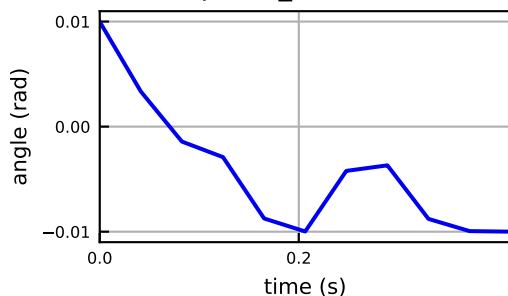
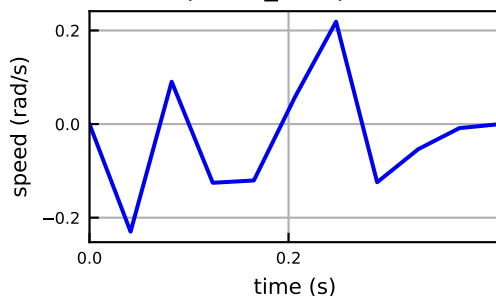


— D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (left leg)

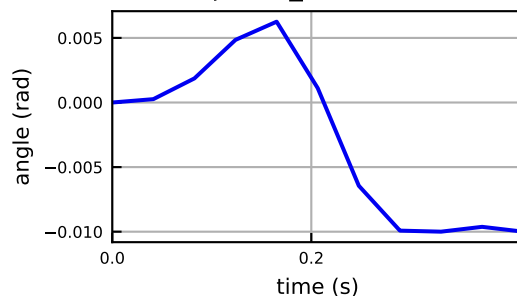
pelvis\_tilt/value



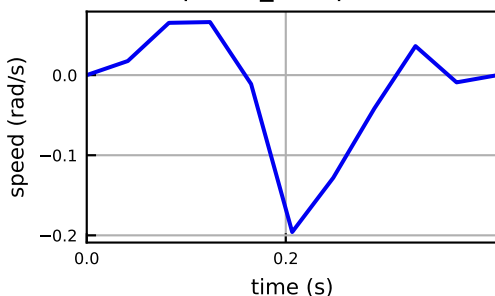
pelvis\_tilt/speed



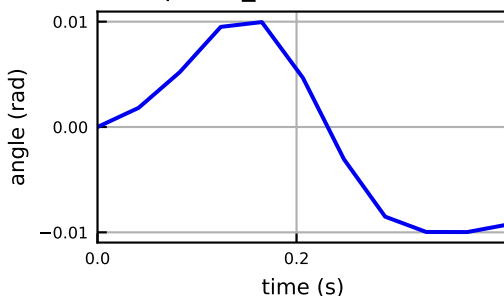
pelvis\_list/value



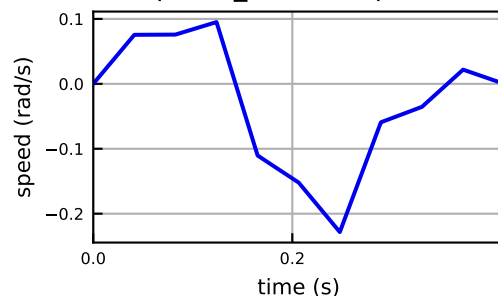
pelvis\_list/speed



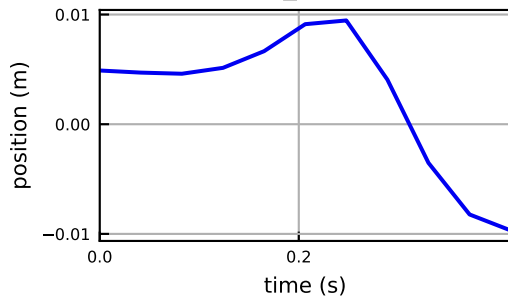
pelvis\_rotation/value



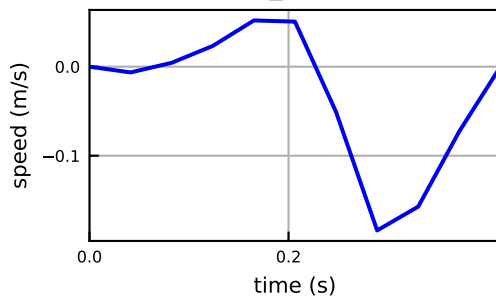
pelvis\_rotation/speed



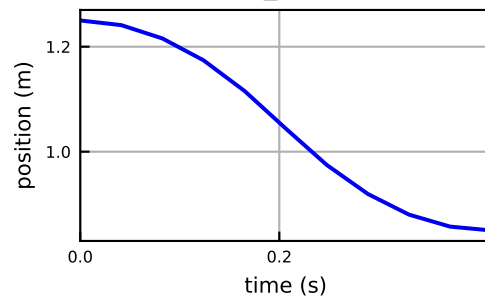
pelvis\_tx/value



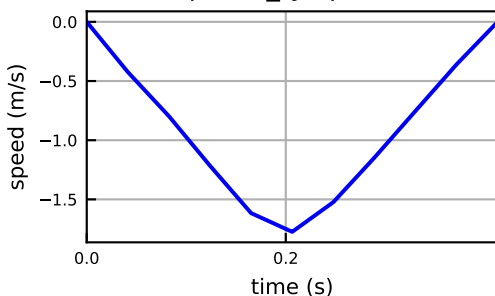
pelvis\_tx/speed



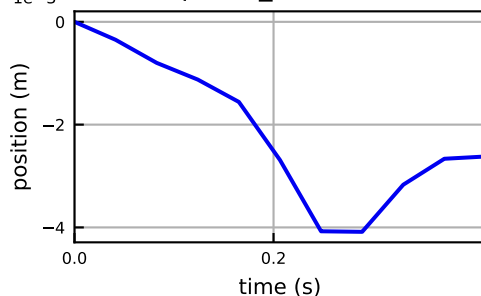
pelvis\_ty/value



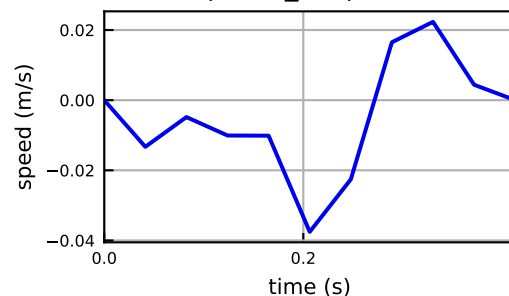
pelvis\_ty/speed



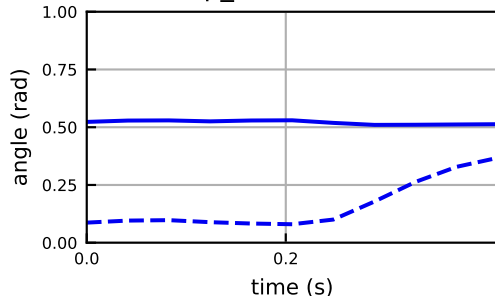
pelvis\_tz/value



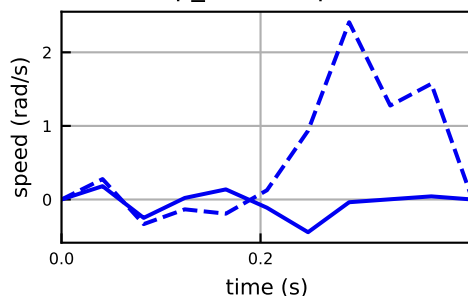
pelvis\_tz/speed



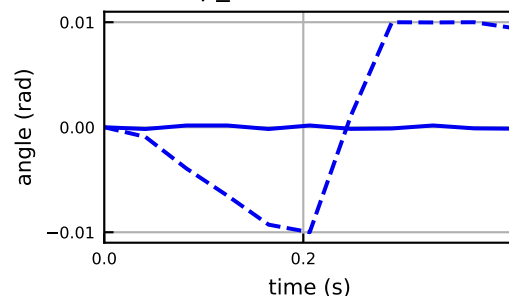
hip\_flexion/value



hip\_flexion/speed

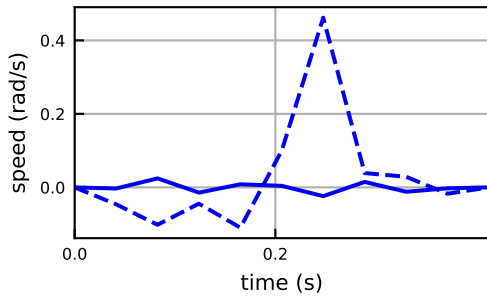


hip\_adduction/value

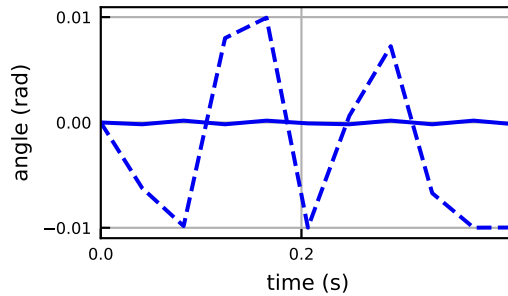


— D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (left leg)

