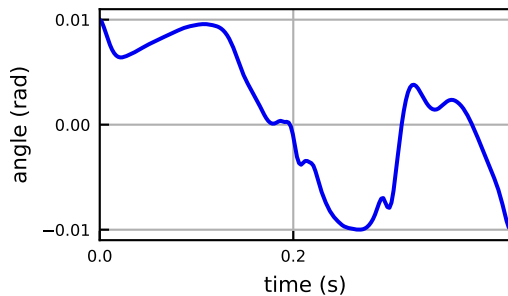
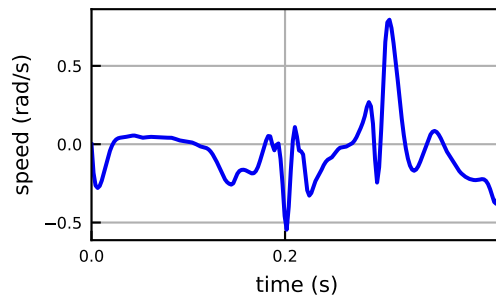


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)

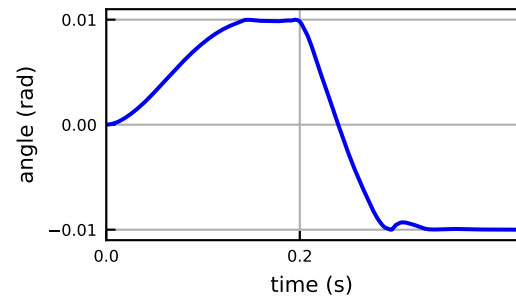
pelvis_tilt/value



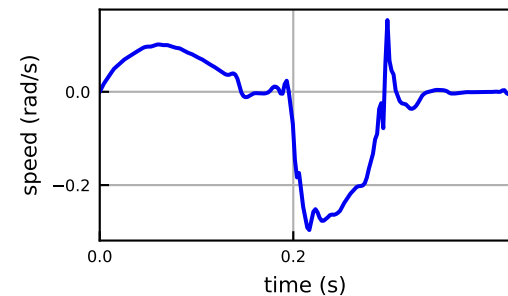
pelvis_tilt/speed



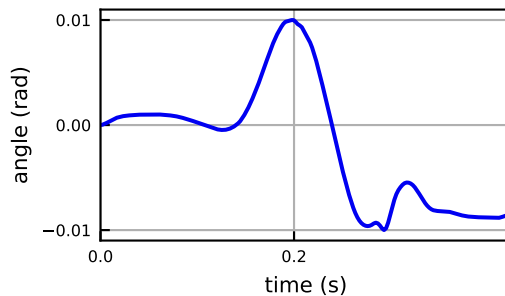
pelvis_list/value



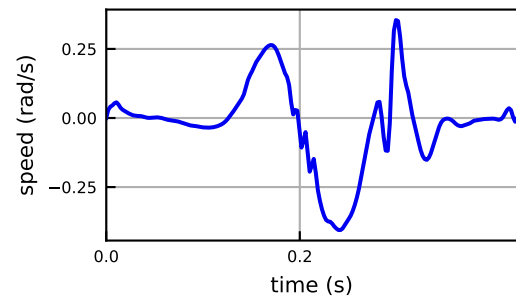
pelvis_list/speed



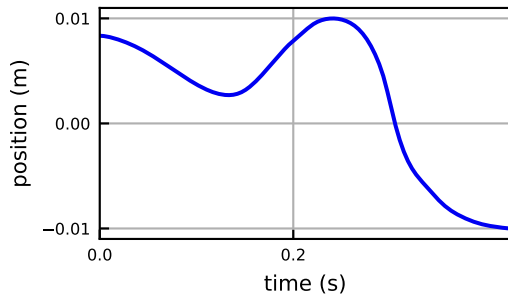
pelvis_rotation/value



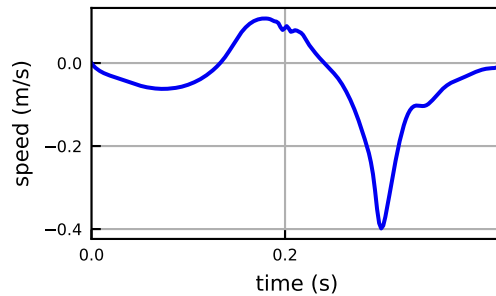
pelvis_rotation/speed



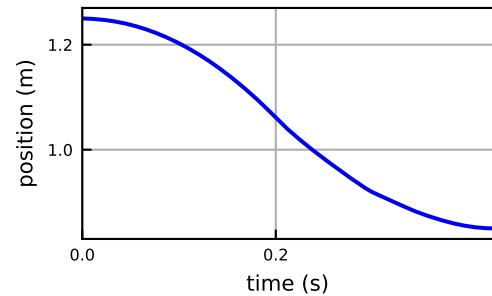
pelvis_tx/value



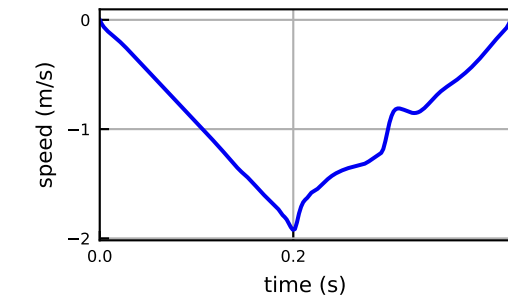
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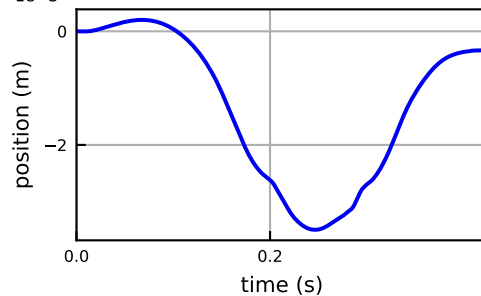
pelvis_ty/value



