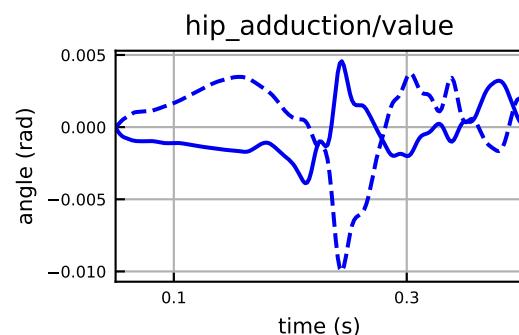
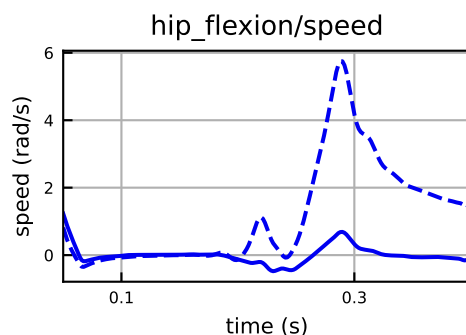
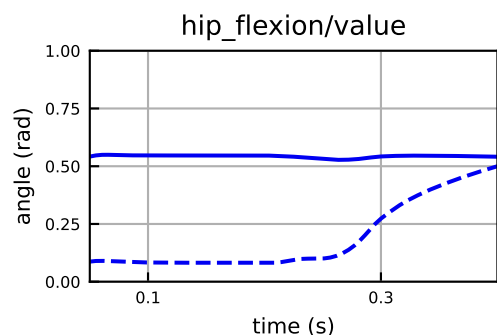
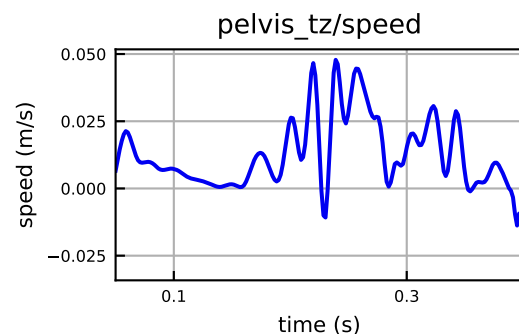
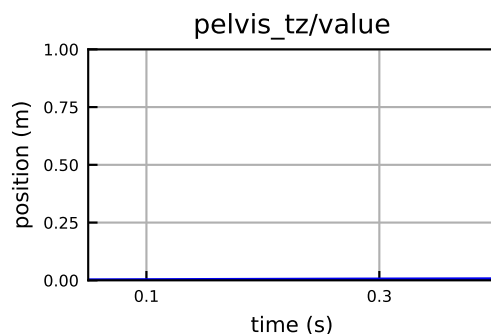
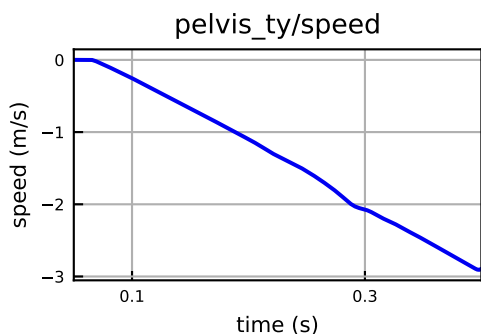
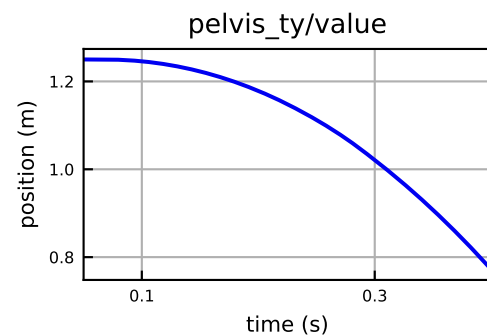
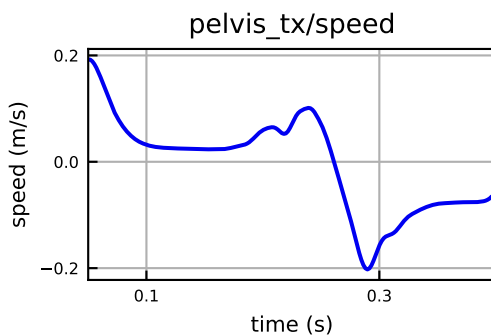
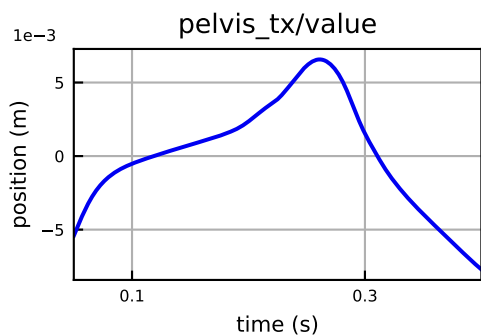
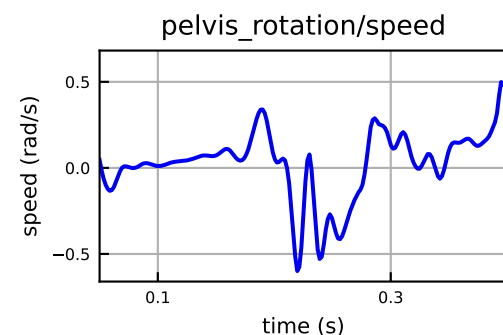
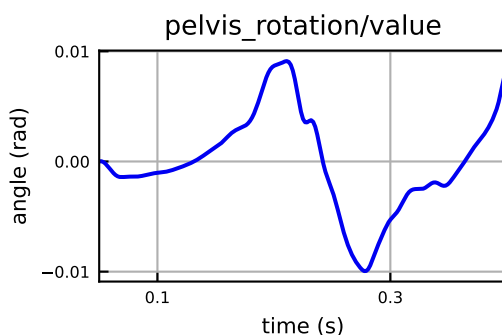
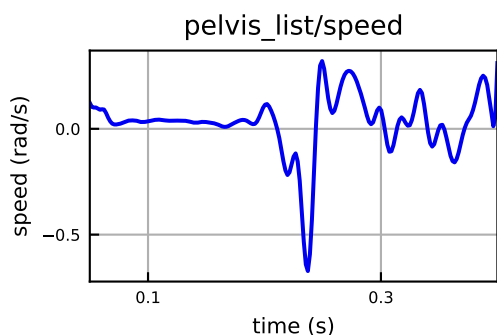
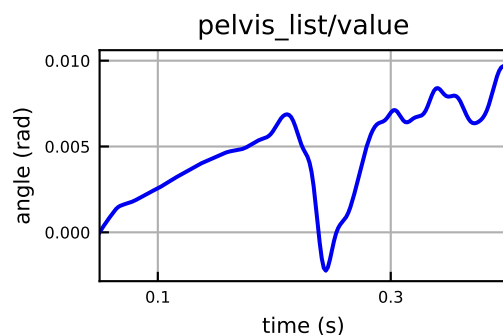
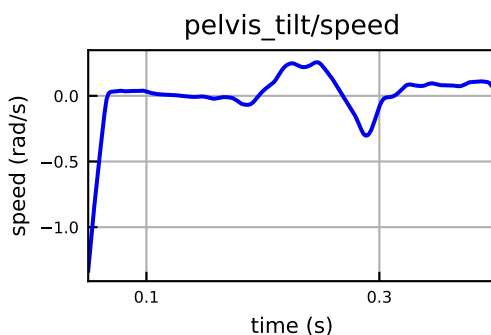
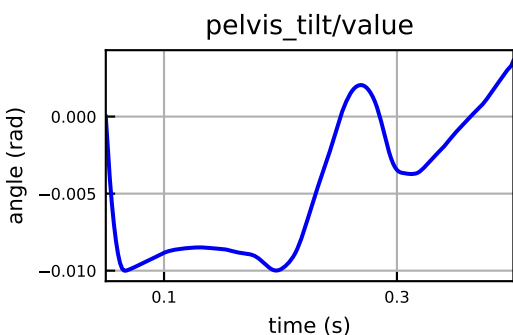
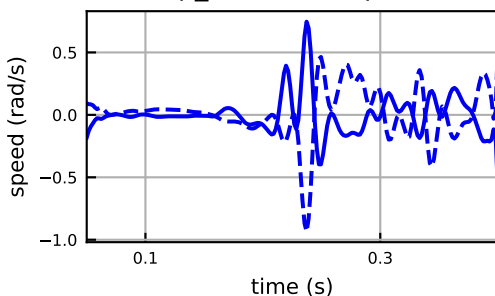


