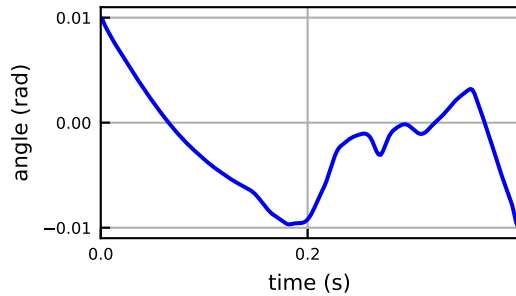
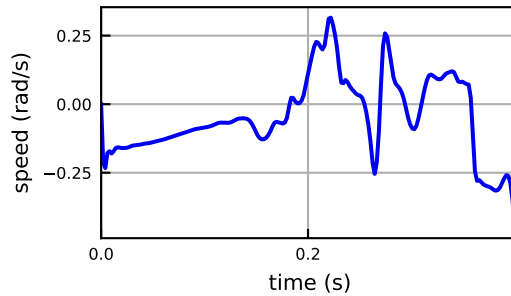


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)

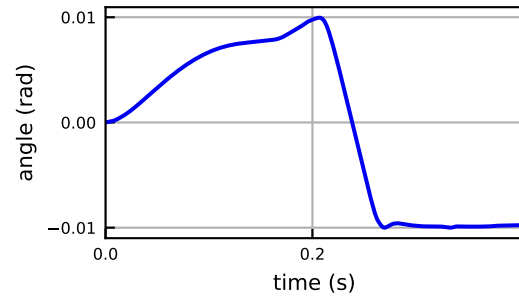
pelvis\_tilt/value



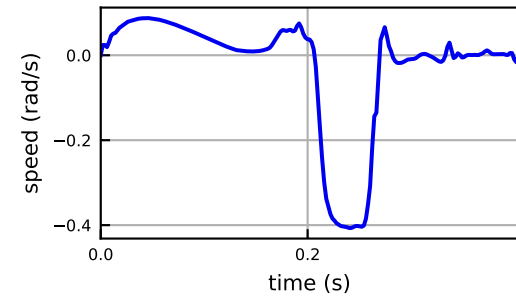
pelvis\_tilt/speed



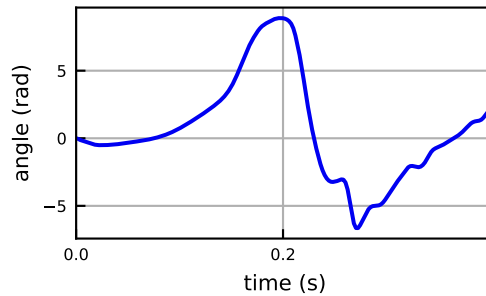
pelvis\_list/value



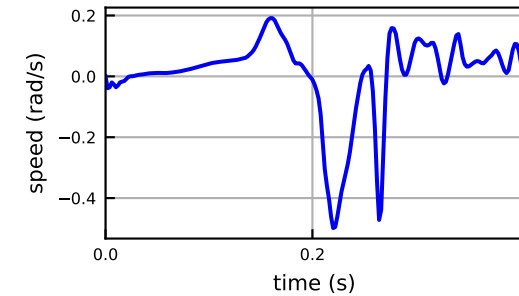
pelvis\_list/speed



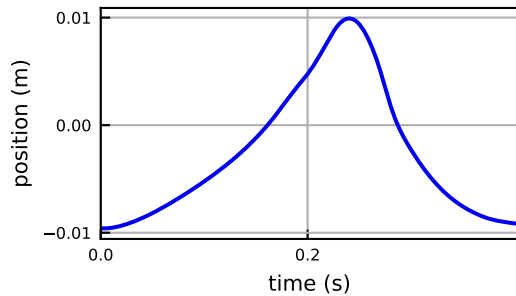
pelvis\_rotation/value



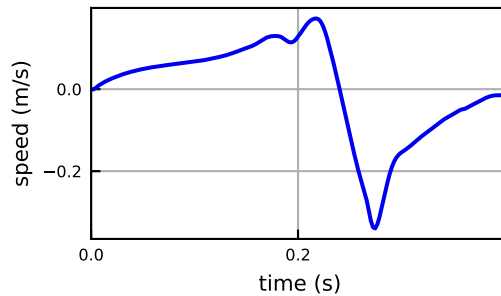
pelvis\_rotation/speed



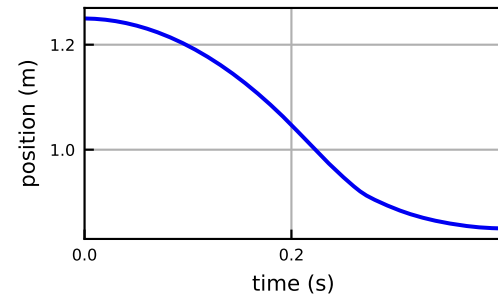
pelvis\_tx/value



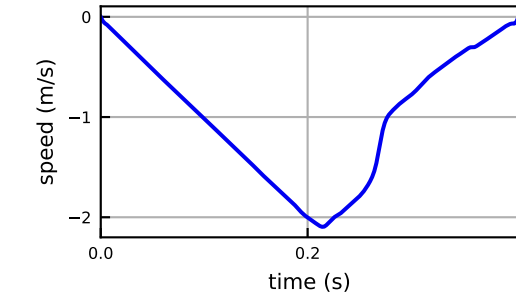
pelvis\_tx/speed



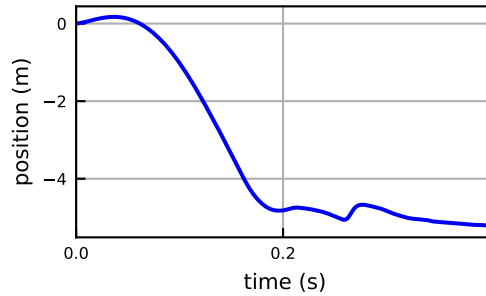
pelvis\_ty/value



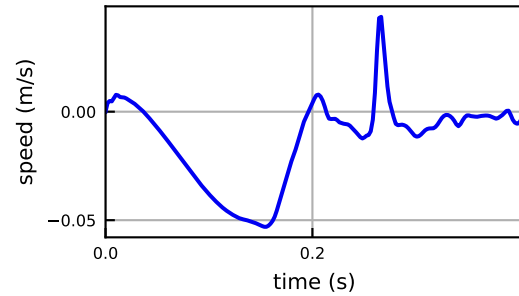
pelvis\_ty/speed



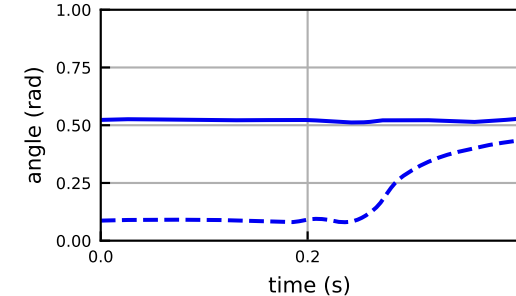
pelvis\_tz/value



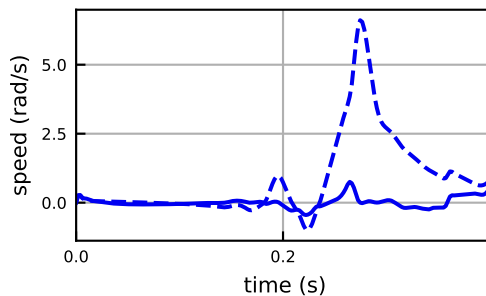
pelvis\_tz/speed



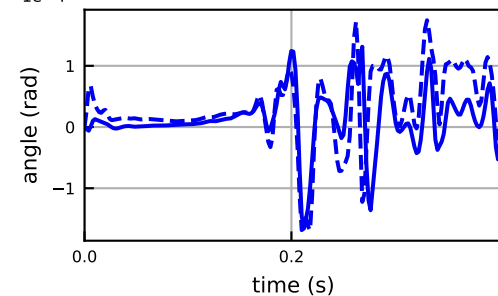
hip\_flexion/value



hip\_flexion/speed

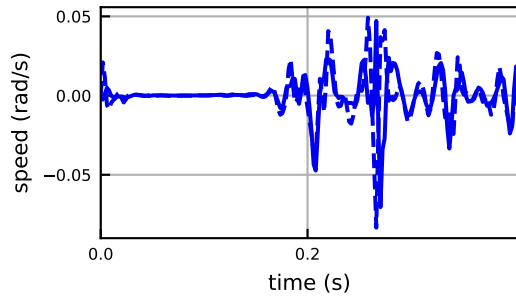


hip\_adduction/value

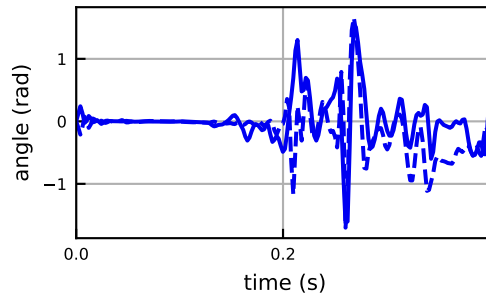


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)

