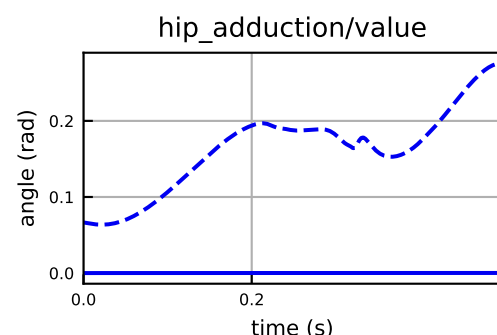
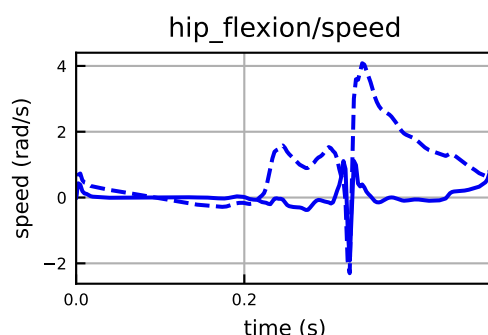
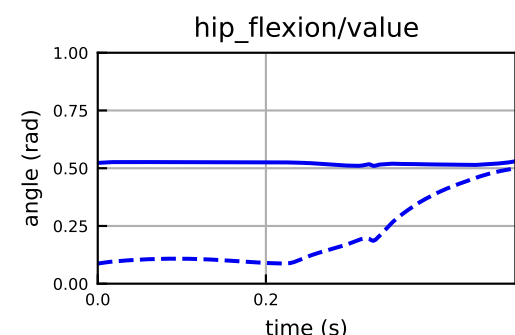
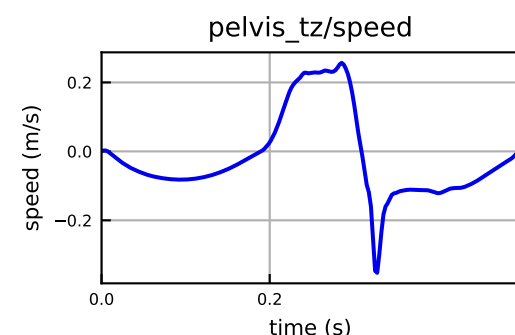
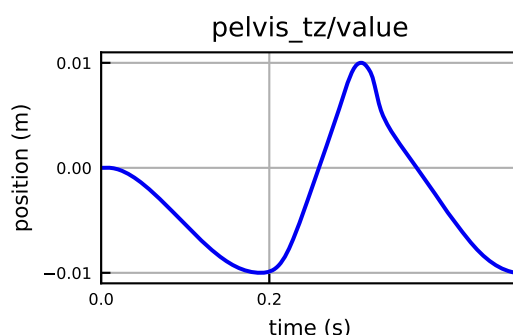
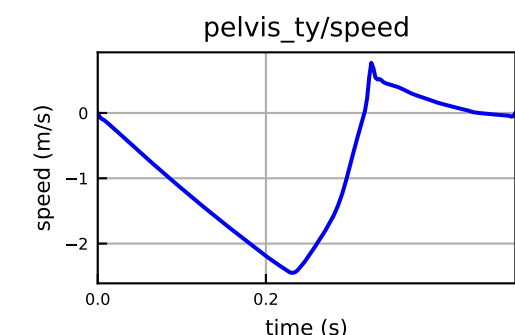
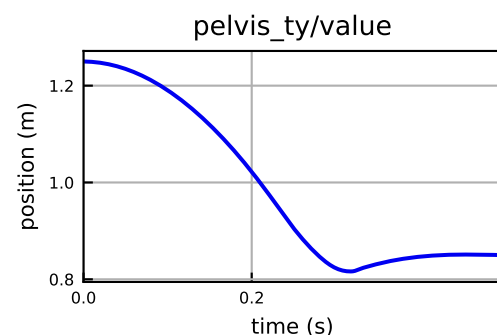
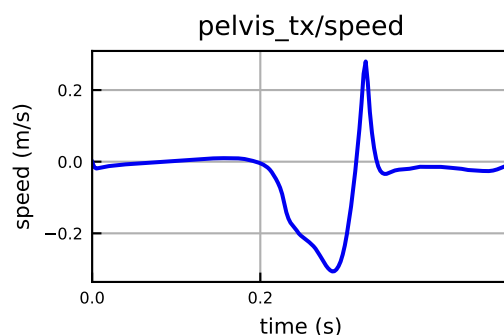
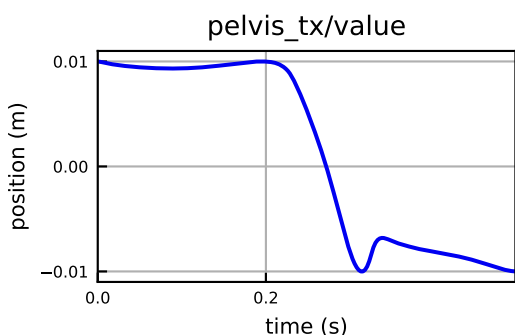
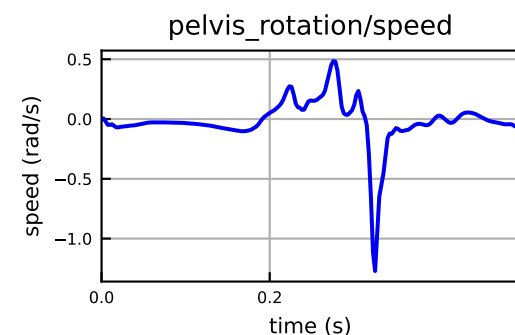
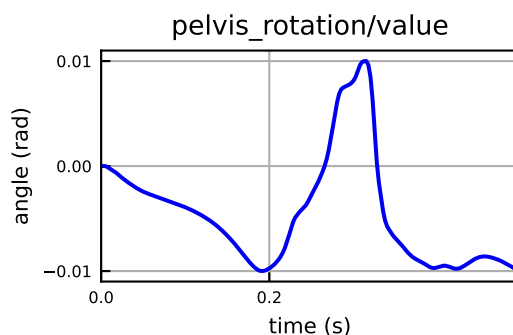
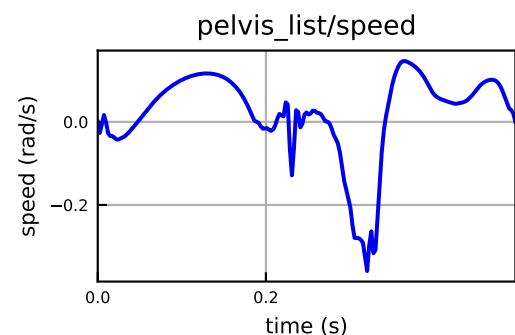
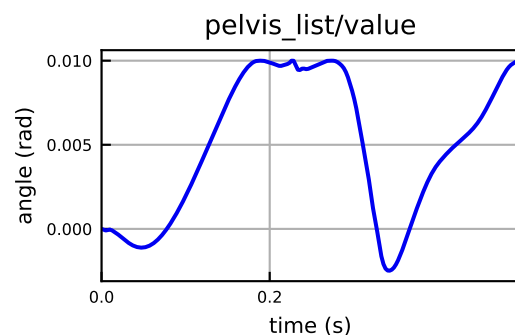
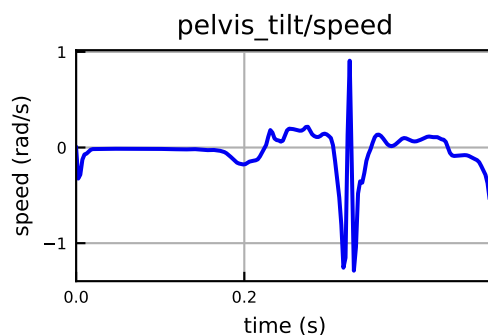
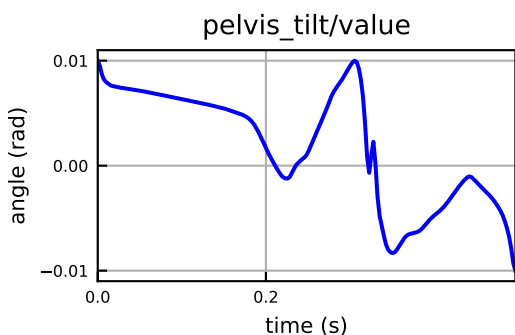
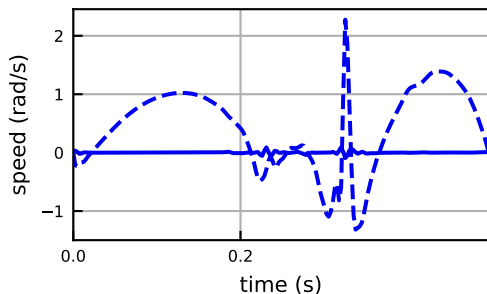


