

Grade Table (for teacher use only)

Question:	1	2	3	4	5	6	Total
Points:	25	15	25	20	10	5	100
Score:							

1. (25 points) Determine whether each of the following statement is true or false. Justify your answers. ("Justify your answer" means you have to provide a reasoning.)

- (a) (5 points) The system described by  $y(t) = x(t - 2) + 1$  is linear.

Answer: **False**

For  $y_1(t) = x_1(t - 2) + 1$  and  $y_2(t) = x_2(t - 2) + 1$ ,  $y_1(t) + y_2(t) \neq x_1(t - 2) + x_2(t - 2) + 1$ . The constant addition (+1) makes the system nonlinear.

- (b) (5 points) If two signals  $\tilde{x}[n]$  and  $\tilde{y}[n]$  have fundamental periods  $M$  and  $N$ , respectively, then the fundamental period of the signal  $z[n] = x[n]y[n]$  is given by the least common multiple of  $M$  and  $N$ . ( $M, N > 0$ )

Answer: **False**

For example, the multiplication of the same signal  $x[n] = e^{j\omega_0 n}$  doubles the frequency:  $x[n]x[n] = e^{j(2\omega_0)n}$  and halves the fundamental period. The statement is only true for the addition of two signals.

- (c) (5 points) When a system described by the LCCDE satisfies the condition of initial rest, the system's input-output relation can be written as  $y(t) = \int_0^\infty h(\tau)x(t - \tau)d\tau$ .

Answer: **True**

If a system described by LCCDE satisfies the condition of initial rest, the system is LTI and **causal**. The causal LTI system's impulse response  $h(t)$  has non-zero values for  $t > 0$ . Therefore, the convolution integral can be written as  $y(t) = \int_{-\infty}^\infty h(\tau)x(t - \tau)d\tau = \int_0^\infty h(\tau)x(t - \tau)d\tau$ .

- (d) (5 points) The system described by  $y(t) = \int_{-\infty}^t e^{(t-\tau)}x(\tau)d\tau$  is stable.

Answer: **False**

The integral is equivalent to the convolution  $y(t) = (e^t u(t)) * x(t)$ . Since the system's output is described by the convolution integral, the system is LTI. The total power of a LTI system's impulse response should be finite to be stable. However,  $h(t) = e^t u(t)$  diverges as  $t \rightarrow \infty$ .

- (e) (5 points) The system described by  $y(t) = \int_{-\infty}^t e^{(t-\tau)} x(\tau) d\tau$  is causal.

Answer: **True**

The system's impulse response  $h(t) = e^t u(t)$  is zero for  $t < 0$ .

2. (15 points) Consider a LTI system described by the following LCCDE:

$$\frac{d^2 y(t)}{dt^2} + 3 \frac{dy(t)}{dt} + 2y(t) = 2x(t) \quad (1)$$

- (a) (5 points) Determine the output  $y(t)$  of the system for the input  $x(t) = 2 \cos\left(\frac{3}{2}t + 1\right)$ .

The given input signal can be decomposed into two frequency components (Euler's relation):

$$\begin{aligned} x(t) &= 2 \cos\left(\frac{3}{2}t + 1\right) \\ &= e^{j(\frac{3}{2}t+1)} + e^{-j(\frac{3}{2}t+1)} \end{aligned}$$

The complex exponential function is the eigenfunction of LCCDE. Therefore, the output is also described as the combination of two exponential functions:  $y(t) = Ae^{j\frac{3}{2}t} + Be^{-j\frac{3}{2}t}$ .

Solving the LCCDE with this  $x(t)$  and  $y(t)$  for each frequency yields:

$$\begin{aligned} A \left( -\frac{9}{4} + 3j \times \frac{3}{2} + 2 \right) e^{j\frac{3}{2}t} &= 2e^j \cdot e^{j\frac{3}{2}t} \rightarrow A = -\frac{8e^j}{1-18j} \\ B \left( -\frac{9}{4} - 3j \times \frac{3}{2} + 2 \right) e^{-j\frac{3}{2}t} &= 2e^{-j} \cdot e^{-j\frac{3}{2}t} \rightarrow B = -\frac{8e^{-j}}{1+18j} \end{aligned}$$

Accordingly, the output  $y(t)$  is given by

$$y(t) = -\frac{8e^j}{1-18j} e^{j\frac{3}{2}t} - \frac{8e^{-j}}{1+18j} e^{-j\frac{3}{2}t}$$

- (b) (10 points) With the condition of initial rest, calculate the impulse response  $h(t)$  of the system.

To find an impulse response, we need to solve the DE with  $x(t) = \delta(t)$

$$\begin{aligned} \frac{d^2 y(t)}{dt^2} + 3 \frac{dy(t)}{dt} + 2y(t) &= 2x(t) \\ \frac{1}{2} \frac{d^2 h(t)}{dt^2} + \frac{3}{2} \frac{dh(t)}{dt} + h(t) &= \delta(t) \end{aligned}$$

This problem is equivalent to

$$\frac{1}{2} \frac{d^2 h(t)}{dt^2} + \frac{3}{2} \frac{dh(t)}{dt} + h(t) = 0$$

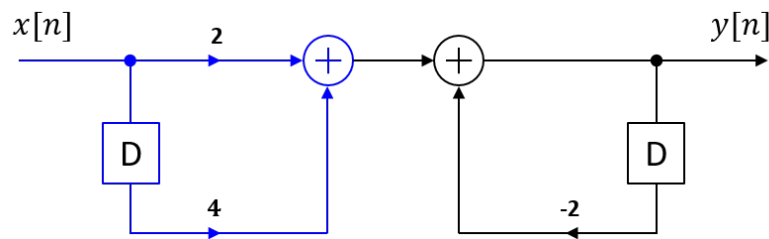
with auxiliary conditions

$$\left. \frac{1}{2} \frac{dh(t)}{dt} \right|_{t=0^+} = 1, \quad h(0^+) = 0$$

The solution is therefore given by

$$h(t) = -2e^{-2t}u(t) + 2e^{-t}u(t)$$

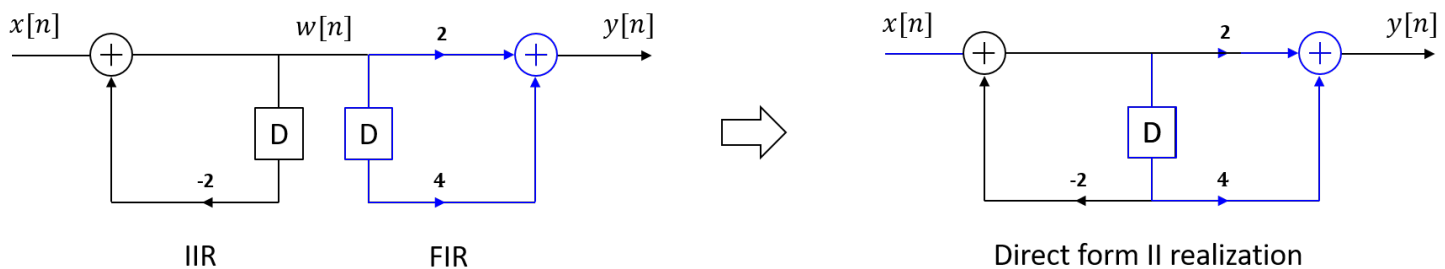
3. (25 points) A discrete-time LTI system is described by the following block diagram



- (a) (5 points) Derive the LCCDE of the given system.

$$y[n] = 2x[n] + 4x[n-1] - 2y[n-1]$$

- (b) (5 points) Draw the block diagram for the Direct form II realization.



Switching the order of FIR & IIR systems

- (c) (5 points) When the system satisfies the condition of initial rest, determine the impulse response  $h[n]$  of this system.

First, derive the impulse response of the IIR part:  $w[n] = x[n] - 2w[n-1]$ .

For  $x[n] = \delta[n]$ ,

$$\begin{aligned} n = 0 &\rightarrow w[0] = 1 - 0 = 1 \\ n = 1 &\rightarrow w[1] = 0 - 2 = -2 \\ n = 2 &\rightarrow w[2] = 0 - 2 \times -2 = 4 \\ \dots & \quad w[n] = (-2)^n u[n] \end{aligned}$$

Next, the FIR part:

$$\begin{aligned}
 y[n] &= 2w[n] + 4w[n-1] \\
 &= 2(-2)^n u[n] + 4(-2)^{n-1} u[n-1] \\
 &= (-2)^n (2u[n] - 2u[n-1]) \\
 &= 2 \cdot (-2)^n \delta[n] \\
 &= 2\delta[n] \text{ (sifting property: } \delta[n]x[n] = \delta[n]x[0])
 \end{aligned}$$

- (d) (5 points) Determine whether the system is stable or not. Justify your answer.

Answer: **Stable**

As derived in (c), squared sum of system's impulse response has finite value. Therefore, the system is stable.

- (e) (5 points) Derive the frequency response  $H(e^{j\omega})$  of the system.

