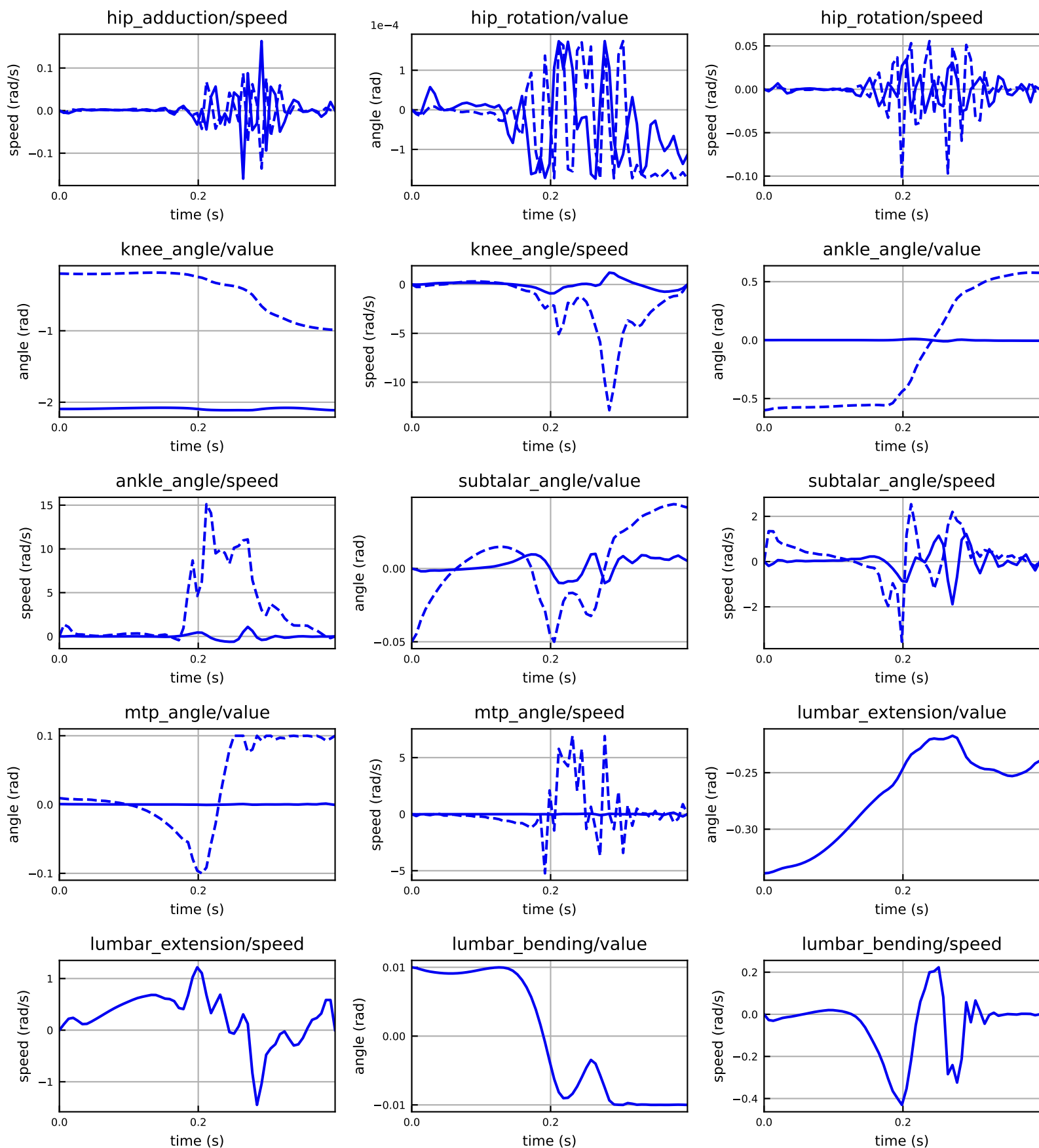
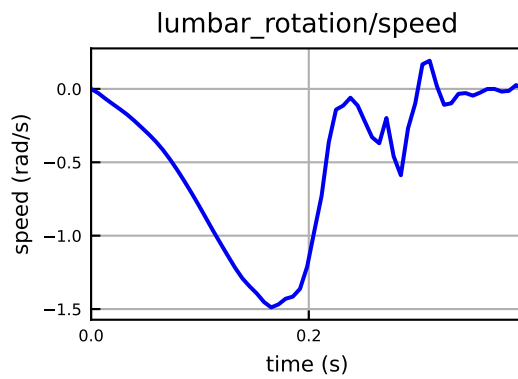
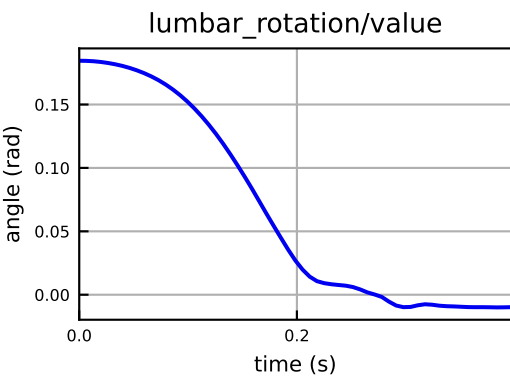
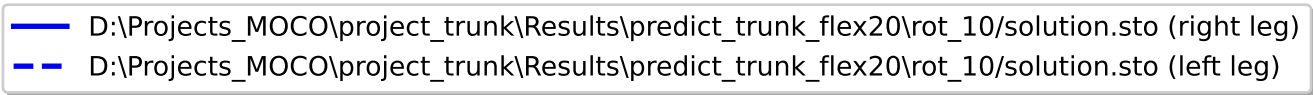
