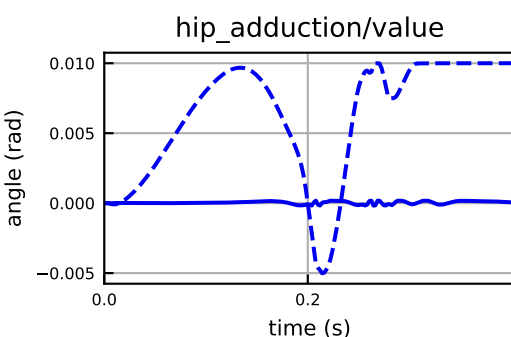
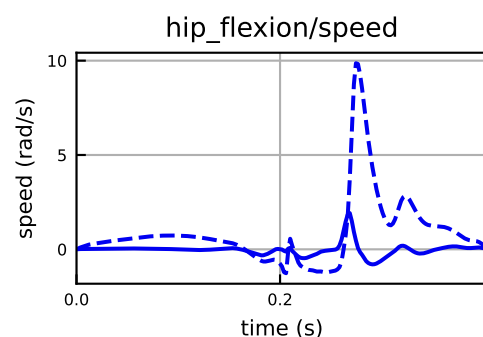
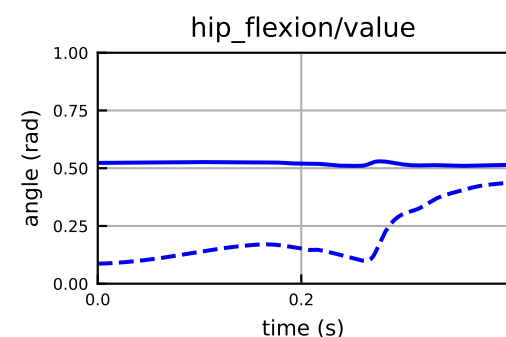
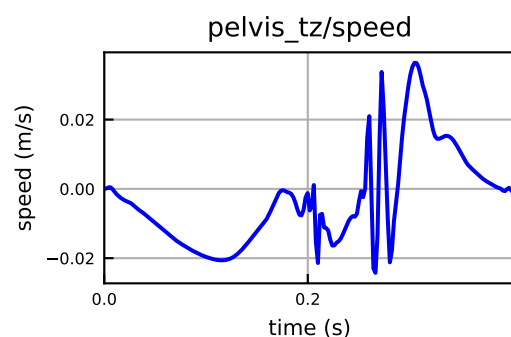
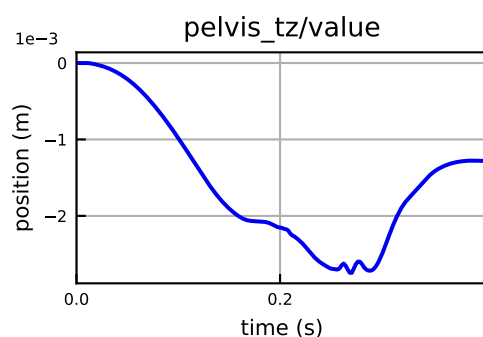
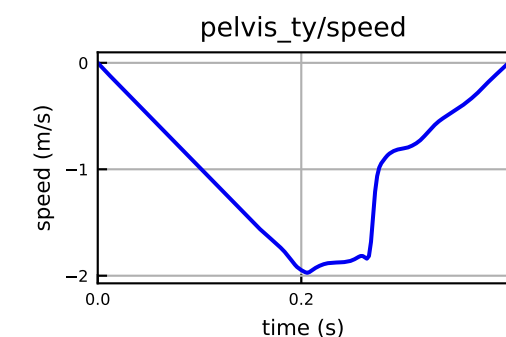
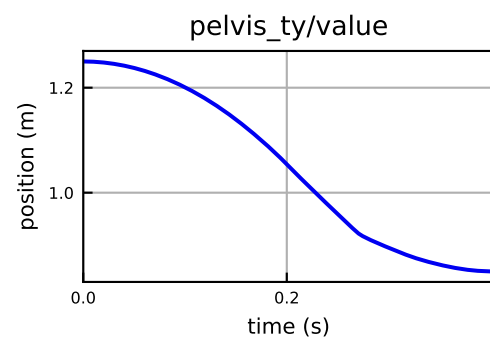
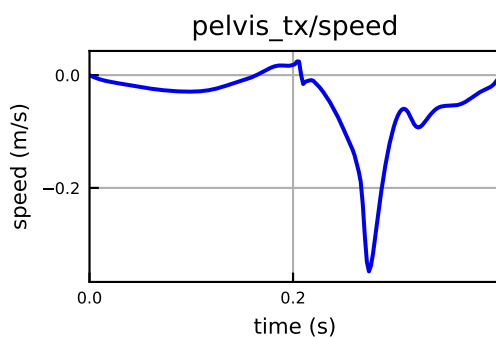
