# Extracting Parts of Programs into Separate Binaries

**Tomáš Mészaroš**

Brno, 2018

# Declaration

Hereby I declare, that this paper is my original authorial work, which I have worked out by my own. All sources, references and literature used or excerpted during elaboration of this work are properly cited and listed in complete reference to the due source.
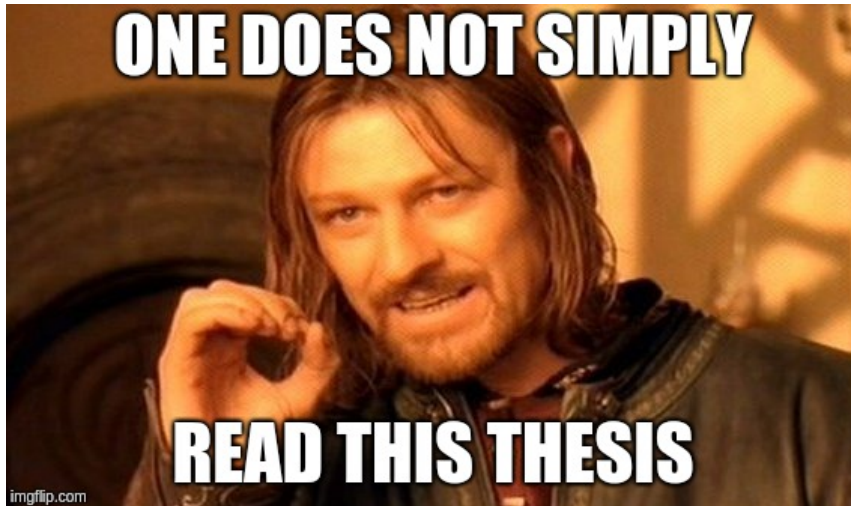
<div align="right">Tomáš Mészaroš</div>

**Advisor:** Mgr. Marek Grác, Ph.D.

# Acknowledgement

Dedicated to those who are brave enough to read this stuff.

You are heroes!

# Abstract

abstract TBA

# Keywords

keyword, keyword, keyword, keyword, keyword, keyword

# Contents

# 1 Introduction: TODO

User wants to know the value of some variable in the program. He/she can run debugger of choice, set breakpoint at the selected variable location and let debugger execute input program step by step until it reaches the selected variable. Finally, debugger steps on the targeted variable and thus can extract its value and provide it back to the user.

The procedure described above is usually part of the standard standard approach when user want to get value of some selected variable during the program execution. Unfortunately, this approach is cumbersome in case when user want to execute above procedure many times. Procedure consists of many manual steps which is time consuming to perform. Ideally, there could be script that takes line of code (or variable name) as an input and produces output with the value of the selected target

Normally, this method would require to use debugger with the scripting support and write scripts that would instruct debugger what exactly to do, basically replicating the manual approach.

Instead of scripting debugger to do the extraction, we could write tool that would accept the same user input as the approach above (line of code/variable name), run analysis on where the execution flow in the program would occur to get to the target instruction and transplant subset of the input program into separate binary.

This way, user will have separate, executable that upon running would produce value of the targeted instruction, without having to manually step thought or script debugger.

This thesis aims to devise method and implement this method in a tool for statically transplanting a subset of a C program. Using the devised method, the selected program subset should be extracted from the original program provided by the user and synthesized as an independent, executable binary.

Proposed solution should be implemented in a tool having appropriate form, either as a standalone application or an LLVM plugin. It should easily accept user to provide their own input programs.

Finally, tool should be used to test at least two real-world open-source C programs in order to find where the room for improvements is and what could be improved in the future.

The following sections of this thesis are structured as follows. In the chapter 2 we will briefly introduce the LLVM compiler infrastructure. Explain what makes it so popular and why we picked this tool for our implementation. The following chapter 3, we will introduce method that is the basis of this thesis aim. We will devote chapter 4 for explaining specific details and intricacies of implementation. Experiments and their results will be discussed in the chapter chapter 5. Finally chapter 6 summarizes the results of this thesis and describes possible further research and development opportunities.

# 2 The LLVM Compiler Infrastructure: TODO

"The LLVM (FOOTNOTE:The name "LLVM" itself is not an acronym; it is the full name of the project.) Project is a collection of modular and reusable compiler and toolchain technologies." [LLV18b]

"an umbrella project that hosts and develops a set of close-knit low-level toolchain components (e.g., assemblers, compilers, debuggers, etc.), which are designed to be compatible with existing tools typically used on Unix systems"

"the main thing that sets LLVM apart from other compilers is its internal architecture." [6] Primary subprojects:

LLVM core clang ... Strengths: "A major strength of LLVM is its versatility, flexibility, and reusability"

## 2.1 Intermediate Representation

Introduction - IR AKA LLVM assembly language AKA LLVM

- "LLVM is a Static Single Assignment (SSA) based representation that provides type safety, low-level operations, flexibility, and the capability of representing 'all' high-level languages cleanly. It is the common code representation used throughout all phases of the LLVM compilation strategy."

- Aims: - "The LLVM representation aims to be light-weight and low-level while being expressive, typed, and extensible at the same time."

- Representations of IR: - as an in-memory compiler IR - as an on-disk bitcode representation (suitable for fast loading by a Just-In-Time compiler) - as a human readable assembly language representation

Example of the IR

We have the following C function add

```
int add(int a, int b) {
    return a+b;
}
```

When using clang compiler with -emit-llvm flag, we get the following representation in IR:

```
define i32 @add(i32 %a, i32 %b) #0 {
entry:
```

```
%a.addr = alloca i32, align 4
%b.addr = alloca i32, align 4
store i32 %a, i32* %a.addr, align 4
store i32 %b, i32* %b.addr, align 4
%0 = load i32, i32* %a.addr, align 4
%1 = load i32, i32* %b.addr, align 4
%add = add nsw i32 %0, %1
ret i32 %add
```

High Level Structure

- Module structure: - functions - global variables - symbol table entries

- using LLVM linker for module combination - we will use this in practice

- Functions: - "A function definition contains a list of basic blocks, forming the CFG (Control Flow Graph) for the function." - PHI nodes

## 2.2 Optimisations

LLVM uses the concept of Passes for the optimisations. Concrete optimisations are implemented as Passes that work with some portion of program code (e.g. Module, Function, Loop, etc.) to collect or transform this portion of the code. [LLV18a]

There are the following types of passes:

Analysis passes - Analysis passes collect information from the IR and feed it into the other passes. They can be also used for the debugging purposes, for example pass that counts number of functions in the module.

Examples:

- basiccg: Basic CallGraph Construction - dot-callgraph: Print Call Graph to "dot" file - instcount: Counts the various types of Instructions

Transform passes - Transform passes change the program in some way. They can use some analysis pass that has been ran before and produced some information.

Examples:

- dce: Dead Code Elimination - loop-deletion: Delete dead loops - loop-unroll: Unroll loops

Utility passes - Utility passes do not fit into analysis passes or transform passes categories.

Examples:

- verify: Module Verifier - view-cfg: View CFG of function - instnamer: Assign names to anonymous instructions

## 2.3 Clang

"The Clang project provides a language front-end and tooling infrastructure for languages in the C language family"

Features and Goals (some overview of clang): - End-User Features - Utility and Applications - Internal Design and Implementation

AST - what is AST - AST in clang - Differences between clang AST and other compilers ASTs - We will not use clangs AST, we will work directly with IR, it better suits this project

# 3 Extracting Program Subsets

In this chapter, we introduce the method for extracting parts of programs from the provided user input.

Starting with the method overview in the section 3.1 where we define what is the user input and briefly outline the method itself, what it does and what are the steps for achieving the final result.

We follow with the example of the method from the user perspective in the section 3.2.

After example, we present in detail each major step that is followed. Starting with computing data dependencies graph (section 3.3). Following with the procedure for finding connected components in the computed data dependencies graph (section 3.4). Next follows introduction of the call graph (section 3.5) and subsequently procedure for finding path from source to target in it (section 3.6). The chapter ends with the section describing methods on eliminating dead components and functions from the code (section 3.7).

## 3.1 Method Overview

Mandatory **input** for the method is a touple with the following definition:

$$input \equiv (code, target)$$

where:

- **code** is a C program source code compiled into the llvm bytecode.
- **target** is an integer value representing line of code from the C program source code.

We also define **source** as an entry to the C program (`main` function).

The method determines what parts of the *input* to extract according to the *source* and *target*. Procedure subsequently calculates possible execution path up to the *target* and extracts this execution path into the separate, functioning executable.

