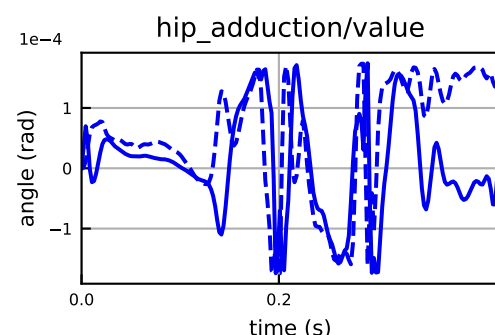
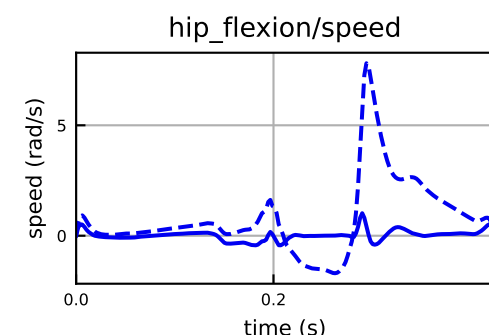
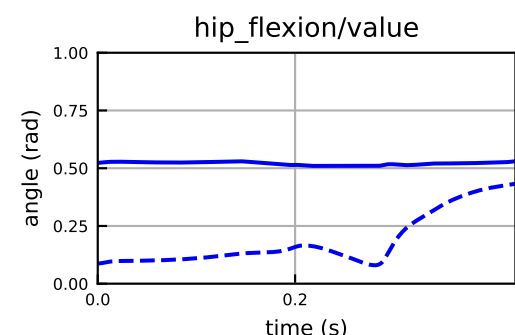
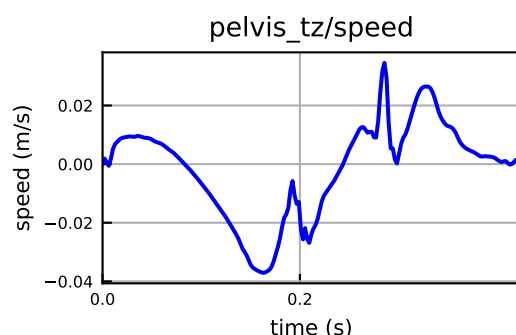
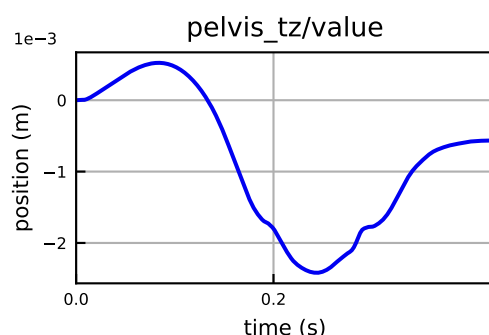
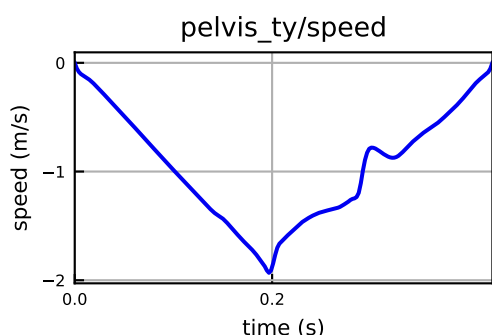
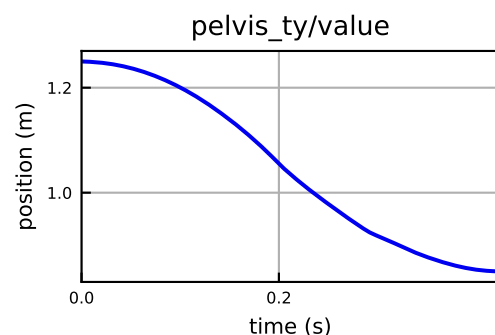
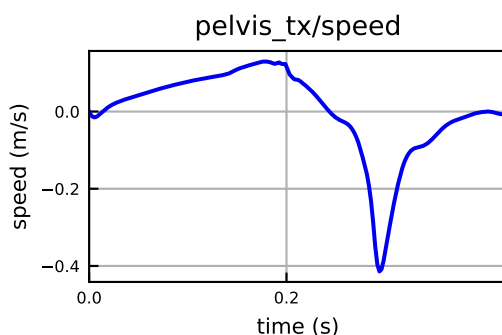
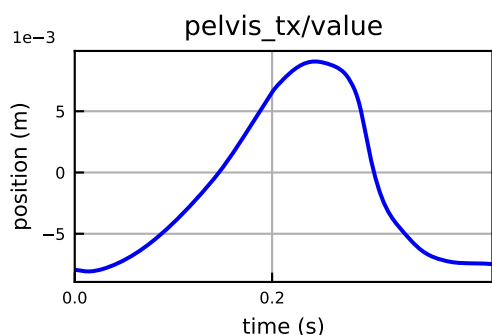
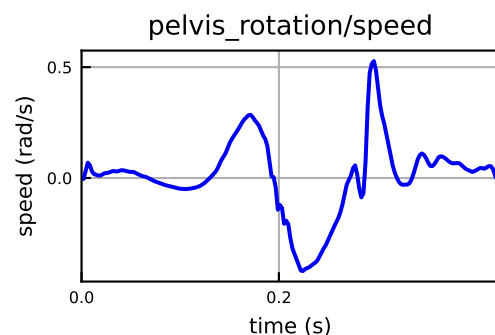
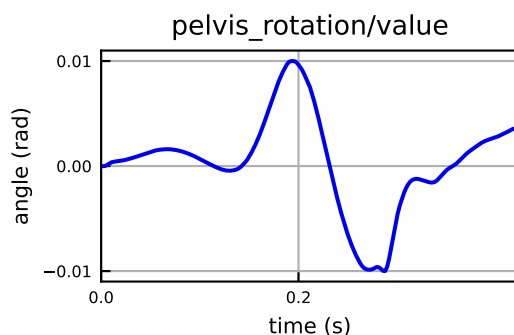
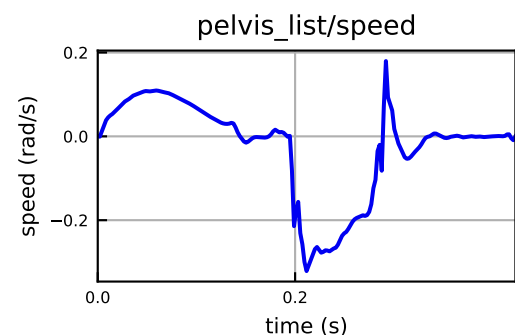
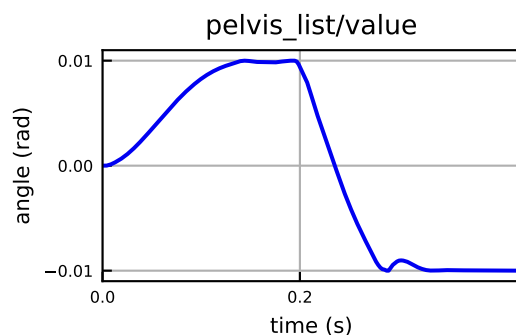
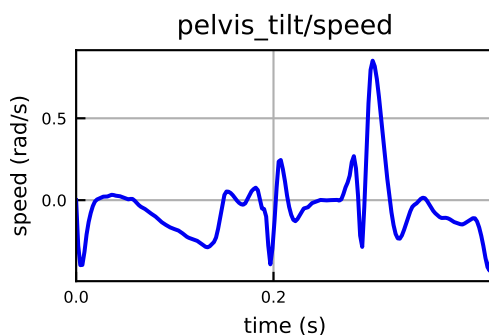
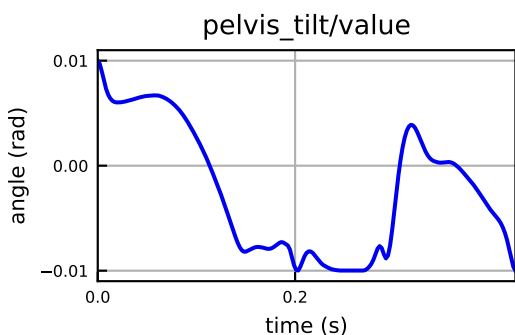
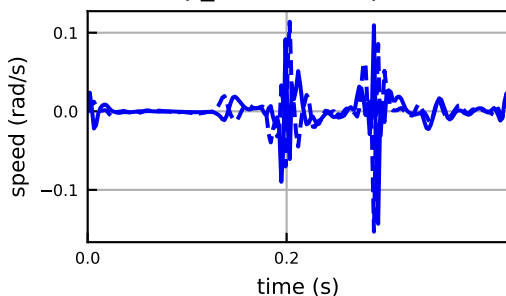