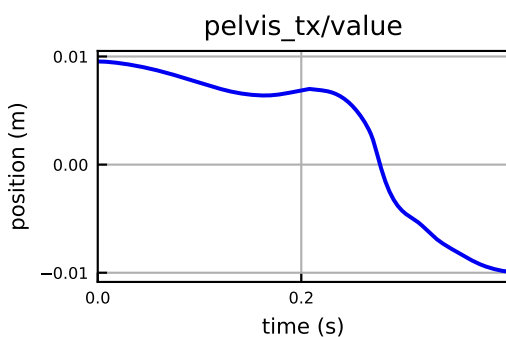
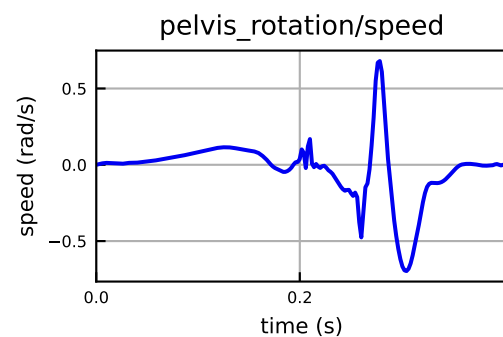
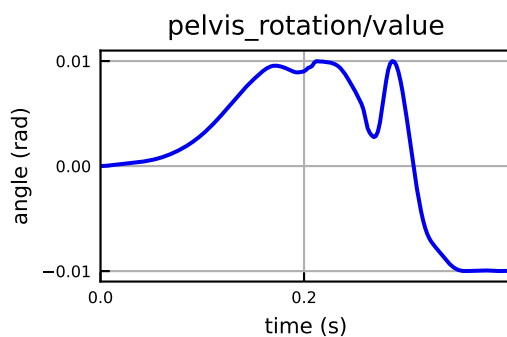
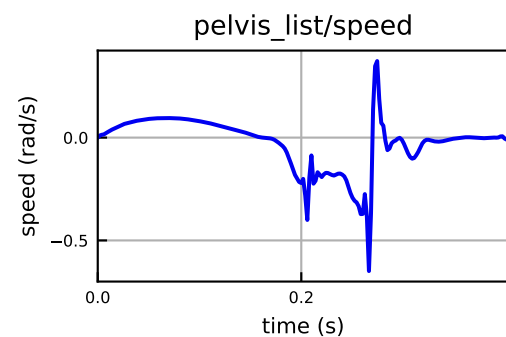
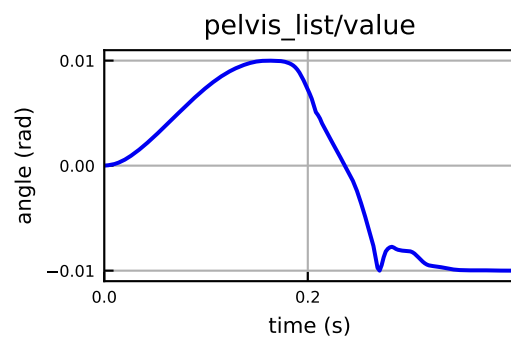
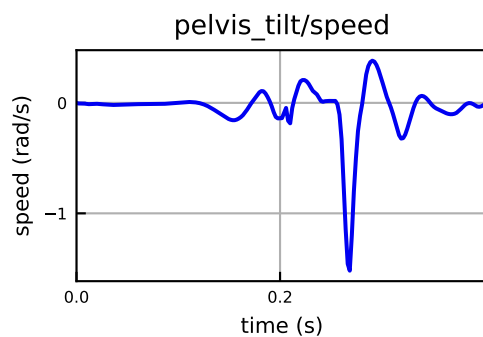
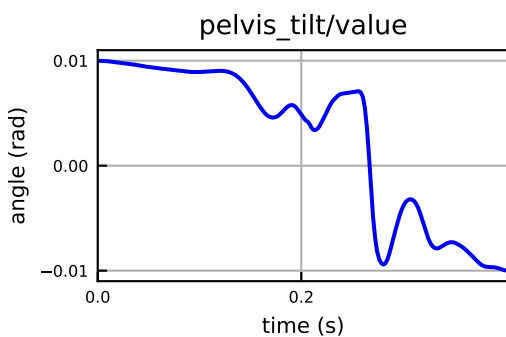
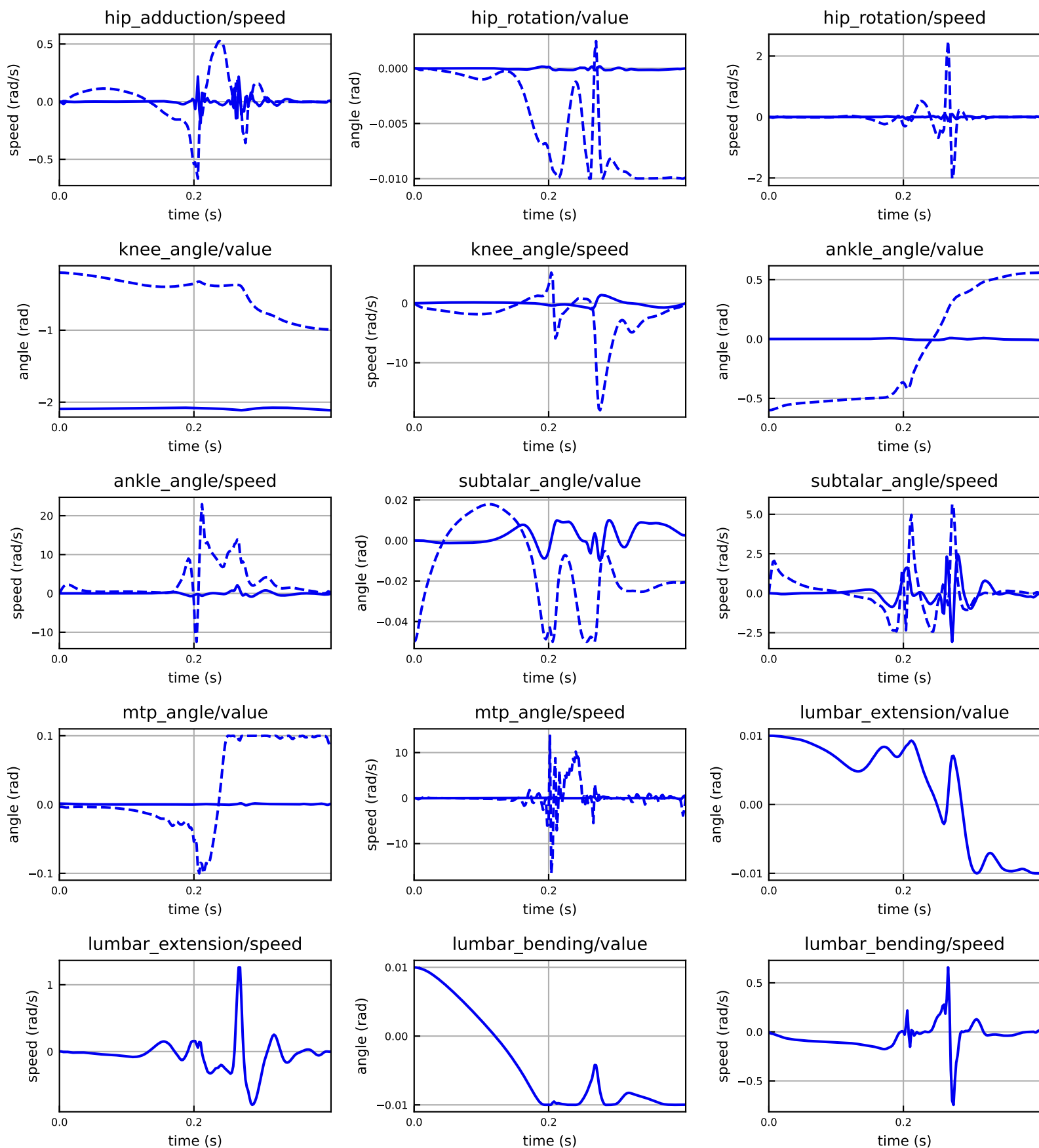


