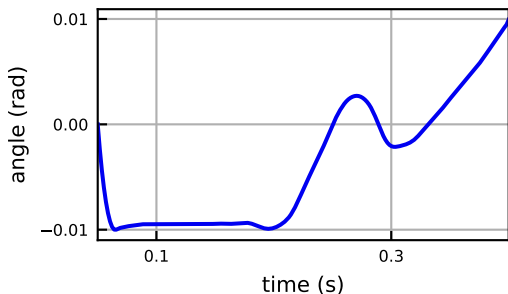
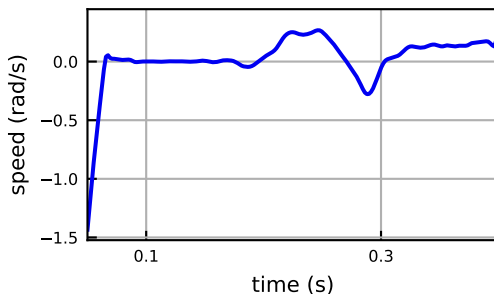


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (left leg)

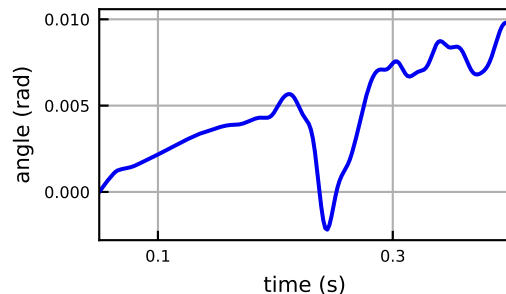
pelvis\_tilt/value



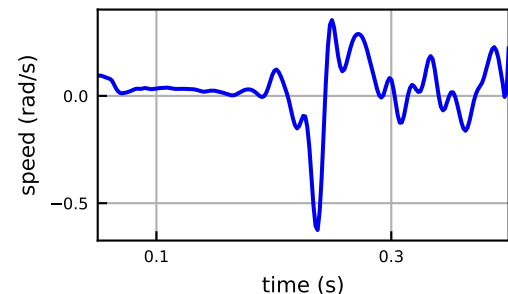
pelvis\_tilt/speed



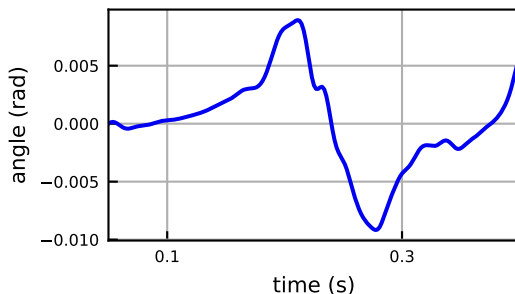
pelvis\_list/value



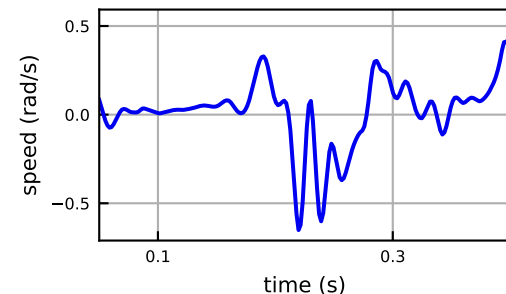
pelvis\_list/speed



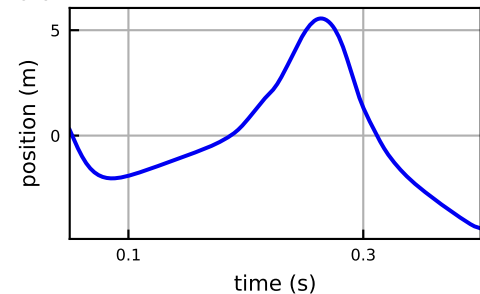
pelvis\_rotation/value



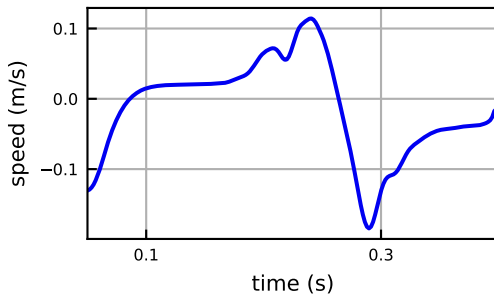
pelvis\_rotation/speed



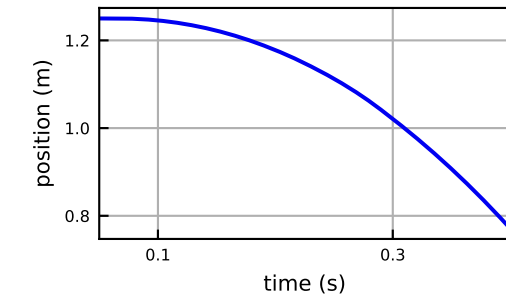
pelvis\_tx/value



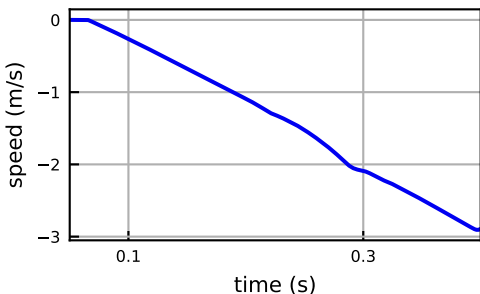
pelvis\_tx/speed



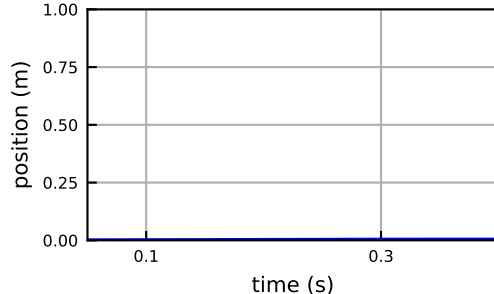
pelvis\_ty/value



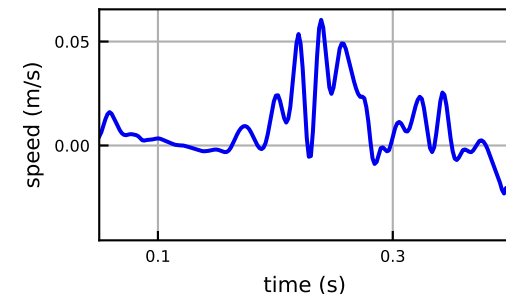
pelvis\_ty/speed



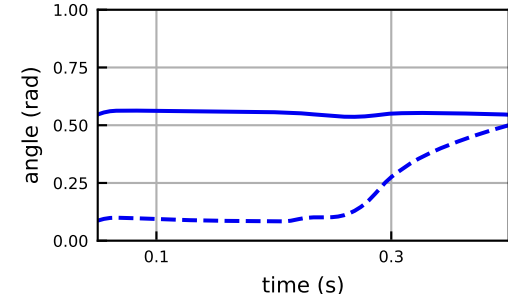
pelvis\_tz/value



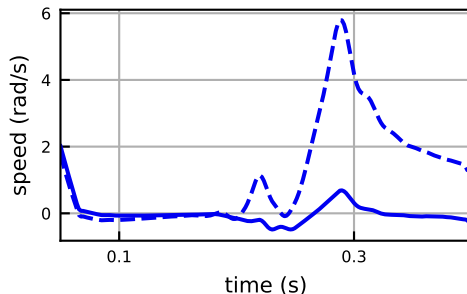
pelvis\_tz/speed



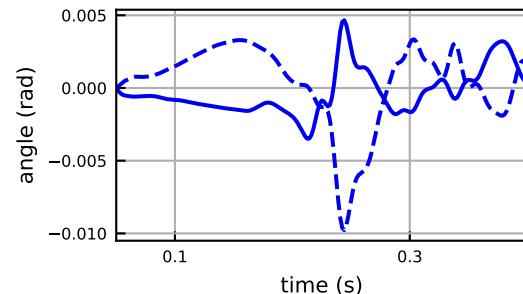
hip\_flexion/value



hip\_flexion/speed

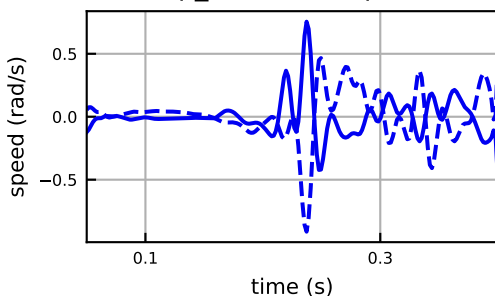


hip\_adduction/value

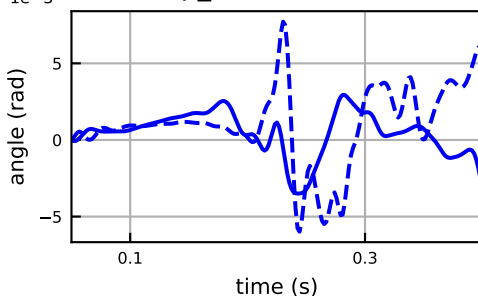


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (left leg)