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30\solution.sto (right leg)
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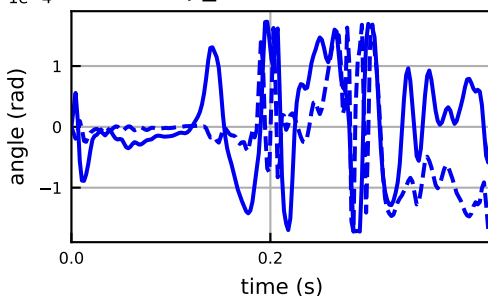


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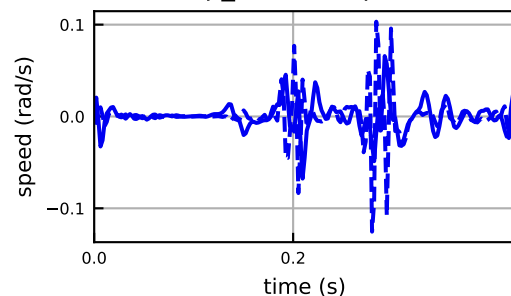
hip_adduction/speed



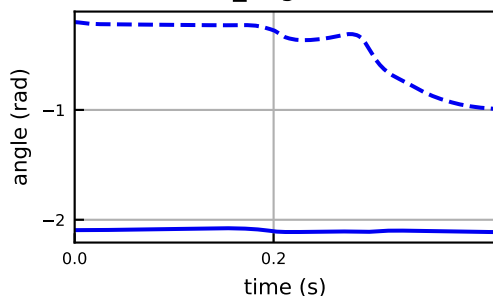
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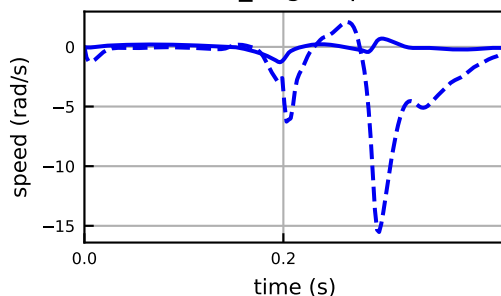
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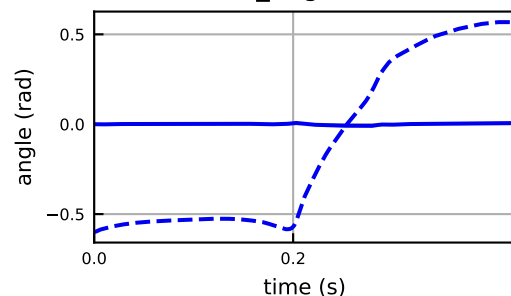
knee_angle/value



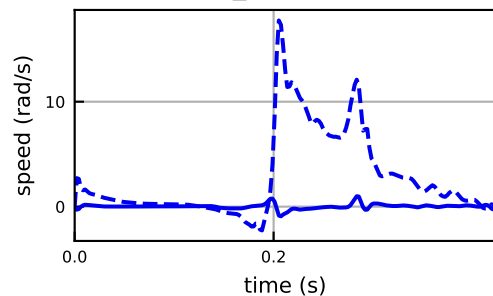
knee_angle/speed



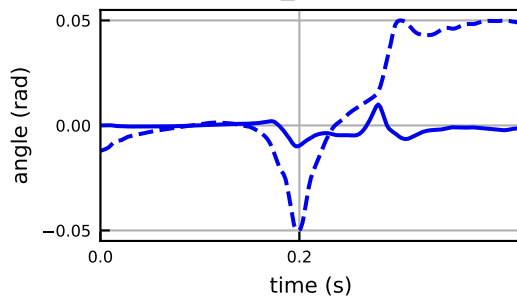
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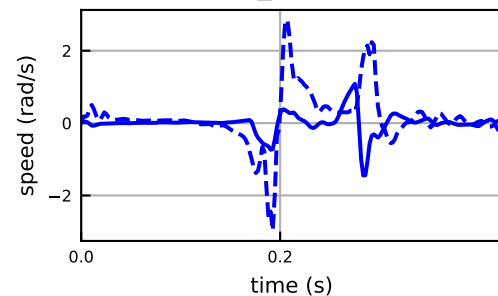
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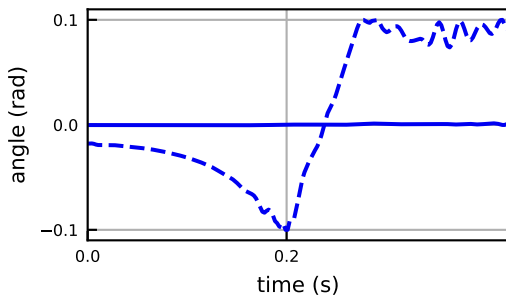
subtalar_angle/value



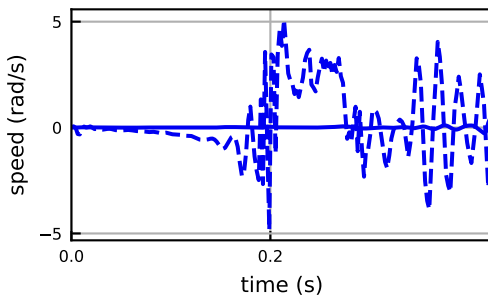
subtalar_angle/speed



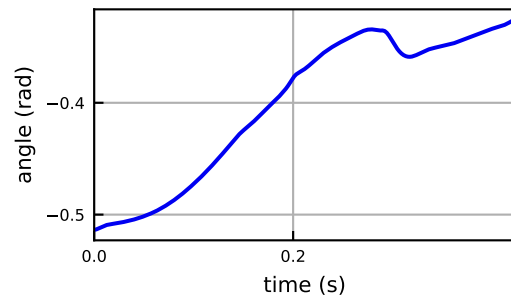
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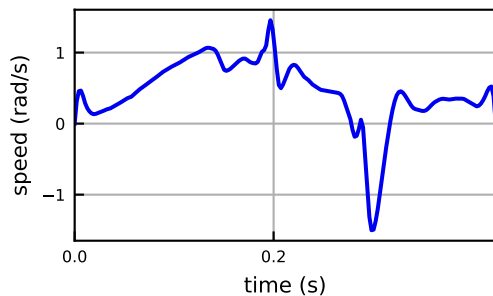
mtp_angle/speed



