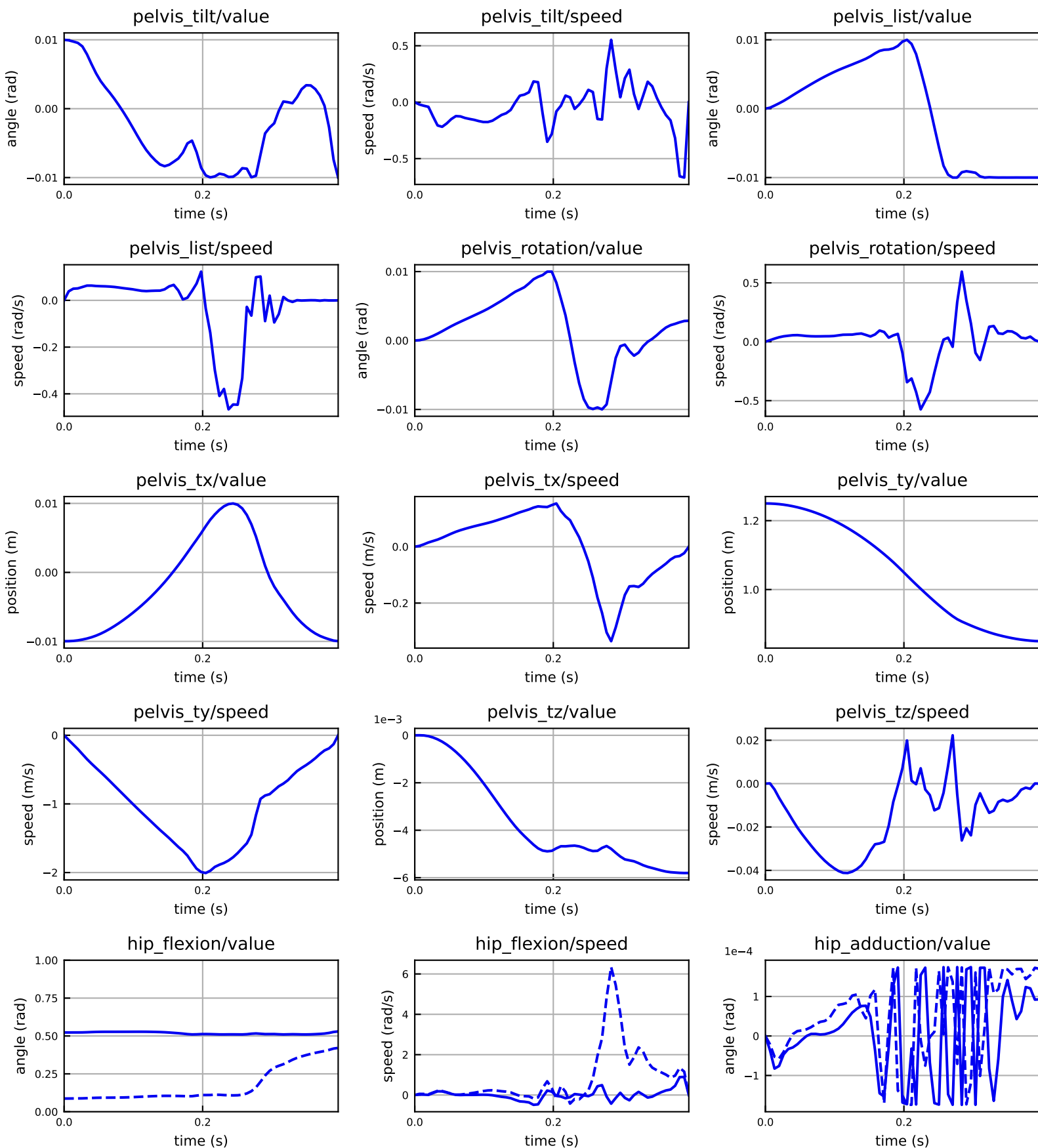
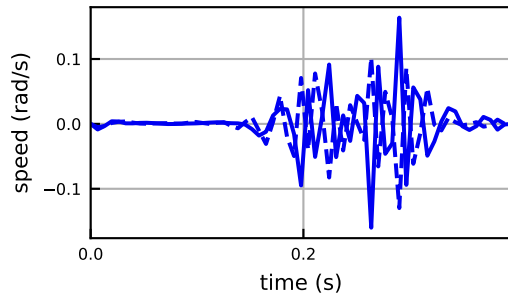


— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (right leg)  
- - - D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (left leg)

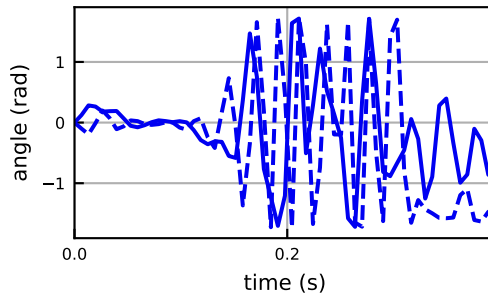


— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (right leg)  
- - - D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (left leg)

