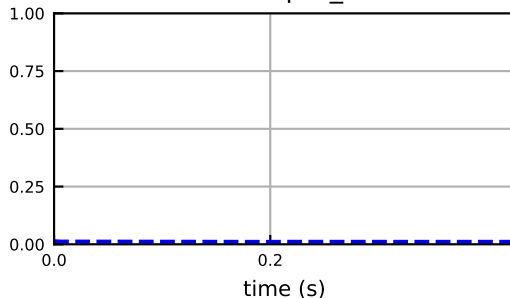
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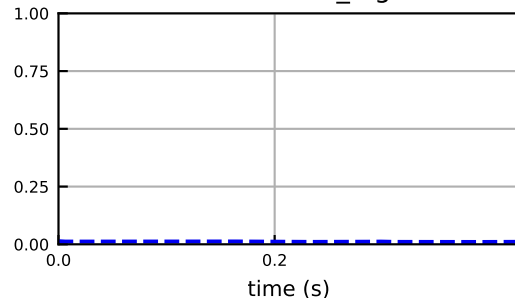
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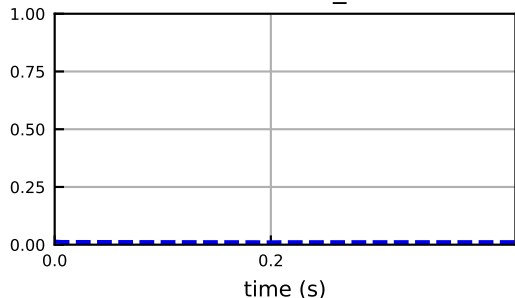
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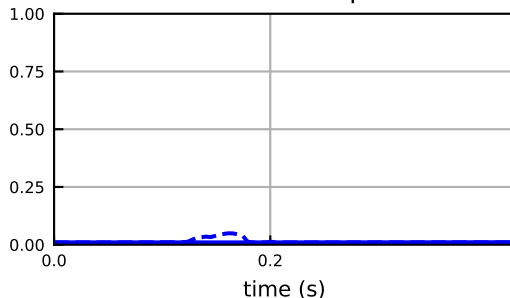
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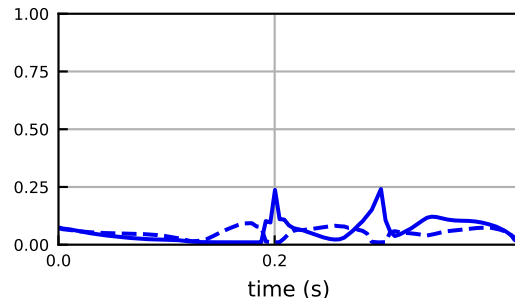
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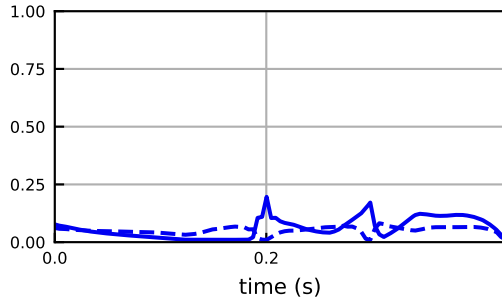


forcesetintobl

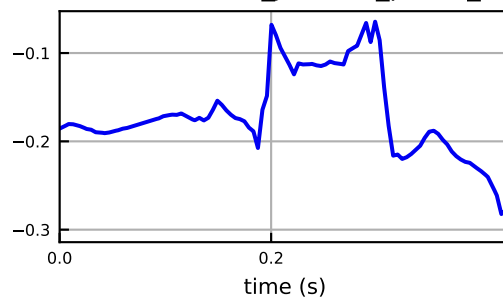


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_10\solution.sto (left leg)

