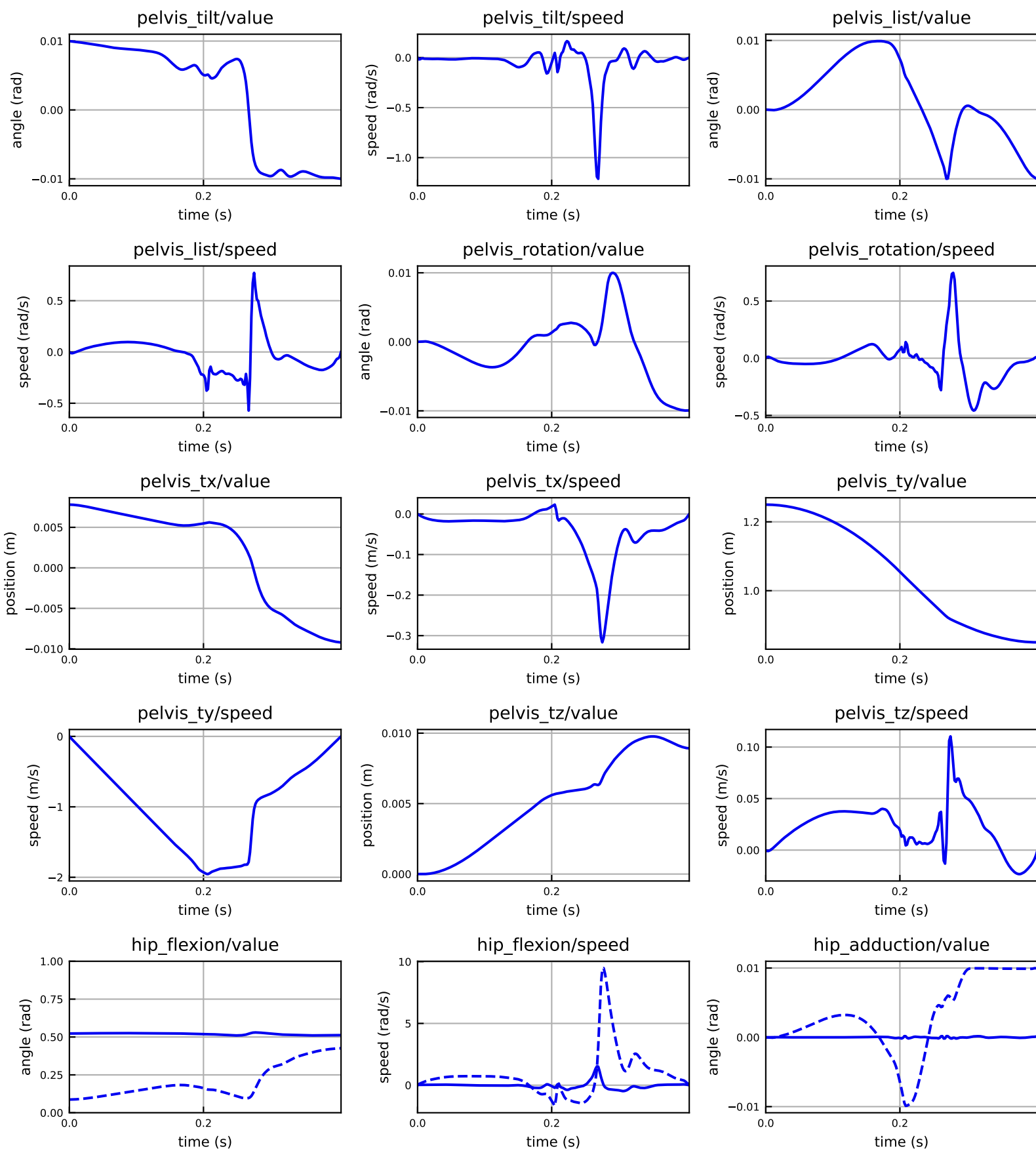
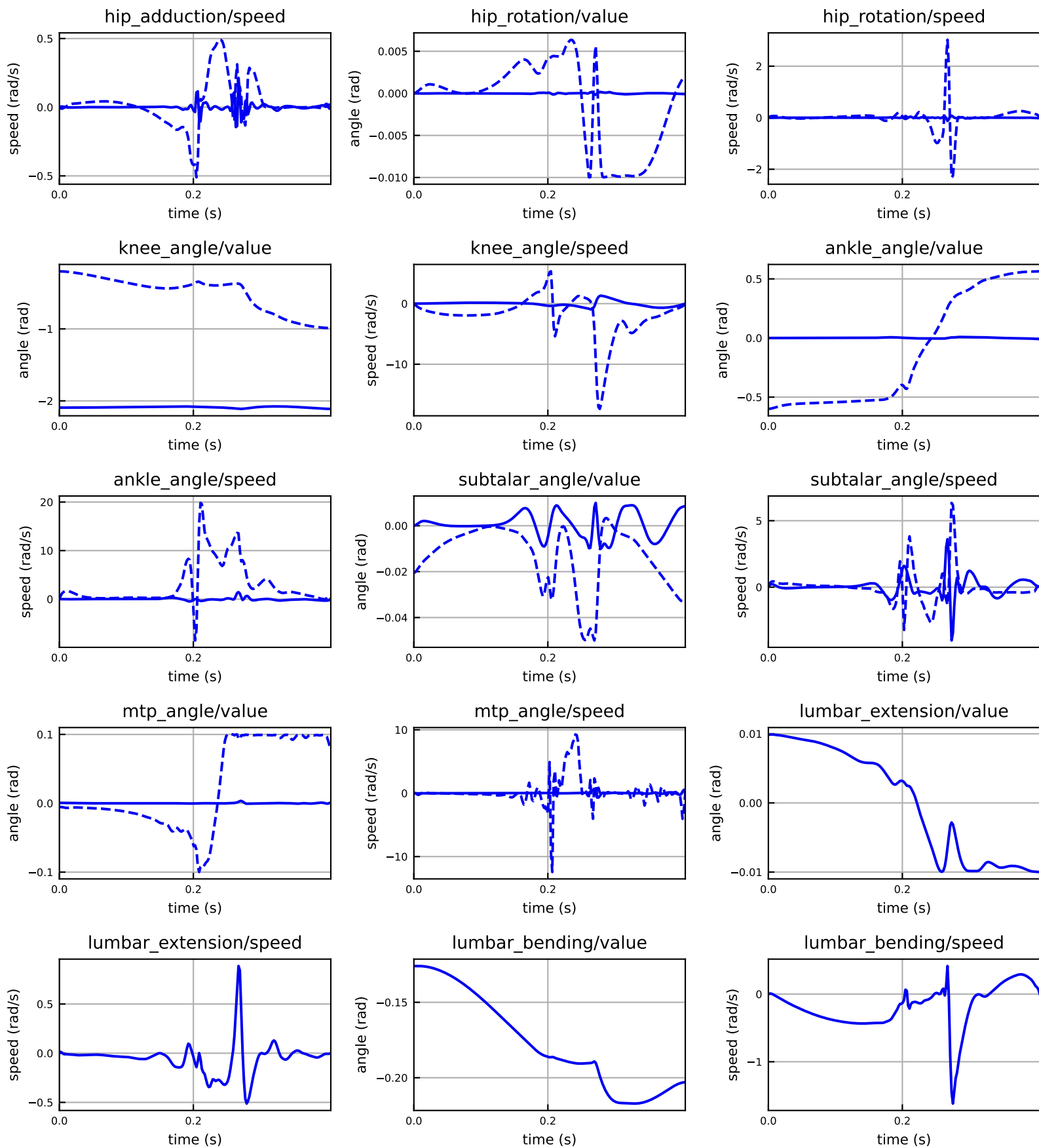


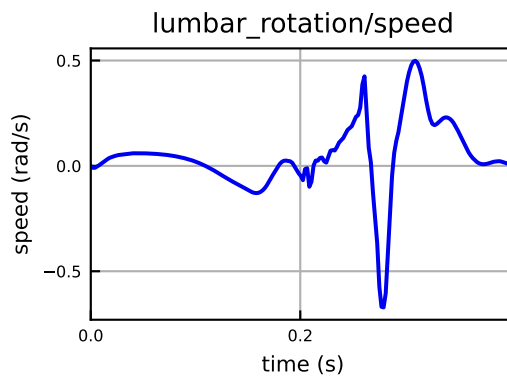
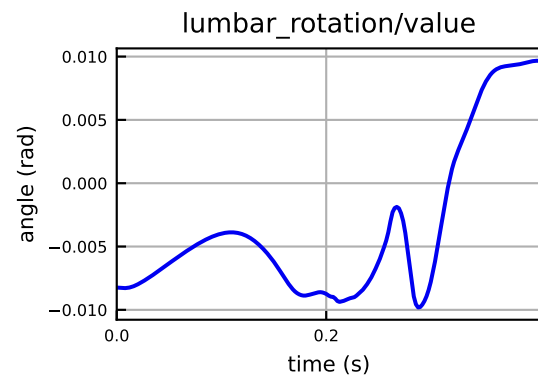
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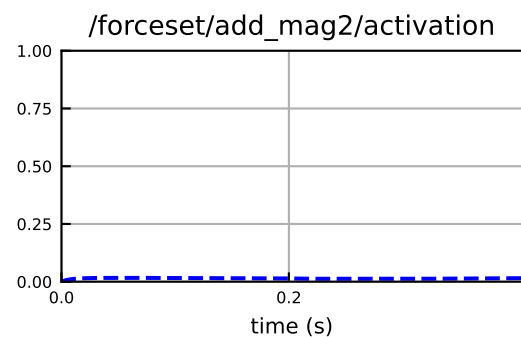
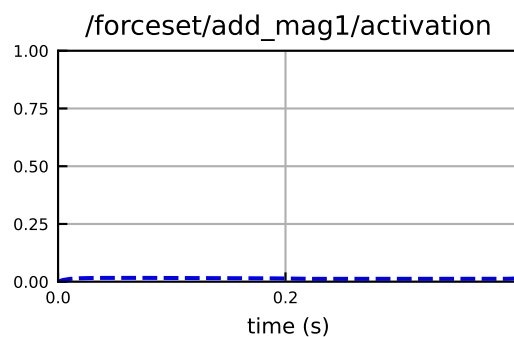
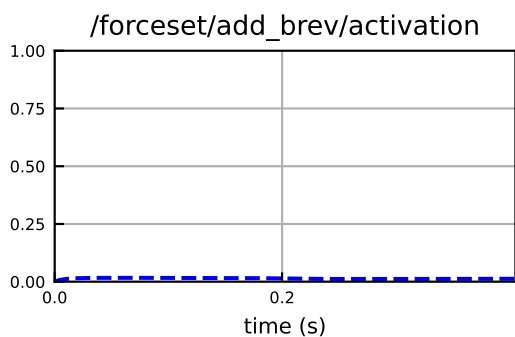
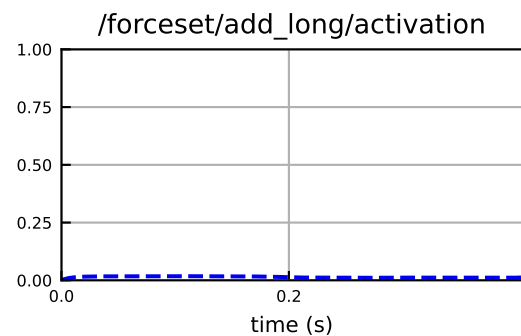
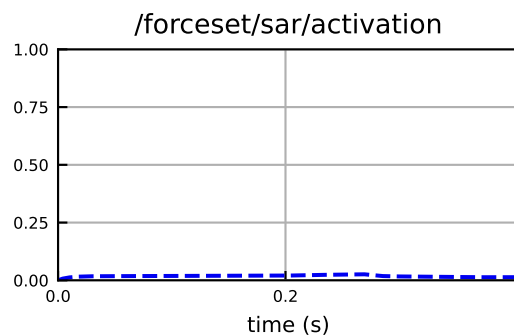
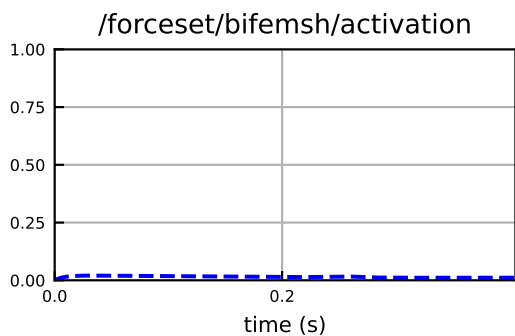
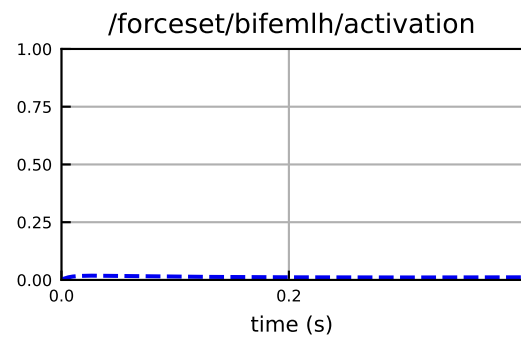
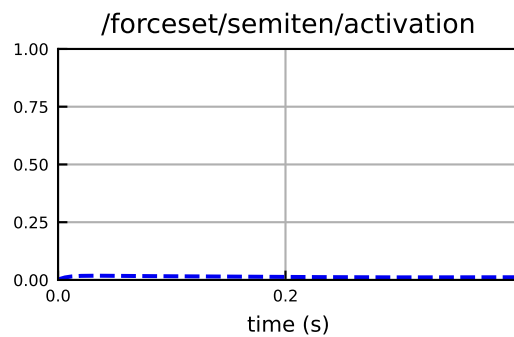
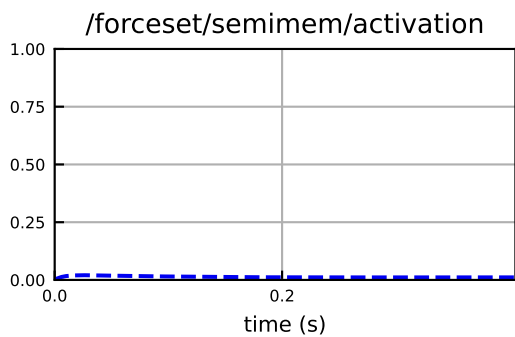
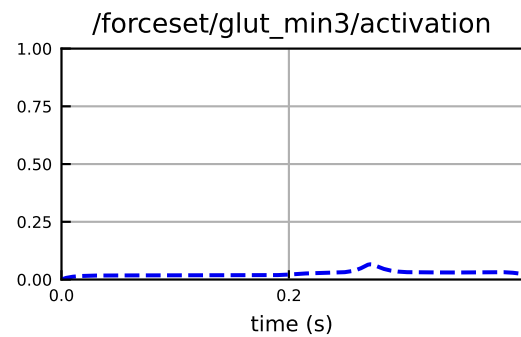
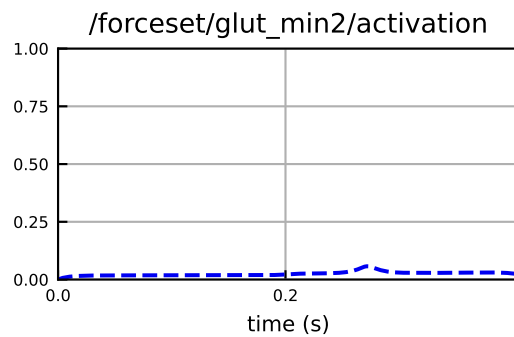
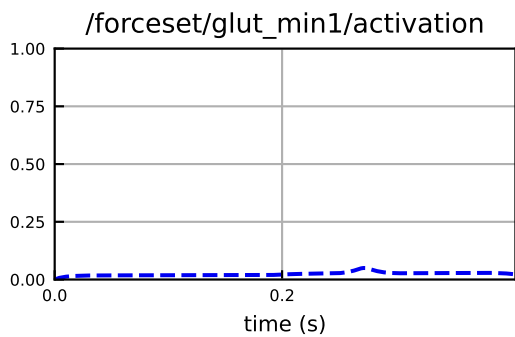
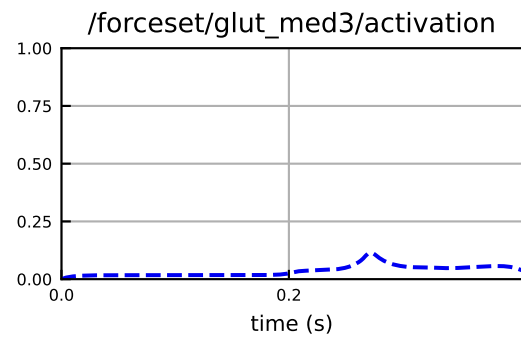