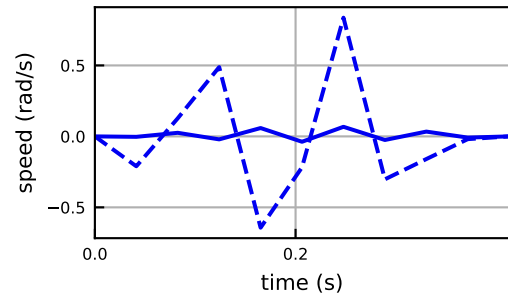
hip\_adduction/speed



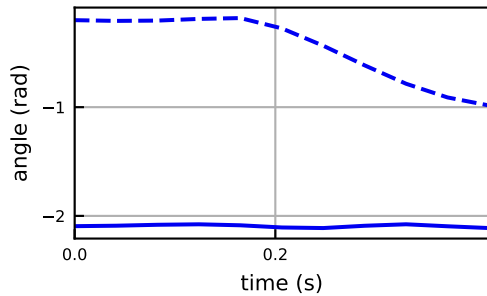
hip\_rotation/value



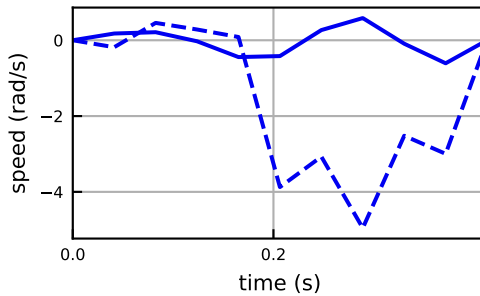
hip\_rotation/speed



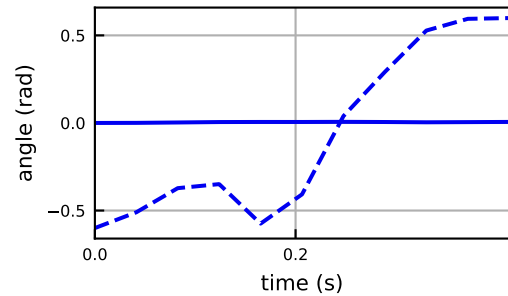
knee\_angle/value



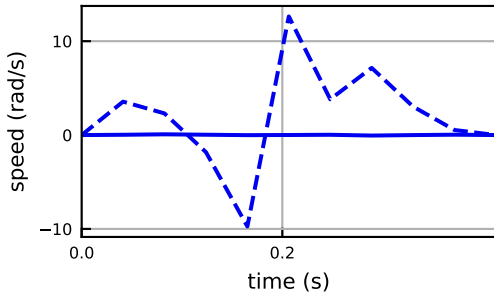
knee\_angle/speed



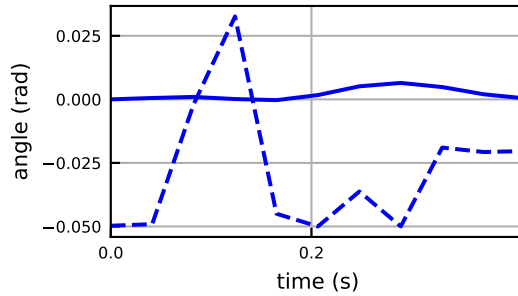
ankle\_angle/value



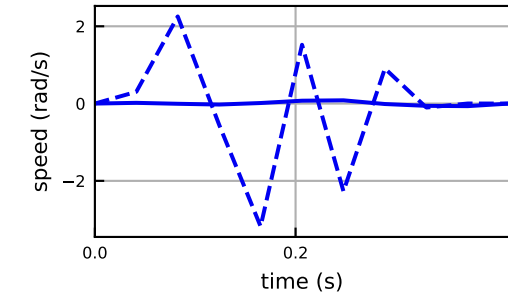
ankle\_angle/speed



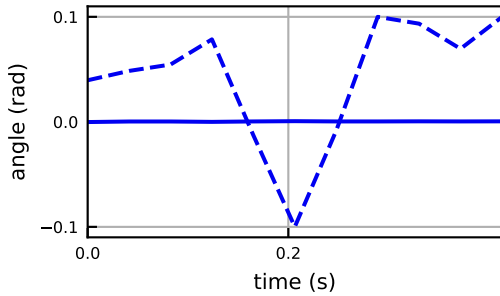
subtalar\_angle/value



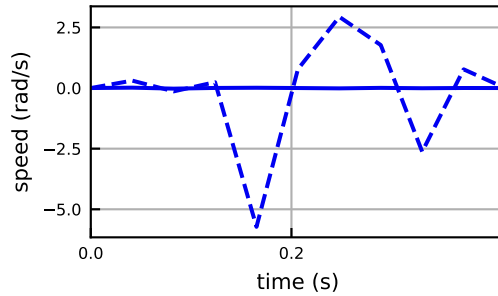
