CSE 6730 Project Checkpoint

Traffic flow simulation: case study of Atlanta traffic

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Jupyter notebook environment setup

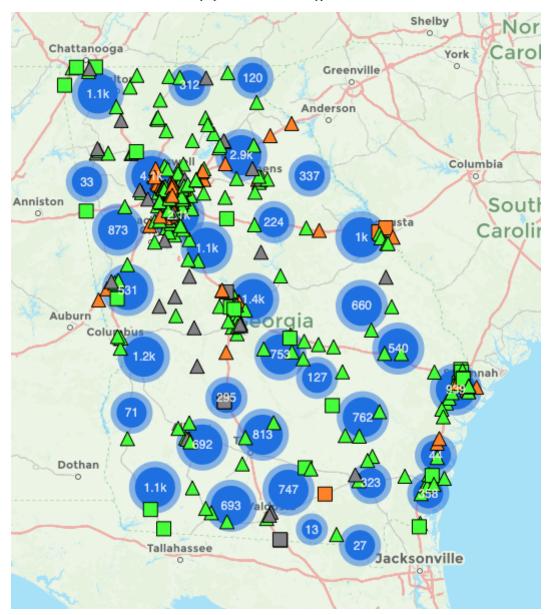
```
In [1]:
        1 # Import packages used in this notebook
         2 import math
         3 import time
         4 import numpy as np
         5 import pandas as pd
         6 %matplotlib inline
         7 import matplotlib.pyplot as plt
         8 from IPython.display import Image, display
```

1. Introduction

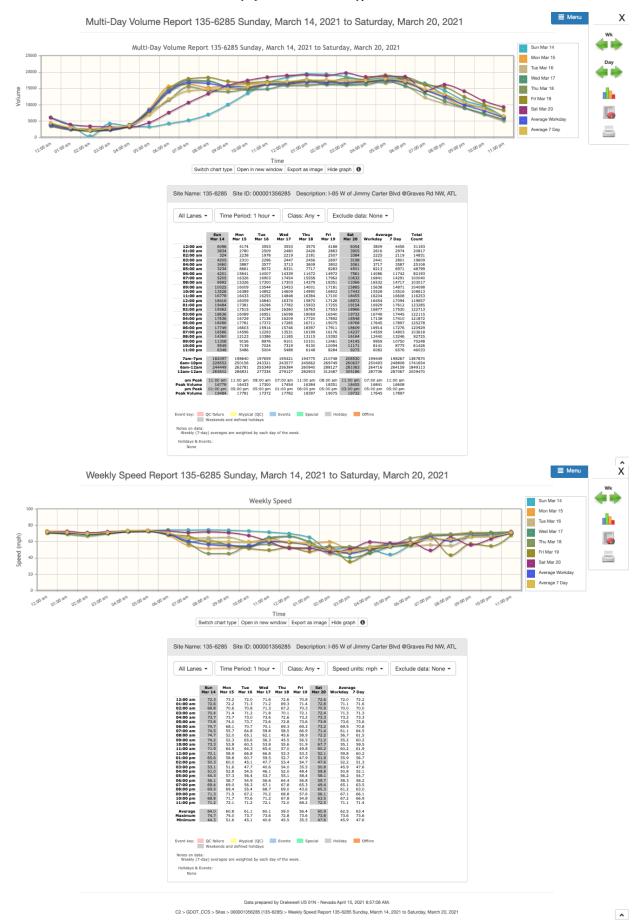
The project objective is to build a mathematical model to simulate the traffic flow in Atlanta. The ultimate goal is to understand the traffic phenomena in order to optimize traffic networks, alleviate congestion, maximize traffic flow and decrease accident rate. To validify the reliability of our models, we will perform case studies via simulating the real traffic data in Atlanta with our models. The implemented models would be tweaked based on the validation.

2. Data collection

The Atlanta traffic data is collected from the website of Georgia Department of Transportation (GDOT): https://gdottrafficdata.drakewell.com/publicmultinodemap.asp (https://gdottrafficdata.drakewell.com/publicmultinodemap.asp)



The green triangles symbolize active continuous count station (CCS) which are the sources in this project for collecting the traffic data. For active CCS, the hourly real-time traffic flow (volume) and speed data are monitored. An example site data of weekly (03/14/2021 - 03/20/2021) volume and speed for station 135-6285 - I-85 of Jimmy Carter Blvd @Graves Rd NW, ATL is shown below:



We compile the March 2021 traffic flow and speed data of four sites on the I-85 road into .csv files which are used in the modeling simulation and verification.