— D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (left leg)

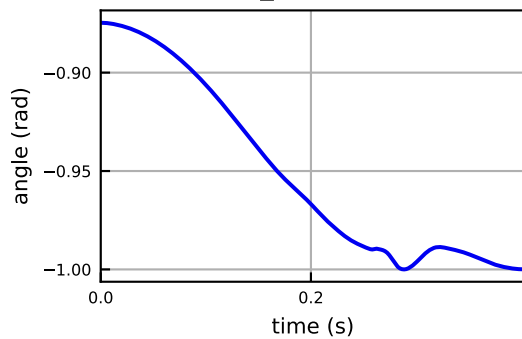


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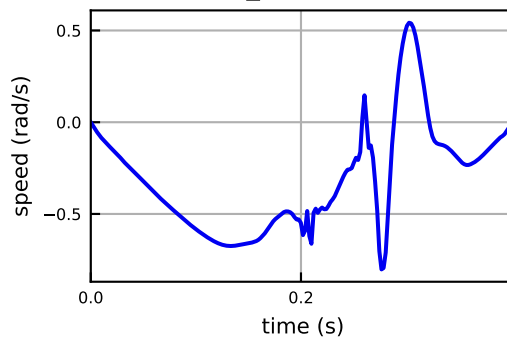


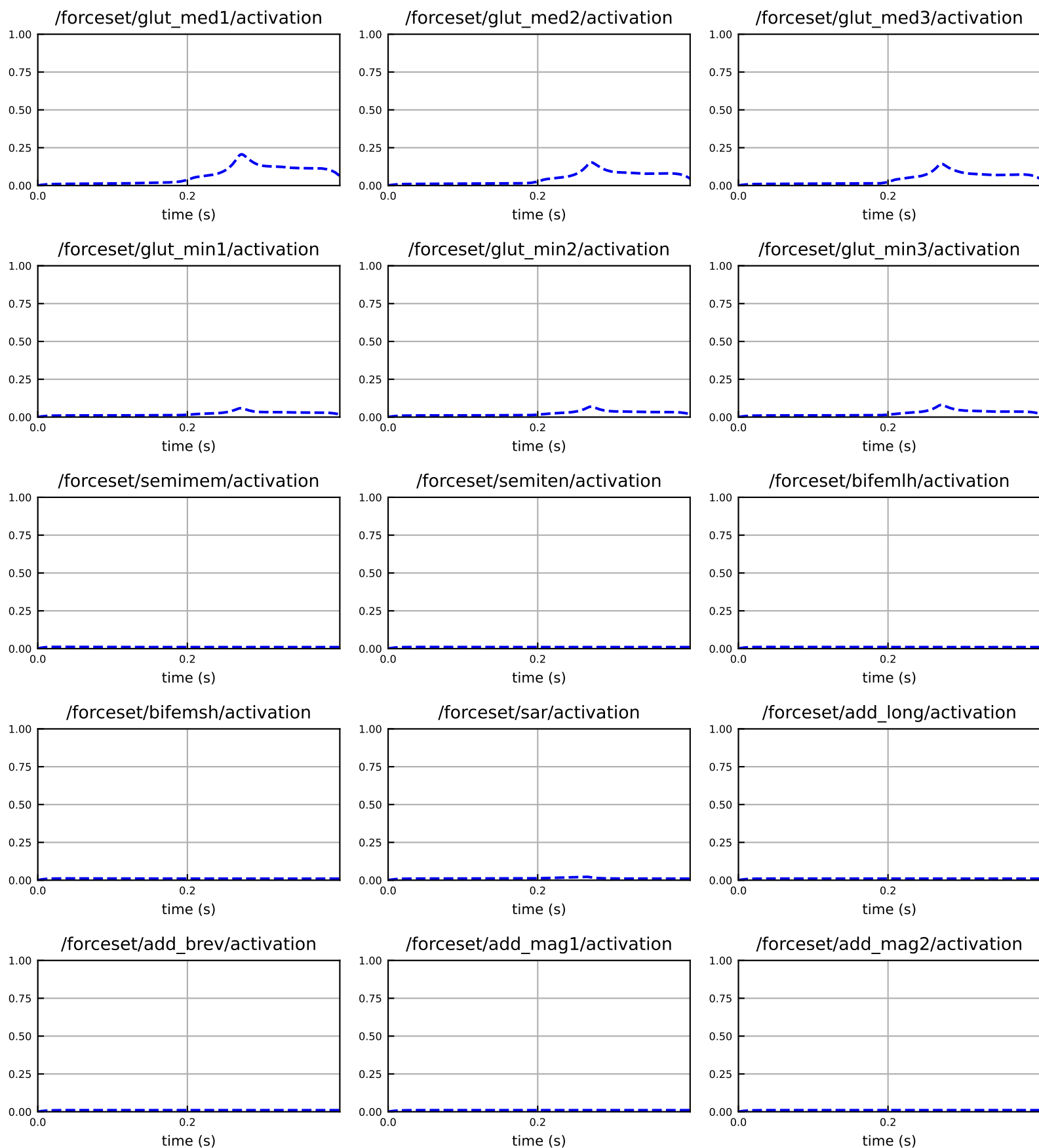
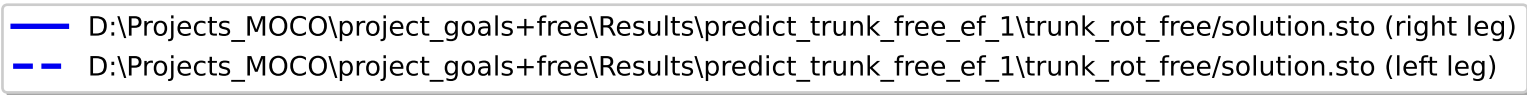
— D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (right leg)  
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lumbar\_rotation/value