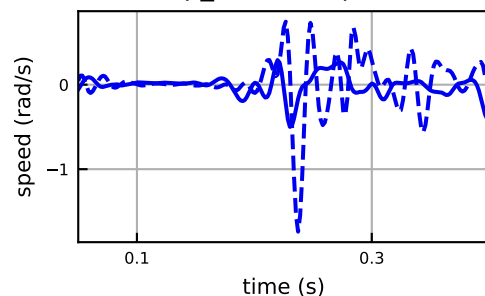
hip\_adduction/speed



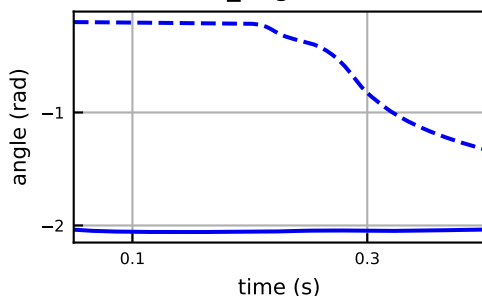
hip\_rotation/value



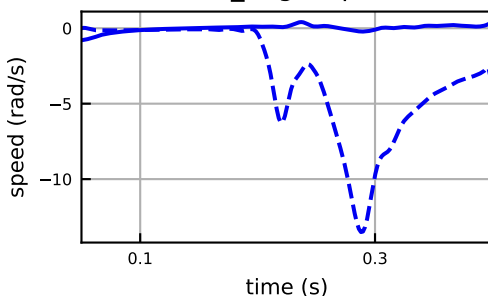
hip\_rotation/speed



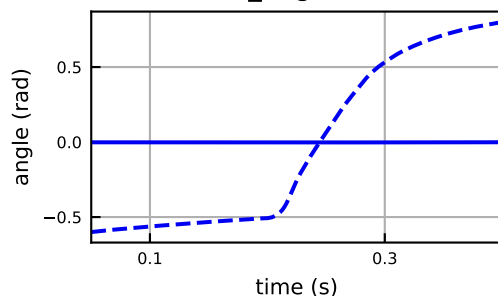
knee\_angle/value



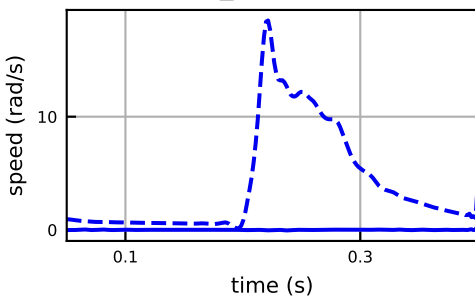
knee\_angle/speed



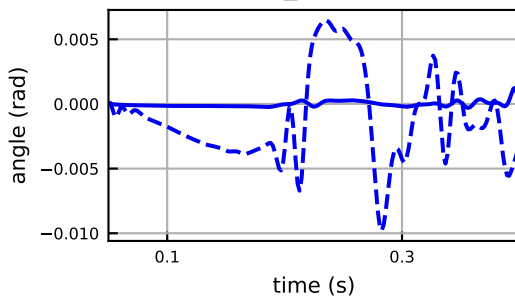
ankle\_angle/value



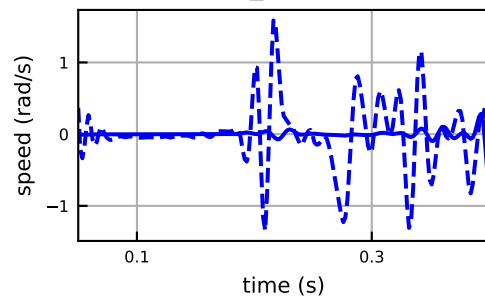
ankle\_angle/speed



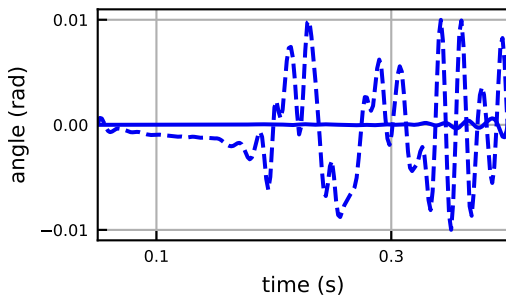
subtalar\_angle/value



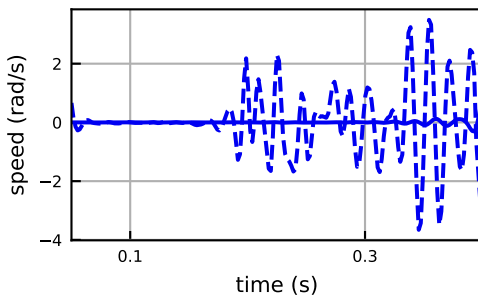
subtalar\_angle/speed