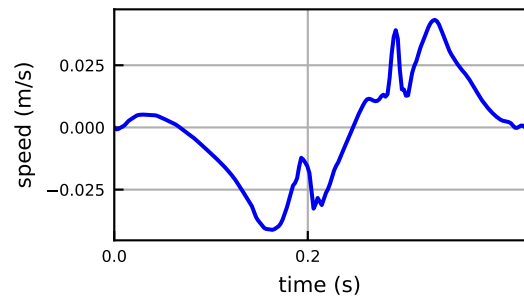
pelvis_ty/speed



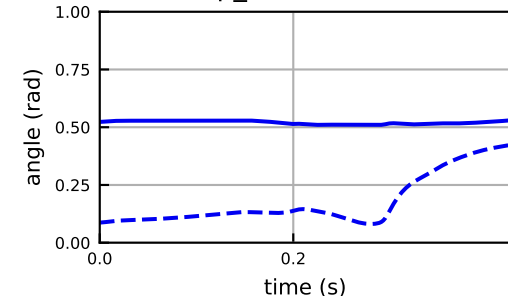
pelvis_tz/value



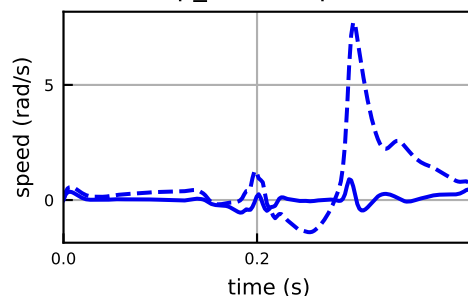
pelvis_tz/speed



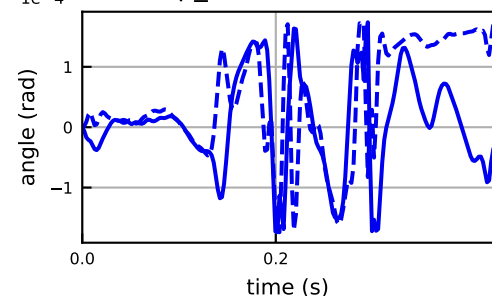
hip_flexion/value



hip_flexion/speed

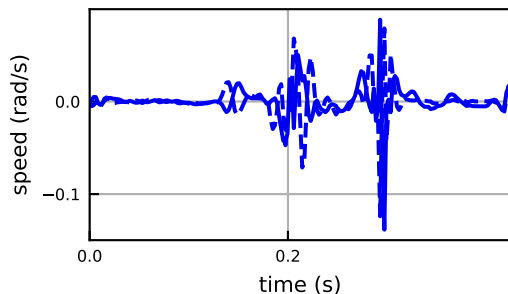


hip_adduction/value

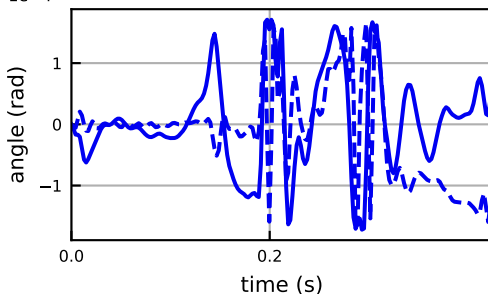


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50\solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50\solution.sto (left leg)