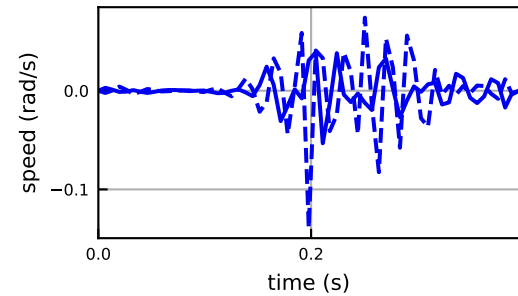
hip\_adduction/speed



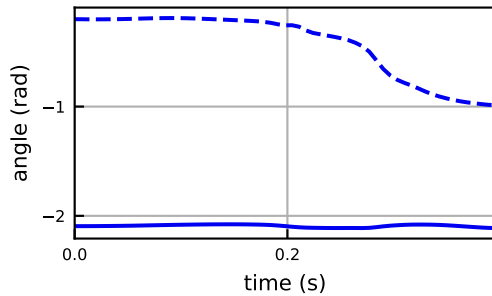
hip\_rotation/value



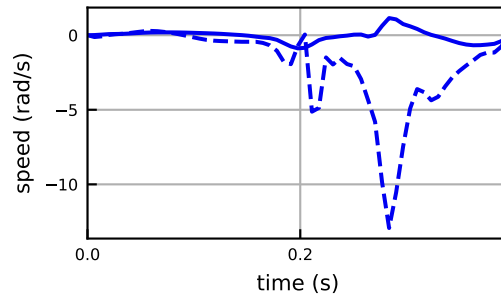
hip\_rotation/speed



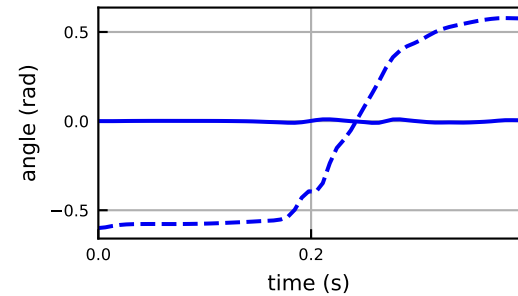
knee\_angle/value



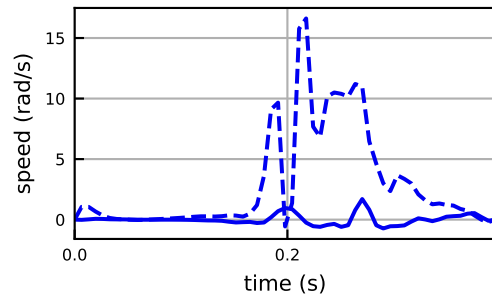
knee\_angle/speed



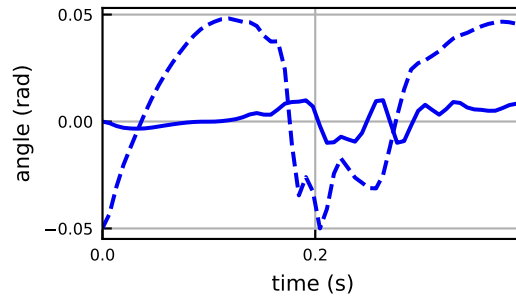
ankle\_angle/value



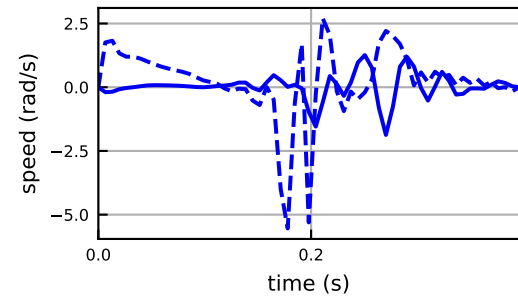
ankle\_angle/speed



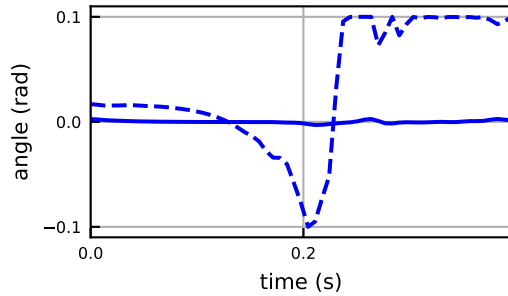
subtalar\_angle/value



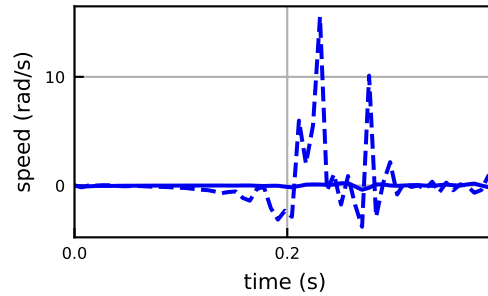
subtalar\_angle/speed



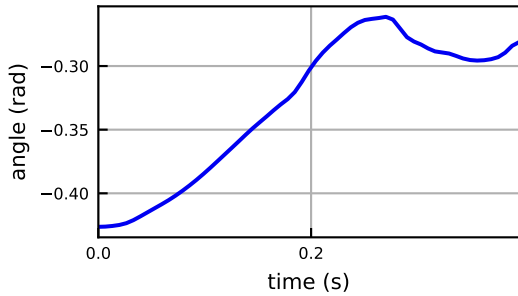
mtp\_angle/value



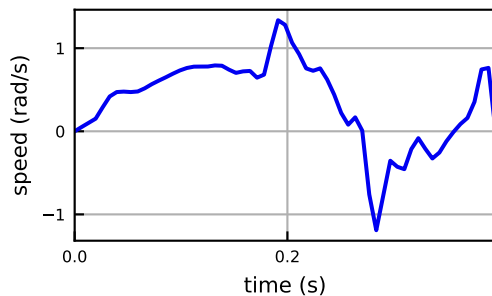
mtp\_angle/speed



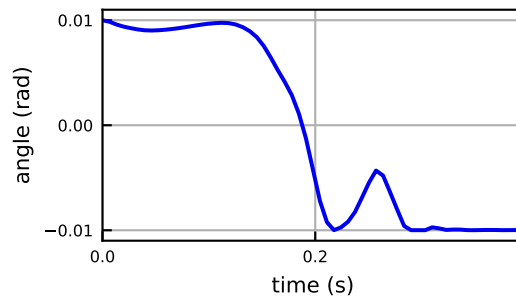
lumbar\_extension/value



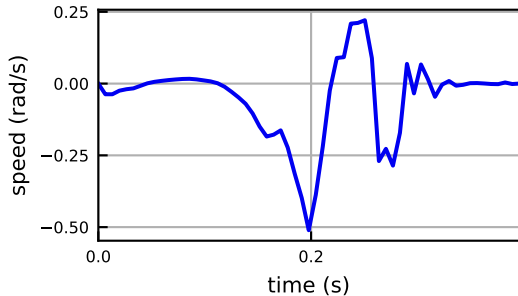
lumbar\_extension/speed

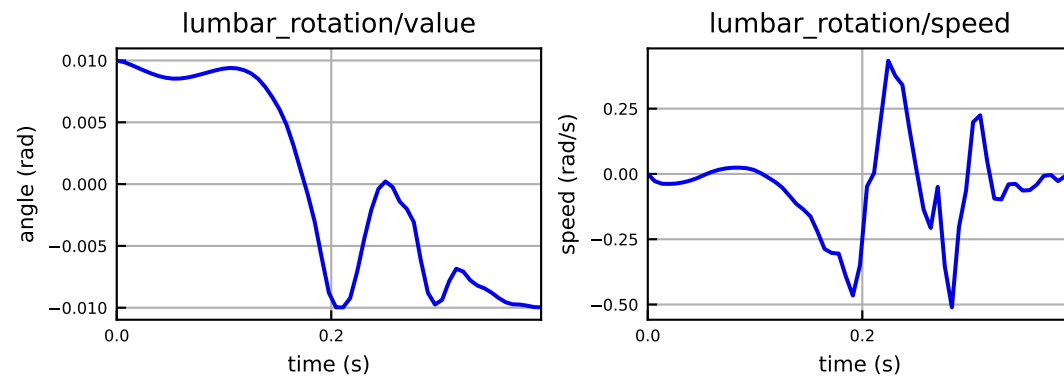


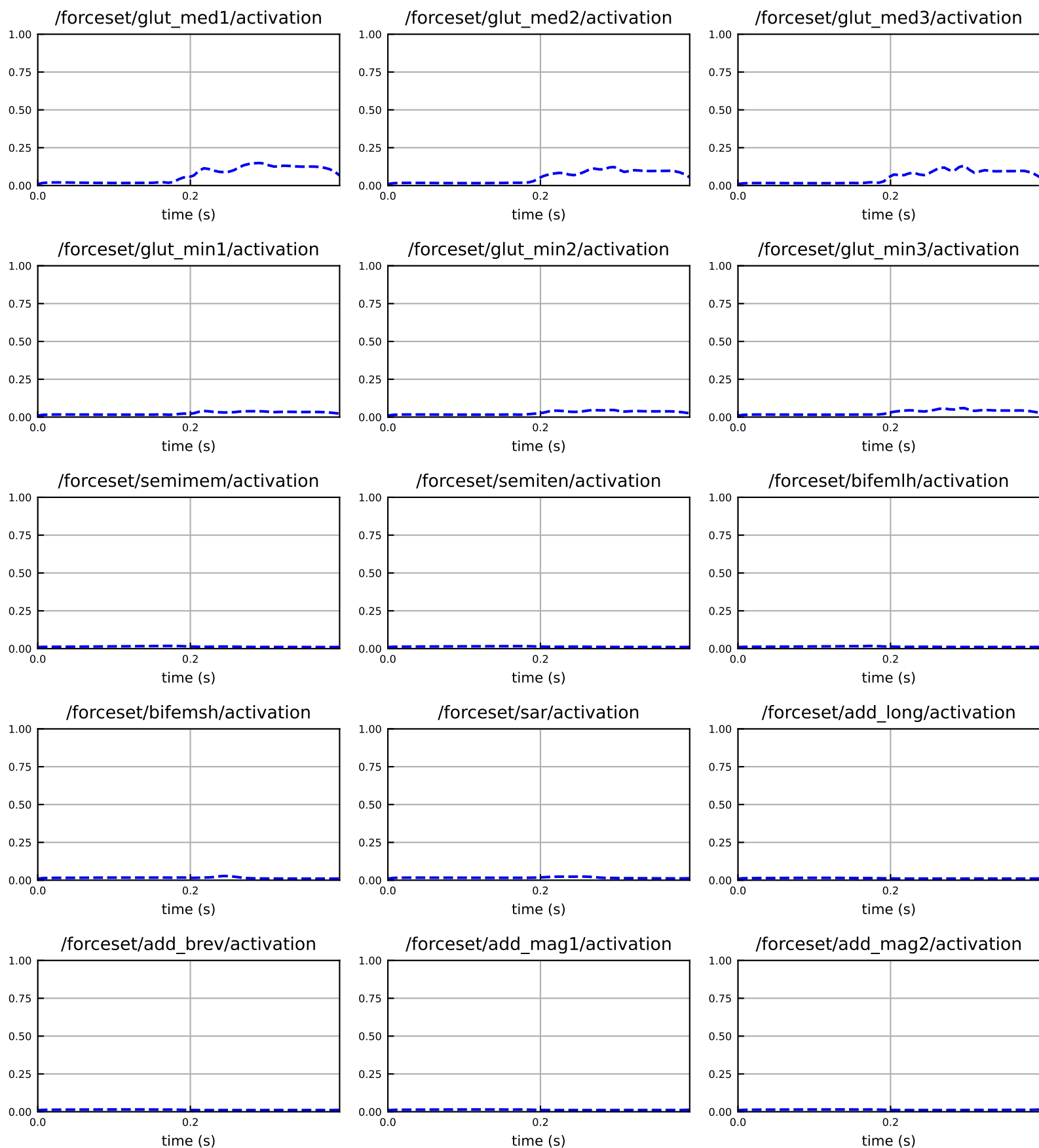
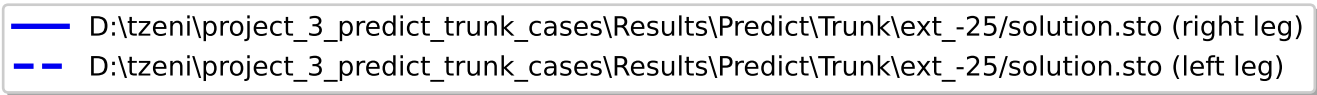
lumbar\_bending/value



lumbar\_bending/speed

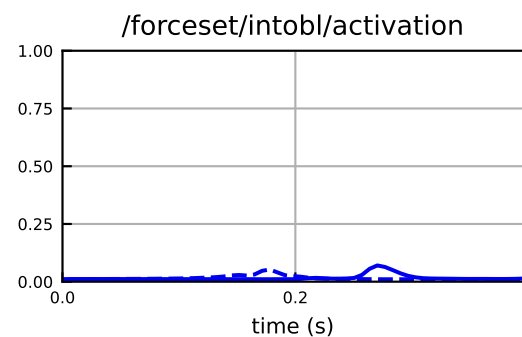
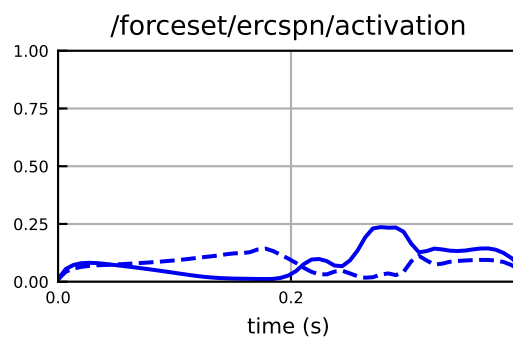
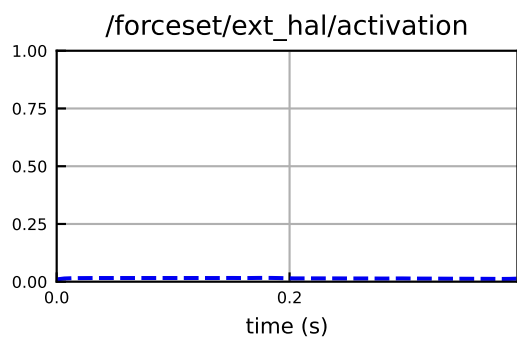
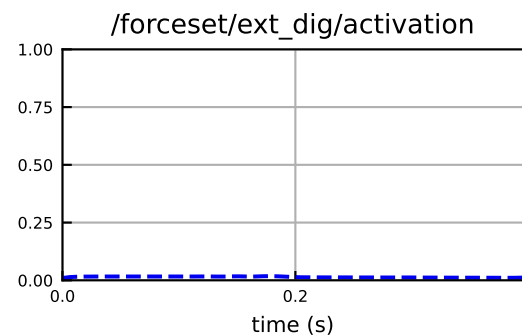
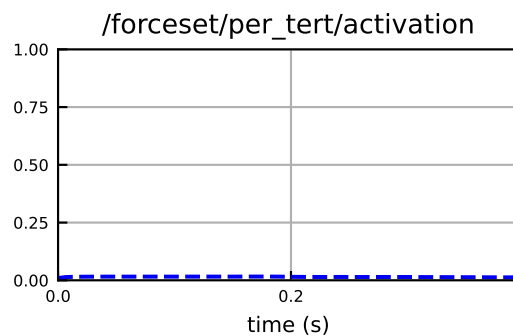
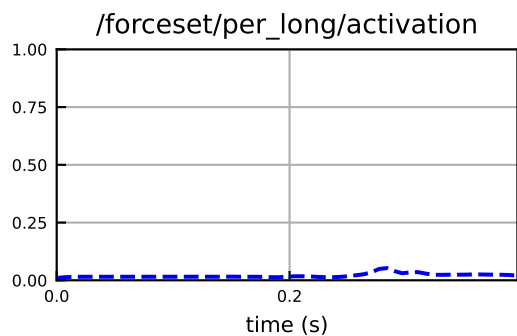
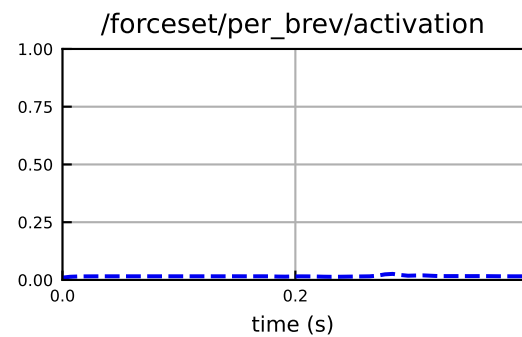
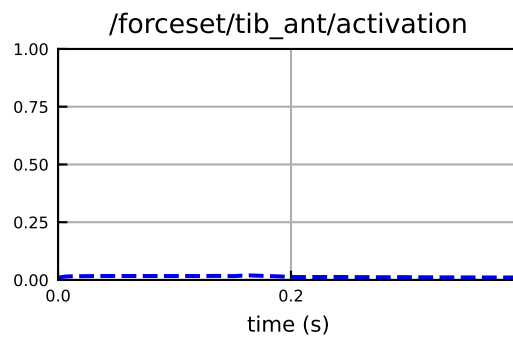
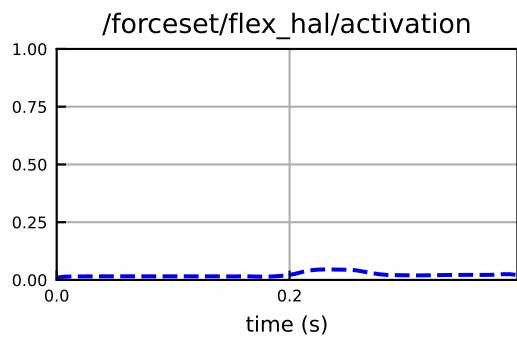
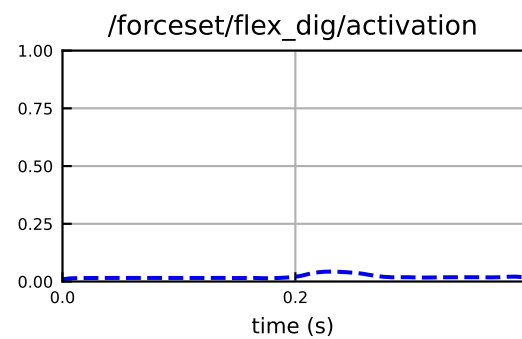
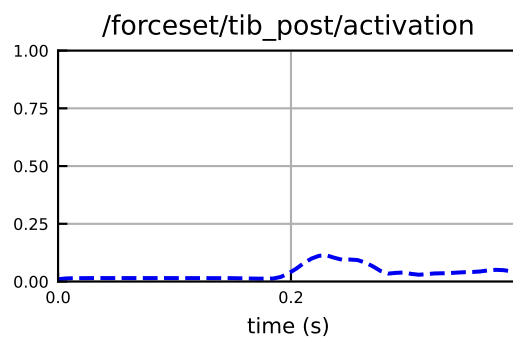
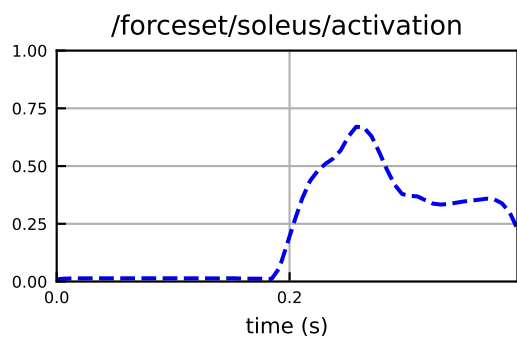
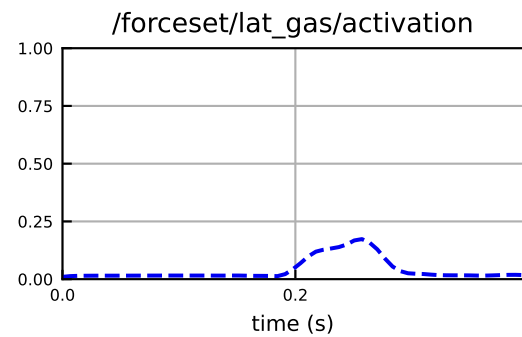
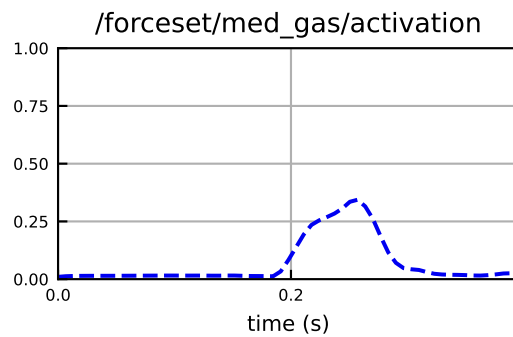
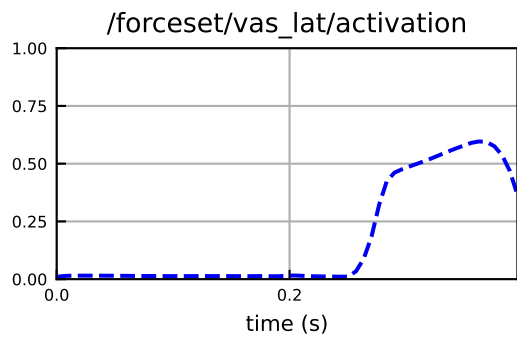