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
- - - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)

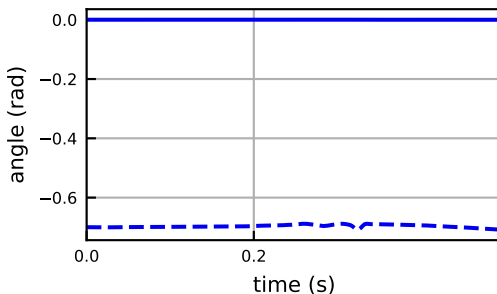


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
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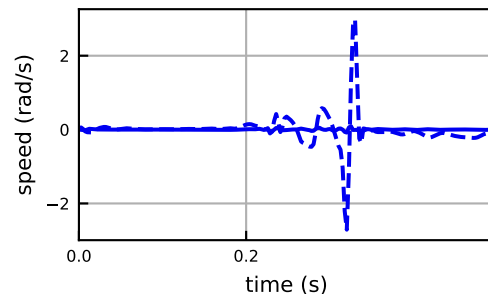
hip_adduction/speed



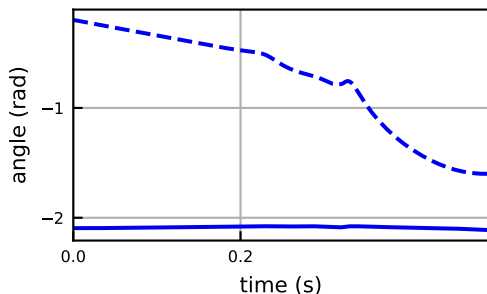
hip_rotation/value



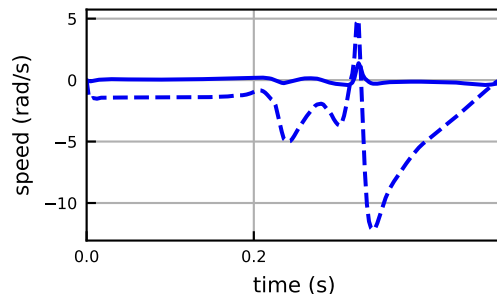
hip_rotation/speed



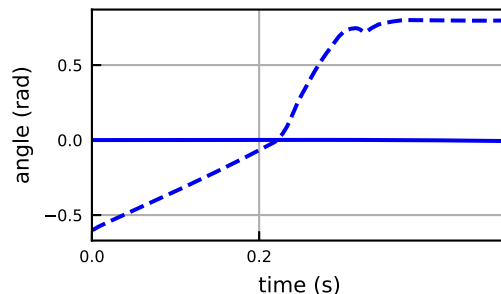
knee_angle/value



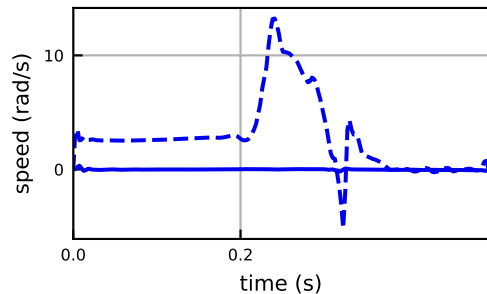
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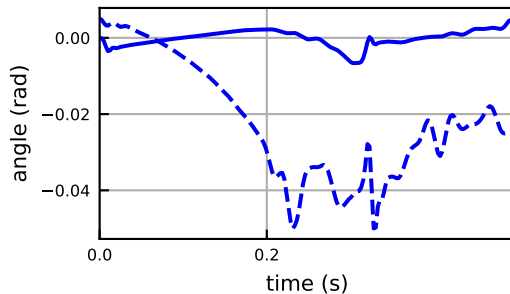
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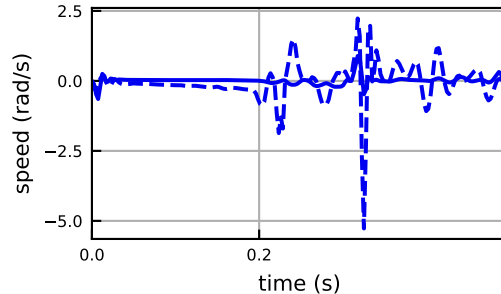
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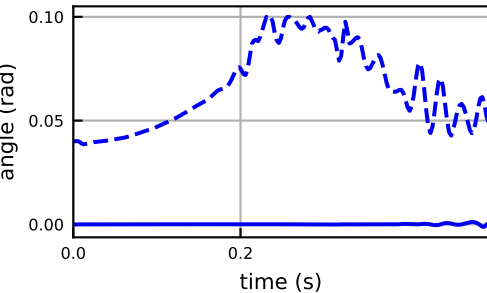
subtalar_angle/value



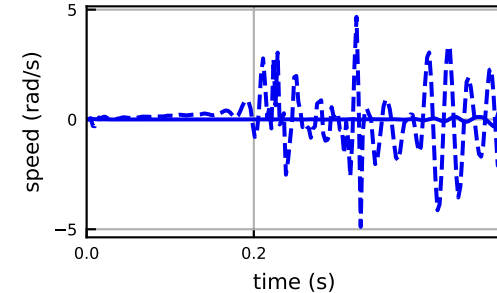
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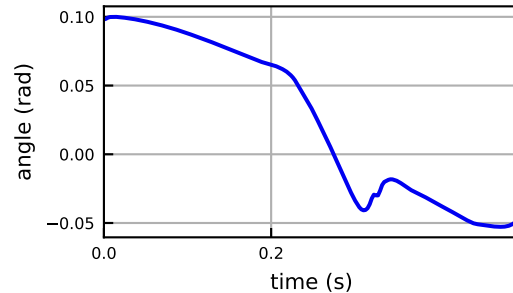
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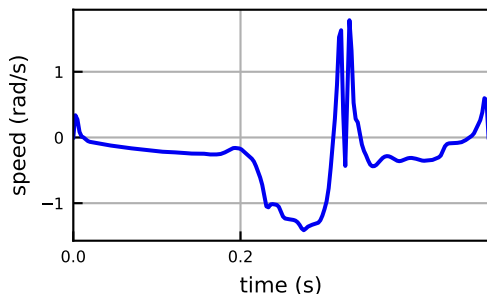
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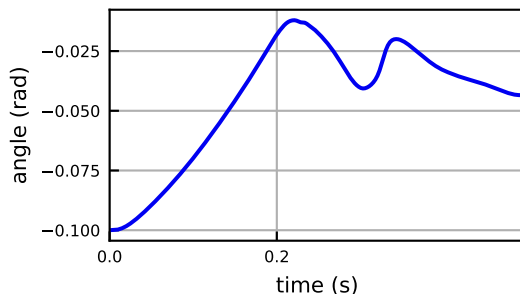
lumbar_extension/value