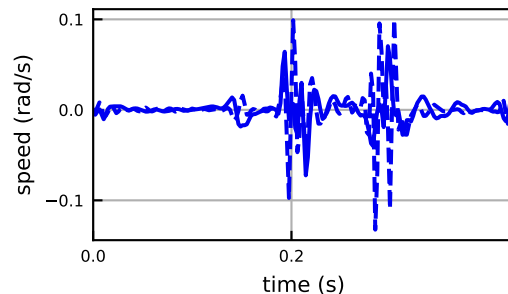
hip_adduction/speed



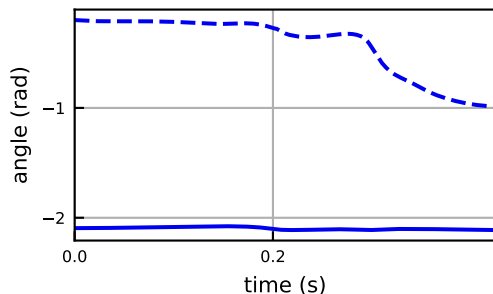
hip_rotation/value



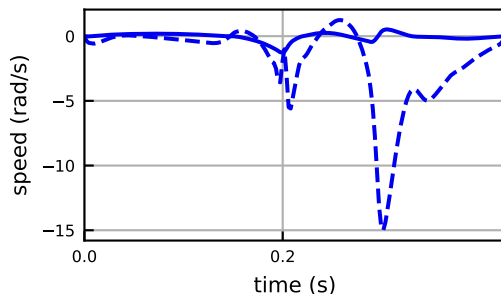
hip_rotation/speed



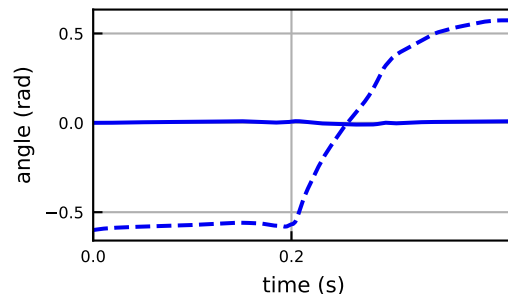
knee_angle/value



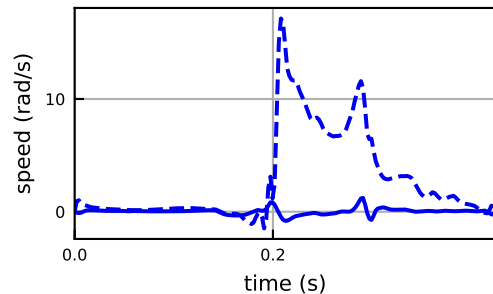
knee_angle/speed



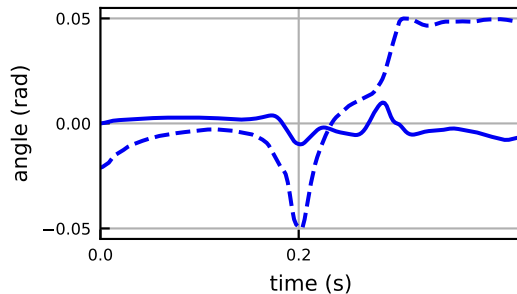
ankle_angle/value



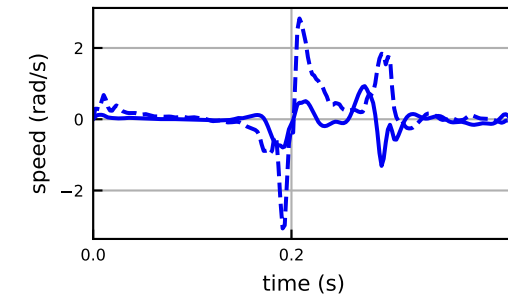
ankle_angle/speed



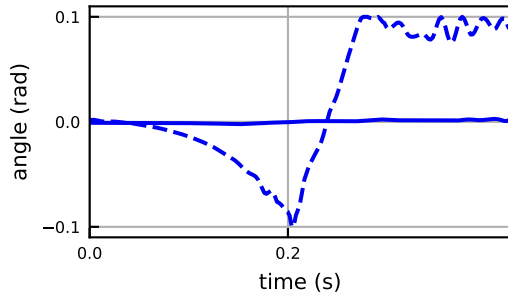
subtalar_angle/value



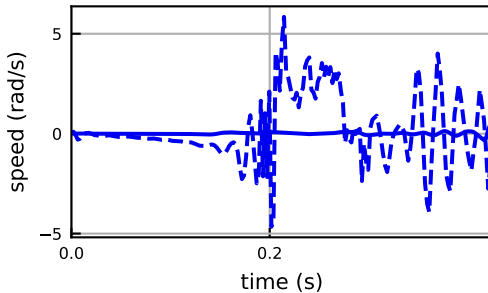
subtalar_angle/speed



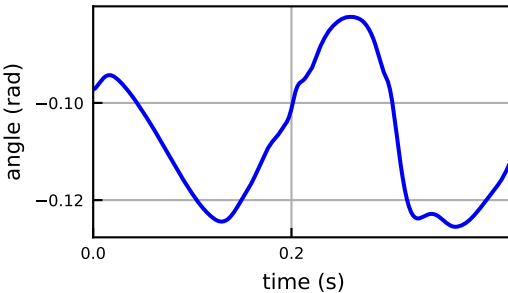
mtp_angle/value



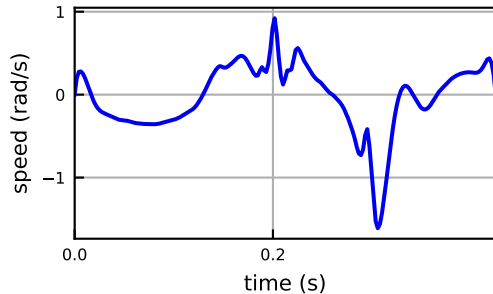
mtp_angle/speed



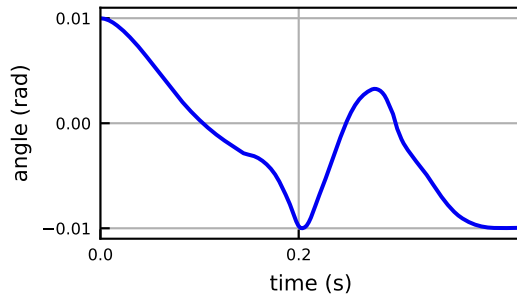
lumbar_extension/value



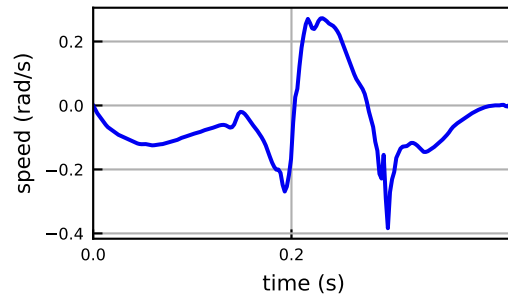
lumbar_extension/speed



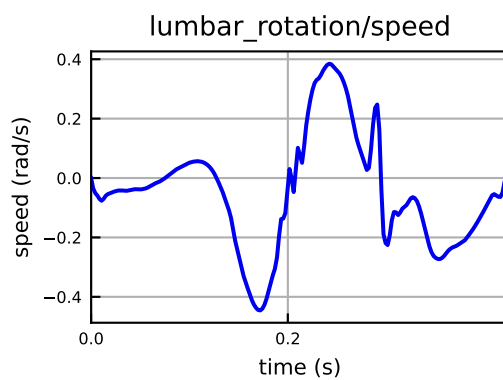
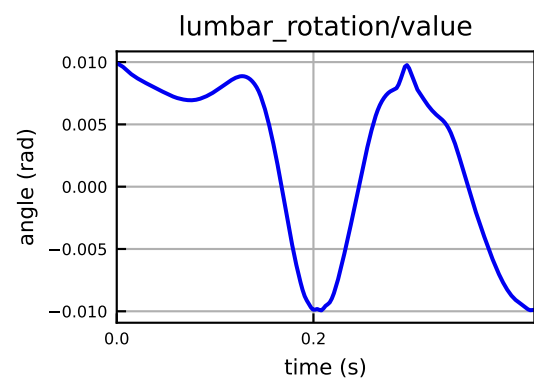
lumbar_bending/value



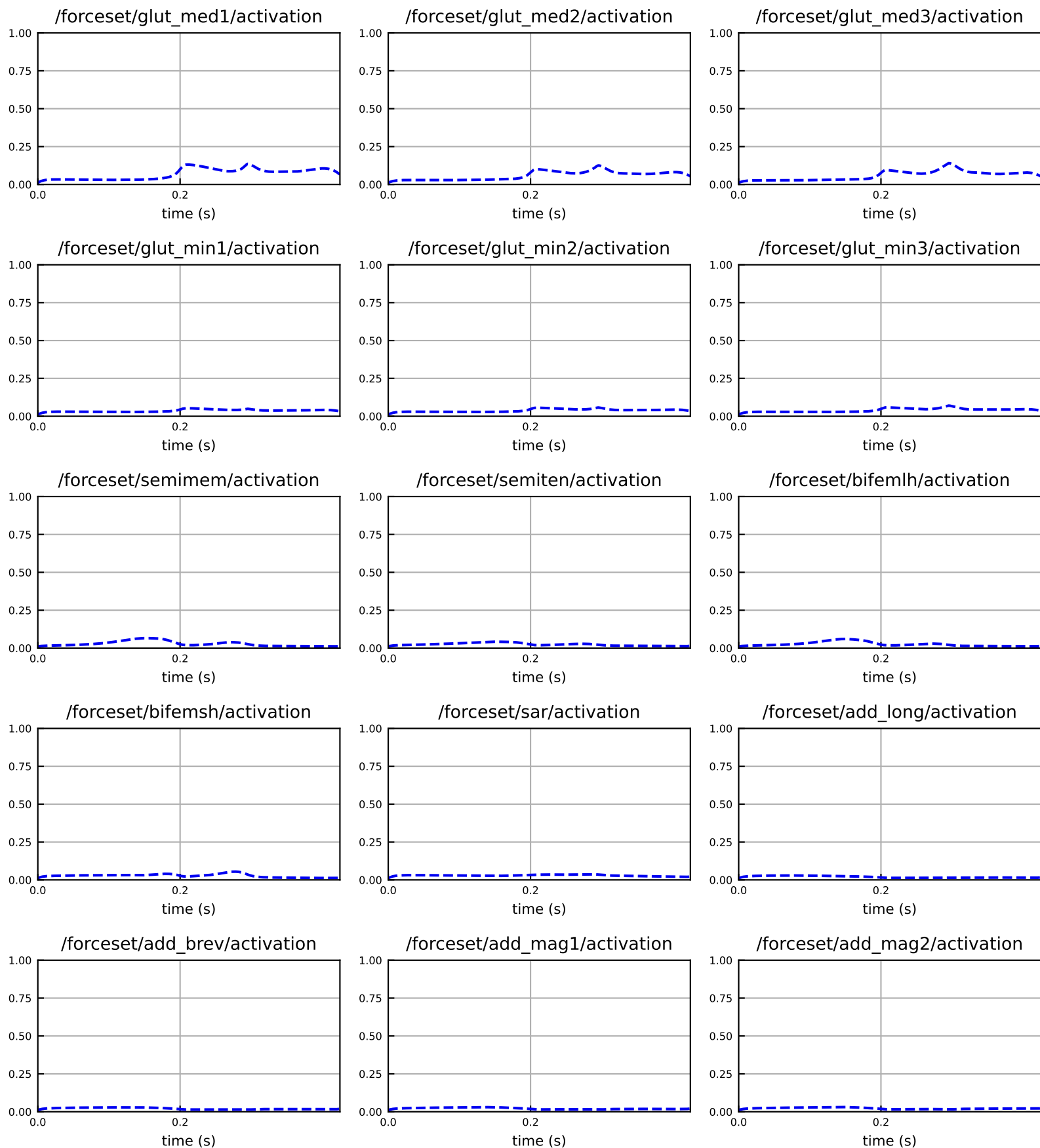
lumbar_bending/speed



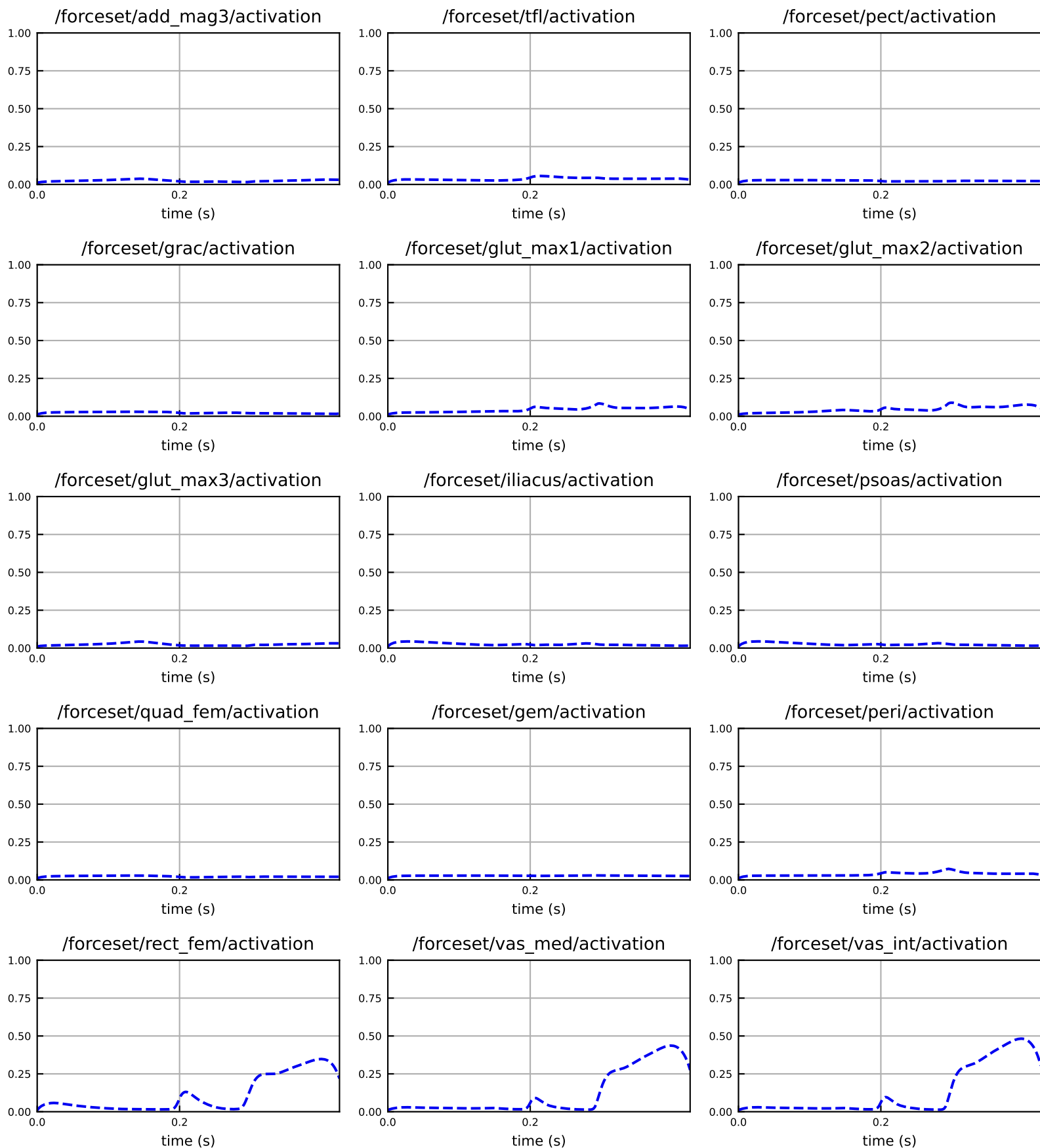
— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)



