

Exceptional Control Flow: Exceptions and Processes

Entire system

CS230 System Programming
10th Lecture

Instructors:

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hit keyboard, outside interruption, ...

Today

- **Exceptional Control Flow**
- Exceptions
- Processes
- Process Control

Control Flow

- **Processors do only one thing:** at a time
 - From startup to shutdown, a CPU simply reads and executes (interprets) a sequence of instructions, one at a time
 - This sequence is the CPU's *control flow* (or *flow of control*) trace of instructions
- Physical control flow**



Altering the Control Flow

■ Up to now: two mechanisms for changing control flow:

- Jumps and branches *within program*
- Call and return *→ more restricted control flow*

React to changes in **program state**
condition codes, flags, ...

■ Insufficient for a useful system:

Difficult to react to changes in **system state**

- Data arrives from a disk or a network adapter *→ disk should notify processor should react*
- Instruction divides by zero *→ possible at runtime*
- User hits Ctrl-C at the keyboard
- System timer expires *→ at certain period of time*

Kill infinite loop

Create event → time is up!

■ System needs mechanisms for “exceptional control flow”

Exceptional Control Flow

■ Exists at all levels of a computer system

■ Low level mechanisms

■ 1. **Exceptions**

- Change in control flow in response to a system event (i.e., change in system state)
- Implemented using combination of hardware and OS software



■ Higher level mechanisms

■ 2. **Process context switch**

- Implemented by OS software and hardware timer

■ 3. **Signals** *→ events created by software*

- Implemented by OS software

■ 4. **Nonlocal jumps**: `setjmp()` and `longjmp()`

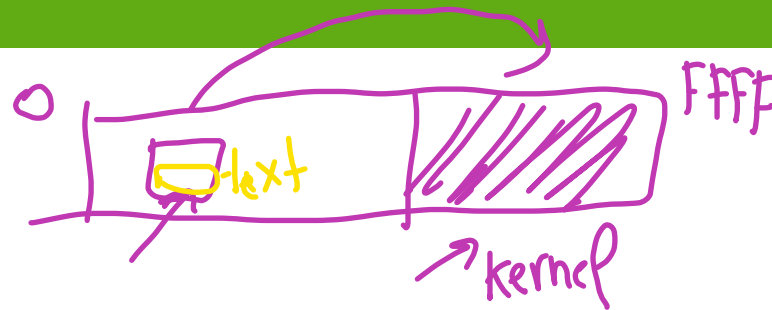
- Implemented by C runtime library

→ jumping outside of memory space

Today

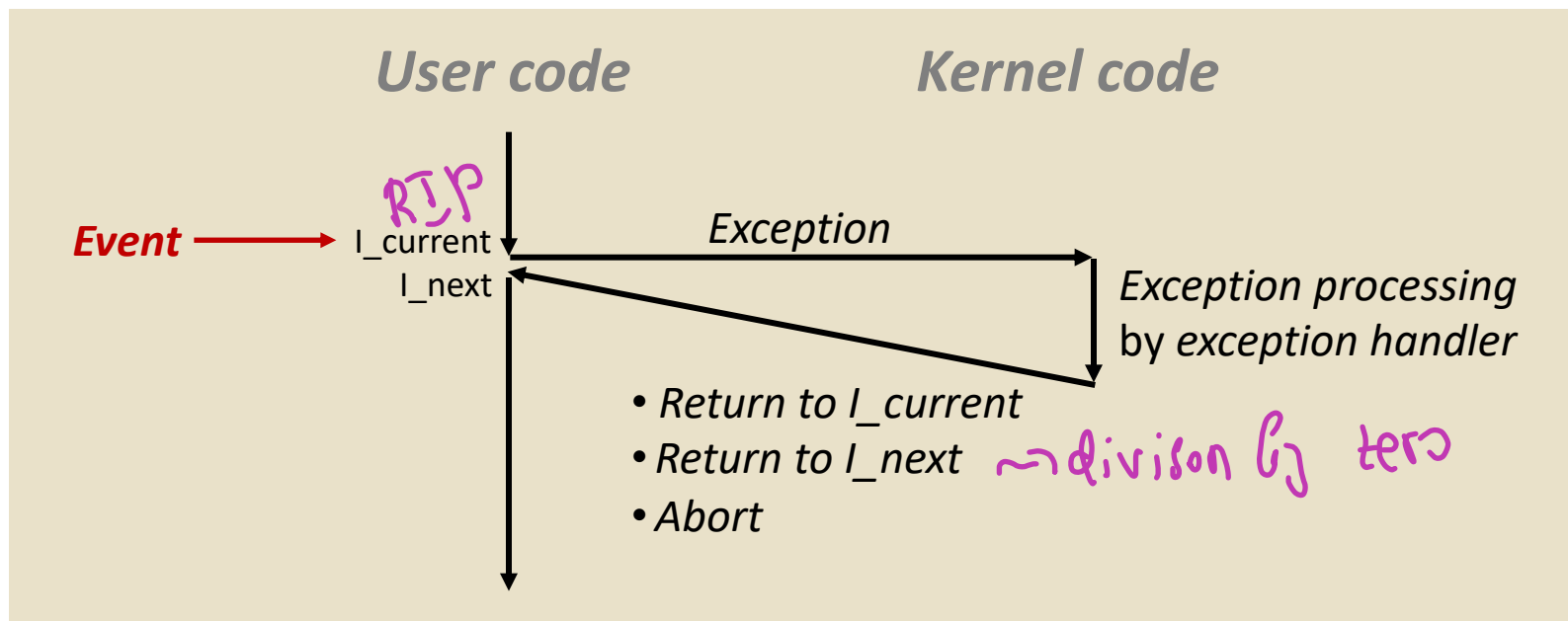
- Exceptional Control Flow
- **Exceptions**
- Processes
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Exceptions



- An **exception** is a transfer of control to the OS *kernel* in response to some *event* (i.e., change in processor state)

- ^{core} Kernel is the memory-resident part of the OS
- Examples of events: Divide by 0, arithmetic overflow, page fault, I/O request completes, typing Ctrl-C



Exception Tables

Kernel space

Exception numbers

Exception Table

0	•
1	•
2	•
...	
n-1	•

Code for exception handler 0

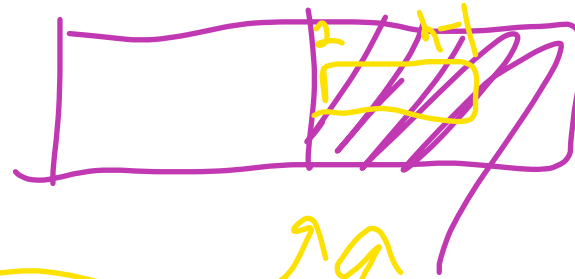
Code for exception handler 1

Code for exception handler 2

...

Code for exception handler n-1

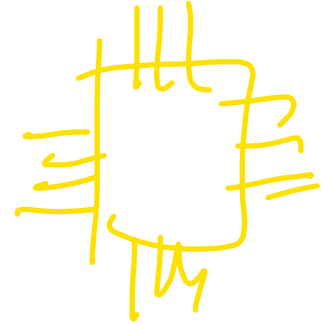
- Each type of event has a unique exception number k
- k = index into exception table (a.k.a. interrupt vector)
- Handler k is called each time exception k occurs



Asynchronous Exceptions (Interrupts)

■ Caused by events external to the processor

- Indicated by setting the processor's *interrupt pin*
- Handler returns to “next” instruction



■ Examples:

- Timer interrupt
 - Every few ms, an external timer chip triggers an interrupt
 - Used by the kernel to take back control from user programs
- I/O interrupt from external device
 - Hitting Ctrl-C at the keyboard
 - Arrival of a packet from a network
 - Arrival of data from a disk

} not controlled by processor

Synchronous Exceptions

- Caused by events that occur as a result of executing an instruction:

- **Traps**

- Intentional
- Examples: **system calls**, breakpoint traps, special instructions
- Returns control to “next” instruction

communicate with kernel (printf)

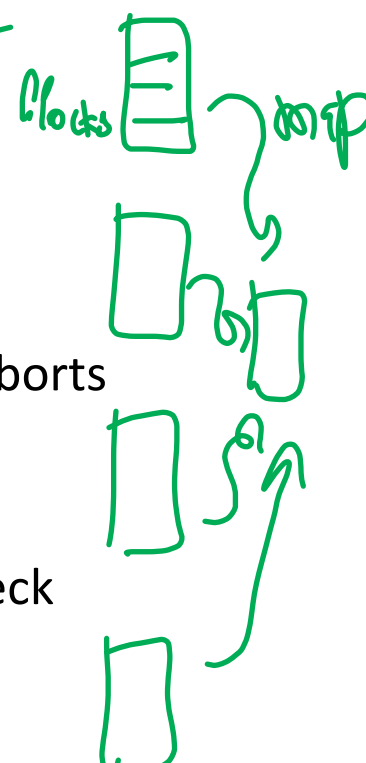
- **Faults**

- Unintentional but possibly recoverable
- Examples: page faults (recoverable), protection faults (unrecoverable), floating point exceptions
- Either re-executes faulting (“current”) instruction or aborts

rev M [X] → res

- **Aborts**

- Unintentional and unrecoverable
- Examples: illegal instruction, parity error, machine check
- Aborts current program *never come back*



System Calls

- Each x86-64 system call has a unique ID number

- Examples:

system \rightarrow for calling, you go to kernel space
lib

<i>Number</i>	<i>Name</i>	<i>Description</i>
0	read	Read file
1	write	Write file
2	open	Open file
3	close	Close file
4	stat	Get info about file
57	fork	Create process
59	execve	Execute a program
60	_exit	Terminate process
62	kill	Send signal to process

\rightarrow number as identifier (for kernel)