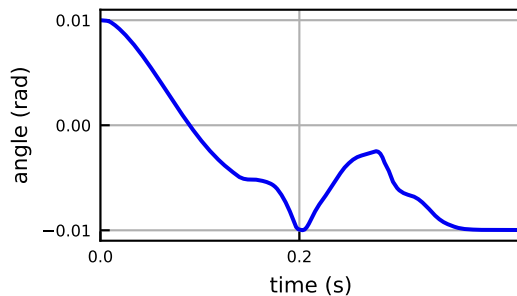
lumbar_extension/value



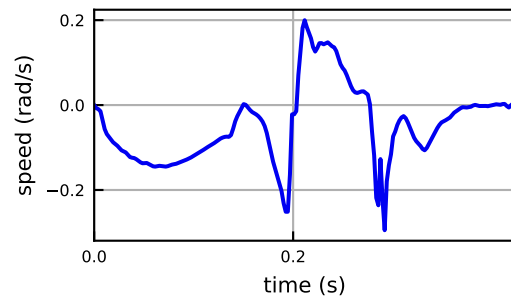
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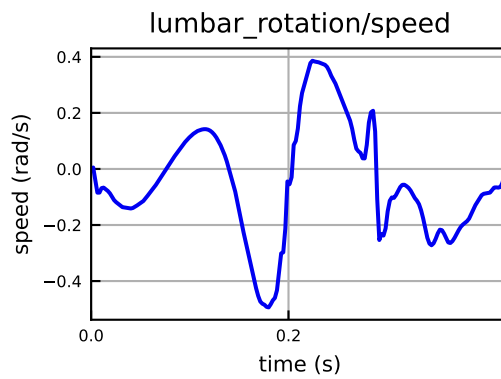
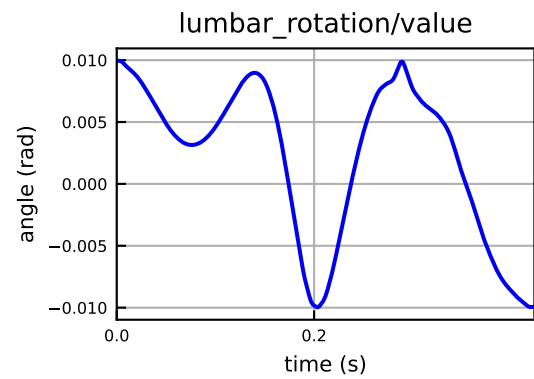
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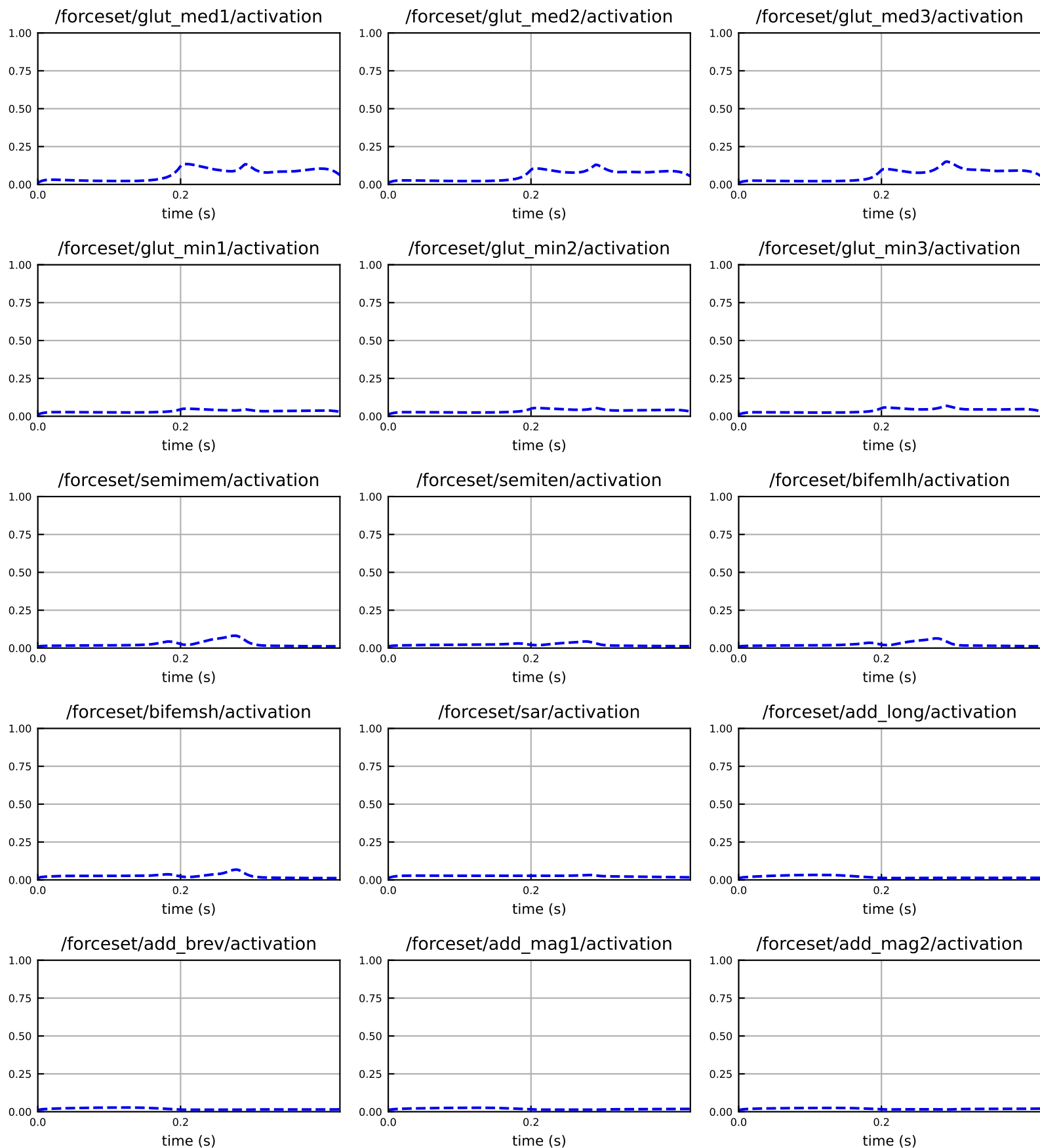
lumbar_bending/speed



