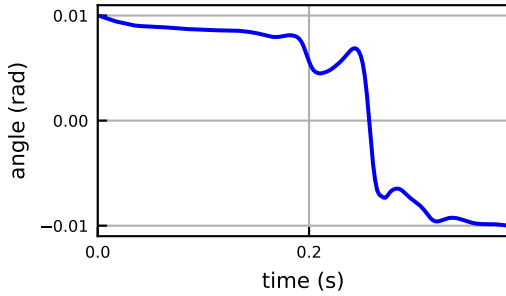
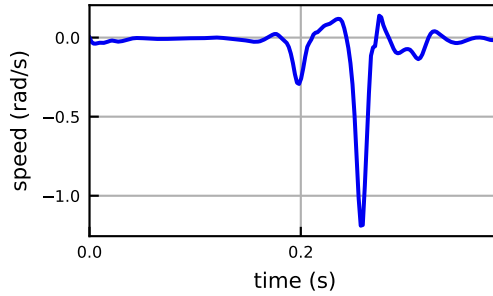


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100\solution.sto (left leg)

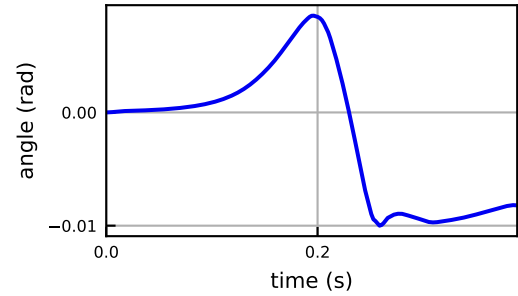
pelvis\_tilt/value



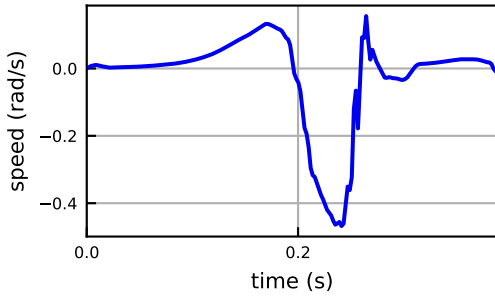
pelvis\_tilt/speed



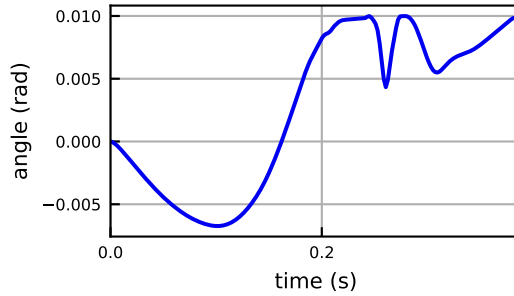
pelvis\_list/value



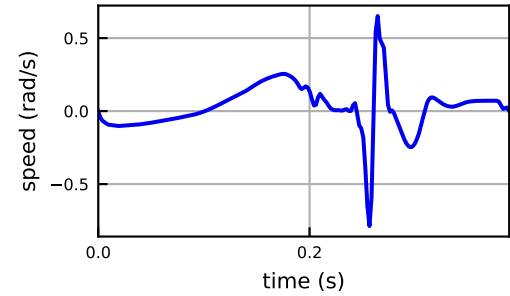
pelvis\_list/speed



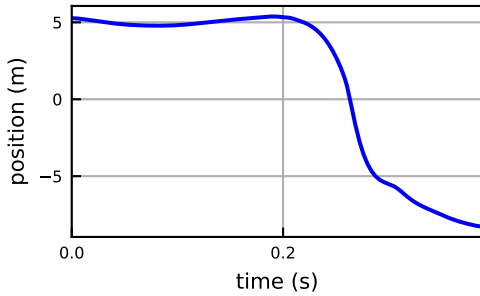
pelvis\_rotation/value



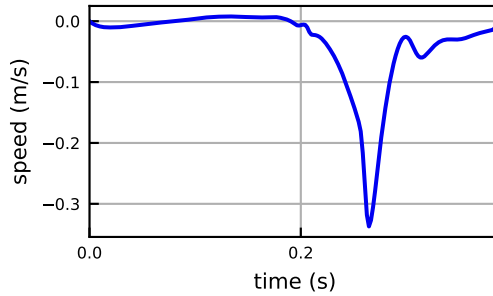
pelvis\_rotation/speed



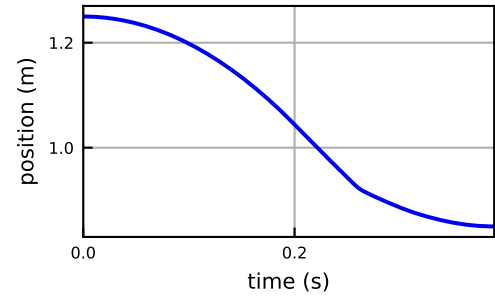
