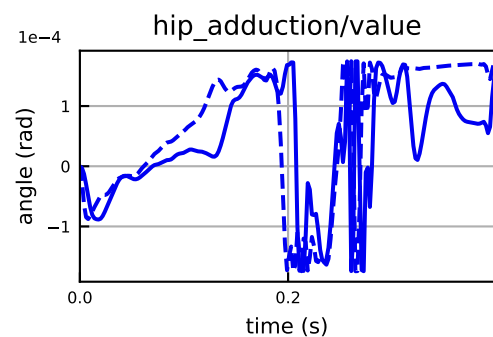
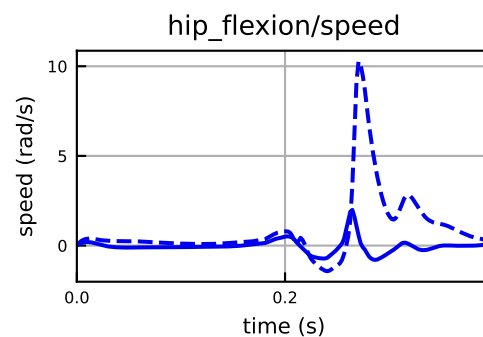
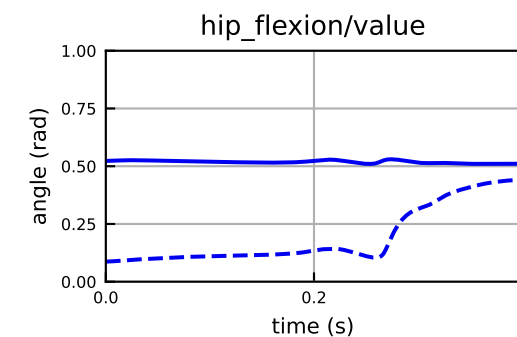
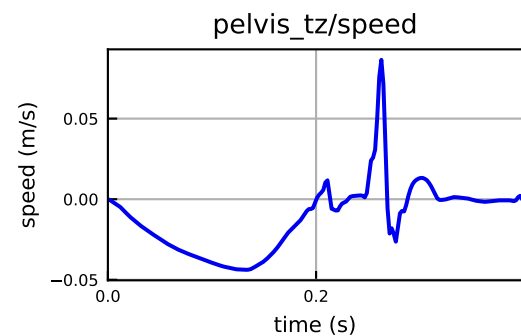
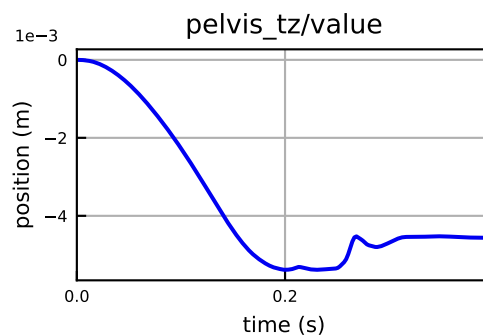
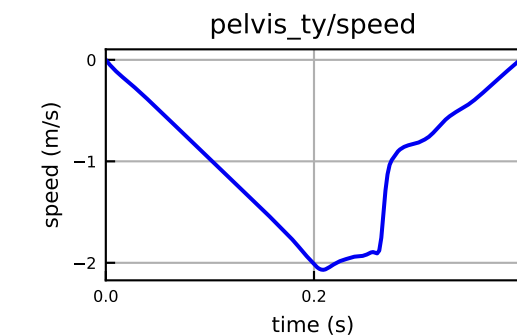
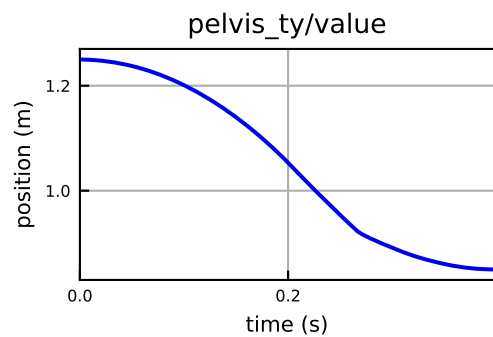
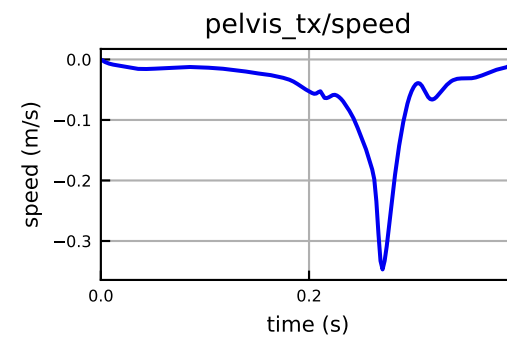
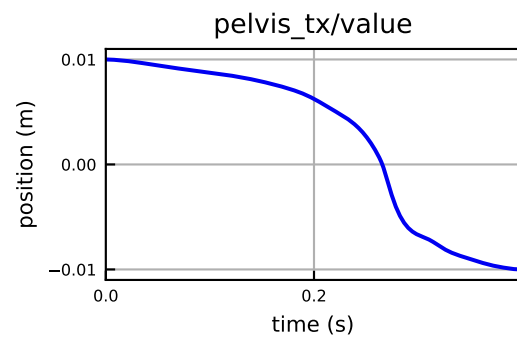
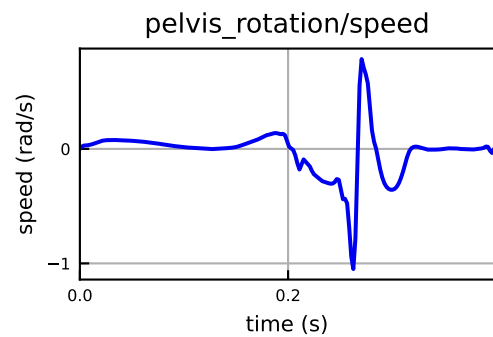
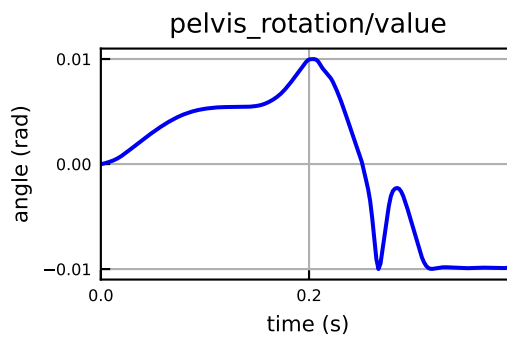
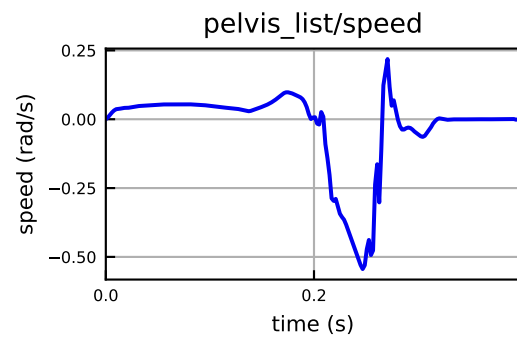
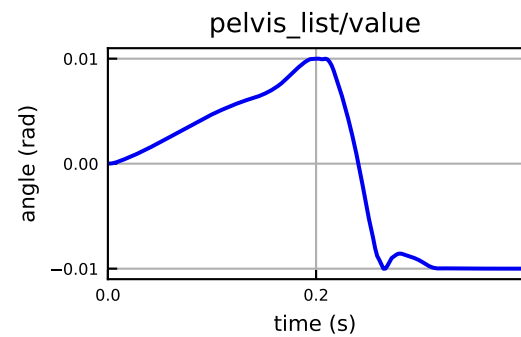
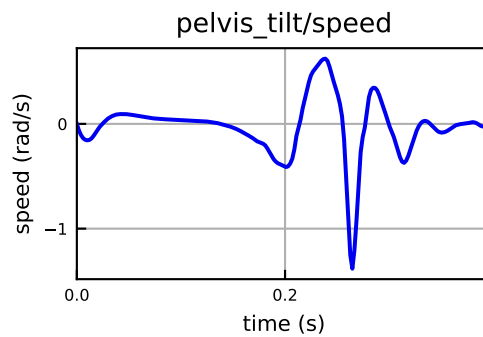
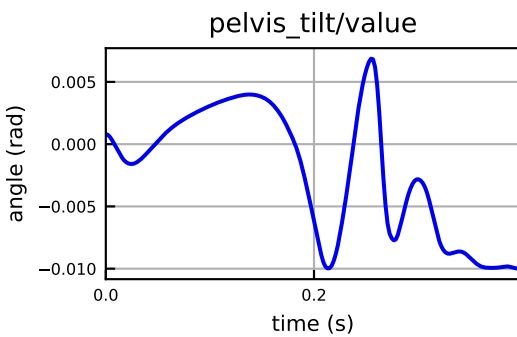
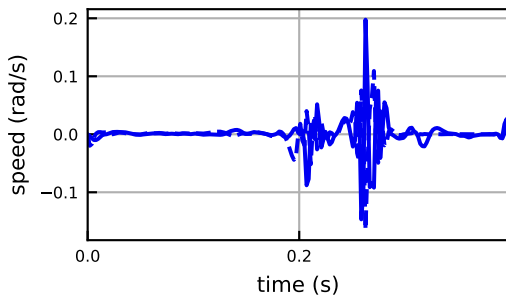