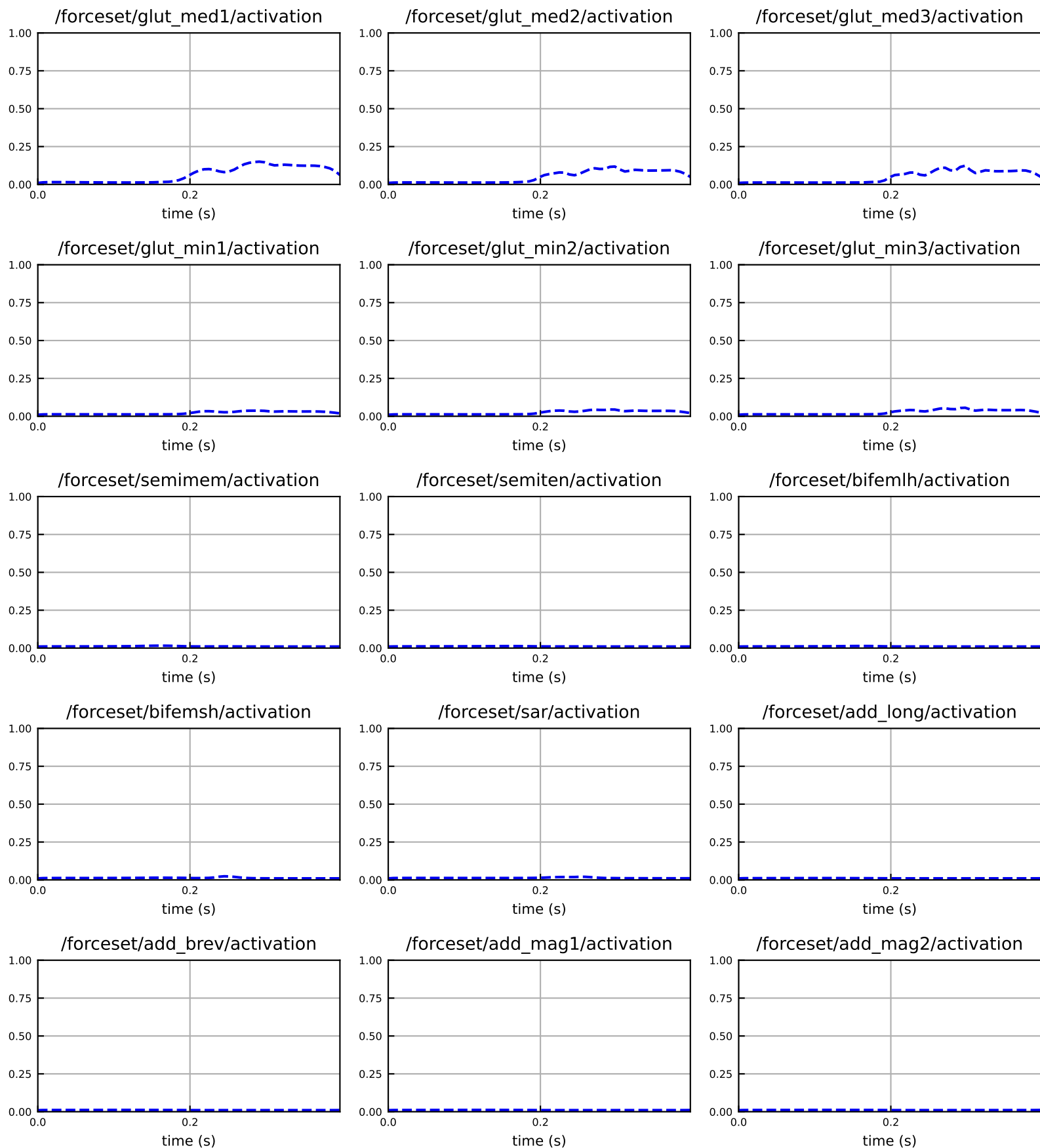
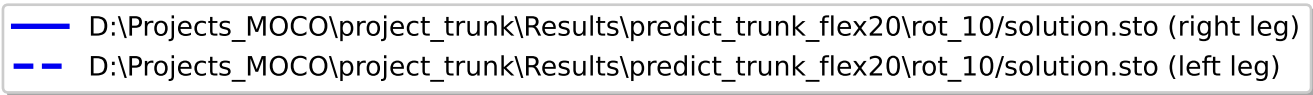
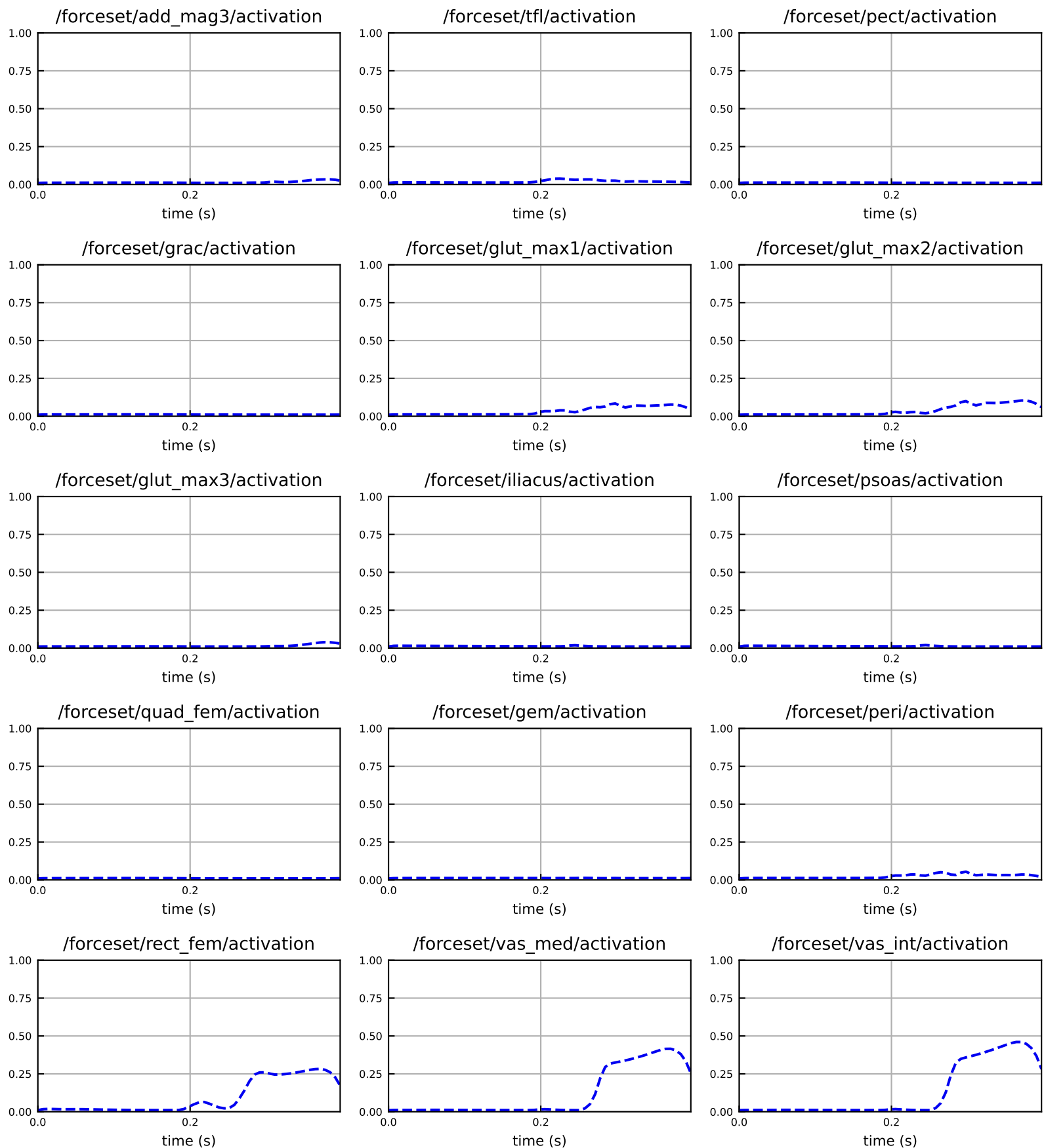
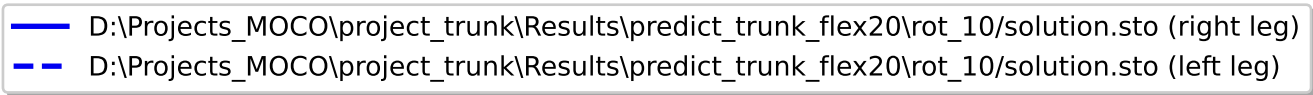