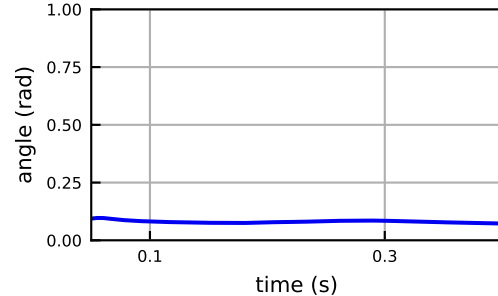
mtp\_angle/value



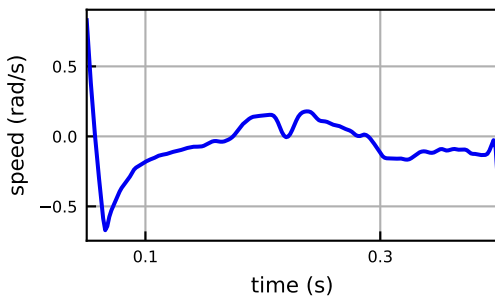
mtp\_angle/speed



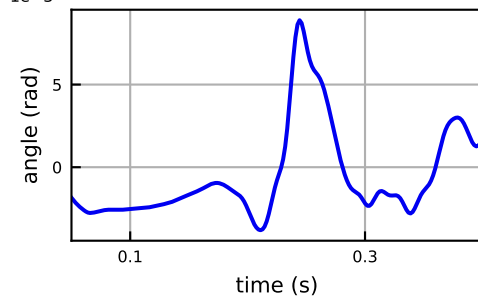
lumbar\_extension/value



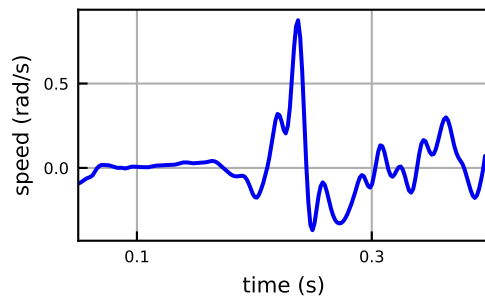
lumbar\_extension/speed



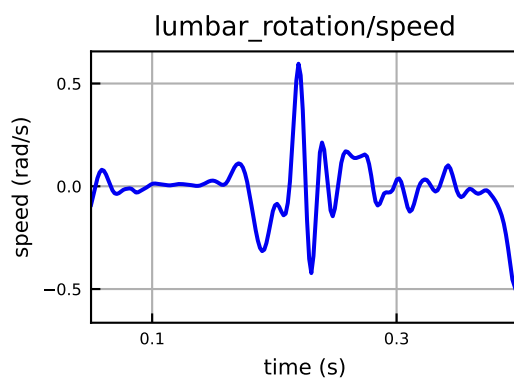
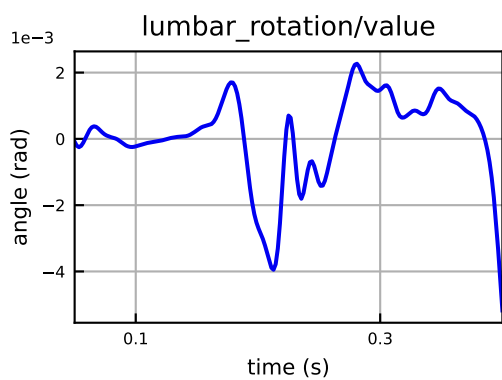
lumbar\_bending/value



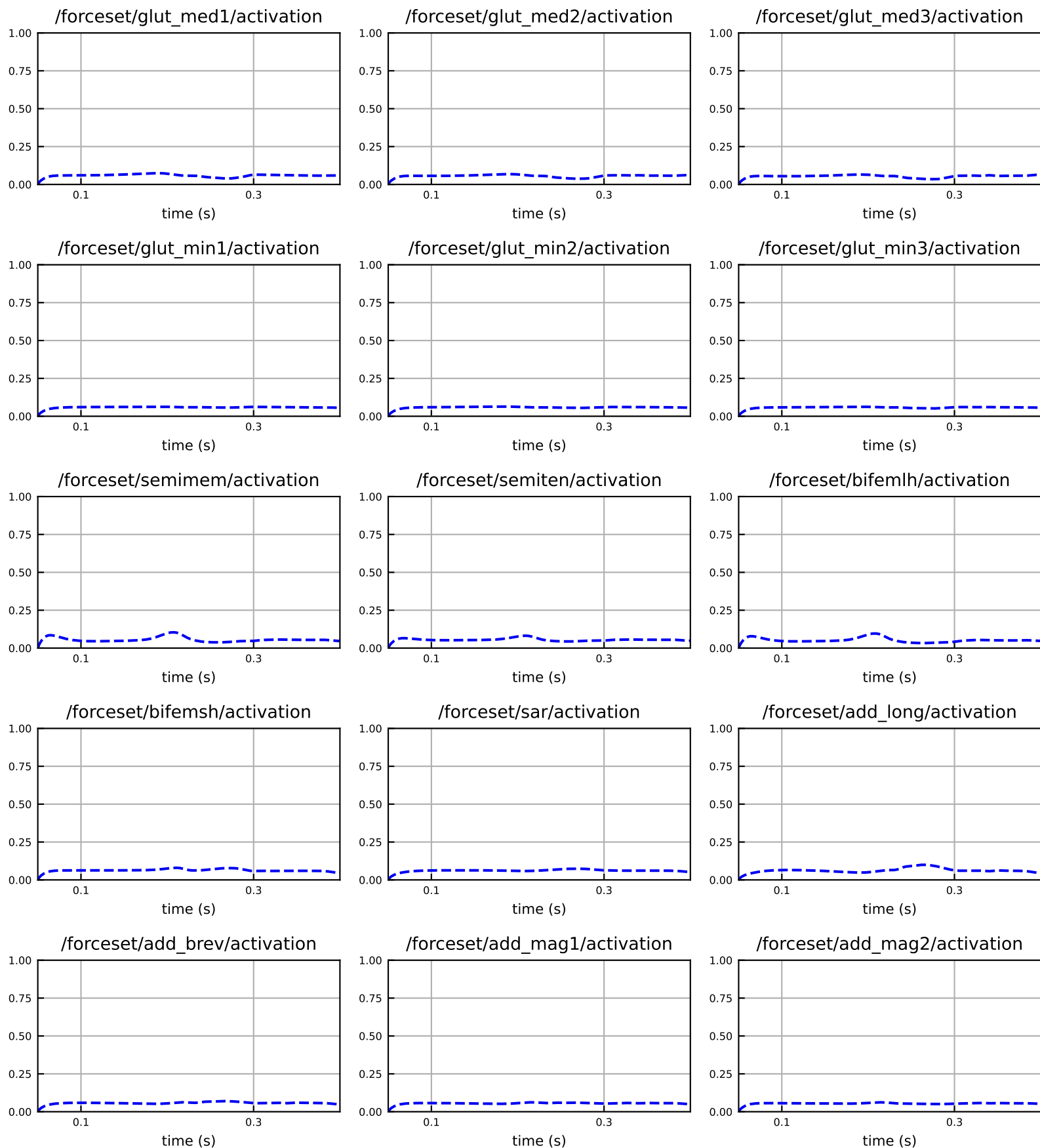
lumbar\_bending/speed



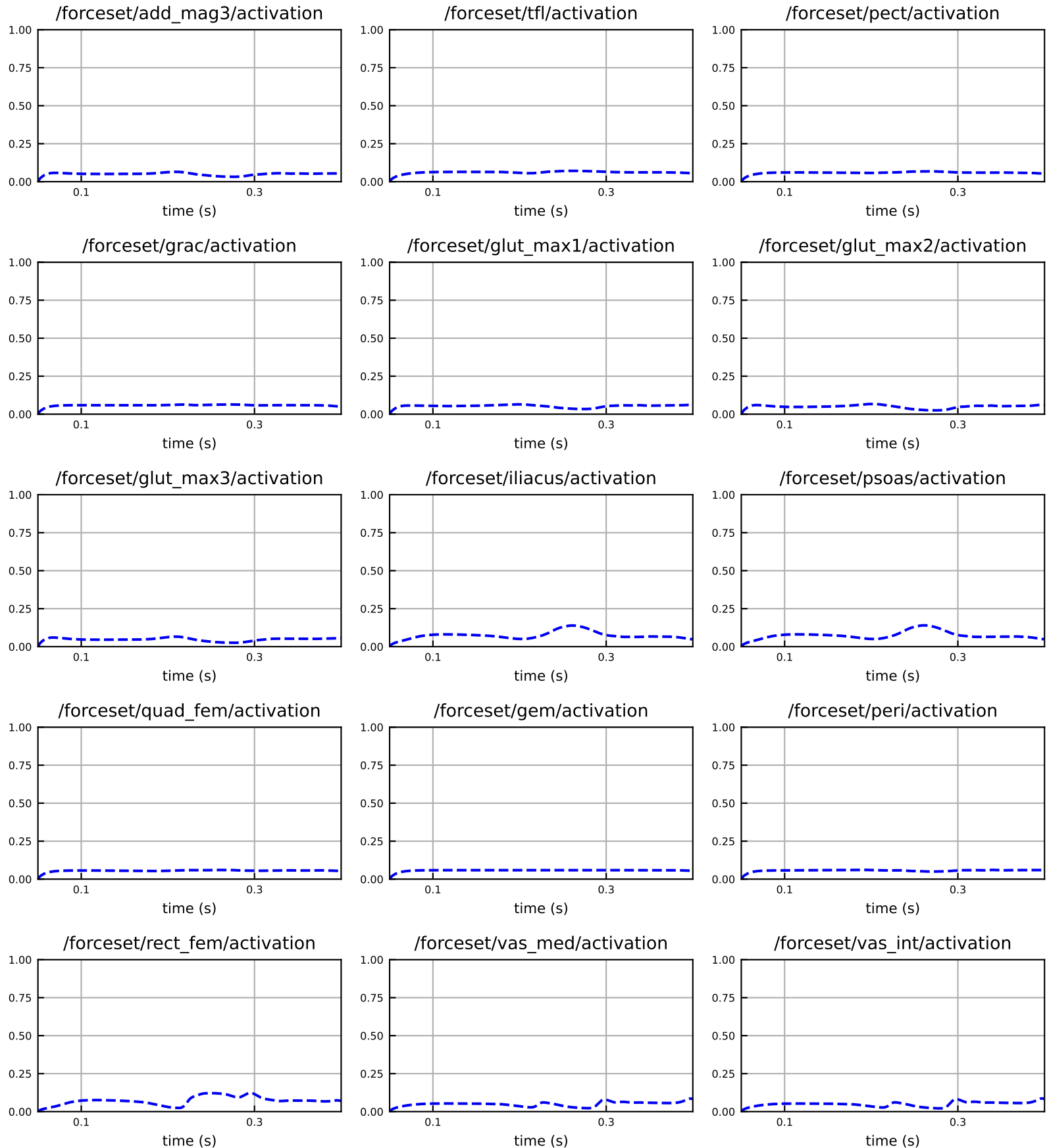
- D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (right leg)
- - D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (left leg)