subtalar\_angle/speed



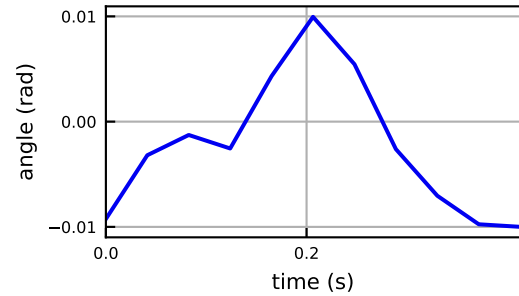
mtp\_angle/value



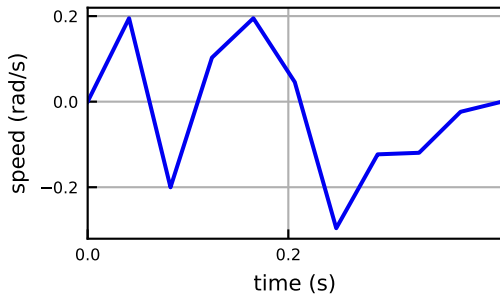
mtp\_angle/speed



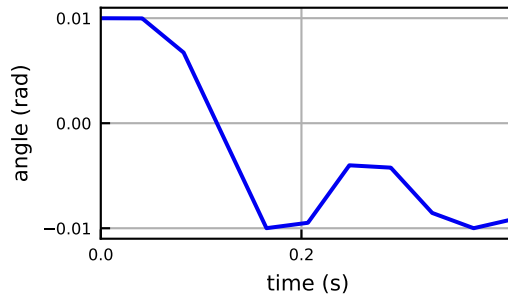
lumbar\_extension/value



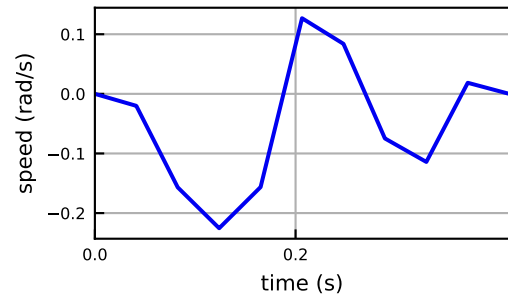
lumbar\_extension/speed



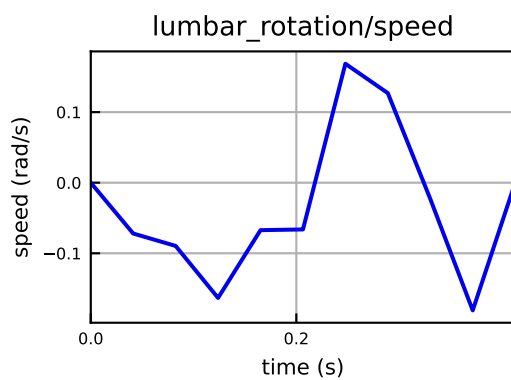
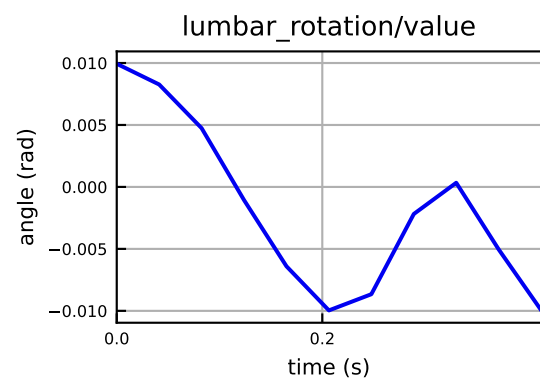
lumbar\_bending/value



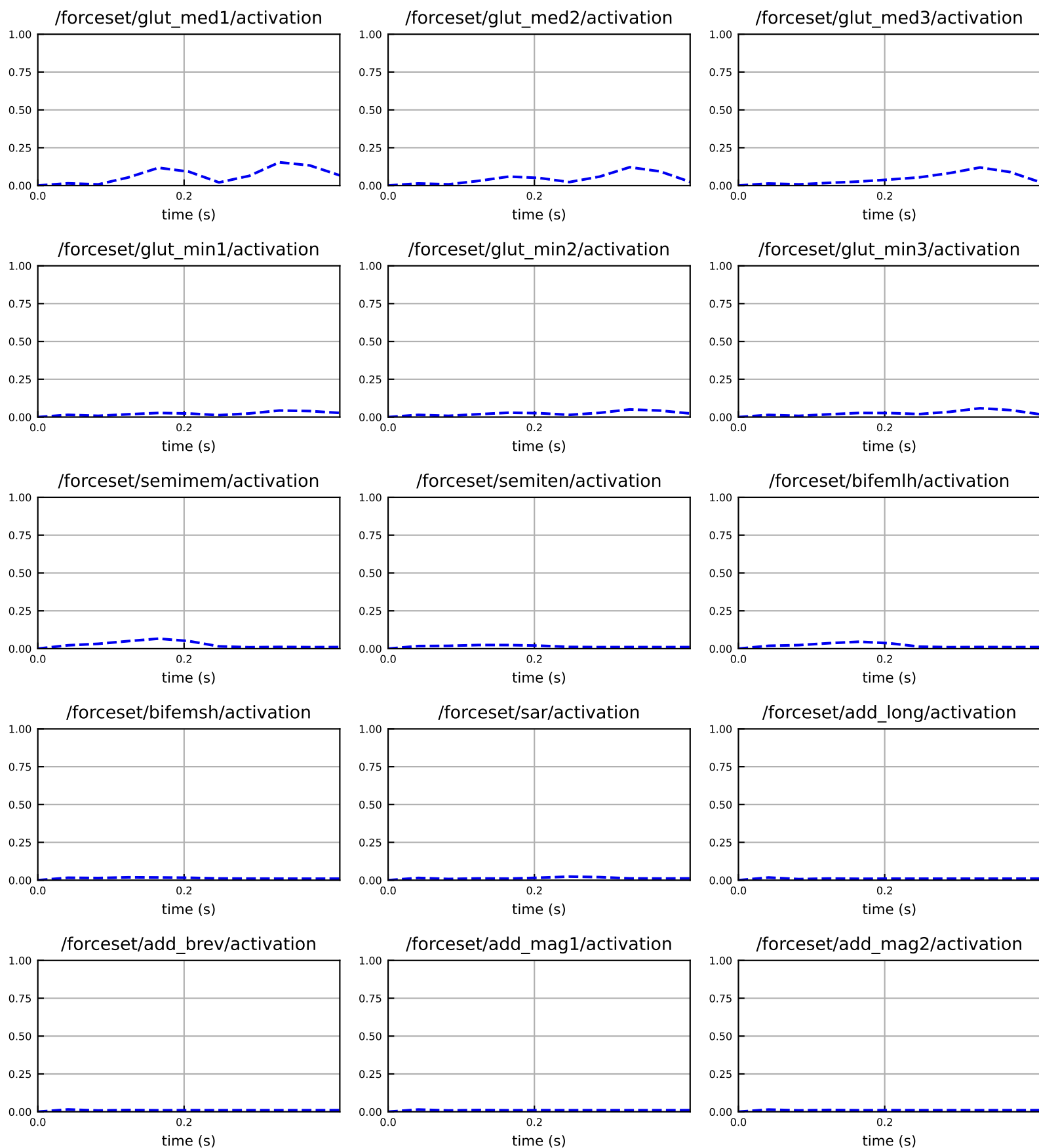
lumbar\_bending/speed



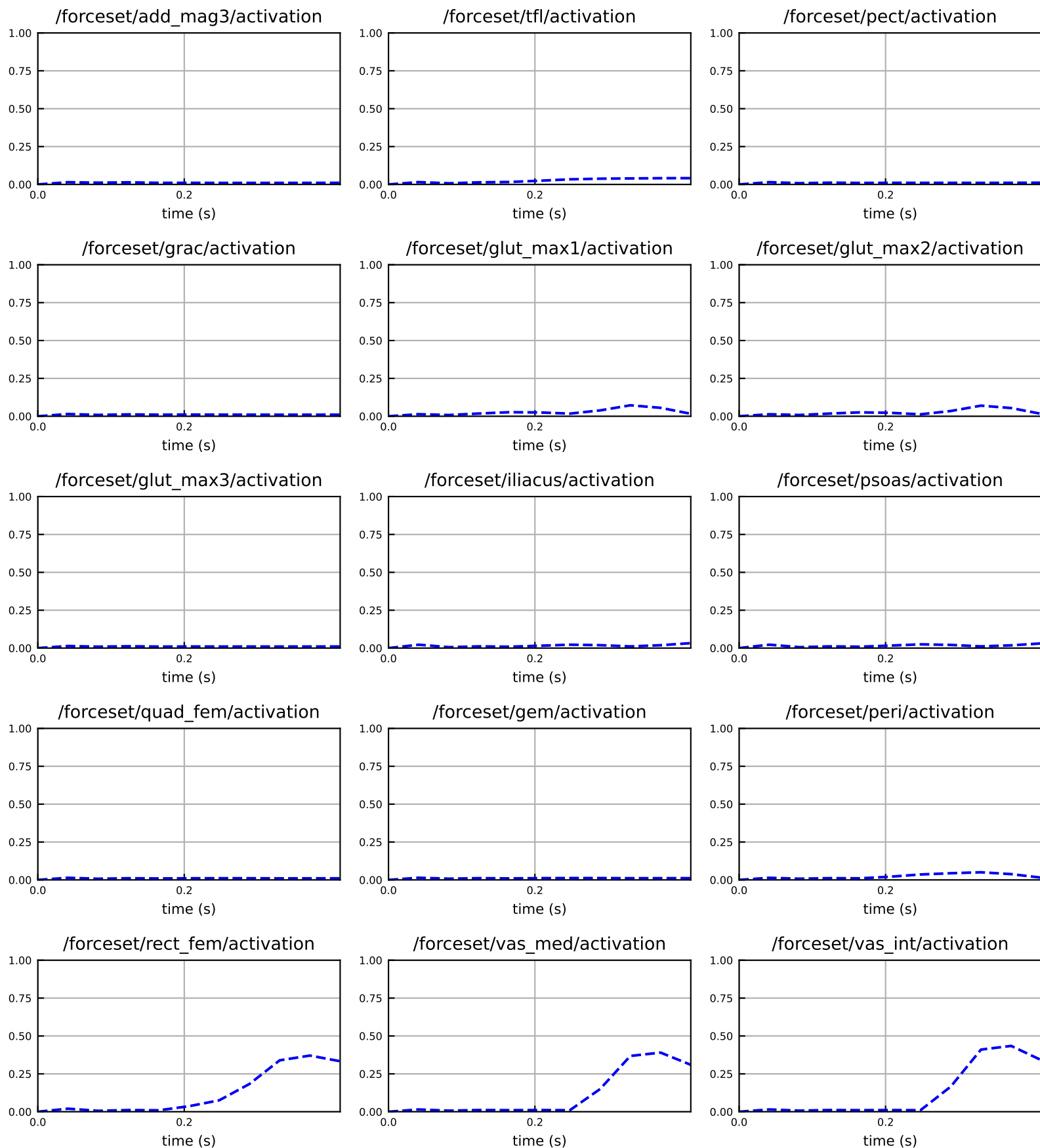
— D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (left leg)



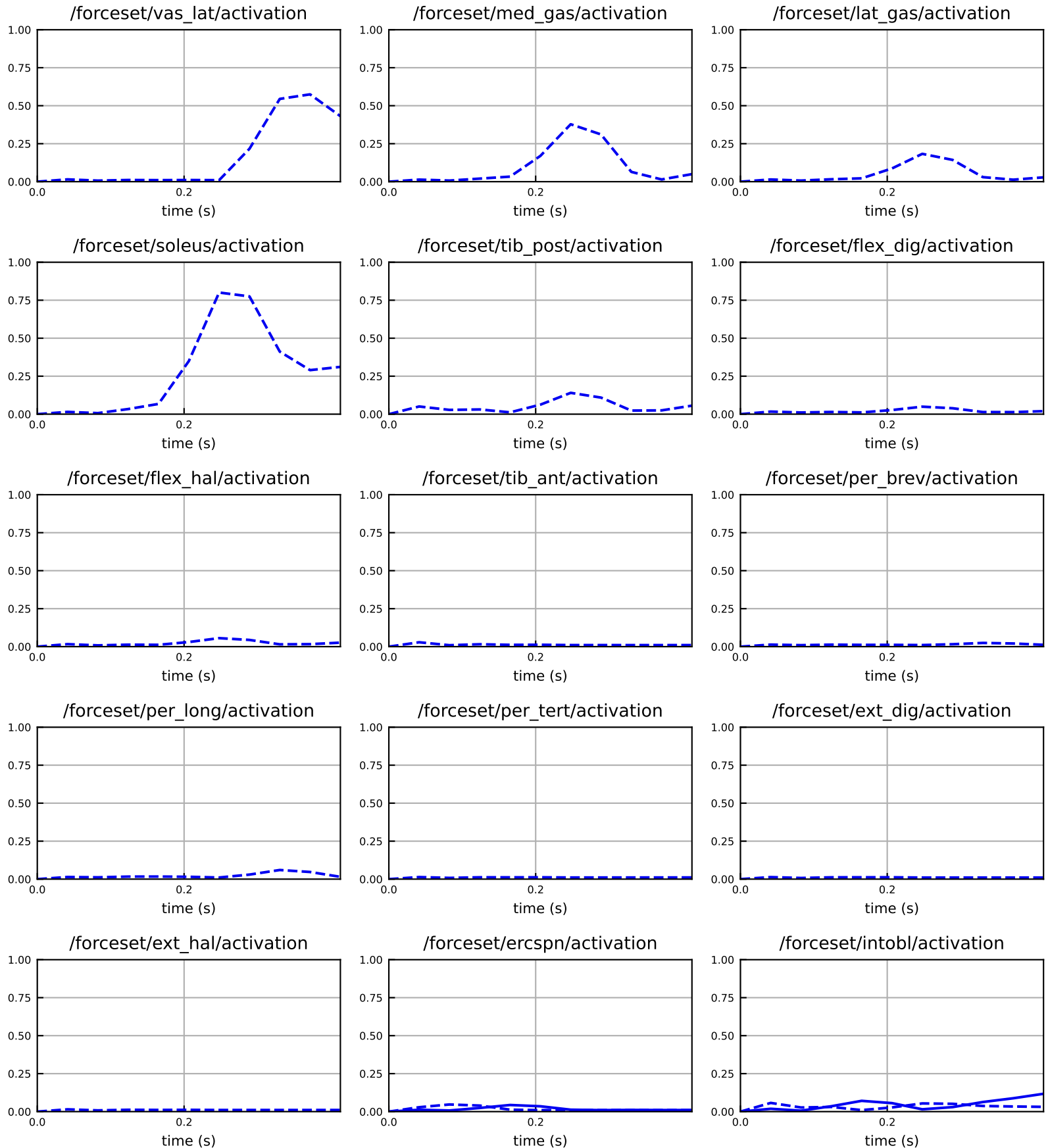
— D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (left leg)

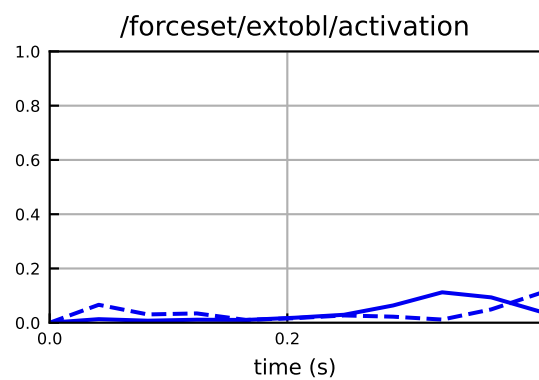
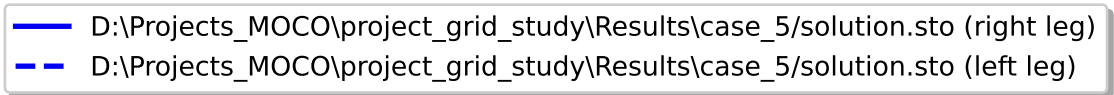


— D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (left leg)



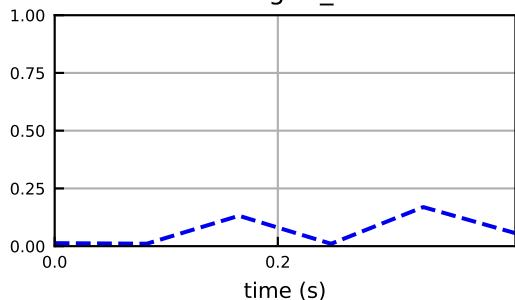
— D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (left leg)



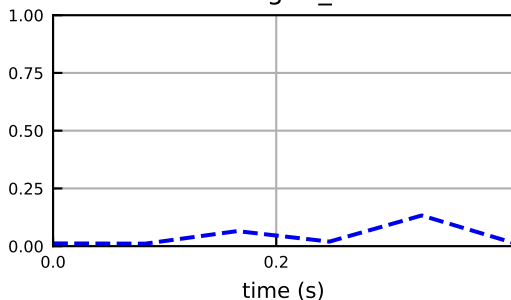


— D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (left leg)