pelvis\_tx/value



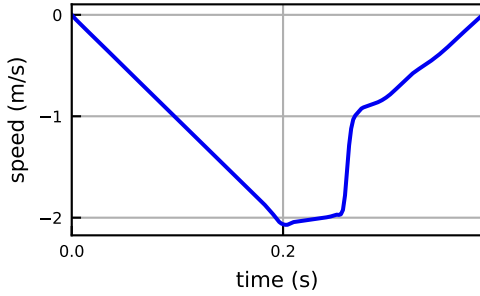
pelvis\_tx/speed



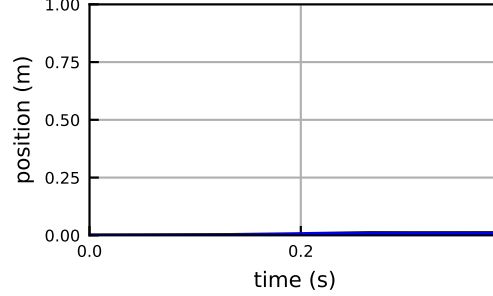
pelvis\_ty/value



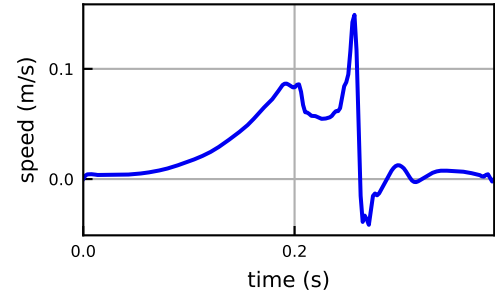
pelvis\_ty/speed



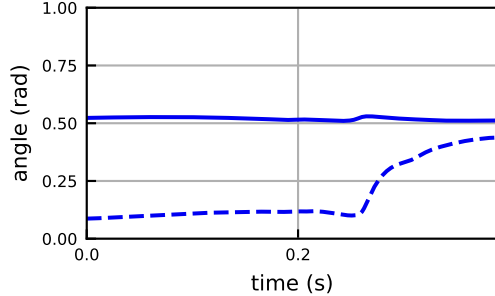
pelvis\_tz/value



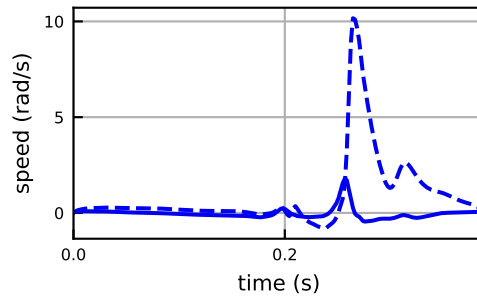
pelvis\_tz/speed



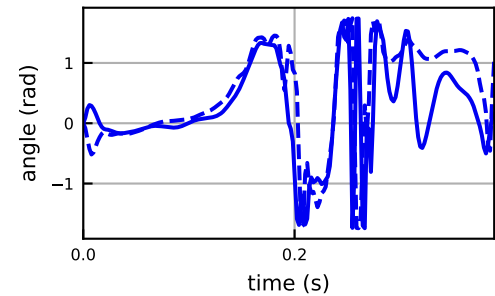
hip\_flexion/value



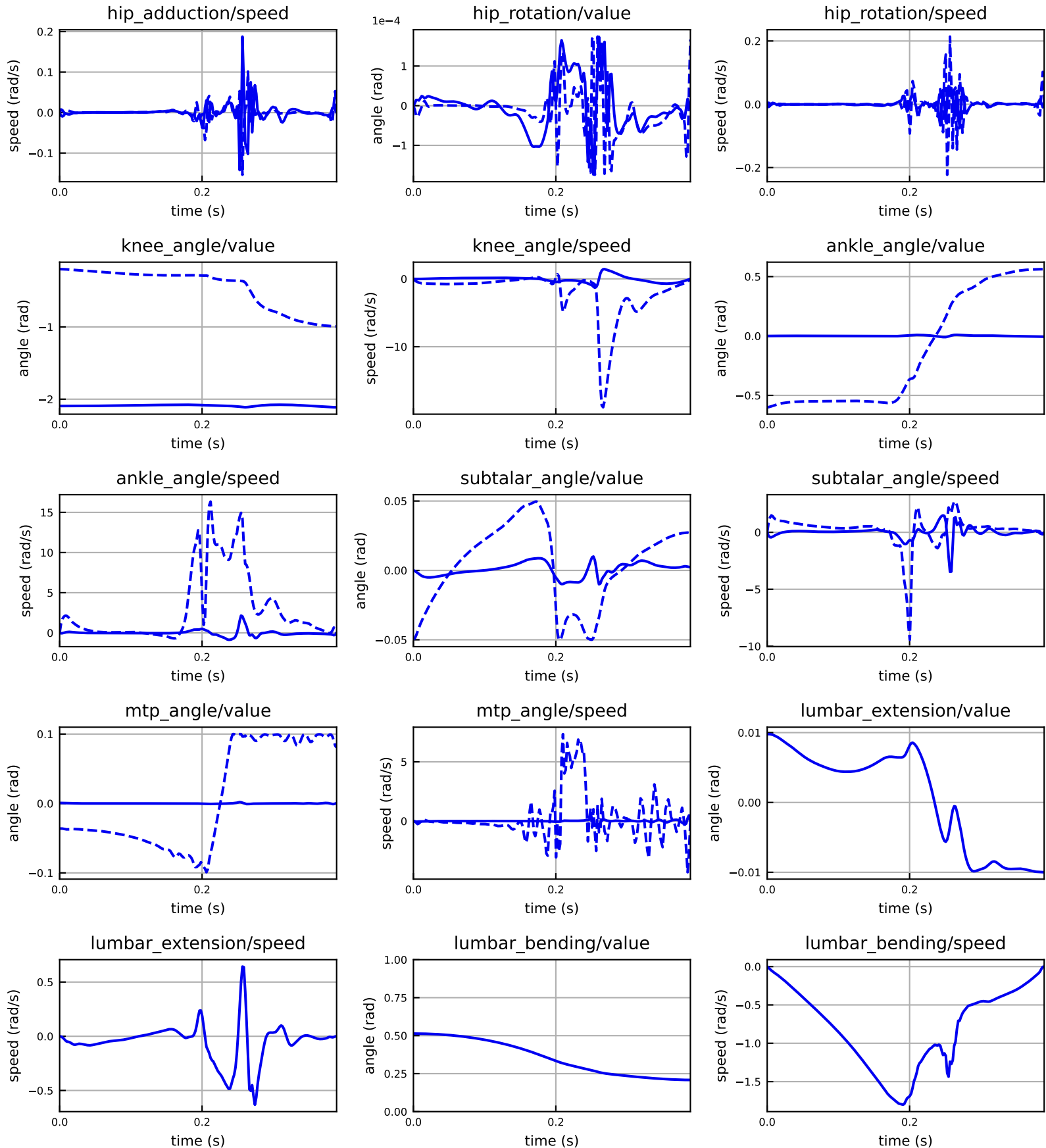
hip\_flexion/speed

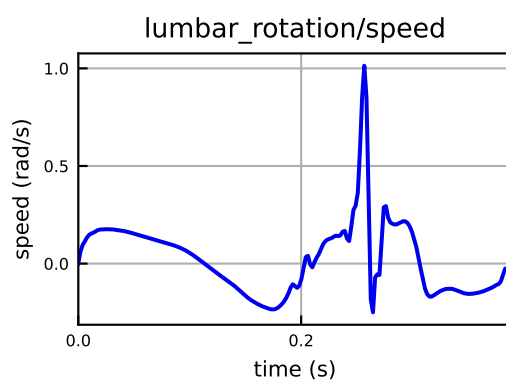
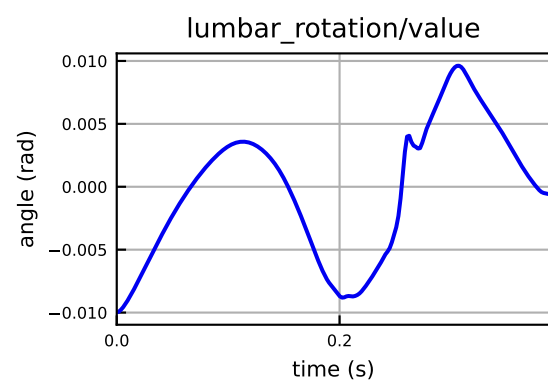
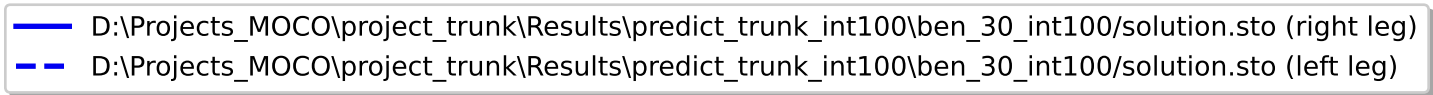


