

1 Turing Machines (3.1)

First proposed by Alan Turing in 1936, the **Turing machine** is a much more accurate model of a general purpose computer. It can do everything that a real computer can do, but even it cannot solve certain problems¹.

1.1 The Idea

- The input string is *written* on the leftmost squares of the tape. The rest of the tape is empty.
- We can read *and* write on the tape. The read/write head starts at the leftmost position on the tape.
- Computation proceeds according to the transition function. In other words, given the current state of machine, and the current symbol being read, the machine will
 - Transition to a new state.
 - Write a symbol to its current position, overwriting the existing symbol.
 - Moves the tape head *L* or *R*.
- Computation ends if and when it enters either the **accept** or the **reject** state. This means that we can have programs that can run forever.

1.2 Language of a Turing Machine

Given a Turing machine M , the language $L(M)$ is the set of all strings w such that the computation of M on w *halts* after entering the accept state. That is, $L(M) = \{w \mid w \text{ is accepted by } M\}$.

1.3 Formal Definition

As usual, the most important thing about the Turing machine is the transition function

$$\delta : Q \times \Gamma \mapsto Q \times \Gamma \times \{L, R\}$$

That is, when the machine is in a certain state q and the head is over a tape square containing the symbol a , and if $\delta(q, a) = (r, b, L)$, then the machine writes the symbol b replacing the a , and goes to state r . The third component is either L or R , and indicates whether the head moves to the left or right after writing. In this case, the L indicates that we move the tape to the left.

Definition 1.1: Turing Machine

A **Turing machine** is a 7-tuple $(Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}})$ where Q, Σ, Γ are all finite sets and

1. Q is the set of states.
2. Σ is the input alphabet not containing the *blank symbol* \sqcup .
3. Γ is the tape alphabet, where $\sqcup \in \Gamma$ and $\Sigma \subseteq \Gamma$.
4. $\delta : Q \times \Gamma \mapsto Q \times \Gamma \times \{L, R\}$ is the transition function.
5. $q_0 \in Q$ is the start state.
6. $q_{\text{accept}} \in Q$ is the accept state.
7. $q_{\text{reject}} \in Q$ is the reject state, where $q_{\text{reject}} \neq q_{\text{accept}}$.

¹In a very real sense, these problems are beyond the theoretical limits of computation.

1.4 Configuration of a Turing Machine

As a Turing machine computes, changes occur in the current state, the current tape contents, and the current head location. A setting of these three items is called a **configuration** of the Turing machine. They are often represented in a special way. For a state q and two strings u and v over the tape alphabet Γ , we write uqv for the configuration where the current state is q , the current tape contents is uv , and the current head location is the first symbol of v .

For example, $1011q_701111$ represents the configuration when the tape is 101101111 , the current state is q_7 , and the head is currently on the second 0.

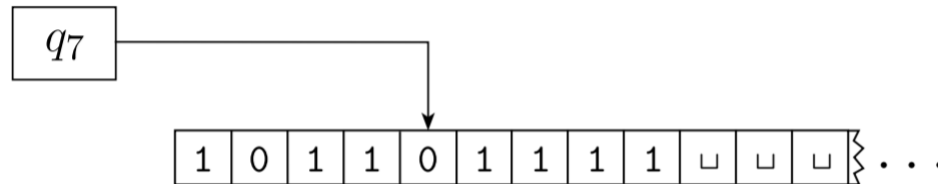


Figure: The configuration $1011q_701111$.

1.4.1 Transitioning Between Configurations

Suppose that a configuration C_1 **yields** configuration C_2 if the Turing machine can legally go from C_1 to C_2 in a single step. We can define this notion formally as follows: suppose we have $a, b, c \in \Gamma$, as well as $u, v \in \Gamma^*$ and states $q_i, q_j \in Q$. In that case, $uaq_i bv$ and $uq_j acv$ are two arbitrary configurations. Say that

$$uaq_i bv \text{ yields } uq_j acv$$

if, in the transition function, $\delta(q_i, b) = (q_j, c, L)$. This handles the case where the Turing machine moves leftward. For a rightward move, say that

$$uaq_i bv \text{ yields } uacq_j v$$

if, in the transition function, $\delta(q_i, b) = (q_j, c, R)$.

1.4.2 Start, Accepting, Rejecting, and Halting Configurations

The start configuration of M on input w is the configuration $q_0 w$, which indicates that the machine is in the start state q_0 with its head at the leftmost position on the tape.

In an accepting configuration, the state of the configuration is q_{accept} .

In a rejecting configuration, the state of the configuration is q_{reject} .

Accepting and rejecting configurations are halting configurations and do not yield further configurations.

1.5 Deciders and Recognizers

We now briefly talk about the difference between deciders and recognizers.

1.5.1 Turing-Recognizable

A language is **Turing-recognizable** if some Turing machine recognizes it, i.e. if $L = L(M)$ for some Turing machine M . When we start a Turing machine on some input, the machine can either *accept*, *reject*, or *loop*. However, sometimes we don't want the machine to loop.

1.5.2 Turing-Decider

A Turing machine M is a **decider** Turing machine (either Turing-decidable or decidable) if it halts on all inputs (i.e. never loops).

L is **Turing-decidable** if some Turing machine that is a decider recognizes it.

1.5.3 Example 1: Turing Machine

Consider the language $L = \{w\#w \mid w \in \{0,1\}^*\}$, which is both not regular and not context-free.

1. Give an idea for a potential Turing machine that recognizes L .

The idea is as follows

- We want to zig-zag across tapes to corresponding positions on either side of $\#$ to check whether these positions agree. If they do not, or there is no $\#$, then we reject. If they do, then cross them off.
- Once all symbols to the left of the $\#$ are crossed off, check for any symbols to the right of $\#$. If there are any, *reject*. Otherwise, accept.

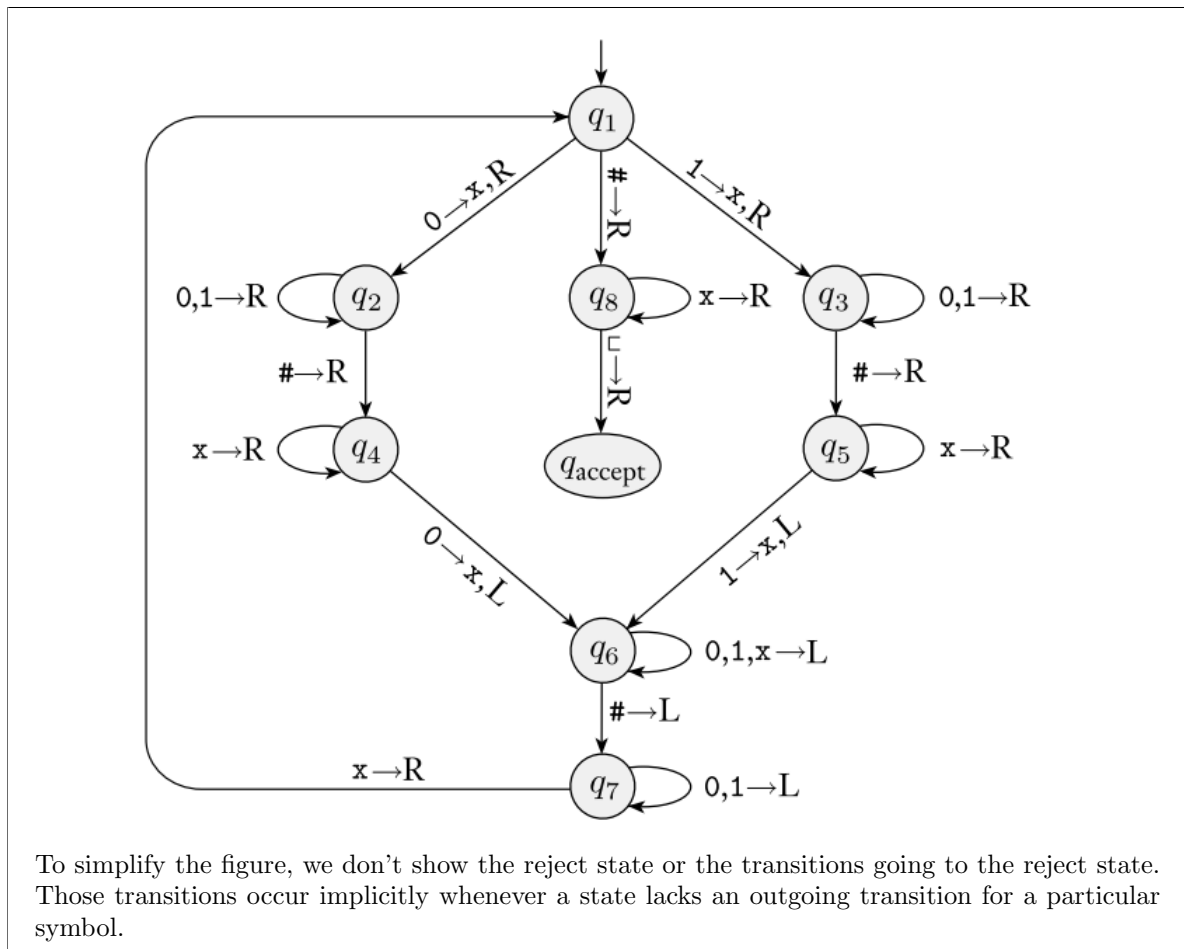
To see what we mean, consider the following example

```
0 1 # 0 1
-> x 1 # 0 1
-> x 1 # x 1
-> x x # x 1
-> x x # x x
```

2. Is this machine a decider?

Yes, because it will halt (either accept or reject) no matter what the input is.