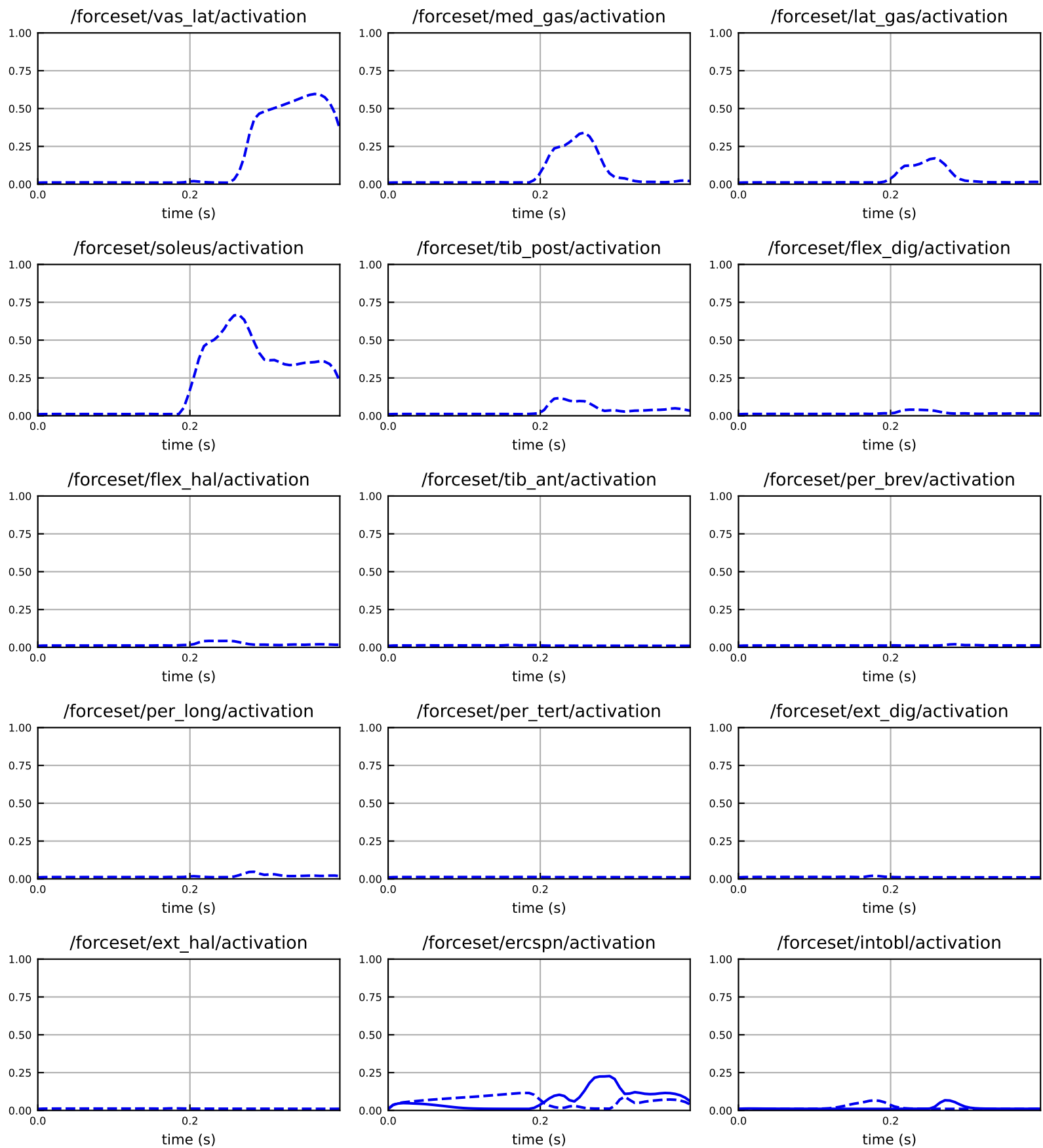
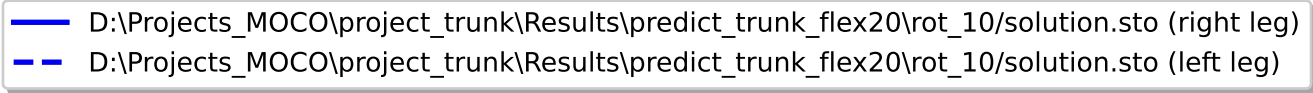
— D:\Projects\_MOCO\project\_trunk\Results\predict\_trunk\_flex20\rot\_10\solution.sto (right leg)  
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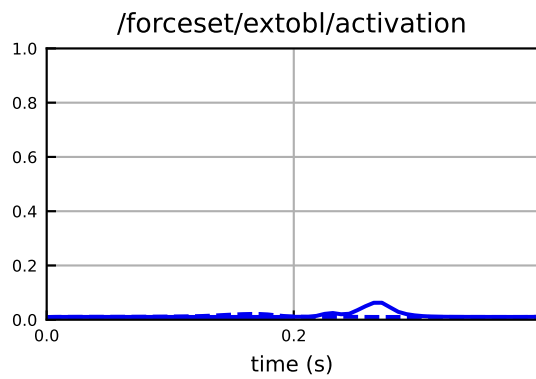
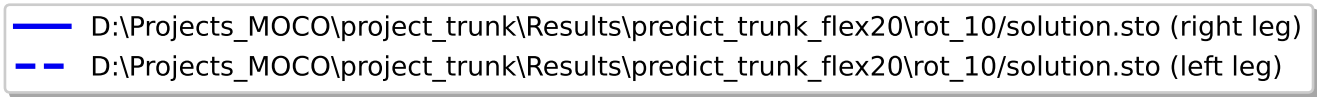