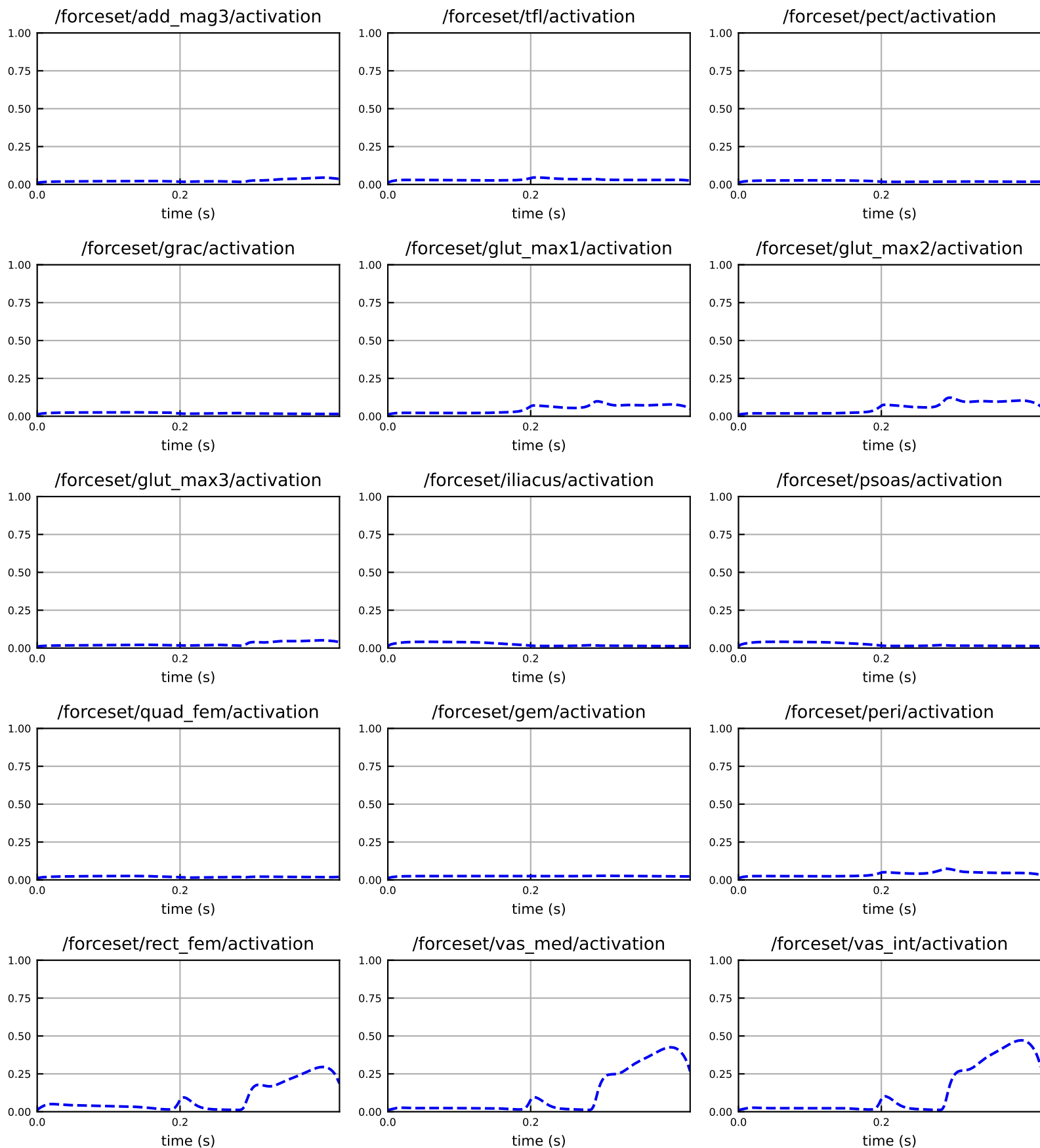
— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30\solution.sto (right leg)
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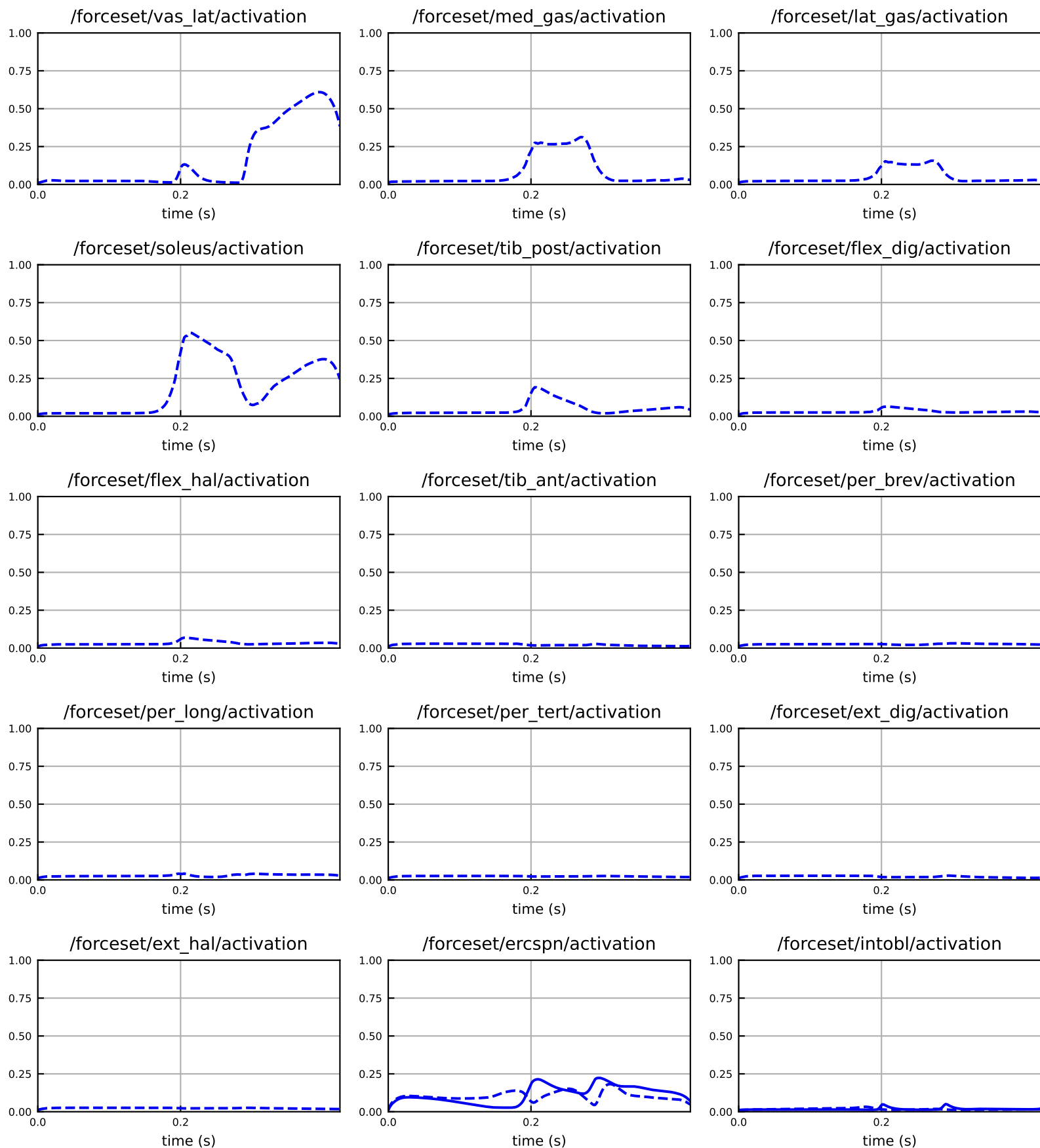
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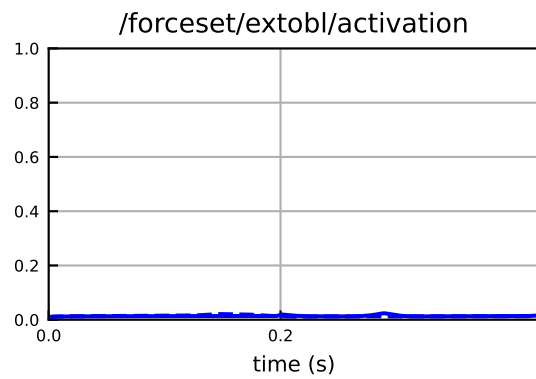
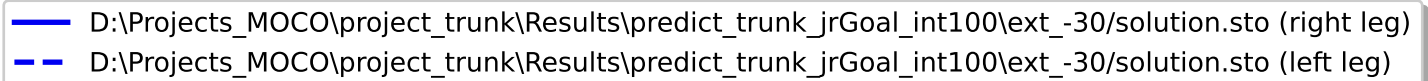


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30/solution.sto (right leg)
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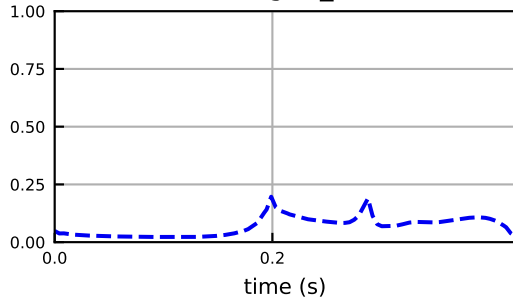
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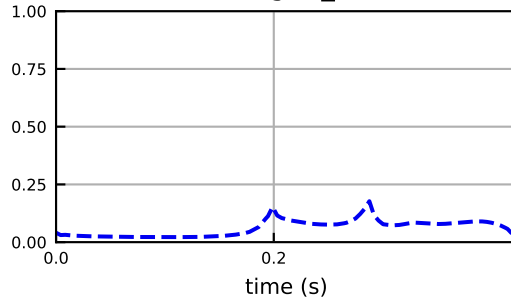


