

1 Helder-Mead Simplex Method (Section 11.5)

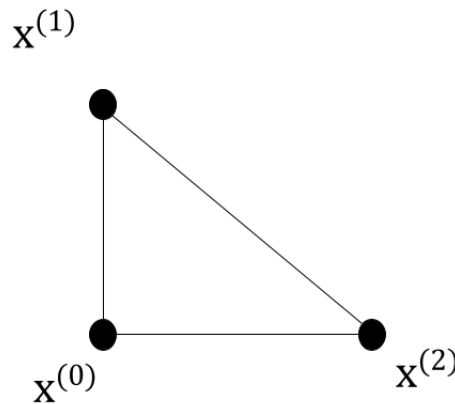
As usual, our goal is to minimize a function $f(x) : \mathbb{R}^n \rightarrow \mathbb{R}$. This method is a direct search method, but does not require a derivative of the function f and doesn't make use of any line searches. This method is versatile, but may be restricted to smaller problems¹.

Before beginning the calculations, we assign values to three parameters, $\alpha = 1$, $\beta = \frac{1}{2}$, and $\gamma = 1$. The values described here are the default values. In each step of this method, we'll have a set of $n + 1$ points $x^{(i)} \in \mathbb{R}^n$,

$$\{x^{(0)}, x^{(1)}, \dots, x^{(n)}\}.$$

Note that the set should be in general position in \mathbb{R}^n ; that is, the set of n points $x^{(i)} - x^{(0)}$ for $1 \leq i \leq n$ is linearly independent.

(Example.) Suppose we're in \mathbb{R}^2 . We have three points in our set, $x^{(0)} \in \mathbb{R}^2$, $x^{(1)} \in \mathbb{R}^2$, and $x^{(2)} \in \mathbb{R}^2$. This gives us



Here, we can consider $x^{(1)}$ and $x^{(2)}$ to be linearly independent, and $x^{(0)}$ is at the origin. By connecting these points with a border, we create a convex hull with the set of points. This convex hull represents a simplex.

We want to reorder/relabel the points so that

$$f(x^{(0)}) \geq f(x^{(1)}) \geq \dots \geq f(x^{(n)}).$$

1.1 Operations on the Search Space

Based on the ordering, the search space will be modified in order to find the desirable points. As one might expect, $f(x^{(0)})$ is the worst and $f(x^{(n)})$ is the best. Some operations to explore the search space include

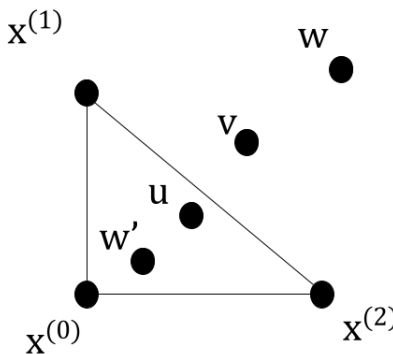
- **Centroid:** $u = \frac{1}{n} \sum_{i=1}^n x^{(i)}$. This is the centroid of the face of the current simplex opposite the worst vertex, $x^{(0)}$.
- **Reflection:** $v = (1 + \alpha)u - \alpha x^{(0)}$.
- **Expansion:** $w = (1 + \gamma)v - \gamma u$. This checks if v was improving the best function value, whether w would improve it even more.
- **Reduction:** $w' = \beta x^{(0)} + (1 - \beta)u$.

¹In other words, for a small n .

(Example.) If we have $x^{(0)} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, $x^{(1)} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, and $x^{(2)} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, then we know $n = 2$ and

$$u = \frac{1}{n} \sum_{i=1}^n x^{(i)} = \frac{1}{2} \sum_{i=1}^2 x^{(i)} = \frac{1}{2} \left(\begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

Roughly speaking, these operations look like



In particular, part of the check we need to do is whether $f(v) < f(x^{(n)})$. If this is the case, we can compute w (the expansion) and see whether this expansion is further beneficial. In particular, we want to see if $f(w) < f(x^{(n)})$; if this is the case, then we can set $x^{(0)} \leftarrow w$ and $f(x^{(0)}) \leftarrow f(w)$. Otherwise, we can set $x^{(0)} \leftarrow v$ and $f(x^{(0)}) \leftarrow f(v)$.

1.2 Desirable Stopping Condition

A desirable stopping condition is the **relative flatness**; that is,

$$\frac{f(x^{(0)}) - f(x^{(n)})}{\max\{|f(x^{(0)})| + |f(x^{(n)})|, 1\}}.$$

Note that we have the maximum condition in the denominator to avoid dividing by 0. So, we would stop if the “relative flatness” is sufficiently small enough.

1.3 Algorithm

The implementation we’ll use does not reorder all the functions, as this is an expensive process (sorting in general is expensive). Instead, we only swap the relative indices. With this said, our function takes the following inputs:

- f , the function to evaluate.
- $\{x^{(0)}, x^{(1)}, \dots, x^{(n)}\}$, the set of candidate points.
- ϵ , the tolerance.
- M , the maximum number of iterations.
- α, β, γ , the three parameters mentioned earlier.

Algorithm 1 Helder-Mead Simplex Method

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1: function HELDERMEADSIMPLEX( $f, \{x^{(i)}\}, \epsilon, M, \alpha, \beta, \gamma$ )
2:   for  $i \leftarrow 1$  to  $n + 1$  do           ▷ Corresponds to constructing simplex by defining values at each vertex.
3:      $F(i) = f(x^{(i-1)})$                  ▷  $F$  is the vector of all function values.
4:      $X(:, i) = x^{(i-1)}$                  ▷ Storing the points into the matrix.
5:   end for
6:    $(f_n, i_n) = \min(F)$ 
7:    $(f_0, f_1, i_0, i_1) = \max_2(F)$ 
8:    $o \leftarrow [1]_{n \times 1}$                  ▷  $n \times 1$  vector of 1's.
9:    $k \leftarrow 0$ 
10:  while  $(f_0 - f_n) / (\max\{|f_0| + |f_1|\}) \geq \epsilon$  and  $k < M$  do
11:     $u \leftarrow \frac{1}{n} \sum_{\ell=1}^n x^{(\ell)}$ 
12:     $v \leftarrow (1 + \alpha)u - \alpha X(:, i_0)$ 
13:     $f_v = f(v)$ 
14:    if  $f_v < f_n$  then
15:       $w \leftarrow (1 + \gamma)v - \gamma u$ 
16:       $f_w \leftarrow f(w)$ 
17:      if  $f_w < f_n$  then
18:         $X(:, i_0) \leftarrow w$ 
19:         $f_0 \leftarrow f_w$ 
20:      else
21:         $X(:, i_0) \leftarrow v$ 
22:         $f_0 \leftarrow f_v$ 
23:      end if
24:    else
25:      if  $f_v \leq f_1$  then
26:         $X(:, i_0) \leftarrow v$ 
27:         $f_0 \leftarrow f_v$ 
28:      else
29:         $b \leftarrow f_0$ 
30:        if  $f_v \leq f_0$  then
31:           $X(:, i_0) \leftarrow v$ 
32:           $f_0 \leftarrow f_v$ 
33:        end if
34:         $w \leftarrow \beta X(:, i_0) + (1 - \beta)u$ 
35:         $f_w \leftarrow f(w)$ 
36:        if  $f_w \leq b$  then
37:           $X(:, i_0) \leftarrow w$ 
38:           $f_0 \leftarrow f_w$ 
39:        else
40:          for  $i \leftarrow 1$  to  $n + 1$  do
41:            if  $i \neq i_n$  then
42:               $X(:, i) \leftarrow \frac{1}{2}(X(:, i) + X(i, i_n))$ 
43:               $F(i) \leftarrow f(X(:, i))$ 
44:            break
45:          end if
46:        end for
47:      end if
48:    end if
49:  end while
50:   $(f_n, i_n) \leftarrow \min(F)$ 
51:   $(f_0, f_1, i_0, f_1) \leftarrow \max_2(F)$ 
52:   $k \leftarrow k + 1$ 
53: end function

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A few notes:

- In line 6, we're computing the index of the minimum point. So, f_n is the smallest function value and i_n is minimum index of said function value.
- In line 7, we're finding the two largest function values f_0, f_1 and the corresponding indices i_0, i_1 . Here, \max_k means to find the k highest elements.