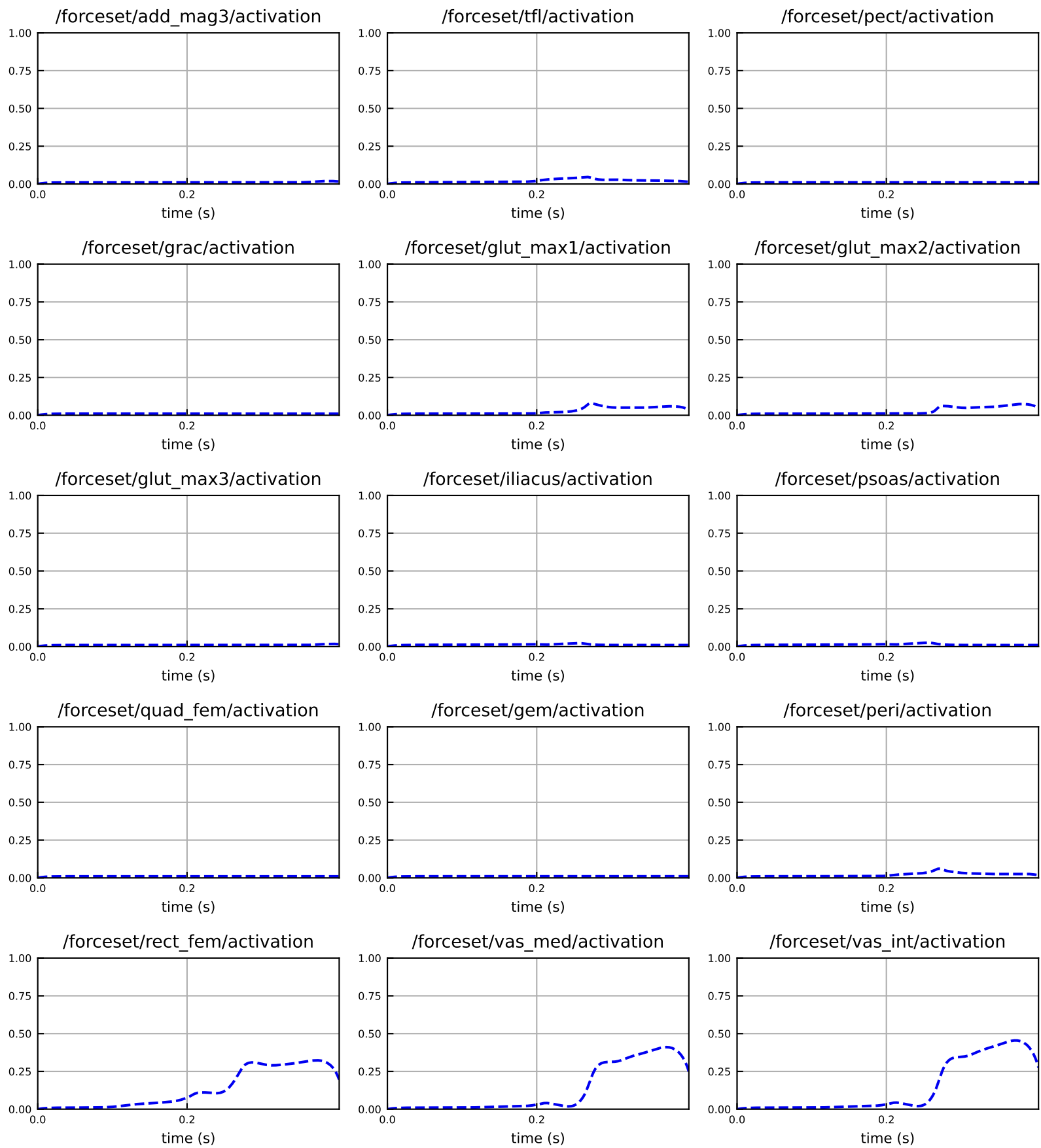


lumbar\_rotation/speed

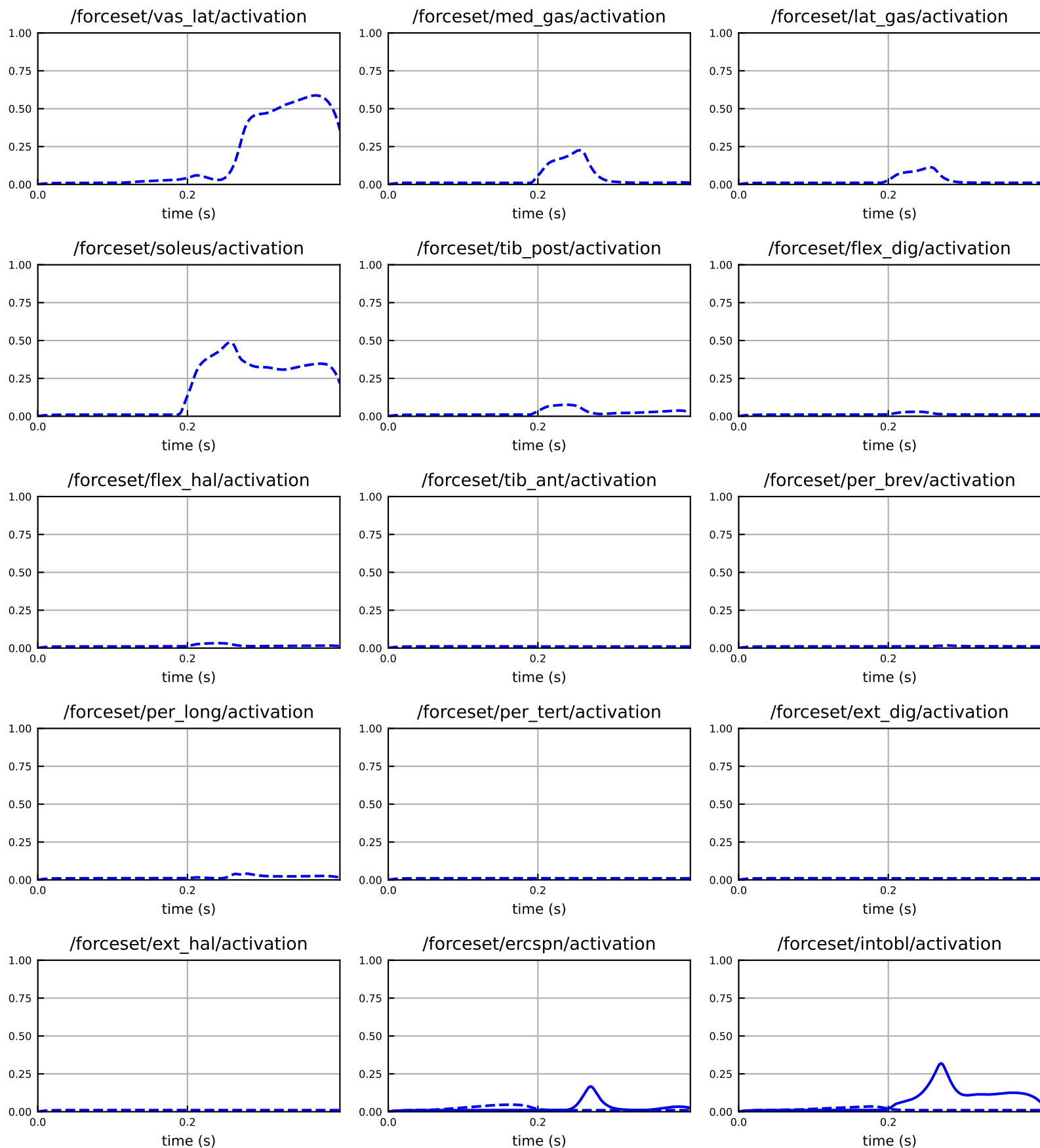


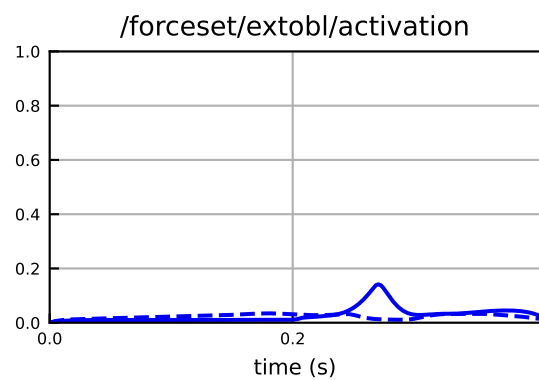
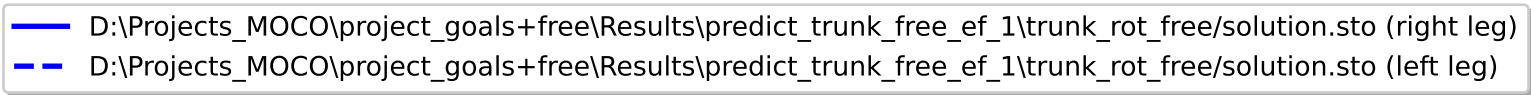