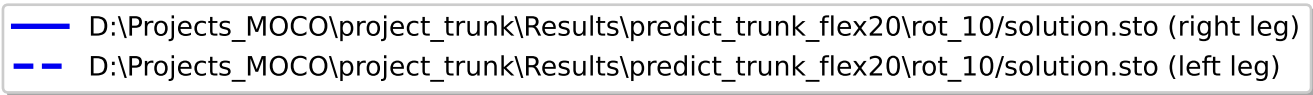




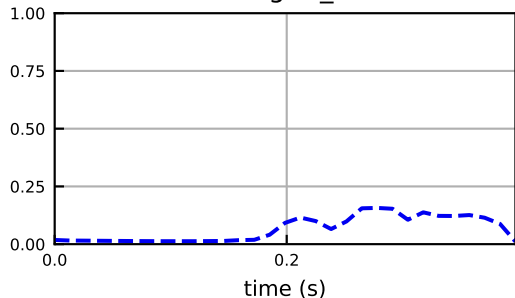




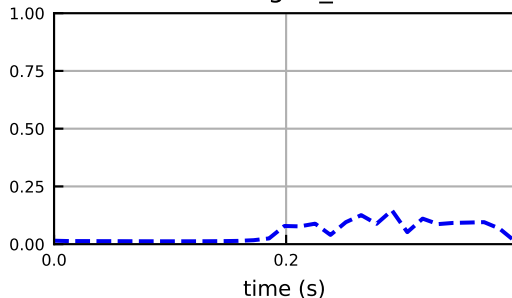




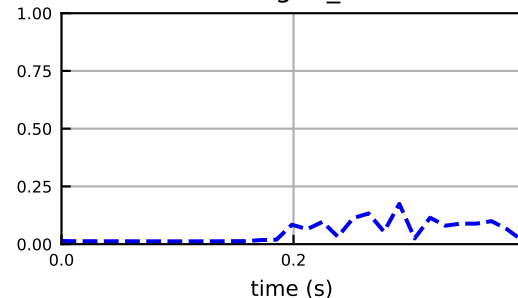
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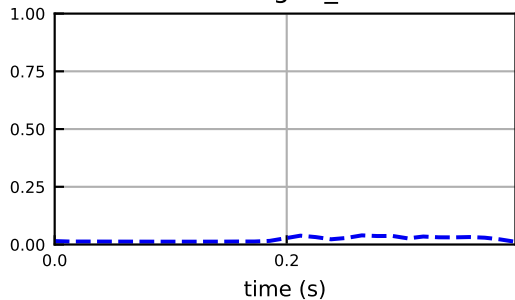
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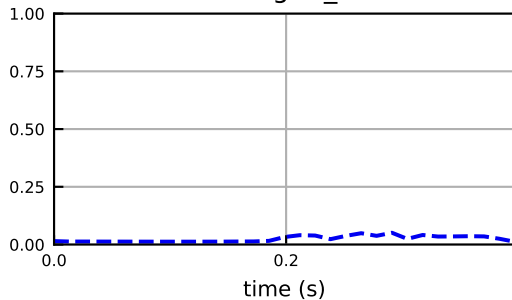
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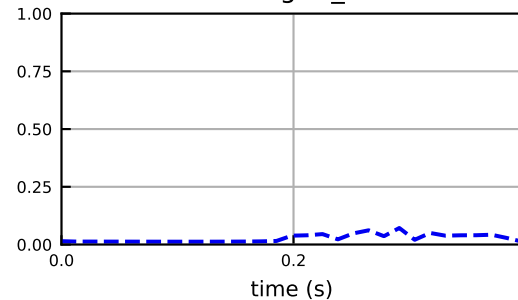
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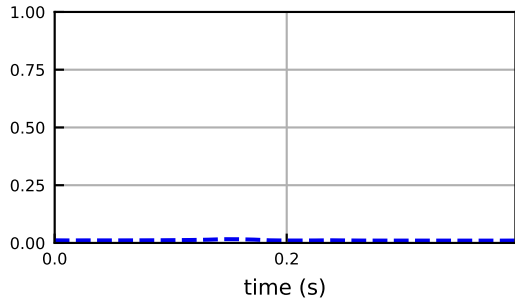
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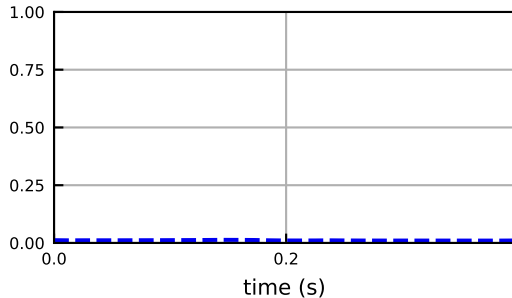
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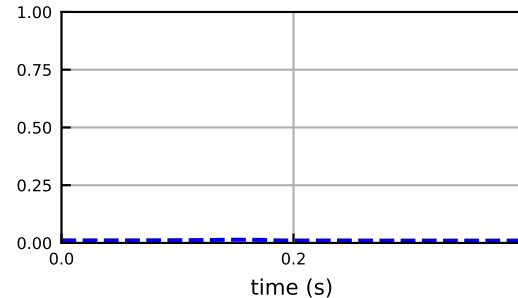
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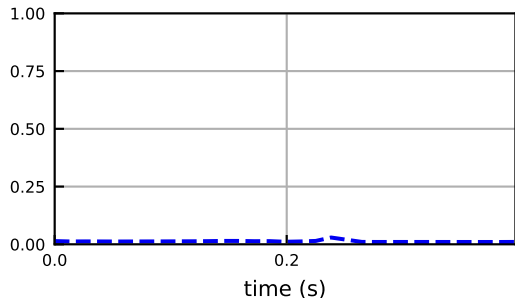
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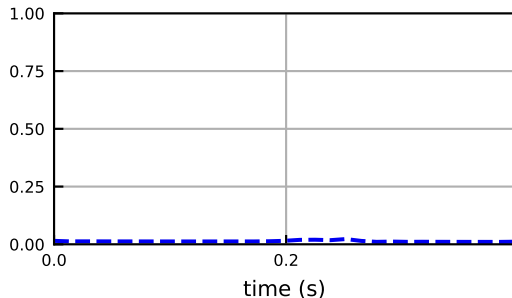
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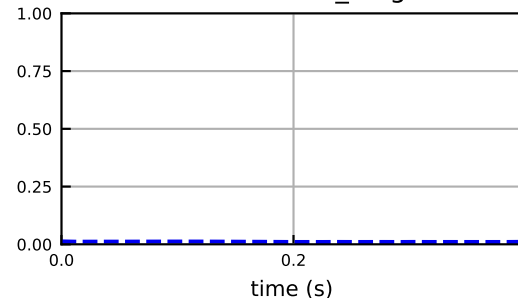
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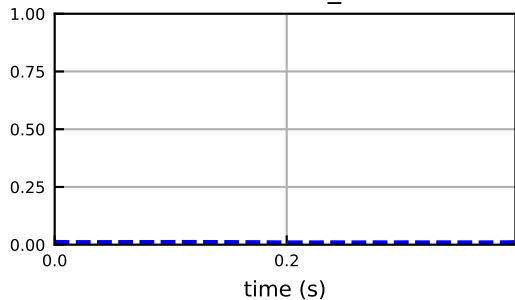
forcesetsar



