5. [10] Give a detailed analysis of the following algorithm. Give the running time of each line of the algorithm (on this page). What is the total running time of classifiers. of the algorithm (on this page). What is the total running time of algorithm Unknown? Hint: or the algorithm (on this page). What is the total running time of algorithm or do anything useful. Algorithm Analysis

```
Input: A weighted graph with n vertices, and m edges
Algorithm Unknown(G)
      p \leftarrow create array of size n to be referenced by vertex id number (id[u]).
  Output: ?????
       Q \leftarrow create array of size n to be referenced by vertex id number.
        for each u ∈ G.vertices() do
           Q[id(u)] \leftarrow null
        for each v ∈ G.vertices() do
            for each u ∈ G.vertices() do
                 if G.areAdjacent(u,v) then
                     P[id(u)] \leftarrow -\infty
         for each u \in G.vertices() do
             for each e \in G.incidentEdges(u) do
                   z \leftarrow G.opposite(u,e)
                   if G.valueAt(e) > P[id(z)] then
                       P[id(z)] \leftarrow valueAt(e)
                       Q[id(z)] \leftarrow e
```

#### Short answer questions:

return Q

- 6. [5] Suppose there are going to be eight nodes in a local area network. If you need to connect those nodes with the least cost (the longer the wire connecting two nodes, the greater the cost). which graph algorithm would you choose to solve your problem? Your choices are: BFS, DFS, Shortest Path, Minimum Spanning Tree, Hamiltonian Path, and Traveling Salesperson (TSP). Briefly justify why your choice is the best and would solve the problem (on this page below).
  - 7. [5] If a graph G has a shortest edge, is there a minimum spanning tree of G containing this edge?

```
Below is the template version of breadth-first search. The hook operations are in bold font.
```

```
Algorithm BFS(G)
           Output labels the edges of G as discovery edges and cross edges
           initResult(G)
           for all u \in G.vertices()
               initVertex(u)
              setLabel(u, UNEXPLORED)
          for all e \in G.edges()
              initEdge(e)
             setLabel(e, UNEXPLORED)
         for all v \in G.vertices()
             if getLabel(v) = UNEXPLORED
                preComponentVisit(G, v)
                bfsTraversal(G, v)
               postComponentVisit(G, v)
        result(G)
    Algorithm bfsTraversal(G, s)
       O ← new empty queue
      setLabel(s, VISITED)
      Q.enqueue(s)
     startBFS(G, s)
     while -Q.isEmpty() do
          v \leftarrow Q.dequeue()
         preVertexVisit(G, v)
         for all e \in G.incidentEdges(v) do
                preEdgeVisit(G, v, e)
                if getLabel(e) = UNEXPLORED
                    w \leftarrow opposite(v, e)
                   if getLabel(w) = UNEXPLORED
                       preDiscoveryEdgeVisit(G, v, e, w)
                       setLabel(e, DISCOVERY)
                       setLabel(w, VISITED)
                       Q.enqueue(w)
                       postDiscoveryEdgeVisit(G, v, e, w)
                   else
                       setLabel(e, CROSS)
                       crossEdgeVisit(G, v, e, w)
              postEdgeVisit(G, v, e, w)
     postVertexVisit(G, v)
finishBFS(G, s)
```

#### Algorithm Design

first(), last(), before(p), after(p), replaceElement(p, o), swapElements(p, q), Sequence ADT: insertBefore(p, o), insertAfter(p, o), insertFirst(o), insertLast(o), remove(p), removeFirst(), size(), isEmpty(), elemAtRank(r), replaceAtRank(r, o), insertAtRank(r, o), removeAtRank(r), atRank(r), rankOf(p), elements()

BinaryTree ADT:

root(), parent(v), children(v), leftChild(v), rightChild(v), sibling(v), isInternal(v), isExternal(v), isRoot(v), size(), elements(), positions(), swapElements(v, w), replaceElement(v, e)

Dictionary ADT

findElement(k), insertItem(k, e), removeElement(k), items()

OrderedDictionary ADT

findElement(k), insertItem(k, e), removeElement(k), closestKeyBefore(k), closestKeyAfter(k), closestElemBefore(k), closestElemAfter(k)

(General) Graph ADT

numVertices(), numEdges(), vertices(), edges(), aVertex(), degree(v), adjacentVertices(v), incidentEdges(v), endVertices(e), opposite(v, e), areAdjacent(v, w), valueAt(v), valueAt(e) insertVertex(o), removeVertex(v), insertEdge(v, w, o), removeEdge(e),

- 1. [15] Give pseudo-code for the overriding hook methods that would specialize the BFS template algorithm above so it determines, for each vertex of G, the edge whose weight is less than the weight of any other edge incident on v; the algorithm must return a Sequence of n pairs, (v, MinE) where v is the vertex and MinE is the smallest weight edge of the edges incident on v. Your solution must use the template algorithm above and must calculate MinE for each vertex v during the traversal, i.e., there must be no loops other than the loops in the BFS algorithm.
  - [5] What is the running time of your algorithm? Justify your answer; the running time for each line of your pseudo-code must be shown and for each line of the BFS template algorithm.
- 2. [15] Define an efficient algorithm to compute binomial coefficients. Binomial coefficients are

B(n,k) = 1 if k=0 or k=nB(n,k)=B(n-1, k-1)+B(n-1, k) if 0 < k < nE.g., B(1,1)=1, B(1,0)=1, B(2,1)=B(1,0)+B(1,1)=2, B(2,2)=1, B(3,2)=B(2,1)+B(2,2)=3, B(2,0)=1, B(2,0)=1,B(3,1)=B(2,0)+B(2,1)=3, B(3,0)=1, B(4,1)=B(3,0)+B(3,1)=4, B(4,2)=B(3,1)+B(3,2)=6, etc. (2) What is B(5,3)?