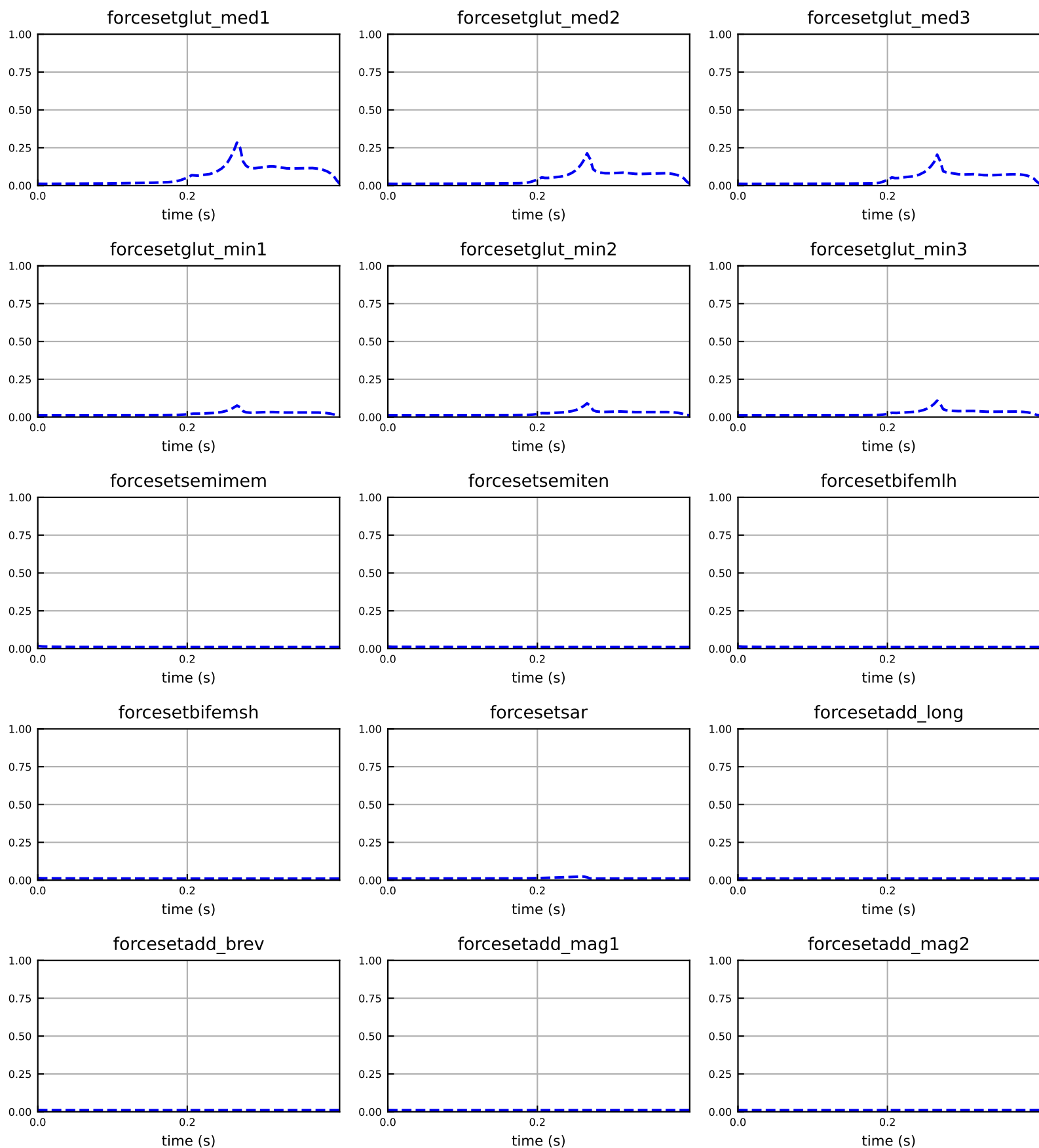
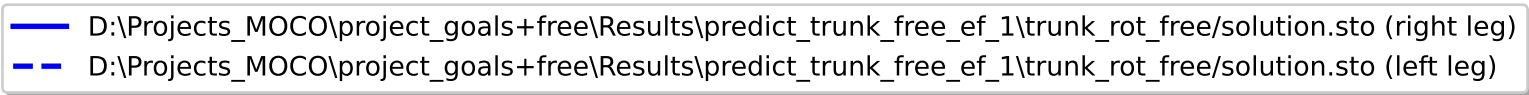
— D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (left leg)



— D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (right leg)  
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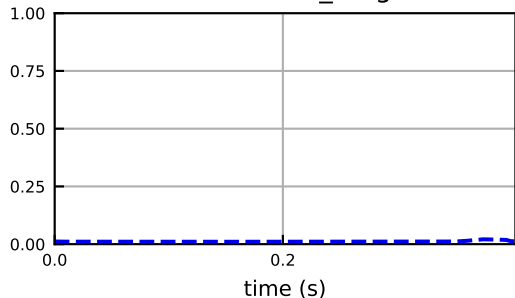




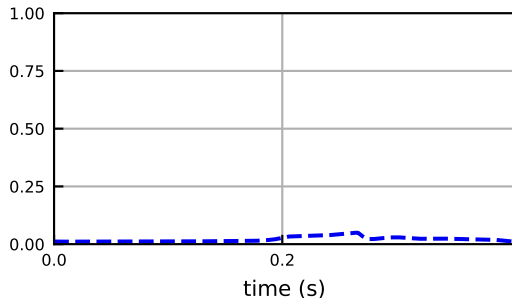


— D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (right leg)  
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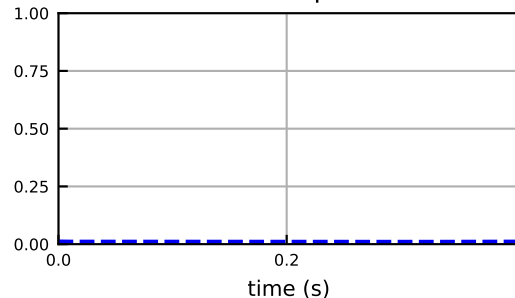
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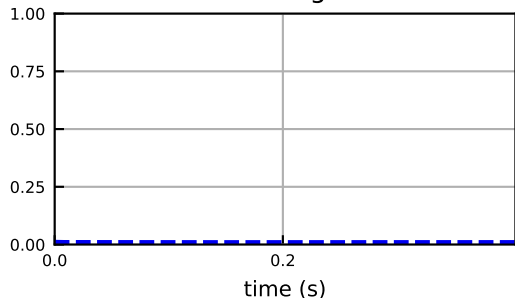
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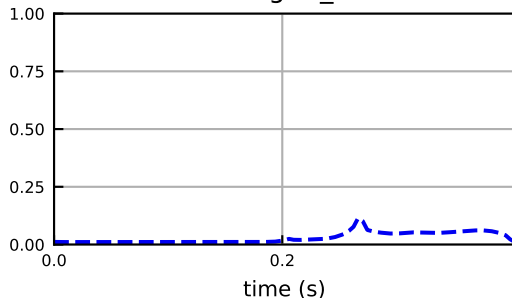
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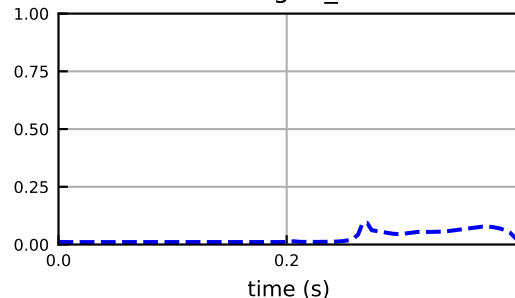
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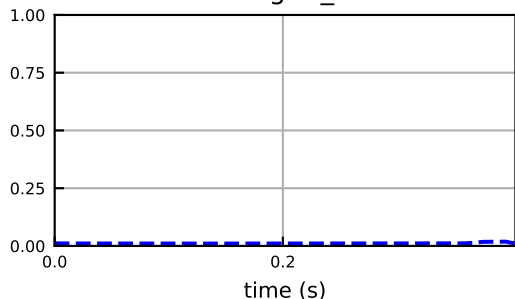
forcesetglut\_max1



