

1 Divided Differences (Section 6.2)

We'll begin by briefly reviewing Newton's Form from the previous section. Recall the coefficients in the Newton form of interpolating polynomial, $P(x)$, where $f(x)$ is interpolated by $P(x)$, is c_i . Then,

$$P(x_i) = \underbrace{f(x_i)}_{\text{Data}} \quad 0 \leq i \leq m.$$

Newton's Form looks like

$$P(x) = c_0 + c_1(x - x_0) + c_2(x - x_0)(x - x_1) + \dots + c_m(x - x_0)(x - x_1) \dots (x - x_{m-1}).$$

Then,

$$\begin{aligned} P(x_0) &= f(x_0) = c_0 \\ P(x_1) &= f(x_1) = c_0 + c_1(x_1 - x_0) \\ P(x_2) &= f(x_2) = c_0 + c_1(x_2 - x_0) + c_2(x_2 - x_0)(x_2 - x_1) \end{aligned} \tag{1}$$

We can represent (1) as a system of equations, modeled using matrices, like so:

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & (x_1 - x_0) & 0 \\ 1 & (x_2 - x_0) & (x_2 - x_0)(x_2 - x_1) \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} f(x_0) \\ f(x_1) \\ f(x_2) \end{bmatrix}.$$

This is a triangular system. We can represent the c_i 's in terms of the $f(x_i)$'s. Thus, the **divided difference** is defined by

$$f[x_0, x_1, x_2, \dots, x_m] \equiv c_m. \tag{2}$$

We say that $f[x_0, x_1, x_2, \dots, x_m]$ is the coefficient of x^m in the polynomial of degree at most n that interpolates f at x_0, x_1, \dots, x_n . With this in mind, some explicit formulas include

- if $m = 0$, then $c_0 = f[x_0] = f(x_0)$.
- if $m = 1$, then $c_1 = f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$.

Thus, the Newton interpolating form can be rewritten as

$$P(x) = \sum_{k=0}^m f[x_0, x_1, x_2, \dots, x_k] \prod_{j=0}^{k-1} (x - x_j).$$

1.1 Higher Order Differences

Theorem 1.1: Divided Difference

Divided differences satisfy the equation,

$$f[x_0, x_1, \dots, x_m] = \frac{f[x_1, x_2, \dots, x_m] - f[x_0, x_1, \dots, x_{m-1}]}{x_m - x_0}.$$

Proof. Let $P_k(x)$ be a polynomial of degree at most k interpolating x_0, x_1, \dots, x_k . Further, let $Q_k(x)$ be a polynomial of degree at most $m-1$ interpolating x_1, x_2, \dots, x_m . Then, we have $P_k(x_i) = f(x_i)$ for $0 \leq i \leq k$ and $q(x_i) = f(x_i)$ for $1 \leq i \leq m$. So,

$$P_m(x) = q(x) + \frac{(x - x_m)}{x_m - x_0} (q(x) - P_{m-1}(x)).$$

We can verify that any data point we substitute in will satisfy the above equation. In any case, the left- and right-hand sides match at x_0, x_1, \dots, x_m . Then, the coefficients on the left- and right- for x^m are

$$f[x_0, x_1, \dots, x_m] = \frac{f[x_1, x_2, \dots, x_m] - f[x_0, x_1, \dots, x_{m-1}]}{x_m - x_0},$$

as desired. □

So, with this formula, if we were to consider $m = 0$, then

$$f[x_0] = f(x_0).$$

Likewise, if we consider $m = 1$, we have

$$f[x_0, x_1] = \frac{f[x_1] - f[x_0]}{x_1 - x_0}.$$

Finally, for $m = 3$, we have

$$f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0}.$$

The recursive relation is given by

$$f[x_i, x_{i+1}, x_{i+2}, \dots, x_{i+j}] = \frac{f[x_{i+1}, x_{i+2}, \dots, x_{i+j}] - f[x_i, x_{i+1}, \dots, x_{i+j-1}]}{x_{i+j} - x_i}. \quad (3)$$

We can describe this recursive relation in terms of a table. For a table of function values $(x_i, f(x_i))$,