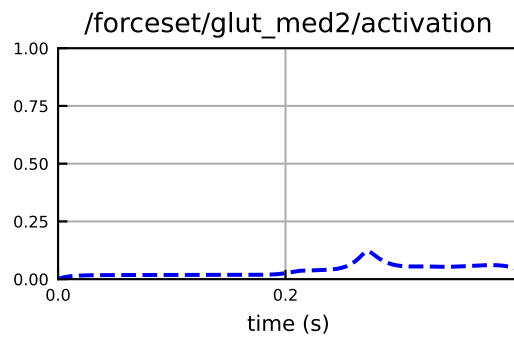
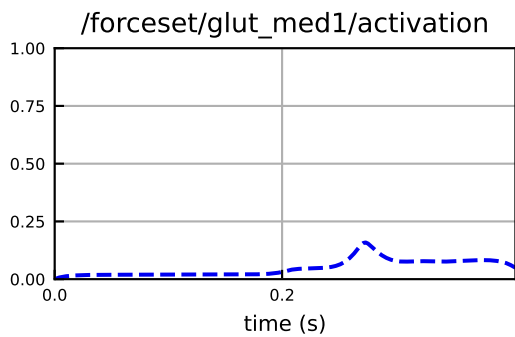
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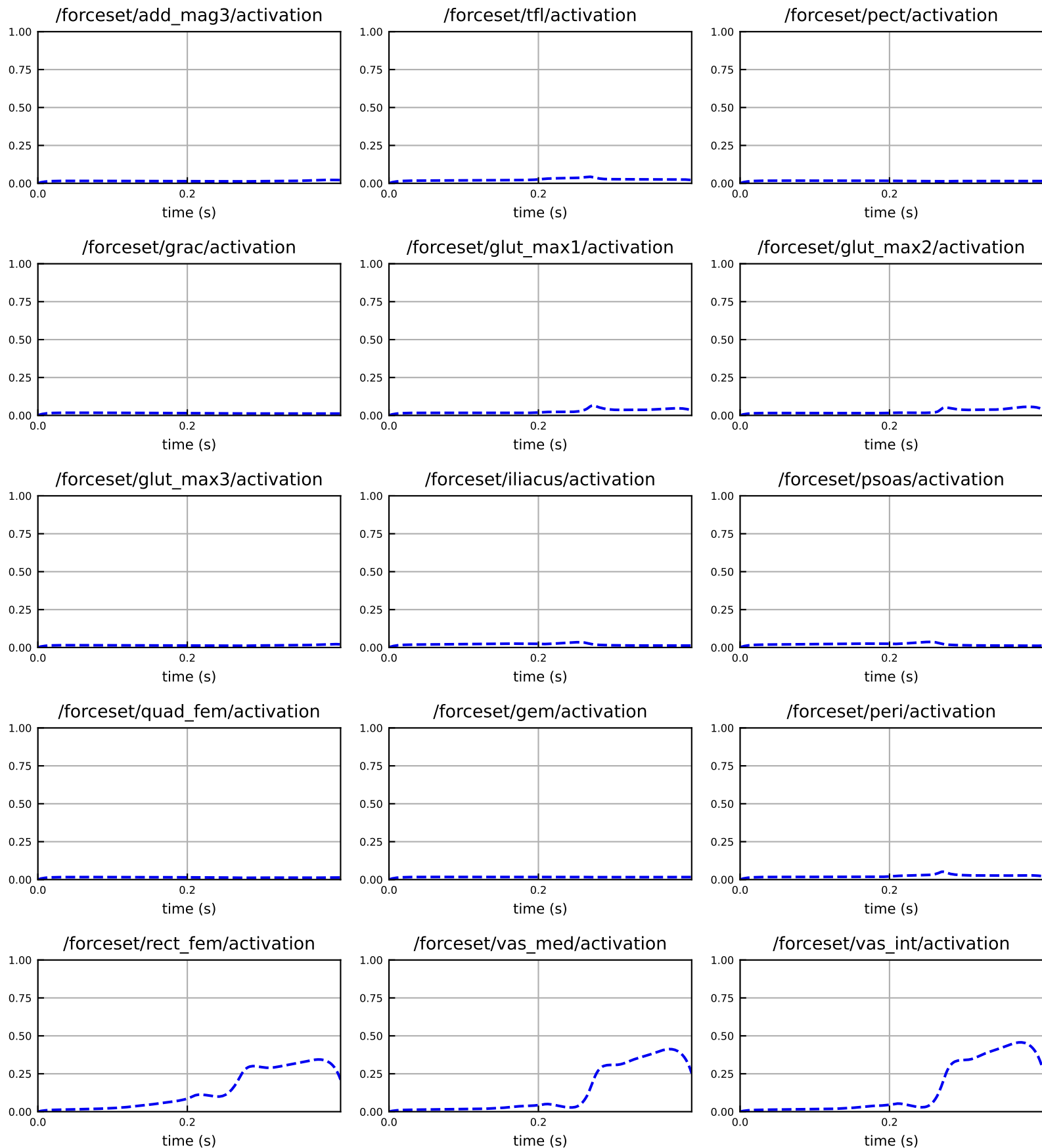
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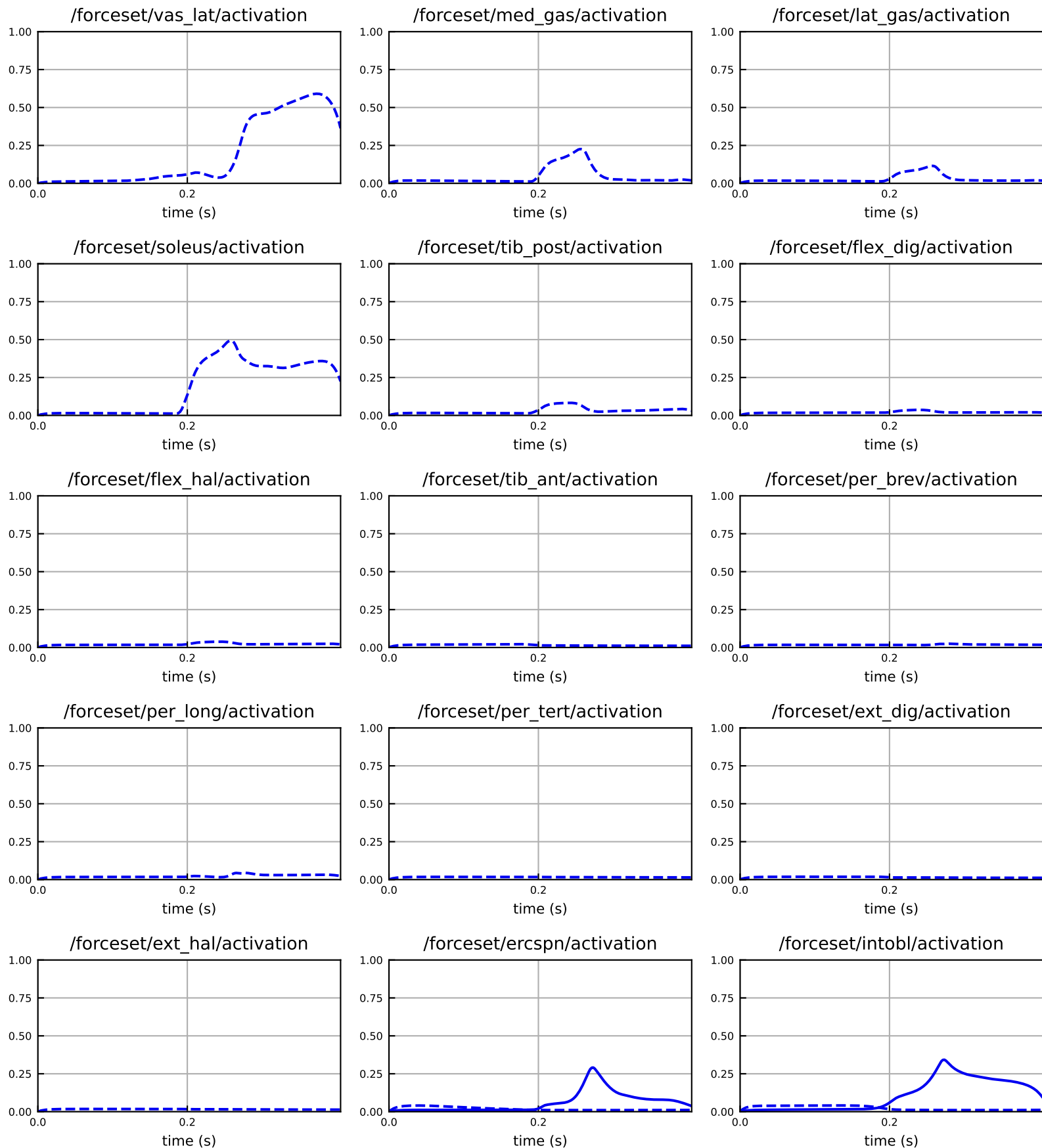
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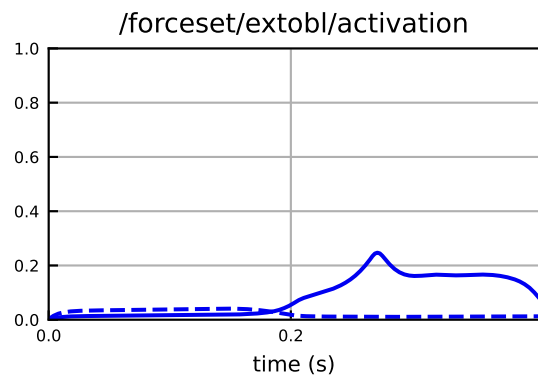
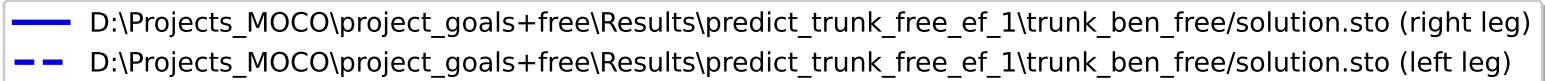


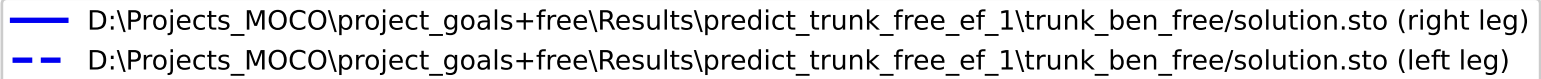
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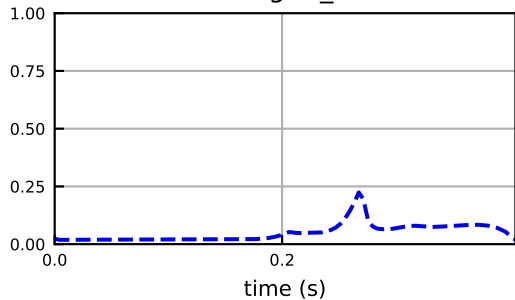
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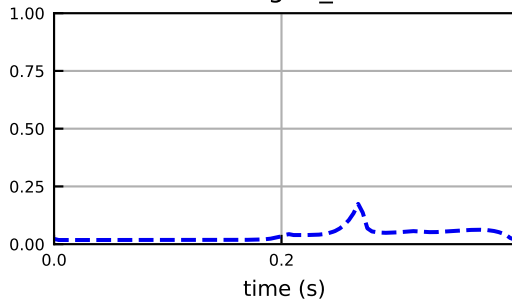




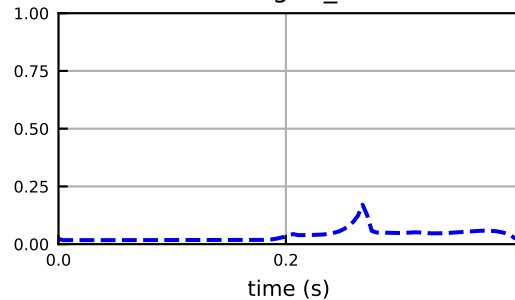
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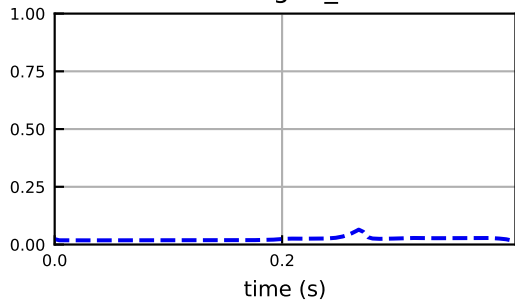