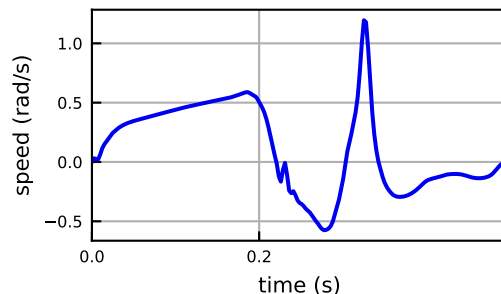
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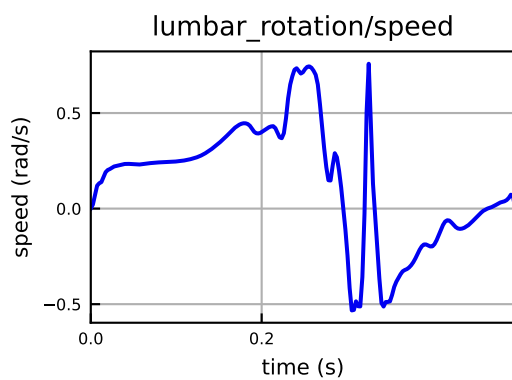
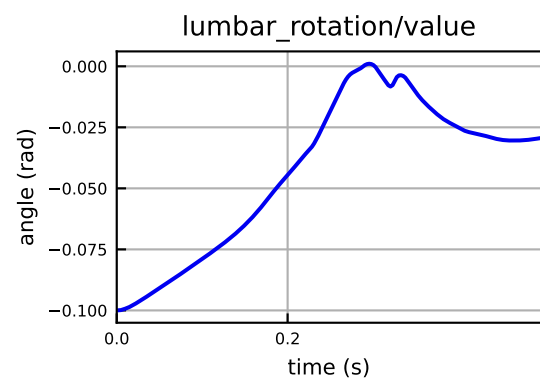
lumbar_bending/value