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_-20\solution.sto (right leg)  
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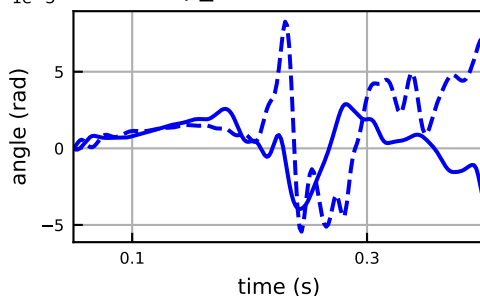


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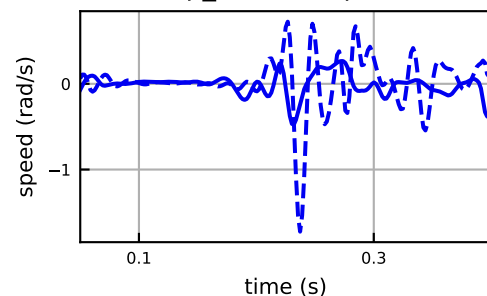
hip\_adduction/speed



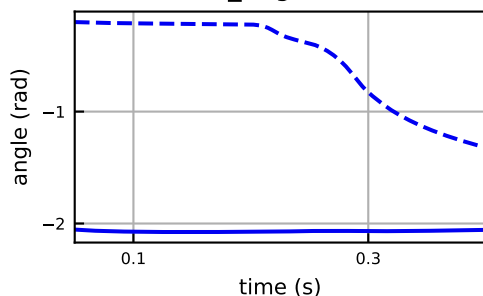
hip\_rotation/value



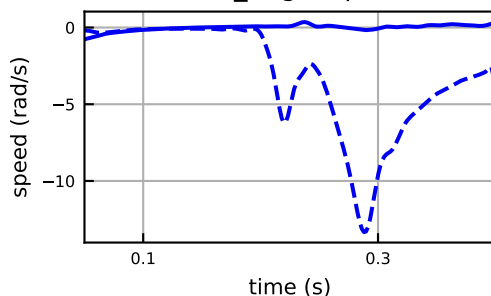
hip\_rotation/speed



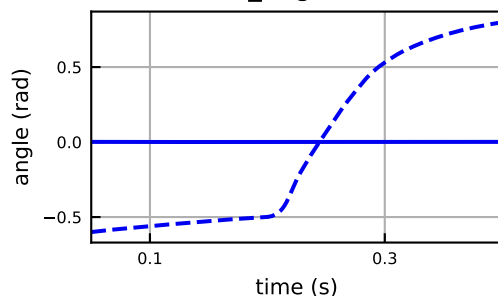
knee\_angle/value



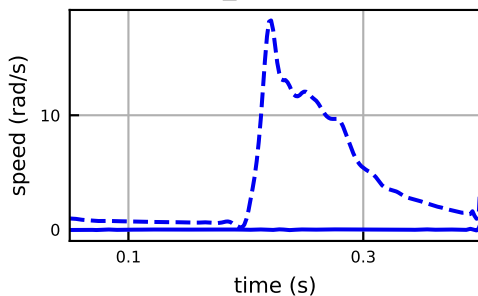
knee\_angle/speed



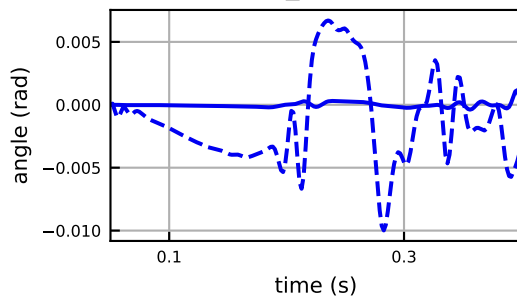
ankle\_angle/value



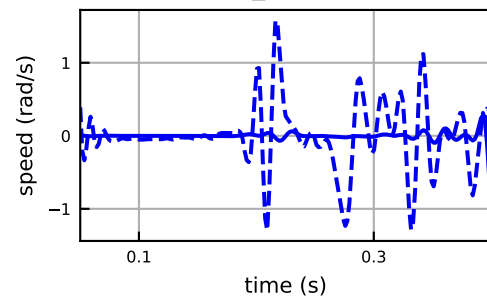
ankle\_angle/speed



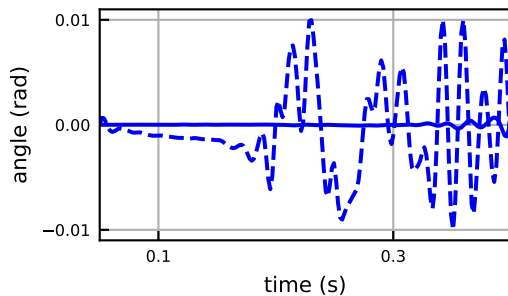
subtalar\_angle/value



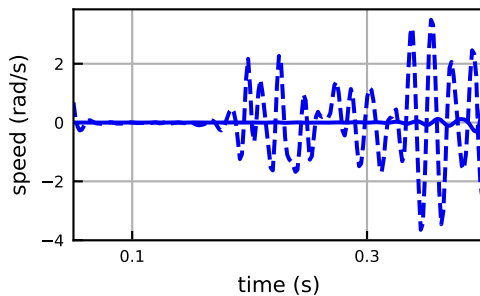
subtalar\_angle/speed



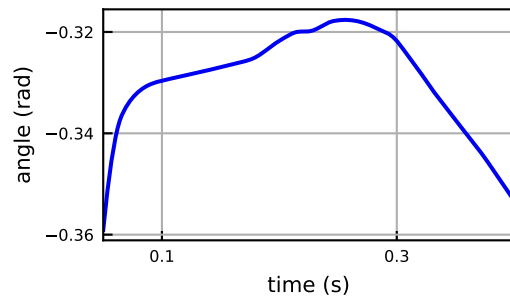
mtp\_angle/value



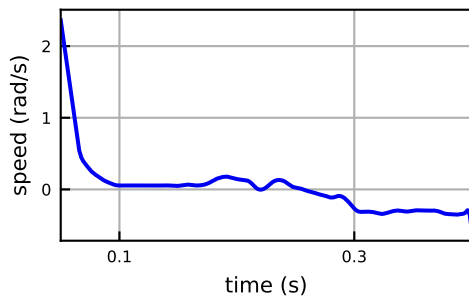
mtp\_angle/speed



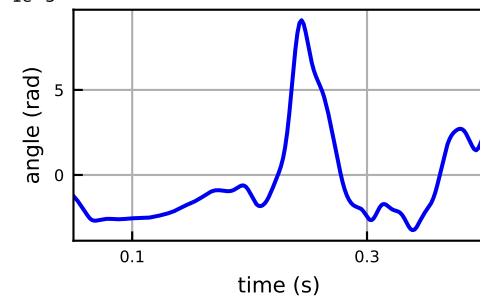
lumbar\_extension/value



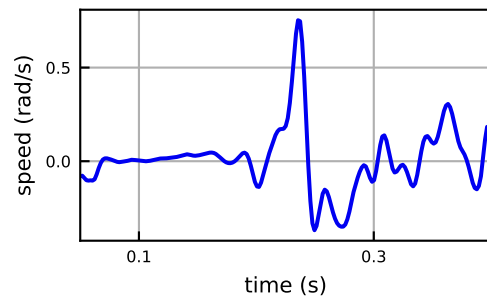
lumbar\_extension/speed



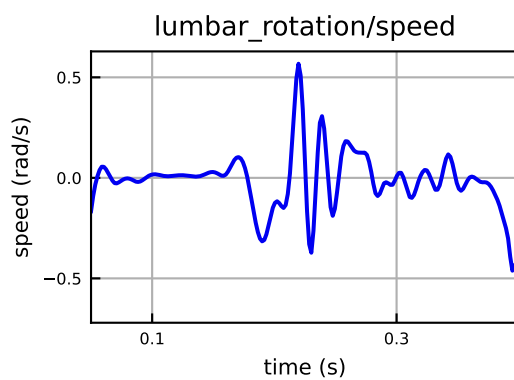
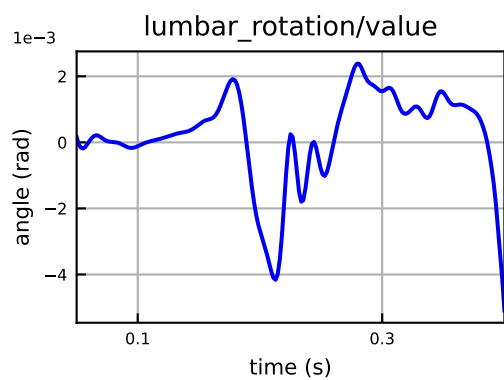
lumbar\_bending/value