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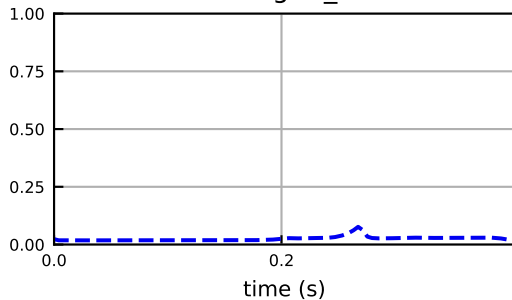
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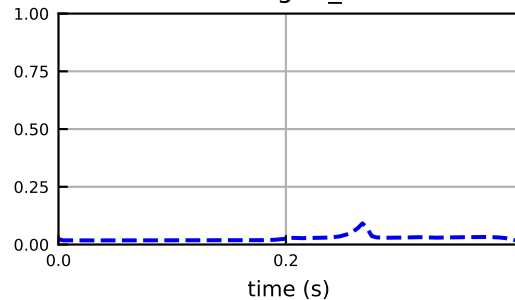
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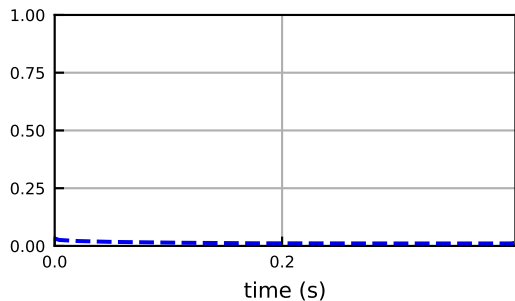
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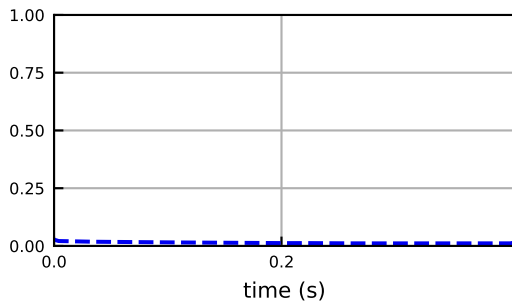
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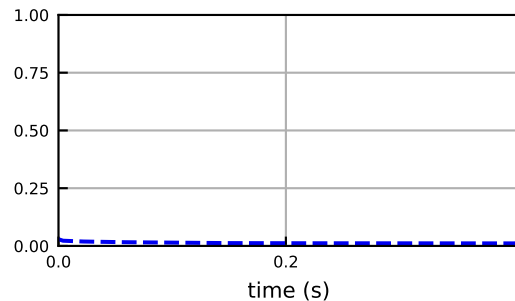
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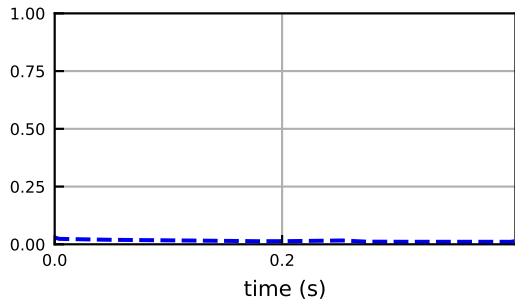
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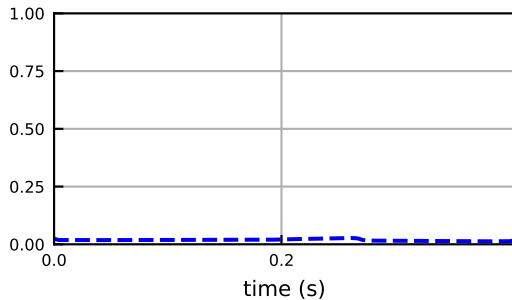