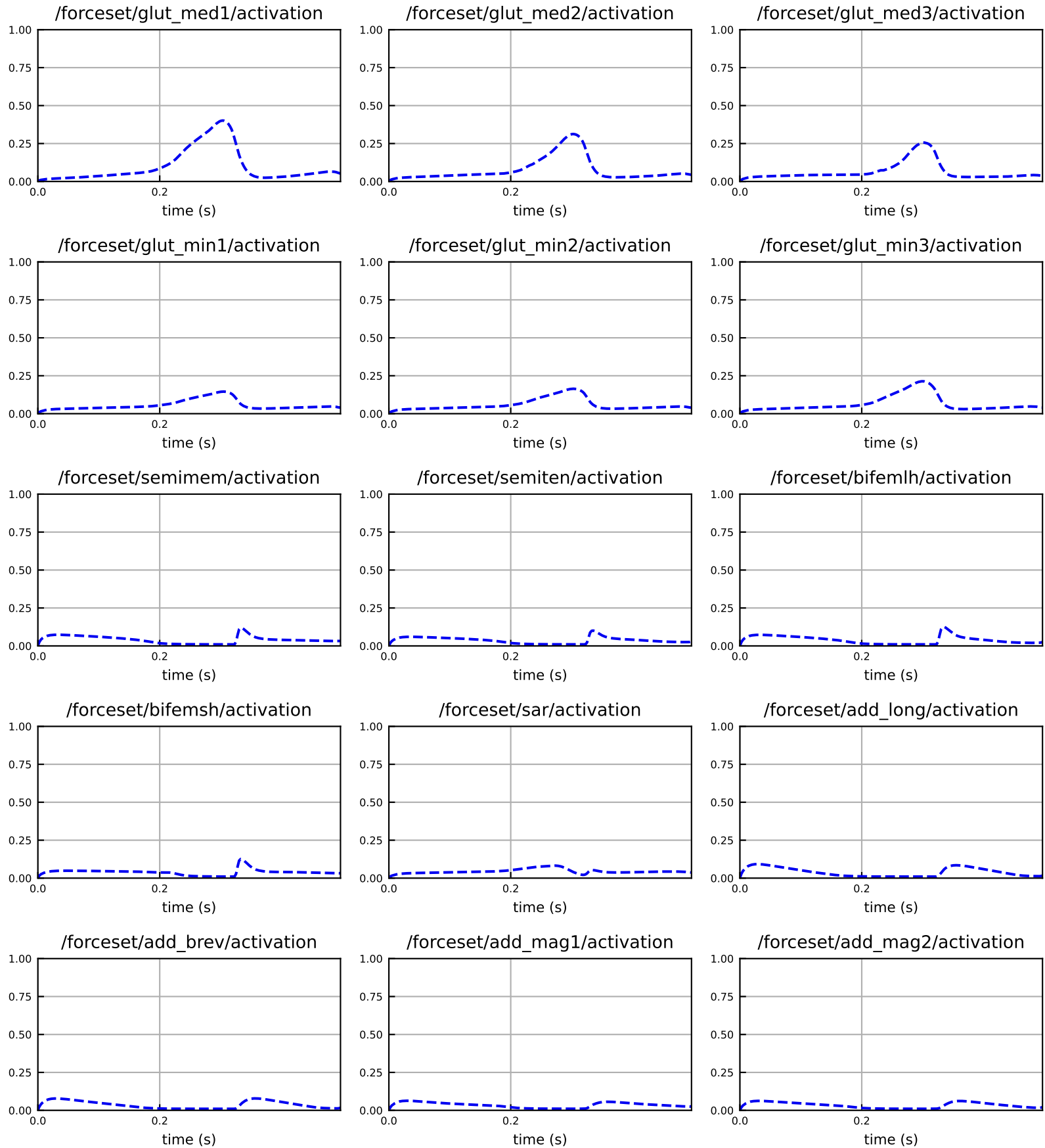
lumbar_bending/speed



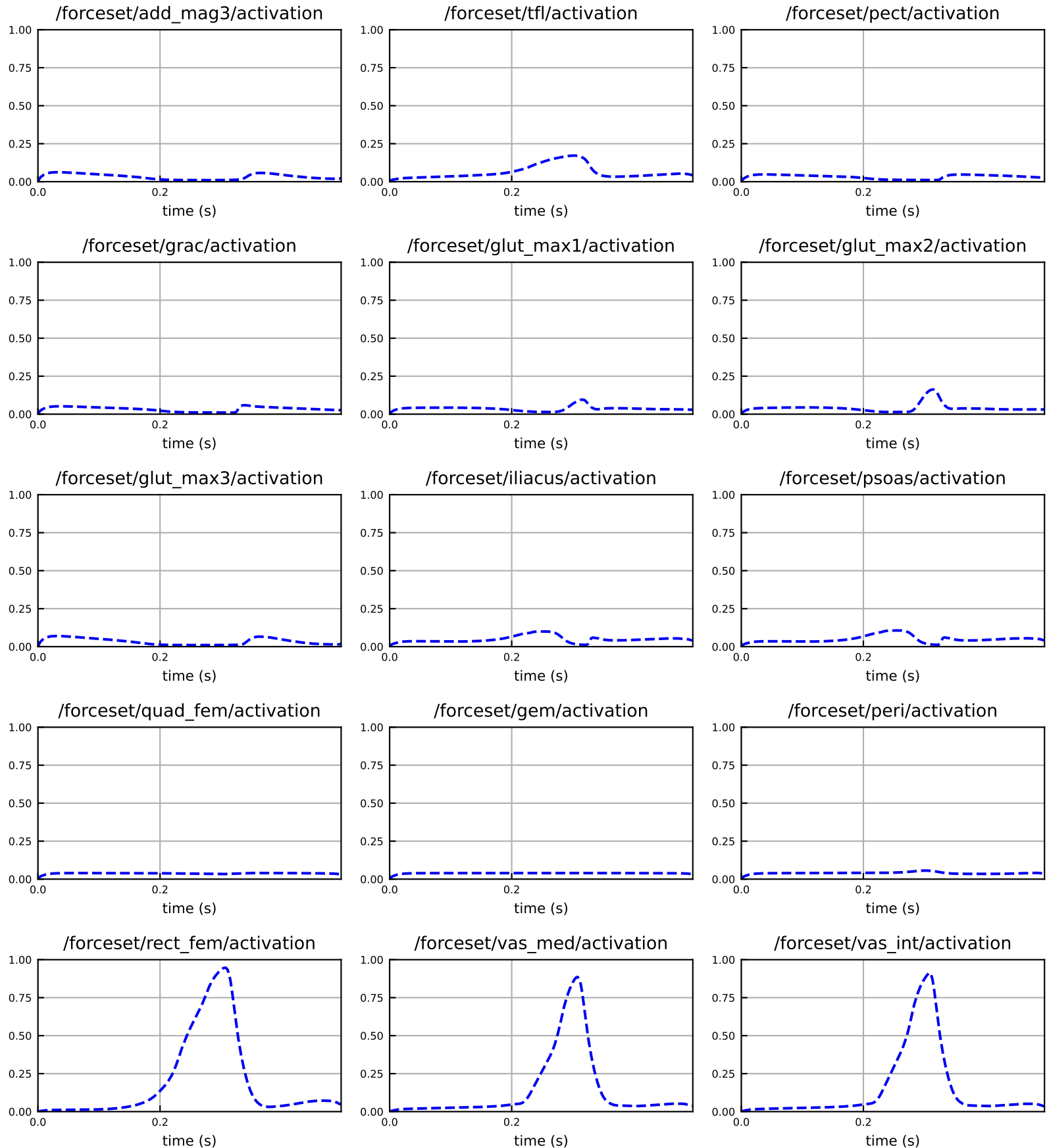
— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
- - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)



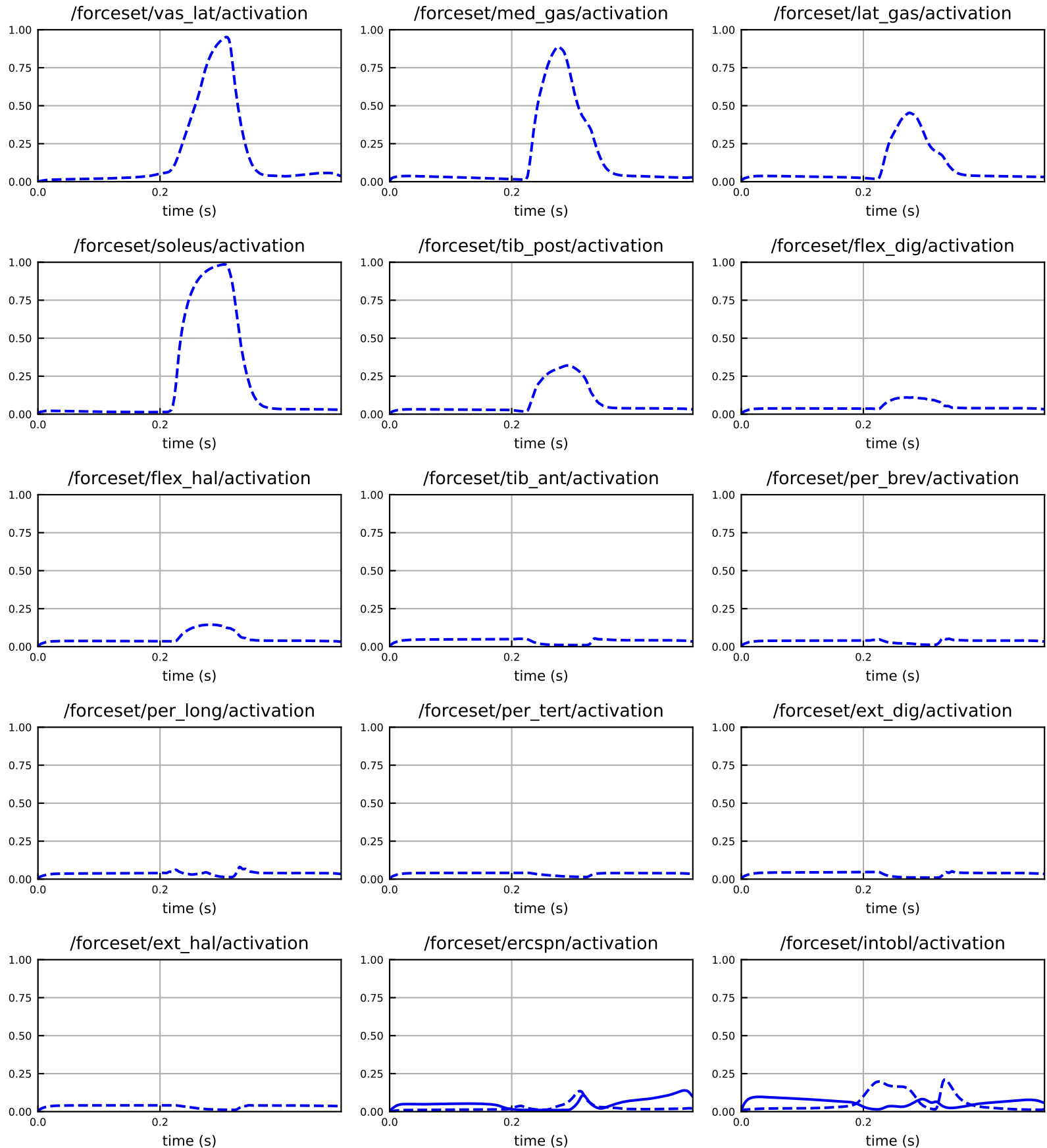
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- - - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)



— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
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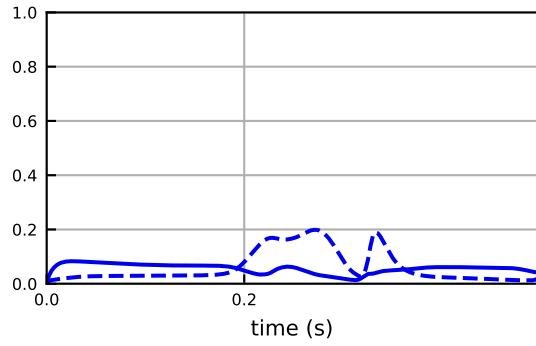


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
- - - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)



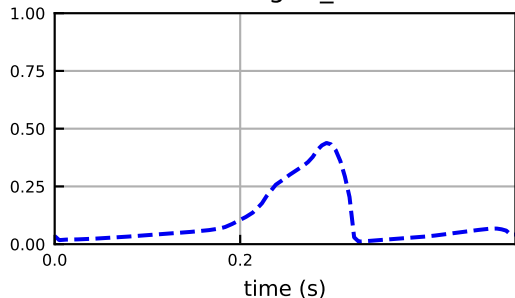
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- - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)

/forceset/extobl/activation

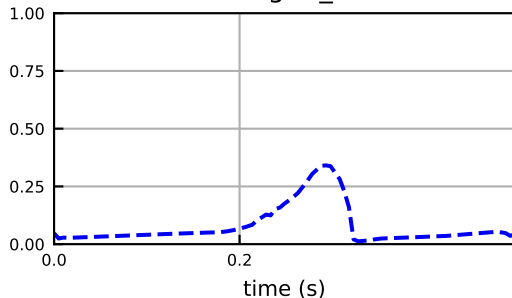


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40/solution.sto (right leg)
- - - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40/solution.sto (left leg)

