

# 1 The Power Method (5.3)

Let  $A \in \mathbb{C}^{n \times n}$ , and assume that  $A$  is semisimple. Let  $\lambda_1, \lambda_2, \dots, \lambda_n$  denote the eigenvalues associated with  $v_1, \dots, v_n$ , respectively. Assume that the vectors are ordered so that  $|\lambda_1| \geq |\lambda_2| \geq \dots \geq |\lambda_n|$ . If  $|\lambda_1| > |\lambda_2|$ , then  $\lambda_1$  is called the **dominant eigenvalue**<sup>1</sup> and  $v_1$  is called the **dominant eigenvector** of  $A$ .

## 1.1 The Iterative Power Method

Assuming we have  $|\lambda_1| > |\lambda_2|$  as described above (otherwise, this method may not work), the general idea behind the iterative power method is that we can pick  $q \in \mathbb{R}^n$  randomly. Then, we can form the sequence of vectors

$$q, Aq, A^2q, A^3q, \dots$$

To calculate this sequence, we don't necessarily need to form the powers of  $A$  explicitly. Each vector in the sequence can be obtained by multiplying the previous vector by  $A$ , e.g.,  $A^{j+1}q = A(A^j q)$ . It's easy to show that the sequence converge, in a sense, to a dominant eigenvector, for almost all choices of  $q$ . Since  $v_1, \dots, v_n$  form a basis for  $\mathbb{C}^n$ , there exists constants  $c_1, \dots, c_n$  such that

$$q = c_1 v_1 + c_2 v_2 + \dots + c_n v_n.$$

We don't know what  $v_1, \dots, v_n$  are, so we don't know what  $c_1, \dots, c_n$  are, either. However, it's clear that, for any choice of  $q$ ,  $c_1$  will be nonzero. The argument that follows is valid for every  $q$  for which  $c_1 \neq 0$ ; multiplying by  $A$ , we have

$$\begin{aligned} Aq &= c_1 A v_1 + c_2 A v_2 + \dots + c_n A v_n \\ &= c_1 \lambda_1 v_1 + c_2 \lambda_2 v_2 + \dots + c_n \lambda_n v_n. \end{aligned}$$

Similarly,

$$\begin{aligned} A^2 q &= A(c_1 \lambda_1 v_1 + c_2 \lambda_2 v_2 + \dots + c_n \lambda_n v_n) \\ &= c_1 \lambda_1 (A v_1) + c_2 \lambda_2 (A v_2) + \dots + c_n \lambda_n (A v_n) \\ &= c_1 \lambda_1 (\lambda_1 v_1) + c_2 \lambda_2 (\lambda_2 v_2) + \dots + c_n \lambda_n (\lambda_n v_n) \\ &= c_1 \lambda_1^2 v_1 + c_2 \lambda_2^2 v_2 + \dots + c_n \lambda_n^2 v_n. \end{aligned}$$

In general, we have

$$\begin{aligned} A^j q &= c_1 \lambda_1^j v_1 + c_2 \lambda_2^j v_2 + \dots + c_n \lambda_n^j v_n \\ &= \lambda_1^j \left( c_1 v_1 + c_2 \left( \frac{\lambda_2}{\lambda_1} \right)^j v_2 + \dots + c_n \left( \frac{\lambda_n}{\lambda_1} \right)^j v_n \right). \end{aligned}$$

In particular, we have

$$\frac{1}{\lambda_1^j} A^j q = c_1 v_1 + c_2 \left( \frac{\lambda_2}{\lambda_1} \right)^j v_2 + \dots + c_n \left( \frac{\lambda_n}{\lambda_1} \right)^j v_n.$$

Notice that  $\lim_{j \rightarrow \infty} \left( \frac{\lambda_i}{\lambda_1} \right)^j = 0$ , so

$$\lim_{j \rightarrow \infty} \frac{1}{\lambda_1^j} A^j q = c_1 v_1,$$

the dominant eigenvector.

**Remark:** This only works if  $\lambda_1$  is known.

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<sup>1</sup>Basically, the largest absolute eigenvalue.