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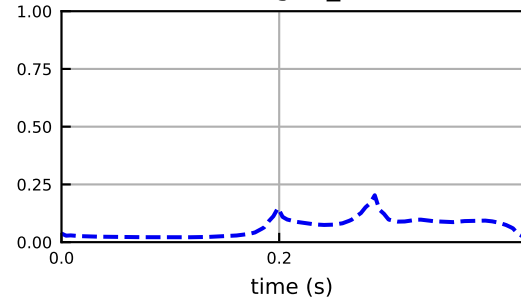
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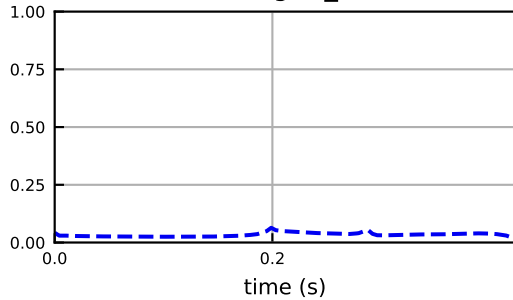
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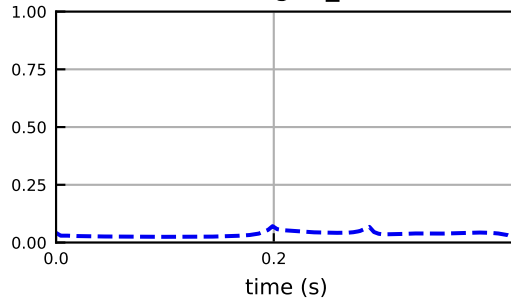
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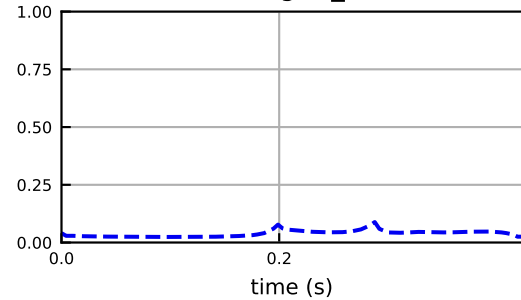
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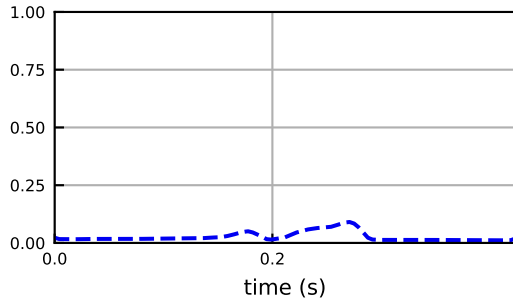
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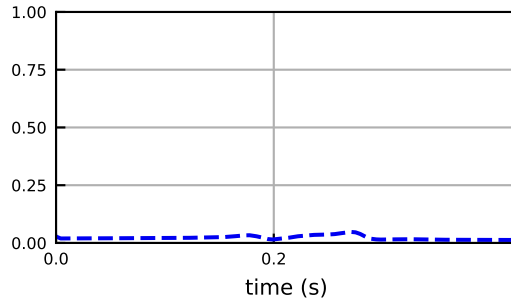
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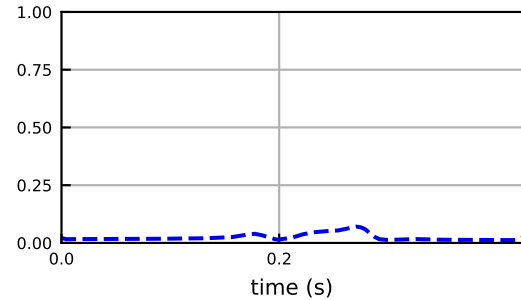
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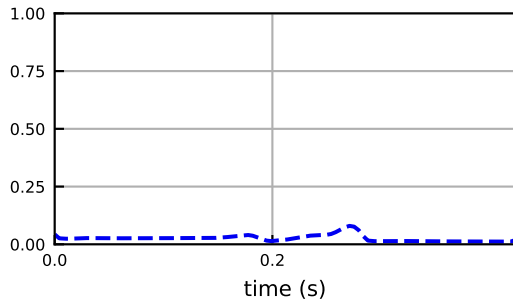
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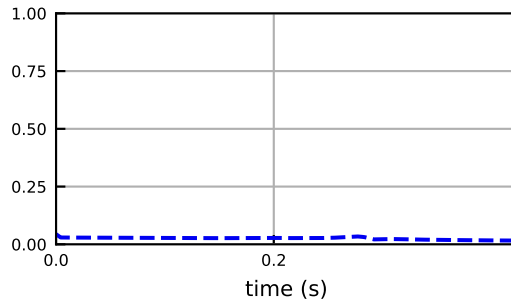
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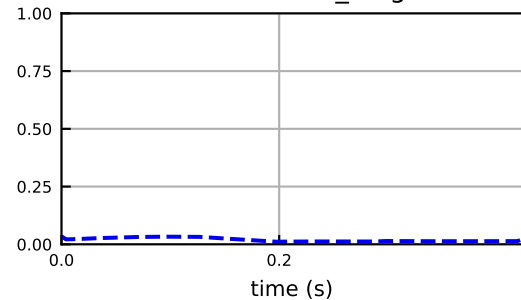
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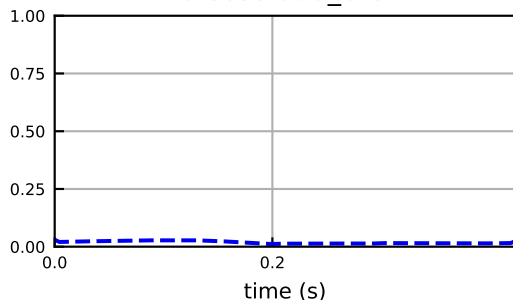
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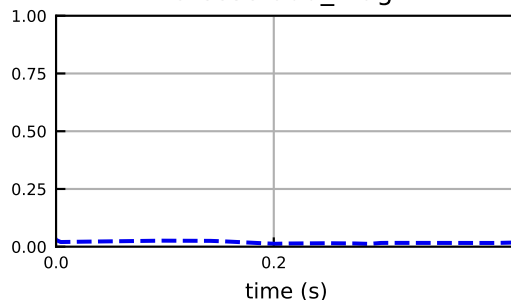
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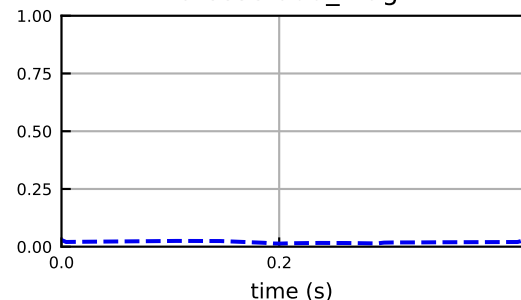
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forcesetadd_mag1

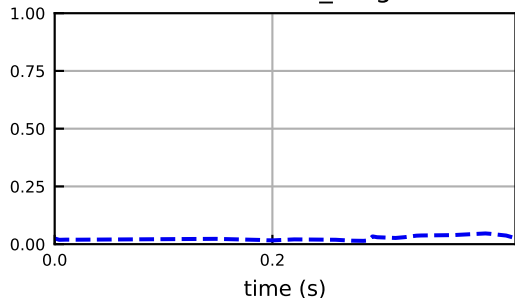


forcesetadd_mag2

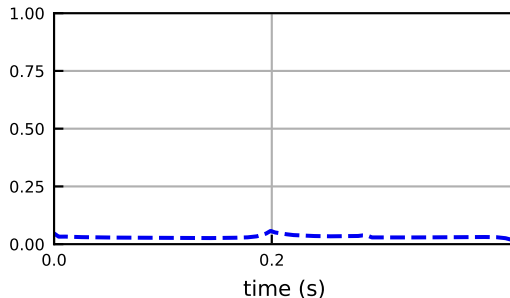


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30/solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30/solution.sto (left leg)