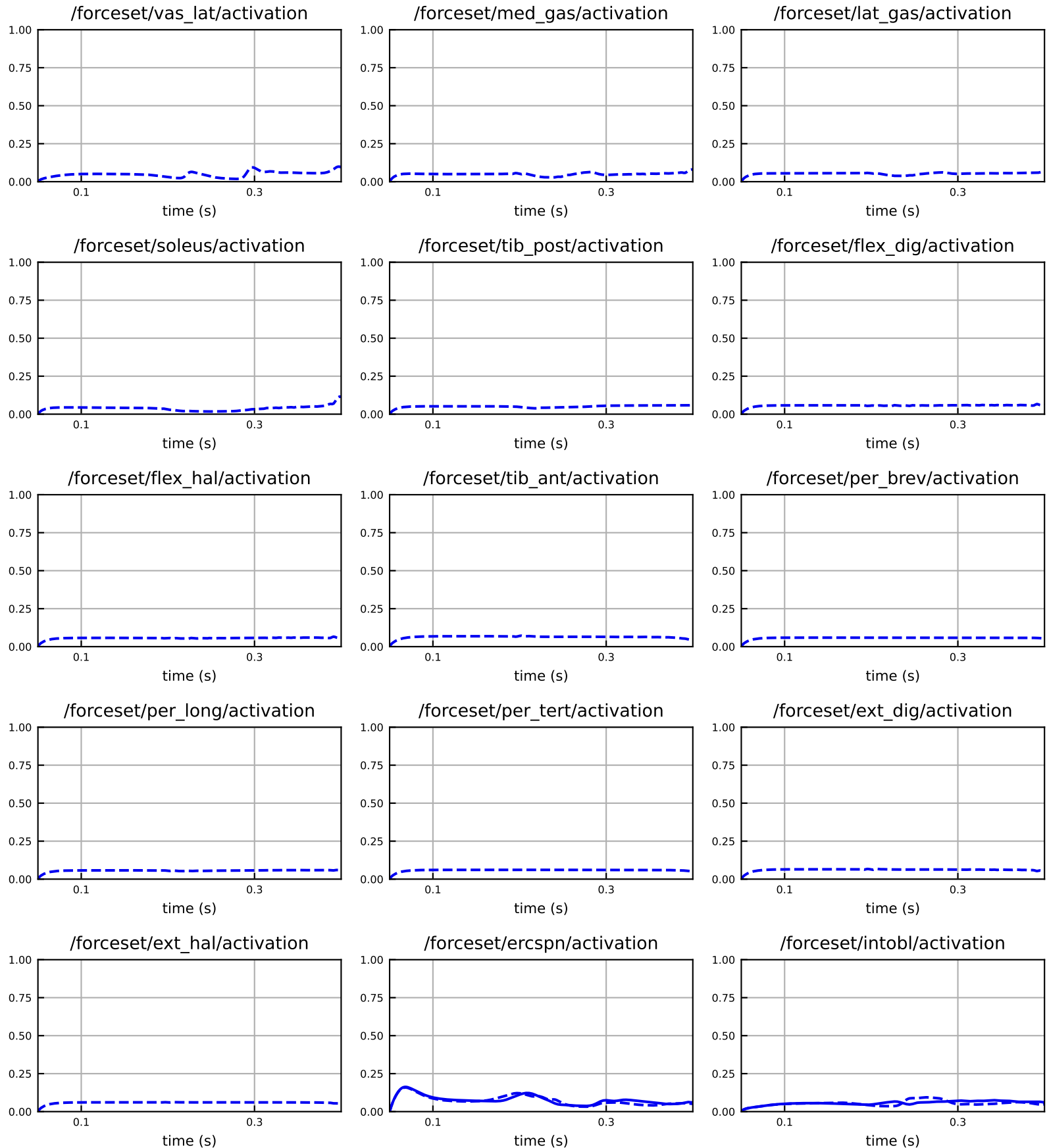
— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (left leg)

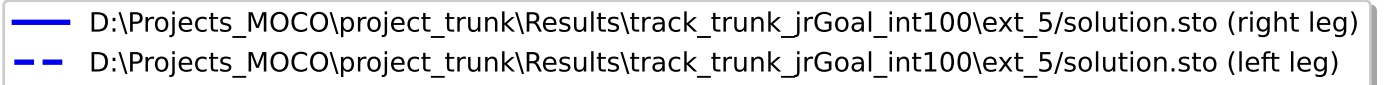


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5/solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5/solution.sto (left leg)

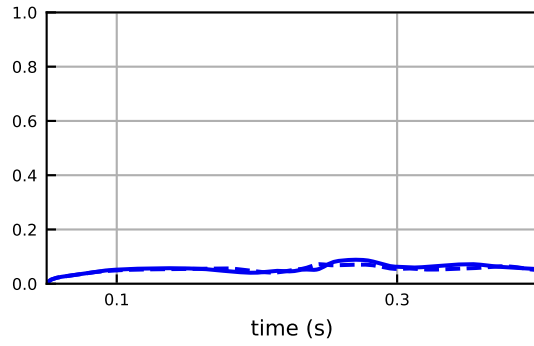


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (left leg)

