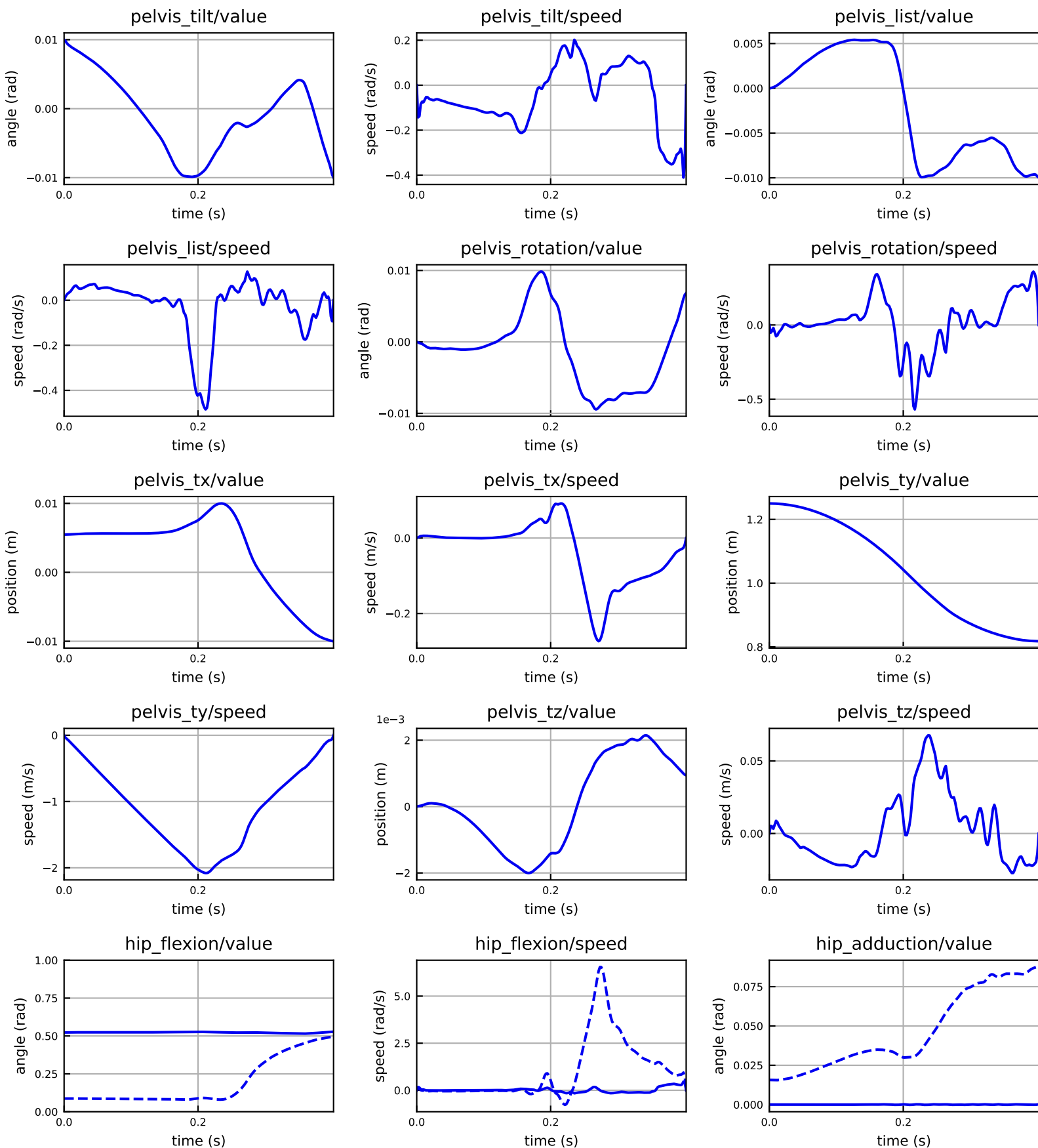
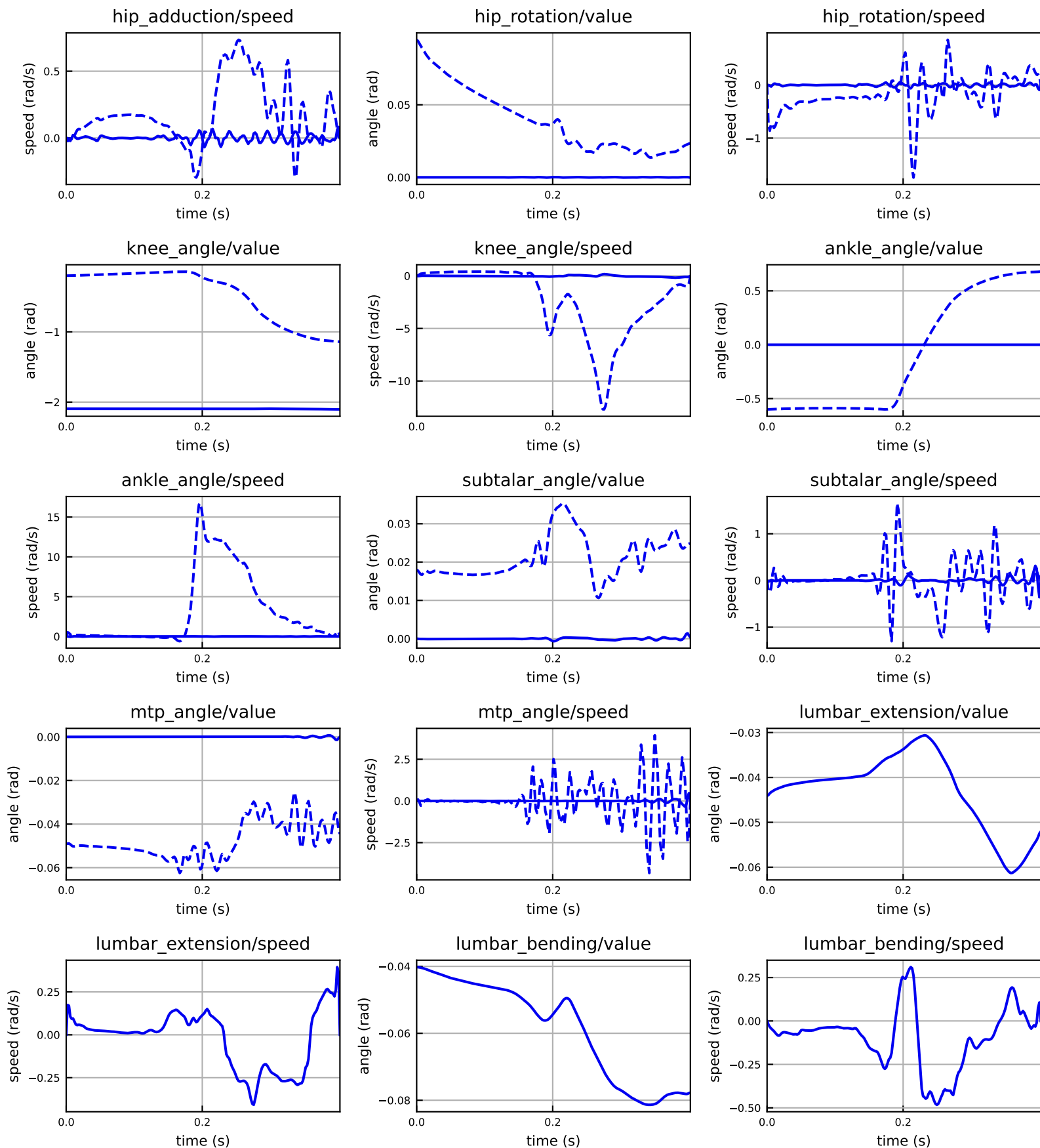