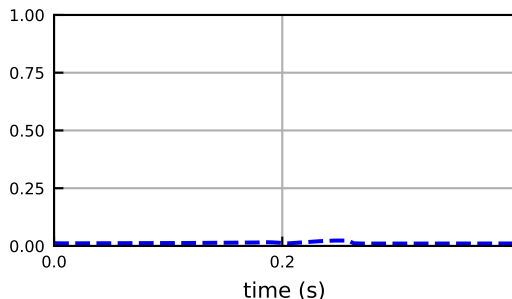
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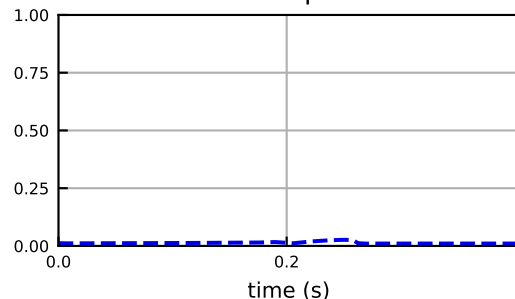
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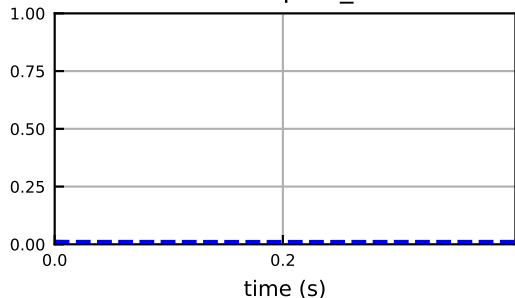
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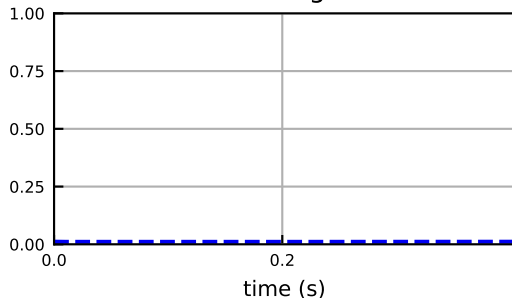
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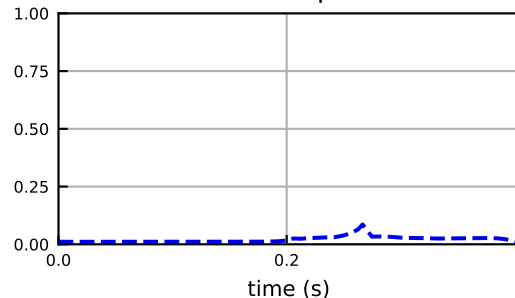
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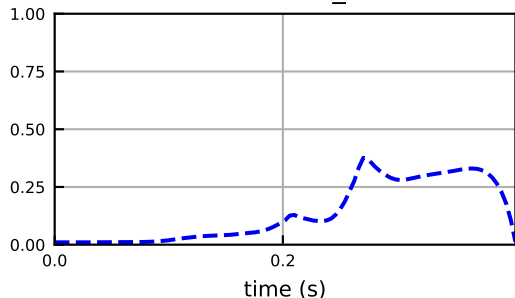
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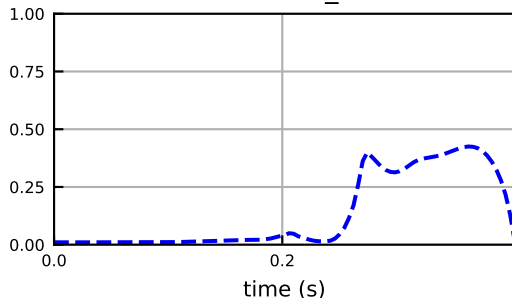
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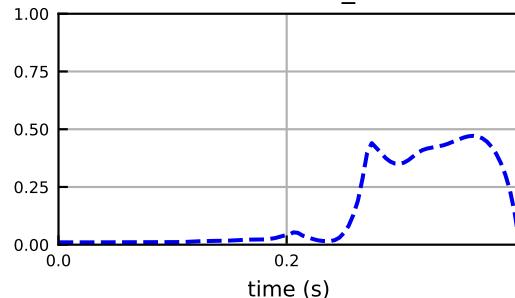
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forcesetvas\_med

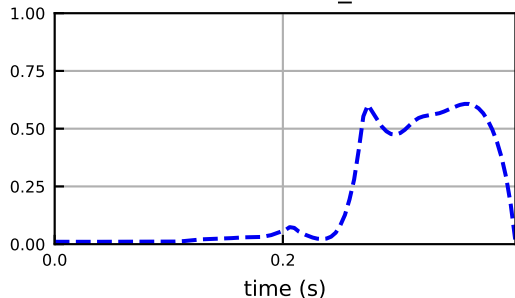


forcesetvas\_int

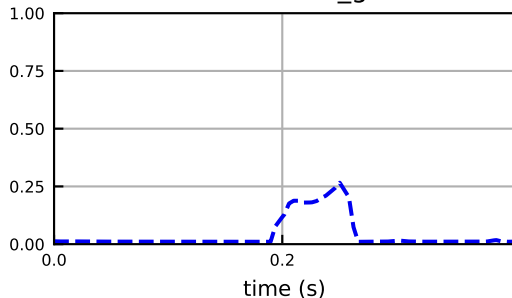


— D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (left leg)

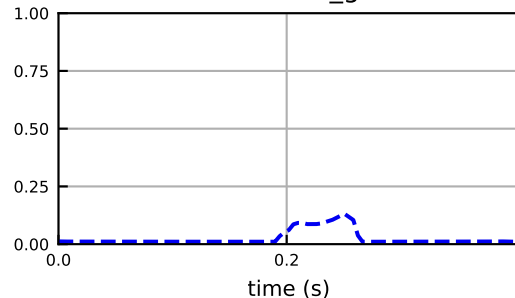
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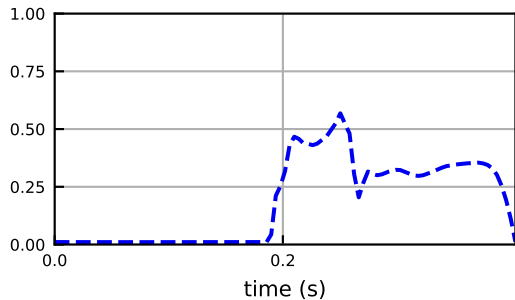
forcesetmed\_gas



