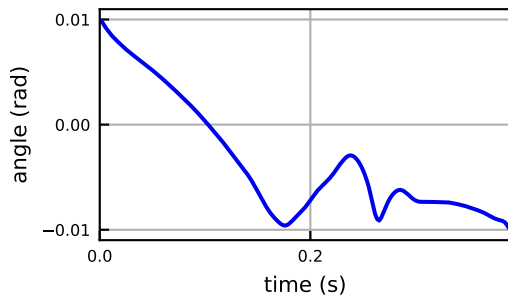
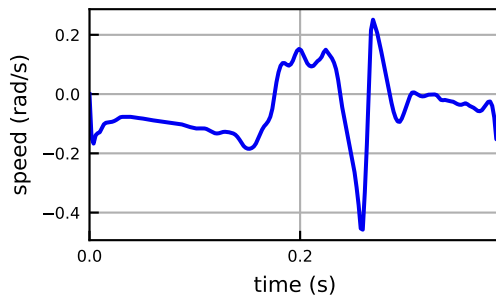


C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le

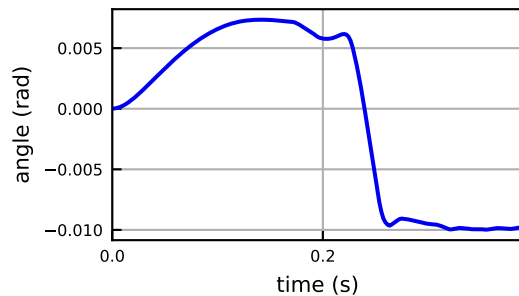
pelvis\_tilt/value



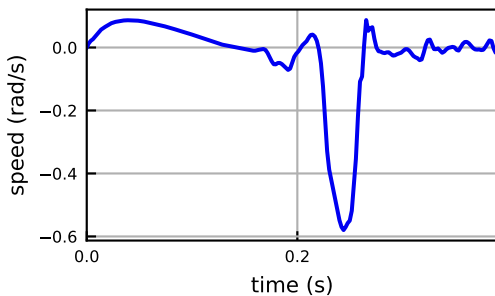
pelvis\_tilt/speed



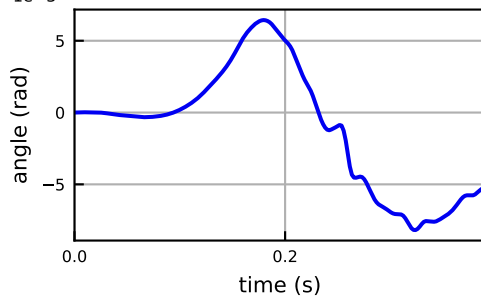
pelvis\_list/value



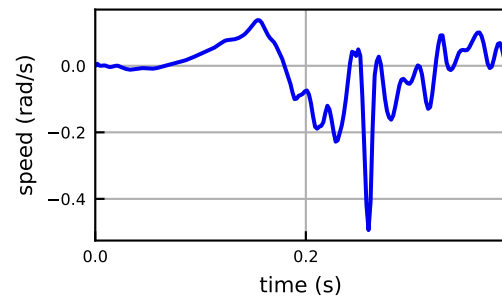
pelvis\_list/speed



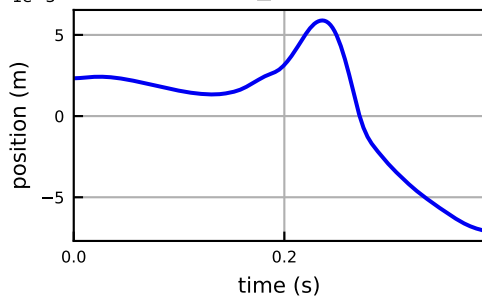
pelvis\_rotation/value



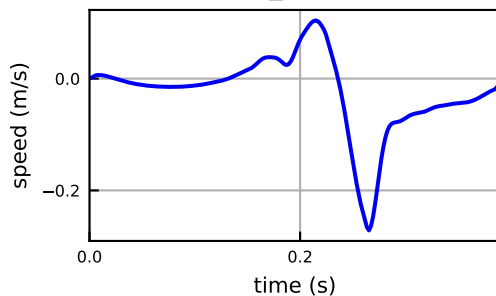
pelvis\_rotation/speed



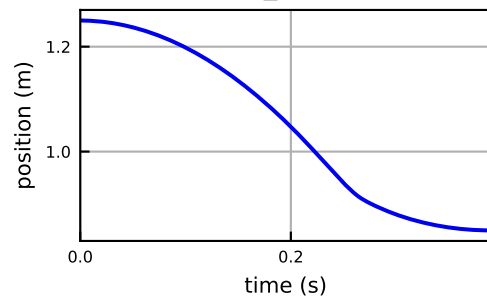