3. Draw the state diagram corresponding to the Turing machine.



4. What is Q (the set of states)?

$$Q = \{q_1, \dots, q_8, q_{\text{accept}}, q_{\text{reject}}\}$$

5. What is Σ ?

$$\Sigma = \{0, 1, \#\}$$

6. What is Γ ?

$$\Gamma = \Sigma \cup \{b, x\}$$

7. Given the string 01#01, run through the Turing machine.

We begin with the initial configuration.

State:	q1
Tape:	0 1 # 0 1
(Next:)	^
Config:	q1 0 1 # 0 1

Here, we read in the 0 and move to q_2 , replacing 0 with x and moving the tape to the right.

```

State:      q2
Tape:       x 1 # 0 1
  (Next:)   ^
Config:     x q2 1 # 0 1

```

At this point, we read in the 1 as well (without crossing anything out) and move the tape to the right.

```

State:      q2
Tape:       x 1 # 0 1
  (Next:)   ^
Config:     x 1 q2 # 0 1

```

For the same reason as above, we read in # as well, transitioning to q_4 and moving the tape to the right.

```

State:      q4
Tape:       x 1 # 0 1
  (Next:)   ^
Config:     x 1 # q4 0 1

```

Now, we read in the 0, replacing it with a x and moving the tape left. We also transition to q_6 .

```

State:      q6
Tape:       x 1 # x 1
  (Next:)   ^
Config:     x 1 q6 # x 1

```

We read in the #, moving the tape to the left and transitioning to q_7 .

```

State:      q7
Tape:       x 1 # x 1
  (Next:)   ^
Config:     x q7 1 # x 1

```

We now keep looping at q_7 whenever we see a 0 or 1. In our case, we only need to read one 1, so we do that, while also moving the tape to the left.

```

State:      q7
Tape:       x 1 # x 1
  (Next:)   ^
Config:     q7 x 1 # x 1

```

We now read in the x and transition to q_1 , moving the tape to the right.

```

State:      q1
Tape:       x 1 # x 1
  (Next:)   ^
Config:     x q1 1 # x 1

```

Now, we transition to q_3 , reading in the 1 and replacing it with an x while also moving the tape to the right.

```

State:      q3
Tape:       x x # x 1
  (Next:)   ^
Config:     x x q3 # x 1

```

We now read in the #, moving the tape to the right and transitioning to q_5 .

```

State:      q5
Tape:       x x # x 1
  (Next:)   ^
Config:     x x # q5 x 1

```

We now read in all of the x's, moving the tape to the right. We only do this once as there is only one x to be read.

```

State:      q5
Tape:       x x # x 1
  (Next:)   ^
Config:     x x # x q5 1

```

We now read in a 1, replacing it with a x, transitioning to q_6 , and moving the tape to the left.

```

State:      q6
Tape:       x x # x x
  (Next:)   ^
Config:     x x # q6 x x

```

At q_6 , we keep reading in the x's. We only do this once, so we move the tape one to the left.

```

State:      q6
Tape:       x x # x x
  (Next:)   ^
Config:     x x q6 # x x

```

Now, we transition to q_7 since the next symbol is #, moving the tape to the left.

```

State:      q7
Tape:       x x # x x
  (Next:)   ^
Config:     x q7 x # x x

```

We transition to q_1 , moving the tape to the right.

```

State:      q1
Tape:       x x # x x
  (Next:)   ^
Config:     x x q1 # x x

```

Since the next symbol to be read is a #, we transition to q_8 , moving the tape to the right.

```

State:      q8
Tape:       x x # x x
  (Next:)   ^
Config:     x x # q8 x x

```

We now keep reading in any x's, moving the tape to the right. This is done twice.

```

State:      q8
Tape:       x x # x x
  (Next:)   ^
Config:     x x # x x q8

```

At this point, we are implicitly at a \sqcup . So, we move to q_{accept} . Thus, this string is accepted.