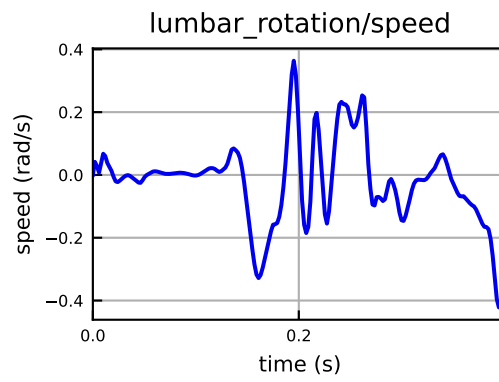
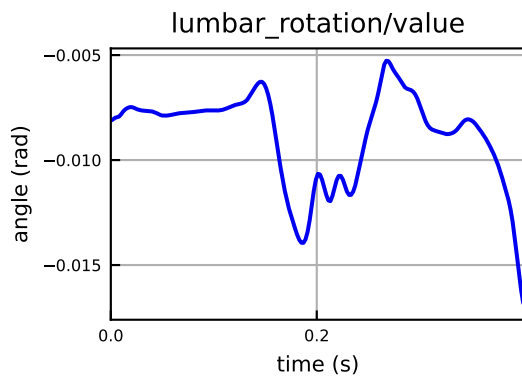


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (right leg)
- - - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (left leg)

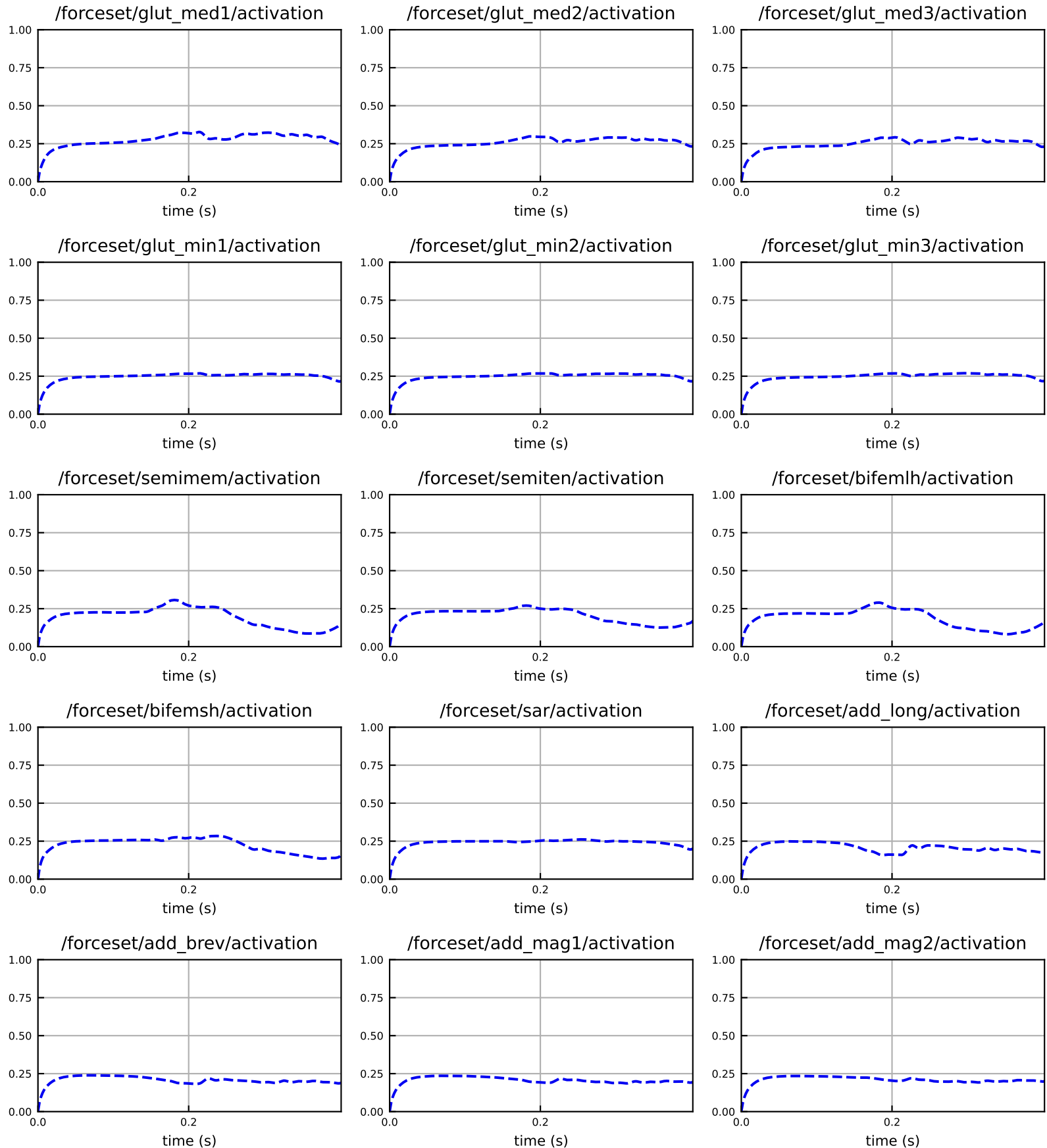


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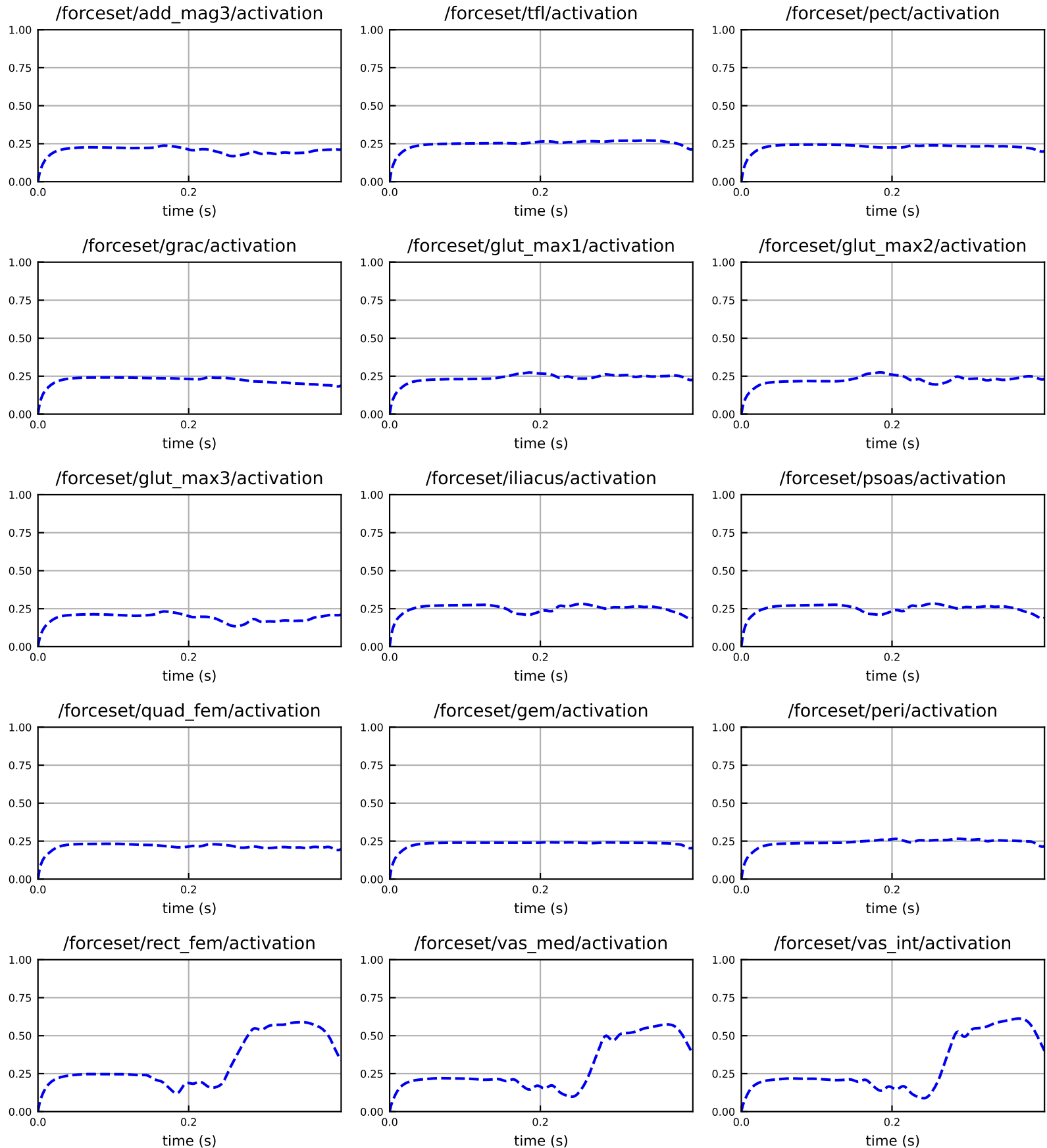




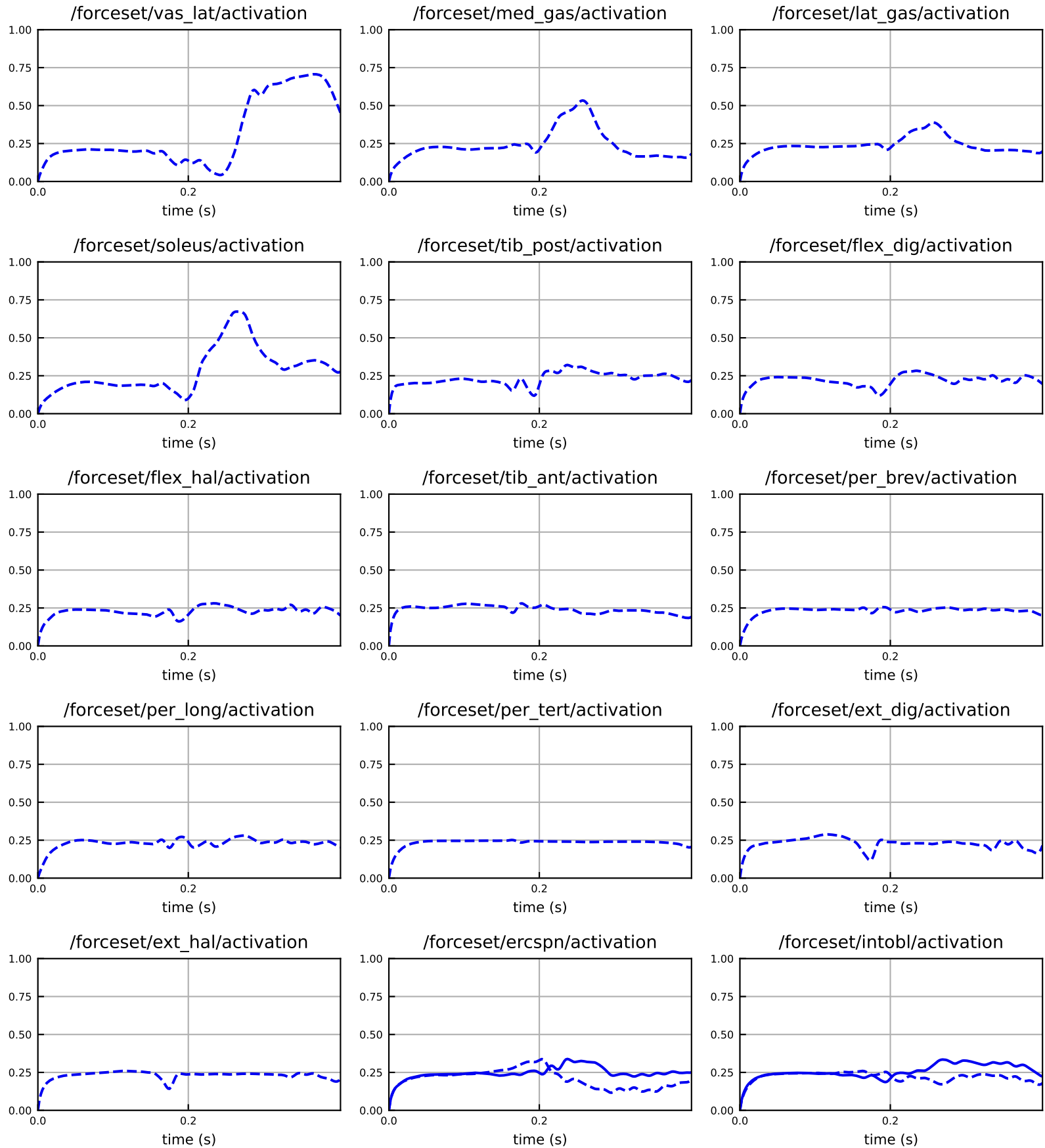
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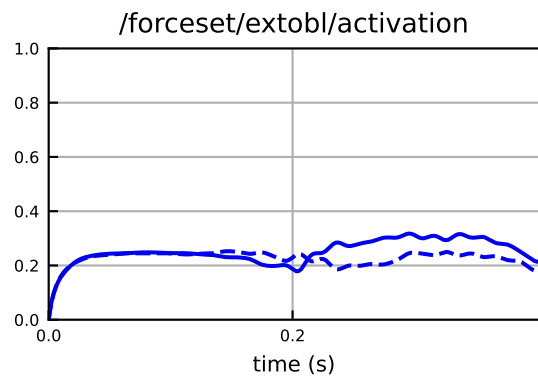
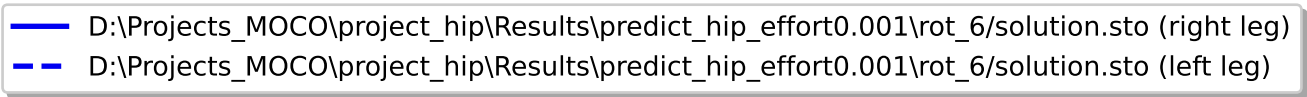


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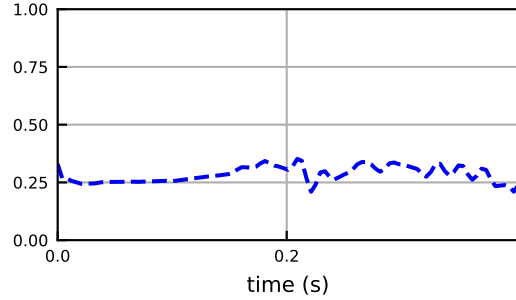
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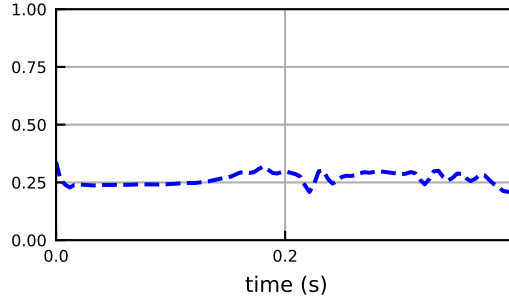


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (right leg)
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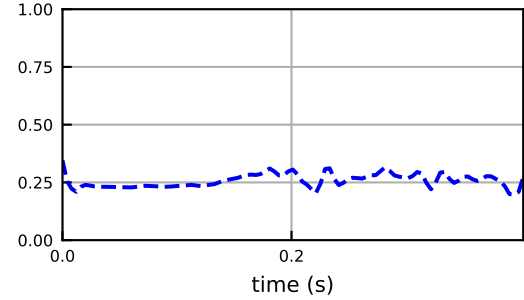
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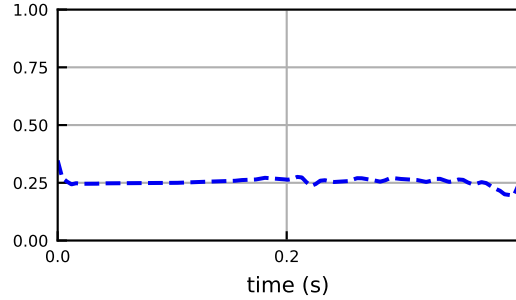
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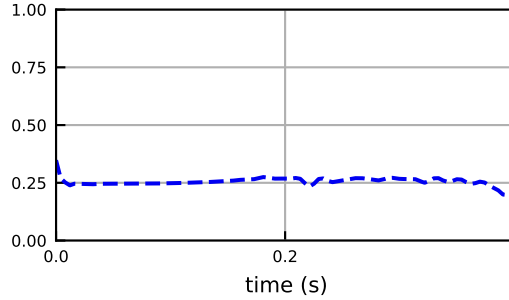
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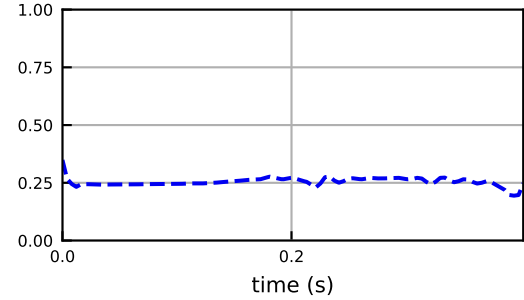
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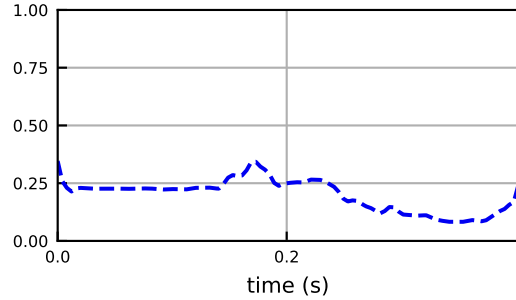
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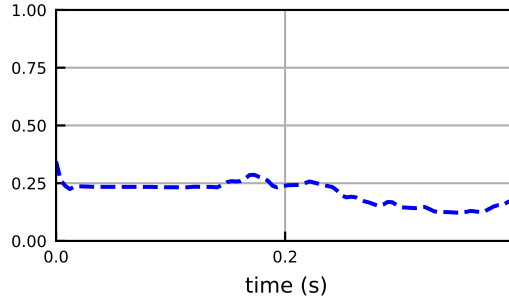
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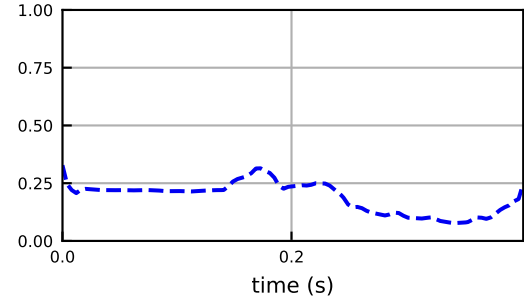
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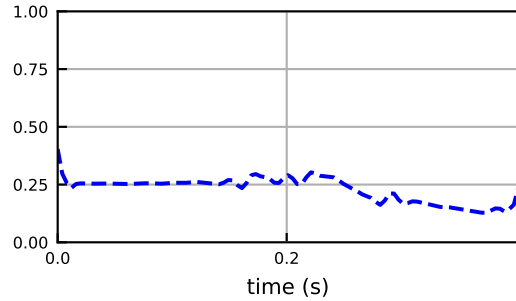
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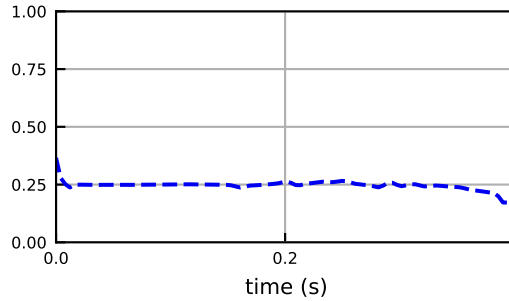
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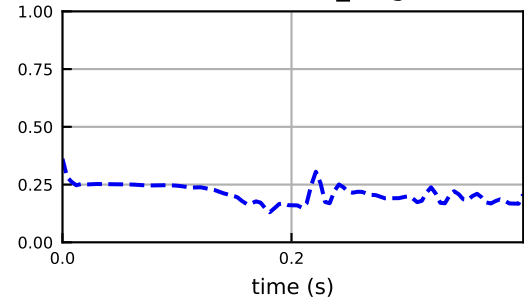
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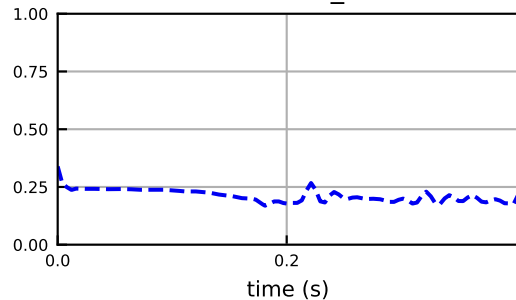
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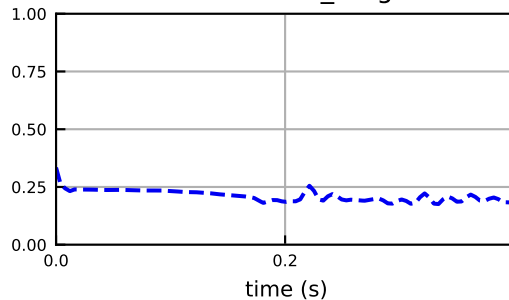
forcesetadd_long



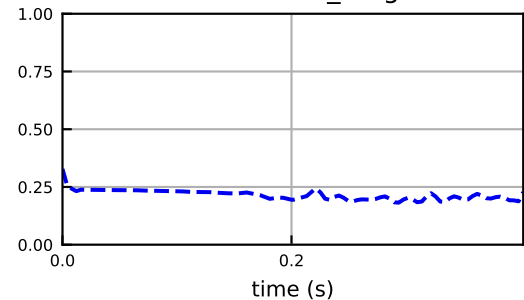
forcesetadd_brev



forcesetadd_mag1

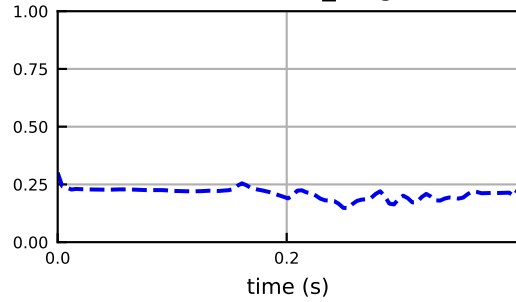


forcesetadd_mag2

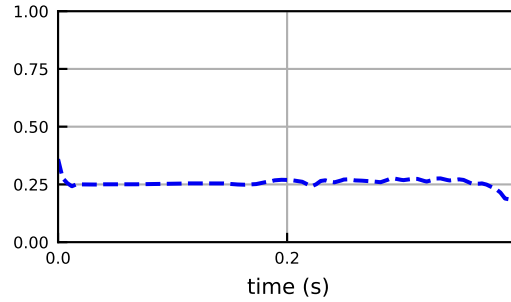


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (right leg)
- - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (left leg)

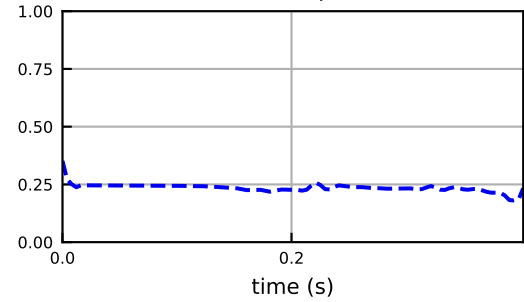
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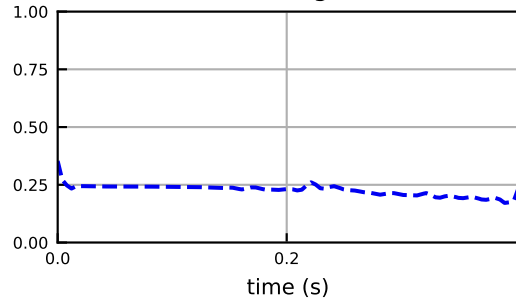
forcesettfl



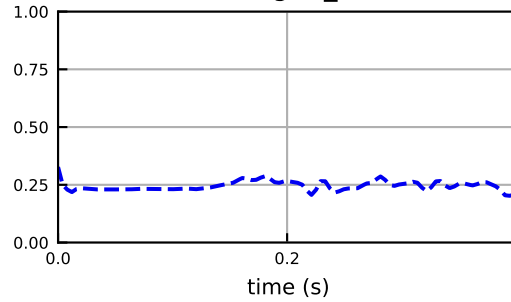
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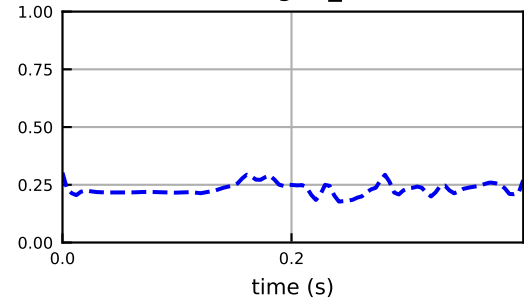
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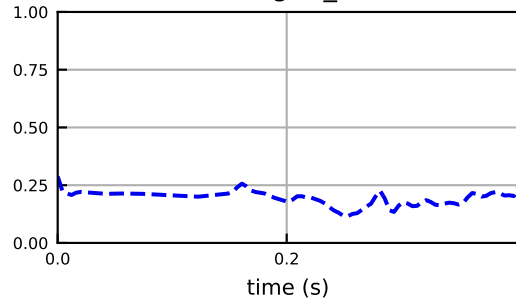
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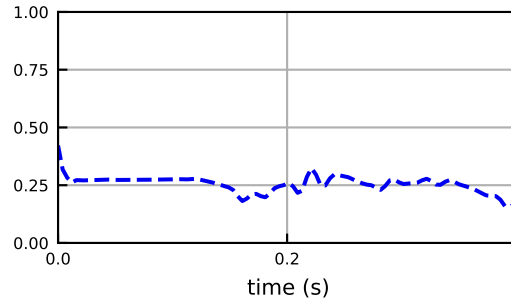
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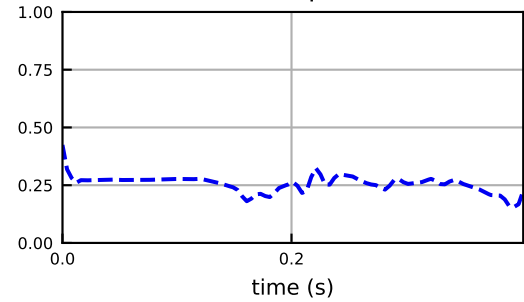
forcesetglut_max3



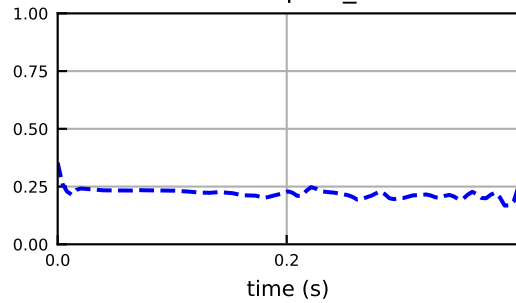
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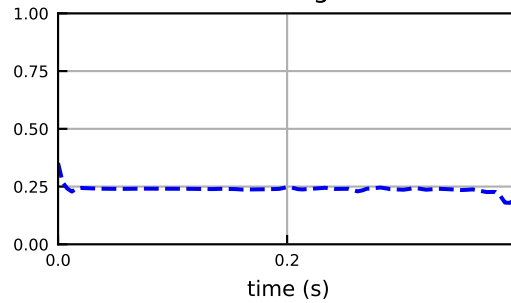
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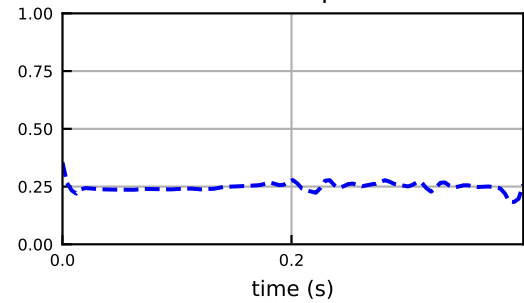
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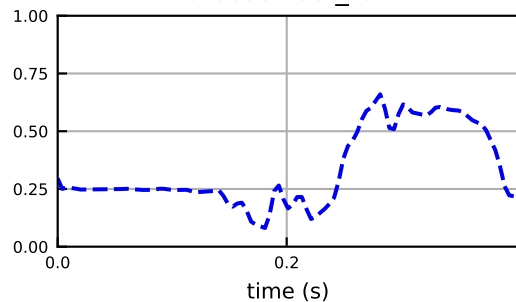
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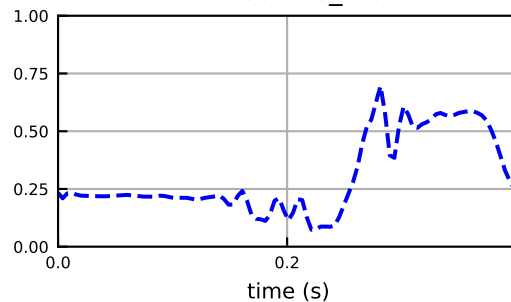
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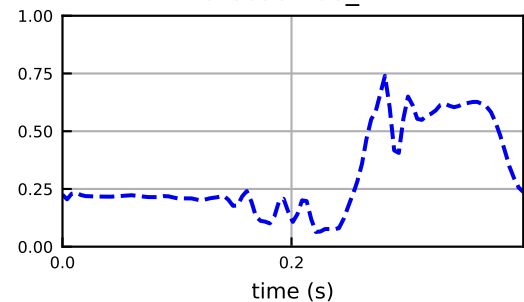
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forcesetvas_med

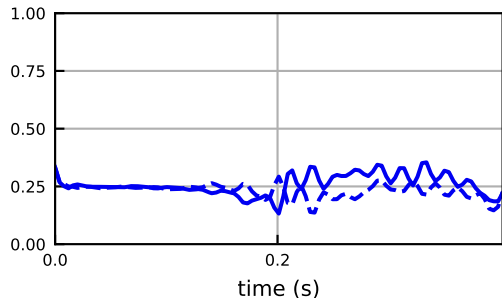


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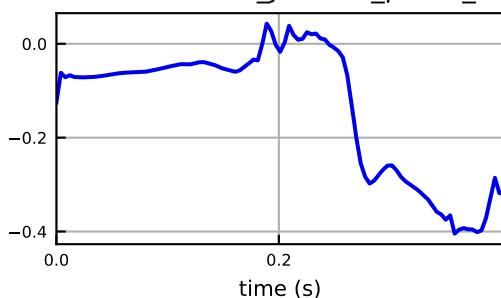


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (right leg)
- - - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (left leg)

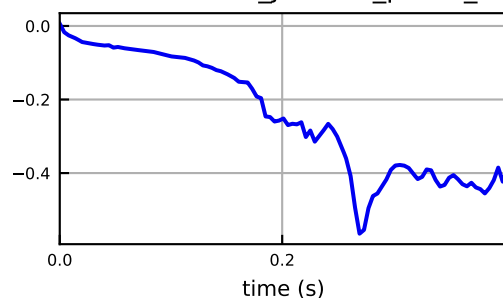
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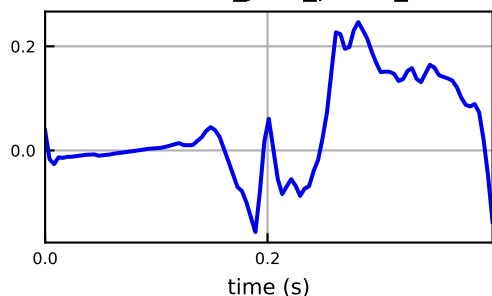
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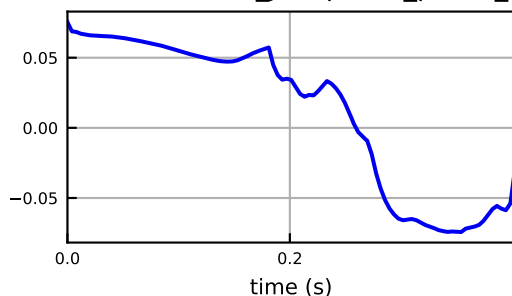
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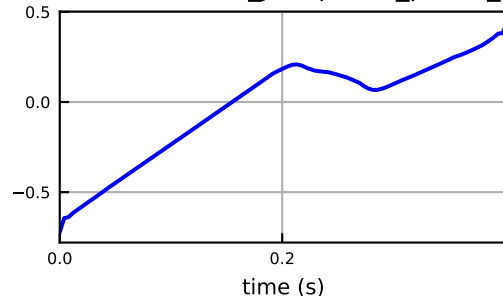
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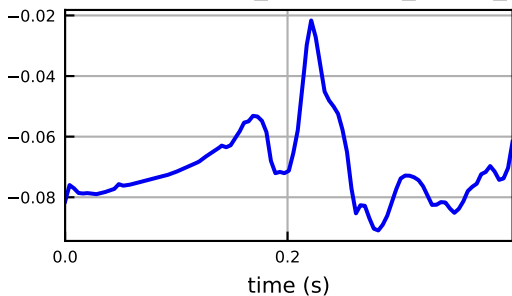
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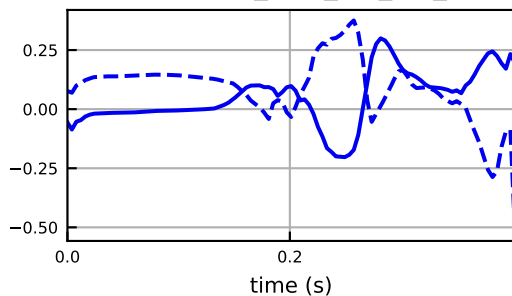
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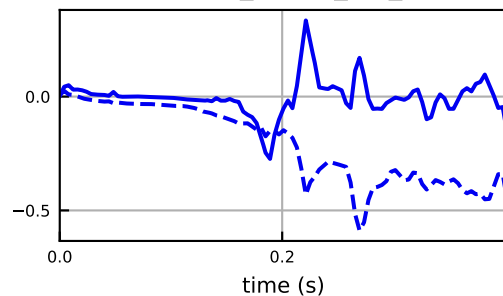
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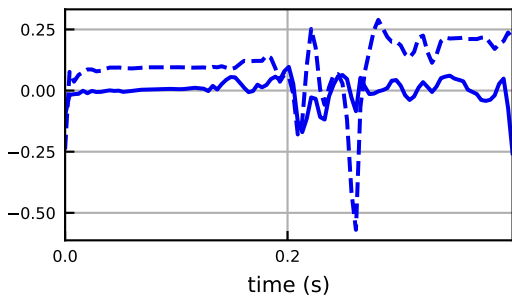
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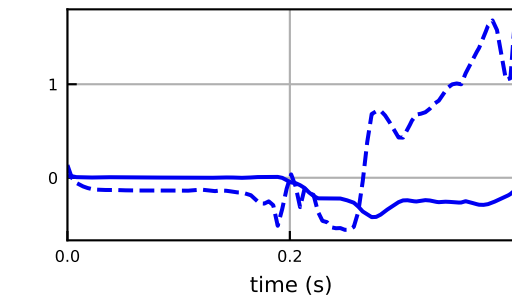
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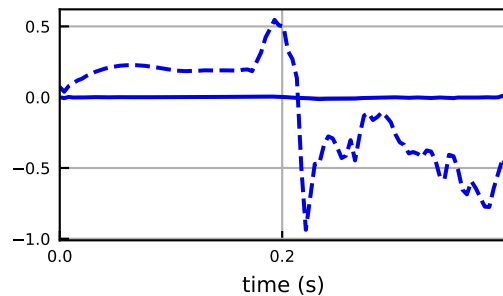
forcesetreserve_joi...hip_hip_rotation



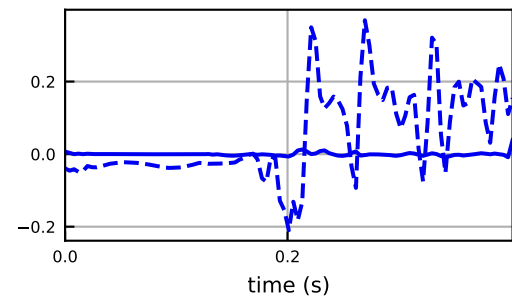
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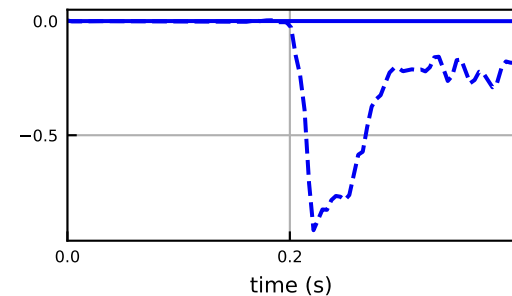
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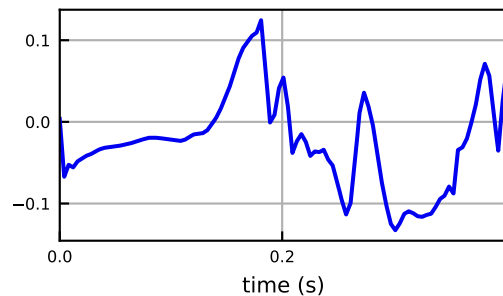
forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension



- D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (right leg)
- - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001\rot_6\solution.sto (left leg)

