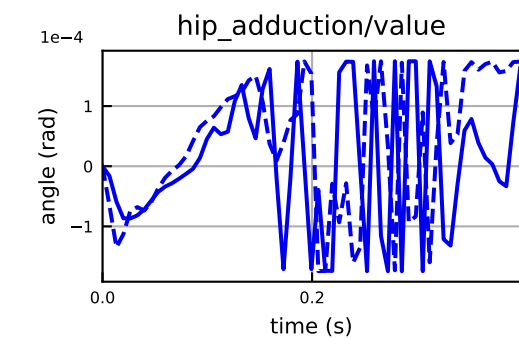
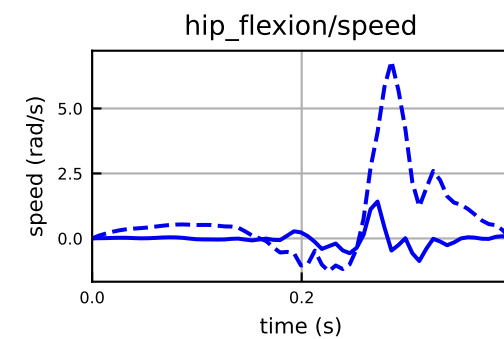
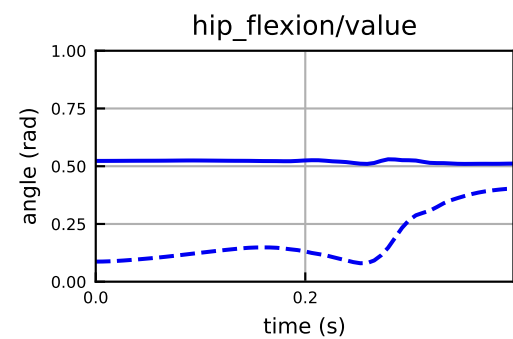
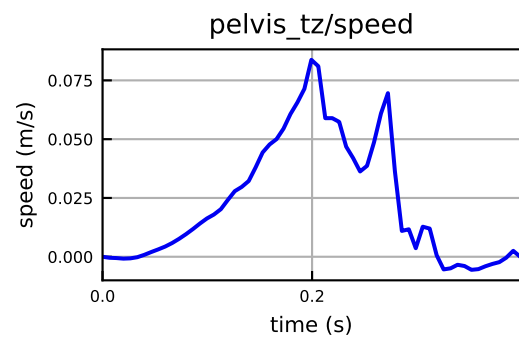
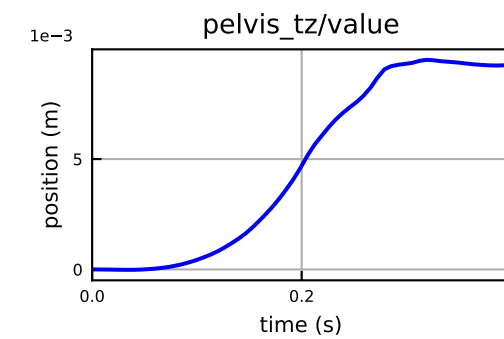
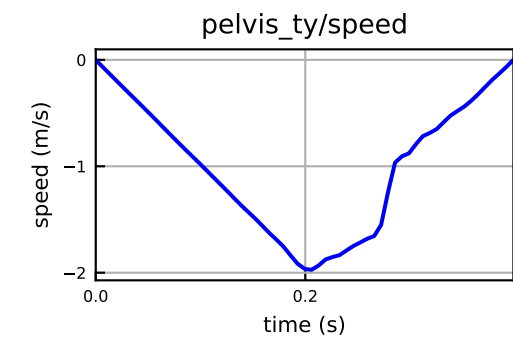
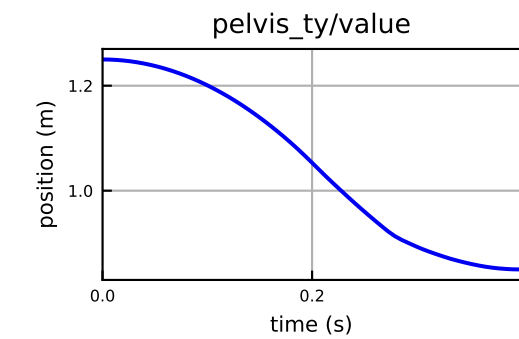
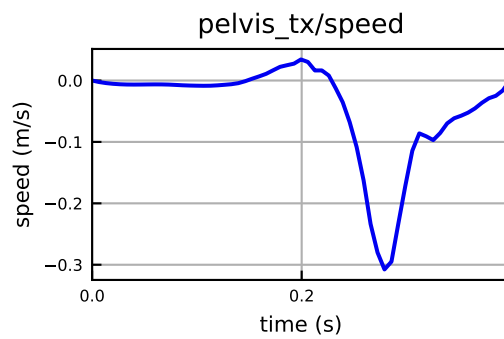
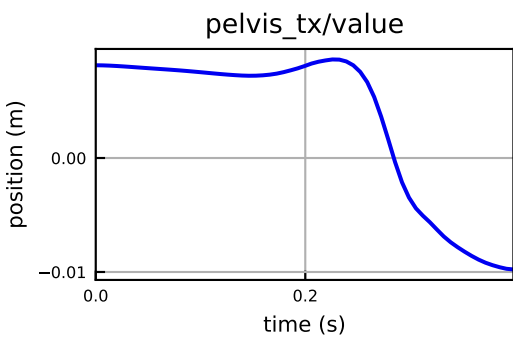