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

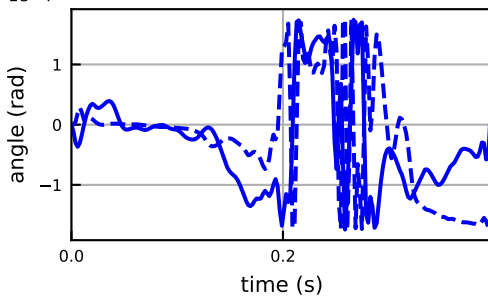


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

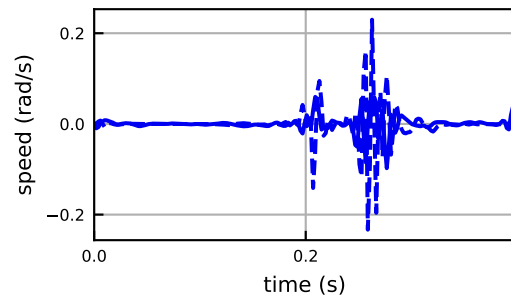
hip\_adduction/speed



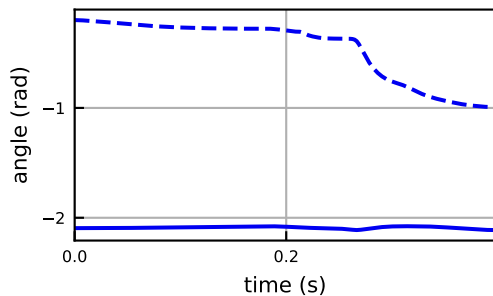
hip\_rotation/value



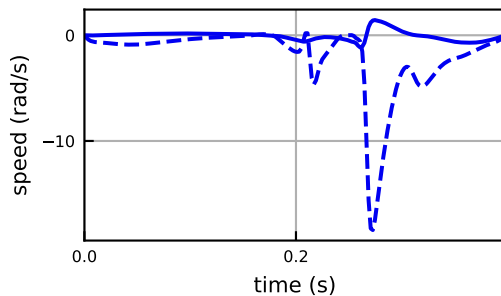
hip\_rotation/speed



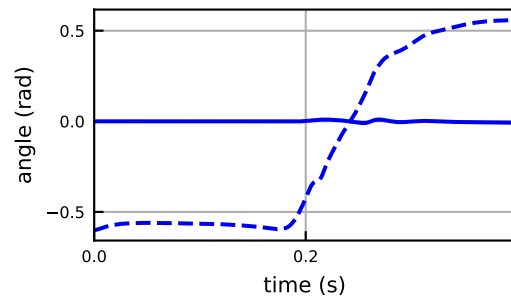
knee\_angle/value



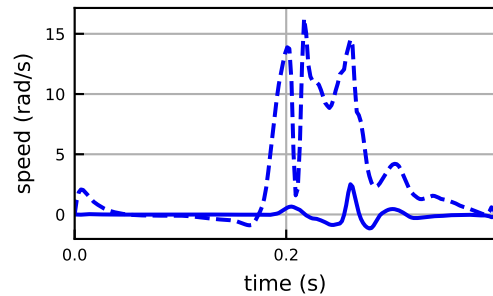
knee\_angle/speed



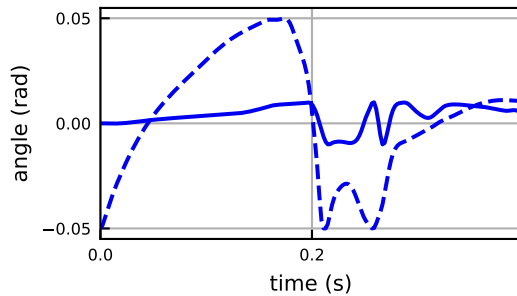
ankle\_angle/value



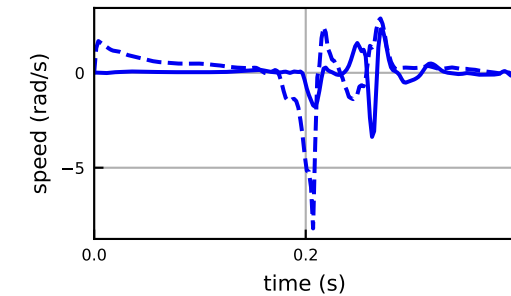
ankle\_angle/speed



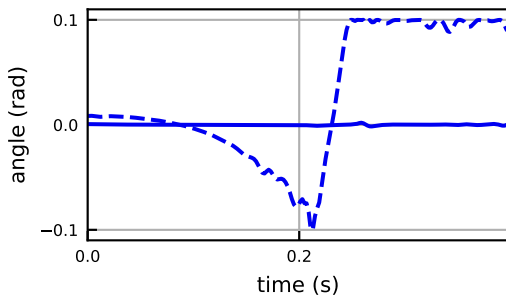
subtalar\_angle/value



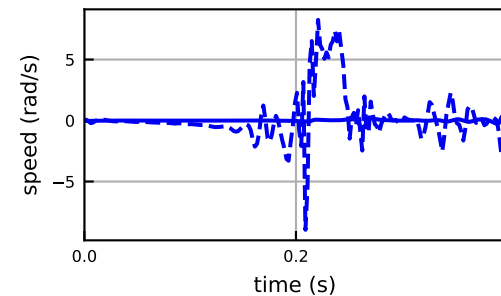
subtalar\_angle/speed



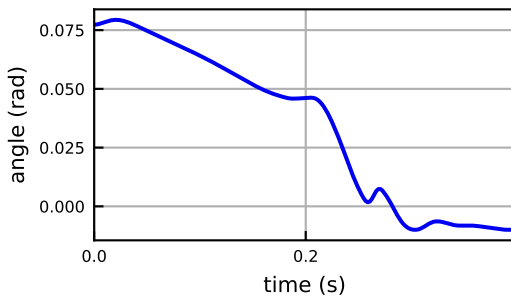
mtp\_angle/value



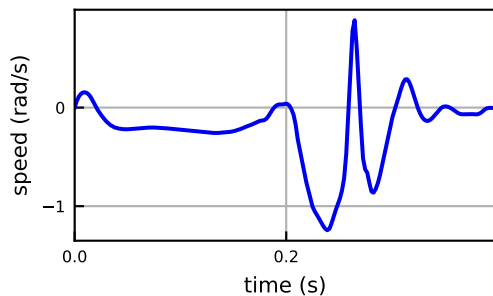
mtp\_angle/speed



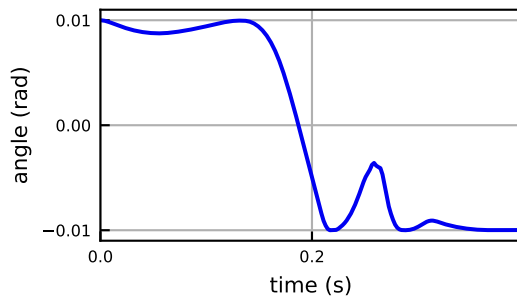
lumbar\_extension/value



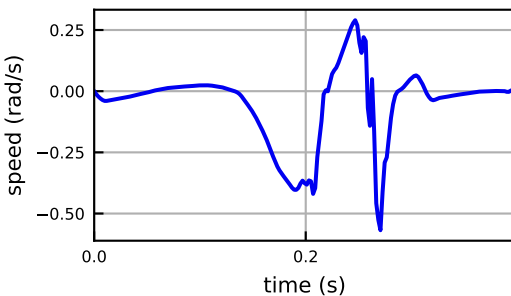
lumbar\_extension/speed



lumbar\_bending/value

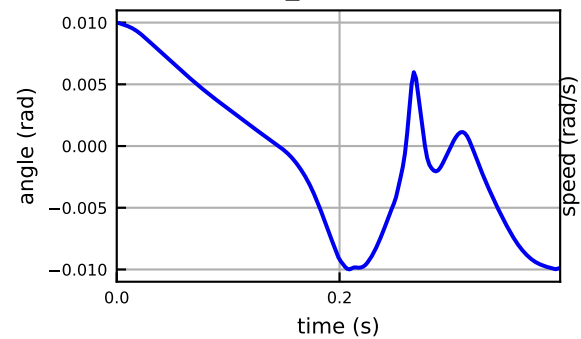


lumbar\_bending/speed

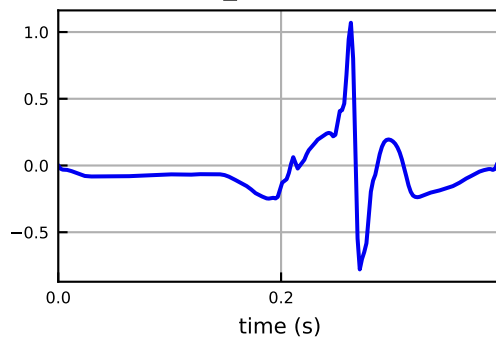


- D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

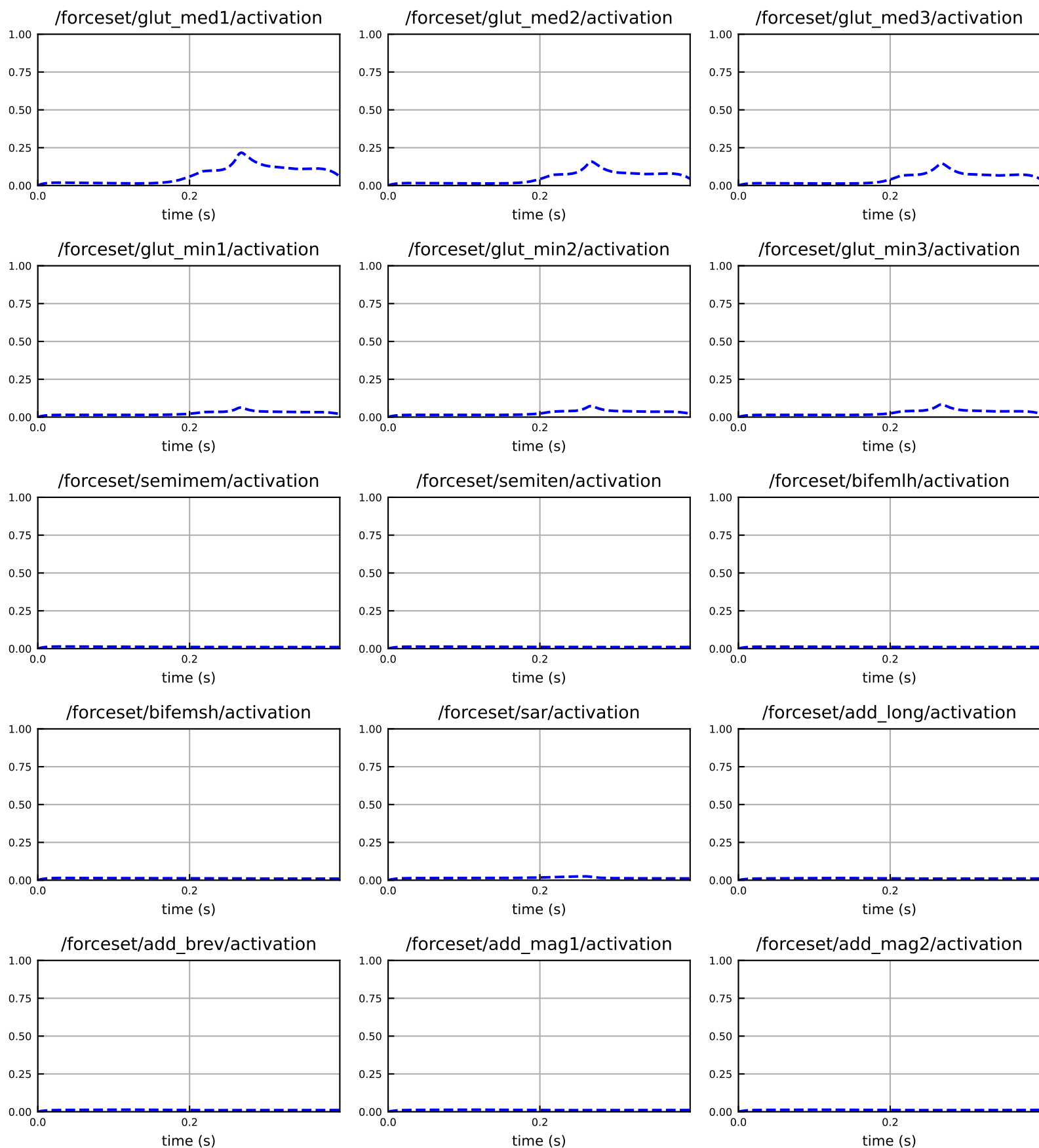
lumbar\_rotation/value



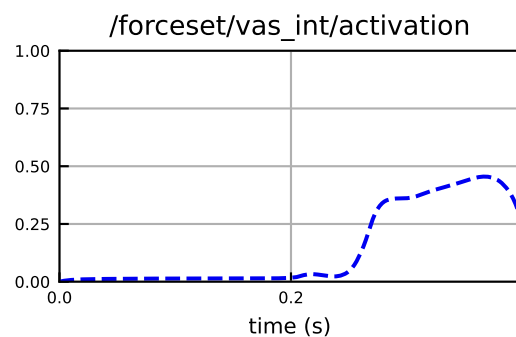
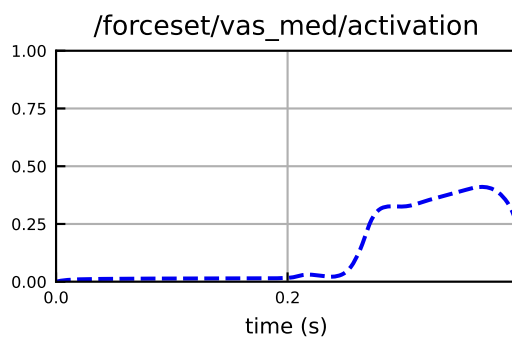
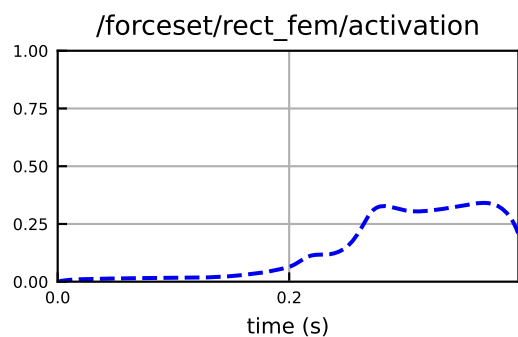
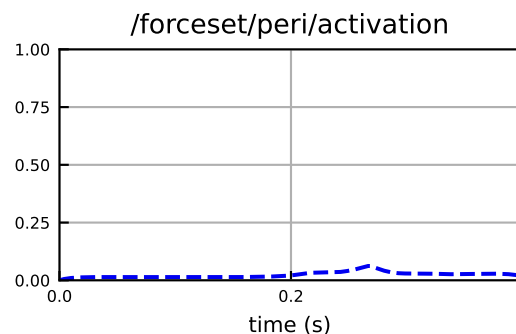
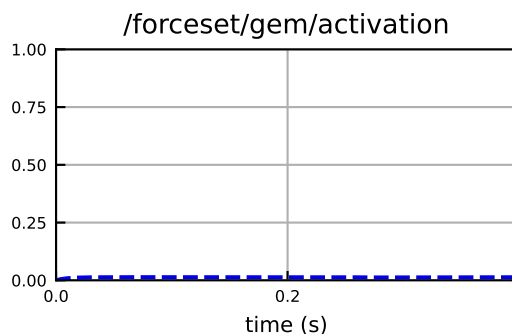
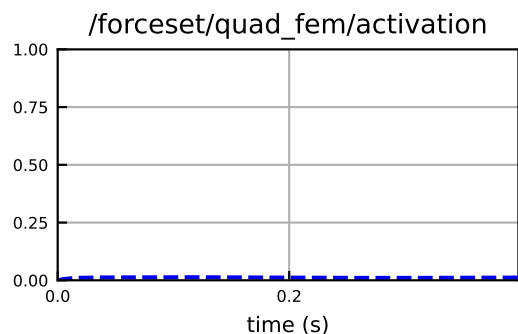
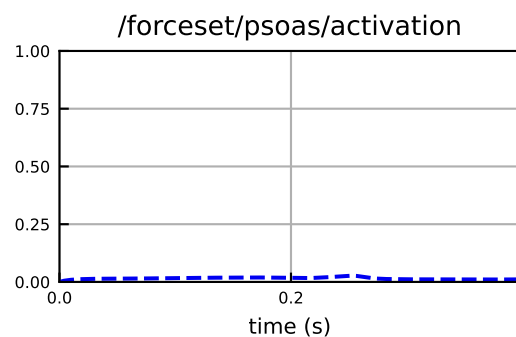
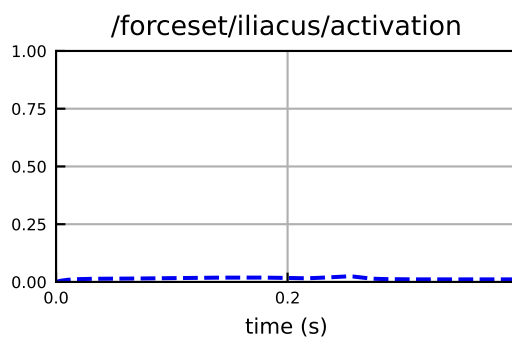
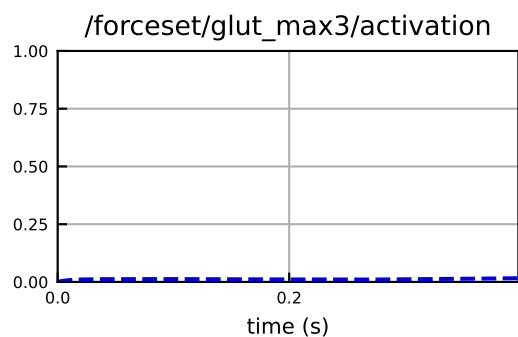
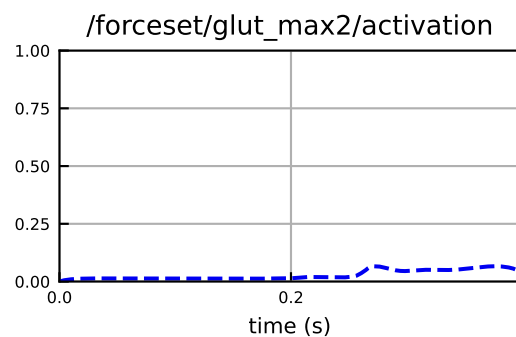
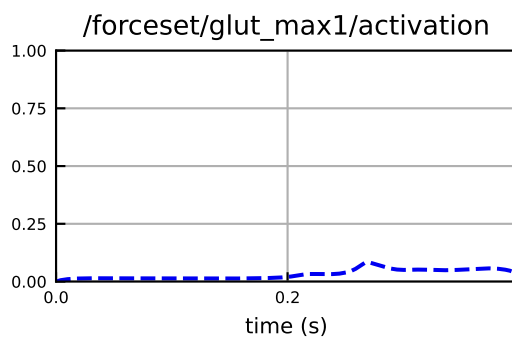
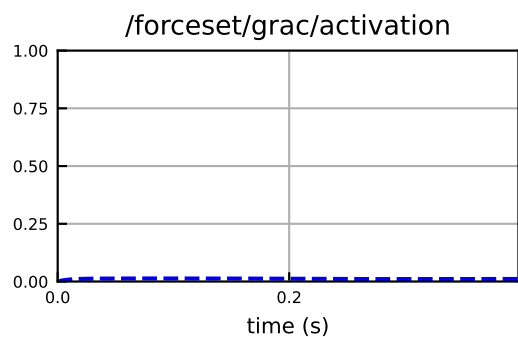
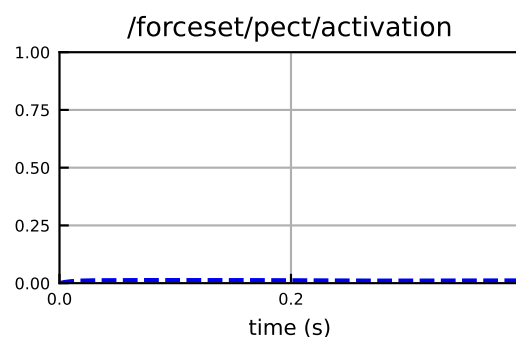
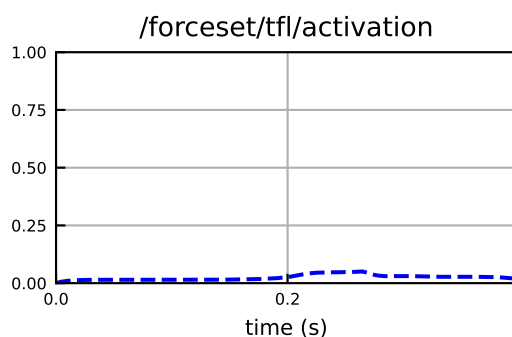
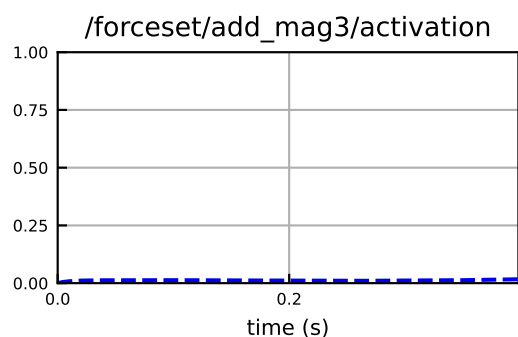
lumbar\_rotation/speed



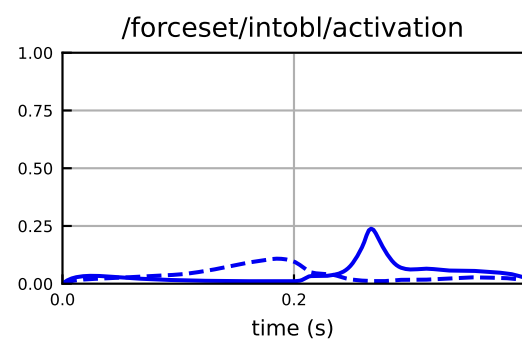
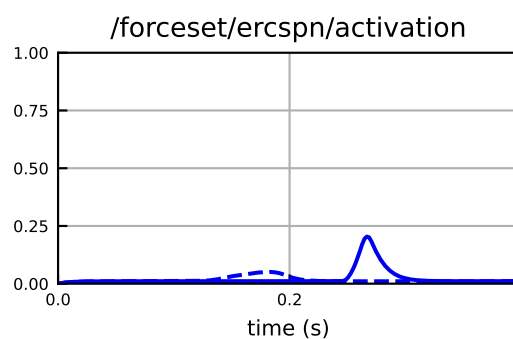
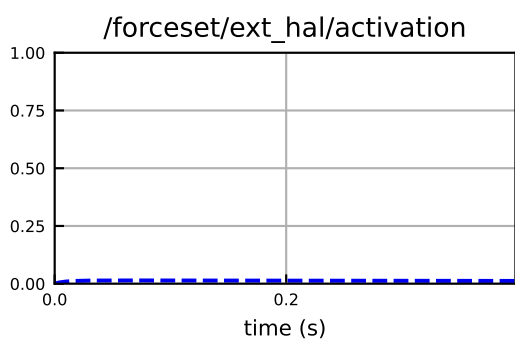
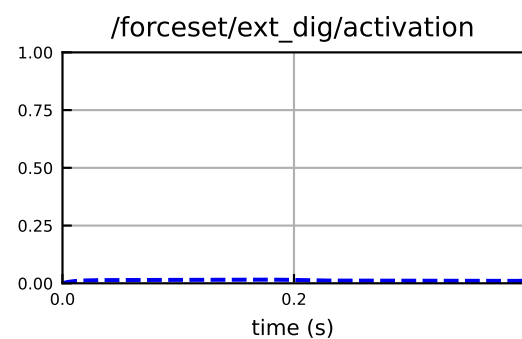
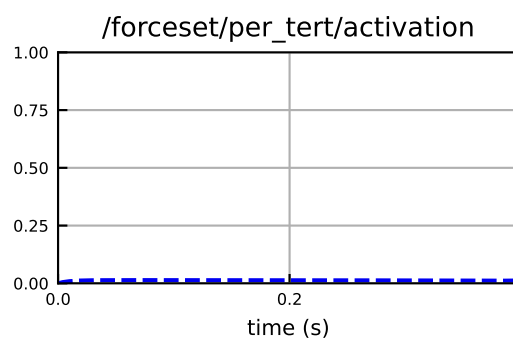
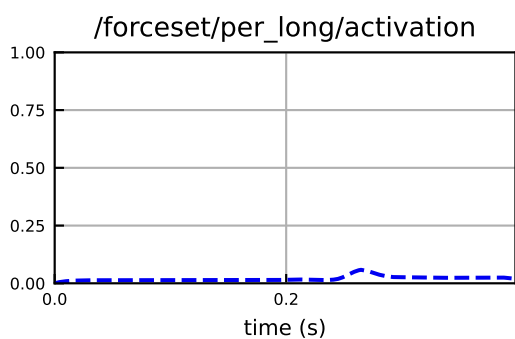
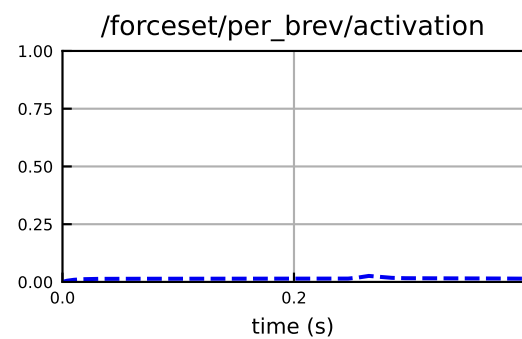
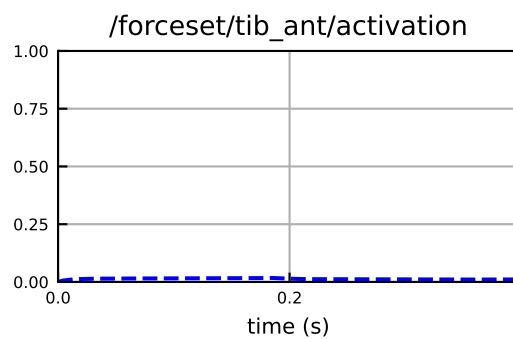
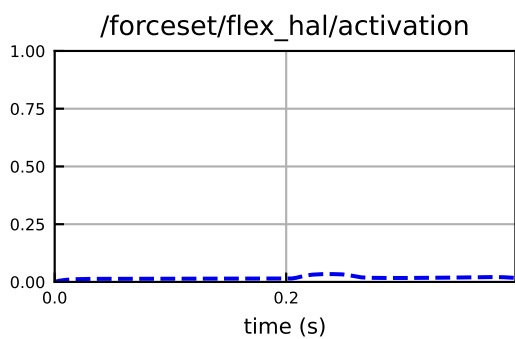
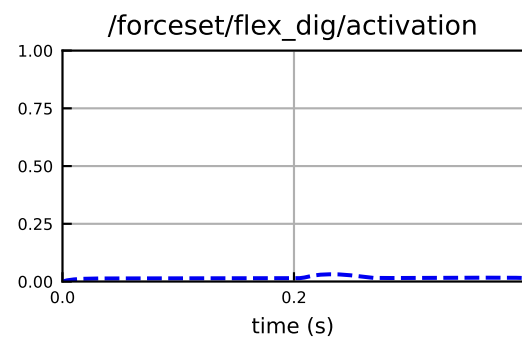
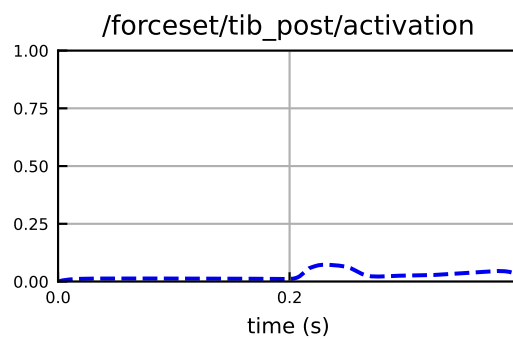
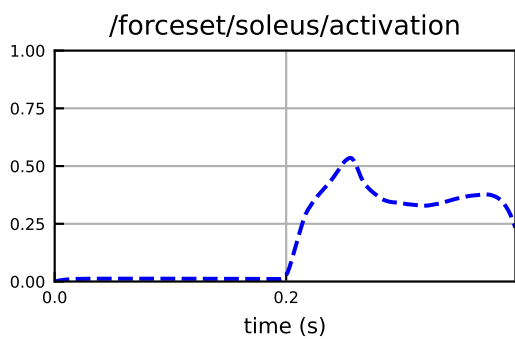
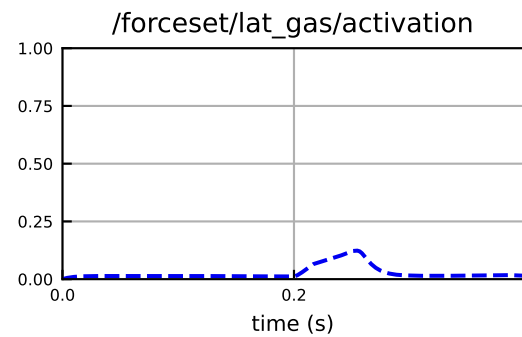
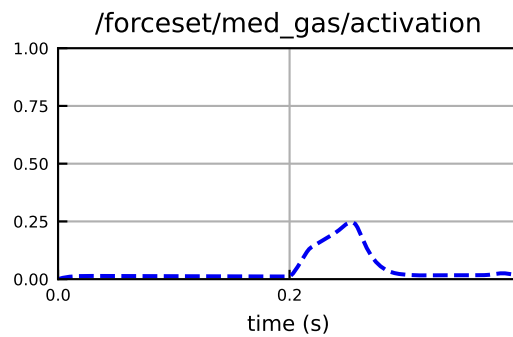
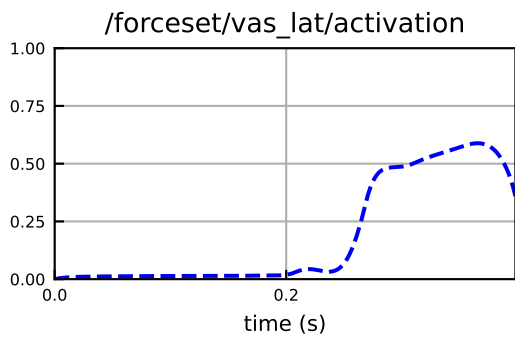
— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)



— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

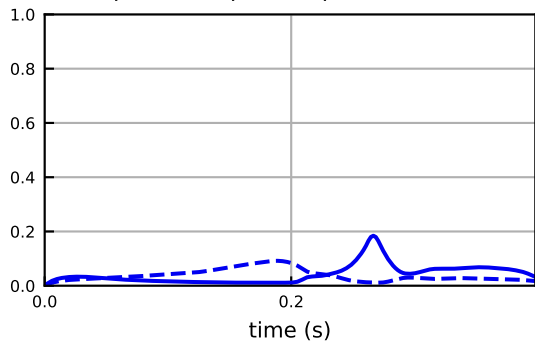


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)



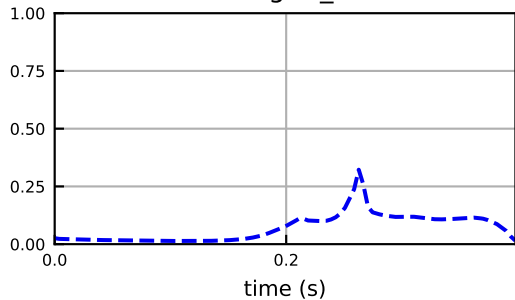
- D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

/forceset/extobl/activation

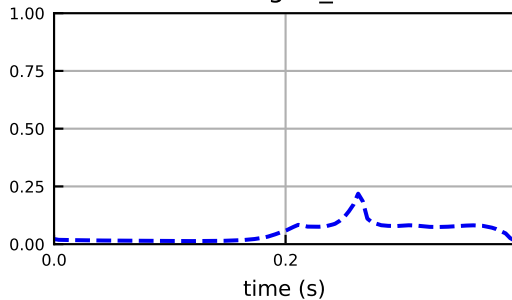


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

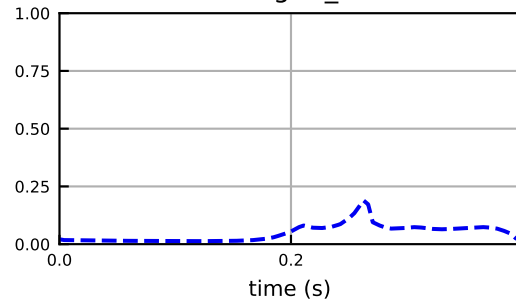
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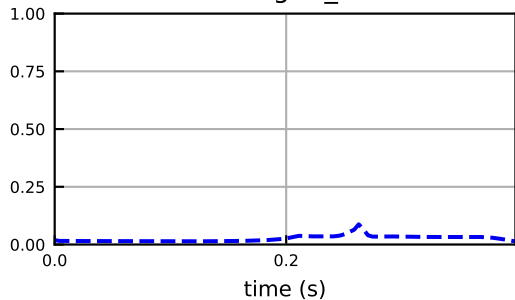
forcesetglut\_med2



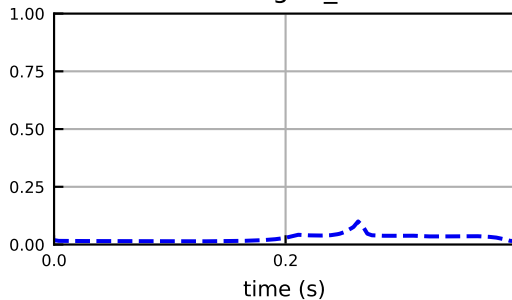
forcesetglut\_med3



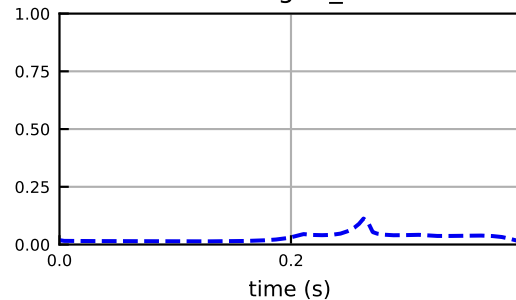
forcesetglut\_min1



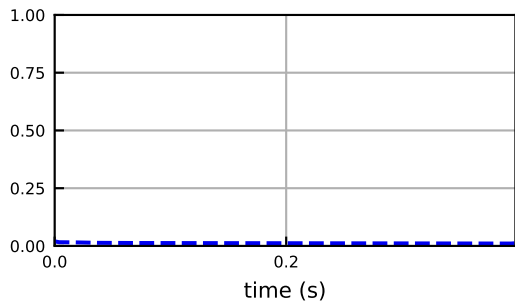
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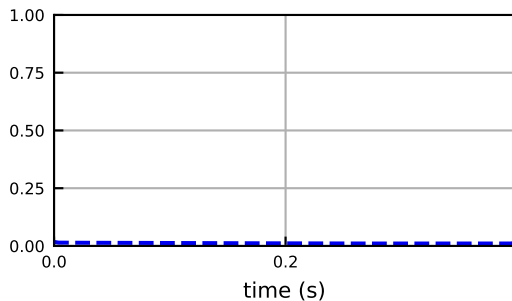
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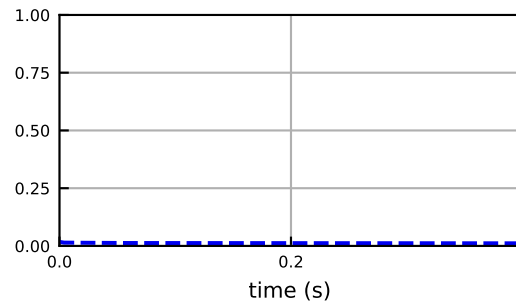
forcesetsemimem



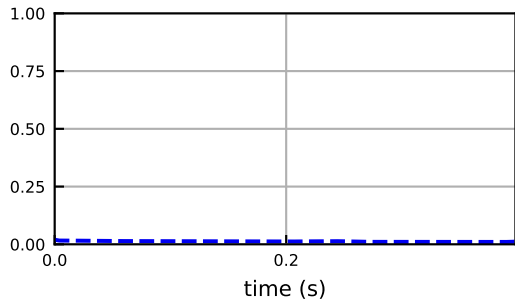
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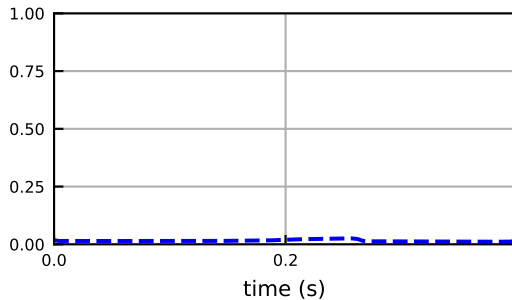
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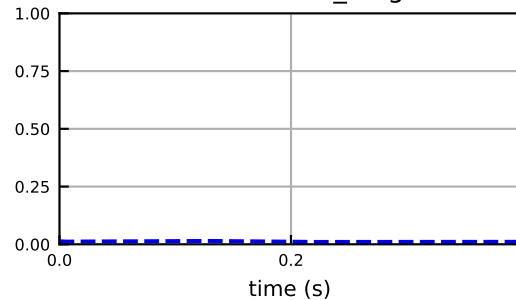
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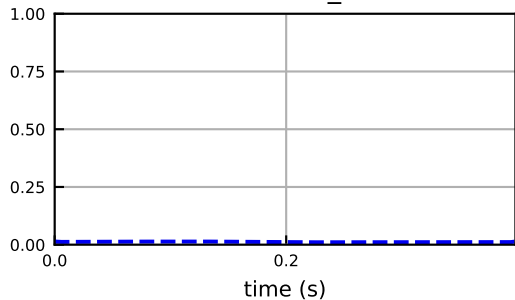
forcesetsar



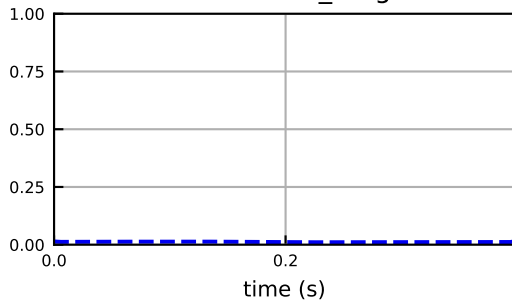
forcesetadd\_long



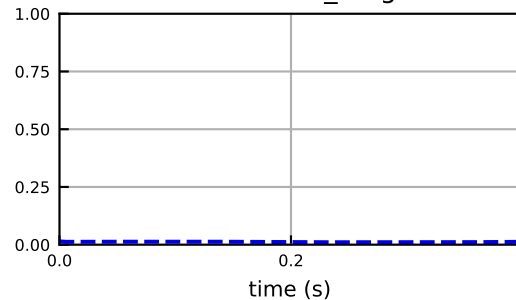
forcesetadd\_brev



forcesetadd\_mag1



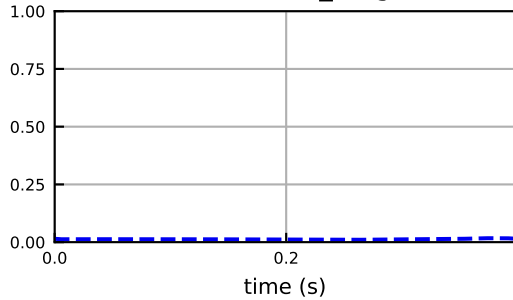
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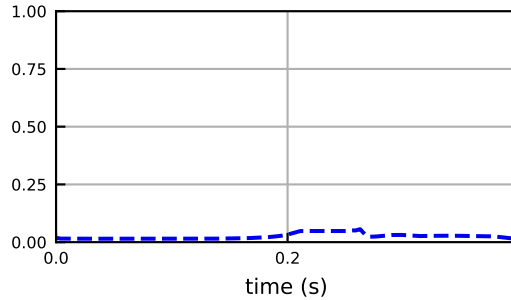


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

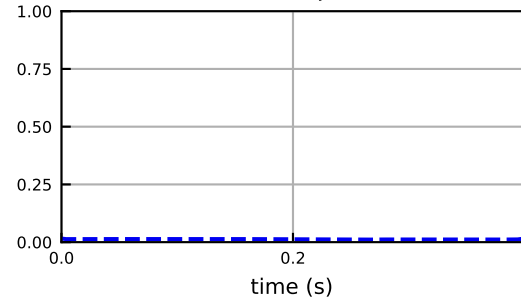
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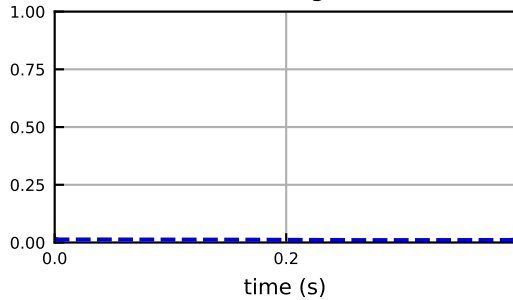
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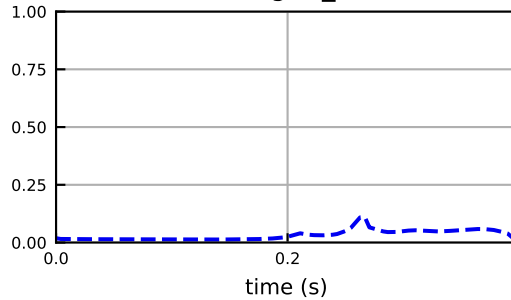
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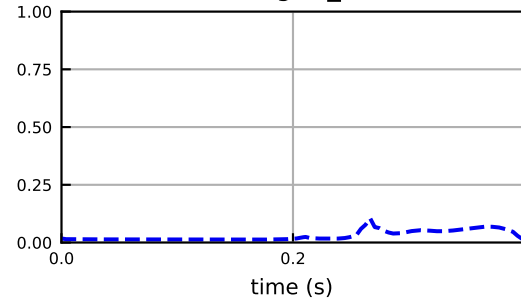
forcesetgrac



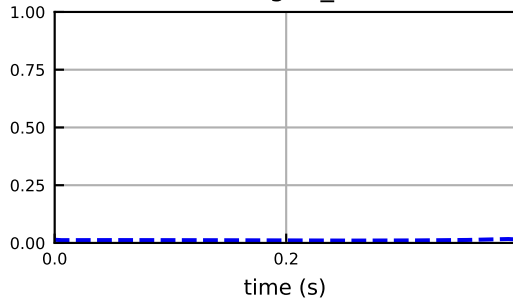
forcesetglut\_max1



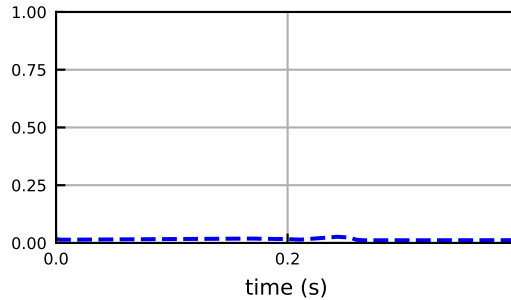
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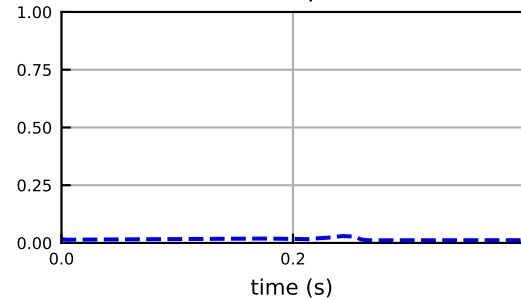
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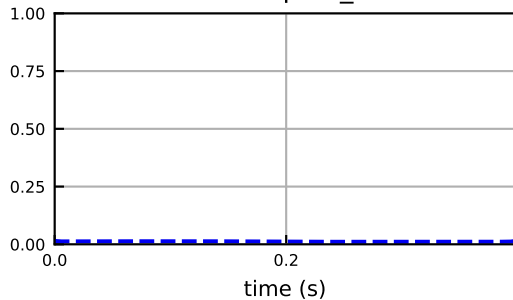
forcesetiliacus



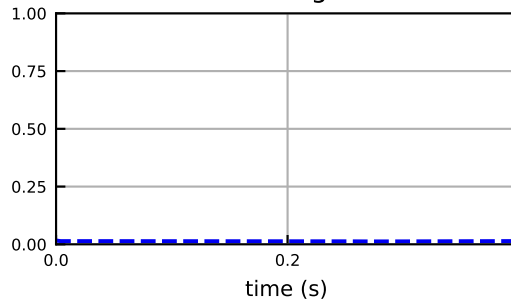
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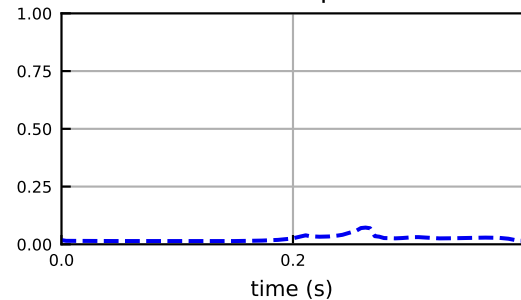
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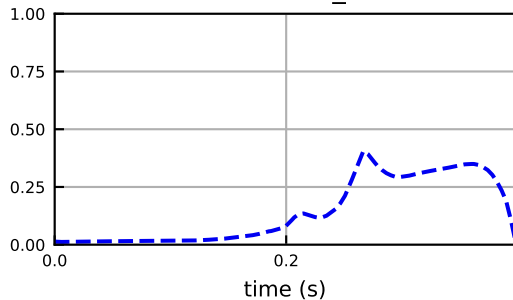
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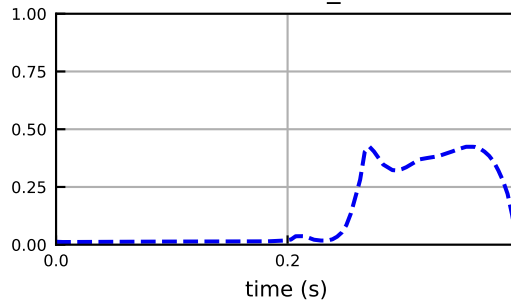
forcesetperi



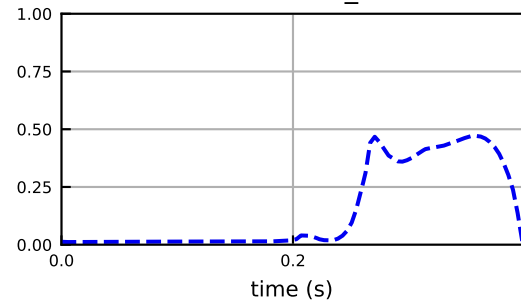
forcesetrect\_fem



forcesetvas\_med

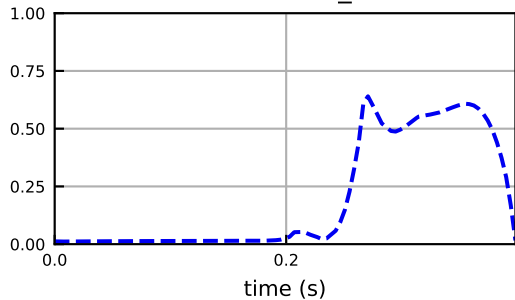


forcesetvas\_int

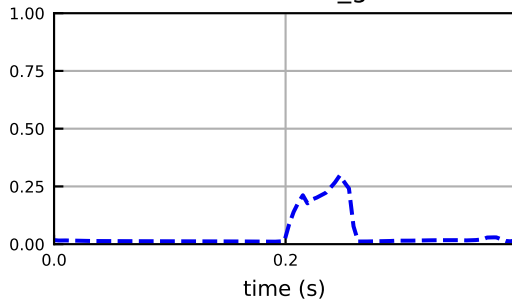


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

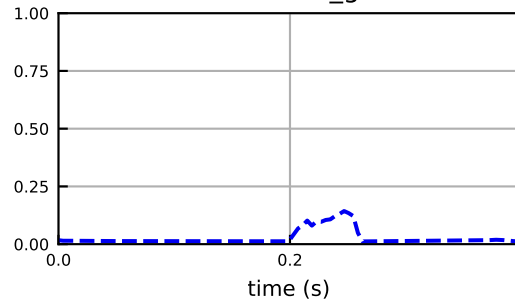
forcesetvas\_lat



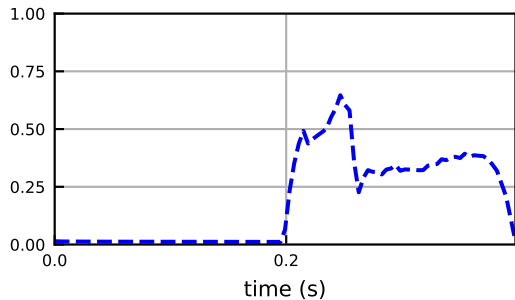
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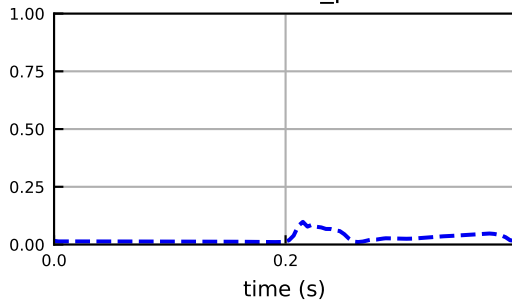
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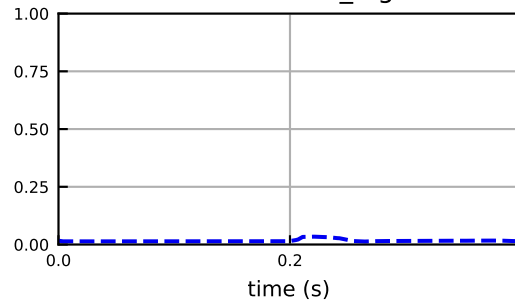
forcesetsoleus



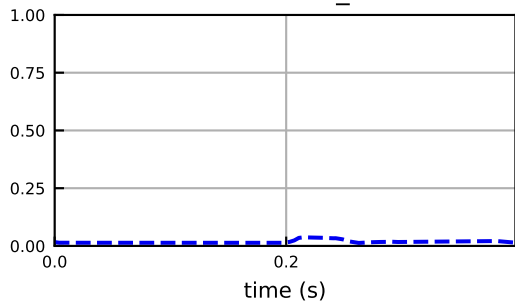
forcesettib\_post



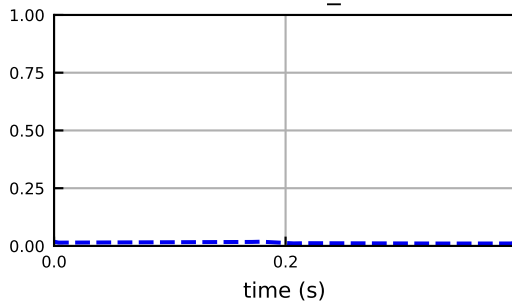
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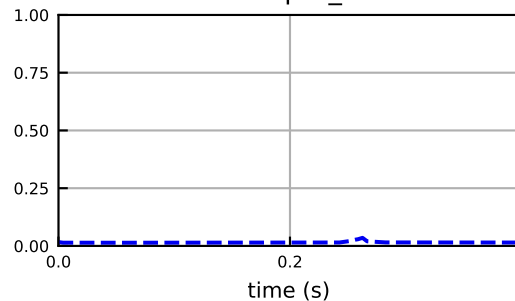
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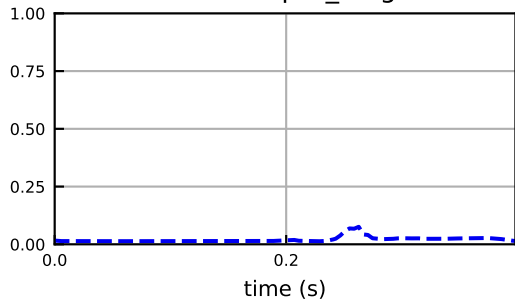
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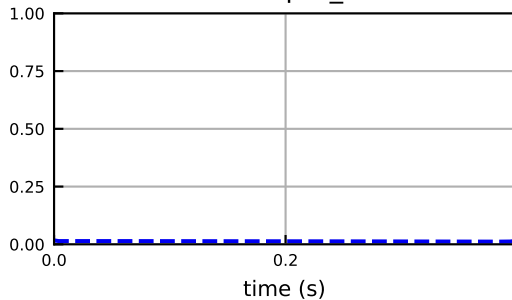
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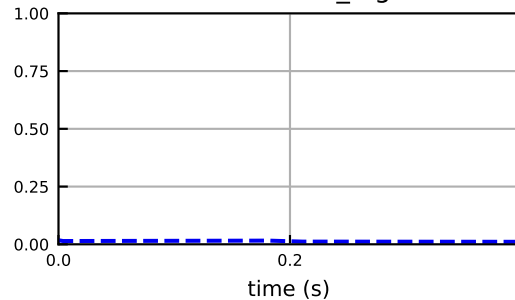
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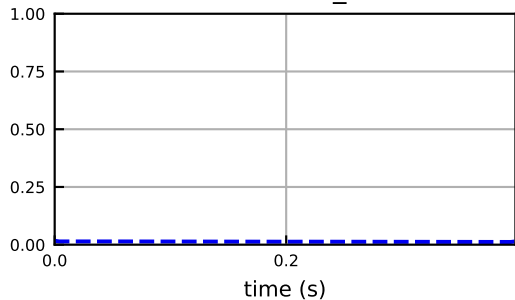
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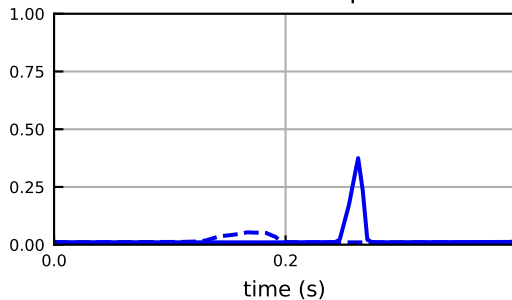
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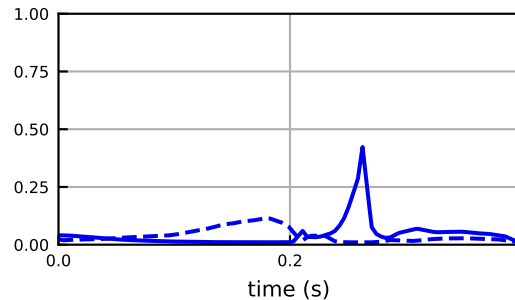
forcesetext\_hal



forcesetercspn

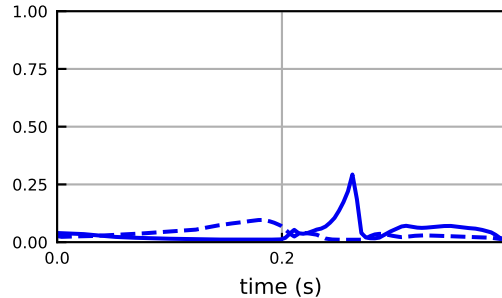


forcesetintobl

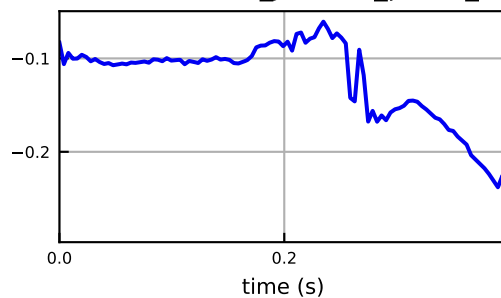


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

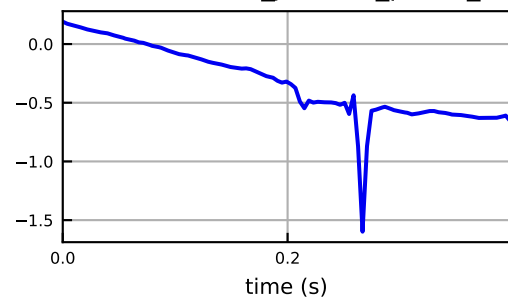
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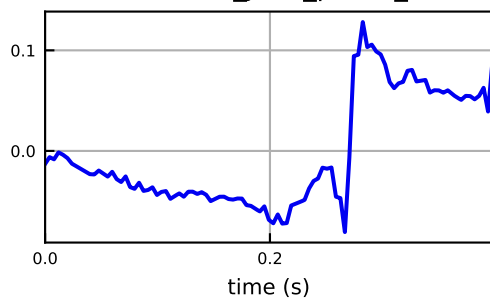
forcesetreserve\_joi...lvis\_pelvis\_tilt



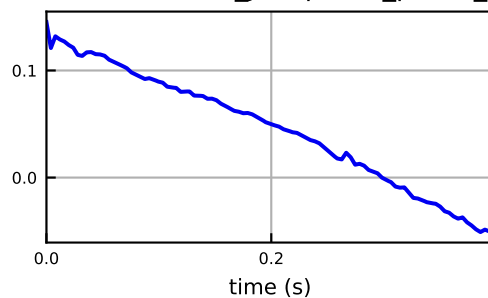
forcesetreserve\_joi...lvis\_pelvis\_list



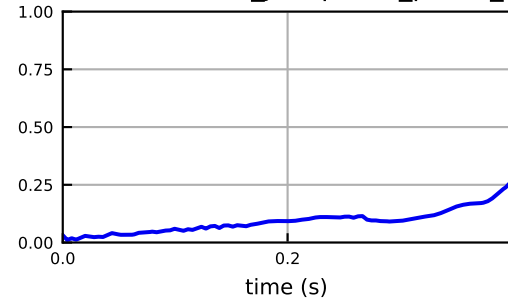
forcesetreserve\_joi...\_pelvis\_rotation



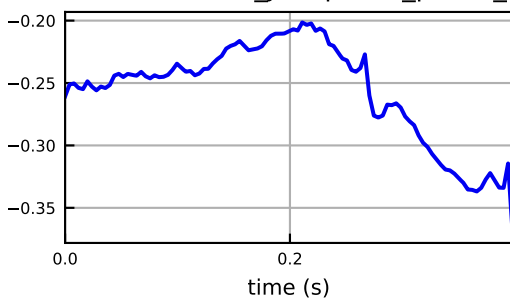
forcesetreserve\_joi...pelvis\_pelvis\_tx



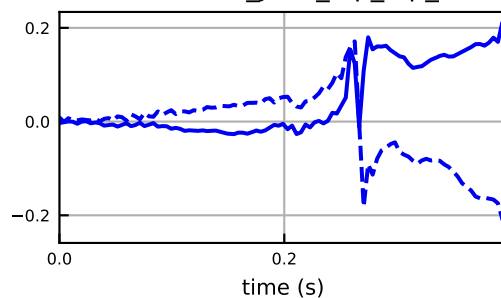
forcesetreserve\_joi...pelvis\_pelvis\_ty



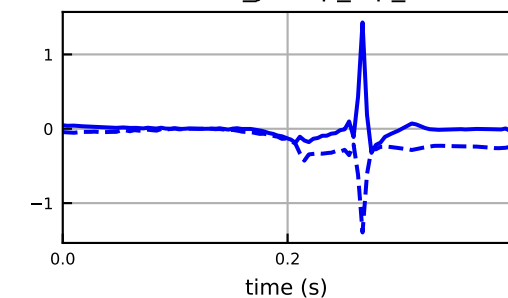
forcesetreserve\_joi...pelvis\_pelvis\_tz



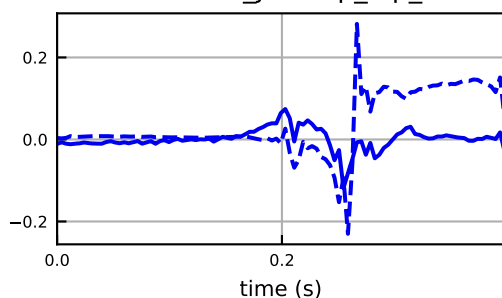
forcesetreserve\_joi...\_hip\_hip\_flexion



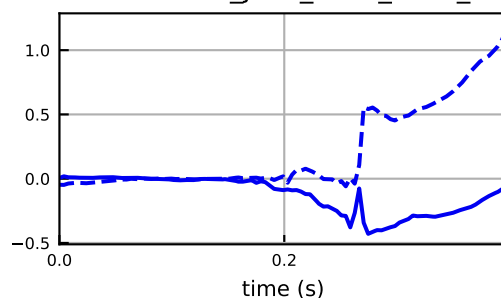
forcesetreserve\_joi...ip\_hip\_adduction



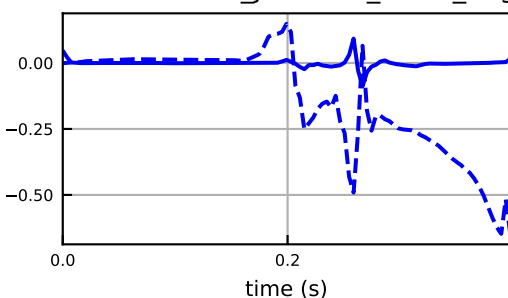
forcesetreserve\_joi...hip\_hip\_rotation



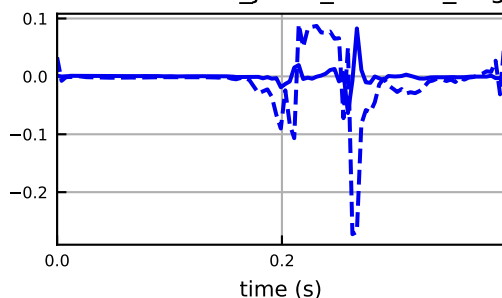
forcesetreserve\_joi...\_knee\_knee\_angle



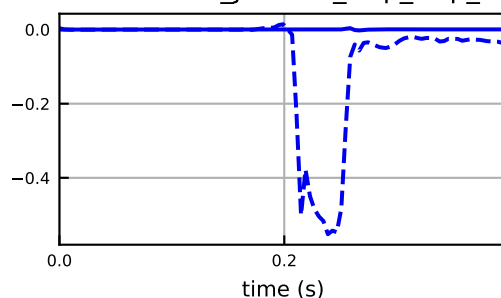
forcesetreserve\_joi...nkle\_ankle\_angle



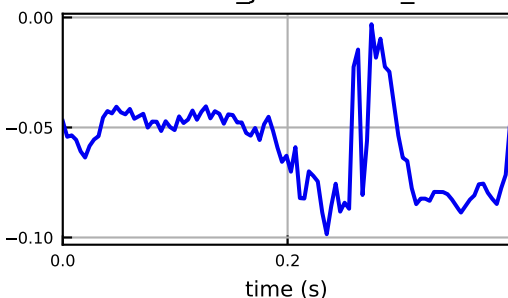
forcesetreserve\_joi...r\_subtalar\_angle



forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension



— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.2\ext\_5\solution.sto (left leg)

forcesetreserve\_joi...k\_lumbar\_bending forcesetreserve\_joi...\_lumbar\_rotation