- [5] What is the running time of your algorithm?
- [15] Given two vertices u and v, create an algorithm to determine (yes/no) whether or not these
- 4. [5] Define what is meant by a spanning tree of a graph G.

[15] Given a graph G=(V, E) and a sub-graph T=(W, F) of G. Give an efficient pseudo-code algorithm that determines (yes/no) whether or not T forms a spanning tree of G. Hint: use the [5 points] What is the running time of your algorithm?

## Algorithms CS435

8. [5] Suppose your boss asks you to design an efficient algorithm to solve an optimization problem. Describe below the strategies you would try first. If you were unsuccessful in designing a polynomial-time algorithm, what would you do?

### NP and NP-Complete

Notation: A → B means instances of problem A can be reduced to instances of problem B by function p in polynomial time.

- 9. [10] Suppose B is a decision problem. Let bo and b1 be instances of problem B such that the decision algorithm for B always returns no (false) on bo and eventually yes (true) on b1. Reduce the LCS (Longest Common Subsequence) Problem to problem B in polynomial time. LCS can be defined as follows: An instance of LCS is composed of two strings S1 and S2 and a positive integer K. The LCS decision problem asks, is there a common subsequence of S1 and S2 with length at most K? Hint: You do not have to remember the LCS algorithm, just call it, i.e., length ← LCS(S1, S2).
- [5] In one sentence describe how LCS computes length and what is its running time.
- 10. (a) [10 points] Show that LSC∈NP. The LSC (Longest Simple Cycle) decision problem can be stated as follows:
  - Given a weighted graph G, does there exist a simple cycle in G with total weight at least K? (the total weight of a cycle is the sum of the edge weights in the cycle)
- (b) [10] Reduce the Hamiltonian Cycle (HC) problem to the above LSC problem. HC can be stated as follows:
  - HC: Given a graph G, does there exist a cycle in G that visits each vertex exactly once?
- (c) [5] Since the Hamiltonian Cycle (HC) problem has been proven to be a member of NPC, what, if anything, can we then conclude about the LSC problem based on 10(a) and 10(b)? If there is a conclusion, then state it otherwise explain why nothing can be concluded.
- 11. Answer true or false to each of the following questions 11(a) to 11(h). If true, briefly justify your answer (using at most 2 sentences in the space provided below). If false, give a counter example, such as, "A could be MST and B could be halting problem" or "A could be in NPC and B in P",

## Algorithms CS435

For parts 11(a) to 11(h), assume A and B are specific decision problems and that f is a polynomial-time function for reducing A to B. 11(a) [2] if  $A \rightarrow_f B$  and  $A \in P$ , then  $B \in P$ 

11(b) [2] if  $A \rightarrow_f B$  and  $B \in NP$ , then  $A \in P$ 

l l (c) [2] if A  $\rightarrow_f$  B and A  $\in$  NPC, then B  $\in$  NPH

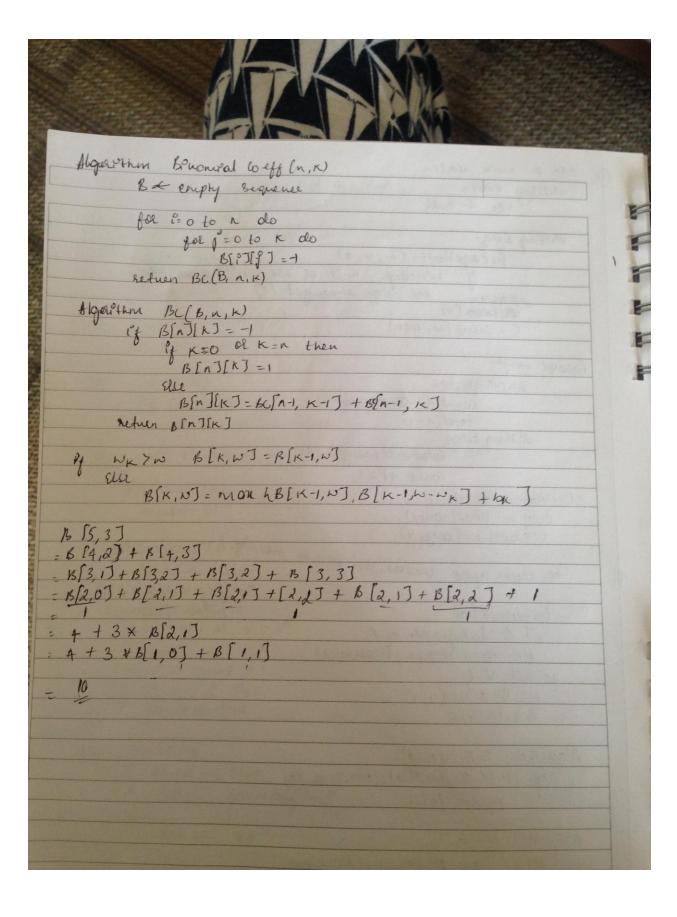
11(d) [2] if  $A \rightarrow_r B$  and  $B \in NPC$ , then  $A \in NPC$ 