hip\_adduction/value

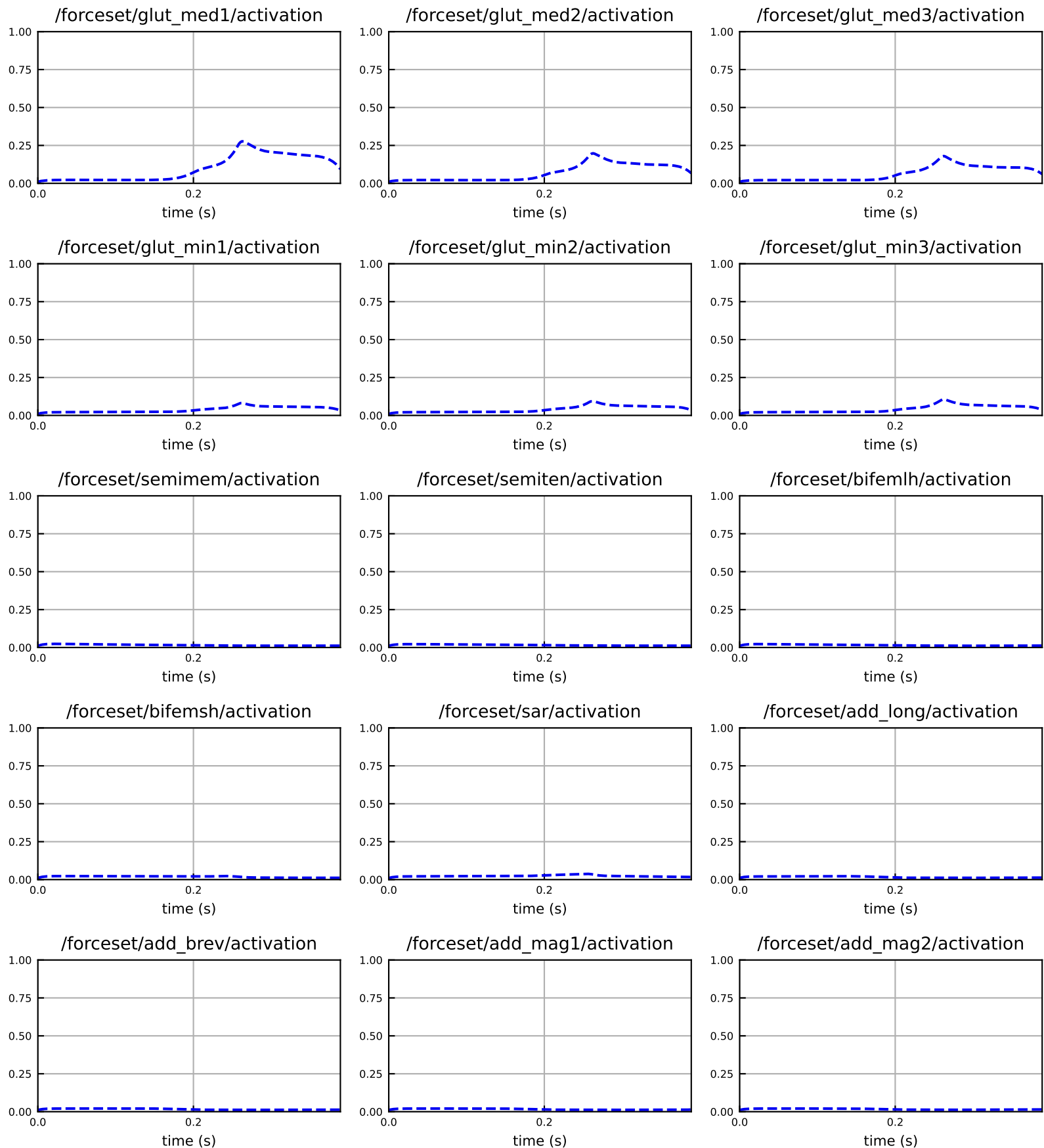


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100\solution.sto (left leg)