System Call Example: Opening File

- User calls: `open(filename, options)`
- Calls `__open` function, which invokes system call instruction `syscall`

```

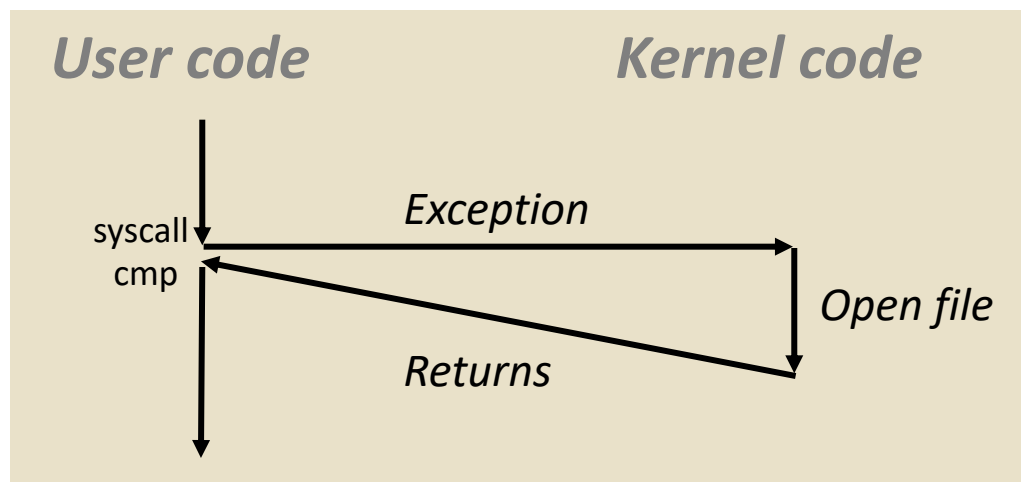
0000000000e5d70 <__open>:
...
e5d79:  b8 02 00 00 00      mov $0x2,%eax    # open is syscall #2
e5d7e:  0f 05               syscall          # Return value in %rax
e5d80:  48 3d 01 f0 ff ff   cmp $0xffffffffffffffff001,%rax
...
e5dfa:  c3                 retq

```

as programmer, never initiate directly

syscall

goes to kernel



- `%rax` contains syscall number
- Other arguments in `%rdi`, `%rsi`, `%rdx`, `%r10`, `%r8`, `%r9`
- Return value in `%rax`
- Negative value is an error corresponding to negative `errno`

failed

Fault Example: Page Fault

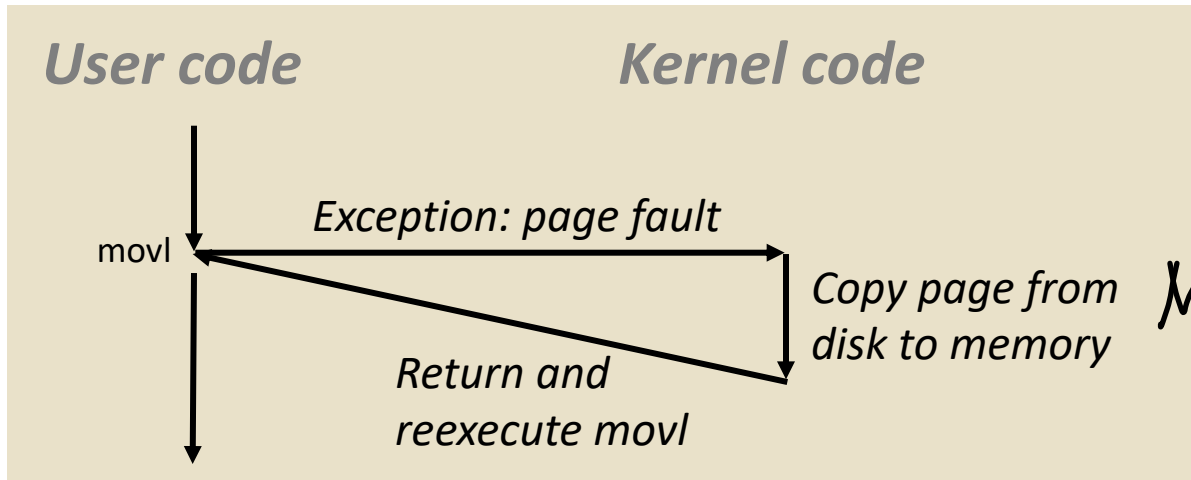
- User writes to memory location
- That portion (page) of user's memory is currently on disk

```
int a[1000];
main ()
{
    a[500] = 13;
}
```

properly allocated

80483b7:	c7 05 10 9d 04 08 0d	movl	\$0xd,0x8049d10
----------	----------------------	-------------	-----------------

no guarantee a[100] physical location



Memory controller

Fault Example: Invalid Memory Reference

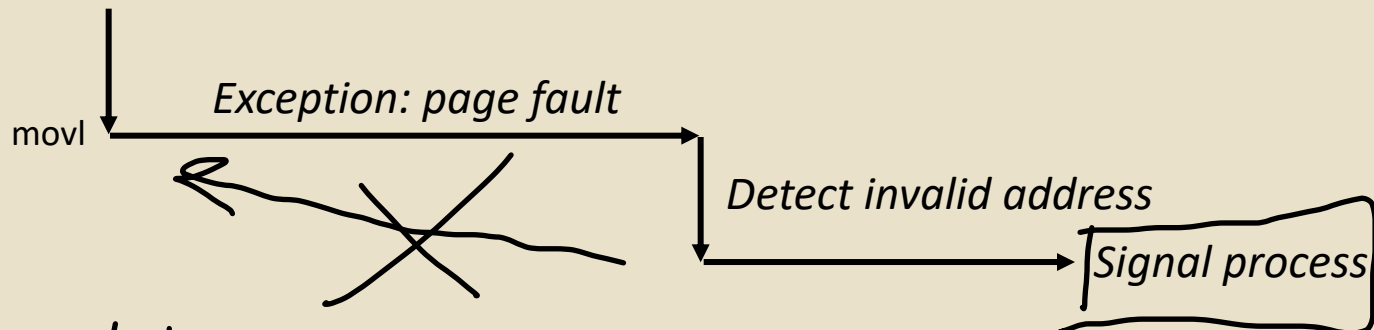
```
int a[1000];
main ()
{
    a[5000] = 13;
}
```

not in $a + 4 \times 1000$
memory

80483b7:	c7 05 60 e3 04 08 0d	movl	\$0xd,0x804e360
----------	----------------------	------	-----------------

User code

Kernel code



- Segmentation fault termination
Sends SIGSEGV signal to user process
- User process exits with "segmentation fault"
not always recoverable

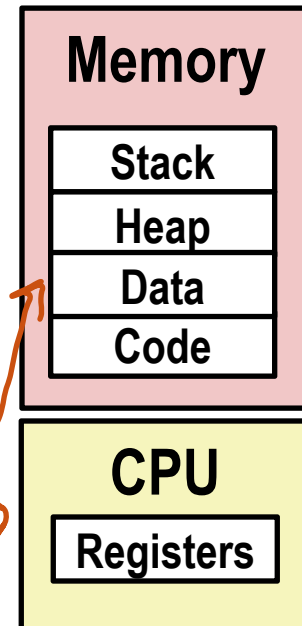
kernel kills
user program

Today

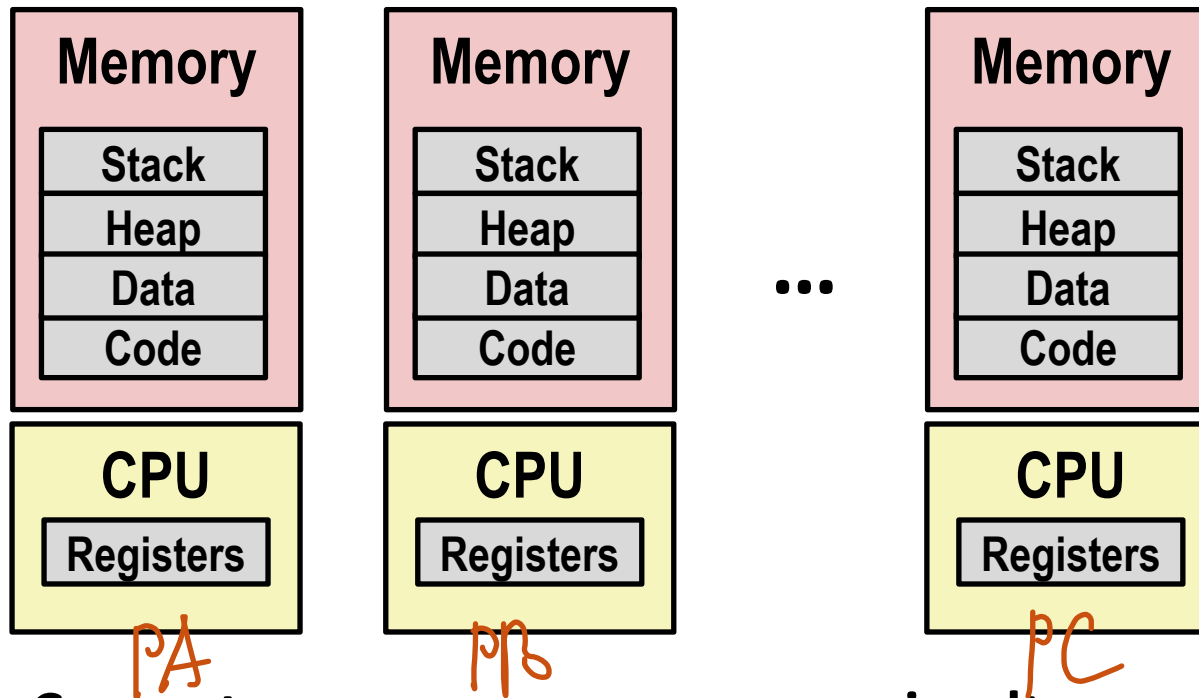
- Exceptional Control Flow
- Exceptions
- **Processes**
- Process Control

Processes

- Definition: A **process** is an instance of a running program. virtual entity
 - One of the most profound ideas in computer science
 - Not the same as “program” or “processor”
 - permanent physical entity /prog multiple processes
- Process provides each program with two key abstractions:
 - **Logical control flow** conceptually
 - Each program seems to have exclusive use of the CPU
 - Provided by kernel mechanism called context switching contiguously physically support multi-processes
 - **Private address space**
 - Each program seems to have exclusive use of main memory.
 - Provided by kernel mechanism called virtual memory time sharing