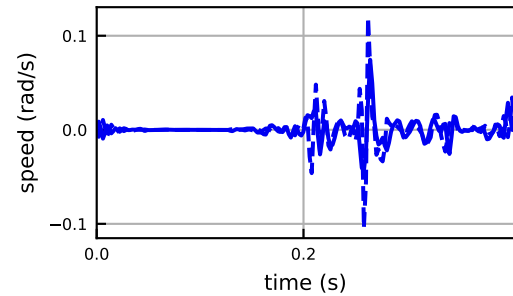
hip\_adduction/speed



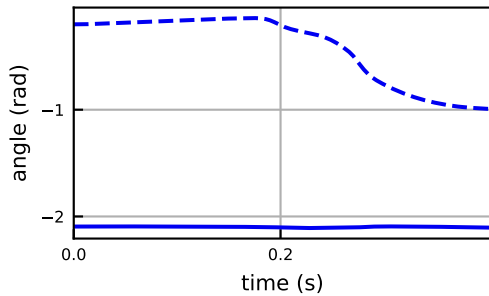
hip\_rotation/value



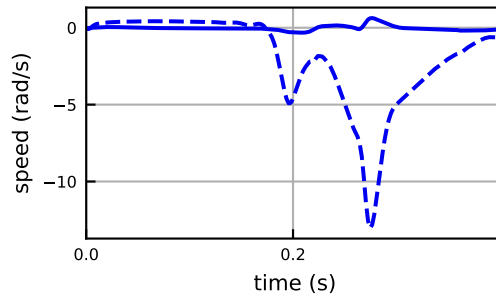
hip\_rotation/speed



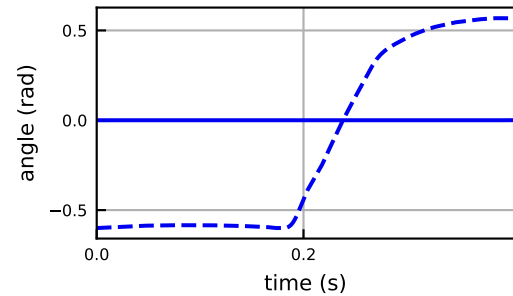
knee\_angle/value



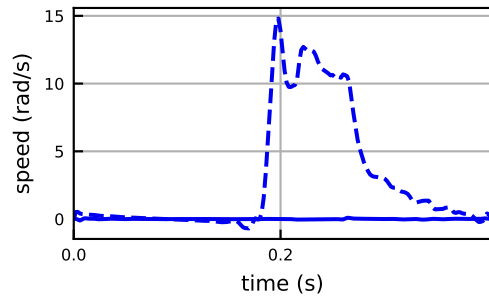
knee\_angle/speed



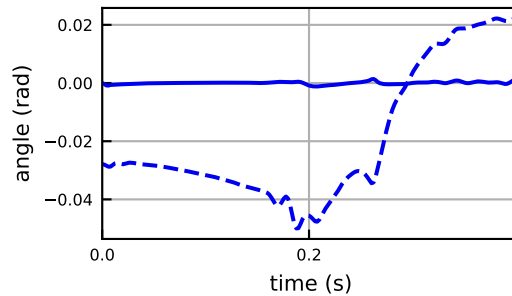
ankle\_angle/value



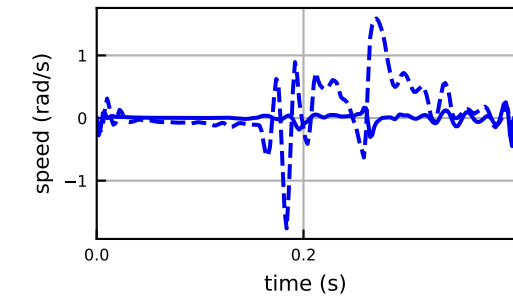
ankle\_angle/speed



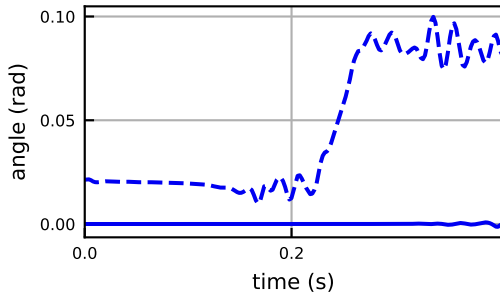
subtalar\_angle/value



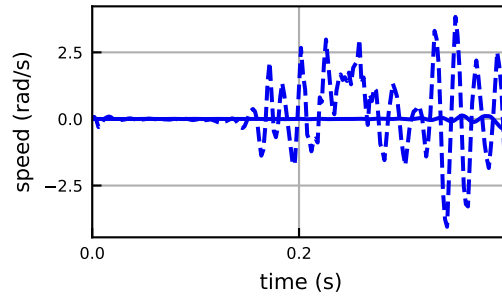
subtalar\_angle/speed



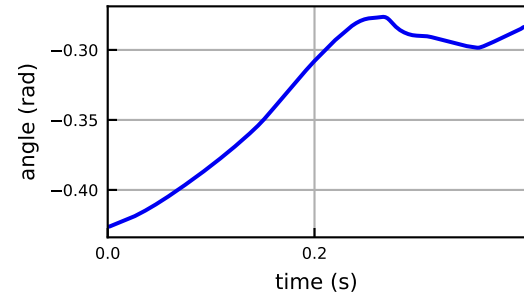
mtp\_angle/value



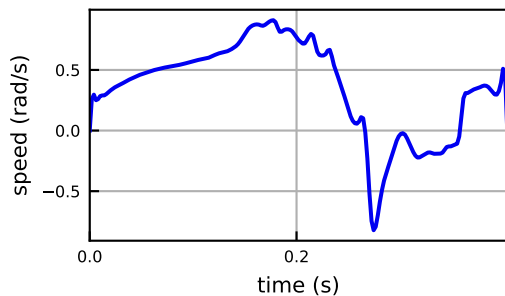
mtp\_angle/speed



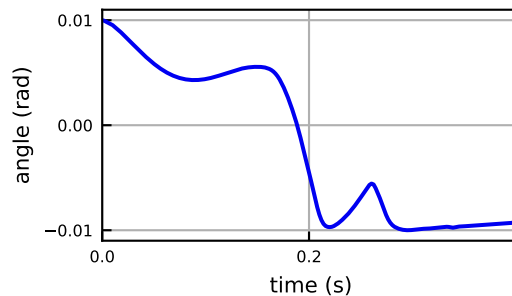
lumbar\_extension/value



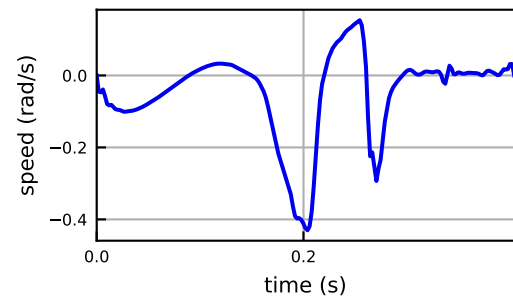
lumbar\_extension/speed



lumbar\_bending/value

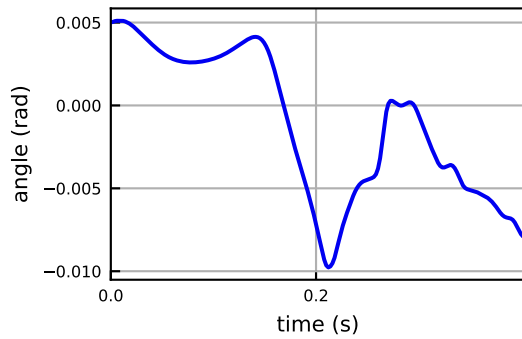


lumbar\_bending/speed

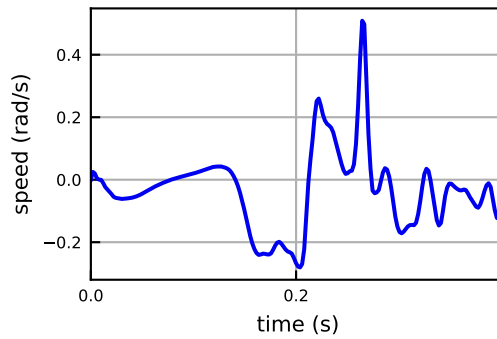


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25/solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25/solution.sto (left leg)