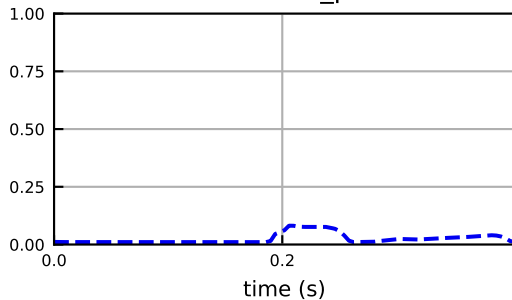
forcesetlat\_gas



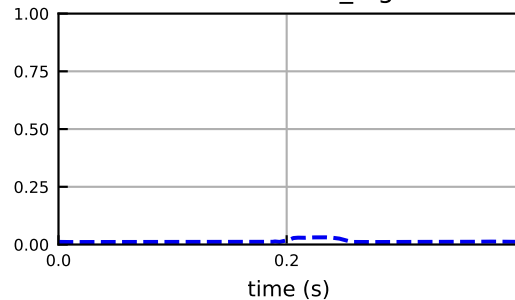
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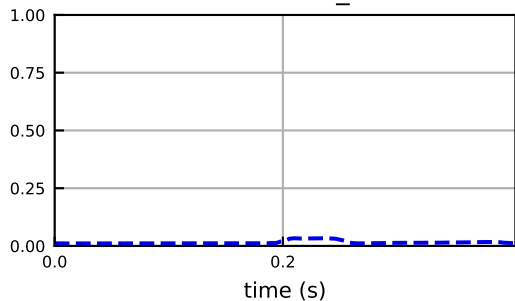
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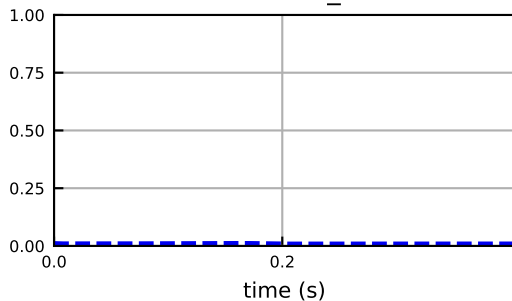
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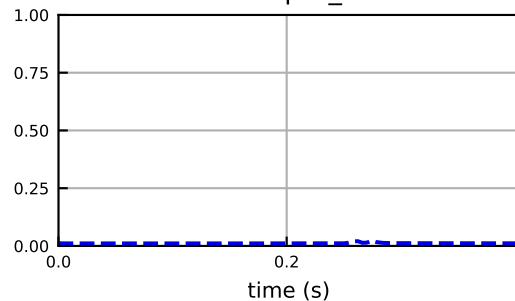
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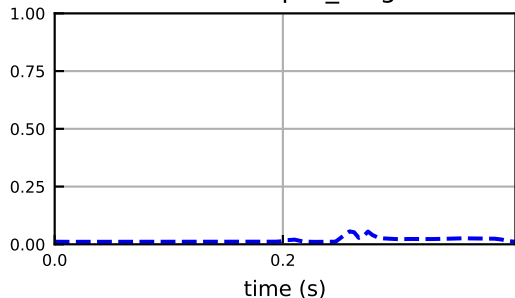
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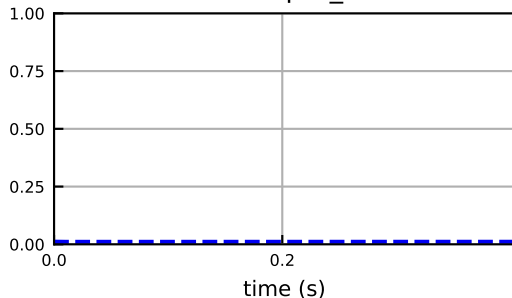
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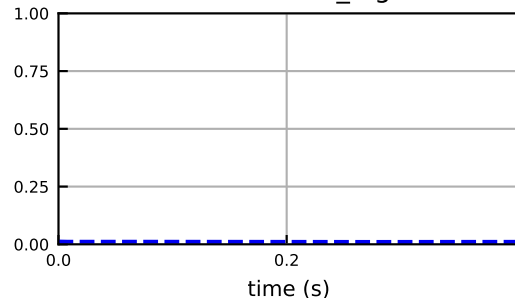
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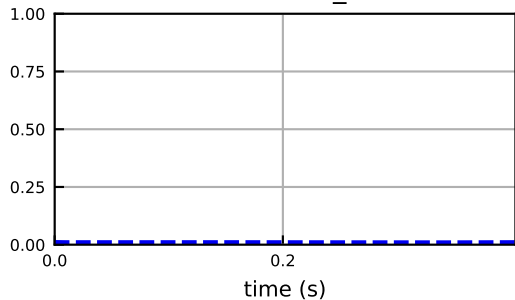
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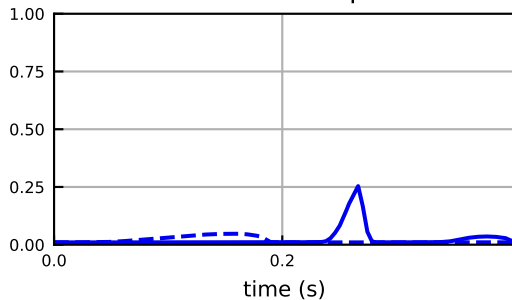
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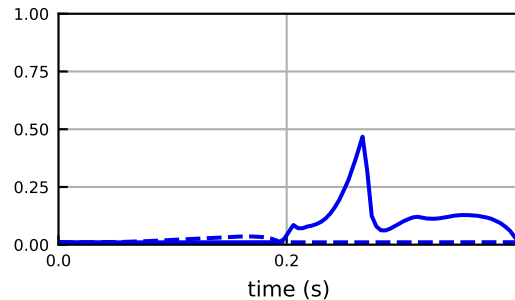
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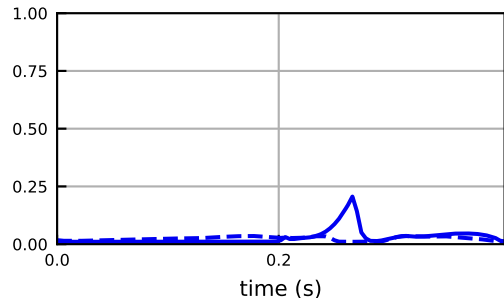


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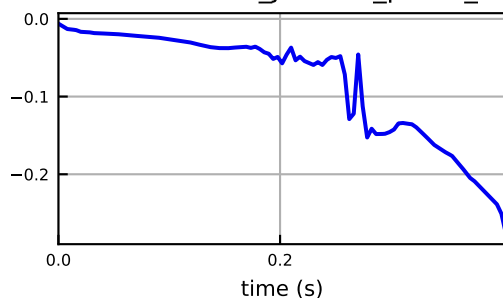


— D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (right leg)  
- - - D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (left leg)

