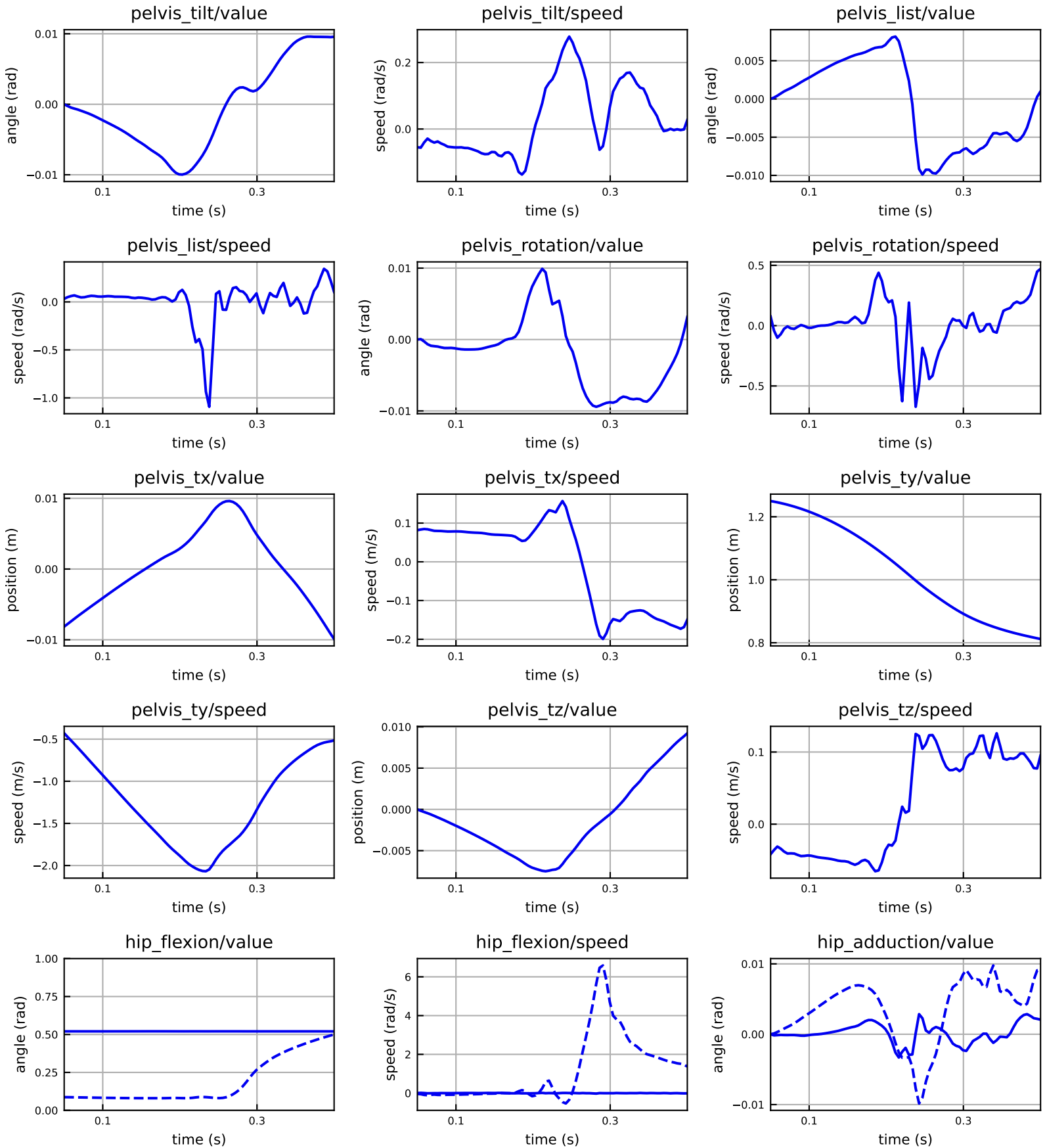
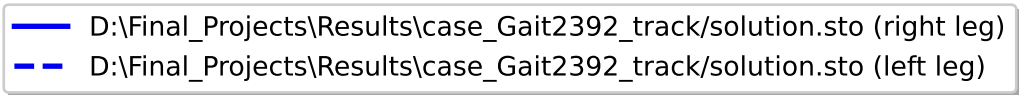
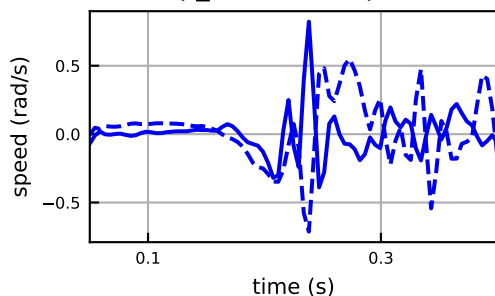


— D:\Final\_Projects\Results\case\_Gait2392\_track\solution.sto (right leg)  
- - - D:\Final\_Projects\Results\case\_Gait2392\_track\solution.sto (left leg)

