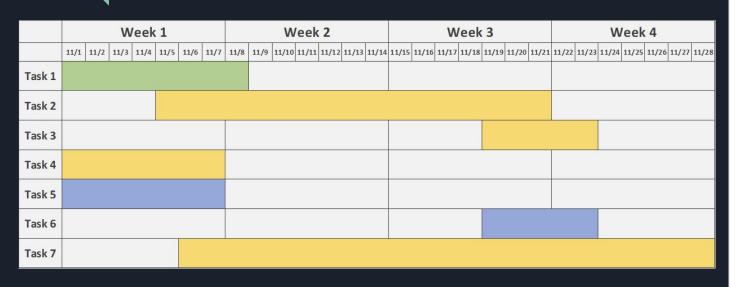
Project 3: Face Detection, Tracking, and Recognition Plan

Group 6: Eric Watson & Hansi Zheng

Key Tasks

- 1) Train the YOLOv5S Model [1] such that it can detect faces (from front/side).
 - a. Record accuracy score of face detection from training
 - b. Record accuracy based on distance from camera
- 2) Implement a system so it simultaneously detects, tracks [2] and recognizes [3] two different faces (Eric & Hansi).
- 3) Design a live demo so the system output can be captured on Zoom.
- 4) Determine the full field of view of the camera, and the angular resolution.
- 5) Determine the farthest distance from camera that the system can accurately operate.
- 6) Record the power, temperature, and resource utilization of the system during operation.
- 7) Work on presentation results.

Schedule & Roles



<u>Tasks</u>

- 1. Train YOLOv5 Model on Face
- Implement a system for detection, tracking, recognition
- 3. Design live demo for Zoom
- 4. Determine camera FOV and angular resolution
- 5. Determine max distance from camera for system operation
- 6. Record system resource usage
- 7. Work on final presentation

<u>Roles</u>

Blue - Hansi

Green - Eric

Yellow - Both

References

1) YOLOv5 Library

https://github.com/ultralytics/yolov5

2) YOLOv5 + DeepSort

https://github.com/mikel-brostrom/Yolov5 DeepSort Pytorch

3) Face Recognition

https://github.com/ageitgey/face_recognition