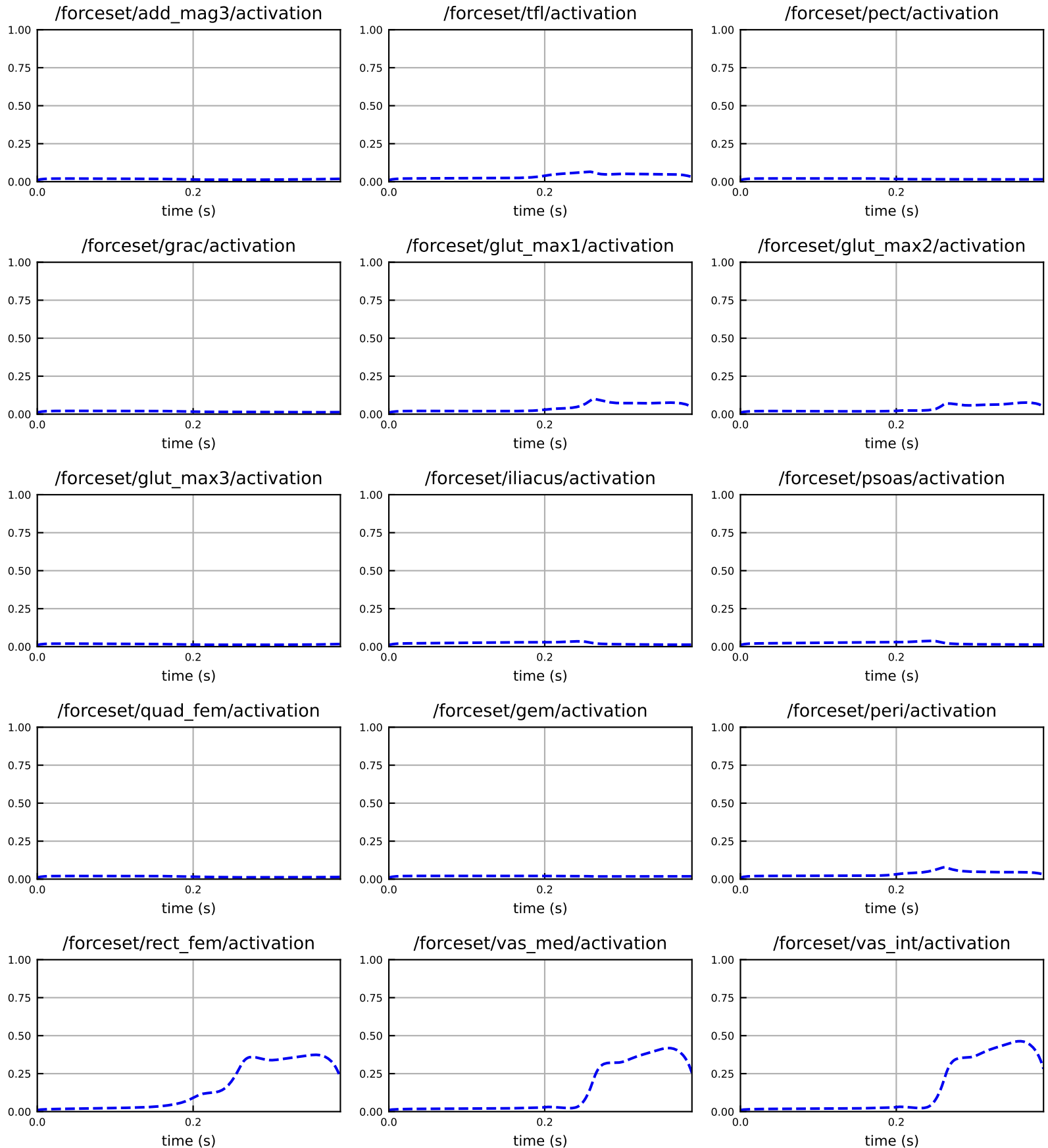


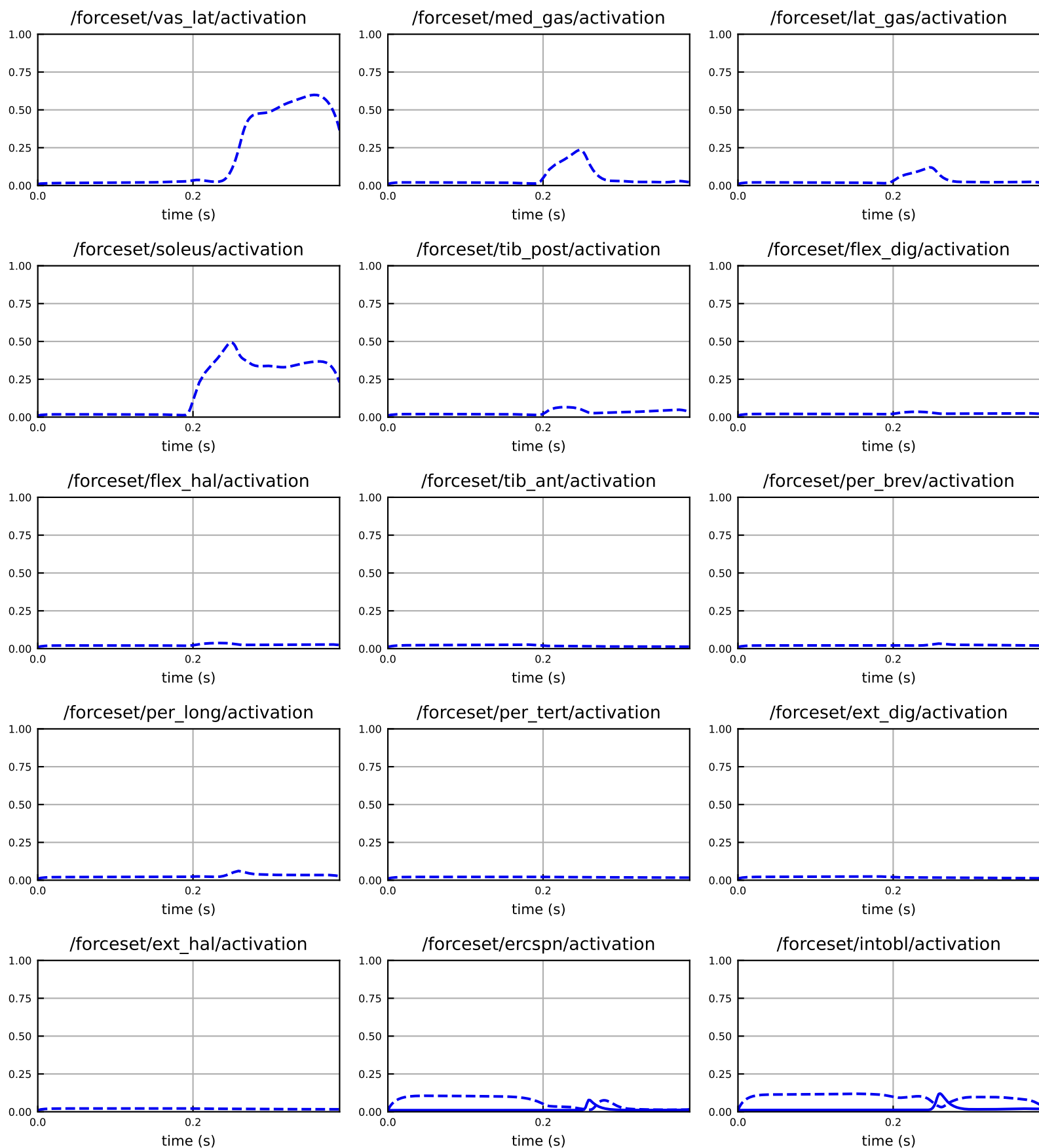
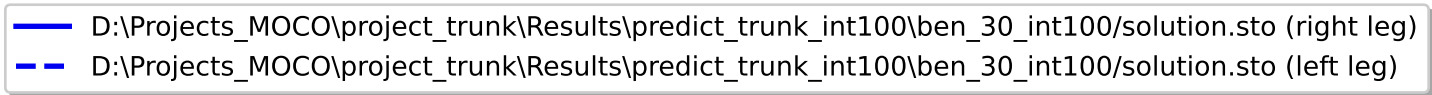


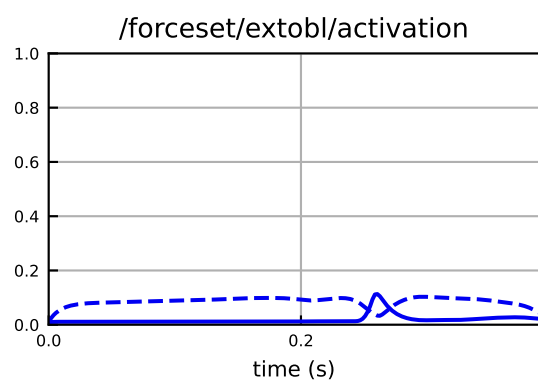
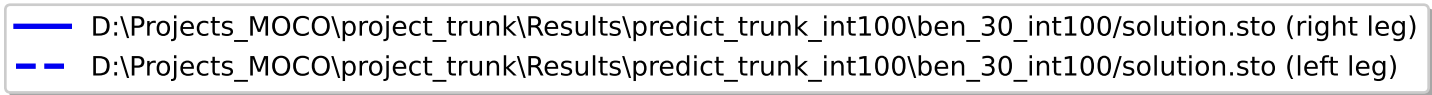
— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100\solution.sto (left leg)



— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100\solution.sto (right leg)  
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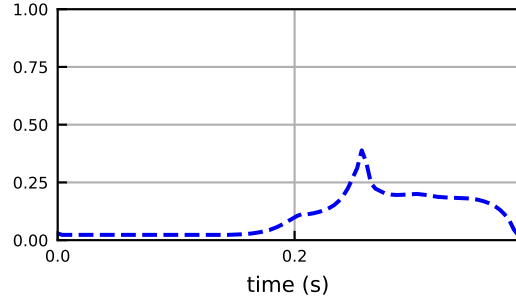




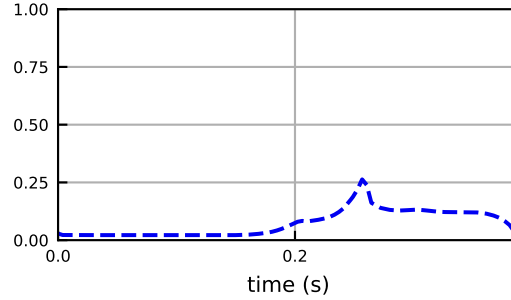


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100/solution.sto (right leg)  
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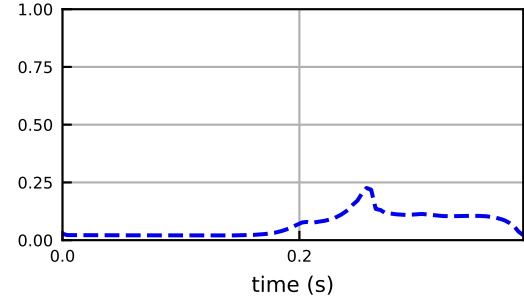
forcesetglut\_med1



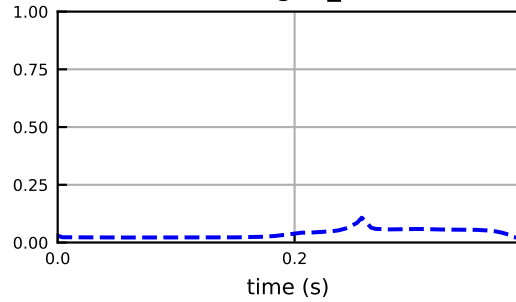
forcesetglut\_med2



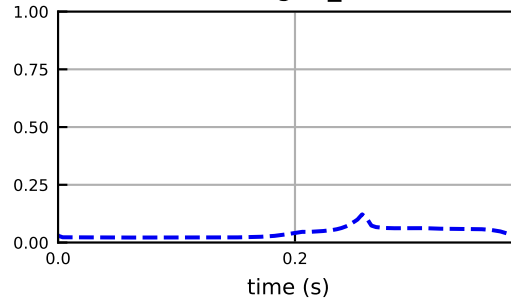
forcesetglut\_med3



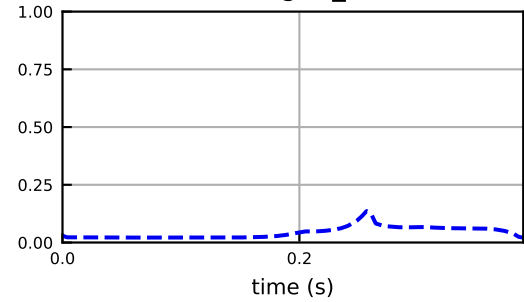
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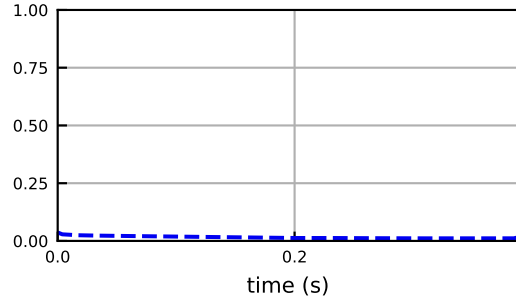
forcesetglut\_min2