- Station 1: I-85 at North Druid Hills Road (station ID: 089-3323)
- Station 2: I-85/SR403 bn I-285 & Chamblee Tucker Rd, ATL (station ID: 089-3332)
- Station 3: I-85 W of Jimmy Carter Blvd @Graves Rd NW, ATL (station ID: 135-6285)
- Station 4: I-85 btwn Jimmy Carter & Indian Trail, Norcross (station ID: 135-6287)

3. Method and results

We intend to simulate the traffic flow with two models (progressively increasing in complexity). The first model would simulate the traffic flow with linear partial differential equations (PDE). This model simplifies the discrete traffic flow as continuous vehicle density. We would solve the PDEs analitically with and without assuming constant density and compare with the results derived from the iterative approach (Runge-Kutta 4th order). The second model (non-linear) would focus on more realistic conditions via taking into account more complex effects, such as the traffic lights, intersections, entrances and exits, etc.

3.1 Linear PDE model

In the linear PDE model, the traffic flow (the number of passing cars per unit time) is formulated as a function of position and time given the initial traffic density (the number of passing cars per unit length). The variables included in this model are

• traffic flow: J• position: x • time: *t*

 vehicle density: ρ • vehicle velocity: v

For the purpose of simulating the traffic flow on a first-order, we make the following assumptions:

- 1. The vehicle density is continuous. It means that our approach does not use individual car behavior to implement the traffic flow simulation.
- 2. The vehicle motion is unidirectional from left to right on a one-lane road of infinite length.
- 3. All vehicles are assumed to have the same length (L) and they are evenly spaced at distance d, which is simplified as a uniform distribution model (the vehicle density is homogeneous along the infinite lane).
- All other factors are not considered in the basic implementation of the model, but they might be tested and discussed given the progress and availability of the schedule.

3.1.1 Linear PDE formulation

The vehicle density ρ is formulated as a function of position x and time t. The vehicle density at position x_0 and time t_0 is calculated as follows according to the definition.

$$\rho(x_0, t_0) = \frac{1}{L+d}$$
 (Eq. 1)

Given the non-negativity of vehicle spacing d, the traffic density is upper bounded by $\frac{1}{L}$. The traffic flow J can be expressed as a linear combination of vehicle speed and traffic density as follows

$$J(x_0, t_0) = \rho(x_0, t_0) * v(x_0, t_0)$$
 (Eq. 2)

Substitute Eq. 1 in Eq. 2, we get

$$J(x_0, t_0) = \frac{v(x_0, t_0)}{L+d}$$
 (Eq. 3)

Consider a position interval Δx and time interval Δt around x_0 and t_0 , according to the Balance law for traffic density, the following equation can be derived

$$\Delta x * (\rho(x_0, t_0 + \Delta t) - \rho(x_0, t_0)) = \Delta t * (J(x_0 + \Delta x, t_0) - J(x_0, t_0))$$
 (Eq. 4)

After conducting Taylor expansion on both sides of Eq. 4 and omitting the third-order in terms of Δx and Δt , we get

$$\frac{\partial \rho}{\partial t} = -\frac{\partial J}{\partial x}$$
 (Eq. 5)

According to Eq.2, substitute J with ρv , the linear PDE model for traffic flow is

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho v}{\partial x} = 0$$
 (Eq. 6)
$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial v}{\partial x} + v \frac{\partial \rho}{\partial x} = 0$$
 (Eq. 7)

Eq. 6 (or Eq. 7) is the expression of continuous traffic flow equation.

Since there are two scenarios of traffic density (spatially homogeneous and spatially heterogenous) between adjacent stations in real traffic, they are separately simulated and discussed below.

3.1.2 Spatially homogeneous traffic density

If there is no intersections between adjacent stations, the traffic densities of these two stations are normally similar with small discrepancy. An example of this scenario is illustrated below. We extract the daily traffic flow and speed data (March 15, 2021, Monday) of two adjacent stations on the I-85 road without intersections in between. The information of these two stations are as follows.

- Entrance (Station 3): I-85 W of Jimmy Carter Blvd @Graves Rd NW, ATL (station ID: 135-6285)
- Exit (Station 4): I-85 btwn Jimmy Carter & Indian Trail, Norcross (station ID: 135-6287)

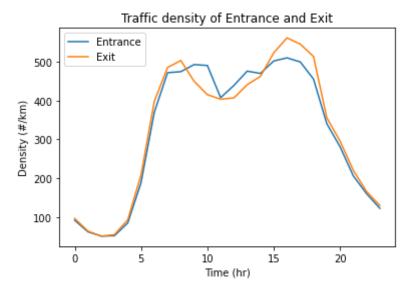


The traffic density at time t_n at location x_i is calculated as the result of traffic flow dividing speed.

$$\rho(x_i, t_n) = \frac{J(x_i, t_n)}{v(x_i, t_n)}$$
 (Eq. 8)

The comparision of traffic density on March 15, 2021 of the entrance and the exit is shown below.

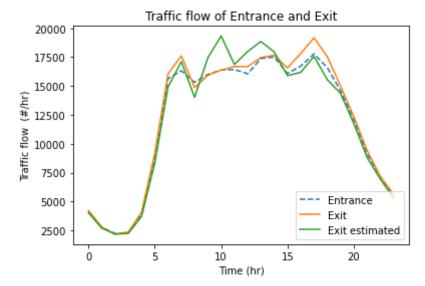
```
In [2]:
            # Read .csv file and extract column data
            col name val1 = ['entrance volume', 'entrance speed', 'exit volume', 'e
         2
            data_val1 = pd.read_csv('gdot_1356285_1356287_031521_firstValidation.cs
         3
            entrance_volume = data_vall.loc[1:,'entrance_volume'].tolist()
            exit_volume = data_vall.loc[1:,'exit_volume'].tolist()
            entrance speed = data_vall.loc[1:,'entrance speed'].tolist()
            exit_speed = data_vall.loc[1:,'exit_speed'].tolist()
            time val1 = data val1.loc[1:,'time'].tolist()
            flow_data_size_val1 = len(entrance_volume)
         9
        10
        11
            # Convert data from format string to float
            for i in range(flow_data_size_val1):
        12
        13
                entrance_volume[i] = float(entrance_volume[i])
        14
                exit volume[i] = float(exit volume[i])
        15
                entrance_speed[i] = float(entrance_speed[i])
        16
                exit_speed[i] = float(exit_speed[i])
        17
                time_val1[i] = float(time_val1[i])
        18
        19
            # Calculate traffic density
            entrance density = np.zeros(flow data size vall)
        20
        21
            exit density = np.zeros(flow data size vall)
        22
            for i in range(flow_data_size_val1):
        23
              entrance density[i] = entrance volume[i] / entrance speed[i]
        24
              exit_density[i] = exit_volume[i] / exit_speed[i]
        25
        26
            # Plot traffic density of entrance and exit
           plt.plot(time val1, entrance density*1.60934, label='Entrance')
        27
           plt.plot(time val1, exit density*1.60934, label='Exit')
           plt.title('Traffic density of Entrance and Exit')
        29
        30 plt.xlabel('Time (hr)')
        31 plt.ylabel('Density (#/km)')
        32 plt.legend(loc= 'upper left')
            plt.show()
```



The result shows that the traffic density at the two stations generally approximate each other although some variations exit during the day. It demonstrates that the traffic density is roughly spatially homogeneous if there is no intersections. With this assumption, the traffic flow of a

targeted location can be estimated by the traffic density of another location and the speed of the targeted location. For instance, we estimate the traffic flow of the exit by leveraging the traffic density of the entrace as follows.

```
In [3]:
            # Estimate exit volume based on entrance density and exit speed
         1
            exit volume estimated = np.zeros(flow data size vall)
         2
            for i in range(flow data size vall):
                exit volume estimated[i] = entrance density[i] * exit speed[i]
          4
         5
            # Calculate absolute error between estimated traffic flow and true valu
         6
         7
            # entrance exit abs error = np.zeros(flow data size vall)
            # for i in range(flow data size val1):
         8
         9
                entrance exit abs error[i] = 100 * abs((exit volume estimated[i]-ex
        10
            # Plot comparison of entrance and exit traffic flow (volume) data
        11
            plt.plot(time val1, entrance volume, '--', label='Entrance')
        12
           plt.plot(time_val1, exit_volume, label='Exit')
        13
        14
            plt.plot(time val1, exit volume estimated, label='Exit estimated')
           plt.title('Traffic flow of Entrance and Exit')
            plt.xlabel('Time (hr)')
            plt.ylabel('Traffic flow (#/hr)')
        17
           plt.legend(loc= 'lower right')
        18
        19
           plt.show()
        20
        21
           # Plot absolute error
        22 # plt.plot(time vall, entrance exit abs error)
        23 # plt.title('Relative percentage error between Entrance & Exit')
        24 # plt.xlabel('Time (hr)')
        25 | # plt.ylabel('Percentage error (%)')
            # plt.show()
        26
```



The above plot shows that during the time slot that the two stations have similar traffic density, the estimated traffic flow approximates the true traffic flow very well. However, the error of the estimation increases for the time window where relatively large discrepancy of traffic density occurs.