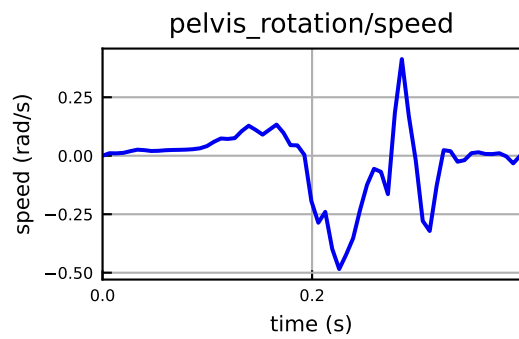
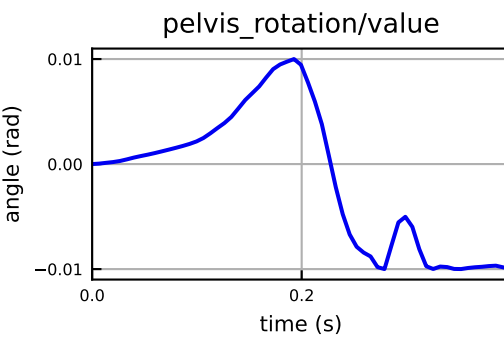
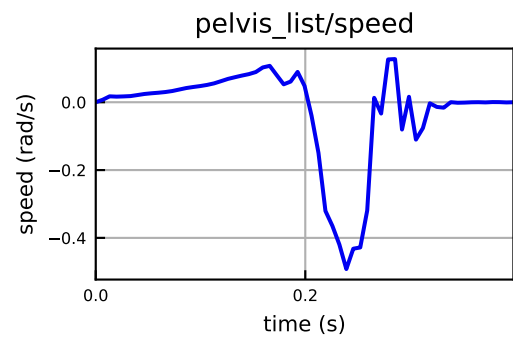
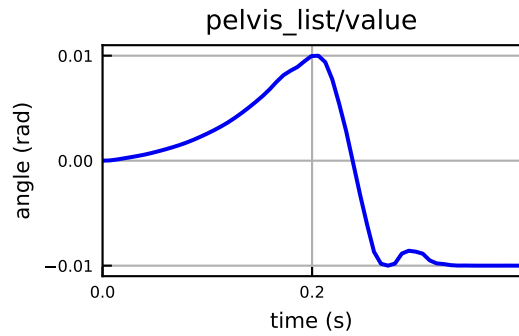
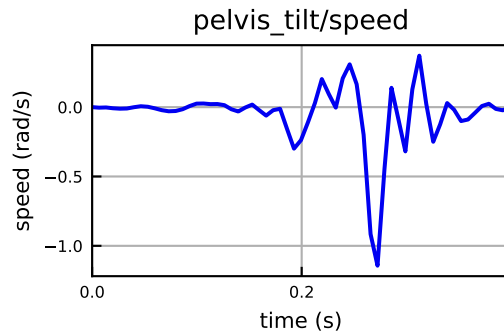
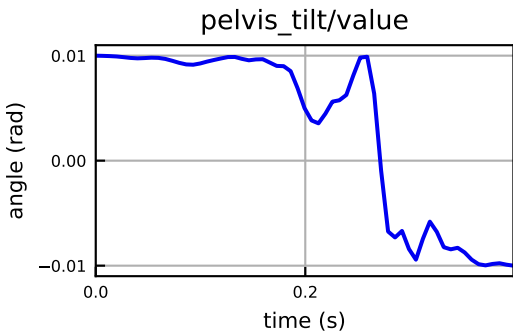
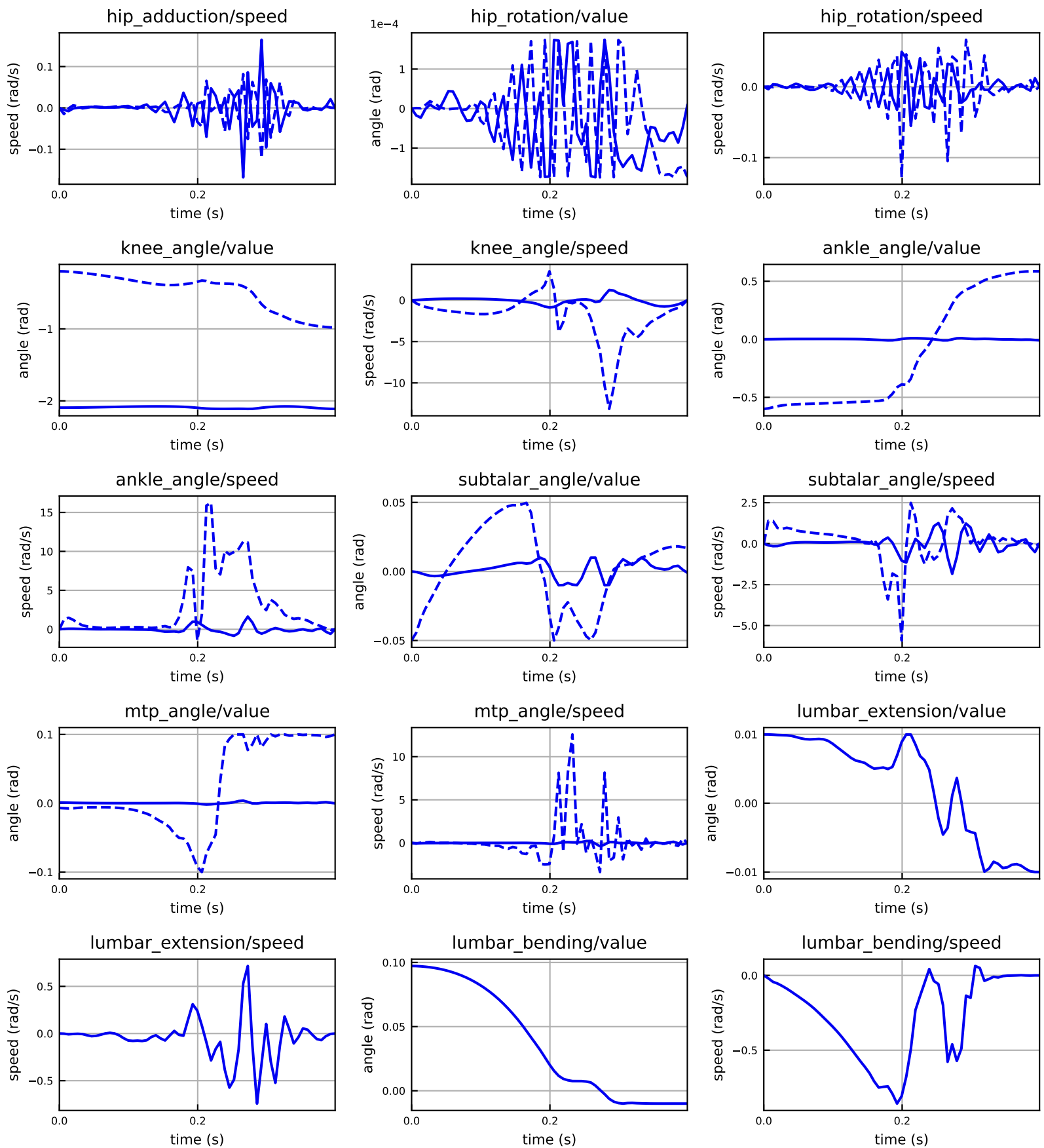
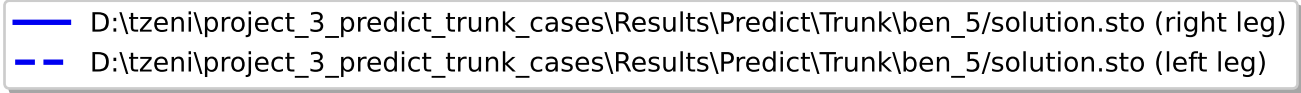