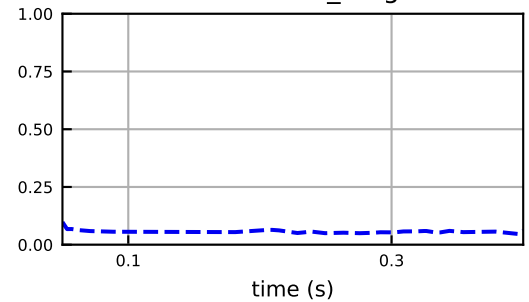
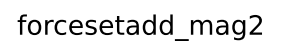
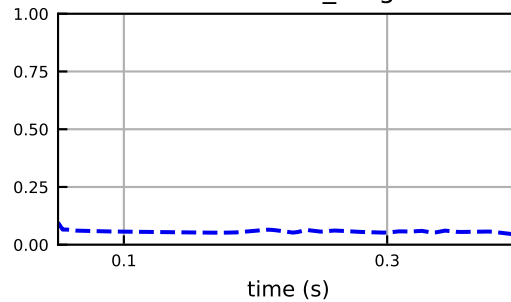
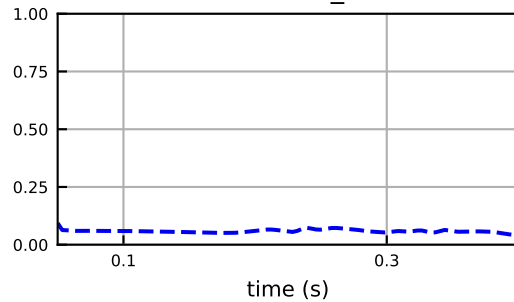
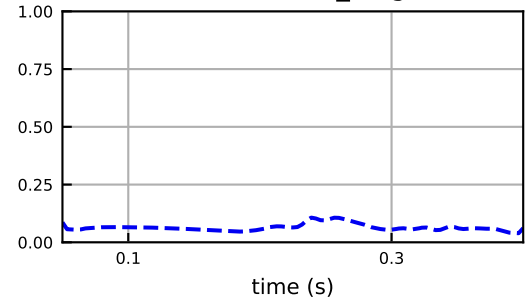
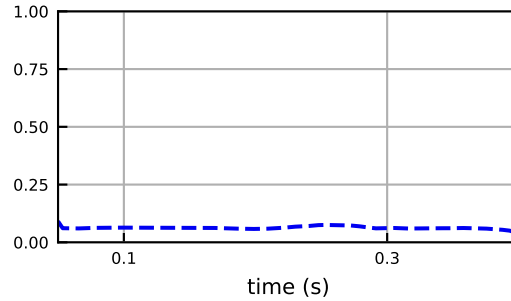
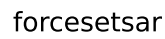
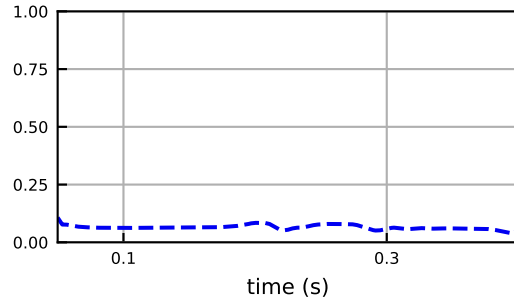
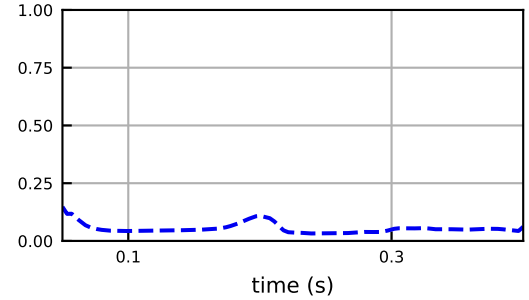
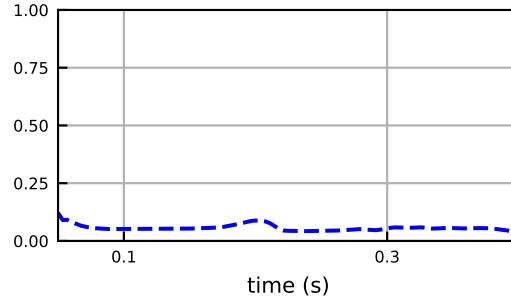
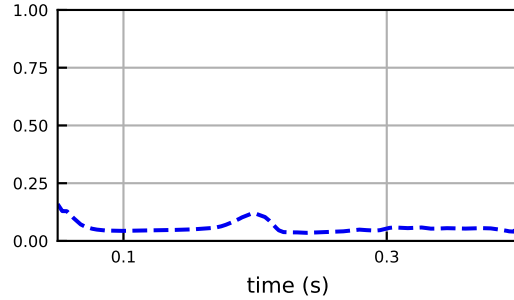
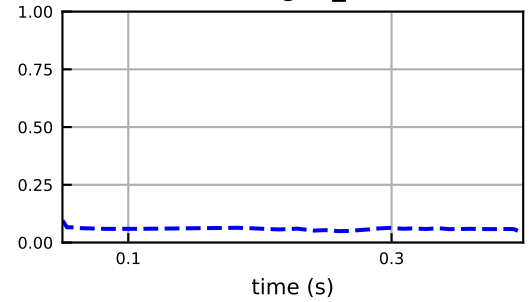
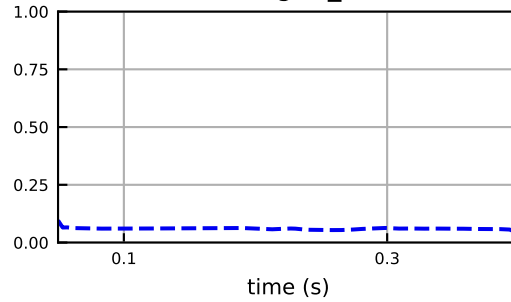
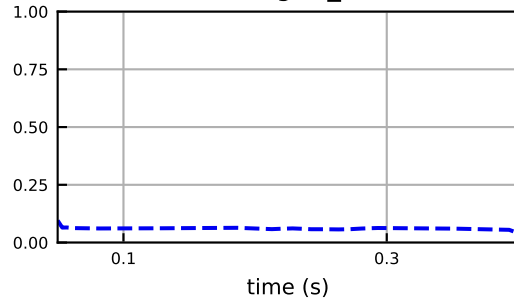
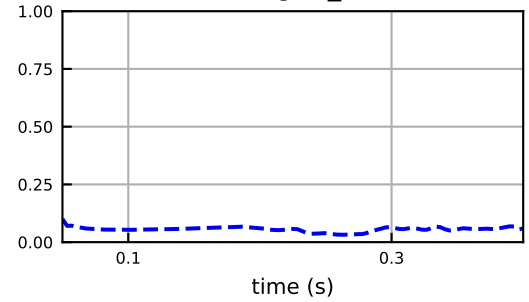
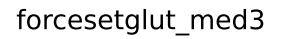
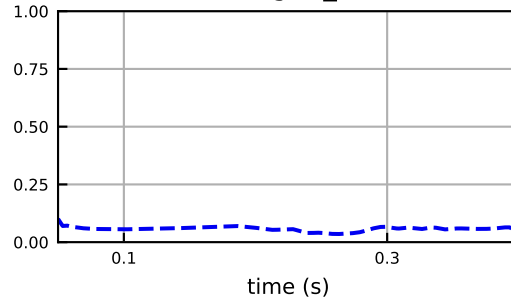
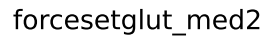
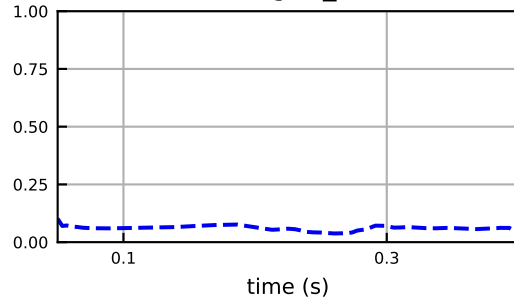
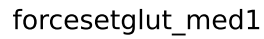




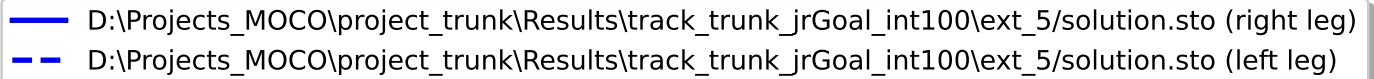
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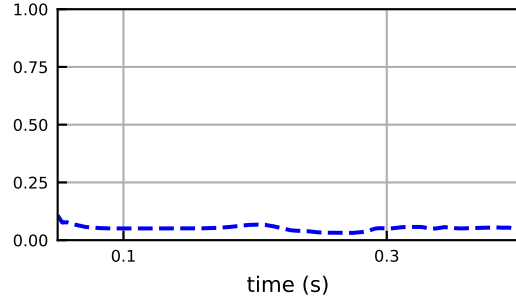
- D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (right leg)
- - D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5\solution.sto (left leg)