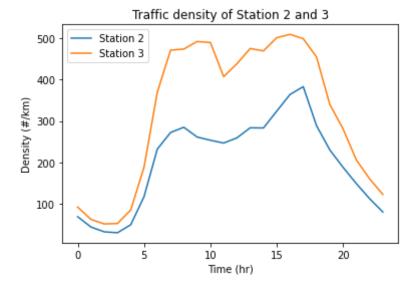
3.1.3 Spatially heterogeneous traffic density

Another scenario is that the traffic densities of the adjacent stations are different. This case normally appears when there are intersections between the stations. The potential imbalance between the input and output traffic flux at the intersections may cause the difference in the traffic density. We extract the daily (March 15, 2021, Monday) traffic data of a pair of adjacent stations (Station 2 and 3) with an intersection in between to illustrate this case. The geographic locations of Station 2 and 3 together with the two boundaries Station 1 and 4 (used in the simulation) are shown below.



The comparison of traffic density between Station 2 and 3 is shown below.

```
In [4]:
         1
            # Read .csv file and extract column data
            col name val2 = ['volume S1', 'speed S1', 'volume S2', 'speed S2', 'volu
            data val2 = pd.read csv('gdot 0893323 0893332 1356285 1356287 031521 se
         3
            volume_S1 = data_val2.loc[1:,'volume_S1'].tolist()
            volume_S2 = data_val2.loc[1:,'volume_S2'].tolist()
            volume S3 = data_val2.loc[1:,'volume_S3'].tolist()
            volume_S4 = data_val2.loc[1:,'volume_S4'].tolist()
         7
            speed S1 = data val2.loc[1:,'speed S1'].tolist()
            speed_S2 = data_val2.loc[1:,'speed_S2'].tolist()
            speed_S3 = data_val2.loc[1:,'speed_S3'].tolist()
         11
            speed S4 = data val2.loc[1:,'speed S4'].tolist()
            time_val2 = data_val2.loc[1:,'time'].tolist()
         12
         13
            flow_data_size_val2 = len(volume_S1)
         14
         15
            # Convert data from format string to float
         16
            for i in range(flow_data_size_val2):
         17
                volume S1[i] = float(volume S1[i])
         18
                volume S2[i] = float(volume S2[i])
         19
                volume_S3[i] = float(volume_S3[i])
         20
                volume S4[i] = float(volume S4[i])
         21
                speed_S1[i] = float(speed_S1[i])
         22
                speed_S2[i] = float(speed_S2[i])
         23
                speed_S3[i] = float(speed_S3[i])
         24
                speed_S4[i] = float(speed_S4[i])
         25
                time_val2[i] = float(time_val2[i])
         26
         27
            # Calculate density for each station & density max and speed max from S
         28
            density S1 = np.zeros(flow data size val2)
         29
            density S2 = np.zeros(flow data size val2)
            density S3 = np.zeros(flow data size val2)
         31
            density S4 = np.zeros(flow data size val2)
         32
            density max = np.zeros(flow data size val2)
         33
            speed max = np.zeros(flow data size val2)
         34
         35
            for i in range(flow_data_size_val2):
         36
              density S1[i] = volume S1[i] / speed S1[i]
         37
              density S2[i] = volume S2[i] / speed S2[i]
         38
              density S3[i] = volume S3[i] / speed S3[i]
         39
              density S4[i] = volume S4[i] / speed S4[i]
         40
              density max[i] = (speed S1[i]*density S4[i] - speed S4[i]*density S1[
         41
              speed_max[i] = speed_S1[i] / (1 - density_S1[i]/density_max[i])
         42
         43
            # Plot density of Station 2 and 3
         44
            plt.plot(time val2, density S2*1.60934, label='Station 2')
         45
            plt.plot(time val2, density S3*1.60934, label='Station 3')
           plt.title('Traffic density of Station 2 and 3')
         46
         47
            plt.xlabel('Time (hr)')
            plt.ylabel('Density (#/km)')
           plt.legend(loc= 'upper left')
         49
         50 plt.show()
```



The above plot shows that there are large difference between the Station 2 and 3, especially during the day time. Hence, the assumption of spatially homogeneous traffic density no longer holds, and it is expected that to estimate the traffic flow of Station 3 via the traffic density of Station 2 would induce large errors.

The idea is to explore the correlation between the speed and the traffic density from the traffic data of Station 1 and 4 and then use this derived correlation to fit the traffic flow given the density data for Station 2 and 3.

Two approaches have been tested. The first approach is to assume a linear velocity formulated by the **Greenshields** model as follows.

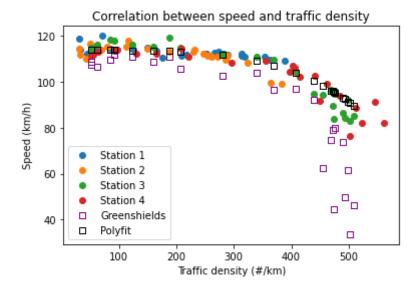
$$v = v_{max}(1 - \frac{\rho}{\rho_{max}})$$
 (Eq. 9)

where v_{max} and ρ_{max} are two unknown parameters (for each hour) that can be calculated by plugging hourly traffic data of Station 1 and 4. Then with derived parameters, the estimated traffic flow for Station 2 and 3 can be calculated as the product of true traffic density and estimated speed

$$J = \rho v_{max} (1 - \frac{\rho}{\rho_{max}}) \qquad \text{(Eq. 10)}$$

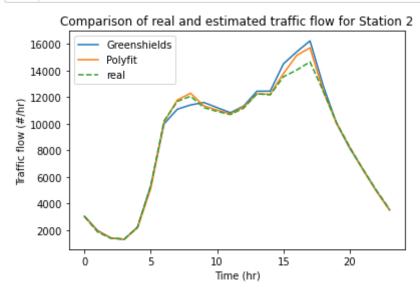
The second approach is to use **polynomial regression** to fit the correlation. The true corrlations between the traffic density and speed for all four stations and the fitted correlations derived from Greenshields model and polynomial regression (fitted with the traffic data of Station 3) are shown in the scatter plot below.

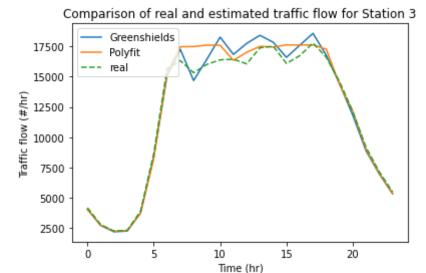
```
In [5]:
            # Concatenate traffic density and speed data of Station 1 and 4
            density S1S4 = np.zeros(2*flow data size val2)
         2
            speed_S1S4 = np.zeros(2*flow_data_size_val2)
         3
            density_S1S4 = np.concatenate((density_S1, density_S4))
            speed S1S4 = np.concatenate((np.array(speed S1), np.array(speed S4)))
         5
         7
            # Polynomial fit (3rd order) the correlation between speed and traffic
            polyfit coeff = np.polyfit(density S1S4, speed S1S4, 3)
         8
         9
            rho_v_polyfit = np.poly1d(polyfit_coeff)
        10
        11
            # Generate fitted speed for Station 3
        12
            speed_S3_fitted = np.zeros(flow_data_size_val2)
        13
            speed_S3_fitted = rho_v_polyfit(density_S3)
        14
        15
            # Plot the correlation between speed and traffic density for four stati
        16
            plt.scatter(density_S1*1.60934, np.array(speed_S1)*1.60934, label='Stat
            plt.scatter(density S2*1.60934, np.array(speed S2)*1.60934, label='Stat
        17
            plt.scatter(density_S3*1.60934, np.array(speed_S3)*1.60934, label='Stat
            plt.scatter(density S4*1.60934, np.array(speed S4)*1.60934, label='Stat
        19
            plt.scatter(density S3*1.60934, speed max*1.60934*(1 - np.array(density
        20
        21
           plt.scatter(density S3*1.60934, speed S3 fitted*1.60934, facecolors='no
        22
            plt.title('Correlation between speed and traffic density')
           plt.xlabel('Traffic density (#/km)')
            plt.ylabel('Speed (km/h)')
           plt.legend(loc= 'lower left')
        25
        26
           plt.show()
```



lower than the actual value (green dot), while the speed fitted from the polynomial regression (black square) approximates the true value well and generally fall within the main sequence formed by the traffic data of four models. The two fitting approaches are utilized to generate the estimated traffic flow for Station 2 and 3 and are plotted in comparison with the true values as shown below.

```
In [6]:
         1
            # Calculate estimated traffic flow for Station 2 and 3
            volume S2 estimated g = np.zeros(flow data size val2)
         2
         3
            volume S3 estimated g = np.zeros(flow_data_size_val2)
            volume S2 estimated p = np.zeros(flow data size val2)
            volume S3 estimated p = np.zeros(flow data size val2)
         5
         7
            for i in range(flow data size val2):
                volume S2 estimated g[i] = density S2[i] * speed max[i] * (1 - dens
         8
         9
                volume S3 estimated g[i] = density S3[i] * speed max[i] * (1 - dens
                volume S2 estimated p[i] = density S2[i] * rho_v polyfit(density S2
        10
        11
                volume S3 estimated p[i] = density S3[i] * rho v polyfit(density S3
        12
        13
            # Plot the real and estimated traffic flow for Station 2
            plt.plot(time val2, volume S2 estimated g, label='Greenshields')
        14
            plt.plot(time_val2, volume_S2_estimated_p, label='Polyfit')
        15
           plt.plot(time_val2, volume_S2, '--', label='real')
        17
            plt.title('Comparison of real and estimated traffic flow for Station 2'
        18
           plt.xlabel('Time (hr)')
            plt.ylabel('Traffic flow (#/hr)')
           plt.legend(loc= 'upper left')
        20
        21
           plt.show()
        22
        23
           # Plot the real and estimated traffic flow for Station 3
            plt.plot(time val2, volume S3 estimated g, label='Greenshields')
        24
            plt.plot(time val2, volume S3 estimated p, label='Polyfit')
           plt.plot(time_val2, volume_S3, '--', label='real')
           plt.title('Comparison of real and estimated traffic flow for Station 3'
        27
        28 plt.xlabel('Time (hr)')
        29 plt.ylabel('Traffic flow (#/hr)')
        30 plt.legend(loc= 'upper left')
        31 plt.show()
```





The figures show that for both Station 2 and 3 the traffic flow fitted with polynomial regression (orange curve) approximates the true values (green dashed line) better compared with the fitting from the Greenshields model (blue curve).

3.1.4 Iterative approach: Runge-Kutta 4th order (RK4)

In this section, we explore the iterative method to generate the numerical solution for the continuous traffic flow PDE. Since the discretization of PDE equation requires the parametric formulation of variables, we utilize Greenshields model to represent the correlation between speed and traffic density (Eq. 9) although it performs not as good as the polynomial regression in fitting the traffic flow. With this assumption, the Eq. 7 can be further discretized as

$$\frac{\partial \rho}{\partial t} + v_{max} (1 - \frac{2\rho}{\rho_{max}}) \frac{\partial \rho}{\partial x} = 0$$
 (Eq. 11)

Denote $C(\rho)=v_{max}(1-\frac{2\rho}{\rho_{max}})$ and apply the *finite difference method*, Eq. 11 can be written as

$$\frac{\rho_j^{n+1} - \rho_j^n}{\Delta t} + C(\rho_j^n) \frac{\rho_j^n - \rho_{j-1}^n}{\Delta x} = 0$$
 (Eq. 12)

Rearrange the time step n + 1 term to the left hand side and time step n terms to the right hand side. The final numerical scheme is

$$\rho_{i}^{n+1} = \rho_{i}^{n} + C(\rho_{i}^{n}) \frac{\Delta t}{\Delta x} (\rho_{i}^{n} - \rho_{i-1}^{n})$$
 (Eq. 13)

Haversine formula

In Eq. 13, Δx denotes the distance between two adjacent stations. Given this distance is the distance between two points on Earth (a sphere), the great-circle distance can be calculated via the haversine formula with the latitudes and longitudes of the two points.

$$hav(\Theta) = sin^{2}(\frac{\phi_{2} - \phi_{1}}{2}) + cos(\phi_{1})cos(\phi_{2})sin^{2}(\frac{\lambda_{2} - \lambda_{1}}{2})$$
(Eq. 14)
$$d = r * \Theta = 2r * arcsin(\sqrt{hav(\Theta)})$$
(Eq. 15)

where hav() is the haversine function, Θ is the central angle, ϕ and λ are latitude and longitude of points, respectively, and r is the Earth radius.