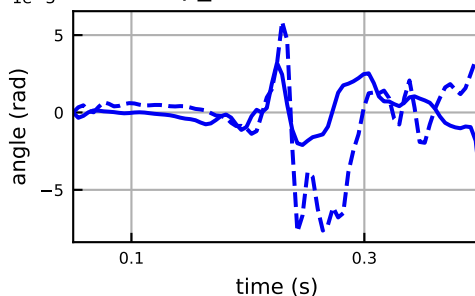




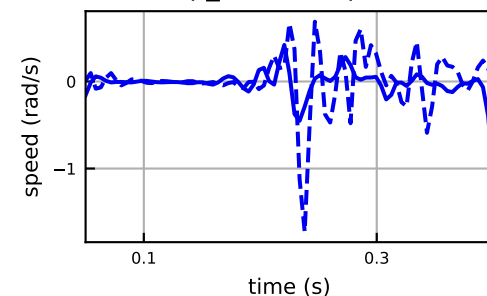
hip\_adduction/speed



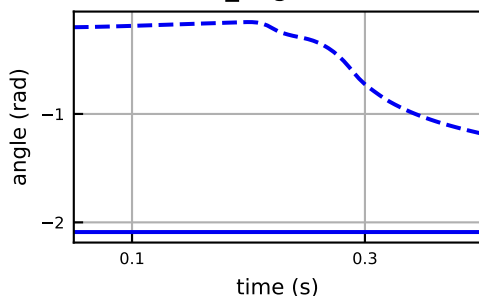
hip\_rotation/value



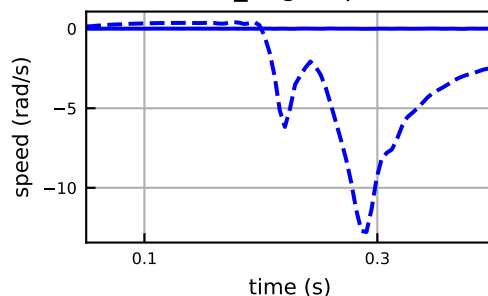
hip\_rotation/speed



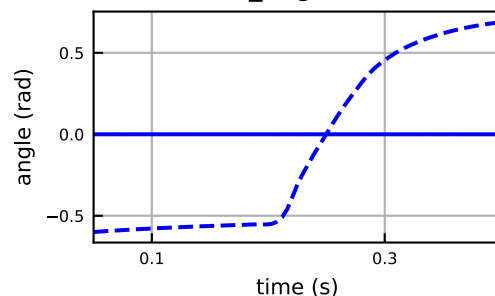
knee\_angle/value



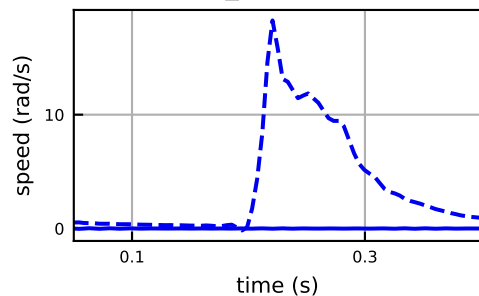
knee\_angle/speed



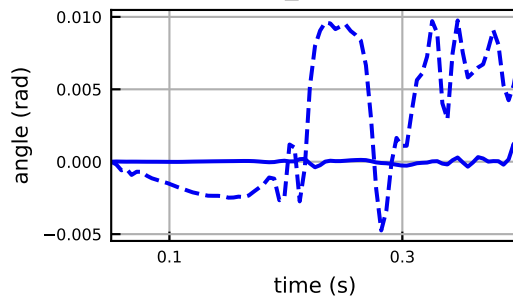
ankle\_angle/value



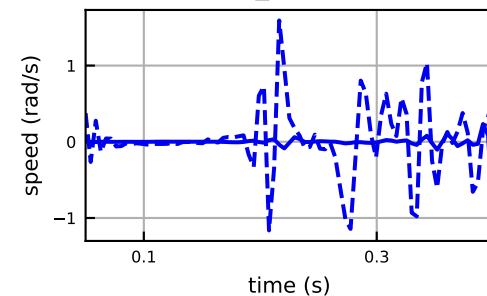
ankle\_angle/speed



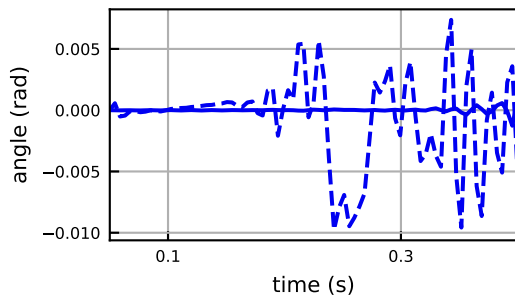
subtalar\_angle/value



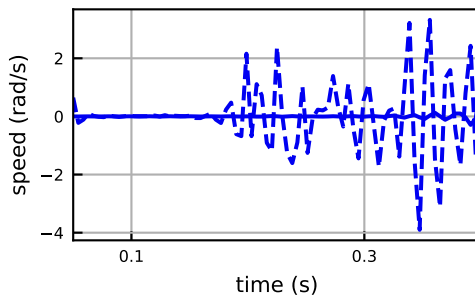
subtalar\_angle/speed



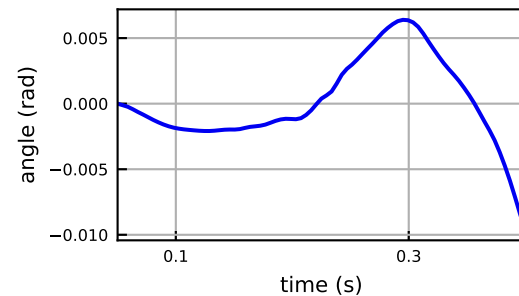
mtp\_angle/value



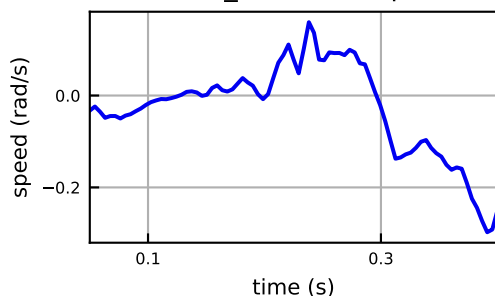
mtp\_angle/speed



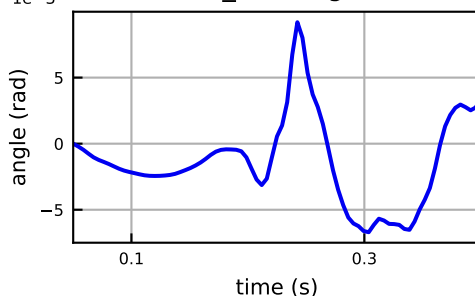
lumbar\_extension/value



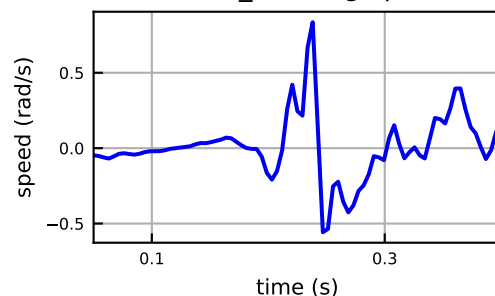
lumbar\_extension/speed

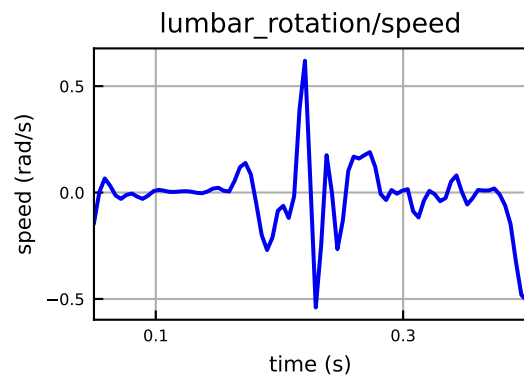
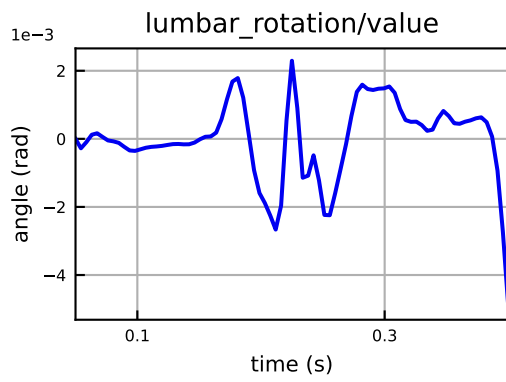