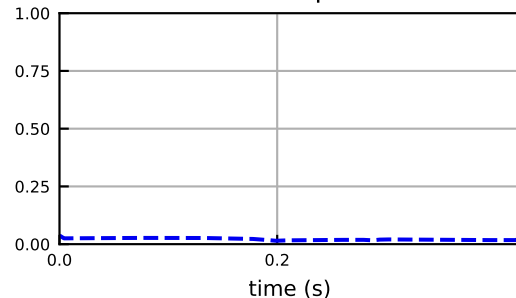
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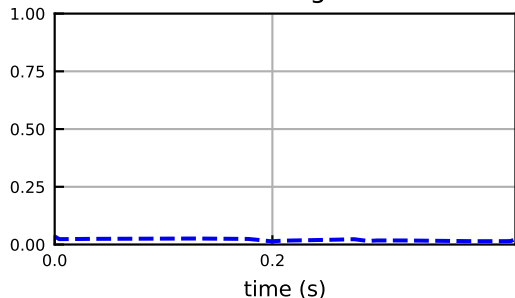
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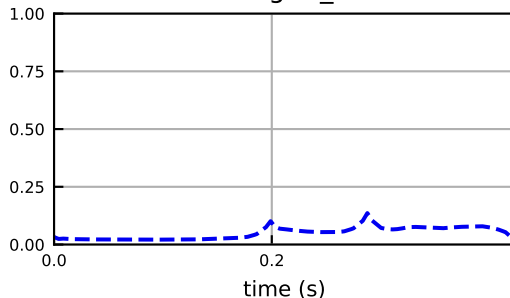
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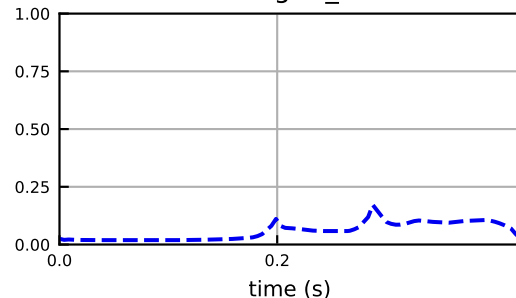
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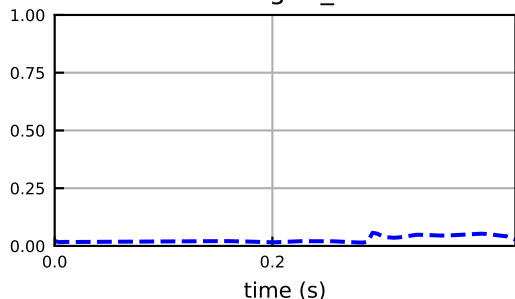
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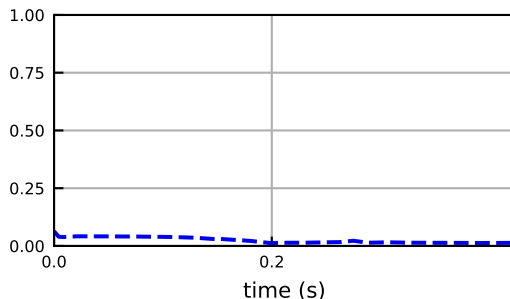
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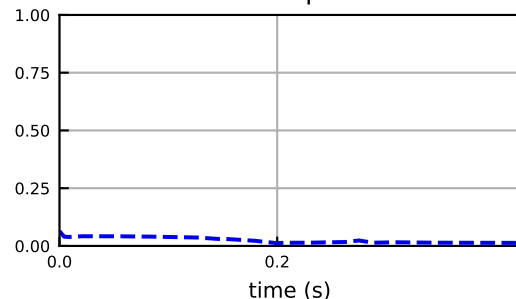
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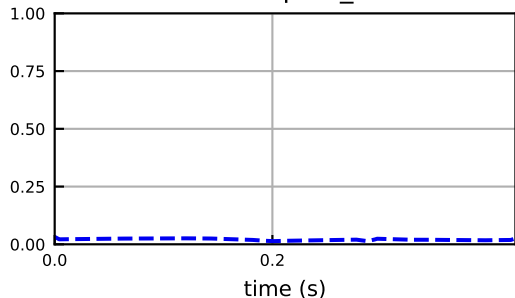
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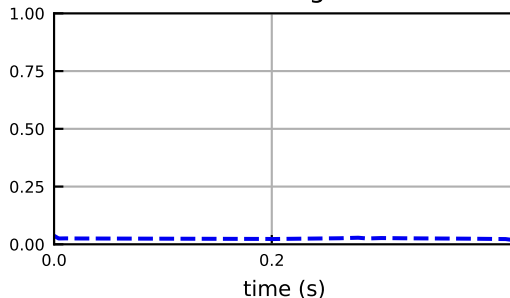
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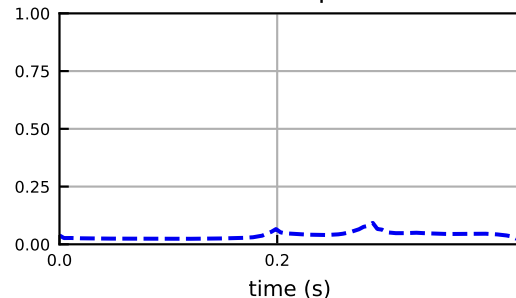
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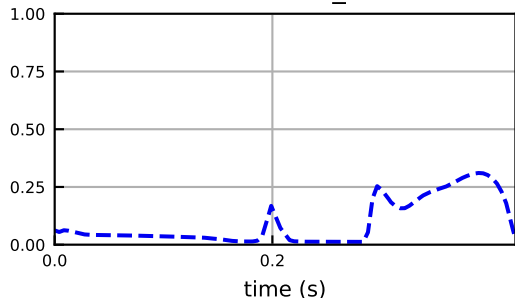
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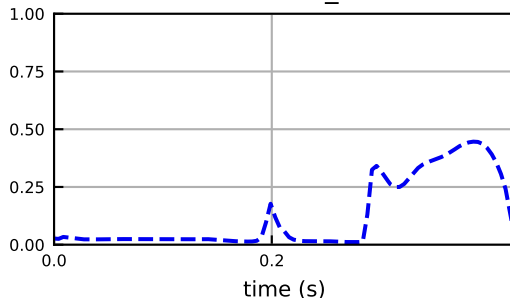
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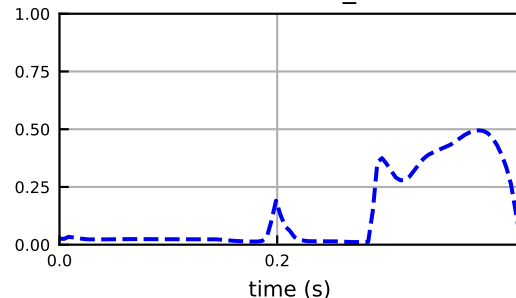
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forcesetvas_med