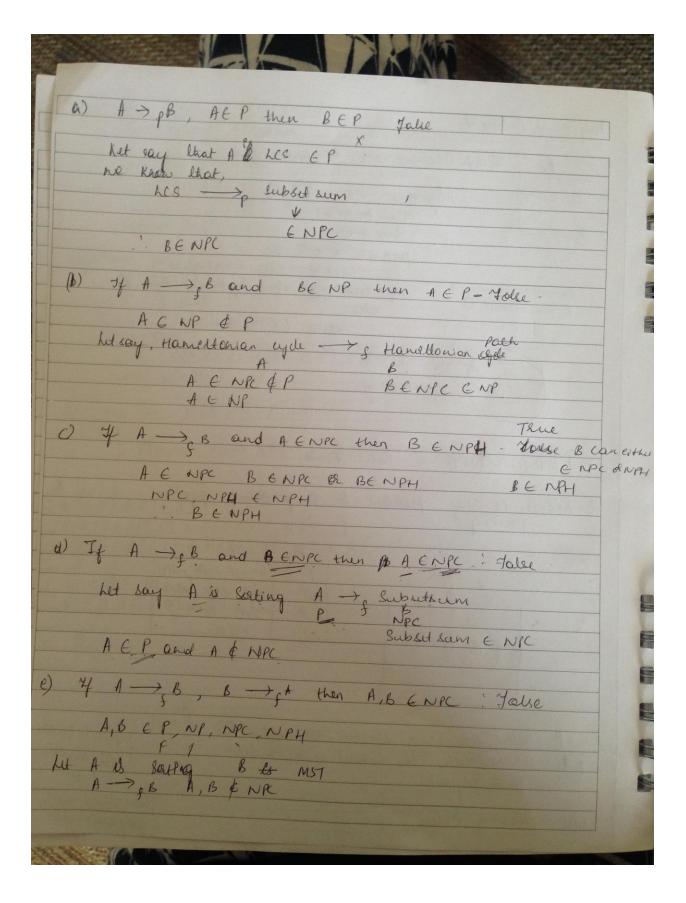
11(e) [2] if A  $\rightarrow_f$  B and B  $\rightarrow_g$  A, then A, B  $\in$  NPC

II(f) [2] if  $A \rightarrow_f B$  and  $B \in NPC$ , then  $B \rightarrow_a A$ 

 $\Pi(g)$  [2] if  $A \rightarrow_{\ell} B$  and  $A \in NPC$ , then  $B \in NPC$ 

11(h) [2] if  $A \rightarrow_t B$  and  $A \in NPH$ , then  $B \in NPC$ 

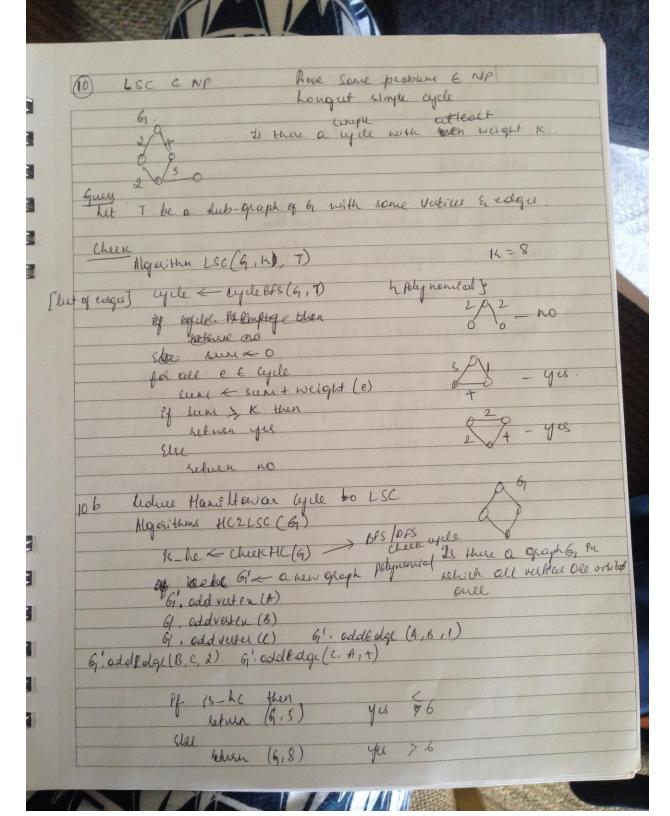




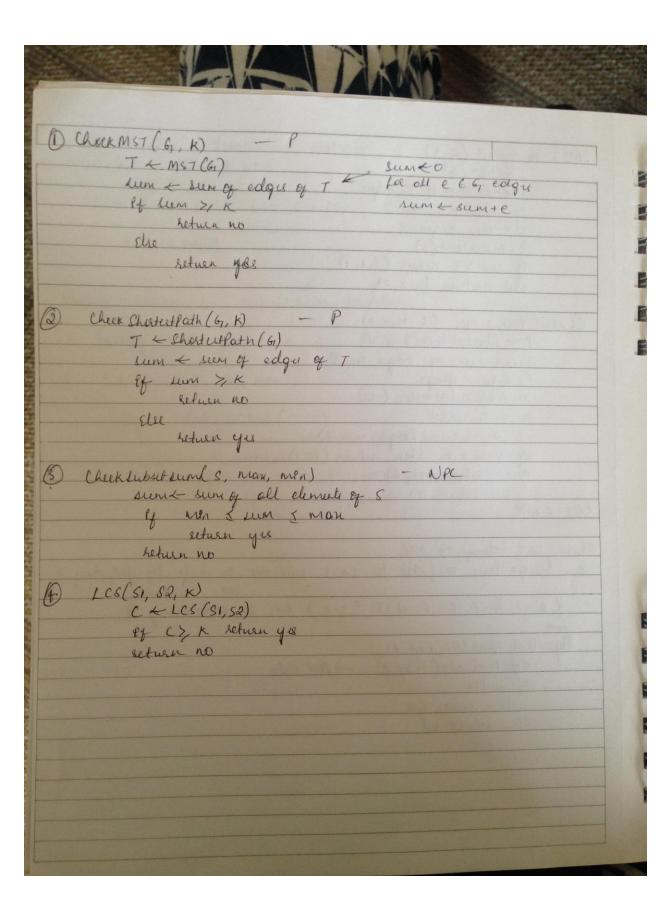
( ) of A > & BENR B > & A : Jalse. B is subsed problem & NPC

A is sating & P A > B BENIX Subsit sum cannot be reclued to seeking.
B + g A 9) \$ A CMPC then B C NR : false A 18- LCS ENPC A > Holling Holling & NPH & N) of A -> & A ENPH then B & NPC : Yolk het say, # is Halting prossen & KIPH Halting problem A is subset sum ENPC ENPH b -> Halting problem ENPH & NPC Rol3.) L -> , NPC (M) h can be solved en polynomial time L -> m (NPC) (P) + Polynemal. (P) M57 -> Subset sum (NPC) della This is not the proof of P = NP

R13.13 N = 123,59,17,47,14,40,22,8} Sum = 100 1 Sum = 130? Subset Siene Randonly PPCK subset & check nehether sum is 100 or not. C13.2 L -> M (5} Benary encoding of exput =5?? bo by Pretances of B setuen no -> bo Return yes -> bo Reduce LCS to B Pr polynomial time S1, S2, K ACS(SI,S2) & K Algorithm LCS2B (SI, S2, K) length - LCS (S1, S2) polynomial ef length < K
Return b1 4484 retuen bo holy 不作作事事 To reduce of any problem from A to 15 Atob (againet of #) Calculation of A Result if healt-true Pretance of 15
Else
Result-palse Pretance of 15



MST to subset (6, K) T + MST (61) total + Sum of T. edges ef total > K then St new sequence S. enect Last (2) Of sum > k setuen (S.1, 1) else setnen (5,2,2) Shortut Path 2 Mst (6, U, V, K) P < Shortest Path (6, 4, V) sunt sun of edges en P M x new graph u & M. Prisat verten (u) v < Purest (W) e + M. Priset Edge (u, v, 2) of sum > K then setuen (M, 1) Else return (M, 2) SAT ENK Show SAT belongs to NP a. Assign true of palse to each voriable in emp by fleggeng corn sandomly Ka=T, b=F, C=F d=T, e=T & fit in dictionary A Algorithm ChecksAT (Frp, A) v < evaluate (Exp,A) -> port oldre Pf V then setuen yes Else solver no



I Whether graph is connected a not. Prit Result (6) St new Engly sequence For Corneded graph Enit Result (G1) Court to Drecomponentisot(6, v) count & west +1 result (G) Alg Pf Count >1 refuer not Connected Il. Epven V'E v" present in the come connected graph. Post Result (61) dount - 0 Post Component V, 18+ (G, V) found & falle Blast Vulen Upust (v) Pf (V = V1) of V = V" then count & count + 1 if court = 2 then found true Result (61) If found = = true return dame conformat Elle Retuer No

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|      |      | versting versen will  |
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| 1,   |      | Ro Edgerlester (G, V, e)  |
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# CS435 Algorithms Final Exam

### February 2, 2006

| Answer True or False to each question in this section. Please write clearly. [2 points each]  Answer True or False to each question in this section. Please write clearly. [2 points each]   |
|--|
| Answer True or False to each question in this section. Please write clearly. [2 points each of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method, a problem should have the property that a series of locally-  1. To use the greedy method the property that a series of locally-  1. To use the greedy method to a global optimal configuration.   |
| Answer True or Faise to Cast 4   |
| 1 To use the global optimal configuration  |
| and anady approach should be and conquel memory  |
| The task scheduling problem is an example of the division of t |
| tasks all south  |
| The fractional knapsack problem can be solved using the greedy method by continued  The fractional knapsack problem can be solved using the greedy method by continued selection of the item with the highest benefit-to-weight ratio.   |
| 4 The fractional knapsack protein and the highest benefit-to-weight ratio.  5 The Recurrence equations are used to evaluate the time-complexity of divide-and-conquer of the item with the highest benefit-to-weight ratio.  5 The Recurrence equations are used to evaluate the time-complexity of divide-and-conquer of the item with the highest benefit-to-weight ratio.   |
| 5 T Recurrence equations are used to community of the second of the seco |
| algorithms. , O(m) time-complexity.  |
| 5 T Recurrence equations are used to evaluate the time-complexity of an algorithms  1.585  The problem of multiplying big integers of size n has O(n) time-complexity.  The dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is similar to the divide-and-conquer approach in the dynamic programming technique is divided in smaller.   |
| 7. F The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is similar to the divide-and-conquer approach.  The dynamic programming technique is divided in smaller, independent sub-problems and the results merged the way that a problem is divided in smaller.  |
| the way that a problem is divided in smaller, independent  |
| together to form the service applied to the muniplying   |
| the way that a problem to together to form the solution.  8. T When the dynamic programming technique is applied to the <i>multiplying matrices</i> problem the time-complexity is reduced from exponential to linear.  The problem that only depends on n.  |
| problem the time-complexity is reduced a running time that only depends on n.  |
| When the dynamic problem the time-complexity is reduced from exponential to interest problem the time-complexity is reduced from exponential to interest and problem that only depends on n.      F Dynamic programming algorithms have a running time that only depends on n.      Section of the same edge.  |
| 9. F Dynamic programming algorithms  10. T Two vertices that are adjacent are endpoints of the same edge.  11. F The sum of the degrees of all vertices in a graph G are equal to the number of edges.  11. F The sum of the degrees of all vertices in a graph G are equal to the number of edges.  |
| The sum of the degrees of all vertices in a graph of the graph.  |
| 11 The sum of the degrees of all vertices in a graph.  12 A spanning tree of a graph contains only some of the vertices of the graph.  12 A spanning tree of a graph contains only some of the vertices of the graph.  |
| 12. F A spanning tree of a graph contains only some of the vertices.  13. T An adjacency list structure has similar performance to the edge list structure but also had a linear system of the edge list structure but also had a linear experiments in methods such as incident Edges (v) and are Adjacent (u, v).  |
| 13. T An adjacency list structure has similar performance to the edge list structure has similar performance in the edge list structure has similar performance has been list structure.   |
| performance improvements in interest performance  |
| 14. T Depth-first search traversal of all undirected gard  |
| 14. The Depth-first search decreases of a graph.  explore the vertices and edges of a graph.  explore the vertices and edges of a graph.  15. The breadth-first search, the edges are marked as either discovery or cross edges to   |
| 15. T In breadth-first search, the edges are marked as   |
| indicate their role in the spanning tree.  To test whether a graph is connected, a DFS traversal can be performed and if some  |
| 16 T To test whether a graph is connected, a DTS travelsed.  |
| 16. To test whether a graph is connected, a DTS travel.  the vertices are not marked as discovered, the graph is not connected.  17. The a computer network, reachability in a directed graph is computed to find out if a line and the control of the property to node w.   |
| to activork reachability in a directed graph to comp   |
| 17. In a computer network, reaching message can be routed from node v to node w.   |
| Market Ma |