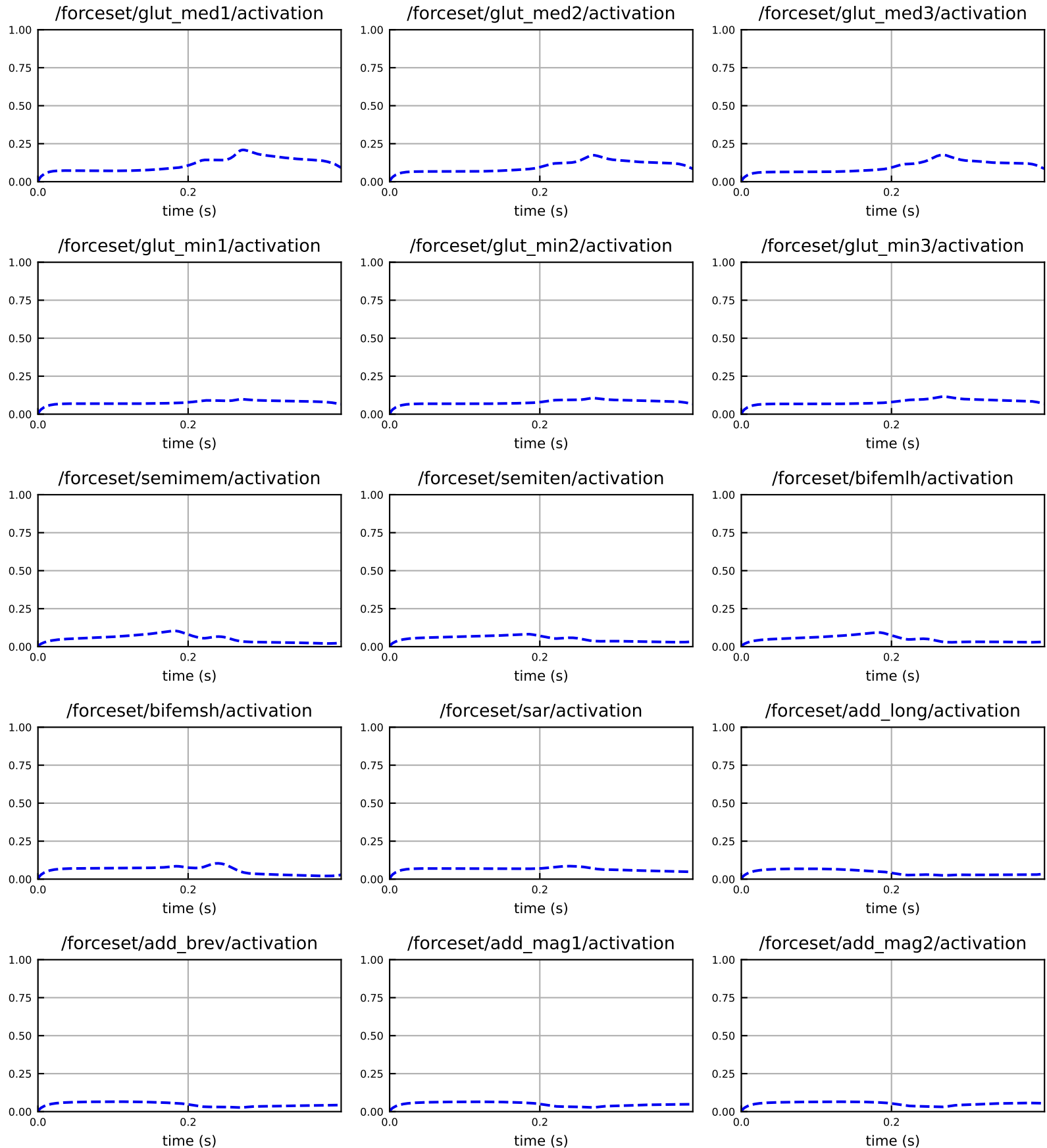
lumbar\_rotation/value



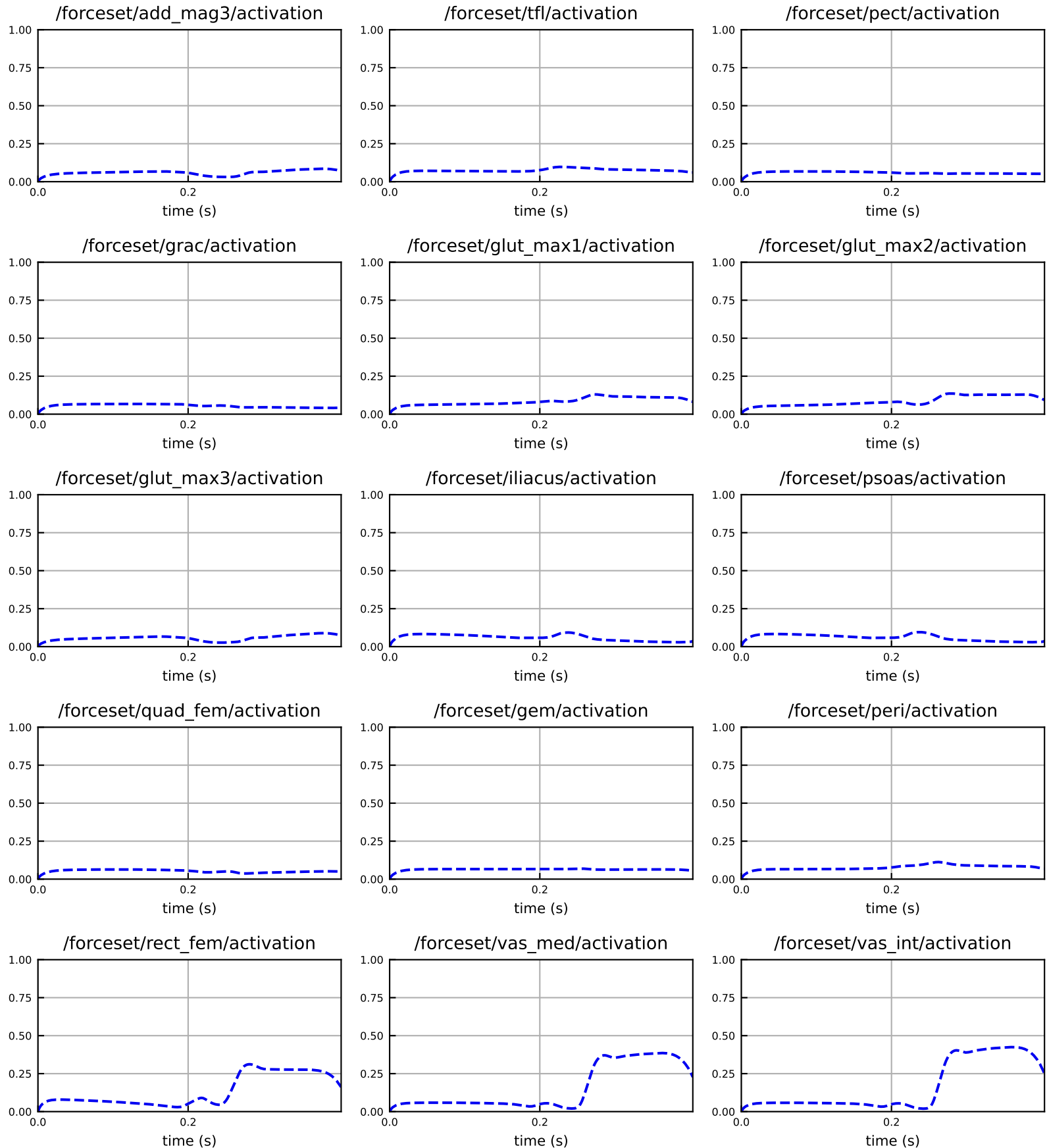
lumbar\_rotation/speed



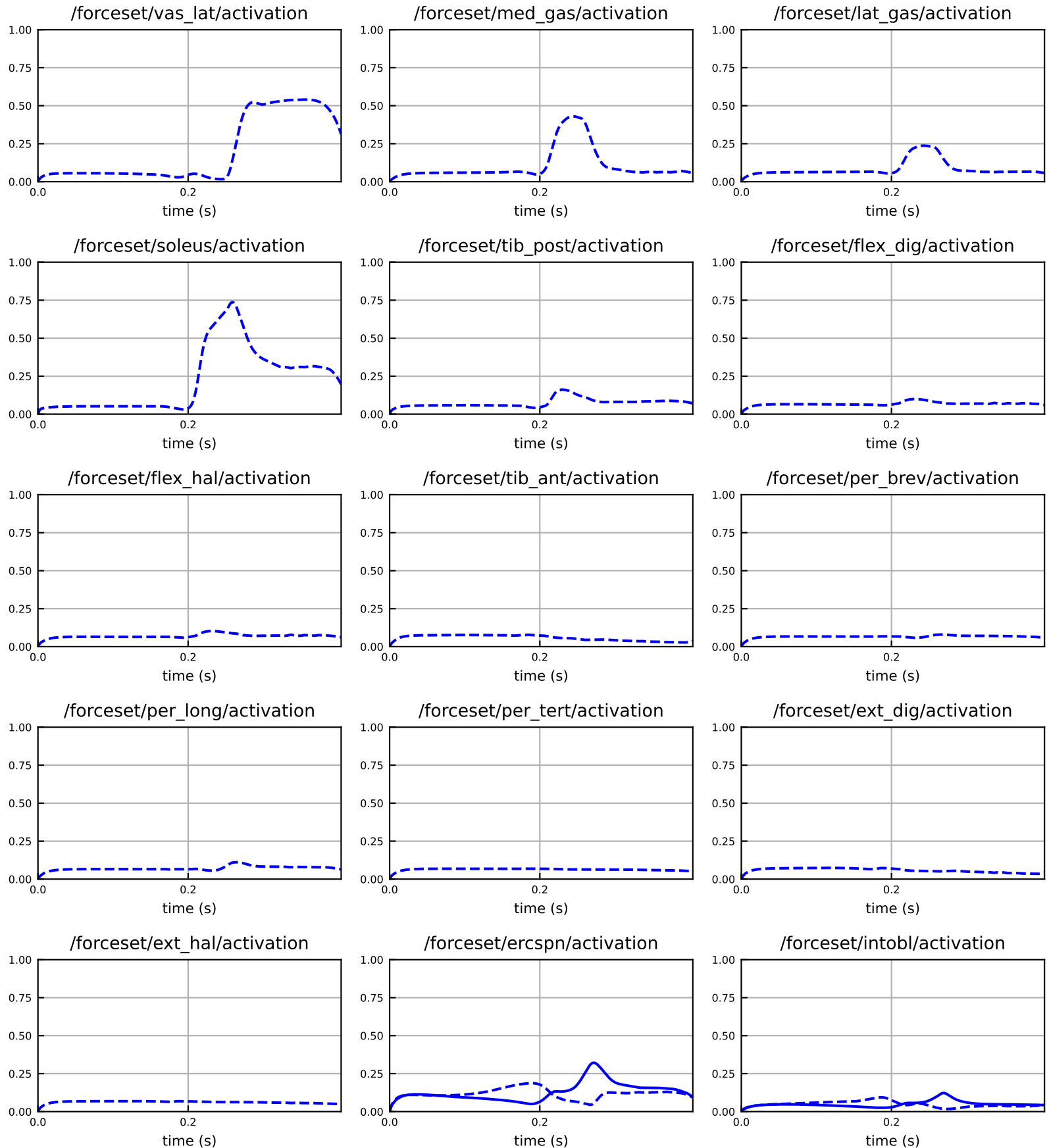
— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)



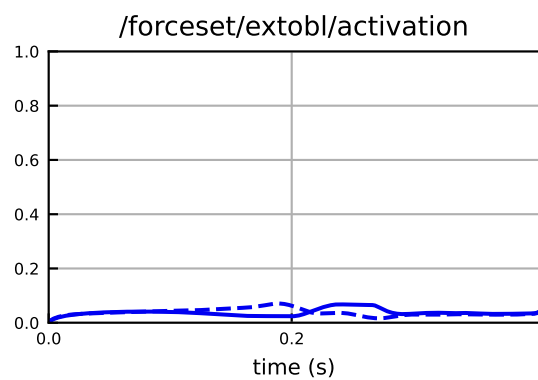
— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)



— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
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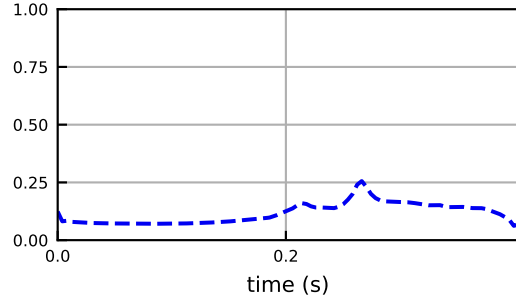


- D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)

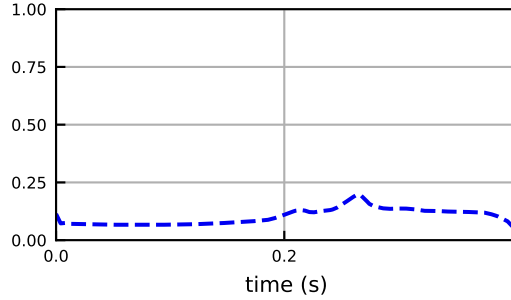


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)