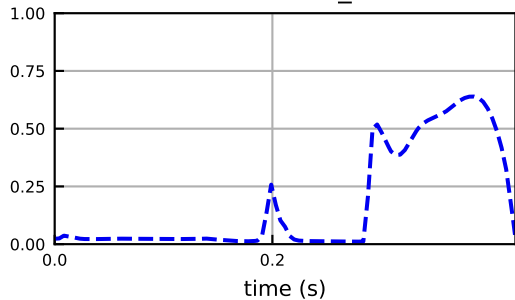


forcesetvas_int

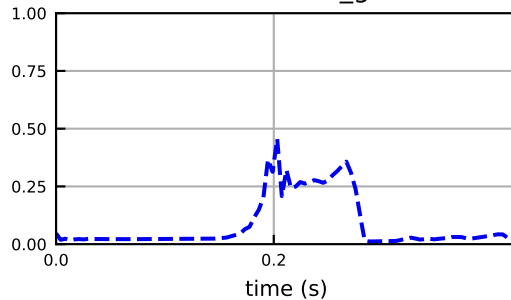


— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30/solution.sto (right leg)
- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30/solution.sto (left leg)

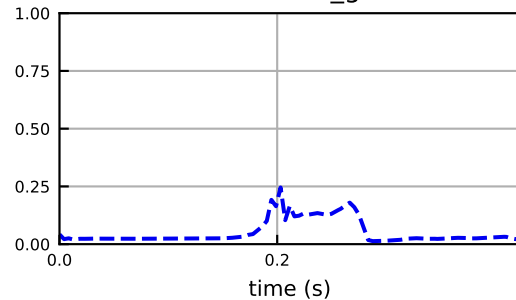
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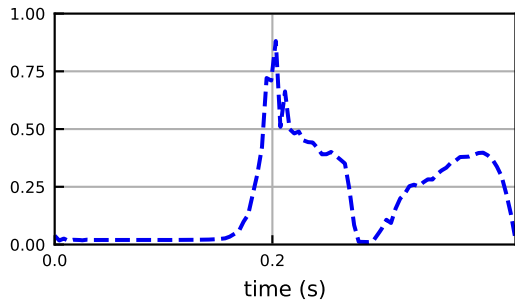
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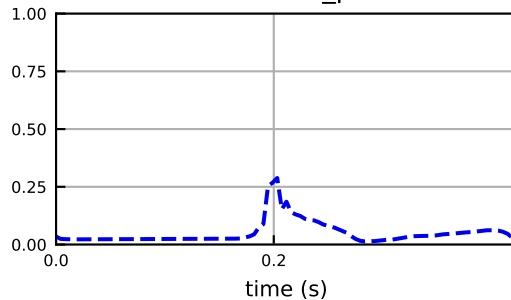
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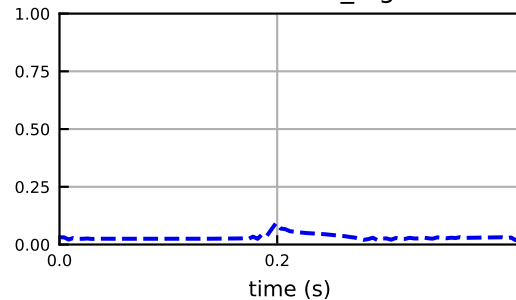
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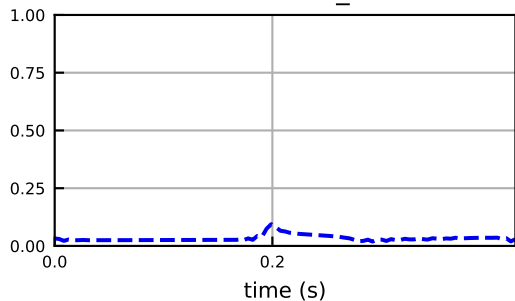
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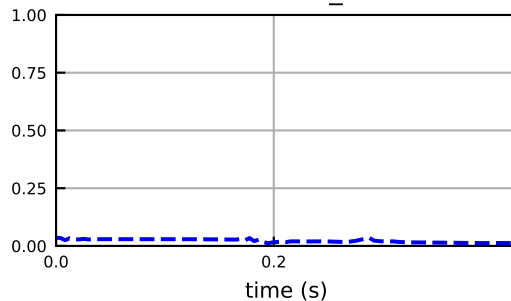
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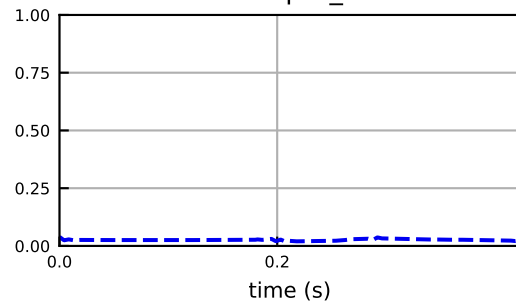
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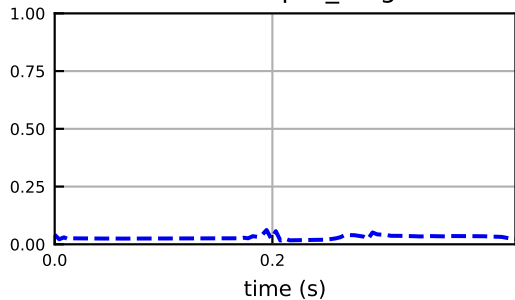
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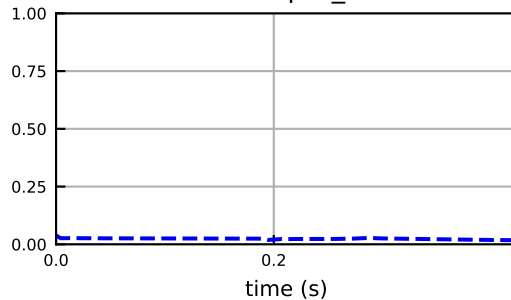
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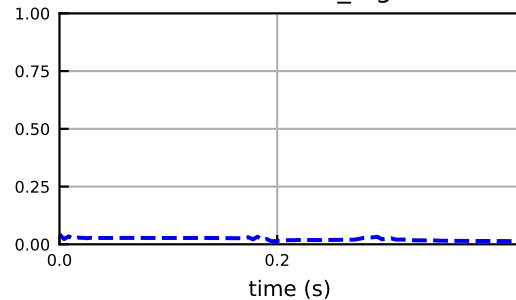
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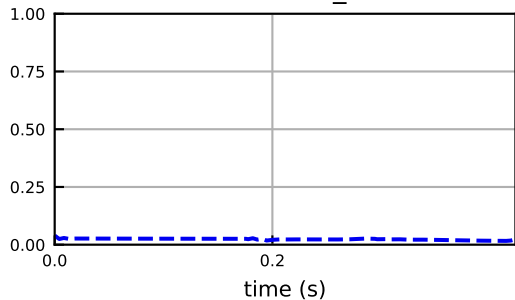
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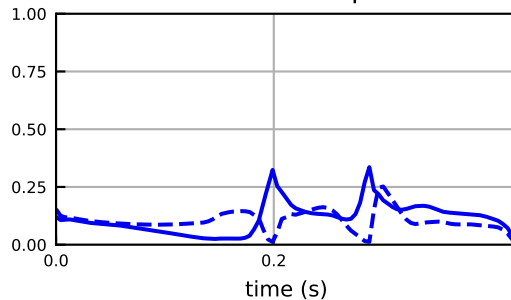
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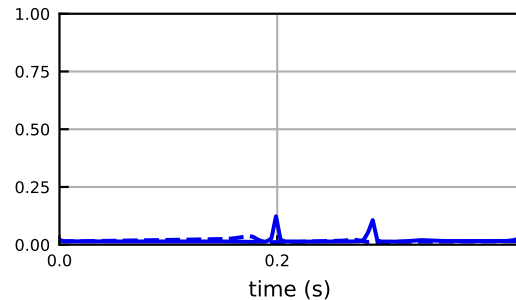
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forcesetercspn