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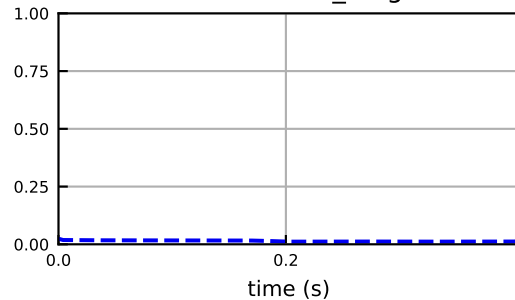
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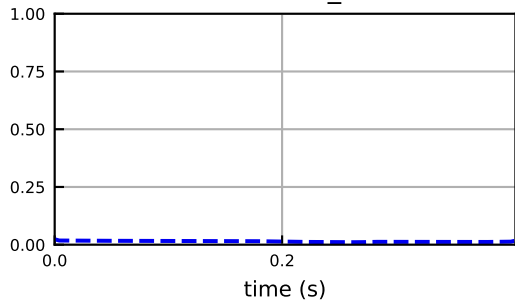
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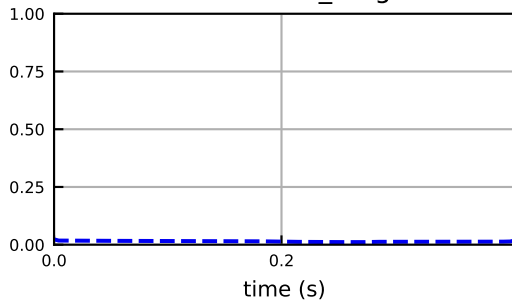
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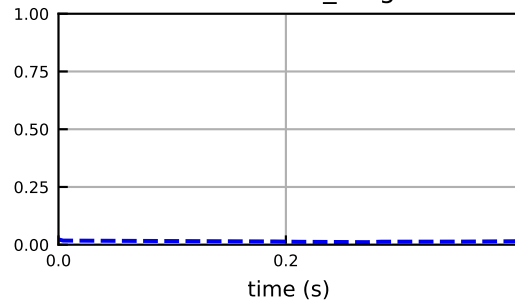
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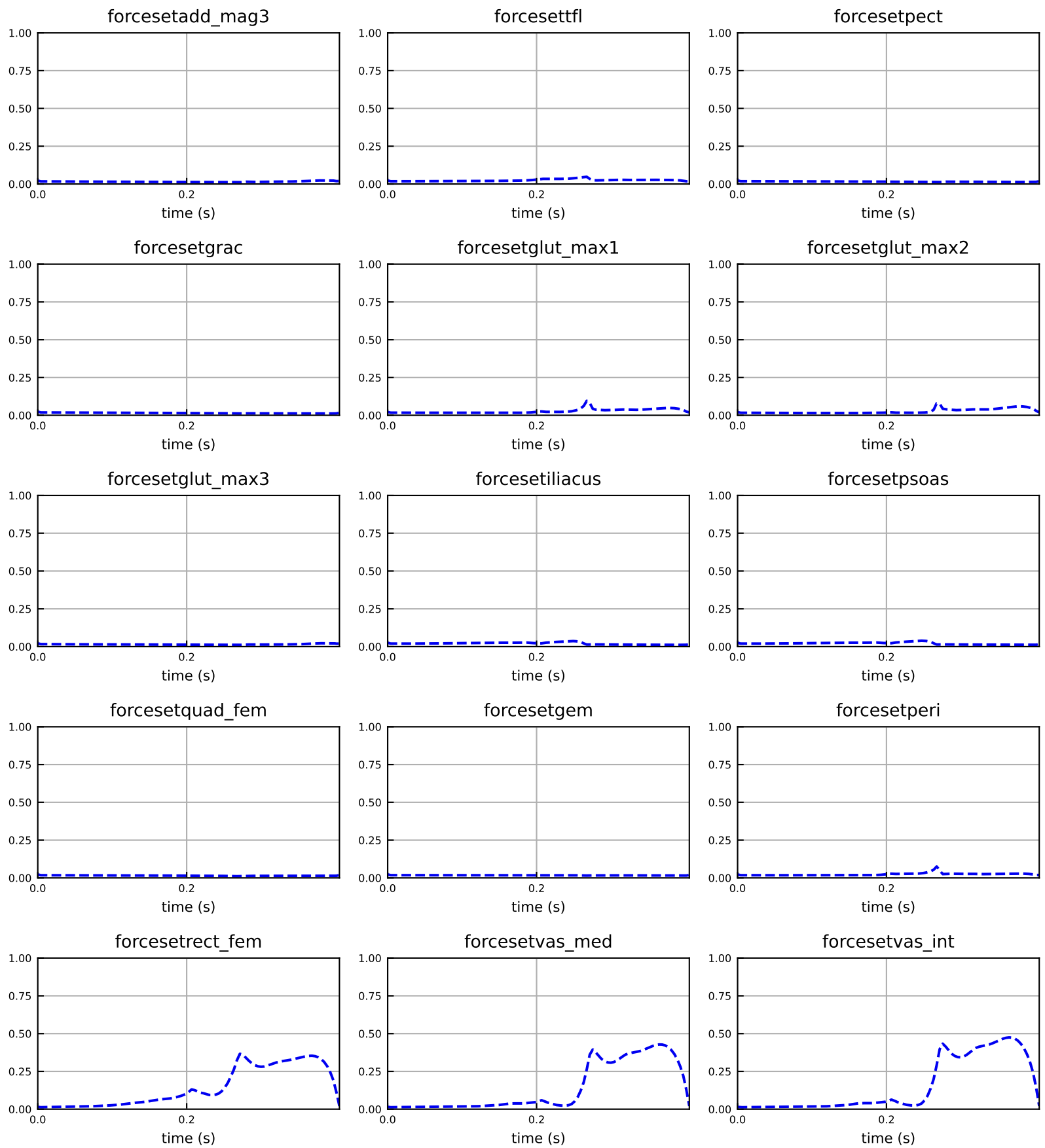
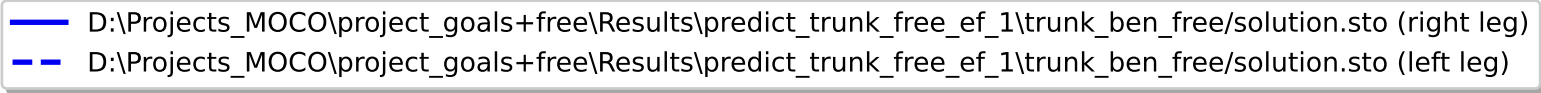


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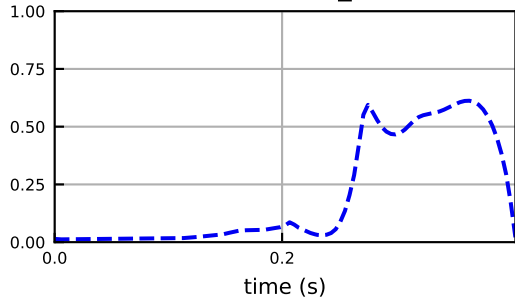
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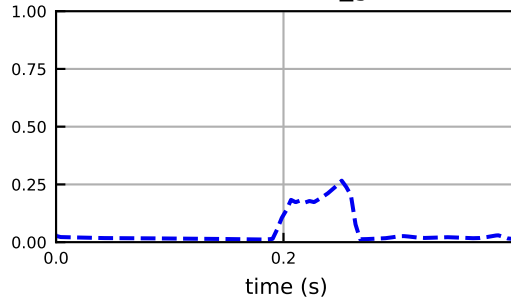


— D:\Projects_MOCO\project_goals+free\Results\predict_trunk_free_ef_1\trunk_ben_free\solution.sto (right leg)