	0	1	2	3
x_0	$f(x_0)$	$f[x_0, x_1]$	$f[x_0, x_1, x_2]$	$f[x_0, x_1, x_2, x_3]$
x_1	$f(x_1)$	$f[x_1, x_2]$	$f[x_1, x_2, x_3]$	
x_2	$f(x_2)$	$f[x_2, x_3]$		
x_3	$f(x_3)$			

Note that $f(x_i) = f[x_i]$. So, the top row of the table corresponds to the coefficients in Newton's form. Each column represents the difference of orders. The recursive relationship is given by

	0	1	2	3
x_0	$f(x_0)$	$f[x_0, x_1]$	$f[x_0, x_1, x_2]$	$f[x_0, x_1, x_2, x_3]$
x_1	$f(x_1)$	$f[x_1, x_2]$	$f[x_1, x_2, x_3]$	
x_2	$f(x_2)$	$f[x_2, x_3]$		
x_3	$f(x_3)$			

For example, the calculation of $f[x_1, x_2, x_3]$ depends on the result of $f[x_1, x_2]$ and $f[x_2, x_3]$; to see why, from (3), note that

$$f[x_1, x_2, x_3] = \frac{f[x_2, x_3] - f[x_1, x_2]}{x_3 - x_1}.$$

(Exercise.) Given the set of points,

x	3	1	5	6
$f(x)$	1	-3	2	4

Compute a divided difference table for these function values.

We have the table

x_i	$f(x_i)$			
3	1	$f[x_0, x_1]$	$f[x_0, x_1, x_2]$	$f[x_0, x_1, x_2, x_3]$
1	-3	$f[x_1, x_2]$	$f[x_1, x_2, x_3]$	
5	2	$f[x_2, x_3]$		
6	4			

Using the table above, we find that,

- for the first column, i.e., $f[x_i, x_j]$,

$$f[x_0, x_1] = \frac{f[x_1] - f[x_0]}{x_1 - x_0} = \frac{f(x_1) - f(x_0)}{x_1 - x_0} = \frac{-3 - 1}{1 - 3} = \frac{-4}{-2} = 2.$$

$$f[x_1, x_2] = \frac{f[x_2] - f[x_1]}{x_2 - x_1} = \frac{f(x_2) - f(x_1)}{x_2 - x_1} = \frac{2 - (-3)}{5 - 1} = \frac{5}{4}.$$

$$f[x_2, x_3] = \frac{f[x_3] - f[x_2]}{x_3 - x_2} = \frac{f(x_3) - f(x_2)}{x_3 - x_2} = \frac{4 - 2}{6 - 5} = \frac{2}{1} = 2.$$

- for the second column, i.e., $f[x_i, x_j, x_k]$,

$$f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0} = \frac{\frac{5}{4} - 2}{5 - 3} = -\frac{3}{8}.$$

$$f[x_1, x_2, x_3] = \frac{f[x_2, x_3] - f[x_1, x_2]}{x_3 - x_1} = \frac{2 - \frac{5}{4}}{6 - 1} = \frac{3}{20}.$$

- for the third column, i.e., $f[x_i, x_j, x_k, x_\ell]$,

$$f[x_0, x_1, x_2, x_3] = \frac{f[x_1, x_2, x_3] - f[x_0, x_1, x_2]}{x_3 - x_0} = \frac{\frac{3}{20} - (-\frac{3}{8})}{6 - 3} = \frac{7}{40}.$$

Therefore, the divided difference table looks like

x_i	$f(x_i)$			
3	1	2	$-\frac{3}{8}$	$\frac{7}{40}$
1	-3	$\frac{5}{4}$	$\frac{3}{20}$	
5	2	2		
6	4			

Recall that the top row of the table corresponds to the coefficients in Newton's form, so we find that the interpolating polynomial $P(x)$ is

$$\begin{aligned} P(x) &= c_0 + c_1(x - x_0) + c_2(x - x_0)(x - x_1) + c_3(x - x_0)(x - x_1)(x - x_2) \\ &= 1 + 2(x - 3) - \frac{3}{8}(x - 3)(x - 1) + \frac{7}{40}(x - 3)(x - 1)(x - 5) \end{aligned}$$