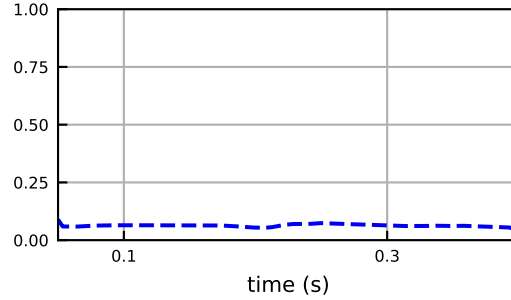




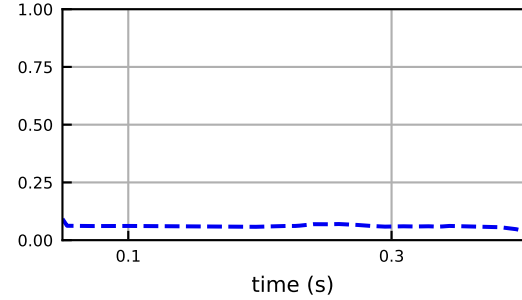
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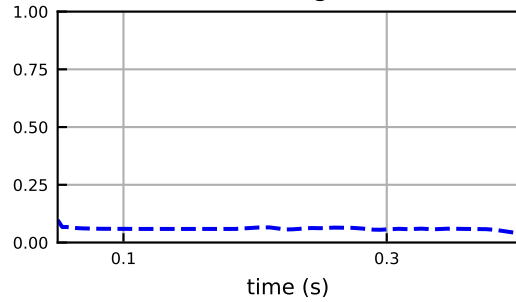
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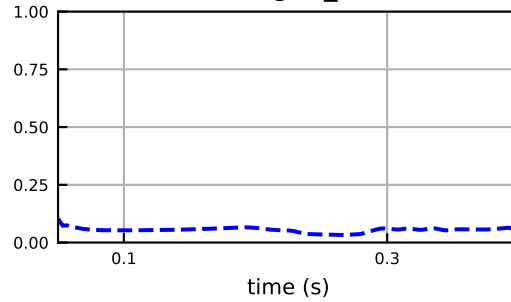
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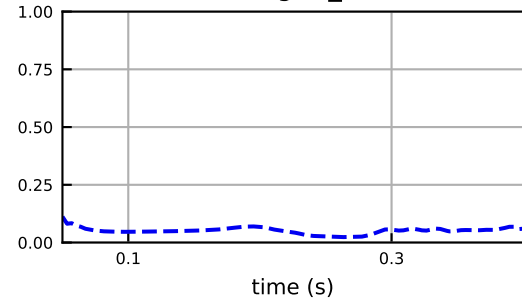
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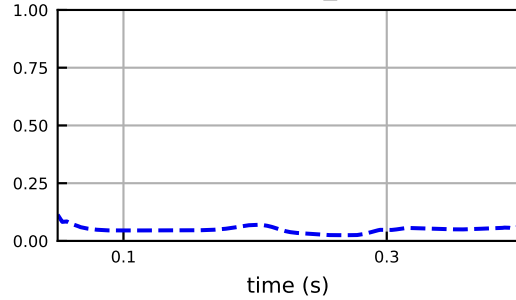
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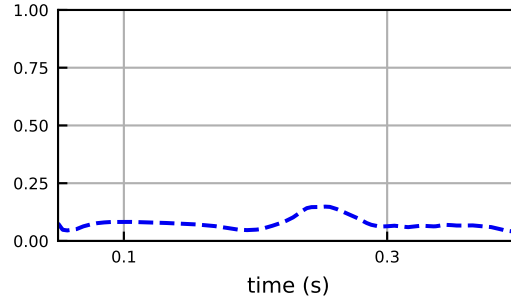
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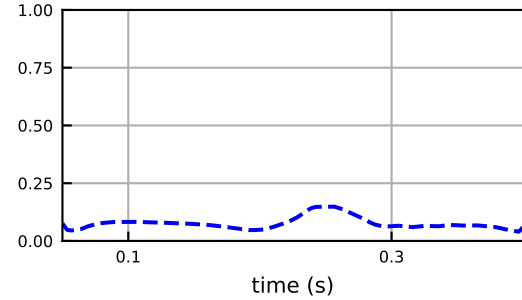
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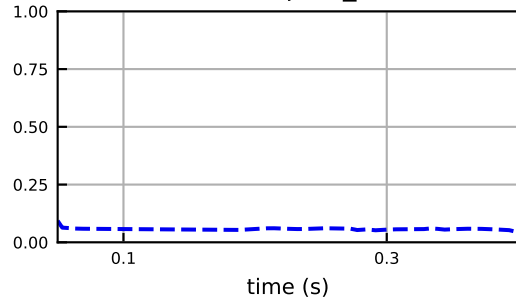
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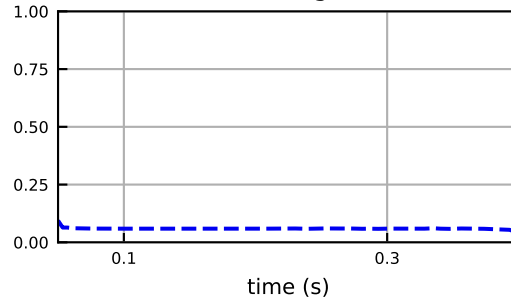
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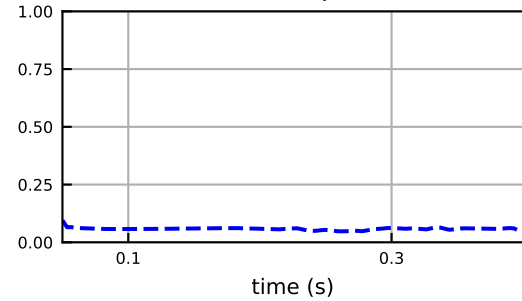
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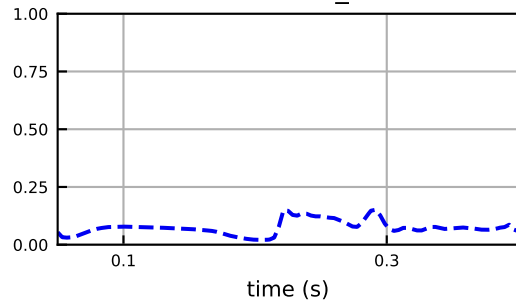
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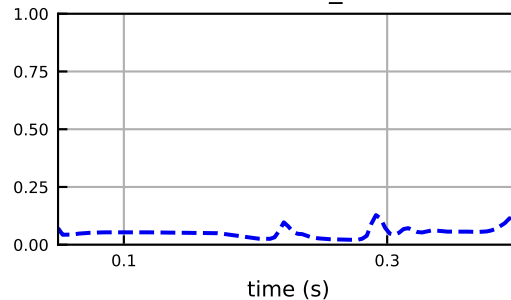
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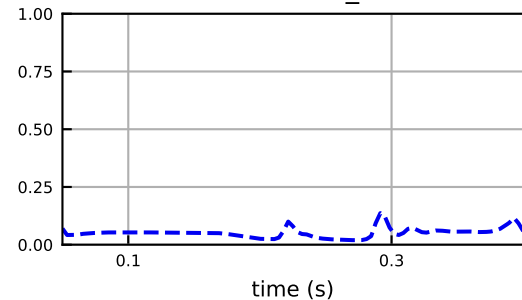
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forcesetvas\_med