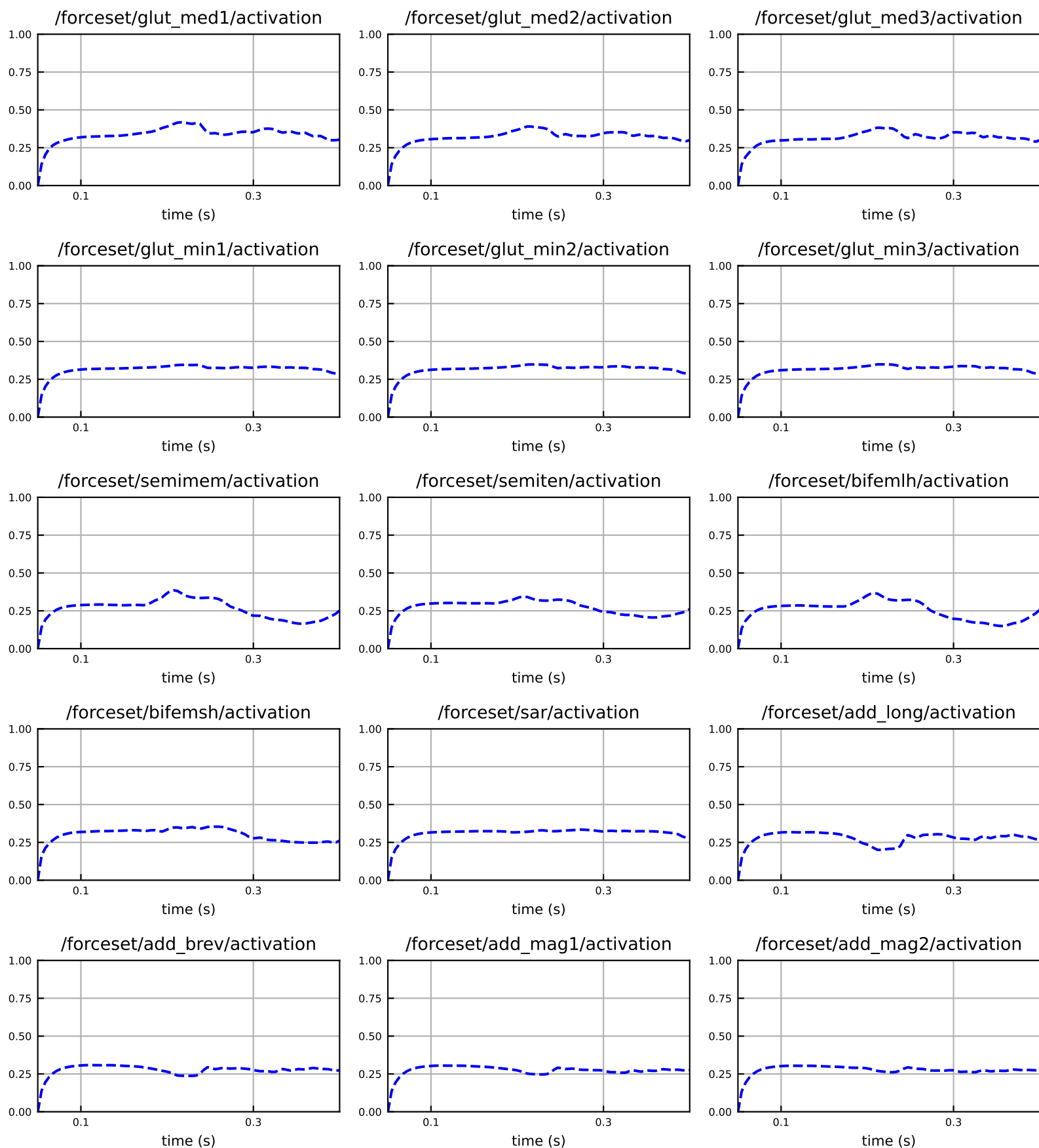
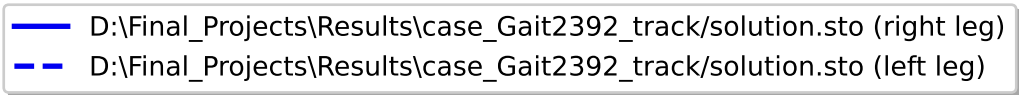
lumbar\_bending/value

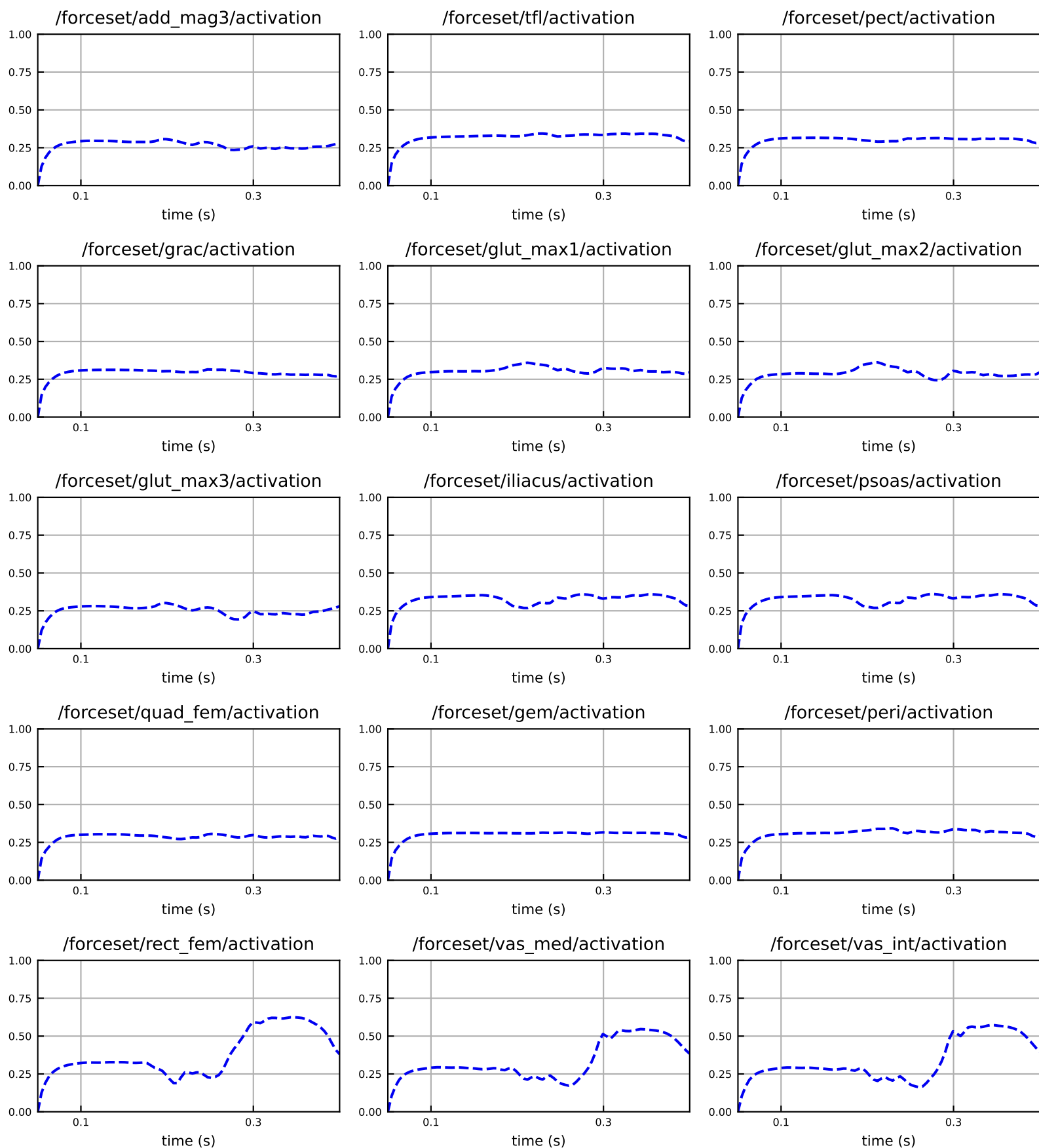
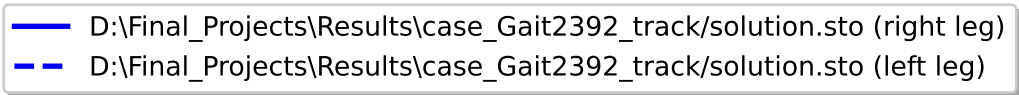


