

Hashing (III): Open Addressing

CSCD 300 – Data Structures

Eastern Washington University

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Goal

In this lecture, we will discuss another mechanism called **open addressing** to solve the hashing collisions.

Outline

- 1 Open addressing
- 2 Hashing functions for open addressing
- 3 Operations

Open addressing

In **open addressing**, if an element is hashed to a table location which is already occupied by another element, the hash function will then try another table location ¹ until it finds a table location where there is no element, unless the whole hash table is already full.

What does that mean ?

- Each table location can have **no more than one** element.
- The number of elements \leq the hash table size.
- The sequence of the table positions **probed** by the hash function **should** be a **permutation** of all the hash table positions.
- We expect each permutation used in the probing procedure has equal probability — **uniform hashing**.
- It is space-saving, because open addressing saves space from avoiding pointers which are used in the hashing with chains.

¹The hash function used in open addressing is not just a fixed function, as we will show later.

Hashing functions for open addressing

Unfortunately, uniform hashing for open addressing is difficult to implement, so next we are to introduce **linear probing**, which is the simplest type of hash function for open addressing, to compute the probe sequence for open addressing. Note that linear probing is not uniform hashing ².

In the rest of the lecture:

- U denotes the universe where element id's are drawn from.
- m denotes the hash table size.

²If you want to know why, I will be happy to discuss it off the lecture

Linear probing

For $i = 0, 1, \dots, m - 1$,

$$h(k, i) = (h'(k) + i) \bmod m$$

where $h' : U \rightarrow \{0, 1, \dots, m - 1\}$ is a normal hash function.

Over $i = 0, 1, \dots, m - 1$, function $h()$ is to try and find the “first” empty array location where the given key k (and its associated value) will be saved.

Operations

Let $\langle h(k, 0), h(k, 1), \dots, h(k, m-1) \rangle$ denote the permutation that probing procedure will follow for a given key k using a hash function h .

```
Open_addr_search(T,k)
  for i = 0 ... m-1
    j = h(k,i)
    if T[j] == k
      return j
    if T[j] == NIL
      return NIL
  return NIL
```

```
//assume we have checked that k does not exist
Open_addr_insert(T,k)
  for i = 0 ... m-1
    j = h(k,i)
    if T[j] == NIL or T[j] == "DELETED"
      T[j] = k
      return j
  return "table overflow"
```

```
Open_addr_delete(T,k)
  p = Open_addr_search(T,k)
  if p != NIL
    T[p] = "DELETED"
```

Questions and comments

- Why DON'T we set NIL to $T[p]$ in the delete operation ?
- Because of this "DELETE" assignment, search performance of open addressing can be worse than hashing with chaining, if there are many delete operations on the hash table. (why ?)