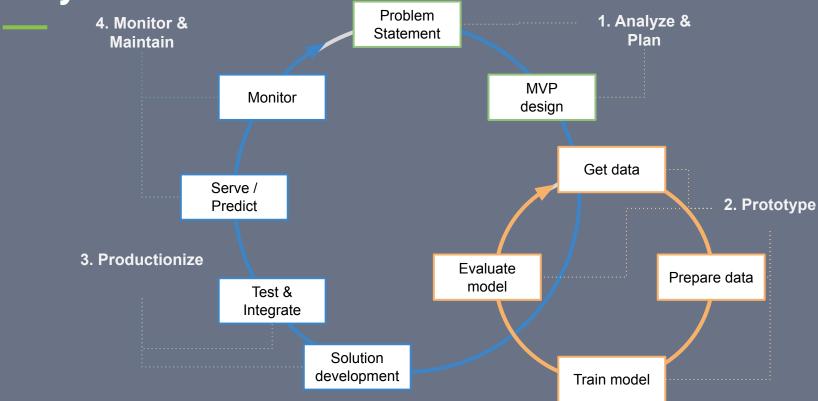
Reproducibility in CV

Overview

Tezikov Roman REPA meetup #1 Why do I need it?



Specific problems

Running CUDA and cuDNN

Bitwise reproducibility is not guaranteed across cuDNN versions, as the implementation of a given routine may change.

Functions without guarantee of reproducibility:

- cudnnConvolutionBackwardFilter
- cudnnConvolutionBackwardData
- cudnnPoolingBackward
- cudnnSpatialTfSamplerBackward

Running CUDA and cuDNN

cudnnPoolingBackward



cudnnConvolutionBackwardFilter

cudnnConvolutionBackwardData

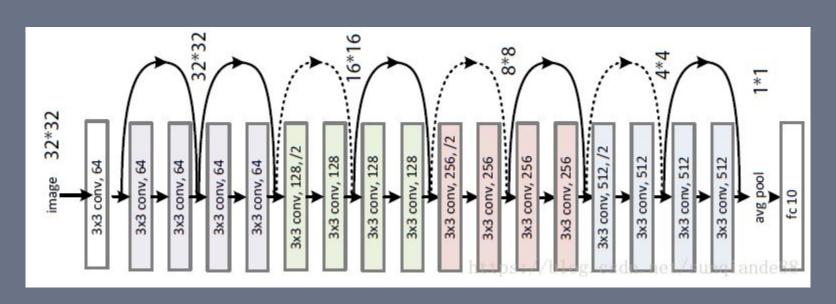
Running CUDA and cuDNN



A number of operations have backwards that use atomicAdd

- CTCLoss
- Many forms of pooling, padding, and sampling

Inaccuracies accumulate with deeper networks





Completely reproducible results are not guaranteed!



Is there any solution?

Make requirements.txt and Dockerfile with frozen dependencies

requirements.txt

```
albumentations=0.2.2
catalyst=19.6.1
imageio=2.5.0
numpy=1.16.3
opencv-python=4.1.0.25
PyYAML=5.1
safitty=1.2.0
tensorboardX=1.6
torch=1.1.0
torchvision=0.2.2.post3
tqdm=4.31.1
```

Make requirements.txt and Dockerfile with frozen dependencies

Dockerfile

```
FROM nvidia/cuda:10.1-devel-ubuntu18.04
ENV LANG=C.UTF-8 LC_ALL=C.UTF-8
RUN apt-get update & \
     apt-get install -y apt-utils & \
     apt-get install -v \
           wget \
           curl \
           python3 \
           python3-pip & \
     rm -rf /var/lib/apt/lists/* /tmp/* /var/tmp/*
COPY ./requirements.txt /workspace/requirements.txt
RUN pip3 install -r /workspace/requirements.txt
```

Store your model & training params as YAML/JSON

```
model params:
  model: ResNeXt50 32×4d
args:
  logdir: "./logs/cifar stages"
data params:
  batch size: 64
  num workers: 1
state_params:
  num epochs: 10
  main metric: &reduce metric accuracy01
  minimize metric: False
optimizer_params:
  optimizer: Adam
  lr: 0.001
  weight decay: 0.0001
scheduler params:
  scheduler: MultiStepLR
  milestones: [10]
  gamma: 0.3
```

Set a seed to all frameworks you use.

```
def set_global_seed(seed: int) → None:
    trv:
        import torch
    except ImportError:
    else:
        torch.manual_seed(seed)
        torch.cuda.manual_seed_all(seed)
    trv:
        import tensorflow as tf.
    except ImportError:
        pass
    else:
        tf.set_random_seed(seed)
    random.seed(seed)
    np.random.seed(seed)
```

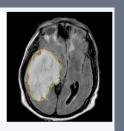
Change cuDNN mode to deterministic

```
torch.backends.cudnn.deterministic = True
torch.backends.cudnn.benchmark = False
```

Pytorch Hub

U-Net for brain MRI

U-Net with batch normalization for biomedical image segmentation with pretrained weights for abnormality segmentation in brain MRI



Deeplabv3-ResNet101

DeepLabV3 model with a ResNet-101 backbone



BERT

Bidirectional Encoder Representations from Transformers.



- Easy to load and use models
- 20+ different models
- Integration with PapersWithCode

```
In[2]: import torch
In[3]: torch.hub.list('pytorch/vision')
Using cache found in /Users/romach/.cache/torch/hub/pytorch_vision_master
Out[3]:
['alexnet',
 'deeplabv3_resnet101',
 'densenet121',
 'densenet161'.
 'densenet169',
 'densenet201',
 'fcn_resnet101',
 'googlenet',
 'inception v3',
 'mobilenet_v2',
```

Frameworks

Common





DL

C_{\(\)}talyst

TeasersREPA meetup #2

- Владислав Грозин «MLFlow и Sacred. Контроль экспериментов в DL»
- Александр Бельских Тема уточняется
- Тезиков Роман «Управление моделями с Catalyst. Workshop»

Questions?