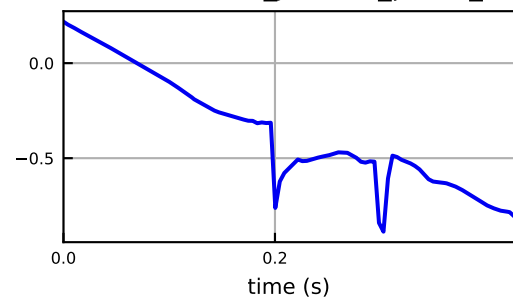
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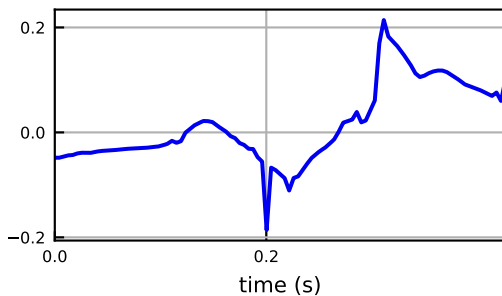
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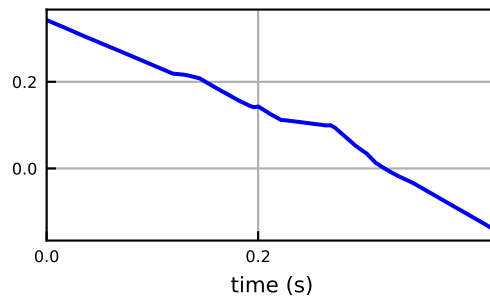
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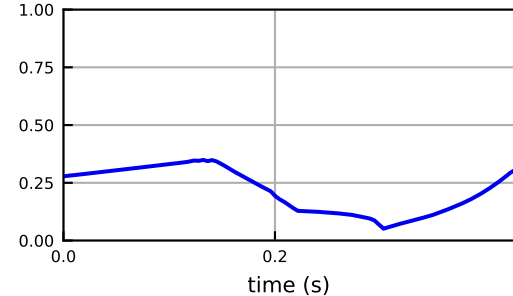
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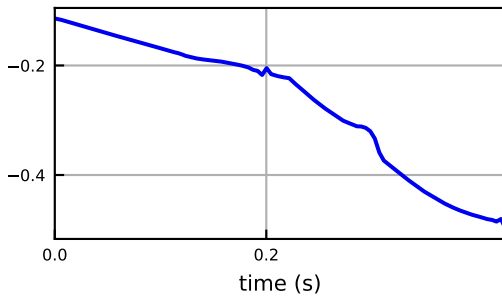
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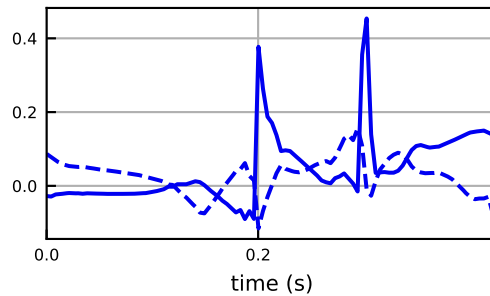
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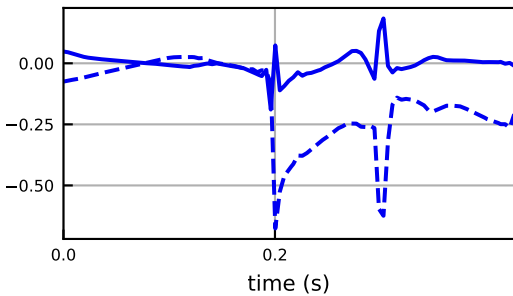
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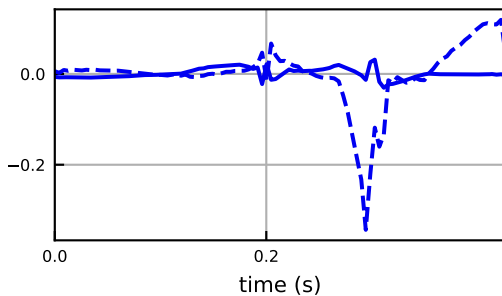
forcesetreserve_joi...hip_hip_flexion



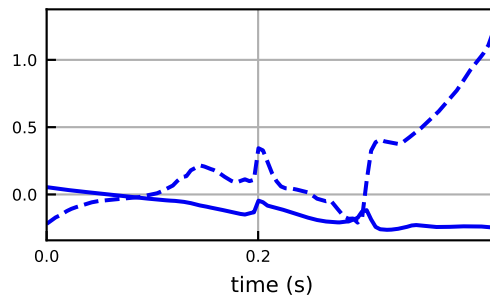
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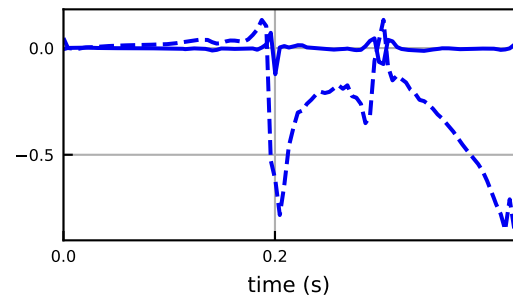
forcesetreserve_joi...hip_hip_rotation



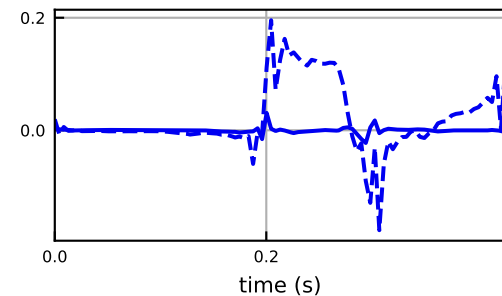
forcesetreserve_joi...knee_knee_angle



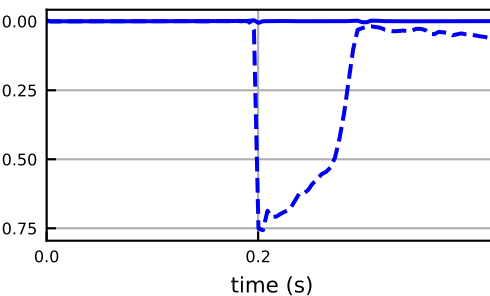
forcesetreserve_joi...nkle_ankle_angle



forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension