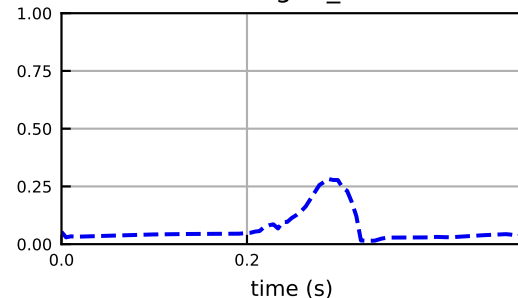
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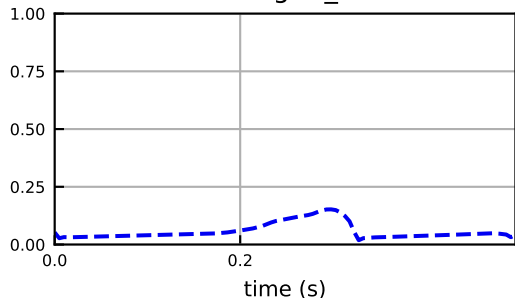
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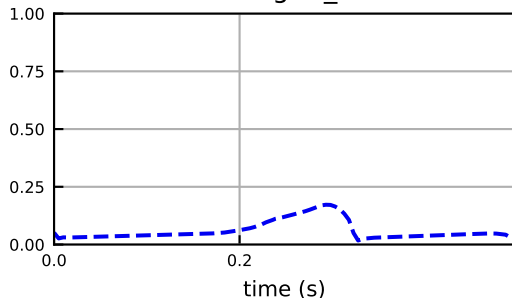
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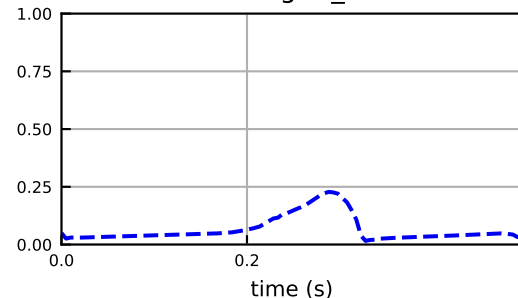
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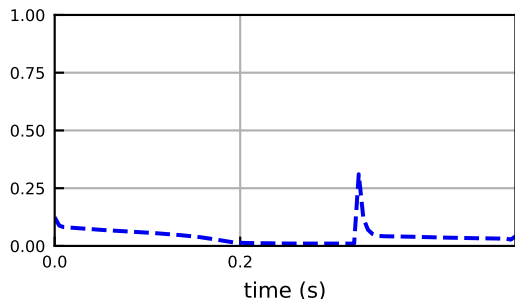
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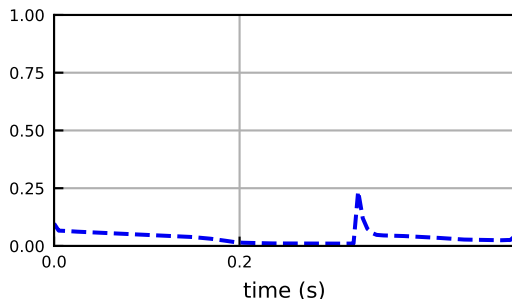
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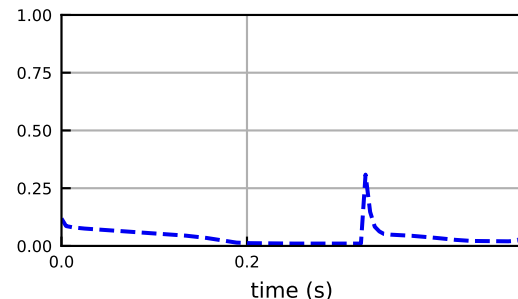
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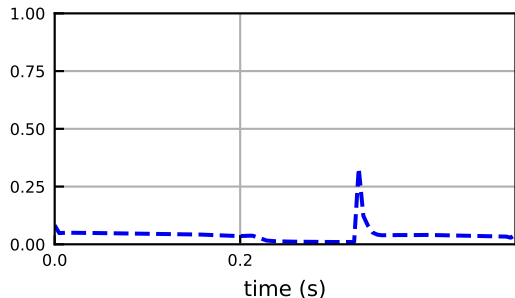
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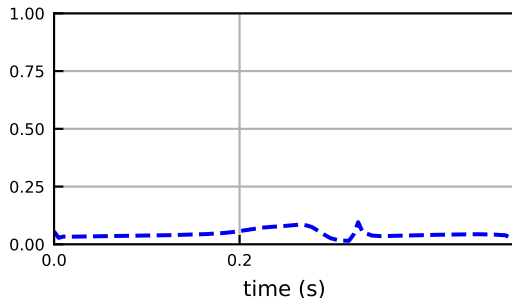
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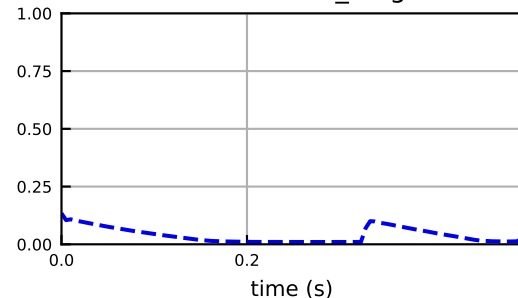
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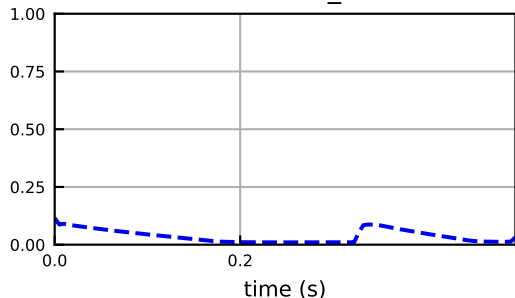
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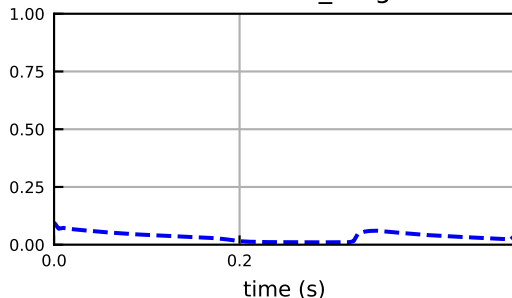
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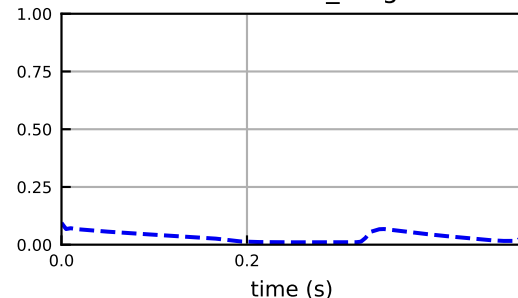
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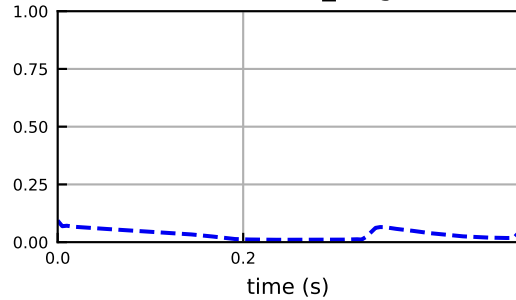