- 18. X The transitive closure of a graph measures the density of the edges in the graph.
- 19. X A topological ordering of a digraph is useful in scheduling tasks that have constraints as
- 20. T Single-source shortest path algorithms find all the paths between a vertex v and w in a weighted graph.

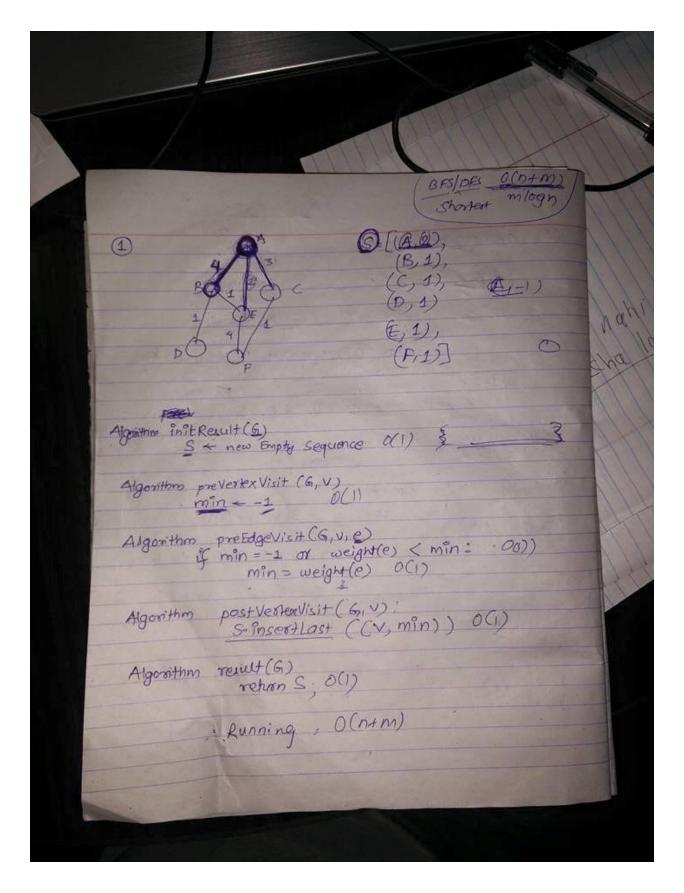
Multiple choice questions. Pick the best answer [3 points each]

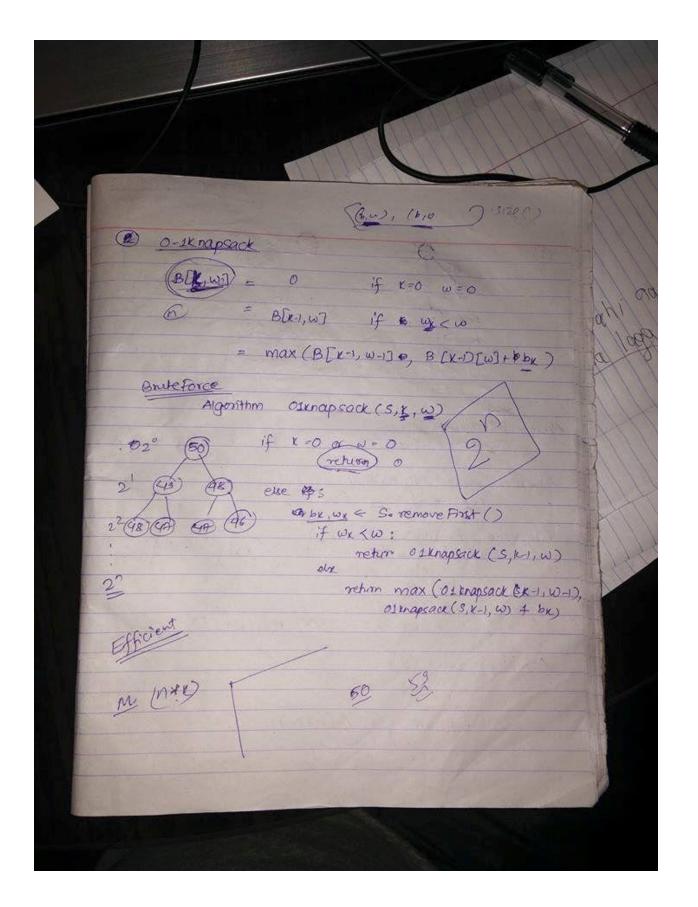
- 21. The depth-first search algorithm we studied uses
  - a) edge reversal
  - b) a min-heap
- t c) fecursion
  - d) transitive closure
- 22. The \_\_\_\_\_ problem can be solved optimally with the greedy approach.
  - a) sum-of-subsets
  - b) traveling salesman
  - c) big integer multiplication
- (a) fractional knapsack
- 23. The iterative substitution method is a technique that depends on our ability to converted to the closed-form version of the recurrence equation.
- X a) see a pattern
  - b) multiply matrices
  - c) draw a tree
  - d) apply a formula
- 24. In the following recurrence relation, the step of merging sub-problem solutions is done times at each level.