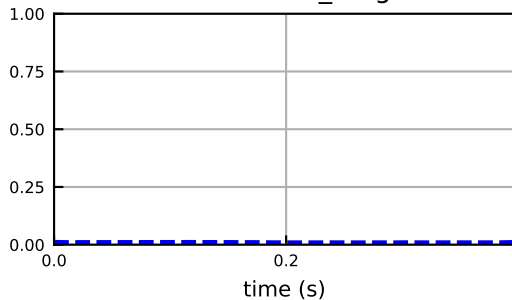
forcesetadd\_long



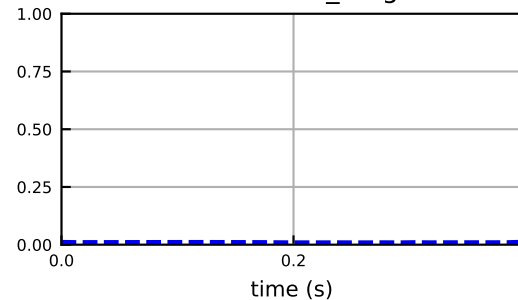
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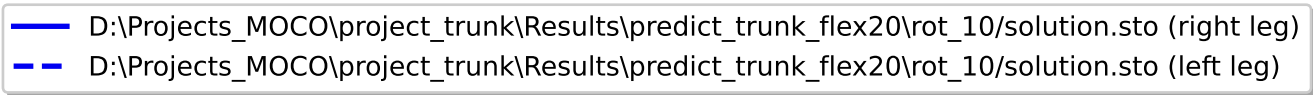
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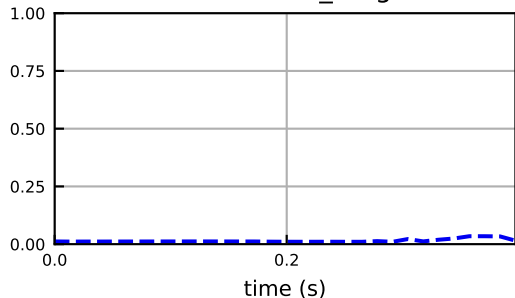
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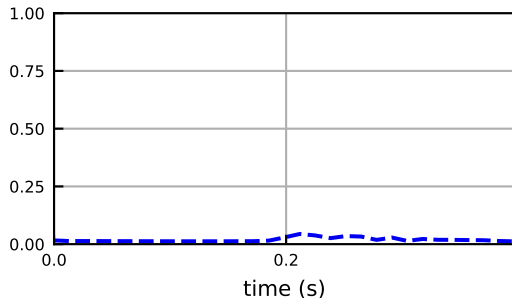




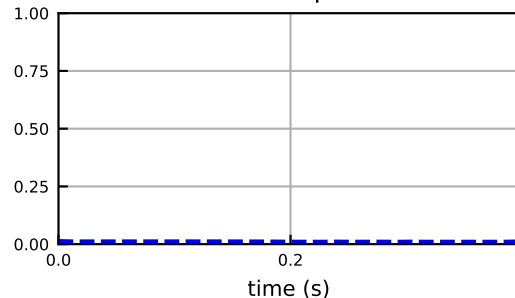
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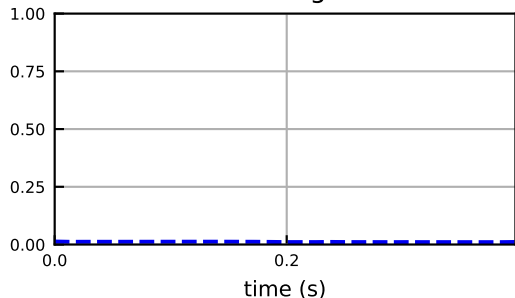
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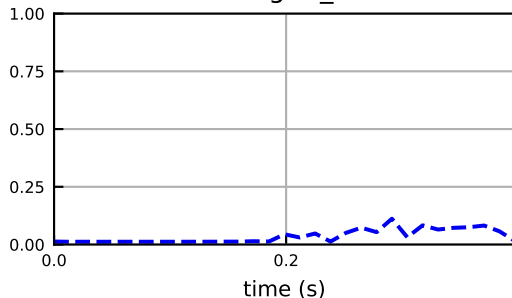
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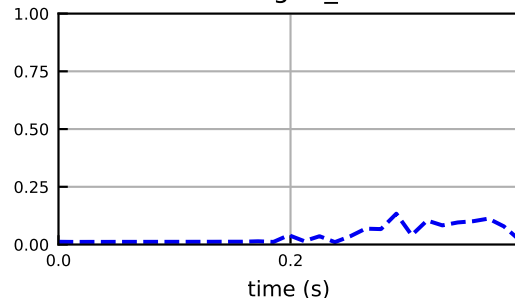
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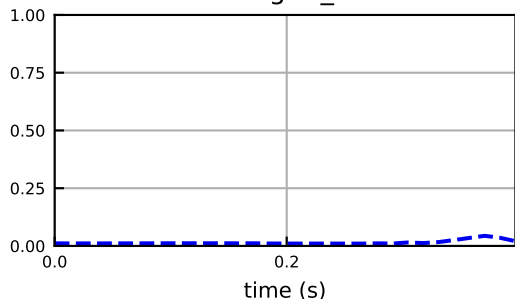
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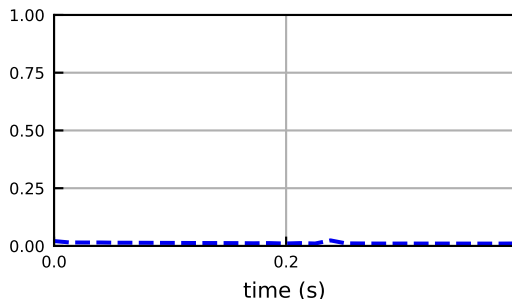
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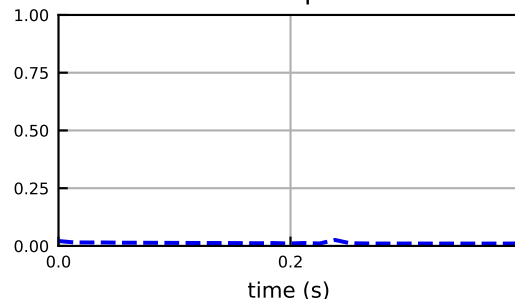
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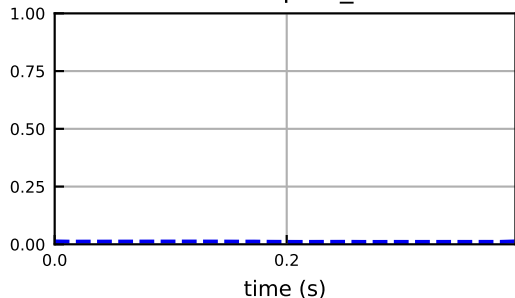
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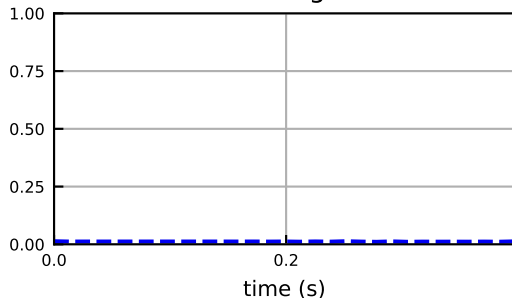
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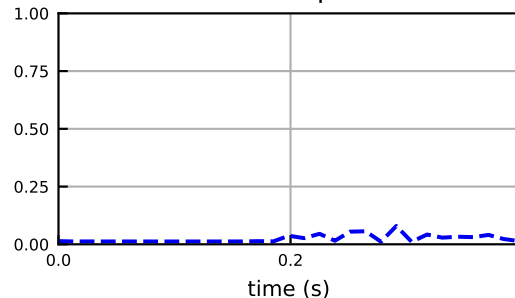
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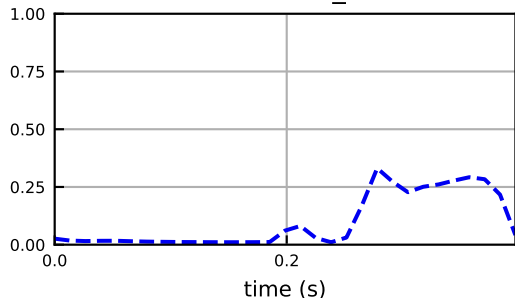
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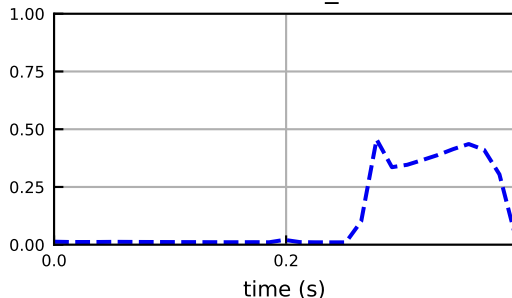
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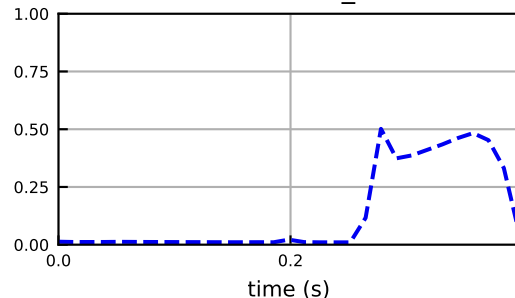
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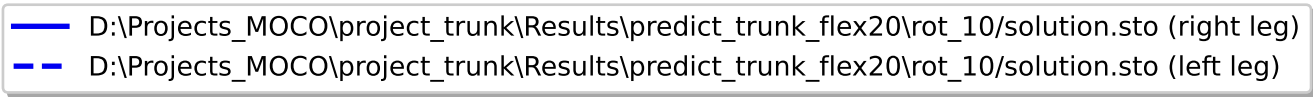