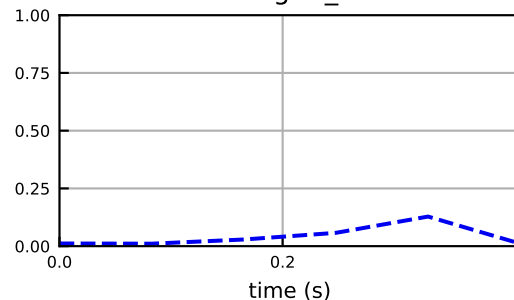
forcesetglut\_med1



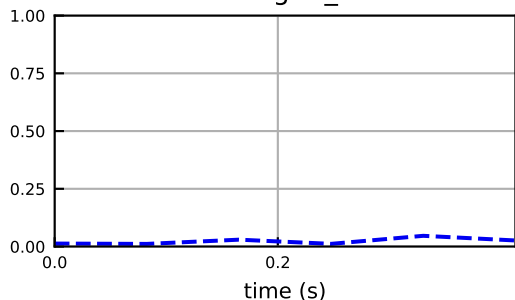
forcesetglut\_med2



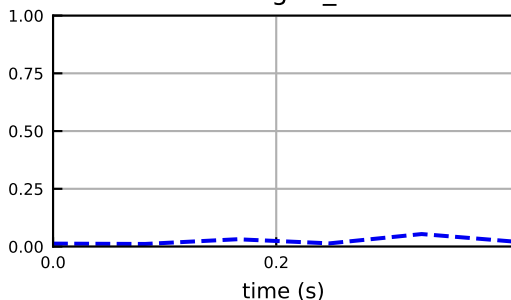
forcesetglut\_med3



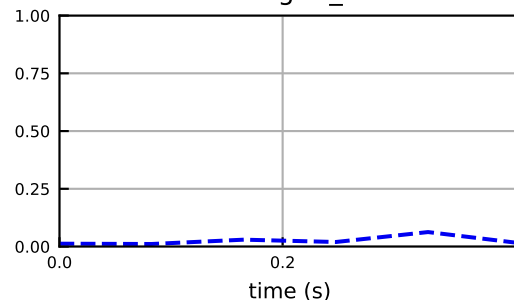
forcesetglut\_min1



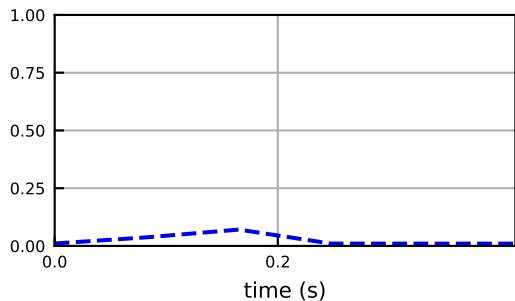
forcesetglut\_min2



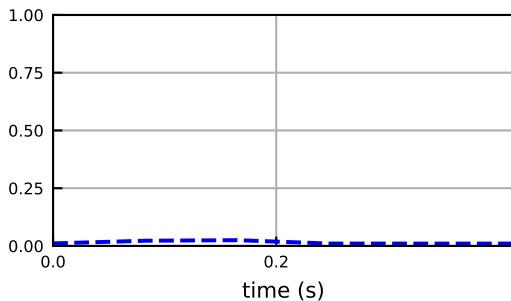
forcesetglut\_min3



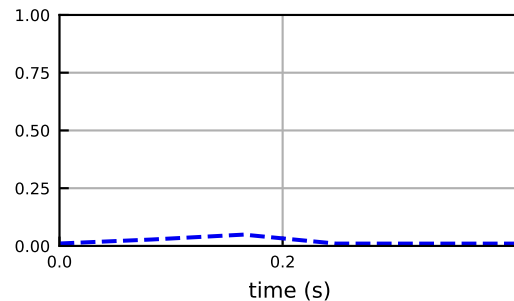
forcesetsemimem



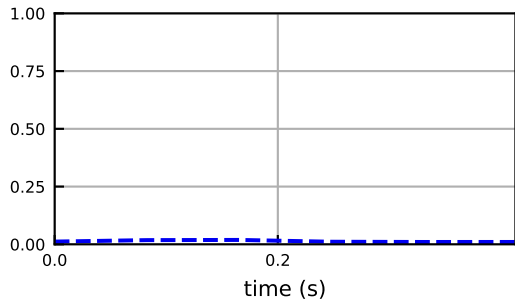
forcesetsemiten



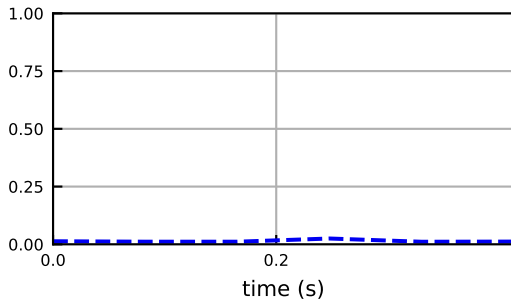
forcesetbifemlh



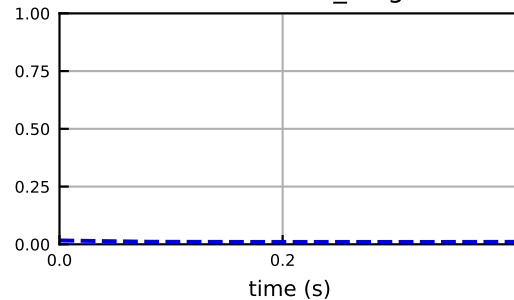
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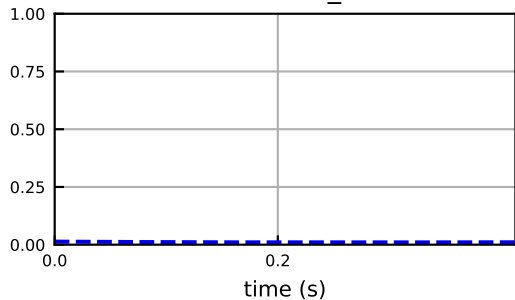
forcesetsar