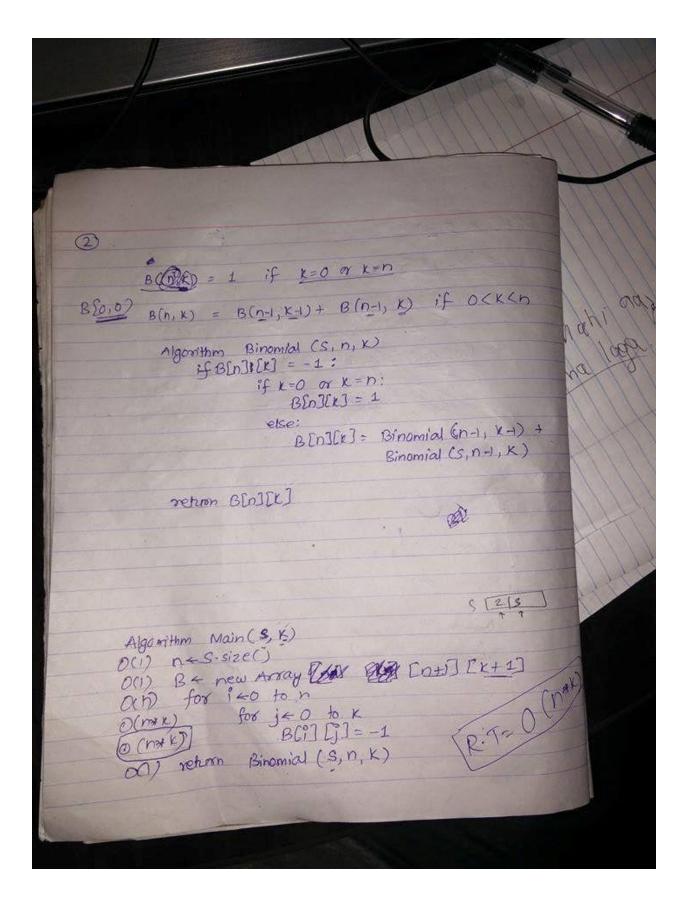
$$T(n) = \begin{cases} 5b & \text{if } n < 2\\ 3T(n/2) + 4n & \text{if } n \ge 2\\ no \text{ of } & \text{extro way done} \end{cases}$$
recursive
call