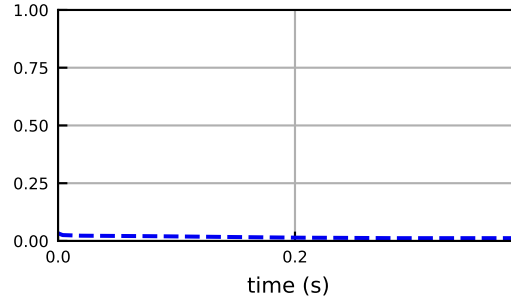
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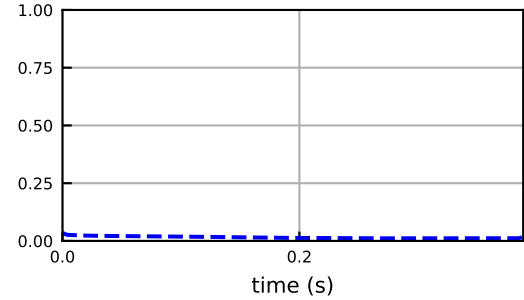
forcesetsemimem



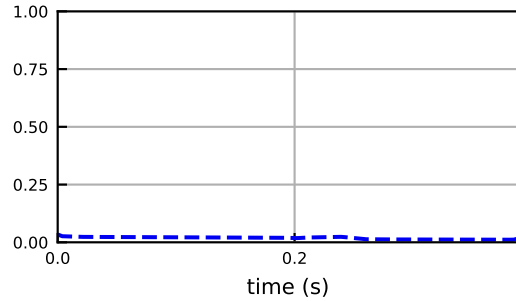
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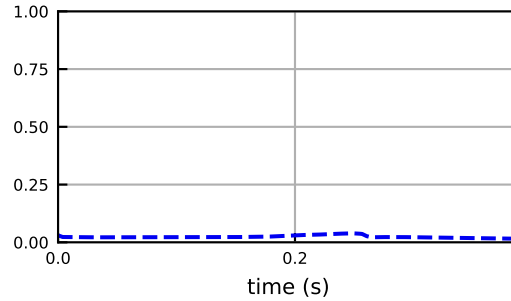
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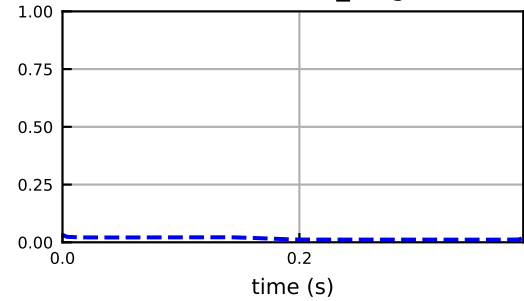
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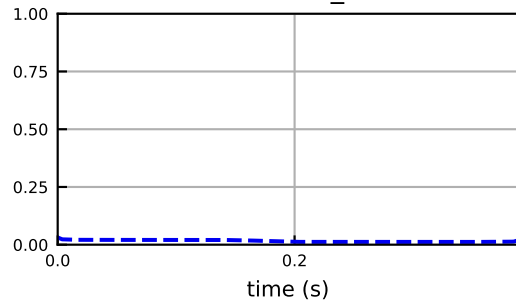
forcesetsar



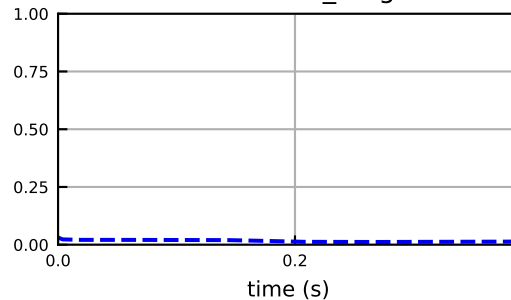
forcesetadd\_long



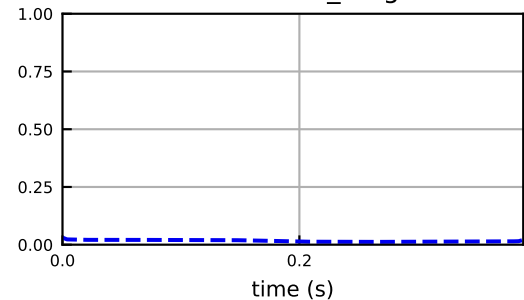
forcesetadd\_brev



forcesetadd\_mag1



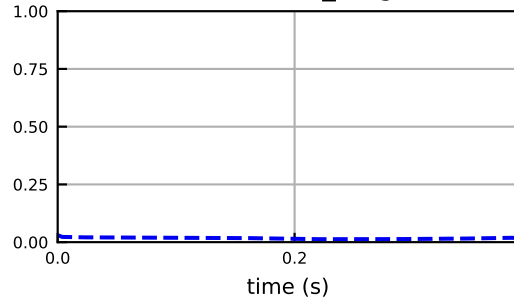
forcesetadd\_mag2



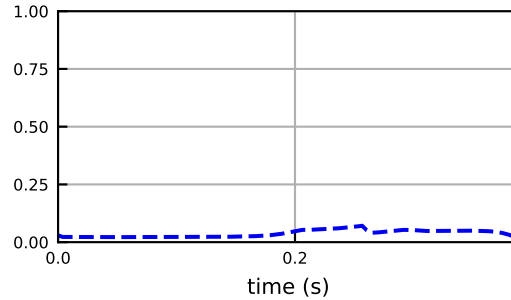


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100/solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100/solution.sto (left leg)

