

LCD16x02 and LM35 Sensor Interface with STM32

In this tutorial, we'll discuss how to interface the LM35 temperature sensor with an STM32F0 microcontroller. Using the ADC to get the analog output voltage of the sensor then converting it back to Celsius degrees, and finally display the result on an LCD 16x2.

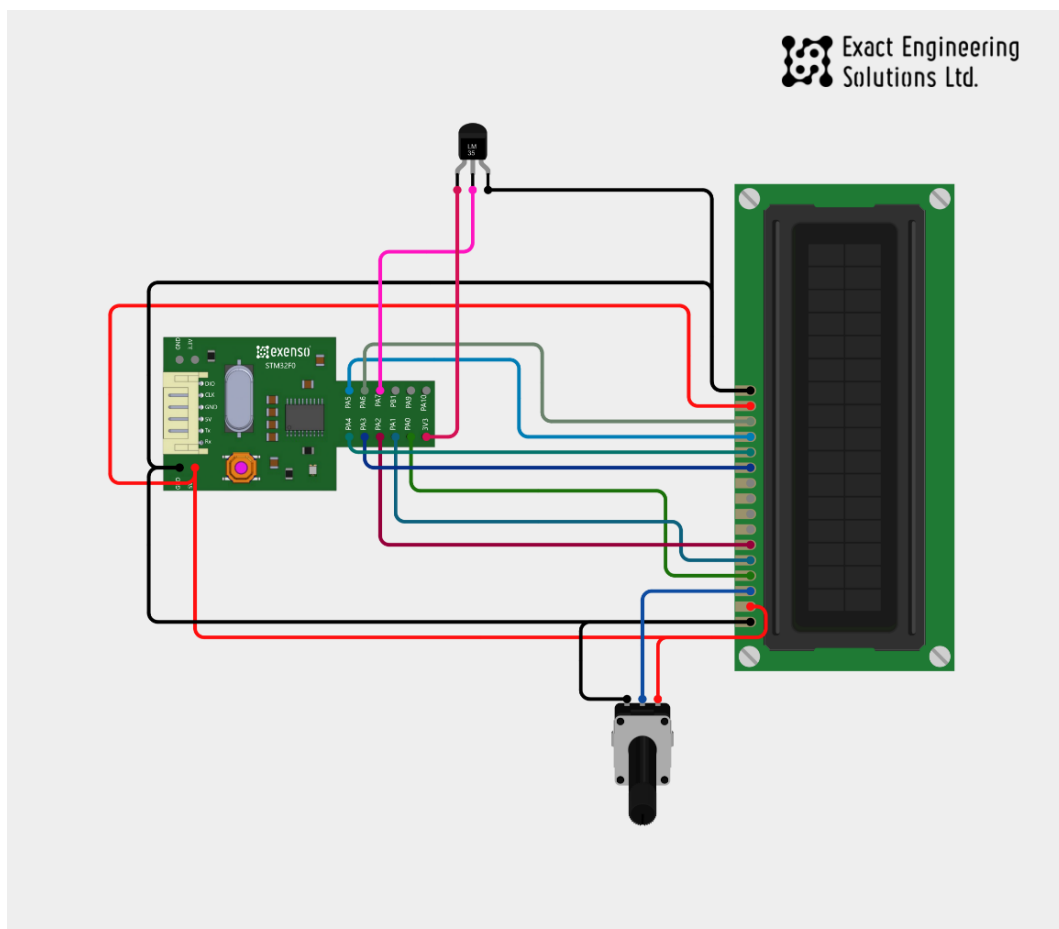
Components Required

You will need the following components –

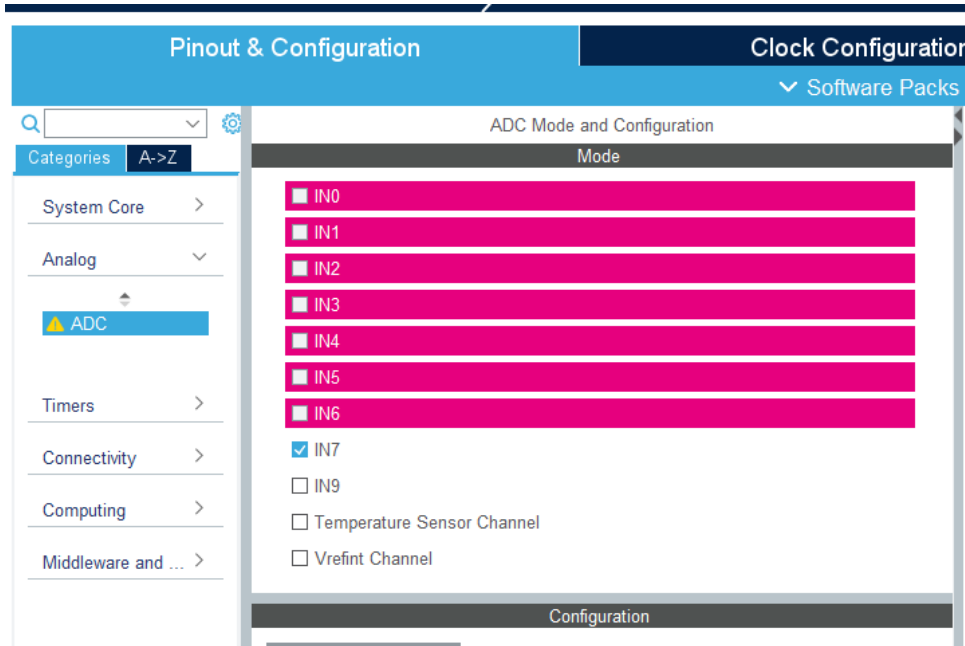
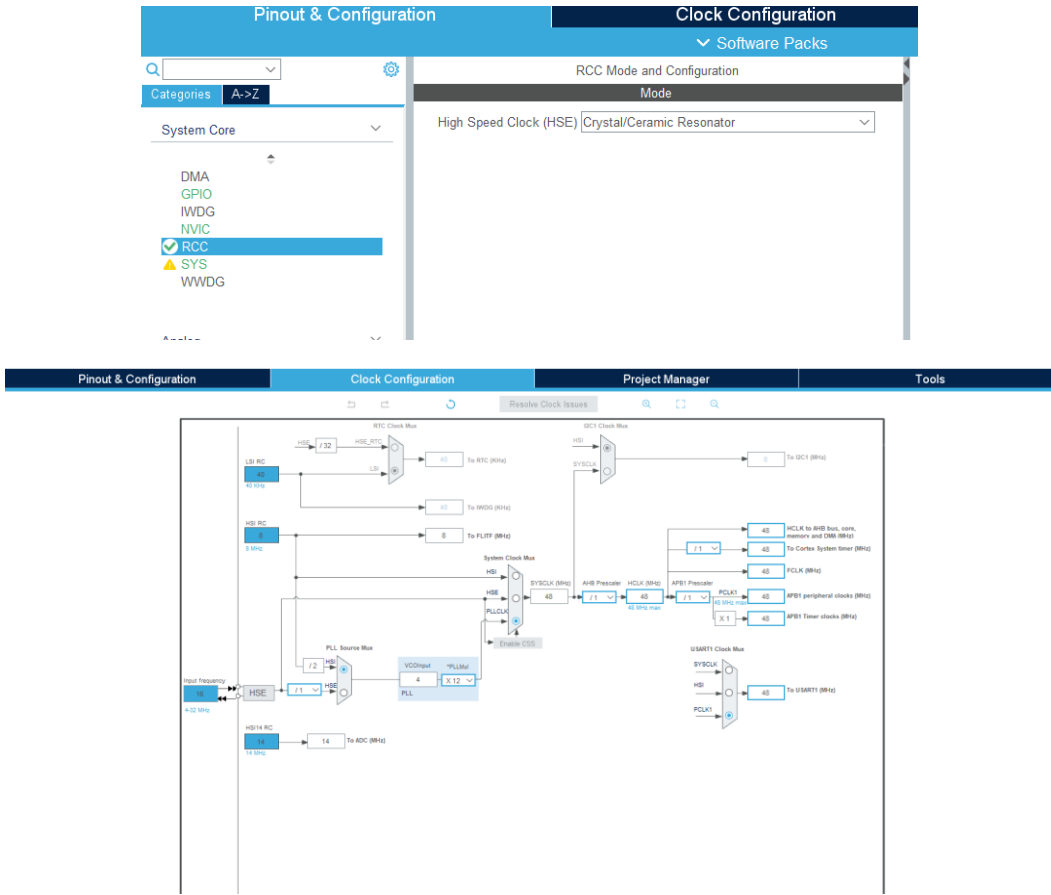
- 1 × Breadboard
- 1 × STM32F030F4P6
- 1× LCD 16x2
- 1× 10KΩ potentiometer
- 1x LM35 Temperature Sensor
- Some Jumper wire

Procedure

Follow the circuit diagram shown in the image given below.