pelvis\_tx/value



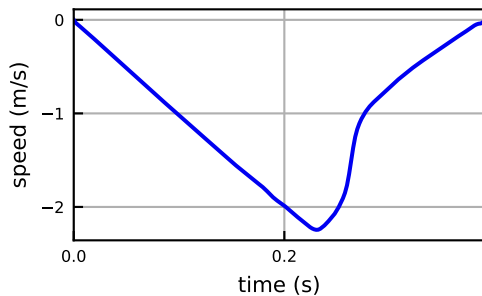
pelvis\_tx/speed



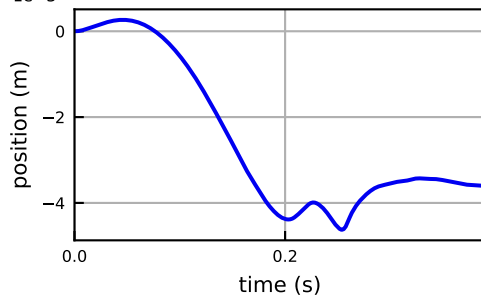
pelvis\_ty/value



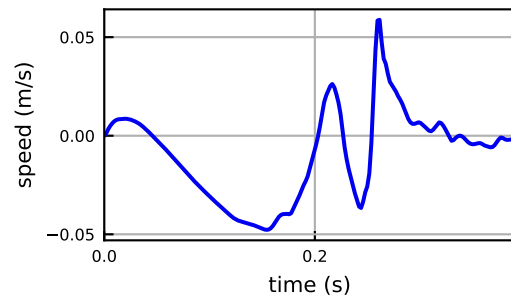
pelvis\_ty/speed



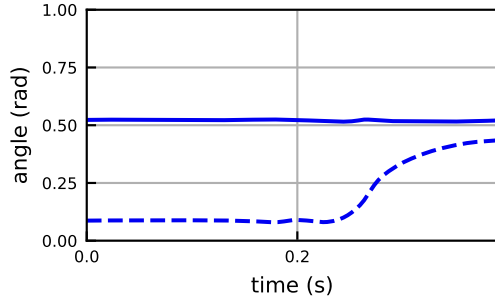
pelvis\_tz/value



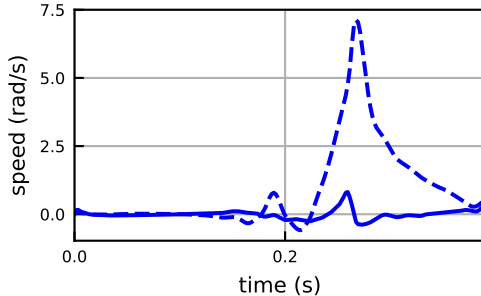
pelvis\_tz/speed



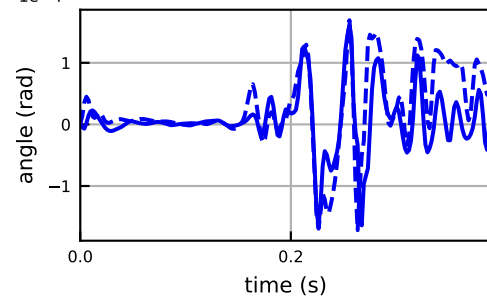
hip\_flexion/value



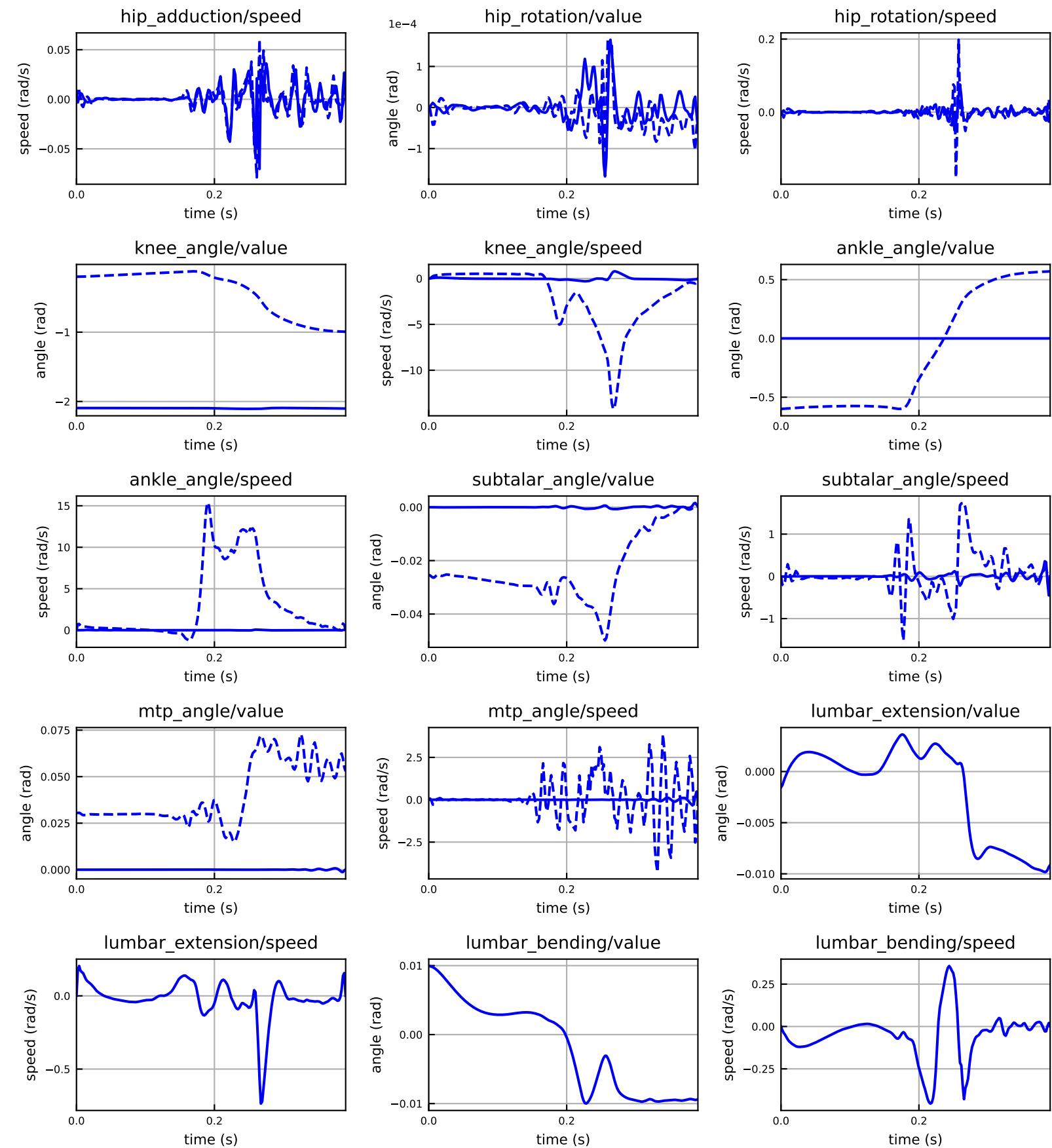
hip\_flexion/speed



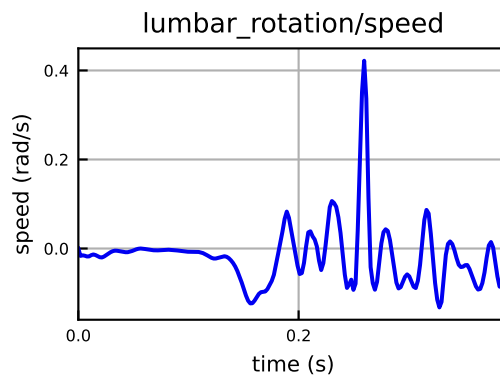
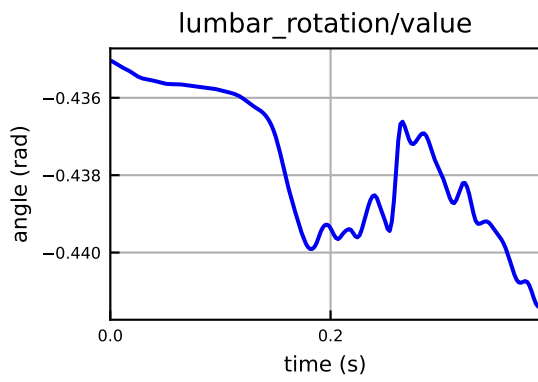
hip\_adduction/value



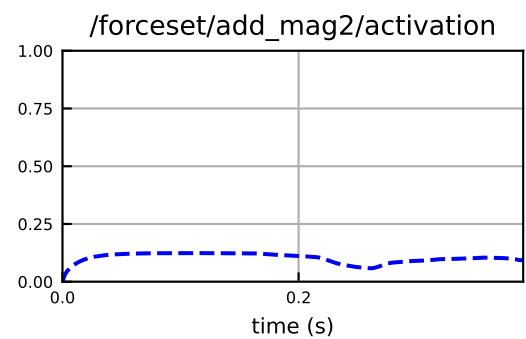
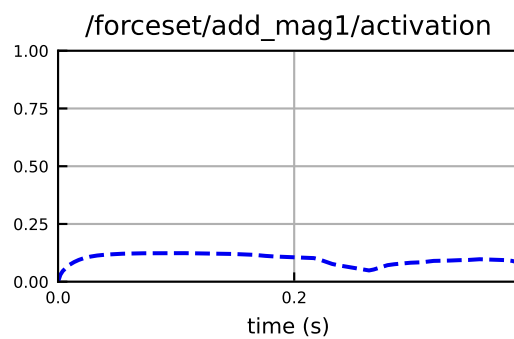
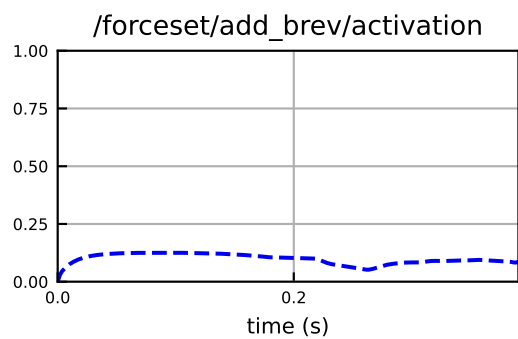
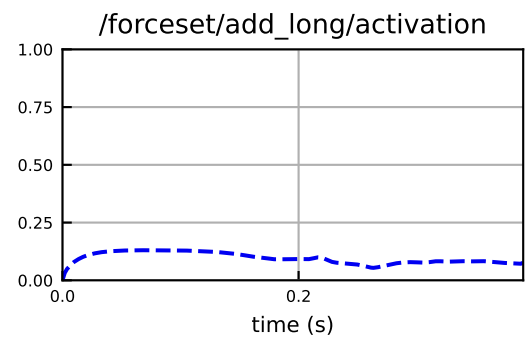
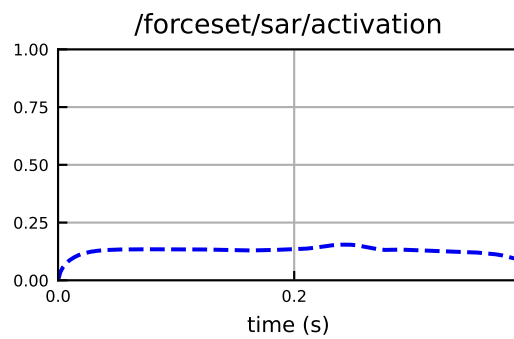
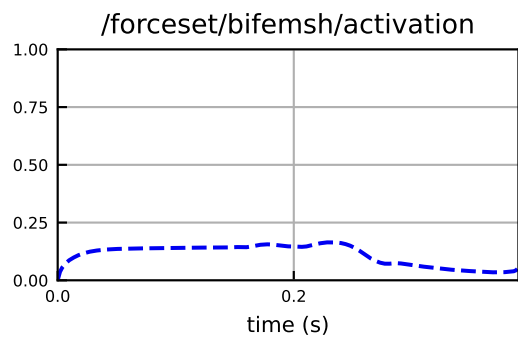
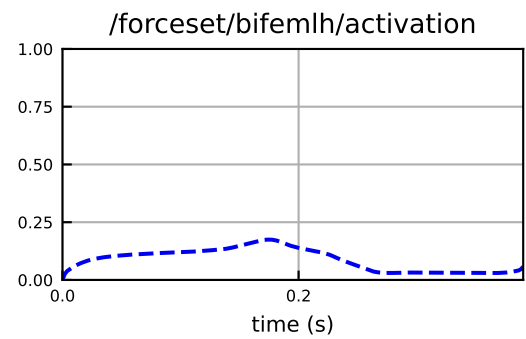
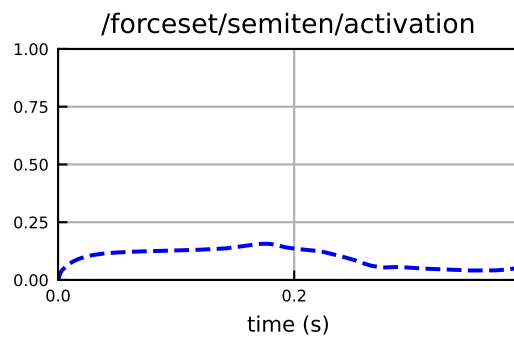
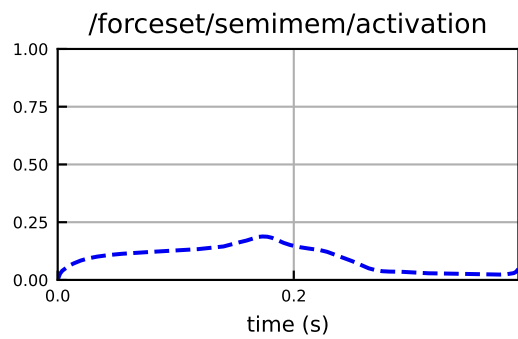
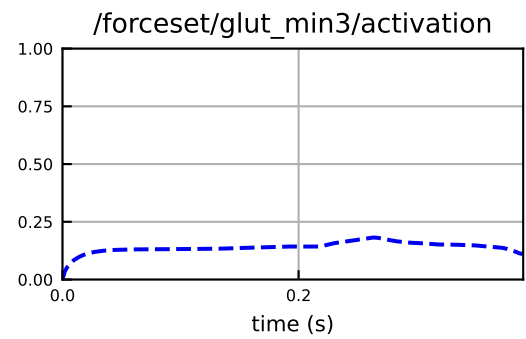
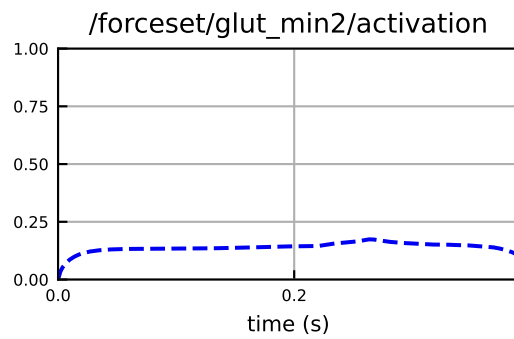
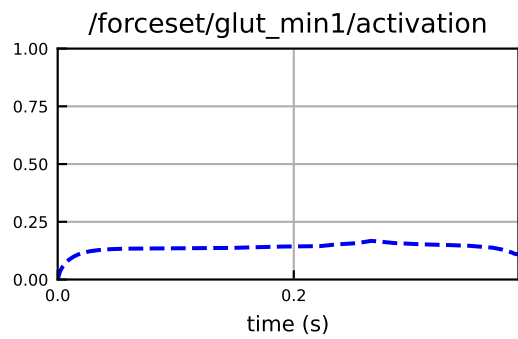
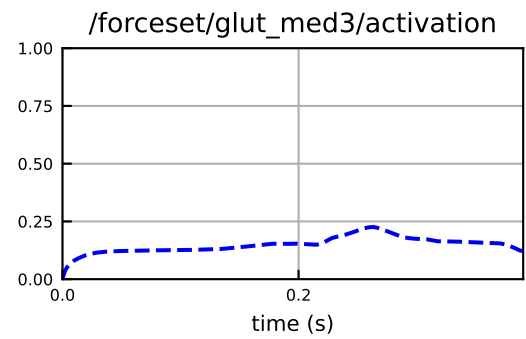
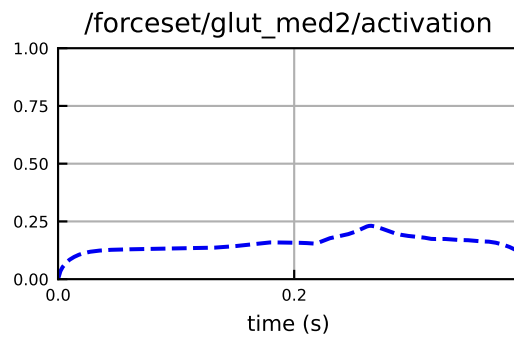
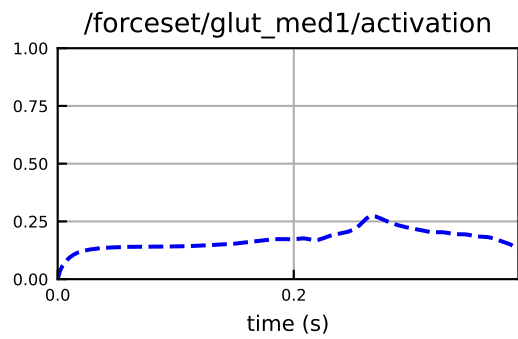
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right)  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left)



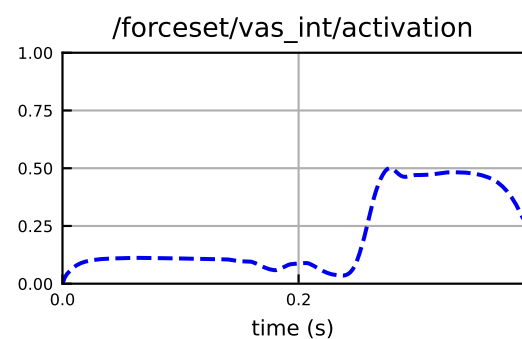
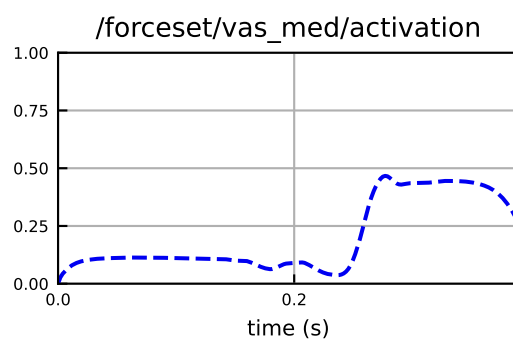
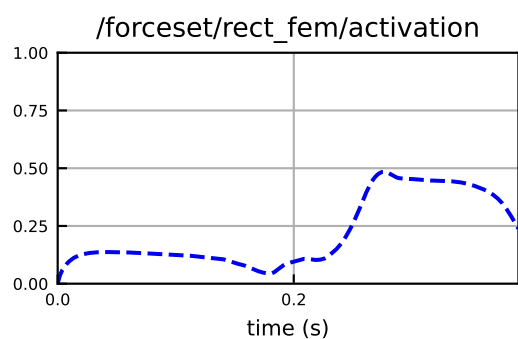
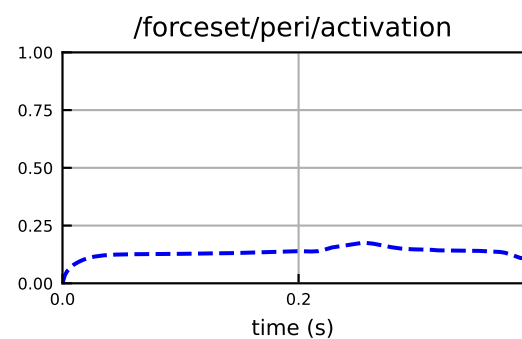
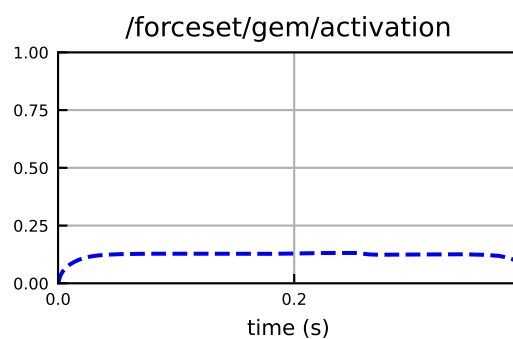
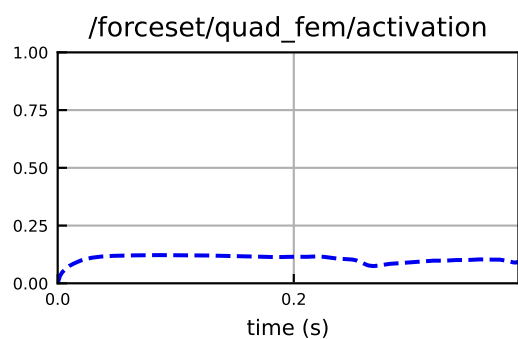
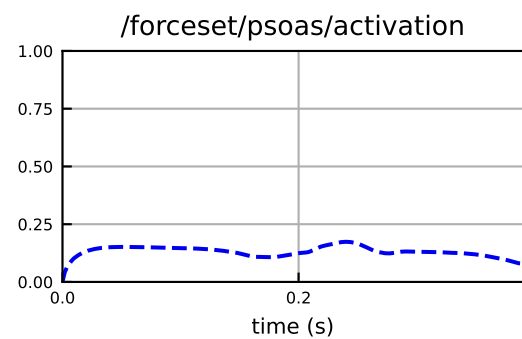
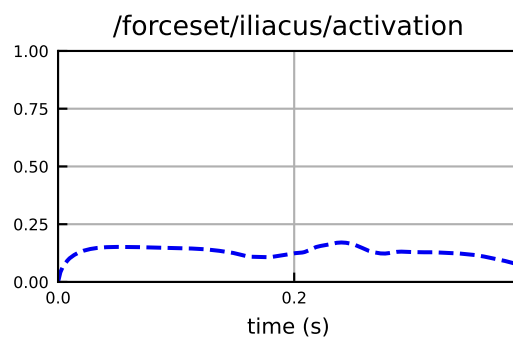
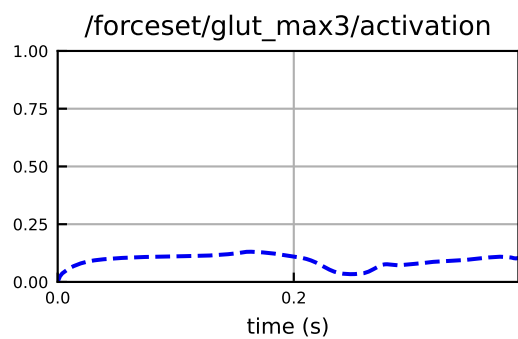
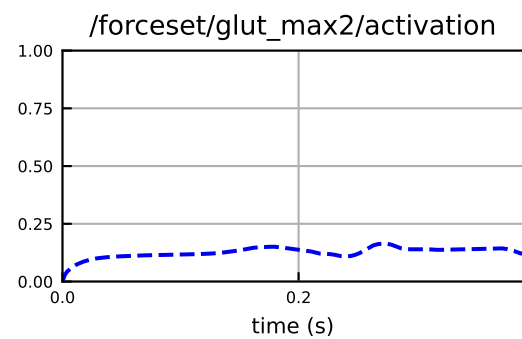
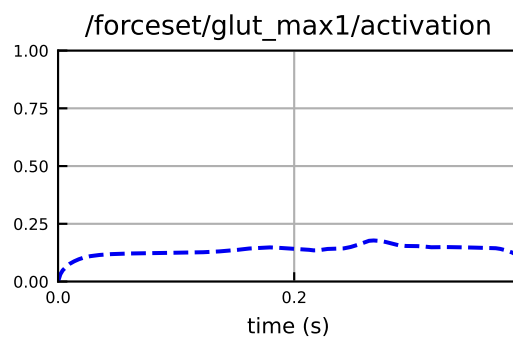
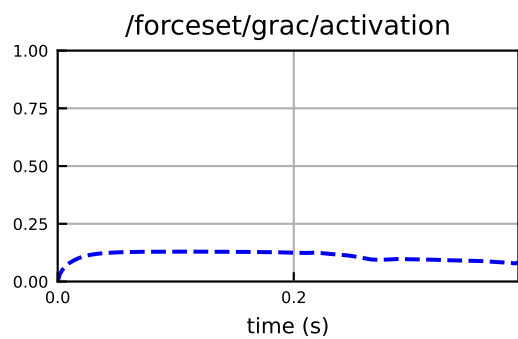
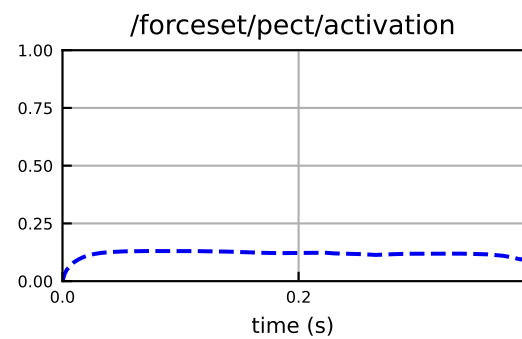
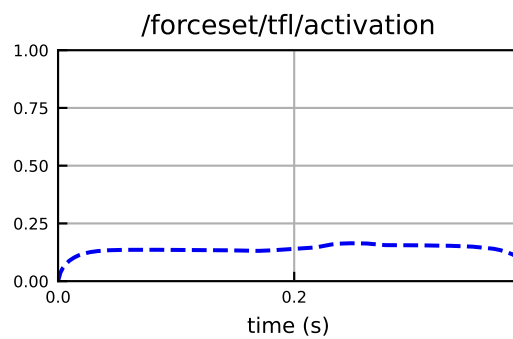
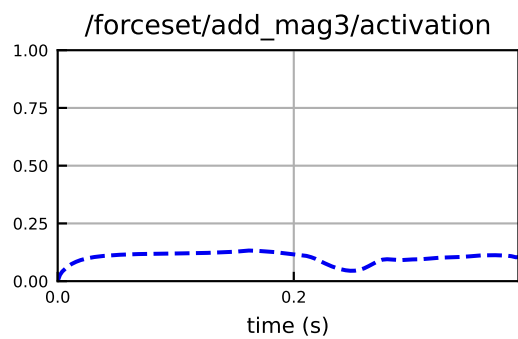
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le



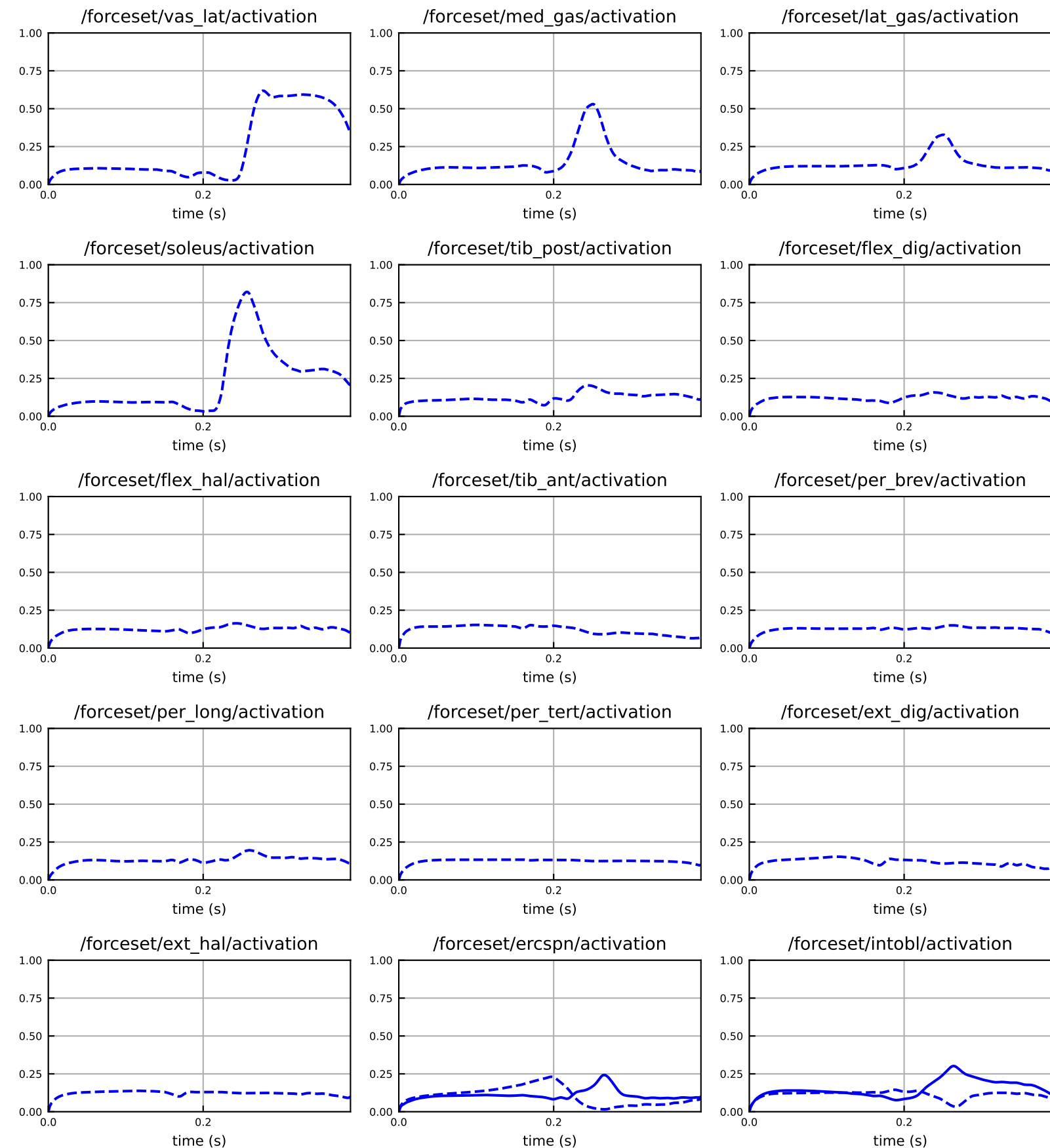
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right le  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le



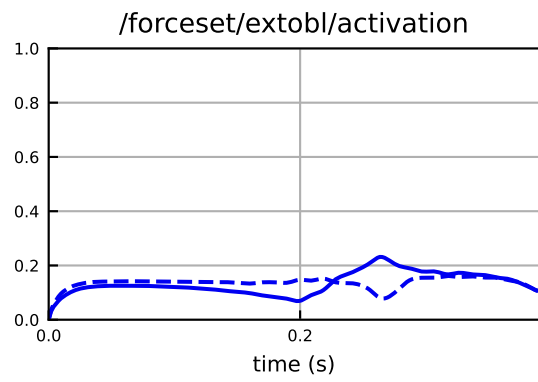
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right le  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le



C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right le  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le



- C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right)
- C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left)

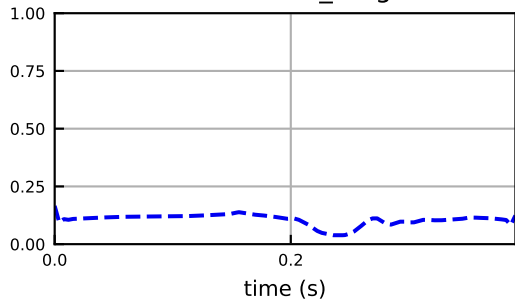




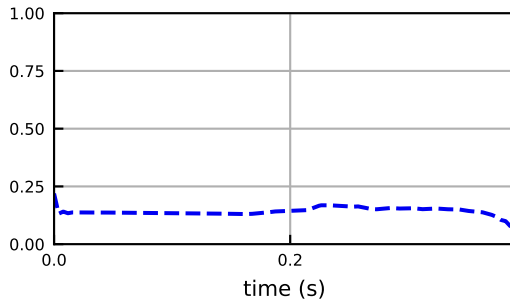


C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right le  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le

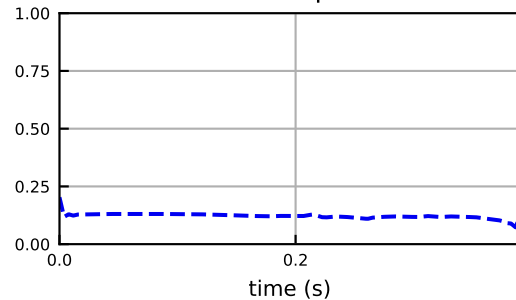
forcesetadd\_mag3



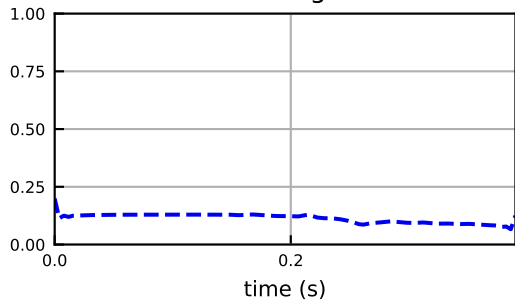
forcesetttfl



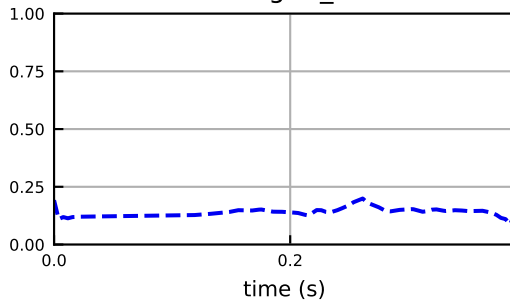
forcesetpect



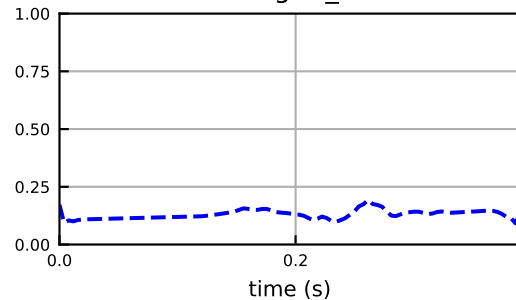
forcesetgrac



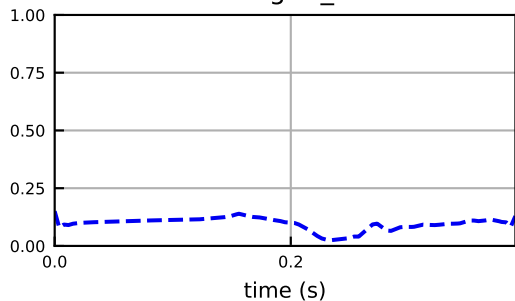
forcesetglut\_max1



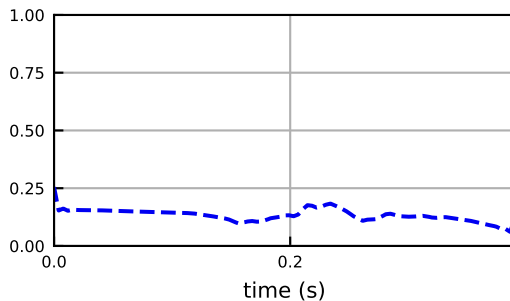
forcesetglut\_max2



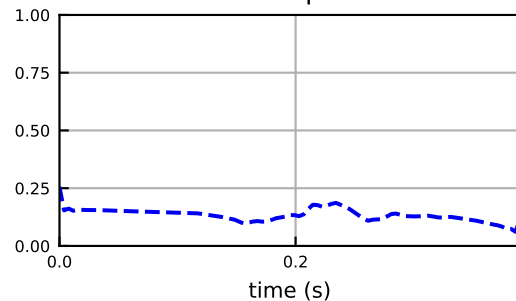
forcesetglut\_max3



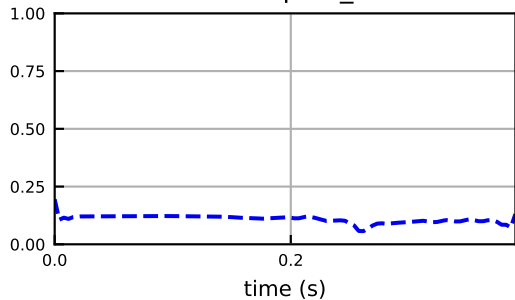
forcesetiliacus



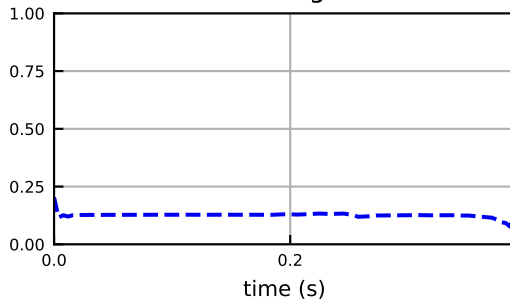
forcesetpsoas



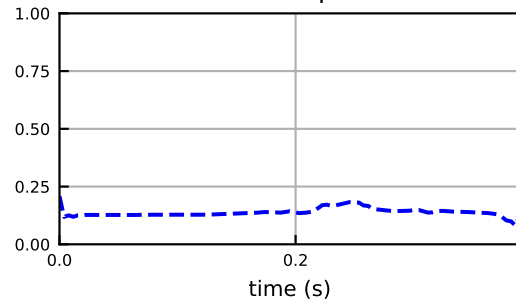
forcesetquad\_fem



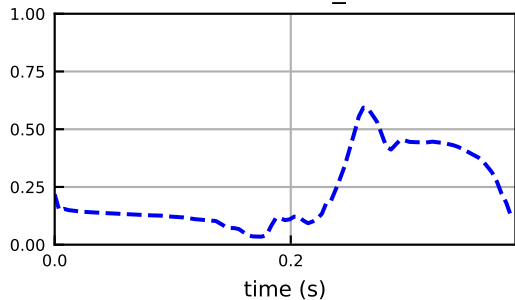
forcesetgem



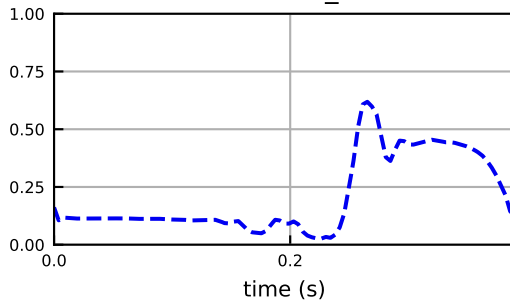
forcesetperi



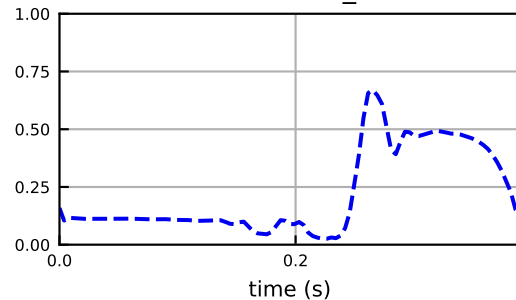
forcesetrect\_fem



forcesetvas\_med

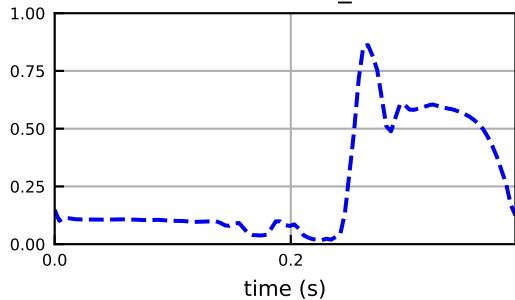


forcesetvas\_int

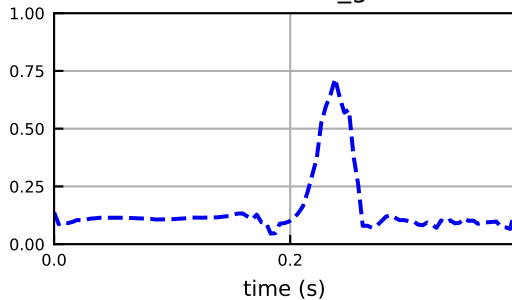


C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right le  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le

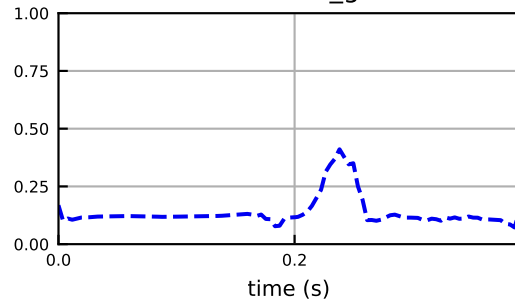
forcesetvas\_lat



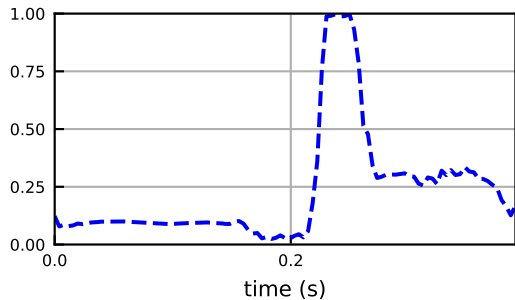
forcesetmed\_gas



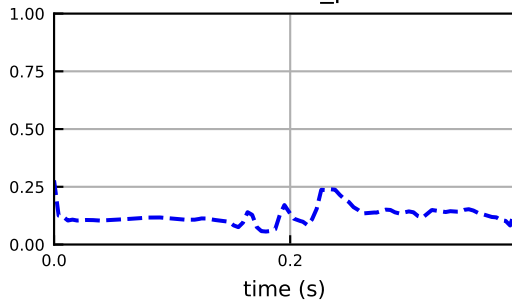
forcesetlat\_gas



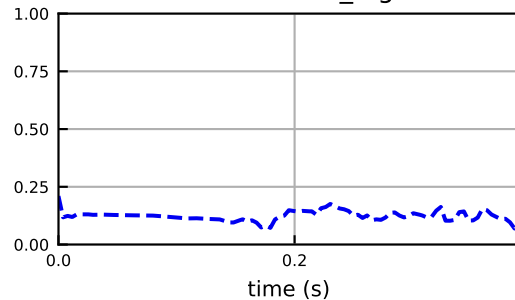
forcesetsoleus



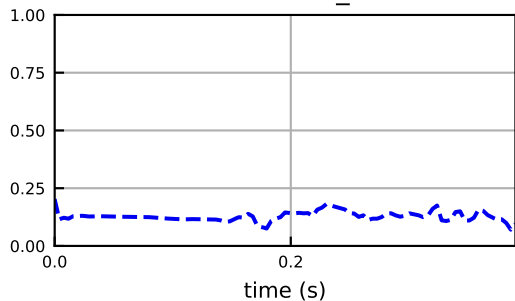
forcesettib\_post



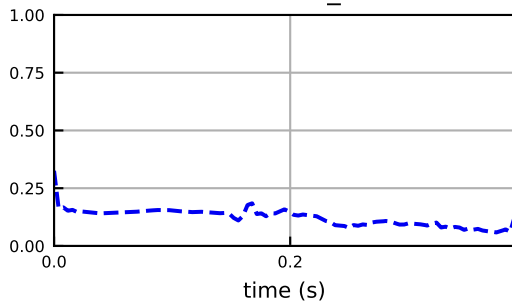
forcesetflex\_dig



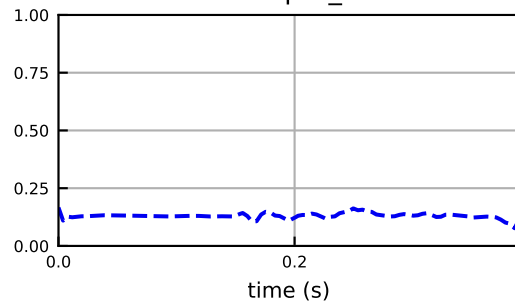
forcesetflex\_hal



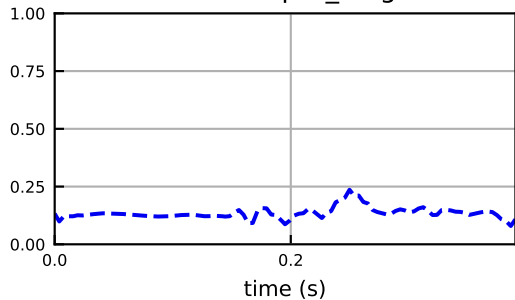
forcesettib\_ant



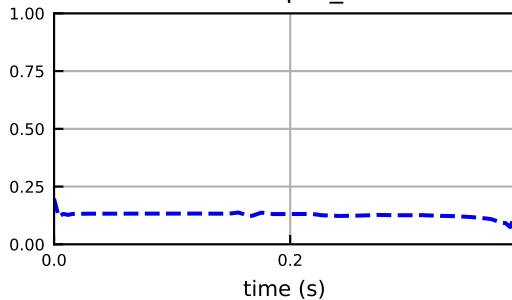
forcesetper\_brev



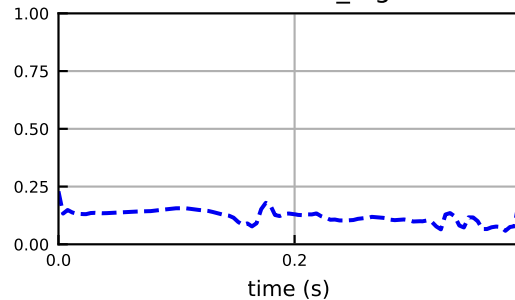
forcesetper\_long



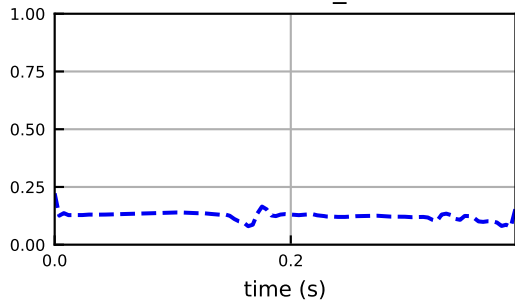
forcesetper\_tert



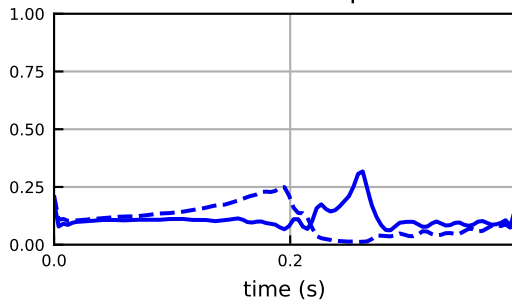
forcesetext\_dig



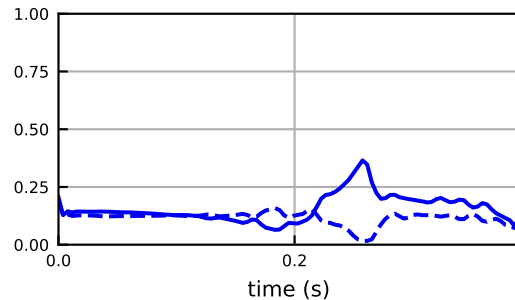
forcesetext\_hal



forcesetercspn

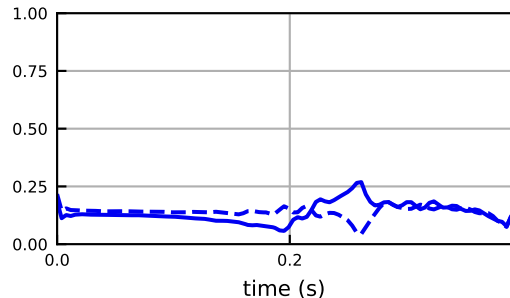


forcesetintobl

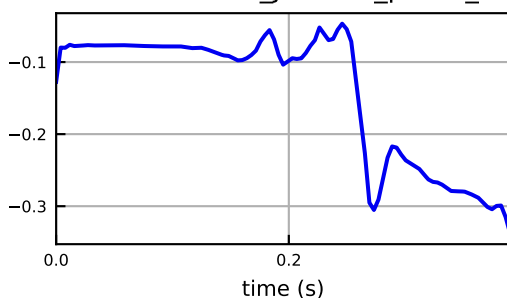


C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le

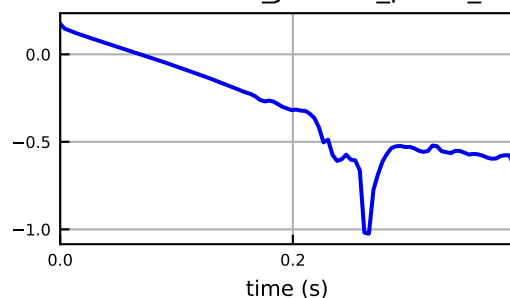
forcesetextobl



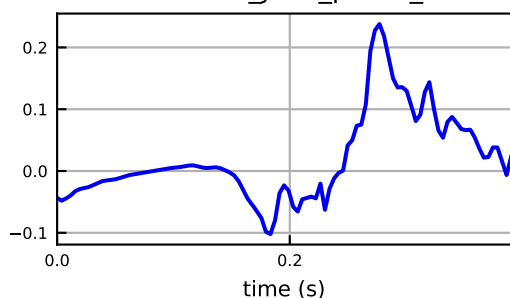
forcesetreserve\_joi...lvis\_pelvis\_tilt