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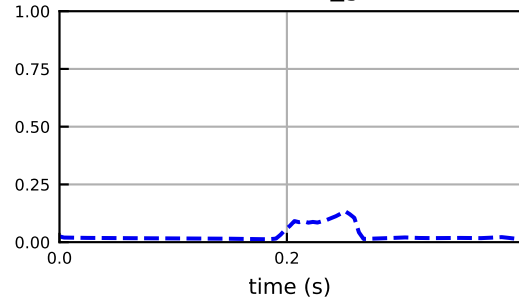
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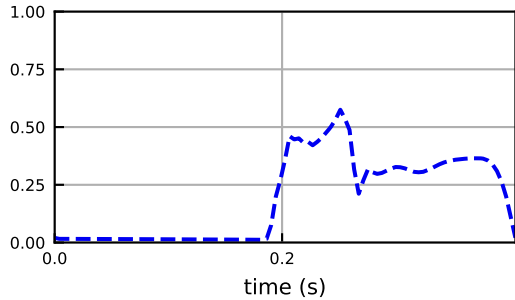
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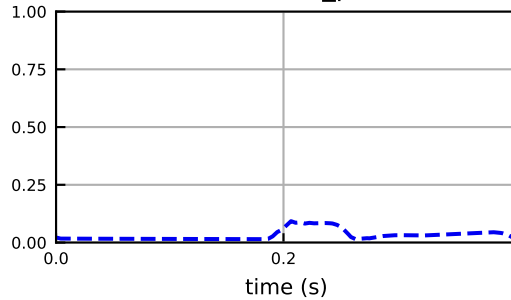
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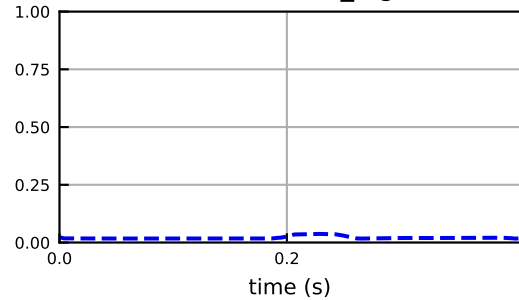
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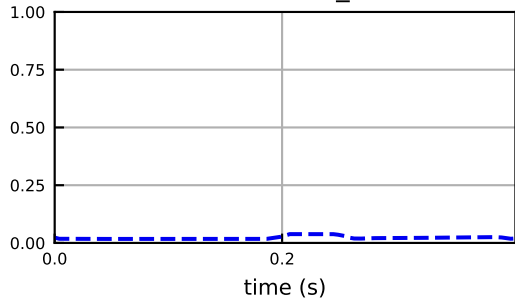
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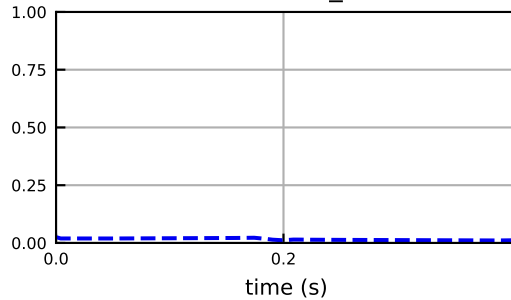
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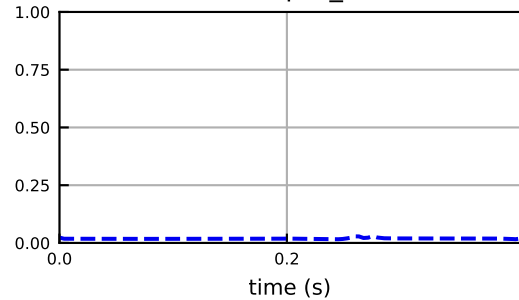
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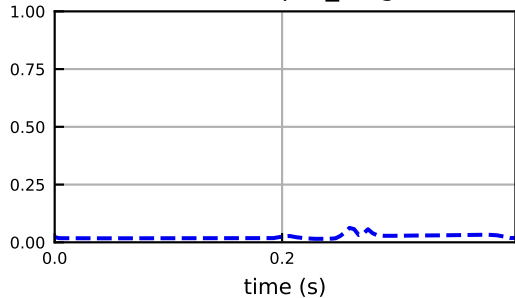
