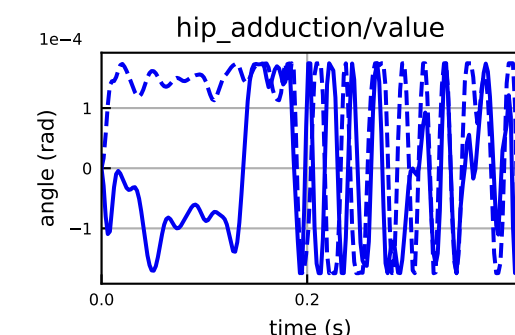
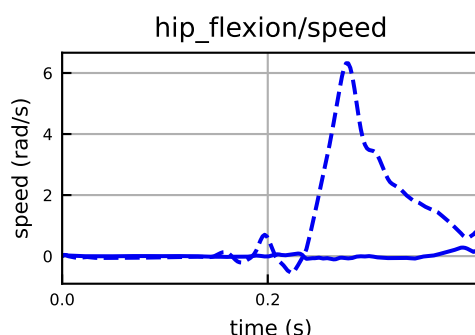
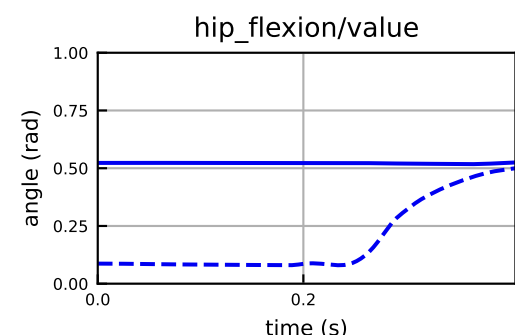
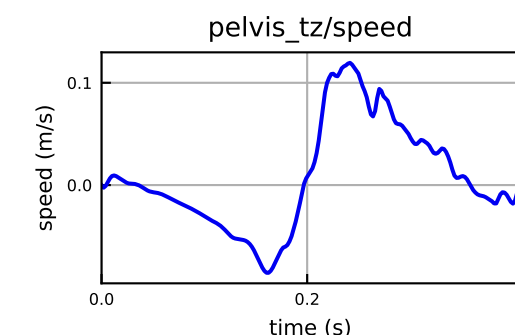
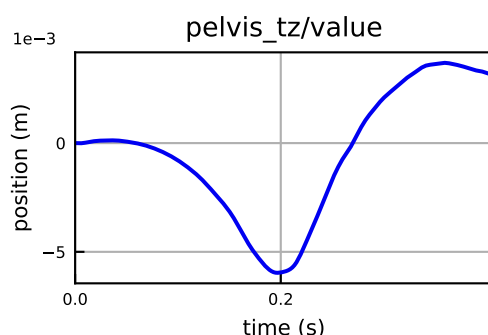
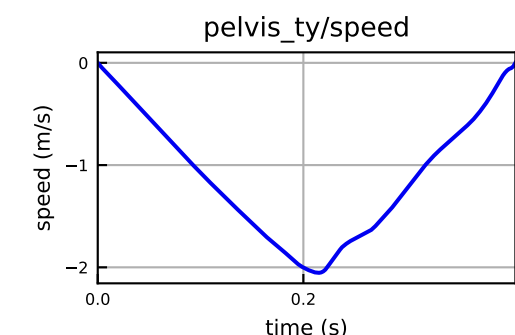
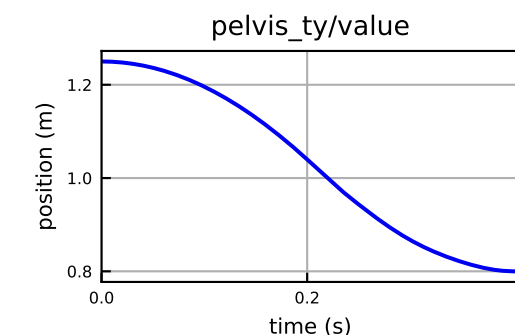
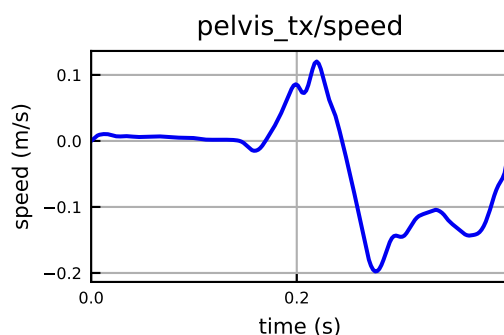
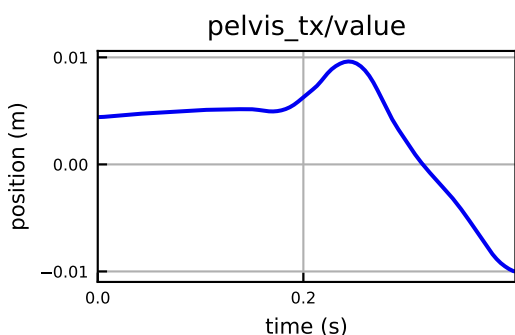
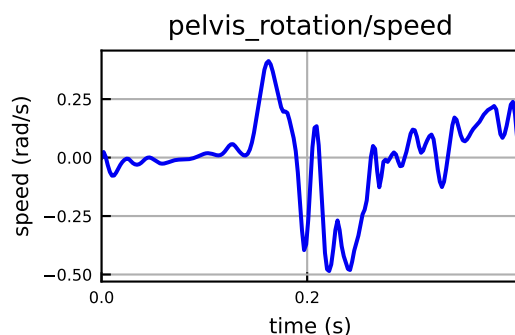
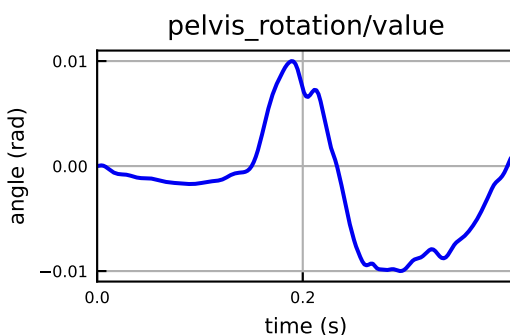
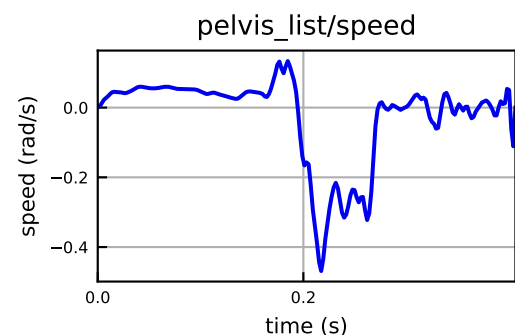
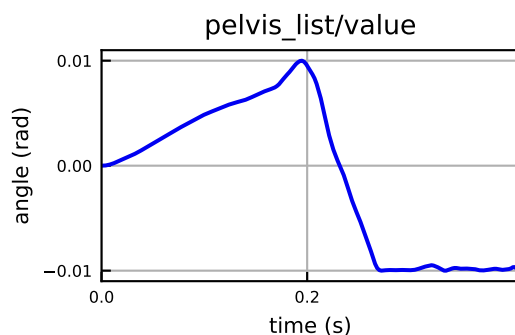
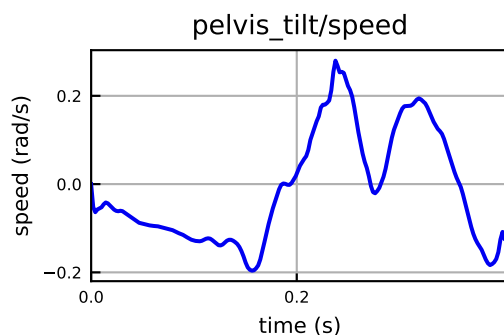
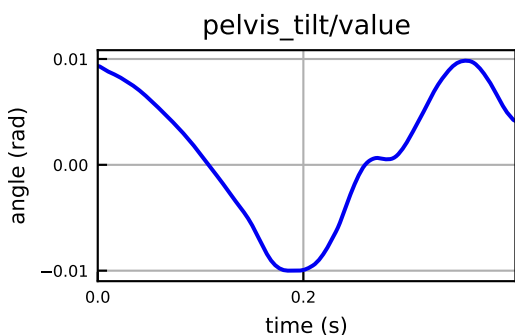
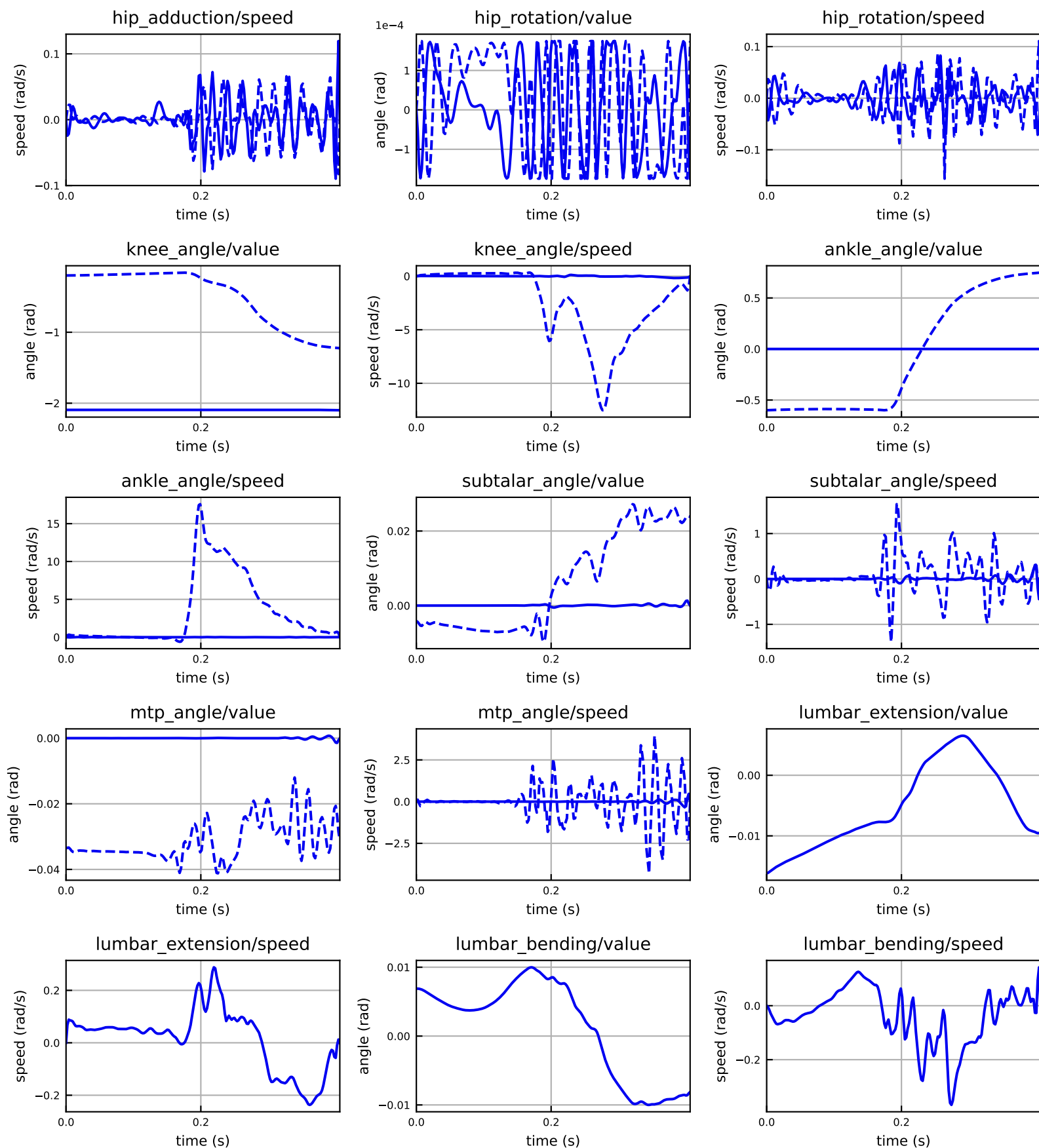


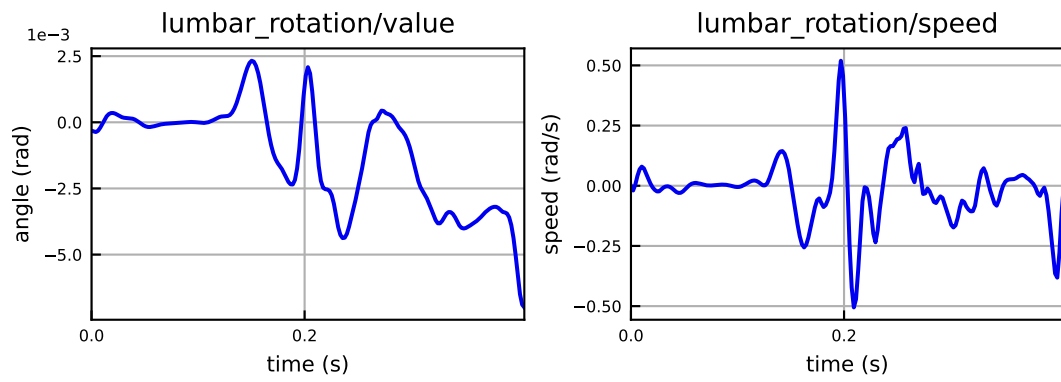
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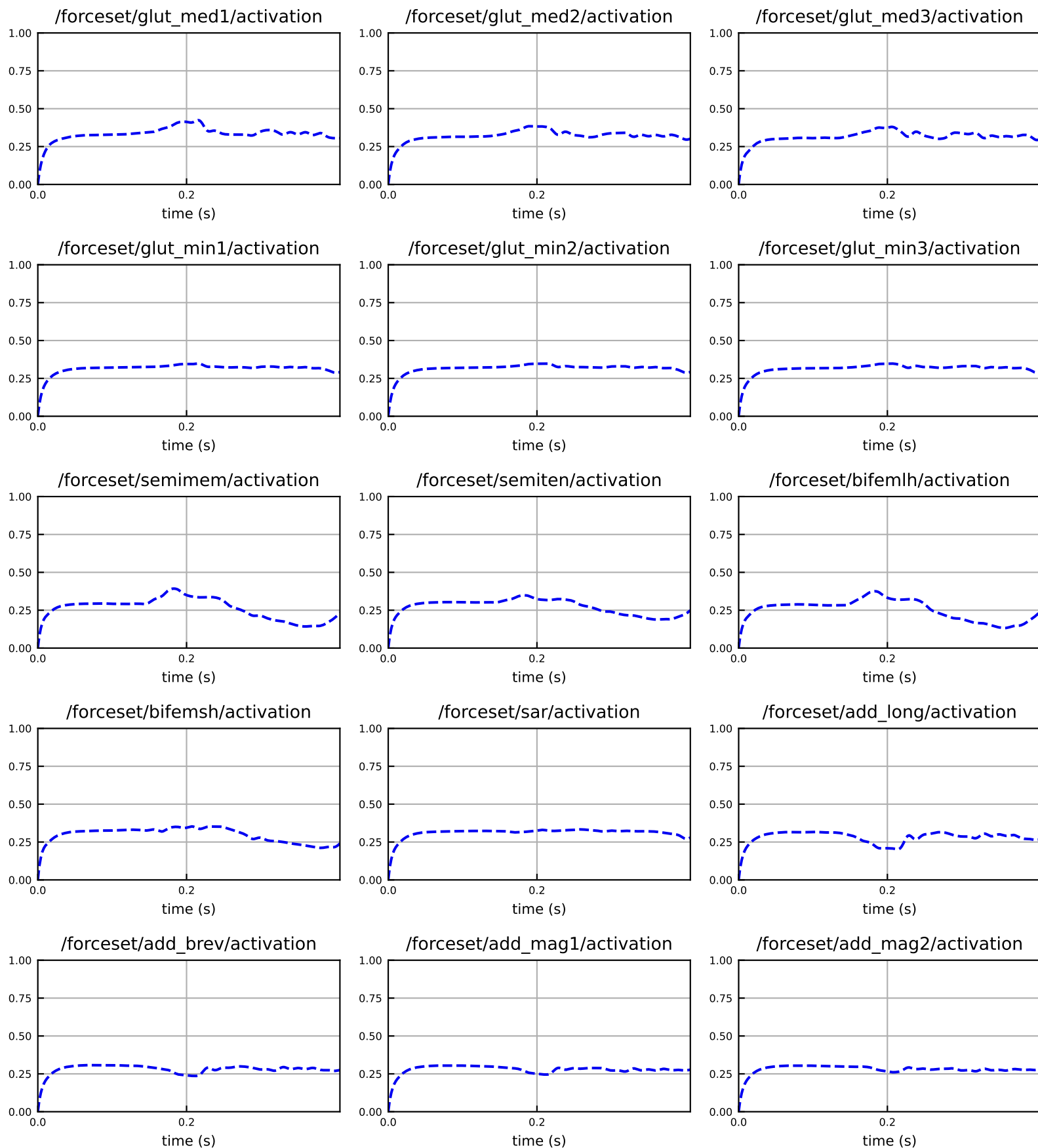
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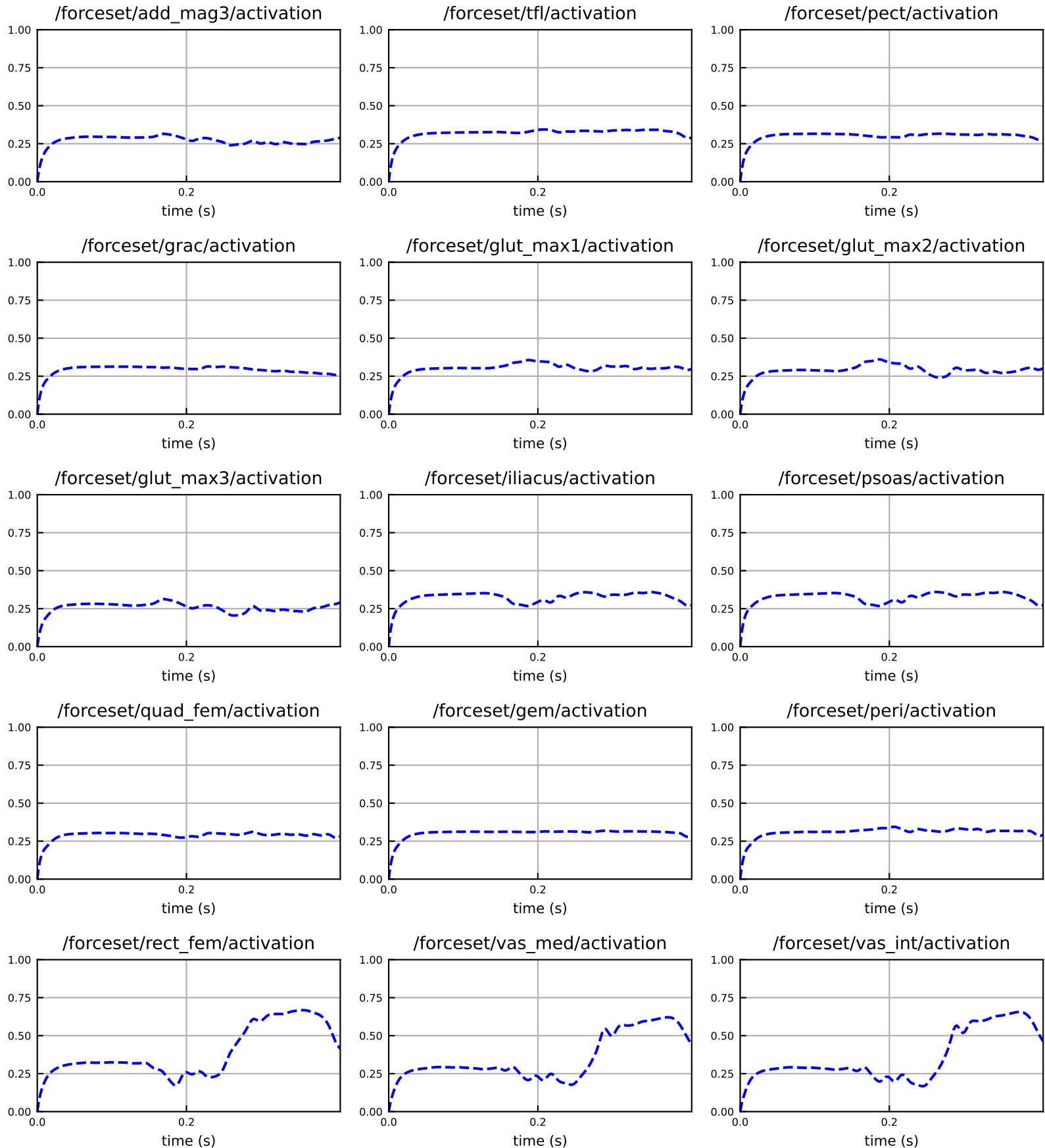