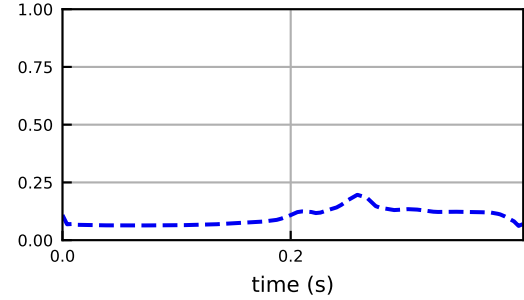
forcesetglut\_med1



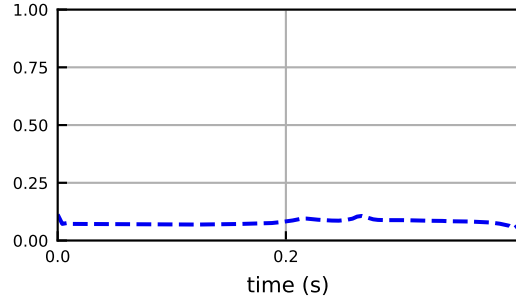
forcesetglut\_med2



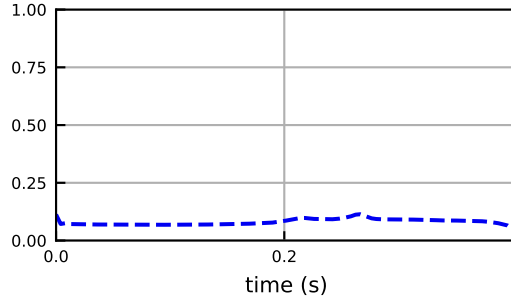
forcesetglut\_med3



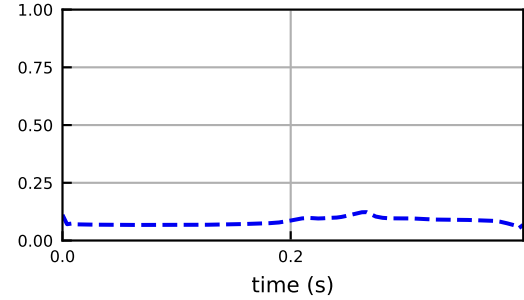
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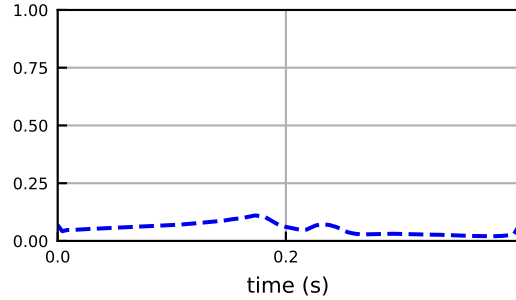
forcesetglut\_min2



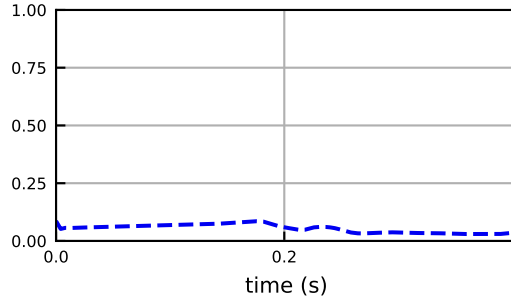
forcesetglut\_min3



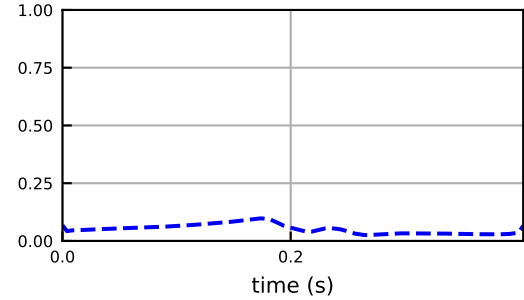
forcesetsemimem



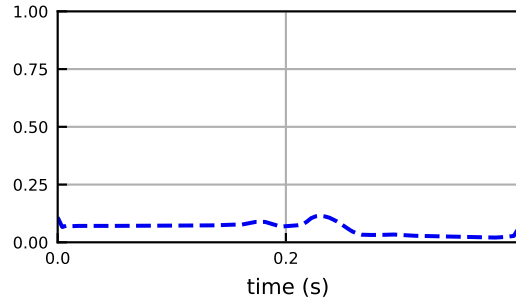
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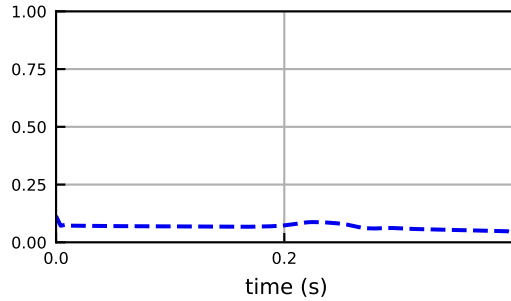
forcesetbifemlh



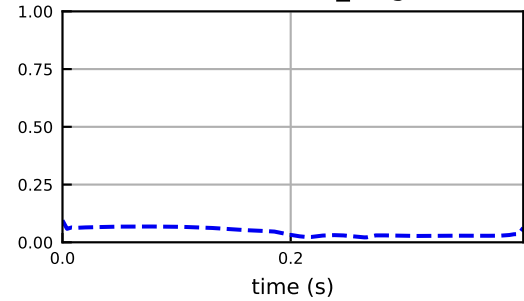
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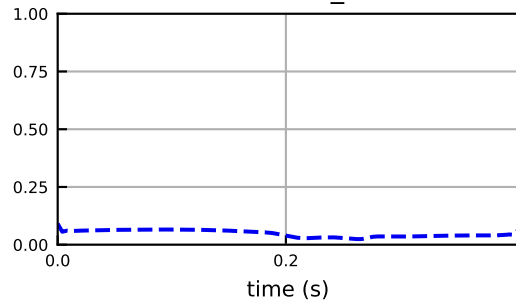
forcesetsar



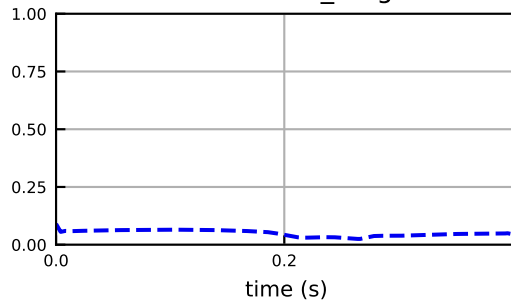
forcesetadd\_long



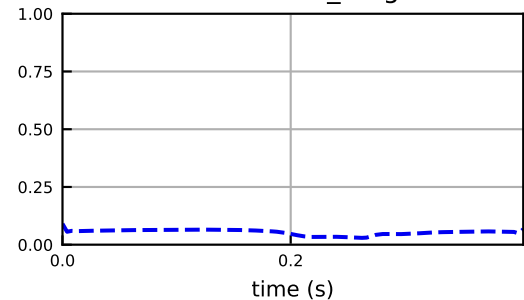
forcesetadd\_brev



forcesetadd\_mag1



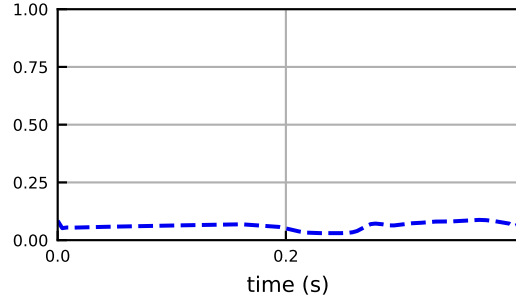
forcesetadd\_mag2



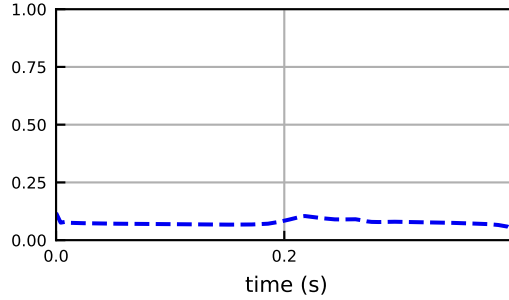


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)