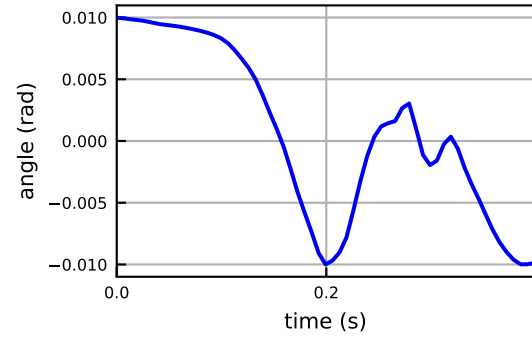
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- - - D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_5\solution.sto (left leg)



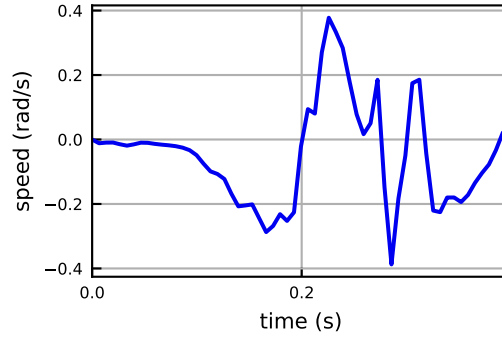




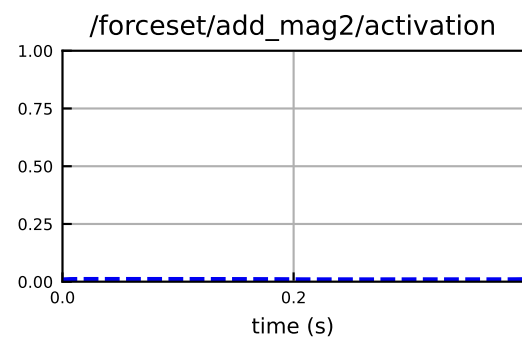
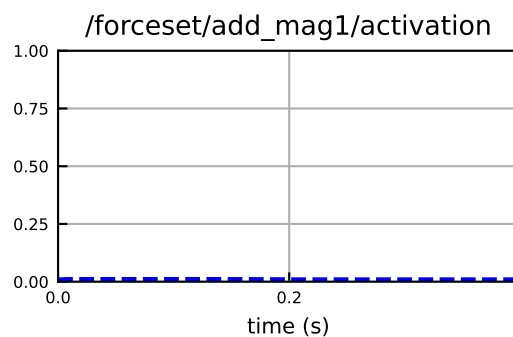
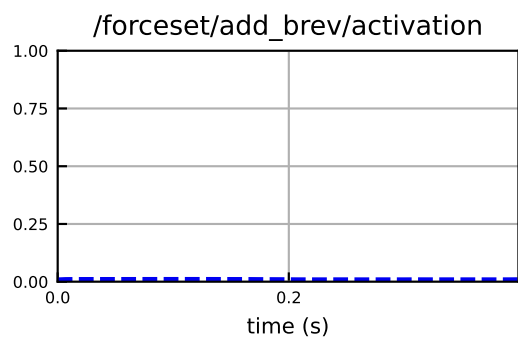
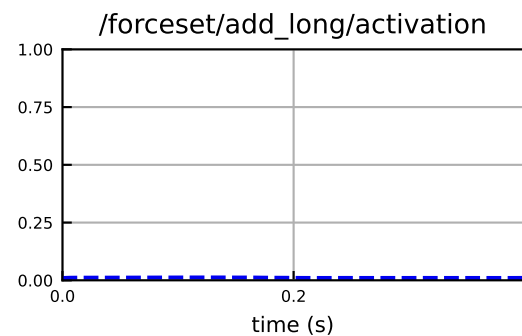
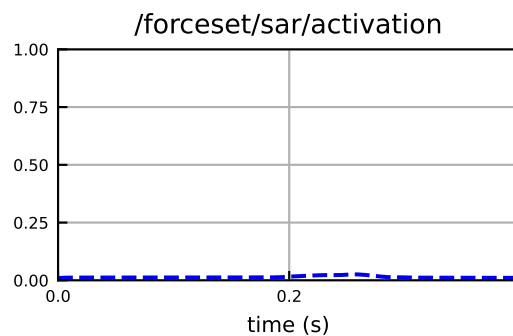
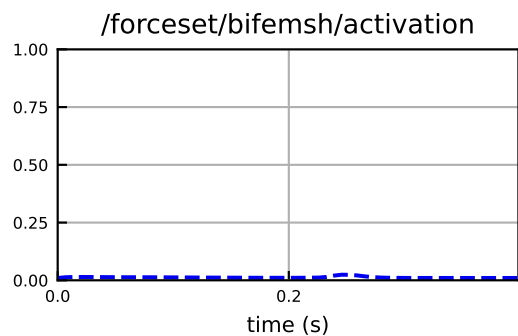
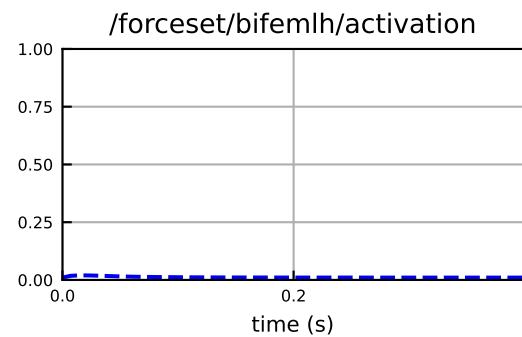
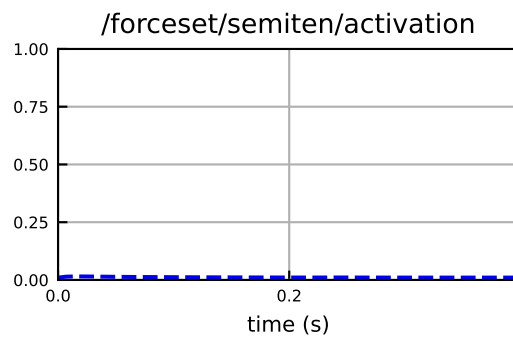
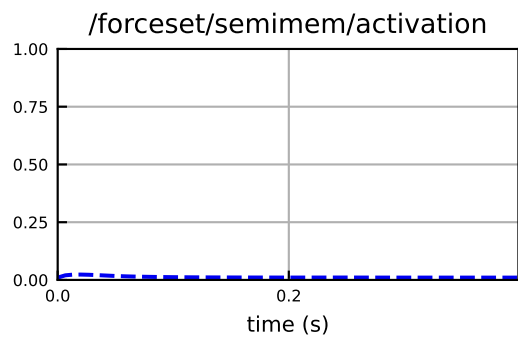
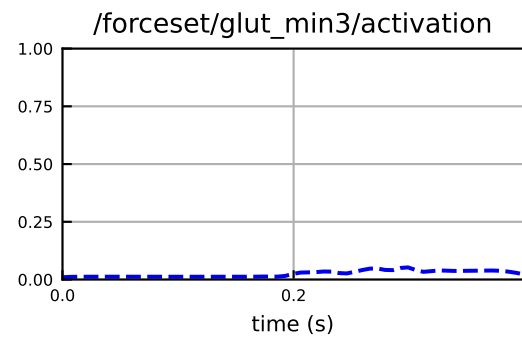
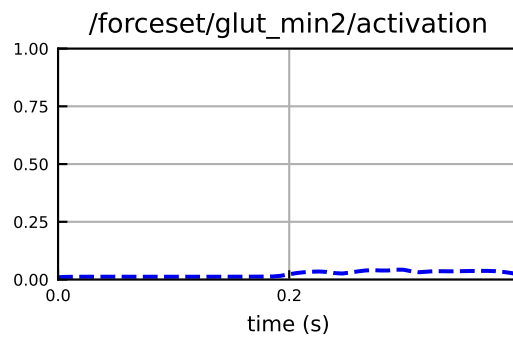
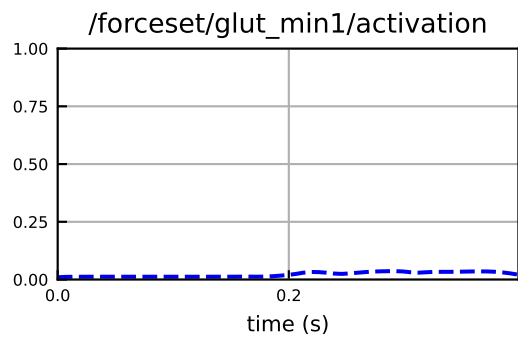
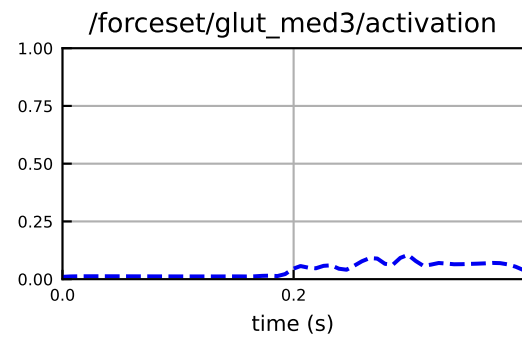
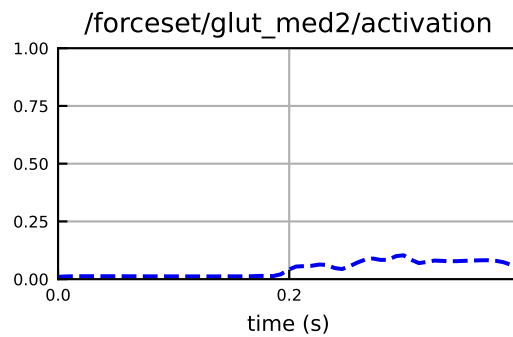
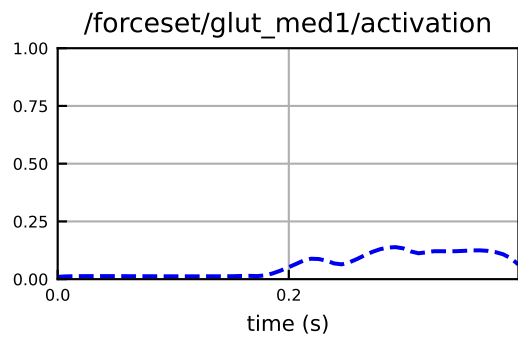
lumbar_rotation/value