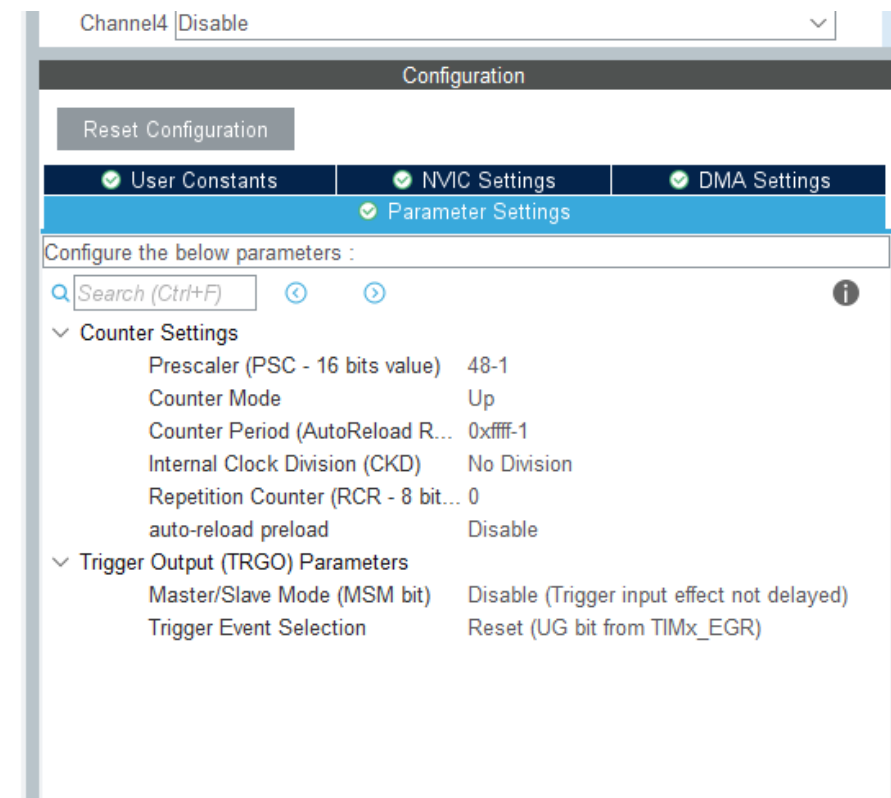
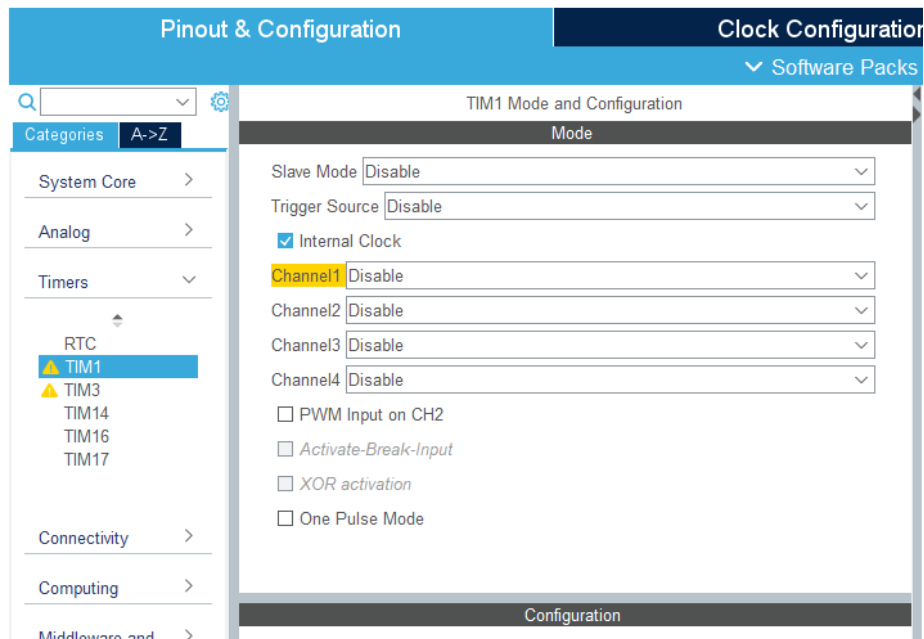
STM32F0 Pin Configuration:



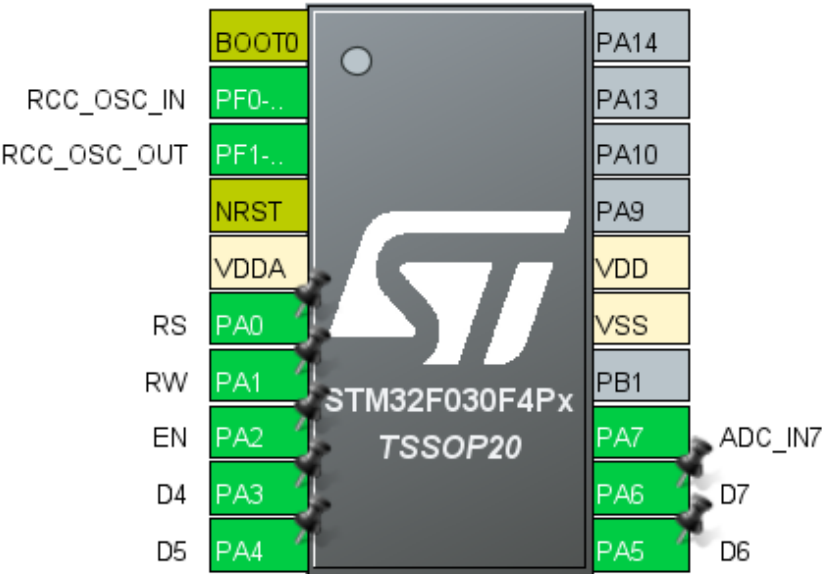
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✓ Parameter Settings	✓ User Constants																							
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✓ ADC_Settings <table border="0"> <tr> <td>Clock Prescaler</td> <td>Asynchronous clock mode</td> </tr> <tr> <td>Resolution</td> <td>ADC 10-bit resolution</td> </tr> <tr> <td>Data Alignment</td> <td>Right alignment</td> </tr> <tr> <td>Scan Conversion Mode</td> <td>Forward</td> </tr> <tr> <td>Continuous Conversion Mode</td> <td>Disabled</td> </tr> <tr> <td>Discontinuous Conversion Mode</td> <td>Disabled</td> </tr> <tr> <td>DMA Continuous Requests</td> <td>Disabled</td> </tr> <tr> <td>End Of Conversion Selection</td> <td>End of single conversion</td> </tr> <tr> <td>Overrun behaviour</td> <td>Overrun data preserved</td> </tr> <tr> <td>Low Power Auto Wait</td> <td>Disabled</td> </tr> <tr> <td>Low Power Auto Power Off</td> <td>Disabled</td> </tr> </table>			Clock Prescaler	Asynchronous clock mode	Resolution	ADC 10-bit resolution	Data Alignment	Right alignment	Scan Conversion Mode	Forward	Continuous Conversion Mode	Disabled	Discontinuous Conversion Mode	Disabled	DMA Continuous Requests	Disabled	End Of Conversion Selection	End of single conversion	Overrun behaviour	Overrun data preserved	Low Power Auto Wait	Disabled	Low Power Auto Power Off	Disabled
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Reset Configuration

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PA0 To PA6 Pin set as OUTPUT



Code

```
#include "main.h"
#include "LCD1602.h"

float LM35_Read(uint16_t ADCvalue , float Ref_voltage, uint16_t bit_Resulation){

    float voltage = ( ADCvalue * Ref_voltage) / bit_Resulation;
    float Temp = voltage / 0.01;
    return Temp;
}

ADC_HandleTypeDef hadc;
TIM_HandleTypeDef htim1;

void SystemClock_Config(void);
static void MX_GPIO_Init(void);
static void MX_TIM1_Init(void);
static void MX_ADC_Init(void);

float temp = 0.0;    // Init int value
uint16_t adcvalue = 0;

int main(void)
{
    HAL_Init();
    SystemClock_Config();
    MX_GPIO_Init();
    MX_TIM1_Init();
    MX_ADC_Init();

    HAL_TIM_Base_Start(&htim1); // Timer On and init this line
    lcd_init();                //LCD init
    lcd_xy(0, 4);              // set cursor postion row 0 and colum 4
    LCD_String("LM35 Temp"); // Print String

    while (1)
    {
        // ADC conversion
        HAL_ADC_Start(&hadc);
        HAL_ADC_PollForConversion(&hadc,200);
        adcvalue = HAL_ADC_GetValue(&hadc);

        // Ref voltage 3.3V and 10bit = 2^10 = 1023
        temp = LM35_Read(adcvalue, 3.3, 1023);

        lcd_xy(1, 5);
        LCD_floatValue(temp, 2); // print Float value and after dot show 2digit
        LCD_String("\337C");    // for degree celcus
        HAL_Delay(500);
    }
}
```

Output:

