

# **Review for Final – E.K 8/10/21**

## **Data Structures**

**1. Give one advantage of a Linked List, as compared to an array.**

Ans. Linked List has much faster Insert and Remove operations than an Array –  $O(1)$  for Linked List and  $O(n)$  for Arrays.

Another one – Linked List allows more flexible memory management than an Array. It does not require large contiguous memory blocks, and needs no preallocation.

## 2. Data Structures – Hashing 1

Insert the following sequence of numbers 23, 46, 12, 21, 75, 5, 3 into a hash table of size 9 using  $h(x) = x \% 9$  as a hash function. % means Mod. Use Chaining with Linked List to avoid collision.

Ans.

0	1	2	3	4	5	6	7	8
	46		12,21, 75,3		23,5			

3.

Suppose that we store  $n$  keys in a hash table of size  $m = n^2$  using a hash function  $h$  randomly chosen from a universal class of hash functions. Then, the probability is less than  $1/2$  that there are any collisions.

### **3. Data Structures – BST, Red-Back tree and Heaps**

- **Focus more on Red-Black Tree and Heaps**

### **Graphs – Basics, DFS, BFS, MST and Shortest paths**

- **Focus more on DFS / BFS and Shortest paths**
- Sample questions / problems as covered in class and in labs
- More problems from these materials

## Hard Problems

4. Suppose  $A$  and  $B$ , and that  $A \rightarrow B$  ( $A$  is Reduceable to  $B$  in Poly time). Circle one answer for each statement below.

If  $A$  is NP-Complete and  $B$  is in NP then  $B$  is NP-Complete.

True

False

If  $B$  is P then  $A$  is P.

True

False

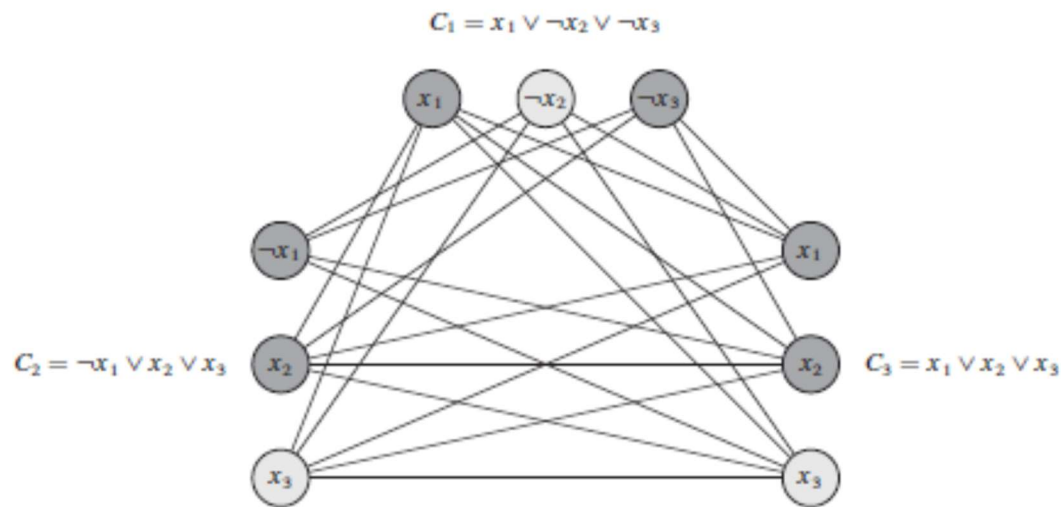
If  $B$  is NP-hard then  $A$  is NP-hard.

True

False

## Reduction -1

5. 3-CNF to Clique - To be done in the Class



**Figure 34.14** The graph  $G$  derived from the 3-CNF formula  $\phi = C_1 \wedge C_2 \wedge C_3$ , where  $C_1 = (x_1 \vee \neg x_2 \vee \neg x_3)$ ,  $C_2 = (\neg x_1 \vee x_2 \vee x_3)$ , and  $C_3 = (x_1 \vee x_2 \vee x_3)$ , in reducing 3-CNF-SAT to CLIQUE. A satisfying assignment of the formula has  $x_2 = 0$ ,  $x_3 = 1$ , and  $x_1$  either 0 or 1. This assignment satisfies  $C_1$  with  $\neg x_2$ , and it satisfies  $C_2$  and  $C_3$  with  $x_3$ , corresponding to the clique with lightly shaded vertices.

Function using 3-CNF is

$$\phi = (x_1 \vee \neg x_2 \vee \neg x_3) \wedge (\neg x_1 \vee x_2 \vee x_3) \wedge (x_1 \vee x_2 \vee x_3)$$

Conditions to form the graph:

- $v_i^r$  and  $v_j^s$  are in different triples, that is,  $r \neq s$ , and
- their corresponding literals are *consistent*, that is,  $l_i^r$  is not the negation of  $l_j^s$ .

Proof:

We must show that this transformation of  $\phi$  into  $G$  is a reduction. First, suppose that  $\phi$  has a satisfying assignment. Then each clause  $C_r$  contains at least one literal  $l_i^r$  that is assigned 1, and each such literal corresponds to a vertex  $v_i^r$ . Picking one such “true” literal from each clause yields a set  $V'$  of  $k$  vertices. We claim that  $V'$  is a clique. For any two vertices  $v_i^r, v_j^s \in V'$ , where  $r \neq s$ , both corresponding literals  $l_i^r$  and  $l_j^s$  map to 1 by the given satisfying assignment, and thus the literals

cannot be complements. Thus, by the construction of  $G$ , the edge  $(v_i^r, v_j^s)$  belongs to  $E$ .

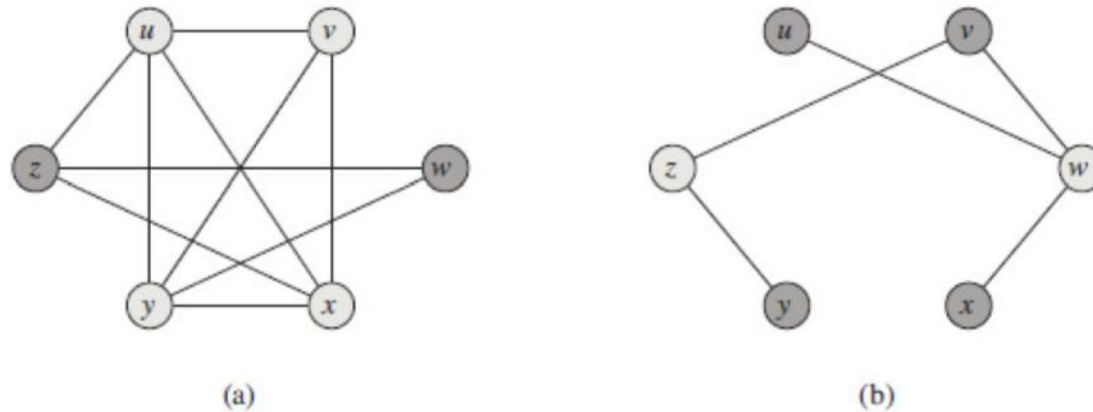
Conversely, suppose that  $G$  has a clique  $V'$  of size  $k$ . No edges in  $G$  connect vertices in the same triple, and so  $V'$  contains exactly one vertex per triple. We can assign 1 to each literal  $l_i^r$  such that  $v_i^r \in V'$  without fear of assigning 1 to both a literal and its complement, since  $G$  contains no edges between inconsistent literals. Each clause is satisfied, and so  $\phi$  is satisfied. (Any variables that do not correspond to a vertex in the clique may be set arbitrarily.) ■

## **Reduction -2**

6. Clique to Vertex Cover - To be done in the Class

(Next Page)

# Clique $\rightarrow$ Vertex Cover



**Figure 34.15** Reducing CLIQUE to VERTEX-COVER. (a) An undirected graph  $G = (V, E)$  with clique  $V' = \{u, v, x, y\}$ . (b) The graph  $\overline{G}$  produced by the reduction algorithm that has vertex cover  $V - V' = \{w, z\}$ .



## Clique $\rightarrow$ Vertex

### Cover: Problem

Suppose that  $G$  has a clique  $V' \subseteq V$  with  $|V'| = k$ . We claim that  $V - V'$  is a vertex cover in  $\overline{G}$ . Let  $(u, v)$  be any edge in  $\overline{E}$ . Then,  $(u, v) \notin E$ , which implies that at least one of  $u$  or  $v$  does not belong to  $V'$ , since every pair of vertices in  $V'$  is connected by an edge of  $E$ . Equivalently, at least one of  $u$  or  $v$  is in  $V - V'$ , which means that edge  $(u, v)$  is covered by  $V - V'$ . Since  $(u, v)$  was chosen arbitrarily from  $\overline{E}$ , every edge of  $\overline{E}$  is covered by a vertex in  $V - V'$ . Hence, the set  $V - V'$ , which has size  $|V| - k$ , forms a vertex cover for  $\overline{G}$ .

## Clique $\rightarrow$ Vertex

### Cover: Solution

Suppose that  $G$  has a clique  $V' \subseteq V$  with  $|V'| = k$ . We claim that  $V - V'$  is a vertex cover in  $\overline{G}$ . Let  $(u, v)$  be any edge in  $\overline{E}$ . Then,  $(u, v) \notin E$ , which implies that at least one of  $u$  or  $v$  does not belong to  $V'$ , since every pair of vertices in  $V'$  is connected by an edge of  $E$ . Equivalently, at least one of  $u$  or  $v$  is in  $V - V'$ , which means that edge  $(u, v)$  is covered by  $V - V'$ . Since  $(u, v)$  was chosen arbitrarily from  $\overline{E}$ , every edge of  $\overline{E}$  is covered by a vertex in  $V - V'$ . Hence, the set  $V - V'$ , which has size  $|V| - k$ , forms a vertex cover for  $\overline{G}$ .

## Clique $\rightarrow$ Vertex

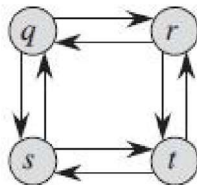
### Cover: Soln. - Converse

Conversely, suppose that  $\bar{G}$  has a vertex cover  $V' \subseteq V$ , where  $|V'| = |V| - k$ . Then, for all  $u, v \in V$ , if  $(u, v) \in \bar{E}$ , then  $u \in V'$  or  $v \in V'$  or both. The contrapositive of this implication is that for all  $u, v \in V$ , if  $u \notin V'$  and  $v \notin V'$ , then  $(u, v) \in E$ . In other words,  $V - V'$  is a clique, and it has size  $|V| - |V'| = k$ . ■

## Dynamic Programming

7.

- a. Consider the unweighted directed graph shown below. Does this graph has optimal substructure to find the longest simple path, say between  $q$  and  $r$  or  $q$  and  $t$ ? Explain your answer. Can you use Dynamic Programming for this problem. Explain why or why not.



Ans.

No, this graph does not have optimal substructure. Consider path  $q \rightarrow r \rightarrow t$ , which is a longest simple path from  $q$  to  $t$ . Is  $q \rightarrow r$  a longest simple path from  $q$  to  $r$ ? No, for the path  $q \rightarrow s \rightarrow t \rightarrow r$  is a simple path that is longer. Is  $r \rightarrow t$  a longest simple path from  $r$  to  $t$ ? No again, for the path  $r \rightarrow q \rightarrow s \rightarrow t$  is a simple path that is longer.

Since the graph does not have optimal substructure, we cannot use Dynamic Programming for this problem.