

D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_10/solution.sto (right leg) D:\Projects_MOCO\project_trunk\Results\track_trunk_jrGoal_int100\ext_10/solution.sto (left leg) hip_adduction/speed hip_rotation/value hip rotation/speed 1e-3 0.5 speed (rad/s) speed (rad/s) angle (rad) 0.0 0.1 0.3 0.1 0.3 0.1 0.3 time (s) time (s) time (s) knee_angle/value knee_angle/speed ankle_angle/value speed (rad/s) 0.5 angle (rad) angle (rad) -10 0.1 0.3 0.1 0.1 0.3 time (s) time (s) time (s) ankle_angle/speed subtalar_angle/value subtalar_angle/speed 0.005 speed (rad/s) speed (rad/s) angle (rad) 0.000 -0.005 -0.010 0.3 0.1 0.1 0.3 0.1 0.3 time (s) time (s) time (s) mtp_angle/value mtp_angle/speed lumbar_extension/value 1.00 0.01 speed (rad/s) 0.75 angle (rad) angle (rad) 0.50 0.00 0.25 -0.01 0.00 0.1 0.3 0.1 0.3 0.1 0.3 time (s) time (s) time (s) lumbar_extension/speed lumbar_bending/value lumbar_bending/speed 1e-3 0.5 speed (rad/s) speed (rad/s) angle (rad) 0.0 0.0

0.1

time (s)

time (s)

time (s)



