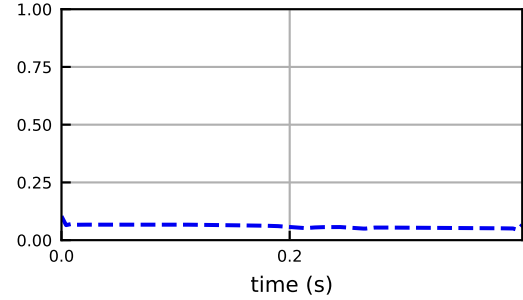
forcesetadd\_mag3



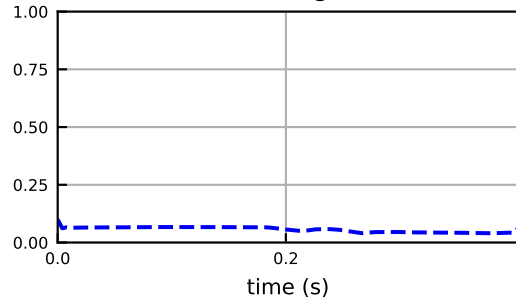
forcesettfl



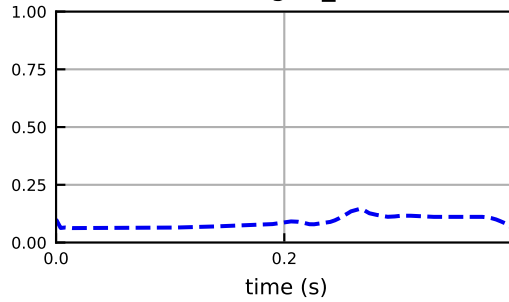
forcesetpect



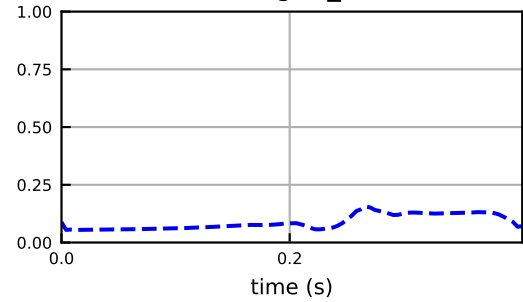
forcesetgrac



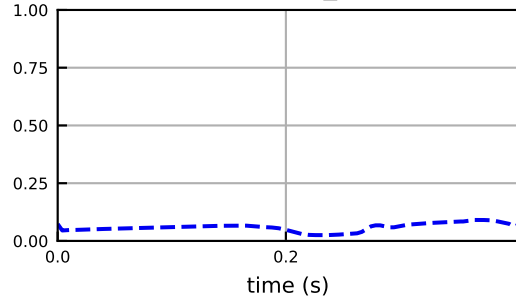
forcesetglut\_max1



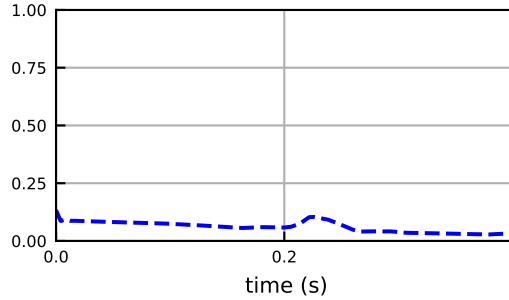
forcesetglut\_max2



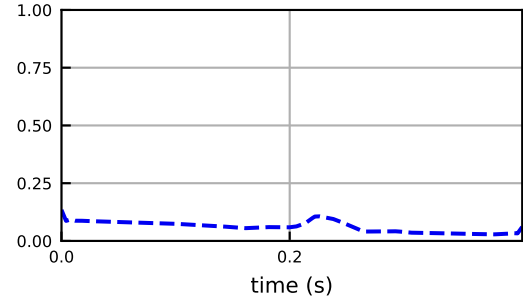
forcesetglut\_max3



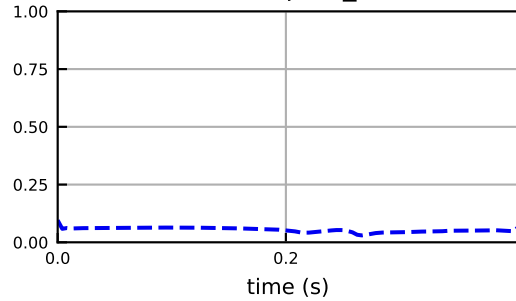
forcesetiliacus



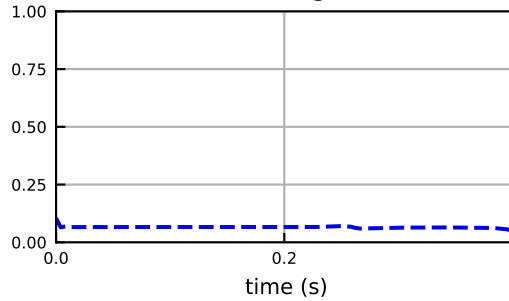
forcesetpsoas



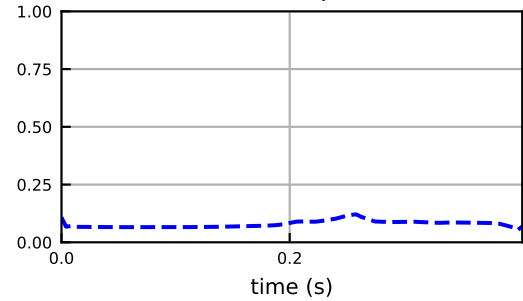
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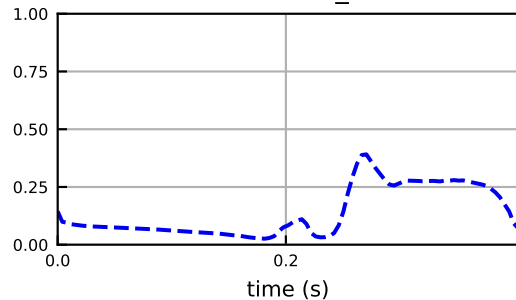
forcesetgem



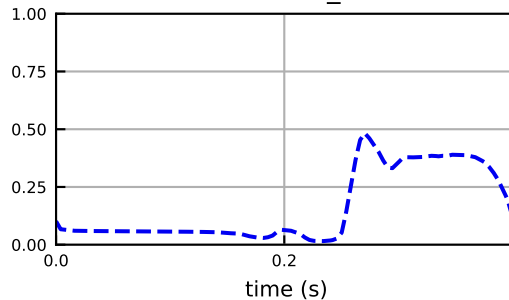
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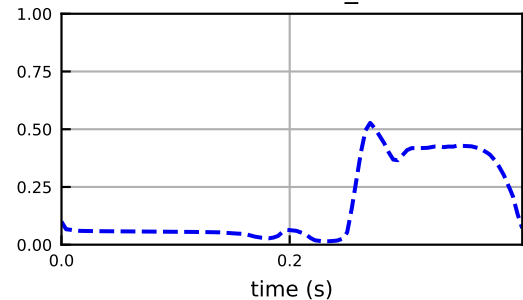
forcesetrect\_fem



forcesetvas\_med

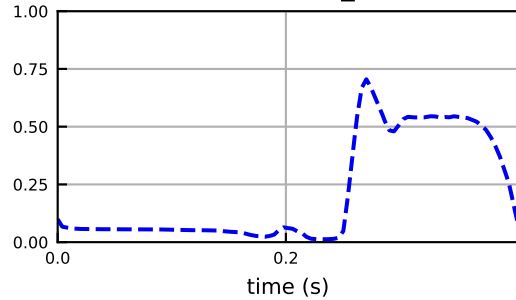


forcesetvas\_int

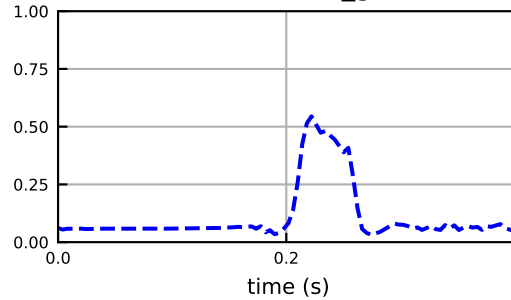


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)