forcesetvas\_med

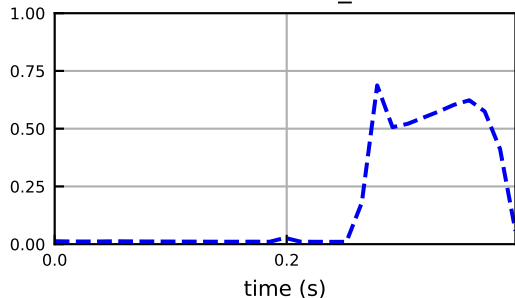


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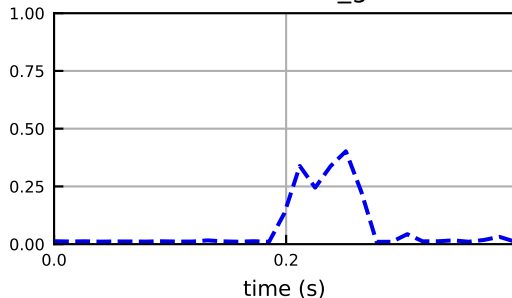




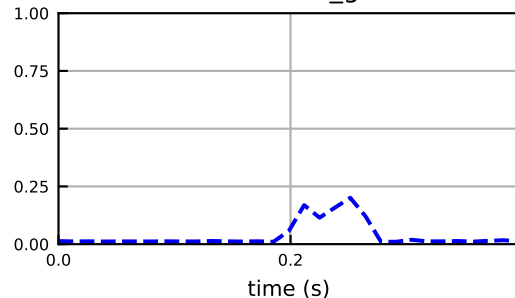
forcesetvas\_lat



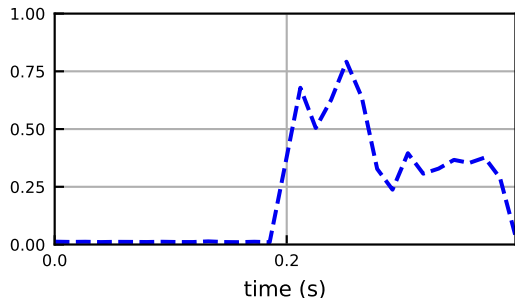
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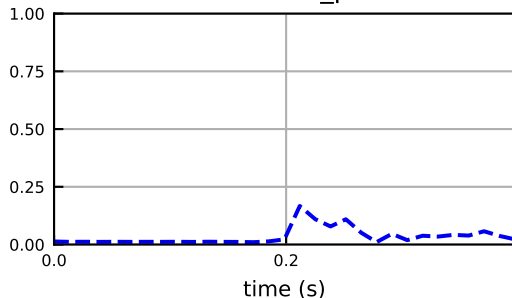
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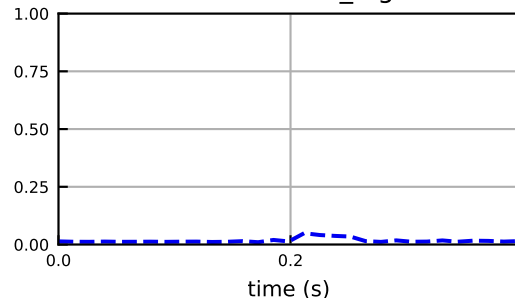
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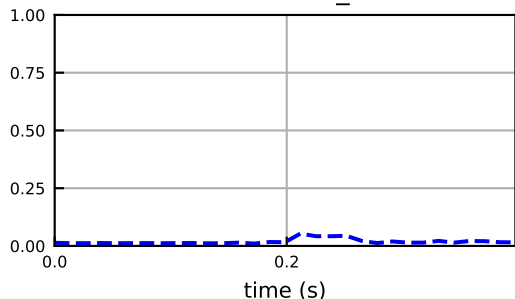
forcesettib\_post