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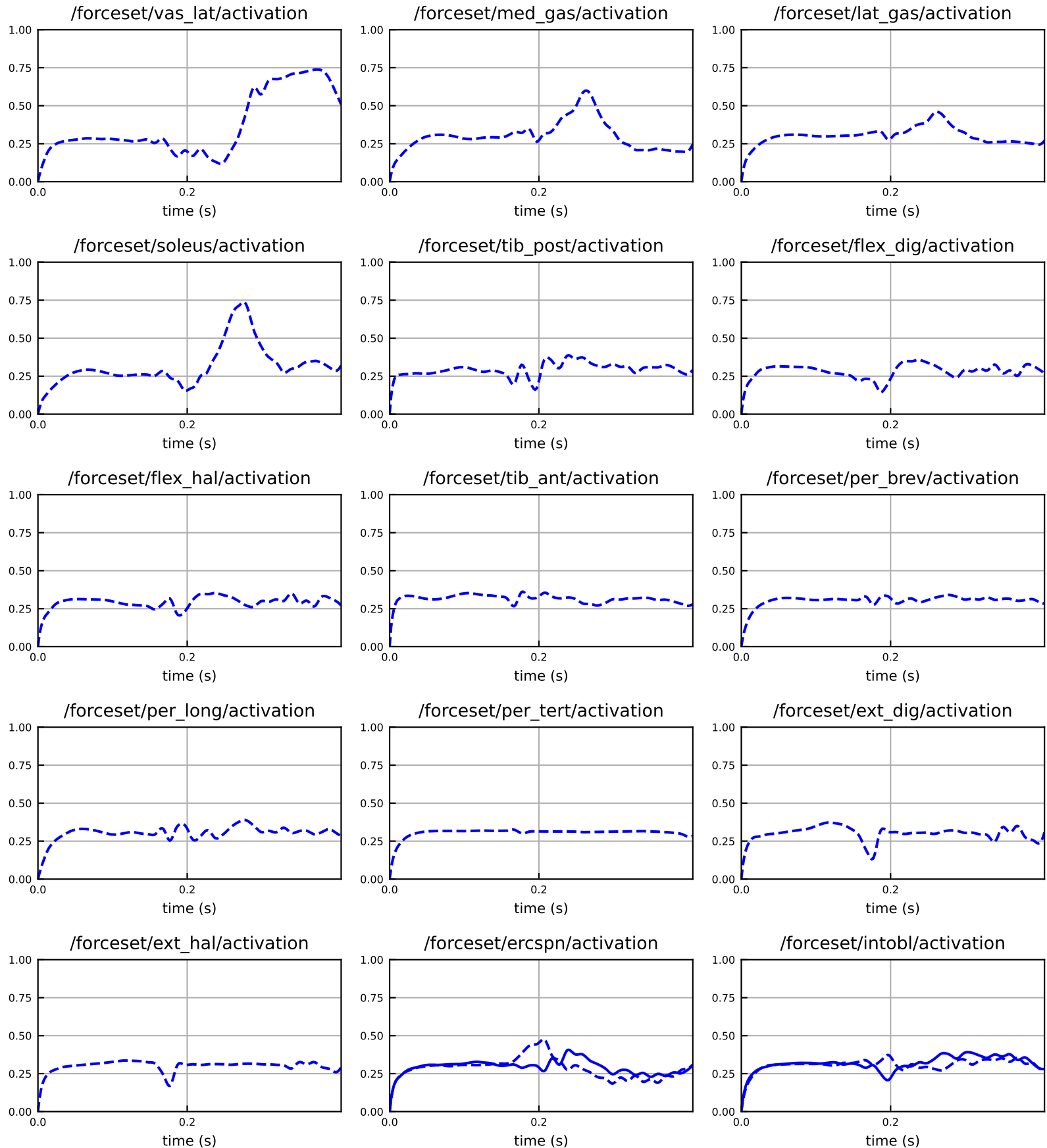
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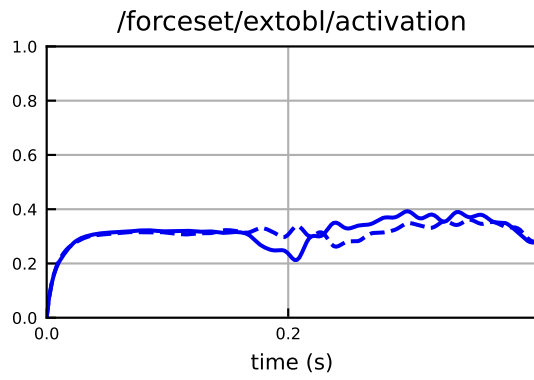
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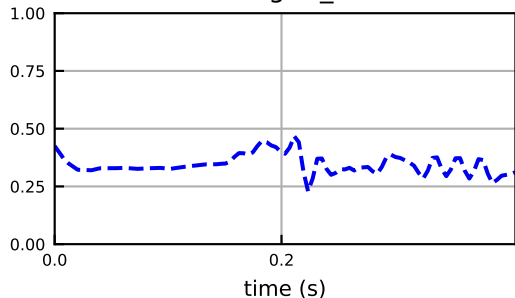


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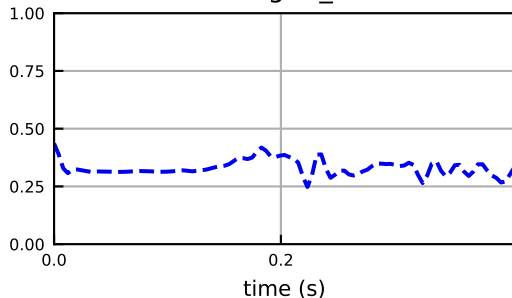


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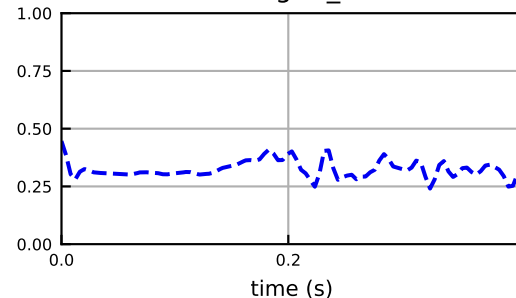
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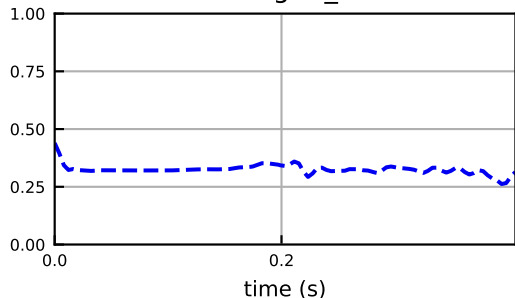
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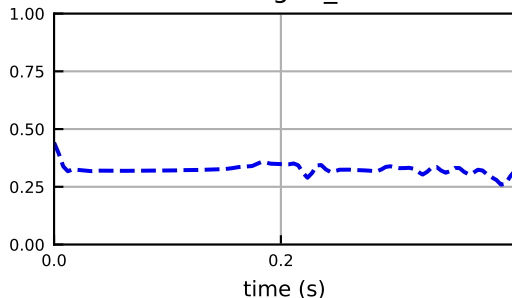
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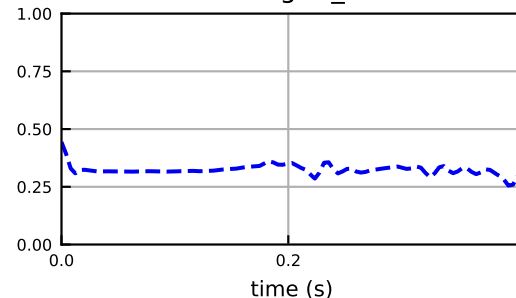
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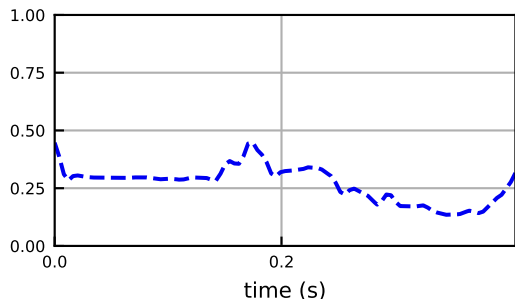
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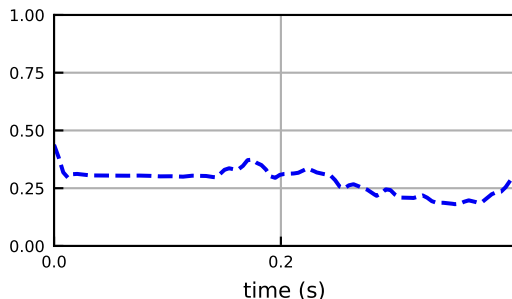
