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----- FAST INPUT FILE -----
NREL 5.0 MW Baseline Wind Turbine for Use in Offshore Analysis.
Properties from Dutch Offshore Wind Energy Converter (DOWEC) 6MW Pre-Design
(10046 009.pdf) and REpower 5M 5MW (5m uk.pdf); Compatible with FAST v6.0.
- Echo input data to "echo.out" (flag)
False
           Echo
   1
           ADAMSPrep - ADAMS preprocessor mode {1: Run FAST, 2: use FAST as a
preprocessor to create an ADAMS model, 3: do both} (switch)
           AnalMode
                      - Analysis mode {1: Run a time-marching simulation, 2: create
a periodic linearized model (switch)
           NumBl - Number of blades (-)
  3
 600.0
                       - Total run time (s)
           TMax
 0.0125
           \mathtt{DT}
                       - Integration time step (s)
 ----- TURBINE CONTROL ------
                    - Yaw control mode {0: none, 1: user-defined from routine
           YCMode
UserYawCont, 2: user-defined from Simulink} (switch)
                       - Time to enable active yaw control (s) [unused when YCMode=0]
9999.9
           TYCOn
  2
           PCMode
                       - Pitch control mode {0: none, 1: user-defined from routine
PitchCntrl, 2: user-defined from Simulink} (switch)
                     - Time to enable active pitch control (s) [unused when PCMode=0]
   0.0
           TPCOn
   3
                       - Variable-speed control mode {0: none, 1: simple VS, 2:
           VSContrl
user-defined from routine UserVSCont, 3: user-defined from Simulink} (switch)
           VS RtGnSp - Rated generator speed for simple variable-speed generator
control (HSS side) (rpm) [used only when VSContrl=1]
                      - Rated generator torque/constant generator torque in Region 3
           VS RtTa
for simple variable-speed generator control (HSS side) (N-m) [used only when
VSContrl=1
9999.9
                       - Generator torque constant in Region 2 for simple
           VS Rgn2K
variable-speed generator control (HSS side) (N-m/rpm^2) [used only when VSContrl=1]
                      - Rated generator slip percentage in Region 2 1/2 for simple
9999.9
           VS SlPc
variable-speed generator control (%) [used only when VSContrl=1]
  2
           GenModel
                       - Generator model {1: simple, 2: Thevenin, 3: user-defined
from routine UserGen (switch) [used only when VSContrl=0]
           GenTiStr
                       - Method to start the generator {T: timed using TimGenOn, F:
generator speed using SpdGenOn} (flag)
                       - Method to stop the generator {T: timed using TimGenOf, F:
           GenTiStp
when generator power = 0} (flag)
9999.9
           SpdGen0n
                      - Generator speed to turn on the generator for a startup (HSS
speed) (rpm) [used only when GenTiStr=False]
   0.0
           TimGenOn
                       - Time to turn on the generator for a startup (s) [used only
when GenTiStr=True
9999.9
           TimGenOf
                       - Time to turn off the generator (s) [used only when
GenTiStp=True
                       - HSS brake model {1: simple, 2: user-defined from routine
   1
           HSSBrMode
UserHSSBr (switch)
           THSSBrDp
                       - Time to initiate deployment of the HSS brake (s)
9999.9
9999.9
                       - Time to initiate deployment of the dynamic generator brake
           TiDynBrk
[CURRENTLY IGNORED] (s)
9999.9
           TTpBrDp(1)
                       - Time to initiate deployment of tip brake 1 (s)
9999.9
           TTpBrDp(2)
                       - Time to initiate deployment of tip brake 2 (s)
9999.9
           TTpBrDp(3)
                       - Time to initiate deployment of tip brake 3 (s) [unused for 2
blades]
           TBDepISp(1) - Deployment-initiation speed for the tip brake on blade 1
9999.9
(rpm)
9999.9
           TBDepISp(2) - Deployment-initiation speed for the tip brake on blade 2
(rpm)
9999.9
           TBDepISp(3) - Deployment-initiation speed for the tip brake on blade 3
(rpm) [unused for 2 blades]
9999.9
           TYawManS
                      - Time to start override yaw maneuver and end standard yaw
control (s)
```