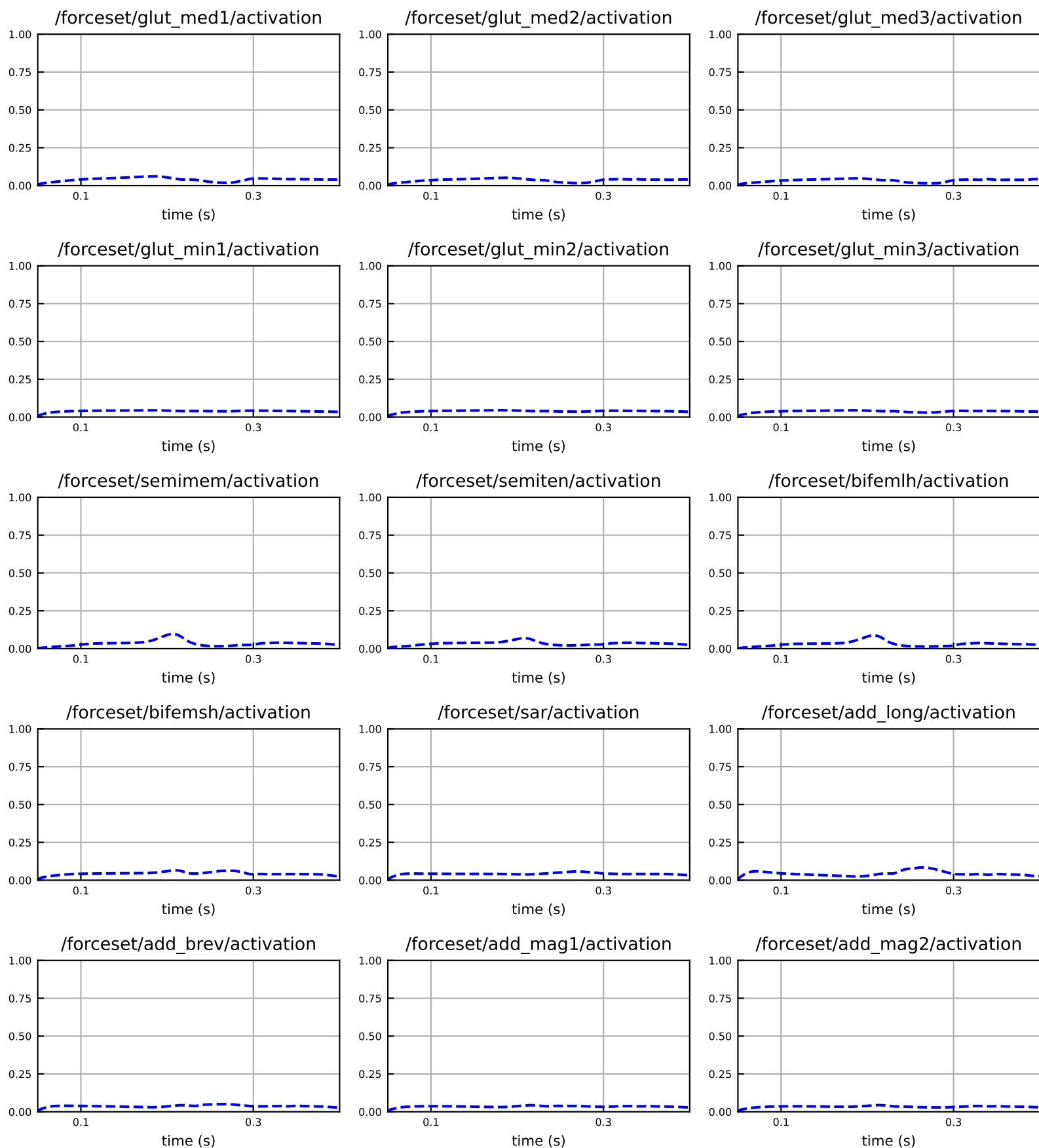
lumbar\_bending/speed



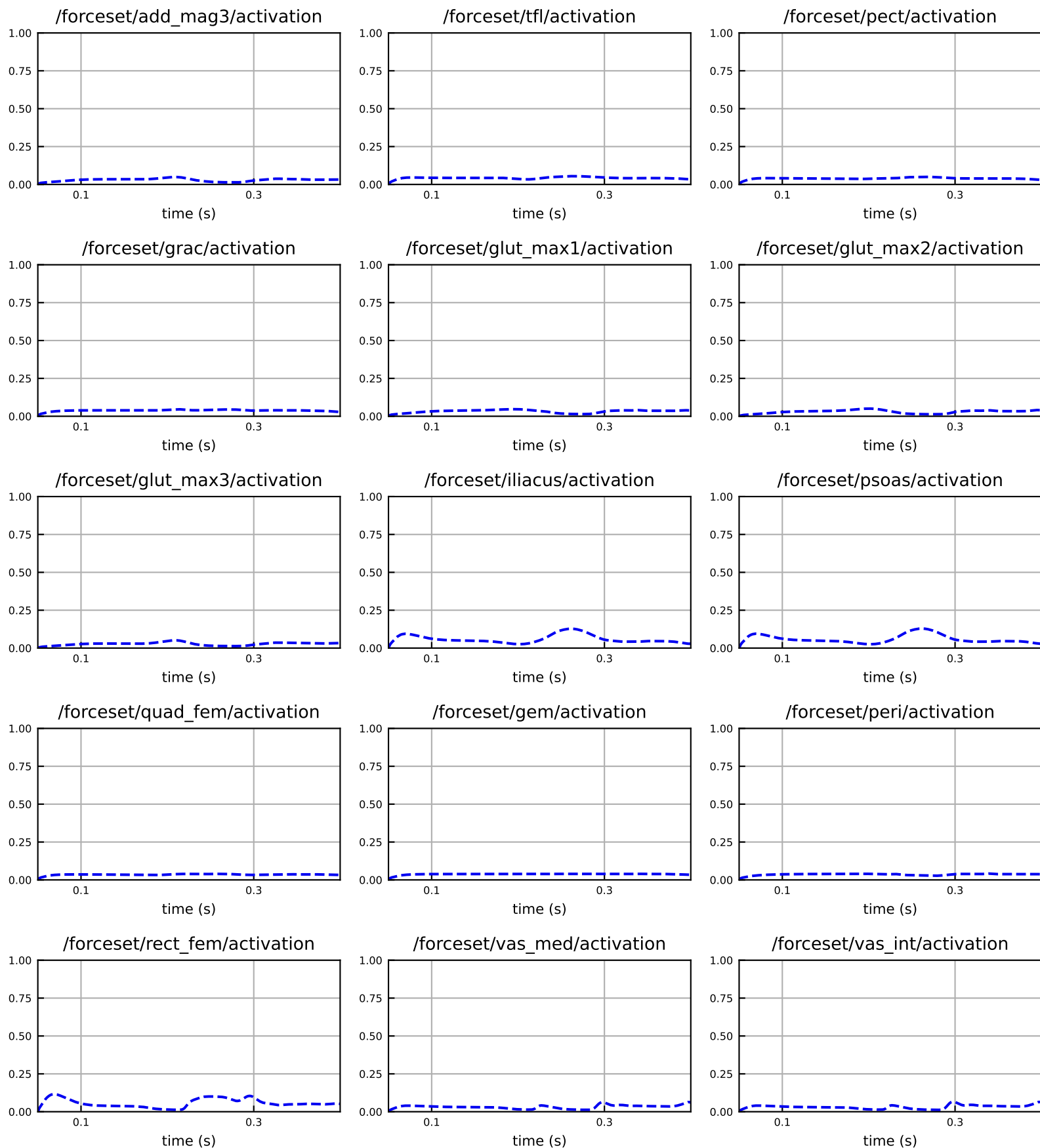
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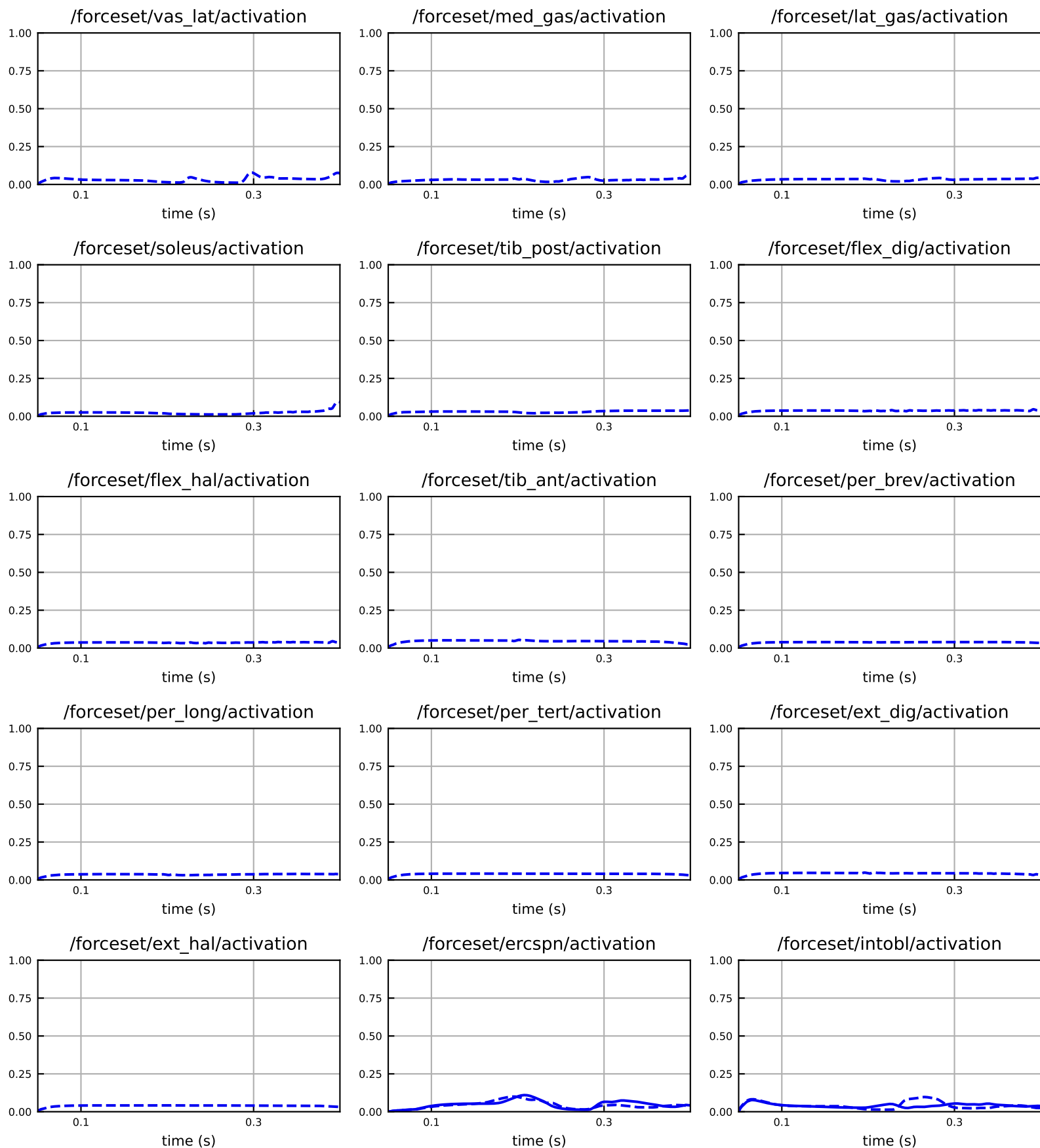
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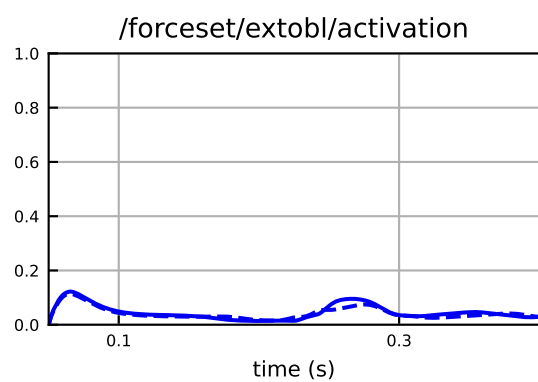