Let  $y[n] = Y(e^{j\omega})e^{j\omega n}$ ,  $x[n] = X(e^{j\omega})e^{j\omega n}$ .

Then, from the difference equation,

$$\begin{aligned}
 Y(e^{j\omega})(1 + 2e^{-j\omega}) &= X(e^{j\omega})(2 + 4e^{-j\omega}) \\
 H(e^{j\omega}) &= \frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{2 + 4e^{-j\omega}}{1 + 2e^{-j\omega}} = 2
 \end{aligned}$$

4. (20 points) Let  $\tilde{x}[n]$  be an arbitrary real-valued signal with the fundamental period  $N$ . Its even and odd parts are denoted by

$$\begin{aligned}
 \tilde{x}_e[n] &= \mathcal{E}v\{\tilde{x}[n]\} \\
 \tilde{x}_o[n] &= \mathcal{O}d\{\tilde{x}[n]\}.
 \end{aligned}$$

- (a) (5 points) Show that

$$\sum_{n=\langle N \rangle} \tilde{x}^2[n] = \sum_{n=\langle N \rangle} \tilde{x}_e^2[n] + \sum_{n=\langle N \rangle} \tilde{x}_o^2[n] \quad (2)$$

By definition,  $\tilde{x}_e[n] = \frac{\tilde{x}[n] + \tilde{x}[-n]}{2}$  and  $\tilde{x}_o[n] = \frac{\tilde{x}[n] - \tilde{x}[-n]}{2}$ .

$$\begin{aligned}
 \tilde{x}_e^2[n] + \tilde{x}_o^2[n] &= \frac{\tilde{x}^2[n] + \tilde{x}^2[-n]}{2} \\
 \longrightarrow \sum_{n=\langle N \rangle} \tilde{x}_e^2[n] + \tilde{x}_o^2[n] &= \sum_{n=\langle N \rangle} \tilde{x}^2[n] + \sum_{n=\langle N \rangle} \tilde{x}^2[-n] \\
 \text{However, } \sum_{n=\langle N \rangle} \tilde{x}^2[-n] &= \sum_{n=\langle N \rangle} \tilde{x}^2[n]. \text{ (sum of a periodic signal over a single period)} \\
 \therefore \sum_{n=\langle N \rangle} \tilde{x}^2[n] &= \sum_{n=\langle N \rangle} \tilde{x}_e^2[n] + \sum_{n=\langle N \rangle} \tilde{x}_o^2[n]
 \end{aligned}$$

- (b) (10 points) Let  $b_k$  and  $c_k$  be the real and imaginary parts of the Fourier series coefficients  $a_k$  of  $\tilde{x}[n]$ , respectively.

$$\tilde{x}[n] \xleftrightarrow{\mathcal{FS}} a_k = b_k + jc_k \quad (3)$$

For the periodic convolution of two coefficients  $d_k = b_k * c_k$ , find the value of  $d_0$ .

Because  $\tilde{x}[n]$  is a real-valued function, its even part  $\tilde{x}_e[n]$  has Fourier series coefficients  $b_k$ , and  $\tilde{x}_o[n]$  has  $jc_k$ .

$$\tilde{x}_e[n] \xleftrightarrow{\mathcal{FS}} b_k, \quad \tilde{x}_o[n] \xleftrightarrow{\mathcal{FS}} jc_k$$

The convolution of two Fourier series coefficients is the multiplication in time domain. Therefore, we have

$$\tilde{x}_e[n]x_o[n] \xleftrightarrow{\mathcal{FS}} b_k * jc_k = d_k$$

The value of  $d_k$  at  $k = 0$  corresponds to the mean value of its time signal:

$$d_0 = \frac{1}{N} \sum_{n=\langle N \rangle} \tilde{x}_e[n]\tilde{x}_o[n]$$

However, from the result of Eq.(2),  $\sum_{n=\langle N \rangle} \tilde{x}_e[n]\tilde{x}_o[n]$  is equal to zero because:

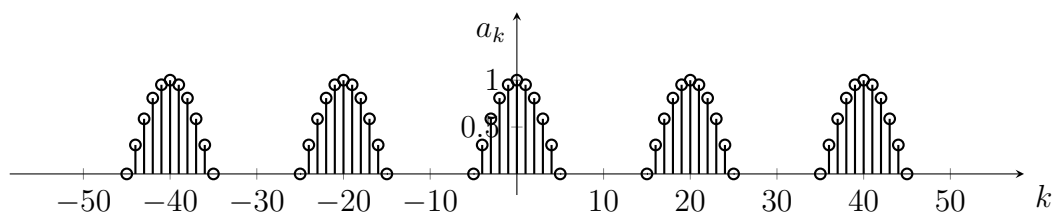
$$\begin{aligned} \sum_{n=\langle N \rangle} \tilde{x}^2[n] &= \sum_{n=\langle N \rangle} (\tilde{x}_e[n] + \tilde{x}_o[n])^2 \\ &= \sum_{n=\langle N \rangle} \tilde{x}_e^2[n] + \sum_{n=\langle N \rangle} \tilde{x}_o^2[n] \end{aligned}$$

Therefore,  $d_0 = 0$ .

