

expect:

$$E^{(0)}(w^{(1)}, b^{(1)}, w^{(2)}, b^{(2)}) = (\bar{x}^{(0)} - \bar{y}^{(0)})^2 =$$

$$= (\bar{x}^{(0)} - \bar{y}^{(0)}) \cdot (\bar{x}^{(0)} - \bar{y}^{(0)}) =$$

$$= (x_0^{(0)} - y_0^{(0)})^2 + (x_1^{(0)} - y_1^{(0)})^2$$

$$\partial_{x_0^{(0)}} E^{(0)} = 2(x_0^{(0)} - y_0^{(0)})$$

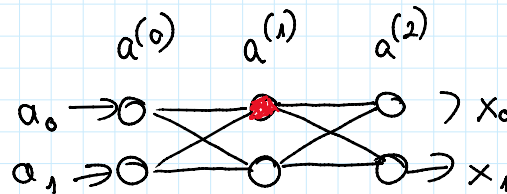
→ change to $a_0^{(L)}$

$$\partial_{x_1^{(0)}} E^{(0)} = 2(x_1^{(0)} - y_1^{(0)})$$

→ change to $a_1^{(L)}$

$$a_0^{(L)} = \sigma(z_0^{(L)})$$

$$z_0^{(L)} = w_{0,0}^{(L)} a_0^{(L-1)} + w_{0,1}^{(L)} a_1^{(L-1)} + b_0^{(L)}$$



How much should $a_0^{(1)}$ change? We know how much $z_0^{(2)}$ and $z_1^{(2)}$ should change.

$$E^{(0)} = (x_0^{(0)} - y_0^{(0)})^2 + (x_1^{(0)} - y_1^{(0)})^2 = (a_0^{(2)} - y_0^{(0)})^2 + (a_1^{(2)} - y_1^{(0)})^2$$

$$= (\sigma(z_0^{(2)}) - y_0^{(0)})^2 + (\sigma(z_1^{(2)}) - y_1^{(0)})^2$$

$$= (\sigma(w_{0,0}^{(2)} a_0^{(1)} + \dots) - y_0^{(0)})^2 + (\sigma(w_{1,0}^{(2)} a_0^{(1)} + \dots) - y_1^{(0)})^2$$

$$\partial_{a_0^{(1)}} E^{(0)} = \Delta_0^{(2)} \cdot w_{0,0}^{(2)} + \Delta_1^{(2)} \cdot w_{1,0}^{(2)} = \Delta_0^{(2)} \cdot w_0^{(2)} \quad \Delta^{(1)} = \begin{bmatrix} \Delta_0^{(2)} \cdot w_0^{(2)} \\ \Delta_1^{(2)} \cdot w_1^{(2)} \end{bmatrix}$$