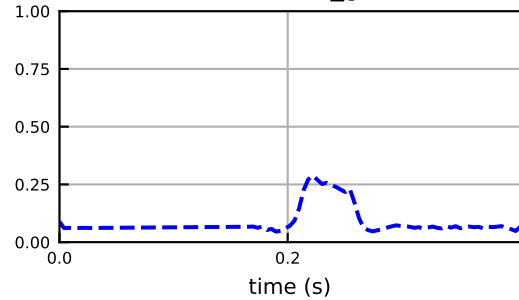
forcesetvas\_lat



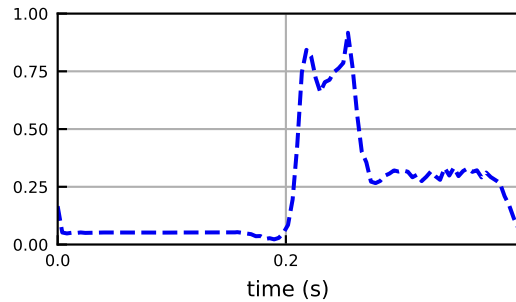
forcesetmed\_gas



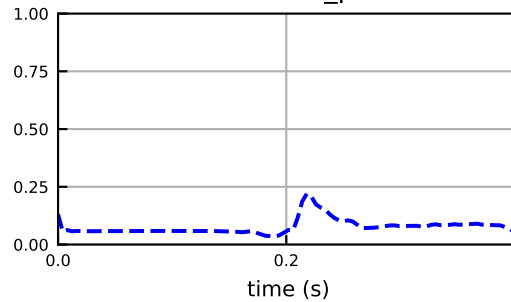
forcesetlat\_gas



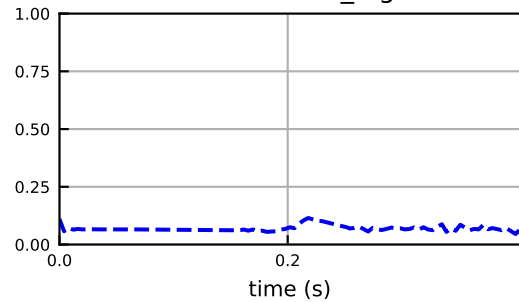
forcesetsoleus



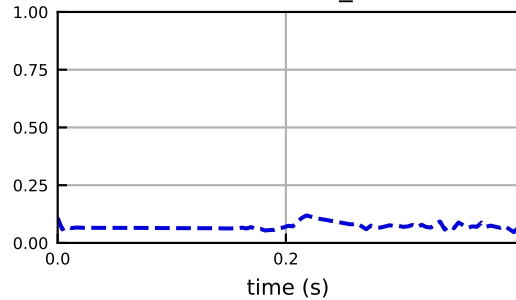
forcesettib\_post



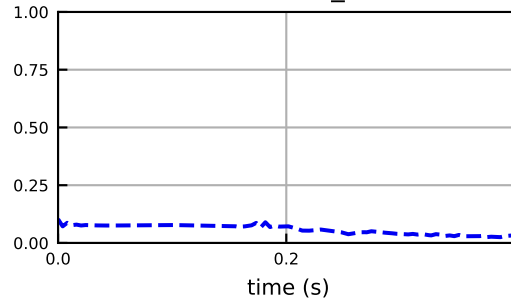
forcesetflex\_dig



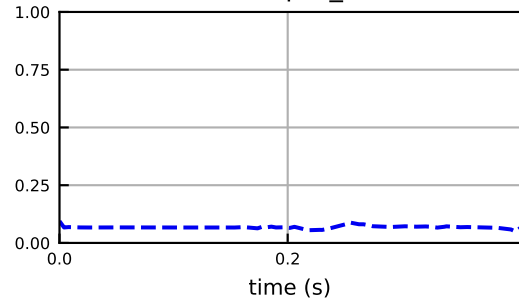
forcesetflex\_hal



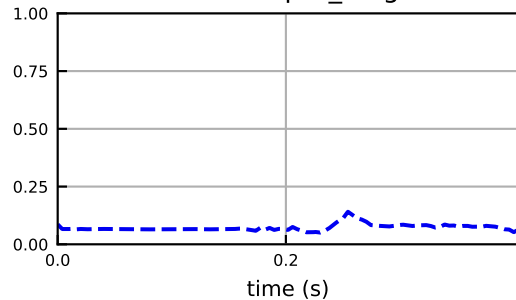
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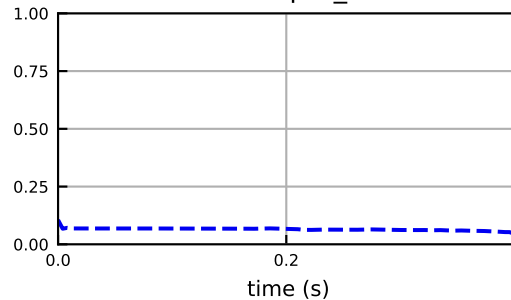
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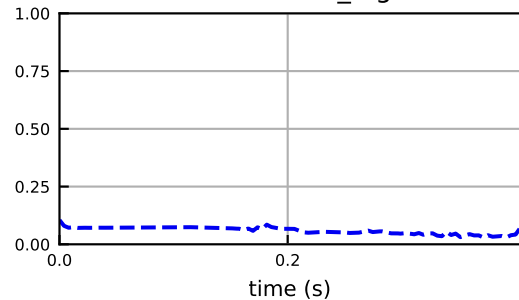
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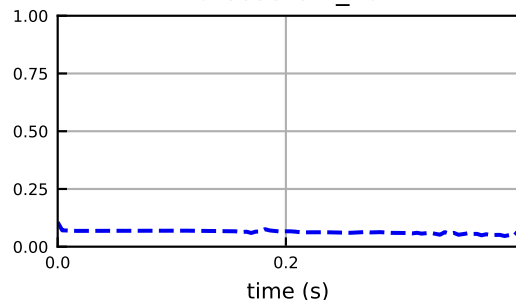
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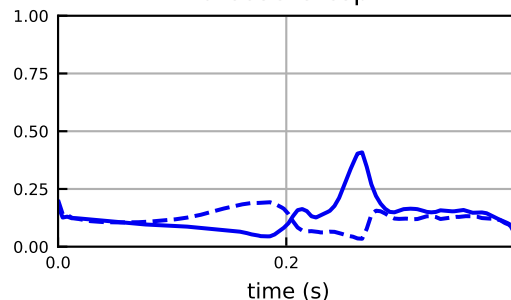
forcesetext\_dig



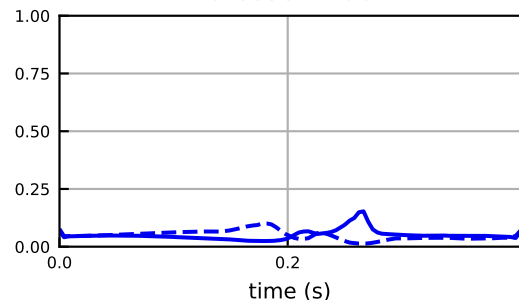
forcesetext\_hal



forcesetercspn

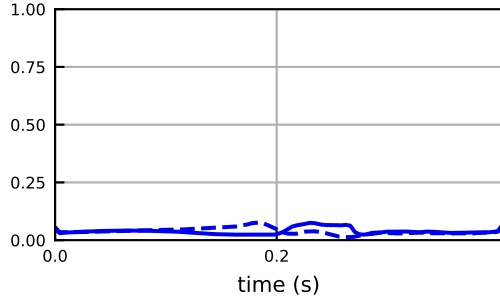


forcesetintobl

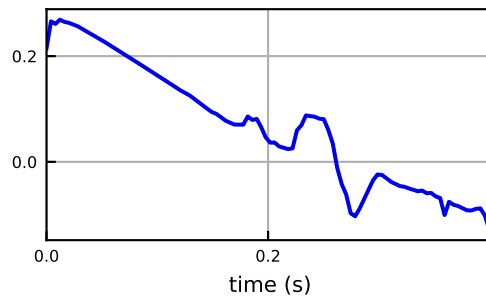


— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25\solution.sto (left leg)