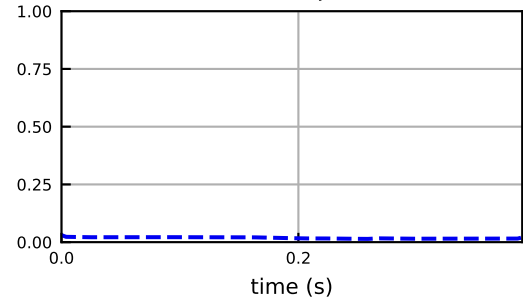
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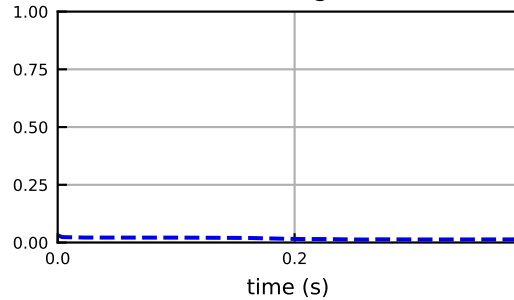
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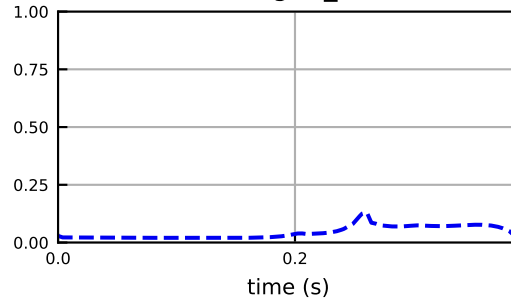
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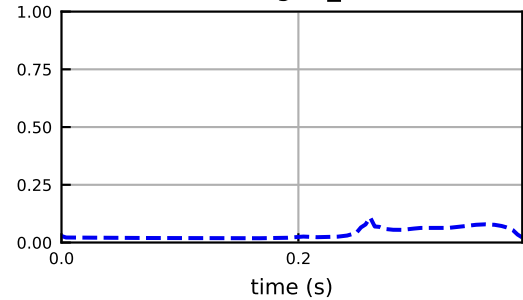
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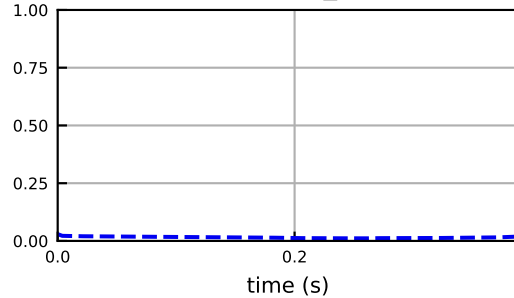
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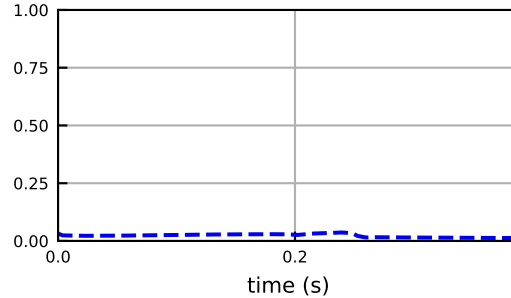
forcesetglut\_max2



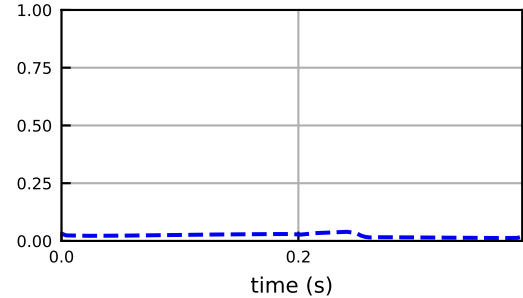
forcesetglut\_max3



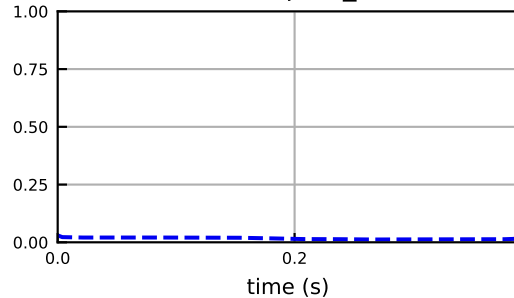
forcesetiliacus



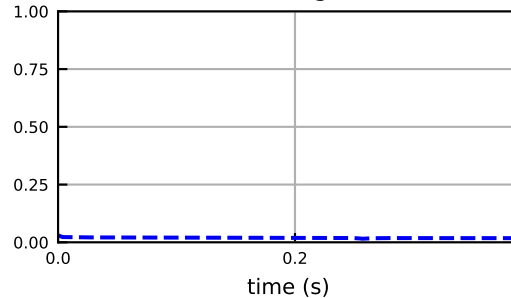
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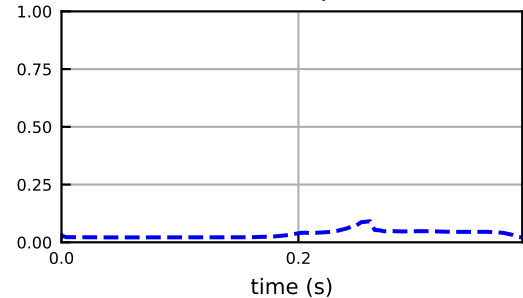
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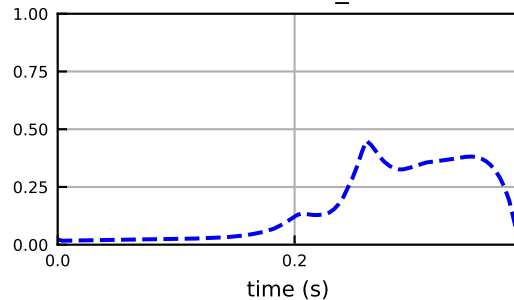
forcesetgem



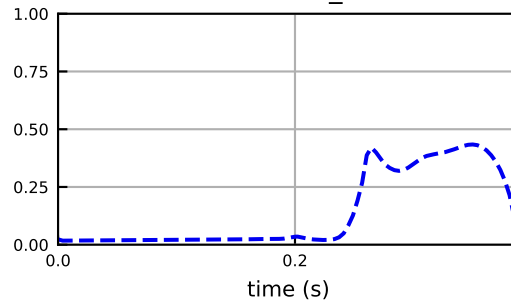
forcesetperi



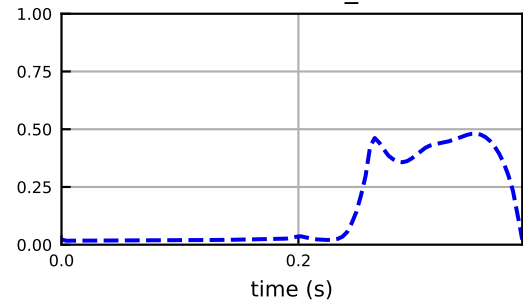
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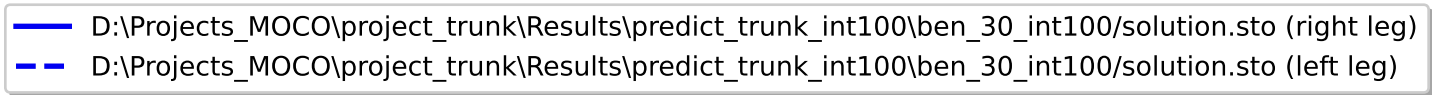


forcesetvas\_med

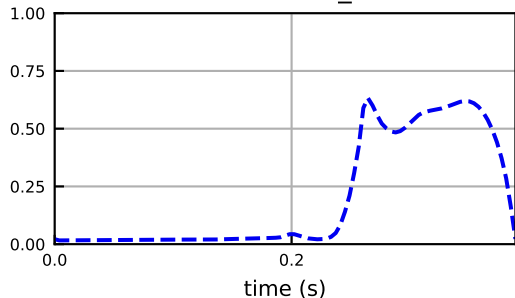


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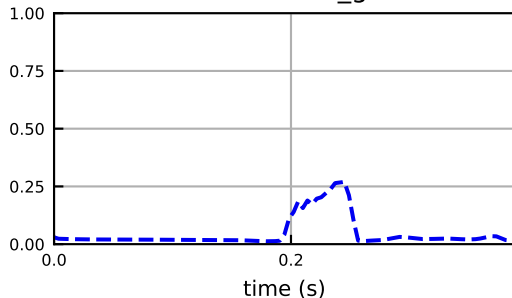