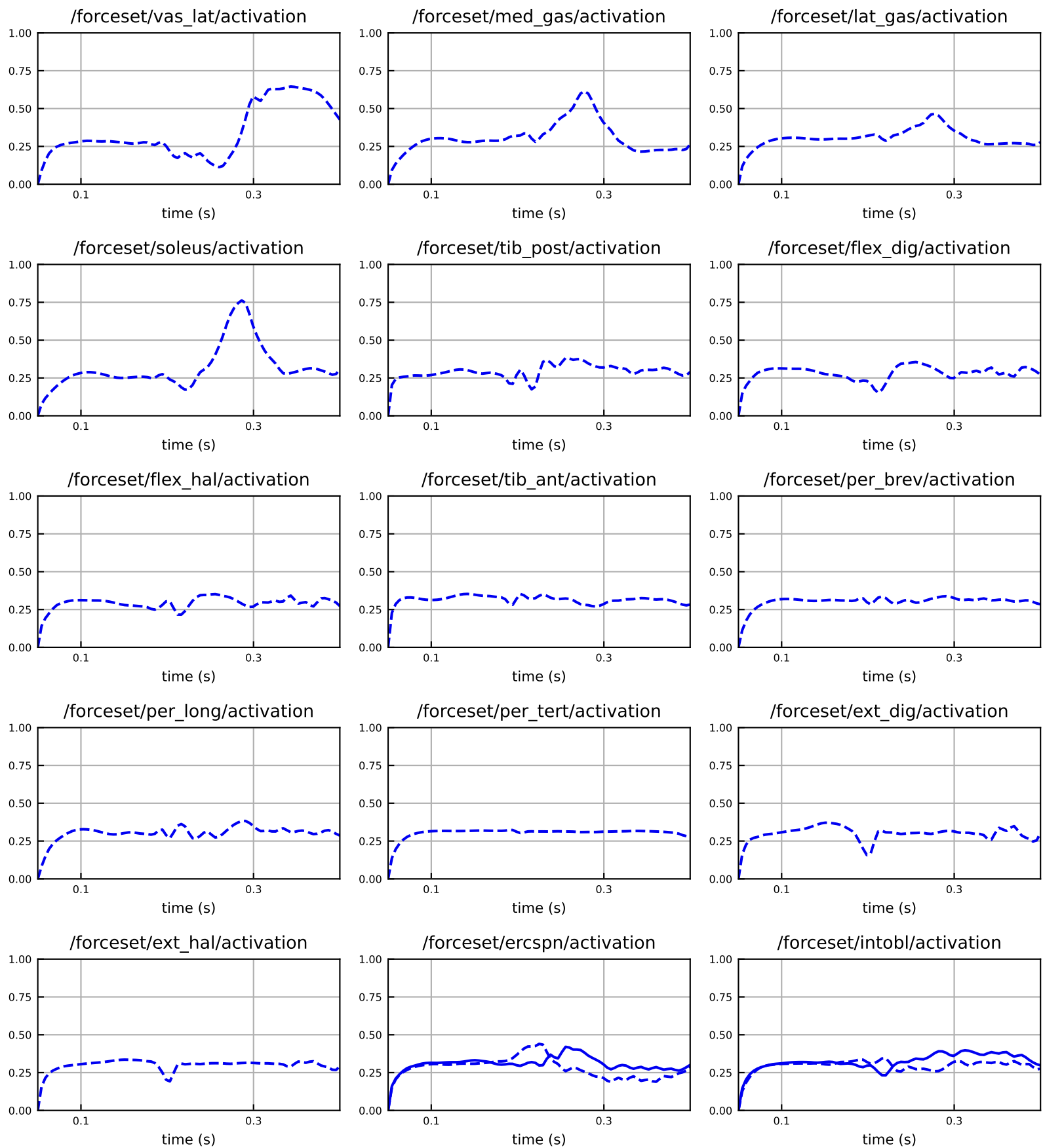
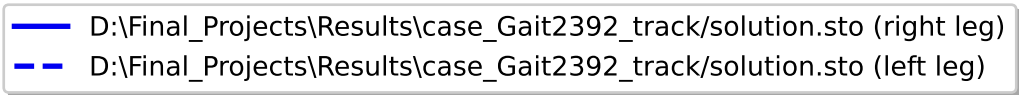
lumbar\_bending/speed