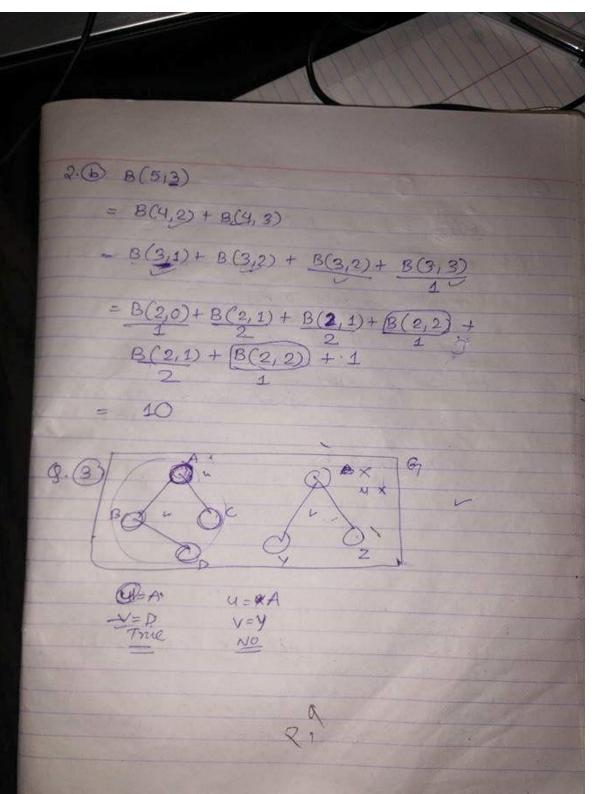
- a) 2
- b) 3
- c) 4
- d) 5

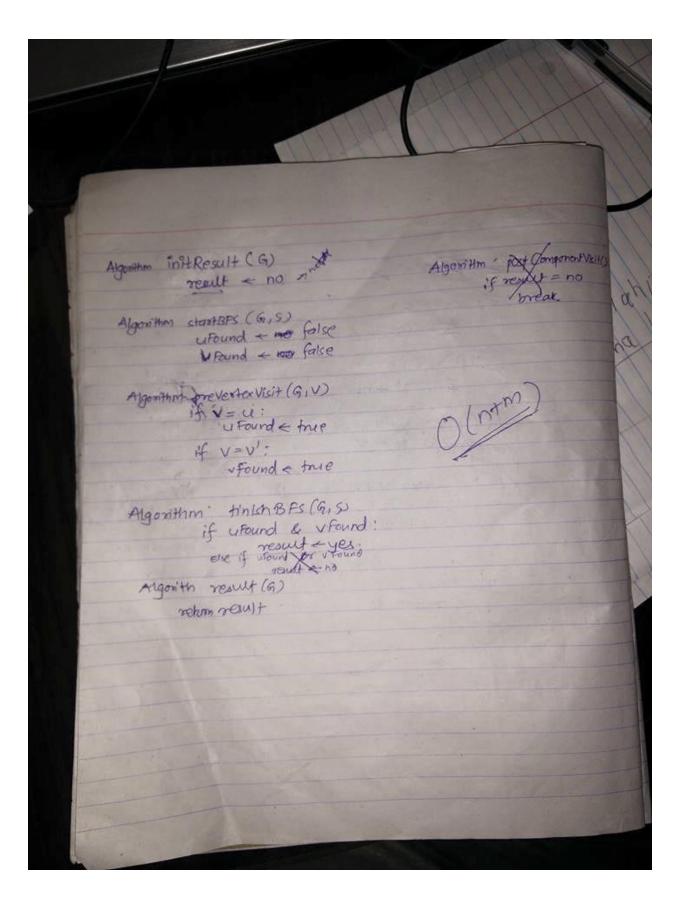
| List : 6×12×  | ((narm))          |               |   |
|---|-------------------|---------------|---|
| Cisi -  |                   | 451           | ne optimal solutions of all                   |
| and in the problem if the   | best solution alv | vays contain  | ns optimal solutions of all                   |
| 25. The applies to a prosent  |                   |               |   |
| (a) principle of optimality   | 46)               | (10)4         | (10 <sup>7</sup> )<br>×4                      |
| b) greedy method  |                   | (10)4<br>×72  | ×4  |
| c) iterative method   |                   |               |   |
| d) big O notation   | 1 and affi        | ciency whe    | n representing a graph                        |
| d) big O notation  26. Which data structure is preferred when w with 10,000 vertices and 200,000 edges at | nd we also need i | fast respons  | e to the areAdjacent                          |
| method?   |                   |               | Japlist - 5                                   |
| a) adjacency matrix   | 9                 | 7.            | Adjacency List                                |
| b) adjacency list   | y= x2             | 9             | edgelist &<br>Adjacency List )<br>Adjacency ! |
| e) edge list  |                   |               | ragico 5                                      |
|   | Name and Co.      | 7             | t to less door not have                       |
| 27. Which of the following problems has not a polynomial-time solution?                                   | been proven to b  | oe intractab  | le, but also does not have                    |
| at 0-1 knapsack problem NPC   |                   |               |   |
| b) minimum spanning tree problem  |                   |               |   |
| c) matrix multiplication problem  |                   |               |   |
| d) searching problem  |                   |               |   |
| 28. What is an application of topological ord   | ering?            |               | ar and a site of the site of                  |
| a) sorting mail by the user's name  |                   |               |   |
| b) finding the path between a pair of vert  | tices             |               |   |
| c) determining connectivity in a graph  |                   |               |   |
| d) showing the inheritance hierarchy in J   | lava interfaces   |               |   |
| 29. A weighted graph will only have one mir   | nimal spanning to | ree if        |   |
| (a) every edge has a different weight   |                   |               |   |
| b) every edge has the same weight   |                   |               |   |
| c) every vertex connects to very other ve   | ertex             |               |   |
| d) every vertex is a separate component   |                   |               |   |
| 30. A is a sequence of vertices that have   | e an edge betwe   | en ooob       | 4.22  |
| a) cycle  | - mi suge between | cii cacii vei | tex and its successor.                        |
| b) map  |                   |               |   |
| c) component  |                   |               |   |
| , d) path   |                   |               |   |
|   |                   |               |   |