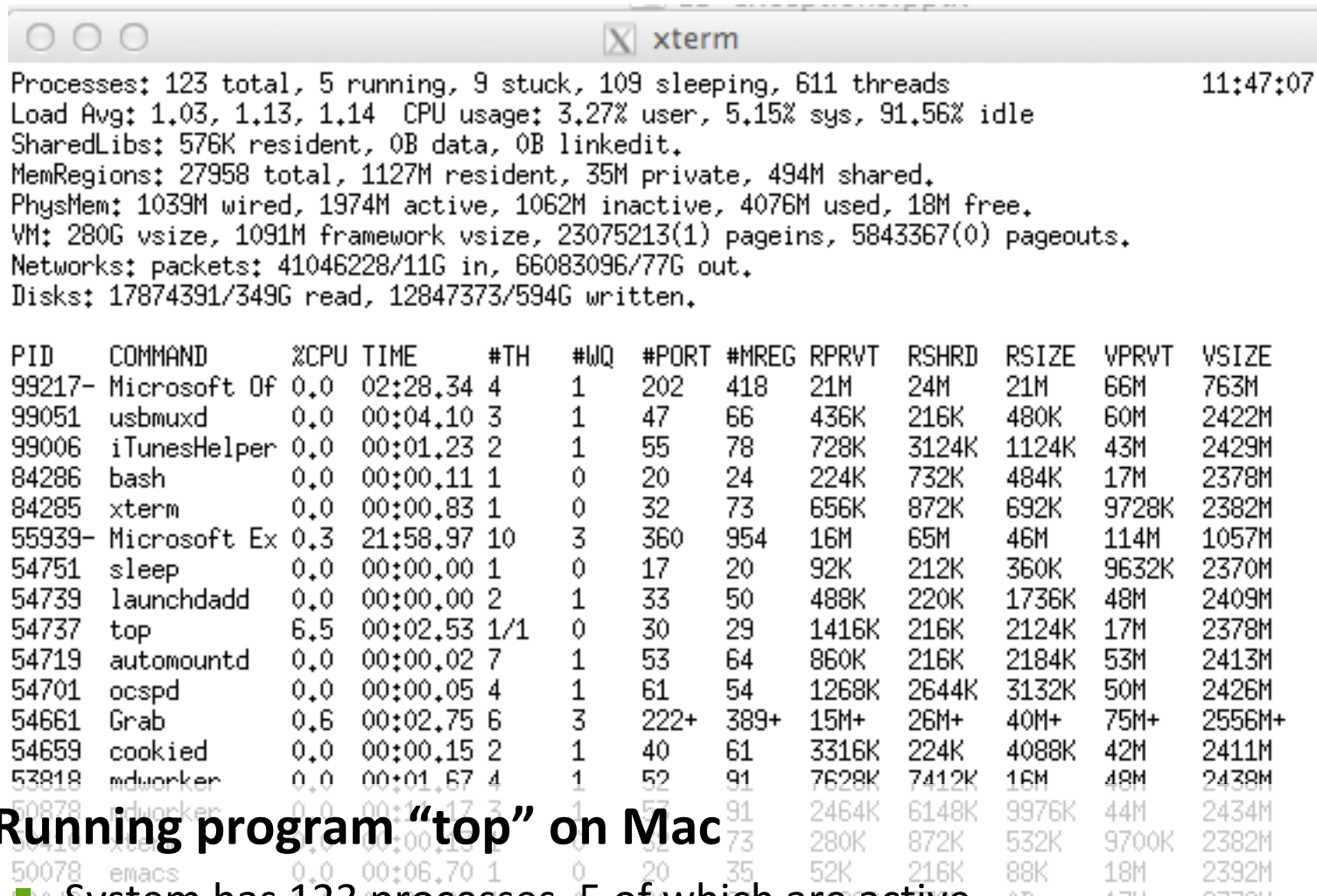
Multiprocessing: The Illusion



*P1 → I've my own
CPU, Memory*

- **Computer runs many processes simultaneously** *(together)*
time-sharing manner
 - Applications for one or more users
 - Web browsers, email clients, editors, ...
 - Background tasks
 - Monitoring network & I/O devices

Multiprocessing Example



The screenshot shows an xterm window with the following system statistics and a process list:

```

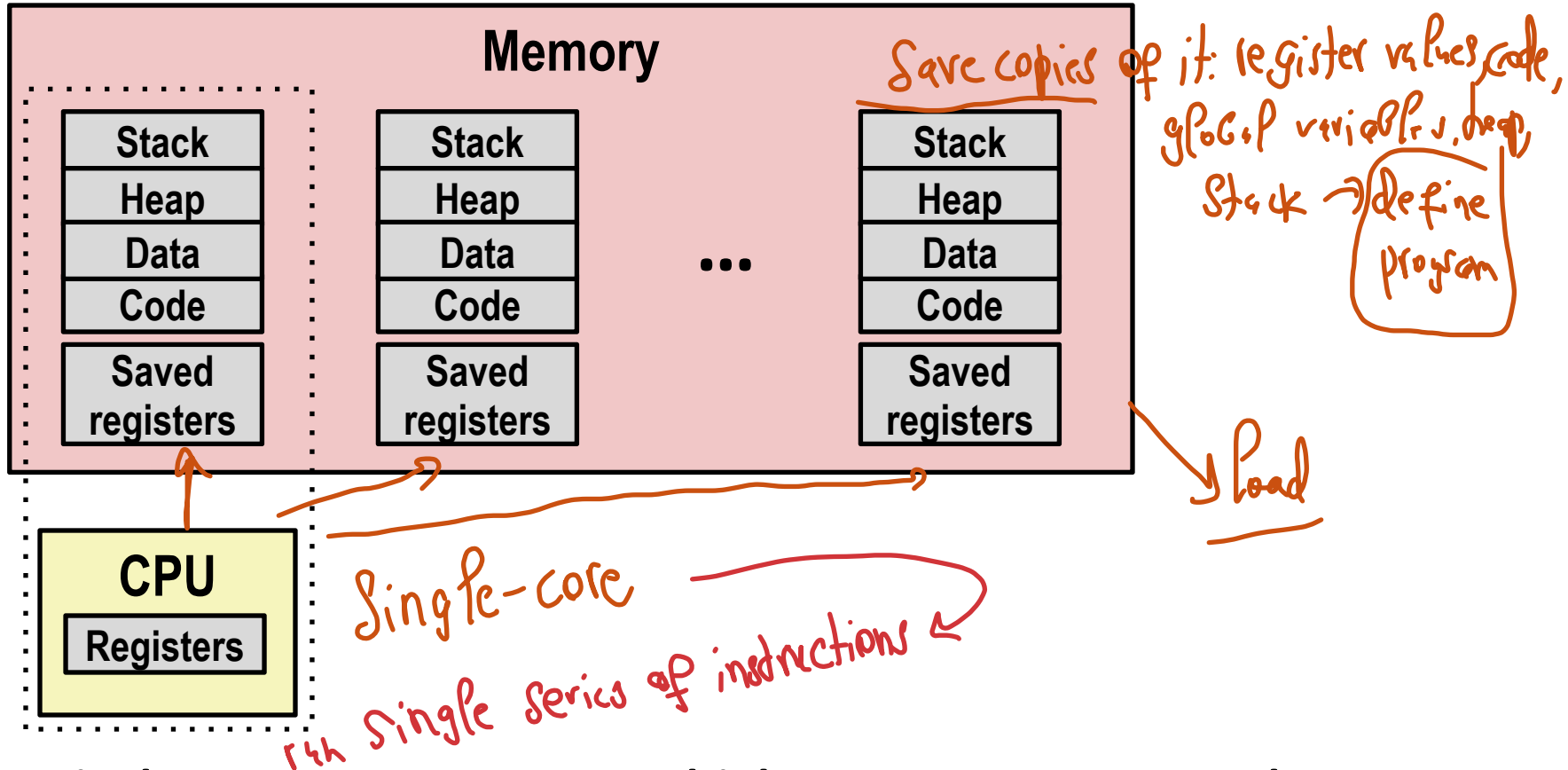
Processes: 123 total, 5 running, 9 stuck, 109 sleeping, 611 threads
Load Avg: 1.03, 1.13, 1.14 CPU usage: 3.27% user, 5.15% sys, 91.56% idle
SharedLibs: 576K resident, 0B data, 0B linkedit.
MemRegions: 27958 total, 1127M resident, 35M private, 494M shared.
PhysMem: 1039M wired, 1974M active, 1062M inactive, 4076M used, 18M free.
VM: 280G vsize, 1091M framework vsize, 23075213(1) pageins, 5843367(0) pageouts.
Networks: packets: 41046228/11G in, 66083096/77G out.
Disks: 17874391/349G read, 12847373/594G written.
  
```

The process list is as follows:

PID	COMMAND	%CPU	TIME	#TH	#WQ	#PORT	#MREG	RPRVT	RSHRD	RSIZE	VPRVT	VSIZE
99217-	Microsoft Of	0.0	02:28.34	4	1	202	418	21M	24M	21M	66M	763M
99051	usbmuxd	0.0	00:04.10	3	1	47	66	436K	216K	480K	60M	2422M
99006	iTunesHelper	0.0	00:01.23	2	1	55	78	728K	3124K	1124K	43M	2429M
84286	bash	0.0	00:00.11	1	0	20	24	224K	732K	484K	17M	2378M
84285	xterm	0.0	00:00.83	1	0	32	73	656K	872K	692K	9728K	2382M
55939-	Microsoft Ex	0.3	21:58.97	10	3	360	954	16M	65M	46M	114M	1057M
54751	sleep	0.0	00:00.00	1	0	17	20	92K	212K	360K	9632K	2370M
54739	launchdadd	0.0	00:00.00	2	1	33	50	488K	220K	1736K	48M	2409M
54737	top	6.5	00:02.53	1/1	0	30	29	1416K	216K	2124K	17M	2378M
54719	automountd	0.0	00:00.02	7	1	53	64	860K	216K	2184K	53M	2413M
54701	ocspd	0.0	00:00.05	4	1	61	54	1268K	2644K	3132K	50M	2426M
54661	Grab	0.6	00:02.75	6	3	222+	389+	15M+	26M+	40M+	75M+	2556M+
54659	cookied	0.0	00:00.15	2	1	40	61	3316K	224K	4088K	42M	2411M
53818	mdworker	0.0	00:01.67	4	1	52	91	7628K	7412K	16M	48M	2438M
50878	mdworker	0.0	00:11.17	3	1	57	91	2464K	6148K	9976K	44M	2434M
50410	top	0.0	00:00.13	0	0	32	73	280K	872K	532K	9700K	2382M
50078	emacs	0.0	00:06.70	1	0	20	35	52K	216K	88K	18M	2392M