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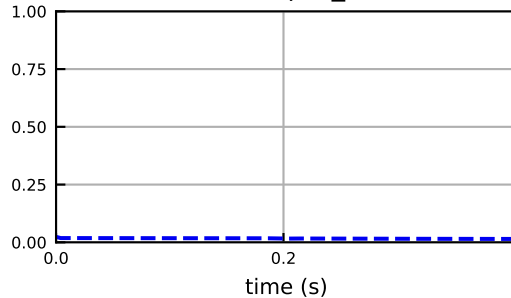
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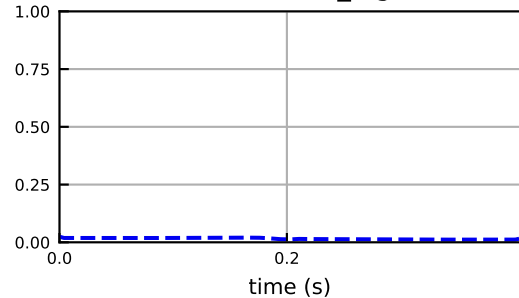
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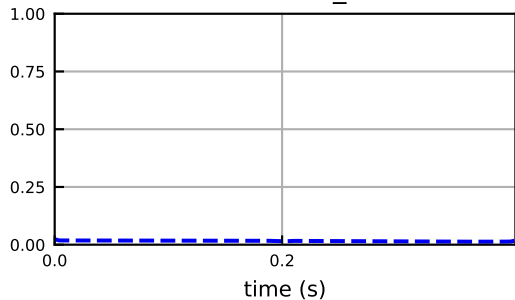
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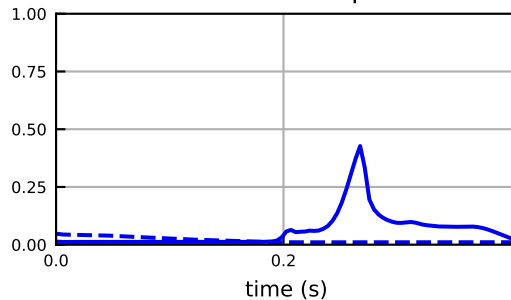
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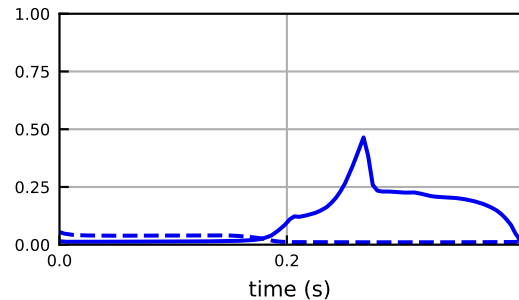
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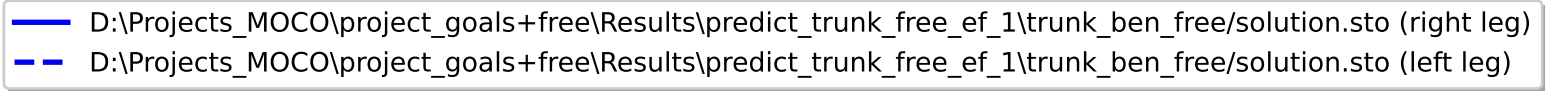


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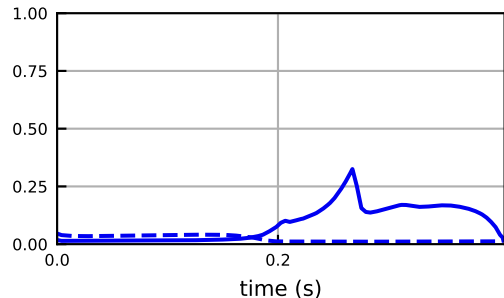


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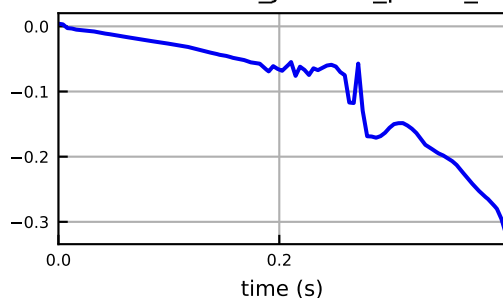




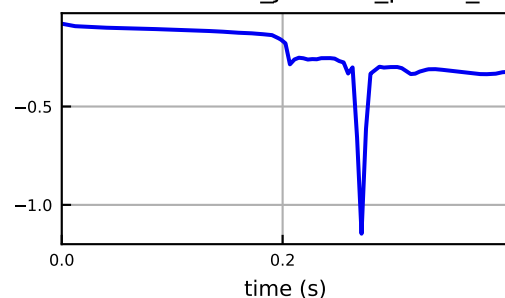
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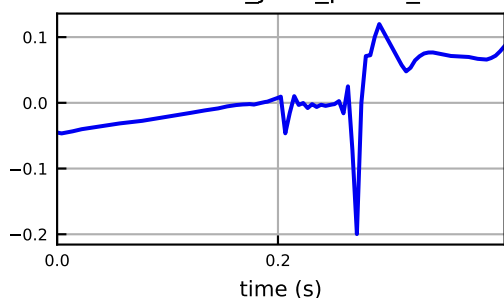
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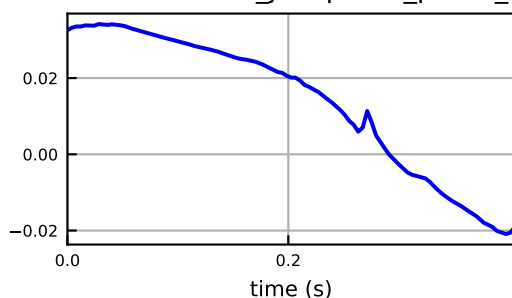
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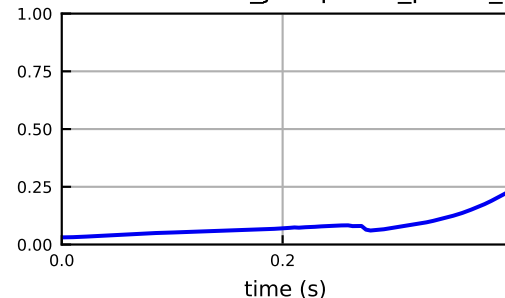
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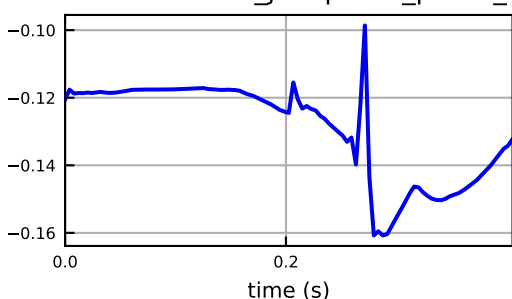
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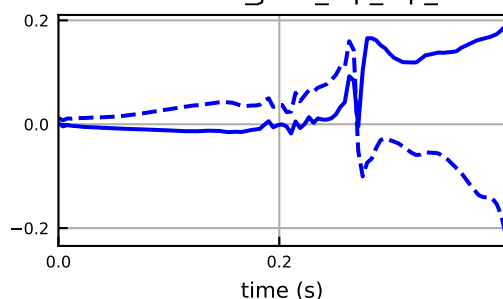
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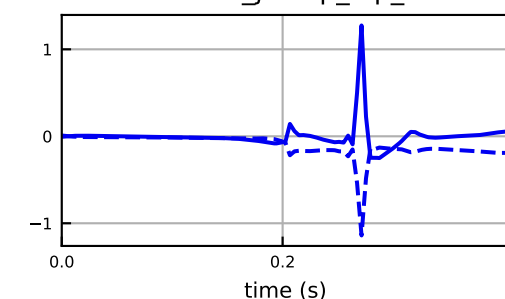
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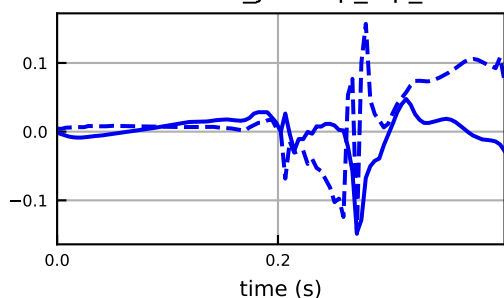
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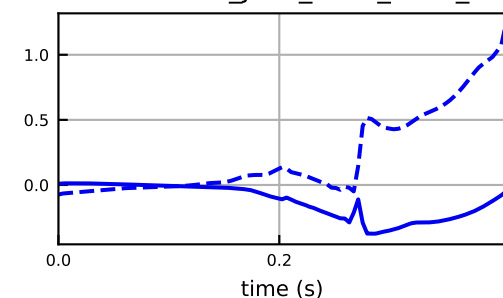
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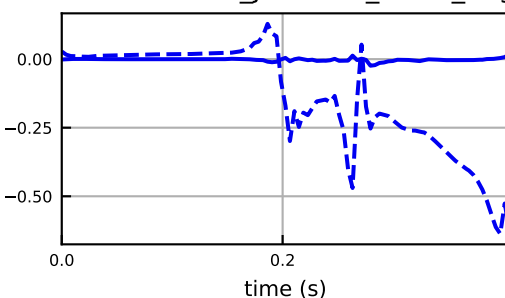
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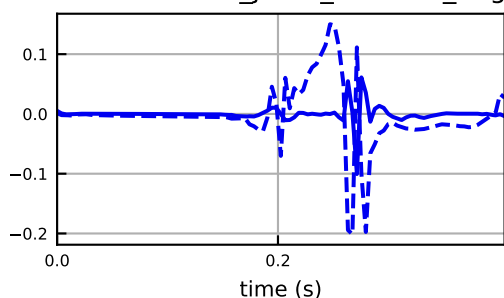
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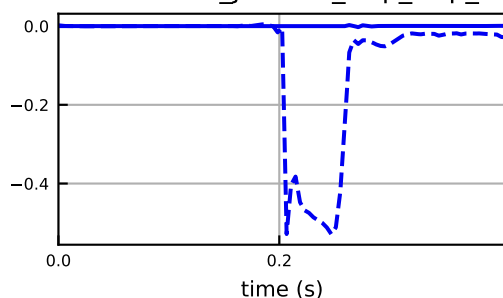
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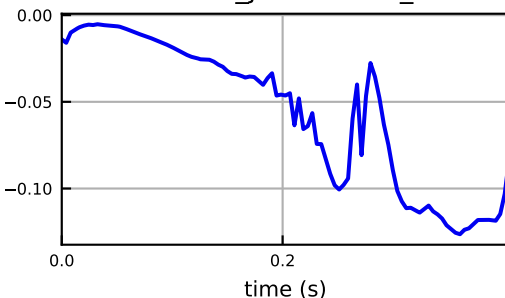
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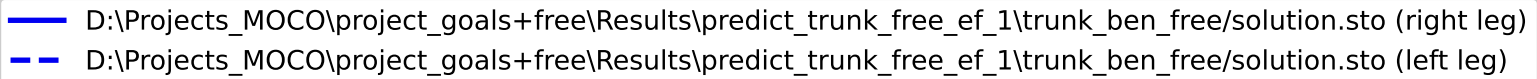


forcesetreserve_jointset_mtp_mtp_angle



forcesetreserve_joi...lumbar_extension





forcesetreserve_joi...k_lumbar_bending forcesetreserve_joi..._lumbar_rotation