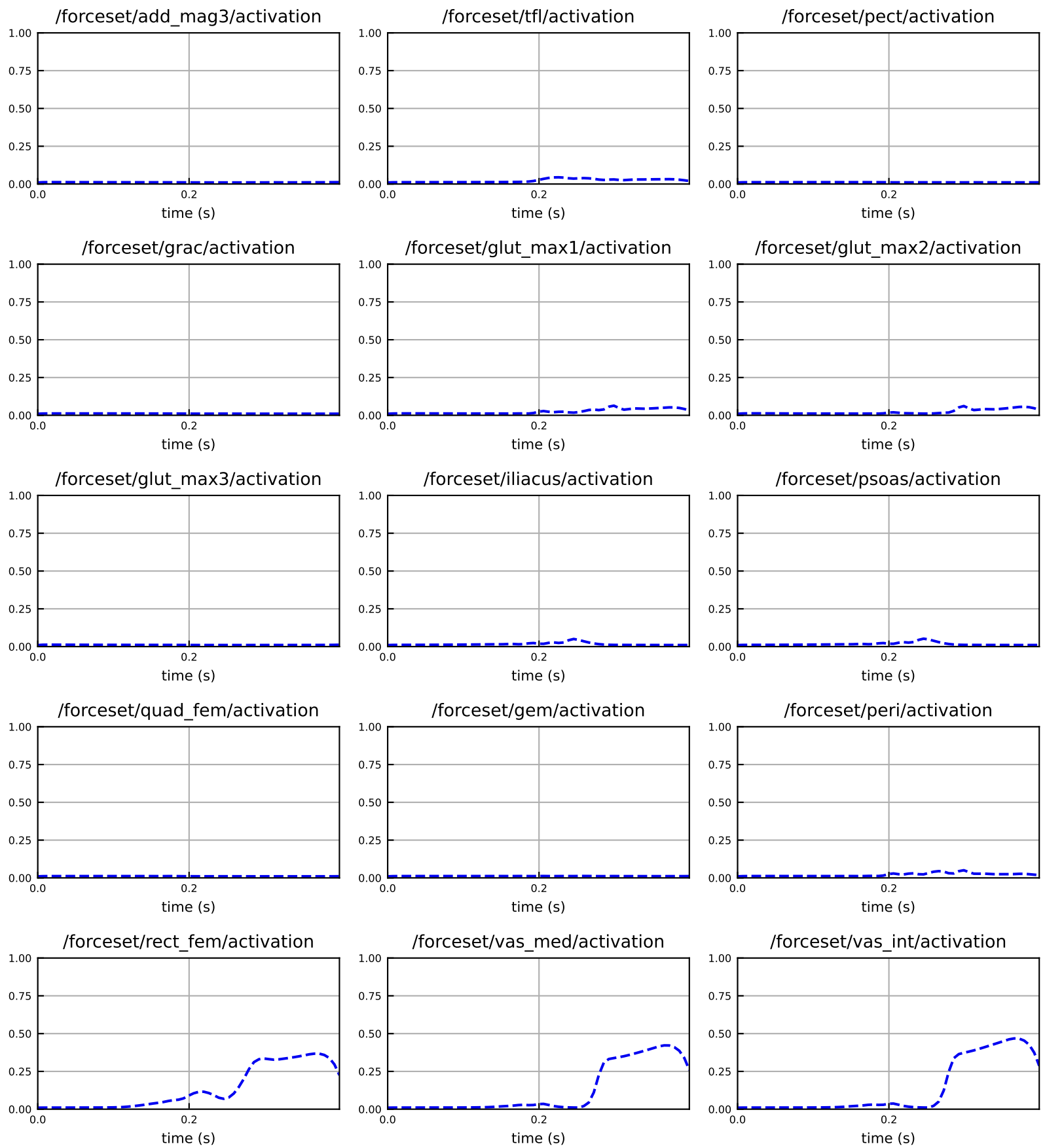


lumbar_rotation/speed

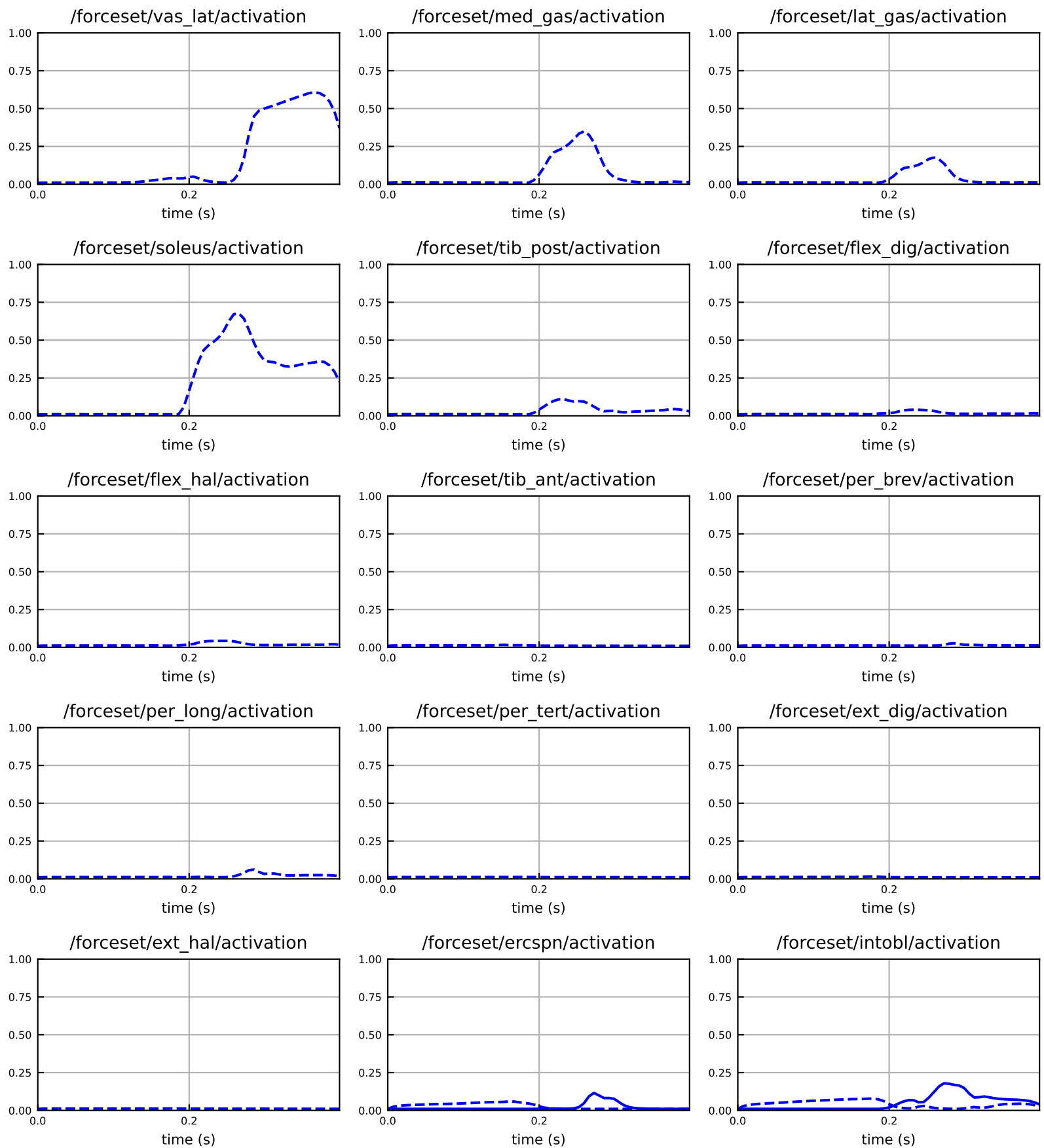


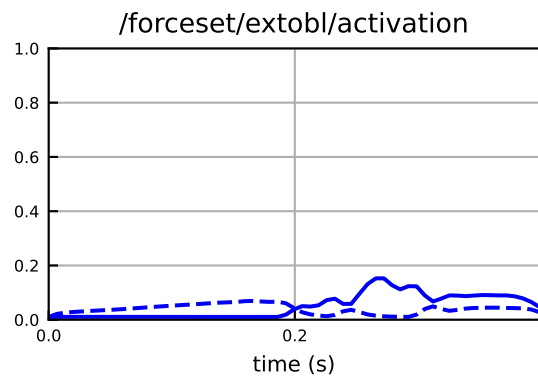
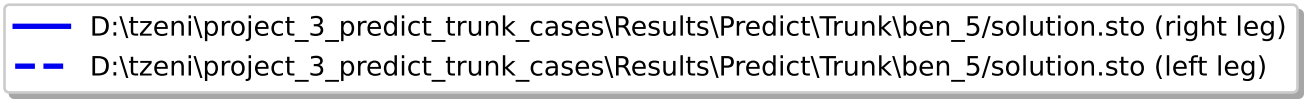
— D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_5/solution.sto (right leg)
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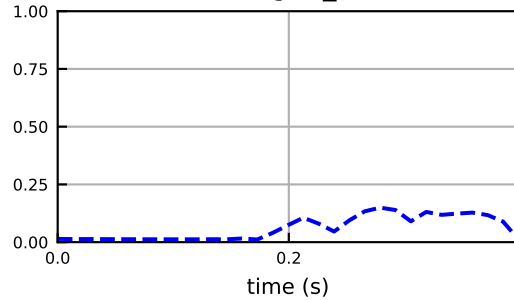
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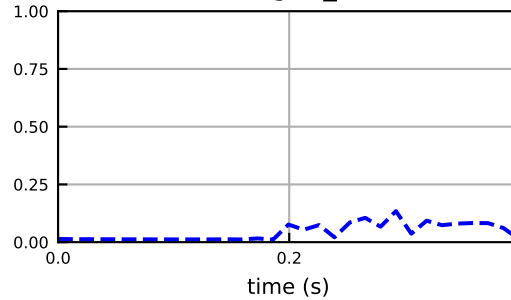


