

Score Table (for teacher use only)

Question:	1	2	3	4	5	Total
Points:	20	20	20	15	25	100
Score:						

This is a CLOSED-BOOK exam.

Please provide ALL DERIVATIONS and EXPLANATIONS with your answers.

Any communication with others during the exam will be regarded as a cheating case.

1. (20 points) Fourier Transform

(a) (10 points) Derive the inverse Fourier transform $x(t)$ of the spectrum

$$X(j\omega) = \int_{-\infty}^{\omega} Y(j\eta) d\eta$$

in terms of $y(t)$. (Do not answer simply using duality. Provide full derivations)

(Hint) Utilize properties of inverse Fourier transform:

$$\delta(\omega) \xleftrightarrow{ICTFT} \frac{1}{2\pi}, \quad \frac{d}{d\omega} A(j\omega) \xleftrightarrow{ICTFT} (-jt)a(t), \quad X(j\omega) * Y(j\omega) \xleftrightarrow{ICTFT} 2\pi x(t)y(t)$$

(Answer)

$$x(t) = -\frac{1}{jt}y(t) + \pi y(0)\delta(t)$$

(Solution) The running integral is the convolution with unit step function. Therefore,

$$X(j\omega) = Y(j\omega) * H(j\omega), \quad x(t) = 2\pi y(t)h(t) \quad (1)$$

where $H(j\omega)$ is the unit step function defined in the frequency domain, and $h(t)$ is its inverse Fourier transform. Let's define the sign function as

$$H(j\omega) = \frac{1}{2}(1 + \text{SGN}(j\omega)) \quad (2)$$

The above equation satisfies

$$\frac{d}{d\omega} H(j\omega) = \delta(\omega) = \frac{1}{2} \frac{d}{d\omega} \text{SGN}(j\omega)$$

Since the sign function has no dc value, its inverse Fourier transform can be derived as

$$\text{SGN}(j\omega) \xLeftrightarrow{ICTFT} \text{sgn}(t) = \frac{1}{-j\pi t}$$

(Using properties of CTFT)

$$\begin{aligned} \delta(\omega) &\xLeftrightarrow{ICTFT} \frac{1}{2\pi} \\ \frac{d}{d\omega} A(j\omega) &\xLeftrightarrow{ICTFT} (-jt)a(t) \end{aligned}$$

From this result and (1)-(2), the inverse Fourier transform of $X(j\omega)$ is given by

$$x(t) = -\frac{1}{jt}y(t) + \pi y(t)\delta(t) = -\frac{1}{jt}y(t) + \pi y(0)\delta(t) \quad (\text{sifting property})$$

(b) (10 points) Find the time signal $x(t)$ whose Fourier transform is given by

$$X(j\omega) = \begin{cases} \frac{\omega+1}{2} & \text{for } |\omega| < 1 \\ 0 & \text{for } |\omega| > 1 \end{cases}$$

(Answer)

$$x(t) = -\frac{\sin t}{j2\pi t^2} + \frac{e^{jt}}{2\pi jt}$$

(Solution) Consider $Y(j\omega)$ defined as

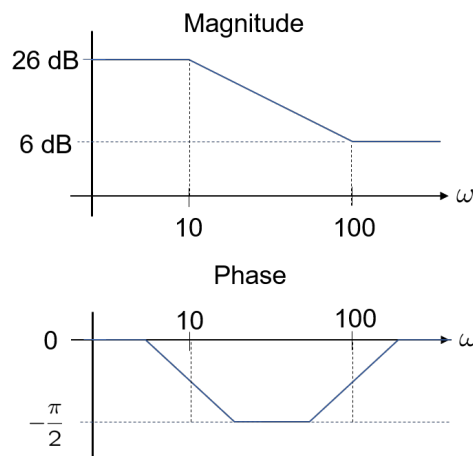
$$Y(j\omega) = \frac{d}{d\omega} X(j\omega) = \begin{cases} \frac{1}{2} & \text{for } |\omega| < 1 \\ 0 & \text{for } |\omega| > 1 \end{cases} \xLeftrightarrow{ICTFT} y(t) = \frac{\sin t}{2\pi t}$$

Then, $X(j\omega) = \int_{-\infty}^{\omega} Y(j\eta) d\eta - U(j(\omega - 1))$. From the result of prob. 1a,

$$\begin{aligned} x(t) &= -\frac{1}{jt}y(t) + \pi y(0)\delta(t) - \frac{1}{2\pi} \left(\frac{-1}{jt} + \pi\delta(t) \right) e^{jt} \\ &= -\frac{\sin t}{j2\pi t^2} + \frac{\delta(t)}{2} + \frac{1}{2\pi} \frac{1}{jt} e^{jt} - \frac{\delta(t)}{2} \quad (y(0) = 1/2\pi) \\ &= -\frac{\sin t}{j2\pi t^2} + \frac{e^{jt}}{2\pi jt} \end{aligned}$$

2. (20 points) For LTI systems satisfying the condition of initial rest, answer to the following questions.

- (a) (10 points) The bode plot of the system is shown below. Derive its (A) frequency response $H(j\omega)$ (B) impulse response $h(t)$ and (C) linear constant coefficient differential equation.



(Answer)

$$H(j\omega) = 2 \frac{j\omega + 100}{j\omega + 10}, \quad h(t) = 2\delta(t) + 180e^{-10t}u(t), \quad \frac{dy(t)}{dt} + 10y(t) = 2\frac{dx(t)}{dt} + 200x(t)$$

(Solution) Gain at zero frequency is 26 dB = $20 \log_{10} 20$.

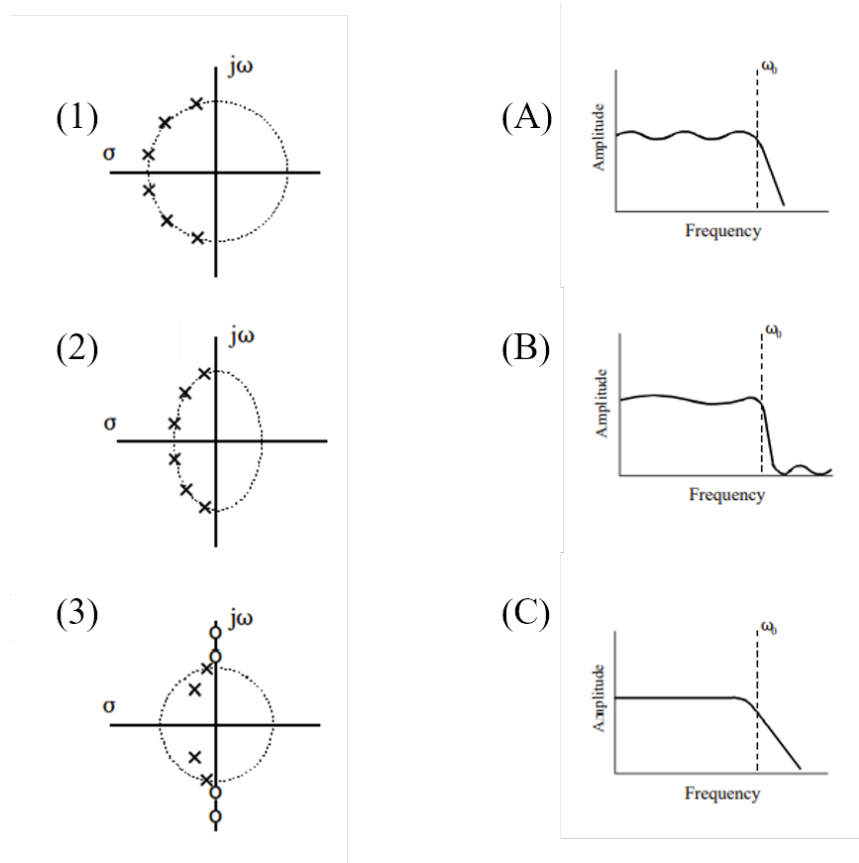
$$\begin{aligned} H(j\omega) &= 20 \cdot \frac{10}{j\omega + 10} \cdot \frac{j\omega + 100}{100} \\ &= 2 \frac{j\omega + 100}{j\omega + 10} \\ h(t) &= F^{-1} \left\{ 2 \frac{j\omega + 100}{j\omega + 10} \right\} \\ &= 2F^{-1} \left\{ 1 + \frac{90}{j\omega + 10} \right\} \\ &= 2(\delta(t) + 90e^{-10t}u(t)) \end{aligned}$$

From the frequency response, the LCCDE can be written as

$$\frac{dy(t)}{dt} + 10y(t) = 2\frac{dx(t)}{dt} + 200x(t)$$

- (b) (10 points) Three pole-zero plots in the s-domain are shown in the left column of the figure. Find matching frequency responses from the right column.

(Answer in the following form: (1)-(A), (2)-(B), (3)-(C))



(Answer) (1) - (C), (2) - (A), (3) - (B)

(Solution)

In the first pole-zero plot of (1), poles are on a circle of the same radius. Therefore, the break frequencies of 2nd-order systems are all the same, and only damping ratios are different. This corresponds to (c), which has no fluctuations in the pass-band and stop-band.

Meanwhile, the poles of (2) have different radii, which yield the three pass-band peaks due to the combination of three 2nd-order responses of different break frequencies.

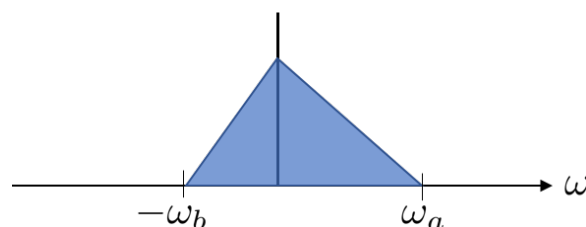
The last one, (3), consists of two 2nd-order poles and zeros, which give two pass-band peaks and two stop-band notches.

3. (20 points) [ST] For a CT signal $x(t)$ given by

$$x(t) = \frac{\sin(3\pi t)}{\pi t} e^{j2\pi t},$$

determine the Nyquist sampling rate by answering the following questions.

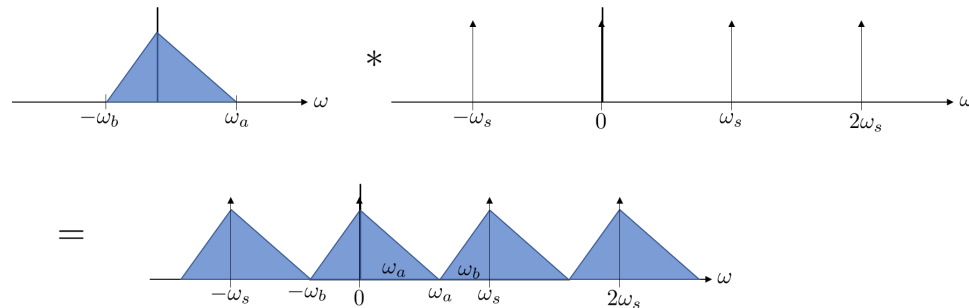
(a) (5 points) Consider an asymmetric signal $Y(j\omega)$ defined in the frequency domain as shown below:



Determine the Nyquist sampling rate ω_s to sample the given signal without aliasing artifact.

(Answer) $\omega_s = \omega_a + \omega_b$

(Solution) The aliasing artifact occurs due to the convolution with periodic impulses of period ω_s . To avoid the overlap between repeated spectra, the period of impulses should be greater than $\omega_s = \omega_a + \omega_b$ (see figure below).



- (b) (10 points) Determine the Fourier transform $X(j\omega)$ of the signal $x(t) = \frac{\sin(3\pi t)}{\pi t} e^{j2\pi t}$.

(Answer) $X(j\omega) = \begin{cases} 1 & \text{for } -\pi < \omega < 5\pi \\ 0 & \text{otherwise} \end{cases}$

(Solution) From the properties of Fourier transform

$$\frac{\sin(Wt)}{\pi t} \xleftrightarrow{CTFT} \text{Rect}_{2W}(\omega) = \begin{cases} 1 & \text{for } -W < \omega < W \\ 0 & \text{otherwise} \end{cases}$$

$$e^{j\omega_0 t} \xleftrightarrow{CTFT} 2\pi\delta(\omega - \omega_0)$$

$$y(t)z(t) \xleftrightarrow{CTFT} \frac{1}{2\pi} Y(j\omega) * Z(j\omega),$$

CTFT of $x(t)$ is given by

$$\begin{aligned} X(j\omega) &= \delta(\omega - 2\pi) * \text{Rect}_{6\pi}(\omega) \\ &= \text{Rect}_{6\pi}(\omega - 2\pi) \\ &= \begin{cases} 1 & \text{for } -\pi < \omega < 5\pi \\ 0 & \text{otherwise} \end{cases} \end{aligned} \quad (3)$$

- (c) (5 points) Determine the Nyquist rate ω_s and the corresponding sampling time T to sample the signal $X(j\omega)$ without aliasing. ($\omega_s = ?$, $T = ?$)

(Solution) Utilizing the results of (3) and problem 4-(a), the Nyquist rate is given by

$$\omega_s = 5\pi + \pi = 6\pi, \quad T = \frac{2\pi}{\omega_s} = \frac{1}{3}$$

4. (15 points) For a CT signal $x(t) = e^{-t}u(t)$, answer the following questions.

- (a) (5 points) Determine Laplace transform $X(s)$ of $x(t)$ and region of convergence (ROC).

(Answer) $X(s) = \frac{1}{s+1}$, ROC: $\text{Re}\{s\} > -1$.

(Solution)

$$\begin{aligned} X(s) &= \int_{-\infty}^{\infty} e^{-t} u(t) e^{-st} dt \\ &= \int_0^{\infty} e^{-(s+1)t} dt = -\frac{1}{s+1} e^{-(s+1)t} \Big|_{t=0}^{\infty} \\ &= \frac{1}{s+1} \quad \text{for } \text{Re}\{s\} > -1 \end{aligned}$$

- (b) (10 points) [ST] The signal $x(t)$ is sampled with the sampling period T . For $x_c(t)$ given by

$$x_c(t) = \sum_{n=0}^{\infty} e^{-nT} \delta(t - nT),$$

derive its Laplace transform $X_c(s)$ and determine the ROC. (Hint: use the property of Laplace transform $\delta(t - \tau) \xLeftrightarrow{\mathcal{L}} e^{-s\tau}$ (ROC: entire s-plane))

(Answer)

$$X(s) = \frac{1}{1 - e^{-(s+1)T}}, \quad \text{ROC: } \text{Re}\{s\} > -1$$

(Solution) From the property of Laplace transform,

$$\begin{aligned} \delta(t - \tau) &\xLeftrightarrow{\mathcal{L}} e^{-s\tau} \quad (\text{ROC: entire s-plane}) \\ \sum_{n=0}^{\infty} e^{-nT} \delta(t - nT) &\xLeftrightarrow{\mathcal{L}} X(s) = \sum_{n=0}^{\infty} e^{-nT} e^{-nsT} \\ X(s) &= \sum_{n=0}^{\infty} (e^{-(s+1)T})^n = \frac{1}{1 - e^{-(s+1)T}} \end{aligned} \tag{4}$$

The above series converges when $|e^{-(s+1)T}| < 1$. Therefore, the exponential function $e^{-(\sigma+1)T}$ should be less than 1 for $s = \sigma + j\omega$. This condition gives the ROC specified as $\text{Re}\{s\} > -1$.

5. (25 points) Z-transform problems

- (a) (10 points) Let $x[n]$ be a signal whose rational z -transform $X(z)$ contains a pole at $z = 1/2$. Given that

$$x_1[n] = \left(\frac{1}{4}\right)^n x[n]$$

is absolutely summable and

$$x_2[n] = \left(\frac{1}{8}\right)^n x[n]$$

is not absolutely summable, determine whether $x[n]$ is left-sided, right-sided, or two sided. Justify your answer.

(Answer) two-sided signal

(Solution)

Consider the z -transform of $x[n]$:

$$X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$

If $x_1[n]$ is absolutely summable, then the above z -transform has ROC at $z = 4$ because the following sum converges:

$$X(4) = \sum_{n=-\infty}^{\infty} x[n]4^{-n}$$

With the same token, $z = 8$ does not belong ROC.

Since the original pole location is at $z = 1/2$, the ROC cannot be the interior region including $z = 4$. At the same time, the ROC should exclude $z = 8$. Therefore, the ROC is the ring between $z = 1/2, 8$, which implies that the original signal is the two-sided sequence.

- (b) (10 points) Consider the following two system functions for stable LTI systems. Determine whether the corresponding systems are causal.

$$(A) \quad H(z) = \frac{1 - \frac{4}{3}z^{-1} + \frac{1}{2}z^{-2}}{z^{-1}(1 - \frac{1}{2}z^{-1})(1 - \frac{1}{3}z^{-1})}, \quad (B) \quad H(z) = \frac{z - \frac{1}{2}}{z^2 + \frac{1}{2}z - \frac{3}{16}}$$

(A) causal / noncausal, (B) causal / noncausal (answer to your answer sheet, not here)

(Answer) (A) Noncausal, (B) causal

(Solution)

(A) To be a causal system, the rational system function should include $z = \infty$ as ROC. However, this system diverges as $z \rightarrow \infty$. Therefore, this system is not causal.

(B) Two poles of this system are at $z = 1/4, -3/4$ ($|z| = 1/4, 3/4$). Because the system is stable, ROC includes the unit circle ($|z| = 1$). The ROC cannot include poles, so ROC is given by the exterior region from the outermost pole ($|z| = 3/4$). The ROC also includes $z = \infty$ since $H(z) \rightarrow 0$ as $z \rightarrow \infty$. Consequently, the system is causal.

- (c) (5 points) For the system response

$$h[n] = 6 \left(\frac{1}{2}\right)^n u[n] + 10 \left(\frac{4}{3}\right)^n u[-n-1]$$

Calculate the z -transform of $h[n]$ and determine the stability of system

(Answer)

$$H(z) = \frac{-4(1 + \frac{3}{4}z^{-1})}{(1 - \frac{1}{2}z^{-1})(1 - \frac{4}{3}z^{-1})}, \quad \text{ROC: } |z| > 1/2 \cap |z| < 4/3, \quad \text{stable}$$

(Solution)

$$\begin{aligned}a^n u[n] &\stackrel{z}{\Longleftrightarrow} \frac{1}{1 - az^{-1}}, \text{ ROC: } |z| > |a| \\ -a^n u[-n-1] &\stackrel{z}{\Longleftrightarrow} \frac{1}{1 - az^{-1}}, \text{ ROC: } |z| < |a| \\ H(z) &= \frac{6}{1 - \frac{1}{2}z^{-1}} - \frac{10}{1 - \frac{4}{3}z^{-1}} \\ &= \frac{-4(1 + \frac{3}{4}z^{-1})}{(1 - \frac{1}{2}z^{-1})(1 - \frac{4}{3}z^{-1})} : \text{ ROC: } |z| > 1/2 \cap |z| < 4/3\end{aligned}\tag{5}$$

ROC includes the unit circle = system is stable.

[End of Problem]