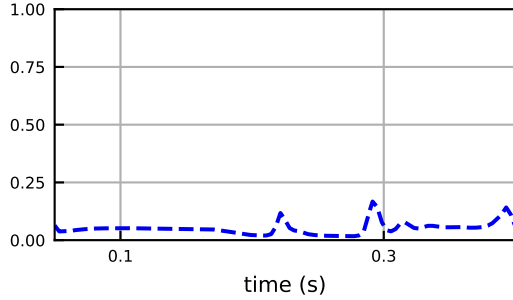


forcesetvas\_int

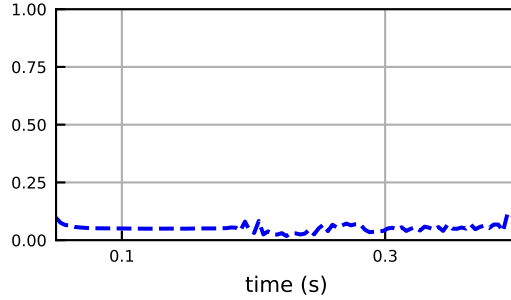


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5/solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_5/solution.sto (left leg)

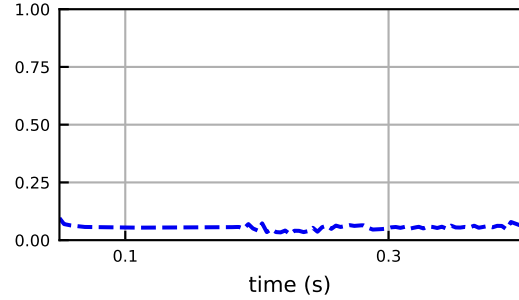
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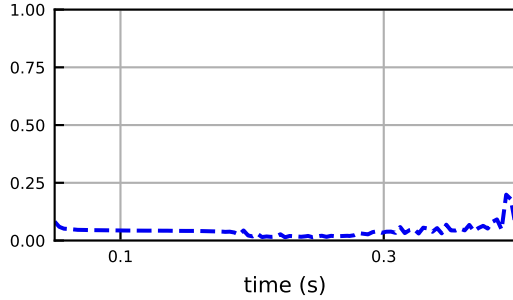
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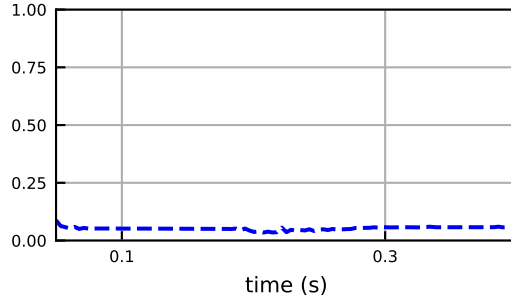
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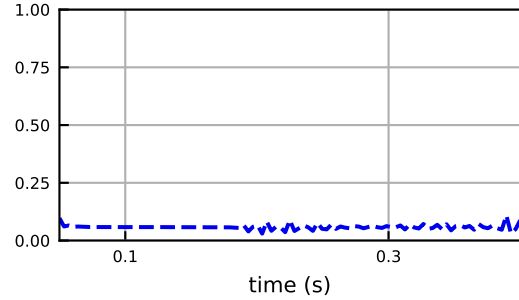
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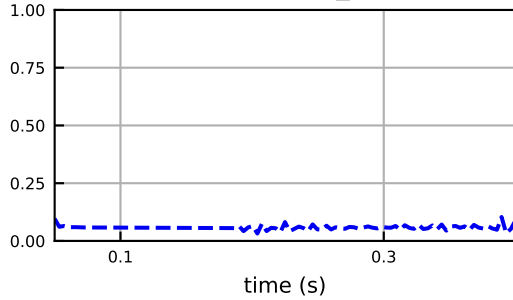
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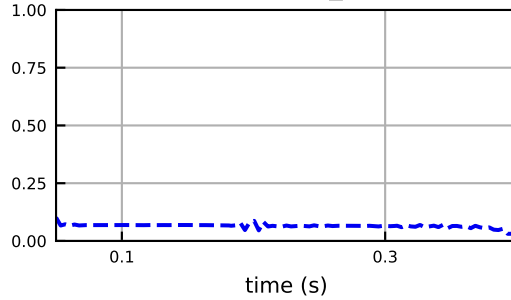
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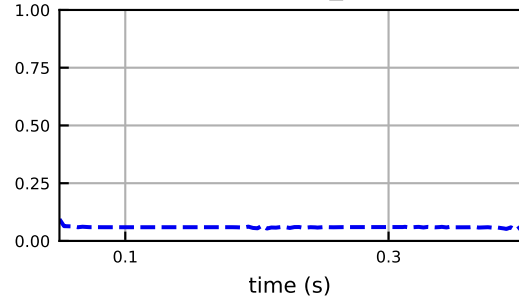
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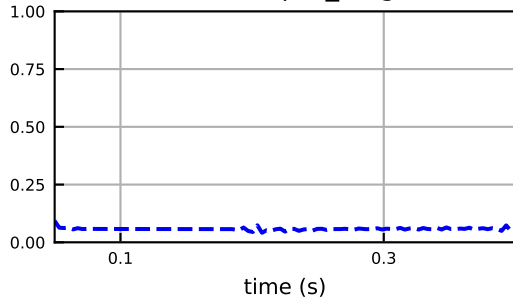
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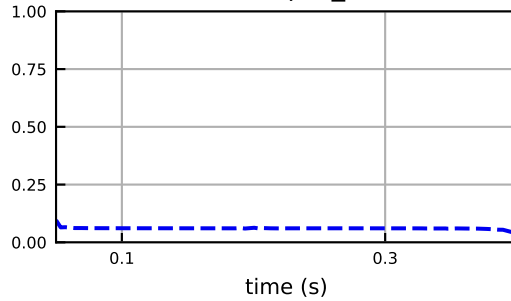
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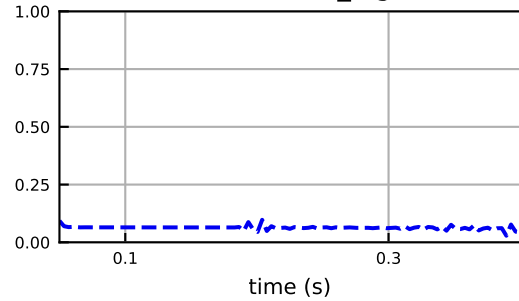
forcesetper\_long



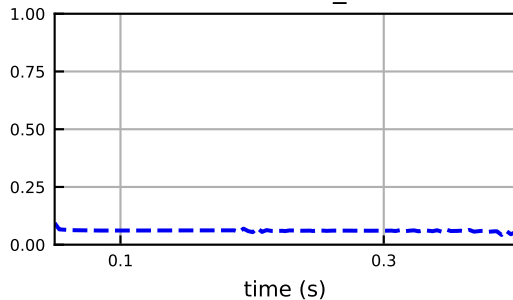
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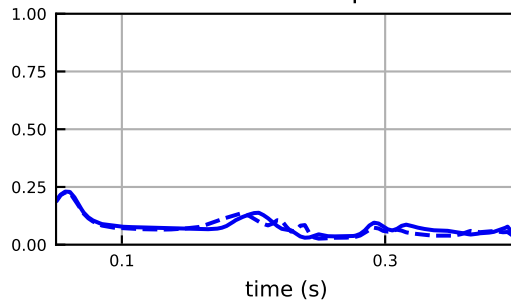
forcesetext\_dig