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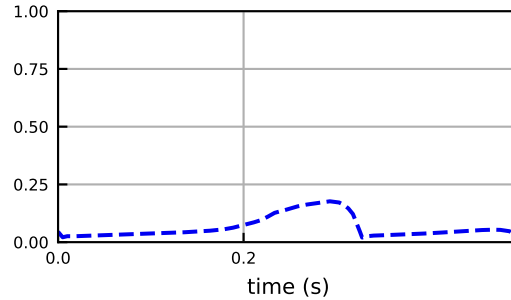


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
- - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)

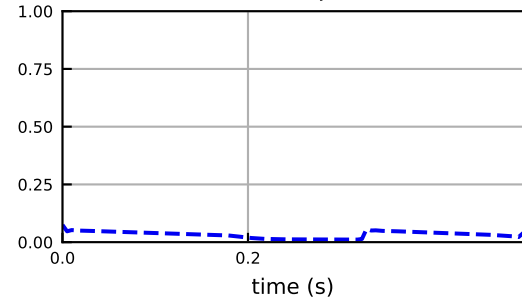
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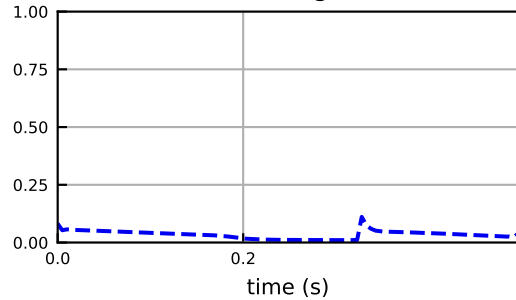
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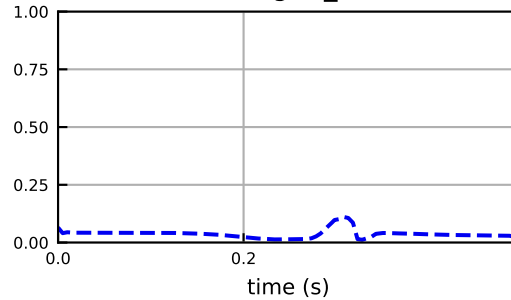
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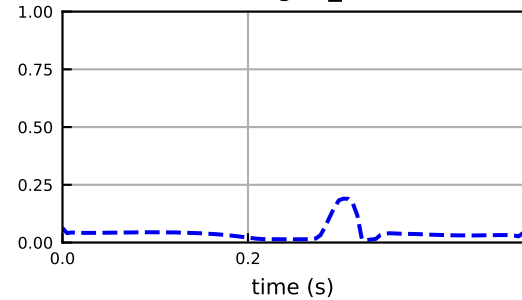
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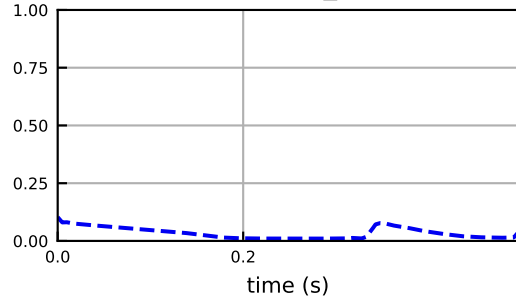
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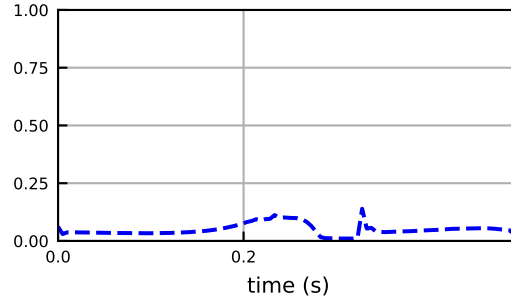
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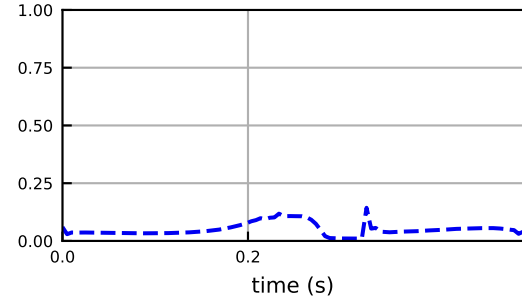
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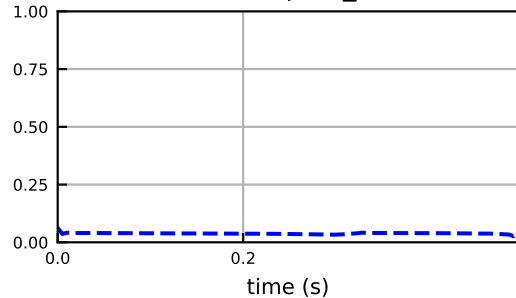
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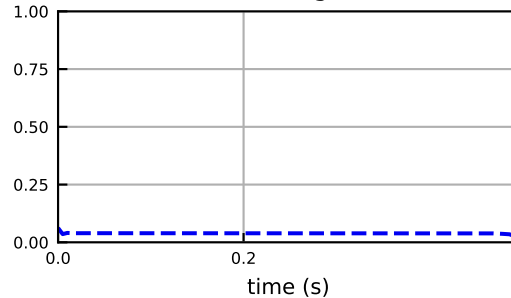
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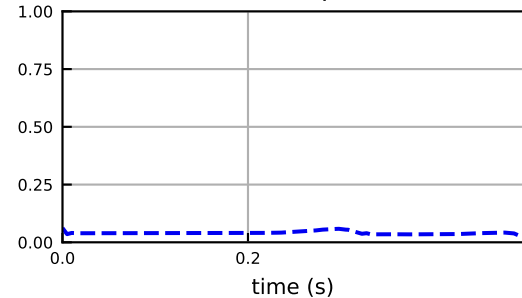
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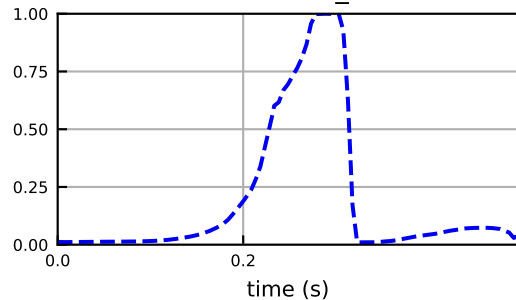
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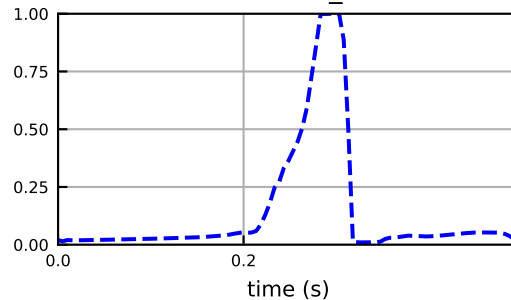
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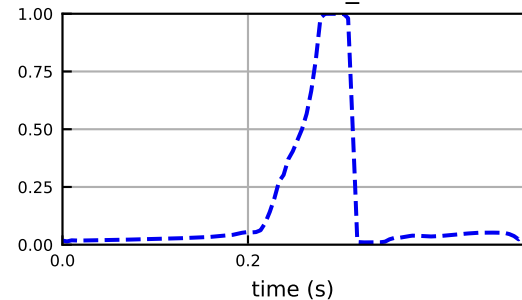
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forcesetvas_med