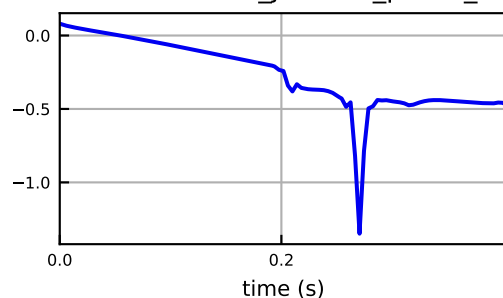
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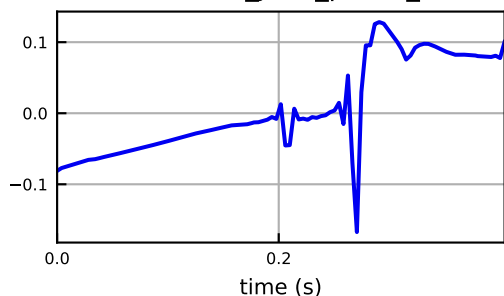
forcesetreserve\_joi...lvis\_pelvis\_tilt



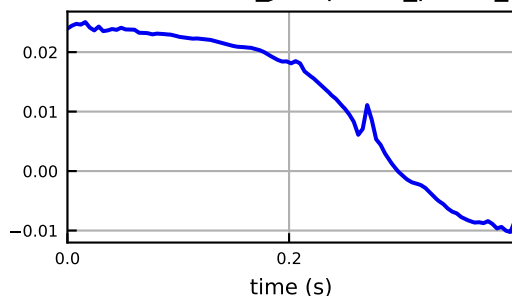
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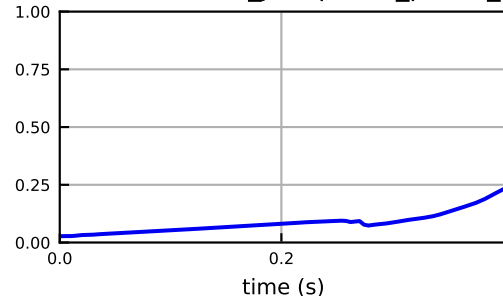
forcesetreserve\_joi...\_pelvis\_rotation



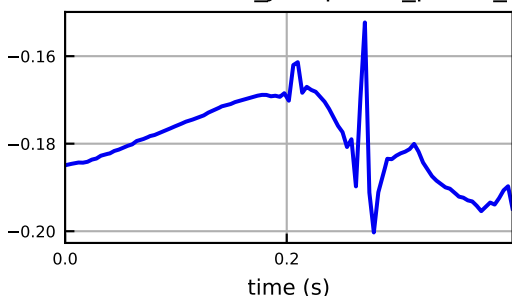
forcesetreserve\_joi...pelvis\_pelvis\_tx



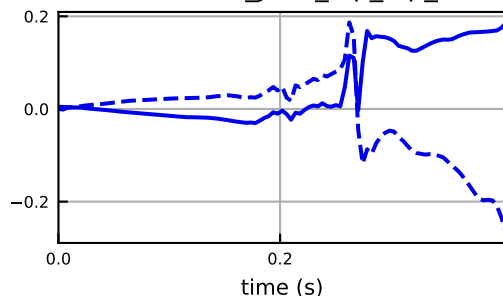
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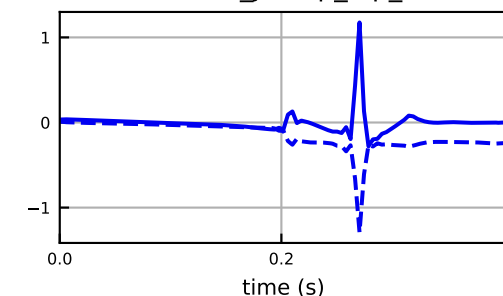
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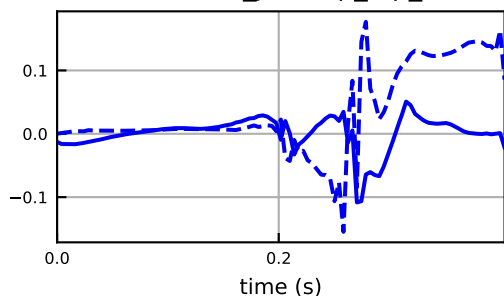
forcesetreserve\_joi...\_hip\_hip\_flexion



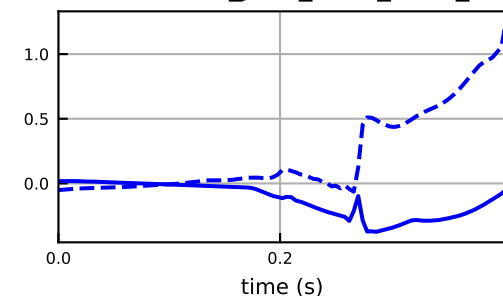
forcesetreserve\_joi...ip\_hip\_adduction



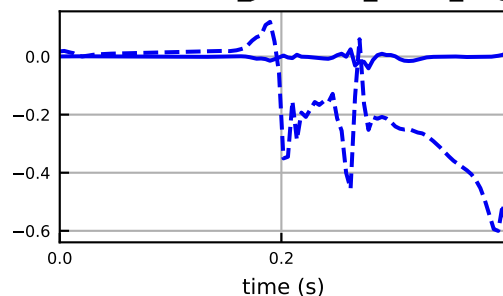
forcesetreserve\_joi...hip\_hip\_rotation



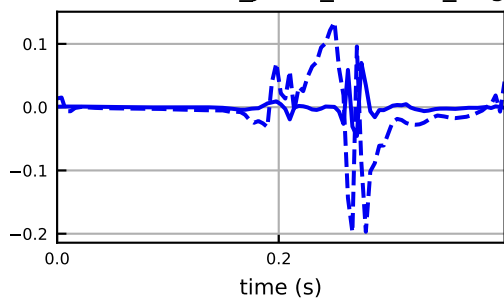
forcesetreserve\_joi...\_knee\_knee\_angle



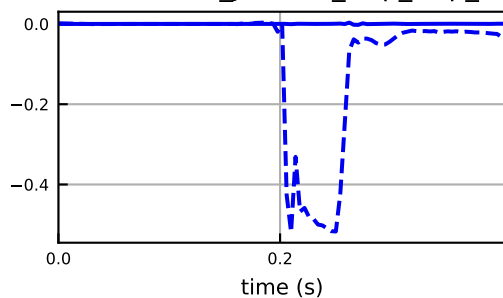
forcesetreserve\_joi...nkle\_ankle\_angle



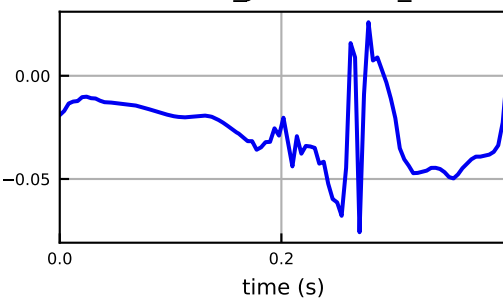
forcesetreserve\_joi...r\_subtalar\_angle



forcesetreserve\_jointset\_mtp\_mtp\_angle



forcesetreserve\_joi...lumbar\_extension



— D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (right leg)  
- - D:\Projects\_MOCO\project\_goals+free\Results\predict\_trunk\_free\_ef\_1\trunk\_rot\_free\solution.sto (left leg)

