

Chapter 2 Probability

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Definitions

Experiments: a process or an action that has an outcome that is now known beforehand.

- Flip a coin 3 times = $\{HHH, \dots, TTT\}$
- Flip " until first H.
 $\searrow \{H, TH, TTH, \dots\}$
- Wait for the bus
 $\{x: x \geq 0\}$

Sample space (S): the set of all possible (elementary) outcomes.

Weight height measuring $\Rightarrow S = \{(x, y) \mid x \geq 0, y \geq 0\}$

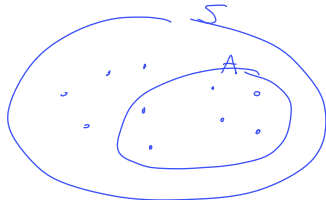
Event: a subset of S , $A, B, C, \dots \subset S$ $\phi \subset S$

Once an experiment is done, we know

whether an event has occurred or not.

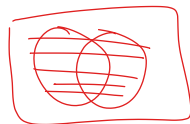
Set Operations

A^c ,



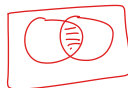
$$A, B \subset S$$

$A \cup B$: the event that A or B or both occur.

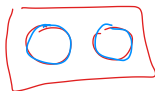


$A \cap B$: the event that both A and B occur ^{simultaneously} ~~at the same time~~.

$$A - B = A \cap B^c$$



Disjoint (Mutually exclusive) events: $A \cap B = \emptyset$



\neq Independent.

Probability of an event

Given an experiment and the sample space S , for each event $A \subset S$, a probability is an “assigned” value that measures the chance of occurrence. “numerical measure of uncertainty”

“nice”

Axioms of probability: Kolmogorov

- ▶ $P(A) \geq 0$
- ▶ $P(S) = 1$
- ▶ A_1, A_2, \dots : sequence of disjoint sets

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

Finite version : A_1, \dots, A_m , disjoint,

$$P\left(\bigcup_{i=1}^m A_i\right) = \sum_{i=1}^m P(A_i)$$

Probability

Many properties can be derived based on the axioms.

- $\textcircled{00}$ $A_1, \dots, A_m = \emptyset$ all empty sets
 disjoint, $\bigcup_{i=1}^m A_i = \emptyset$
 Axiom ③, LHS = $P(\emptyset)$
 RHS = $\sum_{i=1}^m P(\emptyset) = P(\emptyset) + \dots + P(\emptyset) = m P(\emptyset)$
 LHS = RHS $\Rightarrow P(\emptyset) = 0$
- ▶ $P(\emptyset) = 0$
 - ▶ $P(A^c) = 1 - P(A)$ DIY
 - ▶ $P(A) \leq 1 \rightarrow 1 - P(A) \geq 0 \Rightarrow P(A) \leq 1$
from and axiom ①
 - ▶ $P(A) \leq P(B)$ if $A \subset B$ DIY
 - ★ ▶ $P(A \cup B) = P(A) + P(B) - P(A \cap B)$.

 \downarrow
 $P(A \cap B^c) + P(B)$ Ax ③
 $= P(A) - P(A \cap B) + P(B)$
- $\overset{\text{disjoint}}{\curvearrowright}$
 $A \cup B = (A \cap B^c) \cup B$
 $\cdot A = (A \cap B) \cup (A \cap B^c)$
 $\underset{\text{disjoint}}{\curvearrowright}$

Probabilistic Statements

▶ How likely will an event occur?

▶ 20% of raining

▶ ~~Most likely to be~~ at home by 7pm

▶ We have a good chance of winning the championship this year.

Experiment = observe tomorrow's weather
record rain or not
 $S = \{\text{rain, norain}\}$

80%

stabilized

We interpret probability as the **long-run** **relative frequency**.

▶ repeat the experiment as many as possible and observe the proportion of times the event occurs. As the number of trials increases, the relative frequency tends to stabi- lize.

▶ The stabilized value can be served as Probability, which is unknown but can be esti- mated accurately by repeating the experiment many times.

- frequentist "

Counting Rules

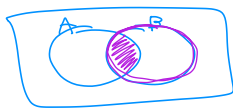
- ▶ $S = \{E_1, \dots, E_N\}$
- ▶ Elementary outcomes are equally likely. $P(\{E_i\}) = 1/N$
- ▶ $\forall A \subset S, P(A) = (\text{no. of elements})/N.$

Product Rule

Permutation

Combination

Conditional Probability



For $A, B \subset S$ with $P(B) > 0$,

Given information, we find
revised probability

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

is the conditional probability of A given that B has happened.

" B acts like new Sample Space"

► Revised probability due to new information

► $P(A \cap B) = P(A|B)P(B) = P(B|A)P(A).$