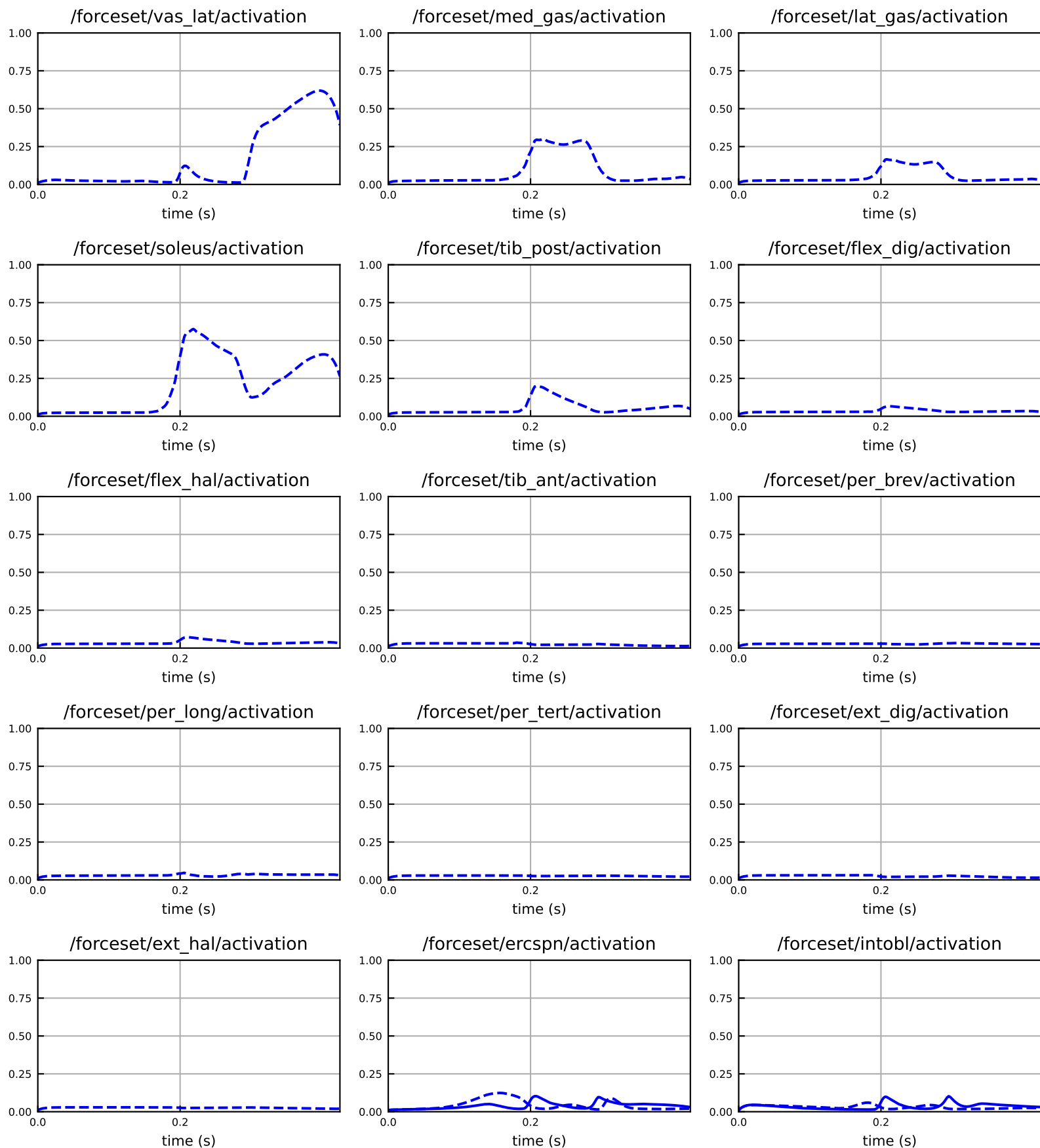
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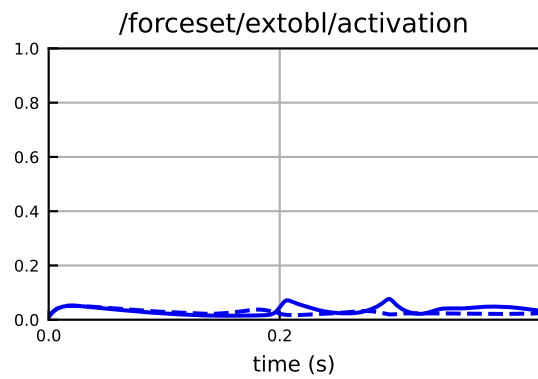
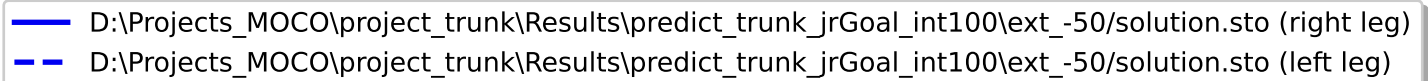


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)



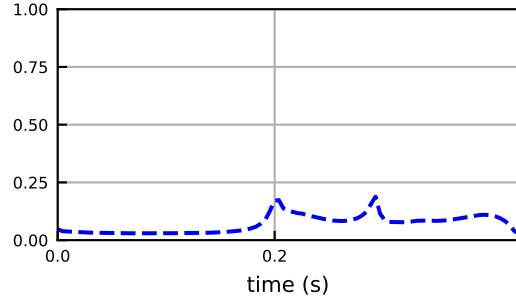
— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)



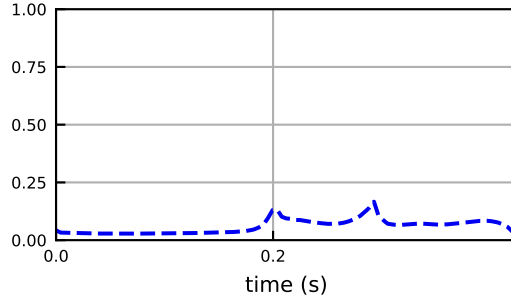


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)