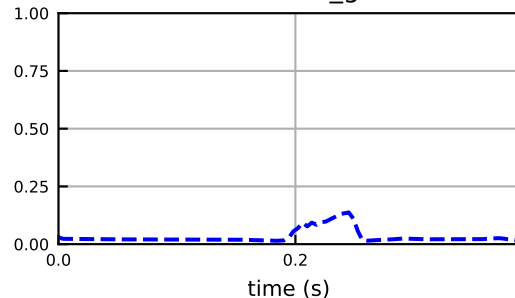
forcesetvas\_lat



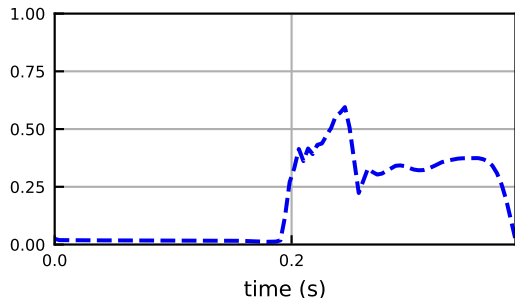
forcesetmed\_gas



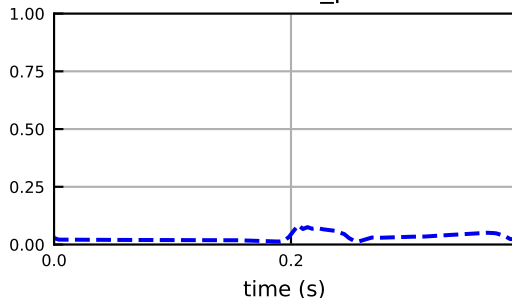
forcesetlat\_gas



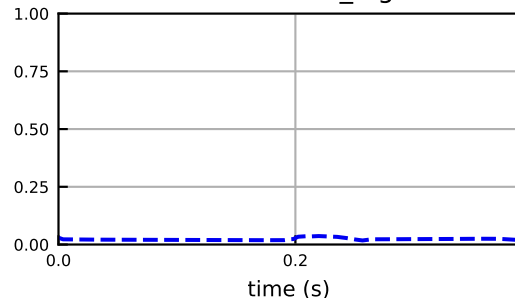
forcesetsoleus



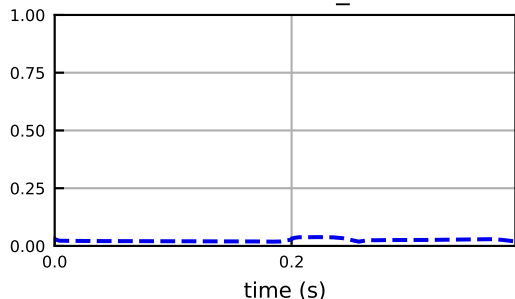
forcesettib\_post



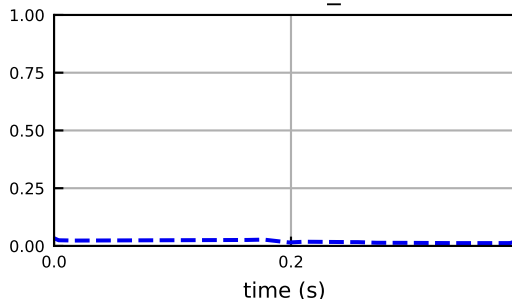
forcesetflex\_dig



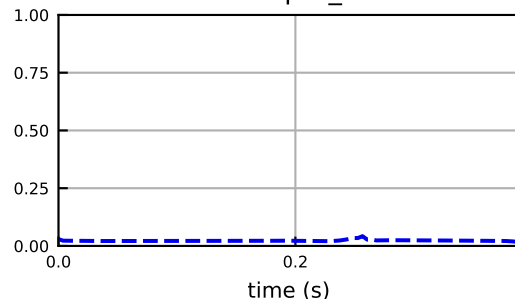
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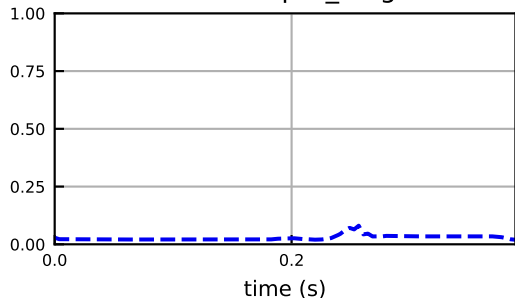
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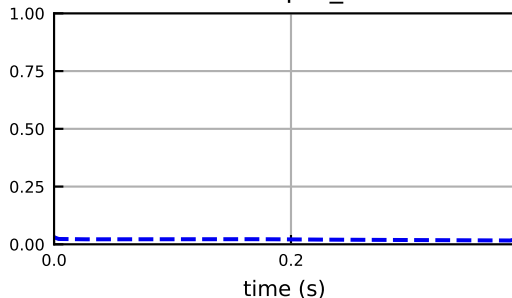
forcesetper\_brev



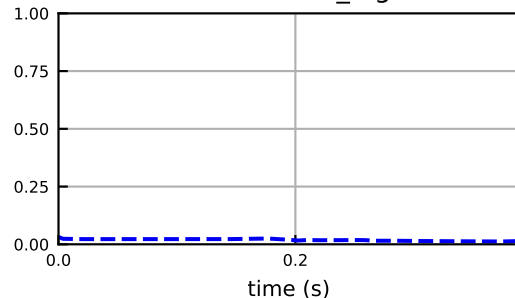
forcesetper\_long



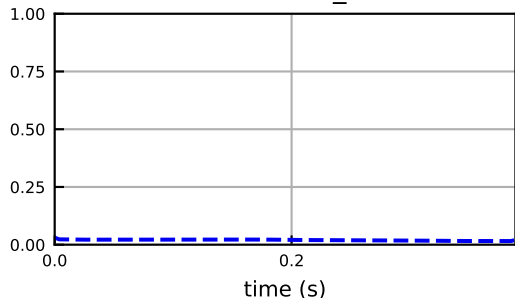
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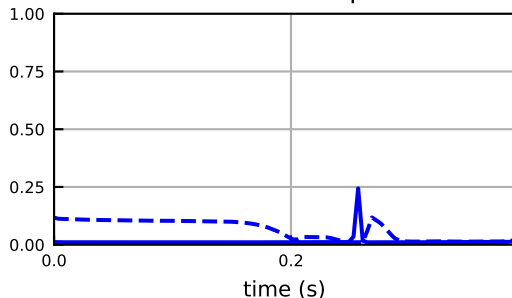
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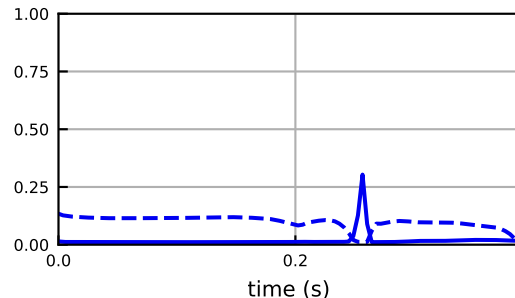
forcesetext\_hal



forcesetercspn

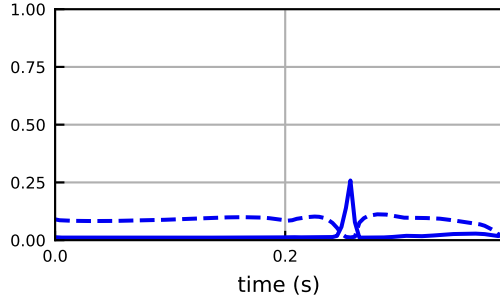


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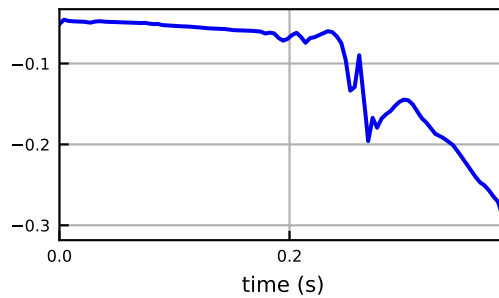