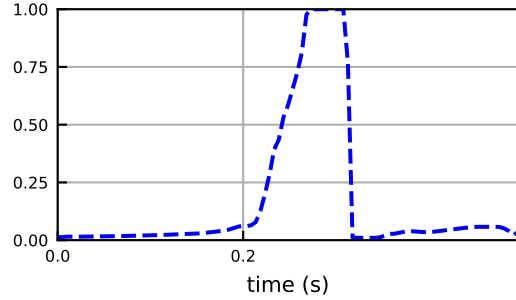


forcesetvas_int

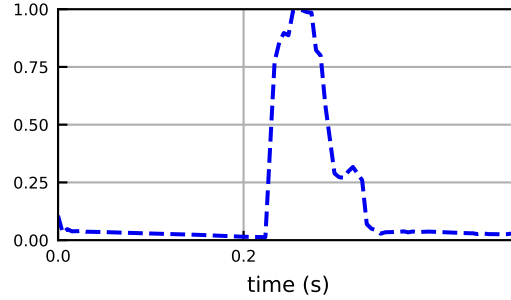


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
- - - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)

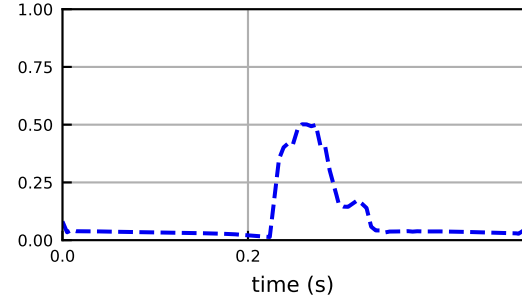
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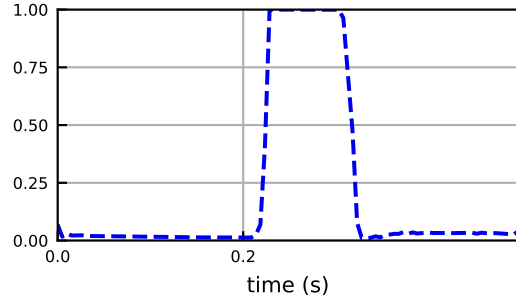
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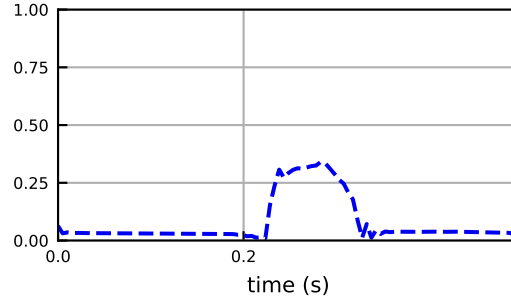
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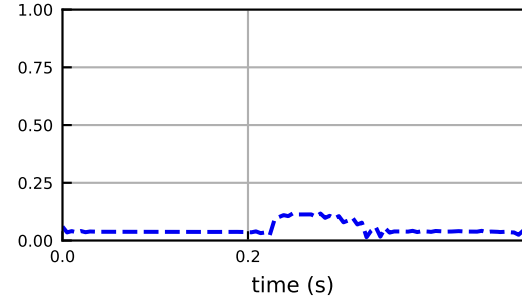
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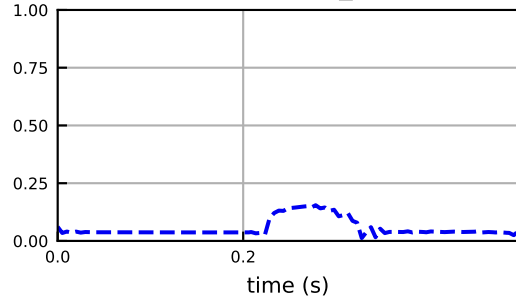
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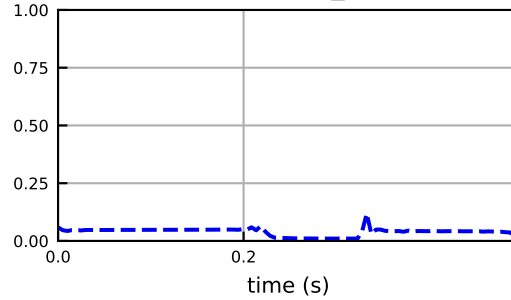
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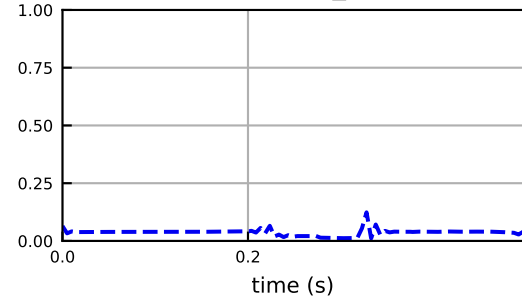
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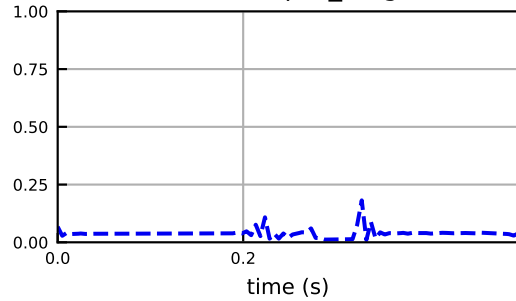
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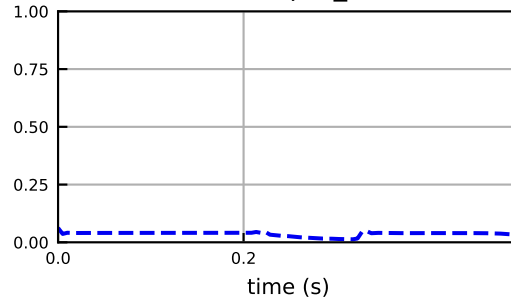
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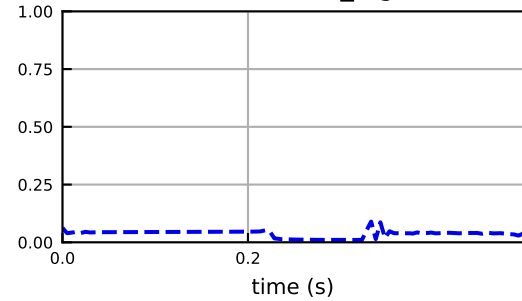
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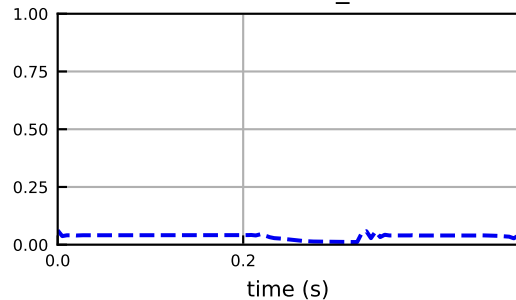
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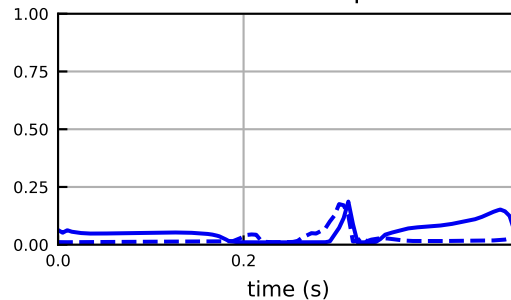
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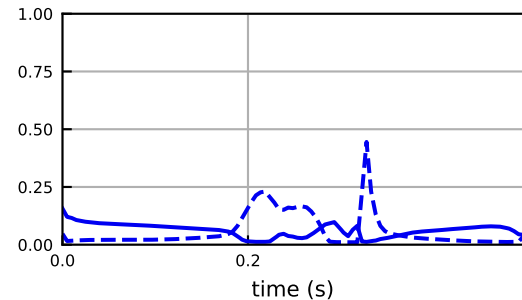
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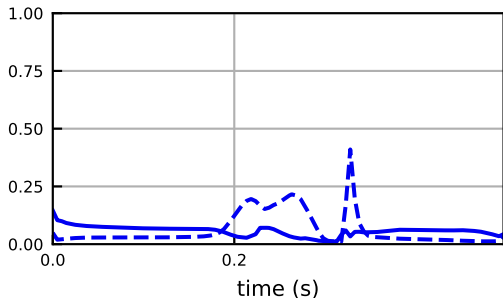


forcesetintobl

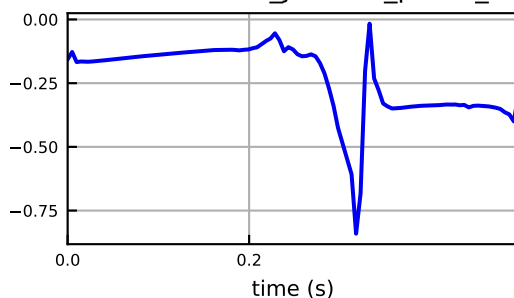


— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
- - - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)