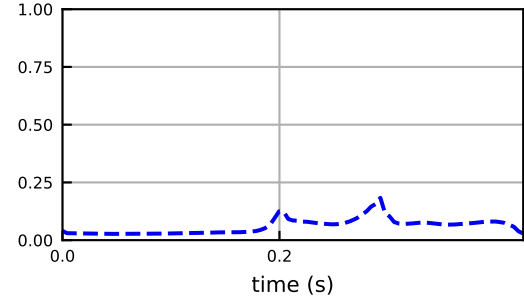
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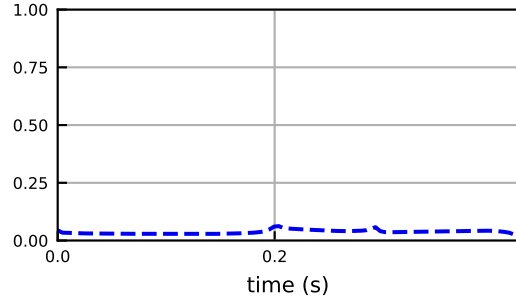
forcesetglut_med2



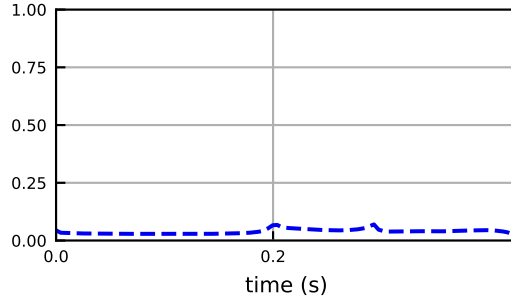
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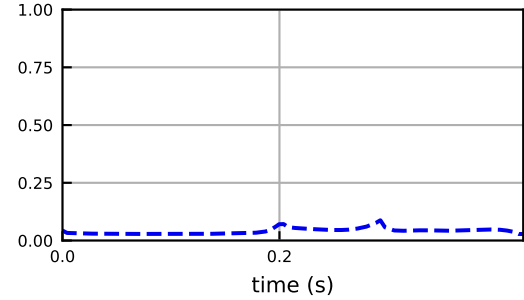
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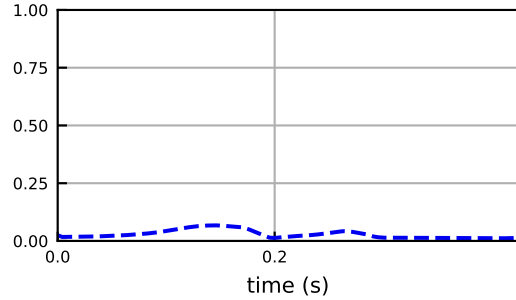
forcesetglut_min2



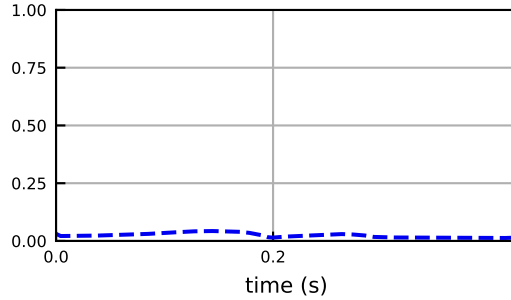
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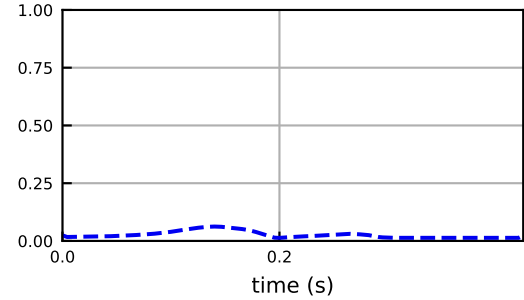
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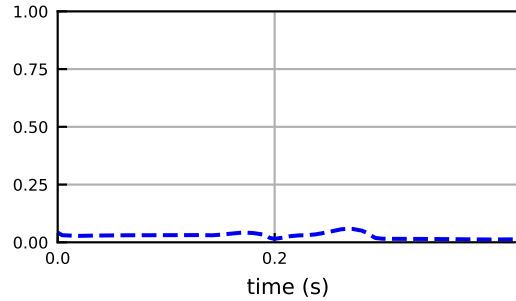
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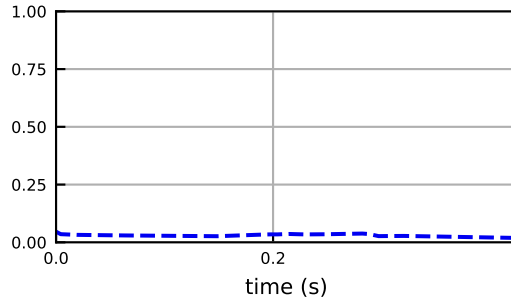
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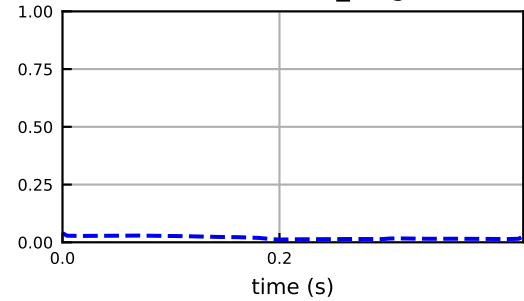
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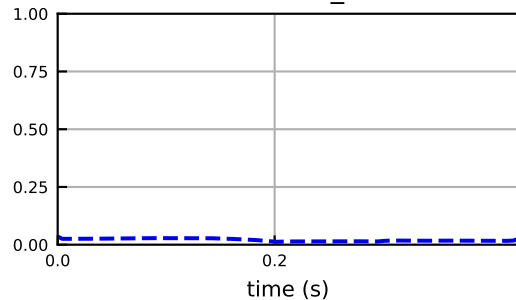
forcesetsar



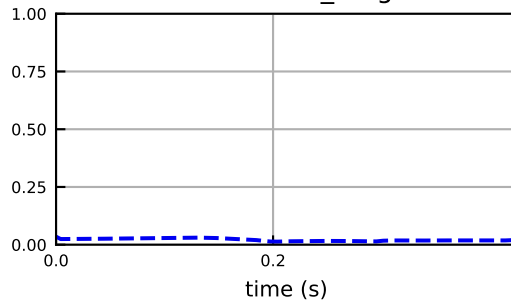
forcesetadd_long



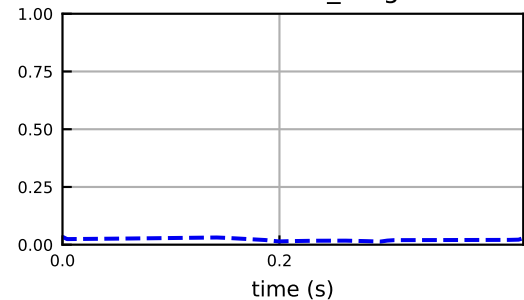
forcesetadd_brev



forcesetadd_mag1

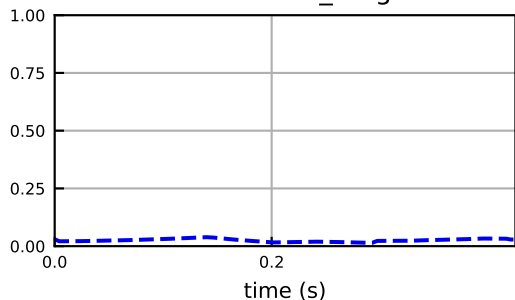


forcesetadd_mag2

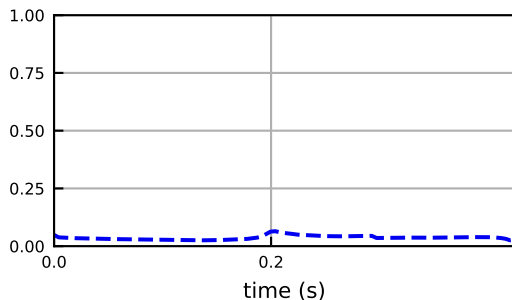


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)