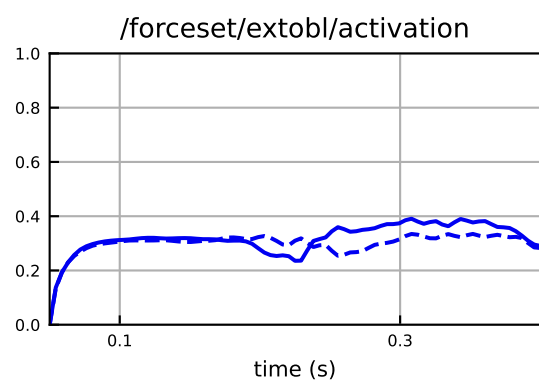
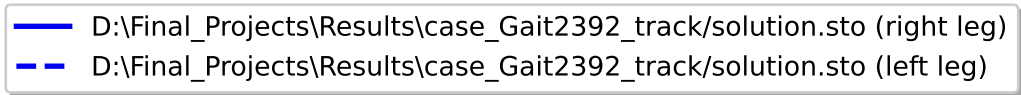


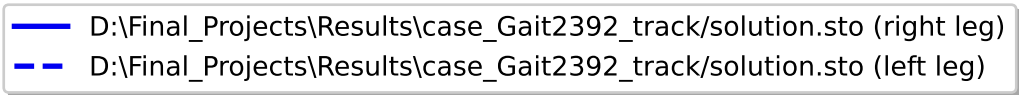




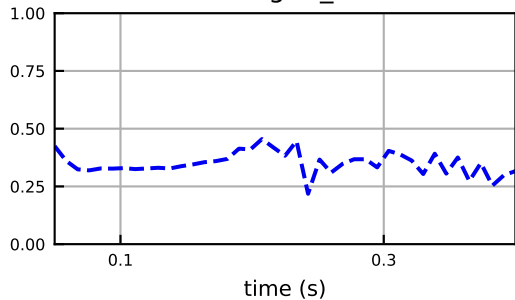




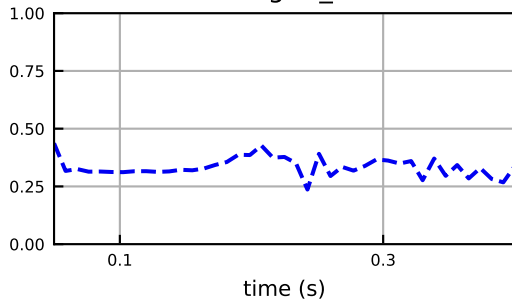




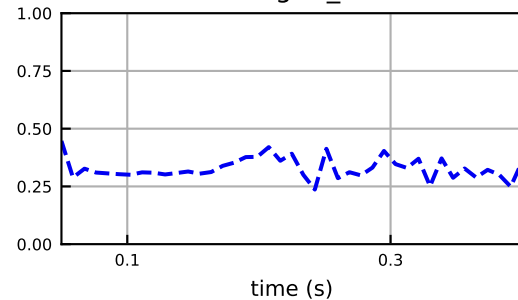
forcesetglut\_med1



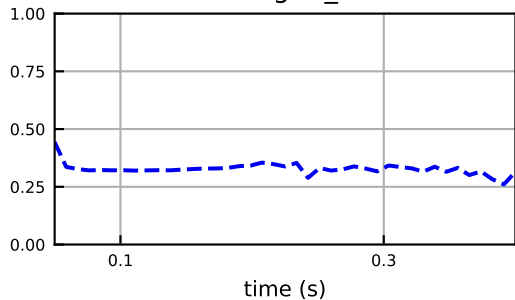
forcesetglut\_med2



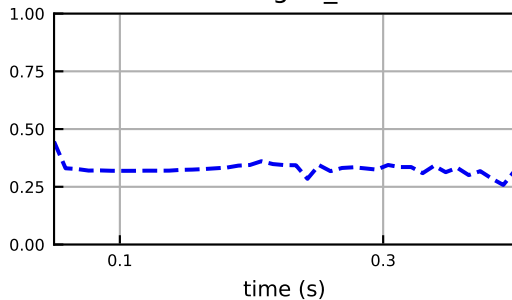
forcesetglut\_med3



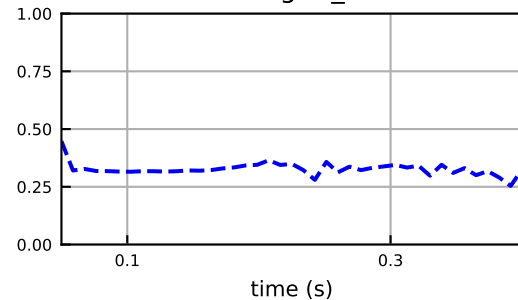
forcesetglut\_min1



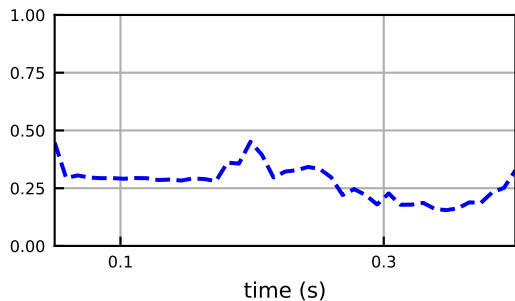
forcesetglut\_min2



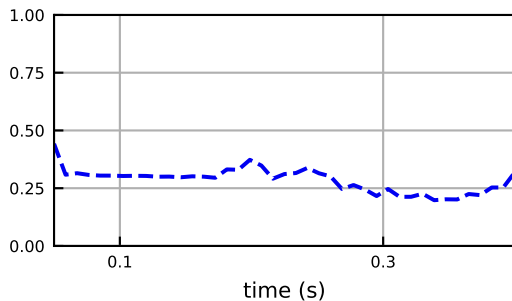
forcesetglut\_min3



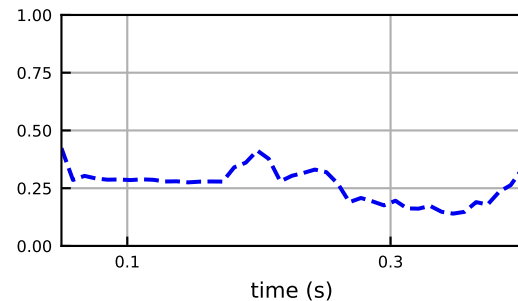
forcesetsemimem



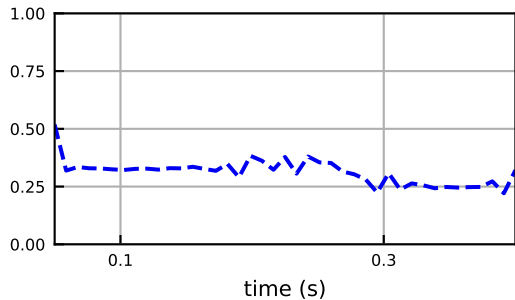
forcesetsemiten



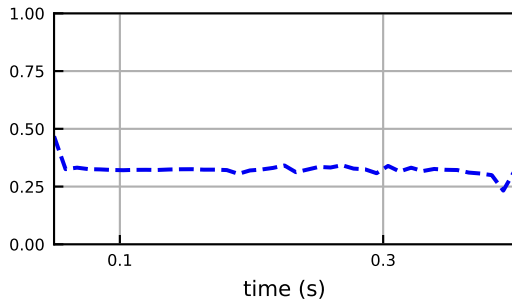
forcesetbifemlh