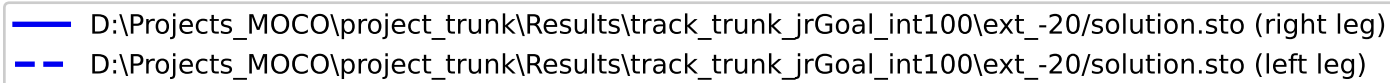


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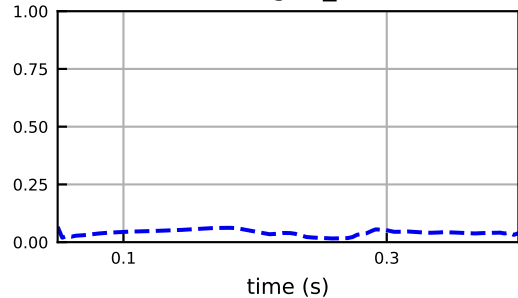
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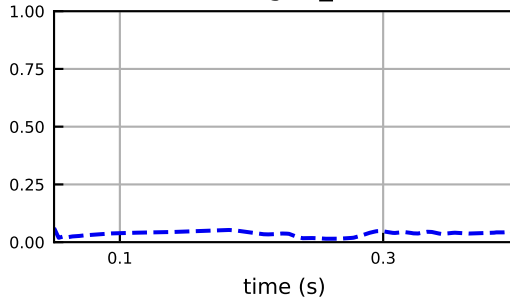