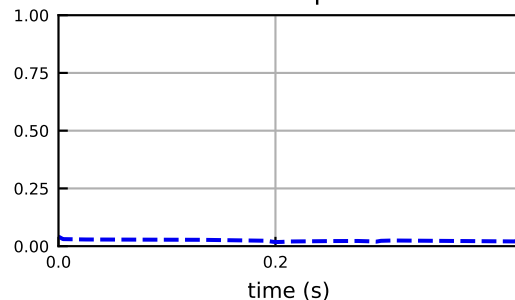
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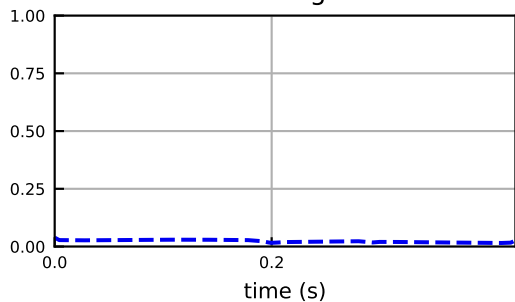
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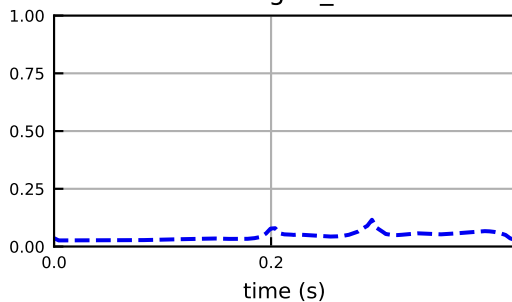
forcesetpect



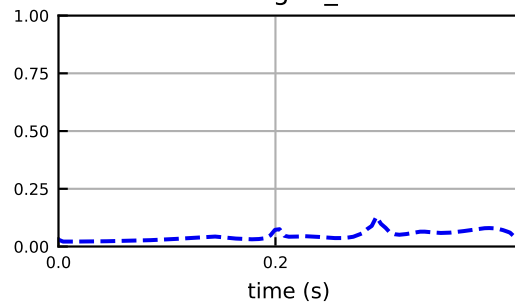
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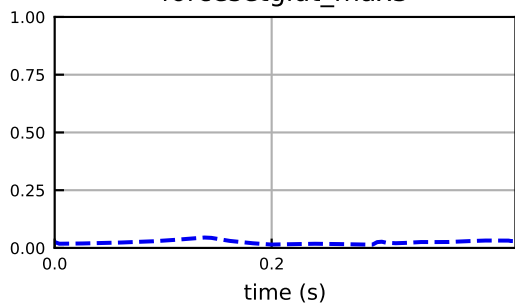
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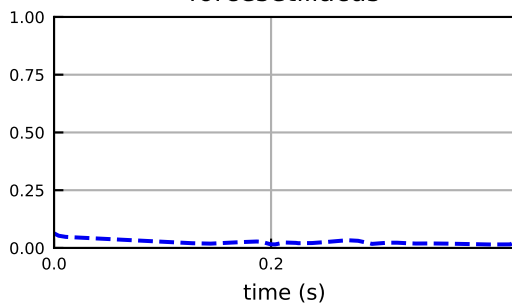
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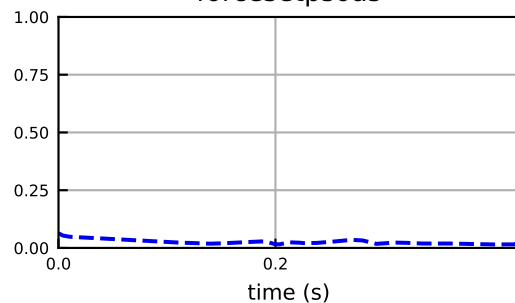
forcesetglut_max3



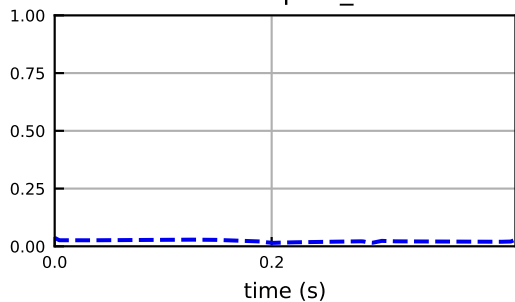
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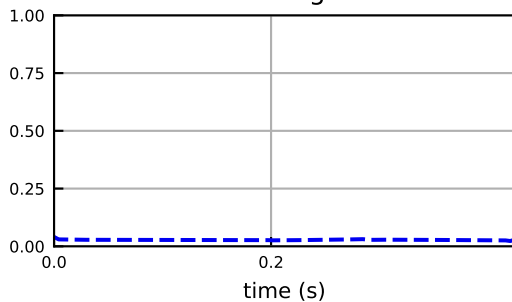
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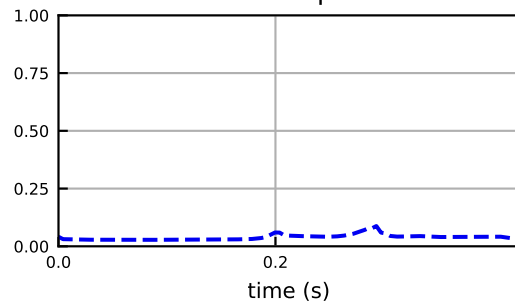
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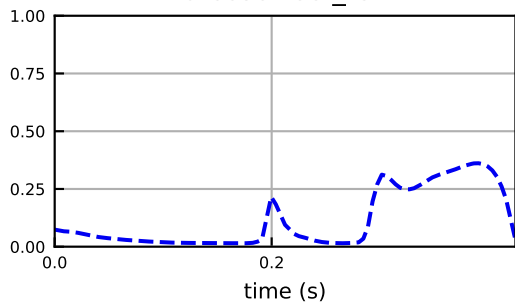
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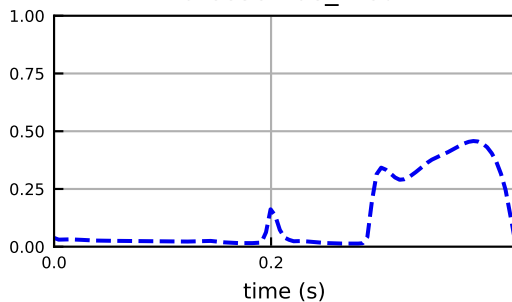
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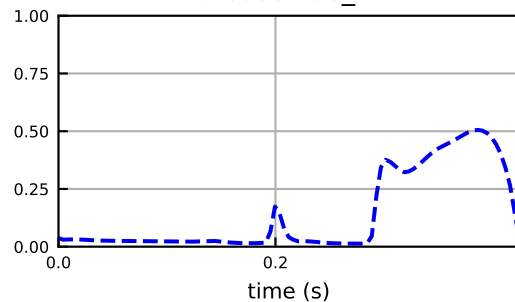
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forcesetvas_med