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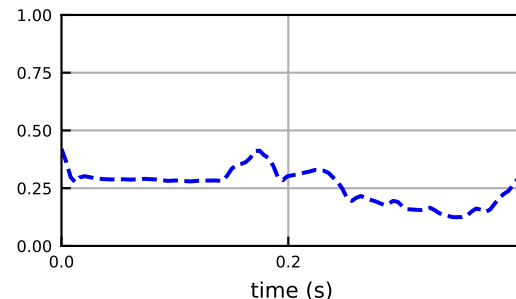
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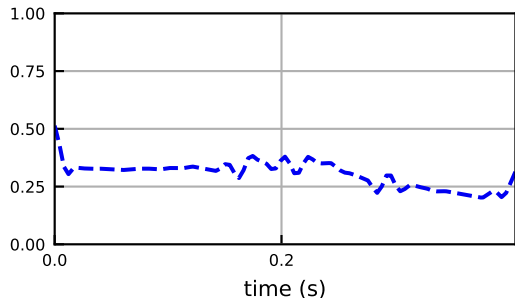
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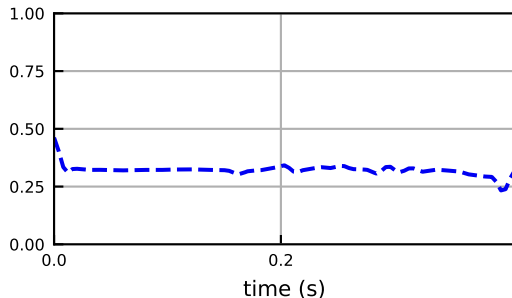
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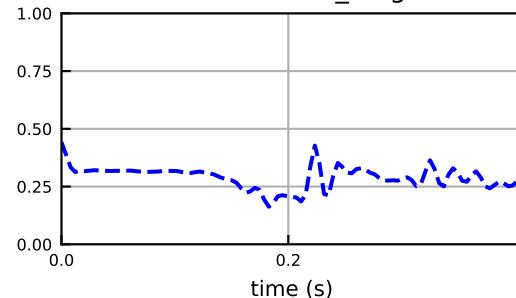
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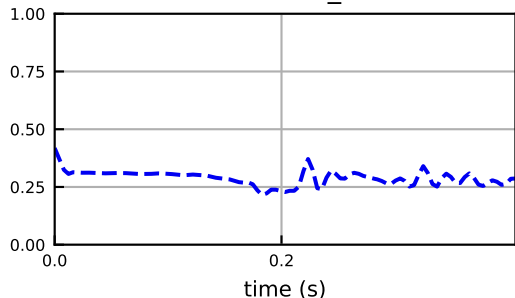
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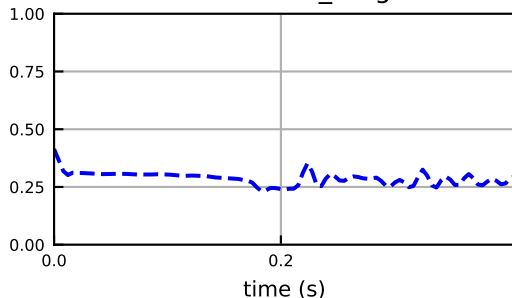
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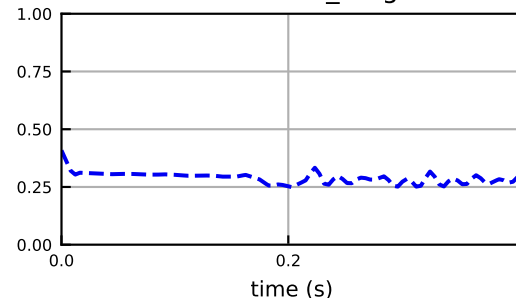
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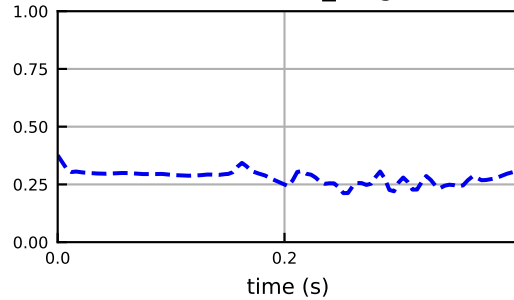


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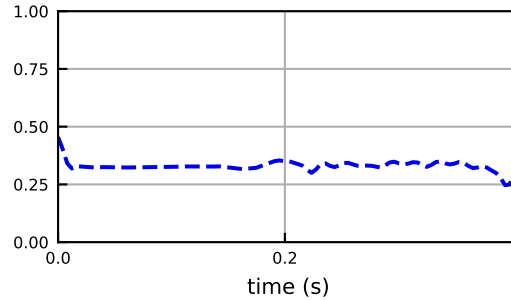


— C:\Users\Mike\Desktop\tzeni\project_trunk\Results\predict_trunk_effort0.002\ext_-1.5\solution.sto (right leg)
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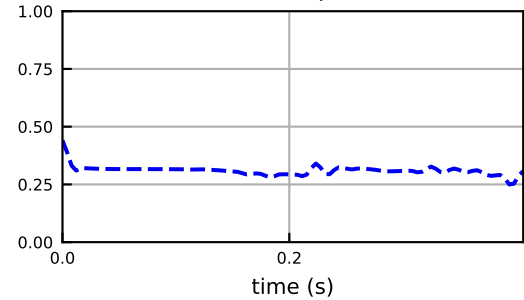
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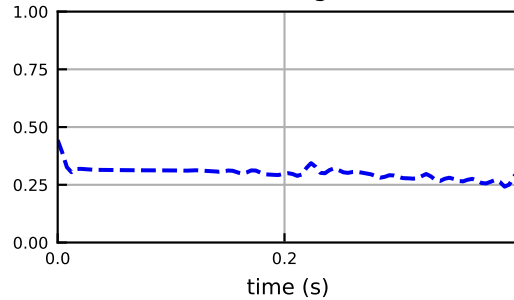
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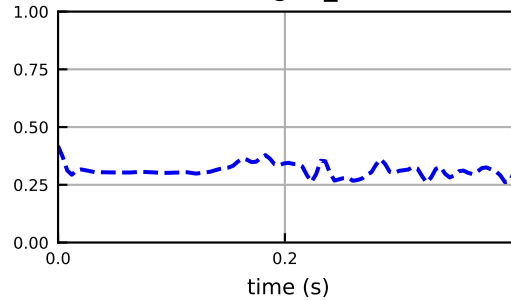
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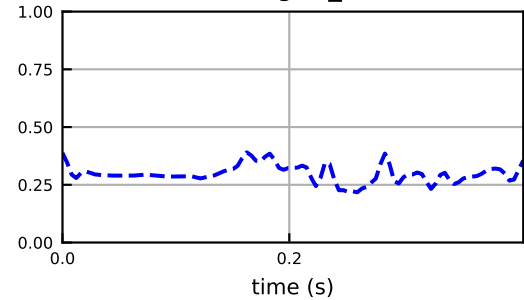
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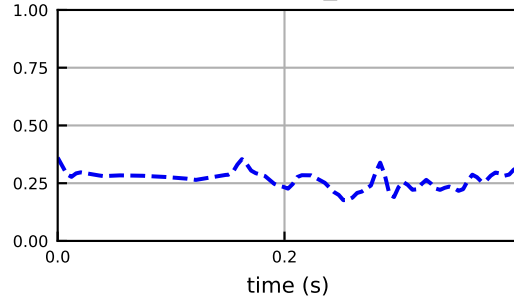
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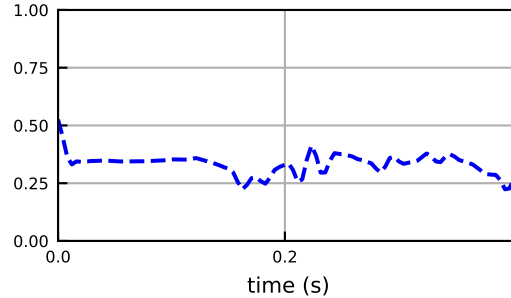
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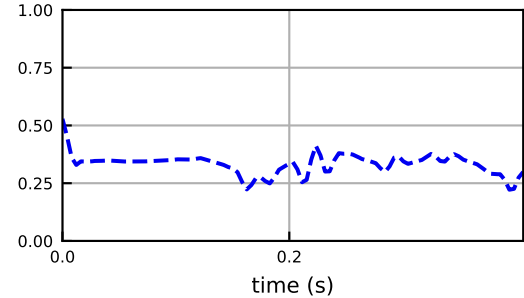
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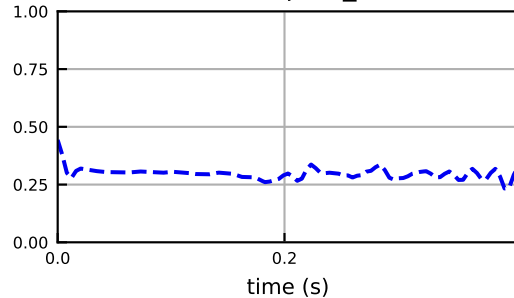
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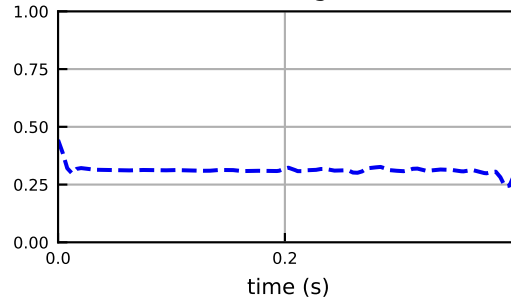
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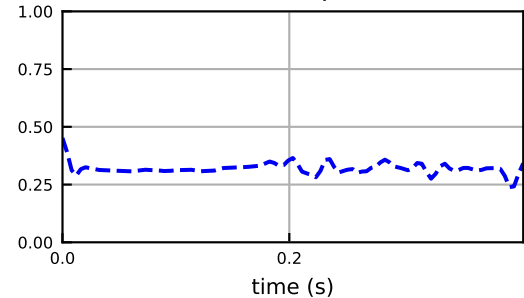
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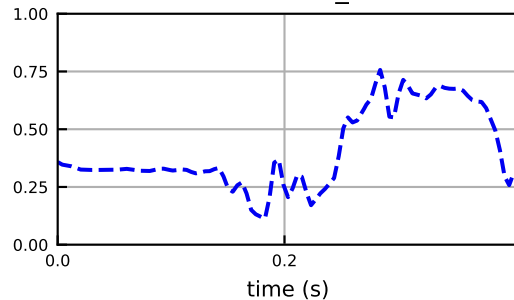
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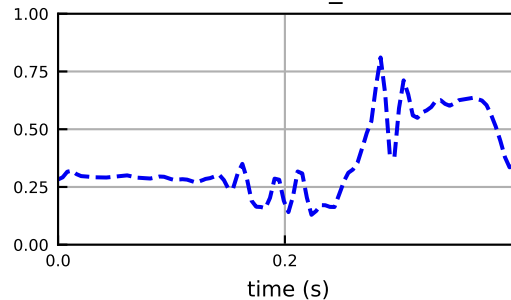
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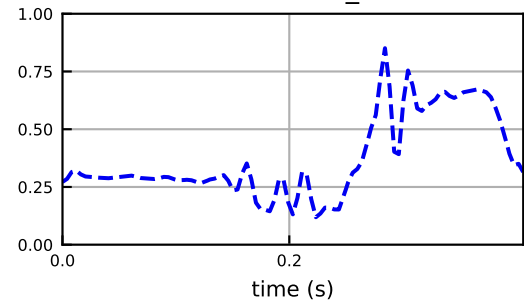
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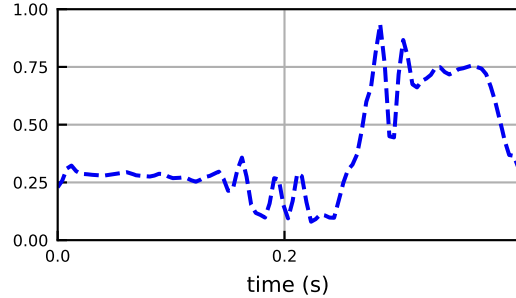


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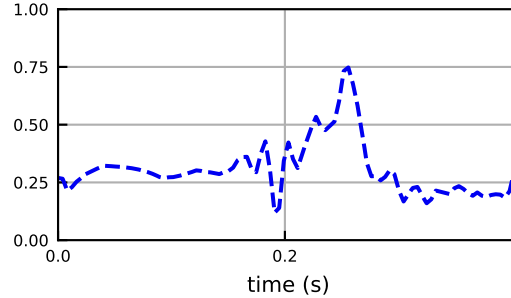


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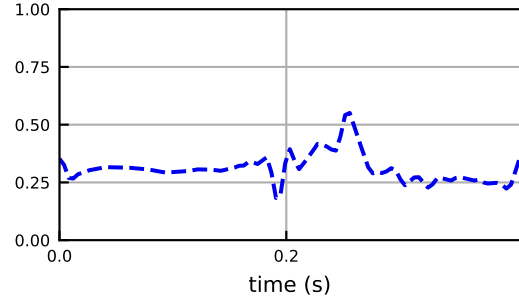
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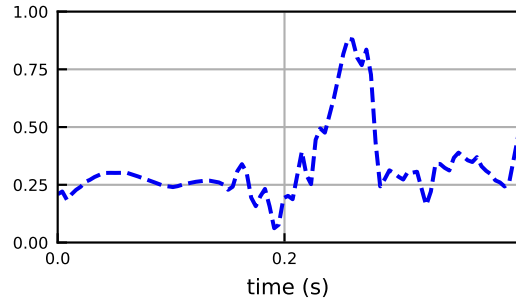
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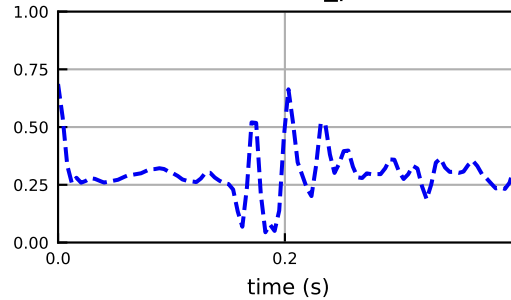
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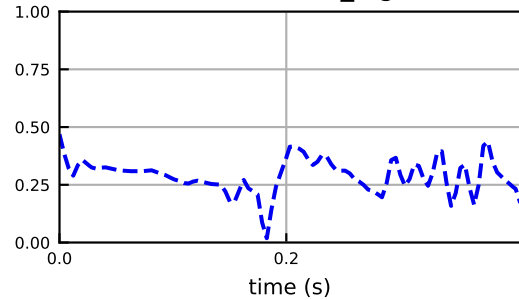
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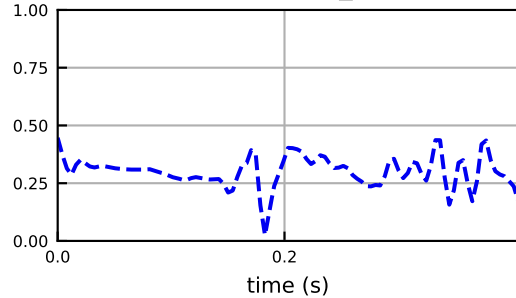
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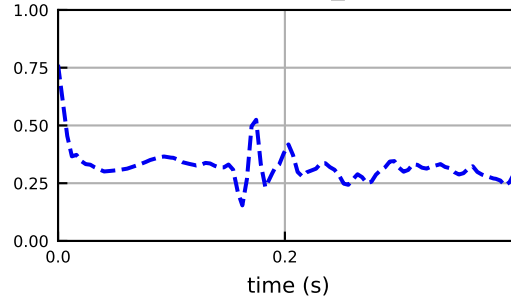
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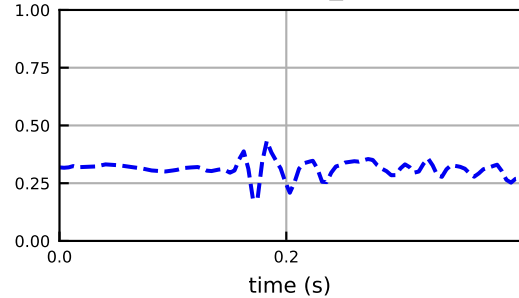
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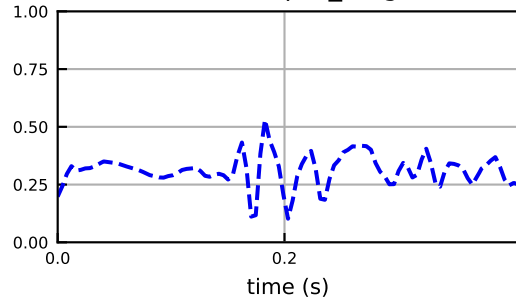
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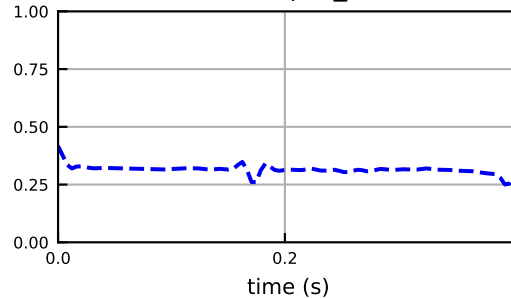
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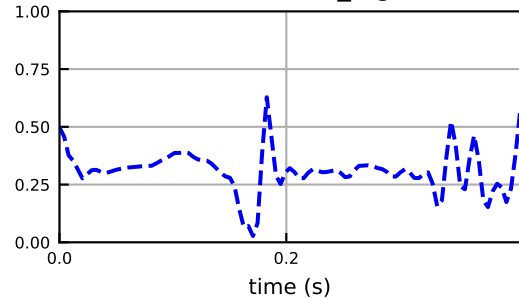
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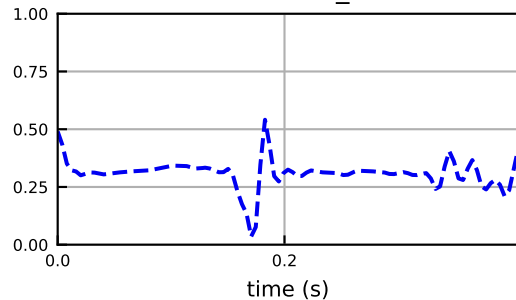
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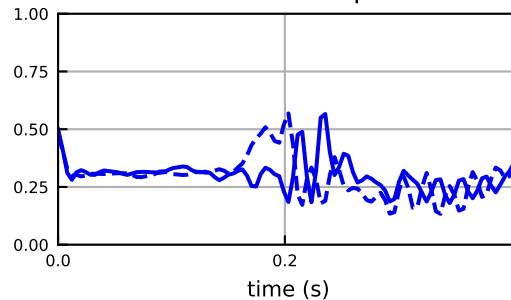
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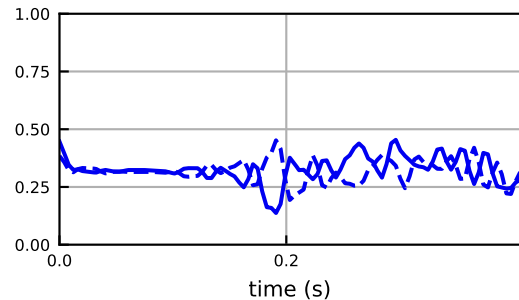