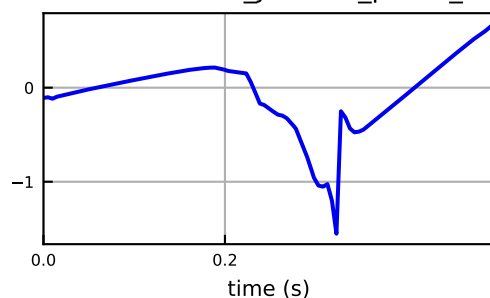
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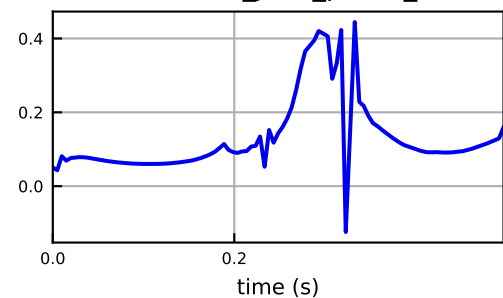
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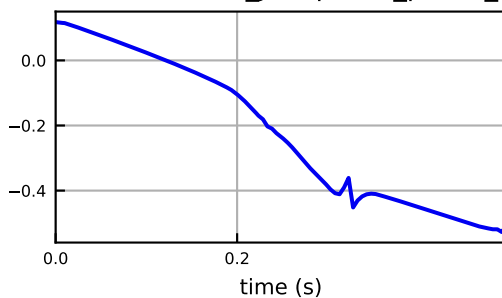
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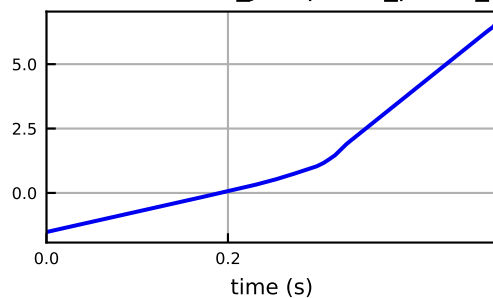
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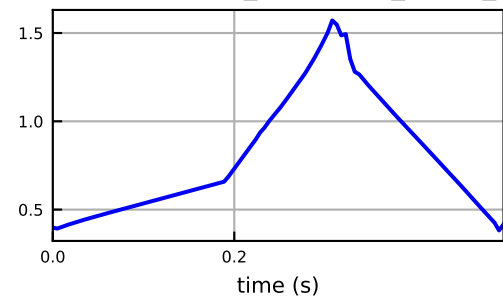
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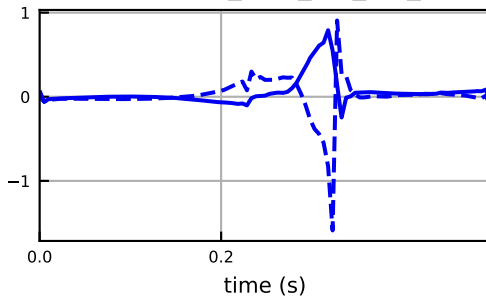
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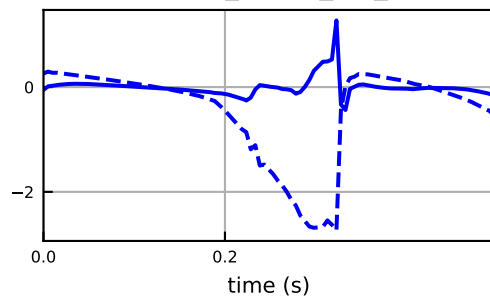
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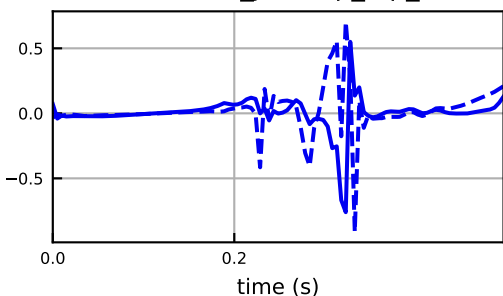
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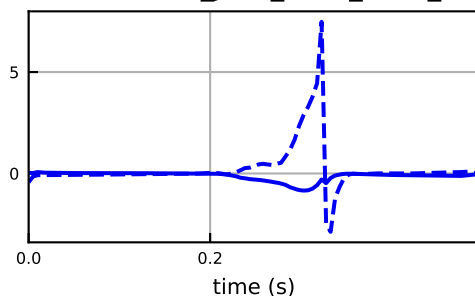
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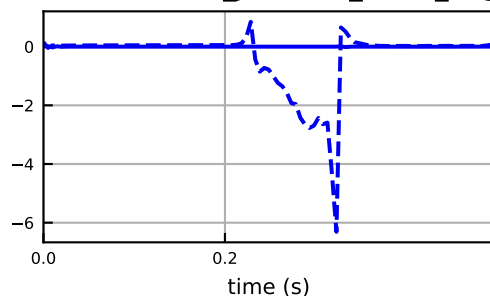
forcesetreserve_joi...hip_hip_rotation



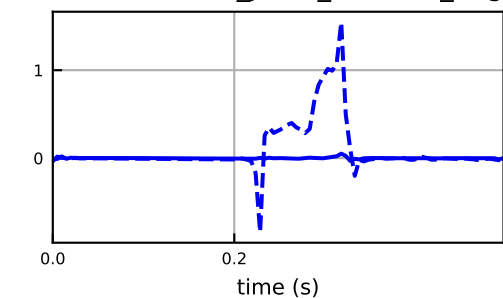
forcesetreserve_joi...knee_knee_angle



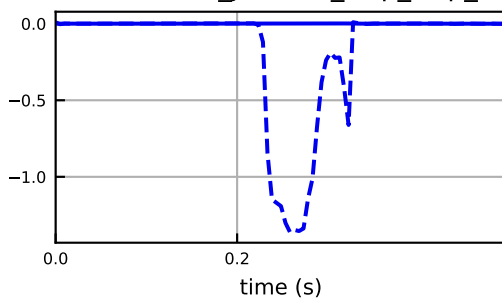
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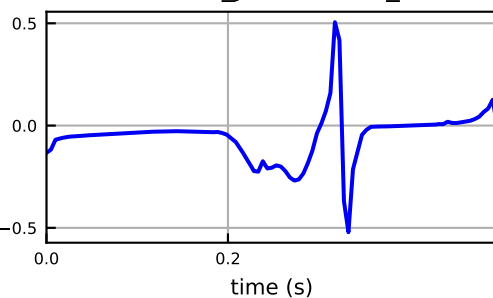
forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension



— D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (right leg)
- - D:\Projects_MOCO\project_hip\Results\predict_hip_effort0.001_2\rot_-40\solution.sto (left leg)

forcesetreserve_joi...k_lumbar_bending forcesetreserve_joi..._lumbar_rotation