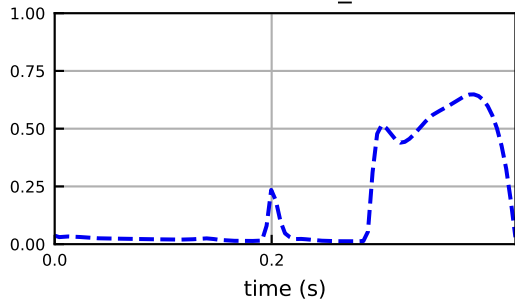


forcesetvas_int

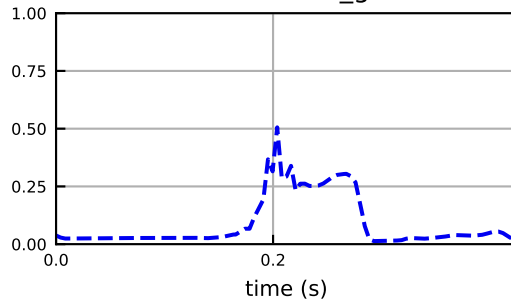


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)

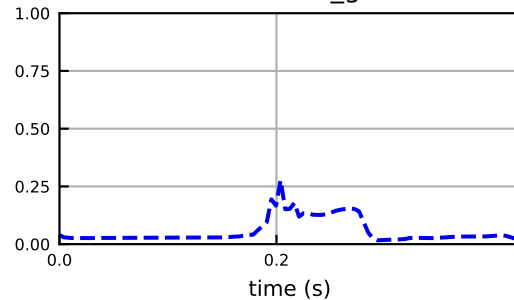
forcesetvas_lat



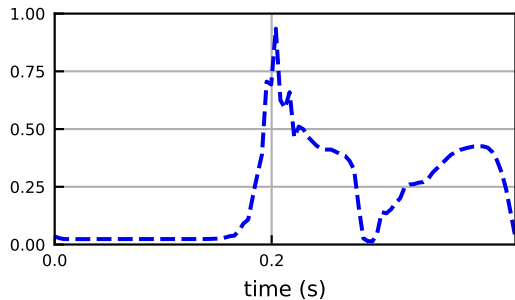
forcesetmed_gas



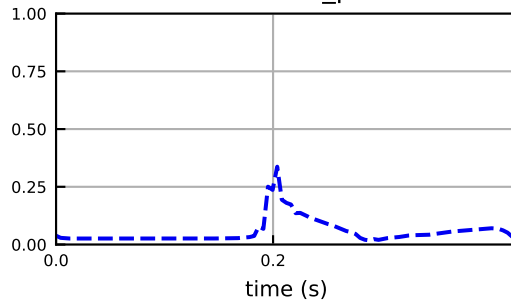
forcesetlat_gas



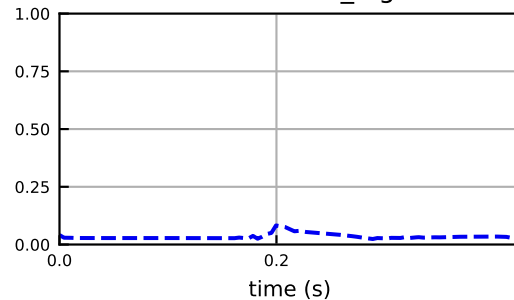
forcesetsoleus



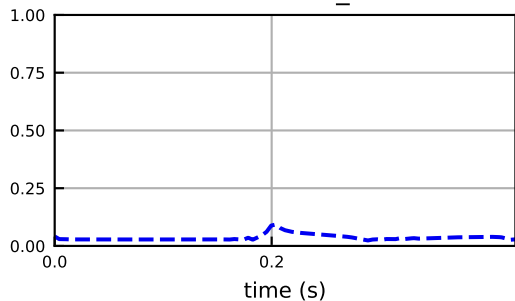
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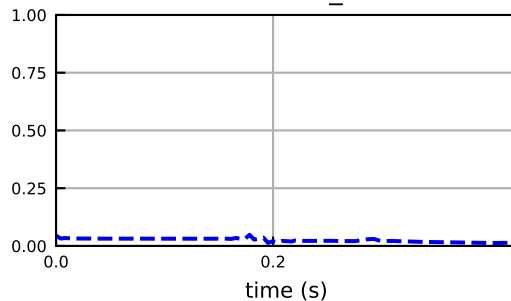
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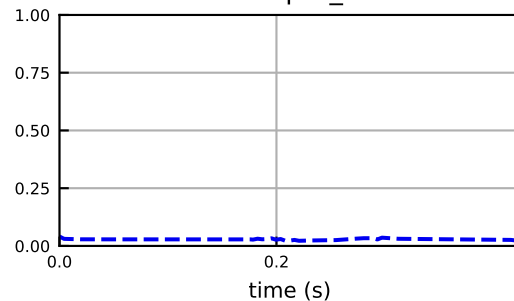
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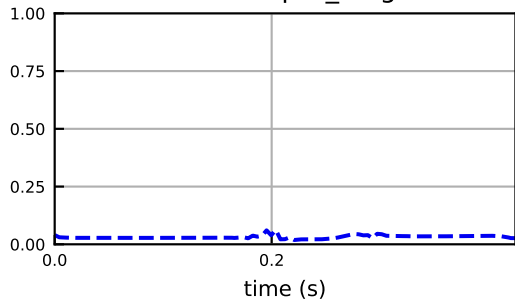
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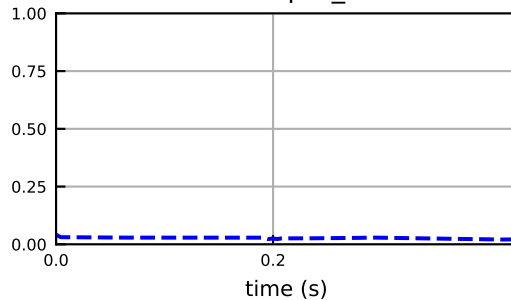
forcesetper_brev



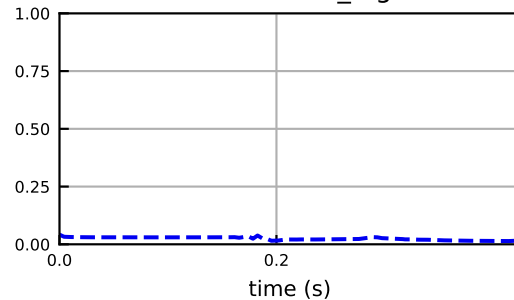
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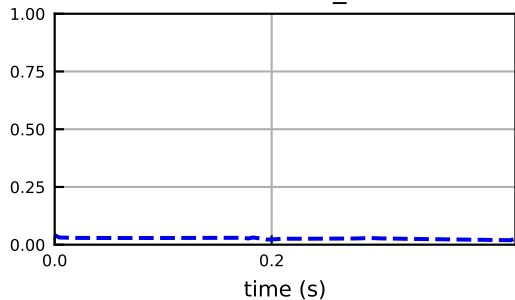
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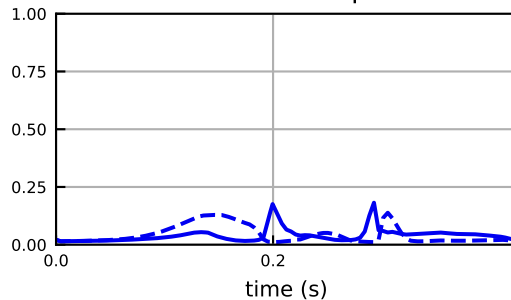
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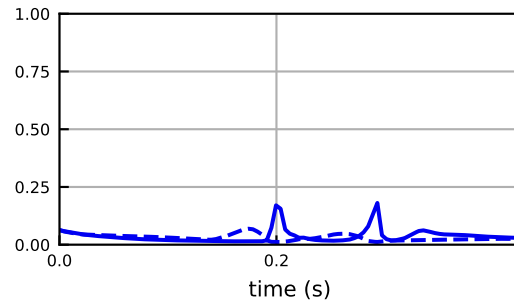
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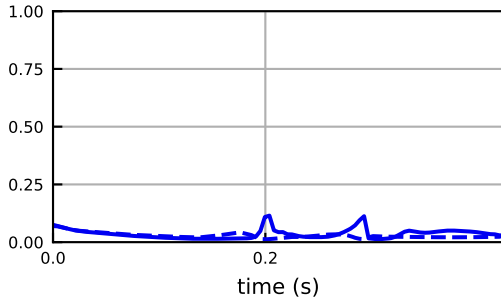