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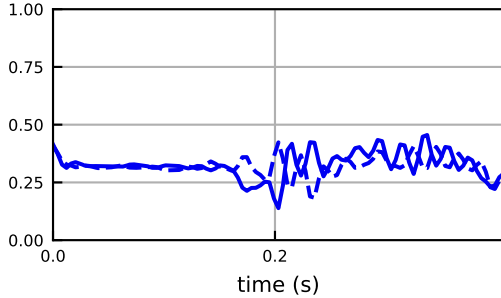


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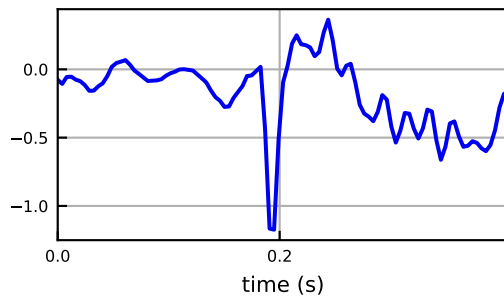


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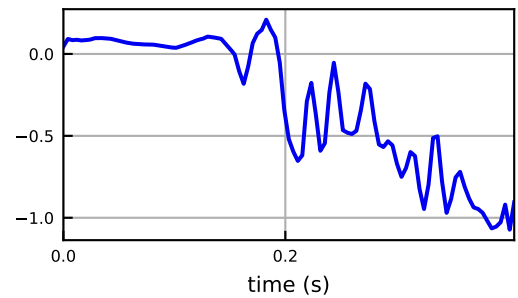
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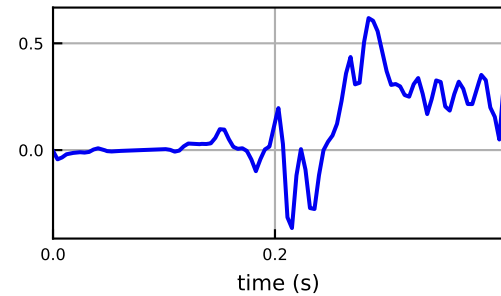
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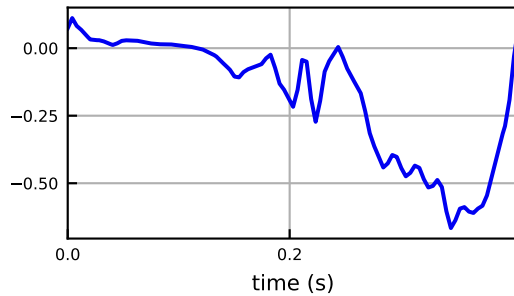
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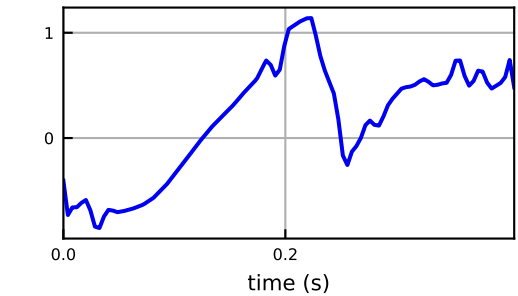
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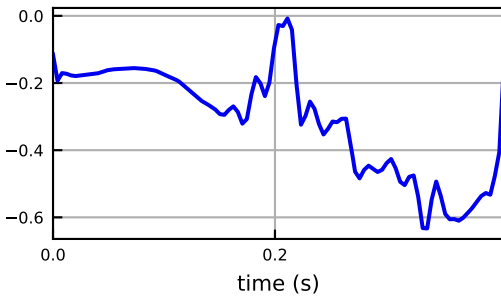
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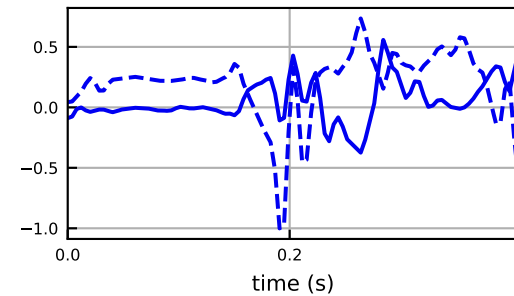
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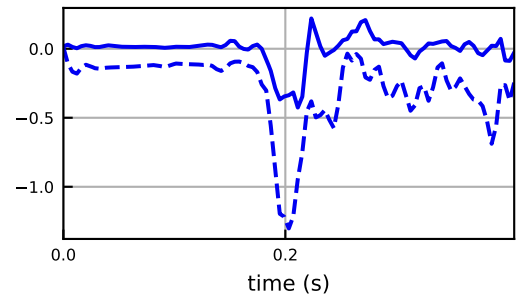