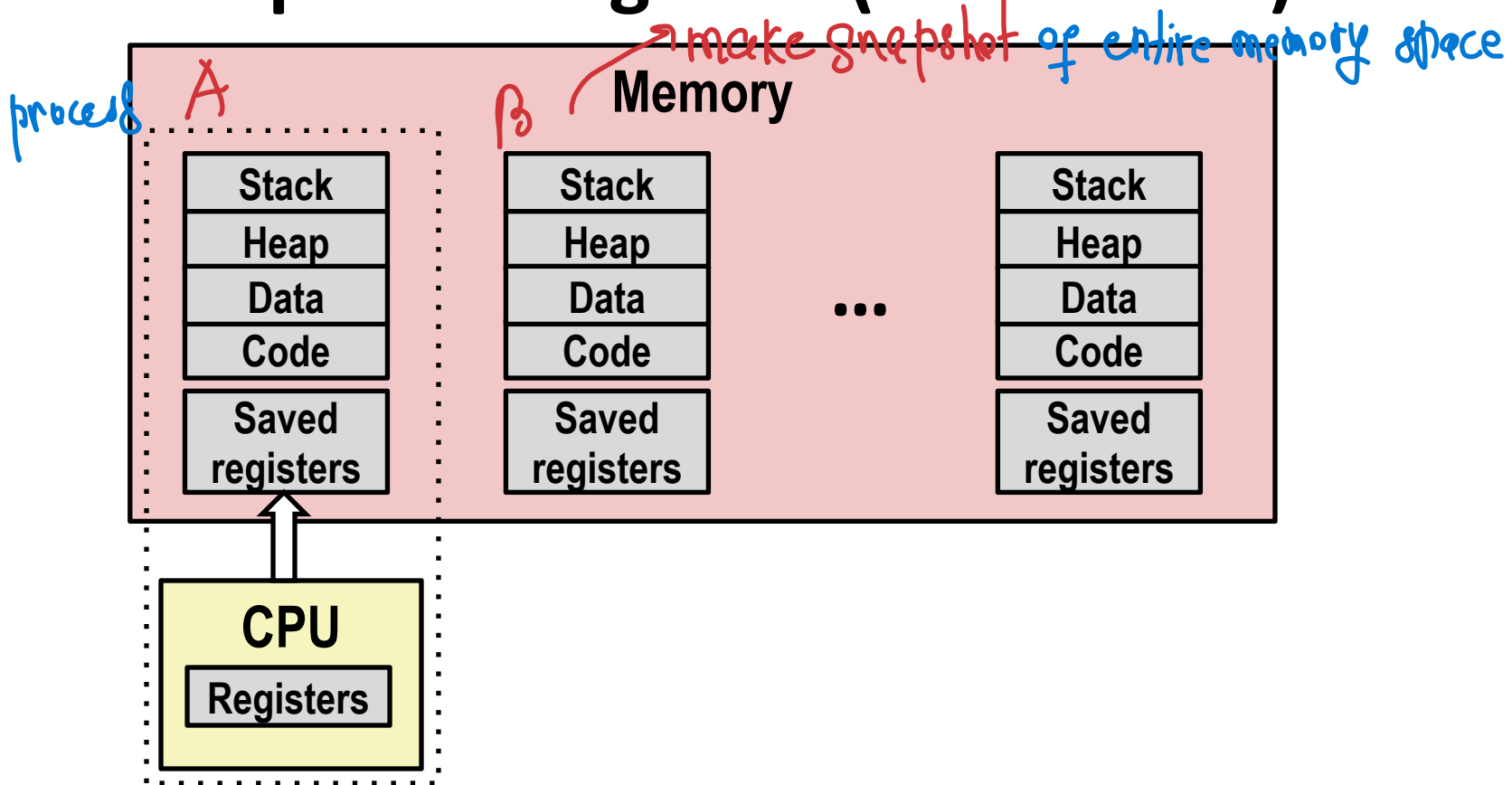
- Running program “top” on Mac
 - System has 123 processes, 5 of which are active
 - Identified by Process ID (PID)

Multiprocessing: The (Traditional) Reality



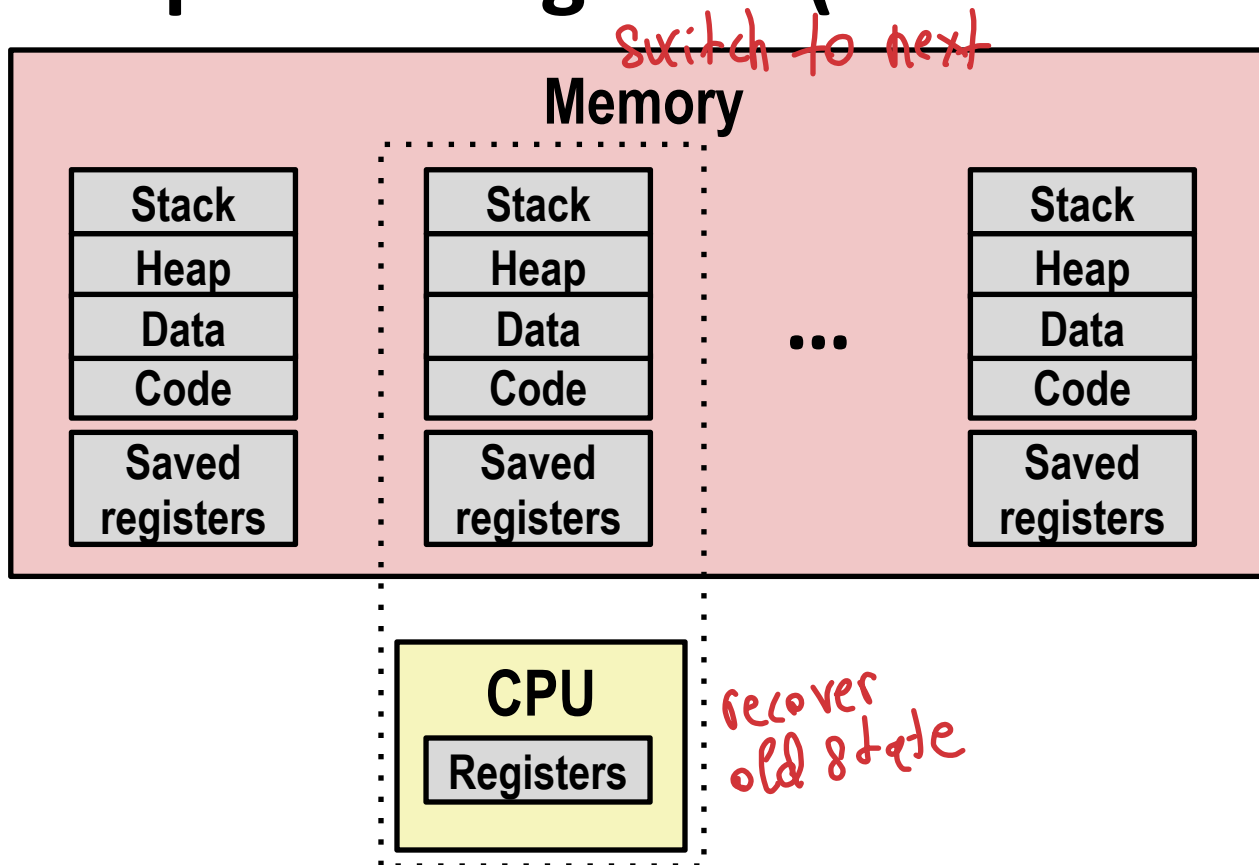
- **Single processor executes multiple processes concurrently**
 - Process executions interleaved (multitasking)
 - Address spaces managed by virtual memory system (later in course)
 - Register values for nonexecuting processes saved in memory

Multiprocessing: The (Traditional) Reality



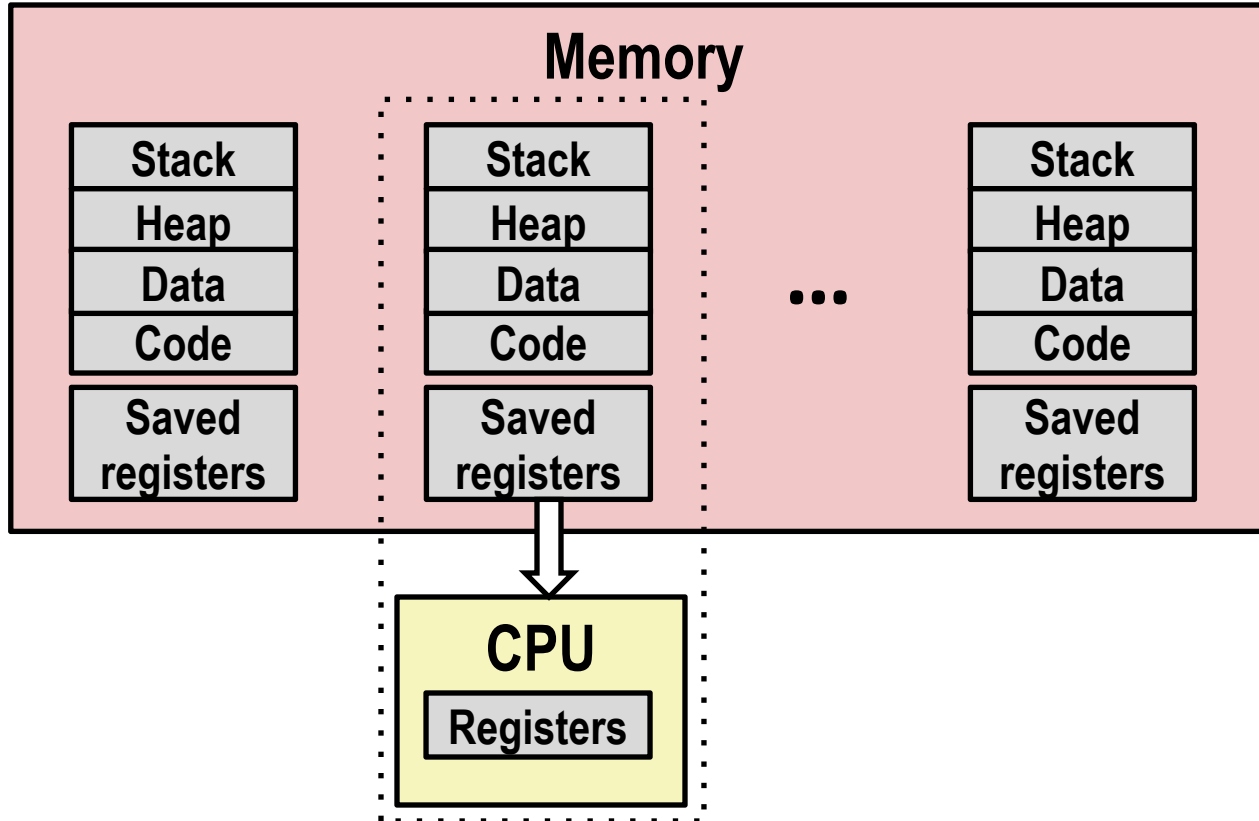
- Save current registers in memory

Multiprocessing: The (Traditional) Reality



- **Schedule next process for execution**

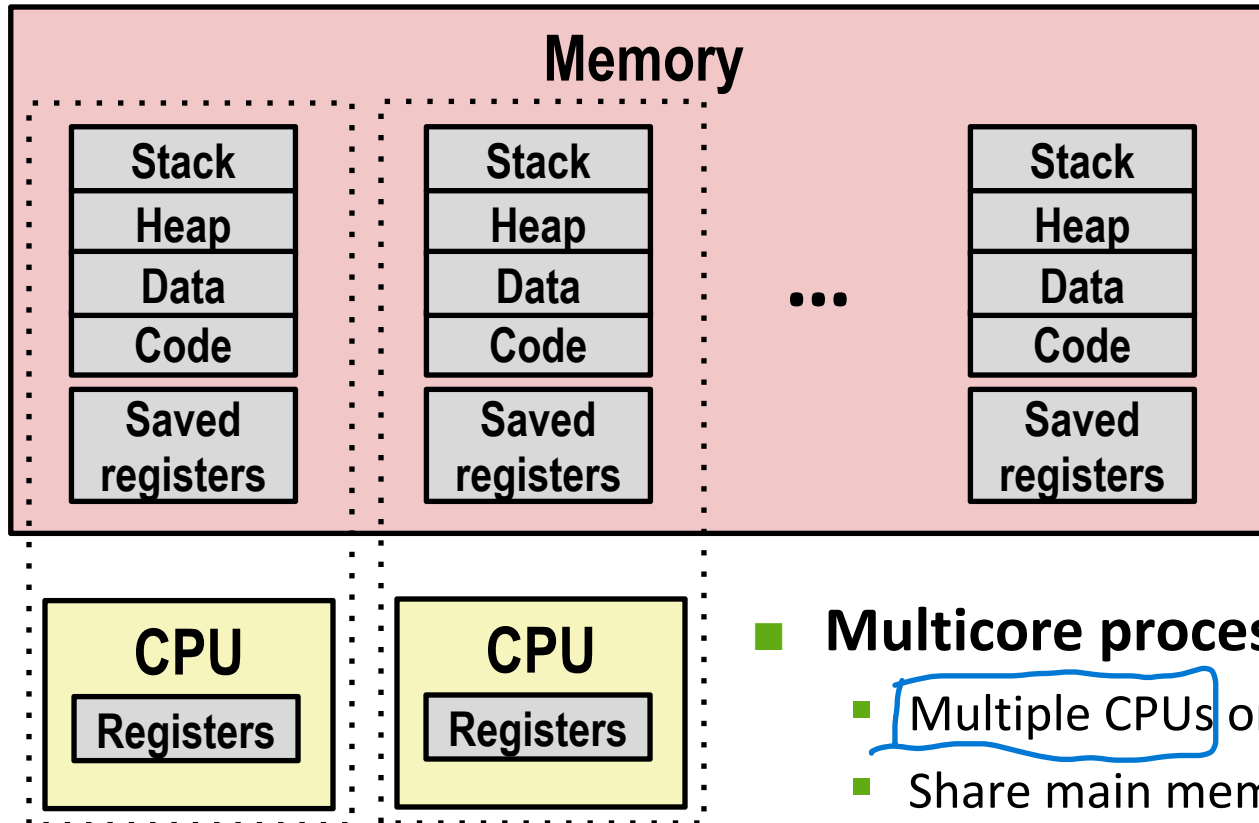
Multiprocessing: The (Traditional) Reality



- Load saved registers and switch address space (context switch)



Multiprocessing: The (Modern) Reality



Context switching

run
multiple
instructions in parallel
≠ time-sharing

■ Multicore processors

- Multiple CPUs on single chip
- Share main memory (and some of the caches)
- Each can execute a separate process
 - Scheduling of processors onto cores done by kernel

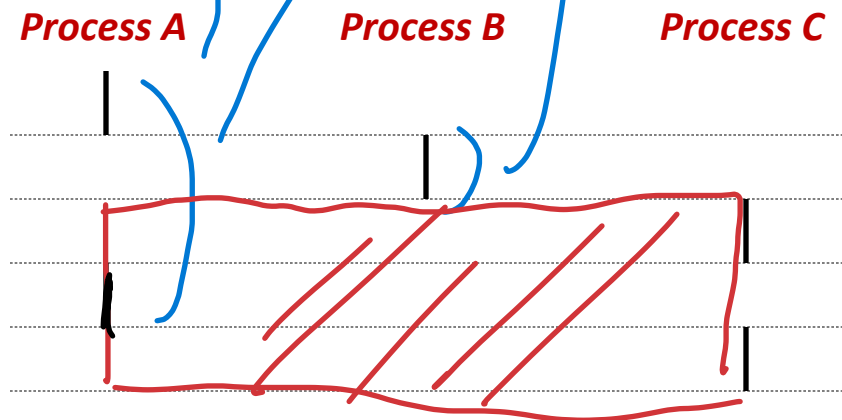
Concurrent Processes

* parallelize

- Each process is a logical control flow.
- Two processes *run concurrently* (are concurrent) if their flows overlap in time
- Otherwise, they are *sequential*
- Examples (running on single core):

- Concurrent: A & B, A & C
- Sequential: B & C

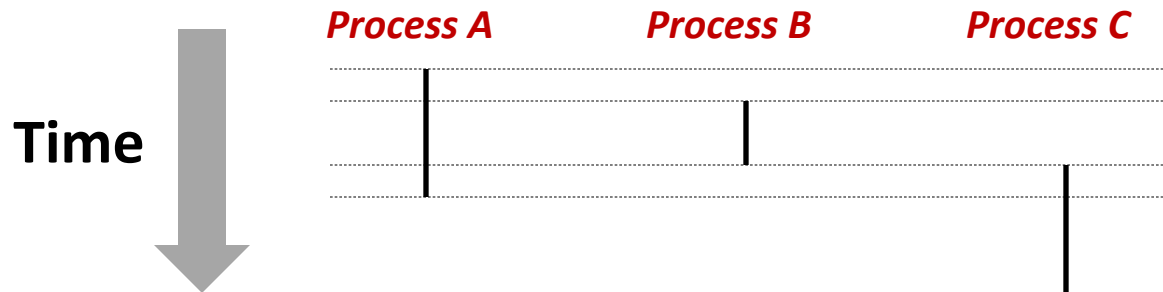
Time
↓



Running on
same core

User View of Concurrent Processes

- Control flows for concurrent processes are physically disjoint in time
- However, we can think of concurrent processes as running in parallel with each other

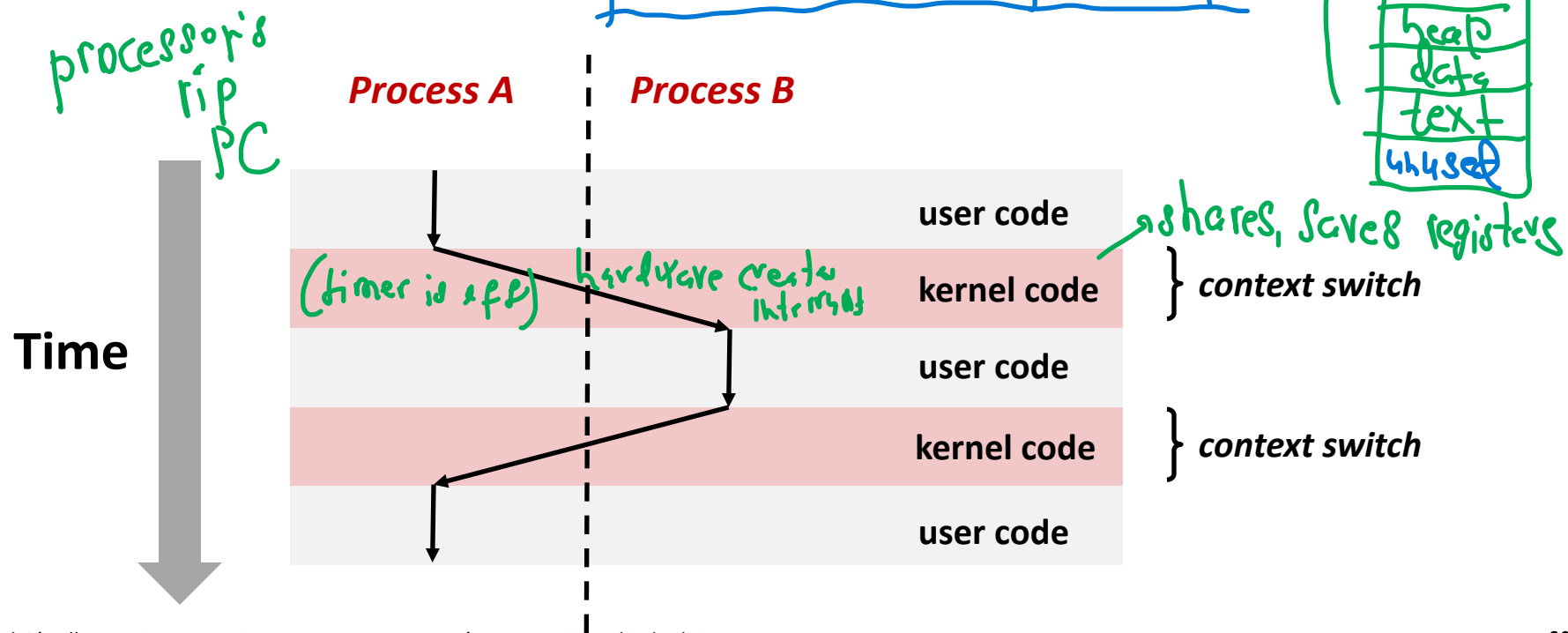


Context Switching

loaded in DRAM
controls the processes

- Processes are managed by a shared chunk of memory-resident OS code called the **kernel** → *core of OS*
 - Important: the kernel is not a separate process, but rather runs as part of some existing process. *they are all shared*

- Control flow passes from one process to another via a **context switch** *processes have region for kernel*



Today

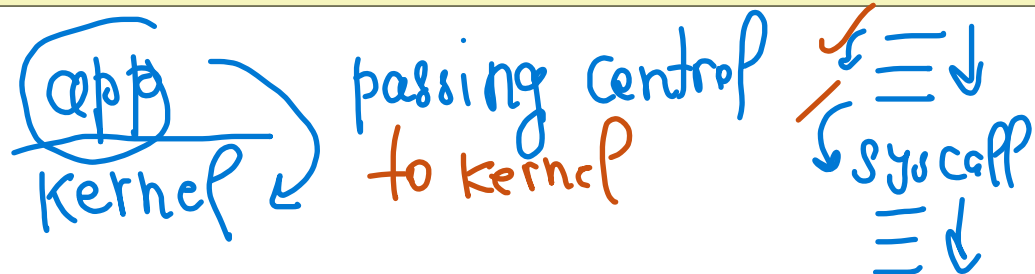
- Exceptional Control Flow
- Exceptions
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- **Process Control**

System Call Error Handling

- ↳ fail here no problem, but **HANDLE IT!**
- On error, Linux system-level functions typically return -1 and set global variable `errno` to indicate cause.
 - Hard and fast rule:
 - You must check the return status of every system-level function
 - Only exception is the handful of functions that return `void`
 - Example:

Krappen for error-check

```
if ((pid = fork()) < 0) {
    fprintf(stderr, "fork error: %s\n", strerror(errno));
    exit(0);
}
```



Error-reporting functions

when you call system-call

- Can simplify somewhat using an *error-reporting function*:

```
void unix_error(char *msg) /* Unix-style error */
{
    fprintf(stderr, "%s: %s\n", msg, strerror(errno));
    exit(0);
}
```

```
if ((pid = fork()) < 0)
    unix_error("fork error");
```

Error-handling Wrappers

- We simplify the code we present to you even further by using Stevens-style error-handling wrappers:

```
pid_t Fork(void)
{
    pid_t pid;

    if ((pid = fork()) < 0)
        unix_error("Fork error");
    return pid;
}
```

fork() → system call

↓
create process

getpid: get process ID

```
pid = Fork();
```

→ simple, protective

Obtaining Process IDs

- `pid_t getpid(void)`

- Returns PID of current process

- `pid_t getppid(void)`

- Returns PID of parent process

processes created by other processes
there's always parent process

Creating and Terminating Processes

From a programmer's perspective, we can think of a process as being in one of three states

■ Running

- Process is either executing, or waiting to be executed and will eventually be scheduled (i.e., chosen to execute) by the kernel

■ Stopped

- Process execution is *suspended* and will not be scheduled until further notice (next lecture when we study signals)

does not
schedule
↑

Ctrl + Z

■ Terminated

- Process is stopped permanently

kill the process

Terminating Processes

■ Process becomes terminated for one of three reasons:

- Receiving a signal whose default action is to terminate (next lecture)
- Returning from the `main` routine *→ I'm done*
- Calling the `exit` function *→ system-call*
sending kernel: stop

■ `void exit(int status)` *→ How I terminate?*

- Terminates with an *exit status* of `status`
- Convention: normal return status is 0, nonzero on error
- Another way to explicitly set the exit status is to return an integer value from the main routine

■ `exit` is called **once** but **never** returns.

```
int main() {  
    return 0;  
}
```

Creating Processes

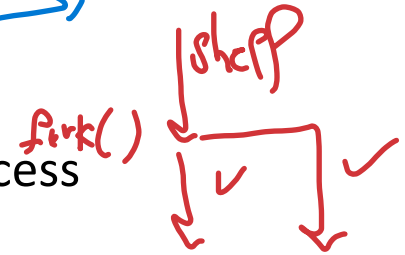
- **Parent process** creates a new running **child process** by calling **fork**

OS creates shell for you (process for the first)

Server →

- **int fork(void)** ^{function call}

- Returns 0 to the child process, child's PID to parent process
- Child is *almost* identical to parent:
 - Child get an identical (but separate) copy of the parent's virtual address space. (same global data, stack)
 - Child gets identical copies of the parent's open file descriptors
 - Child has a different PID than the parent

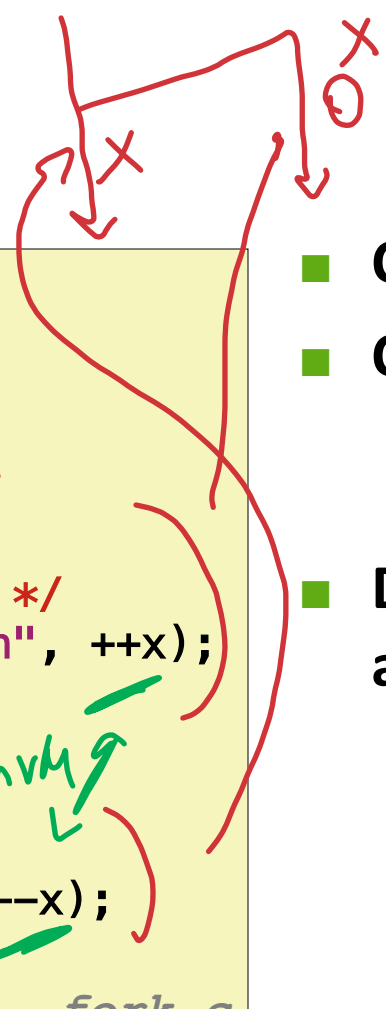


- **fork** is interesting (and often confusing) because

it is called **once** but returns **twice**

process { parent → child's PID } return value
child → 0

fork Example



```

int main()
{
    pid_t pid;
    int x = 1;

    pid = Fork();
    if (pid == 0) { /* Child */
        printf("child : x=%d\n", ++x);
        exit(0);
    }

    /* Parent */
    printf("parent: x=%d\n", --x);
    exit(0);
}

```

2 processes running

different in v4

fork.c

```

linux> ./fork
parent: x=0
child : x=2

```

- Call once, return twice
- Concurrent *Context switching* execution
 - Can't predict execution order of parent and child
- Duplicate but separate address space
 - *x* has a value of 1 when fork returns in parent and child *Separate copies*
 - Subsequent changes to *x* are independent
- Shared open files
 - stdout is the same in both parent and child

Modeling ~~fork~~ with Process Graphs

processes running concurrently

- A *process graph* is a useful tool for capturing the partial ordering of statements in a concurrent program:
 - Each vertex is the execution of a statement
 - $a \rightarrow b$ means a happens before b
 - Edges can be labeled with current value of variables
 - `printf` vertices can be labeled with output
 - Each graph begins with a vertex with no incoming edges
- Any *topological sort* of the graph corresponds to a feasible total ordering.
 - Total ordering of vertices where all edges point from left to right

Process Graph Example

```

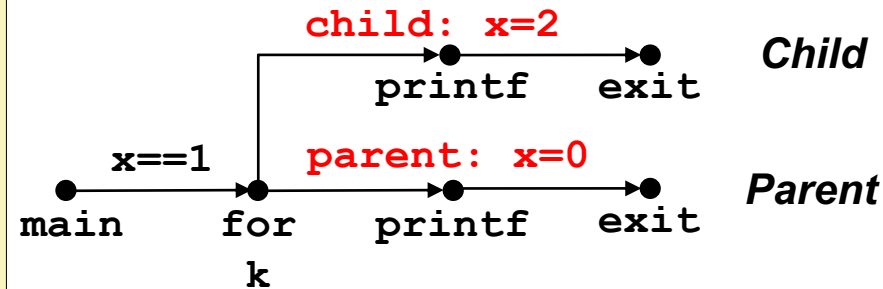
int main()
{
    pid_t pid;
    int x = 1;

    pid = Fork();
    if (pid == 0) { /* Child */
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        exit(0);
    }

    /* Parent */
    printf("parent: x=%d\n", --x);
    exit(0);
}

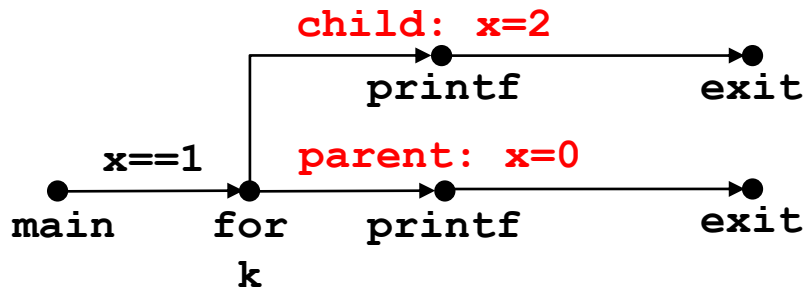
```

fork.c



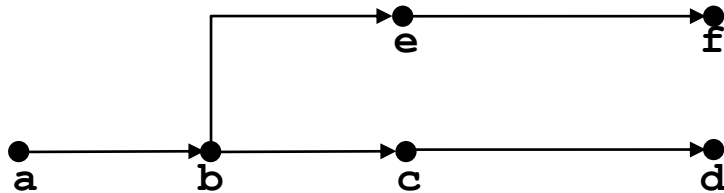
Interpreting Process Graphs

■ Original graph:

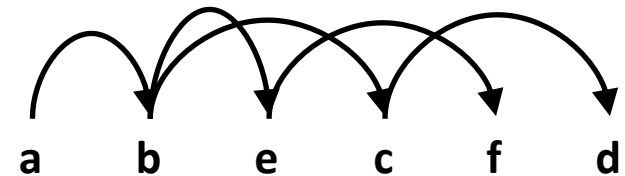


Left-to-right ✓ correct

■ Relabelled graph:

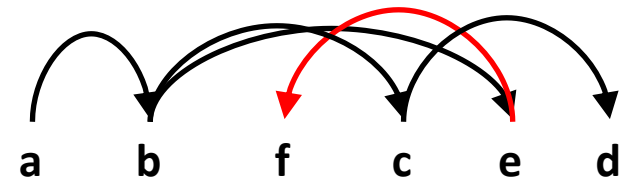


Feasible total ordering:



Wrong!

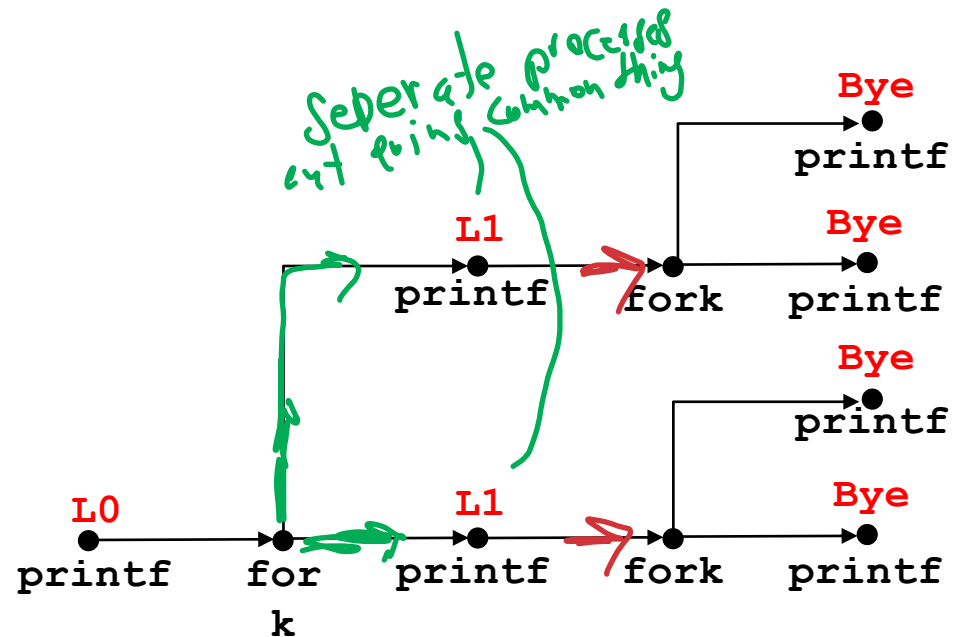
Infeasible total ordering:



fork Example: Two consecutive forks *System call*

```
void fork2()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
```

forks.c



Feasible output:

L0
L1
Bye
Bye
L1
Bye
Bye

Infeasible output:

L0
Bye *→ Bye happens
after L1*
L1
Bye
L1
Bye
Bye

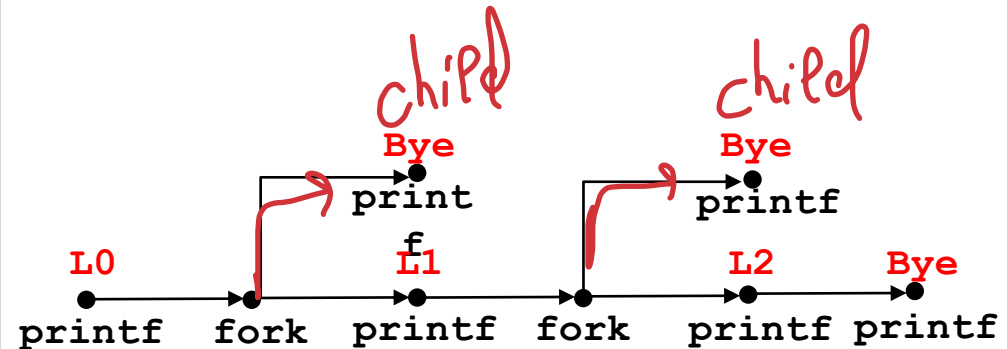
fork Example: Nested forks in parent

```

void fork4()
{
    printf("L0\n");
    if (fork() != 0) {
        printf("L1\n");
        if (fork() != 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}

```

forks.c



Feasible output:

L0
L1
Bye
Bye
L2
Bye

Infeasible output:

L0
Bye
L1
Bye
Bye
L2

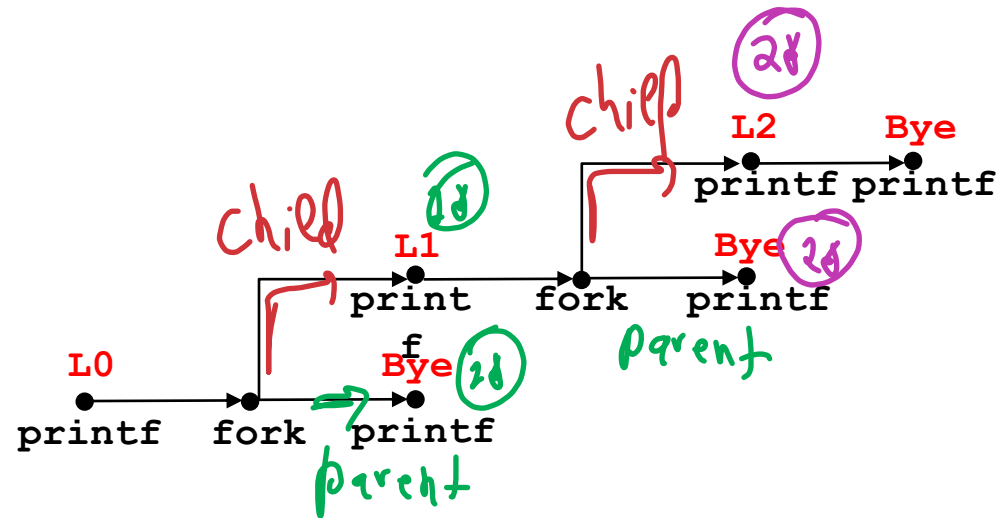
*Last child
reference*

fork Example: Nested forks in children

```

void fork5()
{
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork() == 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
forks.c

```



Feasible output:

L0

Bye

L1

L2

Bye

Bye

order can
be different

Infeasible output:

L0

Bye

L1

Bye

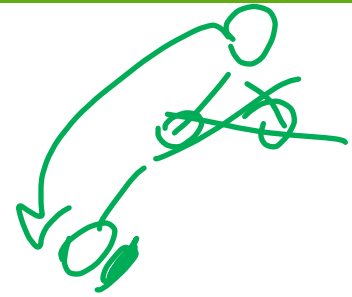
Bye

L2

L2 should be
present

Reaping Child Processes

- **Idea** *child*
 - When process terminates, it still consumes system resources
 - Examples: Exit status, various OS tables *← use these info*
 - Called a "zombie" *→ some info in OS*
 - Living corpse, half alive and half dead
- **Reaping** *→ only by parent*
 - Performed by parent on terminated child (using `wait` or `waitpid`)
 - Parent is given exit status information `exit(0)` *parent waits for a certain process to be done*
 - Kernel then deletes zombie child process *cleans up* *then*
- **What if parent doesn't reap?**
 - If any parent terminates without reaping a child, then the orphaned child will be reaped by `init` process (`pid == 1`) *→ running in the system all the time*
 - So, only need explicit reaping in long-running processes
 - e.g., shells and servers



system cell

parent waits for a certain process to be done

cleans up

then

ultimate genesis process

running in the system all the time

Zombie Example

```
void fork7() {
    if (fork() == 0) {
        /* Child */
        printf("Terminating Child, PID = %d\n", getpid());
        exit(0);
    } else {
        printf("Running Parent, PID = %d\n", getpid());
        while (1)
            ; /* Infinite loop */
    }
}
```

parent infinite loop
never terminate
not zombie

forks.c

```
linux> ./forks 7 &
[1] 6639
```

```
Running Parent, PID = 6639
```

```
Terminating Child, PID = 6640
```

```
linux> ps
```

PID	TTY	TIME	CMD
6585	ttyp9	00:00:00	tcsh
6639	ttyp9	00:00:03	forks
6640	ttyp9	00:00:00	forks <defunct>
6641	ttyp9	00:00:00	ps

```
linux> kill 6639
```

```
[1] Terminated
```

```
linux> ps
```

PID	TTY	TIME	CMD
6585	ttyp9	00:00:00	tcsh
6642	ttyp9	00:00:00	ps

■ **ps** shows child process as "defunct" (i.e., a zombie)

■ Killing parent allows child to be reaped by **init**

manually kill parent process

parent process

not reaping child process (done by init)

Non-terminating Child Example

nobody kills running child process

```
void fork8()
{
    if (fork() == 0) {
        /* Child */
        printf("Running Child, PID = %d\n",
               getpid());
        while (1)
            ; /* Infinite loop */
    } else {
        /* Parent is gone */
        printf("Terminating Parent, PID = %d\n",
               getpid());
        exit(0);
    }
}
```

forks.c

child does not terminate

but child is remaining (running)

```
linux> ./forks 8
Terminating Parent, PID = 6675
Running Child, PID = 6676
linux> ps
  PID TTY          TIME CMD
 6585 tttyp9      00:00:00 tcsh
 6676 tttyp9      00:00:06 forks
 6677 tttyp9      00:00:00 ps
linux> kill 6676
linux> ps
  PID TTY          TIME CMD
 6585 tttyp9      00:00:00 tcsh
 6678 tttyp9      00:00:00 ps
```

■ Child process still active even though parent has terminated

■ Must kill child explicitly, or else will keep running indefinitely

Such inaccuracies can kill your system

parent process → zombie process

wait: Synchronizing with Children

- Parent reaps a child by calling the `wait` function *explicitly*
- `int wait(int *child_status)`
 - pointer*
 *child_status

status info
 →
 - Return ~

PID of child that terminated
 - Suspends current process until one of its children terminates
 - Return value is the pid of the child process that terminated
 - If `child_status != NULL`, then the integer it points to will be set to a value that indicates reason the child terminated and the exit status:
 - Checked using macros defined in `wait.h`
 - WIFEXITED, WEXITSTATUS, WIFSIGNALED, WTERMSIG, WIFSTOPPED, WSTOPSIG, WIFCONTINUED
 - See textbook for details

(?)

wait: Synchronizing with Children

aligning steps
matching behavior

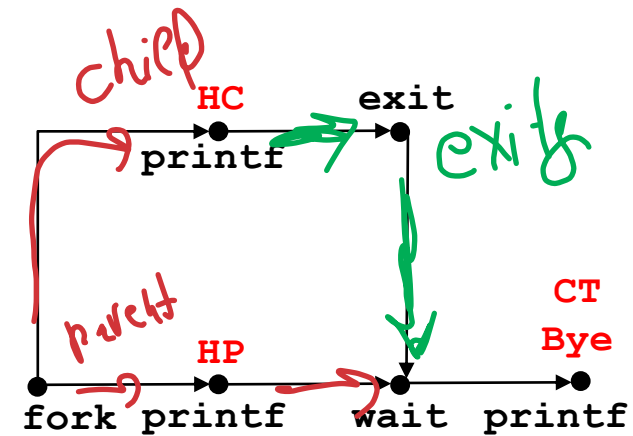
```

void fork9() {
    int child_status;

    if (fork() == 0) { child
        printf("HC: hello from child\n");
        exit(0);
    } else { parent
        printf("HP: hello from parent\n");
        wait(&child_status); sleep
        printf("CT: child has terminated\n");
        printf("Bye\n");
    }
}

```

forks.c



waiting for child process to terminate

shell

not waiting

ps -ef &

shell will wait until ps finishes its job

Feasible output:

HC
HP
CT
Bye

Infeasible output:

HP
CT
Bye
HC

Another wait Example

for only 1 child
to be completed

- If multiple children completed, will take in arbitrary order
- Can use macros WIFEXITED and WEXITSTATUS to get information about exit status

```
void fork10() {
    pid_t pid[N];
    int i, child_status;
```

```
    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0) {
            exit(100+i); /* Child */
        }
```

parent does not get
into loop body

```
    for (i = 0; i < N; i++) { /* Parent */
```

```
        pid_t wpid = wait(&child_status);
```

```
        if (WIFEXITED(child_status))
```

```
            printf("Child %d terminated with exit status %d\n",
```

```
                    wpid, WEXITSTATUS(child_status));
```

```
        else
```

```
            printf("Child %d terminate abnormally\n", wpid);
```

```
    }
```

```
}
```

forks.c

waitpid: Waiting for a Specific Process *terminated*

pass process ID to wait for specific child process to be

■ `pid_t waitpid(pid_t pid, int &status, int options)`

- Suspends current process until specific process terminates
- Various options (see textbook)

```
void fork11() {
    pid_t pid[N];
    int i;
    int child_status;
```

```
    for (i = 0; i < N; i++)
```

```
        if ((pid[i] = fork()) == 0)
            exit(100+i); /* Child */
```

Backwards

```
    for (i = N-1; i >= 0; i--) {
```

partly created child process to be terminated

```
        pid_t wpid = waitpid(pid[i], &child_status, 0);
```

```
        if (WIFEXITED(child_status))
```

```
            printf("Child %d terminated with exit status %d\n",
                   wpid, WEXITSTATUS(child_status));
```

```
        else
```

```
            printf("Child %d terminate abnormally\n", wpid);
```

```
    }
```

```
}
```

forks.c

system call execve: Loading and Running Programs

want to create process of own executable?
fork → creates copy (if/else)

- `int execve(char *filename, char *argv[], char *envp[])`
executable environment variable
- Loads and runs in the current process:

- Executable file `filename` → .sh

- Can be object file or script file beginning with `#!` interpreter (e.g., `#!/bin/bash`) → treat as executable

- ...with argument list `argv`

- By convention `argv[0] == filename`

- ...and environment variable list `envp`

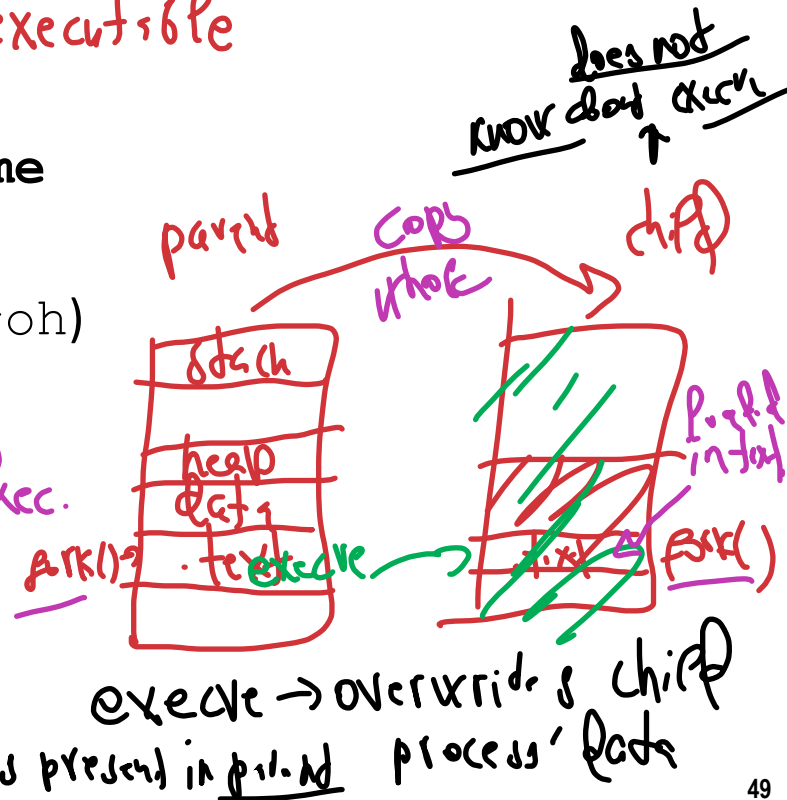
- "name=value" strings (e.g., `USER=droh`)
- `getenv`, `putenv`, `putenv`

- Overwrites code, data, and stack with your exec.

- Retains PID, open files and signal context

- Called **once** and **never** returns

- ...except if there is an error



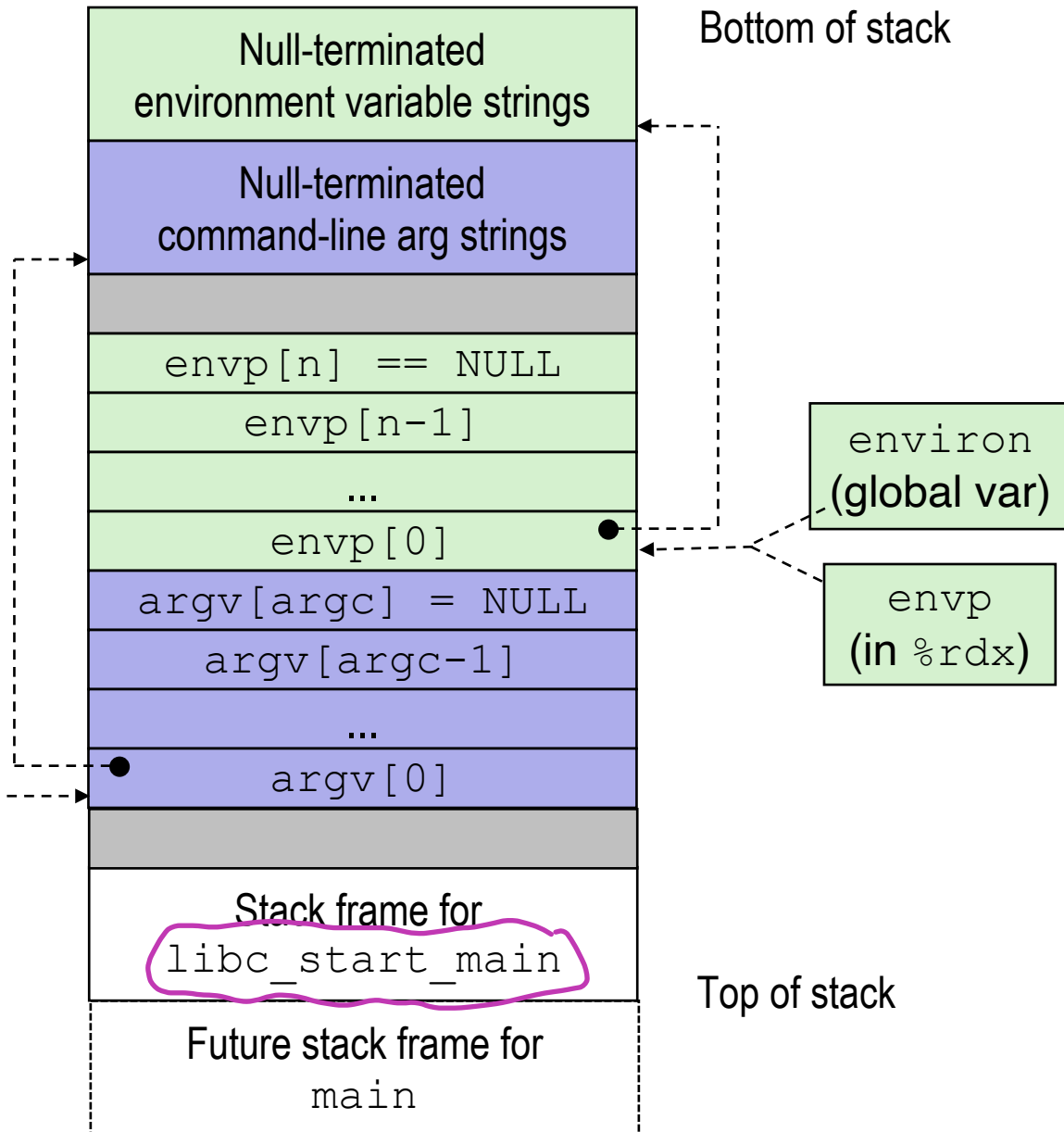
Structure of the stack when a new program starts

VM of new program space

execve kllp overwrite arguments

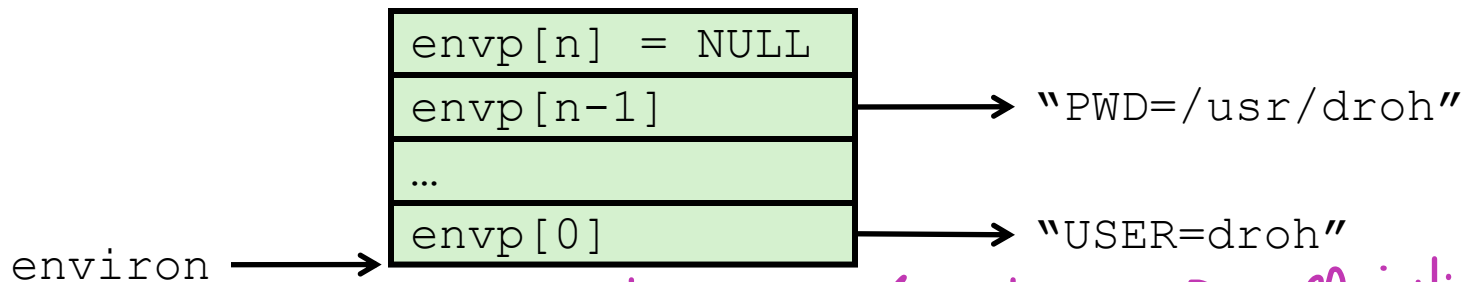
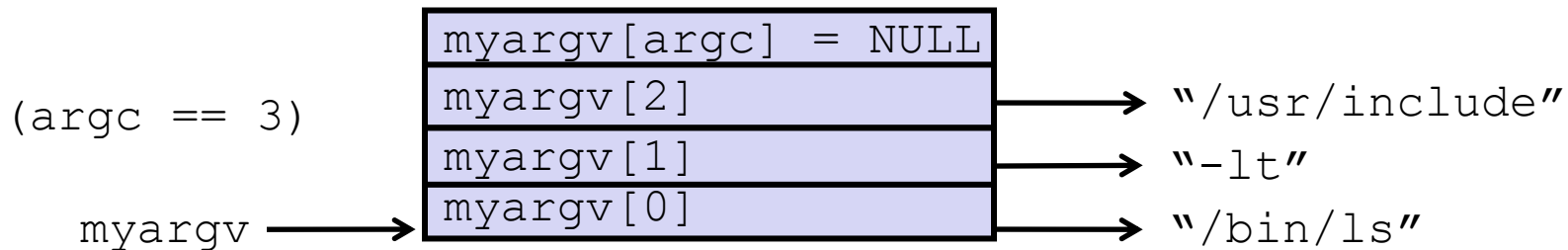
argv
(in %rsi)

argc
(in %rdi)



execve Example

- Executes `"/bin/ls -lt /usr/include"` in child process using current environment:



why both ~ maybe after fork, I would initialize all before execve

```

if ((pid = Fork()) == 0) {    /* Child runs program */
    if (execve(myargv[0], myargv, environ) < 0) {
        printf("%s: Command not found.\n", myargv[0]);
        exit(1);
    }
}

```

Summary

standard control flow → jump, loop, if/else
inside application

■ Exceptions

- Events that require nonstandard control flow (system event)
- Generated externally (interrupts) or internally (traps and faults)
page

■ Processes

- At any given time, system has multiple active processes
- Only one can execute at a time on a single core, though
- (Each process appears to have total control of processor + private memory space) illusion of each process

Summary (cont.)

- **Spawning processes**
 - Call `fork` *→ duplicate exact same memory space*
 - One call, two returns
- **Process completion**
 - Call `exit`
 - One call, no return
- **Reaping and waiting for processes**
 - Call `wait` or `waitpid` *Cleanup method*
- **Loading and running programs**
 - Call `execve` (or variant)
 - One call, (normally) no return