Barring implementation specific details (which are discussed in the chapter 4), the method can be summarized by the following five steps:

1. Compute data dependencies between instructions.

2. Find connected components in the computed data dependencies inside every function.

3. Construct call graph, mapping between connected components and functions that are being called from these components.

4. Find path from source to target in the call graph.

5. Eliminate dead components and functions that do not depend on the path.

Upon completion of the steps mentioned above, the llvm bytecode is produced as an *output*. We can define **output** as the extracted part of the original program according to the *source* and *target* while keeping the consistency of the code intact. By **consistency**, we mean that the *output* code is in a such state that it was possible to be compiled. *Output* is expected to be runnable the same way as the original. **\*\*TODO? explain more here or in another chapter what it means for IR to be compiled without problems?\*\***

## 3.2 Example

User provided us with the *input* in the form of the following C program source code that is stored in the file `example.c`:

─────────────────────────── example.c ───────────────────────────
```c
int foo(int n) {
    int x = n + 10;
    return x;
}

int bar(void) {
    int y = 42;
    return y;
}

int main(void) {
    int some_int = 10;
    int foo_result = foo(some_int);
    int bar_result = bar();
    return 0;
}
```

Since our method does not work directly with the C source code but instead works with the LLVM Intermediate Representation (IR), lets use clang and emit IR from the presented C source code in order to demonstrate the procedure more clearly: [1]

```
clang -S -emit-llvm example.c -o example.s
```

───────

1.  Flag `-S` tells clang to only run preprocess and compilation steps, while `-emit-llvm` makes sure to use the LLVM representation for assembler and object files. For detailed description of various clang flags, visit https://clang.llvm.org/docs/ClangCommandLineReference.html.

Emitted LLVM IR is stored in the file `example.s` and has the following structure:[2]

```
                            example.s
1  define i32 @foo(i32 %n) #0 {
2  entry:
3    %n.addr = alloca i32, align 4
4    %x = alloca i32, align 4
5    store i32 %n, i32* %n.addr, align 4
6    %0 = load i32, i32* %n.addr, align 4
7    %add = add nsw i32 %0, 10
8    store i32 %add, i32* %x, align 4
9    %1 = load i32, i32* %x, align 4
10   ret i32 %1
11 }
12
13 define i32 @bar() #0 {
14 entry:
15   %y = alloca i32, align 4
16   store i32 42, i32* %y, align 4
17   %0 = load i32, i32* %y, align 4
18   ret i32 %0
19 }
20
21 define i32 @main() #0 {
22 entry:
23   %retval = alloca i32, align 4
24   %some_int = alloca i32, align 4
25   %foo_result = alloca i32, align 4
26   %bar_result = alloca i32, align 4
27   store i32 0, i32* %retval, align 4
28   store i32 10, i32* %some_int, align 4
29   %0 = load i32, i32* %some_int, align 4
30   %call = call i32 @foo(i32 %0)
31   store i32 %call, i32* %foo_result, align 4
32   %call1 = call i32 @bar()
33   store i32 %call1, i32* %bar_result, align 4
34   ret i32 0
35 }
```

User also provided the line number **7** from the `example.c` as the target, which corresponds to the line **16** from the `example.s`. Source is the main function.

---

2. Strictly speaking, this is not exactly the IR code that would be emitted by the clang. We have stripped it out of the module info and comments to make it more readable. To see the unmodified `example.s`, please go to the Appendix C.

Procedure for finding mapping between C code referenced by the user input and its analogous IR instruction is implementation detail and is be described in the chapter 4.

When we apply the method on the contents of the `example.s` with respect to the source and target, we get the result stored in the file `example_extracted.s` with the following code:

```
─────────────────── example_extracted.s ───────────────────
define i32 @bar() #0 {
entry:
  %y = alloca i32, align 4
  store i32 42, i32* %y, align 4
  ret i32 %0
}

define i32 @main() #0 {
entry:
  %bar_result = alloca i32, align 4
  %call1 = call i32 @bar()
  store i32 %call1, i32* %bar_result, align 4
  ret i32 0
}
```

As we can see from the `example.c`, execution path from the program entry in the `main` function (which we will call **source**) to the **target** does not include function `foo` and its associated instructions, they can be removed. We are left only with function `bar` which contains target, and necessary instructions in the function `main` along with the `main` itself.

We can now take `example_extracted.s` and recompile it back into the functioning executable.[3]

## 3.3 Computing Data Dependencies

In order to identify what parts of the IR we can afford to remove, it is imperative to compute dependencies between instructions. When removing instructions, we need to preserve consistency of the remaining code so that it can be later compiled into a functional executable. To ensure this, we first compute dependencies among instructions.

We recognize two types of dependencies between IR instructions: control and data dependencies. The following terminology and procedures for computing dependencies that we use are due to the Marek Chalupa master's thesis *Slicing of LLVM Bitcode* [CHA25].

─────────

3.   More about recompilation in the chapter 4.

- "**Control dependence** explicitly states what nodes are controlled by which predicate."

- "A **data dependence** edge is between nodes n and m iff n defines a variable that m uses and there is no intervening definition of that variable on some path between n and m. In other words, the definitions from n reach uses in m."

The crucial information comes from data dependencies. We need to make sure that the IR integrity will remain intact after we are done with removing IR instructions.

The following example demonstrates data dependencies for the previously presented `example.c` source code. Taking closer look specifically at the function `main`:

```
define i32 @main() #0 {
entry:
  %retval = alloca i32, align 4
  %some_int = alloca i32, align 4
  %foo_result = alloca i32, align 4
  %bar_result = alloca i32, align 4
  store i32 0, i32* %retval, align 4
  store i32 10, i32* %some_int, align 4
  %0 = load i32, i32* %some_int, align 4
  %call = call i32 @foo(i32 %0)
  store i32 %call, i32* %foo_result, align 4
  %call1 = call i32 @bar()
  store i32 %call1, i32* %bar_result, align 4
  ret i32 0
}
```

Taking `main` code, we can construct graph G where V is set of vertices (in our case vertex is instruction) and E is set of edges (in our case, edge between vertices V1 and V2 represents data dependency between instruction V1 and V2). In order to compute data dependencies, we use `dg` library. [CHA25] [4]

Computed **data dependency graph** for instructions from the function `main` is presented in the Figure 3.1. This graph is stored and used in the next step of the method for finding connected components (section 3.4).

Taking a closer look at the instruction: `%some_int = alloca i32, align` 4. We see that the following instructions have data dependency on the `%some_int`

```
  store i32 10, i32* %some_int, align 4
  %0 = load i32, i32* %some_int, align 4
```

---

4. For more info please visit https://github.com/mchalupa/dg [CHA25]. We will take a closer look at `dg` in the chapter 4.
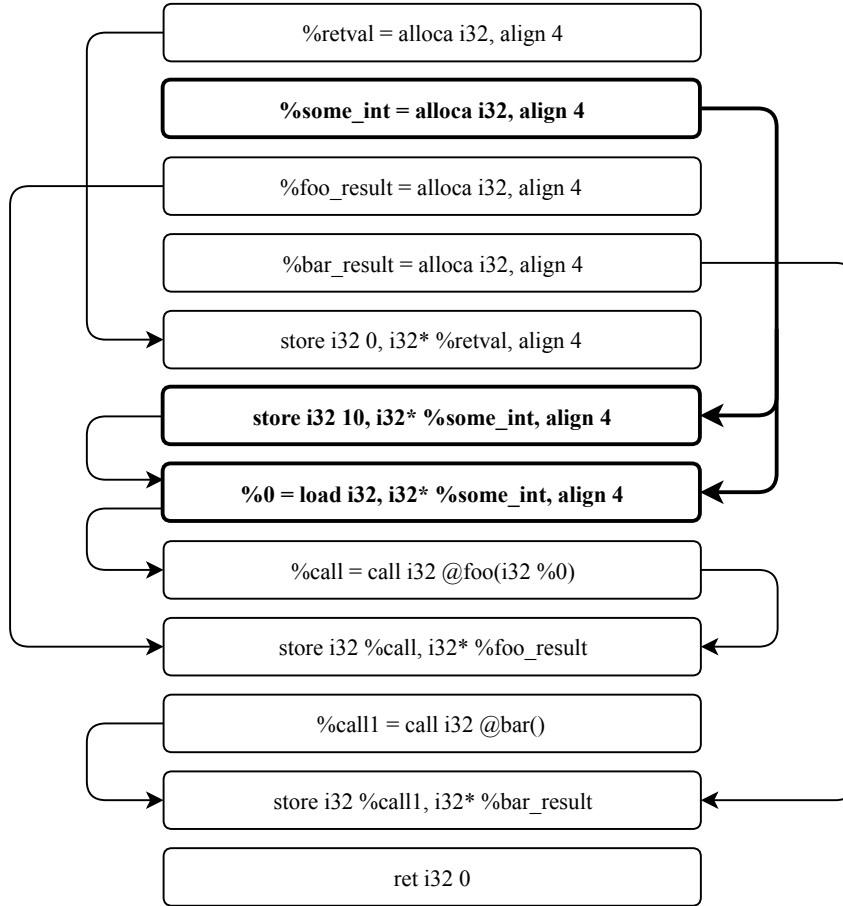
Figure 3.1: Data dependencies graph of the `main` function instructions.

It is apparent that both instructions need `%some_int` for their operand. If we removed `%some_int = alloca i32, align 4` without taking into consideration that there are two instructions that depend on it, we would get into inconsistent state and two dependent instructions would contain undefined values as their operand.[5] This would lead into unsuccessful recompilation of the modified code back into the executable.

## 3.4 Finding Connected Components

Having shown in the previous section what are inter-instruction data dependencies and how important they are in relation to the code consistency. However, they do not fully solve our problem of knowing when it is safe to remove instruction. Data dependencies between only two instructions do not reveal the whole picture. Since we have computed and stored graph of data dependencies, let us propose the idea of computing connected components of this graph.

───────

5. More about undefined values at https://llvm.org/docs/LangRef.html#undefined-values, https://llvm.org/docs/FAQ.html#what-is-this-undef-thing-that-shows-up-in-my-code, https://llvm.org/doxygen/classllvm_1_1UndefValue.html

We define **connected component** as an isolated subgraph, where each pair of vertices is connected by some path.

We use **data dependency graph** computed in the section section 3.3 to find its connected components by using the following algorithm:

```
──────────────────────── finding components ────────────────────────
0. Let G = data dependency graph
1. Run Breadth-first search [Cor+09] on G to visit each instruction
2. IF instruction not in any component:
       create new component and put instruction inside
   ELSE:
       go to next instruction
```

Running the above mentioned algorithm on the **data dependency graph** produces connected components for each function in the input. As an example, we present components for the `main` function in the Figure 3.2 (for the clarity, each component has its own color).

Having instructions within each function separated into connected components comes useful especially because we can answer the question if some particular instruction is in data dependency relationship with multiple other instructions (instructions that form a data dependency path, etc.).

## 3.5 Computing Call Graph

In respect to the program execution flow, user provided the target and we know the source. In order to proceed further, it is needed to compute possible paths from source to target that could be used by the execution of the program. Computing and walking the call graph of the program can produce for us this piece of information.

A **call graph**[6] is a control flow graph that represents relationship between program procedures in respect to control flow.[SSK09] Having call graph $G = \{V, E\}$, set of vertices $V$ typically represents functions and set of edges $E$ represents transfer of control flow from one function to another.

In our context, call graph represents relationship between individual connected components (computed in the section 3.4) and functions that are being called from these components by one of its instructions. In other words, our call graph is a set of mappings from components to the function (or functions).

We construct the call graph using the following algorithm:

──────────

6.   More technically, *call multigraph* [SSK09].
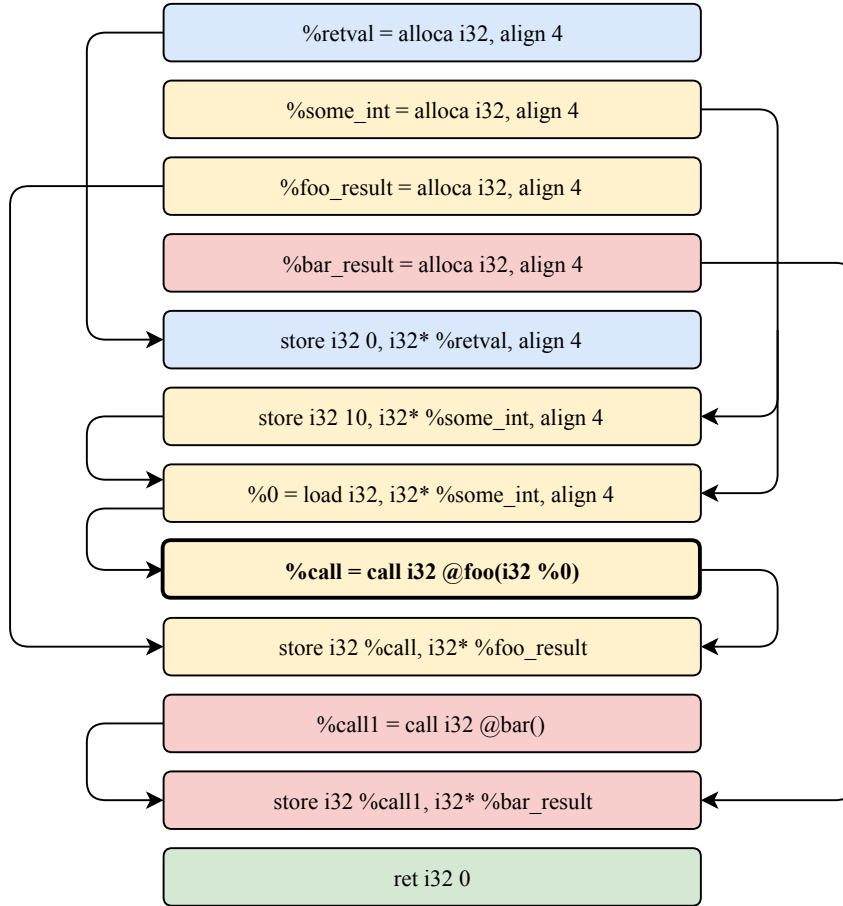
Figure 3.2: Connected components of the data dependencies graph for the `main` function instructions. Individual components are differentiated by the color.

```
─────────────────────── computing call graph ───────────────────────
0. Let FS = set of functions in the code
1. Let CS(f) = set of components inside function f
2. FOR EACH function F in the set FS:
      FOR EACH component C in the set CS(F):
         FOR EACH instruction I in the component C:
            IF instruction I is a call instruction to some function X:
               store information X gets called from the C
```

Running the presented algorithm on the **data dependence graph** of the `main` function that we computed earlier (Figure 3.2) produce call graph structure shown in the Figure 3.3. We know that in the context of the `main` function, there are four distinct components. We can see from the computed call graph, that `i32 @foo(i32 %n)` is being called from the *yellow* component, and `i32 @bar()` is being called from the *red* component.

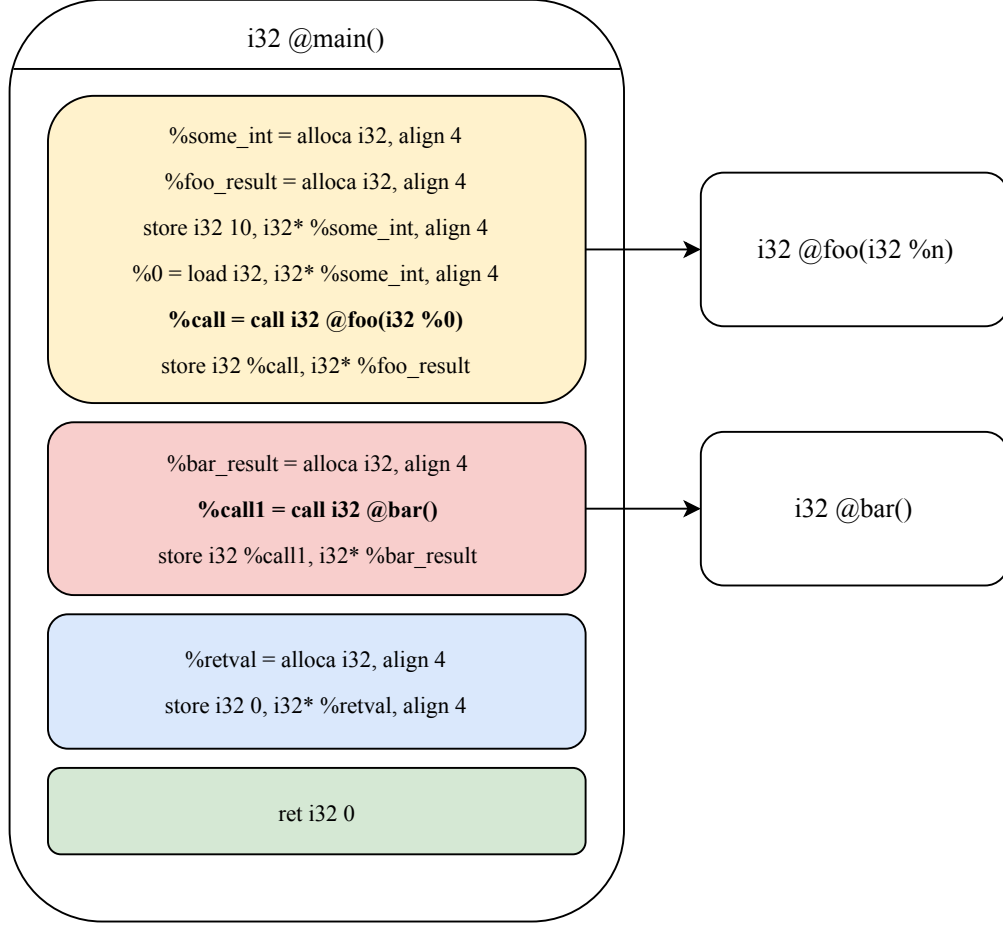Figure 3.3: Call graph computed from the connected components as shown in the Figure 3.2.

## 3.6 Finding Path from Source to Target

Having call graph represented in the structure shown in the Figure 3.3 is beneficial for finding program execution flow path between specific components within the program in relation to their dependencies. We can find path from source to target and know which components this path contains.

*"A **path** is a simple graph whose vertices can be arranged in a linear sequence in such a way that two vertices are adjacent if they are consecutive in the sequence, and are non-adjacent otherwise."*[BM08] In our case, linear sequence of vertices consists of components computed in the section 3.4.

The reason why we constructed call graph in the previous chapter is now apparent. We want to find a path from source to the target and in doing so, know which connected components are part of this path or not. Potentially, there may exist infinite number of such paths. From the optimization standpoint, it would be fitting to find all (or at least as many as we can) paths and pick some path according to selected optimization criteria (shortest path, path with smallest connected components, etc.). However, for our purposes, it will be sufficient to find any path, because our method does not try to optimize final

code in respect to size, speed, etc.

We will use the following algorithm in order to find a path from source to target in the call graph:

---

```
                              finding path
0. Let G = call graph
1. Run Breadth-first search on G to find path from source to target
```
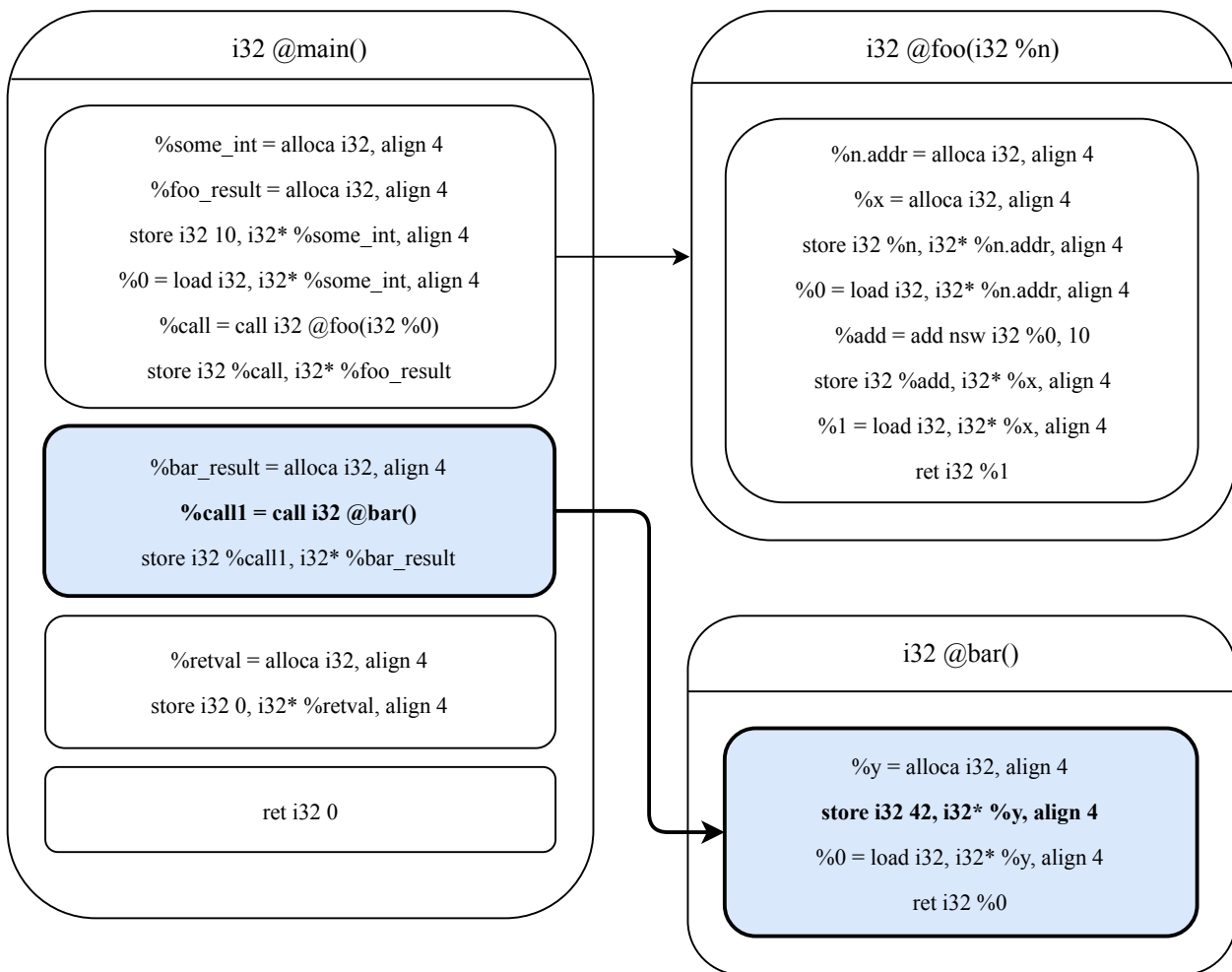
---



Figure 3.4: Path from **source** to **target** computed on the Figure 3.3. Components in the path are *blue*.

Given the source and target, we can see from the Figure 3.4 that path only contains two components, one from `main` function and another from `bar`. These two components are going to be the core of the final, extracted program.

## 3.7  Eliminating Dead Components and Functions

This section is the last step that the method performs. Components and functions that are dead are indentified and removed from the code and therefore, they will not be part of the final, extracted executable.

Element of the code marked as **dead** is defined as such, that it can be safely deleted without compromising integrity of the code. In other words, we can safely remove dead elements from the code without being worried that the execution starting from the source will not reach target.

Having successfully found path from source to target in the last section, we know that each component that is part of the path cannot be marked as dead. Therefore, components outside of path have to be explored and the decision found weather they can be marked as dead and removed or not.

We can use the following basic algorithm for finding and eliminating dead components:

```
———————————————————— eliminating dead components ————————————————————
0. Let CS = set of all components in the code
1. Let PATH = set of components on the path from source to target
2. FOR EACH component C IN set CS:
       IF component C is not in the set PATH:
          IF component C does not contain terminator:
               mark component C as DEAD
3. remove all components marked as DEAD
```

After applying the presented algorithm for eliminating dead components on the code from `example.s` we get the result that is visualised in the Figure 3.5. We can see components marked as dead are colored *red* because they are not part of the path. The *yellow* component with the single instruction stands out. This component is not marked as dead and will not be removed because it contains terminator instruction `ret i32` 0.[7] Finally, all components marked as dead are removed and we are left with the code that we presented in the section 3.2 (`example_extracted.s`). Contents of the `example_extracted.s` are visualized in the Figure 3.6.

Unfortunately, the algorithm presented above works correctly only on the simple, non-complex inputs that are similar to the `example.s`. We will present two slightly more complicated programs to reveal the flaws of this algorithm. In order for method to work correctly, algorithm for eliminating dead components has to be extended to account for the introduced input complexities.

—————

7.  https://llvm.org/doxygen/classllvm_1_1TerminatorInst.html More about terminators and why they need special treatment in the chapter 4.
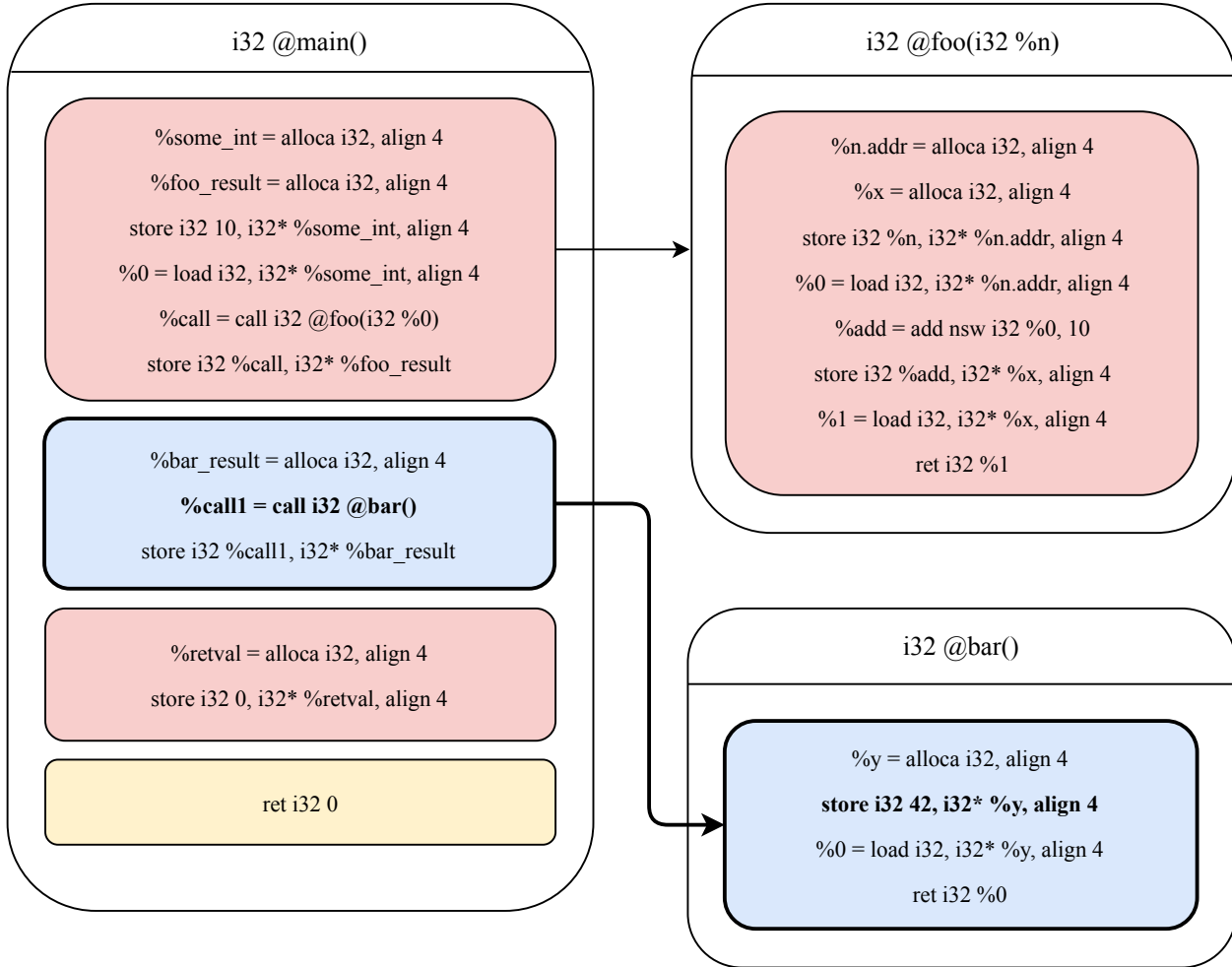
Figure 3.5: `example.s`: Components selected for removal are marked *red*. *Yellow* component is not marked for removal, because it contains terminator.

### 3.7.1 Path Depending on the External Function

```
                              example_mod1.c
 1   int foo(int n) {
 2       int x = n + 10;
 3       return x;
 4   }
 5
 6   int qux(void) {
 7       return 42;
 8   }
 9
10   int bar(void) {
11       int y = qux();
12       return y;
13   }
```

Figure 3.6: `example_extracted.s`: Final state after removing dead components and functions.

```
14
15  int main(void) {
16      int some_int = 10;
17      int foo_result = foo(some_int);
18      int bar_result = bar();
19
20      return 0;
21  }
```

—————————————————— example_mod1.s ——————————————————

```
1   define i32 @foo(i32 %n) #0 {
2   entry:
3     %n.addr = alloca i32, align 4
4     %x = alloca i32, align 4
5     store i32 %n, i32* %n.addr, align 4
6     %0 = load i32, i32* %n.addr, align 4
7     %add = add nsw i32 %0, 10
8     store i32 %add, i32* %x, align 4
9     %1 = load i32, i32* %x, align 4
10    ret i32 %1
11  }
12
13  define i32 @qux() #0 {
14  entry:
15    ret i32 42
16  }
17
18  define i32 @bar() #0 {
```

```llvm
19   entry:
20     %y = alloca i32, align 4
21     %call = call i32 @qux()
22     store i32 %call, i32* %y, align 4
23     %0 = load i32, i32* %y, align 4
24     ret i32 %0
25   }
26
27   define i32 @main() #0 {
28   entry:
29     %retval = alloca i32, align 4
30     %some_int = alloca i32, align 4
31     %foo_result = alloca i32, align 4
32     %bar_result = alloca i32, align 4
33     store i32 0, i32* %retval, align 4
34     store i32 10, i32* %some_int, align 4
35     %0 = load i32, i32* %some_int, align 4
36     %call = call i32 @foo(i32 %0)
37     store i32 %call, i32* %foo_result, align 4
38     %call1 = call i32 @bar()
39     store i32 %call1, i32* %bar_result, align 4
40     ret i32 0
41   }
```

―――――――――――――――― example_mod1_extracted.s ――――――――――――――――

```llvm
1    define i32 @qux() #0 {
2    entry:
3      ret i32 42
4    }
5
6    define i32 @bar() #0 {
7    entry:
8      %y = alloca i32, align 4
9      %call = call i32 @qux()
10     store i32 %call, i32* %y, align 4
11     %0 = load i32, i32* %y, align 4
12     ret i32 %0
13   }
14
15   define i32 @main() #0 {
16   entry:
17     %bar_result = alloca i32, align 4
18     %call1 = call i32 @bar()
19     store i32 %call1, i32* %bar_result, align 4
```

22

```
20    ret i32 0
21  }
```

### 3.7.2 Path Depending on the Branching Instruction

———————————— example_mod2.c ————————————

```
1   int foo(int n) {
2       int x = n + 10;
3       return x;
4   }
5
6   int qux(void) {
7       return 42;
8   }
9
10  int bar(void) {
11      int y = qux();
12      return y;
13  }
14
15  int main(void) {
16      int some_int = 10;
17      int foo_result = foo(some_int);
18      int n = 10;
19      if (n < 42) {
20          int bar_result = bar();
21      }
22      return 0;
23  }
```
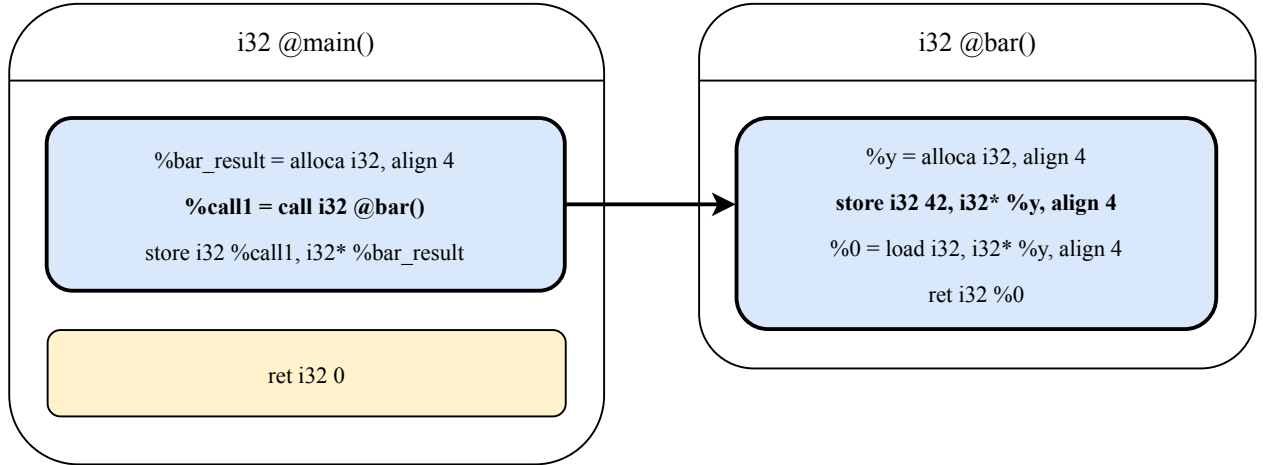
———————————— example_mod2.s ————————————

```
1   define i32 @foo(i32 %n) #0 {
2   entry:
3     %n.addr = alloca i32, align 4
4     %x = alloca i32, align 4
5     store i32 %n, i32* %n.addr, align 4
6     %0 = load i32, i32* %n.addr, align 4
7     %add = add nsw i32 %0, 10
8     store i32 %add, i32* %x, align 4
9     %1 = load i32, i32* %x, align 4
10    ret i32 %1
11  }
```

```
12
13  define i32 @qux() #0 {
14  entry:
15    ret i32 42
16  }
17
18  define i32 @bar() #0 {
19  entry:
20    %y = alloca i32, align 4
21    %call = call i32 @qux()
22    store i32 %call, i32* %y, align 4
23    %0 = load i32, i32* %y, align 4
24    ret i32 %0
25  }
26
27  define i32 @main() #0 {
28  entry:
29    %retval = alloca i32, align 4
30    %some_int = alloca i32, align 4
31    %foo_result = alloca i32, align 4
32    %n = alloca i32, align 4
33    %bar_result = alloca i32, align 4
34    store i32 0, i32* %retval, align 4
35    store i32 10, i32* %some_int, align 4
36    %0 = load i32, i32* %some_int, align 4
37    %call = call i32 @foo(i32 %0)
38    store i32 %call, i32* %foo_result, align 4
39    store i32 10, i32* %n, align 4
40    %1 = load i32, i32* %n, align 4
41    %cmp = icmp slt i32 %1, 42
42    br i1 %cmp, label %if.then, label %if.end
43
44  if.then:                                      ; preds = %entry
45    %call1 = call i32 @bar()
46    store i32 %call1, i32* %bar_result, align 4
47    br label %if.end
48
49  if.end:                                       ; preds = %if.then, %entry
50    ret i32 0
51  }
```

example_mod2_extracted.s

```
1  define i32 @qux() #0 {
2  entry:
```

24

```llvm
  ret i32 42
}

define i32 @bar() #0 {
entry:
  %y = alloca i32, align 4
  %call = call i32 @qux()
  store i32 %call, i32* %y, align 4
  %0 = load i32, i32* %y, align 4
  ret i32 %0
}

define i32 @main() #0 {
entry:
  %n = alloca i32, align 4
  %bar_result = alloca i32, align 4
  store i32 10, i32* %n, align 4
  %0 = load i32, i32* %n, align 4
  %cmp = icmp slt i32 %0, 42
  br i1 %cmp, label %if.then, label %if.end

if.then:                                          ; preds = %entry
  %call1 = call i32 @bar()
  store i32 %call1, i32* %bar_result, align 4
  br label %if.end

if.end:                                           ; preds = %if.then, %entry
  ret i32 0
}
```
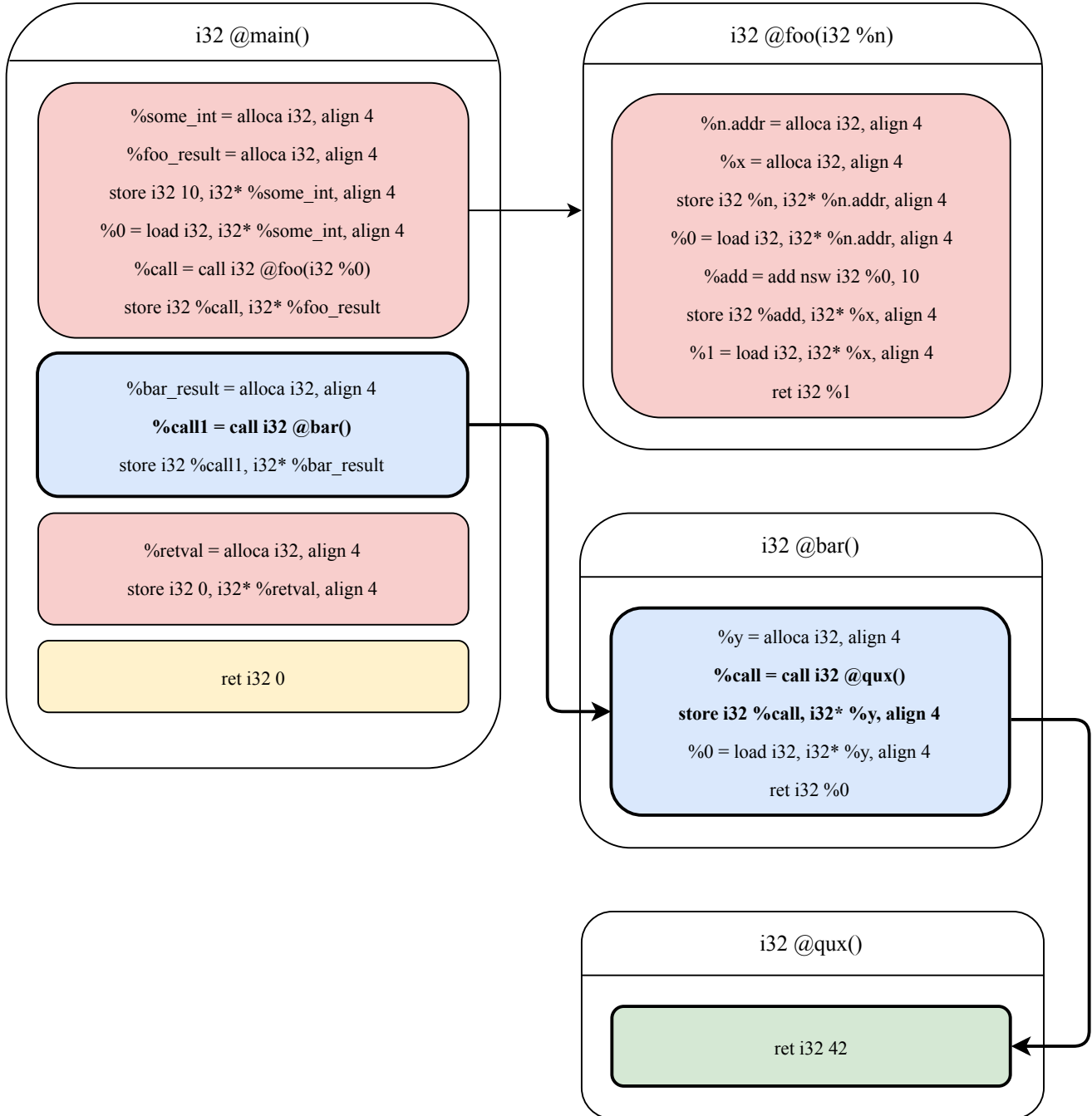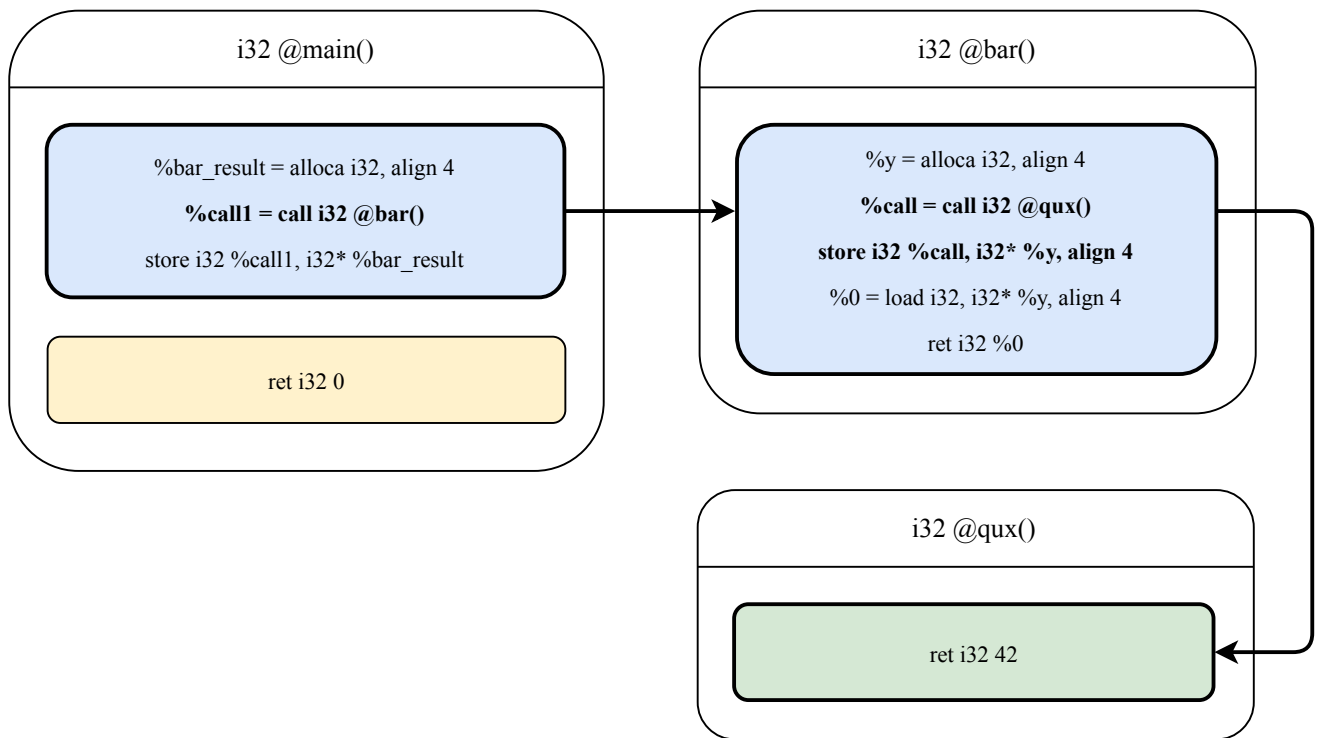
25

Figure 3.7: TODO: Caption

Figure 3.8: TODO: Caption

i32 @main()

%some_int = alloca i32, align 4
%foo_result = alloca i32, align 4
store i32 10, i32* %some_int, align 4
%0 = load i32, i32* %some_int, align 4
%call = call i32 @foo(i32 %0)
store i32 %call, i32* %foo_result

%retval = alloca i32, align 4
store i32 0, i32* %retval, align 4

%n = alloca i32, align 4
store i32 10, i32* %n, align 4
%1 = load i32, i32* %n, align 4
%cmp = icmp slt i32 %1, 42
br i1 %cmp, label %if.then, label %if.end

%bar_result = alloca i32, align 4
**%call1 = call i32 @bar()**
store i32 %call1, i32* %bar_result

br label %if.end

ret i32 0

i32 @foo(i32 %n)

%n.addr = alloca i32, align 4
%x = alloca i32, align 4
store i32 %n, i32* %n.addr, align 4
%0 = load i32, i32* %n.addr, align 4
%add = add nsw i32 %0, 10
store i32 %add, i32* %x, align 4
%1 = load i32, i32* %x, align 4
ret i32 %1

i32 @bar()

%y = alloca i32, align 4
**%call = call i32 @qux()**
**store i32 %call, i32* %y, align 4**
%0 = load i32, i32* %y, align 4
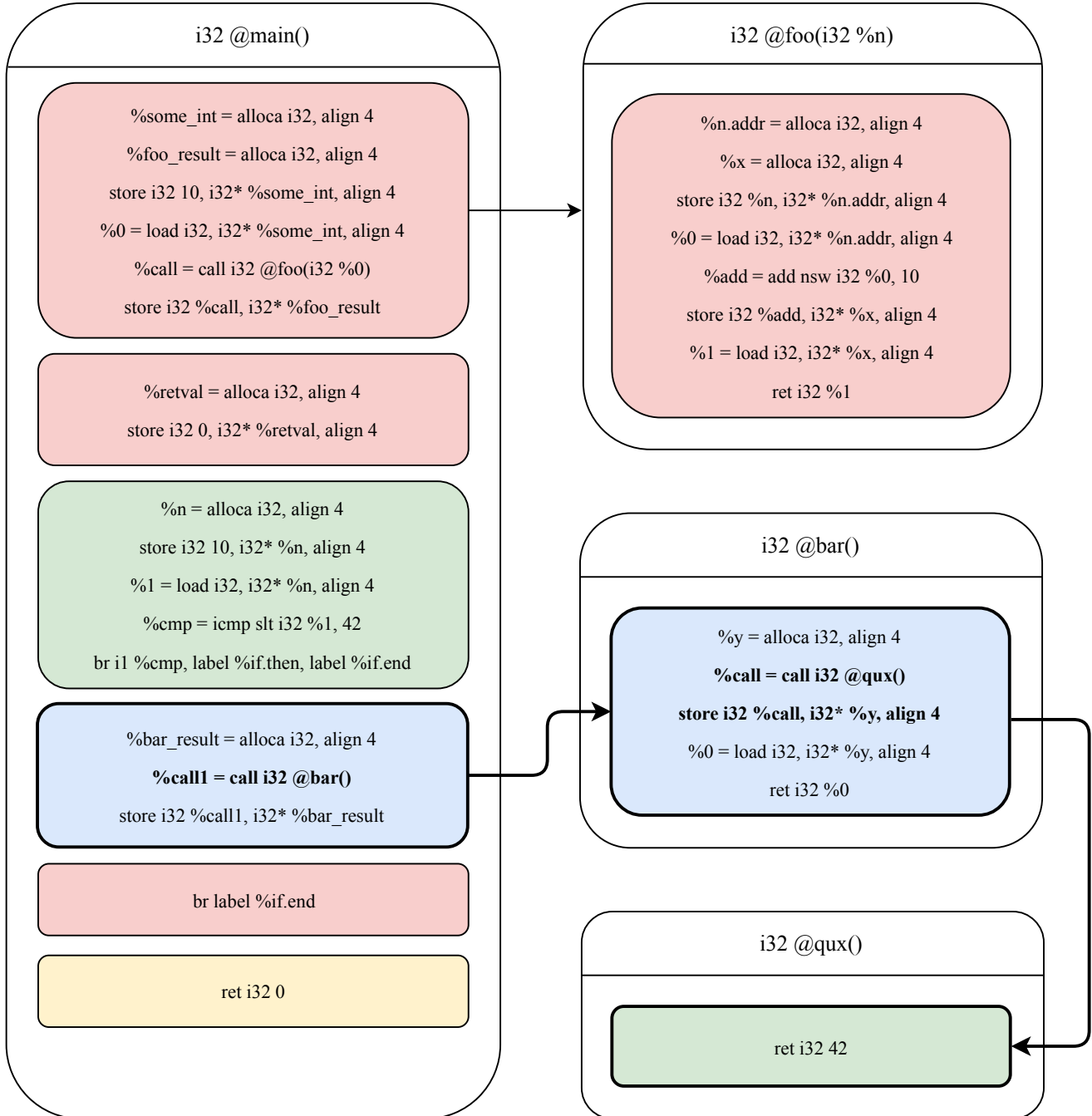ret i32 %0

i32 @qux()
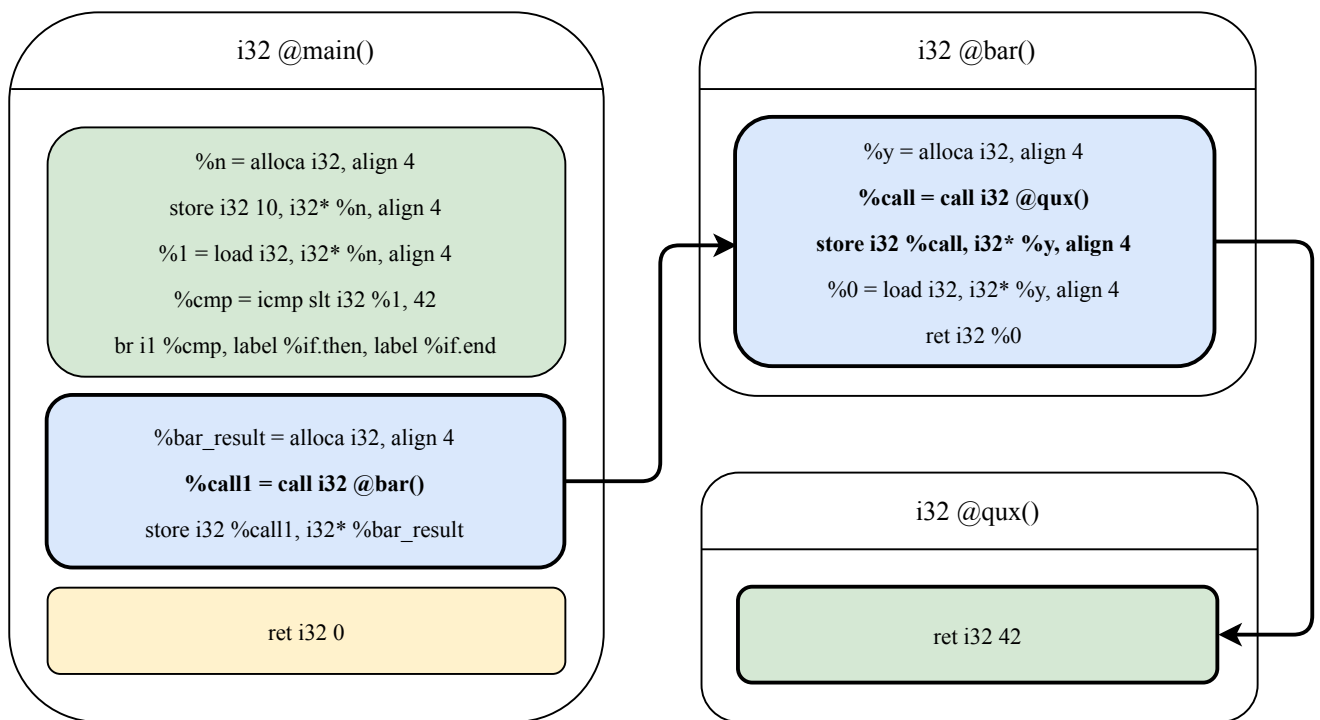
ret i32 42

Figure 3.9: TODO: Caption

Figure 3.10: TODO: Caption

# 4 Implementation: TODO

## 4.1 APEX

### 4.1.1 what is APEX

### 4.1.2 two components of apex

1. launcher

2. APEXPass

## 4.2 Launcher

### 4.2.1 compiling input to bytecode with dbg symbols

### 4.2.2 running basic opts

### 4.2.3 linking input with apexlib

### 4.2.4 running apexpass

### 4.2.5 exporting call graph, dependency graph, disassembly bc

### 4.2.6 running final binaries

## 4.3 APEXPass

### 4.3.1 User Inpur Parsing, Mapping C code to IR

### 4.3.2 Compute data dependencies between instructions.

- running dg, init apexdg

### 4.3.3 Find connected components in the apexdg.

### 4.3.4 Construct call graph, mapping between connected components and functions that are being called from these components.

### 4.3.5 Find path from source to target in the call graph.

### 4.3.6 Eliminate dead components and functions that do not depend on the path.

The simplest and seemingly correct way would be to remove every connected component that is not part of the path that we calculated in the earlier chapter.

This approach would unfortunately produce inconsistent IR. It not enough to remove only components in the path. We need to include every other component that is dependent on any other component that is already part of the path.

Checking if we have any branching dependent on the @path

1. investigating block, collecting basic blocks

2. block has no instruction in "if.*" basic block

3. block has some instruction in "if.*" basic block

4. Find branch instruction that services this BB and add block associated with this branch instruction to the @path.

Computing what dependency blocks we want to keep

1. marking every block from @path as to keep

2. Mark as visited to make sure we do not process this block in BFS.

3. setting up initial queue for BFS search

4. Go over @path and figure out if there are any calls outside the @path. If there are, put those called blocks for investigation into the @queue.

5. running BFS

6. Run BFS from queue and add everything for keeping that is not visited.

7. Collecting everything that we do not want to keep

8. We store blocks and functions that we want to remove into sets.

Removing unwanted blocks

1. Remove instructions that we stored earier. Watch out for terminators (do not remove them).

2. Do not erase instruction that is inside target instructions (We need those instructions intact.)

### 4.3.7 Injecting extraction and exit

### 4.3.8 Recompilation, stripping debug symbols

## 4.4 Recompilation back to the executable

# 5 Experiments: TODO

# 6 Conclusions: TODO

## 6.1 Summary of the Results

## 6.2 Further Research and Development

# Bibliography

[BM08]    J. Bondy and U. Murty, *Graph theory*, 1st. Springer Publishing Company, Incorporated, 2008, ISBN: 1846289696.

[CHA25]   M. CHALUPA, "Slicing of llvm bitcode [online]", Master's thesis, Masaryk University, Faculty of Informatics, Brno, 2016 [cit. 2018-11-25]. [Online]. Available: `Available%20from%20WWW%20%3Chttps://is.muni.cz/th/vik1f/%3E`.

[Cor+09]  T. H. Cormen, C. E. Leiserson, R. L. Rivest, and C. Stein, *Introduction to algorithms, third edition*, 3rd. The MIT Press, 2009, ISBN: 0262033844, 9780262033848.

[LLV18a]  LLVM. (2018). LLVM's Analysis and Transform Passes, [Online]. Available: `https://llvm.org/docs/Passes.html` (visited on 11/09/2018).

[LLV18b]  ——, (2018). The LLVM Compiler Infrastructure, [Online]. Available: `https://llvm.org/` (visited on 11/03/2018).

[SSK09]   A. Sanyal, B. Sathe, and U. Khedker, *Data flow analysis: Theory and practice*. CRC Press, 2009.

# A  Archive structure

Content of the attached archive:

TBA TBA TBA

# B Outline

Extracting Parts of Programs into Separate Binaries

1. Get acquainted with means of the compilation of C programs using the LLVM compiler infrastructure - clang, LLVM Internal Representation, AST, LLVM optimizations.

2. Propose a solution to statically transplant a subset of a C program. This subset should be extracted from the original program and synthesized as an independent binary.

3. Design and implement the proposed solution in a tool having an appropriate form (a standalone application or an LLVM plugin).

4. Test the implemented tool on at least 2 real-world open-source C programs.

---

- Introdution
  - Give introduction to wider context
  - Clearly explain aim of the thesis
  - Give outline of the following chapters

- The LLVM Compiler Infrastructure
  - IR
  - Optimizations
  - clang

- Extracting Program Subsets
  - Intro
  - 
  - Computing Data Dependencies
  - Finding Connected Components
  - Constructing Call Graph
  - Finding Path
  - Removing Unnecessary Parts

- Implementation
  - APEX
  - APEXPass
  - Input Source Code
  - Parsing User Input (Locating Target Instructions)
  - Computing Dependencies using dg
  - Extracting Target Data (Injecting Exit and Extraction)
    * Stripping debug symbols

- Experiments
  - Experiment 1
  - Experiment 2

- Experiment 3

- Conclusion
  - Show our contribution to the problem
  - Show wider image in context to this thesis

# C `example.s`

```llvm
; ModuleID = 'example.c'
source_filename = "example.c"
target datalayout = "e-m:e-i64:64-f80:128-n8:16:32:64-S128"
target triple = "x86_64-unknown-linux-gnu"

; Function Attrs: noinline nounwind optnone uwtable
define i32 @foo(i32 %n) #0 {
entry:
  %n.addr = alloca i32, align 4
  %x = alloca i32, align 4
  store i32 %n, i32* %n.addr, align 4
  %0 = load i32, i32* %n.addr, align 4
  %add = add nsw i32 %0, 10
  store i32 %add, i32* %x, align 4
  %1 = load i32, i32* %x, align 4
  ret i32 %1
}

; Function Attrs: noinline nounwind optnone uwtable
define i32 @bar() #0 {
entry:
  %y = alloca i32, align 4
  store i32 42, i32* %y, align 4
  %0 = load i32, i32* %y, align 4
  ret i32 %0
}

; Function Attrs: noinline nounwind optnone uwtable
define i32 @main() #0 {
entry:
  %retval = alloca i32, align 4
  %some_int = alloca i32, align 4
  %foo_result = alloca i32, align 4
  %bar_result = alloca i32, align 4
  store i32 0, i32* %retval, align 4
  store i32 10, i32* %some_int, align 4
  %0 = load i32, i32* %some_int, align 4
  %call = call i32 @foo(i32 %0)
  store i32 %call, i32* %foo_result, align 4
  %call1 = call i32 @bar()
  store i32 %call1, i32* %bar_result, align 4
```

```
42    ret i32 0
43  }
44
45  attributes #0 = { noinline nounwind optnone uwtable
    ↪   "correctly-rounded-divide-sqrt-fp-math"="false"
    ↪   "disable-tail-calls"="false" "less-precise-fpmad"="false"
    ↪   "no-frame-pointer-elim"="true" "no-frame-pointer-elim-non-leaf"
    ↪   "no-infs-fp-math"="false" "no-jump-tables"="false"
    ↪   "no-nans-fp-math"="false" "no-signed-zeros-fp-math"="false"
    ↪   "no-trapping-math"="false" "stack-protector-buffer-size"="8"
    ↪   "target-cpu"="x86-64" "target-features"="+fxsr,+mmx,+sse,+sse2,+x87"
    ↪   "unsafe-fp-math"="false" "use-soft-float"="false" }
46
47  !llvm.module.flags = !{!0}
48  !llvm.ident = !{!1}
49
50  !0 = !{i32 1, !"wchar_size", i32 4}
51  !1 = !{!"clang version 5.0.1 (tags/RELEASE_500/final)"}
```