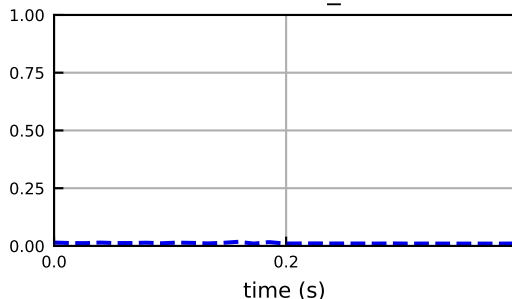
forcesetflex\_dig



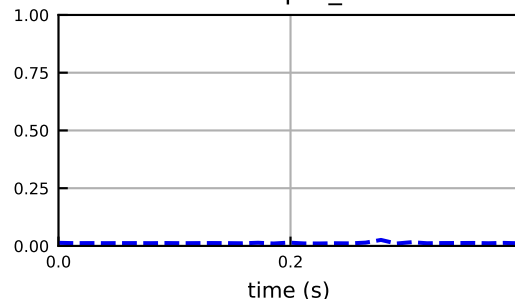
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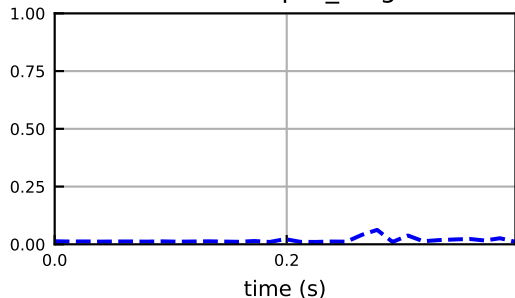
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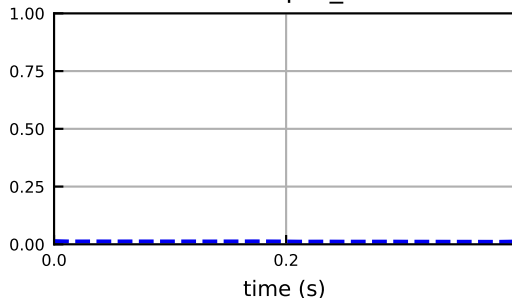
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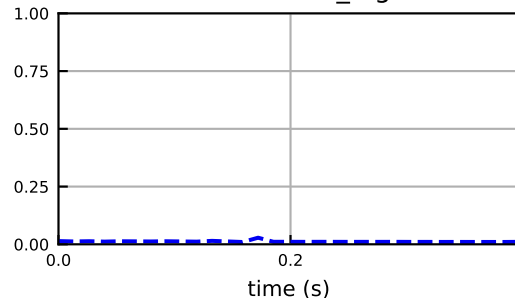
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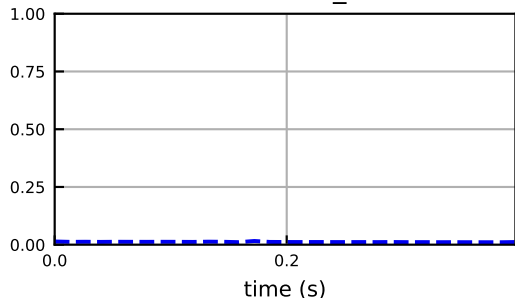
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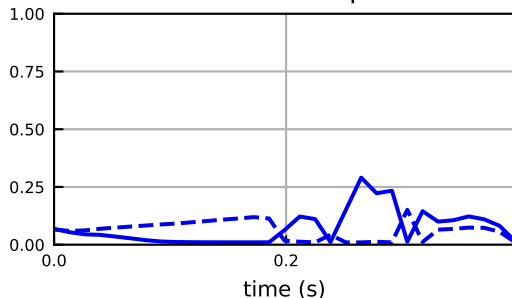
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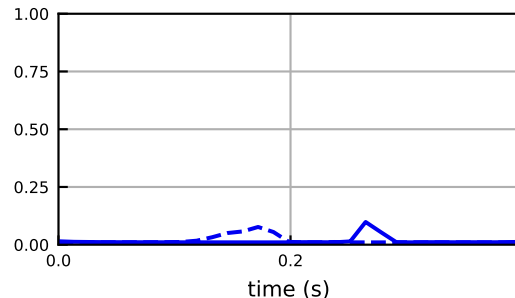
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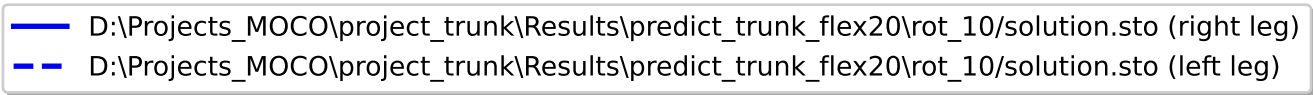


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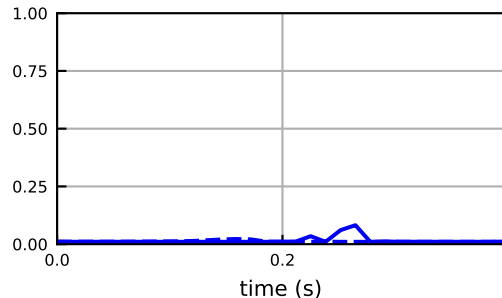


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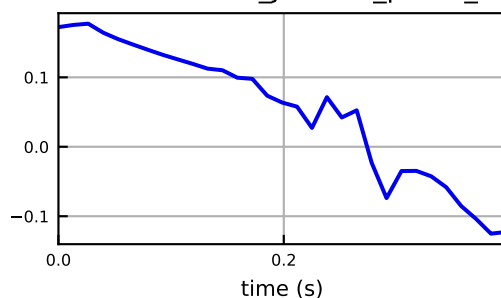




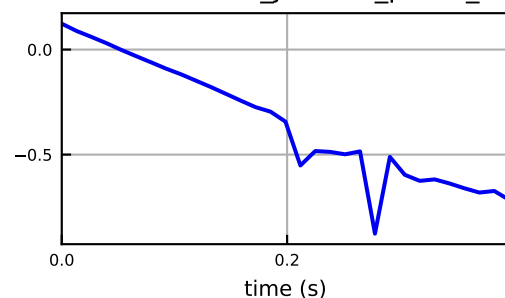
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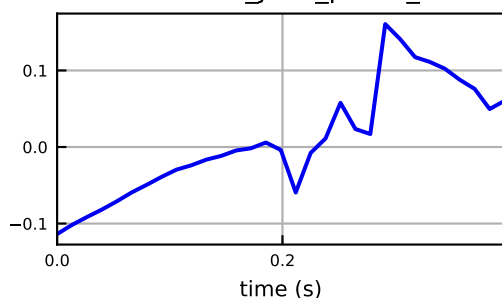
forcesetreserve\_joi...lvis\_pelvis\_tilt