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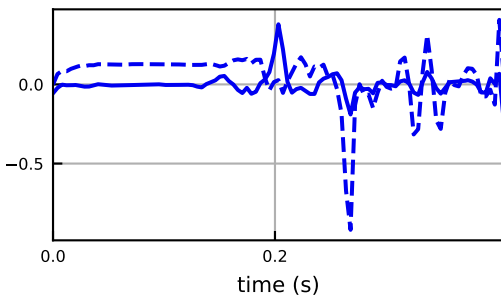
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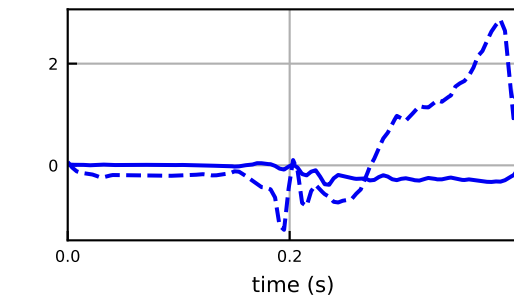
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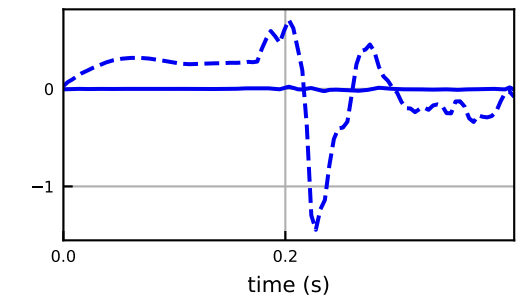
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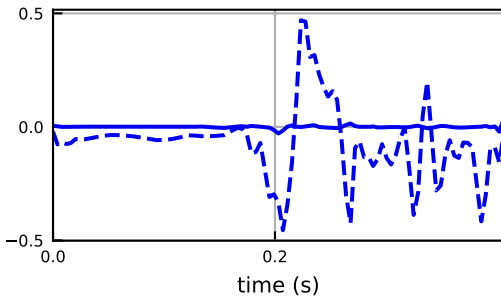
forcesetreserve_joi...knee_knee_angle



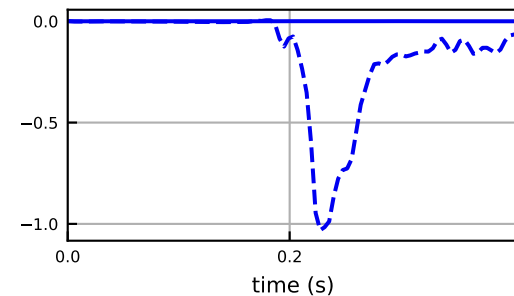
forcesetreserve_joi...nkle_ankle_angle



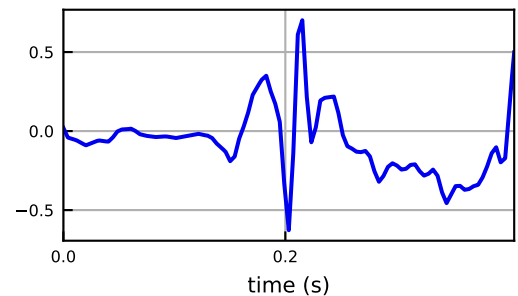
forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension



— C:\Users\Mike\Desktop\tzeni\project_trunk\Results\predict_trunk_effort0.002\ext_-1.5/solution.sto (right leg)
- - C:\Users\Mike\Desktop\tzeni\project_trunk\Results\predict_trunk_effort0.002\ext_-1.5/solution.sto (left leg)

forcesetreserve_joi...k_lumbar_bending forcesetreserve_joi...lumbar_rotation