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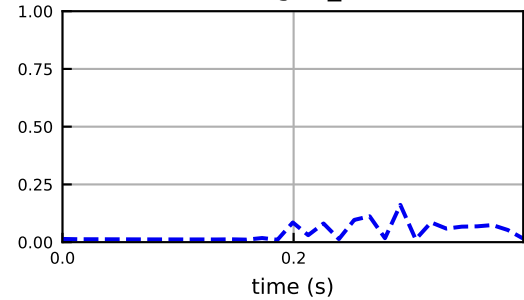
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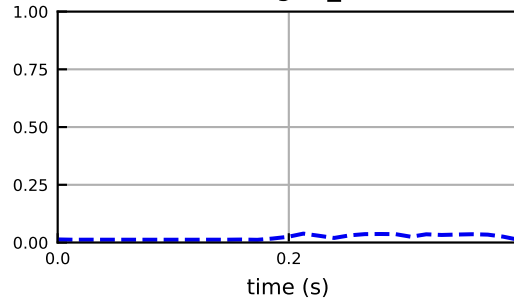
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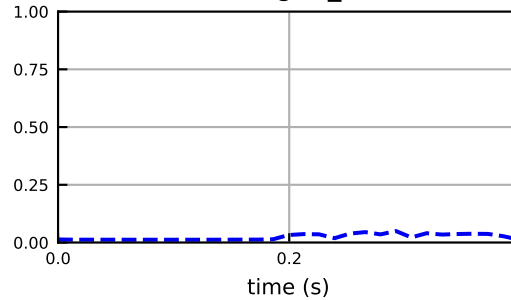
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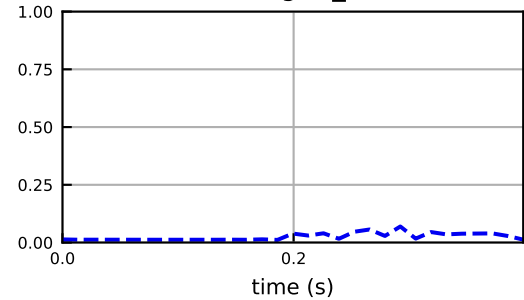
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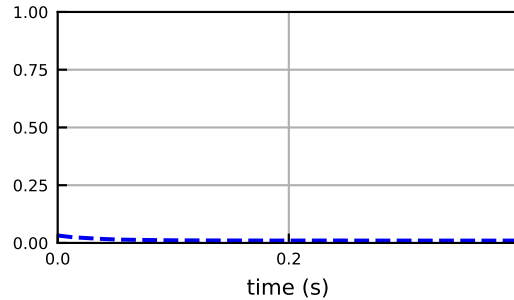
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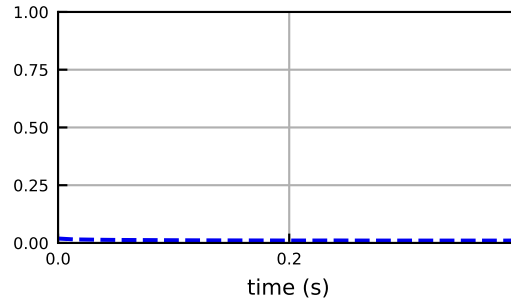
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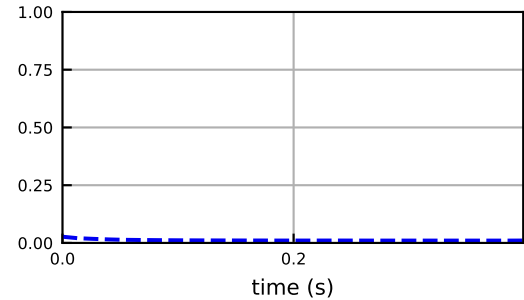
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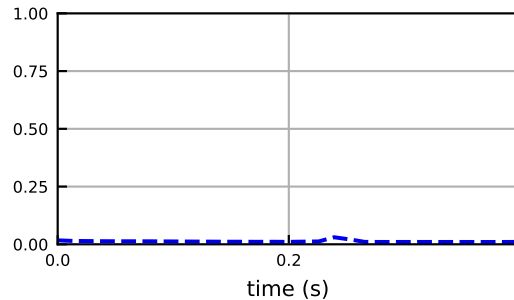
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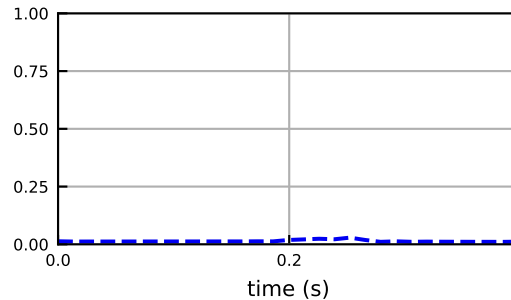
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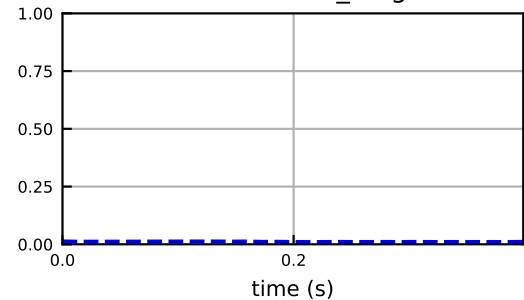
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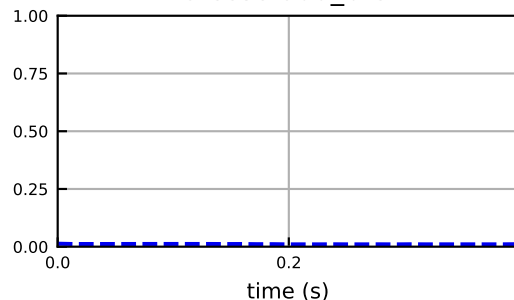
forcesetsar



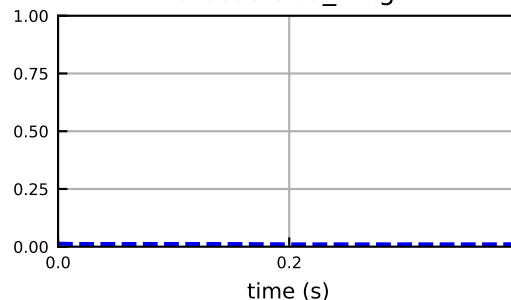
forcesetadd_long



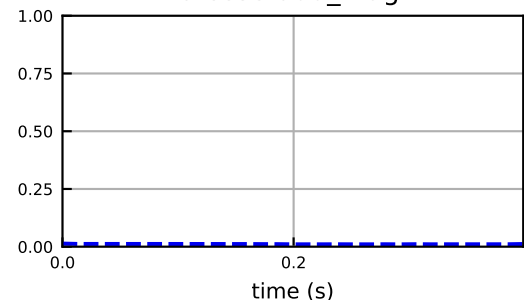
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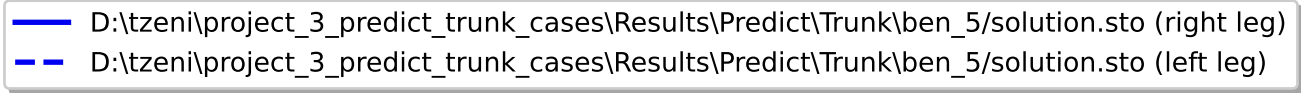


forcesetadd_mag1

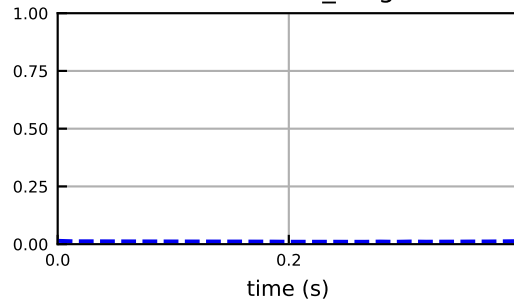


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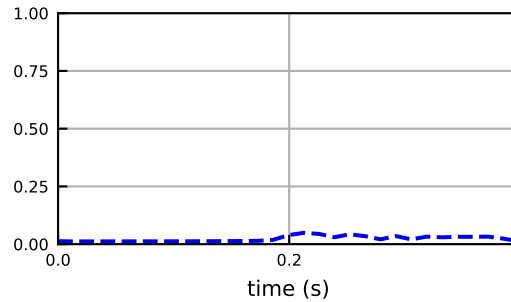