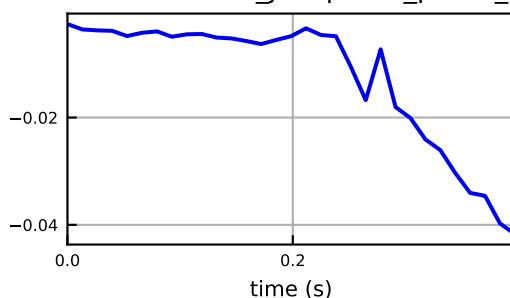
forcesetreserve\_joi...lvis\_pelvis\_list



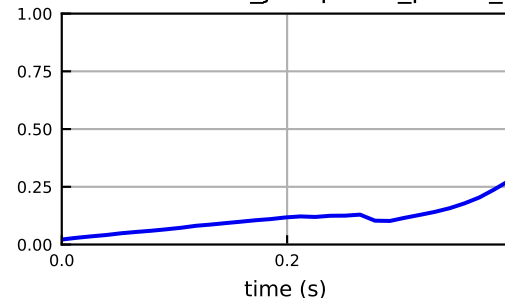
forcesetreserve\_joi...\_pelvis\_rotation



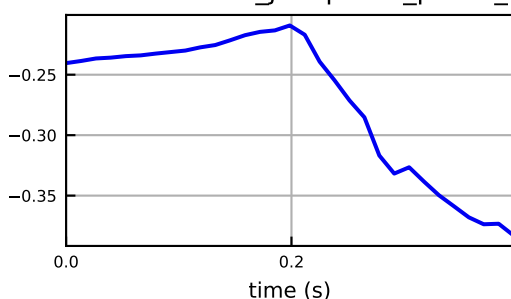
forcesetreserve\_joi...pelvis\_pelvis\_tx



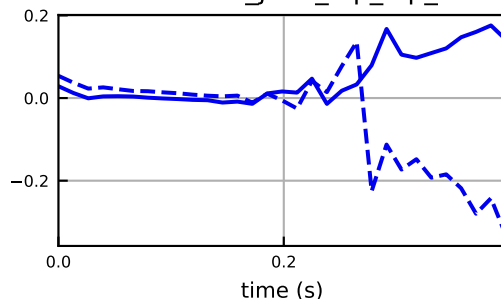
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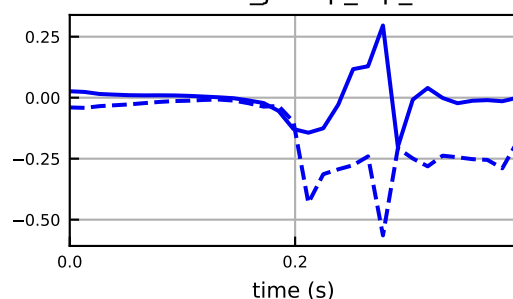
forcesetreserve\_joi...pelvis\_pelvis\_tz



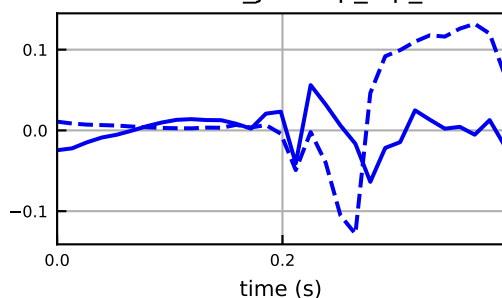
forcesetreserve\_joi...\_hip\_hip\_flexion



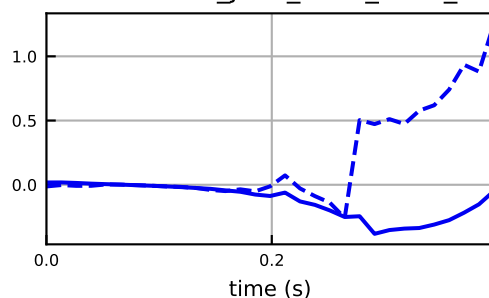
forcesetreserve\_joi...ip\_hip\_adduction



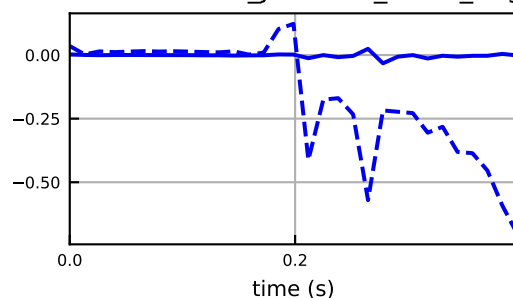
forcesetreserve\_joi...hip\_hip\_rotation



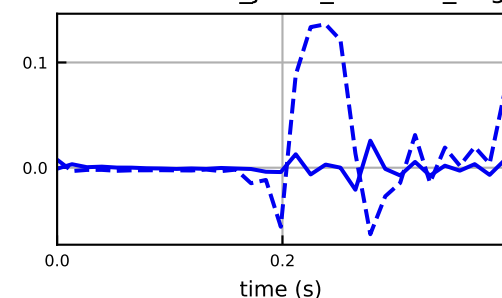
forcesetreserve\_joi...\_knee\_knee\_angle



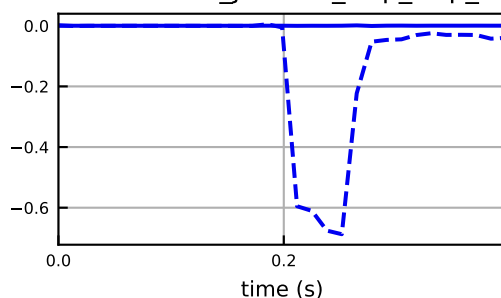
forcesetreserve\_joi...nkle\_ankle\_angle



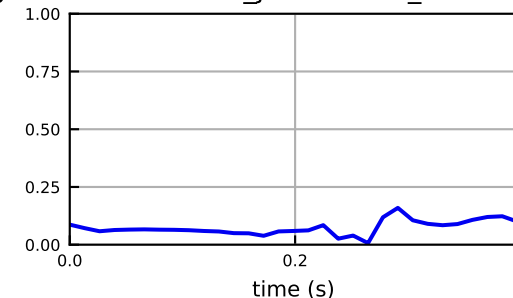
forcesetreserve\_joi...r\_subtalar\_angle

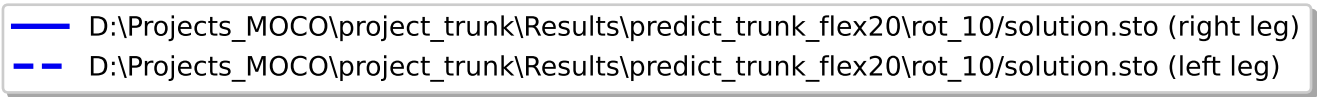


forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension





forcesetreserve\_joi...k\_lumbar\_bending    forcesetreserve\_joi...\_lumbar\_rotation