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100/solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_int100\ben\_30\_int100/solution.sto (left leg)

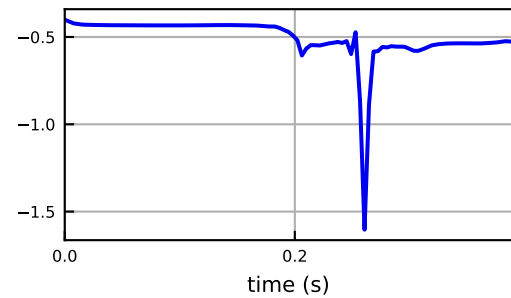
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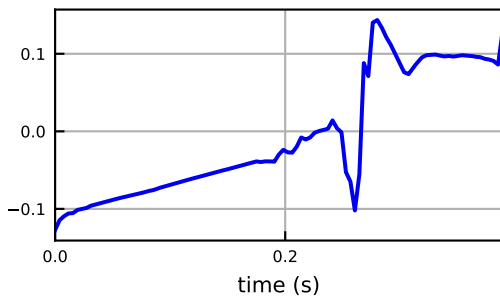
forcesetreserve\_joi...lvis\_pelvis\_tilt



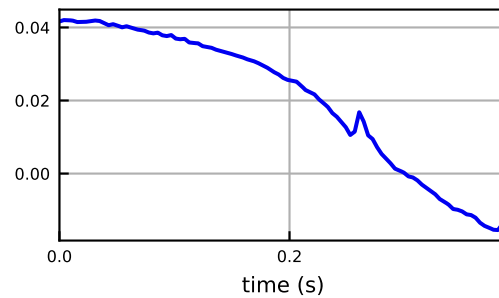
forcesetreserve\_joi...lvis\_pelvis\_list



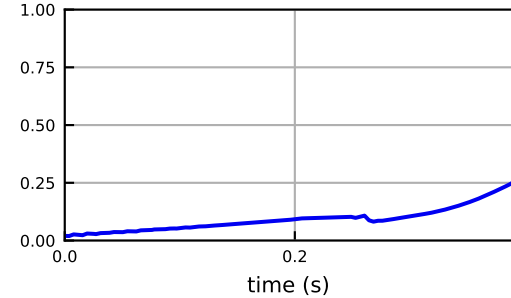
forcesetreserve\_joi...\_pelvis\_rotation



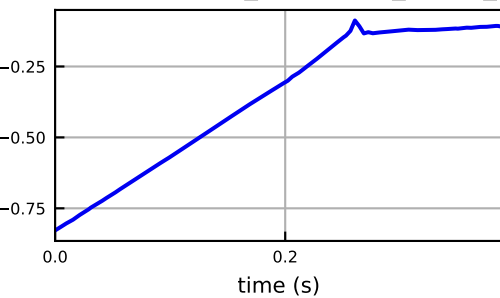
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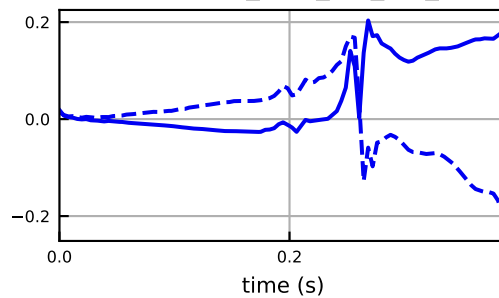
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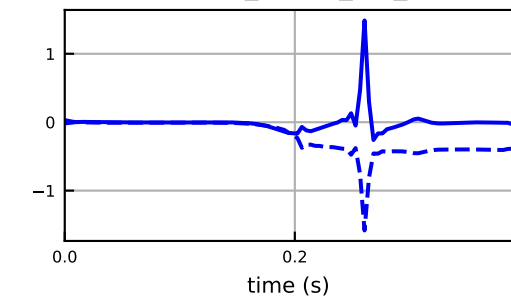
forcesetreserve\_joi...pelvis\_pelvis\_tz



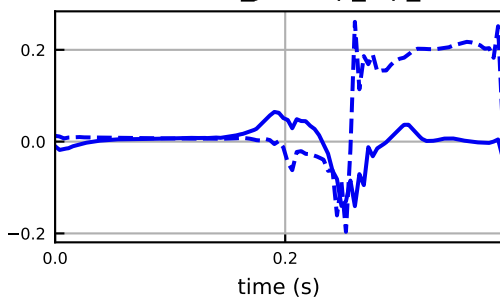
forcesetreserve\_joi...\_hip\_hip\_flexion



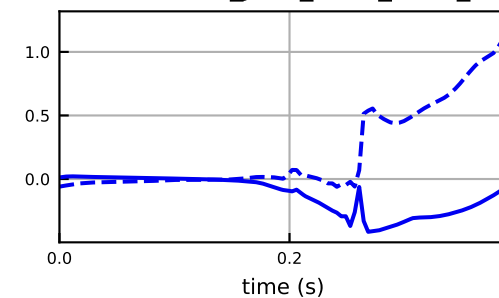
forcesetreserve\_joi...ip\_hip\_adduction



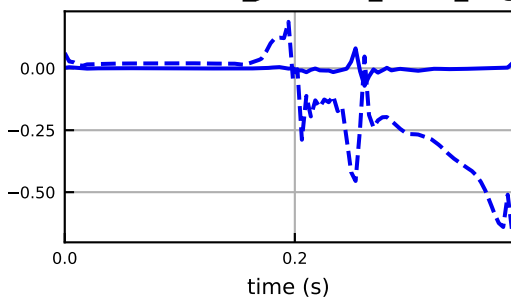
forcesetreserve\_joi...hip\_hip\_rotation



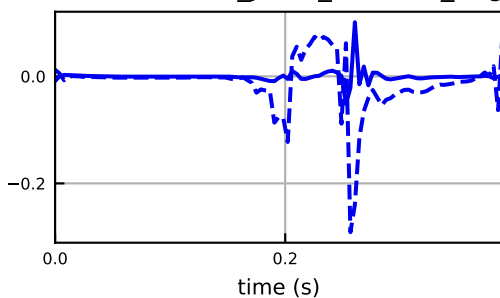
forcesetreserve\_joi...\_knee\_knee\_angle



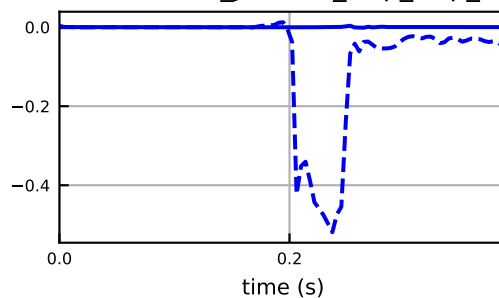
forcesetreserve\_joi...nkle\_ankle\_angle



forcesetreserve\_joi...r\_subtalar\_angle



forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension