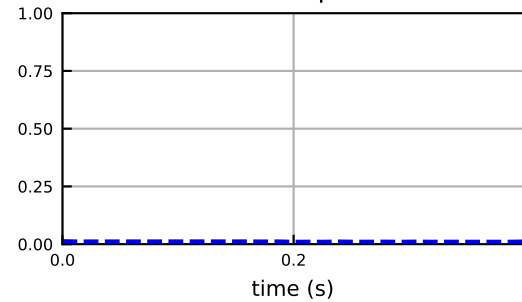
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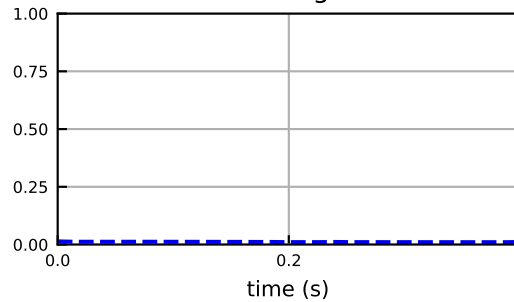
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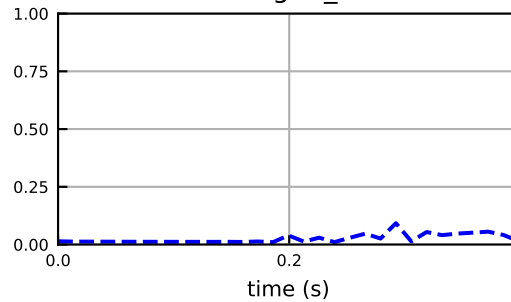
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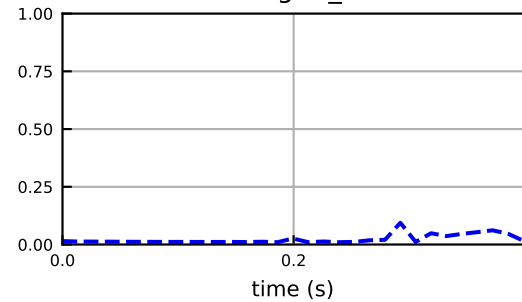
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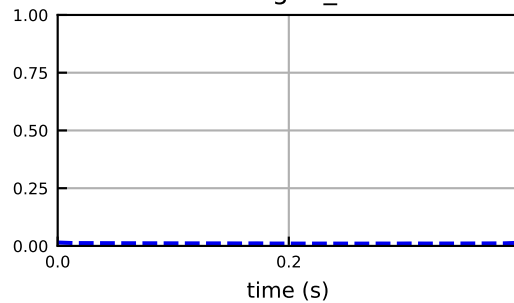
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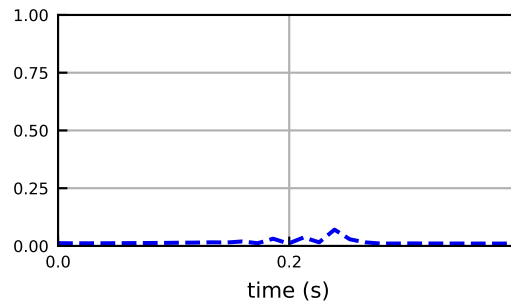
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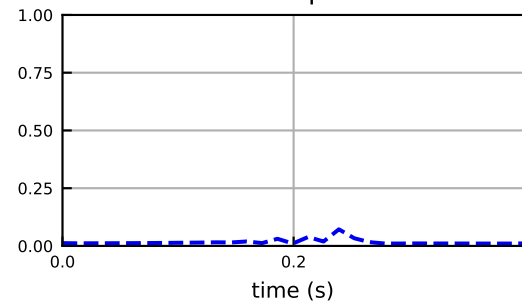
forcesetglut_max3



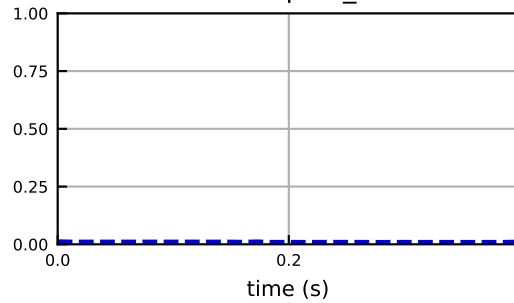
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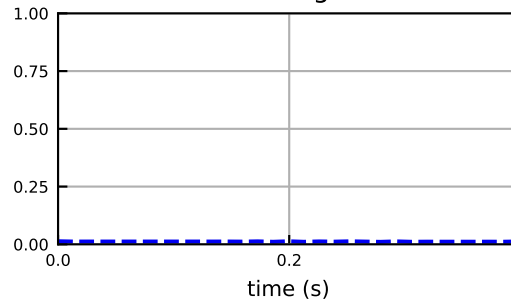
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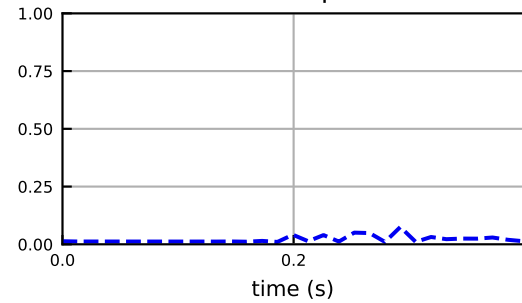
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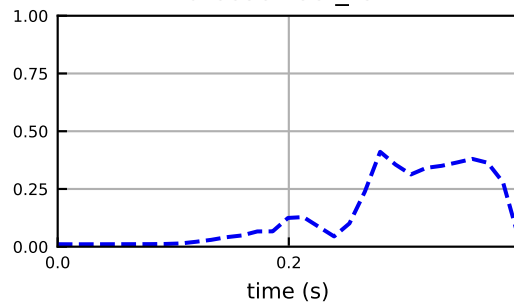
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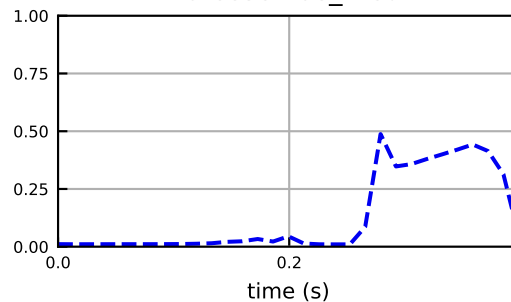
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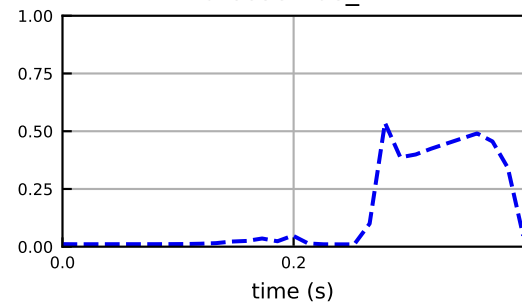
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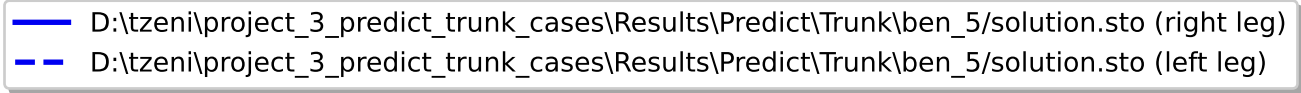