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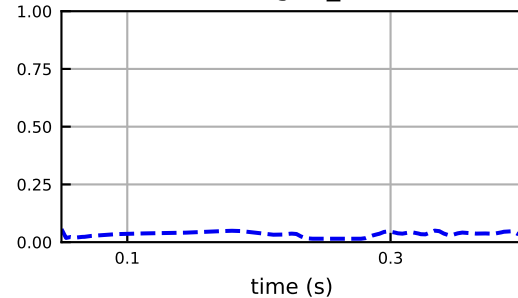
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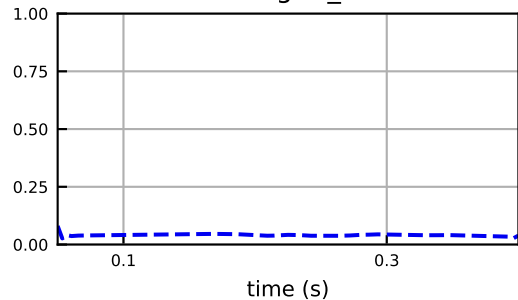
forcesetglut\_med2



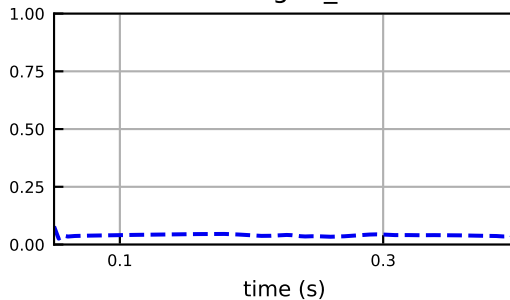
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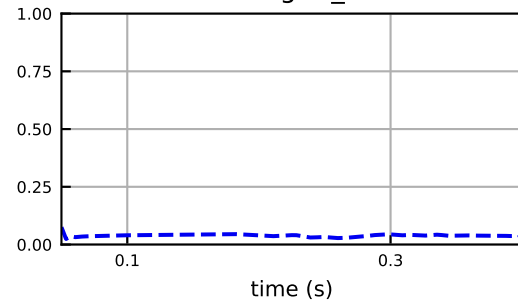
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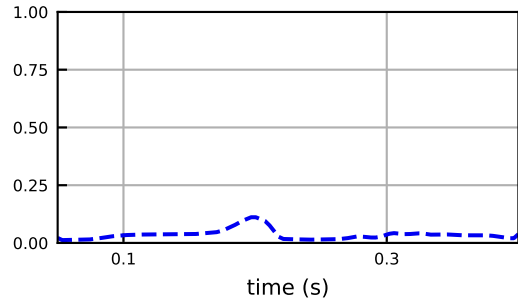
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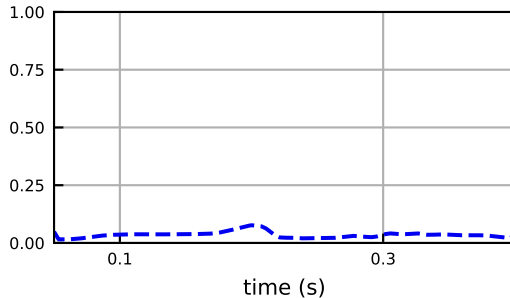
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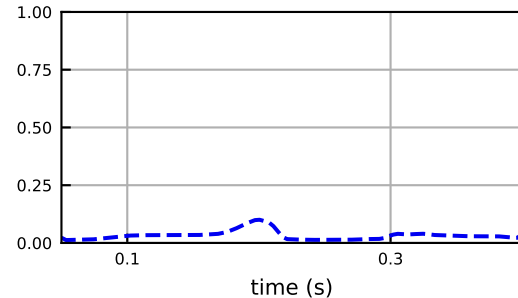
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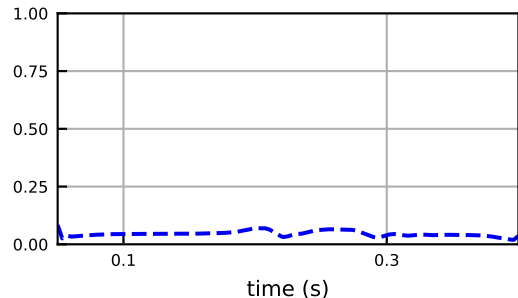
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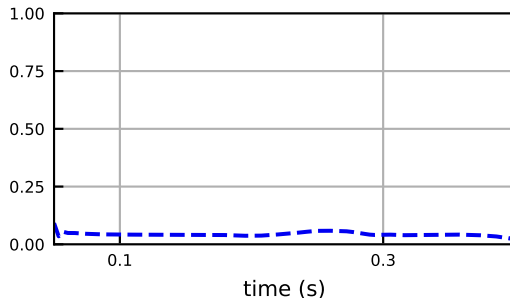
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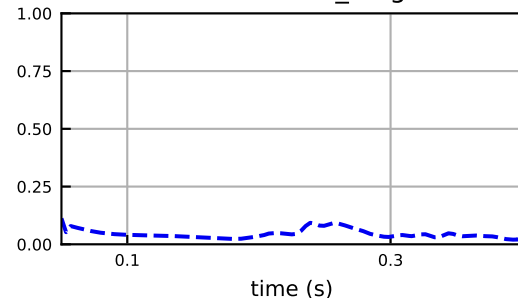
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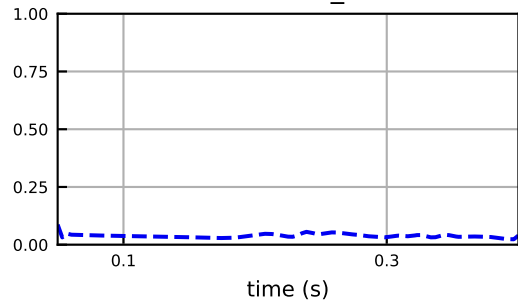
forcesetsar