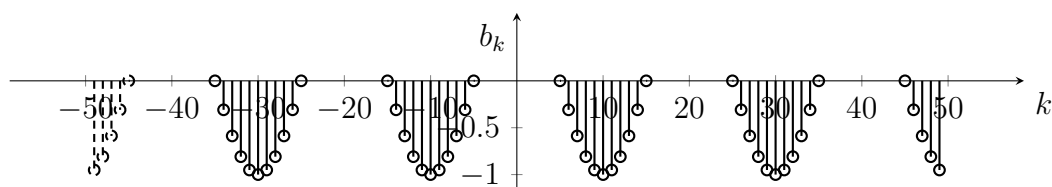
(c) (5 points) Calculate the mean value of  $c_k$ .

The mean value of  $c_k$  corresponds to the zero-time value in time domain. Since  $jc_k$  is the Fourier series coefficients of the odd function  $x_o[n]$ , the zero-time value of  $x_o[0] = 0$ .

5. (10 points) The real-valued Fourier series coefficients  $a_k$  of a periodic discrete-time sequence  $\tilde{x}[n]$  is given as follows:



(a) (5 points) The Fourier series coefficients  $b_k$  of a signal  $\tilde{y}[n]$  is also shown below. Using the relation of two graphs, express  $\tilde{y}[n]$  in terms of  $\tilde{x}[n]$ .



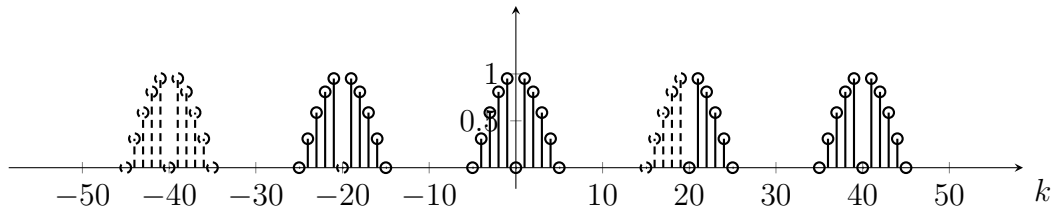
The fundamental period of  $a_k$  is  $N = 20$ .

The signal  $b_k$  is obtained by shifting  $a_k$  by half of its period ( $N/2 = 10$ ) and inverting its sign. Therefore,

$$\begin{aligned} b_k &= -a_{k-10} \\ \tilde{y}[n] &= -\tilde{x}[n]e^{j10\omega_0 n} \\ &= -\tilde{x}[n]e^{j10\frac{2\pi}{N}n} = -\tilde{x}[n]e^{j\pi n} \\ &= -(-1)^n \tilde{x}[n] \end{aligned}$$

- (b) (5 points) Plot the Fourier series coefficients of a signal  $\tilde{x}[n] - 1$  (Also mark the maximum magnitude and fundamental period).

Fourier Series coefficients of a constant are given by a series of impulses  $\delta[k - nN]$  for the period  $N$  and arbitrary integer  $n$ . Therefore, the subtraction  $(-1)$  reduces the zero frequency component and its periodic replicas by one.



6. (5 points) [Matlab Problem] Complete a code for calculating the convolution of signals  $x[n] = [7, 5, 3, 1]$  and  $h[n] = [2, 4]$ . Choose correct expressions among the given examples to complete the code. Then calculate the result of convolution  $y[n]$ .

Answer: (A)- ( 4 ), (B) - ( 3 ), (C) - ([ 14 38 26 14 4 ] )

A. (1) `x=7:-2:end` (2) `x=fliplr(1:7)` (3) `x=flipud(1:2:7)` (4) `x=7:-2:1`

B. (1) `h=2^(1:2)` (2) `h=2:4` (3) `h=2.^(1:2)` (4) `h=2:1:4`

C. Calculate the result of `y = conv(h,x);`