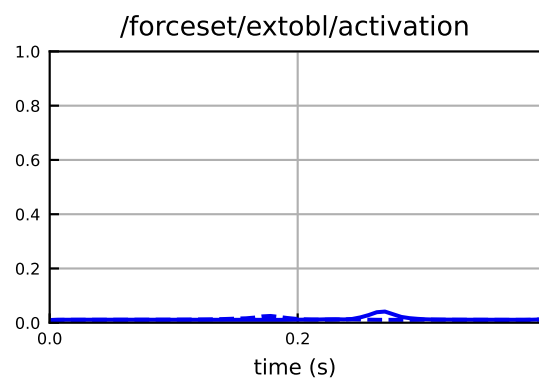
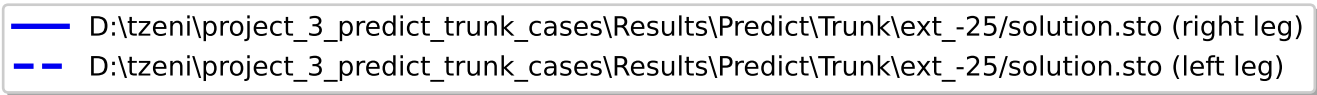


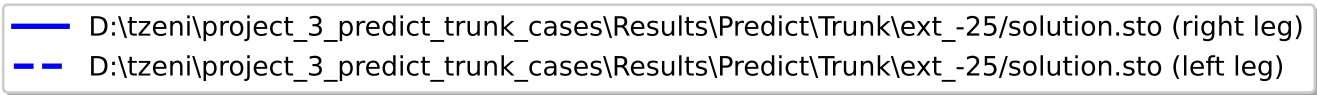




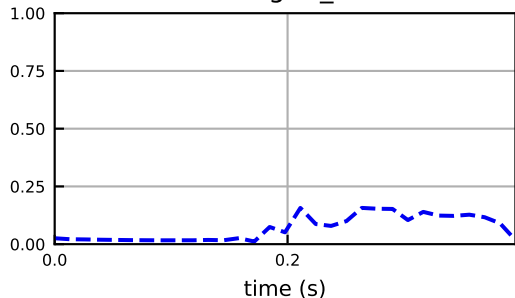
— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (right leg)  
- - D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (left leg)



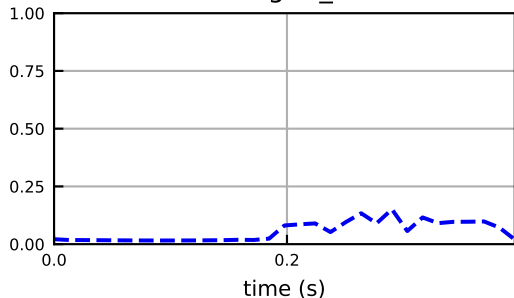




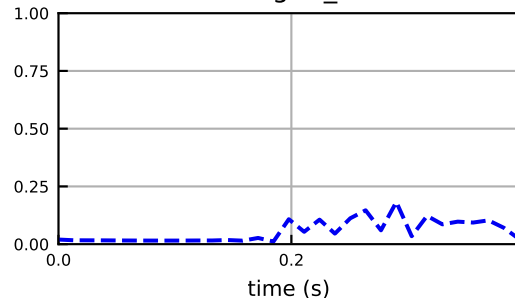
forcesetglut\_med1



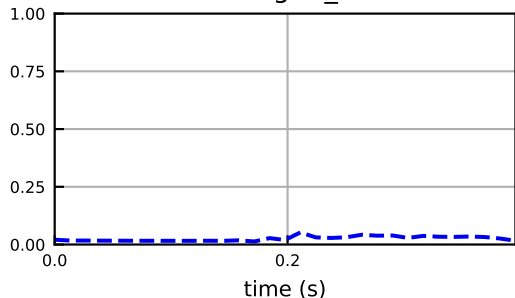
forcesetglut\_med2



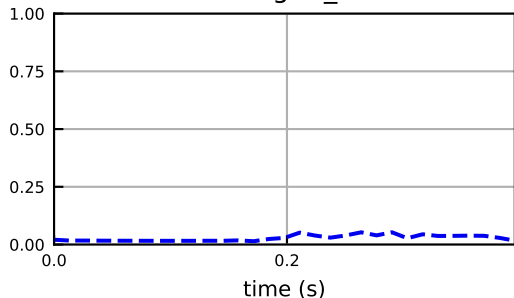
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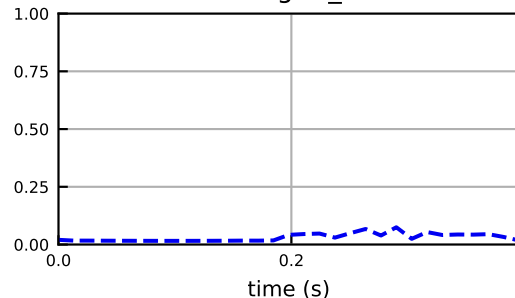
forcesetglut\_min1



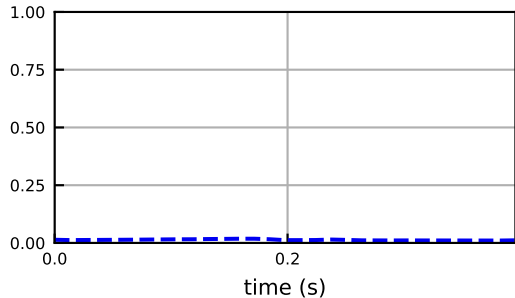
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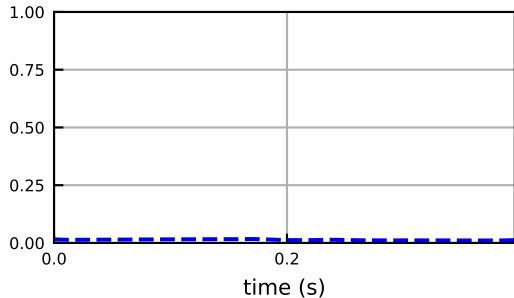
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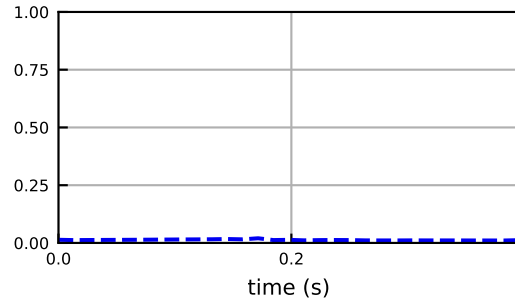
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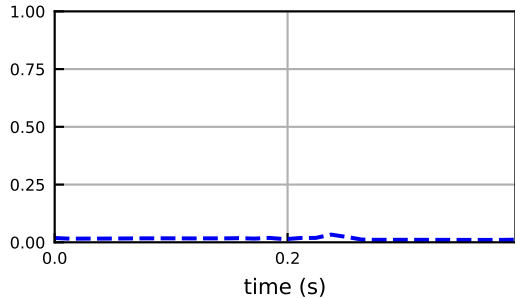
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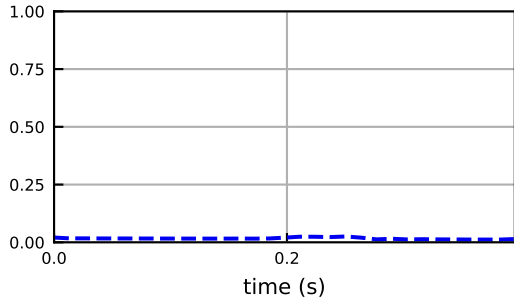
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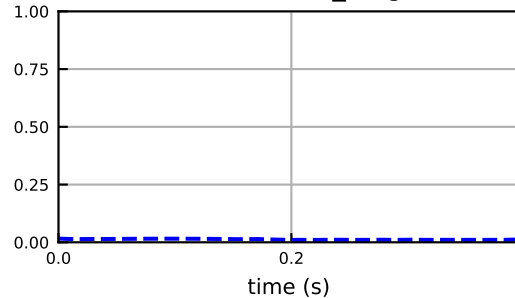
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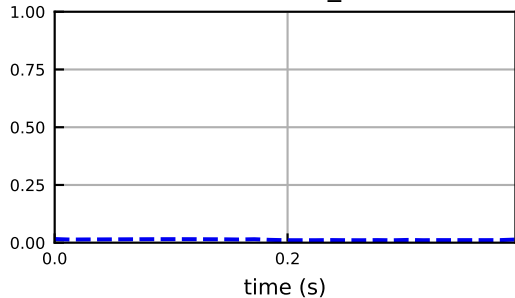
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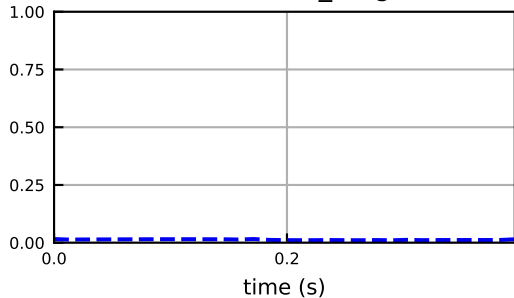
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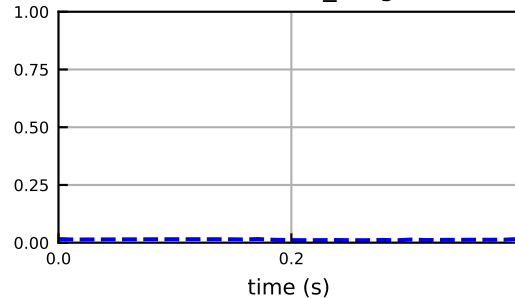
forcesetadd\_brev



forcesetadd\_mag1



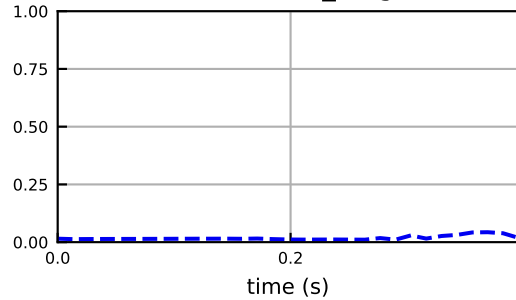
forcesetadd\_mag2



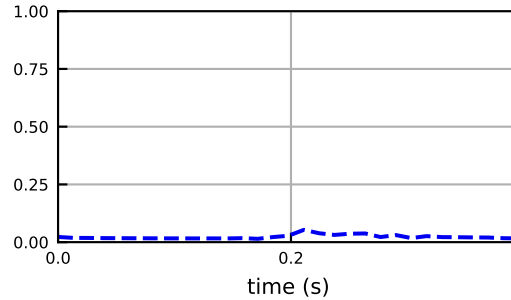


— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (right leg)  
- - - D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (left leg)

