

# Project report – Calcul scientifique

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## 1 Limitations of the power method

We test with matrices of the following shapes

$$1 \quad \begin{pmatrix} 1 & & & (0) \\ & 2 & & \\ & & 3 & \\ & & & \ddots \\ (0) & & & & n \end{pmatrix}$$

$$2 \quad \text{diag}(\text{random}(1e-10, 1))$$

$$3 \quad \text{diag}\left((10^5)^{-\frac{i-1}{n-1}}\right)_{i \in \llbracket 1, n \rrbracket}$$

$$4 \quad \text{diag}\left(1 - (1 - 10^{-2})^{\frac{i-1}{n-1}}\right)_{i \in \llbracket 1, n \rrbracket}$$

Type / Alg	1	2	3	4
<b>eig</b> (10)	20 ms	0 ms	10 ms	10 ms
<b>power</b> (11)	1.77 s	40 ms	60 ms	1.81 s
<b>power</b> (12)	0.9 s	60 ms	60 ms	0.93 s

Table 1: Computation time comparisons

### 1.1 Main computing time drawback of the improved deflation method

**power\_v12** is slower than **power\_v11** on matrices of type **2** (diagonal matrices of random floating point values close to zero). It *is* twice as fast on matrices of type **1** or **4**.

## 2 Extending the power method to compute dominant eigenspace vectors

### 2.1 **subspace\_iter\_v0** : *a basic method to compute a dominant eigenspace*

Without orthonormalisation to force the vectors to evolve to different values during the iteration, there is a large chance that all output eigenvectors will be copies of one of the eigenvectors.

#### 2.1.1 Rayleigh quotient

The size of  $H$  is one order of magnitude less than  $A$ . Therefore, computing the spectral decomposition of  $H$  is much less intensive than computing that of  $A$ 's.

## 2.2 v1: improved version making use of Raleigh-Ritz projection

### 2.2.1 Convergence analysis step

Table 2: Steps of Algorithm 4

Step	Code
Generate an initial set of $m$ orthogonal vectors	48-49
$k = 0$	38
PercentReached = 0	40
$k = k + 1$ 54	
Compute $Y$ such that $Y = A \cdot V$	56
Vorthonormalization of the columns of $Y$	58
Rayleigh-Ritz project applied on matrix $A$ and $V$	61
Convergence analysis	64-112

## 3 v2 and v3: towards an efficient solver

### 3.1 Block approach

**Question 8** Let  $n$  be the size of  $A$  (such that  $A \in_{n,n}()$ ). Computing  $A^2$  takes  $n^2(2n-1)$  flops. Therefore, the computation is

$$pn^2(2n-1) \text{ flops}$$

We have  $V \in_{n,m}()$ , therefore, computing  $A^p \cdot V$  takes

$$pn^2(2n-1) + nm(2n-1) = (2n-1)n(pn+m) \text{ flops}$$

By computing  $A \cdot V$  first, then pre-multiplying the resulting *vector* by  $A$   $p-1$  times, most of the matrix products will be with a vector instead of between two matrices:

The cost is then

$$nm(2n-1) + (p-1)nm(2n-1) = pm(2n-1) \text{ flops}$$

Table 3: Performance for a range of  $p$  values

$p$	iterations
1	86
10	9
20	5
30	3
50	2
100	2
200	<i>does not converge</i>

**Question 10** By increasing the value of  $p$ , we do less orthonormalizations, and converge quicker to the result.

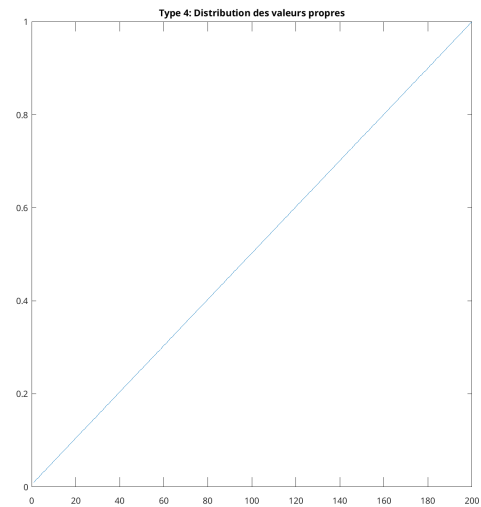
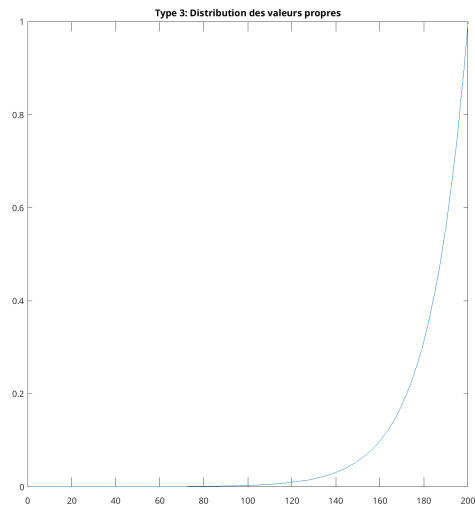
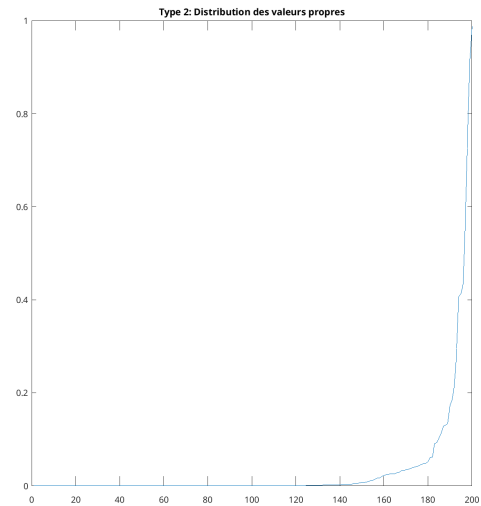
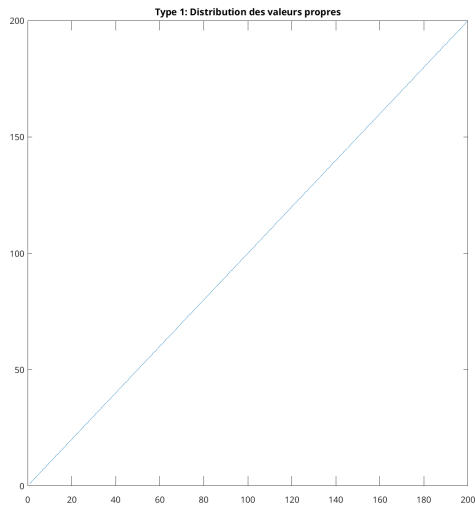
But, similarly to the *learning rate* hyperparameter in neural networks, if we try to converge too quickly, finding a local minimum will never happen and we'll oscillate around, because the steps taken are too big.

**Question 11** We notice that some vectors converge faster to their eigenvector than others, specifically those that have a larger norm and those that are closer to the final guess. That faster convergence will allow for a greater eigenpair quality as the last steps of the convergence will be dedicated

**Question 12** Between `subspace_iter_v1.m` and `subspace_iter_v3.m`, the precision of `subspace_iter_v3.m` will be better because the stopping criterion of `subspace_iter_v3.m` is the same as that of `subspace_iter_v2.m` which was better than that of `subspace_iter_v1.m`. Nevertheless the precision of `subspace_iter_v3.m` is likely to be less good than that of `subspace_iter_v2.m` because vectors are freezer, but by being freezer it will be more towards a better guess

## 4 Numerical Experiments

### 4.1 Question 14



### 4.2 Question 15

Type / Alg	Temps	Nb itérations	Qualité couples propres	Qualité valeurs propres
subspace iteration v0	51s	2689	[3.940e+04 , 1.031e+20]	[9.950e-01 , 1.006e+00]
subspace iteration v1	0.47s	263	[5.752e-14 , 8.534e-08]	[1.670e-14 , 1.408e-13]
subspace iteration v2	0.47s	86	[4.571e-10 , 8.079e-08]	[3.571e-15 , 4.211e-14]
subspace iteration v3	0.73s	86	[1.646e-08 , 8.272e-08]	[1.646e-08 , 8.272e-08]

Table 4: Computation time comparisons