The haversine function is implemented as follows.

```
In [7]:
            # Define haversine formula function to calculate the distance on a sphe
            def haversine distance(point one, point two):
                lat_1, long_1 = point_one
                lat_2, long_2 = point_two
         5
                earth radius = 6371 # unit of km
                lat_1_rad = math.radians(lat_1)
         7
                lat 2 rad = math.radians(lat 2)
         8
                delta_lat = math.radians(lat_2 - lat_1)
                delta_long = math.radians(long_2 - long_1)
         9
                hav_theta = math.sin(delta_lat/2)**2 + math.cos(lat_1_rad)*math.cos
        10
                #theta = 2 * math.atan2(math.sqrt(hav theta), math.sqrt(1-hav theta
        11
                theta = 2 * math.asin(math.sqrt(hav_theta))
        12
                distance = earth radius * theta * 0.539957 # 0.539957 is conversion
        13
                return distance
        14
```

Runge-Kutta 4th order

Runge-Kutta 4th order is a commonly used iterative method (normally referred as "RK4") to discretize the ordinary differential equation for generating approximate solutions. This method is internally composed of the Euler method. Given an initial value problem of

$$\frac{dy}{dt} = f(t, y), y(t_0) = y_0 (Eq. 16)$$

The RK4 method can be expressed as

$$y_{n+1} = y_n + \frac{1}{6}h(k_1 + 2k_2 + 2k_3 + k_4)$$
 (Eq. 17)
 $t_{n+1} = t_n + h$ (Eq. 18)

where h is the time step size, and k_1 , k_2 , k_3 , k_4 are defined as

$$k_{1} = f(t_{n}, y_{n})$$
 (Eq. 19)

$$k_{2} = f(t_{n} + \frac{h}{2}, y_{n} + h\frac{k_{1}}{2})$$
 (Eq. 20)

$$k_{3} = f(t_{n} + \frac{h}{2}, y_{n} + h\frac{k_{2}}{2})$$
 (Eq. 21)

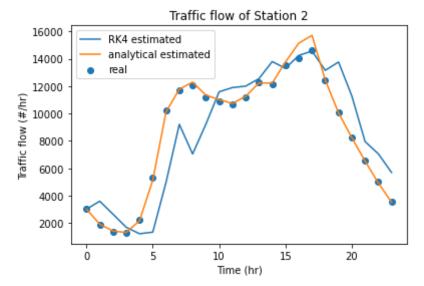
$$k_{4} = f(t_{n} + h, y_{n} + hk_{3})$$
 (Eq. 22)