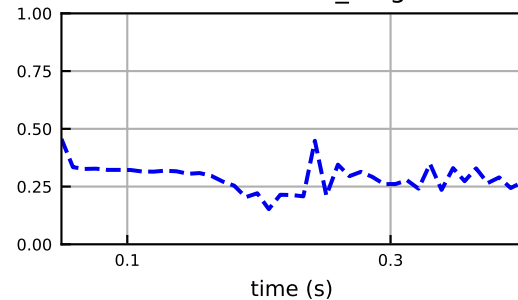
forcesetbifemsh



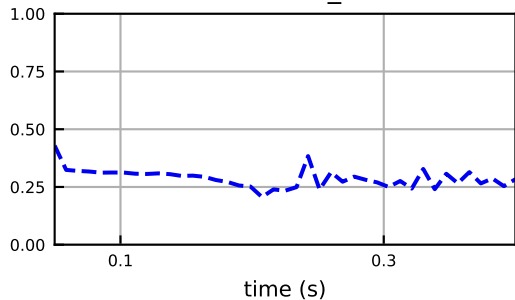
forcesetsar



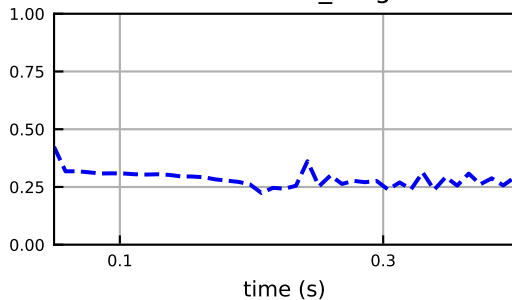
forcesetadd\_long



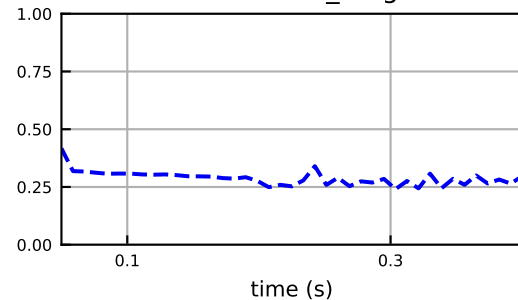
forcesetadd\_brev



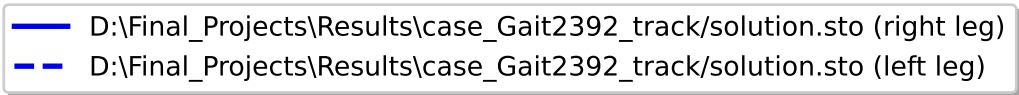
forcesetadd\_mag1



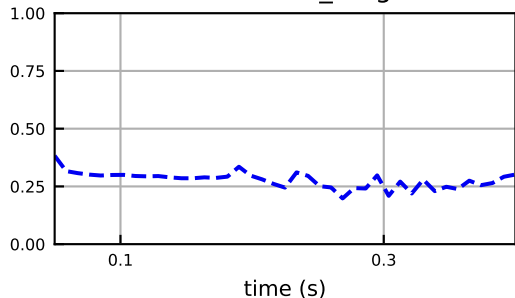
forcesetadd\_mag2



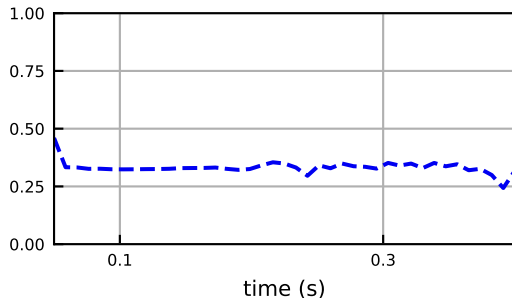




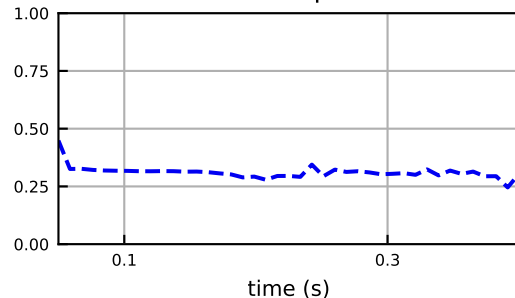
forcesetadd\_mag3



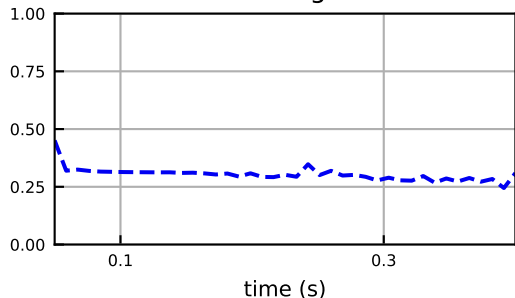
forcesetttfl



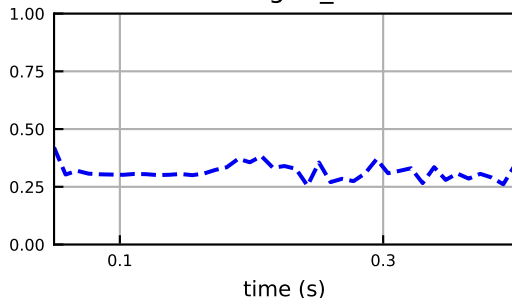
forcesetpect



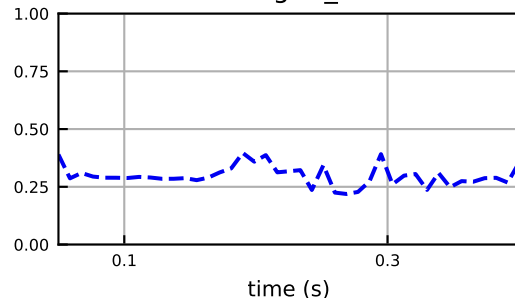
forcesetgrac



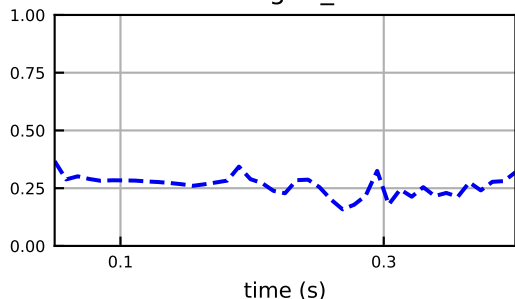
forcesetglut\_max1



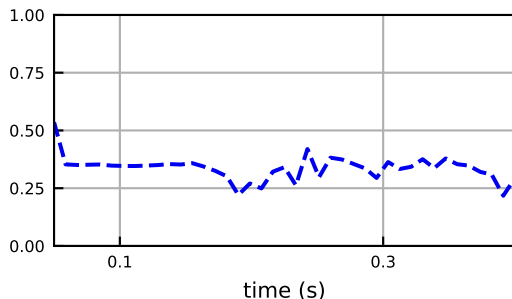
forcesetglut\_max2



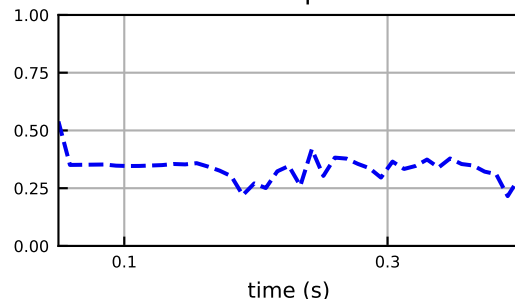
forcesetglut\_max3



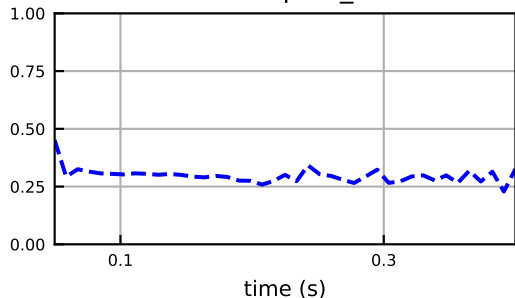
forcesetiliacus



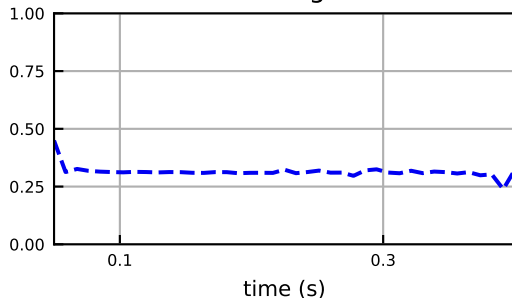
forcesetpsoas



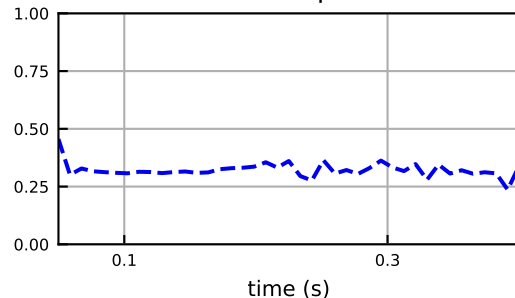
forcesetquad\_fem



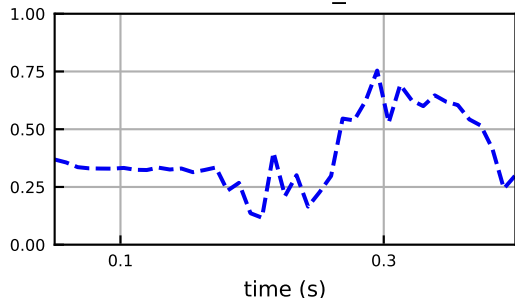
forcesetgem



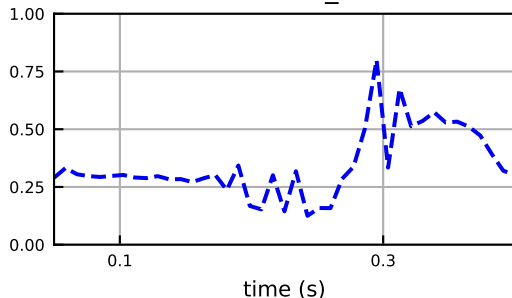
forcesetperi



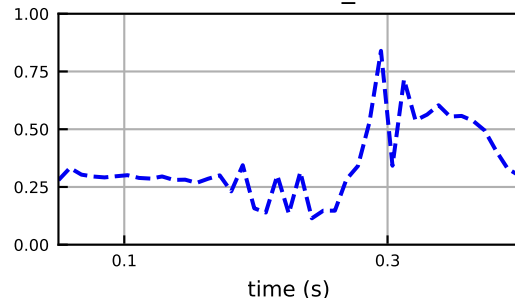
forcesetrect\_fem



forcesetvas\_med



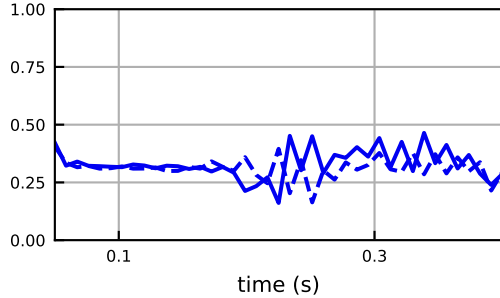
forcesetvas\_int



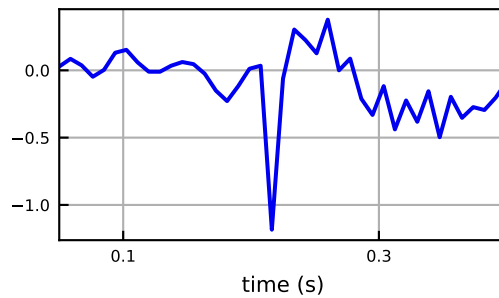


— D:\Final\_Projects\Results\case\_Gait2392\_track\solution.sto (right leg)  
- - - D:\Final\_Projects\Results\case\_Gait2392\_track\solution.sto (left leg)

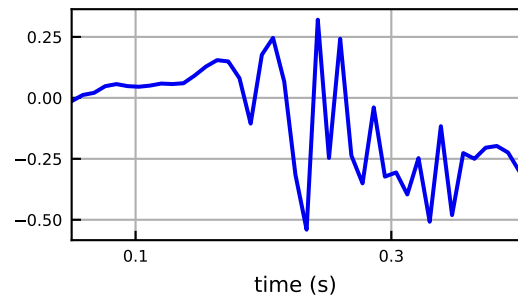
forcesetextobl



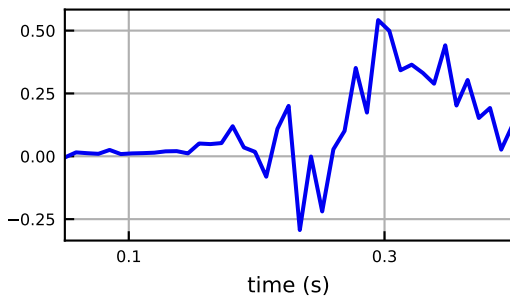
forcesetreserve\_joi...lvis\_pelvis\_tilt