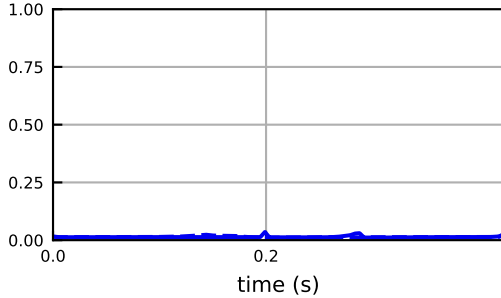


forcesetintobl

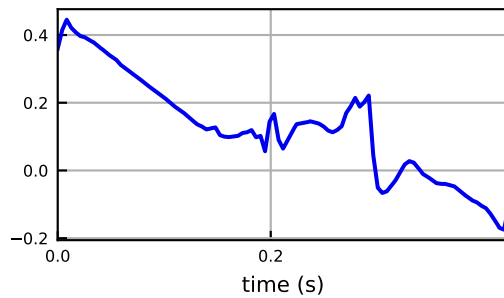


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- - - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30/solution.sto (left leg)

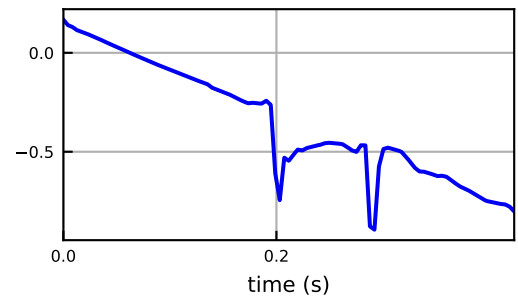
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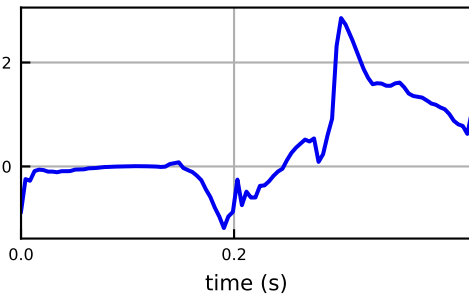
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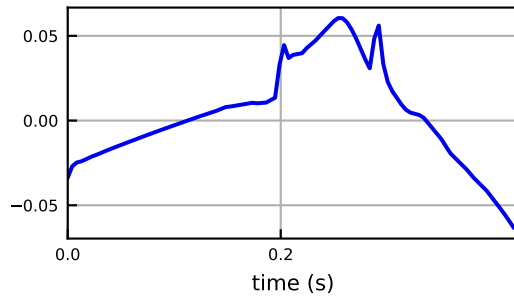
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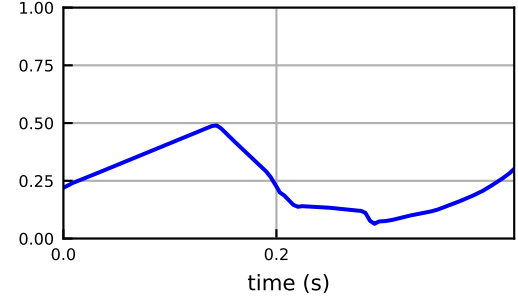
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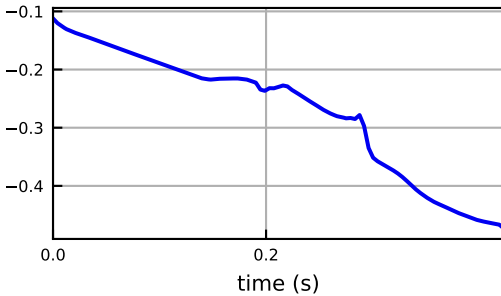
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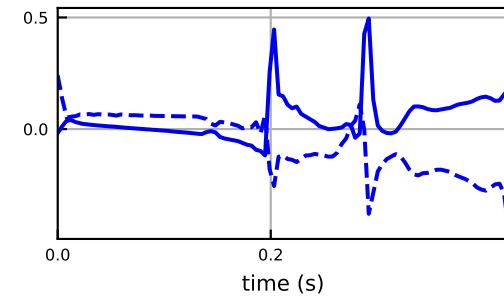
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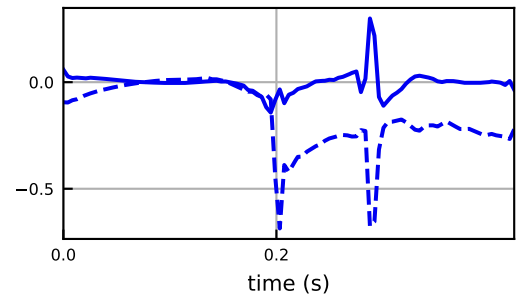
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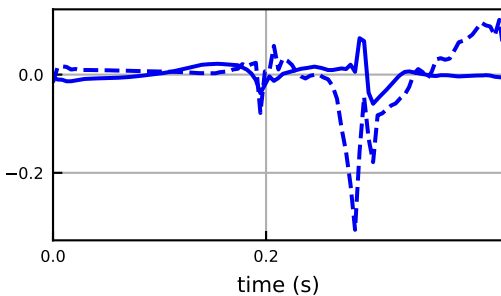
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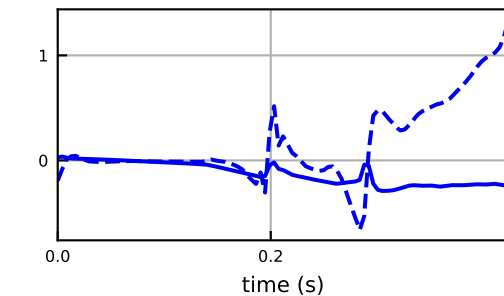
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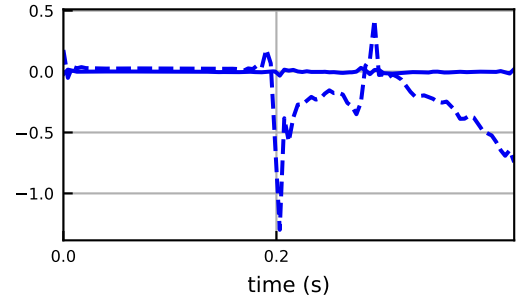
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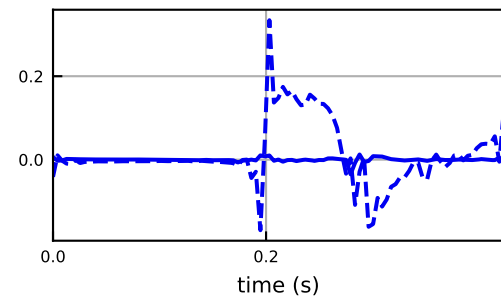
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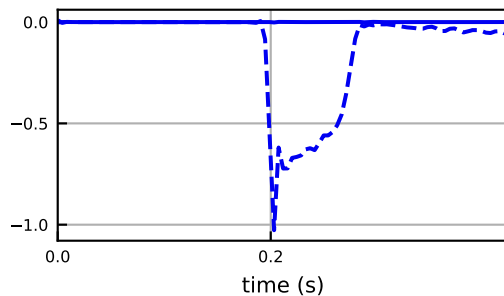
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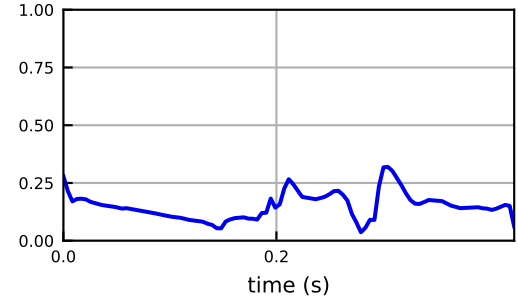
forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension



— D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30/solution.sto (right leg)
- - D:\Projects_MOCO\project_trunk\Results\predict_trunk_jrGoal_int100\ext_-30/solution.sto (left leg)