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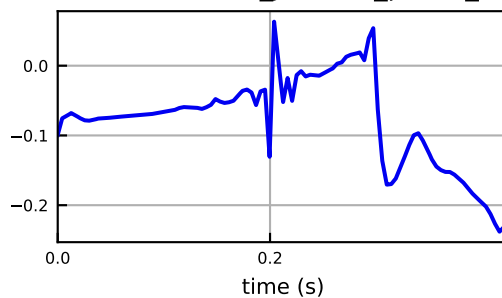


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)

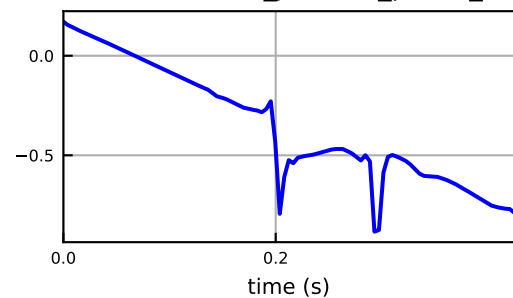
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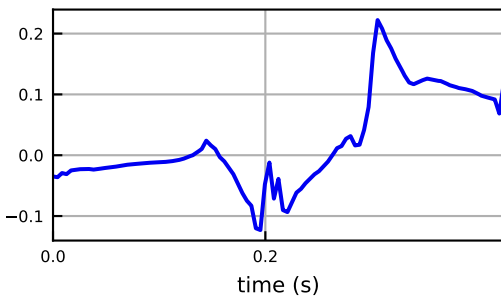
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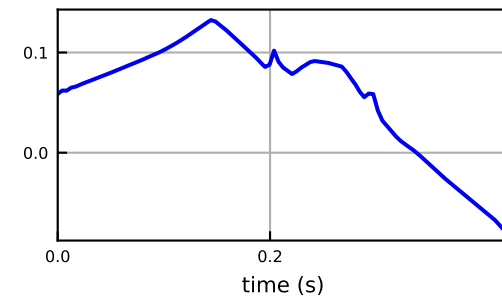
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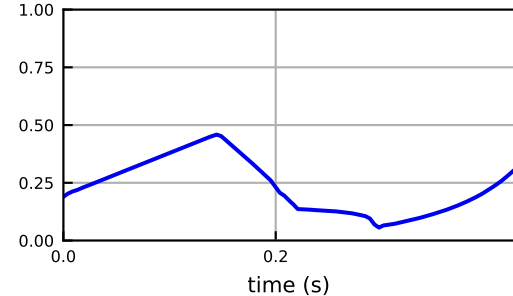
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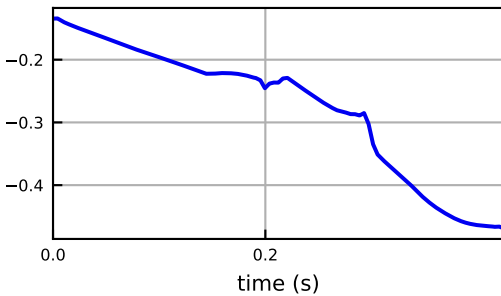
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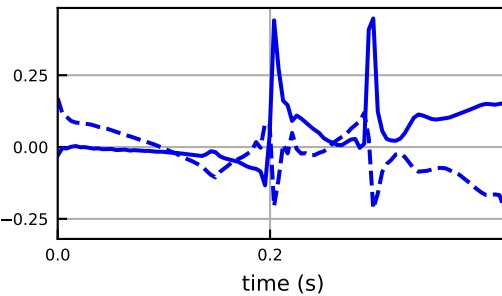
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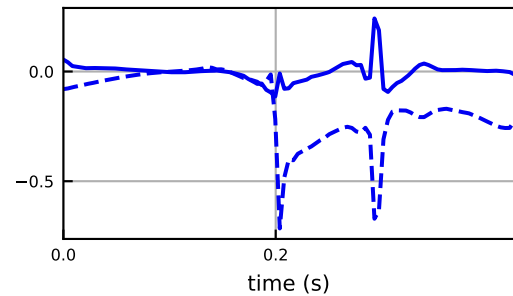
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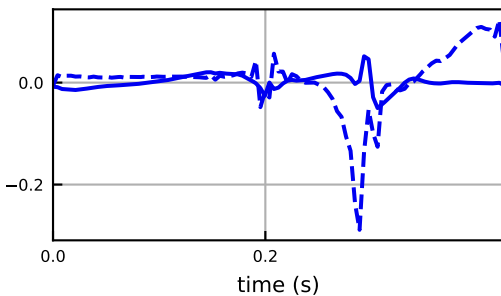
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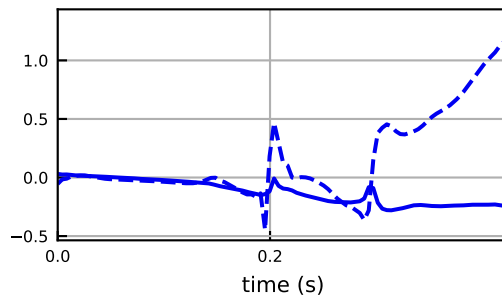
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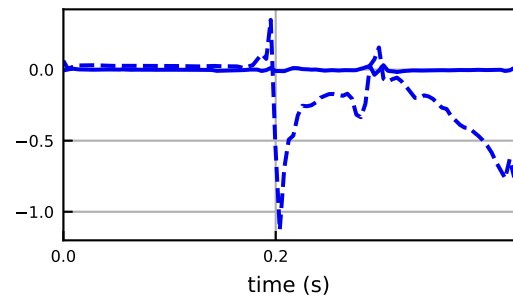
forcesetreserve_joi...hip_hip_rotation



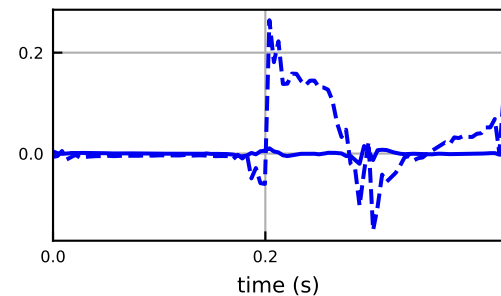
forcesetreserve_joi...knee_knee_angle



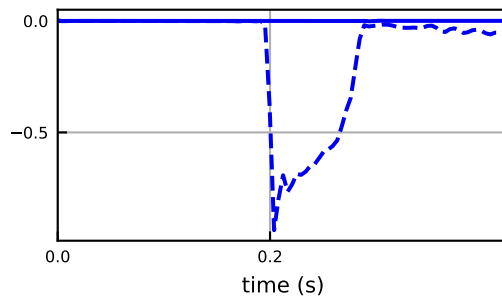
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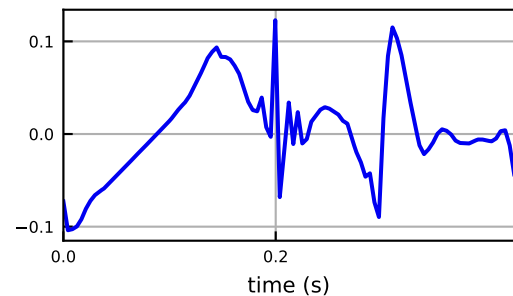
forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension



— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-50/solution.sto (left leg)

forcesetreserve_joi...k_lumbar_bending forcesetreserve_joi..._lumbar_rotation