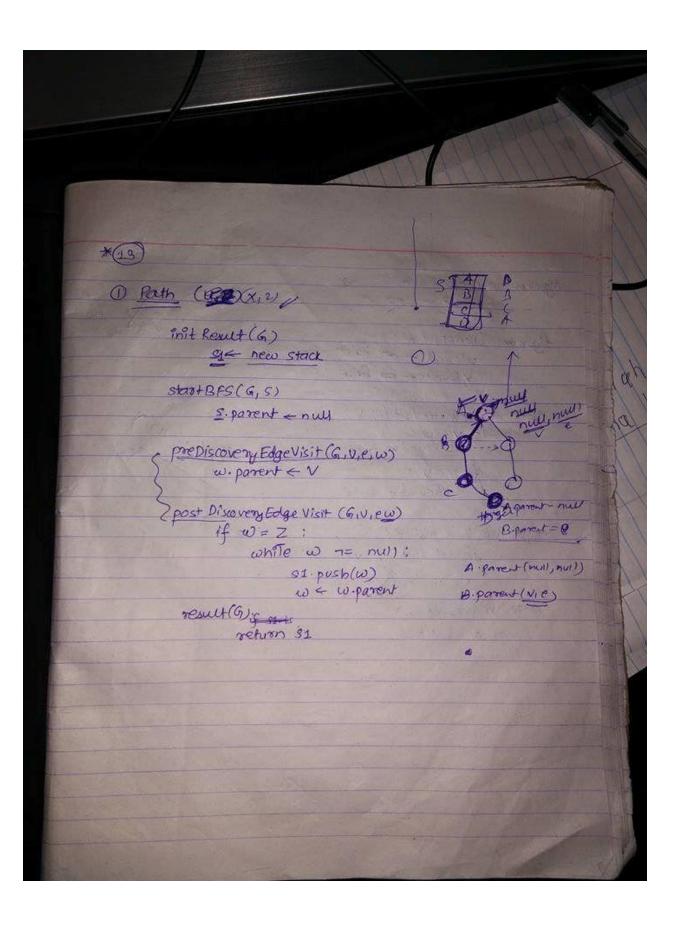


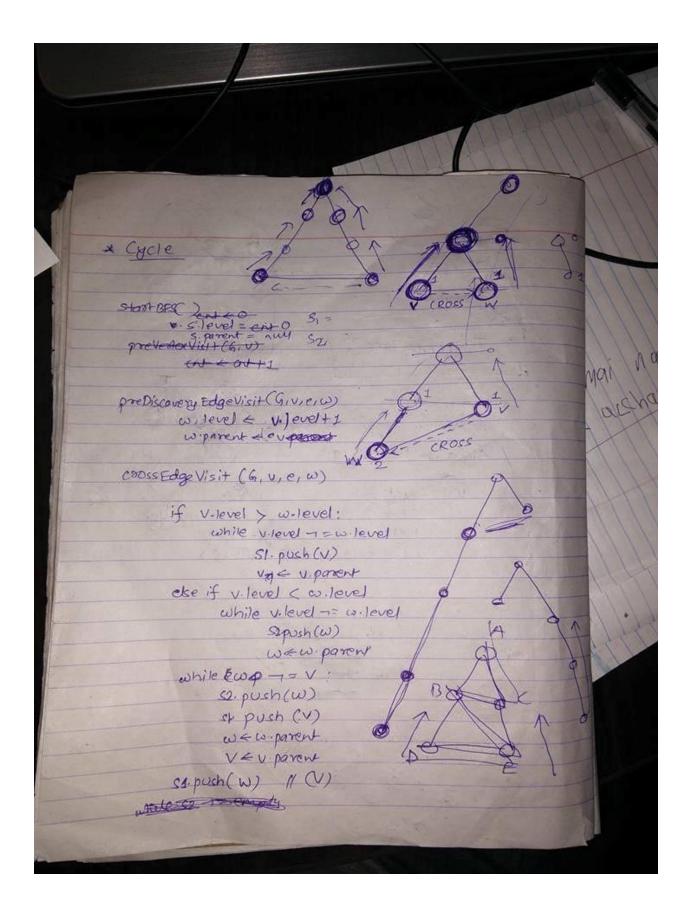


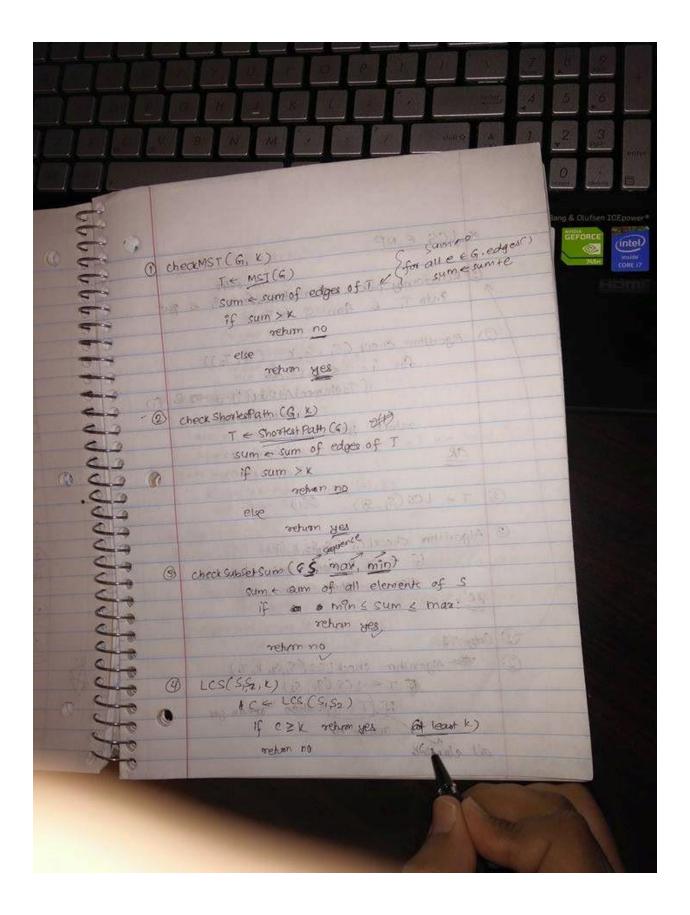


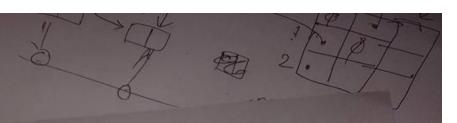








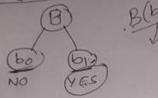




### P-NP Reduction

O Easy (Reduction)

- \* MST, ShortestPath, SubsetSum, LCS,
- \* Language Problem



LCS (\$1,52, K)

a = LCS(\$1,52

LCS

Algorithm 
$$LCS2B(S1,S2,K)$$

$$Q = LCS(S1,S2)$$
if  $a \leq K$  then return by

LCS Brute Force = 2" \* m DP = O(n\*m)

P-> & Sorting, searching, MST, Well, shortest Path. was orknapsack, NPC-> X (Clique Problem) Vertex Cover Hamilton Path Hamil Hon Cycle

NPH -> Halting Problem

For parts 11(a) to 11(b), assume A and B are specific decision problems and that f is a cohmomial-time function for reducing A to B. polynomial-time function for reducing A to B. II(A)[P] if  $A \rightarrow_P B$  and  $A \in P$ , then  $B \in P$ e.g. A- MST(P) ; (B & P) .. A ≠ P 11(b) [2] if  $A \rightarrow_r B$  and  $B \in NP$ , then  $A \in P$ False ASSUM (NPC - NP) B-> OIKMAPSACK (NPC-> NP) 11(c) [2] if  $A \rightarrow_r B$  and  $A \in NPC$ , then  $B \in NPH$ e.g. A BENPL, NPH BC (NPH) Pour 11(d) [2] if  $A \rightarrow_r B$  and  $B \in NPC$ , then  $A \in NPC$ B-SSUM(NPC) AED & NPC False AIBEP & NPC 11(e) (2) if  $A \rightarrow_f B$  and  $B \rightarrow_g A$ , then  $A, B \in NPC$ FOILE A-MSTEP) A-B
B-A
B-Shartert Plaths (1) 11(f) [2] if  $A \rightarrow B$  and  $B \in NPC$ , then  $B \rightarrow_a A$ BAA False A - some problem in B B-> some problem in NFC H(g) [2] if A → B and A ∈ NPC, then B ∈ NPC BENPL & NPC eq. A -> OHENAPSACK (NPC) B - Halking Problem (NPH) 11(h) [2] if A -> B and A & NPH, then B & NPC  $A \rightarrow (B)$ A- Holding Padlem B- Some other problem in BÉNPC NPH whichisnodies NPL

Asjacy Mehrx Adjacency List Edge List Space modent sages Uspenning tree of a connected graph is a spanning subgraph that is tree spanning tree is not unique when the graph is a tree No cycle. NP NPH P -> P,NP,NPC,NPM > P, NP, NPC, NPM -> NPC, NPN, NP NPM > NPM, NPC SAT, 3-SAT, Subset Problem, TSP, Namitonian uycle/path. P -> LCS, MST, NPH > Halling pridem.