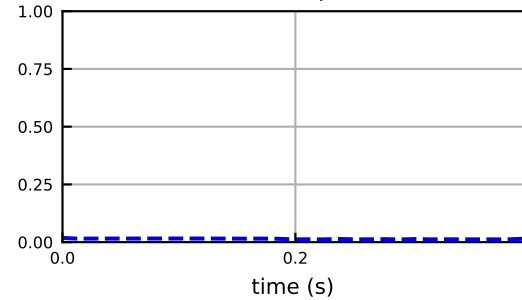
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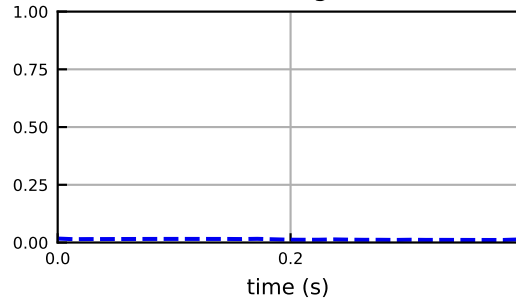
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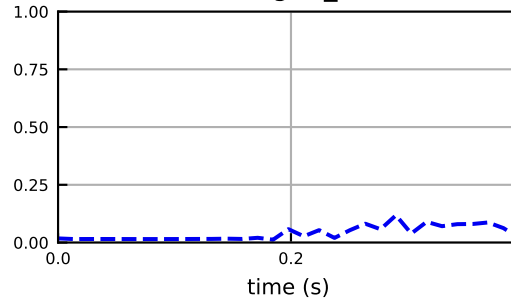
forcesetpect



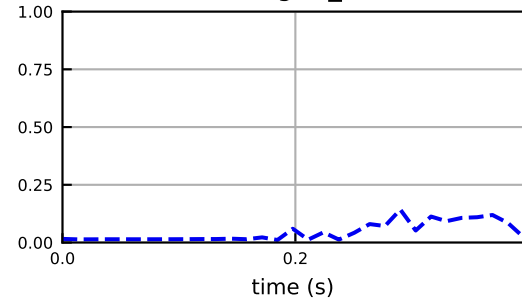
forcesetgrac



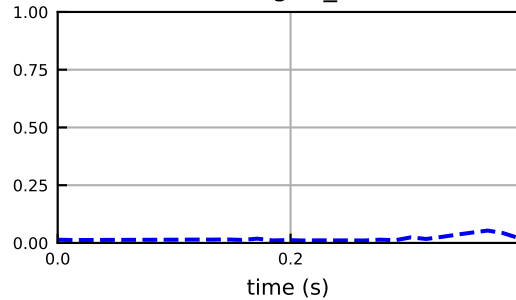
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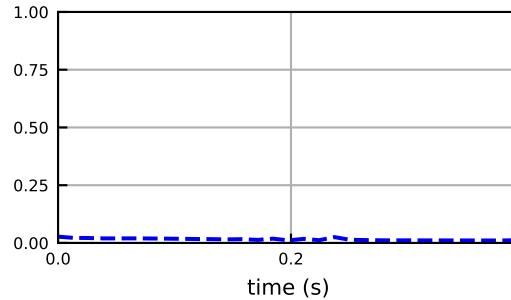
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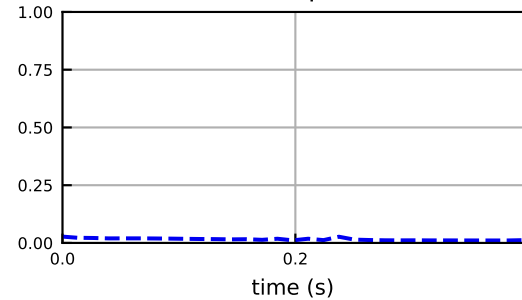
forcesetglut\_max3



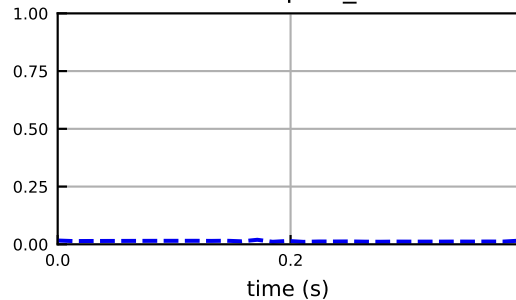
forcesetiliacus



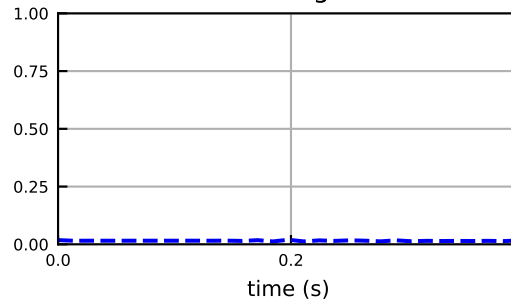
forcesetpsoas



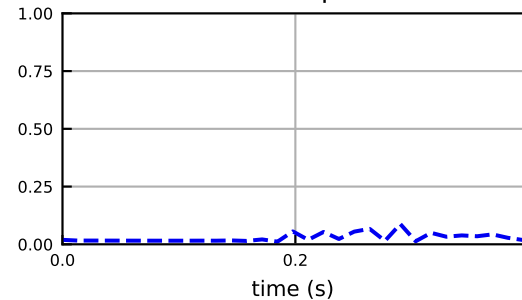
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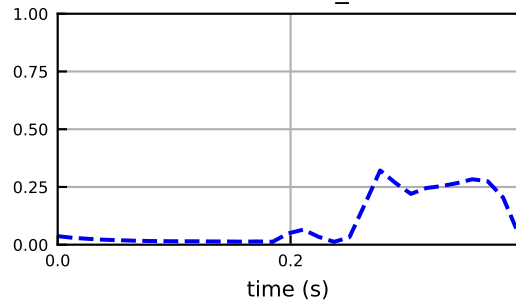
forcesetgem



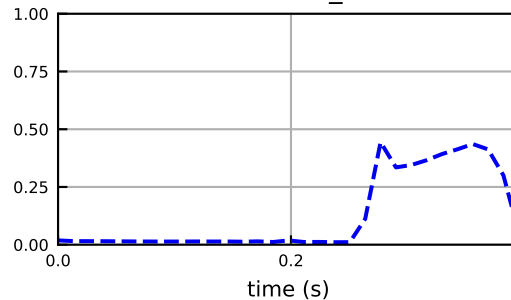
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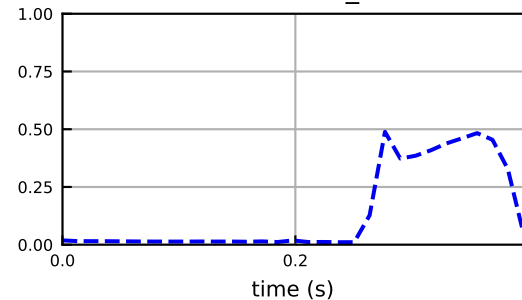
forcesetrect\_fem



forcesetvas\_med

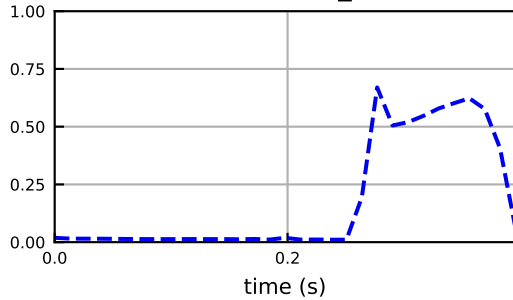


forcesetvas\_int

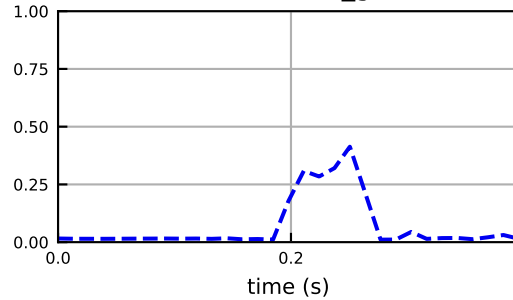




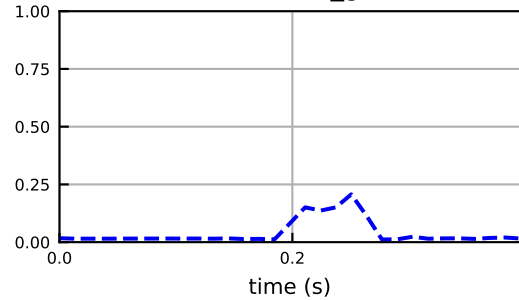
forcesetvas\_lat



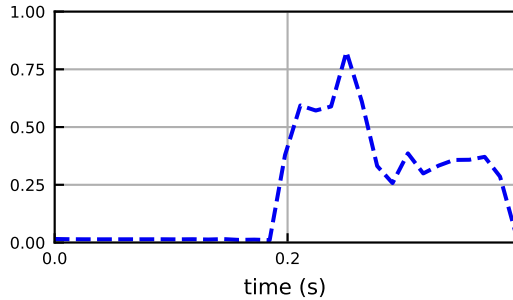
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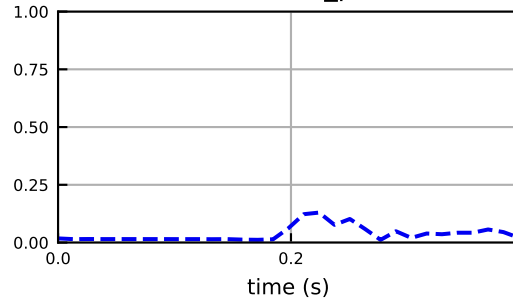
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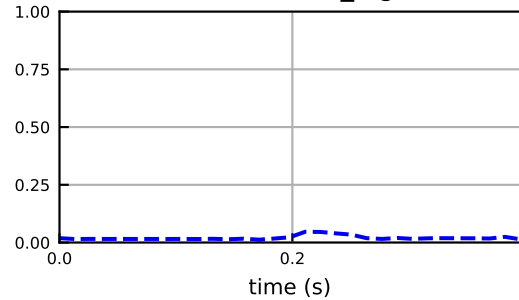
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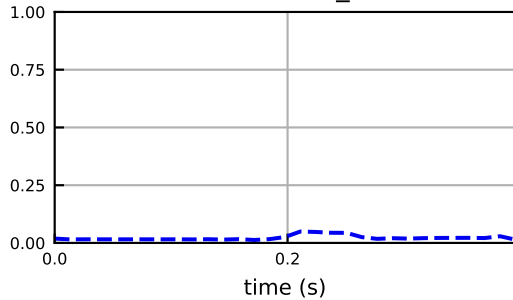
forcesettib\_post



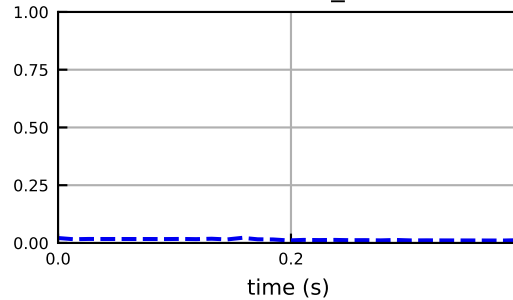
forcesetflex\_dig



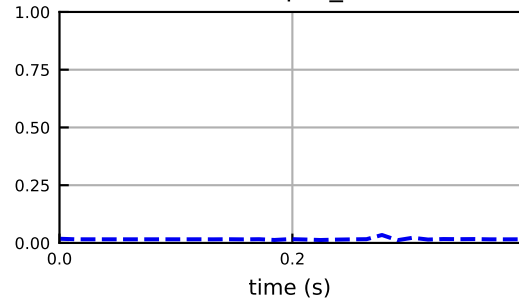
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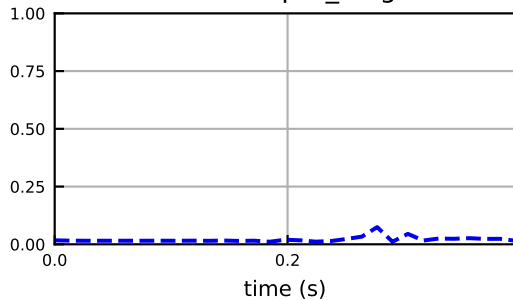
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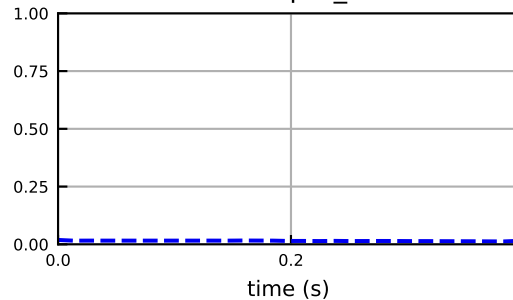
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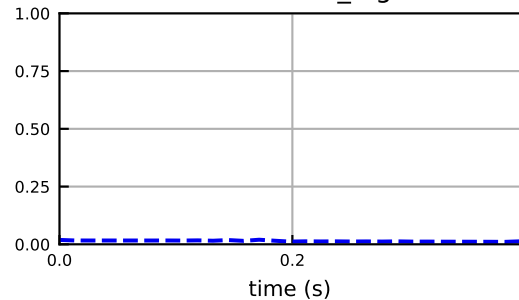
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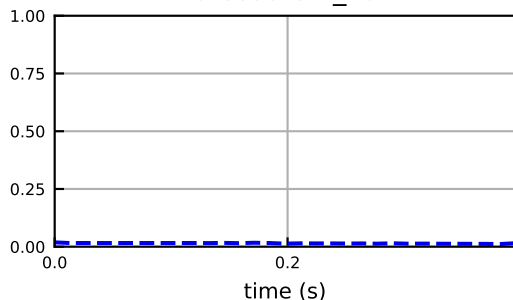
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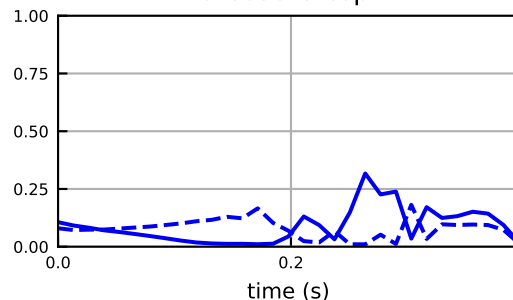
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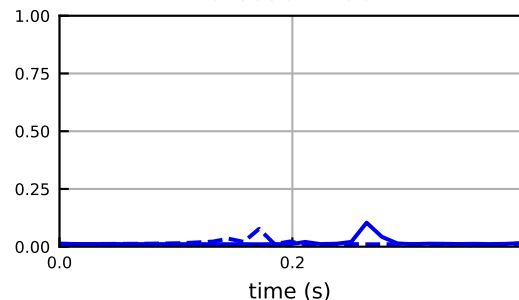
forcesetext\_hal



forcesetercspn

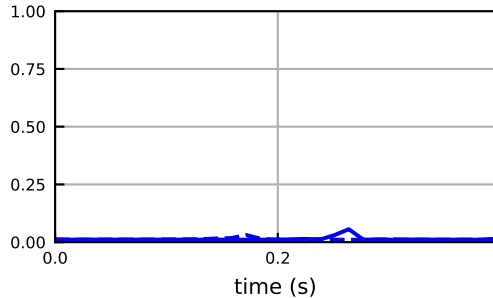


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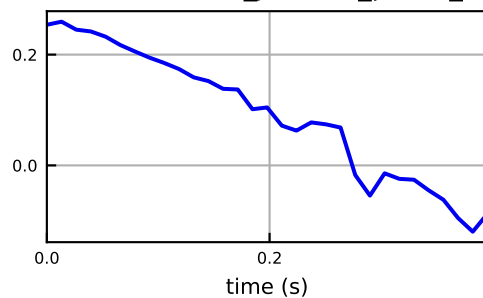


— D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (right leg)  
- - - D:\tzeni\project\_3\_predict\_trunk\_cases\Results\Predict\Trunk\ext\_-25/solution.sto (left leg)

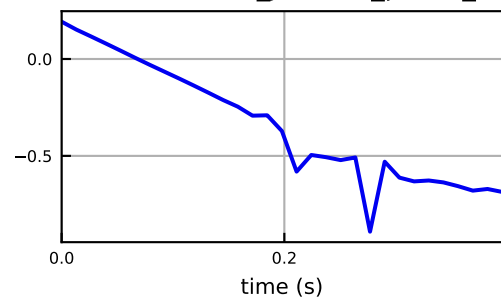
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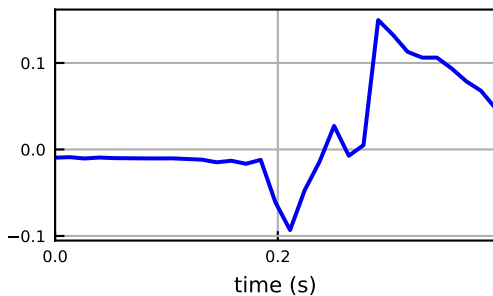
forcesetreserve\_joi...lvis\_pelvis\_tilt



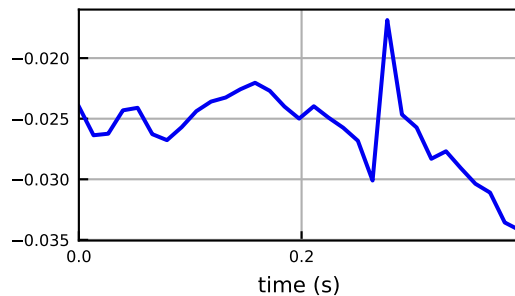
forcesetreserve\_joi...lvis\_pelvis\_list



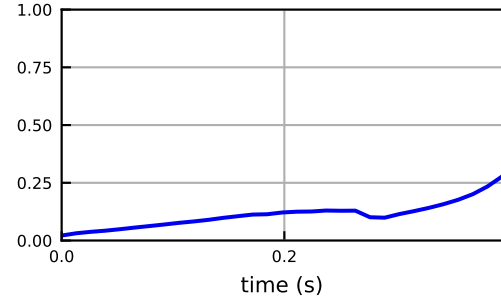
forcesetreserve\_joi...\_pelvis\_rotation



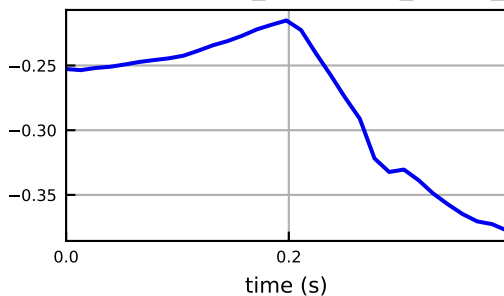
forcesetreserve\_joi...pelvis\_pelvis\_tx



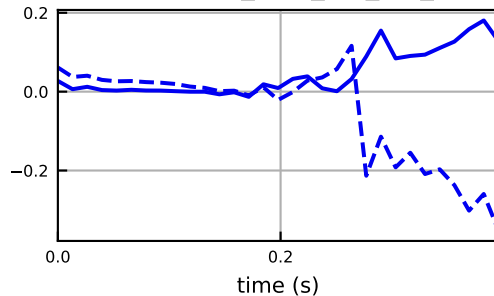
forcesetreserve\_joi...pelvis\_pelvis\_ty



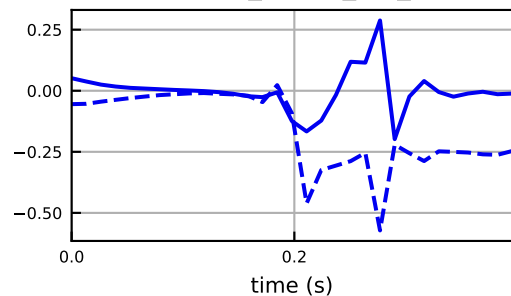
forcesetreserve\_joi...pelvis\_pelvis\_tz



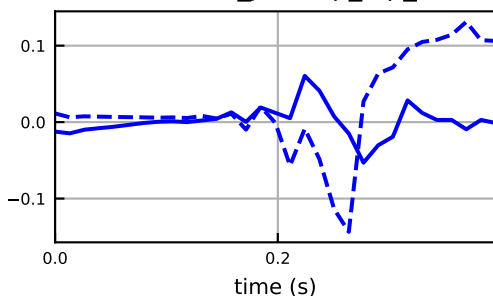
forcesetreserve\_joi...\_hip\_hip\_flexion



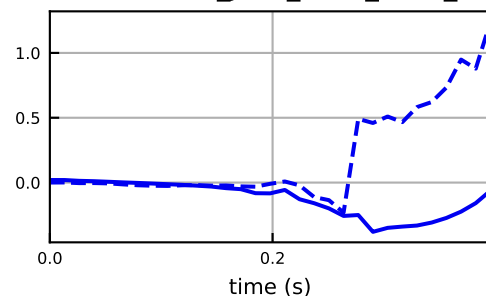
forcesetreserve\_joi...ip\_hip\_adduction



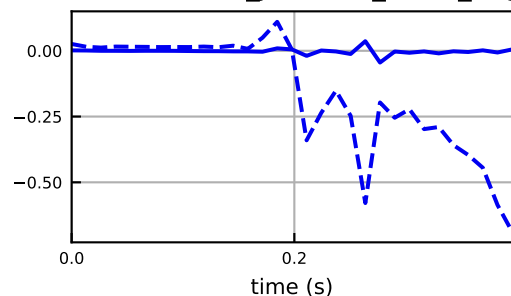
forcesetreserve\_joi...hip\_hip\_rotation



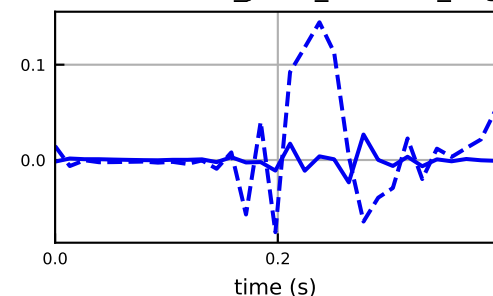
forcesetreserve\_joi...\_knee\_knee\_angle



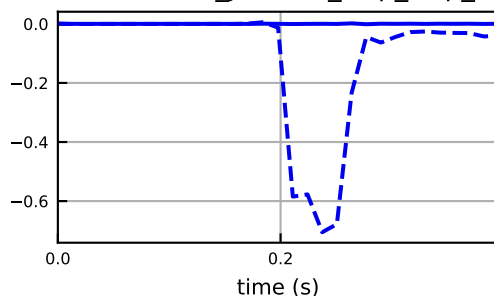
forcesetreserve\_joi...nkle\_ankle\_angle



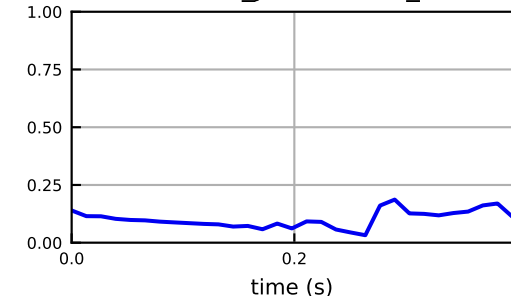
forcesetreserve\_joi...r\_subtalar\_angle



forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension





forcesetreserve\_joi...k\_lumbar\_bending    forcesetreserve\_joi...\_lumbar\_rotation