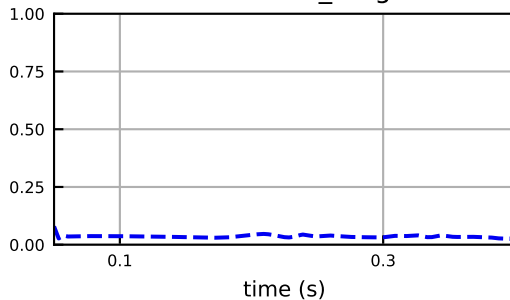
forcesetadd\_long



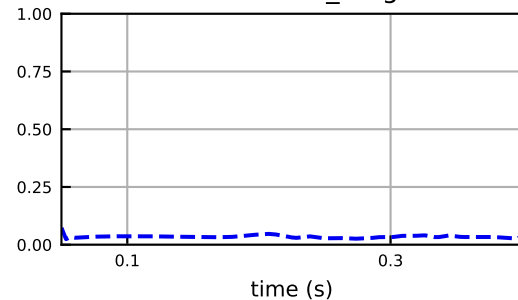
forcesetadd\_brev



forcesetadd\_mag1



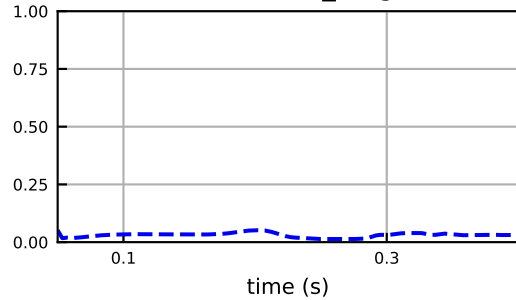
forcesetadd\_mag2



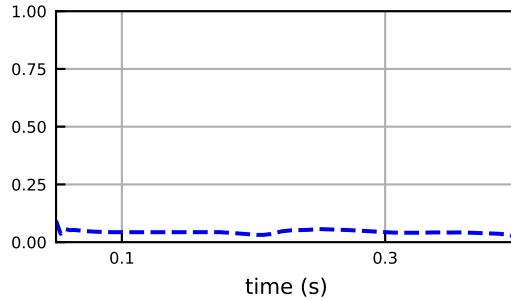


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_-20\solution.sto (right leg)  
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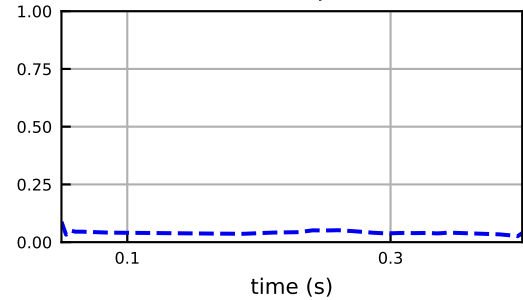
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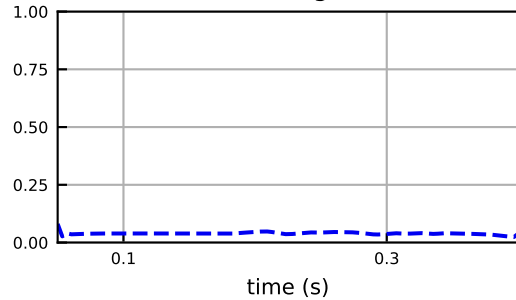
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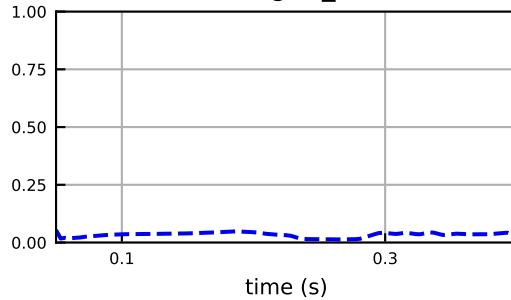
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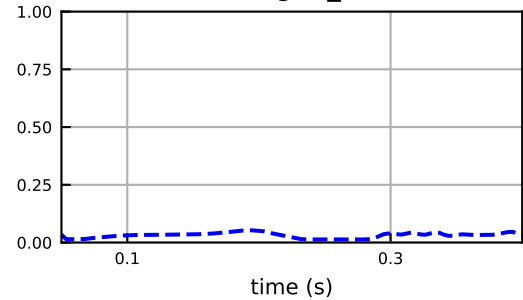
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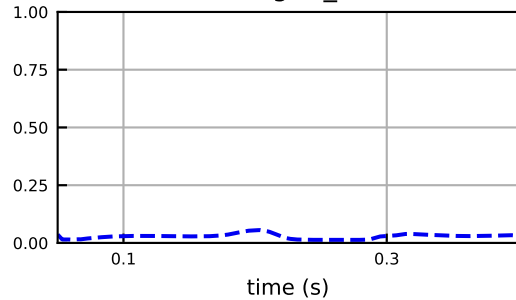
forcesetglut\_max1



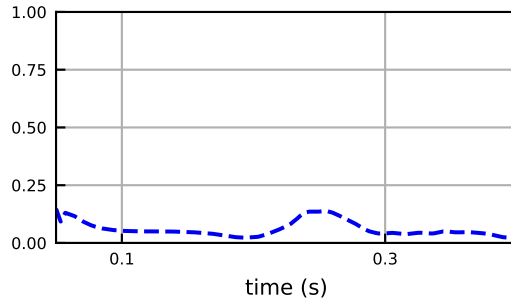
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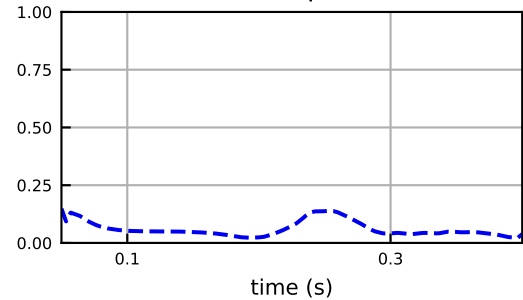
forcesetglut\_max3



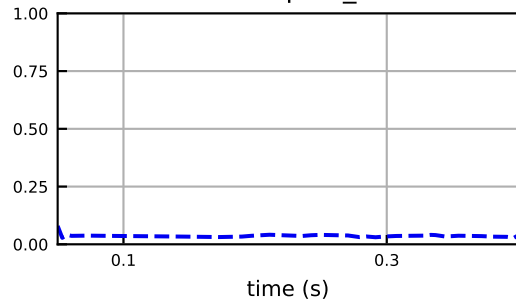
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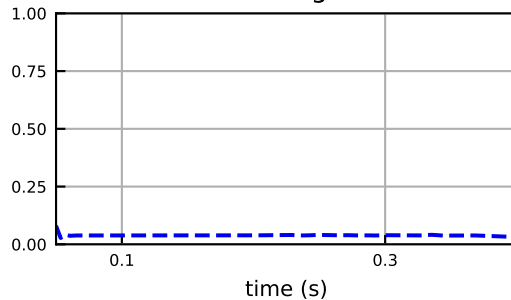
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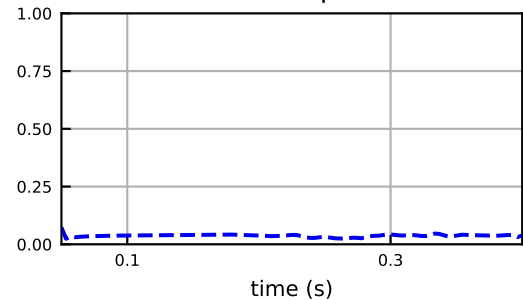
forcesetquad\_fem



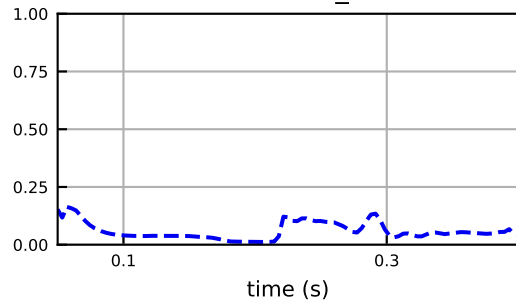
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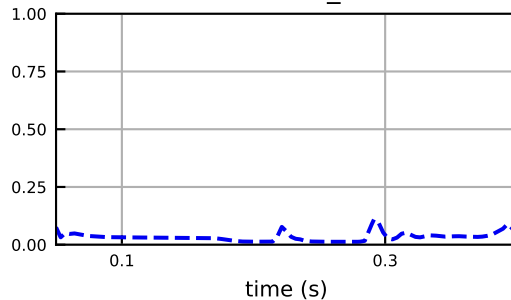
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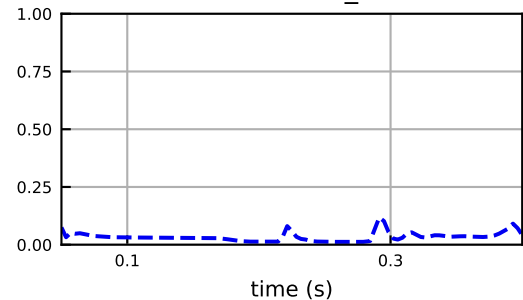
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forcesetvas\_med