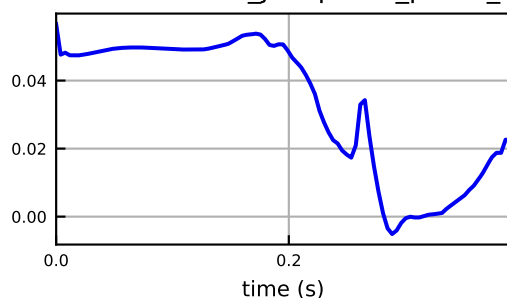
forcesetreserve\_joi...lvis\_pelvis\_list



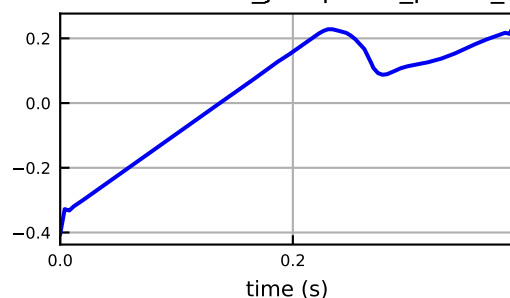
forcesetreserve\_joi...\_pelvis\_rotation



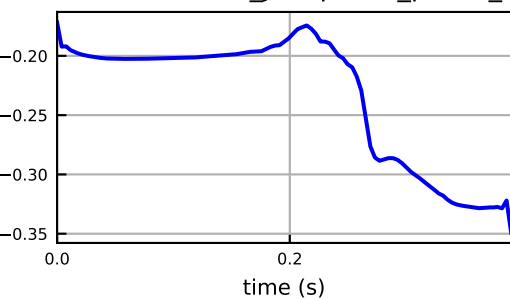
forcesetreserve\_joi...pelvis\_pelvis\_tx



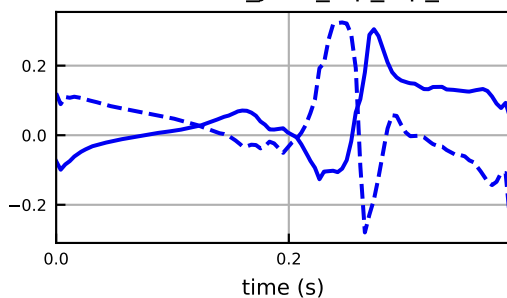
forcesetreserve\_joi...pelvis\_pelvis\_ty



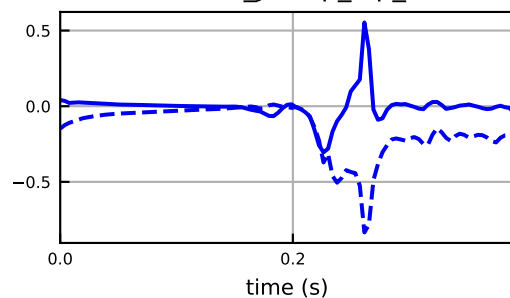
forcesetreserve\_joi...pelvis\_pelvis\_tz



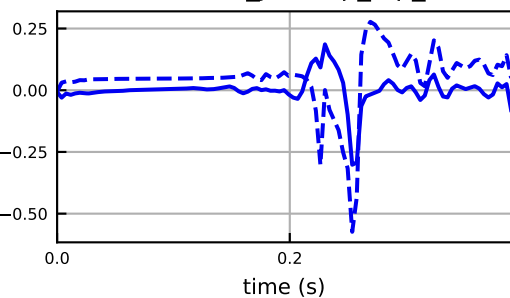
forcesetreserve\_joi...\_hip\_hip\_flexion



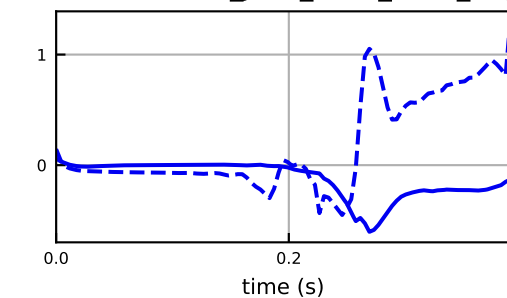
forcesetreserve\_joi...ip\_hip\_adduction



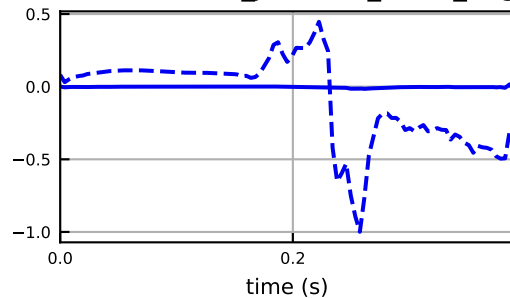
forcesetreserve\_joi...hip\_hip\_rotation



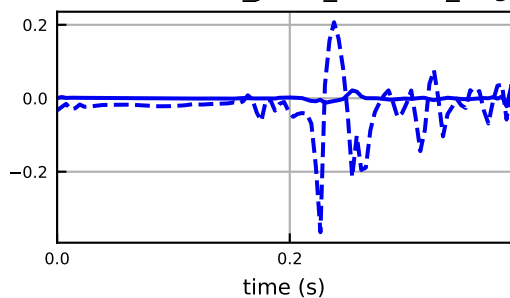
forcesetreserve\_joi...\_knee\_knee\_angle



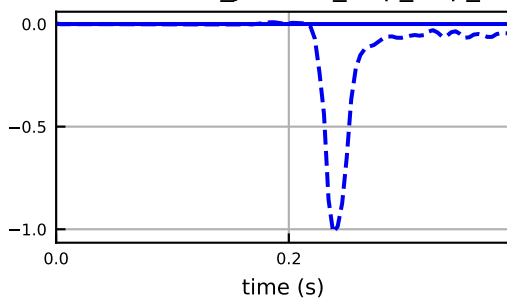
forcesetreserve\_joi...nkle\_ankle\_angle



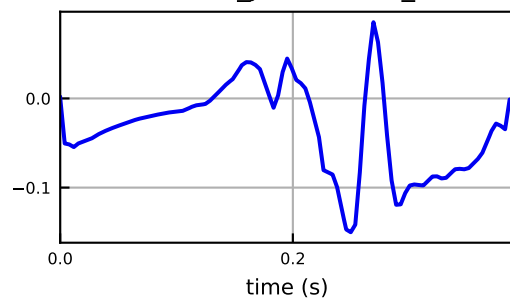
forcesetreserve\_joi...r\_subtalar\_angle



forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension



C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (right  
C:\Users\Mike\Desktop\tzeni\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\_2\rot\_-25\solution.sto (left le

forcesetreserve\_joi...k\_lumbar\_bending    forcesetreserve\_joi...\_lumbar\_rotation