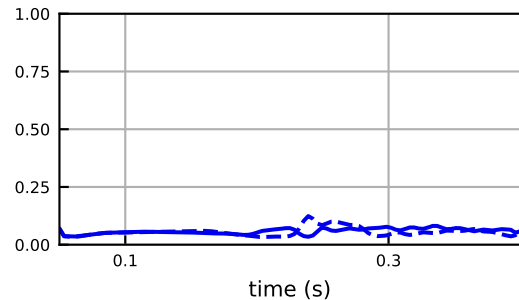
forcesetext\_hal



forcesetercspn

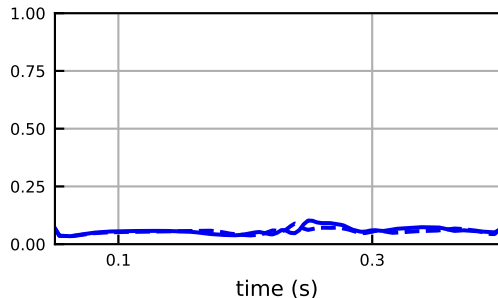


forcesetintobl

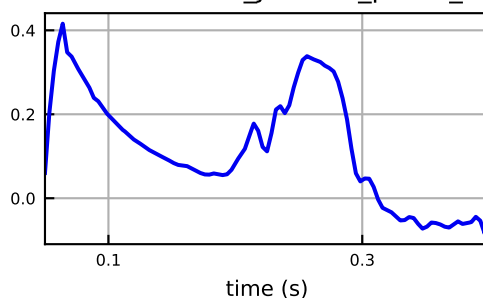


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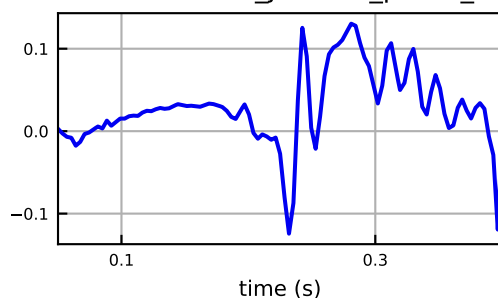
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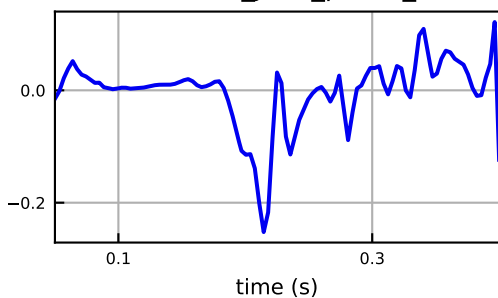
forcesetreserve\_joi...lvis\_pelvis\_tilt



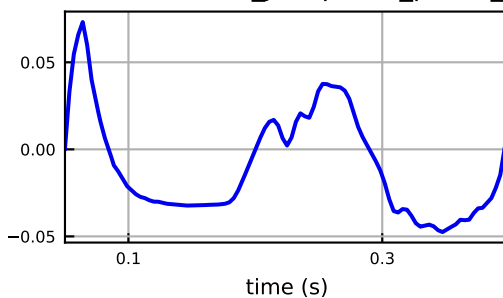
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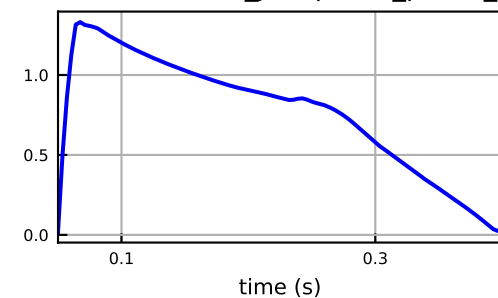
forcesetreserve\_joi...pelvis\_rotation



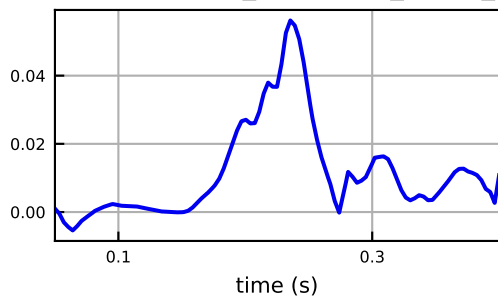
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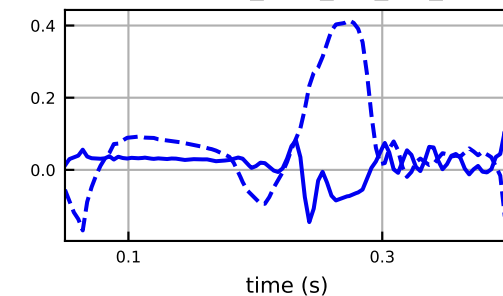
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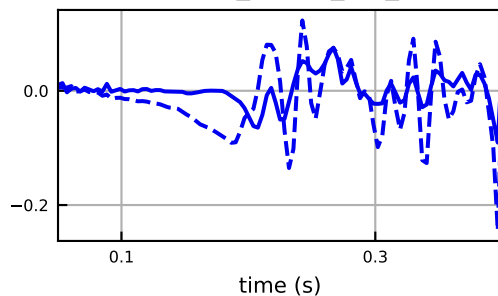
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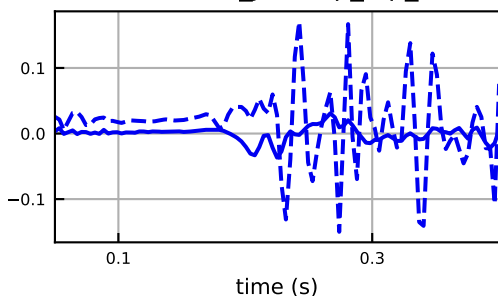
forcesetreserve\_joi...hip\_hip\_flexion



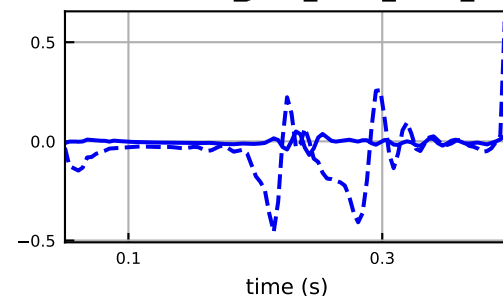
forcesetreserve\_joi...ip\_hip\_adduction



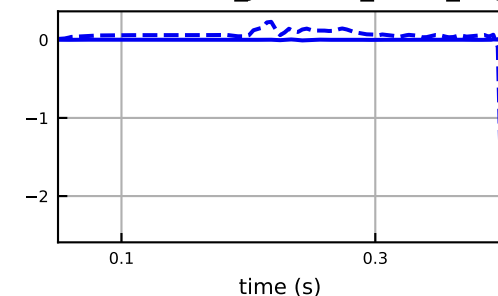
forcesetreserve\_joi...hip\_hip\_rotation



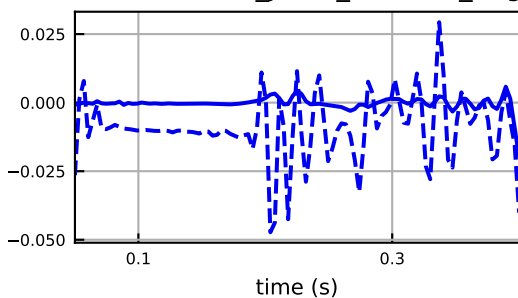
forcesetreserve\_joi...knee\_knee\_angle



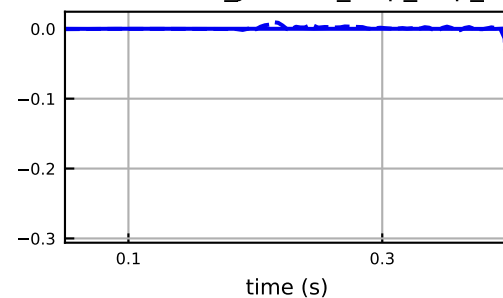
forcesetreserve\_joi...nkle\_ankle\_angle



forcesetreserve\_joi...r\_subtalar\_angle



forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension