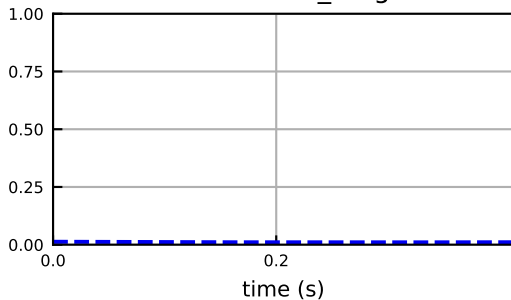
forcesetadd\_long



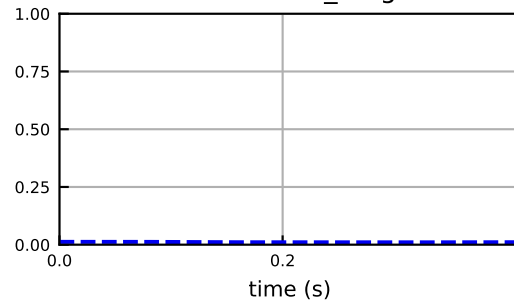
forcesetadd\_brev



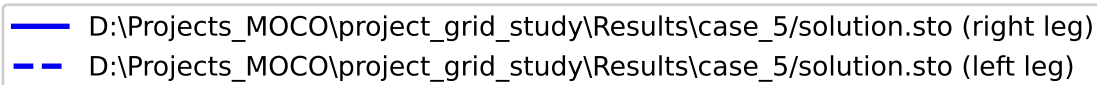
forcesetadd\_mag1



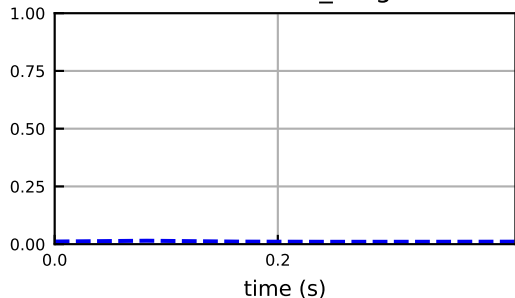
forcesetadd\_mag2



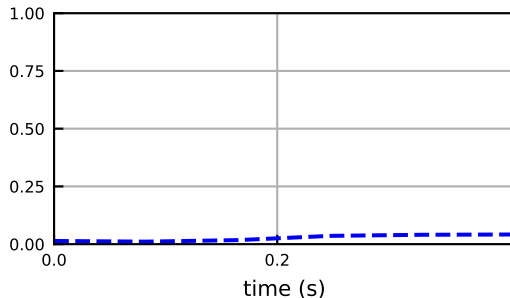




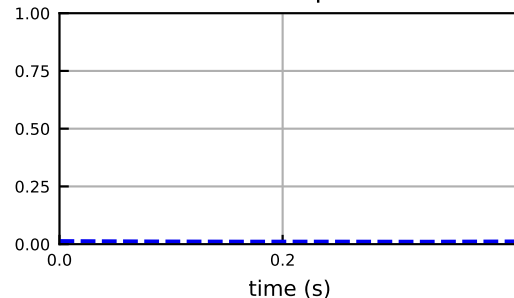
forcesetadd\_mag3



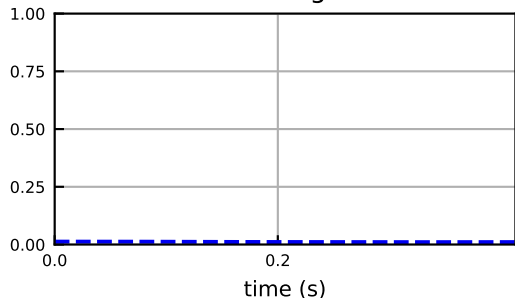
forcesetttfl



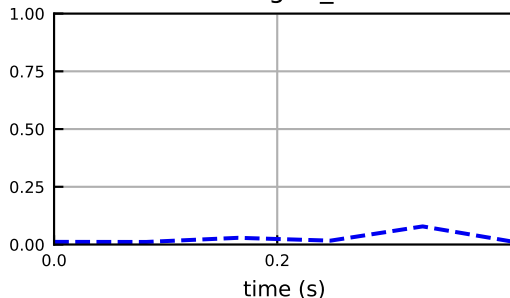
forcesetpect



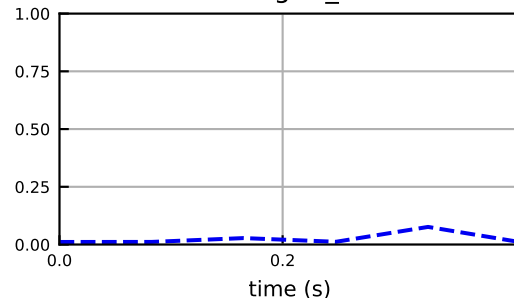
forcesetgrac



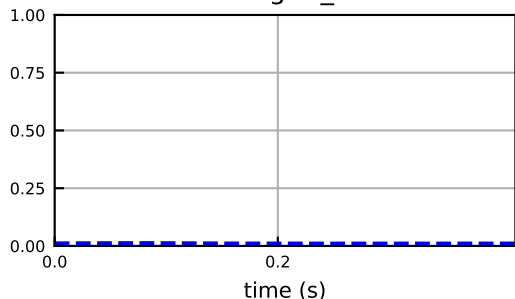
forcesetglut\_max1



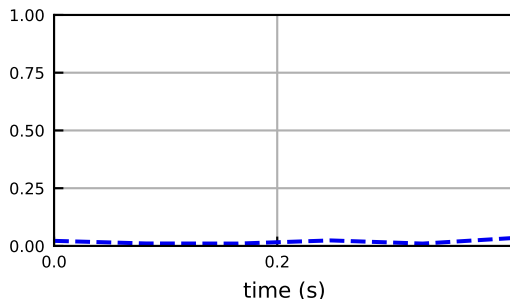
forcesetglut\_max2



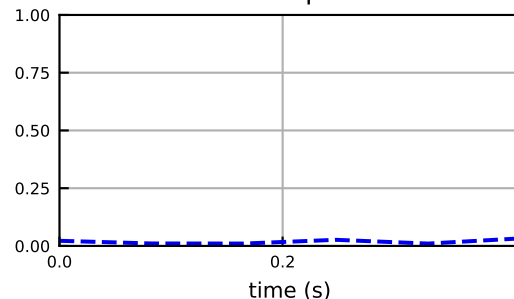
forcesetglut\_max3



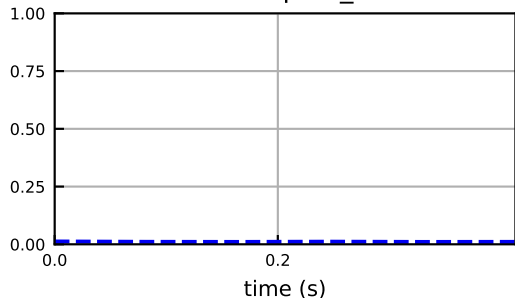
forcesetiliacus



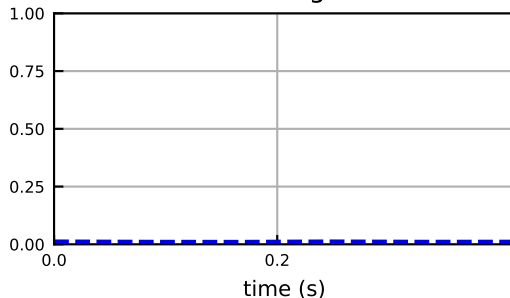
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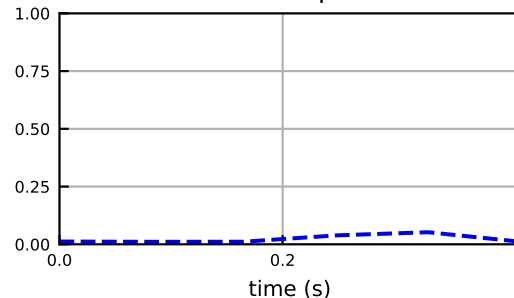
forcesetquad\_fem



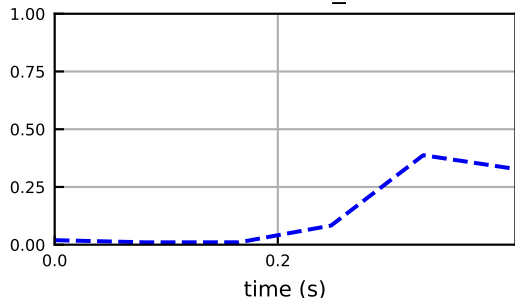
forcesetgem



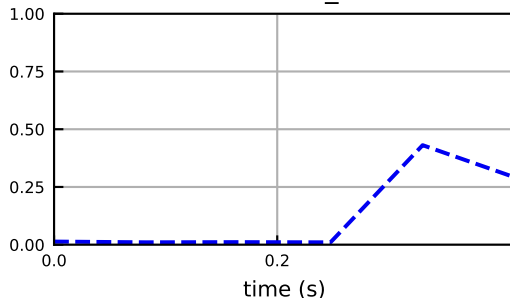
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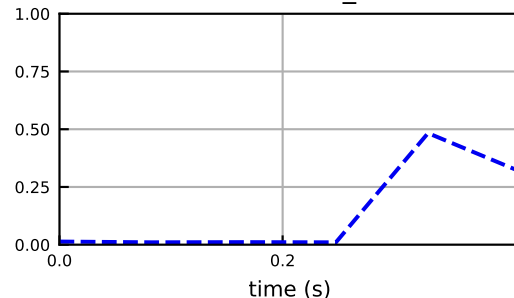
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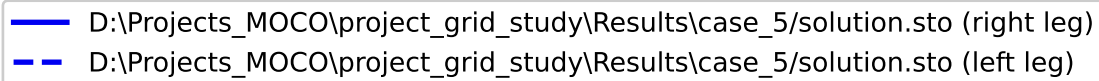


forcesetvas\_med

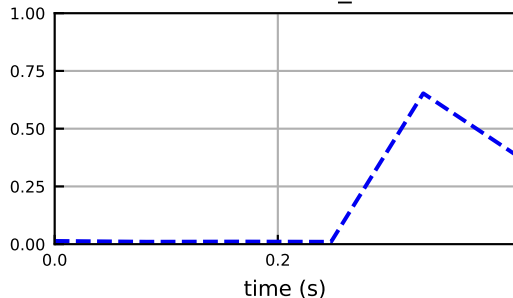


forcesetvas\_int

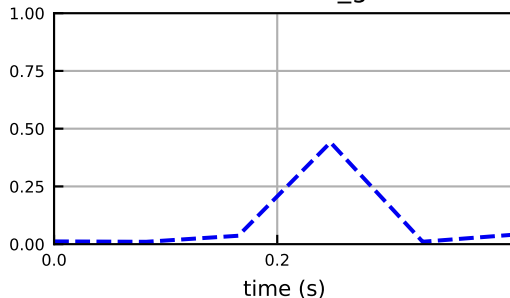




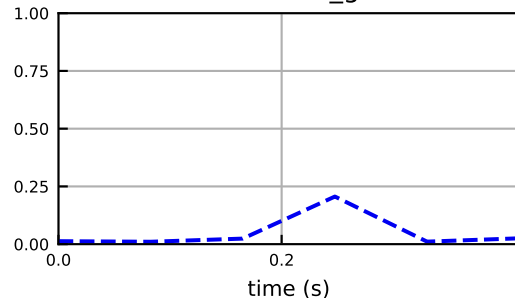
forcesetvas\_lat



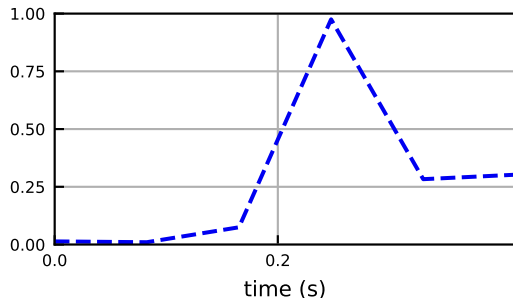
forcesetmed\_gas



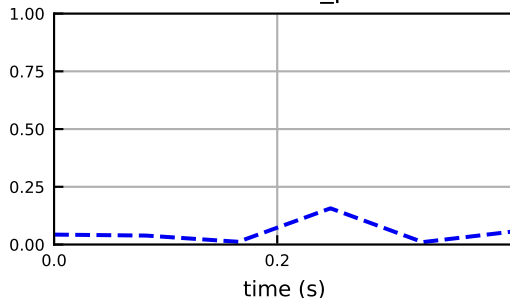
forcesetlat\_gas



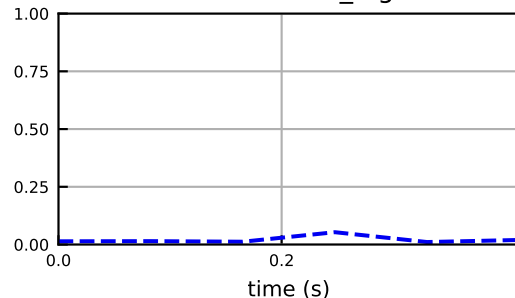
forcesetsoleus



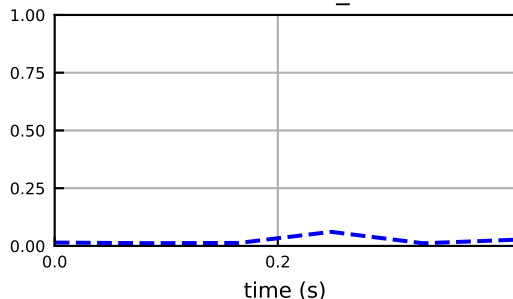
forcesettib\_post



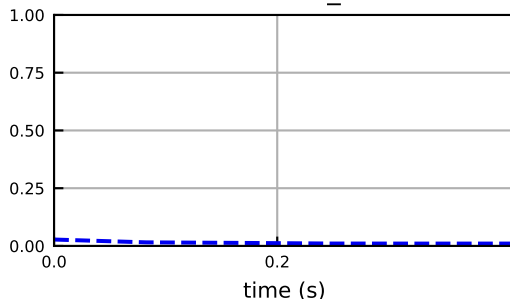
forcesetflex\_dig



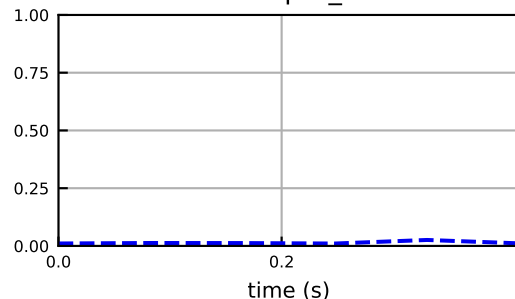
forcesetflex\_hal



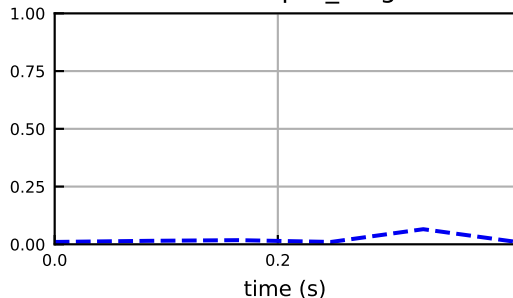
forcesettib\_ant



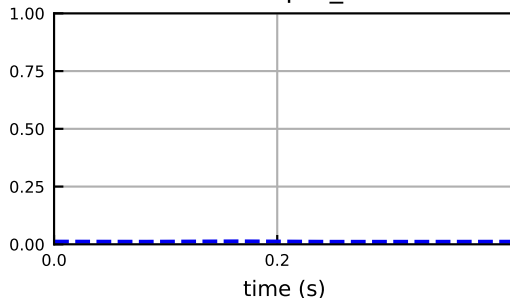
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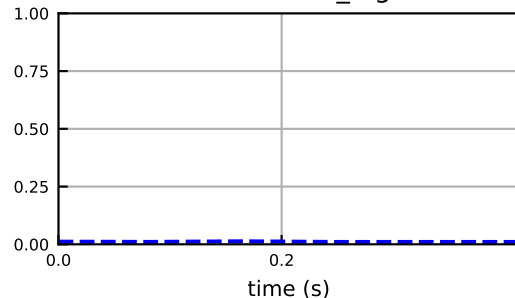
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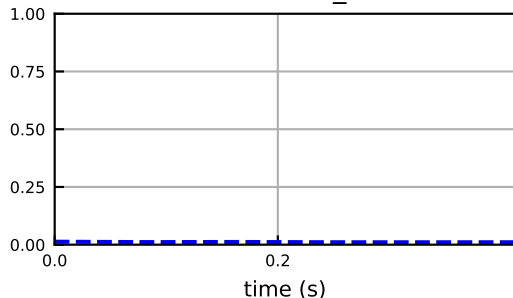
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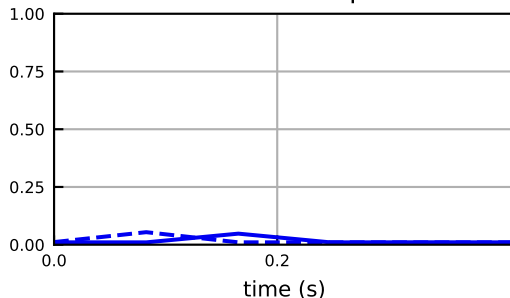
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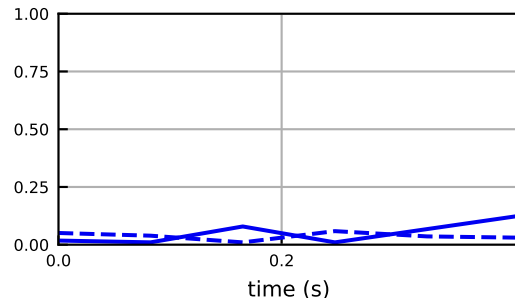
forcesetext\_hal



forcesetercspn

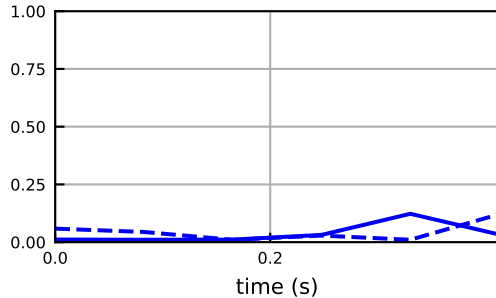


forcesetintobl

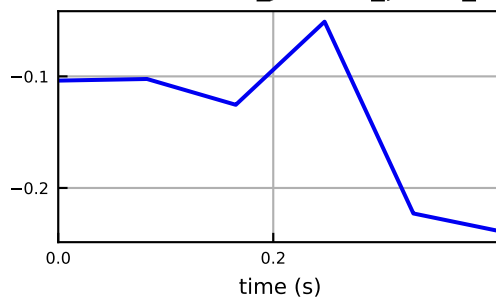


— D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_grid\_study\Results\case\_5\solution.sto (left leg)

