# Intensity Values

**BIOMEDICAL IMAGE ANALYSIS IN PYTHON** 



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#### Pixels and voxels

- Pixels are 2D picture elements
- Voxels are 3D volume elements
- Two properties: intensity and location



### Data types and image size

Array's data type controls range of possible intensities

Type	Range	No. Val.
uint8	0, 255	256
int8	- 128, 127	256
uint16	O, 2 <sup>16</sup>	<b>2</b> <sup>16</sup>
int16	-2 <sup>15</sup> , 2 <sup>15</sup>	2 <sup>16</sup>
float16	~-2 <sup>16</sup> , ~2 <sup>16</sup>	>>2 <sup>16</sup>

```
import imageio
im=imageio.imread('foot-xray.jpg')
im.dtype
        dtype('uint8')
im.size
```

#### 153600

```
im_int64 = im.astype(np.uint64)
im_int64.size
```

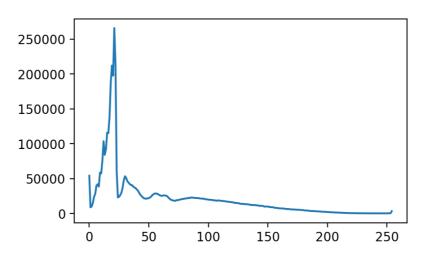
1228800

### Histograms

- Histograms: count number of pixels at each intensity value.
- Implemented in scipy.ndimage
  - higher-dimensional arrays
  - masked data
- Advanced techniques and functionality in scikit-image.

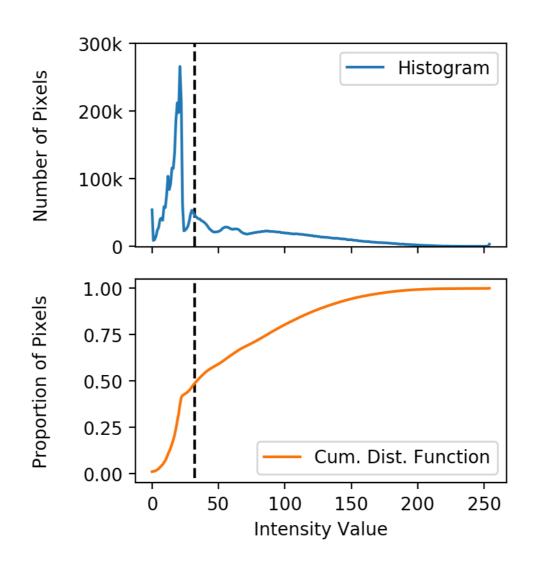
```
plt.plot(hist)
plt.show()
```

#### (256,)



### Equalization

- Distributions often skewed toward low intensities (background values).
- Equalization: redistribute values to optimize full intensity range.
- Cumulative distribution
  function: (CDF) shows
  proportion of pixels in range.



### Equalization

# Dx P

#### (256,)

```
im_equalized = cdf[im] * 255
fig, axes = plt.subplots(2, 1)
axes[0].imshow(im)
axes[1].imshow(im_equalized)
plt.show()
```



# Let's practice!

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## Masks

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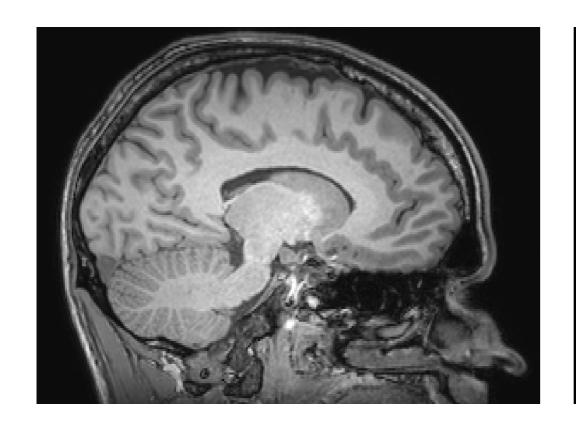
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### Masks

Raw image







### Creating masks

Logical operations result in

True / False at each pixel

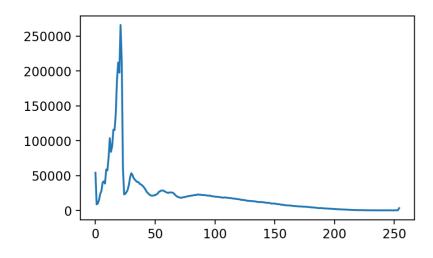
#### **Sample Operations**

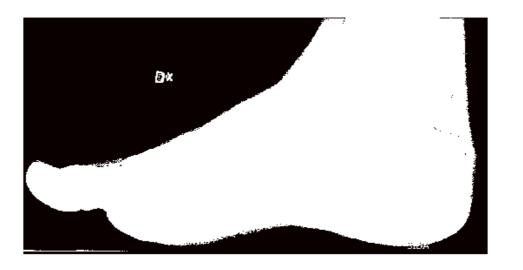
Operation	Example		
Greater	im > 0		
Equal to	im == 1		
X and Y	(im > 0) & (im < 5)		
X or Y	(im > 10)   (im < 5)		

### **Creating masks**

hist=ndi.histogram(im, 0, 255, 256)

$$mask1 = im > 32$$

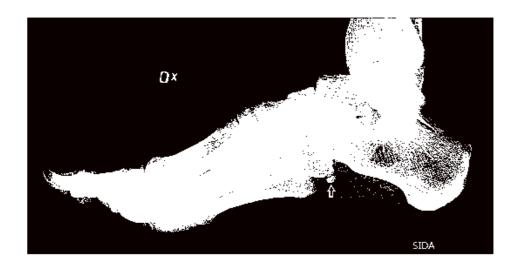




### **Creating masks**

mask2 = im > 64

mask3 = mask1 & ~mask2





### Applying masks

np.where(condition, x, y)
controls what data passes
through the mask.

```
import numpy as np
im_bone = np.where(im > 64, im, 0)
```

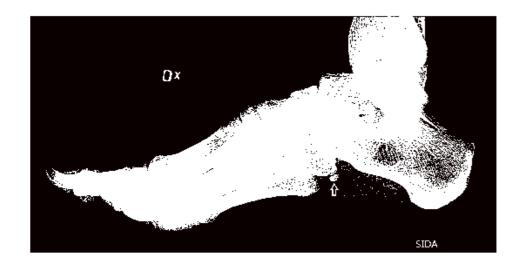
```
plt.imshow(im_bone, cmap='gray')
plt.axis('off')
plt.show()
```



### **Tuning masks**

```
m = np.where(im > 64, 1, 0)
```

ndi.binary\_dilation(m,iterations=5)





### **Tuning masks**

ndi.binary\_erosion(m,iterations=5)



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## **Filters**

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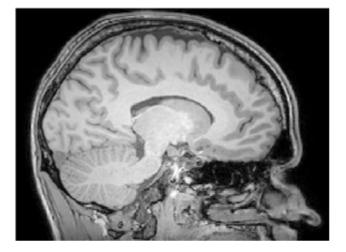


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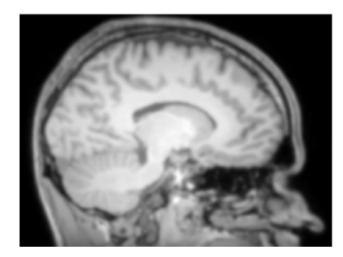


### **Filters**

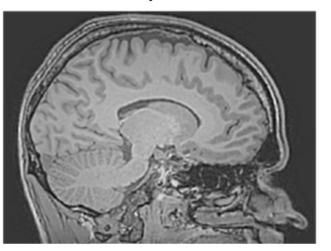
Original



Smoothed



Sharpened



### Convolution with a sharpening filter

\*

Input Array

1	1	1	1	1
1	1	1	1	1
1	1	2	1	1
1	1	1	1	1
1	1	1	1	1

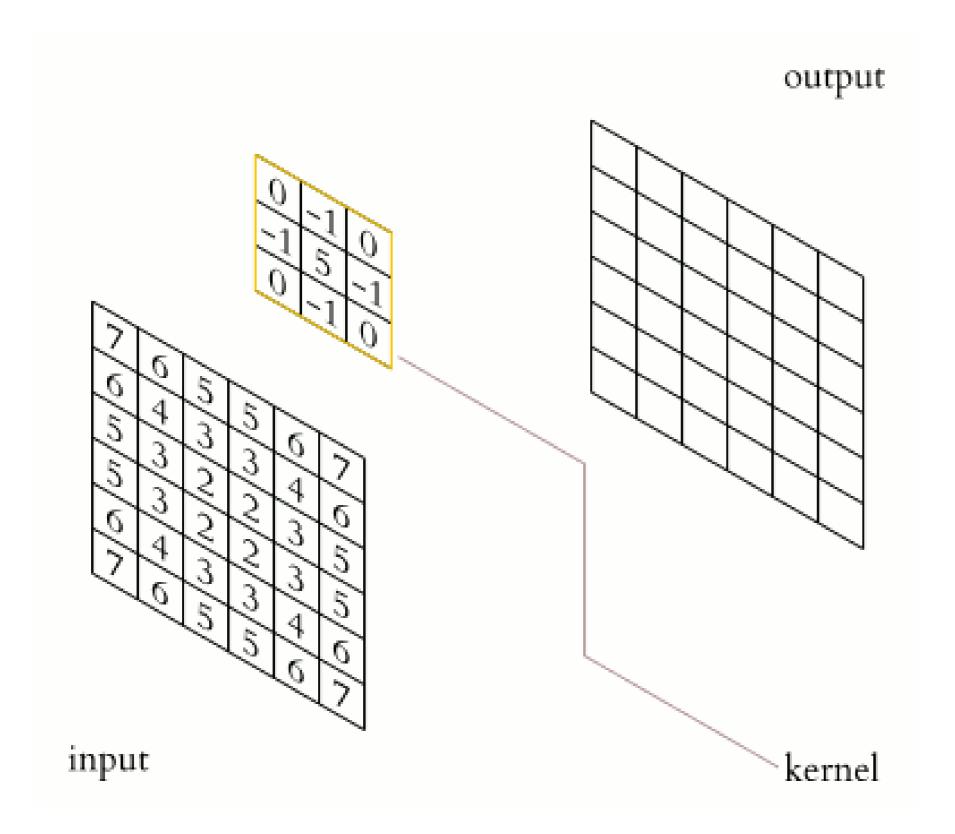
Filter Weights / Kernel

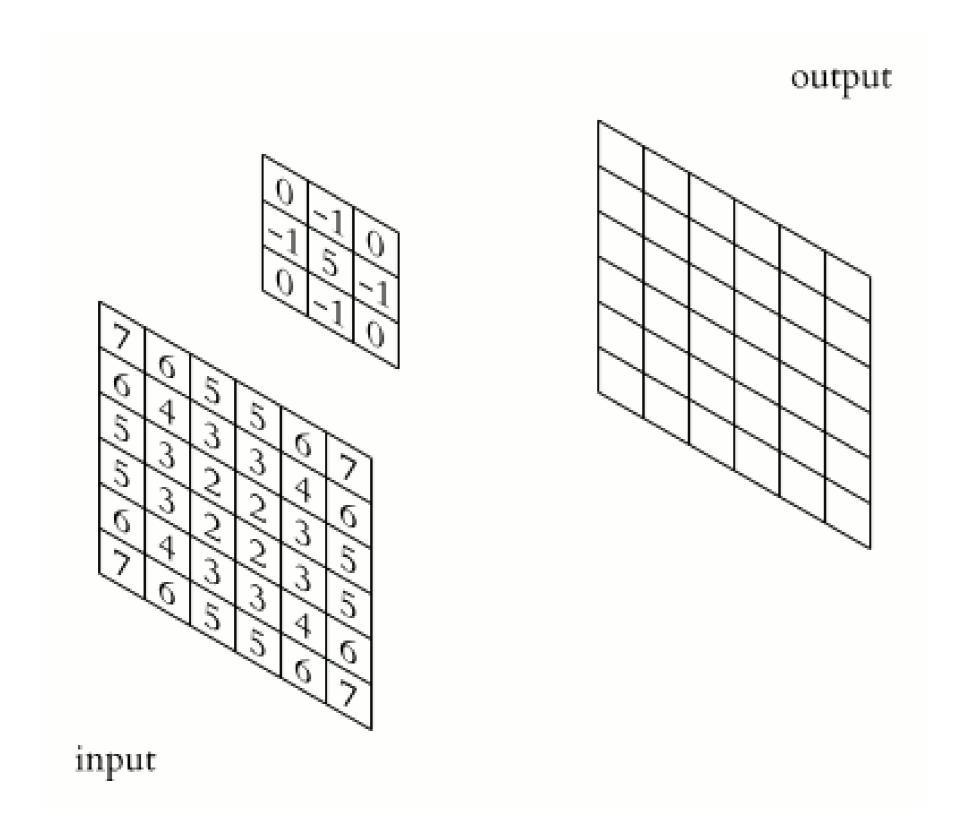
0	-1	0
-1	5	-1
0	-1	0



### Convolution with a sharpening filter

(					
	1 * 0	1 * -1	1 * 0		
Sum	1 * -1	2 * 5	1 * -1	=	6
	1 * 0	1 * -1	1 * 0		
				J	





### Image convolution

```
fig, axes = plt.subplots(2, 1)
axes[0].imshow(im, cmap='gray')
axes[1].imshow(im_filt,cmap='gray')
plt.imshow()
```





### Filtering functions

scipy.ndimage.filters
includes:

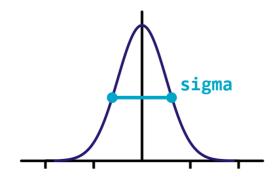
- median\_filter()
- uniform\_filter()
- maximum\_filter()
- percentile\_filter()

ndi.median\_filter(im, size=10)



### Gaussian filtering

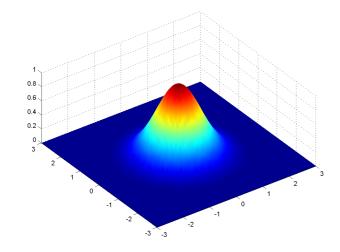
Gaussian distribution in 1 dimension



ndi.gaussian\_filter(im, sigma=5)



Gaussian distribution in 2 dimensions



ndi.gaussian\_filter(im, sigma=10)



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## Feature detection

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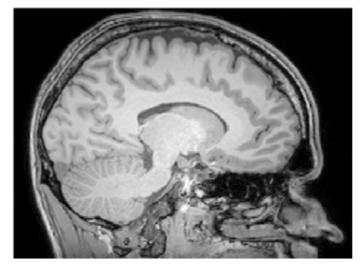
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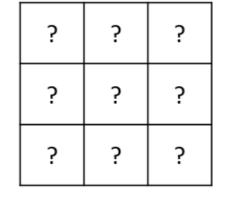
### Edges: sharp changes in intensity

\*

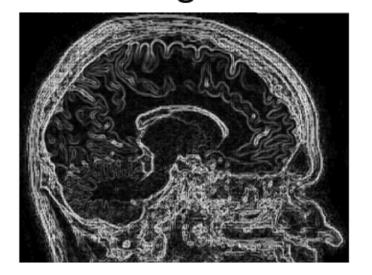
Original

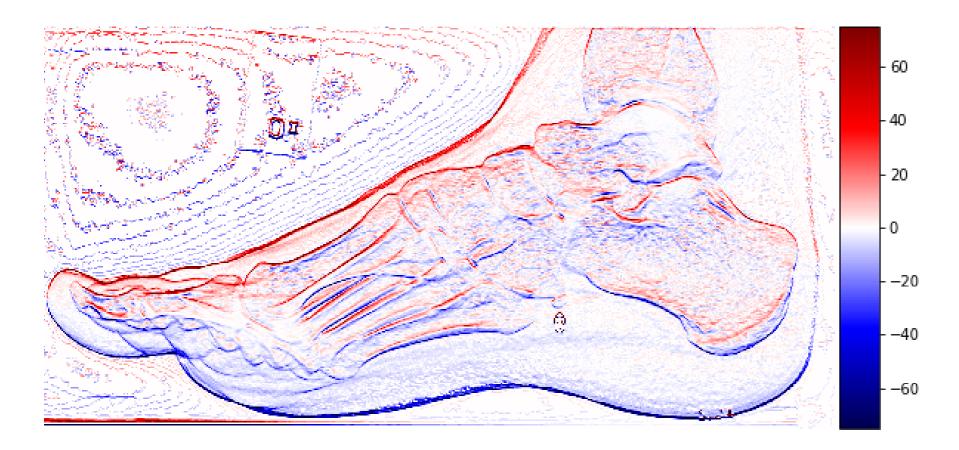


Kernel



Edges





#### Sobel filters

## Sobel (H)

1	2	1
0	0	0
-1	-2	-1

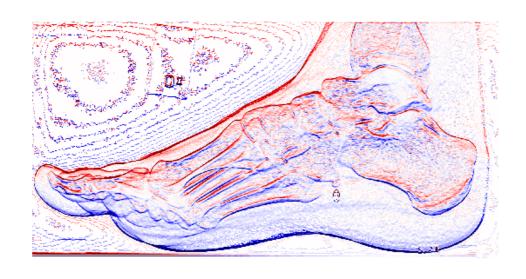
## Sobel (V)

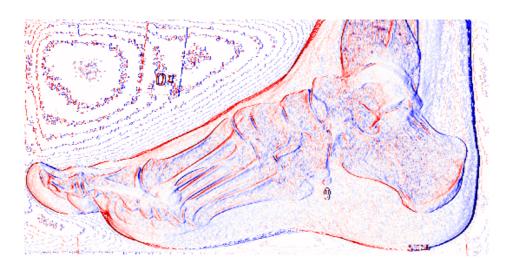
1	0	-1
2	0	-2
1	0	-1

### **Sobel filters**

ndi.sobel(im, axis=0)

ndi.sobel(im, axis=1)



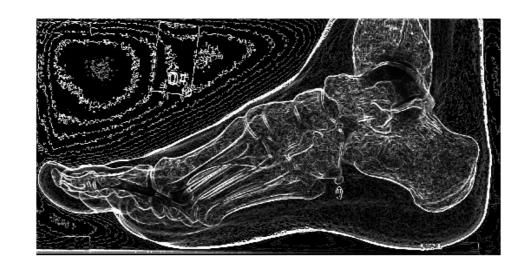


### Sobel filter magnitude

Combine horizontal and vertical edge data by calculating distance:

$$z=\sqrt{x^2+y^2}$$

plt.imshow(edges, cmap='gray')



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