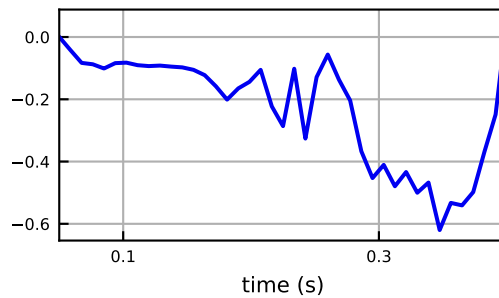
forcesetreserve\_joi...lvis\_pelvis\_list



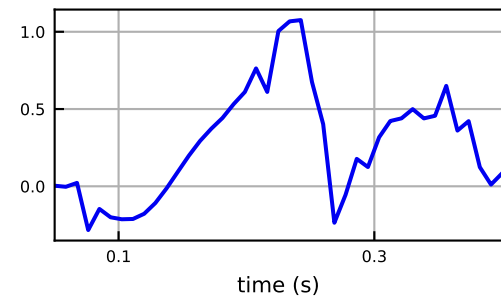
forcesetreserve\_joi...\_pelvis\_rotation



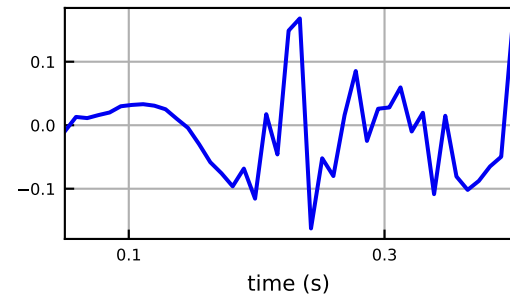
forcesetreserve\_joi...pelvis\_pelvis\_tx



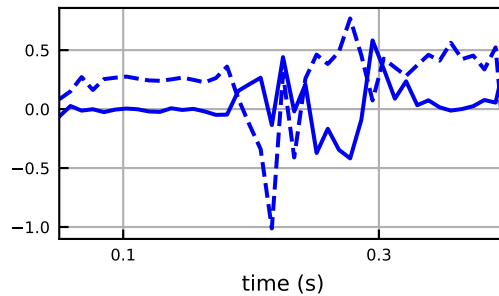
forcesetreserve\_joi...pelvis\_pelvis\_ty



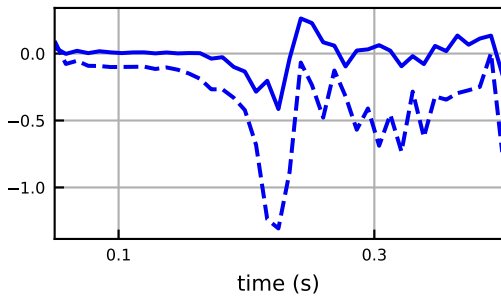
forcesetreserve\_joi...pelvis\_pelvis\_tz



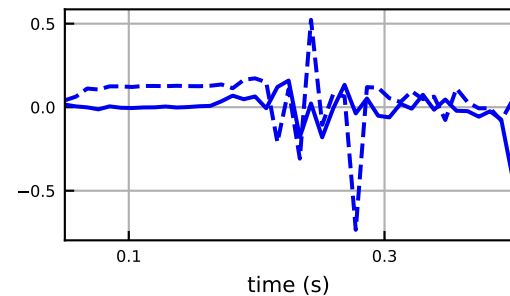
forcesetreserve\_joi...\_hip\_hip\_flexion



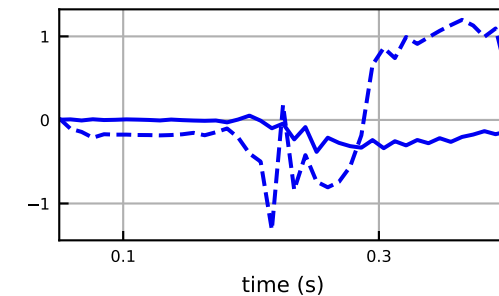
forcesetreserve\_joi...ip\_hip\_adduction



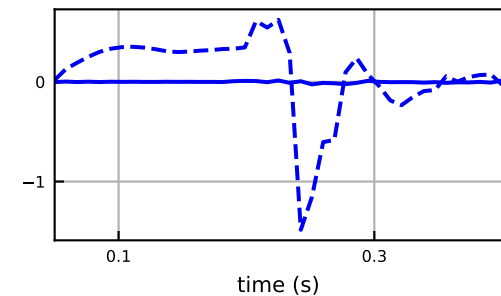
forcesetreserve\_joi...hip\_hip\_rotation



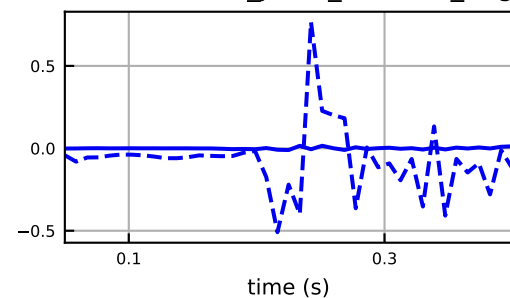
forcesetreserve\_joi...\_knee\_knee\_angle



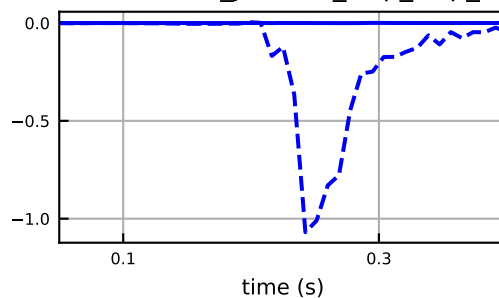
forcesetreserve\_joi...nkle\_ankle\_angle



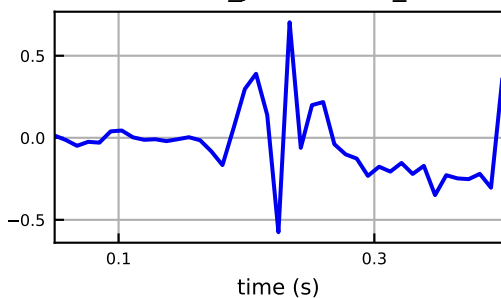
forcesetreserve\_joi...r\_subtalar\_angle

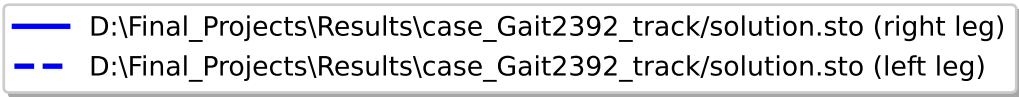


forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension





forcesetreserve\_joi...k\_lumbar\_bending    forcesetreserve\_joi...\_lumbar\_rotation