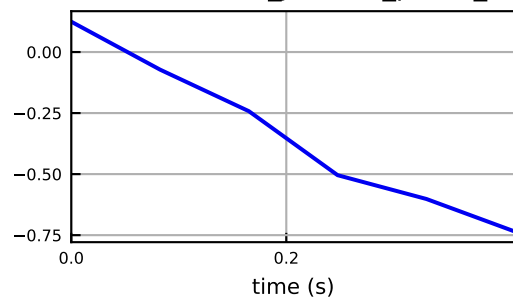
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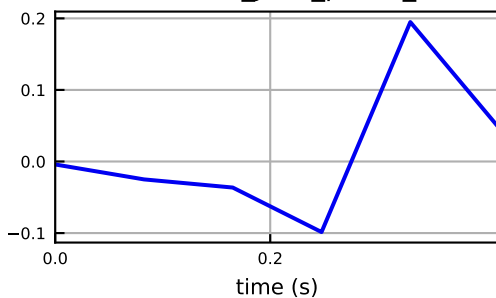
forcesetreserve\_joi...lvis\_pelvis\_tilt



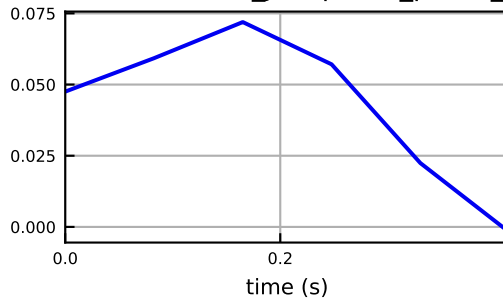
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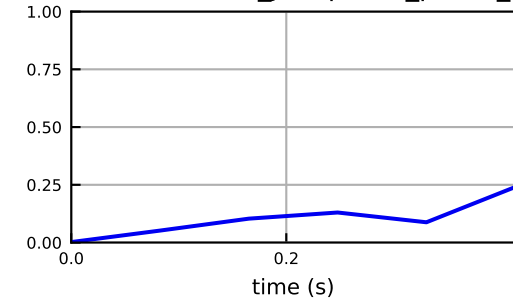
forcesetreserve\_joi...pelvis\_rotation



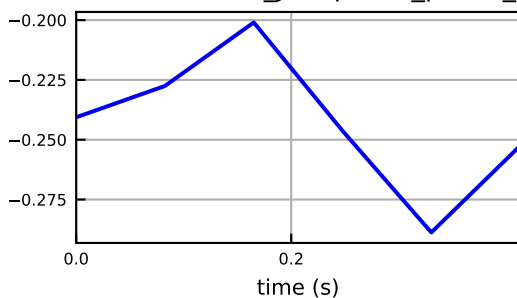
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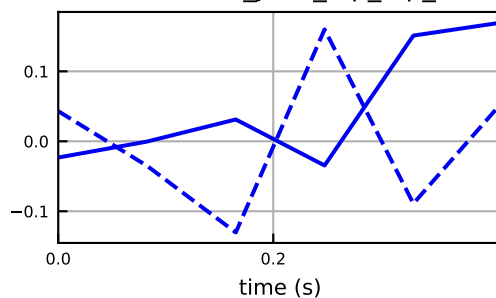
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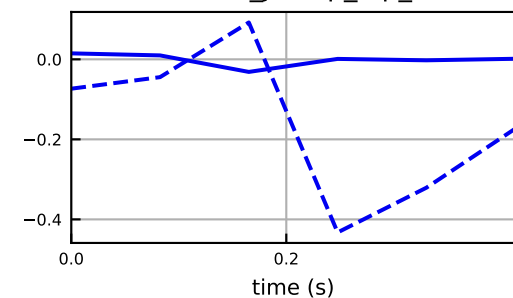
forcesetreserve\_joi...pelvis\_pelvis\_tz



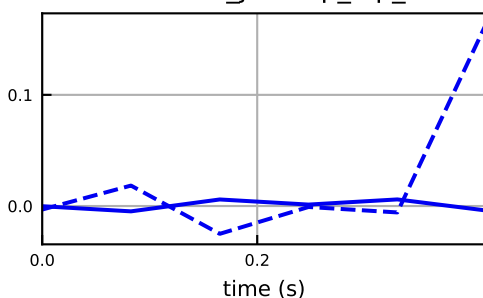
forcesetreserve\_joi...hip\_hip\_flexion



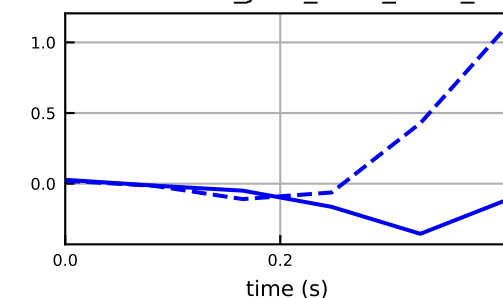
forcesetreserve\_joi...ip\_hip\_adduction



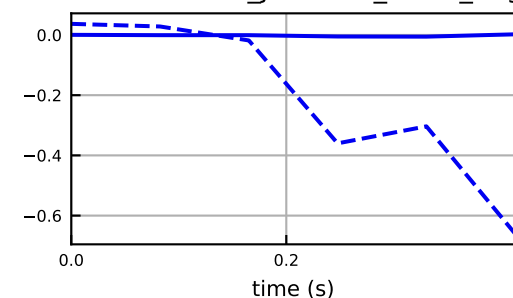
forcesetreserve\_joi...hip\_hip\_rotation



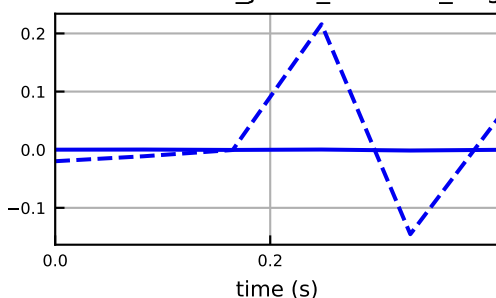
forcesetreserve\_joi...knee\_knee\_angle



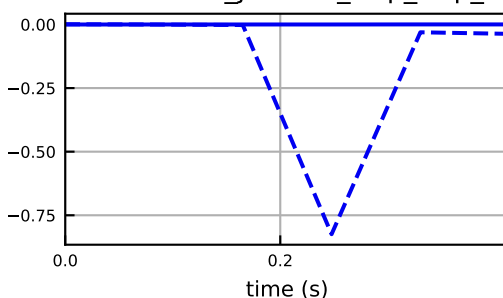
forcesetreserve\_joi...nkle\_ankle\_angle



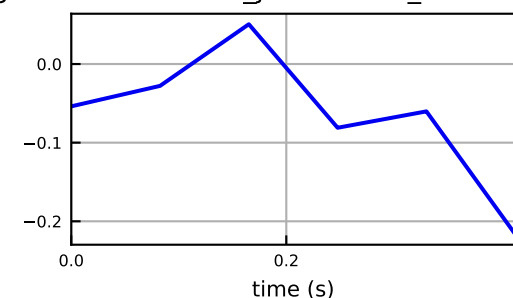
forcesetreserve\_joi...r\_subtalar\_angle

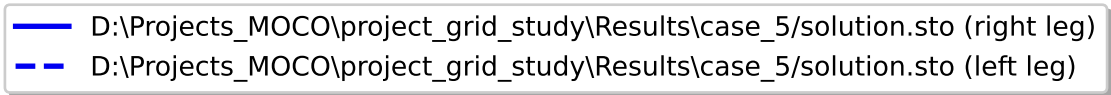


forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension





forcesetreserve\_joi...k\_lumbar\_bending    forcesetreserve\_joi...\_lumbar\_rotation