To apply RK4 in Eq. 13, the f() in RK4 method formulates the differential equation of continous traffic flow, specifically f() represents the derivative of traffic density with respect to time $(\frac{\partial \rho}{\partial t})$. The implementation of RK4 in simulating the traffic flow is shown below with the estimated results for Station 2 and 3 compared with the true values and the fitted values from the analytical derivation.

```
In [8]:
                           1
                                  # Define traffic flow model ODE (time derivative of traffic density)
                                  def drho_dt(rho, v_cur, v_next, distance):
                           2
                           3
                                              return -rho * ((v_next-v_cur)/distance) # Note this ODE does not i
                           5
                                  # Define RK4 function
                                  def rungeKutta4th(drho_dt, v_cur, v_next, distance, t0, rho0, h, n):
                           7
                                              # Initialize time and traffic density array
                           8
                           9
                                              t_array = np.zeros(n+1)
                         10
                                              rho_array = np.zeros(n+1)
                         11
                                              # Assign initial conditions
                         12
                         13
                                              t array[0] = t0
                         14
                                              rho_array[0] = rho0
                         15
                         16
                                              # Interatively calculate traffic density of each time step
                         17
                                              for i in range(1,n+1):
                         18
                         19
                                                         # Calculate k1 to k4 values in RK4 formula
                         20
                                                         k1 = drho_dt(rho_array[i-1], v_cur, v_next, distance)
                         21
                                                         k2 = drho_dt(rho_array[i-1] + 0.5*k1, v_cur, v_next, distance)
                                                         k3 = drho dt(rho array[i-1] + 0.5*k2, v cur, v next, distance)
                         22
                         23
                                                         k4 = drho_dt(rho_array[i-1] + k3, v_cur, v_next, distance)
                         24
                         25
                                                         # Assign updated t and calculated rho to the corresponding time
                         26
                                                         t array[i] = t array[i-1] + h
                                                         rho_array[i] = rho_array[i-1] + (1.0/6.0)*h*(k1 + 2*k2 + 2*k3 +
                         27
                         28
                                              # Return iteratively derived traffic density at time step n
                         29
                         30
                                              return rho array[n]
```

```
In [9]:
         1 # Define input parameters for RK4
          2
           t initial = 0
          3 num iteration = 1
            sub step size = 0.01
          5
           # Define station coordinates
            coord S1 = [33.82764, -84.34427]
          7
            coord S2 = [33.88379, -84.26857]
           # Assign time variable for Station 1 and 2
         10
         11 | time S1 = time val2
         12 | time_S2 = time_val2
```

```
In [10]:
          1
             # Convert speed array to Numpy array
             speed S1 array = np.array(speed S1)
           3
             speed_S2_array = np.array(speed_S2)
             # Initialize empty array to store results
            rho S1 initial = np.zeros(len(time S1))
           7
             rho S2 = np.zeros(len(time S1))
            rho S2 approx = np.zeros(len(time S1))
             best_step_size = np.zeros(len(time_S1))
          10
             volume_S2_approx = np.zeros(len(time_S1))
          11
             # Assign values for the first row of density arrays for Station 2
          12
          13
             rho S2[0] = density S2[0]
          14
             rho S2 approx[0] = rho S2[0] # the initial traffic density is assigned
          15
             volume_S2 approx[0] = rho_S2[0] * speed_S2[0]
          16
          17
             # Iteratively calculate the estimated traffic density of all time steps
          18
             for i in range(0, len(time S1)-1):
          19
          20
                 # Assign speed values of current time step and next time step for S
          21
                 v cur = speed S1[i]
          22
                 v_next = speed_S1[i+1]
          23
                 # Calculate distance between Station 1 and 2
          24
          25
                 dist = haversine distance(coord S1, coord S2)
          26
          27
                 # Assign initial traffic density value of all time steps for Static
          28
                 rho S1 initial[i] = volume S1[i] / speed S1[i]
          29
          30
                 # Create an array with various time step size
          31
                 step size = np.arange(sub step size, 1, sub step size)
          32
          33
                 # Collect all results of traffic density of Station 2 of next time
          34
                 rho S2 step size res = np.zeros(len(step size))
          35
                 for j in range(0, len(step size)):
          36
                     rho S2 step size res[j] = rungeKutta4th(drho dt, v cur, v next,
          37
          38
                 # Select the simulated traffic density value of Station 2 that appr
          39
                 rho S2[i+1] = density S2[i+1]
                 rho S2 approx[i+1] = min(rho S2 step size res, key=lambda x: abs(x-
          40
          41
                 # Estimate the traffic flow value of Station 2 for the next time st
          42
          43
                 volume S2 approx[i+1] = rho S2 approx[i+1] * speed S2[i+1]
          44
          45
             # Plot RK4, analytical estimated traffic flow of Station 2 and 3 compar
             plt.scatter(time S2, volume S2, label='real')
             plt.plot(time S2, volume S2 approx, label='RK4 estimated')
             plt.plot(time S2, volume S2 estimated p, label='analytical estimated')
          49
            plt.title('Traffic flow of Station 2')
          50 plt.xlabel('Time (hr)')
          51 plt.ylabel('Traffic flow (#/hr)')
          52 plt.legend(loc= 'upper left')
          53 plt.show()
```



The above figure shows that RK4 estimated results have relatively large discrepancy from the ground true values compared with the analytical derivation. To be noted, this RK4 implementation simplifies the PDE as the spatially homogeneous traffic density. The consideration of spatially heterogeneous traffic density scenario is still in progress.

3.2 Complex model [in progress]

Given many real-world factors in traffic are not considered in the basic model, we expect the performance of the simple model to simulate the traffic data is poor. As a result, our second model would be a non-linear model that incorporates several effects, such as traffic light, intersection, etc. We haven't figured out what type of non-linear model would be best to fit in this section. We will work on the development of the complex model after literature review and further group discussions. Same as the first model, after the implementation, the validity of the model would be tested on the real traffic data to see if the fitting performance is improved. It is expected that parameter tuning would be involved.

Reference

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