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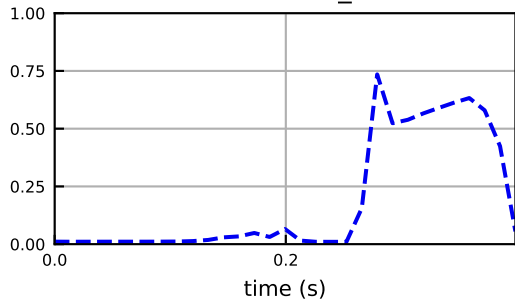


forcesetvas_int

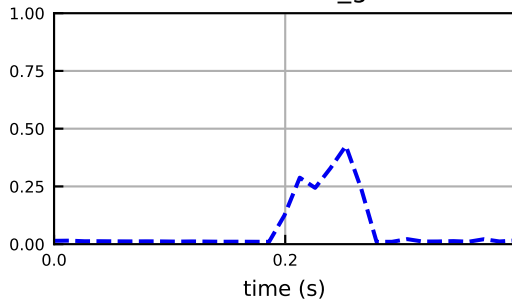




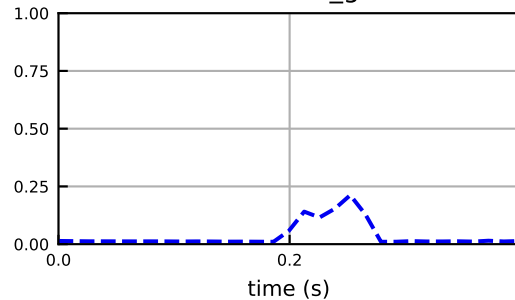
forcesetvas_lat



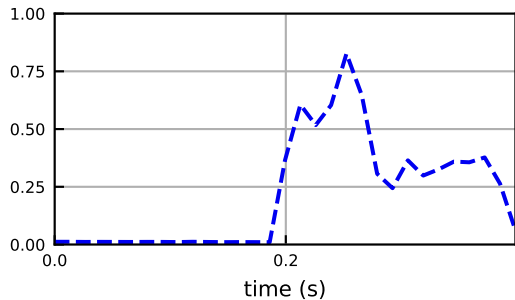
forcesetmed_gas



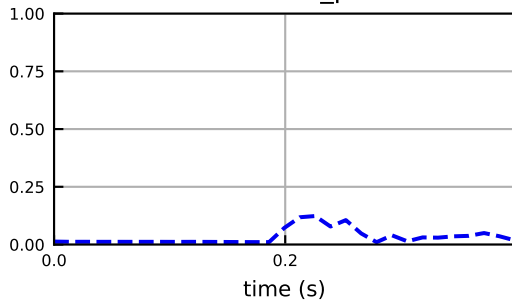
forcesetlat_gas



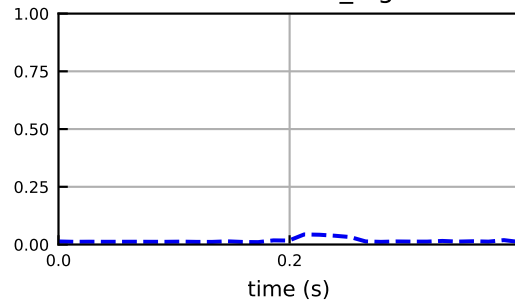
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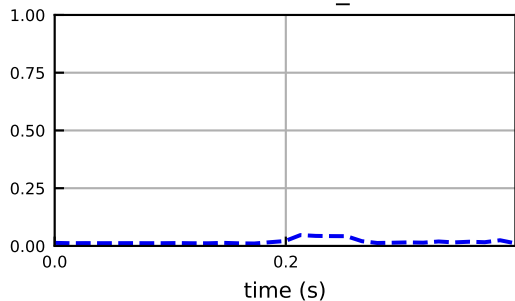
forcesettib_post



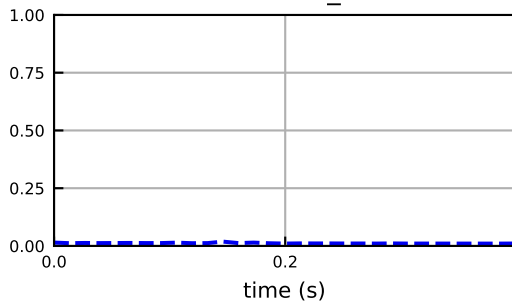
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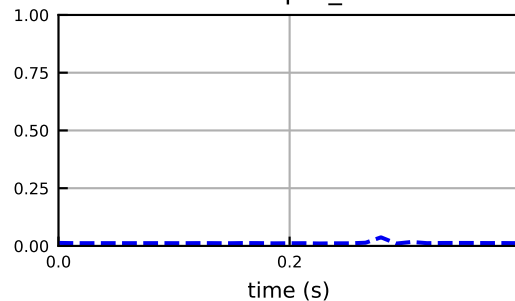
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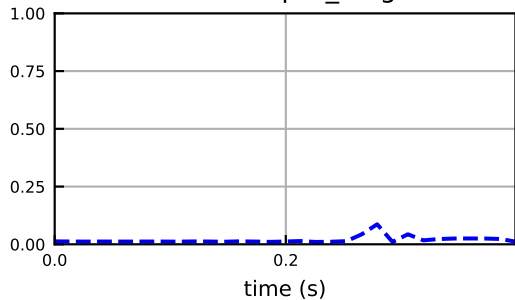
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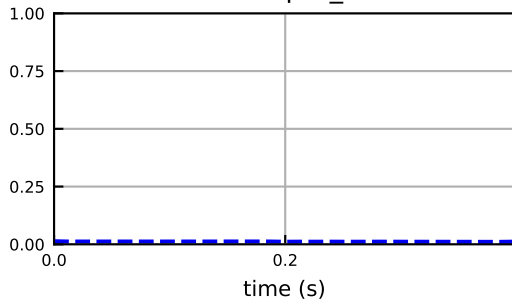
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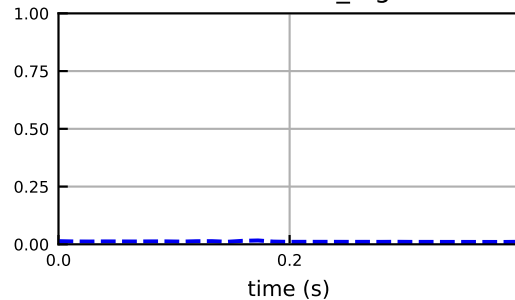
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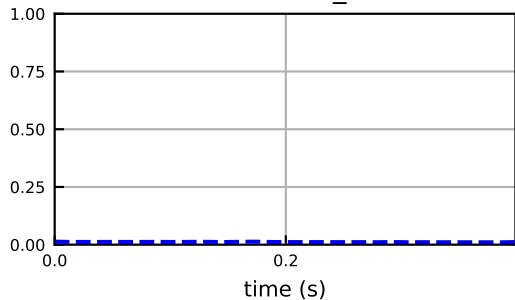
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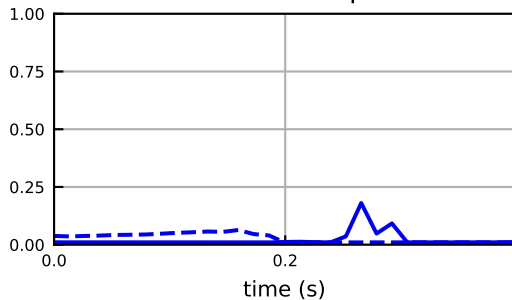
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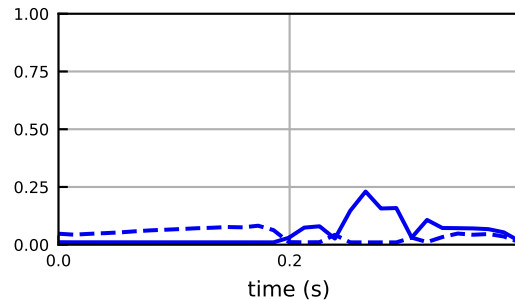
forcesetext_hal



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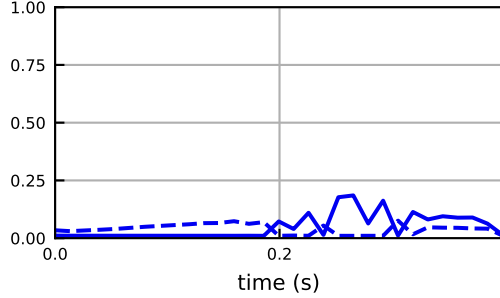


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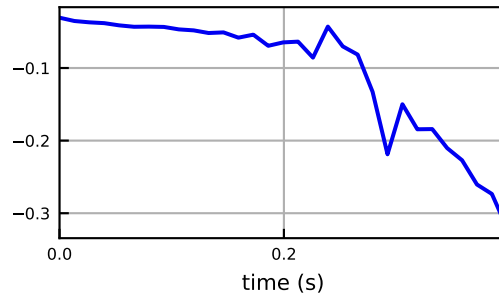


— D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_5\solution.sto (right leg)
- - - D:\tzeni\project_3_predict_trunk_cases\Results\Predict\Trunk\ben_5\solution.sto (left leg)

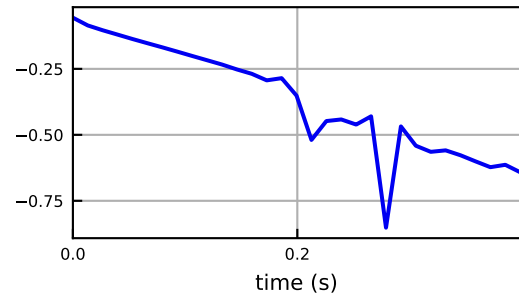
forcesetextobl



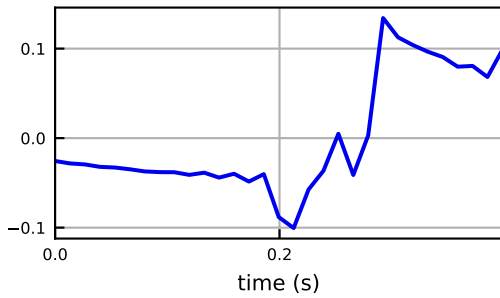
forcesetreserve_joi...lvis_pelvis_tilt



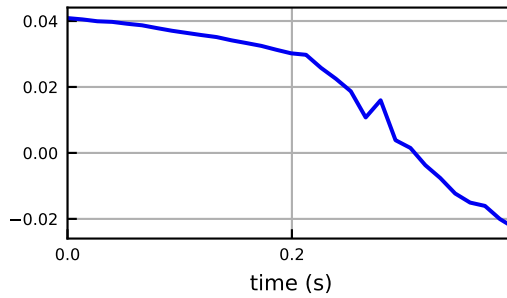
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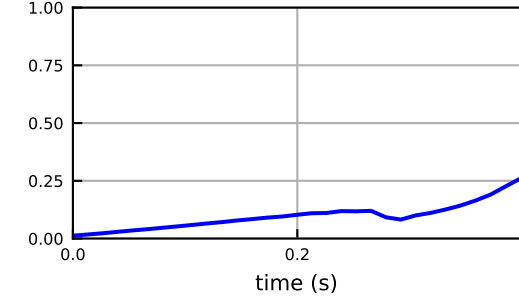
forcesetreserve_joi..._pelvis_rotation



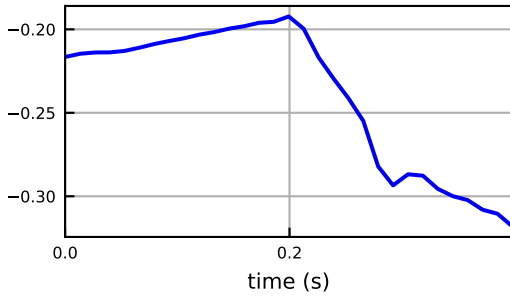
forcesetreserve_joi...pelvis_pelvis_tx



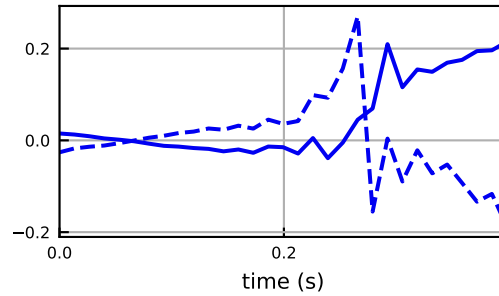
forcesetreserve_joi...pelvis_pelvis_ty



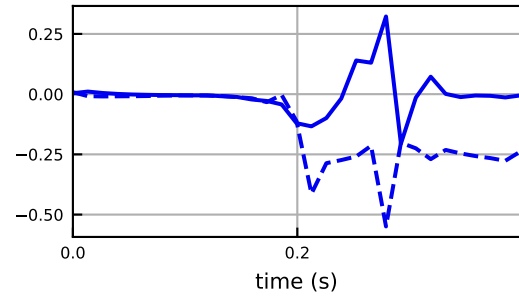
forcesetreserve_joi...pelvis_pelvis_tz



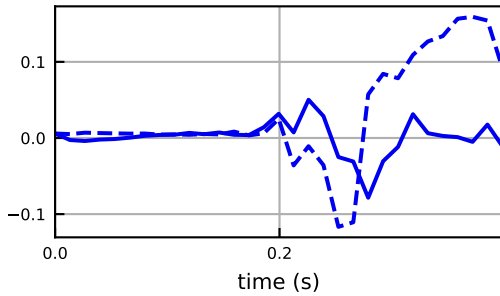
forcesetreserve_joi..._hip_hip_flexion



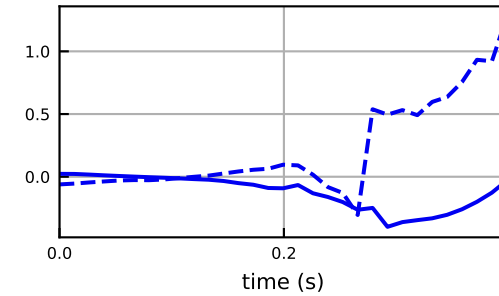
forcesetreserve_joi...ip_hip_adduction



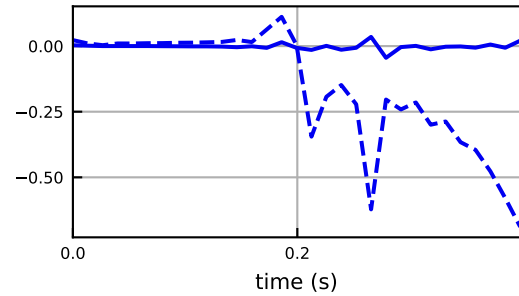
forcesetreserve_joi...hip_hip_rotation



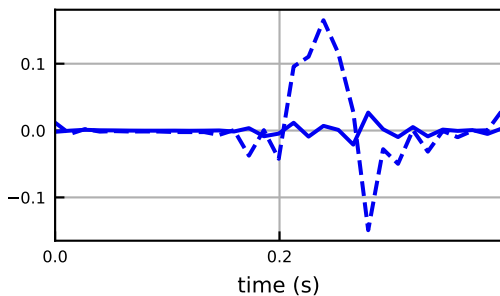
forcesetreserve_joi..._knee_knee_angle



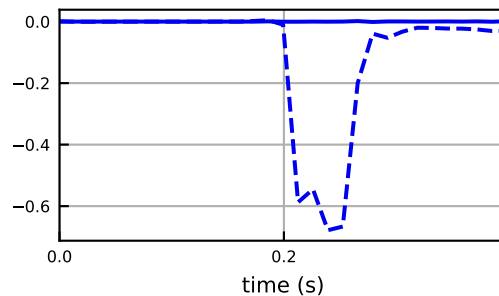
forcesetreserve_joi...nkle_ankle_angle



forcesetreserve_joi...r_subtalar_angle



forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension