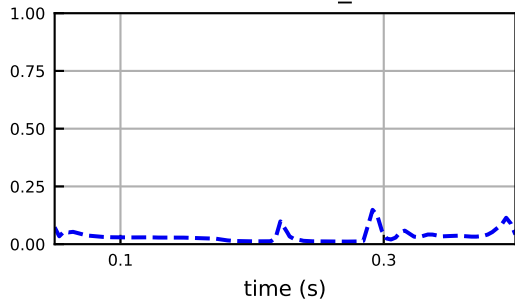


forcesetvas\_int

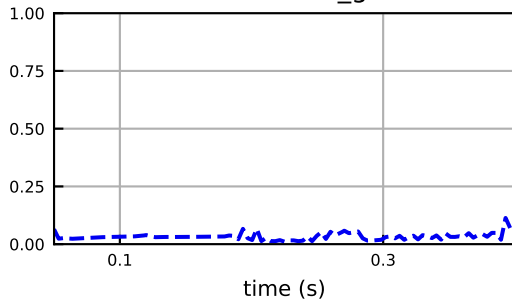


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_-20\solution.sto (right leg)  
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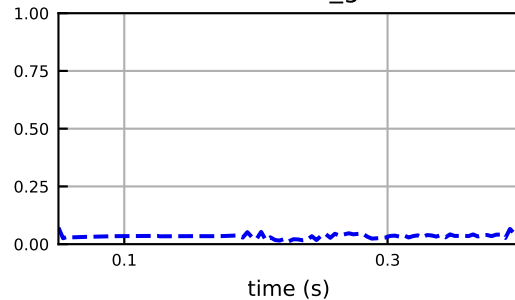
forcesetvas\_lat



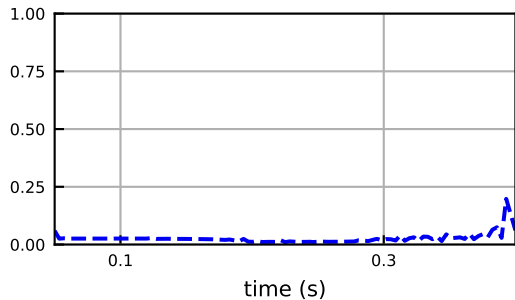
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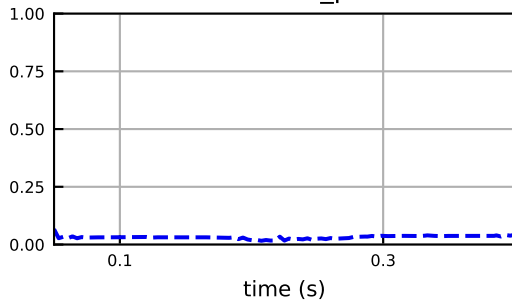
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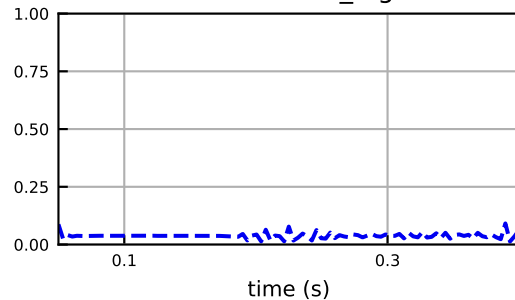
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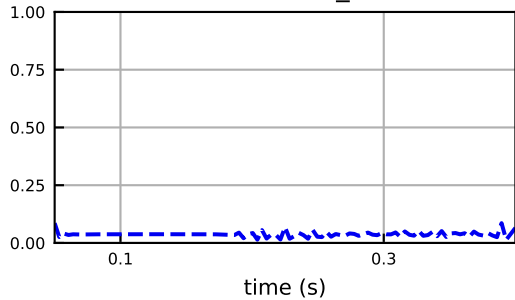
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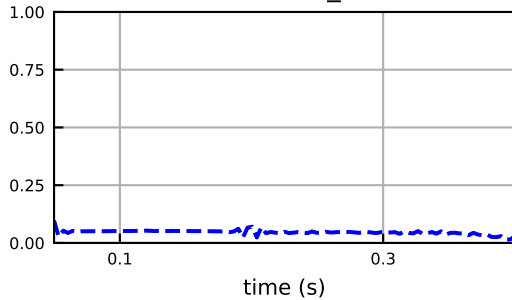
forcesetflex\_dig



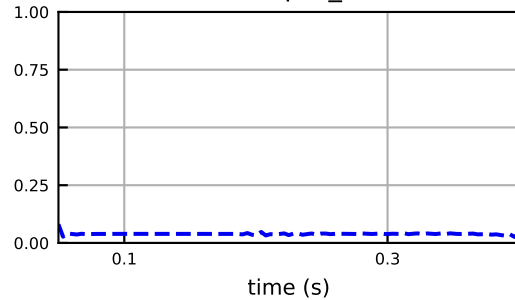
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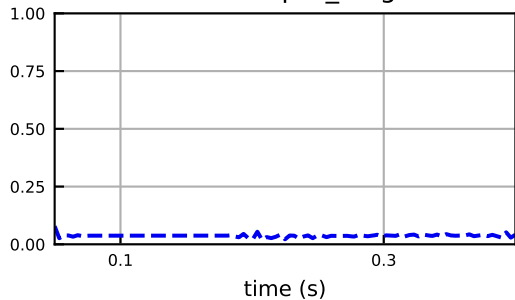
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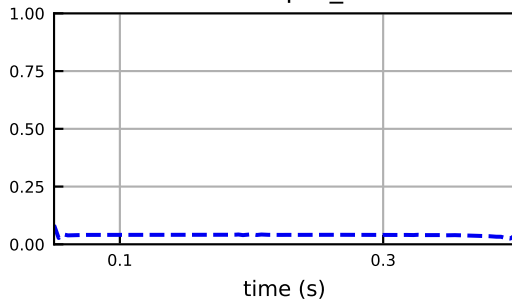
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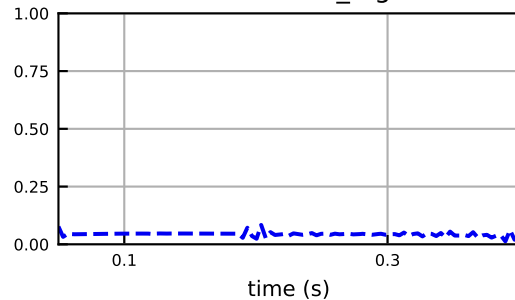
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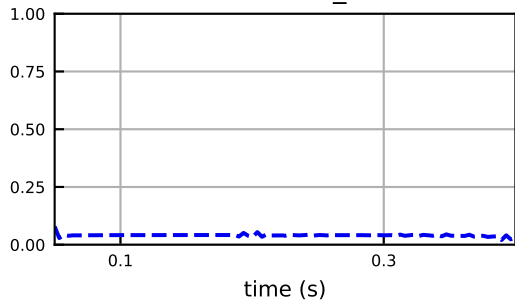
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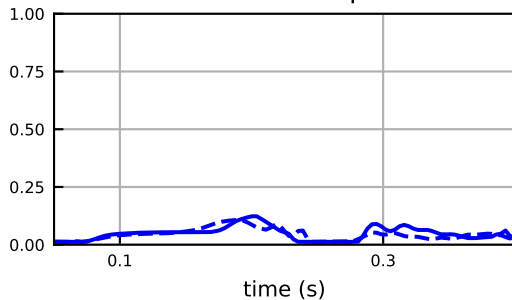
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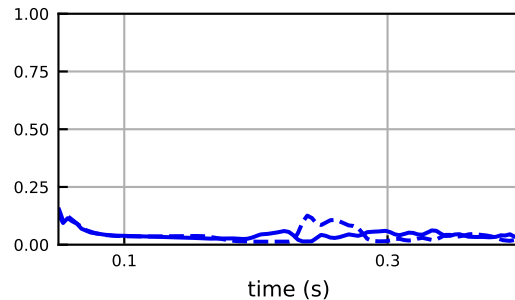
forcesetext\_hal



forcesetercspn

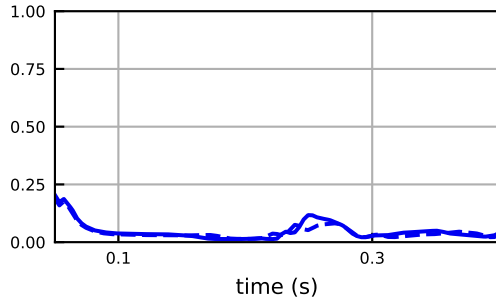


forcesetintobl

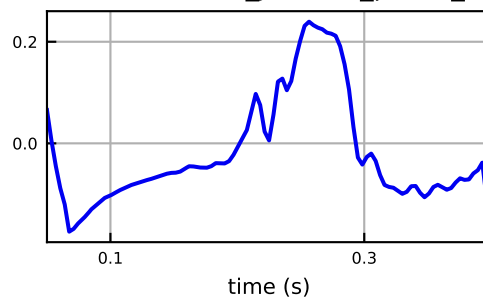


— D:\Projects\_MOCO\project\_trunk\Results\track\_trunk\_jrGoal\_int100\ext\_-20\solution.sto (right leg)  
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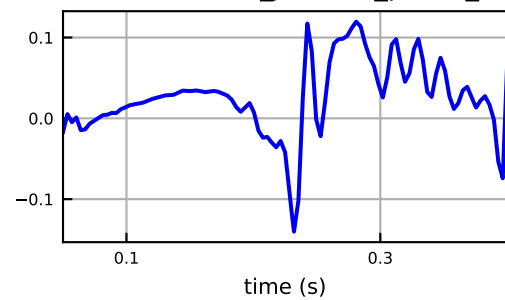
forcesetextobl



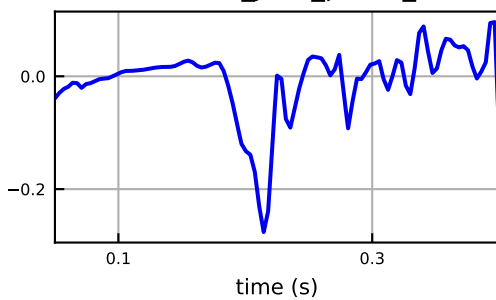
forcesetreserve\_joi...lvis\_pelvis\_tilt



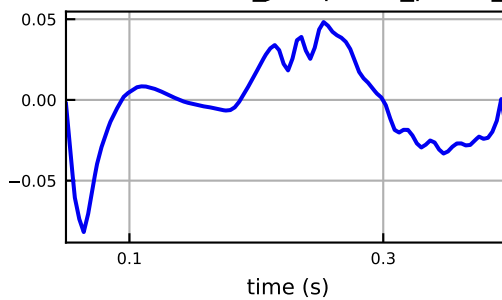
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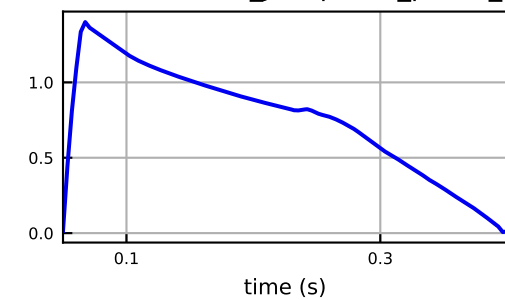
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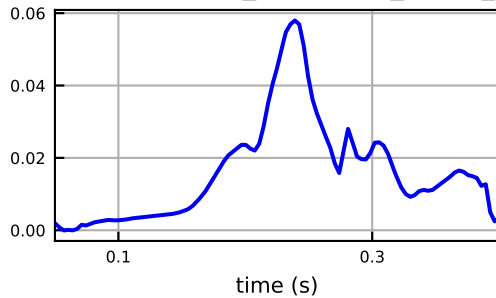
forcesetreserve\_joi...pelvis\_pelvis\_tx



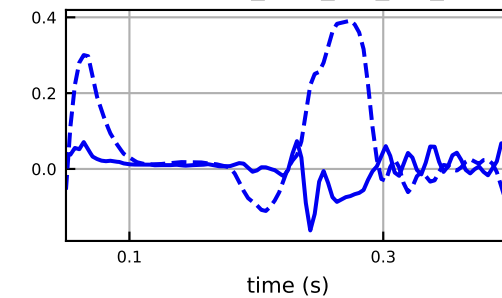
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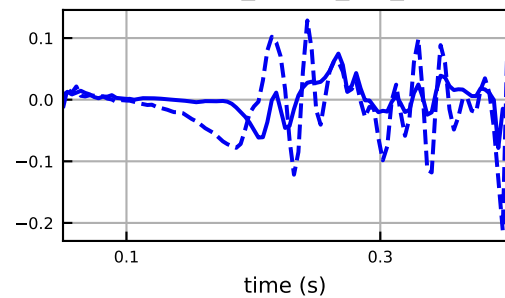
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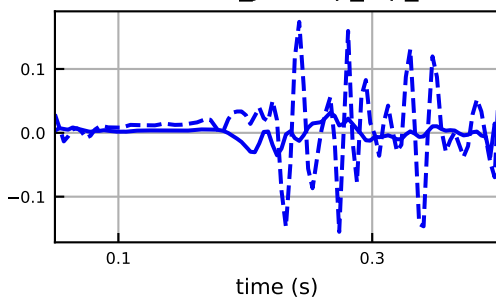
forcesetreserve\_joi...hip\_hip\_flexion



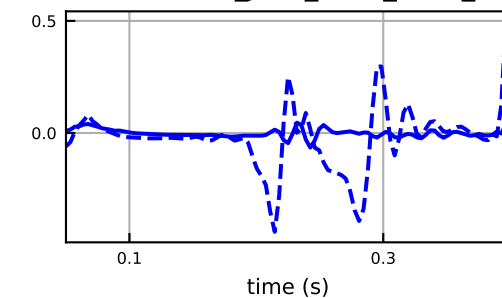
forcesetreserve\_joi...ip\_hip\_adduction



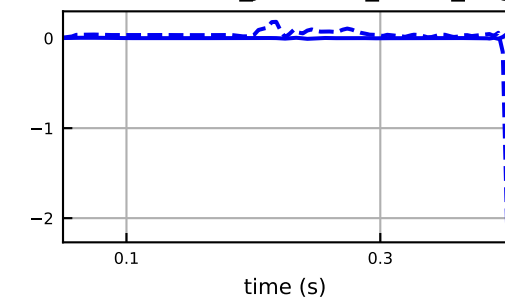
forcesetreserve\_joi...hip\_hip\_rotation



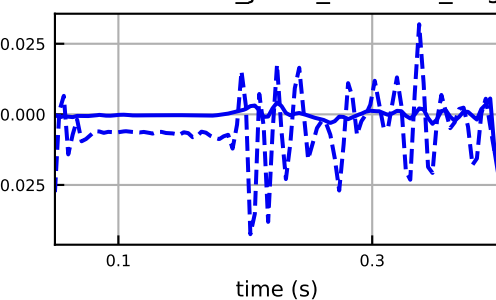
forcesetreserve\_joi...knee\_knee\_angle



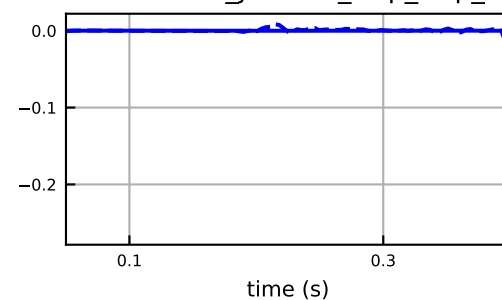
forcesetreserve\_joi...nkle\_ankle\_angle



forcesetreserve\_joi...r\_subtalar\_angle



forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension