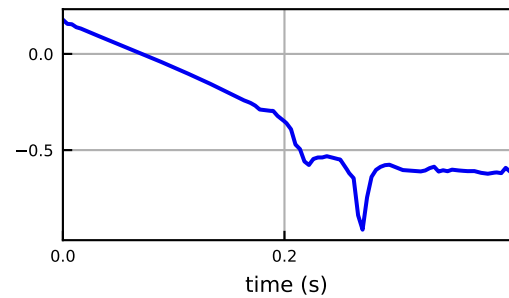
forcesetextobl



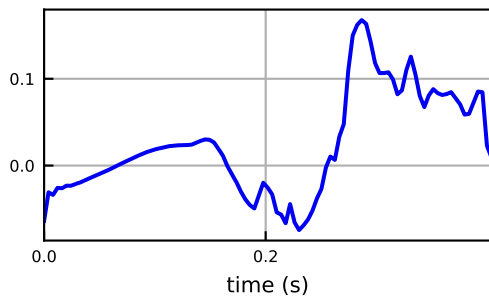
forcesetreserve\_joi...lvis\_pelvis\_tilt



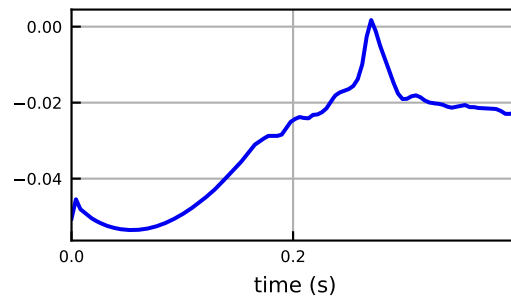
forcesetreserve\_joi...lvis\_pelvis\_list



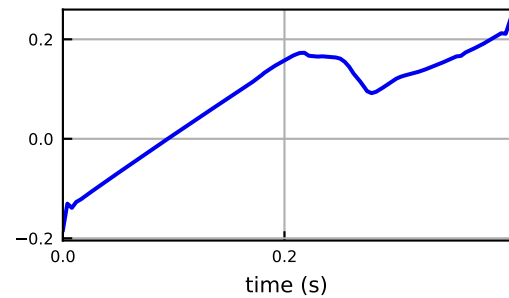
forcesetreserve\_joi...\_pelvis\_rotation



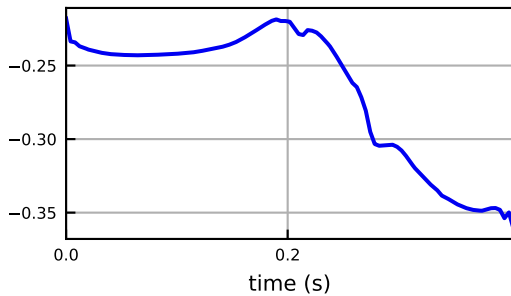
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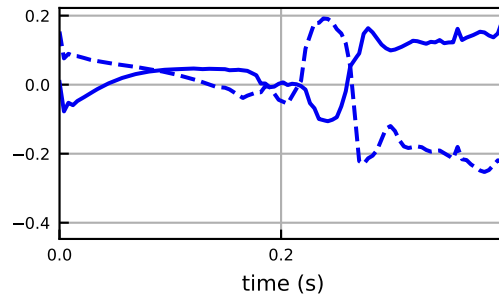
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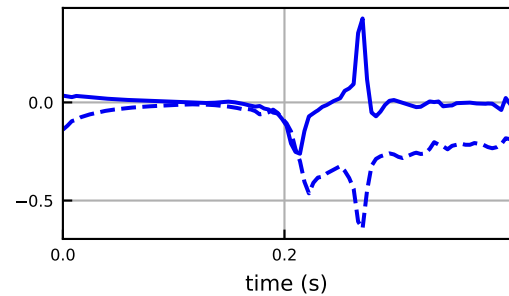
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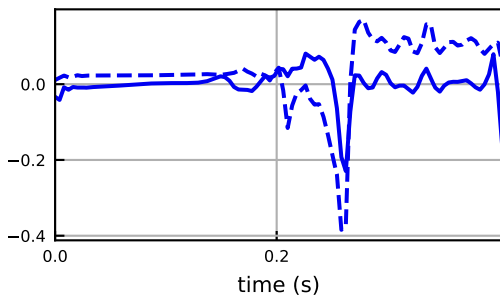
forcesetreserve\_joi...\_hip\_hip\_flexion



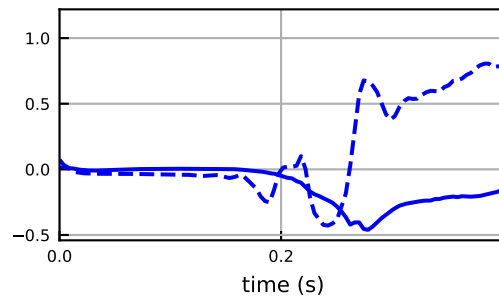
forcesetreserve\_joi...ip\_hip\_adduction



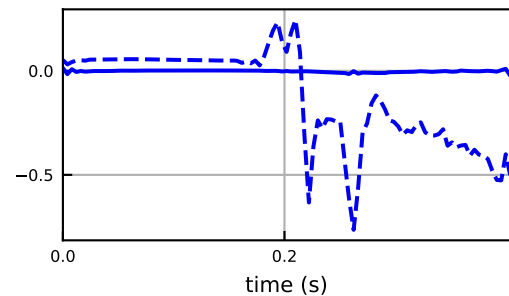
forcesetreserve\_joi...hip\_hip\_rotation



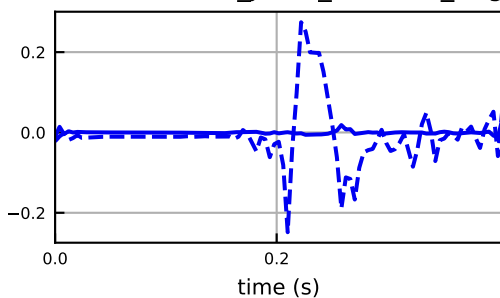
forcesetreserve\_joi...\_knee\_knee\_angle



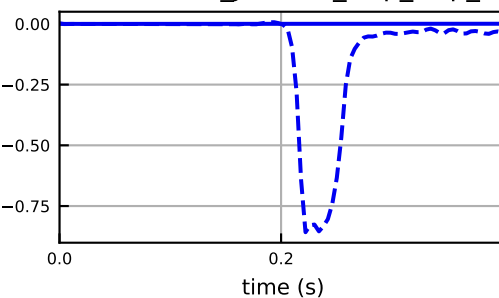
forcesetreserve\_joi...nkle\_ankle\_angle



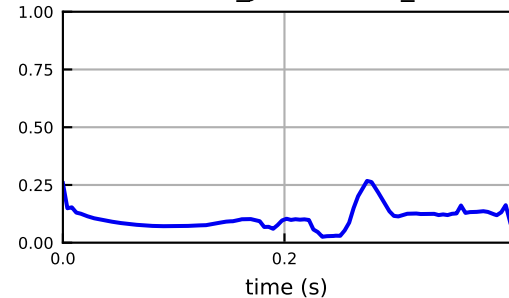
forcesetreserve\_joi...r\_subtalar\_angle



forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension



— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25/solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_effort0.002\ext\_-25/solution.sto (left leg)

forcesetreserve\_joi...k\_lumbar\_bending forcesetreserve\_joi...\_lumbar\_rotation

